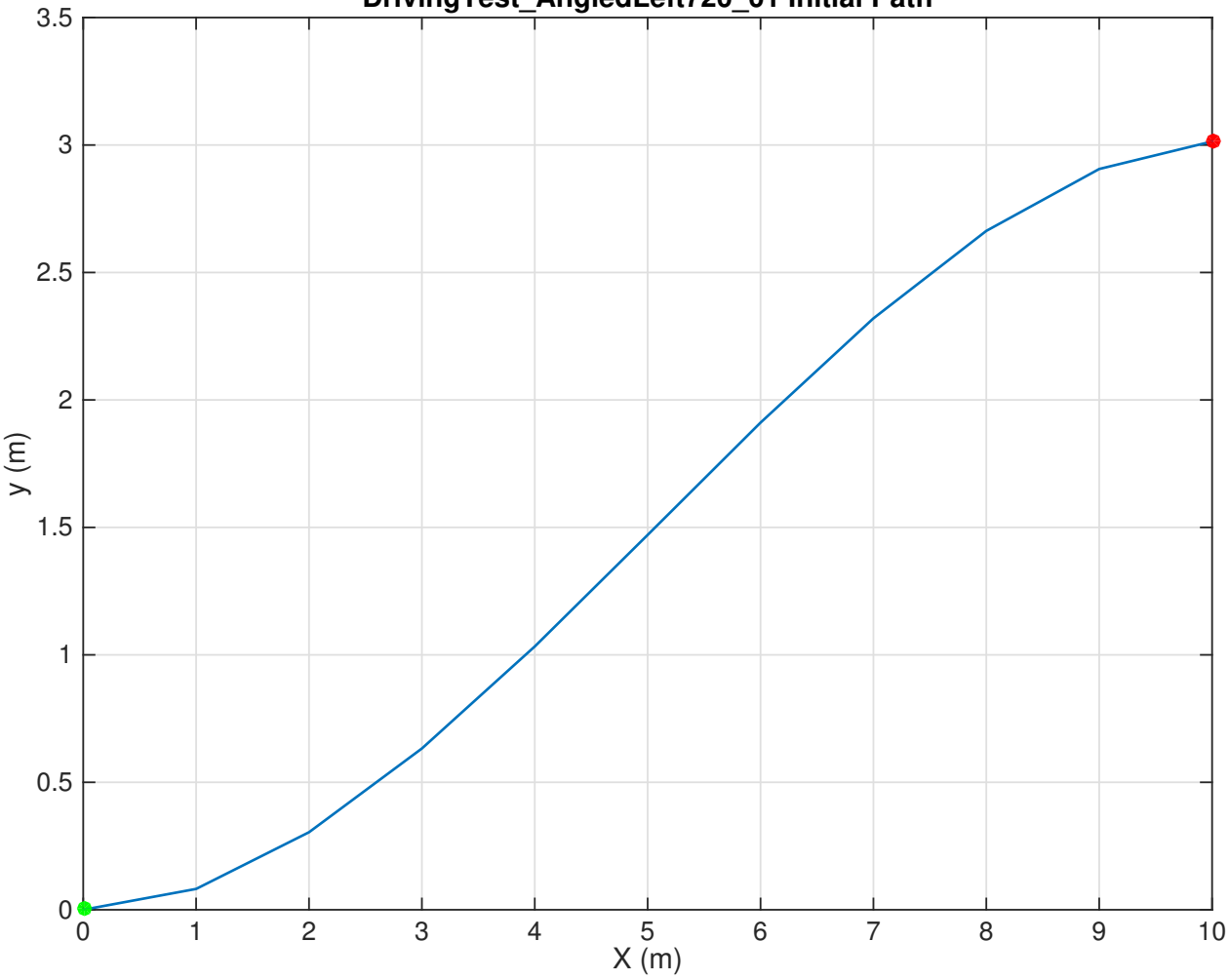
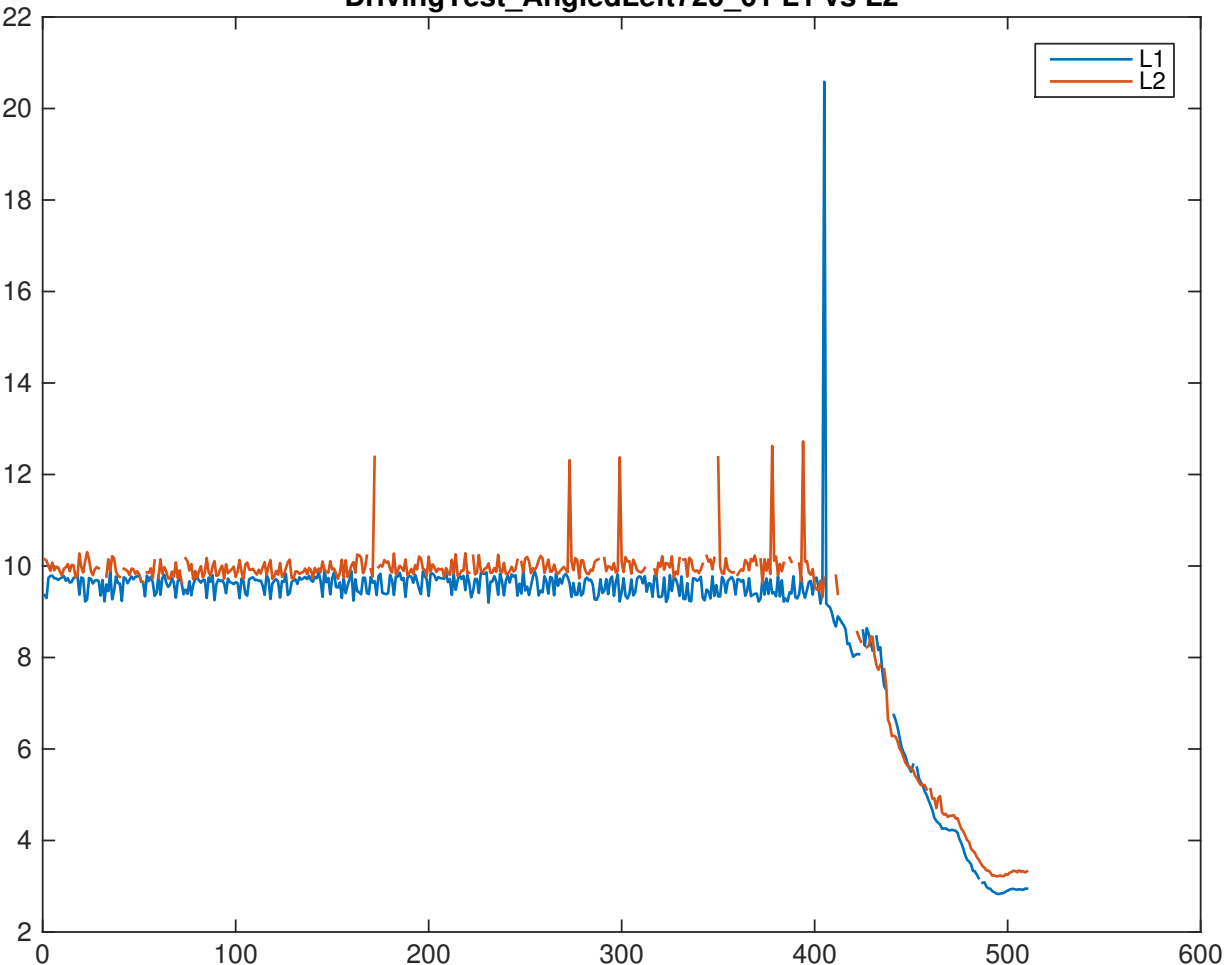


