

# 8th Lecture Computer Networks

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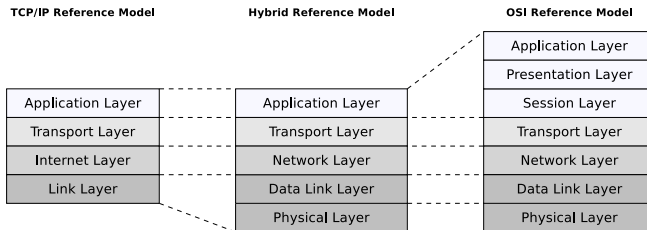
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# Agenda for Today

- Data link layer (part 3)
  - Media access control methods
    - Media access control method of Ethernet
    - Media access control method of WLAN
  - Address resolution with ARP

# Data Link Layer

- Functions of the data link layer
  - Pack packets of the network layer into frames
  - Break the bit stream of the physical layer into frames
  - Ensure correct transmission of the frames inside a physical network from one network device to another one via error detection with checksums
  - Provide physical addresses (MAC addresses)
  - Control access to the transmission medium



- Devices: Bridge, Layer-2-Switch (Multiport-Bridge)
- Protocols: Ethernet, Token Ring, WLAN, Bluetooth

- With Ethernet and WLAN the network devices or stations use a shared transmission medium
- To coordinate media access and to avoid collisions, media access control methods are required
  - Ethernet uses the media access control method **CSMA/CD**
  - WLAN uses the media access control method **CSMA/CD**
- Bluetooth is not discussed here, because Bluetooth devices are organized in **piconets**
  - In each piconet, the master coordinates a media access

# Media Access Control Method CSMA/CD

- In contrast to Token Ring, for Ethernet it's impossible to clearly predict the waiting time and amount of data that can be transmitted
- All participants are related to the medium access in direct competition
- The Waiting time and amount of data depend on the number of participants and the amount of data which is send by the individual participants
- Ethernet uses the media access control method „Carrier Sense Multiple Access / Collision Detection“ (CSMA/CD)

# Meaning of CSMA/CD

- **Carrier Sense (CS) means:**

- Each network device monitors the channel before transmitting, and it only transmits when the channel is free
- This means that the network devices can distinguish between a free and a busy connecting cable

- **Multiple Access (MA) means:**

- All network devices access the same transmission medium in a competitive way

- **Collision Detection (CD) means:**

- Each network device also monitors the channel during transmission, in order to detect collisions as early as possible and to perform error handling when needed

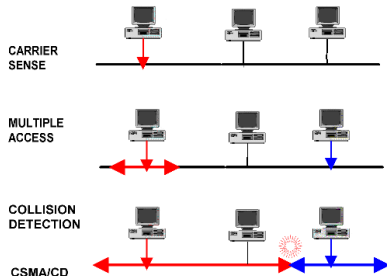


Image source: <http://www.payer.de/cmc/cmcs08.htm>

# Functioning of CSMA/CD (1/2)

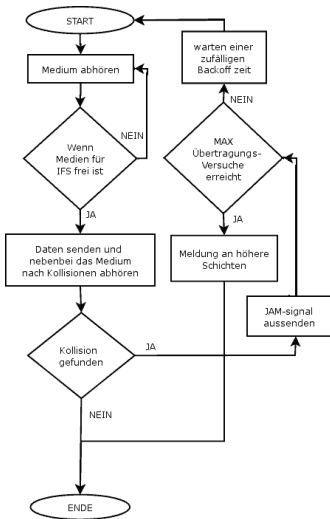


Image source: Wikipedia

- If a network device wants to transmit frames via Ethernet, it operates according to the following sequence

## 1 Monitor the transmission medium

- Transmission medium is free  $\Rightarrow$  step 2
- Transmission medium is busy  $\Rightarrow$  step 3

## 2 Start transmission and continue to monitor the transmission medium

- Successful transmission
  - Send success message to upper network layers  $\Rightarrow$  step 5
- Collision is detected
  - Stop frame transmission and send the 48 bit long (*jam signal*) to announce the collision  $\Rightarrow$  step 3

