

Model Evaluation

Tobias Scheffer

Overview

- Risk, empirical risk
- Precision, recall
- ROC curves
- Evaluation protocols
- Model selection

Learning and Evaluation

- Learning problem
 - ◆ Input: data $S = (\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)$
 - ◆ Output: model $f_\theta: X \rightarrow Y$
- When model is applied, it is used to make predictions for new instances \mathbf{x} .
- How well will f_θ perform at application time?
 - ◆ What does “well” even mean?
 - ◆ How can it be determined?

Model Evaluation

- Central assumption about data: drawn according to single (unknown) distribution $p(\mathbf{x}, y)$.
- **“IID assumption”**: Instances $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_m, y_m)$ are drawn independently and from an identical distribution.
- Independent: $p\left((\mathbf{x}_{i+j}, y_{i+j}) | (\mathbf{x}_i, y_i)\right) = p\left((\mathbf{x}_{i+j}, y_{i+j})\right)$.
- Identical distribution: $\forall i: (\mathbf{x}_i, y_i) \sim p(\mathbf{x}, y)$

Model Evaluation

- **“IID assumption”**: Instances $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)$ are drawn independently and from an identical distribution.
- Independent: $p\left((\mathbf{x}_{i+j}, y_{i+j}) | (\mathbf{x}_i, y_i)\right) = p\left((\mathbf{x}_{i+j}, y_{i+j})\right)$.
 - ◆ Counter-example: predicting ground motion during earthquakes.
 - ◆ \mathbf{x}_i : magnitude and epicenter of earthquake, sensor location, ground properties; y_i : ground acceleration at sensor location.
 - ◆ Observations at different sensor locations during the same earthquake are highly dependent.
 - ◆ Number of sensor stations often large, number of earthquakes is small; especially of high-magnitude earthquakes.
 - ◆ “Effective sample size” is much smaller than apparent sample size.

Model Evaluation

- **“IID assumption”**: Instances $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)$ are drawn independently and from an identical distribution.
- Independent: $p\left((\mathbf{x}_{i+j}, y_{i+j}) | (\mathbf{x}_i, y_i)\right) = p\left((\mathbf{x}_{i+j}, y_{i+j})\right)$.
 - ◆ Counter example: people who are surveyed at a random but fixed geographical location.
 - ◆ Consequence: a dependent sample contains less variance than an independent sample.

Model Evaluation

- **“IID assumption”**: Instances $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)$ are drawn independently and from an identical distribution.
- Independent: $p\left((\mathbf{x}_{i+j}, y_{i+j}) | (\mathbf{x}_i, y_i)\right) = p\left((\mathbf{x}_{i+j}, y_{i+j})\right)$.
 - ◆ Counter example: people who are surveyed at a random but fixed geographical location.
 - ◆ Consequence: a dependent sample contains less variance than an independent sample.
- Identical distribution: $\forall i: (\mathbf{x}_i, y_i) \sim p(\mathbf{x}, y)$
 - ◆ Counter example: first half of the data generated under laboratory conditions, second half collected “in the wild”.
 - ◆ Consequence: model trained on laboratory data may perform poorly “in the wild”.

Loss Function

- Loss function: How bad is it if the model predicts value $f_{\theta}(\mathbf{x}_i)$ when the true value of the target variable is y_i ?

$$\ell(f_{\theta}(\mathbf{x}_i), y_i)$$

- Example loss functions:

- ◆ Zero-one loss (classification):

$$\ell_{0/1}(f_{\theta}(\mathbf{x}_i), y_i) = \begin{cases} 0 & \text{if } f_{\theta}(\mathbf{x}_i) = y_i \\ 1 & \text{otherwise} \end{cases}$$

- ◆ Quadratic loss (regression):

$$\ell_2(f_{\theta}(\mathbf{x}_i), y_i) = (f_{\theta}(\mathbf{x}_i) - y_i)^2$$

- ◆ Perceptron loss, hinge loss, ε -insensitive loss, ...

Risk

- Risk of model f_θ : expected loss over underlying distribution $p(\mathbf{x}, y)$.

- Finite set Y (classification):

$$R(\theta) = E_{(\mathbf{x}, y) \sim p(\mathbf{x}, y)}[\ell(\mathbf{x}, y)] = \sum_{y \in Y} \int \ell(f_\theta(\mathbf{x}), y) p(\mathbf{x}, y) d\mathbf{x}$$

- Infinite Y (regression):

$$R(\theta) = E_{(\mathbf{x}, y) \sim p(\mathbf{x}, y)}[\ell(\mathbf{x}, y)] = \int \int \ell(f_\theta(\mathbf{x}), y) p(\mathbf{x}, y) d\mathbf{x} dy$$

- Expected zero-one loss (risk for zero-one loss function) is called **error rate**.
- 1-error rate is called **accuracy**.

Risk

- Risk of model f_θ : expected loss over underlying distribution $p(\mathbf{x}, y)$.

- Finite set Y (classification):

$$R(\theta) = E_{(\mathbf{x}, y) \sim p(\mathbf{x}, y)}[\ell(\mathbf{x}, y)] = \sum_{y \in Y} \int \ell(f_\theta(\mathbf{x}), y) p(\mathbf{x}, y) d\mathbf{x}$$

- Infinite Y (regression):

$$R(\theta) = E_{(\mathbf{x}, y) \sim p(\mathbf{x}, y)}[\ell(\mathbf{x}, y)] = \int \int \ell(f_\theta(\mathbf{x}), y) p(\mathbf{x}, y) d\mathbf{x} dy$$

- It is generally impossible to determine the risk:
 - ◆ $p(\mathbf{x}, y)$ is not known.
 - ◆ Generally impossible to integrate over all instances \mathbf{x} .

Empirical Risk

- Impossible to calculate risk

$$R(\theta) = E_{(\mathbf{x}, y) \sim p(\mathbf{x}, y)} [\ell(f_\theta(\mathbf{x}), y)]$$

- → Empirical risk: estimate on sample $S \sim p(\mathbf{x}, y)^n$.

$$\hat{R}_S(\theta) = \frac{1}{n} \sum_{i=1}^n \ell(f_\theta(\mathbf{x}_i, y_i))$$

- Empirical risk is a random variable; depends on the instances S that are drawn.
- If S is drawn **IID**, then it is governed by $p((\mathbf{x}_1, y_1) \times \cdots \times$

Estimators

- In statistics, an **estimator** is any rule for calculating an estimate of a quantity.
- A procedure for that determines the empirical risk is an estimator of the risk.

- An estimator is called unbiased if the expected value of the estimate is the true quantity:

$$\hat{R}(\theta) \text{ is unbiased} \Leftrightarrow E_{S \sim p(\mathbf{x}, y)^n} [\hat{R}_S(\theta)] = R(\theta)$$

- An estimator that is not unbiased has a bias:

$$B(\hat{R}(\theta)) = E_{S \sim p(\mathbf{x}, y)^n} [\hat{R}_S(\theta)] - R(\theta)$$

Bias of the Empirical Risk

- Bias of the empirical risk:

$$B\left(\hat{R}(\theta)\right) = E_{S \sim p(\mathbf{x}, y)^n} \left[\hat{R}_S(\theta) \right] - R(\theta)$$

- Empirical risk is unbiased estimator if:

$$E_{S \sim p(\mathbf{x}, y)^n} \left[\hat{R}_S(\theta) \right] = R(\theta)$$

- Empirical risk is optimistic estimator if:

$$E_{S \sim p(\mathbf{x}, y)^n} \left[\hat{R}_S(\theta) \right] - R(\theta) < 0$$

- Empirical risk is pessimistic estimator if:

$$E_{S \sim p(\mathbf{x}, y)^n} \left[\hat{R}_S(\theta) \right] - R(\theta) > 0$$

Bias of the Empirical Risk

- Bias of the empirical risk:

$$B\left(\hat{R}(\theta)\right) = E_{S \sim p(\mathbf{x}, y)^n} \left[\hat{R}_S(\theta) \right] - R(\theta)$$

- The bias is a systematical offset between risk and empirical risk.
- It can be caused by a particular experimental setting used to determine the empirical risk.
- Large bias: risk is systematically estimated too low or too high.

Variance of an Estimator

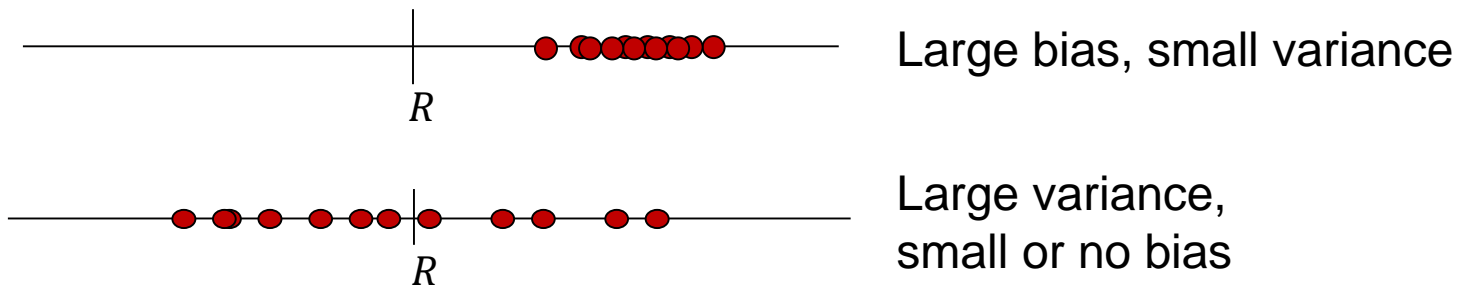
- Estimator $\hat{R}_S(\theta)$ has a variance

$$Var[\hat{R}_S(\theta)] = E_{S \sim p(\mathbf{x}, y)} \left[\left(E[R_S(\theta)] - \hat{R}_S(\theta) \right)^2 \right]$$

- The variance is caused by the fact that the empirical risk is calculated on a finite sample.
- Zero-one loss: empirical risk $\hat{R}_S(\theta)$ follows binomial distribution with mean value $R(\theta)$.
- High variance: empirical risk is a crude estimate of the risk.
- The larger a sample the empirical risk is based on, the lower its variance becomes.

Bias and Variance of Empirical Risk

- Empirical risk $\hat{R}_S(\theta)$ determined repeatedly on multiple samples S_1, \dots, S_k
 - Value of \hat{R}_{S_i} for sample S_i



Estimation Error

- Estimation error: expected quadratic difference between empirical risk and risk.

$$E_{S \sim p(\mathbf{x}, y)^n} \left[\left(\hat{R}_S(\theta) - R(\theta) \right)^2 \right]$$

- Can be decomposed into bias and variance

$$\begin{aligned} & E_{S \sim p(\mathbf{x}, y)^n} \left[\left(\hat{R}_S(\theta) - R(\theta) \right)^2 \right] \\ &= E \left[\hat{R}_S(\theta)^2 - 2R(\theta)\hat{R}_S(\theta) + R(\theta)^2 \right] \\ &= E \left[\hat{R}_S(\theta)^2 \right] - 2R(\theta)E \left[\hat{R}_S(\theta) \right] + R(\theta)^2 \\ &= E \left[\hat{R}_S(\theta) \right]^2 - 2R(\theta)E \left[\hat{R}_S(\theta) \right] + R(\theta)^2 + E \left[\hat{R}_S(\theta)^2 \right] - E \left[\hat{R}_S(\theta) \right]^2 \\ &= \left(E \left[\hat{R}_S(\theta) \right] - R(\theta) \right)^2 + E \left[\hat{R}_S(\theta)^2 \right] - E \left[\hat{R}_S(\theta) \right]^2 \\ &= \text{Bias} \left[\hat{R}(\theta) \right]^2 + \text{Var} \left[\hat{R}(\theta) \right] \end{aligned}$$

Algebraic formula
for the variance

Overview

- Risk, empirical risk
- Precision, recall
- ROC curves
- Evaluation protocols
- Model selection

Alternative Measures to Risk

- Risk is not always a meaningful measure.
- Not always possible to specify a meaningful loss function
 - ◆ Mine detector: what is the cost of exploding?
 - ◆ On the other hand, a mine detector that always says “there could be a mine here” is useless.
- Error rate / accuracy are not meaningful for rare classes.
 - ◆ Earth quake prediction tool that always says “there will be no earthquake today” has accuracy of >99.9% (in most countries).

