Machine Learning Lecture 7

Clustering

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Acknowledgement

- A large part of slides in this lecture are originally from
 - Prof. Andrew Ng (Stanford University)
 - Prof. Shuai Li (Shanghai Jiao Tong University)



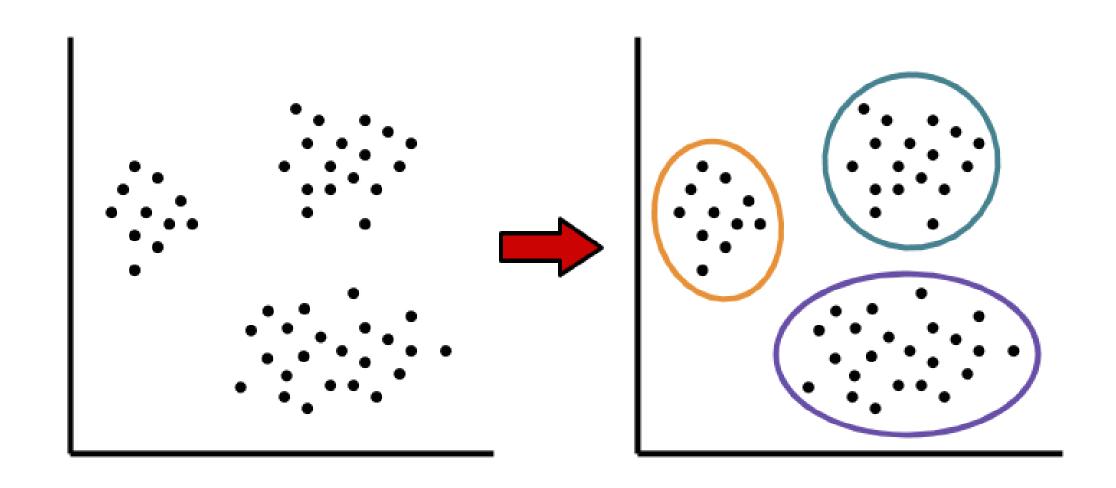
Prof. Andrew Ng Stanford University



Prof. Shuai Li Shanghai Jiao Tong University

Unsupervised Learning

Unsupervised learning example



Supervised Learning	Unsupervised Learning
Input data is labelled	Input data is unlabeled
Uses training dataset	Uses just input dataset
Used for prediction	Used for analysis
Classification and regression	Clustering, density estimation and dimensionality reduction

Clustering

Clustering

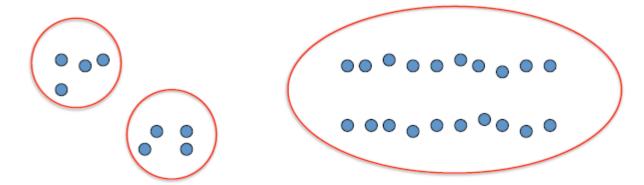
- Unsupervised learning
- Requires data, but no labels
- Detect patterns e.g. in
 - Group emails or search results
 - Customer shopping patterns
 - Regions of images
- Useful when don't know what you're looking for
- But: can get gibberish

Clustering (cont.)

- Goal: Automatically segment data into groups of similar points
- Question: When and why would we want to do this?
- Useful for:
 - Automatically organizing data
 - Understanding hidden structure in some data
 - Representing high-dimensional data in a low-dimensional space
- Examples: Cluster
 - customers according to purchase histories
 - genes according to expression profile
 - search results according to topic
 - Facebook users according to interests
 - a museum catalog according to image similarity

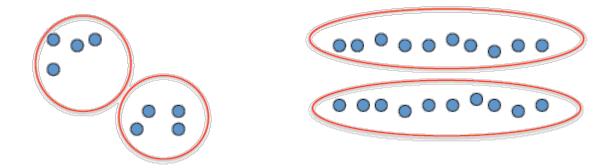
Intuition

- Basic idea: group together similar instances
- Example: 2D point patterns



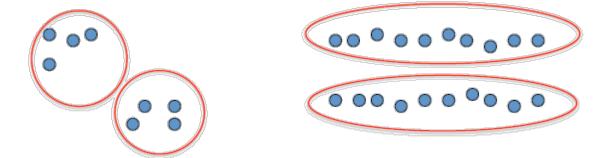
Intuition (cont.)

