Universität Potsdam

Institut für Informatik Lehrstuhl Maschinelles Lernen



Linear Classification Models

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Overview

- Linear classification models
- Empirical risk minimization
 - Gradient descent method
 - Inexact line search
 - Stochastic gradient descent methods
- Loss functions and regularizers for classification
- Special cases
 - Perceptron
 - Support vector machines
- Multi-class classification

Classification

- Input: an instance $x \in X$
 - ◆ E.g., X can be a vector space over attributes
 - The Instance is then an assignment of attributes.

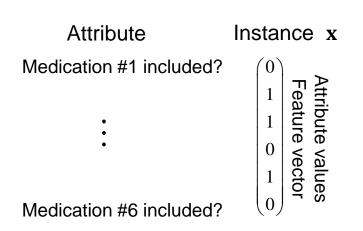
•
$$\mathbf{x} = \begin{pmatrix} x_1 \\ \vdots \\ x_m \end{pmatrix}$$
 is a feature vector

- Output: Class $y \in Y$; where Y is a finite set.
 - The class is also referred to as the target attribute
 - y is also referred to as the (class) label

$$x \rightarrow classifier \rightarrow y$$

Classification: Example

- Input: Instance $x \in X$
 - X: the set of all possible combinations of regiment of medication



Medication combination



• Output: $y \in Y = \{\text{toxic, ok}\}$



Linear Classification Models

Hyperplane given by normal vector & displacement:

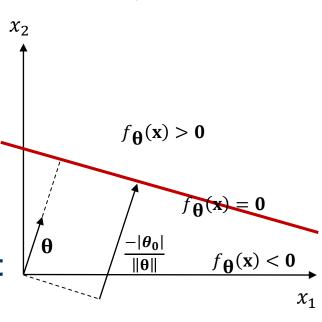
$$H_{\mathbf{\theta}} = \{ \mathbf{x} | f_{\mathbf{\theta}} (\mathbf{x}) = \mathbf{x}^{\mathrm{T}} \mathbf{\theta} + \theta_0 = 0 \}$$

- Example: $X = \mathbb{R}^2$
- Decision function:

$$f_{\boldsymbol{\theta}}(\mathbf{x}) = \mathbf{x}^{\mathrm{T}} \mathbf{\theta} + \theta_0$$

■ Binary classifier, $y \in \{+1, -1\}$:

$$y_{\theta}(\mathbf{x}) = \operatorname{sign}\left(f_{\theta}(\mathbf{x})\right)$$



Linear Classification Models

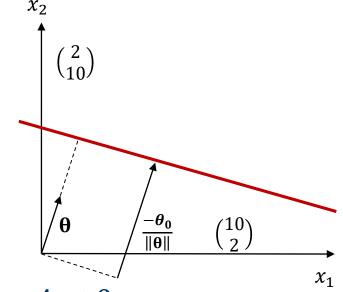
Hyperplane given by normal vector & displacement:

$$H_{\boldsymbol{\theta}} = \{ \mathbf{x} | f_{\boldsymbol{\theta}} (\mathbf{x}) = \mathbf{x}^{\mathrm{T}} \boldsymbol{\theta} + \theta_0 = 0 \}$$

- Example: $X = \mathbb{R}^2$
- Decision function:

$$f_{\mathbf{\theta}}(\mathbf{x}) = \mathbf{x}^{\mathrm{T}} \begin{pmatrix} 1 \\ 3 \end{pmatrix} - 20$$

Example points:



$$f_{\theta} \begin{pmatrix} 10 \\ 2 \end{pmatrix} = (10 \quad 2) \begin{pmatrix} 1 \\ 3 \end{pmatrix} - 20 = -4 < 0$$

$$f_{\theta} \begin{pmatrix} 2 \\ 10 \end{pmatrix} = (2 \quad 10) \begin{pmatrix} 1 \\ 3 \end{pmatrix} - 20 = 12 > 0$$

Linear Classification Model

- Offset can "disappear" into parameter vector.
- Example
 - Before: $f_{\theta}(\mathbf{x}) = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}^{\mathrm{T}} \begin{pmatrix} 1 \\ 3 \end{pmatrix} 20$

• After:
$$f_{\theta}(\mathbf{x}) = \begin{pmatrix} 1 \\ x_1 \\ x_2 \end{pmatrix}^{\mathrm{T}} \begin{pmatrix} -20 \\ 1 \\ 3 \end{pmatrix}$$

- New constant attribute $x_0 = 1$ added to all instances
- Offset θ_0 integrated into θ .

Learning Linear Classifiers

Input to the Learner: Training data T_n .

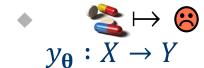
$$\mathbf{X} = \begin{pmatrix} x_{11} & \cdots & x_{1m} \\ \vdots & \ddots & \vdots \\ x_{n1} & \cdots & x_{nm} \end{pmatrix}$$
 Linear classifier:

$$\mathbf{y} = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}$$

Training Data:

$$T_n = \{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)\}$$

Output: a Model



$$y_{\mathbf{\theta}}(\mathbf{x}) = \begin{cases} \mathbf{\Theta} & \text{if } \mathbf{x}^{\mathrm{T}} \mathbf{\theta} \ge 0 \\ & \text{otherwise} \end{cases}$$

Linear classifier with parameter vector $\boldsymbol{\theta}$.

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Solve

$$\underset{\boldsymbol{\theta}}{\operatorname{argmin}} \sum_{i=1}^{n} \ell(f_{\boldsymbol{\theta}}(\mathbf{x}_i), y_i) + \lambda \Omega(\boldsymbol{\theta})$$

- Loss function $\ell(f_{\theta}(\mathbf{x}_i), y_i)$: cost of the model's output $f_{\theta}(\mathbf{x})$ when the true value is y.
 - The empirical risk is $\widehat{R}_n(\mathbf{\theta}) = \sum_{i=1}^n \ell(f_{\mathbf{\theta}}(\mathbf{x}_i), y_i)$
 - Empirical estimate of risk $R(\theta) = \int \ell(f_{\theta}(\mathbf{x}), y) dP_{\mathbf{x}, y}$
- Regularizer $\Omega(\theta)$ & trade-off parameter $\lambda \geq 0$:
 - Background information about preferred solutions
 - Provides numerical stability (Tikhonov-Regularizer)
 - allows for tighter error bounds (PAC-Theory)

Solve

$$\underset{\boldsymbol{\theta}}{\operatorname{argmin}} \sum_{i=1}^{n} \ell(f_{\boldsymbol{\theta}}(\mathbf{x}_i), y_i) + \lambda \Omega(\boldsymbol{\theta})$$

Linear model:

$$\underset{\boldsymbol{\theta}}{\operatorname{argmin}} \sum_{i=1}^{n} \ell(\mathbf{x}_{i}^{\mathrm{T}}\boldsymbol{\theta}, y_{i}) + \lambda \Omega(\boldsymbol{\theta})$$

Linear model: solve

$$\underset{\boldsymbol{\theta}}{\operatorname{argmin}} \sum_{i=1}^{n} \ell(\mathbf{x}^{\mathrm{T}}\boldsymbol{\theta}, y_i) + \lambda \Omega(\boldsymbol{\theta})$$

- How to find solution:
 - Classification: No analytic solution but numeric solutions (gradient descent, cutting plane, interior point method)
 - Regression: analytic solution.