# Functioning of CSMA/CD (2/2)

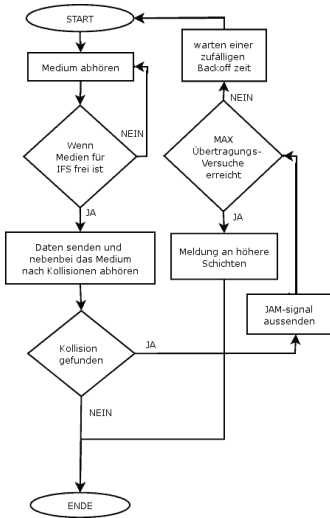
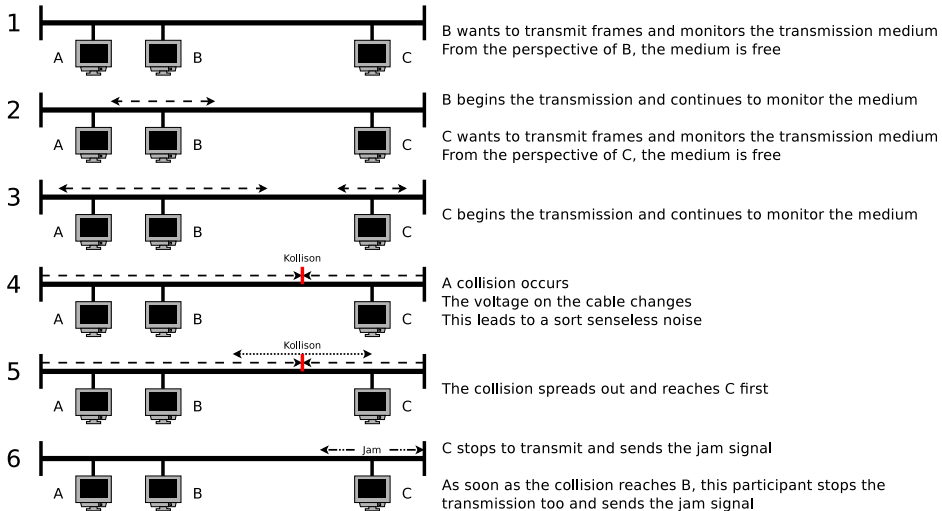


Image source: Wikipedia

- 3 Transmission medium is busy. Check the number of transmission attempts:
  - Maximum not yet reached
    - Wait a random time  $\Rightarrow$  step 1
    - The random time is calculated using the backoff method
  - Maximum is reached  $\Rightarrow$  step 4
- 4 Error
  - Maximum number of transmission attempts reached
  - Send error message to upper network layers  $\Rightarrow$  step 5
- 5 Leave transmission mode



# Example of CSMA/CD



# Network Size and Collision Detection

- A collision must be detected by the sender
- It is important that the transmission of a frame is **not completed** when a collision occurs
  - Otherwise, the network device might already be finished with the transmission and believes the transmission was successful
- Each frame must have a certain minimum length
  - It must be dimensioned in a way that the transmission duration for a frame with minimum length does not fall below the maximum RTDT (round trip delay time)
    - The RTDT is the time it takes for a frame to travel from one end of the network to the most distant end and return back
- This ensures that a collision reaches the sender before it's transmission is finished
  - If a sender detects a collision, it knows that it's frame has not arrived correctly at the receiver, and can try the transmission again later

# Minimum Frame Length and Collision Detection (Example)

- For Ethernet, a maximum network size, and a minimum frame length is defined
- The **minimum frame length**, where collision detection is still possible, is calculated as follows:

$$P = 2 * U * \frac{D}{V}$$

$P$  = Minimum frame length in bits  
 $U$  = Data transmission speed of the transmission medium in bits per second (bps)  
 $D$  = Network length in meters  
 $V$  = Signal speed on the transmission medium in meters per second (mps)

- Calculation example for 10BASE5 with 10 Mbps and coaxial cables:
  - $U = 10 \text{ Mbps} = 10,000,000 \text{ bps}$
  - $D = 2,500 \text{ meters}$  (this is the maximum length for 10BASE5)
  - $V = \text{speed of light} * \text{velocity factor}$ 
    - Speed of light  $c = 299,792,458 \text{ mps}$
    - Velocity factor  $ABF = 0.77$  for coaxial cables
    - $V = c * ABF \approx 231,000,000 \text{ mps}$

$$P = 2 * 10 * \frac{2500}{231} \approx 218 \text{ Bits} \approx 28 \text{ bytes}$$