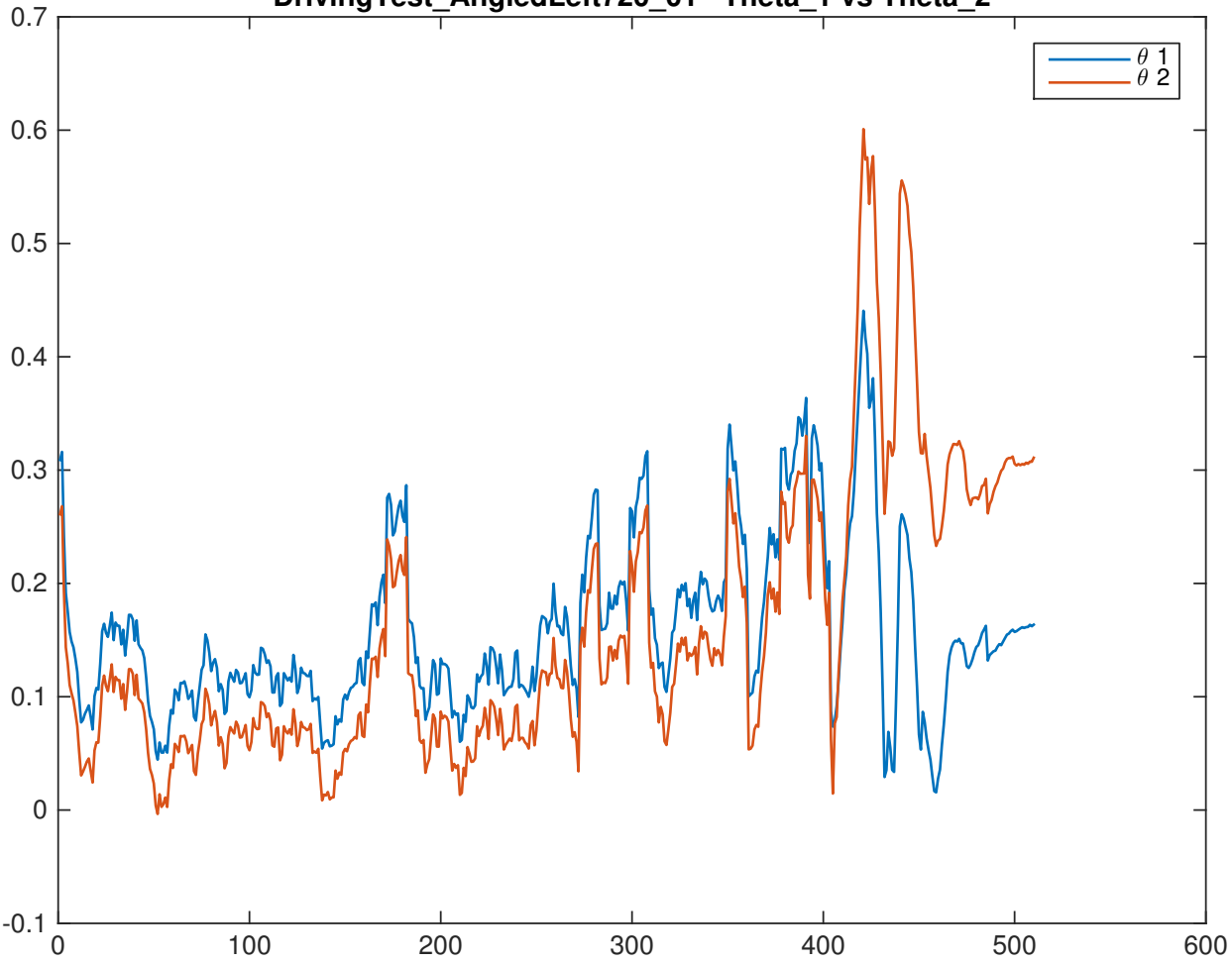
DrivingTest\_AngledLeft720\_01 Initial Path



