

Christopher T. Morse

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EDUCATION	University of Virginia <i>M.S. in Computer Science</i> GPA: 4.00 / 4.00 University of Minnesota – Twin Cities <i>B.A. in Computer Science, Minor in Music</i> GPA: 3.91 / 4.00	Charlottesville, VA Expected May 2023 Minneapolis, MN May 2021
WORK EXPERIENCE	Teaching Assistant, University of Virginia <i>CS 1010: Introduction to Information Technology</i> <i>CS 4501: Robotics for Software Engineers</i> <ul style="list-style-type: none">Designed and led engaging laboratory sections for 50+ students.Created final projects and associated instructional materials. Research Assistant, University of Virginia <i>Leading Engineering for Safe Software (LESS) Laboratory</i> <ul style="list-style-type: none">Created a novel method for inferring spatial properties from robot data.Built a pipeline to approximate scene coverage for AV perception systems. Research Assistant, University of Minnesota <i>Interactive Robotics and Vision (IRV) Laboratory</i> <ul style="list-style-type: none">Developed a streamlined method for paired diver image generation to combat data scarcity.Investigated a method for synthetic image generation to aid with data augmentation. Teaching Assistant, University of Minnesota <i>CSCI 2011 : Discrete Structures of Computer Science</i> <i>CSCI 1133 : Intro. to Computing and Programming Concepts</i> <ul style="list-style-type: none">Conducted laboratory sections to encourage student collaboration and participation.Hosted office hours and discussion sections; assisted with grading and proctoring. REU Research Assistant, University of Nebraska <i>Nebraska Intelligent MoBile Unmanned Systems (NIMBUS) Laboratory</i> <ul style="list-style-type: none">Analyzed effects of hyperparameter tuning and data augmentation on UAV detection.	Spring 2023 Fall 2022 Summer 2021 - Winter 2022 Winter 2019 - Fall 2020 Fall 2019 Fall 2018, Spring 2019 Summer 2019
PROJECTS	Network Packet Analysis with NLP <ul style="list-style-type: none">Created a novel command line tool to parse and query network data with NLP.Utilized the GPT-3 API to generate SQL queries over MySQL data tables. VAE-Guided Testing Framework for OpenPilot <ul style="list-style-type: none">Designed and trained a VAE for manifold approximation of traffic images.Clustered training set images with K-Means and PCA to exploit underrepresented features.	Spring 2023 Spring 2022
SKILLS	Python/C++/SQL – Machine Learning – Manifold Statistics – Computer Vision – Robotics	
SERVICE, HONORS, AND AWARDS	<ul style="list-style-type: none">Paper Reviewer, IEEE International Conference on Robotics and AutomationUROP Research Award Recipient2nd Place; University of Nebraska REU Research Competition	Fall 2022 Summer 2020 Summer 2019
PUBLICATIONS	C. Morse , L. Feng, M. Dwyer, S. Elbaum, “A Framework for the Unsupervised Inference of Relations Between Sensed Object Spatial Distributions and Robot Behaviors.” Accepted to the <i>2023 IEEE International Conference on Robotics and Automation (ICRA)</i> . M. J. Islam, C. Edge, Y. Xiao, P. Luo, M. Mehtaz, C. Morse , S. S. Enan, and J. Sattar, “Semantic Segmentation of Underwater Imagery: Dataset and Benchmark.” <i>2020 IEEE International Conference on Intelligent Robots and Systems (IROS)</i> .	