- this means that the minimum frame length of 64 bytes for Ethernet is more than enough

# Velocity Factor (Wave Propagation Speed)

- The velocity factor, also known as wave propagation speed, depends on transmission medium and is:
  - 1 for the vacuum
  - 0.60 for twisted pair cables
  - 0.67 for optical fiber
  - 0.60 for coaxial cables
- Describes the speed of a signal on a transmission medium relative to the speed of light

# Network Size and Collision Detection (Example)

- The **maximum network size**, where collision detection is still possible, is calculated as follows:

$$2 * S_{max} = V * t_{frame}$$

$S_{max}$  = Maximum network size with collision detection  
 $V$  = Signal speed of the transmission medium in meters per second (mps)  
 $t_{frame}$  = transmission duration of a frame in seconds

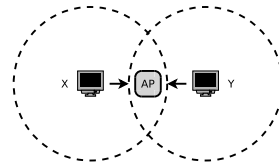
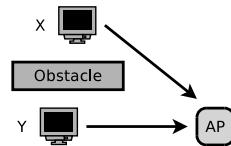
- Calculation example for 10BASE5 with 10 Mbps and coaxial cables:
  - $V = 231,000,000 \text{ mps} = 231 * 10^6 \text{ mps}$
  - Transmission duration  $t_{frame}$  = Transmission duration for a single bit multiplied with the number of bits in a frame ( $\Rightarrow 512 \text{ bit} = 64 \text{ byte}$ )
    - The transmission duration for a single bit at 10 mbps is 0.1 microseconds
    - A frame with the minimum frame length of 64 bytes needs requires  $51.2\mu\text{s}$  for a complete transmission
  - A  $51.2\mu\text{s}$  long signal travels in the coaxial cable the following distance:  
 $231 * 10^6 * 51.2 * 10^{-6} = 11,827.20 \text{ m} = 11.82 \text{ km}$
  - A frame which is 64 bytes large needs for  $2 * 2,500 \text{ m} = 5,000 \text{ m}$  less than half the minimum transmission time of  $51.2\mu\text{s}$ 
    - The maximum network size of 2.5 km is dimensioned small enough

- The media access method CSMA/CD is absolutely necessary for computer networks that are based on the bus network topology, because at this topology, all network devices are directly connected with a common transmission medium
- Almost all Ethernet-based networks nowadays *fully switched* and therefore free from collisions

- CSMA/CD does not work with wireless networks
  - In contrast to wired computer networks based of Ethernet, it's not guaranteed that all collisions are detected in wireless networks
- With CSMA/CD, the sender detects occurring collisions
  - In wired networks with a common transmission medium, each participant receives the transmissions of all other participants
    - Therefore each participant detects any collision
  - For wireless networks such as WLAN, this is not always the case
    - For this reason, the media access methods *Carrier Sense Multiple Access / Collision Avoidance* (CSMA/CA) is used which tries to minimize the occurrence of collisions
- Two special characteristics of the transmission medium in wireless networks lead to undetected collisions at the receiver
  - **Hidden terminal problem**
  - **Fading**
- The hidden terminal problem and fading both make multiple access in wireless networks more complicated compared to wired networks

# Zwei Spezielle Eigenschaften des Übertragungsmediums

- **Hidden terminal problem** (Problem caused by invisible or hidden terminal device)
  - X and Y both send frames to the Access Point
  - Because of obstacles the stations X and Y can not detect their transmissions, although they interfere each other at the Access Point
- **Fading** (decreasing signal strength)
  - X and Y both send frames to the Access Point
  - The electromagnetic waves of the wireless network are gradually weakened by obstacles and in free space
  - Caused by the positions of X and Y to each other stations, their signals are too weak that the stations can detect each others transmissions



Source: **Computernetzwerke**, James F. Kurose, Keith W. Ross, Pearson (2008)



## ❶ CSMA/CA

- Strategy: *Listen before talk*
- Collision avoidance through random backoff time
- Minimum distance between frames
- Receive acknowledgements via ACK (not for broadcast)
- Default method which is implemented in all WLAN devices

