1 Problem Set I solving wave equation

$$\frac{\partial^2 \phi}{\partial^2 t} = c^2 \frac{\partial^2 \phi}{\partial^2 x} \tag{1}$$

1.1 fully first order formulation

$$\eta = \phi_{,t}, \quad \chi = \phi_{,x} \tag{2}$$

 $\eta(t,x)\chi(t,x)\vec{u}(\phi,\eta,\chi)$

$$\vec{u}_{,t} + \mathbf{A}\vec{u}_{,x} = \vec{S} \tag{3}$$

1.2 initial condition

$$\phi(0,x) = e^{\sin^2\left(\frac{\pi x}{L}\right)} - 1, \quad 0 \le x \le L \tag{4}$$

with periodic condition:

$$\phi(t,x) = \phi(t,x \pm L) \tag{5}$$

2 Program

```
#include <cstdio>
1
    #include <cmath>
    #include <fstream>
    #include <iostream>
   using namespace std;
    void output(int ti, int xi, double t, double x[], double phi[][2]);
    void init(double t, double x[], double phi[][2], double eta[][2], double chi[][2],

→ int xSteps, double dx, double L);
    void boundaryCondition(int ti, int xSteps, double phi[][2], double eta[][2], double

    chi[][2]);

    double secondOrderSpatial(double funct2[][2], int xi, double dx);
10
    void forwardEulerMethod(double funct[][2], double funct2[][2], double dt, int xi,
11

→ double dx, double factor, int deriv);

    void solvingWaveEquation(double phi[][2], double eta[][2], double chi[][2], double t,

→ double dt, double x[], double dx, double CSpeed, int xSteps, int tSteps);
    void updateFunc(int xSteps, double phi[][2], double eta[][2], double chi[][2]);
13
    void gnuplot();
14
    void rungekuttaSolver(double y[],int n,double x,double h, void (derivs)(double,
15

→ double[], double[]));
    void waveDGL(double dt, double y[], double dydt[], double dx);
16
17
    void output(int ti, int xi, double t, double x[], double phi[][2]){
        // x phi
19
        cout << x[xi] << ' ' << phi[xi][ti] << endl;</pre>
20
    };
21
22
    void init(double t, double x[], double phi[][2], double eta[][2], double chi[][2],
23
    → int xSteps, double dx, double L){
        cout << "reset" << endl;</pre>
        cout << "set xrange [0:1]" << endl;</pre>
        cout << "set yrange [-10:10]" << endl;</pre>
26
        gnuplot();
27
        for (int i = 2; i < xSteps-2; i=i+1) {</pre>
```

```
phi[i][0] = exp(pow(sin(M_PI/L*((i-2)*dx)),2))-1;
                                      //chi[i][0] = phi[i][0];
30
                                      chi[i][0] =
31
                                       \rightarrow exp(pow(sin(M_PI/L*((i-2)*dx)),2))*2*sin(M_PI/L*((i-2)*dx))*cos(M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx)*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx)*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx)*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx)*M_PI/L*((i-2)*dx)*M_PI/L*((i-2)*dx)*M_PI/L*((i-2)*dx)*M_PI/L*((i-2)*dx)*M_PI/L*((i-2)*dx)*M_PI/L*((i-2)*dx)*M_PI/L*((i-2)*dx)*M_PI/L*((i-2)*dx)*M_PI/L*((i-2)*dx)*M_PI/L*((i-2)*dx)*M_PI/L*((i-2)*d
                                      //chi[i][0] = (i-2)*dx;
32
                                      //chi[i][0] = sin(M_PI/L*((i-2)*dx));
33
                                      //chi[i][0] = 1;
34
                                      eta[i][0] = -chi[i][0];
35
                                      //eta[i][0] = 0;
36
                                      //eta[i][0] = 1;
37
                                      //eta[i][0] = pow(sin(M_PI/L*((i-2)*dx)),2);
38
                                      //eta[i][0] =
                                                exp(pow(sin(M_PI/L*((i-2)*dx)),2))*2*sin(M_PI/L*((i-2)*dx))*cos(M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx)*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx)*M_PI/L*((i-2)*dx)*M_PI/L*((i-2)*dx)*M_PI/L*((i-2)*dx))*M_PI/L*((i-2)*dx)*M_PI/L*((i-2)*dx)*M_PI/L*((i-2)*dx)*M_PI/L*((i-
                                      x[i]=(i-2)*dx;
40
                                      output(0, i, t, x, phi);
41
                                      x[xSteps-2]=(xSteps-4)*dx;
                         boundaryCondition(0, xSteps, phi, eta, chi);
44
                         output(0, (xSteps-2), t, x, phi);
45
            };
47
48
             void boundaryCondition(int ti, int xSteps, double phi[][2], double eta[][2], double
49
                        chi[][2]){
                        phi[0][ti] = phi[xSteps-5][ti];
