

Assessment of Inertial-Coupling Terms in EOMs mAEWing2 FEM 1.2 – Initial Results

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Intro and Objectives

- Typically, inertial coupling between RB and Elastic DOFs is ignored.
- But the FEM for mAEWing2 has raised some questions - collinearity
- We want to
 - Model the inertial coupling presently assumed small ✓
 - Assess the effects of the coupling present – in process

Review of EOM's

$$m \ddot{\mathbf{V}}_{CM} + m(\boldsymbol{\omega}_{B,I} \times \mathbf{V}_{CM}) = m\mathbf{g} + \mathbf{F}$$

Ang-momentum change

$$[\mathbf{J}] \dot{\boldsymbol{\omega}}_{B,I} + \boldsymbol{\omega}_{B,I} \times [\mathbf{J}] \boldsymbol{\omega}_{B,I} + \boxed{\dot{\mathbf{J}}} \boldsymbol{\omega}_{B,I} + \sum_{i=1}^n \sum_{j=1}^n \left(\mathbf{h}_{i,j} (\dot{\eta}_i \dot{\eta}_j + \eta_i \ddot{\eta}_j) + \boldsymbol{\omega}_{B,I} \times \mathbf{h}_{i,j} \eta_i \dot{\eta}_j \right) = \mathbf{M}$$

$$M_{i,i} \ddot{\eta}_j + M_{i,i} \omega_i^2 \eta_j - \sum_{j=1}^n \left(\dot{\boldsymbol{\omega}}_{B,I} \cdot \mathbf{h}_{i,j} \eta_j + 2 \boldsymbol{\omega}_{B,I} \cdot \mathbf{h}_{i,j} \dot{\eta}_j \right) - \frac{1}{2} \boldsymbol{\omega}_{B,I}^T \boxed{\overline{\Delta \mathbf{J}_i}} \boldsymbol{\omega}_{B,I} = \mathbf{Q}_i, \quad i = 1 \dots n$$

Ang Accel of MA

Coriolis

Centrifugal Loading

$$\mathbf{J} = \mathbf{J}_{Rig} + \Delta \mathbf{J} + \Delta^2 \mathbf{J}$$

$$\boxed{\dot{\mathbf{J}}} = \sum_{i=1}^n [\Delta J_i] \dot{\eta}_i + \sum_{i=1}^n \sum_{j=1}^n [\Delta^2 J_{i,j}] \eta_i \dot{\eta}_j$$

$$\Delta \mathbf{J} = \sum_{i=1}^n [\Delta J_i] \eta_i(t)$$

$$\overline{\Delta \mathbf{J}_i} = [\Delta J_i] + \sum_{j=1}^n [\Delta^2 J_{i,j}] \eta_j$$

$$\Delta^2 \mathbf{J} = \sum_{i=1}^n \left(\sum_{j=1}^n [\Delta^2 J_{i,j}] \eta_i(t) \eta_j(t) \right)$$

Red terms currently assumed small

Blue terms (+ $\mathbf{h}_{i,j}$) estimated by VT team
From FEM 1.2 results - $fn(m_i, \phi_i)$

The $h_{i,j}$ Rigid-Elastic Coupling Terms

- As noted in intro, these terms are all zero for collinear mode shapes.
- But in FEMs 1.1 and 1.2, the mode shapes are not collinear.
- VT has determined that for FEM 1.2 , these $h_{i,j}$ coupling terms are all
on the order of 10^{-26} lb-in^2 , compared to RB inertia terms $\sim 10^3 \text{ lb-in}^2$
- At this point they will not be considered further

Effect on Perturbation Dynamics in Level Flight

Linearizing about straight and level flight, the perturbation equations are

$$m \frac{d}{dt} \mathbf{V}_{CM} + m \left(\frac{d}{dt} \boldsymbol{\omega}_{B,I} \times \mathbf{V}_{\text{Ref } CM} \right) = m \left[\frac{d}{dt} \mathbf{DCM} \right] \mathbf{g} + \frac{d}{dt} \mathbf{F}, \quad [\mathbf{DCM}] = \text{Direction-cosine matrix}$$