## ❷ CSMA/CA RTS/CTS (Request To Send/Clear To Send)

- Solves the problem of hidden terminals
- Optional method and implemented in most WLAN devices

## ❸ CSMA/CA PCF (Point Coordination Function)

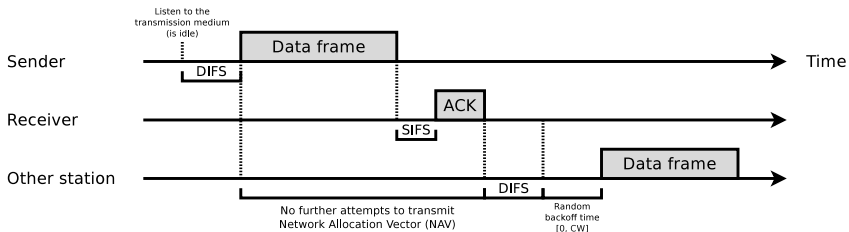
- Access Point controls the access to the transmission medium
- Optional method and seldom implemented

Source: Lecture slides of Prof. Dr. Michael Massoth and Wikipedia

- Erkennt bei CSMA/CD (Ethernet) ein sendender Teilnehmer eine Kollision, bricht er das Senden des Rahmens ab
- WLAN verwendet aber keine Kollisionserkennung, sondern mit CSMA/CA eine Kollisionsvermeidung (eigentlich ist es nur eine Kollisionsminimierung)
  - Hat eine Station mit dem Senden eines Rahmens begonnen, überträgt sie den vollständigen Rahmen in jedem Fall
    - Es gibt also kein Zurück mehr, wenn eine Station einmal mit dem Senden begonnen hat
  - Der Sender muss darum erkennen können, wenn ein Rahmen nicht korrekt beim Empfänger angekommen ist

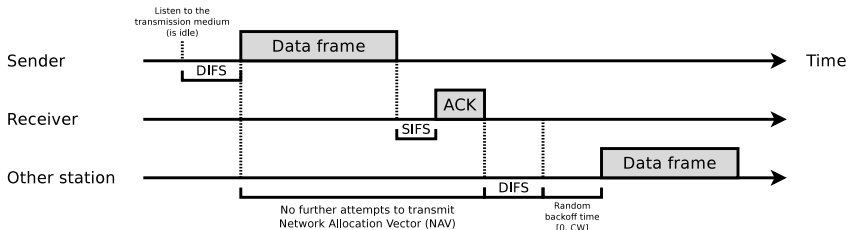
# Functioning of CSMA/CA – 1/5

- At first, the sender *listens* to the transmission medium (carrier sense)
- The transmission medium needs to be idle for a short period
  - This period is called **Distributed Interframe Spacing (DIFS)**  $\approx 50\mu s$
- If the transmission medium is free for the duration of one DIFS, the station can send start to transmit a frame



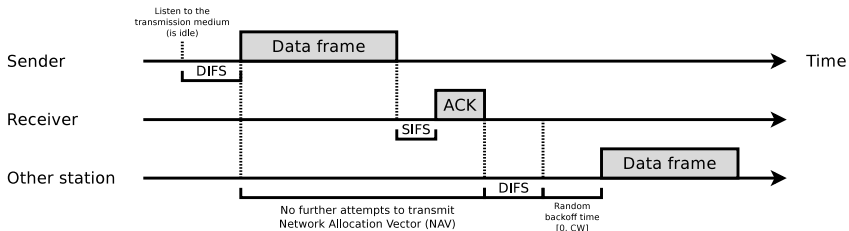
# Functioning of CSMA/CA – 2/5

- If a station receives a frame which passes the CRC check, then it waits for a short period
  - This period is called **Short Interframe Spacing (SIFS)**  $\approx 10\mu s$
  - Then the receiver sends an **acknowledgement frame (ACK)**
    - Die Empfangsbestätigung durch ACK erfolgt nicht bei einem Broadcast
- DIFS und SIFS garantieren bei CSMA/CA einen Mindestabstand zwischen aufeinanderfolgenden Rahmen



