

Simulation Based Inference (Part I)

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Outline

Motivation

Monte Carlo

Important Sampling

Conclusion

Why Simulation Based Inference

- In statistics, direct calculation of the moments of a random variable is usually not feasible.

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Why Simulation Based Inference

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- ▶ This is even expensive in Bayesian statistics because posterior distributions are usually not simple distributions.
- ▶ Applied widely in finance and financial econometrics.
- ▶ Sometimes are time consuming. C/C++, MATLAB call C, or R call C have to be used.

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Sometimes we can but most of times we can't get this done analytically.

- ▶ If we can decompose $f(x) = h(x)p(x)$, where $p(x)$ is a simple probability density function (pdf), then we have

$$\int_a^b f(x)dx = \int_a^b h(x)p(x)dx = \mathbb{E}_{p(x)}[h(x)]$$

Why MC Works?

Law of Large Numbers (LLN)

- ▶ Given an independent and identically distributed (iid) sequence of random variables Y_1, Y_2, \dots, Y_n with $\bar{Y}_n = n^{-1} \sum_{i=1}^n Y_i$ and $E(Y_i) = \mu$, then for any $\epsilon > 0$ we have

$$P(|\bar{Y}_n - \mu| > \epsilon) \rightarrow 0$$

as $n \rightarrow \infty$.

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as $n \rightarrow \infty$.

- ▶ According to LLN, as $n \rightarrow \infty$, \bar{Y}_n will close to μ , and the approximation will be more accurate.

MC for integral

- If we can generate a random sample $\{x_1, \dots, x_n\}$ from $p(x)$, then

$$\int_a^b f(x)dx = \int_a^b h(x)p(x)dx = \mathbb{E}_{p(x)}[h(x)] \approx \frac{1}{n} \sum_{i=1}^n h(x_i)$$

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- ▶ A simple case. Integrating a function of $f(x)$ over $[a, b]$ is nothing else than computing the mean of $f(x)$ assuming that $x \sim U[0, 1]$, then

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- ▶ If we can simulate a random variable X over many times from its distribution, we will know almost everything about X .

Monte Carlo Integration in Bayesian Statistics

- In Bayesian inference, MC integration can be used to approximate posterior distribution

$$I(y) = \int_a^b f(y|x)p(x)dx \approx \hat{I}(y) = \frac{1}{n} \sum_{i=1}^n f(y|x_i)$$

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$$\text{SE}^2[\hat{I}(y)] = \frac{1}{n} \left(\frac{1}{n-1} \sum_{i=1}^n \left(f(y|x_i) - \hat{I}(y) \right)^2 \right)$$

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- ▶ This is often used to fit latent state time series models where the augmented parameters are highly correlated.
- ▶ This is also widely applied in particle filter methods in terms of one-step and multi-step ahead forecasting.

Example 1 – with a Normal distribution

- Suppose we want to calculate the expectation of $g(x) = x^d, d \in \mathbb{R}$, where $x \sim N(0, \sigma^2)$ with pdf $p(x) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right)$ truncated in $[a, b]$.

$$\begin{aligned} \mathbb{E}[g(x)] &= \int_a^b g(x)p(x)dx \\ &= \int_a^b x^d \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right) dx \end{aligned}$$

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- We can simulate either the normal distribution or a uniform distribution over $[a, b]$.

$$E[g(x)] = \int_a^b \frac{b-a}{\sqrt{2\pi}\sigma} x^d \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right) \frac{1}{b-a} dx$$

Example 1 – with a Normal distribution (Cont'd)

Table: Estimate the expectation of $g(X) = X$ with $X \sim N(0, 1)$

	$N(0, 1)$		$U[-5, 5]$	
n	Average	SD	Average	SD
5000	0.009268	1.00122	0.014602	1.176178
10,000	0.006634	0.99461	-0.002638	1.180575
15,000	-0.004639	0.99906	0.013984	1.197937
20,000	0.003777	0.99015	0.010644	1.182507

Example 1 – with a Normal distribution (Cont'd)

Table: Estimate the expectation of $g(X) = X^2$ with $X \sim N(0, 1)$

	$N(0, 1)$		$U[-7, 7]$	
n	Average	SD	Average	SD
5000	1.00234	1.4116	0.9809	1.3898
10,000	0.98920	1.4030	0.9879	1.3928
15,000	0.99809	1.3942	1.0172	1.4101
20,000	0.98037	1.3954	0.9916	1.3963

Example 2 – with a Gamma distribution

- Suppose we want to calculate the expectation of $g(x) = x^d$, where $x \sim \text{Gamma}(\alpha, \beta)$ with pdf $p(x) = \frac{1}{\Gamma(\alpha)\beta^\alpha} x^{\alpha-1} \exp\left(-\frac{x}{\beta}\right)$ truncated in $[a, b]$.

