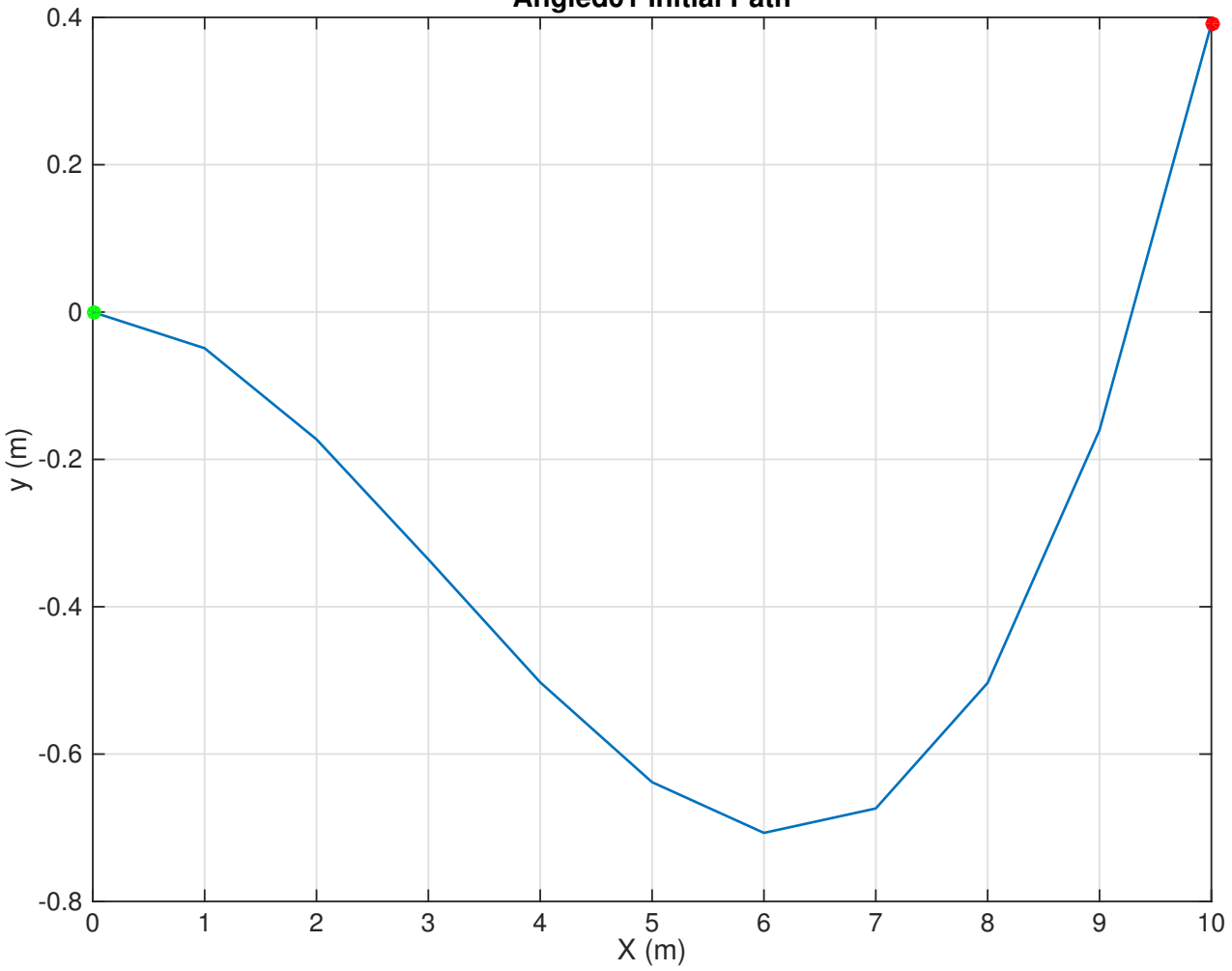
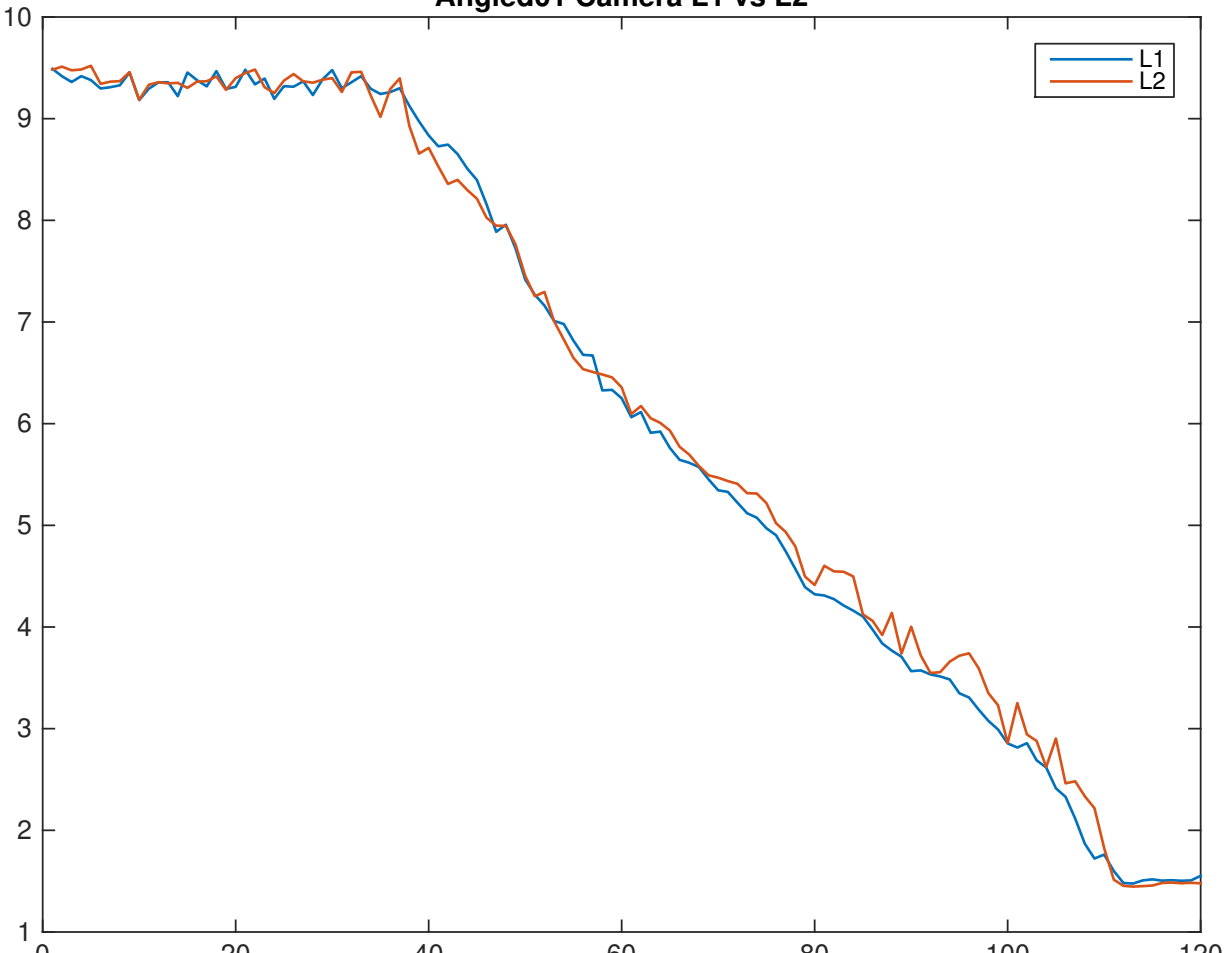