Linear classification model: minimize

$$L(\boldsymbol{\theta}) = \sum_{i=1}^{n} \ell(\mathbf{x}^{\mathrm{T}}\boldsymbol{\theta}, y_i) + \lambda \Omega(\boldsymbol{\theta})$$

- Gradient:
 - Vector of the derivatives with respect to each individual parameter
 - Direction of the steepest increase of the function $L(\theta)$.

$$abla L(\mathbf{\theta}) = egin{pmatrix} rac{\partial L(\mathbf{\theta})}{\partial heta_1} \ dots \ rac{\partial L(\mathbf{\theta})}{\partial heta_m} \end{pmatrix}$$

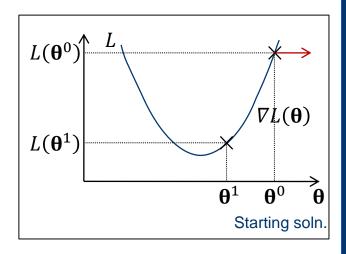
Linear classification model: minimize

$$L(\boldsymbol{\theta}) = \sum_{i=1}^{n} \ell(\mathbf{x}^{\mathrm{T}}\boldsymbol{\theta}, y_i) + \lambda \Omega(\boldsymbol{\theta})$$

Gradient descent method:

```
RegERM(Data: (\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n))
Set \mathbf{\theta}^0 = \mathbf{0} and t = 0
DO

Compute gradient \nabla L(\mathbf{\theta}^t)
Compute step size \alpha^t
Set \mathbf{\theta}^{t+1} = \mathbf{\theta}^t - \alpha^t \nabla L(\mathbf{\theta}^t)
Set t = t+1
WHILE \|\mathbf{\theta}^t - \mathbf{\theta}^{t+1}\| > \varepsilon
RETURN \mathbf{\theta}^t
```



Linear classification model: minimize

$$L(\boldsymbol{\theta}) = \sum_{i=1}^{n} \ell(\mathbf{x}^{\mathrm{T}}\boldsymbol{\theta}, y_i) + \lambda \Omega(\boldsymbol{\theta})$$

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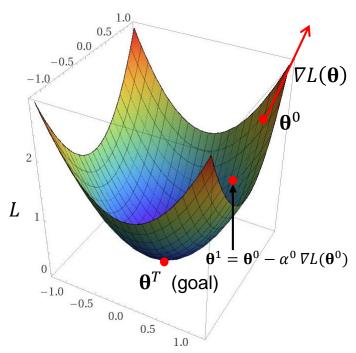
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Linear classification model: minimize

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Set t = t+1
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RETURN \mathbf{\theta}^t
```

- The step size α^t can be determined through
 - Line search
 - Barzilai-Borwein method
 - ...

ERM: Gradient Method with Line Search

Determine step size through line search:

```
RegERM-LineSearch (Data: (\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n))
Set \mathbf{\theta}^0 = \mathbf{0} and t = 0

DO

Compute gradient \nabla L(\mathbf{\theta}^t)

Choose step size \alpha^t:
\alpha^t = \operatorname*{argmin}_{\alpha>0} L(\mathbf{\theta}^t - \alpha \nabla L(\mathbf{\theta}^t))
Set \mathbf{\theta}^{t+1} = \mathbf{\theta}^t - \alpha^t \nabla L(\mathbf{\theta}^t)
Set t = t+1

WHILE \|\mathbf{\theta}^t - \mathbf{\theta}^{t+1}\| > \varepsilon

RETURN \mathbf{\theta}^t
```

- In practice it is often too expensive to compute the optimal step size.
 - Necessary Criterion: $L(\theta^t \alpha \nabla L(\theta^t)) < L(\theta^t)$.

ERM: Gradient with Inexact Line Search

Determine step size through inexact line search:

```
RegERM-LineSearch (Data: (\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n))
Set \mathbf{\theta}^0 = \mathbf{0} and t = 0

DO

Compute gradient \nabla L(\mathbf{\theta}^t)

Set \alpha^t = 1

WHILE L(\mathbf{\theta}^t - \alpha^t \nabla L(\mathbf{\theta}^t)) \ge L(\mathbf{\theta}^t)

Set \alpha^t = \alpha^t/2

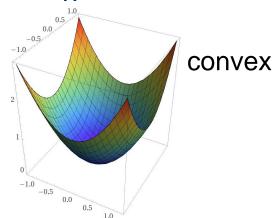
Set \mathbf{\theta}^{t+1} = \mathbf{\theta}^t - \alpha^t \nabla L(\mathbf{\theta}^t)

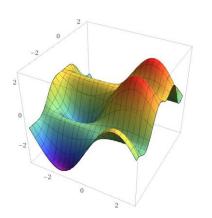
Set t = t + 1

WHILE \|\mathbf{\theta}^t - \mathbf{\theta}^{t+1}\| > \varepsilon

RETURN \mathbf{\theta}^t
```

- Properties of the gradient descent method:
 - Optimization criterion improved with every step.
 - Converges to the global minimum of the optimization criterion when this criterion is convex.
- The sum of convex functions is convex.
- Therefore, optimization criterion is convex if
 - Loss function is convex and
 - Regularizer is convex





not convex

ERM: Stochastic Gradient Method

- Idea: Determine the gradient for a random subset of the samples (e.g., a single instance).
- Less computation per optimization step, but only approximate descent direction.
- Optimization criterion with regularizer in sum:

$$L(\mathbf{\theta}) = \sum_{i=1}^{n} \left[\ell(f_{\mathbf{\theta}}(\mathbf{x}_i), y_i) + \frac{\lambda}{n} \Omega(\mathbf{\theta}) \right]$$

Stochastic gradient for a single instance:

$$\nabla_{\mathbf{x}_i} L(\mathbf{\theta}) = \frac{\partial}{\partial \mathbf{\theta}} \ell(f_{\mathbf{\theta}}(\mathbf{x}_i), y_i) + \frac{\lambda}{n} \frac{\partial}{\partial \mathbf{\theta}} \Omega(\mathbf{\theta})$$

ERM: Stochastic Gradient Method

Approximate gradient using single examples.

```
RegERM-Stoch (Data: (\mathbf{x}_1, y_1), ..., (\mathbf{x}_n, y_n))

Set \mathbf{\theta}^0 = \mathbf{0} and t = 0

DO

Shuffle data randomly

FOR i = 1, ..., n

Compute subset gradient \nabla_{\mathbf{x}_i} L(\mathbf{\theta}^t)

Compute step size \alpha^t

Set \mathbf{\theta}^{t+1} = \mathbf{\theta}^t - \alpha^t \nabla_{\mathbf{x}_i} L(\mathbf{\theta}^t)

