

$$\underline{\Sigma}_i = \underline{\Sigma} :$$

$$g_i(\underline{x}) = -\frac{1}{2}(\underline{x} - \underline{\mu}_i)^T \underline{\Sigma}^{-1}(\underline{x} - \underline{\mu}_i) + \ln P_Y(i)$$

Quantity  $(\underline{x} - \underline{\mu})^T \underline{\Sigma}^{-1}(\underline{x} - \underline{\mu})$  called Mahalanobis distance

If  $P_Y(i) = 1/M$ , then  $\hat{\alpha}(\underline{x}) = \arg \min_i (\underline{x} - \underline{\mu}_i)^T \underline{\Sigma}^{-1}(\underline{x} - \underline{\mu}_i)$   
minimum dist. using m-distance

Equivalently

$$g_i(\underline{x}) = \underline{\mu}_i^T \underline{\Sigma}^{-1} \underline{x} - \frac{1}{2} \underline{\mu}_i^T \underline{\Sigma}^{-1} \underline{\mu}_i + \ln P_Y(i)$$

General  $\underline{\Sigma}_i$  linear discriminant  
 (Decision region boundaries still hyperplanes but not  $\perp$  to line bet. means)

$$g_i(\underline{x}) = -\frac{1}{2}(\underline{x} - \underline{\mu}_i)^T \underline{\Sigma}_i^{-1}(\underline{x} - \underline{\mu}_i) - \frac{1}{2} \ln(\det \underline{\Sigma}_i) + \ln P_Y(i)$$

Equivalently,

$$g_i(\underline{x}) = \underline{\mu}_i^T \underline{\Sigma}_i^{-1} \underline{x} - \frac{1}{2} \underline{\mu}_i^T \underline{\Sigma}_i^{-1} \underline{\mu}_i - \frac{1}{2} \underline{x}^T \underline{\Sigma}_i^{-1} \underline{x} - \frac{1}{2} \ln(\det \underline{\Sigma}_i) + \ln P_Y(i)$$

quadratic discriminant fns.

Decision regions

surfaces can be hyperplanes, hyper spheres, hyperellipsoids, hyper paraboloids, etc.

Decision regions may not be simply connected.

$$Y=i \text{ w.p. } P_Y(i) \quad i=1, \dots, m$$

$$L_{ij} = \text{loss in deciding } i \text{ when } Y=j \\ = L(\alpha(x)=i, Y=j)$$

Recall: Bayes decision

$$\begin{aligned} \hat{\alpha}(x) &= \operatorname{argmin}_{i=1, \dots, m} \sum_{j=1}^m L_{ij} P_{Y|X}(j|x) \\ &= \operatorname{argmin}_{i=1, \dots, m} \sum_{j=1}^m L_{ij} P_Y(j) f_{X|Y}(x|j) \quad (1) \end{aligned}$$

Consider likelihood ratio

$$\Lambda_i(x) = \frac{f_{X|Y}(x|i)}{f_{X|Y}(x|1)}, \quad i=1, \dots, m$$

Thus,  $\Lambda_1(x) = 1$ . Dividing by  $f_{X|Y}(x|1)$  in (1):

$$\hat{\alpha}(x) = \operatorname{argmin}_{i=1, \dots, m} [L_{i1} P_Y(1) + \sum_{j=2}^m L_{ij} P_Y(j) \Lambda_j(x)]$$

Decision based on  $m-1$ -dim vector  $\begin{bmatrix} \Lambda_2(x) \\ \vdots \\ \Lambda_m(x) \end{bmatrix}$

$R_i = \{x : \hat{\alpha}(x) = i\}$  = set of pts satisfying

$$L_{i1} P_Y(1) + \sum_{j=2}^m L_{ij} P_Y(j) \Lambda_j(x) \leq L_{k1} P_Y(1) + \sum_{j=2}^m L_{kj} P_Y(j) \Lambda_j(x) \quad \forall k \neq i$$

$$\text{or } (L_{ii} - L_{ki}) P_Y(i) + \sum_{j=2}^m (L_{ij} - L_{kj}) P_Y(j) \Lambda_j(\underline{x}) \leq 0 \quad \forall k \neq i$$

In the space of likelihood ratios, inequality corresp. to halfspace defined by the affine space

$$(L_{ii} - L_{ki}) P_Y(i) + \sum_{j=2}^m (L_{ij} - L_{kj}) P_Y(j) \Lambda_j(\underline{x}) = 0$$

This separates  $R_i$  and  $R_k$ .

