

Christopher T. Morse

morse164@umn.edu — (402) 326-7906

EDUCATION	University of Virginia <i>Ph.D. in Computer Science</i> Cumulative GPA: 3.90 / 4.00 Technical GPA: 3.86 / 4.00 University of Minnesota – Twin Cities <i>Bachelor of Arts in Computer Science, Music Minor</i> Cumulative GPA: 3.90 / 4.00 Technical GPA: 3.86 / 4.00	Charlottesville, VA Expected May 2027 Minneapolis, MN Expected May 2021
HONORS AND AWARDS	<i>2nd Place</i> ; University of Nebraska REU Research Symposium UROP Research Award Recipient UMN College of Liberal Arts Dean’s List	Summer 2019 Summer 2020 Fall 2017 – Present
WORK EXPERIENCE	Research Assistant, University of Minnesota – IRV Lab <ul style="list-style-type: none">Developed a streamlined method for paired diver image generation to combat data scarcity.Investigated a method for synthetic image generation for data augmentation.Evaluated object detection models, organized the resulting data, and generated figures.Assisted with pool trials, experimentation, and dataset organization. Teaching Assistant, University of Minnesota – Department of CS&E <i>CSCI 2011 : Discrete Structures of Computer Science</i> <i>CSCI 1133 : Intro. to Computing and Programming Concepts</i> <ul style="list-style-type: none">Conducted laboratory sections to encourage student collaboration and participation.Hosted office hours to further enhance students’ understanding of the course material.Assisted with discussion sections, grading, and exam proctoring. REU Research Assistant, University of Nebraska – NIMBUS Lab <ul style="list-style-type: none">Analyzed the benefits of network optimization and data augmentation on UAV detection.Coordinated with graduate students and faculty mentors to organize and complete tasks.Created and presented a research poster for the UNL Summer Research Symposium.	Winter 2019 - Present Fall 2019 Fall 2018, Spring 2019 Summer 2019
PROJECTS	UROP Research Project: Pool2Ocean <i>Synthetic Data Generation for Underwater Object Detection Using CycleGAN</i> <ul style="list-style-type: none">Implemented a generative approach for data augmentation to aid underwater detections.Improved average precision by 43% after including synthetic images in the training set.Created and presented a research poster for the UMN Virtual Research Symposium. REU Research Project: Real-Time Unmanned Drone Detection <i>Optimization Through Data Augmentation and Transfer Learning</i> <ul style="list-style-type: none">Utilized transfer learning and data augmentation to build resilience through blurry frames.Developed ‘ABLAIS,’ a system for reproducing bounding box labels on altered images.Modified an existing implementation of RetinaNet to enhance real-time drone detection.	Summer 2020 Summer 2019
PUBLICATIONS	M. J. Islam, C. Edge, Y. Xiao, P. Luo, M. Mehtaz, C. Morse , S. S. Enan, and J. Sattar, “Semantic Segmentation of Underwater Imagery: Dataset and Benchmark.” Accepted to the <i>2020 IEEE International Conference on Intelligent Robots and Systems (IROS)</i> .	