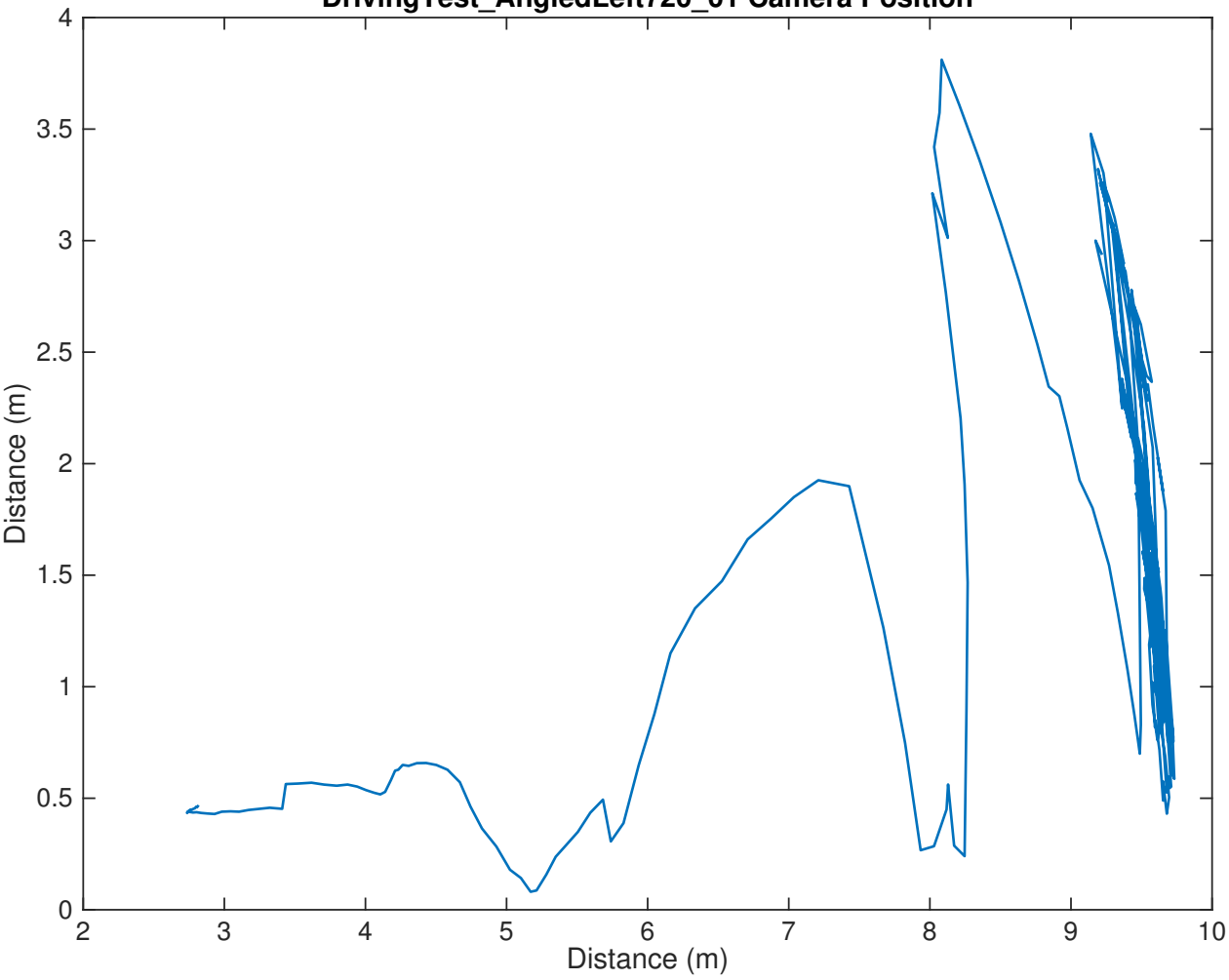
DrivingTest\_AngledLeft720\_01 L1 vs L2

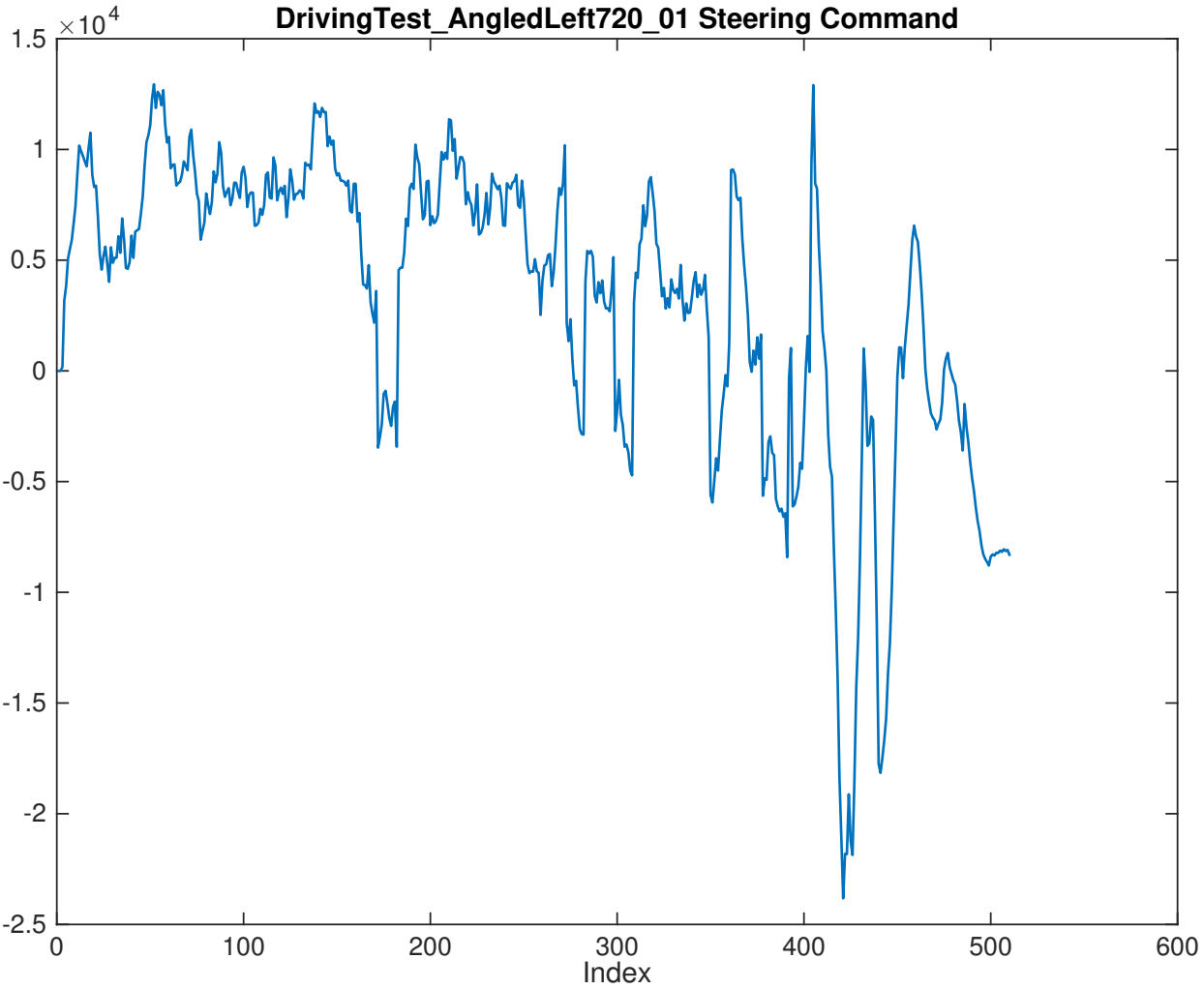


DrivingTest\_AngledLeft720\_01 Theta\_1 vs Theta\_2

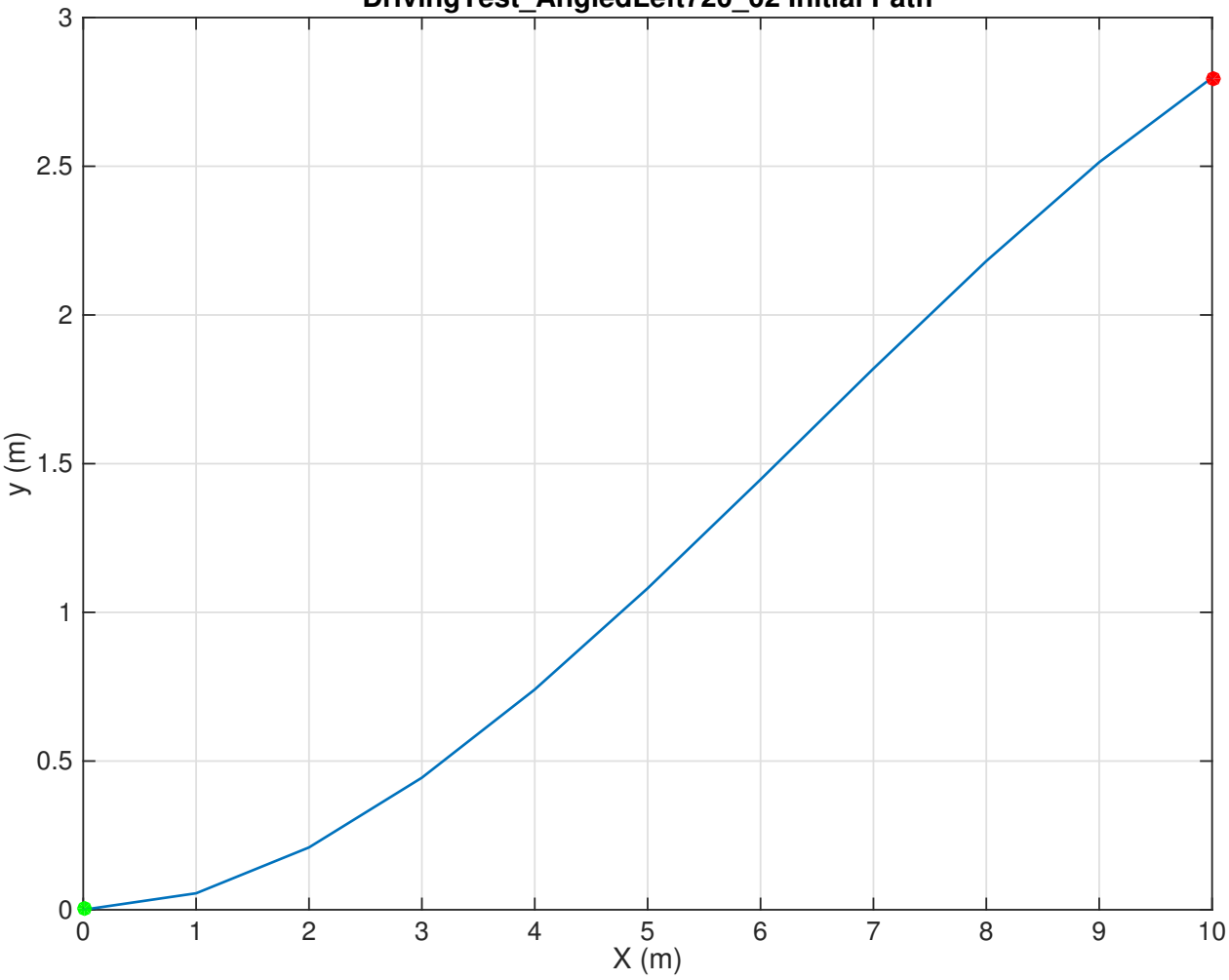