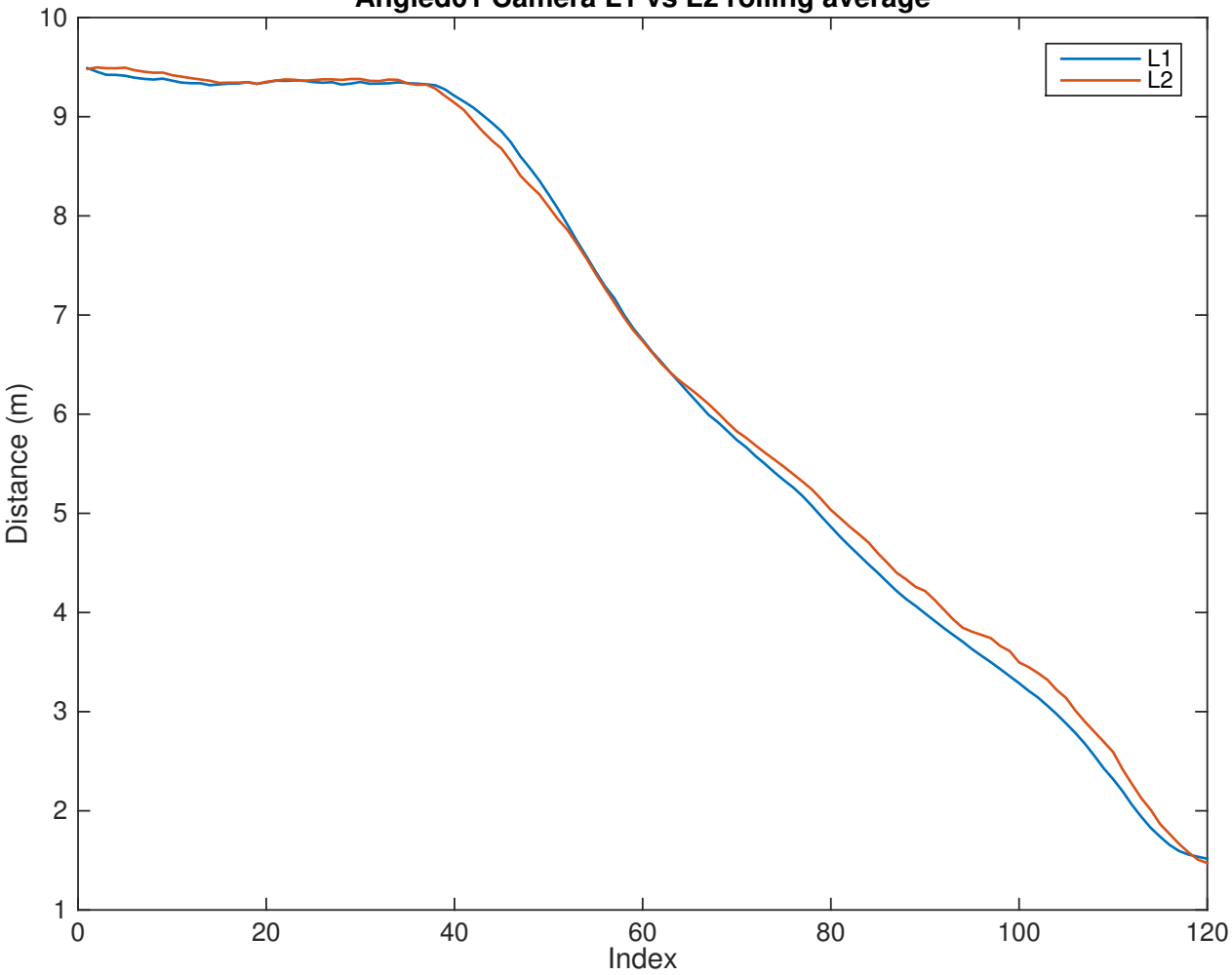
