Simulation Based Inference: Gibbs Sampling

Chris Men

chrismen4@gmail.com

September 29, 2017

Outline

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Summary

▶ In statistics, direct maximum likelihood estimation (MLE) algorithms sometimes are difficult to derive.

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- ▶ Gibbs sampling is an alternative of the expectation-maximization (EM), and most of times is much easier to implement.
- ▶ Applied widely in finance and financial econometrics.
- Sometimes are time consuming. C/C++, MATLAB call C, or R call C have to be used.

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- Gibbs sampling generates correlated time series.
- ▶ A burn in period is needed before performing inference.
- The joint distribution is not known explicitly or is difficult to sample from directly.

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- ▶ We have generated a sample $\{\theta_i^{(1)}, ..., \theta_i^{(L)}\}$ from the conditional distribution of θ_i .
- ▶ The estimate of θ_i is

$$\hat{\theta}_i = \frac{1}{L-l} \sum_{k=l+1}^{L} \theta_i^{(k)},$$

where the first l generated numbers are discarded as burn in.

Gibbs Algorithm (cont'd)

Table: Gibbs algorithm.

$$\begin{array}{ll} \textbf{Step 0}. & \textbf{Initialize } \{\theta_1^{(0)},...,\theta_m^{(0)}\}, \textbf{ set } k = 0. \\ \textbf{Step 1}. & \textbf{Sample } \theta_1^{(k+1)}|\theta_2^{(k)},...,\theta_m^{(k)}. \\ & \textbf{Sample } \theta_2^{(k+1)}|\theta_1^{(k+1)},\theta_3^{(k)},...,\theta_m^{(k)}. \\ & \cdot \\ & \cdot \\ & \textbf{Sample } \theta_m^{(k+1)}|\theta_1^{(k+1)},\theta_2^{(k+1)},...,\theta_{m-1}^{(k+1)}. \\ \textbf{Step 2}. & \textbf{Go to Step 1}. \end{array}$$

 Gibbs sampler generates posterior samples by sweeping through each variable to sample from its conditional distribution with the remaining variables fixed to their current values.

Example 1 – fit a univariate normal distribution

▶ Suppose that we have a data set $\mathbf{y} = \{y_i, i = 1, ..., n\}$, which is generated from a univariate normal distribution $y \sim N(\mu, \sigma^2)$ with pdf $p(y) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(y-\mu)^2}{2\sigma^2}\right)$.

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- ▶ The likelihood of the data based on the model is

$$f(\mathbf{y}|\mu,\sigma^2) = \prod_{i=1}^n f(y_i|\mu,\sigma^2) \propto \left(\frac{1}{\sigma^2}\right)^{\frac{n}{2}} \exp\left(-\frac{\sum_{i=1}^n (y_i-\mu)^2}{2\sigma^2}\right)$$

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▶ The posterior distribution of the two parameters μ and σ^2 is

$$\begin{split} f(\mu, \sigma^2 | \mathbf{y}) &\propto f(\mu | \mu_*, \sigma_*^2) \mathrm{IG}(\sigma^2 | \alpha_\sigma, \beta_\sigma) \Pi_{i=1}^n f(y_i | \mu, \sigma^2) \\ &\propto \left(\frac{1}{\sigma_*^2}\right)^{\frac{1}{2}} \exp\left(-\frac{(\mu - \mu_*)^2}{2\sigma_*^2}\right) \frac{(\beta_\sigma)^{\alpha_\sigma} e^{-\beta_\sigma/\sigma^2}}{\Gamma(\alpha_\sigma)(\sigma^2)^{\alpha_\sigma + 1}} \\ &\times \left(\frac{1}{\sigma^2}\right)^{\frac{n}{2}} \exp\left(-\frac{\sum_{i=1}^n (y_i - \mu)^2}{2\sigma^2}\right), \end{split}$$

where $f(\mu|\mu_*, \sigma_*^2)$ and $IG(\sigma^2|\alpha_\sigma, \beta_\sigma)$ are two prior distributions.