Set t = t + 1

END

WHILE \|\mathbf{\theta}^t - \mathbf{\theta}^{t+1}\| > \varepsilon

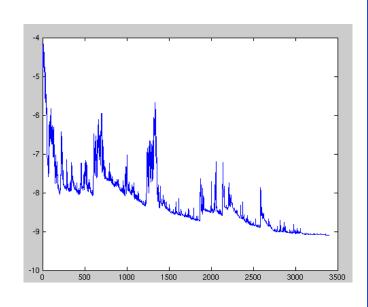
RETURN \mathbf{\theta}^t
```

ERM: Stochastic Gradient Method

- In every step only one summand of the optimization criterion is improved.
- The total optimization criterion can be worsened by these individual steps.
- Converges to the optimum if the step sizes satisfy:

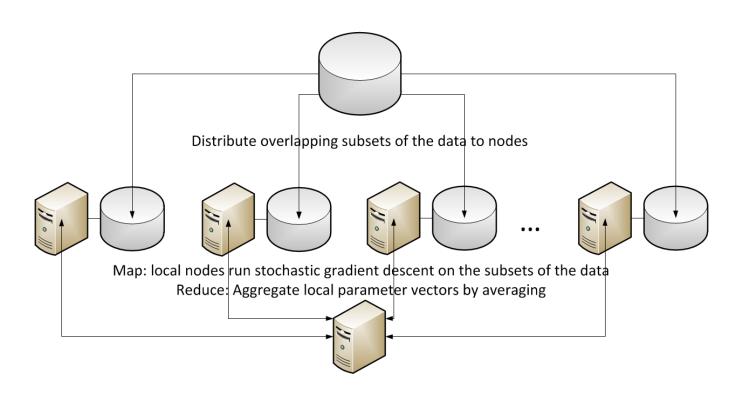
$$\sum_{t=1}^{\infty} \alpha^t = \infty$$
 and $\sum_{t=1}^{\infty} (\alpha^t)^2 < \infty$

(Robbins & Monro, 1951)

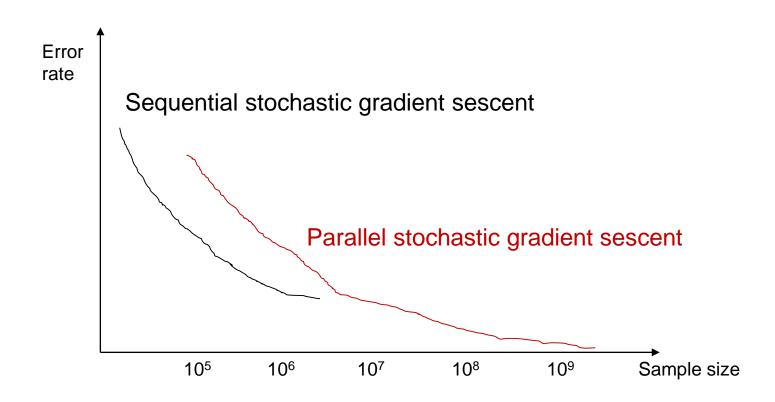


- Stochastic Gradient slows down when training data does not fit into main memory.
- Examples then have to be paged into and out of memory.
- For even larger training samples, data may not fit onto local persistent memory, have to be moved over the network during iterations.
- Remedy: distribute data over multiple nodes, perform computation in parallel on these nodes.

 Resulting parameters: average of parameters found by parallel stochastic gradient on data subsets.



- Resulting parameters: average of parameters found by parallel stochastic gradient on data subsets.
- Averaging the local parameter vectors is an approximation: typically not as good as sequantial stochastic gradient descent would on all be.
- Caveat: for non-convex problems, local parameters can be different local minima; averaging different local minima can be bad.



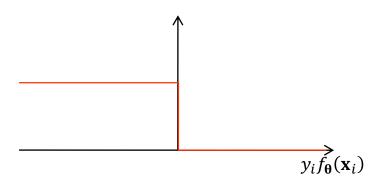
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Zero-one loss:

$$\ell_{0/1}(f_{\theta}(\mathbf{x}_i), y_i) = \begin{cases} 1 & -y_i f_{\theta}(\mathbf{x}_i) \neq y_i \\ 1 & -y_i f_{\theta}(\mathbf{x}_i) > 0 \\ 0 & -y_i f_{\theta}(\mathbf{x}_i) \leq 0 \end{cases}$$

$$\operatorname{sign}(f_{\theta}(\mathbf{x}_i)) = y_i$$



Zero-one loss:

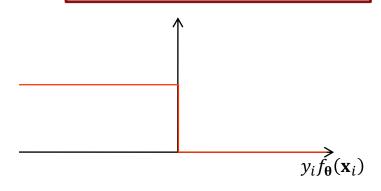
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$$\operatorname{sign}(f_{\boldsymbol{\theta}}(\mathbf{x}_i)) \neq y_i$$

$$\operatorname{sign}(f_{\boldsymbol{\theta}}(\mathbf{x}_i)) \leq 0$$

$$\operatorname{sign}(f_{\boldsymbol{\theta}}(\mathbf{x}_i)) = y_i$$

Zero-one loss is not convex ⇒ difficult to minimize!



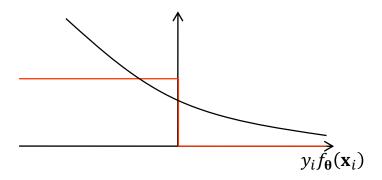
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$$\operatorname{sign}(f_{\boldsymbol{\theta}}(\mathbf{x}_i)) = y_i$$

Logistic loss:

$$\ell_{log}(f_{\theta}(\mathbf{x}_i), y_i) = \log(1 + e^{-y_i f_{\theta}(\mathbf{x}_i)})$$



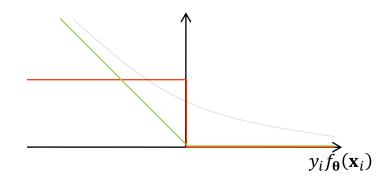
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Logistic loss:

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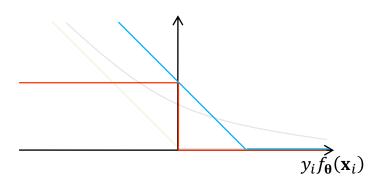
Perceptron loss:

$$\ell_p(f_{\theta}(\mathbf{x}_i), y_i) = \begin{cases} -y_i f_{\theta}(\mathbf{x}_i) & -y_i f_{\theta}(\mathbf{x}_i) > 0 \\ 0 & -y_i f_{\theta}(\mathbf{x}_i) \le 0 \end{cases} = \max(0, -y_i f_{\theta}(\mathbf{x}_i))$$

Zero-one loss:

Logistic loss:

$$\ell_{log}(f_{\theta}(\mathbf{x}_i), y_i) = \log(1 + e^{-y_i f_{\theta}(\mathbf{x}_i)})$$



Perceptron loss:

$$\ell_p(f_{\theta}(\mathbf{x}_i), y_i) = \begin{cases} -y_i f_{\theta}(\mathbf{x}_i) & -y_i f_{\theta}(\mathbf{x}_i) > 0 \\ 0 & -y_i f_{\theta}(\mathbf{x}_i) \le 0 \end{cases} = \max(0, -y_i f_{\theta}(\mathbf{x}_i))$$

Hinge loss:

$$\ell_h(f_{\theta}(\mathbf{x}_i), y_i) = \begin{cases} 1 - y_i f_{\theta}(\mathbf{x}_i) & 1 - y_i f_{\theta}(\mathbf{x}_i) > 0 \\ 0 & 1 - y_i f_{\theta}(\mathbf{x}_i) \le 0 \end{cases} = \max(0.1 - y_i f_{\theta}(\mathbf{x}_i))$$

ERM: Regularizers for Classification

- Idea: use as few attributes as possible:
 - $\Omega_0(\mathbf{\theta}) \propto \|\mathbf{\theta}\|_0 = \text{ number of } j \text{ with } \theta_j \neq 0$

 Ω_0 is not convex \Rightarrow difficult to minimize!

Manhattan norm (encourages scarcity):

$$\Omega_1(\mathbf{\theta}) \propto \|\mathbf{\theta}\|_1 = \sum_{j=1}^m |\theta_j|$$

- Squared Euclidean norm (encourages small weights):
 - $\Omega_2(\boldsymbol{\theta}) \propto \|\boldsymbol{\theta}\|_2^2 = \sum_{j=1}^m \theta_j^2$

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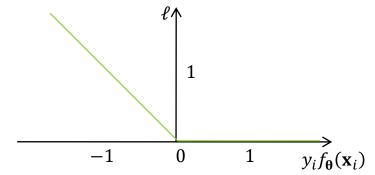
ERM: Perceptron

Loss function:

$$\ell_{p}(f_{\theta}(\mathbf{x}_{i}), y_{i})$$

$$= \begin{cases} -y_{i}f_{\theta}(\mathbf{x}_{i}) & -y_{i}f_{\theta}(\mathbf{x}_{i}) > 0 \\ 0 & -y_{i}f_{\theta}(\mathbf{x}_{i}) \leq 0 \end{cases}$$

$$= \max(0, -y_{i}f_{\theta}(\mathbf{x}_{i}))$$



- No regularizer
- Classes $y \in \{-1, +1\}$
- Stochastic gradient method:



Rosenblatt, 1960

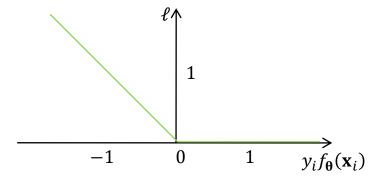
ERM: Perceptron

Loss function:

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Rosenblatt, 1960

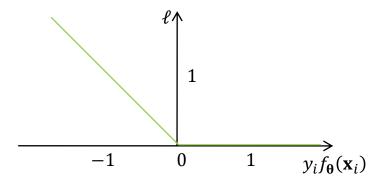
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Rosenblatt, 1960

ERM: Perceptron Algorithm