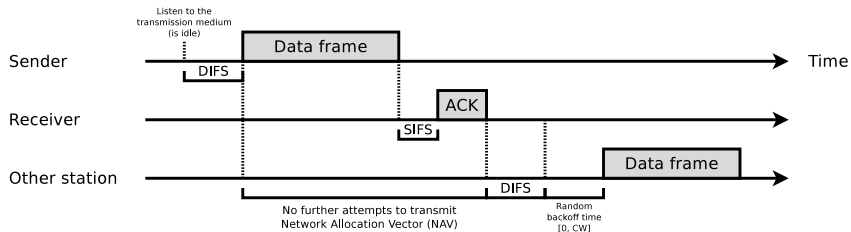
# Functioning of CSMA/CA – 3/5

- Ist das Übertragungsmedium (der Kanal) belegt, finden bis zum Ablauf des Netzbelegungsvektors – **Network Allocation Vectors (NAV)** – keine weiteren Sendeversuche statt
- Der NAV ist eine Zählvariable, die von jeder Station selbst verwaltet wird
  - Verringert die Kollisionen bei CSMA/CA
  - Enthält die Zeit, die das Übertragungsmedium voraussichtlich belegt sein wird



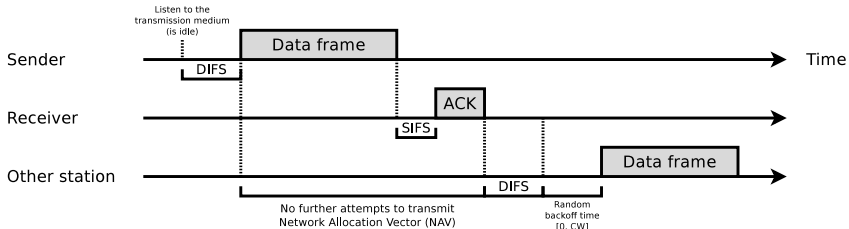
# Functioning of CSMA/CA – 4/5

- Empfängt eine Station zum Beispiel die Information „*Das Übertragungsmedium ist für die nächsten x Datenrahmen belegt*“, trägt sie die erwartete Belegungszeitspanne in ihren NAV ein
- Der NAV wird mit der Zeit dekrementiert, bis er den Wert 0 erreicht
- Solange der  $NAV > 0$  ist, unternimmt eine Station keine Sendeversuche
  - Dabei ist es egal, ob das Übertragungsmedium frei oder belegt ist



# Functioning of CSMA/CA – 5/5

- Nach Ablauf des NAV und einem weiteren DIFS mit freiem Übertragungsmedium wird eine **Backoffzeit** aus dem **Contention Window** (CW) erzeugt
  - Das CW ist ein Wert, den jeder IEEE 802.11 Rahmen enthält
  - Mit dem CW wird eine zufällige Zeitspanne als Backoff definiert
  - Die CW-Zeitspanne liegt zwischen einem minimalen und einem maximalen Wert
  - Die CW-Zeitspanne wird bei jeder auftretenden Kollision verdoppelt
- Nach dem Ablauf der Backoffzeit wird der Rahmen gesendet

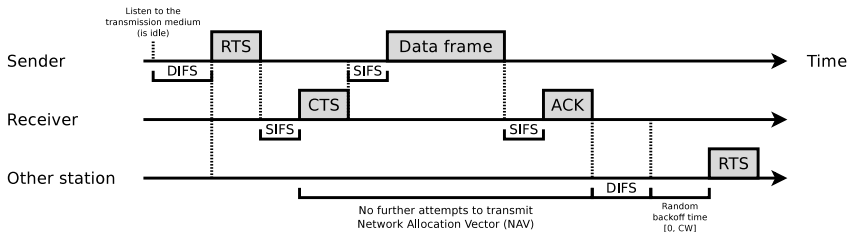


- The media access control method CSMA/CA reduces the number of collisions
  - But it can not avoid all collisions
- An improved collision avoidance provides CSMA/CA RTS/CTS
  - Sender and receiver exchange with this method **control frames** before the sender begins to transmit
    - This way, all available stations know that a transmission will start soon
  - The control frames are **Request To Send (RTS)** and **Clear To Send (CTS)**
  - both control frames contain a field which indicates how long the transmission medium (the channel) will be occupied



