

$$\delta x^1 = \delta x_0^1$$

$$\delta x^2 = \delta x_0^2 + \frac{1}{2} (h_{2L}^{\text{TT}} \delta x_0^2 + h_{23}^{\text{TT}} \delta x_0^3)$$

$$\delta x^3 = \delta x_0^3 + \frac{1}{2} (h_{23}^{\text{TT}} \delta x_0^2 + h_{33}^{\text{TT}} \delta x_0^3)$$

$$h_{yy} = -h_{zz} = 2 \operatorname{Re} \{ A_+ e^{i\omega(t - \frac{x}{c})} \}$$

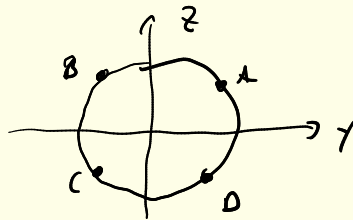
$$= 2A_+ \cos(\omega(t - \frac{x}{c}))$$

$$h_{yz} = h_{zy} = 2A_x \cos(\omega(t - \frac{x}{c}))$$

① $A_+ = \frac{1}{2}$ plus polarized

$$A_x = 0$$

② $A_+ < 0$ cross polarized
 $A_x = \frac{1}{2}$



$$\delta x^2 = \delta x_0^2 + \frac{1}{2} (h_{2L}^{\text{TT}} \delta x_0^2 + h_{23}^{\text{TT}} \delta x_0^3)$$

$$\delta x^3 = \delta x_0^3 + \frac{1}{2} (h_{23}^{\text{TT}} \delta x_0^2 + h_{33}^{\text{TT}} \delta x_0^3)$$

$$\delta x^2 = \delta x_0^2 + \frac{1}{2} (2A_+ c \delta x_0^2 + 2A_x c \delta x_0^3) \quad A_x = 0$$

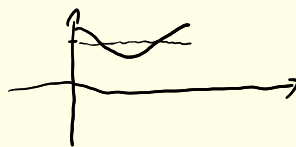
$$= \delta x_0^2 (1 + A_+ c) + A_x c \delta x_0^3 = \delta x_0^2 (1 + A_+ c)$$

$$\delta x^3 = \delta x_0^3 (1 - A_+ c) + A_x c \delta x_0^2 \quad A_x = 0$$

$$A = \frac{1}{2} \quad = \delta x_0^3 (1 - A_+ c) \quad (A_x = 0)$$

$$\delta x^2 = \delta x_0^2 (1 + \frac{1}{2} c)$$

$$\delta x^3 = \delta x_0^3 (1 - \frac{1}{2} c)$$



$$\frac{2\pi}{T} (t - \frac{x}{c}) = \frac{\pi}{2}$$

$$t = 0$$

$$-\frac{2\pi}{T} \frac{x}{c} = \frac{\pi}{2}$$

$$T = -\frac{4x}{c}$$

$$\omega(-\frac{x}{c}) = \frac{\pi}{2}$$

$$\omega = -\frac{\pi c}{2x}$$

$$(2) \quad A_+ = 0 \quad A_- = \frac{1}{2}$$

$$h_{yy} = -h_{zz} = 2\text{Re} \{ A_+ e^{i\omega(t-\frac{x}{c})} \}$$

$$= 2A_+ \cos(\omega(t-\frac{x}{c}))$$

$$h_{yz} = h_{zy} = 2A_- \cos(\omega(t-\frac{x}{c}))$$

$$\delta x^2 = \delta x_0^2 + \frac{1}{2} (h_{22}^{\text{TT}} \delta x_0^2 + h_{23}^{\text{TT}} \delta x_0^3)$$

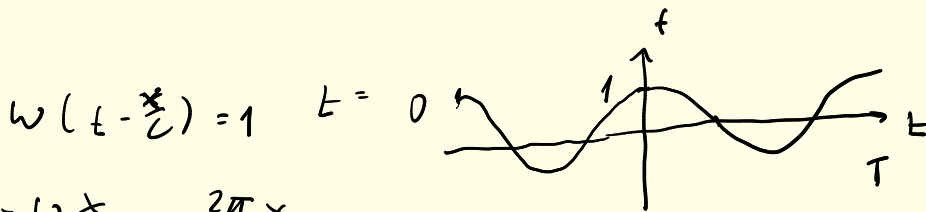
$$\delta x^3 = \delta x_0^3 + \frac{1}{2} (h_{23}^{\text{TT}} \delta x_0^2 + h_{33}^{\text{TT}} \delta x_0^3)$$

$$\delta x^2 = \delta x_0^2 (1 + A_+ c) + A_- c \delta x_0^3 \quad A_+ = 0 \quad A_- = \frac{1}{2}$$

$$\delta x^3 = \delta x_0^3 (1 - A_+ c) + A_- c \delta x_0^2$$

$$\delta x^2 = \delta x_0^2 + A_- c \delta x_0^3 = \delta x_0^2 + \frac{1}{2} c \delta x_0^3$$

$$\delta x^3 = \delta x_0^3 + A_- c \delta x_0^2 = \delta x_0^3 + \frac{1}{2} c \delta x_0^2$$



$$-\omega \frac{x}{c} = -\frac{2\pi}{T} \frac{x}{c} = 1$$

$$T = \frac{-2\pi x}{c}$$

Solution:

$$\delta x^1 = \delta x^1_0$$

$$\delta x^2 = \delta x^2_0 + \frac{1}{2} h_{yy} \delta x^2$$

$$\delta x^3 = \delta x^3_0 - \frac{1}{2} h_{yy} \delta x^3$$

$$A_x = 0$$

$$A_+ = \frac{1}{2}$$

$$\delta x^1 = \delta x^2 \left(1 + \frac{1}{2} A_+ \cos(\omega(t - \frac{x}{c})) \right)$$

$$\delta x^3 = \delta x^3 \left(1 - \frac{1}{2} A_+ \cos(\omega(t - \frac{x}{c})) \right)$$

$$A(0, r, 0) \quad C(0, -r, 0)$$

$$B(0, 0, r) \quad D(0, 0, -r)$$

$$\begin{matrix} \pi \\ A(0, \frac{3}{2}r, 0) & C(0, -\frac{3}{2}r, 0) \\ B(0, 0, \frac{r}{2}) & D(0, 0, -\frac{r}{2}) \end{matrix}$$

$$\begin{matrix} 2\pi \\ A(0, \frac{r}{2}, 0) & C(0, -\frac{r}{2}, 0) \\ B(0, 0, \frac{3}{2}r) & D(0, 0, -\frac{3}{2}r) \end{matrix}$$

$$-11- \quad \text{line } \vec{D}_2$$

in cross polarisation, both arms are stretched in the same way.

You need both plus and cross waves to detect and do not have blind spots.

So you need a network of many detectors around the world.