```
Perceptron (Instances \{(\mathbf{x}_i,y_i)\})
   Set \mathbf{\theta}=\mathbf{0}

DO

FOR i=1,...,n

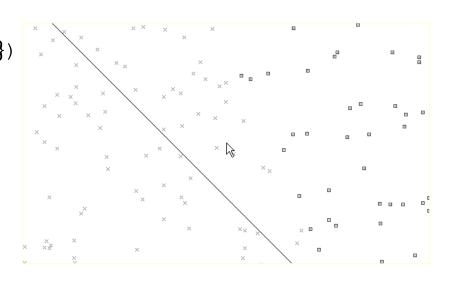
IF y_if_{\mathbf{\theta}}(\mathbf{x}_i) \leq 0

THEN \mathbf{\theta}=\mathbf{\theta}+y_i\mathbf{x}_i

END

WHILE \mathbf{\theta} changes

RETURN \mathbf{\theta}
```

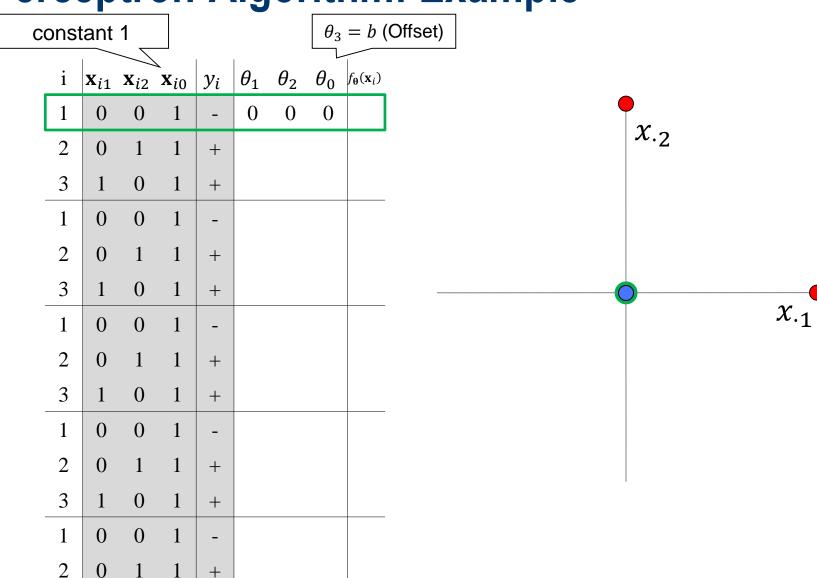


- Stochastic gradient method with $\varepsilon = 0$ and step size $\alpha^t = 1$
 - Terminates, although $\sum_{t=1}^{\infty} (\alpha^t)^2 = \infty$ when data is linearly separable.

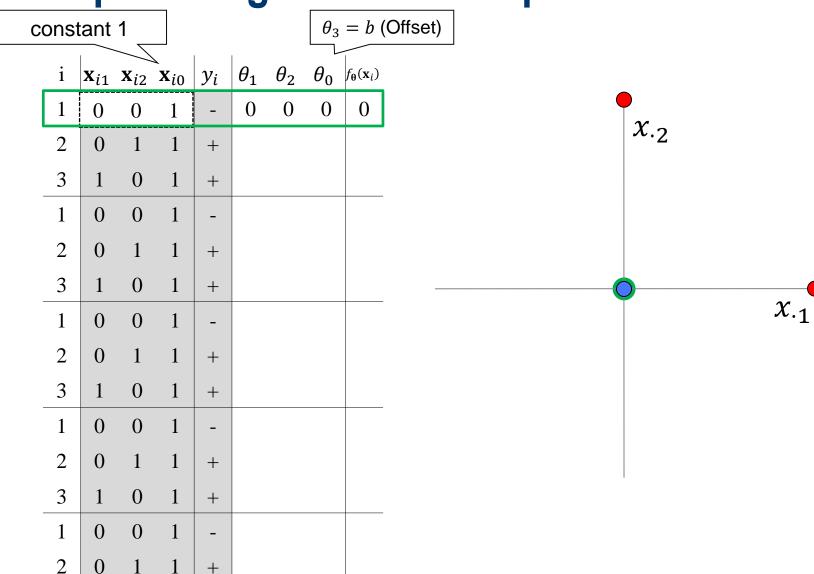


Rosenblatt, 1960

THEN $y_i f_{\boldsymbol{\theta}}(\mathbf{x}_i) \leq 0$ $\boldsymbol{\theta} = \boldsymbol{\theta} + y_i \mathbf{x}_i$

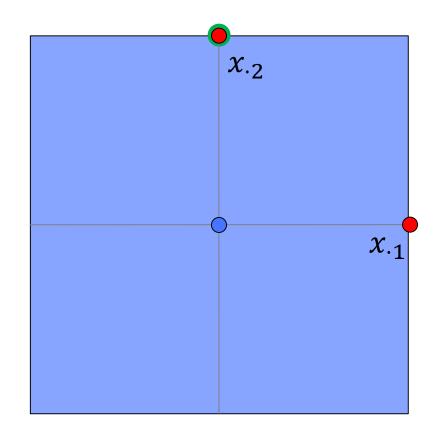


IF $y_i f_{\mathbf{\theta}}(\mathbf{x}_i) \le 0$ THEN $\mathbf{\theta} = \mathbf{\theta} + y_i \mathbf{x}_i$

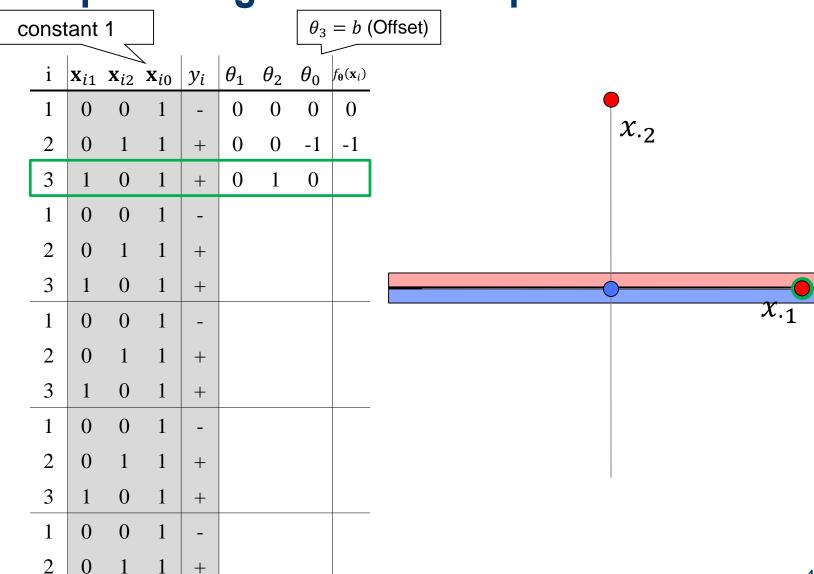


IF $y_i f_{\boldsymbol{\theta}}(\mathbf{x}_i) \leq 0$ THEN $\boldsymbol{\theta} = \boldsymbol{\theta} + y_i \mathbf{x}_i$

						- J	_					
C	onst	tant	1					θ_3	=b (Offse	et))
	i	\mathbf{x}_{i1}	\mathbf{x}_{i2}	\mathbf{x}_{i0}	y_i	$ heta_1$	θ_2	θ_0	$f_{\mathbf{\theta}}(\mathbf{x}_i)$			
-	1	0	0	1	-	0	0	0	0			
	2	0	1	1	+	0	0	-1				
	3	1	0	1	+							
	1	0	0	1	-							
	2	0	1	1	+							
	3	1	0	1	+							
-	1	0	0	1	-							
	2	0	1	1	+							
	3	1	0	1	+							
-	1	0	0	1	-							
	2	0	1	1	+							
	3	1	0	1	+							
-	1	0	0	1	-							
	2	0	1	1	+							



IF $y_i f_{\boldsymbol{\theta}}(\mathbf{x}_i) \leq 0$ THEN $\boldsymbol{\theta} = \boldsymbol{\theta} + y_i \mathbf{x}_i$

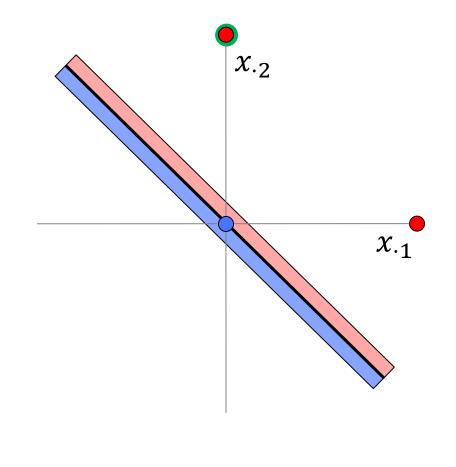


									••••	
C	ons	tant	1_					θ_3	=b (Offset)
	i	\mathbf{x}_{i1}	\mathbf{x}_{i2}	\mathbf{x}_{i0}	y_i	hinspace hin	θ_2	$ heta_0$	$f_{\boldsymbol{\theta}}(\mathbf{x}_i)$	
•	1	0	0	1	-	0	0	0	0	
	2	0	1	1	+	0	0	-1	-1	$\chi_{\cdot 2}$
	3	1	0	1	+	0	1	0	0	
	1	0	0	1	-	1	1	1		
	2	0	1	1	+					
	3	1	0	1	+					
-	1	0	0	1	-					
	2	0	1	1	+					
	3	1	0	1	+					
-	1	0	0	1	-					
	2	0	1	1	+					
	3	1	0	1	+					1
-	1	0	0	1	-					
	2	0	1	1						

 $x_{\cdot 1}$

$$\theta_3 = b$$
 (Offset)

		$\overline{}$	$\overline{}$							
	i	\mathbf{x}_{i1}	\mathbf{x}_{i2}	\mathbf{x}_{i0}	y_i	$ heta_1$	θ_2	θ_0	$f_{\mathbf{\theta}}(\mathbf{x}_i)$	
	1	0	0	1	-	0	0	0	0	
	2	0	1	1	+	0	0	-1	-1	
	3	1	0	1	+	0	1	0	0	
_	1	0	0	1	-	1	1	1	1	
	2	0	1	1	+	1	1	0		
	3	1	0	1	+					
	1	0	0	1	-					
	2	0	1	1	+					
	3	1	0	1	+					
	1	0	0	1	-					
	2	0	1	1	+					
	3	1	0	1	+					
-	1	0	0	1	-					
	2	0	1	1	+					

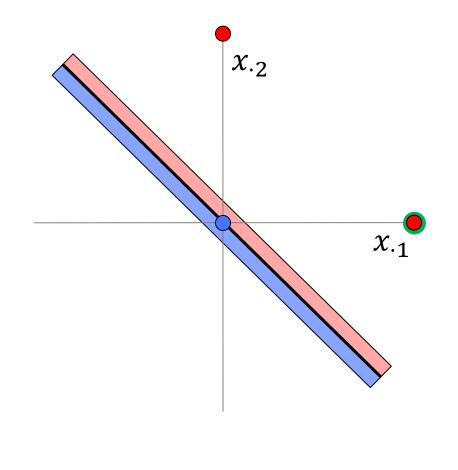


IF $y_i f_{\boldsymbol{\theta}}(\mathbf{x}_i) \leq 0$ THEN $\boldsymbol{\theta} = \boldsymbol{\theta} + y_i \mathbf{x}_i$

Perceptron-Algorithm: Example

$$\theta_3 = b$$
 (Offset)

								$\overline{}$	
	i	\mathbf{x}_{i1}	\mathbf{x}_{i2}	\mathbf{x}_{i0}	y_i	hinspace hin	θ_2	θ_0	$f_{\mathbf{\theta}}(\mathbf{x}_i)$
-	1	0	0	1	-	0	0	0	0
	2	0	1	1	+	0	0	-1	-1
	3	1	0	1	+	0	1	0	0