DrivingTest\_AngledLeft720\_01 Camera Position

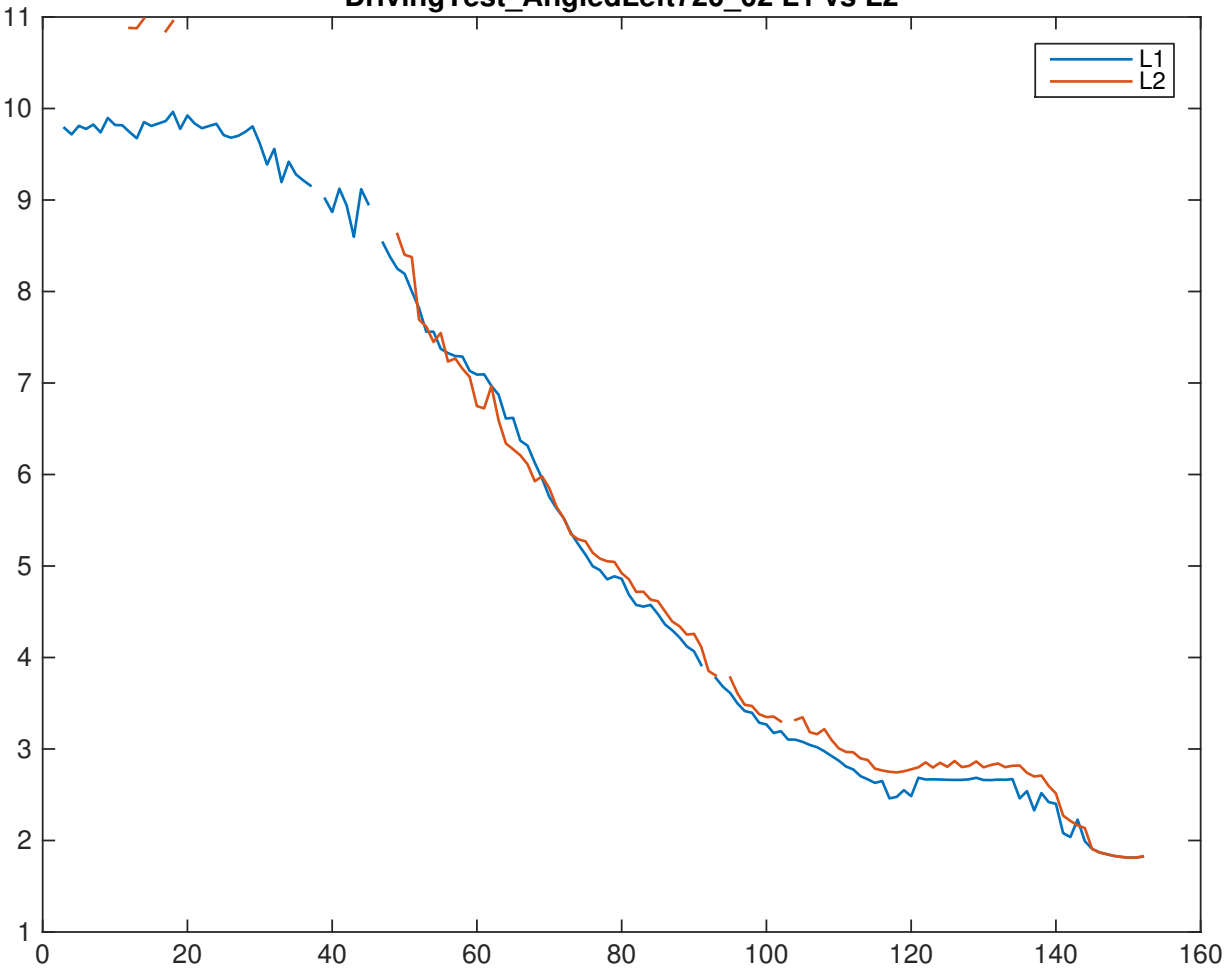




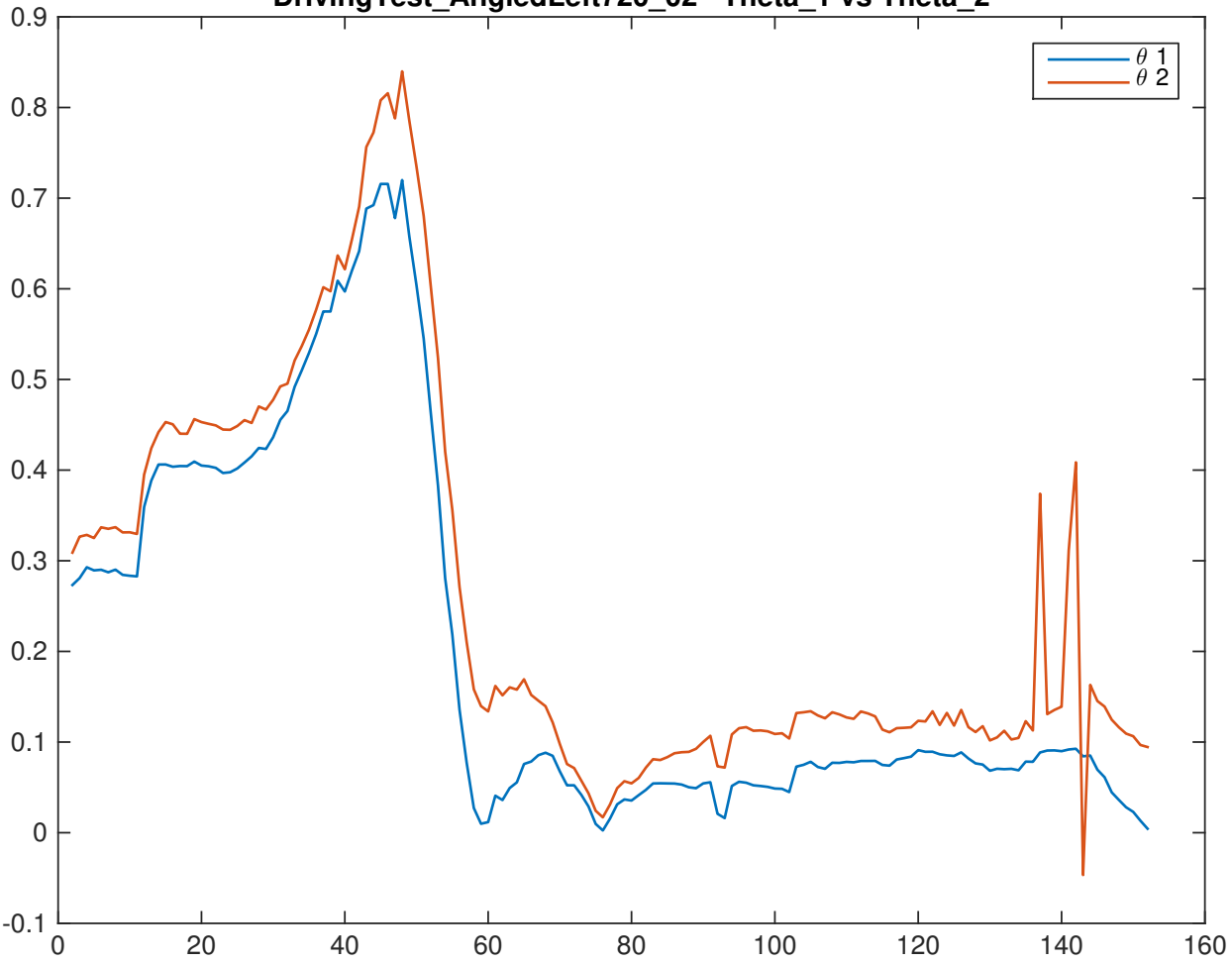
DrivingTest\_AngledLeft720\_02 Initial Path