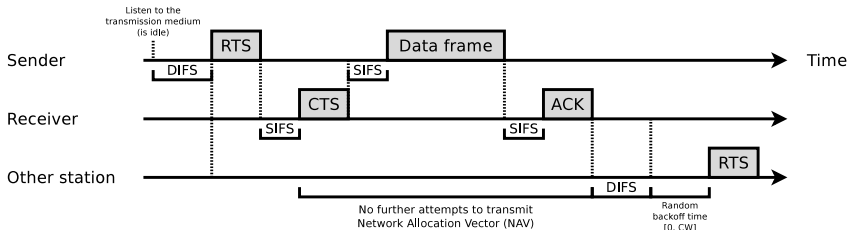
# Functioning of CSMA/CA RTS/CTS – 1/4

- After the DIFS, the sender transmits a **RTS** frame to the receiver
  - The RTS frame contains a field that specifies the period, the sender wants to reserve (use) the transmission medium (the channel)
    - In the RTS frame, the sender specifies the length of data frame to be transmitted



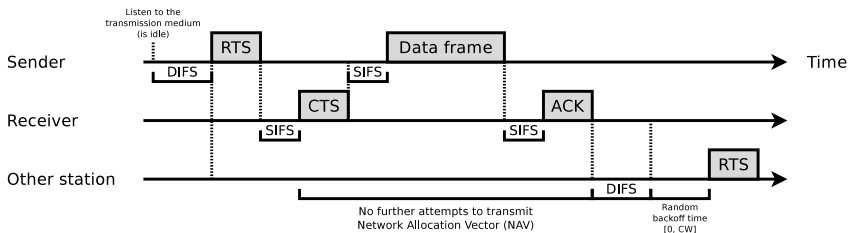
# Functioning of CSMA/CA RTS/CTS – 2/4

- the receiver acknowledges this by waiting the SIFS and then transmitting a **CTS** frames, which also contains the period, the sender wants to reserve the transmission medium
  - The receiver sends the length field back to the sender and confirms this way the length of the data frame to be transmitted



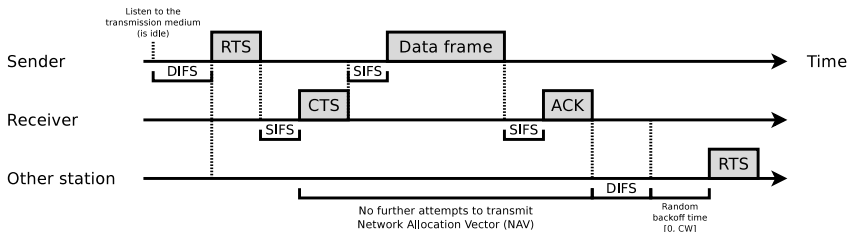
# Functioning of CSMA/CA RTS/CTS – 3/4

- After the receiver successfully received the data frame, he waits a SIFS and transmits an ACK frame to the sender
- All other stations wait the time ( $\Rightarrow$  frame length) which is specified in the CTS frame
- Collisions can only occur during the transmission of RTS and CTS frames



# Functioning of CSMA/CA RTS/CTS – 4/4

- Advantage: CSMA/CA RTS/CTS reduces collisions, because it solves the problem of hidden terminals
- Drawbacks:
  - Delays which are caused by the reservation of the transmission medium occur
  - The RTS and CTS frames which are used to reserve the transmission medium are overhead



# CSMA/CA RTS/CTS in Practice

- CSMA/CA RTS/CTS is optional for WLAN and is mostly implemented
  - In practice, it is used for reserving channels for the transmission of big data frames
- For each station, a RTS threshold value can be set (driver?)
  - This way it can be defined that RTS/CTS is used only when a frame is bigger than the threshold value
- Often, the default threshold value is higher than the maximum frame length (2.346 byte) for IEEE 802.11
  - Then, the RTS/CTS sequence can be omitted for all transmitted data frames

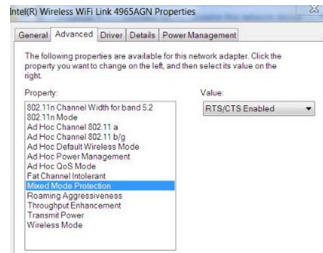


Image source: <http://www.itedge.net>

Source: **Computernetzwerke**, James F. Kurose, Keith W. Ross, Pearson (2008)