Angled01 Initial Path



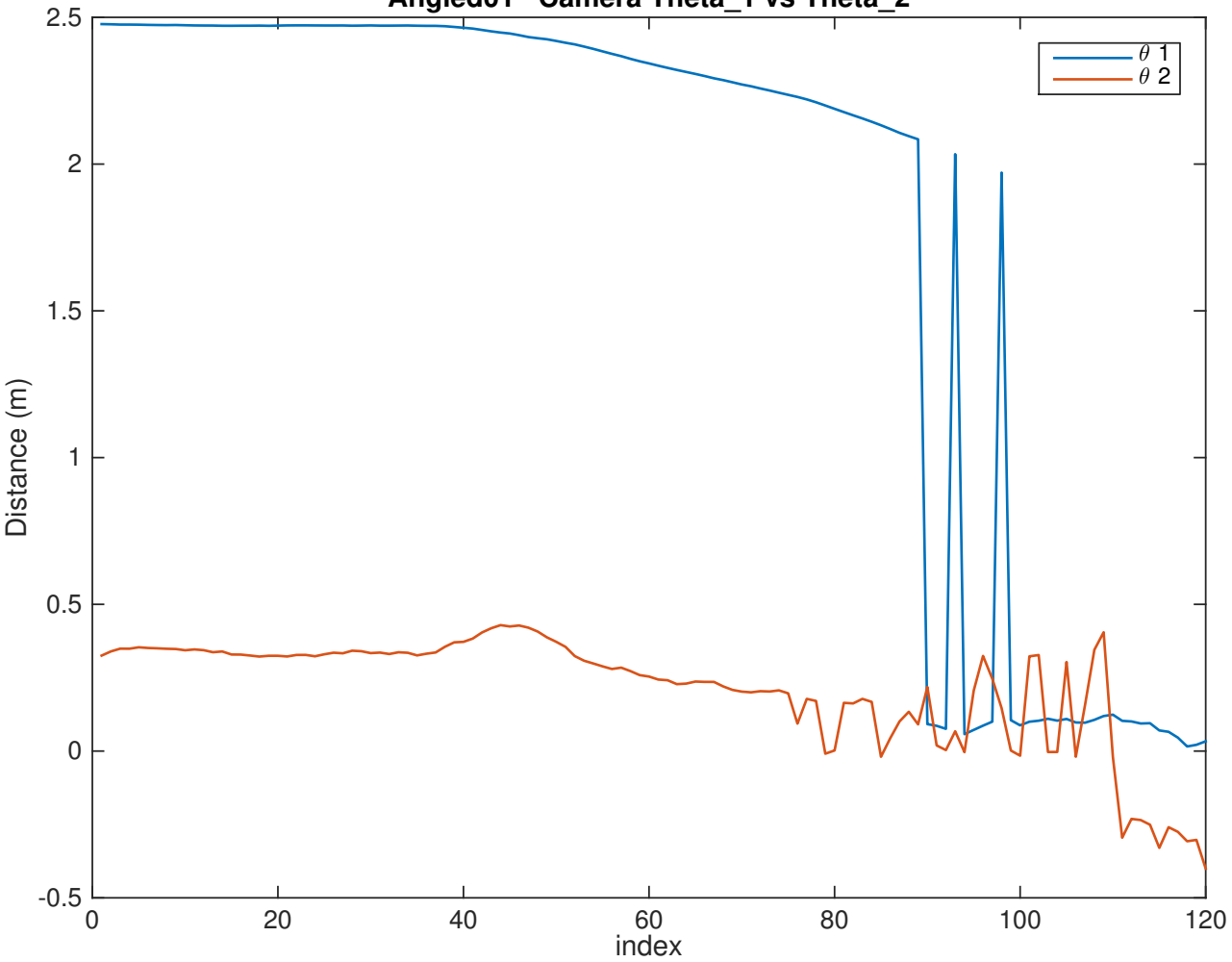