$R_i$  = convex region defined by  $m-1$  affine halfspaces.

- If  $L_{ii} = 0 \quad \forall i$  and  $L_{ij} = g_j \quad \forall i \neq j$

(i.e. cost of making error when  $Y=j$  indep of how error was made). Then,

$$\begin{aligned} \sum_{j=1}^m L_{ij} P_Y(j) \Lambda_j(\underline{x}) &= \sum_{j \neq i} g_j P_Y(j) \Lambda_j(\underline{x}) \\ &= \sum_{j=1}^m g_j P_Y(j) \Lambda_j(\underline{x}) - g_i P_Y(i) \Lambda_i(\underline{x}) \end{aligned}$$

$$\begin{aligned} \text{Thus, } \hat{\alpha}(\underline{x}) &= \arg \min_i \sum_{j=1}^m L_{ij} P_Y(j) \Lambda_j(\underline{x}) \\ &= \arg \min_i \underbrace{\sum_{j=1}^m g_j P_Y(j) \Lambda_j(\underline{x}) - g_i P_Y(i) \Lambda_i(\underline{x})}_{\text{same for all } i} \\ &= \arg \max_{i=1, \dots, m} g_i P_Y(i) \Lambda_i(\underline{x}) \end{aligned}$$

View as set of binary threshold comparisons,

$$g_i p_Y(i) \wedge_i(\underline{x}) \underset{\hat{\alpha} \neq j}{\overset{\hat{\alpha} \neq j}{\geq}} g_j p_Y(j) \wedge_j(\underline{x})$$

$$\frac{\wedge_j(\underline{x})}{\wedge_i(\underline{x})} = \frac{f_{\underline{x}|Y}(\underline{x}|j)}{f_{\underline{x}|Y}(\underline{x}|i)} \underset{\hat{\alpha} \neq j}{\overset{\hat{\alpha} \neq i}{\geq}} \frac{g_i p_Y(i)}{g_j p_Y(j)} \equiv \eta_{ji}$$

