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CSE 461

Lab 2

B-Tree Implementation

1. B-Tree

Source Code:

```
// C++ program for B-Tree insertion
// For simplicity, assume order  $m = 2 * t$ 
#include<iostream>
#include<fstream>
using namespace std;

//forward declaration
template <class keyType>
class BTree;

// A BTree node
template <class keyType>
class Node
{
private:
    keyType *keys;    // An array of keys
    int t;            //  $m = 2 * t$ 
    Node<keyType> **C; // An array of child pointers
    int nKeys;        // Current number of keys
    bool isLeaf;      // Is true when node is leaf. Otherwise false
public:
    Node(int _t, bool _isLeaf); // Constructor

    // Inserting a new key in the subtree rooted with
    // this node. The node must be non-full when this
    // function is called
    void insertNonFull(keyType k);
```

```
// Splitting the child y of this node. i is index of y in  
// child array C[]. The Child y must be full when this function is called  
void splitChild(int i, Node<keyType> *y);
```

```
// Traversing all nodes in a subtree rooted with this node  
void traverse();
```

```
// A function to search a key in subtree rooted with this node.  
Node *search(keyType k); // returns NULL if k is not present.
```

```
// A function that returns the index of the first key that is greater  
// or equal to k  
int findKey(keyType k);
```

```
// A wrapper function to remove the key k in subtree rooted with  
// this node.  
void remove(keyType k);
```

```
// A function to remove the key present in idx-th position in  
// this node which is a leaf  
void removeFromLeaf(int index);
```

```
// A function to remove the key present in idx-th position in  
// this node which is a non-leaf node  
void removeFromNonLeaf(int index);
```

```
// A function to get the predecessor of the key- where the key  
// is present in the idx-th position in the node  
keyType getPred(int index);
```

```
// A function to get the successor of the key- where the key  
// is present in the idx-th position in the node  
keyType getSucc(int index);
```

```
// A function to fill up the child node present in the idx-th  
// position in the C[] array if that child has less than t-1 keys  
void fill(int index);
```

```

// A function to borrow a key from the C[idx-1]-th node and place
// it in C[idx]th node
void promoteFromPrev(int index);

// A function to borrow a key from the C[idx+1]-th node and place it
// in C[idx]th node
void promoteFromNext(int index);

// A function to merge idx-th child of the node with (idx+1)th child of
// the node
void merge(int index);

// Make BTree friend of this so that we can access private members of this
// class in BTree functions
friend class BTree<keyType>;
};

// A BTree
template <class keyType>
class BTree
{
private:
    Node<keyType> *root; // Pointer to root node
    int t;              // Minimum degree
public:
    // Constructor (Initializes tree as empty)
    BTree(int t0 )
    { root = NULL; t = t0; }

    // function to traverse the tree
    void traverse()
    { if (root != NULL) root->traverse(); }

    // function to search a key in this tree
    //Node<int>* search(keyType k)
    Node<keyType>* search(keyType k)
    { return (root == NULL)? NULL : root->search(k); }

    // The main function that inserts a new key in this B-Tree

```

```

//void insert(keyType k);
void insert(keyType k);

// The main function that removes a new key in this B-Tree
void remove(keyType k);
};

// Constructor for Node class
template<class keyType>
Node<keyType>::Node(int t0, bool isLeaf0)
{
    // Copy the given minimum degree and leaf property
    t = t0;
    isLeaf = isLeaf0;

    // Allocate memory for maximum number of possible keys
    // and child pointers
    keys = new keyType[2*t-1];
    C = new Node<keyType> *[2*t];

    // Initialize the number of keys as 0
    nKeys = 0;
}

// Traverse all nodes in a subtree rooted at this node
template<class keyType>
void Node<keyType>::traverse()
{
    // Depth-first traversal
    // There are nKeys keys and nKeys+1 children, traverse through nKeys keys
    // and first nKeys children
    for (int i = 0; i < nKeys; i++)
    {
        // If this is not leaf, then before printing key[i],
        // traverse the subtree rooted at child C[i].
        if (isLeaf == false)
            C[i]->traverse();
        cout << " " << keys[i];
    }
}