DrivingTest\_AngledLeft720\_02 L1 vs L2

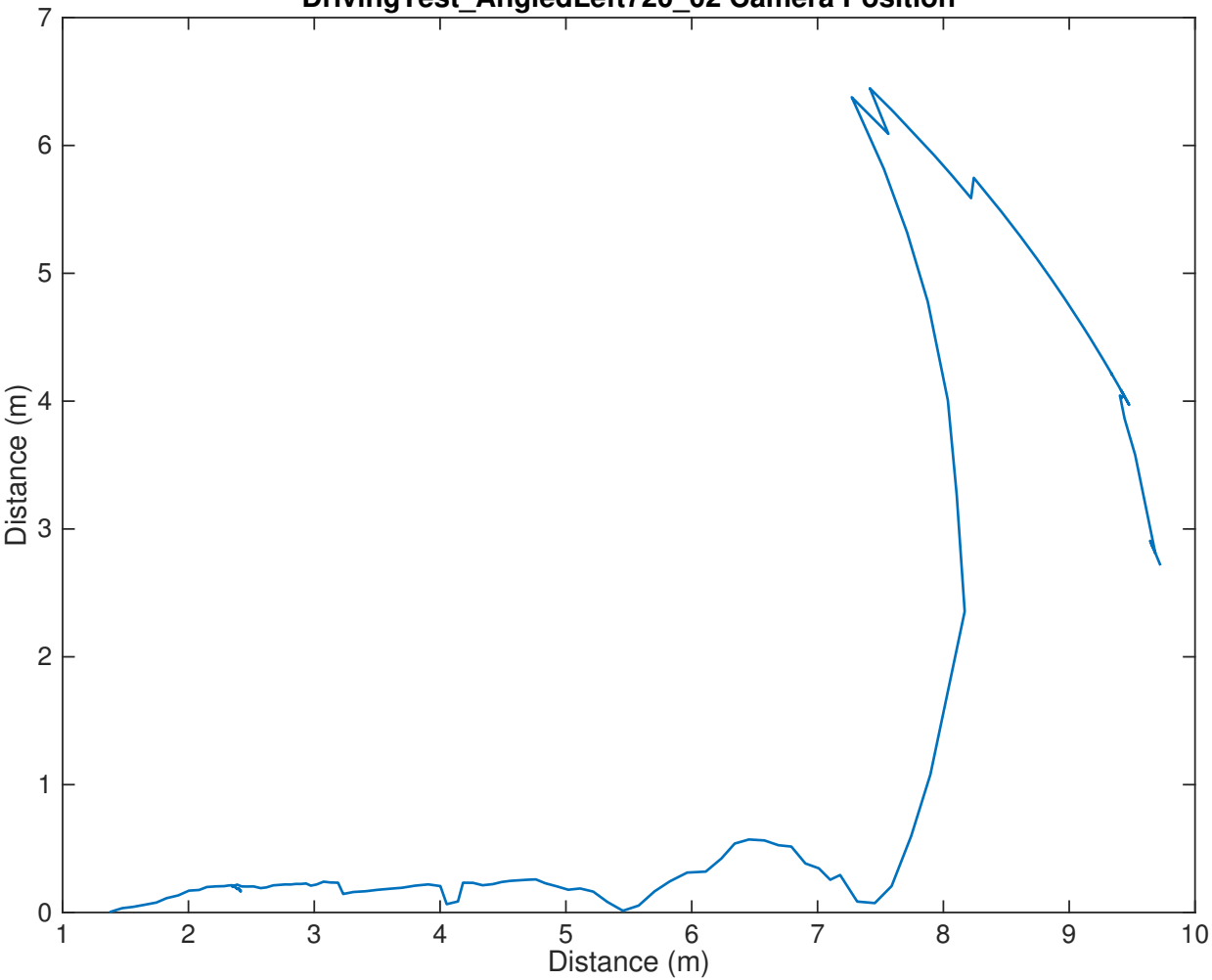


DrivingTest\_AngledLeft720\_02 Theta\_1 vs Theta\_2

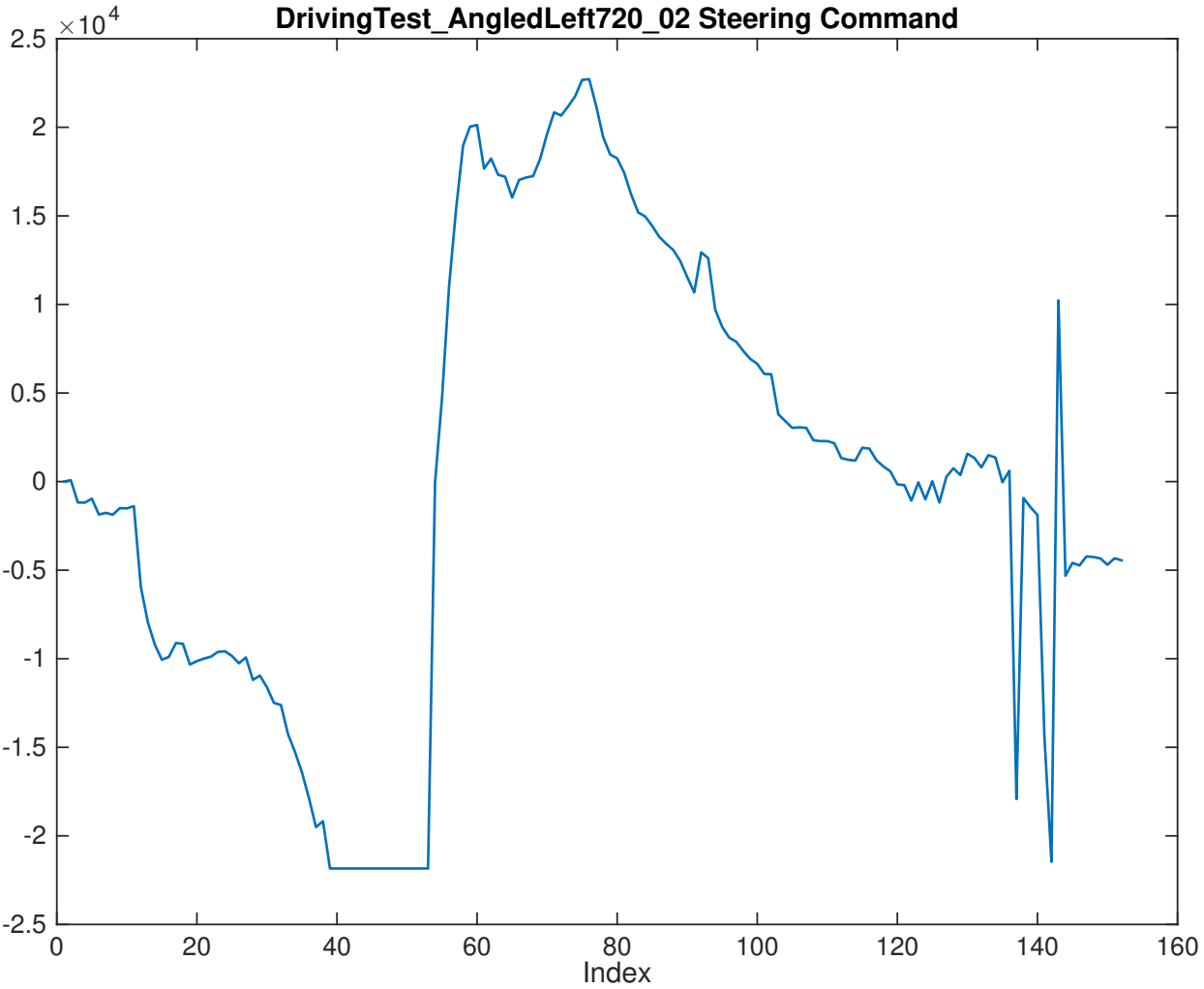




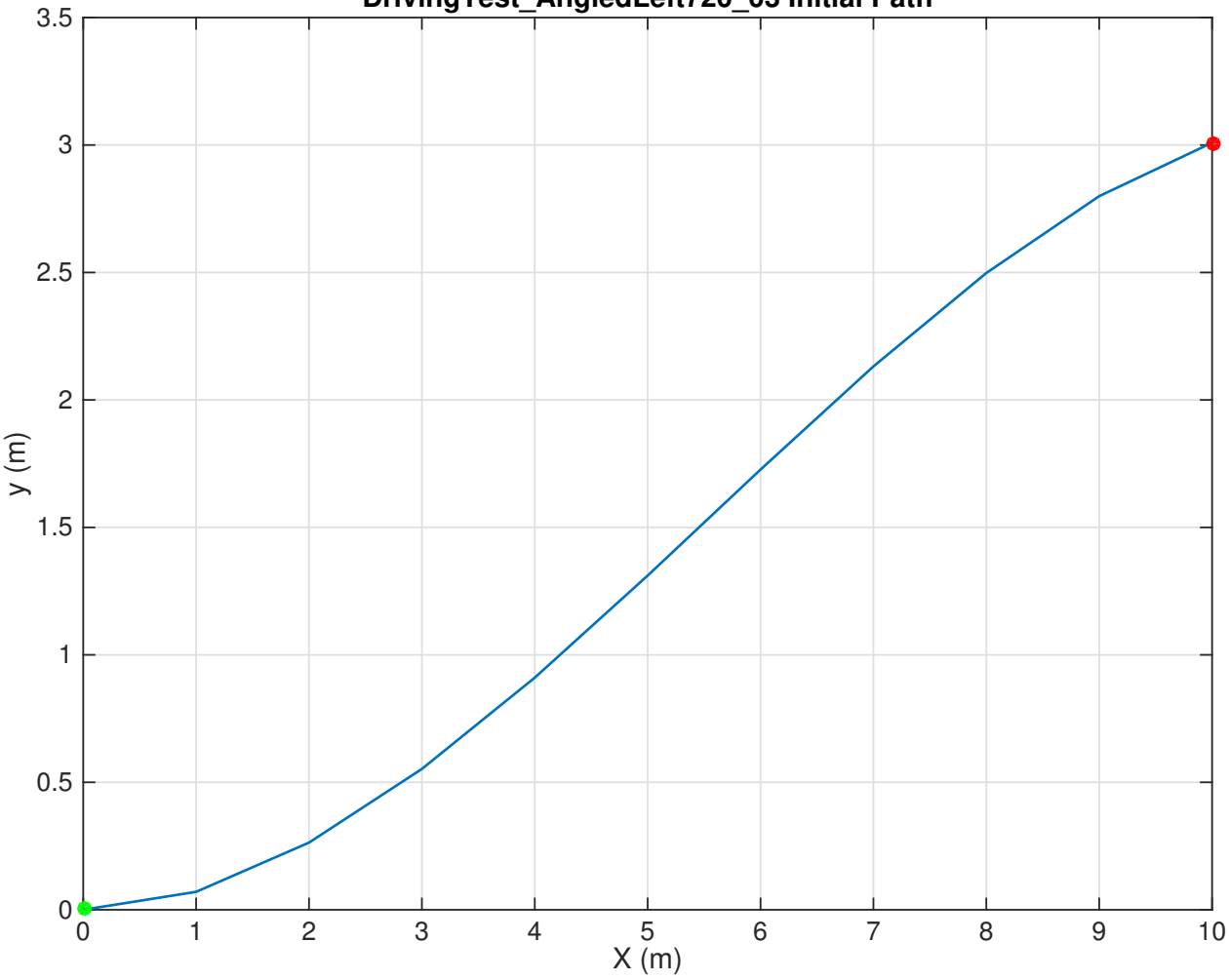
DrivingTest\_AngledLeft720\_02 Camera Position