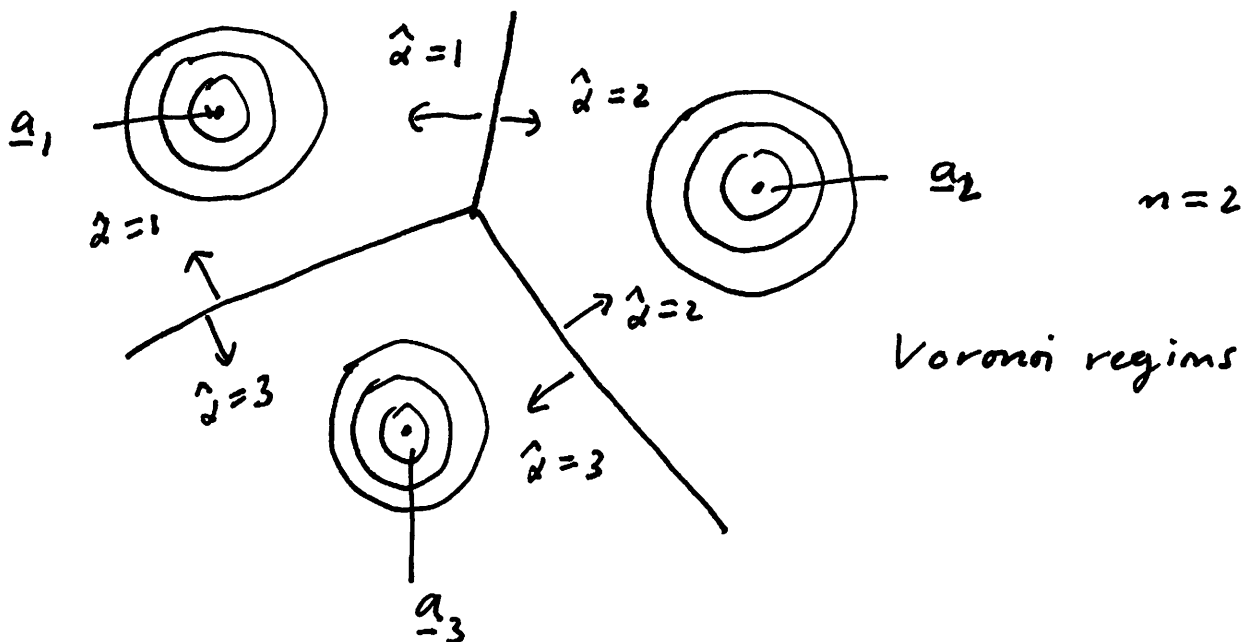
$$\frac{\wedge_j(\underline{x})}{\wedge_i(\underline{x})} \geq \eta_{ji} \quad \forall i \neq j \Rightarrow j \text{ is Bayes decision}$$

Ex:  $Y=i: \quad \underline{X} = \underline{a}_i + \underline{z} \quad \underline{z} \sim \mathcal{N}(\underline{0}, \sigma^2 \mathbf{I})$

i.e.  $\underline{X} \sim \mathcal{N}(\underline{a}_i, \sigma^2 \mathbf{I}) \quad \underline{a}_i = \begin{bmatrix} a_{i1} \\ \vdots \\ a_{in} \end{bmatrix}$

From p.36, each binary threshold comparison has form:

$$(\underline{a}_j - \underline{a}_i)^T \underline{x} \underset{\hat{\alpha} \neq j}{\overset{\hat{\alpha} \neq i}{\geq}} \sigma^2 \ln \eta_{ji} + \frac{\|\underline{a}_j\|^2 - \|\underline{a}_i\|^2}{2}$$



- Decision threshold bet. each pair of categories is affine space  $\perp$  to line joining 2 signals
- $(\underline{a}_j - \underline{a}_1)^T \underline{x}$ ,  $2 \leq j \leq m$  is a suff. stat. for m-ary problem since  $(\underline{a}_j - \underline{a}_1)^T \underline{x} = (\underline{a}_j - \underline{a}_1)^T \underline{x} - (\underline{a}_1 - \underline{a}_1)^T \underline{x}$
- If  $n > m-1$ , reduce to  $m-1$  dimensions by expressing  $\underline{a}_i - \underline{a}_1$  in terms of  $\leq m-1$  basis vectors.
- Calculating  $\Pr(e)$  in Gaussian m-ary decision problem is hard, even when calculating in  $m-1$  dimensional space. Must integrate over Voronoi regions
- often good enough to give good upper bound to  $\Pr(e)$ .

Union bound:

$$P\left(\bigcup_{j=1}^K E_j\right) \leq \sum_{j=1}^K P(E_j) \quad \text{for any set of events } E_1, \dots, E_K.$$

Then,

$$\Pr(e | \gamma = i) \leq \sum_{j \neq i} P\left((\underline{a}_j - \underline{a}_i)^T \underline{x} \geq \sigma^2 \ln \eta_{ji} + \frac{\|\underline{a}_j\|^2 - \|\underline{a}_i\|^2}{2}\right)$$

$$= \sum_{j \neq i} \alpha \left( \frac{\sigma \ln \eta_{ji}}{\|\underline{a}_j - \underline{a}_i\|} + \frac{\|\underline{a}_j - \underline{a}_i\|}{2\sigma} \right).$$

(47)