```

```

    // Print the subtree rooted with last child
    if (isLeaf == false)
        C[nKeys]->traverse();
}

// Search key k in subtree rooted with this node
template<class keyType>
Node<keyType> *Node<keyType>::search(keyType k)
{
    // Find the first key >= k
    int i = 0;
    while (i < nKeys && k > keys[i])
        i++;

    // If the found key is equal to k, return this node
    if ( i < nKeys ) // added by Tong
        if (keys[i] == k)
            return this;

    // If key is not found here and this is a Leaf node
    if (isLeaf == true)
        return NULL;

    // Go to the appropriate child
    return C[i]->search(k);
}

// The main function that inserts a new key in this B-Tree
template <class keyType>
void BTree<keyType>::insert( keyType k)
{
    // If tree is empty
    if (root == NULL)
    {
        // Allocate memory for root
        root = new Node<keyType>(t, true);
        root->keys[0] = k; // Insert key
        root->nKeys = 1; // Update number of keys in root
    }
}

```

```

    }
    else // If tree is not empty
    {
        // If root is full, then tree grows in height
        if (root->nKeys == 2*t-1)
        {
            // Allocate memory for new root
            Node<keyType> *s = new Node<keyType>(t, false);

            // Make old root as child of new root
            s->C[0] = root;

            // Split the old root and move 1 key to the new root
            s->splitChild(0, root);

            // New root has two children now. Decide which of the
            // two children is going to have new key
            int i = 0;
            if (s->keys[0] < k)
                i++;
            s->C[i]->insertNonFull(k);

            // Change root
            root = s;
        }
        else // If root is not full, call insertNonFull for root
            root->insertNonFull(k);
    }
}

```

// A utility function to insert a new key in this node
 // The assumption is, the node must be non-full when this
 // function is called

```

template <class keyType>
void Node<keyType>::insertNonFull(keyType k)
{
    // Initialize index as index of rightmost element
    int i = nKeys-1;

```

```

// If this is a Leaf node
if (isLeaf == true)
{
    // The following loop does two things
    // a) Finds the location of new key to be inserted
    // b) Moves all greater keys to one place ahead
    while (i >= 0 && keys[i] > k)
    {
        keys[i+1] = keys[i];
        i--;
    }

    // Insert the new key at found location
    keys[i+1] = k;
    nKeys++;
}
else // If this node is not Leaf
{
    // Find the child which is going to have the new key
    while (i >= 0 && keys[i] > k)
        i--;

    // See if the found child is full
    if (C[i+1]->nKeys == 2*t-1)
    {
        // If the child is full, then split it
        splitChild(i+1, C[i+1]);

        // After split, the middle key of C[i] goes up and
        // C[i] is splitted into two. See which of the two
        // is going to have the new key
        if (keys[i+1] < k)
            i++;
    }
    C[i+1]->insertNonFull(k);
}
}

```

// Splitting the child y of this node

```

// Note that y must be full when this function is called
template<class keyType>
void Node<keyType>::splitChild(int i, Node *y)
{
    // Create a new node which is going to store (t-1) keys
    // of y
    Node *z = new Node(y->t, y->isLeaf);
    z->nKeys = t - 1;

    // Copy the last (t-1) keys of y to z
    for (int j = 0; j < t-1; j++)
        z->keys[j] = y->keys[j+t];

    // Copy the last t children of y to z
    if (y->isLeaf == false)
    {
        for (int j = 0; j < t; j++)
            z->C[j] = y->C[j+t];
    }

    // Reduce the number of keys in y
    y->nKeys = t - 1;

    // Since this node is going to have a new child,
    // create space of new child
    for (int j = nKeys; j >= i+1; j--)
        C[j+1] = C[j];

    // Link the new child to this node
    C[i+1] = z;

    // A key of y will move to this node. Find location of
    // new key and move all greater keys one space ahead
    for (int j = nKeys-1; j >= i; j--)
        keys[j+1] = keys[j];

    // Copy the middle key of y to this node
    keys[i] = y->keys[t-1];
}