Angled01 Camera L1 vs L2



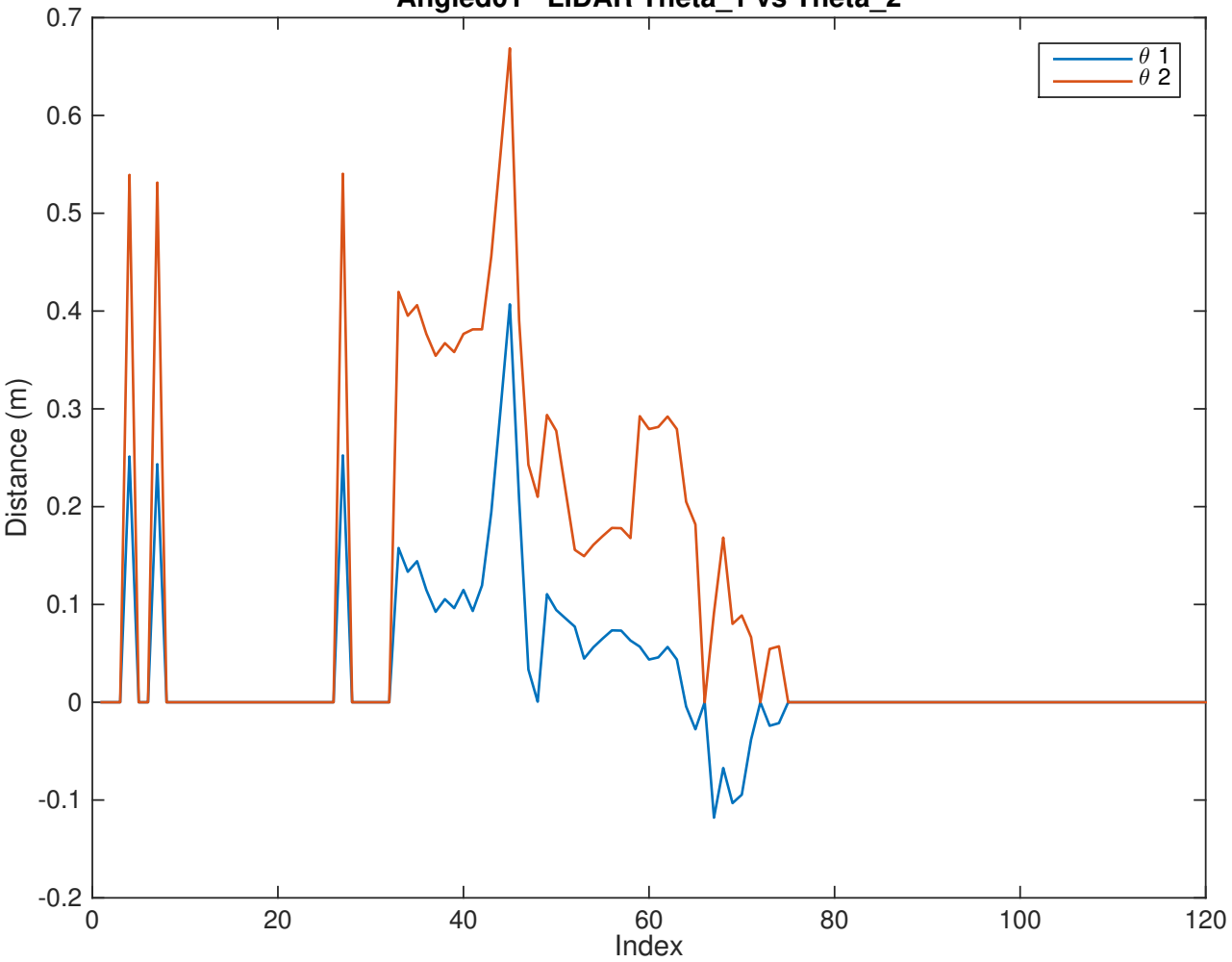
