x(8.)(ab)x = a(bx) **THM1.1.13** If W is a subset of a vector space V s.t. $\mathbf{x}, \mathbf{y} \in \mathbb{Q}$ and for any $a, b \in \mathbb{F}$ the vector $a\mathbf{x} + b\mathbf{y} \in W$, then W is a subspace of V. **DEFLinHull** of S(S), smallest subspace of V that contains S,i.e. intersection of all subspaces of V that contain S. $\mathbf{THM1.2.6Span}(S)$ $=\langle S \rangle$. **DEF** \bigoplus Where W_1, W_2 are subspaces of V, then $W_1 + W_2 = W_1 \bigoplus W_2$ if $W_1 \cap W_2 = 0$. **DEFComplementarysubspaces** W_1 and W_2 if $V = W_1 \bigoplus W_2$ **THMReplacement**: V is a vector space spanned by $S = s_1, \dots, s_m$. If $T = t_1, \dots, t_n$ is a L.I. subset of V, then $\leq m$ and

DEFVecSp: $1.x+y = y+x2.(x+y)+z = x+(y+z)3.Add.Id.0 \in V|0+x = x4.\exists Add.Inv.(-x)|x+$ (-x) = 0(5.)F.Dis.Lawa(x + y) = ax + ay(6.)S.Dis.Law(a + b)(x) = ax + bx(7.)Mul.Id.1x =

 $\exists S' \subset S$ having m-n elements such that $T \cup S'$ spans V. **THMExtension**: W is a subspace of VIf $T = t_1, \dots, t_n$ and $S = s_1, \dots, s_m$ span W and V, respectively, then $\exists S' \subset S$ having

m-n elements such that $T \cup S'$ is a basis for V. **DEFQuotientSpaces**: W subspace of V. The set $x + W|x \in V(orequivalently[[x]]|x \in V)$ of all cosets of W in V is denoted V/W and is called the quotient of V modulo W. $\overrightarrow{\mathbf{DEF}} \boxplus \Box$: Let W be a subspace of V. Define operations

 $\boxplus: V/W \times V/W \to V/W$ and $\boxdot: \mathbb{F} \times V/W \to V/W$ given by (i) $(x+W) \boxplus (y+W) = (x+y) + W$ and $a \square (x + W) = (ax) + W$. These are the operations of vector addition and scalar multiplication on V/W. CHAP2 DEFLineartransformation Let V and V be vector spaces over \mathbb{F} . A

map $L:V\to W$ is a linear transformation from V into W if $L(ax_1+bx_2)=aL(x_1)+bL(x_2)$ for $x_1, x_2 \in V$ and $a, b \in \mathbb{F}$ COR2.1.17 A linear transforamtion is invertible if and only if it is

bijective. **Prop.2.1.24**: If $V \cong W$ are isomorphic vector spaces, with isoorphism $L: V \to W$, then: (i) A linear equation holds in V iff it also holds in W: that is $\sum_{i=1}^{n} a_i \mathbf{x_i} = \mathbf{0}$ holds in V iff $\sum_{i=1} a_i L_i \mathbf{x_i} = \mathbf{0}$ holds in W. (ii) A set $B = \{\mathbf{v_i}, \dots, \mathbf{v_n}\}$ is a basis of V iff $B = \{L\mathbf{v_i}, \dots, L\mathbf{v_n}\}$

is a basis for W. Moreover, the dimension of V is equal to the dimension of V. (iii) The subspaces of V are in vijective correspondence with the subspaces of W. (iv) If K: W \rightarrow U is any

have $\mathcal{N}(KL) = L^{-1}\mathcal{N}(K) = \{v|L(\mathbf{v}) \in \mathcal{N}(K)\}$ and $\mathcal{R}(KL) = \mathcal{R}(K)$ **THMF.Iso.** If V and X are vector spaces and $L:V\to X$ is a linear transformation, then $V/\mathcal{N}(L)\cong \mathcal{R}(L)$. in Let V and W be finite-dimensional vector spaces. If $L:V\to is$ a linear transformation then $\dim(V) = \dim\mathcal{R}(L) + \dim\mathcal{N}(L) = \operatorname{rank}(L) + \operatorname{nullity}(L)$. CORSec. Iso. Thm. Assume V_1 and V_2 are subspaces of V. Then $V_1/(V_1 \cap V_2) \cong (V_1 + V_2)/V_2$. CORDim Formula If V_1 and V_2 are finitedimensional subspaces of a vector space V, then $\dim(V_1) + \dim(V_2) = \dim(V_1 \cap V_2) + \dim(V_1 + V_2)$

DEFSimilarMatrices Two square matrices $A, B \in M_n(\mathbb{F})$ are said to be similar if there exists a nonsingular $P \in M_n(\mathbb{F})$ such that $B = P^{-1}AP$. **DEFBernsteinPolynomials** Given $n \in \mathbb{N}_{>0}J$,

particular, if L is surjective, then $V/N(L) \cong X$. THM2.2.7 If V is a finite-dimensional vector space and W is a subspace of V, then $\dim(V) = \dim(W) + \dim(V/W)$ **THMRank - Nullity**

the Bernstein polynomials $B_j^n(x)_{j=0}^n$ of degree n are defined as $B_j^n(x) = \binom{n}{j} x^j (1-x)^{n-j}$, where $\binom{n}{j} = \frac{n!}{j!(n-j)!}$ LEM2.5.3For $j = 0, 1, \dots, n$ $B_j^n(x) = \sum_{i=j}^n (-1)^{i-j} \binom{n}{i} \binom{i}{j} x^i$ THM2.5.4 For any $n \in \mathbb{N}$, the set T_n of degree n Bernstein polynomials $T_n = B_j^n(x)_{i=0}^n$ forms a basis for $\mathbb{F}[x]^n$

DEFTrace The trace is the sum of the elements along the main diagonal **PROP2.6.2**All of the elementary matrices are invertible. **DEFRowEquivalence**The B is said to be row equivalent to the matrix A if there exists a finite collection of elementary matrices E_1, E_2, \ldots, E_n such that $B = E_1 E_2 \dots E_n$ **DEFREF** A is REF if (i) leading coefficient of each row is strictly to the right

of the previous row's leading coefficient (ii) All nonzero rows are above any zero rows and RREF if (iii) the leading coefficient of every row is 1 (iv) The leading coefficient of every row is the only

nonzero entry in its column. **DEFPermutation** Different arrangements of a set. Even if it has an even number of inversions, odd if an odd number of inversions. Sign is 1 if even, -1 if odd. **DEFInversion** A pair $(\sigma(i), \sigma(j))$ such that i < j and $\sigma(i) > \sigma(j)$. **THM2.8.7** If $A, B \in M_n(\mathbb{F})$,

then $\det(AB) = \det(A)\det(B)$ COR2.8.8 $\det(A^{-1} = (\det(A))^{-1})$ Cramer's Rule If $A \in M_n(\mathbb{F})$ is

nonsingular, then the unique solution to Ax = b is $x = A^{-1}b = \frac{\operatorname{adj}(A)}{\det(A)}b$. Moreover, if $A_i(b) \in M_n(\mathbb{F})$ is the matrix A with the i-th column replaced by b, then the i-th coordinate of x is $x_i = \frac{\det(A_i(b))}{\det(A)}$