Alternative Measures to Risk

- Alternative performance measures for binary classification.
- Let decision function $f_{\theta}(\mathbf{x})$ return continuous value.
- Decision rule for binary classification: $y_{\theta}(\mathbf{x}) = \begin{cases} +1 & \text{if } f_{\theta}(\mathbf{x}) \geq \theta_0 \\ -1 & \text{if } f_{\theta}(\mathbf{x}) < \theta_0 \end{cases}$
- By adjusting threshold θ_0 decision rule can be made more sensitive or more conservative.
- We will now study measures that quantify how well the decision function separates positive from negative instances, independent of any threshold value θ_0 .
 - ◆ Precision-recall curves
 - ◆ ROC curves

Overview

- Risk, empirical risk
- Evaluation protocols
- Model selection
- Precision, recall
- ROC curves

Precision and Recall

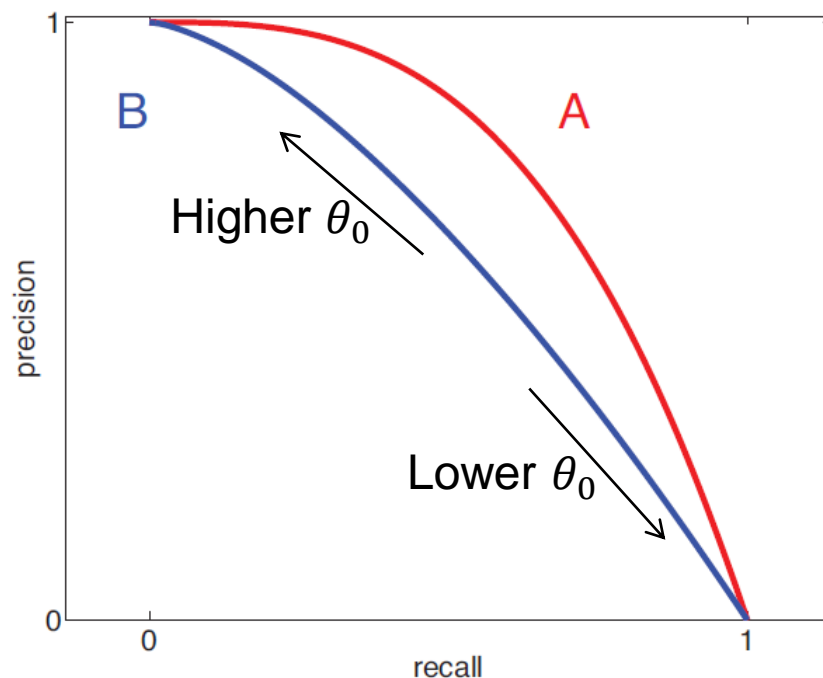
- Alternative performance measure for binary classification.
 - ◆ Example: medical diagnostics system for rare disease.
 - ◆ Patient \mathbf{x}_i has disease if $y_i = +1$.
 - ◆ Classifier diagnoses disease for patient \mathbf{x} if $y_\theta(\mathbf{x}_i) = +1$.
- True positives:
 - ◆ Patient has disease ($y_i = +1$), classifier recognizes ($y_\theta(\mathbf{x}_i) = +1$)
- False positives:
 - ◆ Patient is healthy ($y_i = -1$), but classifier diagnoses disease ($y_\theta(\mathbf{x}_i) = +1$)
- True negatives:
 - ◆ Patient is healthy ($y_i = -1$), classifier recognizes ($y_\theta(\mathbf{x}_i) = -1$)
- False negatives:
 - ◆ Patient has disease ($y_i = +1$), classifier misses ($y_\theta(\mathbf{x}_i) = -1$)

Precision and Recall

- Let n_{TP} be the number of true positives.
- Let n_{FP} be the number of false positives.
- Let n_{TN} be the number of true negatives.
- Let n_{FN} be the number of false negatives.
- Precision: $P = \frac{n_{TP}}{n_{TP} + n_{FP}}$
 - ◆ Rate of true positives among all instances that are classified as positives
 - ◆ Answers: “How accurate is classifier when it says +1?”
- Recall: $R = \frac{n_{TP}}{n_{TP} + n_{FN}}$
 - ◆ Rate of true positives among all positive instances
 - ◆ Answers: “How many of the positive instances does the classifier detect?”

Precision-Recall Curves

- Evaluates decision function $f_{\theta}(\mathbf{x})$ independent of threshold θ_0 .
- Shows which pairs of precision and recall can be obtained by varying threshold θ_0 .
- Each point on the curve is a classification rule with a particular values of θ_0 .
- Which decision function is better – A or B?



Example: Malware Detection

- Instances are client computers
- Error rate $E_{(\mathbf{x}, y)}[\ell_{0/1}(\mathbf{x}, y)]$:
 - ◆ Rate at which computers are misclassified as infected / not infected.
- If 0.1% of all computers are infected:
 - ◆ An error rate of 0.1% may mean that no infection is detected.
 - ◆ An error rate of 0.2% may mean all alarms are false alarms.

Example: Malware Detection

- Precision: $P = \frac{n_{TP}}{n_{TP} + n_{FP}}$
 - ◆ Rate of actual infections among all alarms.
 - ◆ $P = 80\%$ means: 20% of all alarms are false alarms.
 - ◆ Low precision means the tool is annoying.
- Recall: $R = \frac{n_{TP}}{n_{TP} + n_{FN}}$
 - ◆ Proportion of malware that is detected.
 - ◆ $R = 60\%$ means: 40% of all malware goes unnoticed.
 - ◆ Low recall means the tool is useless.
- Precision and recall are good performance measures for malware detection.
- Caveat: precision and recall of a fixed model change when the class ratio changes.

F Measures

- F_α measures combine precision and recall values into single value:

$$F_\alpha = \frac{n_{TP}}{\alpha(n_{TP} + n_{FP}) + (1 - \alpha)(n_{TP} + n_{FN})}$$

- $\alpha = 1$: Precision
- $\alpha = 0$: Recall
- $\alpha = 0.5$: “F-measure”, harmonic mean of precision and recall.
- Alternative definition: F_β measures.
 - ◆ Relationship: $\alpha = \frac{1}{1+\beta}$

F Measures

- F_α measures are not the aggregate of the precision-recall curve but of a single point on that curve.
- F_α measures are highly dependent on that point, determined by the decision threshold θ_0 .
- There is rarely (never?) a good motivation for maximizing F_α measures in machine learning.
- However, if maximizing F_α is the goal, it is crucial to adjust θ_0 for maximal F_α .
- The value of θ_0 that maximizes F_α depends on the class ratio.
- Measuring F_α for a default threshold such as $\theta_0 = 0$ makes no sense at all.

Overview

- Risk, empirical risk
- Evaluation protocols
- Model selection
- Precision, recall
- ROC curves

ROC Analysis

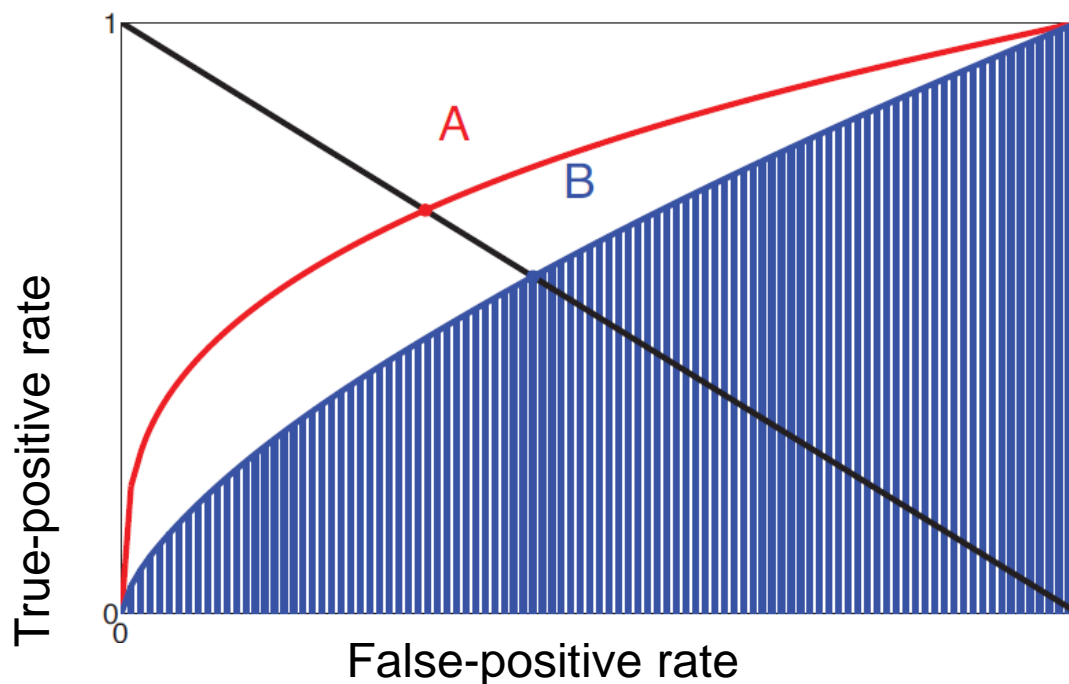
- Alternative performance measure for binary classification.
 - ◆ Example: diagnosis of rare disease.
 - ◆ Patient \mathbf{x}_i has disease if $y_i = +1$.
 - ◆ Classifier diagnoses disease for patient \mathbf{x} if $y_\theta(\mathbf{x}_i) = +1$.
- True-positives:
 - ◆ Patient has the disease ($y_i = +1$), classifier recognizes it ($y_\theta(\mathbf{x}_i) = +1$)
- False positives:
 - ◆ Patient is healthy ($y_i = -1$), but classifier diagnoses disease ($y_\theta(\mathbf{x}_i) = +1$)
- True negatives:
 - ◆ Patient is healthy ($y_i = -1$), classifier recognizes ($y_\theta(\mathbf{x}_i) = -1$)
- False negatives:
 - ◆ Patient has disease ($y_i = +1$), classifier misses ($y_\theta(\mathbf{x}_i) = -1$)

ROC Analysis

- Let n_{TP} be the number of true positives.
- Let n_{FP} be the number of false positives.
- Let n_{TN} be the number of true negatives.
- Let n_{FN} be the number of false negatives.
- True-positive rate (recall): $r_{TP} = \frac{n_{TP}}{n_{TP} + n_{FN}}$
 - ◆ Rate of true positives among all positive instances
 - ◆ Answers: “How many of the positive instances does the classifier detect?”
- False-positive rate: $r_{FP} = \frac{n_{FP}}{n_{FP} + n_{TN}}$
 - ◆ Rate of false positives among all instances that are really negatives.
 - ◆ Answers: “How many of the negative instances does the classifier misclassify as positive?”