Angled01 Camera L1 vs L2 rolling average



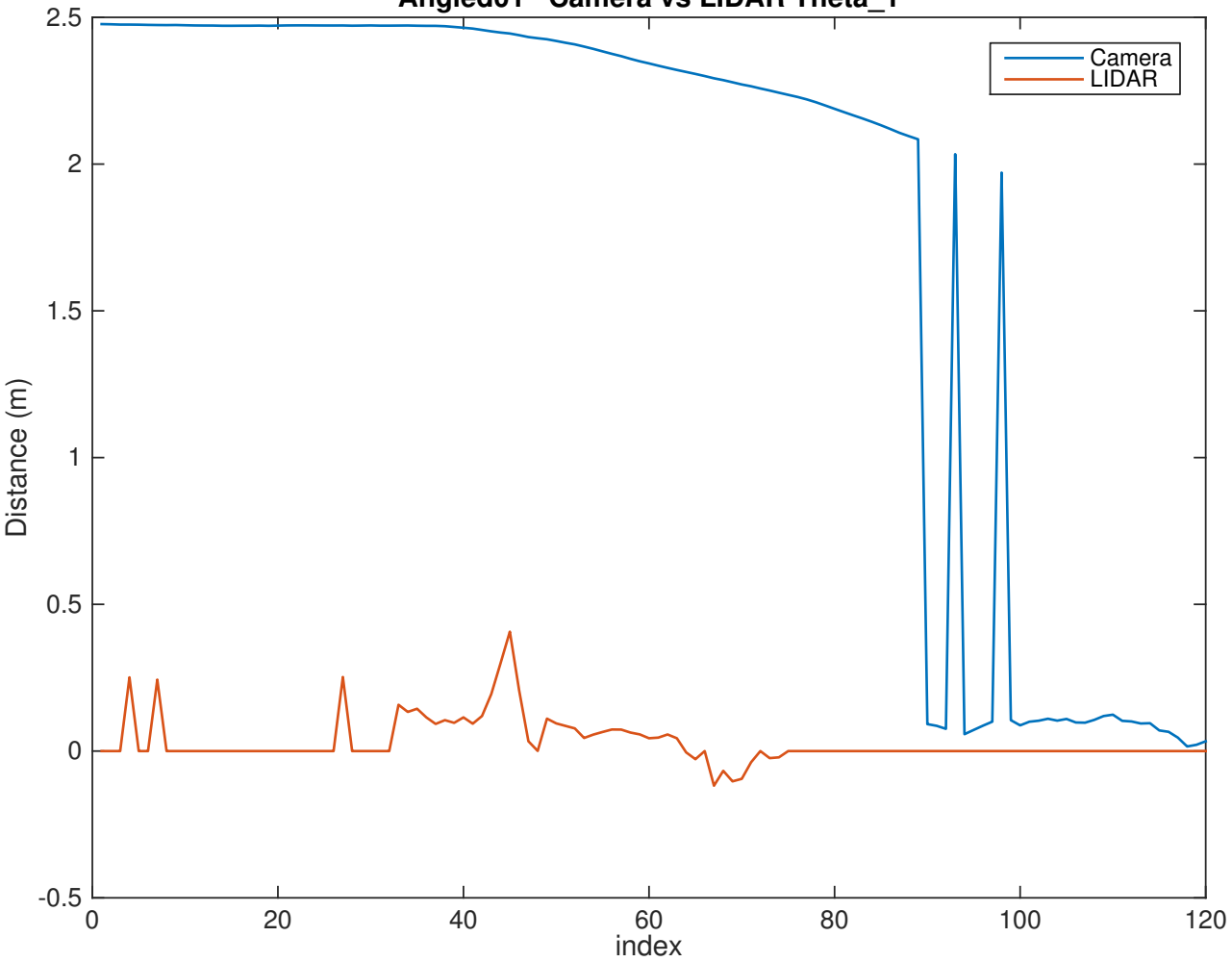