- Basic idea: group together similar instances
- Example: 2D point patterns



Intuition (cont.)

- Basic idea: group together similar instances
- Example: 2D point patterns



- What could "similar" mean?
- One option: small Euclidean distance (squared)
- Clustering results are crucially dependent on the measure of similarity (or distance) between "points" to be clustered

Set-up

• Given the data: $\mathcal{D} = \{x_1, \dots, x_N\}$

• Each data point x is d-dimensional:

$$x_i = (x_{i,1}, ..., x_{i,d})$$

Define a distance function between data:

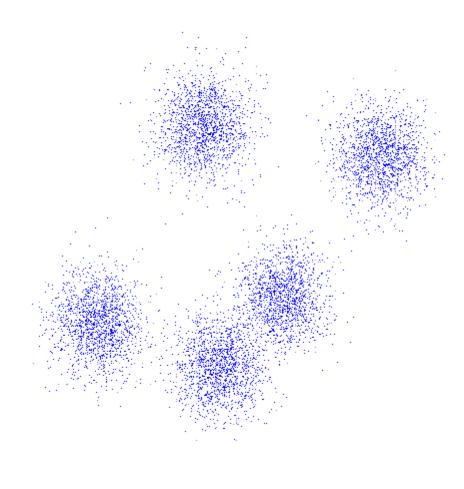
$$d(\mathbf{x}_n,\mathbf{x}_m)$$
.

Goal: segment the data into K groups

K-Means

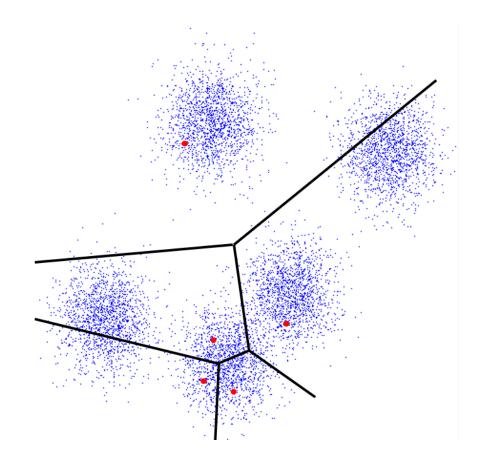
K-Means

- An iterative clustering algorithm
- Initialize: Pick *K* random points as cluster centers
- Alternate:
 - Assign data points to closest cluster center
 - Change the cluster center to the average of its assigned points
- Stop: when no points' assignments change



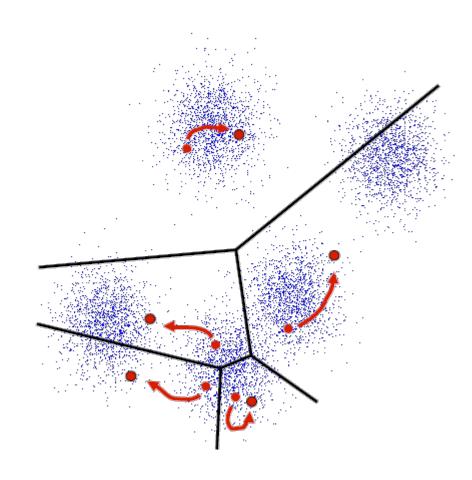
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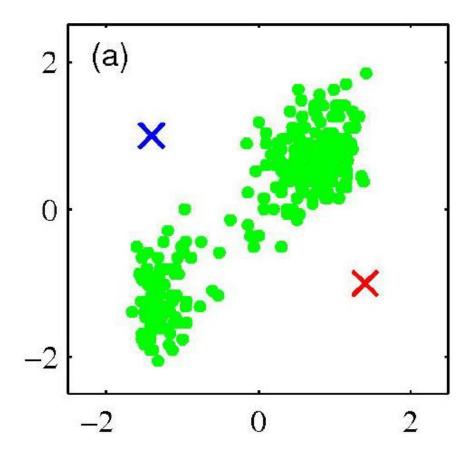
K-Means (cont.)