-	1	0	0	1	-	1	1	1	1
	2	0	1	1	+	1	1	0	1
	3	1	0	1	+	1	1	0	
	1	0	0	1	-				
	2	0	1	1	+				
	3	1	0	1	+				
	1	0	0	1	-				
	2	0	1	1	+				
	3	1	0	1	+				
_	1	0	0	1	-				
	2	0	1	1	+				

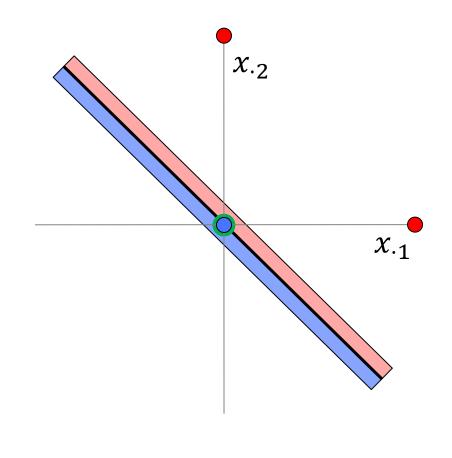


THEN $y_i f_{\boldsymbol{\theta}}(\mathbf{x}_i) \leq 0$ $\boldsymbol{\theta} = \boldsymbol{\theta} + y_i \mathbf{x}_i$

Perceptron-Algorithm: Example

$$\theta_3 = b$$
 (Offset)

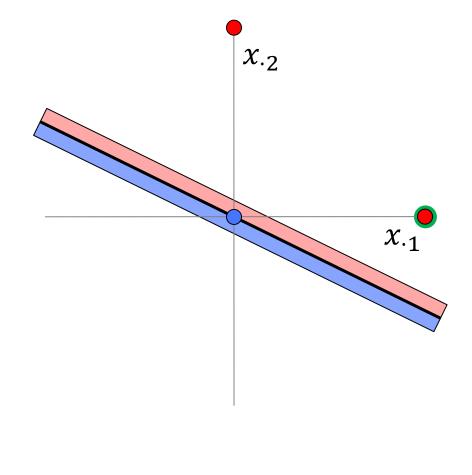
		$\overline{}$						
i	\mathbf{x}_{i1}	\mathbf{x}_{i2}	\mathbf{x}_{i0}	y_i	hinspace hin	θ_2	θ_0	$f_{\mathbf{\theta}}(\mathbf{x}_i)$
1	0	0	1	-	0	0	0	0
2	0	1	1	+	0	0	-1	-1
3	1	0	1	+	0	1	0	0
1	0	0	1	-	1	1	1	1
2	0	1	1	+	1	1	0	1
3	1	0	1	+	1	1	0	1
1	0	0	1	-	1	1	0	
2	0	1	1	+				
3	1	0	1	+				
1	0	0	1	-				
2	0	1	1	+				
3	1	0	1	+				
1	0	0	1	-				
2	0	1	1	+				



							,			
C	onst	ant	1					θ_3	=b	(
	i	\mathbf{x}_{i1}	\mathbf{x}_{i2}	\mathbf{x}_{i0}	y_i	$ heta_1$	θ_2	θ_0	$f_{\mathbf{\theta}}(\mathbf{x}_i)$	
•	1	0	0	1	-	0	0	0	0	
	2	0	1	1	+	0	0	-1	-1	
	3	1	0	1	+	0	1	0	0	
	1	0	0	1	-	1	1	1	1	
	2	0	1	1	+	1	1	0	1	
	3	1	0	1	+	1	1	0	1	
•	1	0	0	1	-	1	1	0	0	
	2	0	1	1	+	1	1	-1		
	3	1	0	1	+					•
	1	0	0	1	_					
	2	0	1	1	+					
	3	1	0	1	+					
•	1	0	0	1	-					
	2	0	1	1						

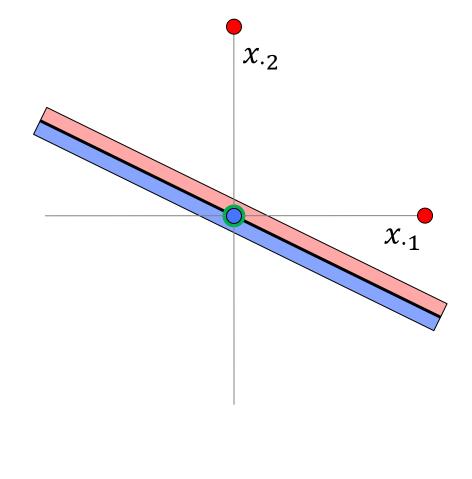
$$\theta_3 = b$$
 (Offset)

	_	$\overline{}$		ı	ı			
i	\mathbf{x}_{i1}	\mathbf{x}_{i2}	\mathbf{x}_{i0}	y_i	$ heta_1$	θ_2	$ heta_0$	$f_{\mathbf{\theta}}(\mathbf{x}_i)$
1	0	0	1	-	0	0	0	0
2	0	1	1	+	0	0	-1	-1
3	1	0	1	+	0	1	0	0
1	0	0	1	-	1	1	1	1
2	0	1	1	+	1	1	0	1
3	1	0	1	+	1	1	0	1
1	0	0	1	-	1	1	0	0
2	0	1	1	+	1	1	-1	0
3	1	0	1	+	1	2	0	
1	0	0	1	-				
2	0	1	1	+				
3	1	0	1	+				
1	0	0	1	-				
2	0	1	1	+				



$$\theta_3 = b$$
 (Offset)

			_	1				
i	\mathbf{x}_{i1}	\mathbf{x}_{i2}	$\mathbf{\hat{x}}_{i0}$	y_i	θ_1	θ_2	$ heta_0$	$f_{\mathbf{\theta}}(\mathbf{x}_i)$
1	0	0	1	-	0	0	0	0
2	0	1	1	+	0	0	-1	-1
3	1	0	1	+	0	1	0	0
1	0	0	1	-	1	1	1	1
2	0	1	1	+	1	1	0	1
3	1	0	1	+	1	1	0	1
1	0	0	1	-	1	1	0	0
2	0	1	1	+	1	1	-1	0
3	1	0	1	+	1	2	0	1
1	0	0	1	-	1	2	0	
2	0	1	1	+				
3	1	0	1	+				
1	0	0	1	-				
2	0	1	1	+				

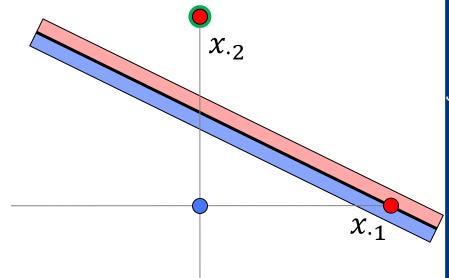


IF $y_i f_{\boldsymbol{\theta}}(\mathbf{x}_i) \leq 0$ THEN $\boldsymbol{\theta} = \boldsymbol{\theta} + y_i \mathbf{x}_i$

constant 1

$$\theta_3 = b$$
 (Offset)

			_ \					L	
	i	\mathbf{x}_{i1}	\mathbf{x}_{i2}	\mathbf{x}_{i0}	y_i	$ heta_1$	θ_2	$ heta_0$	$f_{\mathbf{\theta}}(\mathbf{x}_i)$
•	1	0	0	1	-	0	0	0	0
	2	0	1	1	+	0	0	-1	-1
	3	1	0	1	+	0	1	0	0
٠	1	0	0	1	-	1	1	1	1
	2	0	1	1	+	1	1	0	1
	3	1	0	1	+	1	1	0	1
•	1	0	0	1	-	1	1	0	0
	2	0	1	1	+	1	1	-1	0
	3	1	0	1	+	1	2	0	1
	1	0	0	1	-	1	2	0	0
	2	0	1	1	+	1	2	-1	
•	3	1	0	1	+				
-	1	0	0	1	-				
	2	0	1	1	+				

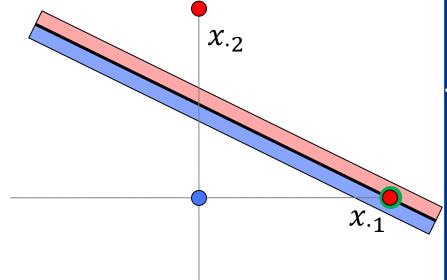


IF $y_i f_{\boldsymbol{\theta}}(\mathbf{x}_i) \leq 0$ THEN $\boldsymbol{\theta} = \boldsymbol{\theta} + y_i \mathbf{x}_i$

Perceptron-Algorithm: Example

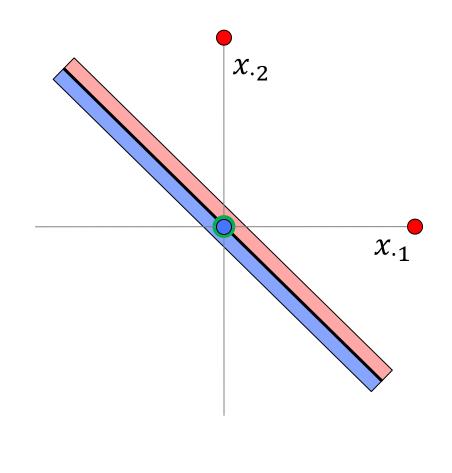
$$\theta_3 = b$$
 (Offset)

										_