50
                         eta[0][ti] = eta[xSteps-5][ti];
51
                         chi[0][ti] = chi[xSteps-5][ti];
52
                         phi[1][ti] = phi[xSteps-4][ti];
                         eta[1][ti] = eta[xSteps-4][ti];
54
                         chi[1][ti] = chi[xSteps-4][ti];
55
                         phi[xSteps-3][ti] = phi[2][ti];
56
                         eta[xSteps-3][ti] = eta[2][ti];
57
                         chi[xSteps-3][ti] = chi[2][ti];
58
                         phi[xSteps-2][ti] = phi[3][ti];
59
                         eta[xSteps-2][ti] = eta[3][ti];
                         chi[xSteps-2][ti] = chi[3][ti];
                         phi[xSteps-1][ti] = phi[4][ti];
62
                         eta[xSteps-1][ti] = eta[4][ti];
63
                         chi[xSteps-1][ti] = chi[4][ti];
64
            };
65
66
             double secondOrderSpatial(double funct2[][2], int xi, double dx){
67
                         return (funct2[xi+1][0]-funct2[xi-1][0])/(2*dx);
            };
69
70
             void forwardEulerMethod(double funct[][2], double funct2[][2], double dt, int xi,
71

→ double dx, double factor, int deriv) {
                         if (deriv == 0) {
72
                                      funct[xi][1]=funct[xi][0]+factor*dt*funct2[xi][0];
73
                         } else {
                                      funct[xi][1]=funct[xi][0]+factor*dt*secondOrderSpatial(funct2, xi, dx);
76
             };
77
             void solvingWaveEquation(double phi[][2], double eta[][2], double chi[][2], double t,
79
                        double dt, double x[], double dx, double CSpeed, int xSteps, int tSteps){
                         for (int j = 1; j <= tSteps; j=j+1) {</pre>
80
                                      t=j*dt;
                                      gnuplot();
                                      for (int i = 2; i < xSteps-2; i=i+1) {</pre>
83
```

```
forwardEulerMethod(phi, eta, dt, i, dx, 1, 0);
                  forwardEulerMethod(eta, chi, dt, i, dx, pow(CSpeed, 2), 1);
85
                  forwardEulerMethod(chi, eta, dt, i, dx, 1, 1);
86
                  output(1, i, t, x, phi);
87
              };
88
              boundaryCondition(1, xSteps, phi, eta, chi);
89
              output(1, (xSteps-2), t, x, phi);
90
              cout << "elapsed time" << endl;</pre>
91
              updateFunc(xSteps, phi, eta, chi);
92
         };
93
     };
94
     void updateFunc(int xSteps, double phi[][2], double eta[][2], double chi[][2]){
96
         for (int i = 0; i <= xSteps; i=i+1) {</pre>
97
              phi[i][0] = phi[i][1];
98
              chi[i][0] = chi[i][1];
              eta[i][0] = eta[i][1];
100
              }
101
     };
102
     void gnuplot(){
104
         cout << "plot '-' w 1" << endl;</pre>
105
     };
106
107
108
109
     void waveDGL(double t, double y[], double dydt[], double dx){
110
         //dydt[0] =y[1];
111
         //dydt[1] = pow(CSpeed, 2)*(-y[2][i+2]+8*y[2][i+1]-8*y[2][i-1]+y[2][i-2])/(12*dx)
112
         //dydt[2] = (-y[1][i+2]+8*y[1][i+1]-8*y[1][i-1]+y[1][i-2])/(12*dx);
113
     }
114
115
     int main(int argc, char** argv)
116
         const double CSpeed = 1;
         const double CMax = 0.005;
119
         const double dx = stod(argv[1]); //
120
         const double L = 1; // gridSpace
121
         const double timeLength = 1;
122
         const double dt = CMax*dx/abs(CSpeed);
123
         const int nGhosts = 4;
124
         const int xSteps = int( L / dx ) + nGhosts;
         //const int tSteps = int (timeLength / dt );
126
         const int tSteps = int ( stod(argv[2]));
127
128
         double //
129
         x[xSteps],
130
         t=0.
131
         phi[xSteps][2],
132
         chi[xSteps][2],
133
         eta[xSteps][2]
134
135
136
         cout << "# parameters dx=" << dx << " dt=" << dt << " xSteps=" << xSteps <<
137
          \hookrightarrow endl;
138
         init(t, x, phi, eta, chi, xSteps, dx, L);
140
         // cases for solver
141
```

```
//{{solving wave equation}}
solvingWaveEquation(phi, eta, chi, t, dt, x, dx, CSpeed, xSteps, tSteps);

//{{forth order spatial derivative}}
//{{Runge Kutter solver}}
return 0;
};
```