- **PCF = Point Coordination Function**
- The access point controls the media access by requesting the registered stations to transmit data frames
  - The approach is called **polling**
- CSMA/CA PCF is an optional method and seldom implemented
  - For this reason it is not discussed here in detail

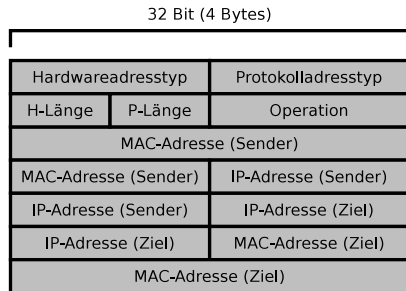
- Das **Address Resolution Protocol (ARP)** übersetzt IP-Adressen der Vermittlungsschicht in MAC-Adressen der Sicherungsschicht
- Will ein Netzwerkgerät Daten an einen Empfänger senden, gibt es auf der Vermittlungsschicht die IP-Adresse des Empfängers an
- Auf der Sicherungsschicht ist aber die MAC-Adresse nötig
  - Darum muss in der Sicherungsschicht die Adressauflösung erfolgen
  - Um die MAC-Adresse eines Netzwerkgeräts innerhalb des LAN zu erfahren, versendet ARP einen Rahmen mit der MAC-Broadcast-Adresse FF-FF-FF-FF-FF-FF als Zieladresse
    - Dieser Rahmen wird von jedem Netzwerkgerät entgegengenommen und ausgewertet
    - Der Rahmen enthält die IP-Adresse des gesuchten Netzwerkgeräts
  - Fühlt sich ein Gerät mit dieser IP-Adresse angesprochen, schickt es eine ARP-Antwort an den Sender
    - Die gemeldete MAC-Adresse wird im lokalen ARP-Cache des Senders gespeichert

- Der ARP-Cache dient zur Beschleunigung der Adressauflösung
  - Er enthält eine Tabelle mit vier Spalten
    - Protokolltyp (IP)
    - Protokolladresse des Senders (IP-Adresse)
    - Hardware-Adresse des Sender (MAC-Adresse)
    - Ablaufzeit – Time To Live (TTL)
  - Die TTL wird vom Betriebssystem festgelegt
  - Wird ein Eintrag in der Tabelle verwendet, verlängert sich die TTL
- Aktuelle Linux-Distributionen verwerfen Einträge im ARP-Cache nach ca. 5 Minuten
- Wird ein Eintrag in der Tabelle verwendet, wird die TTL verlängert
- Unter Linux kann der ARP-Cache mit `arp` angezeigt und verändert werden
- Mit `arping` kann man manuell Anforderungen zur Adressauflösung versenden



# Aufbau von ARP-Nachrichten (1/2)

- ARP-Nachrichten werden im Nutzdatenteil von Ethernet-Rahmen übertragen
  - Das Typ-Datenfeld im Ethernet-Rahmen wird auf den Wert 0x0806 für das ARP-Protokoll gesetzt
- Das Datenfeld H-Länge enthält die Länge der Hardwareadressen (MAC-Adressen) in Bytes
  - Bei Ethernet sind MAC-Adressen 6 Bytes lang
- Das Datenfeld P-Länge enthält die Länge der Protokolladressen (IP-Adressen) in Bytes
  - Bei IPv4 sind IP-Adressen 4 Bytes lang



# Aufbau von ARP-Nachrichten (2/2)

- Die Quell-MAC-Adresse ist die MAC-Adresse des Senders bei einer ARP-Anforderung und die MAC-Adresse des antwortenden Hosts bei einer ARP-Antwort
- Die Ziel-MAC-Adresse ist in einer ARP-Anforderung gleichgültig und enthält in einer ARP-Antwort die MAC-Adresse des anfragenden Hosts
- Die Quell-IP-Adresse ist bei einer ARP-Anforderung die IP des anfragenden Host und bei einer ARP-Antwort die IP des antwortenden Hosts
- Die Ziel-IP-Adresse ist bei einer ARP-Anforderung die IP-Adresse des gesuchten Hosts und bei einer ARP-Antwort die IP-Adresse des anfragenden Hosts