ROC Analysis

- Alternative measure of how well the decision function separates positive from negative instances, independent of any threshold value θ_0 .

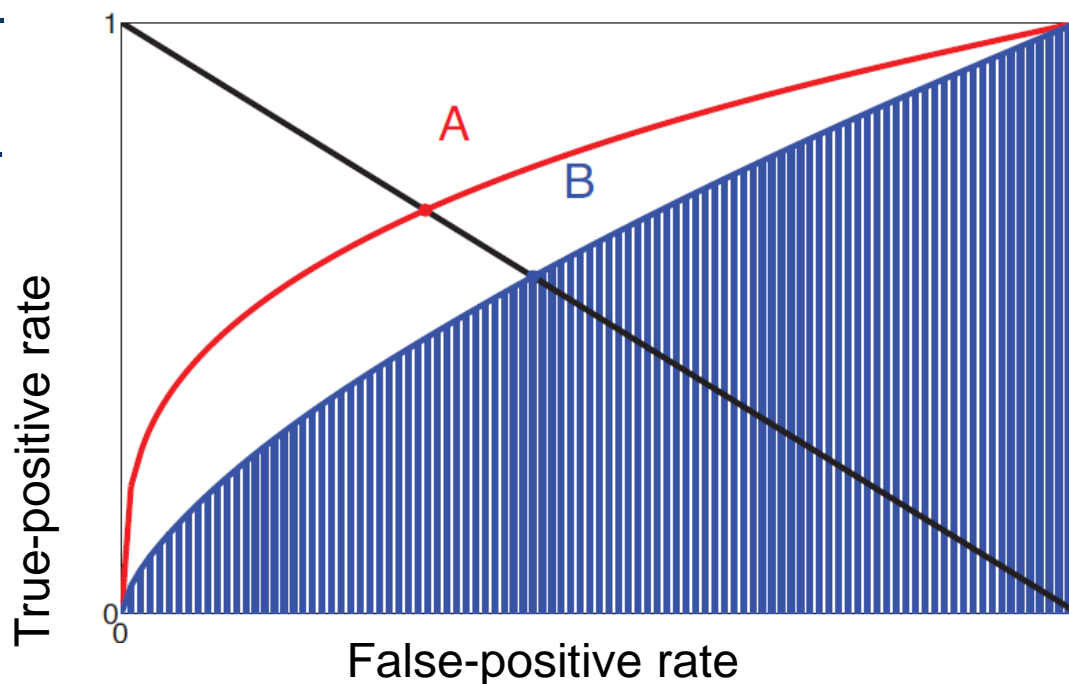


ROC Analysis

- Each curve characterizes a decision function f_θ .
- Each point is a classification rule for a value of θ_0 .
- Which is better, A or B?

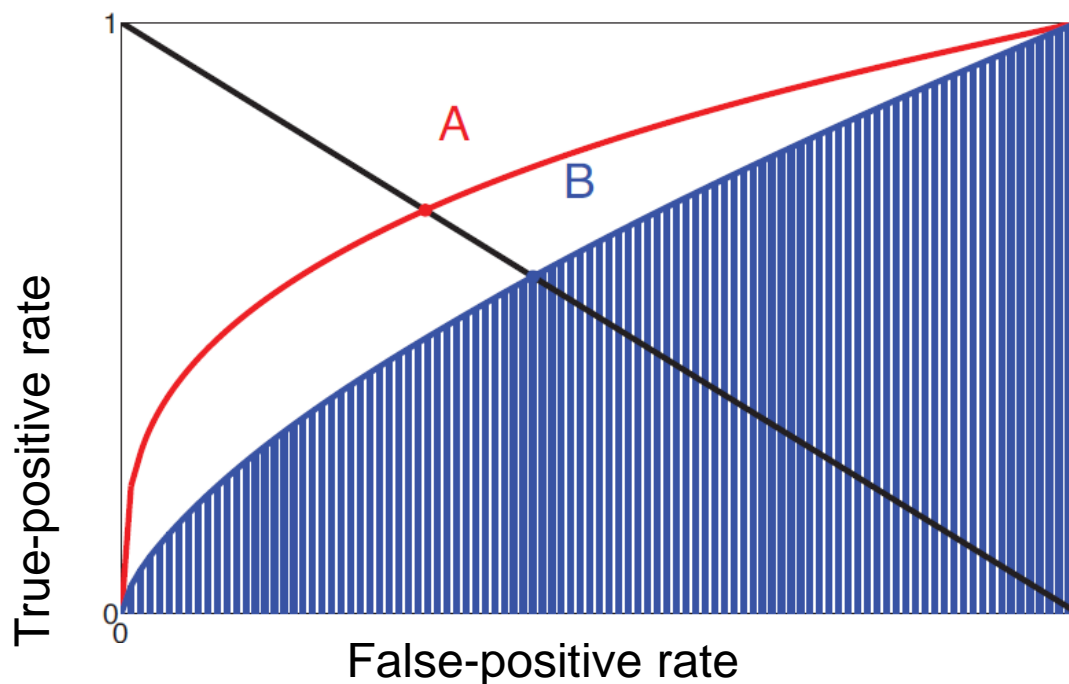
- $r_{TP} = \frac{n_{TP}}{n_{TP} + n_{FN}}$

- $r_{FP} = \frac{n_{FP}}{n_{FP} + n_{TN}}$



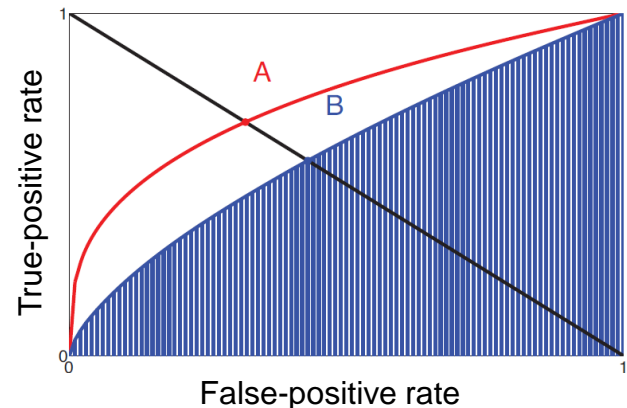
ROC Analysis

- Equal error rate (EER): value $r_{TP} = 1 - r_{FP}$.
- Scalar aggregate of curve: Area under ROC curve (AUC).



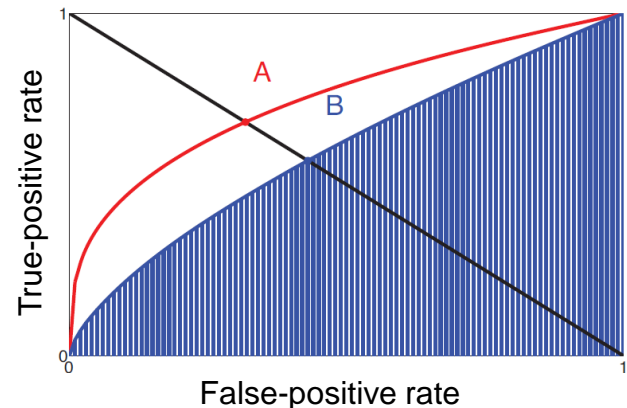
ROC Analysis

- Area under the ROC curve (AUC):
 - ◆ Let \mathbf{x}_+ be a randomly drawn positive instance.
 - ◆ Let \mathbf{x}_- be a randomly drawn negative instance.
 - ◆ $AUC(\theta) = P(f_\theta(\mathbf{x}_+) > f_\theta(\mathbf{x}_-))$.
- AUC = Probability that randomly drawn positive instance has higher score than random negative instance.



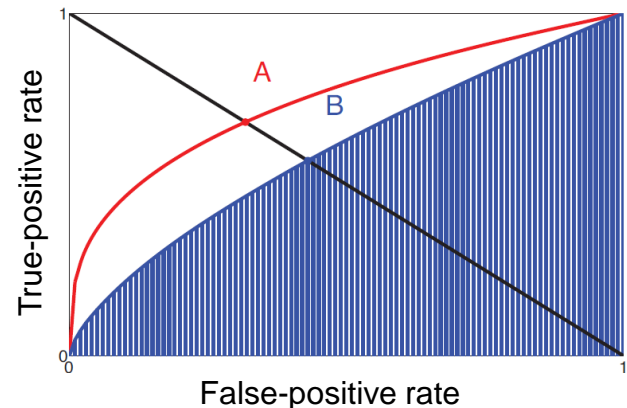
ROC Analysis

- ROC curves are invariant with respect to class ratio.
- When the ratio of positive to negative instances changes over time (and model stays fixed):
 - ◆ The error rate generally changes;
 - ◆ Precision and recall generally change;
 - ◆ The ROC curve (and AUC) remain the same.
- ROC analysis is great when the class ratio can change.
 - ◆ E.g., medical diagnostics during epidemic.



ROC Analysis

- ROC analysis is often used
 - ◆ When positive instances are rare (accuracy of 99.9% is meaningless if positive class is extremely rare)
 - ◆ When class ratio is unknown (probability of stepping on a mine varies by country).
 - ◆ When class ratio changes over time (probability that a patient has influenza varies seasonally).



Example: Medical Diagnosis

- True-positive rate (recall): $r_{TP} = \frac{n_{TP}}{n_{TP} + n_{FN}}$
 - ◆ Proportion of infected persons that are detected.
 - ◆ $r_{TP} = 60\%$ means: 40% of all infections go unnoticed.
 - ◆ Low recall means the diagnostic tool is useless.
- False-positive rate: $r_{FP} = \frac{n_{FP}}{n_{FP} + n_{TN}}$
 - ◆ Rate at which healthy individuals are diagnosed as infected.
 - ◆ $r_{FP} = 5\%$ means that 5% of all healthy patients have to undergo further diagnostic procedures or potentially unneeded treatment.
 - ◆ High false-positive rate means that many patients will be sent to further diagnostic procedures.
- True-positive and false-positive rate are invariant with respect to class ratio.

Overview

- Risk, empirical risk
- Precision, recall
- ROC curves
- Evaluation protocols
- Model selection

Evaluation Protocols

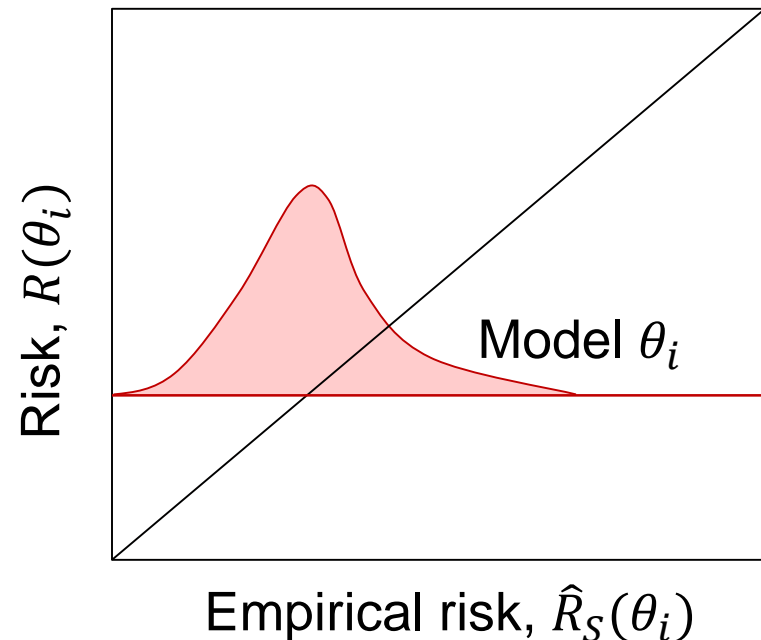
- Usually, model f_θ is not given and evaluation data cannot be drawn from $p(\mathbf{x}, y)$.
- Typical case, data $S = (\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)$ and learning method are given.
- Data S have to be used for training and evaluation.
- Desired output: model f_θ and risk estimate.