$$\begin{aligned} \mathbb{E}[g(x)] &= \int_a^b g(x)f(x)dx \\ &= \int_a^b x^d \frac{1}{\Gamma(\alpha)\beta^\alpha} x^{\alpha-1} \exp\left(-\frac{x}{\beta}\right) dx \end{aligned}$$

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- We can simulate either the normal distribution or a uniform distribution on $[a, b]$.

$$\mathbb{E}[g(x)] = \int_a^b \frac{b-a}{\Gamma(\alpha)\beta^\alpha} x^{d+\alpha-1} \exp\left(-\frac{x}{\beta}\right) \frac{1}{b-a} dx$$

Example 2 – with a Gamma distribution (Cont'd)

Table: Estimate the expectation of $g(X) = X$ with $X \sim \text{Gamma}(1, 0.5)$

n	$\text{Gamma}(1, 0.5)$		$U[0, 5]$	
	Average	SD	Average	SD
5000	0.50094	0.50042	0.49119	0.60671
10,000	0.49756	0.49354	0.49277	0.60859
15,000	0.50293	0.50395	0.49519	0.61078
20,000	0.50148	0.50725	0.49931	0.61285

Example 3 – Value at risk (VaR)

- Suppose we want to estimate $F_Y(y) = P(Y \geq y) = E[I_{[y, +\infty)}(Y)]$, where $Y \sim N(0, 1)$.

$$\begin{aligned} E[I_{[y, +\infty)}(Y)] &= \int_y^{+\infty} \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right) dx \\ &= \int_{-\infty}^{+\infty} h(x) \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right) dx \end{aligned}$$

where $h(x) = 0$ if $x < y$ and $h(x) = 1$ if $x \geq y$.

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where $h(x) = 0$ if $x < y$ and $h(x) = 1$ if $x \geq y$.

- Draw an iid sample $\{Y_1, \dots, Y_n\}$ from $N(0, 1)$, then the estimator is

$$E[I_{[y, +\infty)}(Y)] = \frac{1}{n} \sum_{i=1}^n h(Y_i) = \frac{\# \text{ of draws } \geq y}{n}$$

Example 4 – how to calculate π ?

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- ▶ The pdf of X and Y is $f(x, y) = 1/4, -1 \leq x \leq 1, -1 \leq y \leq 1$.
- ▶ Define $h(x, y) = 1$ if $x^2 + y^2 \leq 1$ and $h(x, y) = 0$ otherwise.
- ▶ Draw an iid sample $\{(x_1, y_1), \dots, (x_n, y_n)\}$ from $X \sim U(-1, 1)$ and $Y \sim U(-1, 1)$, then the estimator is

$$\pi = E[h(x, y)] \approx \frac{4}{n} \sum_{i=1}^n h(x_i, y_i) = \frac{4 * (\# \text{ of draws satisfying } x_i^2 + y_i^2 \leq 1)}{n}$$

Example 4 – how to calculate π ? (Cont'd)

Table: Estimate π

n	MC	SD
5000	3.056	0.0034
1000	3.224	0.0016
1500	3.211	0.0011
2000	3.136	0.0008
50000000	3.133	8.240823e-05

Why Important Sampling (IS)?

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- ▶ Suppose the density $p(x)$ roughly approximates the density (of interest) $q(x)$, then

$$\int_a^b f(x)q(x)dx = \int_a^b f(x)\left(\frac{q(x)}{p(x)}\right)p(x)dx = E_{p(x)}\left[f(x)\left(\frac{q(x)}{p(x)}\right)\right]$$

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- ▶ Give a sample $\{x_i, i = 1, \dots, n\}$ drawn from $p(x)$, the IS estimator is

$$\int_a^b f(x)q(x)dx \approx \frac{1}{n} \sum_{i=1}^n f(x_i) \left(\frac{q(x_i)}{p(x_i)}\right)$$

Why Important Sampling (IS)?

- In Bayesian statistics, we have,

$$J(y) = \int_a^b f(y|x)q(x)dx,$$

which can be approximated by

$$J(y) \approx \frac{1}{n} \sum_{i=1}^n f(y|x_i) \left(\frac{q(x_i)}{p(x_i)} \right).$$

An alternative

- An alternative formulation of IS is

$$\int_a^b f(x)q(x)dx \approx \hat{I}(x) = \frac{1}{n} \sum_{i=1}^n \omega_i f(x_i) / \sum_{i=1}^n \omega_i, \text{ where } \omega_i = \frac{q(x_i)}{p(x_i)},$$

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which is called weighted average.