```



```

    // Increment count of keys in this node
    nKeys++;
}

template<class keyType>
void Node<keyType>::removeFromLeaf(int index)
{
    // Shift all the keys after the index position one place
    for (int i = index+1; i < nKeys; ++i)
        keys[i-1] = keys[i];

    nKeys--;

    return;
}

template<class keyType>
void Node<keyType>::removeFromNonLeaf(int index)
{
    keyType k = keys[index];

    // If the child (C[index]) that precedes k has at least t keys,
    // find the predecessor 'pred' of k which is the rightmost key of
    // the subtree rooted at
    // C[index]. Replace k by pred and delete the rightmost key, which
    // is at a leaf ( calling remove() recursively)

    if (C[index]->nKeys >= t)
    {
        keyType pred = getPred(index);
        keys[index] = pred;
        C[index]->remove(pred);
    }

    // If the child C[index] has less than t keys, examine C[index+1].
    // If C[index+1] has at least t keys, find the successor 'succ' of k in
    // the subtree rooted at C[index+1]
    // Replace k by succ and remove succ in C[index+1]

```

```

else if (C[index+1]->nKeys >= t)
{
    keyType succ = getSucc(index);
    keys[index] = succ;
    C[index+1]->remove(succ);
}

// If both C[index] and C[index+1] has less than t keys, merge k and all of C[index+1]
// into C[index]
// Now C[index] contains 2t-1 keys
// Free C[index+1] and remove k from C[index]
else
{
    merge(index);
    C[index]->remove(k);    // remove k from C[index]
}

return;
}

```

```

// Get predecessor of keys[index]
template<class keyType>
keyType Node<keyType>::getPred(int index)
{
    // Keep moving to the rightmost node until we reach a leaf
    Node<keyType> *cur=C[index];
    while (!cur->isLeaf)
        cur = cur->C[cur->nKeys]; // rightmost child pointer

    // cur now points to a leaf node
    // Return the last key (rightmost, at position cur->nKeys-1) of the leaf
    return cur->keys[cur->nKeys-1];
}

```

```

//Get successor of keys[index]
template<class keyType>
keyType Node<keyType>::getSucc(int index)
{

```

```

// Keep moving the leftmost node starting from C[index+1] until we reach a leaf
Node<keyType> *cur = C[index+1];
while (!cur->isLeaf)
    cur = cur->C[0];

// Return the first key (leftmost) of the leaf
return cur->keys[0];
}

```

```

template<class keyType>
void Node<keyType>::merge(int index)
{
    Node<keyType> *child = C[index];
    Node<keyType> *sibling = C[index+1];

    // Pulling a key from the current node and inserting it into (t-1)th
    // position of C[index]
    child->keys[t-1] = keys[index];

    // Copying the keys from C[index+1] to C[index] at the end
    for (int i=0; i < sibling->nKeys; ++i)
        child->keys[i+t] = sibling->keys[i];

    // Copying the child pointers from C[index+1] to C[index]
    if (!child->isLeaf)
    {
        for(int i=0; i <= sibling->nKeys; ++i)
            child->C[i+t] = sibling->C[i];
    }

    // Moving all keys after index in the current node one step before -
    // to fill the gap created by moving keys[index] to C[index]
    for (int i=index+1; i < nKeys; ++i)
        keys[i-1] = keys[i];

    // Moving the child pointers after (index+1) in the current node one
    // step before
    for (int i=index+2; i <= nKeys; ++i)
        C[i-1] = C[i];
}