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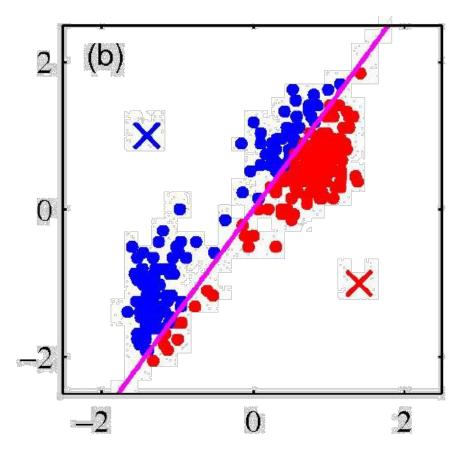


Example

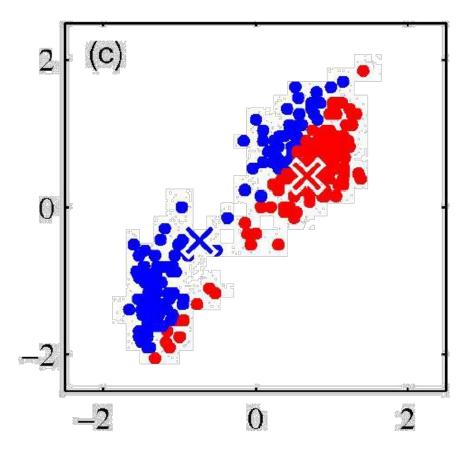
- Pick *K* random points as cluster centers (means)
- Shown here for K=2



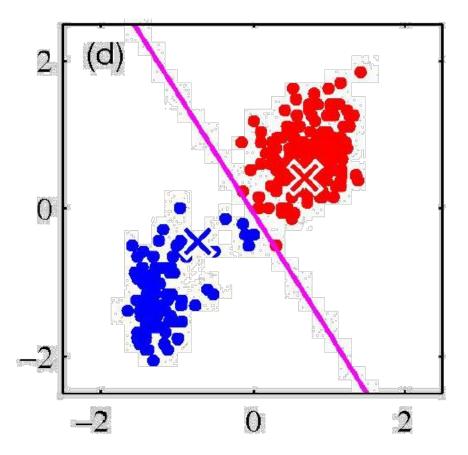
- Iterative step 1
- Assign data points to closest cluster center



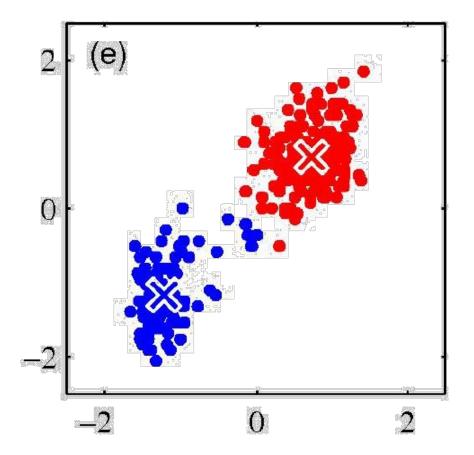
- Iterative step 2
- Change the cluster center to the average of the assigned points



