- (a) Solve the following differential equation using Laplace Transform Methods. Assume all initial conditions are 0.
 - (b) Find the solution if the initial conditions are not all zero. Specifically, find x(t) when x(0)=0, x'(0)=.25.

$$\frac{d^2x(t)}{dt^2} + 4x(t) = t$$

$$USe \qquad 1) \qquad \mathcal{I}\left[\frac{d^2x(t)}{dt^2}\right] = s^2 \times (s) - s \times (o) - x'(o)$$

$$2) \qquad \mathcal{I}\left[t\right] = \frac{1}{s^2}$$

$$\frac{dx^{2}(t)}{dt^{2}} + 4x/t) = t$$

$$\Rightarrow s^{2}x(s) - 5x/0) - x'(0) + 4x(s) = \frac{1}{s^{2}}$$

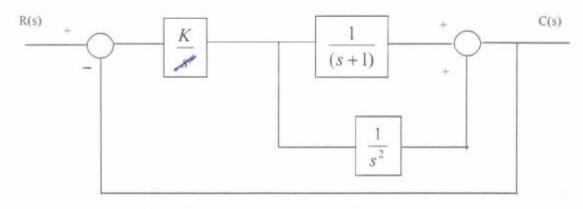
$$x(s) = \frac{1}{s^{2}(s^{2}+4)} + \frac{5x/0) + x'(0)}{s^{2}+4}$$

a) • Ic's 0 implies
$$X(s) = \frac{1}{s^{2}(s^{2}+4)} = \frac{(1/4)}{s^{2}} + \frac{(-1/4)}{s^{2}+4}$$
and $X(t) = (\frac{1}{4}t - \frac{1}{8}sin 2t)$ $u(t)$

b)
$$\chi(6) = 0$$
 and $\chi'(6) = .25$ implies
$$\chi(5) = \frac{1}{5^{2}/5^{2}+4} + \frac{.25}{5^{2}} + \frac{.25}{5^{2}} + \frac{.25}{5^{2}+4} + \frac{.25}{5^{2}+4}$$

$$= \frac{.25}{5^{2}}$$
and $\chi'(6) = 0$ and $\chi'(6) = .25$ tu(t)

2. Find the range of K for stability in the following system.



$$\frac{1}{s+1} + \frac{1}{s^2} = \frac{s^2 + s + 1}{s^2 (s+1)}$$

$$\frac{\mathcal{K}\left(5^2+5+1\right)}{5^2(5+1)}$$

$$\frac{k(s^2 + s + 1)}{s^3 + (k+1)s^2 + ks + k}$$

Routh table:

$$\begin{array}{ccc}
K & & & & & & & & & & \\
K & \longrightarrow & & & & & & & & \\
O & \longrightarrow & & & & & & & \\
& \longrightarrow & & & & & & & \\
& \longrightarrow & & & & & & & \\
& \longrightarrow & & & & & & & \\
& \longrightarrow & & & & & & \\
& \longrightarrow & & & & & & \\
\end{array}$$

 $\int_{S_0}^{S_0} K > 0$ Winter 1999

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- 3. (a) Find the single block (closed loop) transfer function for either problem (3-1) or (3-2).
 - (b) Draw the unit step response of your transfer function. Calculate the overshoot, settling time, and peak time.

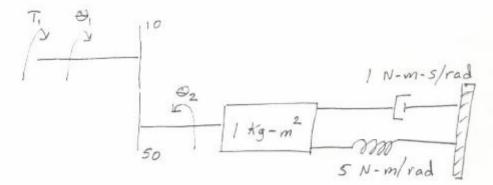


Figure 3-1. The transfer function of interest is $\theta 2(s)/T(s)$

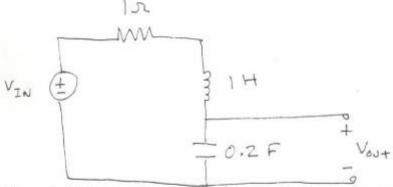


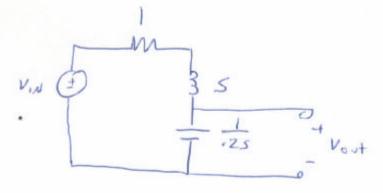
Figure 3-2. The transfer function of interest is Vout(s)/Vin(s)