$$[\mathbf{J}_{\text{Ref}}] \frac{d}{dt} \boldsymbol{\omega}_{B,I} = \frac{d}{dt} \mathbf{M}, \quad \Rightarrow \quad [\mathbf{J}_{\text{Ref}}] = [\mathbf{J}_{\text{Rig}} + \Delta \mathbf{J}_{\text{Ref}} + \Delta^2 \mathbf{J}_{\text{Ref}}]$$

$$M_{i,i} \frac{d}{dt} \ddot{\eta}_i + M_{i,i} \omega_i^2 \frac{d}{dt} \eta_i = \mathbf{Q}_i, \quad i = 1 \dots n$$

$$\Delta \mathbf{J}_{\text{Ref}} = \sum_{i=1}^n [\Delta J_i] \eta_{i \text{ Ref}}(t)$$

$$\Delta^2 \mathbf{J}_{\text{Ref}} = \sum_{i=1}^n \left(\sum_{j=1}^n [\Delta^2 J_{i,j}] \eta_{i \text{ Ref}}(t) \eta_{j \text{ Ref}}(t) \right)$$

Note that \mathbf{J}_{Ref} is a function of the structural deformation in trim

The Trim Solutions

Trim constraints:

$$0 = m[\mathbf{DCM}_{\text{Ref}}]\mathbf{g} + \mathbf{F}_{\text{Ref}} \quad \Rightarrow L_{\text{Ref}} \approx mg$$

$$0 = \mathbf{M}_{\text{Ref}} \quad \Rightarrow M_A + M_T = 0$$

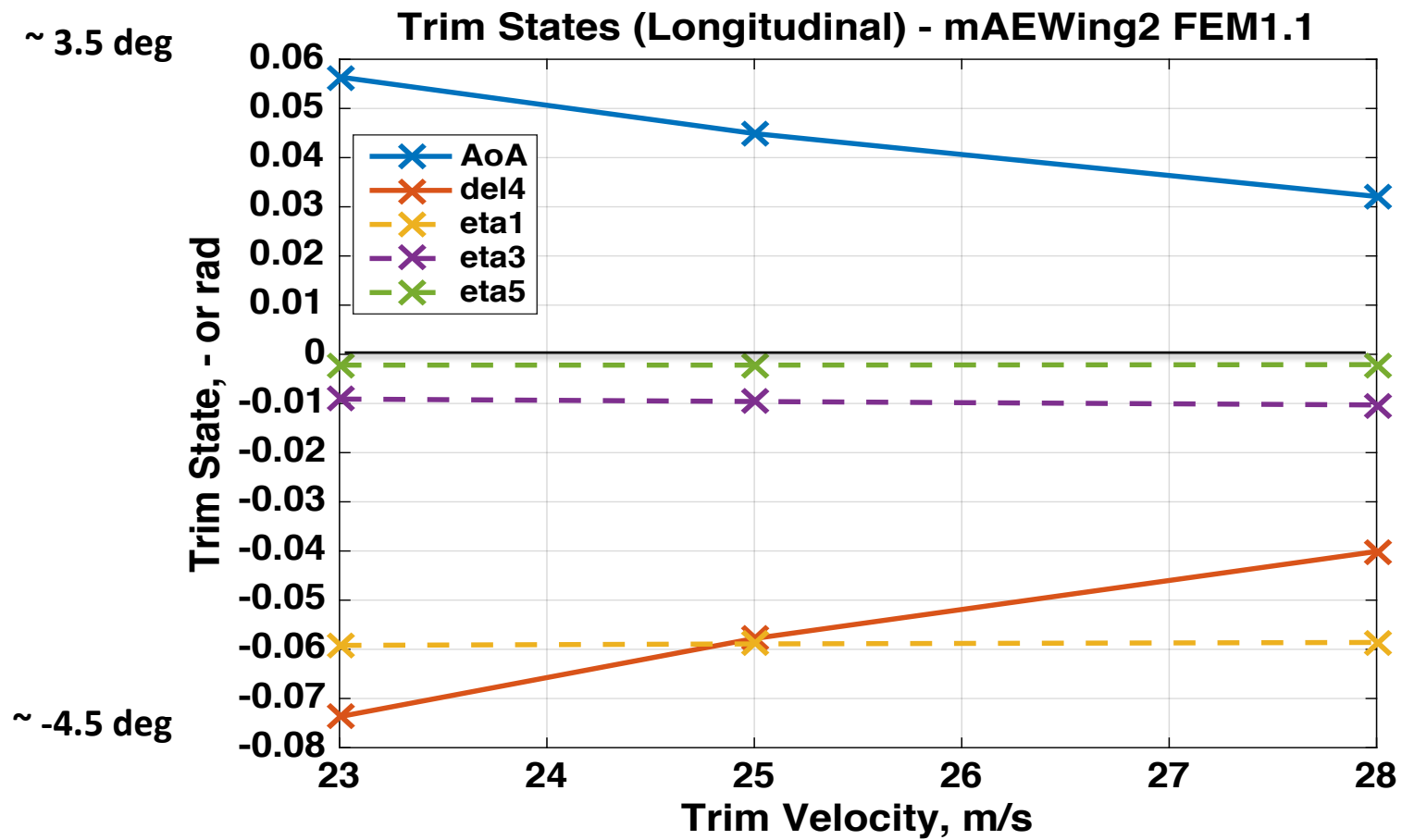
$$M_{i,i}\omega_i^2\eta_{i\text{Ref}} = \mathbf{Q}_{i\text{Ref}}, \quad i = 1 \dots n \quad \Rightarrow \mathbf{Q}_{i\text{Ref}} - M_{i,i}\omega_i^2\eta_{i\text{Ref}} = 0 \quad \text{symmetric modes only}$$