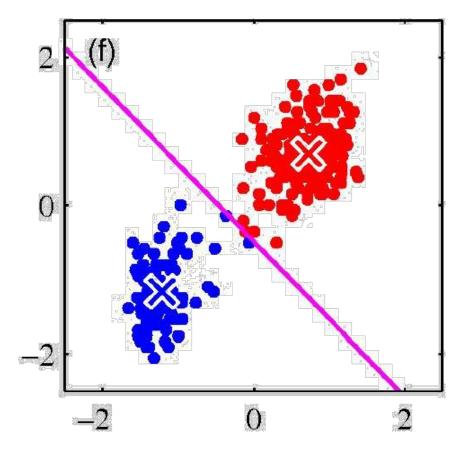
- Repeat until convergence
- Convergence means that the differences of the center positions in two continuous loops is smaller than a threshold



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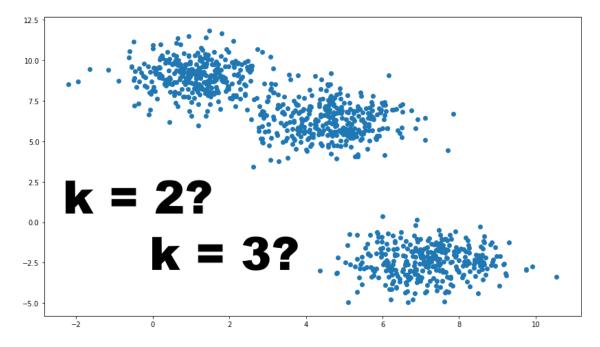
Remained Questions in K-Means

Remained questions in K-means

- Although the workflow of K-means is straight forward, there are some important questions that need to be discussed
- How to choose the hyper-parameter *K*?
- How to initialize?

How to choose K?

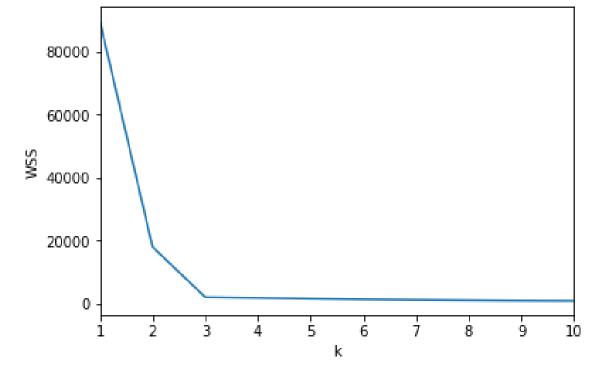
- K is the most important hyper-parameter in K-means which strongly affects its performance. In some situation, it's not an easy task to find the proper K
- The solution includes:
 - The elbow method
 - The silhouette method



The elbow method

 Calculate the Within-Cluster-Sum of Squared Errors (WSS) for different values of K, and choose the K for which WSS stops dropping significantly. In the plot of WSS-versus-k, this is visible as an elbow

• Example: K = 3



The silhouette method

• The problem of the elbow method is that in many situations the most suitable K cannot be unambiguously identified. So we need the silhouette method

• The silhouette value measures how similar a point is to its own cluster (cohesion) compared to other clusters (separation). The range of the silhouette value is between +1 and -1. A high value is desirable and indicates that the point is placed in the correct cluster

The silhouette method (cont.)

• For each data point $i \in C_k$, let a(i) be its mean distance to all other points in the same cluster

$$a(i) = \frac{1}{|C_k| - 1} \sum_{j \in C_k, i \neq j} d(i, j)$$

• And let b(i) be the smallest mean distance to other clusters

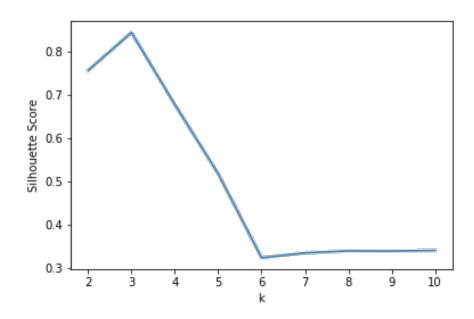
$$b(i) = \min_{l \neq k} \frac{1}{|C_l|} \sum_{j \in C_l} d(i, j)$$

The silhouette method (cont.)