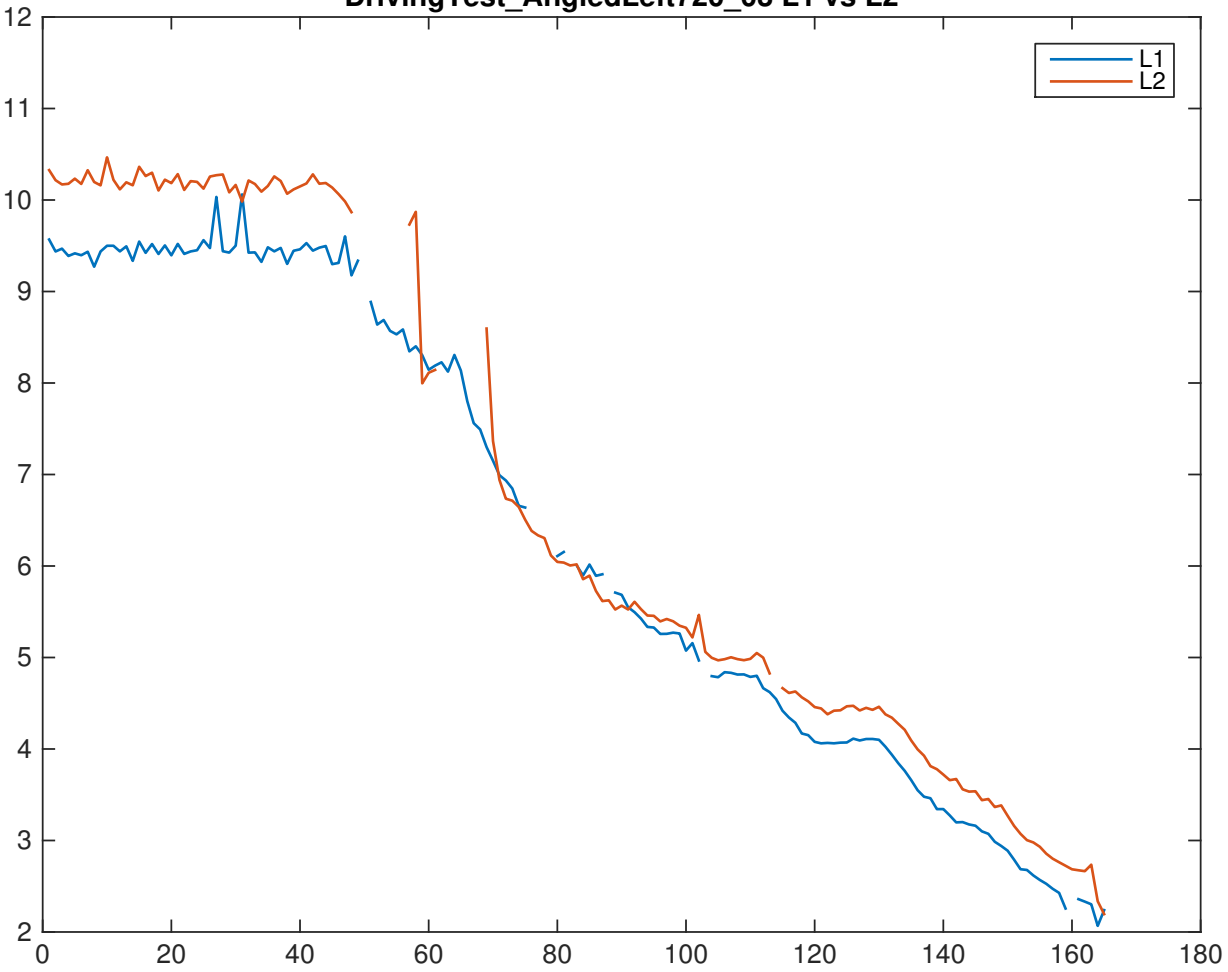
DrivingTest\_AngledLeft720\_02 Steering Command



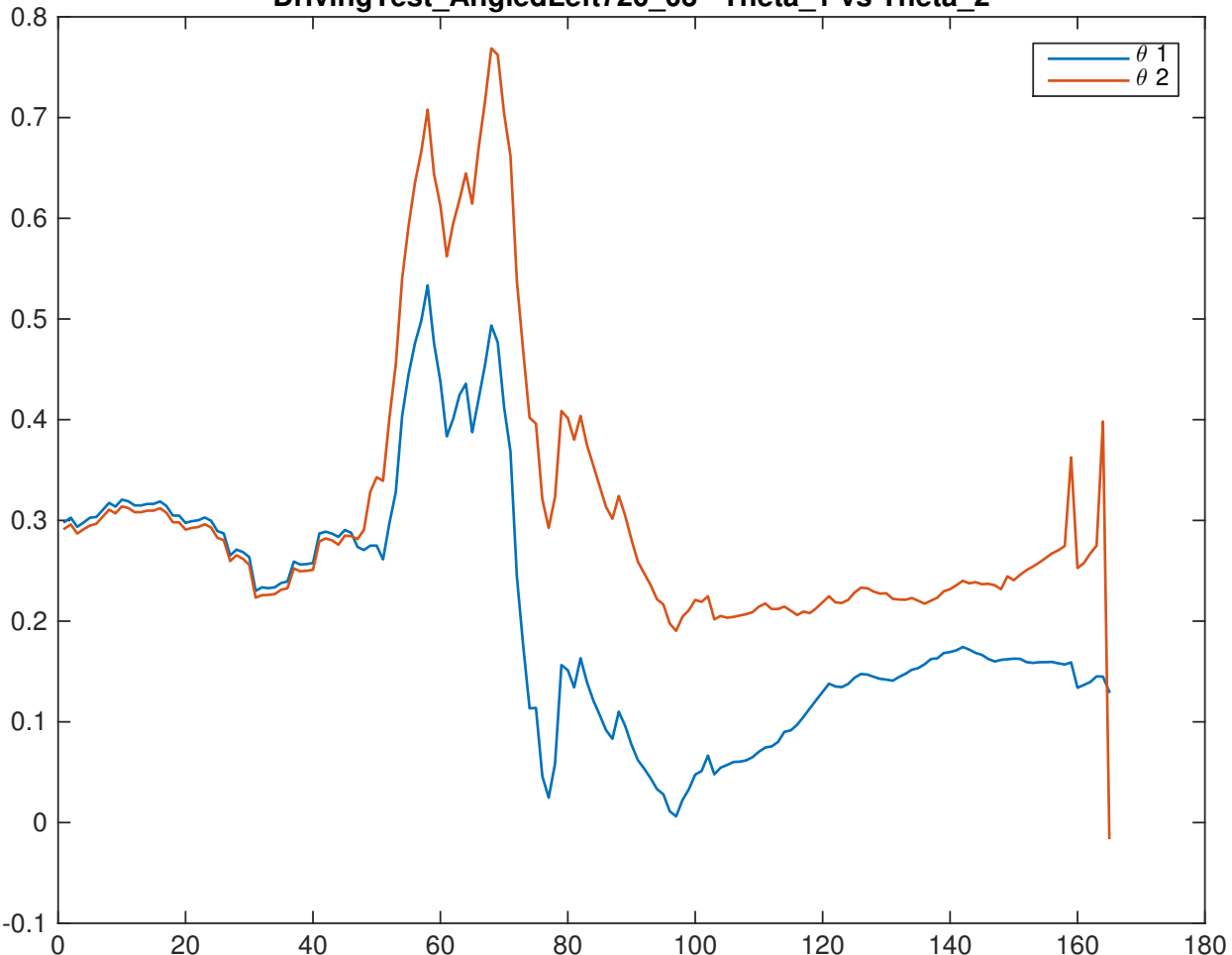
DrivingTest\_AngledLeft720\_03 Initial Path