Or, in terms of the coefficients

$$\begin{bmatrix} C_{L_\alpha} & C_{L_\delta} & C_{L_{\eta_1}} & \dots \\ C_{M_\alpha} & C_{M_\delta} & C_{M_{\eta_1}} & \dots \\ C_{Q^1_\alpha} & C_{Q^1_\delta} & \left(C_{Q^1_{\eta_1}} - \frac{M_{i,i}\omega_1^2}{q_\infty S_W \bar{c}} \right) & \dots \\ \vdots & \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} \alpha_{\text{Trim}} \\ \delta_{\text{Trim}} \\ \eta_{1\text{Trim}} \\ \vdots \end{bmatrix} = \begin{bmatrix} mg / q_\infty S_W - C_{L_0} \\ -C_{M_0} \\ 0 \\ \vdots \end{bmatrix}$$

Solve for the trim states

mAEWing2 Trim, Using Symmetric Flap 4



The Change in Inertia Tensor

Jrigid =

$$\begin{bmatrix} 29,283. & 1.1416\text{e-}05 & -328.7. \\ 1.1416\text{e-}05 & 4042. & -1.8735\text{e-}05 \\ -328.7. & -1.8735\text{e-}05 & 32,923. \end{bmatrix} \text{ lb-in}^2$$

Theoretically zero
for symmetric vehicle

Jref 28 m/s =

$$\begin{bmatrix} 29,283. & -9.1365\text{e-}04 & -328.7 \\ -9.1365\text{e-}04 & 4042. & 2.0266\text{e-}03 \\ -328.7 & 2.0266\text{e-}03 & 32,923. \end{bmatrix} \text{ lb-in}^2$$