Example 1 – fit a univariate normal distribution (Cont'd) – simulate μ

▶ The conditional distribution of μ is

$$f(\mu|\sigma^2, \mathbf{y}) \propto \exp\left(-\frac{(\mu - \mu_*)^2}{2\sigma_*^2}\right) \exp\left(-\frac{\sum_{i=1}^n (y_i - \mu)^2}{2\sigma^2}\right)$$
$$\propto \exp\left(-\frac{1}{2}\left[\mu^2\left(\frac{1}{\sigma_*^2} + \frac{n}{\sigma^2}\right) - 2\mu\left[\frac{\mu_*}{\sigma_*^2} + \frac{\sum_{i=1}^n y_i}{\sigma^2}\right]\right)$$

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▶ The conditional distribution of μ is then

$$f(\mu|\sigma^2, \mathbf{y}) \sim N\left(\frac{B}{A}, \frac{1}{A}\right)$$

where

$$B = \frac{\mu_*}{\sigma_*^2} + \frac{\sum_{i=1}^n y_i}{\sigma_*^2}, A = \frac{1}{\sigma_*^2} + \frac{n}{\sigma_*^2}$$

Example 1 – fit a univariate normal distribution (Cont'd) – simulate σ^2

▶ The conditional distribution of σ^2 is

$$f(\sigma^{2}|\mu,\mathbf{y}) \propto \frac{(\beta_{\sigma})^{\alpha_{\sigma}} e^{-\beta_{\sigma}/\sigma^{2}}}{\Gamma(\alpha_{\sigma})(\sigma^{2})^{\alpha_{\sigma}+1}} \left(\frac{1}{\sigma^{2}}\right)^{\frac{n}{2}} \exp\left(-\frac{\sum_{i=1}^{n} (y_{i}-\mu)^{2}}{2\sigma^{2}}\right)$$

$$\propto \frac{e^{-\beta_{\sigma}/\sigma^{2}}}{(\sigma^{2})^{\alpha_{\sigma}+1}} \left(\frac{1}{\sigma^{2}}\right)^{\frac{n}{2}} \exp\left(-\frac{\sum_{i=1}^{n} (y_{i}-\mu)^{2}}{2\sigma^{2}}\right)$$

$$\propto \left(\frac{1}{\sigma^{2}}\right)^{(\alpha_{\sigma}+\frac{n}{2})+1} \exp\left(-\frac{\beta_{\sigma}+\frac{1}{2}\sum_{i=1}^{n} (y_{i}-\mu)^{2}}{\sigma^{2}}\right)$$

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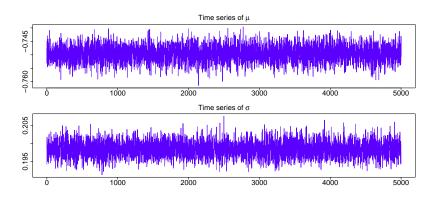
▶ The conditional distribution of σ^2 is

$$f(\sigma^2|\mu, \mathbf{y}) \sim \mathrm{IG}(\hat{\alpha}_{\sigma}, \hat{\beta}_{\sigma})$$

where

$$\hat{\alpha}_{\sigma} = \alpha_{\sigma} + \frac{n}{2}, \hat{\beta}_{\sigma} = \beta_{\sigma} + \frac{1}{2} \sum_{i=1}^{n} (y_i - \mu)^2$$

Example 1 – fit a univariate normal distribution (Cont'd) – sampled time series



The algorithm was iterated 5000 times to fit a data set artificially generated from $N(-0.75, 0.2^2)$.

Example 1 – fit a univariate normal distribution (Cont'd)

Table: Estimate μ and σ of a normal distribution $N(\mu, \sigma^2)$.

		Case 1			Case 2	
Parameter	True	Average	SD	True	Average	SD
μ	-0.75	-0.7495	0.00307	0.5	0.48144	0.03935
σ	0.2	0.1984	0.00223	2.5	2.51564	0.02814

The Gibbs algorithm was iterated 5000 times. After the first 500 iterations were discarded, parameters were estimated by sample means.

▶ Suppose that we have a data set $\mathbf{y} = \{y_i, i = 1, ..., n\}$, which is generated from a mixture of two normal distributions.

$$f(y) = \rho \times f_1(y|\mu_1, \sigma_1^2) + (1 - \rho) \times f_2(y|\mu_2, \sigma_2^2),$$

where $0 < \rho < 1$. The comment functions $f_i(y|\mu_i, \sigma_i^2)$, i = 1, 2, are normal pdfs.

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- For the distribution to be identifiable, we assume that $\mu_1 < \mu_2$ and $\sigma_1^2 < \sigma_2^2$.
- ▶ The likelihood of the proposed model takes a complicated form.
- ▶ To simplify this, we introduce latent variables $\mathbf{z} = (z_1, ..., z_n)$, which are defined below,

$$z_i = \begin{cases} 0, & \text{with probability } \rho, \\ 1, & \text{with probability } 1 - \rho, \end{cases}$$

for i = 1, ..., n.