```

```

// Updating the key count of child and the current node
child->nKeys += sibling->nKeys+1;
nKeys--;

// Freeing the memory occupied by sibling
delete(sibling);

return;
}

// A function to fill child node that has less than t-1 keys after deletion
template<class keyType>
void Node<keyType>::fill(int index)
{
    // If the previous child(C[index-1]) has more than t-1 keys, promote a key
    // from that child
    if (index!=0 && C[index-1]->nKeys>=t)
        promoteFromPrev(index);

    // If the next child(C[index+1]) has more than t-1 keys, promote a key
    // from that child
    else if (index!=nKeys && C[index+1]->nKeys>=t)
        promoteFromNext(index);

    // Merge C[index] with its sibling
    // If C[index] is the last child, merge it with its previous sibling
    // Otherwise merge it with its next sibling
    else
    {
        if (index != nKeys)
            merge(index);
        else
            merge(index-1);
    }

    return;
}

// A function to promote a key from C[index-1] and insert it

```

```

// into C[index]
template< class keyType>
void Node<keyType>::promoteFromPrev(int index)
{
    Node< keyType> *child=C[index];
    Node< keyType> *sibling=C[index-1];

    // The last key from C[index-1] goes up to the parent and key[index-1]
    // from parent is inserted as the first key in C[index]. Thus, the loses
    // sibling one key and child gains one key

    // Moving all key in C[index] one step ahead
    for (int i=child->nKeys-1; i>=0; --i)
        child->keys[i+1] = child->keys[i];

    // If C[index] is not a leaf, move all its child pointers one step ahead
    if (!child->isLeaf)
    {
        for(int i=child->nKeys; i>=0; --i)
            child->C[i+1] = child->C[i];
    }

    // Setting child's first key equal to keys[index-1] from the current node
    child->keys[0] = keys[index-1];

    // Moving sibling's last child as C[index]'s first child
    if(!child->isLeaf)
        child->C[0] = sibling->C[sibling->nKeys];

    // Moving the key from the sibling to the parent
    // This reduces the number of keys in the sibling
    keys[index-1] = sibling->keys[sibling->nKeys-1];

    child->nKeys += 1;
    sibling->nKeys -= 1;

    return;
}

```

```

// A function to promote a key from the C[index+1] and place
// it in C[index]
template< class keyType>
void Node<keyType>::promoteFromNext(int index)
{

    Node< keyType> *child=C[index];
    Node< keyType> *sibling=C[index+1];

    // keys[index] is inserted as the last key in C[index]
    child->keys[(child->nKeys)] = keys[index];

    // Sibling's first child is inserted as the last child
    // into C[index]
    if (!(child->isLeaf))
        child->C[(child->nKeys)+1] = sibling->C[0];

    //The first key from sibling is inserted into keys[index]
    keys[index] = sibling->keys[0];

    // Moving all keys in sibling one step behind
    for (int i=1; i < sibling->nKeys; ++i)
        sibling->keys[i-1] = sibling->keys[i];

    // Moving the child pointers one step behind
    if (!sibling->isLeaf)
    {
        for(int i=1; i <=sibling->nKeys; ++i)
            sibling->C[i-1] = sibling->C[i];
    }

    // Increasing and decreasing the key count of C[index] and C[index+1]
    // respectively
    child->nKeys += 1;
    sibling->nKeys -= 1;

    return;
}

```

```

template<class keyType>
void Node<keyType>::remove(keyType k)
{
    int index = findKey(k);

    // The key to be removed is present in this node
    if (index < nKeys && keys[index] == k)
    {
        if (isLeaf) // The node is a leaf
            removeFromLeaf(index);
        else // The node is an internal node
            removeFromNonLeaf(index);
    }
    else
    {
        // The key is not in the node, but in a descendant
        // If this node is a leaf node, then the key is not present in tree
        if (isLeaf)
        {
            cout << "The key " << k << " not found in the tree\n";
            return;
        }

        // The key to be removed is present in the sub-tree rooted at this node
        // The flag isLast indicates whether the key is present in the sub-tree rooted
        // at the last child of this node
        bool isLast = ( index==nKeys)? true : false );

        // If the child where the key is supposed to exist is underflow,
        // we fill that child
        if (C[index]->nKeys < t)
            fill(index); // call a function to fill the child

        // If the last child has been merged, it must have merged with the previous
        // child and so we recurse on the (index-1)th child. Else, we recurse on the
        // (index)th child which now has atleast t keys
        if (isLast && index > nKeys)
            C[index-1]->remove(k);
        else
    }
}