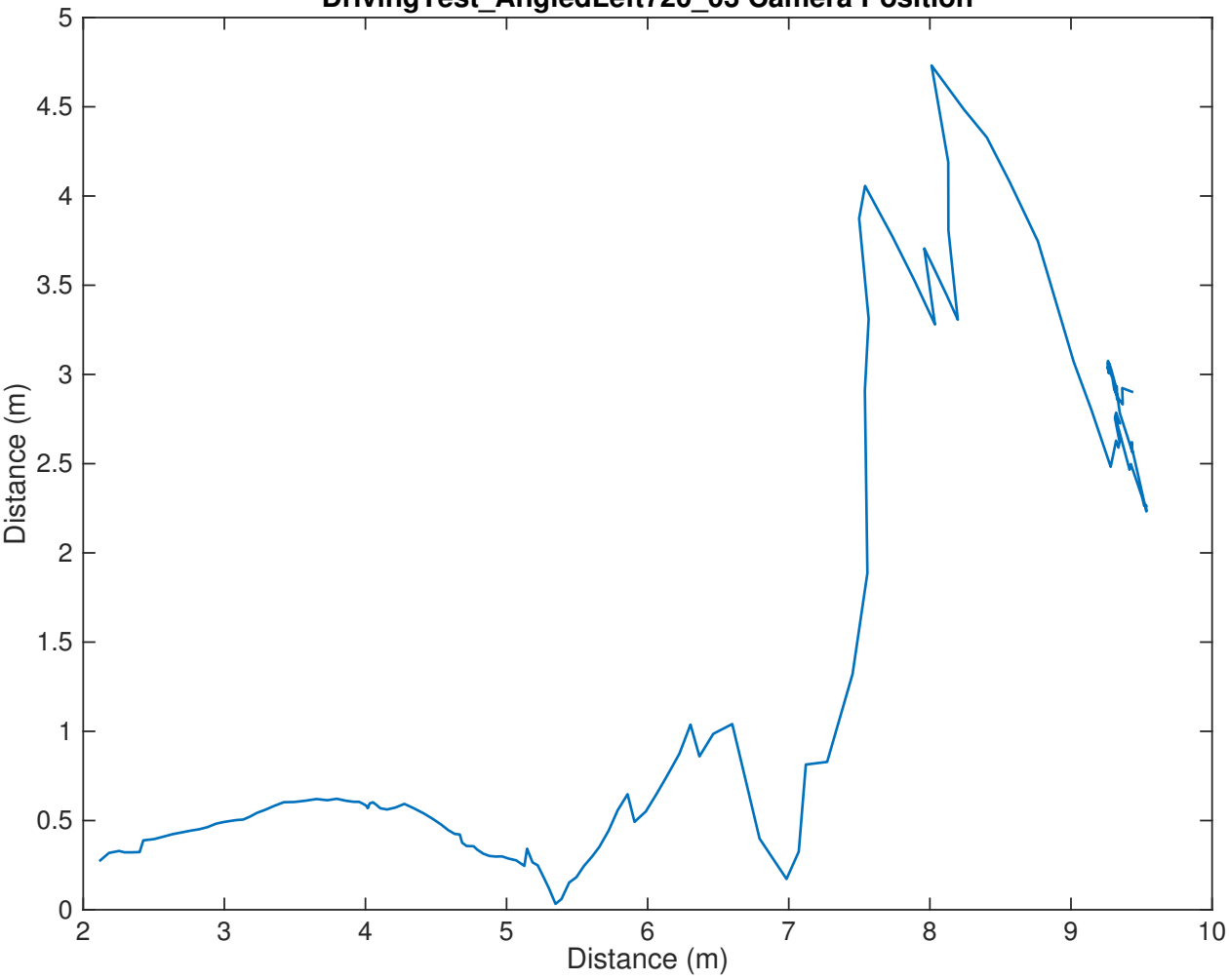
DrivingTest\_AngledLeft720\_03 L1 vs L2



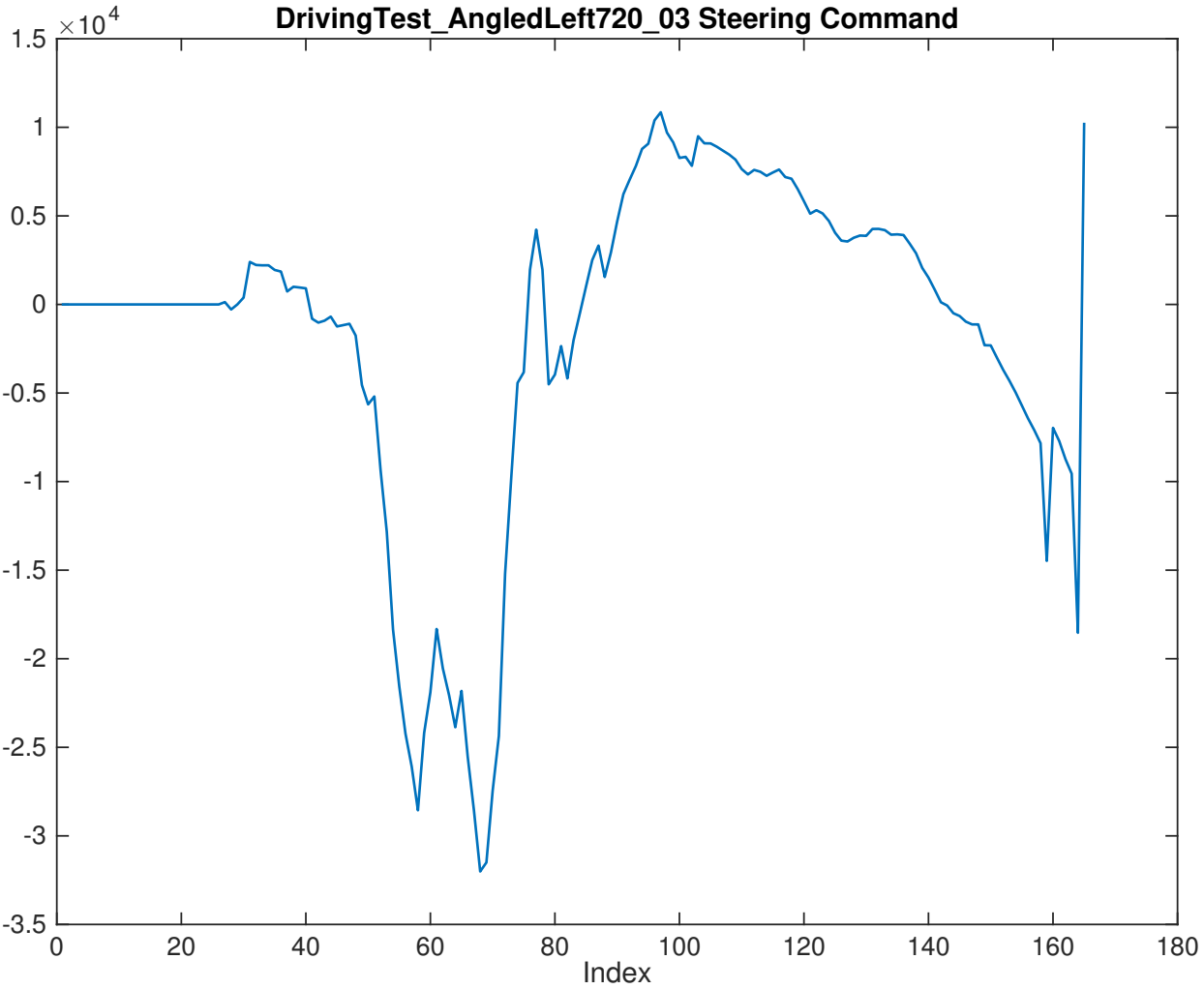
DrivingTest\_AngledLeft720\_03 Theta\_1 vs Theta\_2



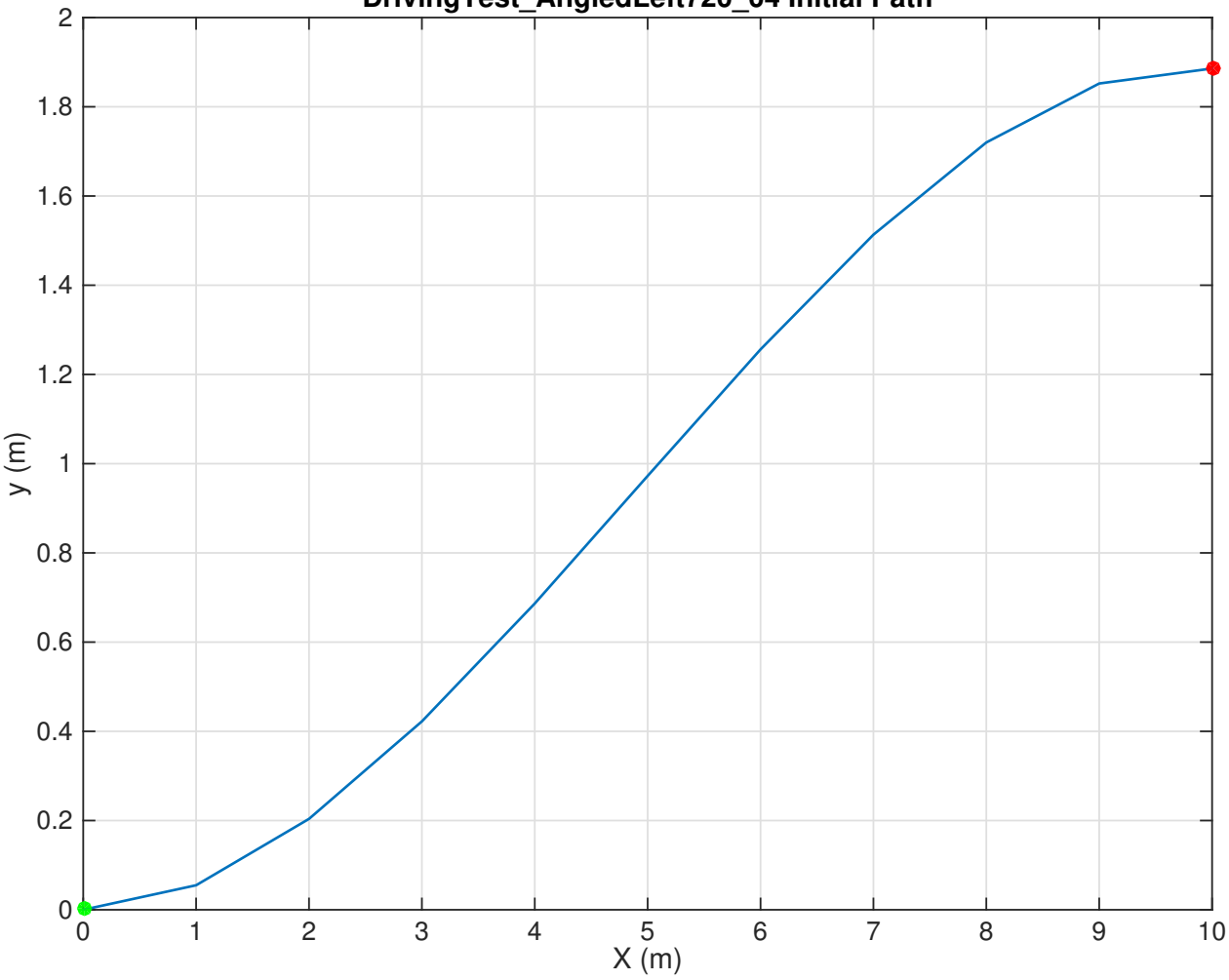
DrivingTest\_AngledLeft720\_03 Camera Position