Evaluation Protocols

- Can we first train model f_θ on S and then evaluate the model on the same data?
- Will $\hat{R}_S(\theta)$ be unbiased, optimistic, or pessimistic?

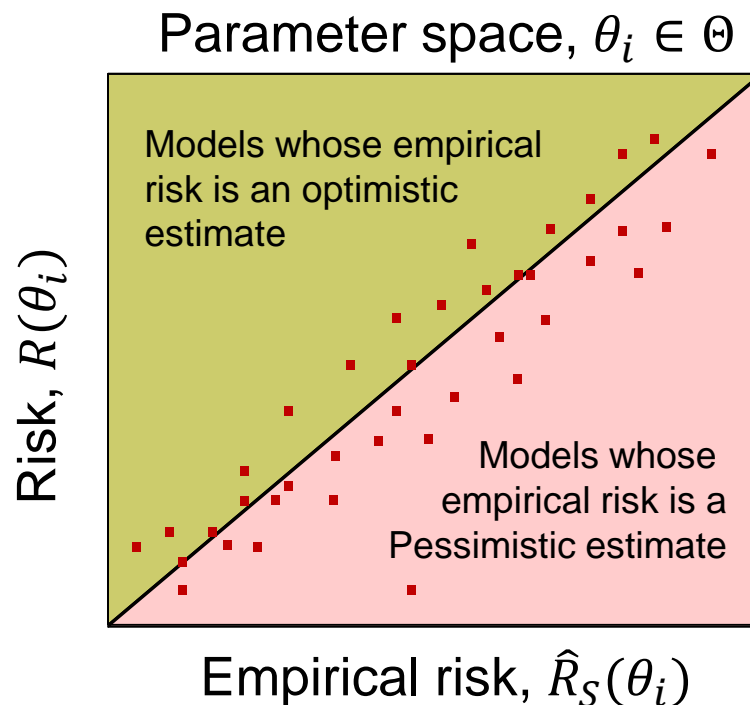
Evaluation Protocols

- Every model $\theta_i \in \Theta$ has a risk $R(\theta_i)$.
- Its empirical risk $\hat{R}_S(\theta_i)$ follows a distribution with mean value $R(\theta_i)$.



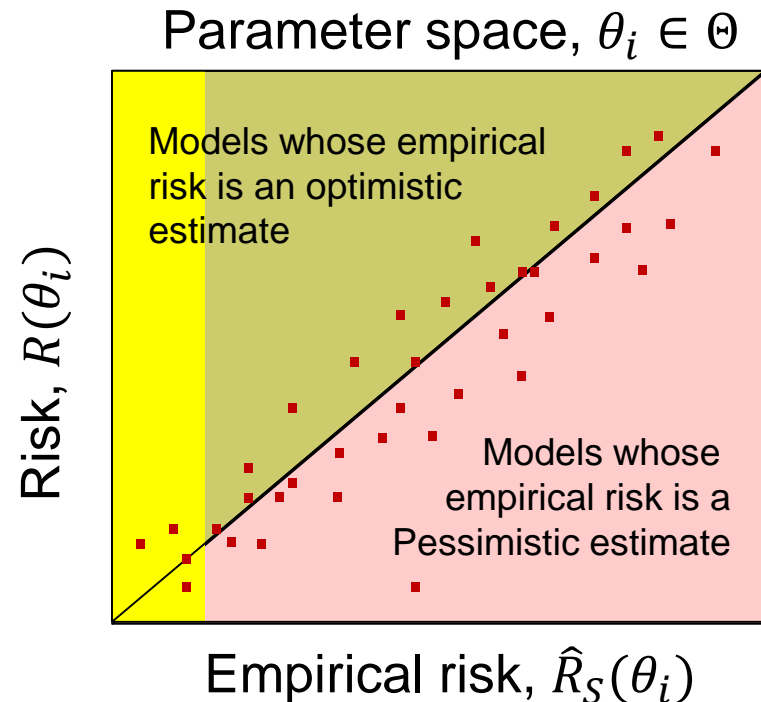
Evaluation Protocols

- Some models get lucky (upper-left area), some are unlucky (lower-right area).



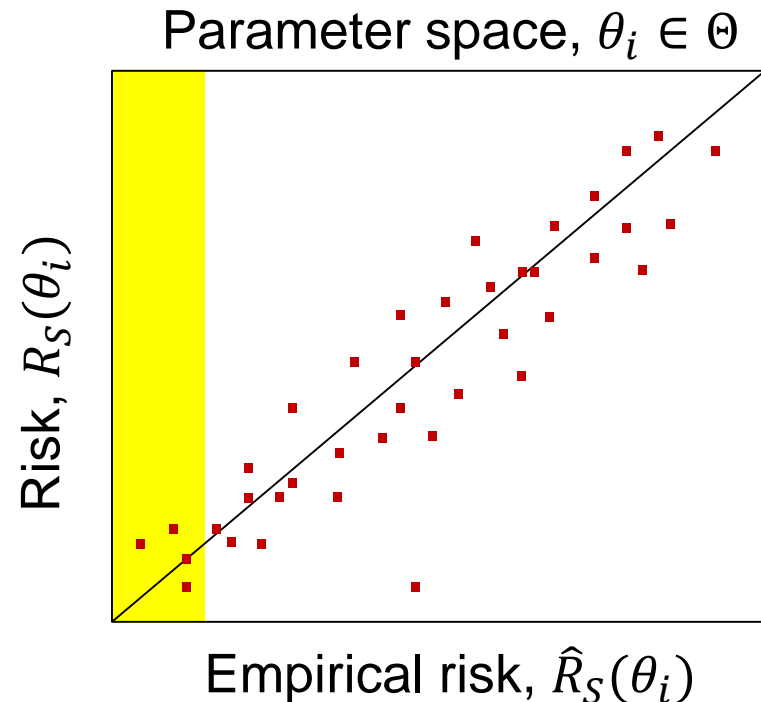
Evaluation Protocols

- Learning algorithm will choose a model with small empirical risk (on the far left).
- In this area, most models' empirical risk is an optimistic estimate.



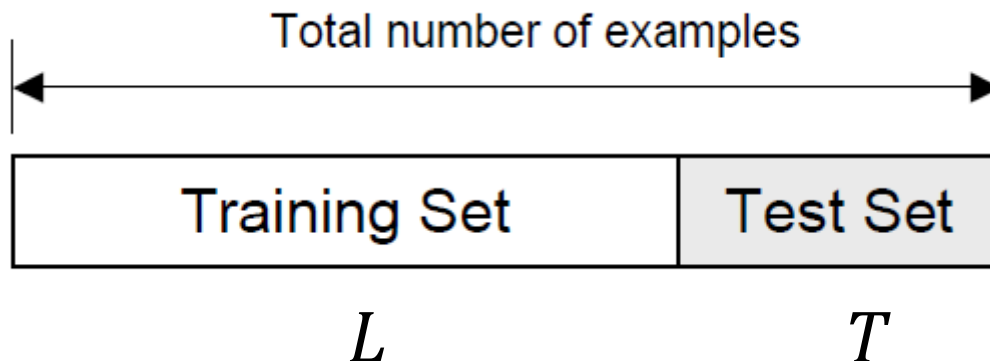
Evaluation Protocols

- Learning algorithm will choose a model with small empirical risk (on the far left).
- For those θ_* on the left: $E_S[\hat{R}_S(\theta_*)] < R(\theta_*)$ (otherwise they would be further right).
- This is called **selection bias**.
- **Empirical risk on training data is optimistic.**



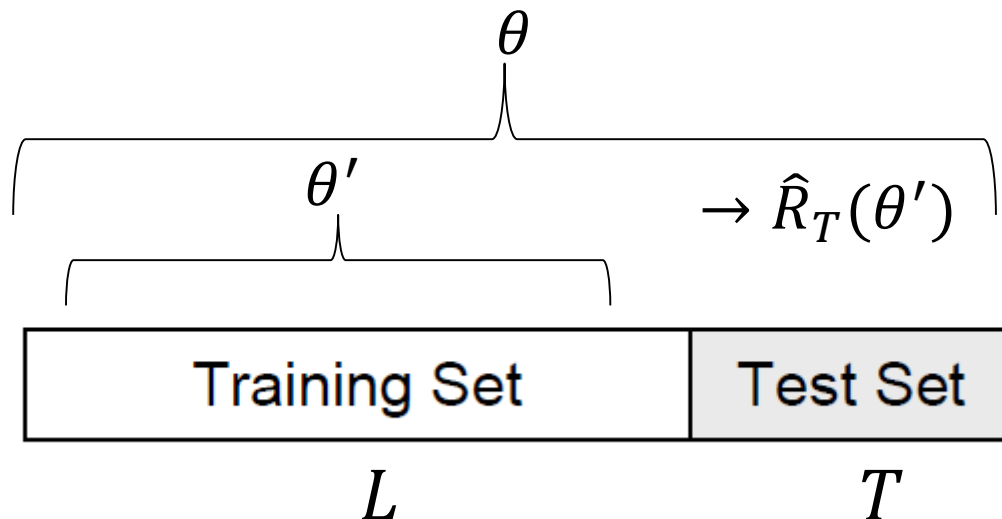
Holdout Testing

- Idea: error estimation on independent test data
- Given: data $S = (\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)$
- Divide the data into
 - ◆ Training data $L = (\mathbf{x}_1, y_1), \dots, (\mathbf{x}_m, y_m)$ and
 - ◆ Test data $T = (\mathbf{x}_{m+1}, y_{m+1}), \dots, (\mathbf{x}_n, y_n)$



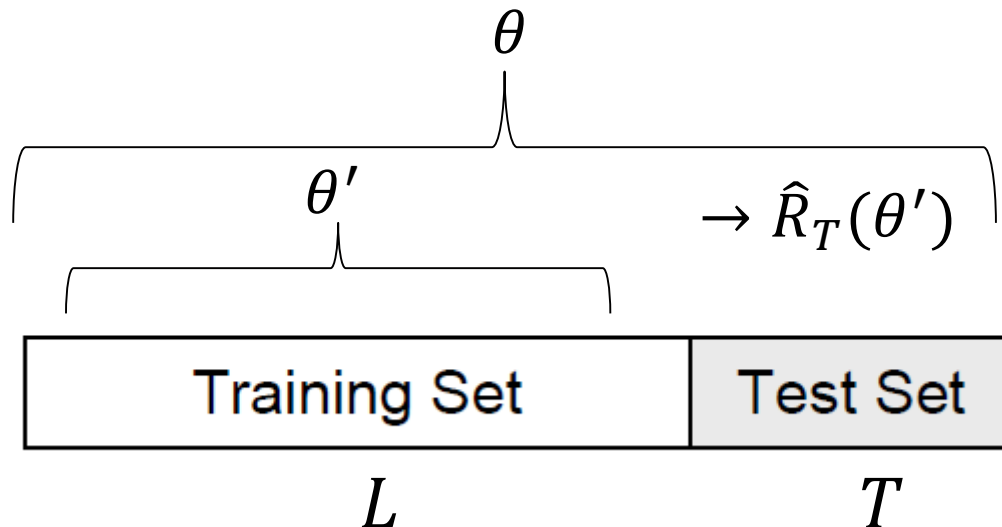
Holdout Testing

- Start learning algorithm with data L and obtain model f_{θ} from it.
- Determine empirical risk $\hat{R}_T(\theta')$ from data T .
- Start learning algorithm with all data S and obtain Model f_{θ} from it.
- Output: model f_{θ} & $\hat{R}_T(\theta')$ as the estimator of $R(\theta)$.