```

```

        C[index]->remove(k);
    }

    return;
}

template <class keyType>
void BTree<keyType>::remove(keyType k)
{
    if (!root)
    {
        cout <<"Tree empty\n";
        return;
    }

    // Call the remove function for root node
    root->remove(k);

    // If the root node has 0 keys, make its first child as the new root
    // if it has a child, otherwise set root as NULL
    if (root->nKeys==0)
    {
        Node < keyType> *tmp = root;
        if (root->isLeaf)
            root = NULL;
        else
            root = root->C[0];
        // Free the old root
        delete tmp;
    }

    return;
}

// A utility function that returns the index of the first key that is
// greater than or equal to k
template <class keyType>
int Node<keyType>::findKey(keyType k)
{

```



```

int index = 0;
while(index < nKeys && keys[index] < k)
    ++index;
return index;
}

```

// Driver program to test above functions

```
int main()
```

```
{
```

```
    BTree<string> t(3); // A B-Tree with minimum degree 3, order 6
```

```
    fstream file;
```

```
    string word, filename;
```

```
    filename = "input.txt";
```

```
    file.open(filename.c_str());
```

```
    while(file >> word)
```

```
    {
```

```
        if(!t.search(word)){
```

```
            t.insert(word);
```

```
        }
```

```
    }
```

```
    file.close();
```

```
    cout << "Traversal of the constructed tree is: " << endl;
```

```
    t.traverse();
```

```
    cout << endl;
```

```
    cout << endl;
```

```
    cout << endl;
```

```
    t.remove("B-trees,");
```

```
    t.remove("nodes.");
```

```
    t.remove("node,");
```

```
    t.remove("range.");
```

```
    t.remove("tree,");
```

```
    t.remove("trees,");
```

```

t.remove("changes.");
t.remove("space,");
t.remove("data,");
t.remove("example,");
t.remove("data,");
t.remove("example,");
t.remove("searches,");
t.remove("range,");
t.remove("insertions,");

cout << endl;
cout << endl;
cout << "Traversal of the constructed tree after remove keys is: " << endl;
t.traverse();
cout << endl;
cout << endl;

return 0;
}

```

Outputs:

Script started on 2020-04-21 14:48:48-07:00 [TERM="xterm" TTY="/dev/pts/0"

COLUMNS="102" LINES="49"]

^[]0;006151141@csusb.edu@jb359-3:~/CSE461/lab2/btree^G[006151141@csusb.edu@jb359-3
btree]\$ g++ -o btree btree.cpp^M

^[]0;006151141@csusb.edu@jb359-3:~/CSE461/lab2/btree^G[006151141@csusb.edu@jb359-3
btree]\$./^H^[[K^H^[[Kcat input.txt^M

In computer science, a B-tree is a self-balancing tree data structure that maintains ^M sorted data and allows searches, sequential access, insertions, and deletions in ^M logarithmic time. The B-tree is a generalization of a binary search tree in that a node ^M can have more than two children. Unlike self-balancing binary search trees, the B-tree is ^M well suited for storage systems that read and write relatively large blocks of data, such ^M as discs. It is commonly used in databases and file systems. In B-trees, internal ^M (non-leaf) nodes can have a variable number of child nodes within some pre-defined ^M range. When data is inserted or removed from a node, its number of child nodes changes. ^M In order to maintain the pre-defined range, internal nodes may be joined or split. Because ^M a range of child nodes is permitted, B-trees do not need re-balancing as frequently as ^M other self-balancing search trees, but may waste some space, since nodes are not entirely ^M

full. The lower and upper bounds on the number of child nodes are typically fixed for a particular implementation. For example, in a 2-3 B-tree (often simply referred to as a 2-3 tree), each internal node may have only 2 or 3 child nodes.

```
^M
^[[0;006151141@csusb.edu@jb359-3:~/CSE461/lab2/btree^G[006151141@csusb.edu@jb359-3
btree]$ ^M
^[[0;006151141@csusb.edu@jb359-3:~/CSE461/lab2/btree^G[006151141@csusb.edu@jb359-3
btree]$ ./btree^M
```