DrivingTest\_AngledLeft720\_03 Steering Command

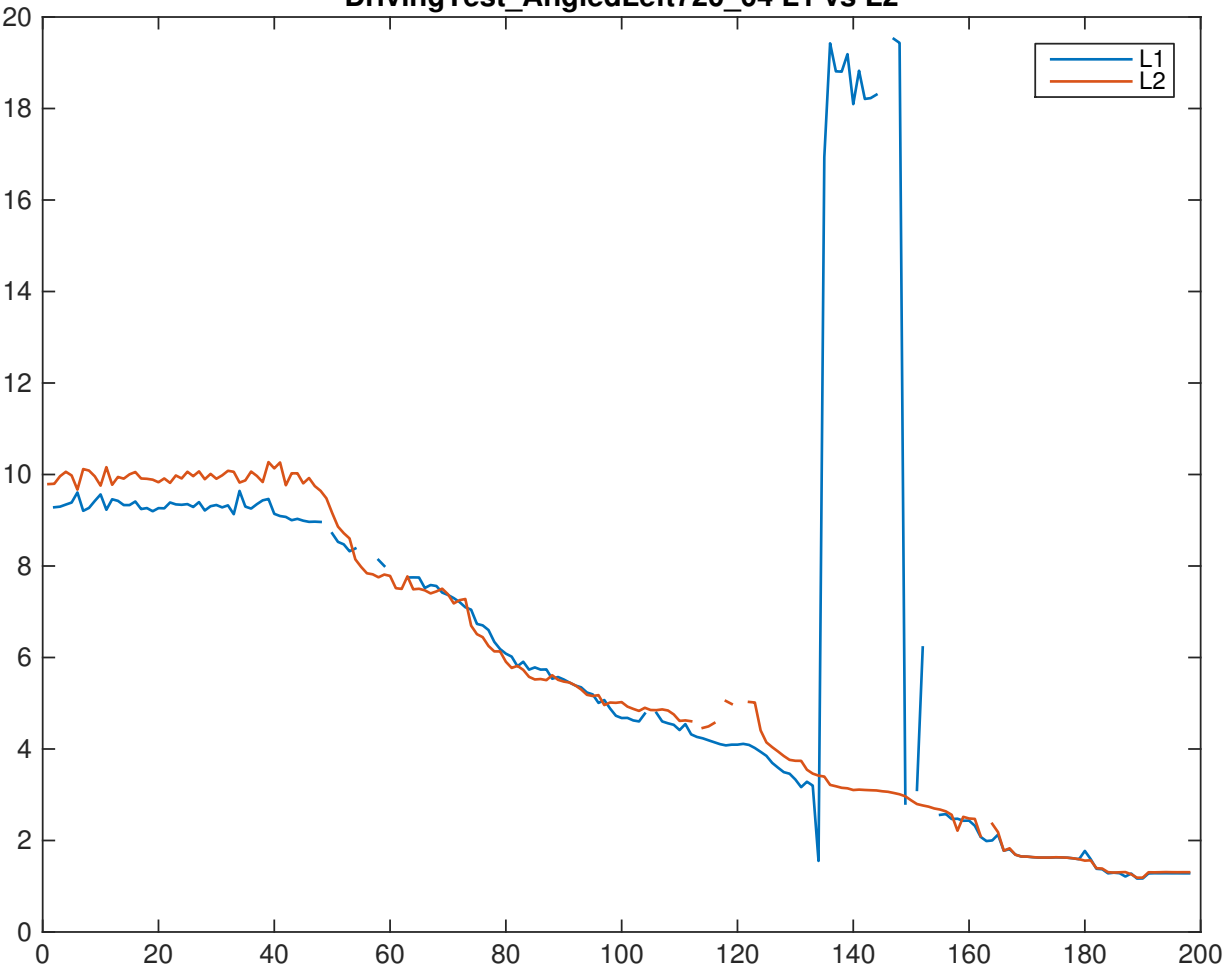


DrivingTest\_AngledLeft720\_04 Initial Path

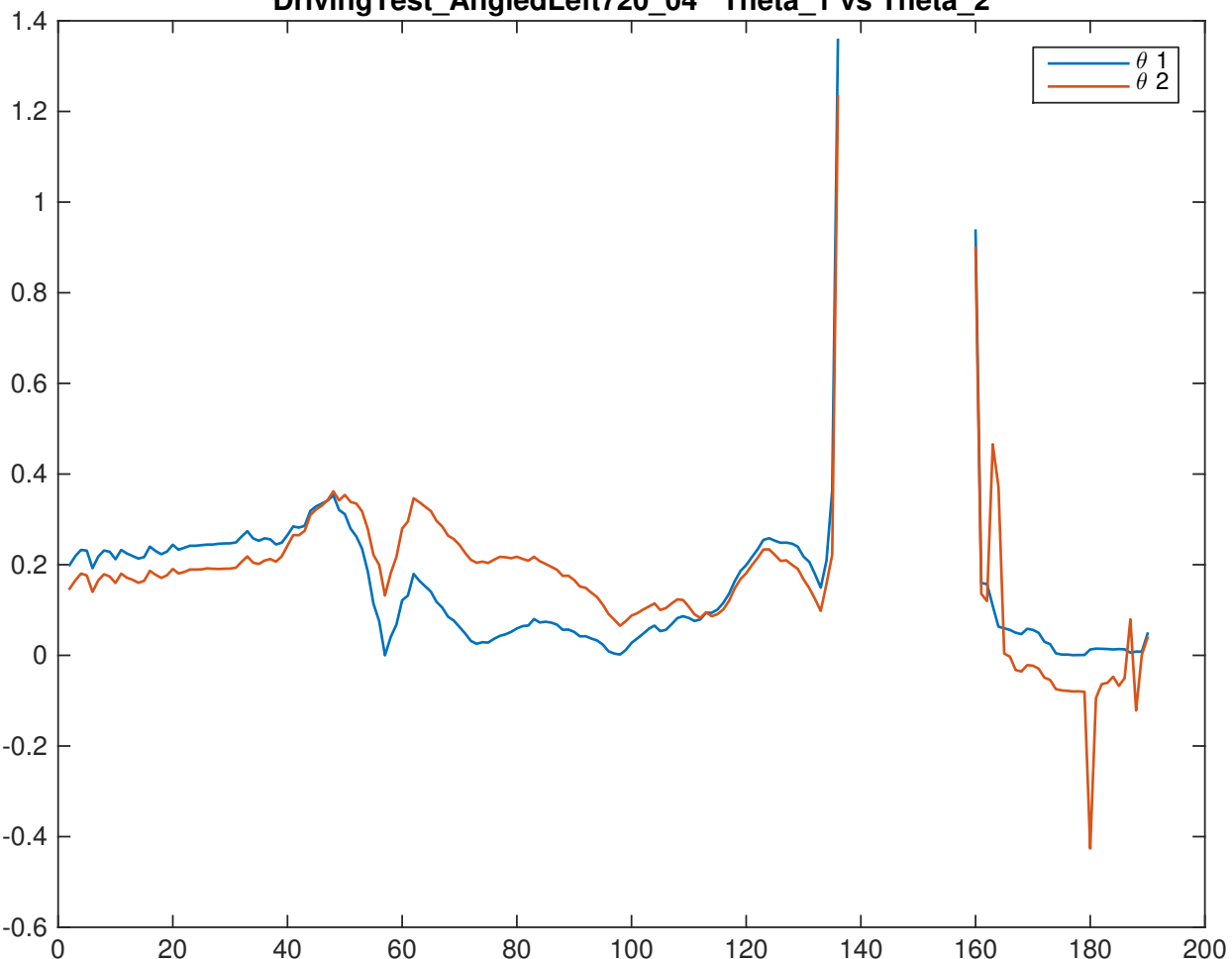




DrivingTest\_AngledLeft720\_04 L1 vs L2



DrivingTest\_AngledLeft720\_04 Theta\_1 vs Theta\_2



DrivingTest\_AngledLeft720\_04 Camera Position