	i	\mathbf{x}_{i1}	\mathbf{x}_{i2}	\mathbf{x}_{i0}	y_i	$ heta_1$	θ_2	θ_0	$f_{\mathbf{\theta}}(\mathbf{x}_i)$	
	1	0	0	1	-	0	0	0	0	
	2	0	1	1	+	0	0	-1	-1	
	3	1	0	1	+	0	1	0	0	
	1	0	0	1	-	1	1	1	1	
	2	0	1	1	+	1	1	0	1	
	3	1	0	1	+	1	1	0	1	
-	1	0	0	1	-	1	1	0	0	
	2	0	1	1	+	1	1	-1	0	
	3	1	0	1	+	1	2	0	1	
	1	0	0	1	-	1	2	0	0	
	2	0	1	1	+	1	2	-1	1	
	3	1	0	1	+	1	2	-1		
	1	0	0	1	-					
	2	0	1	1	+					



$$\theta_3 = b$$
 (Offset)

		/					<u>ا</u>	_
i	\mathbf{x}_{i1}	\mathbf{x}_{i2}	\mathbf{x}_{i0}	y_i	$ heta_1$	θ_2	$ heta_0$	$f_{\mathbf{\theta}}(\mathbf{x}_i)$
1	0	0	1	-	0	0	0	0
2	0	1	1	+	0	0	-1	-1
3	1	0	1	+	0	1	0	0
1	0	0	1	-	1	1	1	1
2	0	1	1	+	1	1	0	1
3	1	0	1	+	1	1	0	1
1	0	0	1	-	1	1	0	0
2	0	1	1	+	1	1	-1	0
3	1	0	1	+	1	2	0	1
1	0	0	1	-	1	2	0	0
2	0	1	1	+	1	2	-1	1
3	1	0	1	+	1	2	-1	0
1	0	0	1	-	2	2	0	
2	0	1	1	+				

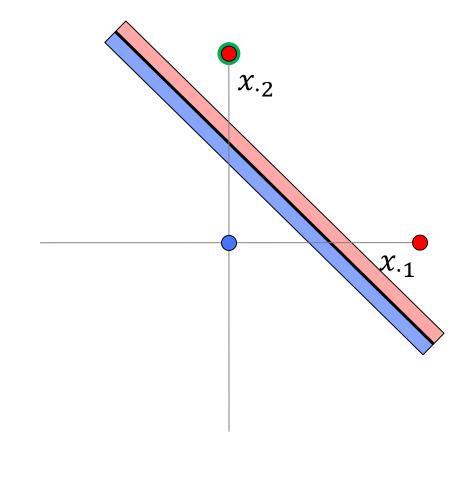


IF $y_i f_{\boldsymbol{\theta}}(\mathbf{x}_i) \leq 0$ THEN $\boldsymbol{\theta} = \boldsymbol{\theta} + y_i \mathbf{x}_i$

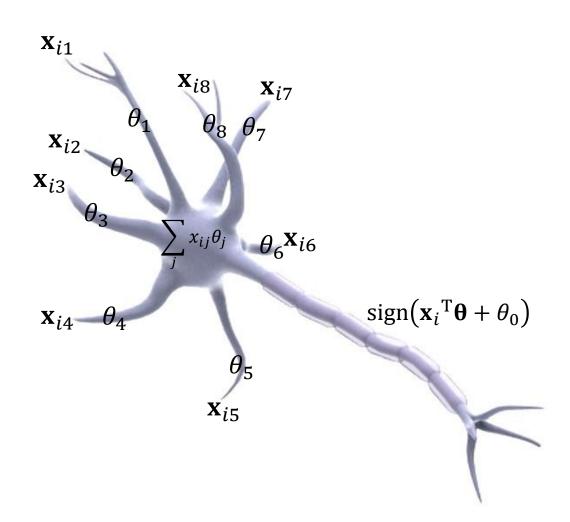
Perceptron-Algorithm: Example

$\theta_3 =$	b	(Offset)	
$\theta_3 =$	b	(Offset)	

i	\mathbf{x}_{i1}	\mathbf{x}_{i2}	\mathbf{x}_{i0}	y_i	$ heta_1$	θ_2	$ heta_0$	$f_{\mathbf{\theta}}(\mathbf{x}_i)$
1	0	0	1	-	0	0	0	0
2	0	1	1	+	0	0	-1	-1
3	1	0	1	+	0	1	0	0
1	0	0	1	-	1	1	1	1
2	0	1	1	+	1	1	0	1
3	1	0	1	+	1	1	0	1
1	0	0	1	-	1	1	0	0
2	0	1	1	+	1	1	-1	0
3	1	0	1	+	1	2	0	1
1	0	0	1	-	1	2	0	0
2	0	1	1	+	1	2	-1	1
3	1	0	1	+	1	2	-1	0
1	0	0	1	-	2	2	0	0
2	0	1	1	+	2	2	-1	



ERM: Perceptron



Perceptron

- Perceptron algorithm minimizes the sum of the perceptron loss over all samples
- No regularizer
- Update rules realized as stochastic gradient search
- Fixed step size of 1; hence there is no guarantee that it will converge (unless data is separable).
- Perceptron finds (some) separating hyperplane between positive and negative samples
- Perceptron converges if such a hyperplane exists.

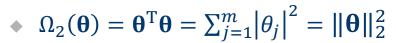
Overview

- Linear classification models
- Empirical risk minimization
 - Gradient descent method
 - ♦ Inexact line search
 - ◆ Stochastic gradient descent methods
- Loss functions and regularizers for classification
- Special cases
 - ◆ Perceptron
 - Support vector machines
- Multi-class classification

- Class $y \in \{-1, +1\}$
- Loss function:

$$\ell_h(f_{\theta}(\mathbf{x}_i), y_i) = \begin{cases} 1 - y_i f_{\theta}(\mathbf{x}_i) & \text{if } 1 - y_i f_{\theta}(\mathbf{x}_i) > 0 \\ 0 & \text{if } 1 - y_i f_{\theta}(\mathbf{x}_i) \le 0 \end{cases}$$
$$= \max(0, 1 - y_i f_{\theta}(\mathbf{x}_i))$$





Loss function is 0, if...

$$\begin{split} &\sum_{i=1}^{n} \max \left(0, 1 - y_{i} f_{\theta}(\mathbf{x}_{i})\right) = 0 \\ &\Leftrightarrow \ \forall_{i=1}^{n} \colon y_{i} f_{\theta}(\mathbf{x}_{i}) \geq 1 \\ &\Leftrightarrow \ \forall_{i=1}^{n} \colon y_{i} \mathbf{x}_{i}^{\mathsf{T}} \theta \geq 1 \\ &\Leftrightarrow \ \forall_{i=1}^{n} \colon y_{i} \mathbf{x}_{i}^{\mathsf{T}} \frac{\theta}{\|\theta\|_{2}} \geq \frac{1}{\|\theta\|_{2}} \end{split}$$