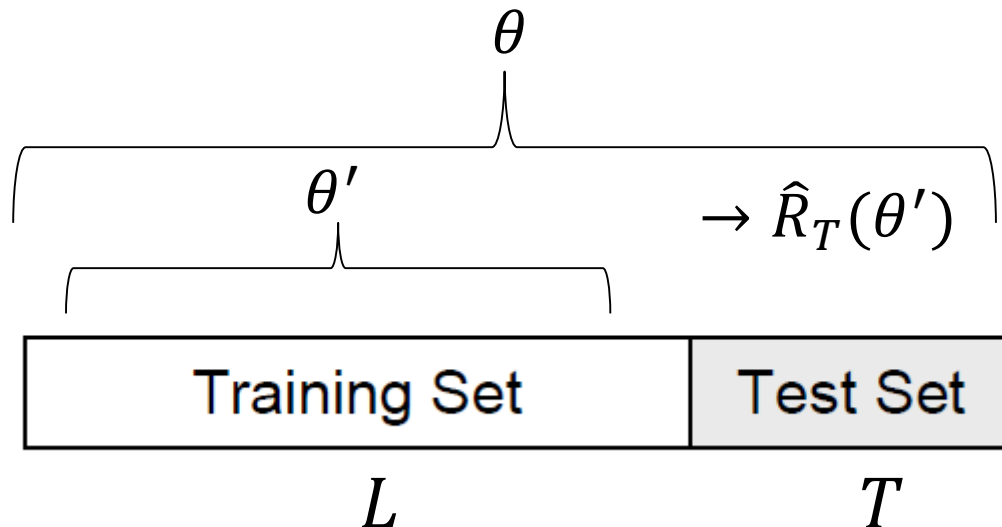
Holdout Testing: Analysis

- Is the estimator $\hat{R}_T(\theta')$ of the risk of model $R(\theta)$
 - ◆ unbiased,
 - ◆ optimistic,
 - ◆ pessimistic?
- Hint: the more training data, the better the model.



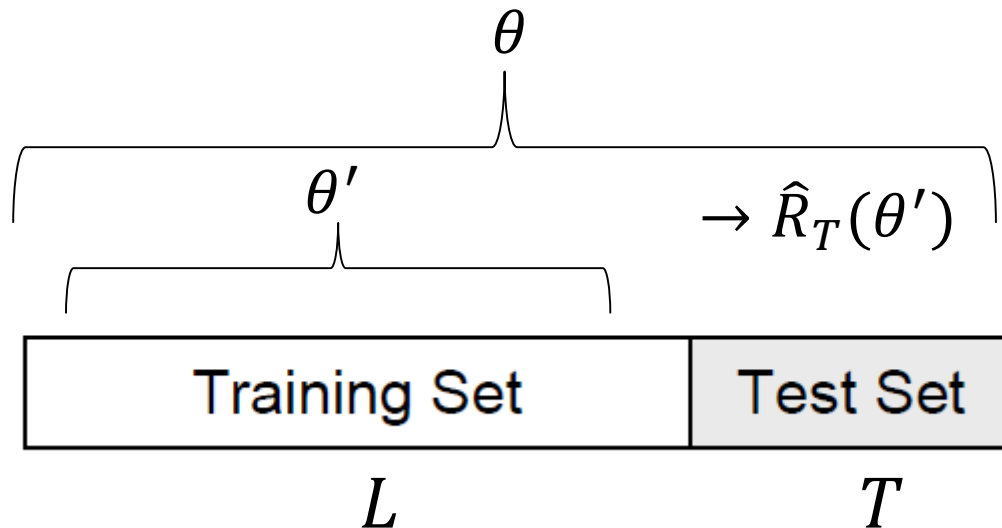
Holdout Testing: Analysis

- Estimate $\hat{R}_T(\theta')$ is obtained on a small part of the available data.
- Therefore, its variance is relatively high, especially if the overall sample is small.
- Holdout testing is used in practice for large available samples.



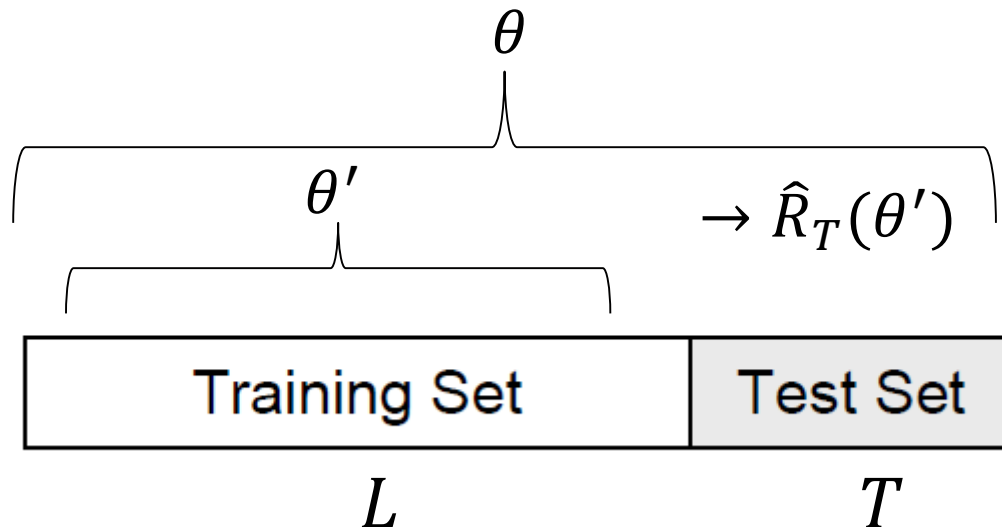
Holdout Testing: Analysis

- Using empirical risk $\hat{R}_T(\theta')$ is an **pessimistic** estimator of the risk $R(\theta)$.
- Because θ' is trained with fewer training instances than θ .



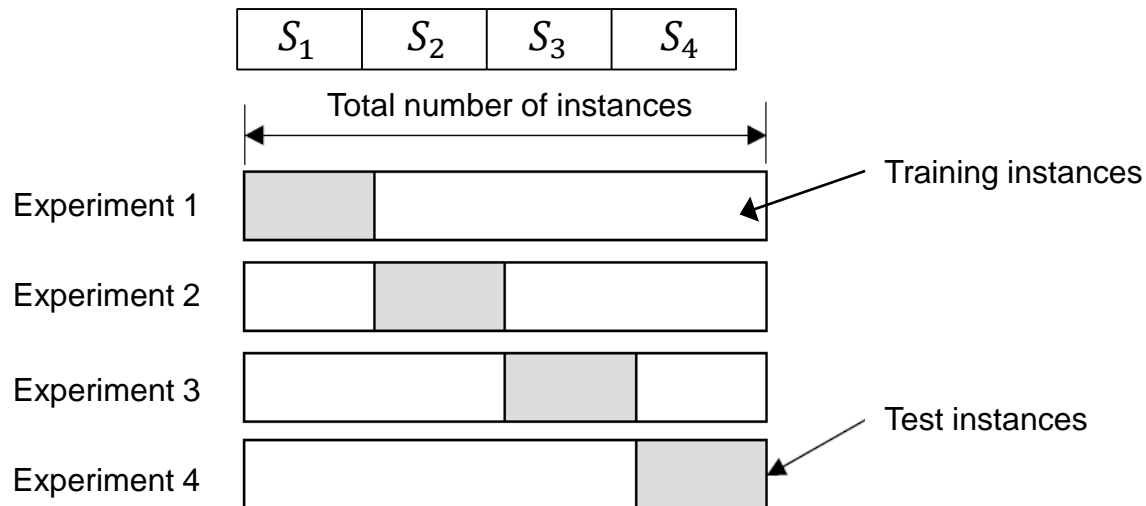
Holdout Testing: Analysis

- One could instead return model θ' .
- Empirical risk $\hat{R}_T(\theta')$ would be an unbiased estimate of $R(\theta')$.
- But since θ' was trained on fewer data, it would result in an inferior model.



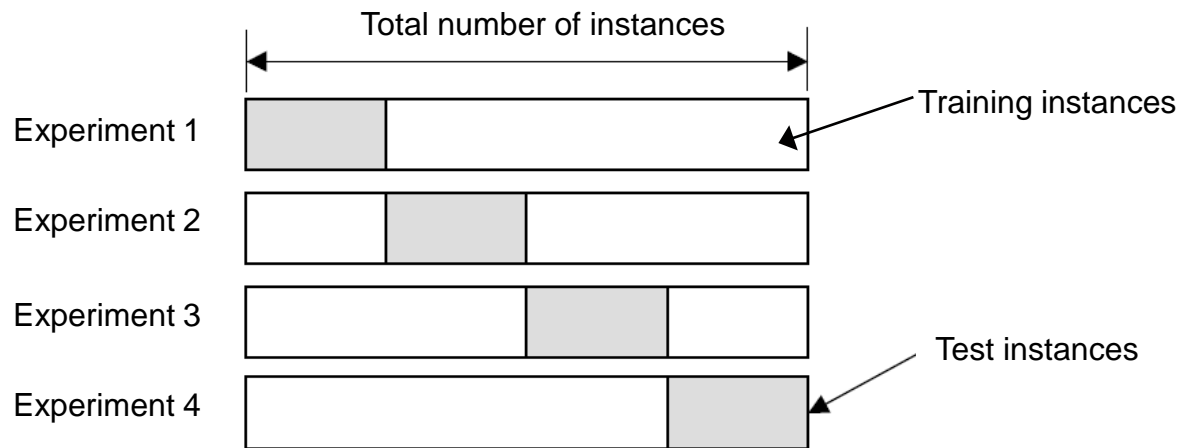
K-Fold Cross Validation

- Given: data $S = (\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)$
- Partition S into k equally sized portions S_1, \dots, S_k .
- Repeat for $i = 1 \dots k$
 - ◆ Train f_{θ_i} with training set $S = S \setminus S_i$.
 - ◆ Calculate empirical risk $\hat{R}_{S_i}(\theta_i)$ on S_i .
- Calculate average $\hat{R}_S = \frac{1}{k} \sum_i \hat{R}_{S_i}(\theta_i)$



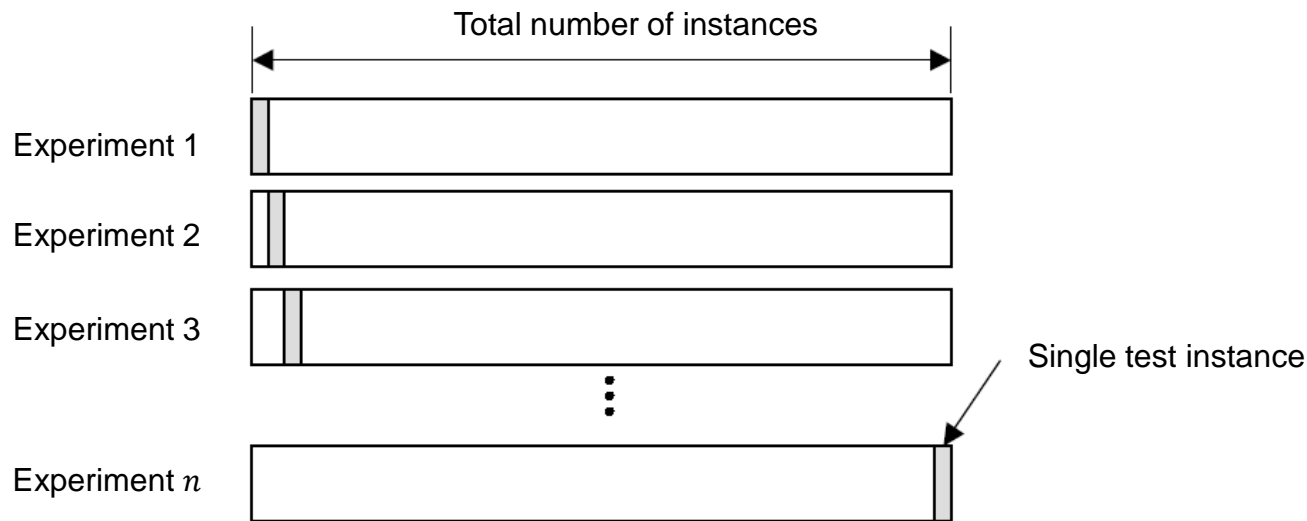
Cross Validation

- Then, train f_θ on all data S .
- Return model f_θ and estimator \hat{R}_S .



