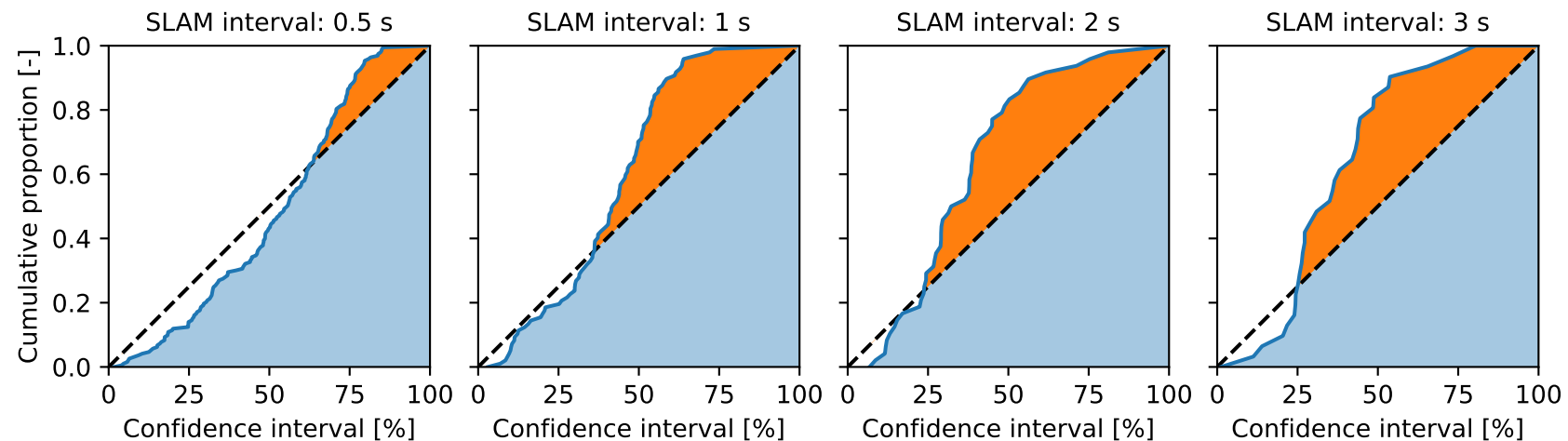
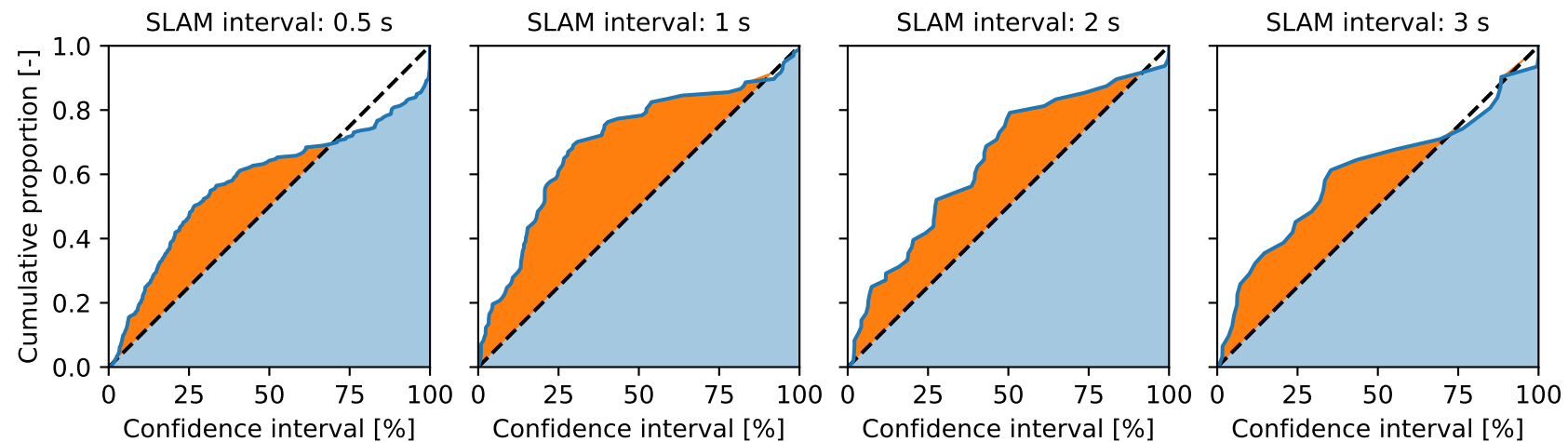


Position error



Orientation error



--- perfect uncertainty estimate — actual uncertainty estimate orange uncertainty overestimation