Balltracking method

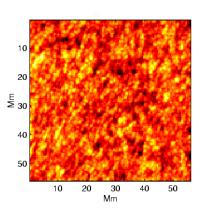
Christian Gößl

July 5, 2014

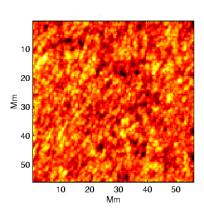
Structure

- Motivation
- Main idea
- Tracking procedure
 - Ball motion
 - Steps to Analysing data
 - Examples
- Further aspects

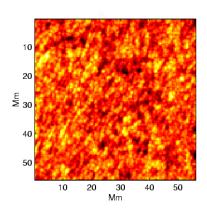
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- method for evaluation and dealculation of datas from
 SOHO/MDI



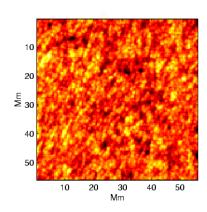
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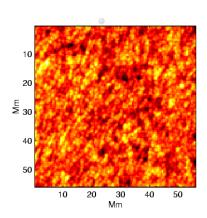
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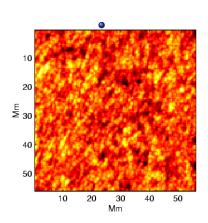
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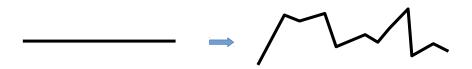
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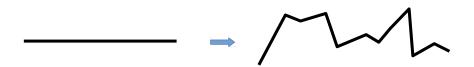
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- interaction between the bumps
- tracking the bumps with floating

- bumps push the balls
- approx balls have the average motion/direction of the bumps
- prediction of mean motion of the bumps



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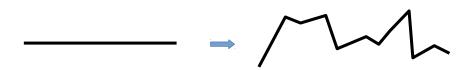
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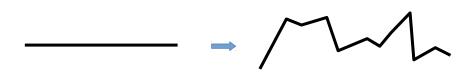
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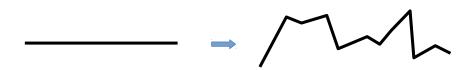
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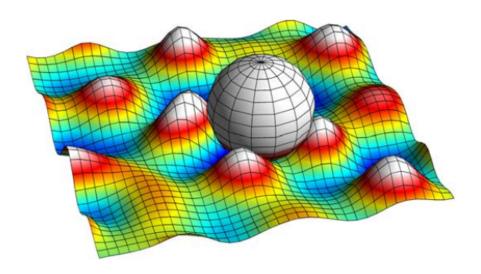
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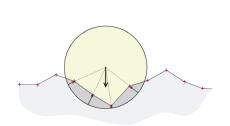


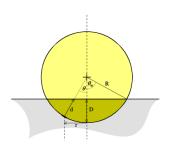
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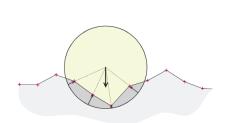
Main idea

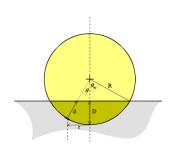




- $m\vec{v} = \sum_i \vec{f}_i m\vec{g} \alpha \vec{v}$
- \vec{f}_i penetration force at each data points at the
- $m\vec{g}$ gravitation force and $-\alpha \vec{v}$ damping force

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$$d\vec{v} = dt \left(\frac{\widetilde{A}_m}{\pi \widetilde{D}_p^2 \widetilde{R}_s^2} \sum_i \widetilde{d}_i - \widetilde{A}_m \widetilde{g} - \frac{\vec{v}}{\widetilde{T}_d} \right)$$

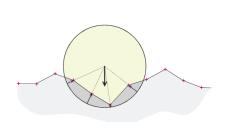


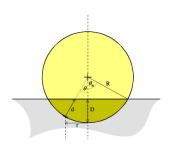


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- $m\vec{v} = \sum_{i} \vec{f}_{i} m\vec{g} \alpha \vec{v}$
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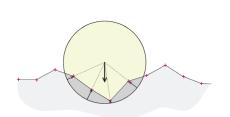


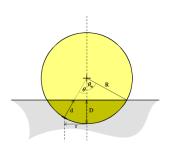


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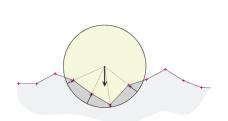
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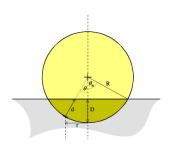




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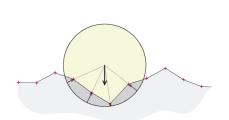


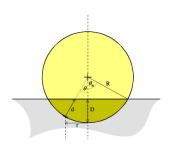




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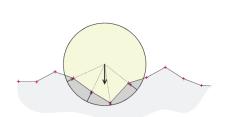


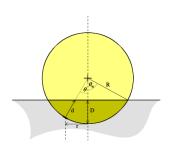


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1: choose number of ball:

- 2: divide data surface in a grid and randomly set balls in grid cells
- 3: let the balls settle down to the nearest local minimum
- 4: update the surface to the next time step

- 5: bumps moving, disappearing, forming and pushed the balls to the next local minimum (store new position)
- 6: remove any balls which too close to each other balls and falling off the edge
- Repeat from Step 4

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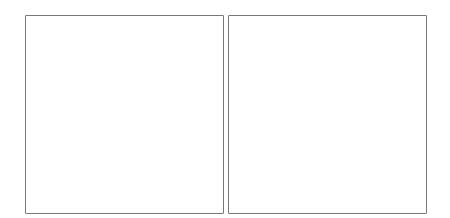
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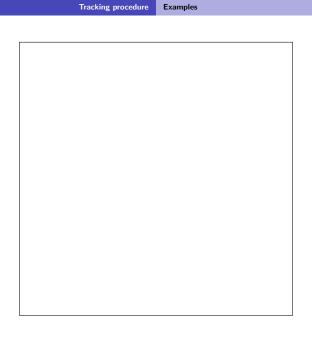
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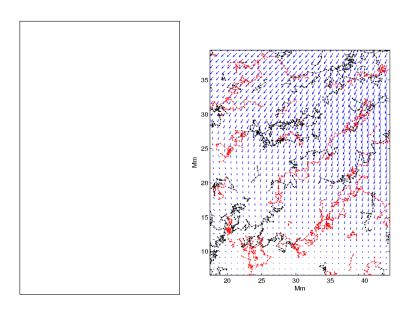
Examples



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- smoothing and rescaling the output data
 - smoothing resolution
 - speed calibration
- comparison between Local Correlation tracking LCT and Balltracking

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