Leave-One-Out Cross Validation

- Special case $k = n$ is also called *leave-one-out* error estimation

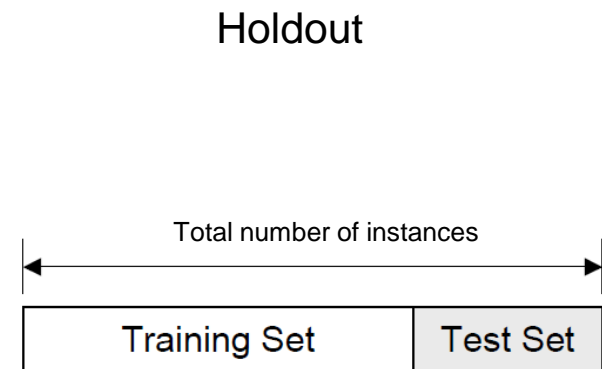
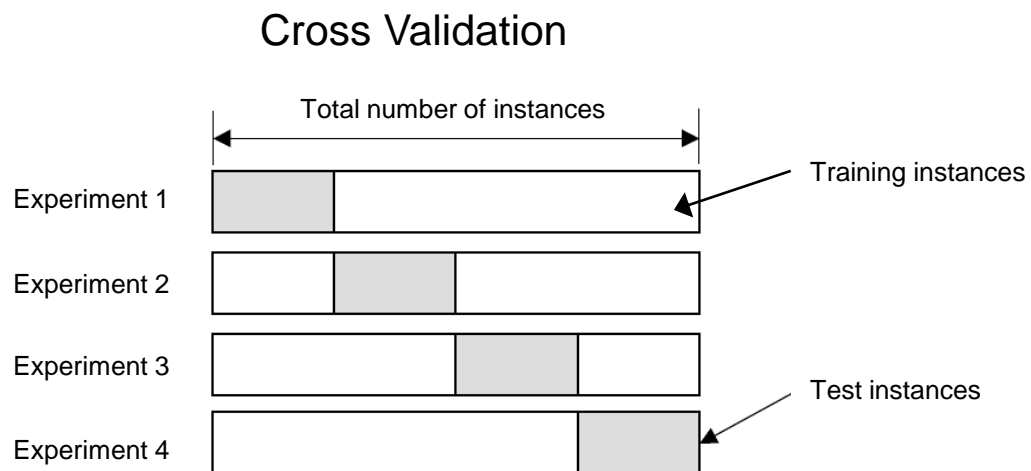


Cross Validation: Analysis

- Is the estimator
 - ◆ optimistic / pessimistic / unbiased?

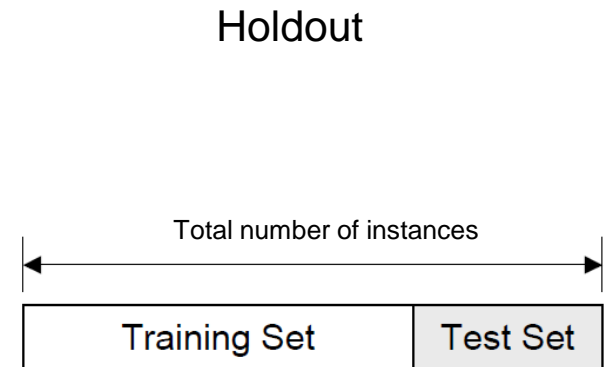
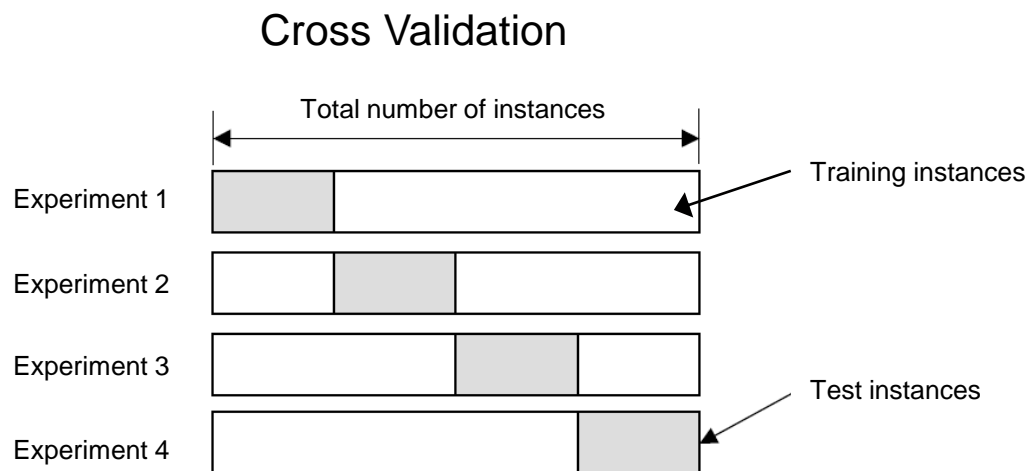
Cross Validation: Analysis

- Is the estimator
 - ◆ optimistic / pessimistic / unbiased?
- Estimator is slightly pessimistic:
 - ◆ Model f_{θ_i} is trained on a $(k - 1)/k$ -th fraction of the available data.
 - ◆ Model f_{θ} is trained on the entire data.



Cross Validation: Analysis

- Bias/Variance compared to holdout testing?
- Variance is lower than with holdout testing
 - ◆ Averaging over several holdout experiments reduces the estimator's variance.
 - ◆ All data is incorporated into the estimator.
- Bias similar to holdout testing, depending on the split ratios.



Overview

- Risk, empirical risk
- Precision, recall
- ROC curves
- Evaluation protocols
- **Model selection**

Model Selection

- Compare several different learning approaches
 - ◆ Should one use decision trees?
 - ◆ SVMs? Logistic Regression?
- Set regularization parameter for a learning approach
 - ◆ For instance, set value for λ for regularized empirical risk minimization.

Model Selection: Example

- Regularization parameter λ in optimization criterion

$$\theta^* = \operatorname{argmin}_{\theta} \sum_i \ell(f_{\theta}(\mathbf{x}_i), y_i) + \lambda \|\theta\|^2 \quad \lambda = ?$$

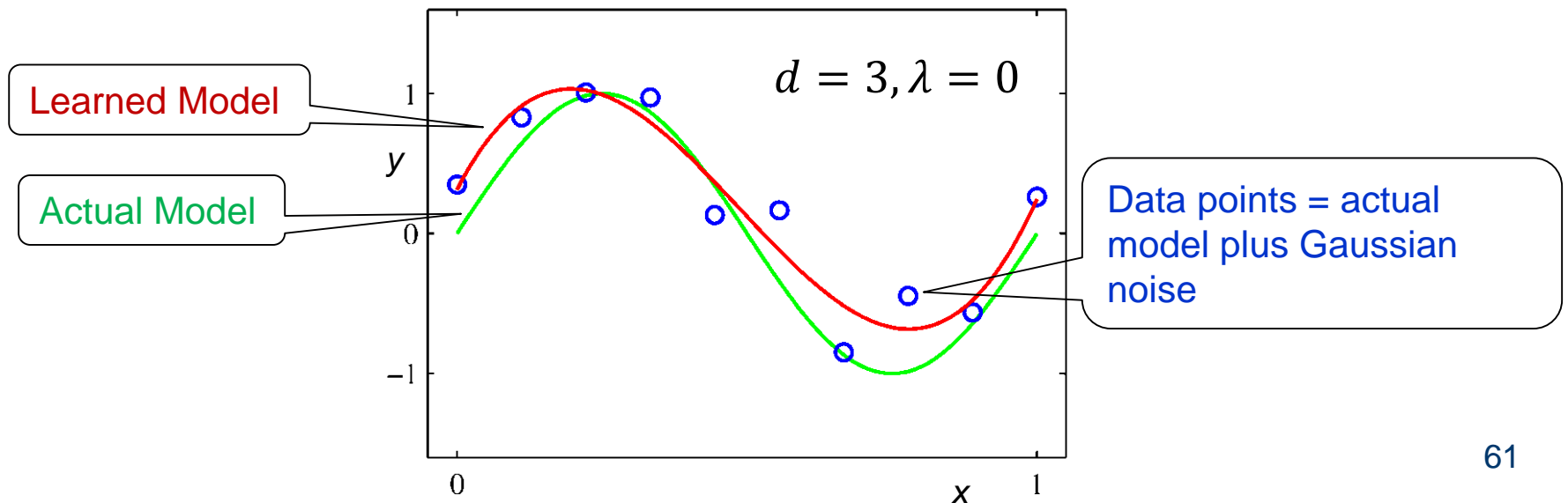
- (Hyper)parameters that specify the model class;
e.g. the degree for polynomial regression

$$f_{\theta}(x) = \sum_{j=0}^d \theta_j x^j \quad d = ?$$

- Desired output: hyperparameter (λ, d) , model f_{θ} , and estimate of the model's risk.
- How do we use available data to achieve this?

