Mixed method for linear elastic thin-plate flexure:

variational form

3 PROBLEM DESCRIPTION

2

- 4 Consider a thin plate loaded with some force f = f(x, y). Let **M** denote the moment tensor and $\eta = \eta(x, y)$
- represent the vertical deflection in response to f. With λ_1 and λ_2 some appropriately-defined scalar-valued
- functions in x and y, the governing equation and constitutive relation on the plate are:

$$-\nabla \cdot (\nabla \cdot \mathbf{M}) = f \tag{1a}$$

$$\mathbf{M} = \lambda_1 \nabla \nabla \eta + \lambda_2 tr \left(\nabla \nabla \eta \right) \mathbf{I}$$
 (1b)

⁷ (I the two-by-two identity). The goal is to separately put Equations 1a and 1b into variational form.

8 USEFUL IDENTITIES

Some useful identities which will help in attaining the variational forms for Equations 1a and 1b. In the identities below, α and β will denote scalar quantities, \vec{a} and \vec{b} are vectors, and \mathbf{A} and \mathbf{B} are tensors. Ω represents the domain of the problem, Γ is the boundary, and \hat{n} is the unit, outward-pointing vector normal to Γ .

$$\nabla \cdot (\alpha \mathbf{A}) = \alpha (\nabla \cdot \mathbf{A}) + \mathbf{A} \cdot \nabla \alpha \tag{2}$$

$$\nabla \cdot (\alpha \vec{a}) = \alpha (\nabla \cdot \vec{a}) + \vec{a} \cdot \nabla \alpha \tag{3}$$

$$\int_{\Omega} \nabla \cdot \vec{a} = \int_{\Gamma} \vec{a} \cdot \hat{n} \tag{4}$$

...hopefully some more useful identities will become apparent...

: 2

$_{14}$ PUTTING EQUATION 1a INTO VARIATIONAL FORM

Multiply both sides of the governing equation by arbitrary scalar function w = w(x, y). Then

$$-w\nabla \cdot (\nabla \cdot \mathbf{M}) = wf$$

- Note that the left-hand side is the product of the scalar variable -w with the divergence of the vector
- $(\nabla \cdot \mathbf{M})$. Therefore, by the product rule of Equation 3, the equation above can be rewritten so that

$$(\nabla \cdot \mathbf{M}) \cdot \nabla w - \nabla \cdot [w(\nabla \cdot \mathbf{M})] = wf.$$

Integrating over the domain Ω , we have that

$$\int_{\Omega} [(\nabla \cdot \mathbf{M}) \cdot \nabla w] - \int_{\Omega} \nabla \cdot [w(\nabla \cdot \mathbf{M})] = \int_{\Omega} wf.$$

Finally, by the Divergence Theorem of Equation 4, it follows that

$$\int_{\Omega} [(\nabla \cdot \mathbf{M}) \cdot \nabla w] - \int_{\Gamma} [w(\nabla \cdot \mathbf{M}) \cdot \hat{n}] = \int_{\Omega} wf$$
 (5)

20 PUTTING EQUATION 1b INTO VARIATIONAL FORM

Let N be an arbitrary tensor function. Then the constitutive equation of Equation 1b requires that

$$\int_{\Omega} \mathbf{N} : \mathbf{M} = \int_{\Omega} \lambda_1 \mathbf{N} : \nabla \nabla \eta + \int_{\Omega} \lambda_2 \mathbf{N} : tr(\nabla \nabla \eta) \mathbf{I}$$

22 I'll split the right-hand side up into two pieces:

23 The first term

24 First, we'll try writing the expression

$$\int_{\Omega} \lambda_1 \mathbf{N} : \nabla \nabla \eta \tag{6}$$

in terms of only first derivatives...

The second term

27 Finally, put the expression

$$\int_{\Omega} \lambda_2 \mathbf{N} : tr(\nabla \nabla \eta) \mathbf{I} \tag{7}$$

28 in terms of only first derivatives...