 Hessian normal form: normal vector has length 1
$$\Leftrightarrow \ \forall_{i=1}^{n} \colon y_{i} \mathbf{x}_{i}^{\mathsf{T}} \frac{\theta}{\|\theta\|_{2}} \geq \frac{1}{\|\theta\|_{2}}$$

$$\Leftrightarrow \ \forall_{i=1}^{n} \colon \operatorname{proj}_{\theta} \mathbf{x}_{i} \begin{cases} \geq \frac{1}{\|\theta\|_{2}} & \text{if } y_{i} = +1 \\ \leq \frac{-1}{\|\theta\|_{2}} & \text{if } y_{i} = -1 \end{cases}$$

Loss function is 0, if...

$$\sum_{i=1}^{n} \max(0, 1 - y_{i} f_{\theta}(\mathbf{x}_{i})) = 0$$

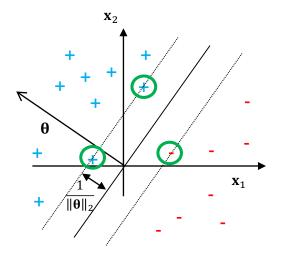
$$\Leftrightarrow \forall_{i=1}^{n} : y_{i} f_{\theta}(\mathbf{x}_{i}) \geq 1$$

$$\Leftrightarrow \forall_{i=1}^{n} : y_{i} \mathbf{x}_{i}^{T} \mathbf{\theta} \geq 1$$

$$\Leftrightarrow \forall_{i=1}^{n} : y_{i} \mathbf{x}_{i}^{T} \frac{\mathbf{\theta}}{\|\mathbf{\theta}\|_{2}} \geq \frac{1}{\|\mathbf{\theta}\|_{2}}$$

$$\Leftrightarrow \forall_{i=1}^{n} : \mathbf{x}_{i}^{T} \frac{\mathbf{\theta}}{\|\mathbf{\theta}\|_{2}} \left\{ \geq \frac{1}{\|\mathbf{\theta}\|_{2}} \quad \text{if } y_{i} = +1 \right\}$$

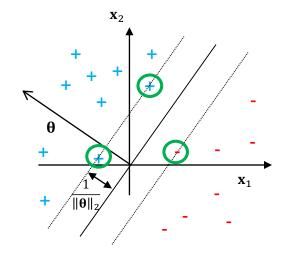
$$\leq \frac{-1}{\|\mathbf{\theta}\|_{2}} \quad \text{if } y_{i} = -1$$



Distance of closest point to plane (margin)

- For loss to be 0, all training samples must
 - lie on the correct side of separating plane,
 - and have a minimal margin (gap) of $\frac{1}{\|\mathbf{\theta}\|_2}$ to the plane.

- Loss function is 0 if all training samples have a margin of at least ¹/_{||θ||2}.
 - Points that lie $\frac{1}{\|\theta\|_2}$ from the plane are support vectors

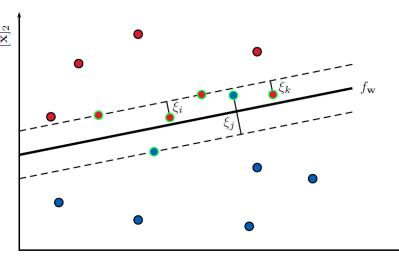


- Regularizer
 - $\Omega_2(\boldsymbol{\theta}) = \boldsymbol{\theta}^T \boldsymbol{\theta} = \|\boldsymbol{\theta}\|_2^2$; is zero only if $\boldsymbol{\theta} = \boldsymbol{0}$
 - Minimizing $\Omega_2(\theta) \iff$ maximizing margin $\frac{1}{\|\theta\|_2}$
- SVM is also referred to as a *large margin classifier* because its optimization criterion is minimized by the plane with the largest margin from any sample.

- If loss function >0, some instances violate margin.
- Loss function as a sum of slack terms

 $\sum_{i=1}^{n} \max(0,1-y_i f_{\theta}(\mathbf{x}_i)) = \sum_{i=1}^{n} \xi_i$ $\xi_i = \max(0,1-y_i f_{\theta}(\mathbf{x}_i))$

Slack term or margin violation



 $[\mathbf{x}]_1$

Points with non-zero slack are support vectors

- Minimize hinge loss and L2-norm $\|\mathbf{\theta}\|_2^2 = \mathbf{\theta}^T \mathbf{\theta}$ of the parameter vector.
- Hinge loss is positive for a sample if the sample has a distance (margin) of less than $\frac{1}{\|\theta\|_2}$ to the separating hyperplane.
- SVM thereby finds the hyperplane with the greatest margin that separates the most possible samples. It trades off between
 - The size of the margin $\frac{1}{\|\theta\|_2}$
 - And the sum of the slack errors $\sum_{i=1}^{n} \xi_i$