► Conditional on these latent variables, we have

$$y_i|\theta \sim \left\{ \begin{array}{ll} \mathcal{N}(\mu_1, \sigma_1^2), & \text{if } z_i = 0, \\ \mathcal{N}(\mu_2, \sigma_2^2), & \text{if } z_i = 1. \end{array} \right.$$

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► The likelihood of the data y given the model separates into two parts, each of them corresponding to each of the two mixture components,

$$l(\theta|\mathbf{y}, \mathbf{z}) \propto \prod_{i=1, z_i=0}^{n} \frac{\rho}{\sigma_1} \exp\left\{-\frac{1}{2} \frac{(y_i - \mu_1)^2}{\sigma_1^2}\right\}$$
$$\prod_{i=1, z_i=1}^{n} \frac{(1-\rho)}{\sigma_2} \exp\left\{-\frac{1}{2} \frac{(y_i - \mu_2)^2}{\sigma_2^2}\right\}$$

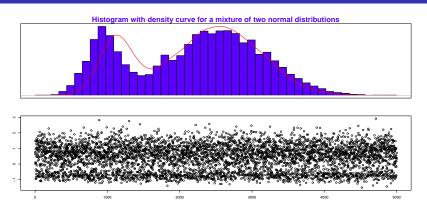


Figure: The data was generated from a mixture of two normal distributions with pdf: $f(y) = 0.25 \times f_1(y| -0.75, 0.2^2) + 0.75 \times f_2(y|0.75, 0.6^2)$

Table: The Gibbs estimation procedure.

```
Step 0. Initialize \mu_1, \mu_2, \sigma_1, \sigma_2 and \rho.
```

Step 1. Sample
$$z_i, i = 1, ..., n$$
.

Step 2. Sample
$$\rho$$
.

Step 3. Sample
$$\mu_1, \sigma_1^2$$
.

Step 4. Sample
$$\mu_2$$
, σ_2^2 .

Step 1. The conditional probability that the observed y_i has been generated by the first mixture component is

$$f(z_i = 0 | \mathbf{y}, \theta) = \frac{\frac{\rho}{\sigma_1} \exp\left\{-\frac{1}{2} \frac{(y_i - \mu_1)^2}{\sigma_1^2}\right\}}{\frac{\rho}{\sigma_1} \exp\left\{-\frac{1}{2} \frac{(y_i - \mu_1)^2}{\sigma_1^2}\right\} + \frac{(1 - \rho)}{\sigma_2} \exp\left\{-\frac{1}{2} \frac{(y_i - \mu_2)^2}{\sigma_2^2}\right\}}.$$

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▶ The simulation of the latent variables z_i , i = 1, ..., n, can be carried out by simulating Bernoulli distributions.

Step 2. The conditional posterior density of $f(\rho|\theta_{-\rho}, \mathbf{y}, \mathbf{z})$, where $\theta_{-\rho}$ denotes the remaining parameters except ρ , has the following kernel,

$$f(\rho|\mathbf{y}, \theta_{-\rho}, \mathbf{z}) \propto \rho^{T_0} (1-\rho)^{T_1},$$

where $T_k = \#\{z_i = k\}, k = 0, 1$, the number of observations assigned to the k-th component.

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where $T_k = \#\{z_i = k\}, k = 0, 1$, the number of observations assigned to the k-th component.

▶ It is obvious that $\rho \sim \text{Beta}(T_0 + 1, T_1 + 1)$, and the simulation of ρ is easier to carry out.

Step 3. The conditional distribution of μ_1 is

$$f(\mu_{1}|\mathbf{y}, \theta_{-\mu_{1}}, \mathbf{z})$$

$$\propto \prod_{i=1, z_{i}=0}^{n} \exp\left\{-\frac{1}{2} \frac{(y_{i} - \mu_{1})^{2}}{\sigma_{1}^{2}}\right\}$$

$$\propto \exp\left\{-\frac{1}{2} \left[\frac{T_{0}}{\sigma_{1}^{2}} \mu_{1}^{2} - 2 \frac{\mu_{1}}{\sigma_{1}^{2}} \sum_{i=1, z_{i}=0}^{n} y_{i}\right]\right\}.$$

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$$\propto \prod_{i=1, z_{i}=0}^{n} \exp \left\{ -\frac{1}{2} \frac{(y_{i} - \mu_{1})^{2}}{\sigma_{1}^{2}} \right\}$$

$$\propto \exp \left\{ -\frac{1}{2} \left[\frac{T_{0}}{\sigma_{1}^{2}} \mu_{1}^{2} - 2 \frac{\mu_{1}}{\sigma_{1}^{2}} \sum_{i=1, z_{i}=0}^{n} y_{i} \right] \right\}.$$