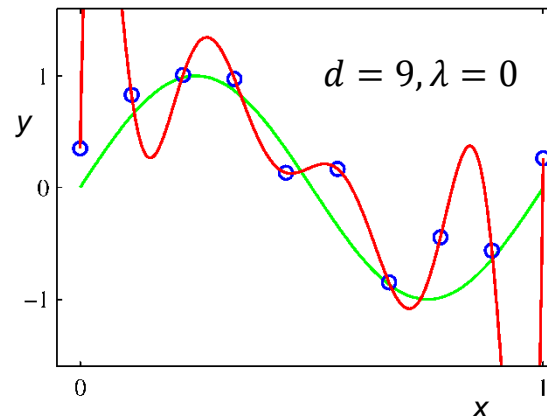
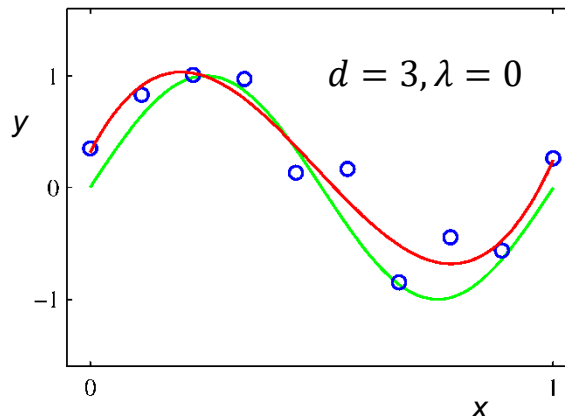
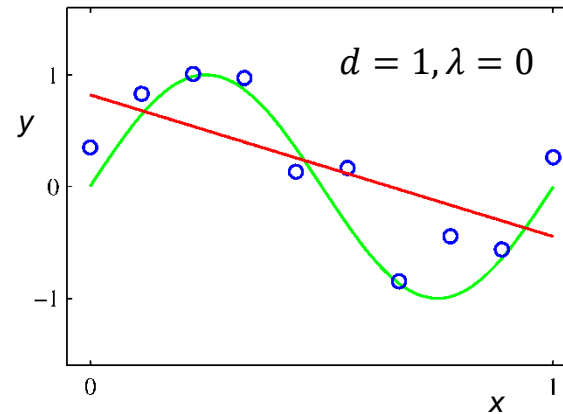
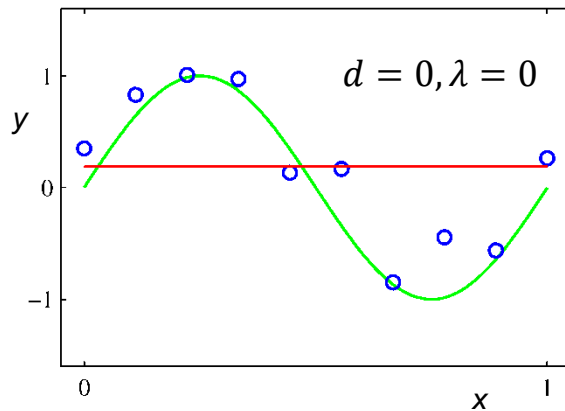
Example: Polynomial Regression

- Polynomial model of degree d : $f_{\theta}^d(x) = \sum_{j=0}^d \theta_j x^j$
- Regularized empirical risk minimization: $\theta^* = \underset{\theta}{\operatorname{argmin}} \sum_{i=1}^n (f_{\theta}^d(x_i) - y_i)^2 + \lambda \|\theta\|^2$



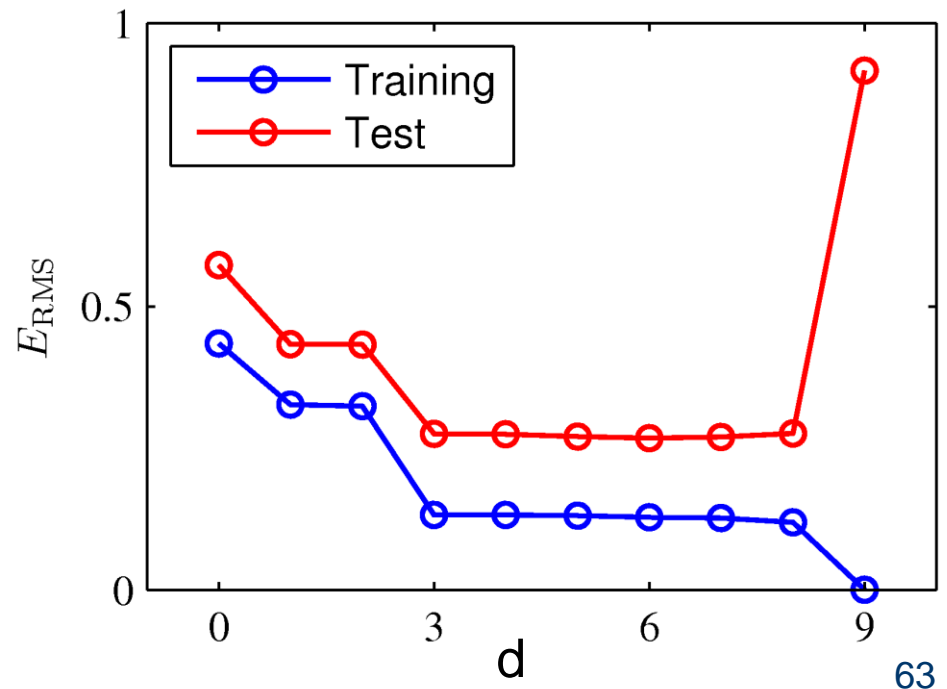
Polynomial Regression

- Success of the learning depends on the selected polynomial degree d , which controls the complexity of the model.



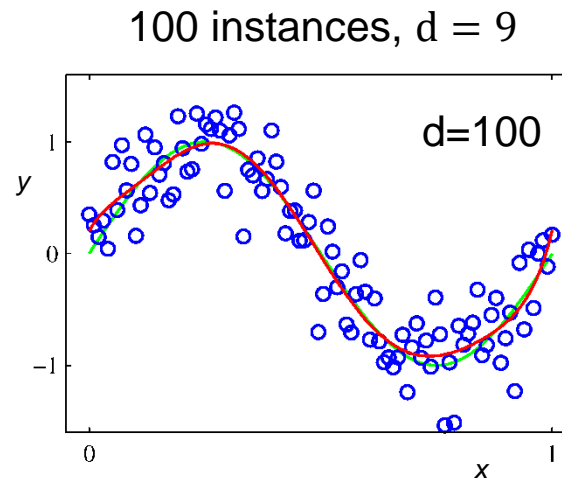
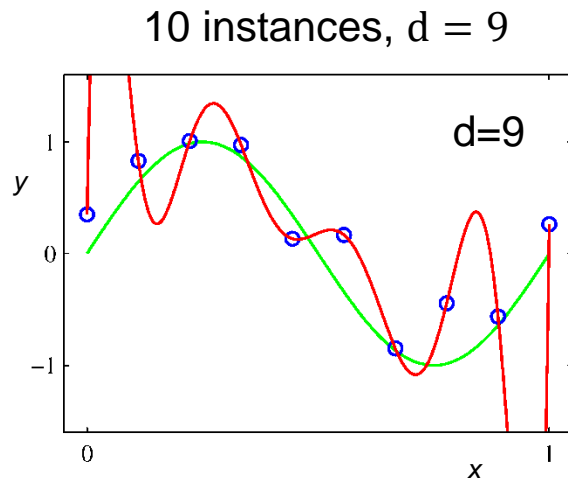
Polynomial Regression: Empirical Risk on Training vs. Test Sample

- Empirical risk on training vs. test data for different polynomial degrees.
- “Overfitting”: empirical risk on training data decreases as d is increased. Empirical risk on test data has a minimum, then increases again.



Example: Polynomial Regression

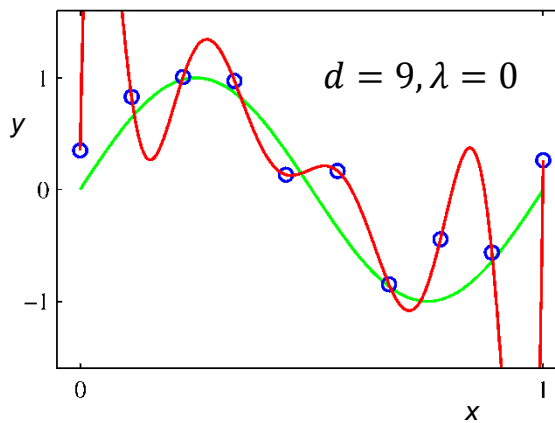
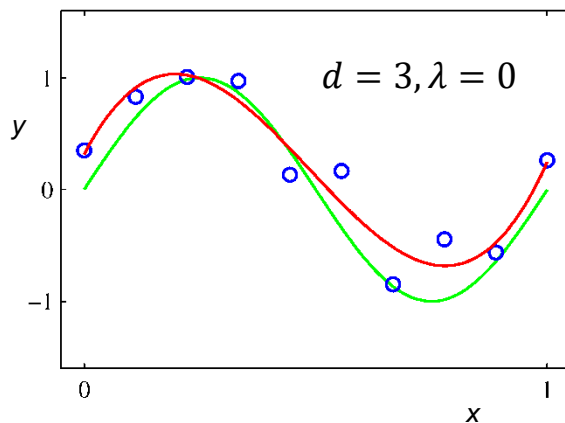
- If more data are available, more complex models can be fitted.



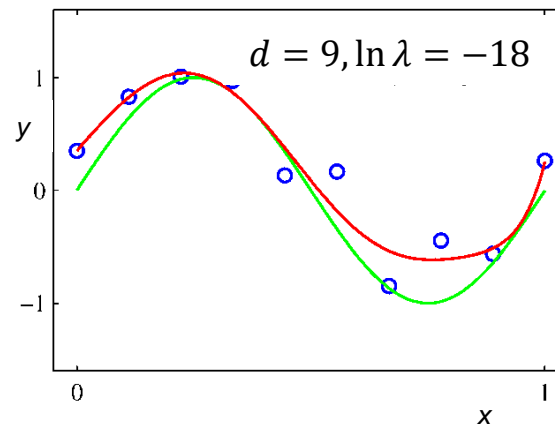
- Given fixed amount of data, optimal d has to be found.

Example: Polynomial Regression

- Regularization factor λ has a similar effect to d .

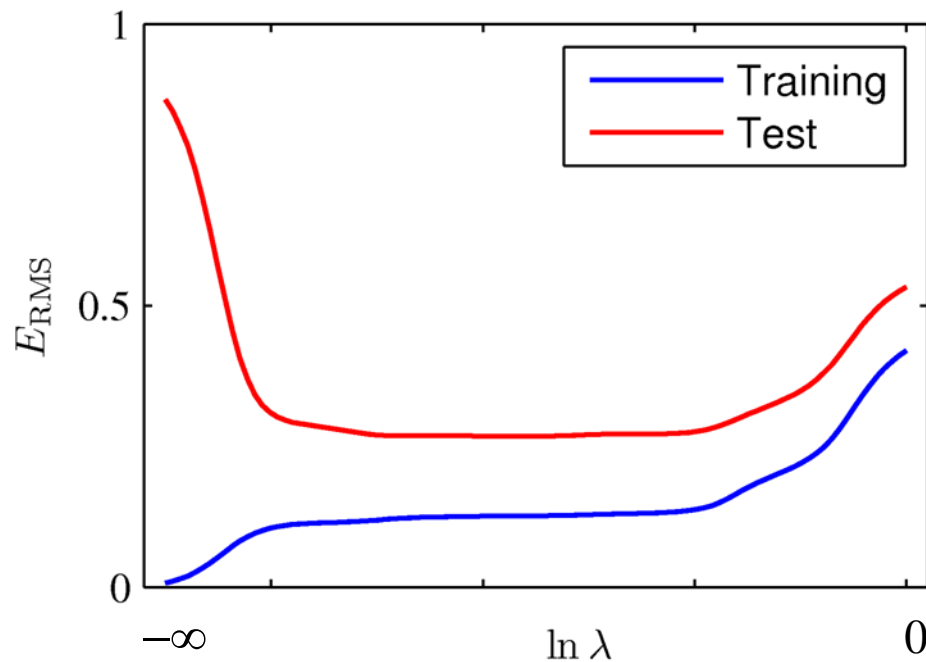


- Both λ and d constrain the model complexity.