Traversal of the constructed tree is: ^M

(non-leaf) (often 2 2-3 3 B-tree B-trees B-trees, Because For In It The Unlike When a access, allows and are as be binary blocks bounds but can changes. child children. commonly computer data data, databases deletions discs. do each entirely example, file fixed for frequently from full. generalization have implementation. in inserted insertions, internal is its joined large logarithmic lower maintain maintains may more need node node, nodes nodes. not number of on only or order other particular permitted, pre-defined range range, range. re-balancing read referred relatively removed science, search searches, self-balancing sequential simply since some sorted space, split. storage structure such suited systems systems. than that the time. to tree tree), trees, two typically upper used variable waste well within write^M

^M

^M

The key data, not found in the tree^M

The key example, not found in the tree^M

^M

^M

Traversal of the constructed tree after remove keys is: ^M

(non-leaf) (often 2 2-3 3 B-tree B-trees Because For In It The Unlike When a access, allows and are as be binary blocks bounds but can child children. commonly computer data databases deletions discs. do each entirely file fixed for frequently from full. generalization have implementation. in inserted internal is its joined large logarithmic lower maintain maintains may more need node nodes not number of on only or order other particular permitted, pre-defined range re-balancing read referred relatively removed science, search self-balancing sequential simply since some sorted split. storage structure such suited systems systems. than that the time. to tree two typically upper used variable waste well within write^M

^M

```
^[[0;006151141@csusb.edu@jb359-3:~/CSE461/lab2/btree^G[006151141@csusb.edu@jb359-3
btree]$ exit^M
```

exit^M

Script done on 2020-04-21 14:49:41-07:00 [COMMAND_EXIT_CODE="0"]

```
[005319687@csusb.edu@jb358-2 lab2]$ g++ -o btree btree.cpp
```

```
[005319687@csusb.edu@jb358-2 lab2]$ ./btree
```

Traversing through the Tree:

(non-leaf) (often 2 2-3 3 B-tree B-trees Because For In It The Unlike When a access, allows and are as be binary blocks bounds but can changes. child children. commonly computer data data, databases deletions discs. do each entirely example, file fixed for frequently from full. generalization have implementation. in inserted insertions, internal is its joined large logarithmic lower maintain maintains may more need node node, nodes nodes. not number of on only or order other particular permitted, pre-defined range range, range. re-balancing read referred relatively removed science, search searches, self-balancing sequential simply since some sorted space, split. storage structure such suited systems systems. than that the time. to tree tree), trees, two typically upper used variable waste well with in write

The key data, not found in the tree

The key example, not found in the tree

Traversing through the Tree after deleting 15 keys:

(non-leaf) (often 2 2-3 3 B-tree B-trees Because For In It The Unlike When a access, allows and are as be binary blocks bounds but can child children. commonly computer data databases deletions discs. do each entirely file fixed for frequently from full. generalization have implementation. in inserted internal is its joined large logarithmic lower maintain maintains may more need node nodes not number of on only or order other particular permitted, pre-defined range re-balancing read referred relatively removed science, search self-balancing sequential simply since some sorted split. storage structure such suited systems systems. than that the time. to tree two typically upper used variable waste well within write

```
[005319687@csusb.edu@jb358-2 lab2]$ █
```

2. Report

After doing this lab, we figured out how to implement the B-Tree algorithm using the C++ language. The instructions and the steps were very straight-forward and we managed to figure out the material quickly. One difficulty that we encountered in this lab was finding the findKey function but the TA told us what to do and we managed to figure it out quickly. Also, filling out the missing part of the code was straight-forward because there are already comments that tell you what to do for that missing code. Overall, we believe that we should get the full 20 points because we managed to get the right outputs and we implemented the algorithms correctly.