• The silhouette value of $i \in C_k$ is defined as:

$$s(i) = \begin{cases} \frac{b(i) - a(i)}{\max\{a(i), b(i)\}}, & if |C_k| > 1\\ 0, & if |C_k| = 1 \end{cases}$$

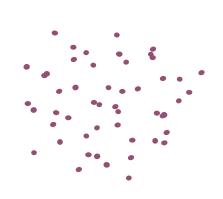
- The silhouette score is the average of s(i) among all data
- Choose the k with the maximal silhouette score

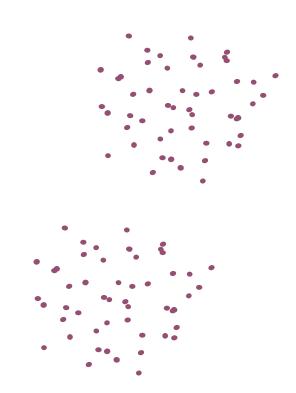


How to initialize center positions?

• The positions of the centers in the stage of initialization are also very important in K-means algorithms. In some situations it can produce totally different clustering results

• Example:

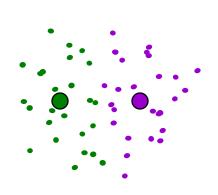


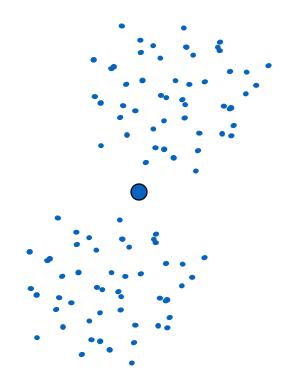


How to initialize center positions? (cont.)

• The positions of the centers in the stage of initialization are also very important in K-means algorithms. In some situations it can produce totally different clustering results

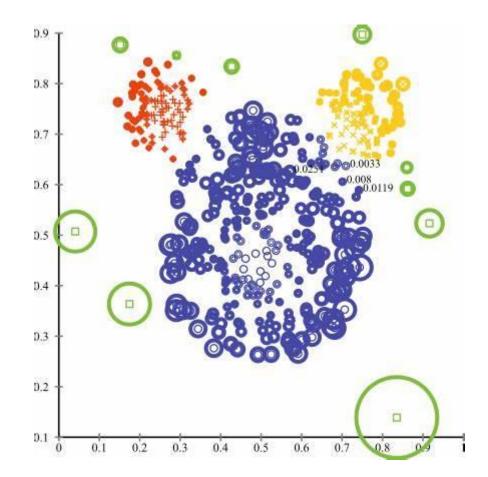
• Example:





A possible solution

- Pick one point at random, then K-1 other points, each as far away as possible from the previous points
 - OK, as long as there are no *outliers* (points that are far from any reasonable cluster)



K-means++

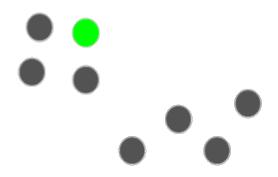
- 1. The first centroid is chosen uniformly at random from the data points that we want to cluster. This is similar to what we do in K-Means, but instead of randomly picking all the centroids, we just pick one centroid here
- 2. Next, we compute the distance d_x is the nearest distance from data point x to the centroids that have already been chosen
- 3. Then, choose the new cluster center from the data points with the probability of x being proportional to d_x^2
- 4. We then repeat steps 2 and 3 until *K* clusters have been chosen

Example

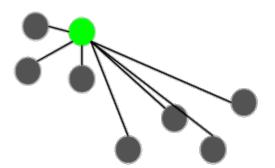
• Suppose we have the following points and we want to make 3 clusters here:



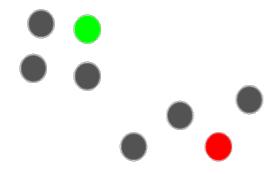
• First step is to randomly pick a data point as a cluster centroid:



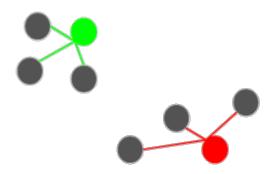
• Calculate the distance d_{x} of each data point with this centroid:



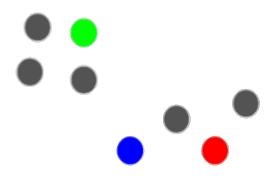
- The next centroid will be sampled with the probability proportional to $d_{\it x}^2$
- Say the sampled is the red one



• To select the last centroid, compute d_{χ} , which is the distance to its closest centroid



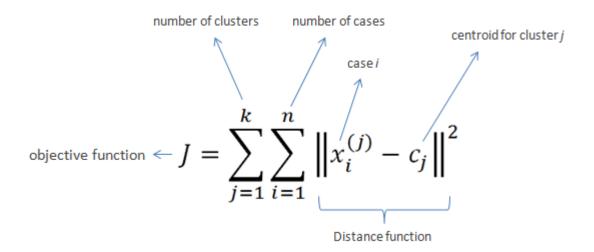
- Sample the one with the probability proportional to d_{χ}^2
- Say, the blue one



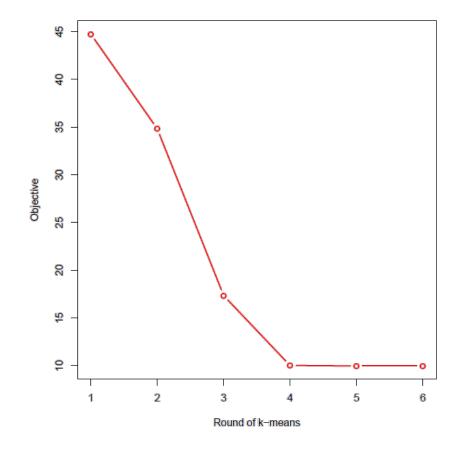
Properties of K-Means

How to measure the performance

 K-means can be evaluated by the sum of distance from points to corresponding centers, or the WSS



• The loss will approach zero when increase *K*



Properties of the K-means algorithm

Guaranteed to converge in a finite number of iterations

- Running time per iteration:
 - Assign data points to closest cluster center O(KN) time
 - 2. Change the cluster center to the average of its assigned points O(N)

Distance

• Distance is of crucial importance in K-means. So what kind of properties should the distance measure have?

- Symmetric
 - D(A,B) = D(B,A)
- Positivity, and self-similarity
 - $D(A,B) \ge 0$, and D(A,B) = 0 iff A = B
- Triangle inequality
 - $D(A,B) + D(B,C) \ge D(A,C)$

Convergence of K-means

Objective

$$\min_{\mu} \min_{C} \sum_{i=1}^{k} \sum_{x \in C_i} |x - \mu_i|^2$$

1. Fix μ , optimize C:

optimize
$$C$$
:
$$\min_{C} \sum_{i=1}^{k} \sum_{x \in C_{i}} |x - \mu_{i}|^{2} = \min_{C} \sum_{i} |x_{i} - \mu_{x_{i}}|^{2}$$

2. Fix C, optimize μ :

$$\min_{\mu} \sum_{i=1}^k \sum_{x \in C_i} |x - \mu_i|^2$$

– Take partial derivative of μ_i and set to zero, we have

Not guaranteed to converge to optimal

$$\mu_i = \frac{1}{|C_i|} \sum_{x \in C_i} x$$

Step 2 of kmeans

Kmeans takes an alternating optimization approach, each step is guaranteed to decrease the objective – thus guaranteed to converge

Application: Segmentation

 Goal of segmentation is to partition an image into regions each of which has reasonably homogenous visual appearance

Cluster the colors













8%



17%