Small terms affected

Delta J =

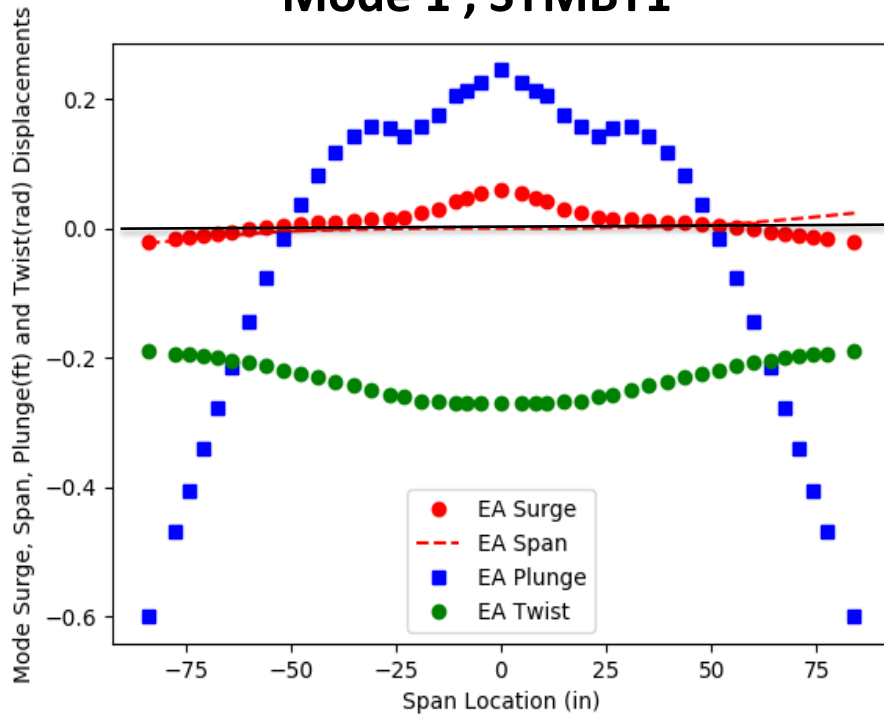
$$\begin{bmatrix} 4.0702\text{e-}03 & -9.2507\text{e-}04 & 2.0037\text{e-}03 \\ -9.2507\text{e-}04 & 4.1497\text{e-}03 & 2.0454\text{e-}03 \\ 2.0037\text{e-}03 & 2.0454\text{e-}03 & 8.4147\text{e-}05 \end{bmatrix} \text{ lb-in}^2$$

Preliminary conclusion,
this effect remains small,
But effects on longitudinal
eigenvalues and flutter
will be further evaluated.

Reason: non-collinear mode shapes are of small magnitude

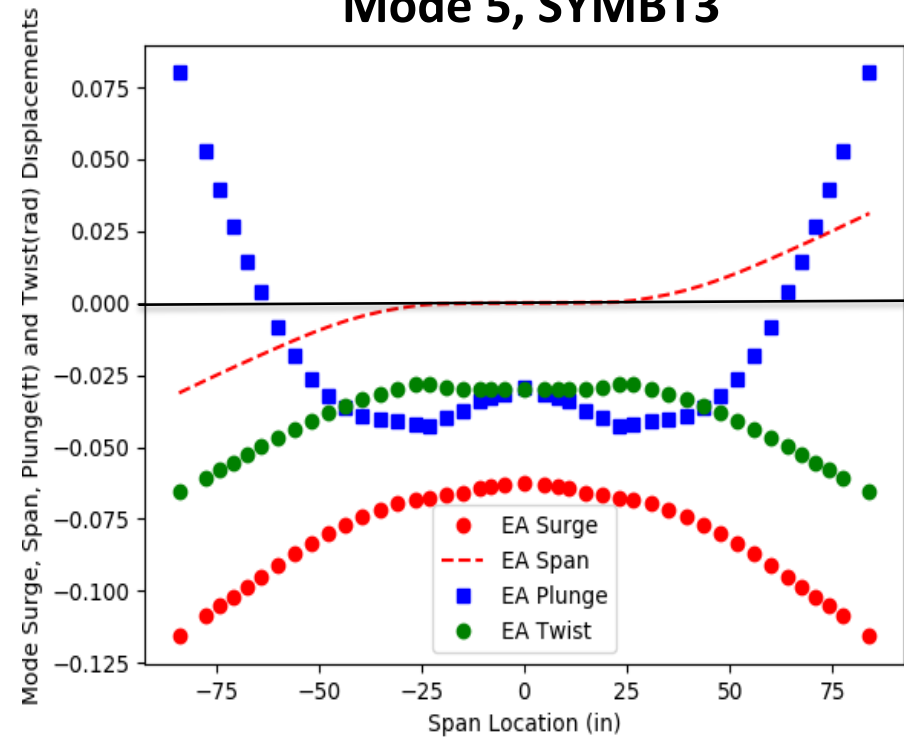
Example FEM 1.1 Mode Shapes

Mode 1, SYMBT1



Mostly collinear, $d_{\max} = 0.6$ ft

Mode 5, SYMBT3



Not collinear, $d_{\max} = 0.075$ ft

Conclusions

- So far, results support ignoring these effects in level flight
- Further eigenvalue analysis will be performed
- In future, need to continue monitoring FEM mode shapes
- Effects in maneuvering flight must also be monitored, but terms will likely remain negligible unless maneuvering is very aggressive.