- The associated MC variance is

$$\text{Var}(\hat{I}) = \frac{1}{n} \sum_{i=1}^n \omega_i (f(x_i) - \hat{I}(x))^2 / \sum_{i=1}^n \omega_i$$

Example 3 – Value at risk (VaR) (Cont'd)

- Suppose we want to estimate $P(Y \geq 3)$, where $Y \sim N(0, 1)$.

$$P(Y \geq 3) = \int_3^{+\infty} \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right) dx = \int_{-\infty}^{+\infty} h(x) \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right) dx,$$

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where $h(x) = 0$ if $x < 3$ and $h(x) = 1$ if $x \geq 3$.

- Draw an iid sample $\{y_1, \dots, y_n\}$ from $N(\mu, 1)$, then the estimator is

$$E[I_{[3, +\infty)}(Y)] \approx \frac{1}{n} \sum_{i=1}^n \frac{h(y_i)f(y_i)}{g(y_i)},$$

where $f(y)$ is the density of $N(0, 1)$ and $g(y)$ is the density of $N(\mu, 1)$.

Example 3 – Value at risk (VaR) (Cont'd)

Table: Estimate $p(Y > 3) = 0.001349898$

	$\mu = 0$	$\mu = 3$	$\mu = 4$
n	Average	Average	Average
5000	0.001	0.001352	0.001352
10,000	0.0016	0.001296	0.001295
15,000	0.0007	0.001394	0.001372
20,000	0.0013	0.001389	0.001389

Example 4

- Suppose we want to calculate the expectation of $g(X) = \exp\left(-\frac{1}{2\exp(X)}\right)$, where $X \sim N(\mu, \sigma^2)$ with pdf $f(X)$.

$$\begin{aligned} E[g(X)] &= \int_{-\infty}^{+\infty} g(x)f(x)dx \\ &= \int_{-\infty}^{+\infty} \exp\left(-\frac{1}{2\exp(x)}\right) \frac{1}{\sqrt{2\pi}\sigma^2} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right) dx \end{aligned}$$

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- Notice that $\exp(-x)$ is a convex function which is bounded above by a linear function of μ . By taking Taylor expansion for $\exp(-x)$ at μ we get

$$\log(g(x)) = -\frac{1}{2}e^{-x} \leq -\frac{1}{2}[\exp(-\mu)(1 + \mu) - x \exp(-\mu)]$$

Example 4 (Cont'd)

- Then we get

$$g(x) * f(x) \leq \exp \left(-\frac{1}{2} [\exp(-\mu)(1 + \mu) - x \exp(-\mu)] \right) \\ \times \frac{1}{\sqrt{2\pi}\sigma^2} \exp \left(-\frac{(x - \mu)^2}{2\sigma^2} \right)$$

Example 4 (Cont'd)

- ▶ Then we get

$$g(x) * f(x) \leq \exp \left(-\frac{1}{2} [\exp(-\mu)(1 + \mu) - x \exp(-\mu)] \right) \\ \times \frac{1}{\sqrt{2\pi}\sigma^2} \exp \left(-\frac{(x - \mu)^2}{2\sigma^2} \right)$$

- ▶ After eliminating some constant terms, we get

$$g(x) * f(x) \leq k \cdot f_N \left(\mu + \frac{\sigma^2}{2} \exp(\mu), \sigma^2 \right) \stackrel{\text{def}}{=} k \cdot f^*$$

Example 4 (Cont'd)

- ▶ The expectation of $g(X)$ is

$$\begin{aligned} \mathbb{E}[g(X)] &= \int_{-\infty}^{\infty} g(x) \left(\frac{f(x)}{f^*(x)} \right) f^*(x) dx = \mathbb{E}_{f^*(x)} \left[g(x) \left(\frac{f(x)}{f^*(x)} \right) \right] \\ &\approx \frac{1}{n} \sum_{i=1}^n \frac{g(x_i) f(x_i)}{f^*(x_i)} \end{aligned}$$

Example 4 (Cont'd)

Table: Estimate $g(X) = \exp\left(-\frac{1}{2\exp(X)}\right)$ with $X \sim N(3, 1)$

	IS	MC
n	Average	Average
5000	0.96089	0.96113
10,000	0.96125	0.96140
15,000	0.96088	0.96078
20,000	0.96146	0.96154

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- ▶ The assumption in this talk is that we can simulate a target distribution directly.
- ▶ Monte Carlo methods are useful for obtaining integrals, especially for truncated distributions.
- ▶ Important sampling is even useful for integrals with complicated functions.
- ▶ MC and IS are widely used in financial engineering.

Thank you!

References

- [1] McLeish, D. L. Monte Carlo Simulation and Finance. Wiley, New York (2005) ([full text](#)).
- [2] McLeish, D. L. and Z. Men. 2015. Extreme Value Importance Sampling for Rare Event Risk Measurement. K. Glau et al. (eds.), Innovations in Quantitative Risk Management. Springer Proceedings in Mathematics & Statistics. Volume 99, 2015, pp 317-335. ([full text](#)).
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