Linear classification model: minimize

$$L(\boldsymbol{\theta}) = \sum_{i=1}^{n} \left[\max(0, 1 - y_i \mathbf{x}_i^{\mathrm{T}} \boldsymbol{\theta}) + \frac{\lambda}{n} \boldsymbol{\theta}^{\mathrm{T}} \boldsymbol{\theta} \right]$$

Gradient:

$$\nabla L(\boldsymbol{\theta}) = \sum_{i=1}^{n} \nabla_{\mathbf{x}_i} L(\boldsymbol{\theta})$$

• Stochastic gradient for x_i :

Linear classification model: minimize

$$L(\boldsymbol{\theta}) = \sum_{i=1}^{n} \left[\max(0, 1 - y_i \mathbf{x}_i^{\mathrm{T}} \boldsymbol{\theta}) + \frac{\lambda}{n} \boldsymbol{\theta}^{\mathrm{T}} \boldsymbol{\theta} \right]$$

Gradient:

$$\nabla L(\boldsymbol{\theta}) = \sum_{i=1}^{n} \nabla_{\mathbf{x}_i} L(\boldsymbol{\theta})$$

• Stochastic gradient for x_i :

$$\nabla_{\mathbf{x}_i} \boldsymbol{L}(\boldsymbol{\theta}) = \begin{cases} \frac{2\lambda}{n} \boldsymbol{\theta} & \text{if } y_i \mathbf{x}_i^{\mathrm{T}} \boldsymbol{\theta} > 1 \\ \frac{2\lambda}{n} \boldsymbol{\theta} - y_i \mathbf{x}_i & \text{if } y_i \mathbf{x}_i^{\mathrm{T}} \boldsymbol{\theta} < 1 \end{cases}$$

- $L(\theta)$ can be minimized using stochastic gradient descent method ("Pegasos")
 - Very fast, often used in practice
- L(θ) can be minimized using gradient descent method ("Primal SVM")

Overview

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Multi-Class Classification

 Motivation: we would like to extend classification to problems with more than 2 classes.

$$Y = \{1, ..., k\}$$

- Problem: we cannot separate k classes with a single hyperplane.
- Idea: Each class y has a separate function $f_{\theta}(\mathbf{x}, y)$ that is used to predict how likely y is given \mathbf{x} .
 - Each function is modeled as linear.
 - We predict class y with the highest scoring function for x.

Multi-Class Classification

Decision functions:

$$f_{\mathbf{\theta}}(\mathbf{x}, \mathbf{y}) = \mathbf{x}^{\mathrm{T}} \mathbf{\theta}^{\mathbf{y}}$$

Classifier:

$$y_{\mathbf{\theta}}(\mathbf{x}) = \underset{y \in Y}{\operatorname{argmax}} f_{\mathbf{\theta}}(\mathbf{x}, y)$$

Model parameters:

$$\mathbf{\theta} = \begin{pmatrix} \mathbf{\theta}^1 \\ \vdots \\ \mathbf{\theta}^k \end{pmatrix}$$

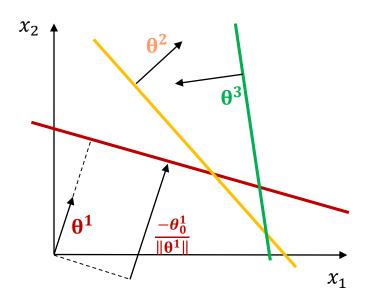
Multi-Class Classification

Decision functions:

$$f_{\mathbf{\theta}}(\mathbf{x}, \mathbf{y}) = \mathbf{x}^{\mathrm{T}} \mathbf{\theta}^{\mathbf{y}}$$

Classifier:

$$y_{\mathbf{\theta}}(\mathbf{x}) = \underset{y \in Y}{\operatorname{argmax}} f_{\mathbf{\theta}}(\mathbf{x}, y)$$



Linear Classification Methods



- Linear hyperplane separates classes.
- Empirical risk minimization
 - Gradient descent method
 - Inexact line search
 - Stochastic gradient descent methods
- Perceptron
 - Stochastic gradient, perceptron loss, no regularizer
- Support vector machines
 - Gradient or stochastic gradient, hinge loss, L2regularizer.
 - Maximizes margin between instances and plane.
- Multi-class classification: multiple planes.