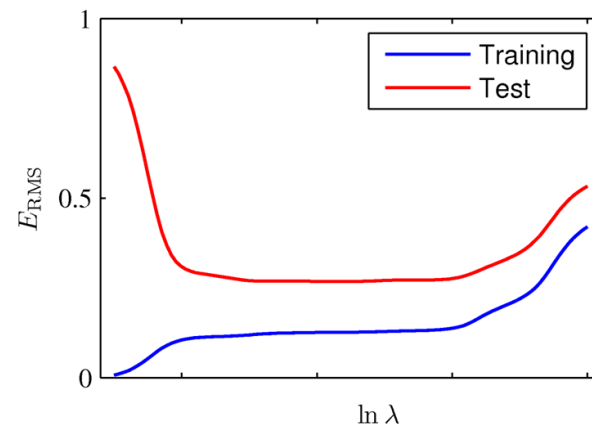
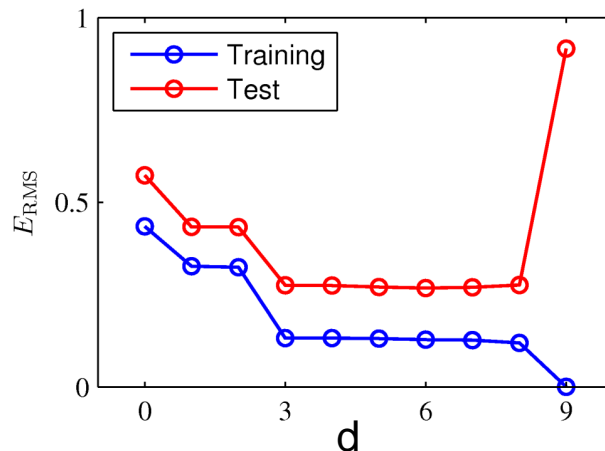
Regularized Polynomial Regression

- Empirical risk on training vs. test sample.
- Empirical risk on training sample decreases when regularization decreases.
- There is a regularization factor that minimizes the risk.



Regularized Polynomial Regression

- Regularizer acts like a limitation on the model complexity and prevents overfitting.
- In practice it is best to control model complexity through regularization (direct parameters like the polynomial degree often are not available).
- Regularizer has to be tuned on available data.

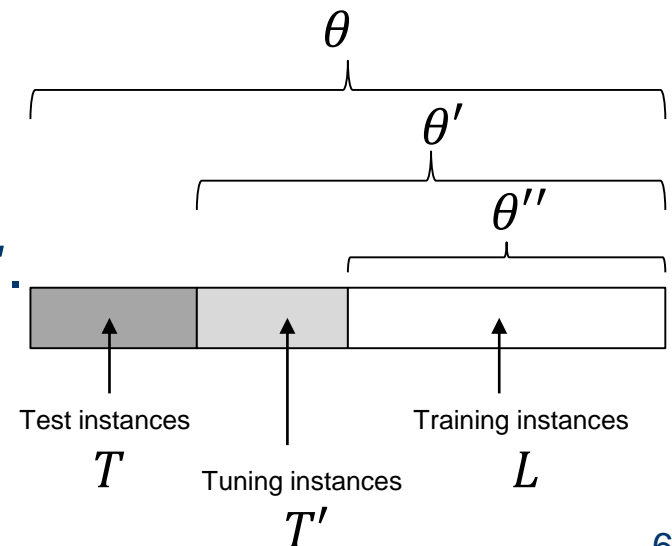


Model Selection, Setting Hyperparameters

- Desired output: hyperparameter (λ, d) , model f_θ , and estimate of the model's risk.
- Idea: Iterate over values of (λ, d) , train model, evaluate; take best values and train final model.
- Cannot tune hyperparameters on training data because low regularization leads to low empirical risk on training data but high risk on test data.
- Evaluating multiple models (for different values of λ, d) on the same test set results in an optimistic bias.
- Therefore, triple or nested cross validation.

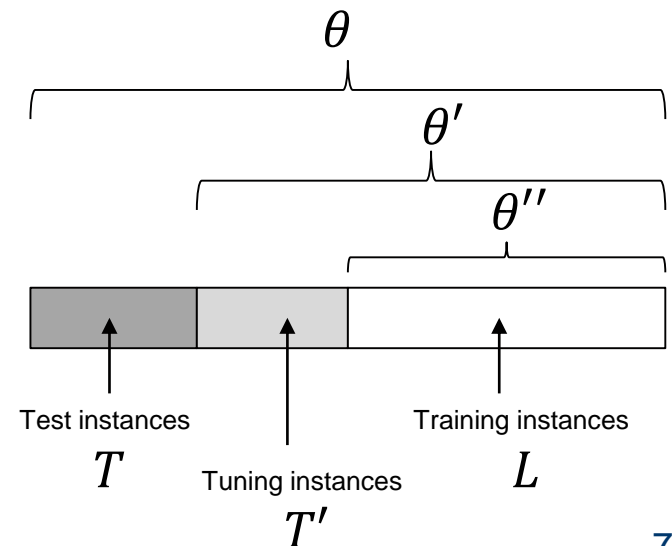
Triple Cross Validation

- Iterate over all values of the hyperparameters λ (grid search)
 - ◆ Train model $f_{\theta''}^{\lambda}$ on L .
 - ◆ Evaluate $f_{\theta''}^{\lambda}$ on T' by calculating $\hat{R}_{T'}(f_{\theta''}^{\lambda})$
- Use hyperparameter λ^* that gave lowest $\hat{R}_{T'}(f_{\theta''}^{\lambda^*})$.
- Train model $f_{\theta'}^{\lambda^*}$ on $L \cup T'$.
- Determine $\hat{R}_T(f_{\theta'}^{\lambda^*})$.
- Train model $f_{\theta}^{\lambda^*}$ on $L \cup T' \cup T$.
- Return model $f_{\theta}^{\lambda^*}$ and estimate $\hat{R}_T(f_{\theta}^{\lambda^*})$.



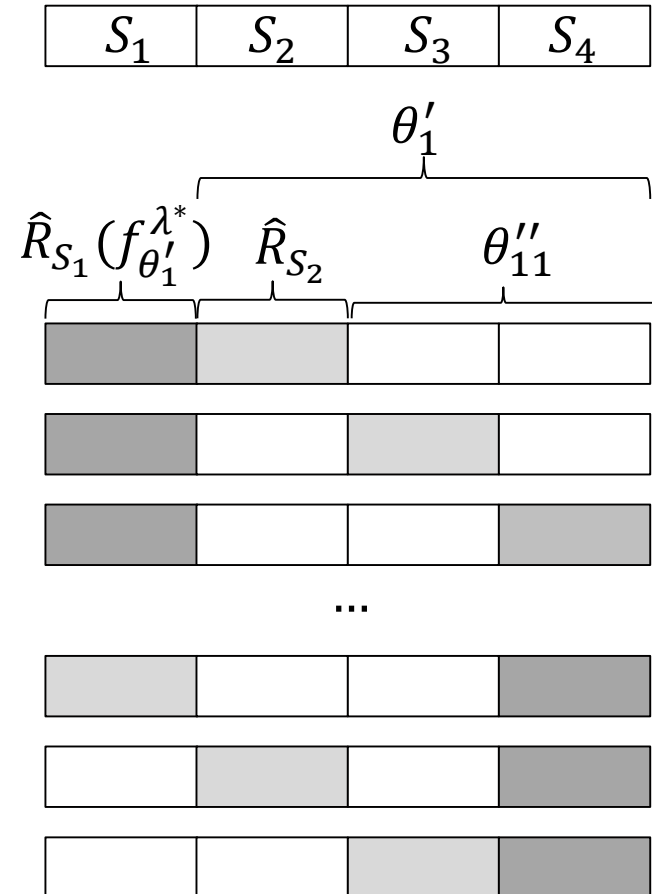
Triple Cross Validation: Analysis

- Empirical risk $\hat{R}_T(\theta')$ is a pessimistic estimator for $R(\theta)$ because θ' is trained on less data than θ .
- λ^* may be a poor estimate of the optimal parameters because T' may be small.
- The variance of $\hat{R}_T(\theta')$ may high because T may be small.
- Protocol is used when the total sample S is very large.



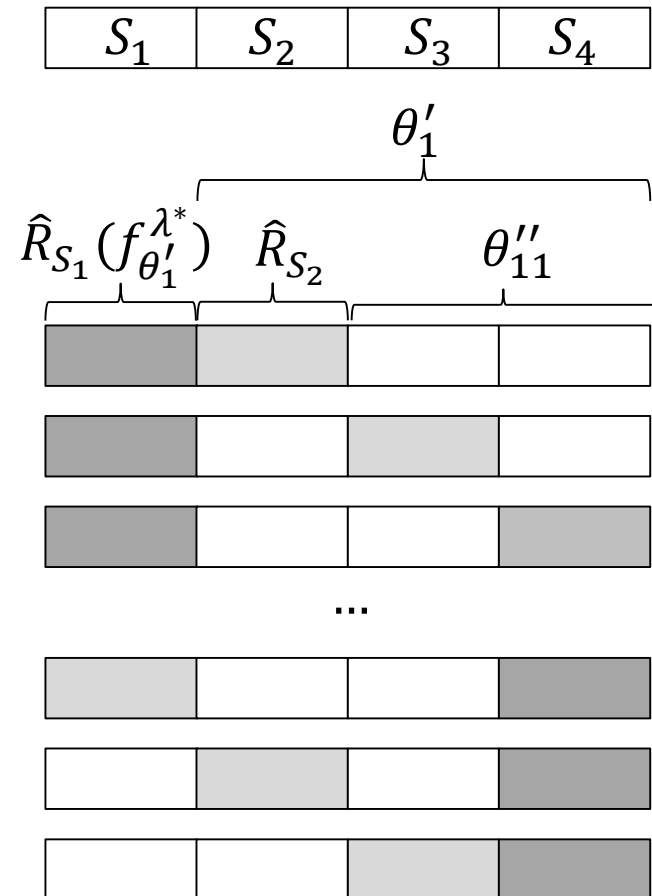
Nested Cross Validation

- For $i = 1 \dots k$
 - ◆ Iterate over values λ
 - ★ For $j = 1 \dots k \setminus i$
 - Train $f_{\theta_{ij}}^\lambda$ on $S \setminus S_i \setminus S_j$
 - Determine $\hat{R}_{S_j}(f_{\theta_{ij}}^\lambda)$
 - ★ Average \hat{R}_{S_j} to determine $\hat{R}_{S \setminus S_i}(f_{\theta'_i}^\lambda)$
 - ◆ Choose λ_i^* that minimizes $\hat{R}_{S \setminus S_i}(f_{\theta'_i}^\lambda)$
 - ◆ Train $f_{\theta_i}^{\lambda_i^*}$ on $S \setminus S_i$
 - ◆ Determine $\hat{R}_{S_i}(f_{\theta_i}^{\lambda_i^*})$
- Average $\hat{R}_{S_i}(f_{\theta_i}^{\lambda_i^*})$ to determine $\hat{R}_S(f_{\theta^*}^{\lambda^*})$
- Determine λ^* by simple cross validation (iterate over values λ , train on $S \setminus S_i$, measure $\hat{R}_{S_i}(f_{\theta_i}^\lambda)$)
- Train $f_{\theta}^{\lambda^*}$ on S
- Return $f_{\theta}^{\lambda^*}$ and $\hat{R}_S(f_{\theta^*}^{\lambda^*})$



Nested Cross Validation: Analysis

- Complexity: k^2 models have to be trained and evaluated
- Slightly pessimistic because $f_{\theta}^{\lambda^*}$ has been trained on more data than the $f_{\theta_i}^{\lambda_i^*}$.
- Lower variance than triple cross validation because all data is used for evaluation
- Better estimate of λ^* because almost all data is used for tuning.
- Best tuning protocol when few data are available.



Summary

- Risk: expected loss over input distribution $p(\mathbf{x}, y)$.
- Empirical risk: estimate of risk on data.
- Precision-recall curves and ROC curves characterize decision function. Each point on curve is classifier for some threshold θ_0 .
- Evaluation protocols:
 - ◆ Hold-out testing: good for large samples
 - ◆ K-fold Cross Validation: good for small samples.
- Model selection: tune model hyperparameters.
 - ◆ Triple cross validation: good for large samples.
 - ◆ Nested cross validation: good for small samples.