$$57(5) \quad \Theta_2$$

$$9 \quad 15^2\Theta_2(5) \quad 75\Theta_2(5)$$

$$5T(5) = \Theta_{2}(5)[5^{2}+5+5]$$

3-2

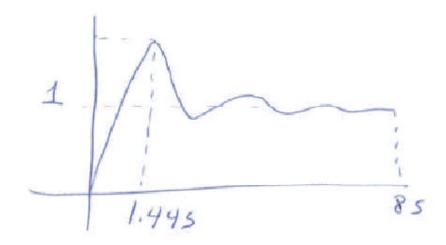


$$\frac{V_{0,1}(s)}{V_{1,1}(s)} = \frac{1}{\frac{1}{.2s} + s + 1}$$

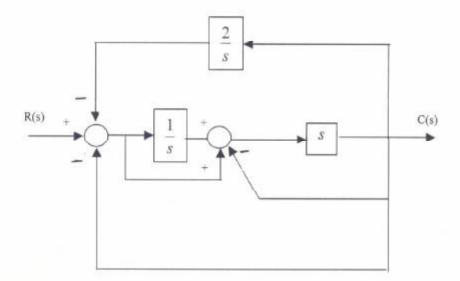
$$= \frac{5}{s^2 + s + 5}$$

3b)
$$W_n^2 = 5$$
 or $W_n = \sqrt{5}$
 $23W_n = 1$ or $3 = .223$

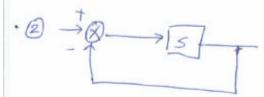
$$T_{p} = 1.445$$
 $T_{s} = 85$



- 4. (a) Find the time domain output of the following system when excited by a step input. What is the steady state error?
 - (b) How do your answers for (a) change if the input is $e^{-3t}u(t)$?



Parallel form
$$\frac{1}{5}+1=\frac{5+1}{5}$$



$$\frac{2}{5} \text{ and } 1 \text{ in feedback}$$

$$\frac{1}{1+\frac{2}{5}} = \frac{5}{5+2}$$

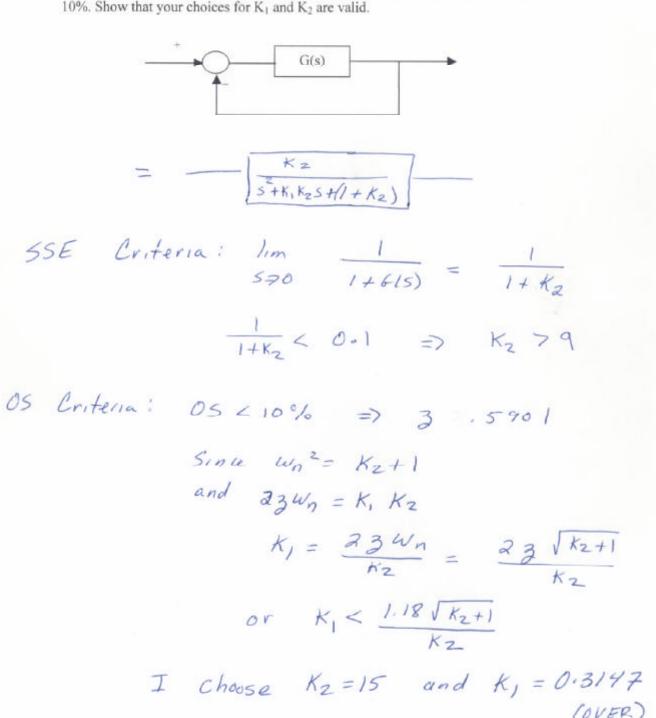
a)
$$s tep$$
 Response
$$\int_{-1}^{1} \left[\frac{1}{5} \cdot \frac{s}{2s+2} \right] = \int_{-1}^{1} \left[\frac{1}{2} \right] = \frac{1}{2} e^{-t} u(t)$$

$$SSE = \lim_{s \to 0} \frac{1}{1 + \frac{s}{2s+2}} = 1$$

b)
$$e^{-3t}$$
 $u(t)$ Response
$$\int_{-1}^{1} \left[\frac{1}{s+3} \cdot \frac{1}{s+1} \right] = \int_{-1}^{1} \left[\frac{(3/4)}{s+3} + \frac{(-1/4)}{s+1} \right] \\
= \left(\frac{3}{4} e^{-3t} - \frac{1}{4} e^{-t} \right) u(t)$$

$$55E = \lim_{s \to 0} \frac{s R(s)}{1+6ls} = \lim_{s \to 0} \frac{s}{1+\frac{s}{2s+2}} = 0$$

5. In the following system, $G(s) = \frac{K_2}{s^2 + K_1 K_2 s + 1}$. Design (choose) values for K_1 and K_2 so that the steady state error due to a step input is less than .1 and the overshoot is less than



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Show Validity

Bouth Table:

$$5^{2}$$
 | 1+K2
 5^{1} K₁K₂ 0
 5^{0} 1+K₂

50 K, K2 >0

and 1+Kz >0

both are true for

 $K_1 = 0.3147$

Kz = 15.