▶ It is easier to see that $\mu_1 \sim \mathcal{N}(\frac{b_1}{a_1}, \frac{1}{a_1})$, where

$$a_1 = \frac{T_0}{\sigma_1^2}, \quad b_1 = \frac{1}{\sigma_1^2} \sum_{i=1}^n y_i.$$

Step 4. Given an Inverse Gamma prior distribution $\sigma_1^2 \sim \mathcal{I}G(\alpha, \delta)$, the conditional distribution of σ_1^2 is

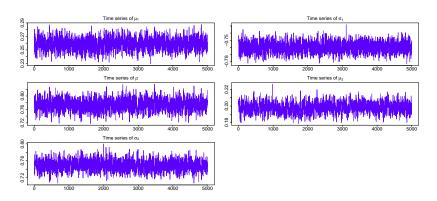
$$f(\sigma_1^2|\mathbf{y}, \mathbf{z}, \theta_{\sigma_1^2}) \propto \frac{1}{(\sigma_1^2)^{\alpha+1}} \exp\left\{-\frac{\delta}{\sigma_1^2}\right\} \prod_{i=1, z_i=0}^n \frac{1}{\sigma_1^2} \exp\left\{-\frac{1}{2} \frac{(y_i - \mu_1)^2}{\sigma_1^2}\right\}$$
$$\propto \frac{1}{(\sigma_1^2)^{\alpha+1+T_0/2}} \exp\left\{-\frac{\delta + \frac{1}{2} \sum_{i=1, z_i=0}^n (y_i - \mu_1)^2}{\sigma_1^2}\right\}.$$

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$$f(\sigma_1^2|\mathbf{y}, \mathbf{z}, \theta_{\sigma_1^2}) \propto \frac{1}{(\sigma_1^2)^{\alpha+1}} \exp\left\{-\frac{\delta}{\sigma_1^2}\right\} \prod_{i=1, z_i=0}^n \frac{1}{\sigma_1^2} \exp\left\{-\frac{1}{2} \frac{(y_i - \mu_1)^2}{\sigma_1^2}\right\}$$
$$\propto \frac{1}{(\sigma_1^2)^{\alpha+1+T_0/2}} \exp\left\{-\frac{\delta + \frac{1}{2} \sum_{i=1, z_i=0}^n (y_i - \mu_1)^2}{\sigma_1^2}\right\}.$$

It is seen that $\sigma_1^2 \sim \mathcal{I}G(c,d)$, where $c = \alpha + T_0/2$ and $d = \delta + \frac{1}{2} \sum_{i=1, z_i=0}^n (y_i - \mu_1)^2$, respectively.

Example 2 – fit a mixture of two normal distributions – sampled time series



The algorithm was iterated 5000 times to fit a data set artificially generated from $0.25 \times N(-0.75, 0.2^2) + (1 - 0.25) \times N(0.75, 0.6^2)$.

Table: Fit a mixture distribution: $\rho \times N(\mu_1, \sigma_1^2) + (1 - \rho) \times N(\mu_2, \sigma_2^2)$.

		Case 1			Case 2	
Parameter	True	Average	SD	True	Average	SD
μ_1	-0.75	-0.7624	0.0075	0.25	0.2451	0.0048
σ_1	0.2	0.2023	0.0059	0.2	0.1943	0.0045
ho	0.25	0.2439	0.0077	0.5	0.4913	0.0100
μ_2	0.75	0.7241	0.0128	1.25	1.2096	0.0271
σ_2	0.6	0.6187	0.0098	1.2	1.2061	0.0169

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- ▶ Gibbs algorithms are usually easier to implement.
- ▶ Gibbs methods are widely used in solving time series models.
- Mixture distributions can be imposed to time series and non-time series models.

Motivation Gibbs Algorithm Examples Summary

Thank you!

References

- [1] Robert, C. and G., Casella. 2013. Monte Carlo Statistical Methods: Edition 2. London: Chapman and Hall.
- [2] Gilks, W. R., Richardson, S., and Spiegelhalter, D. J. 1995. Markov Chain Monte Carlo in Practice. London: Chapman and Hall.
- [3] Paul Glasserman. 2013. Monte Carlo Methods in Financial Engineering (Stochastic Modelling and Applied Probability). (Springer).