Angled01 Camera Theta_1 vs Theta_2



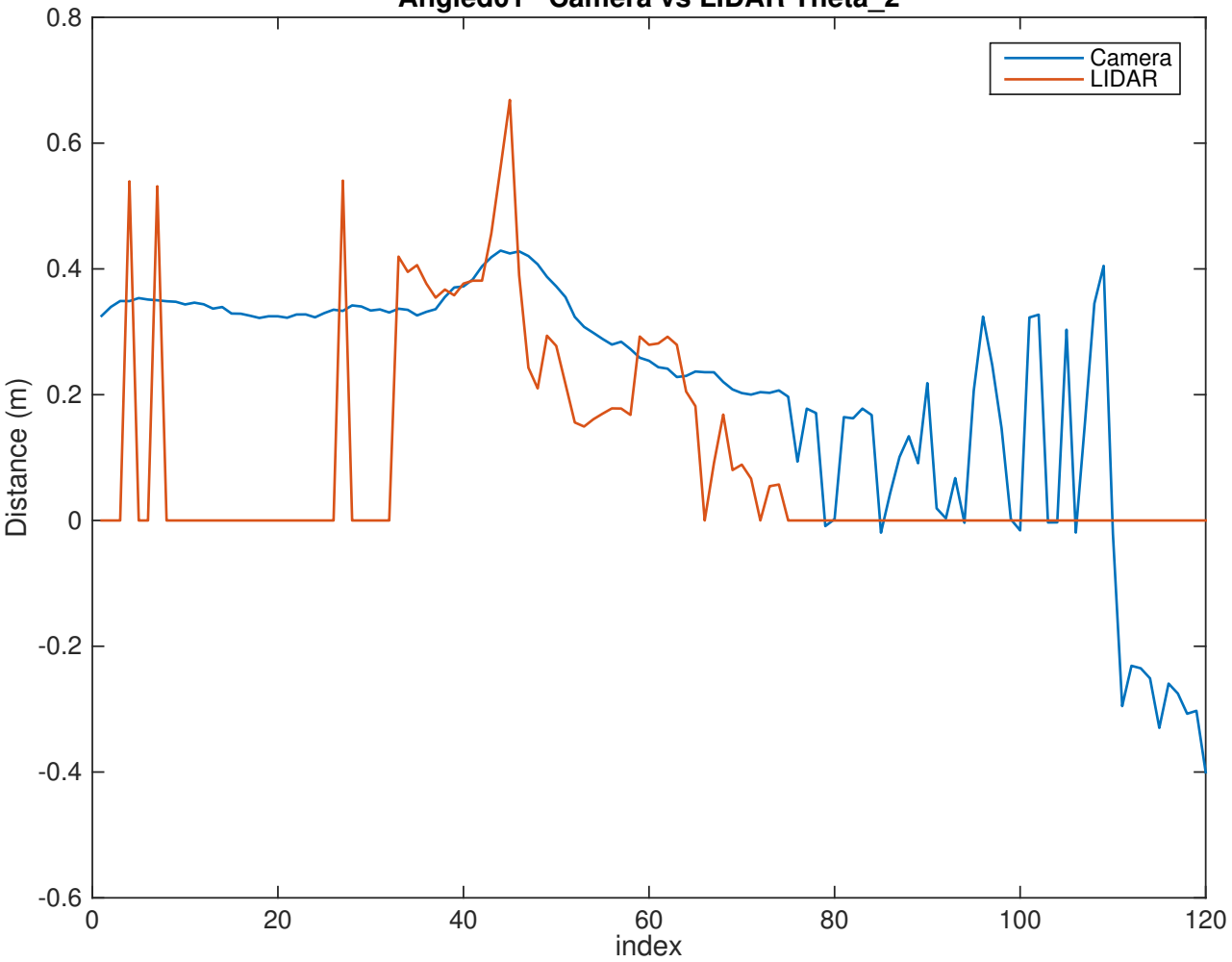
Angled01 LIDAR Theta_1 vs Theta_2



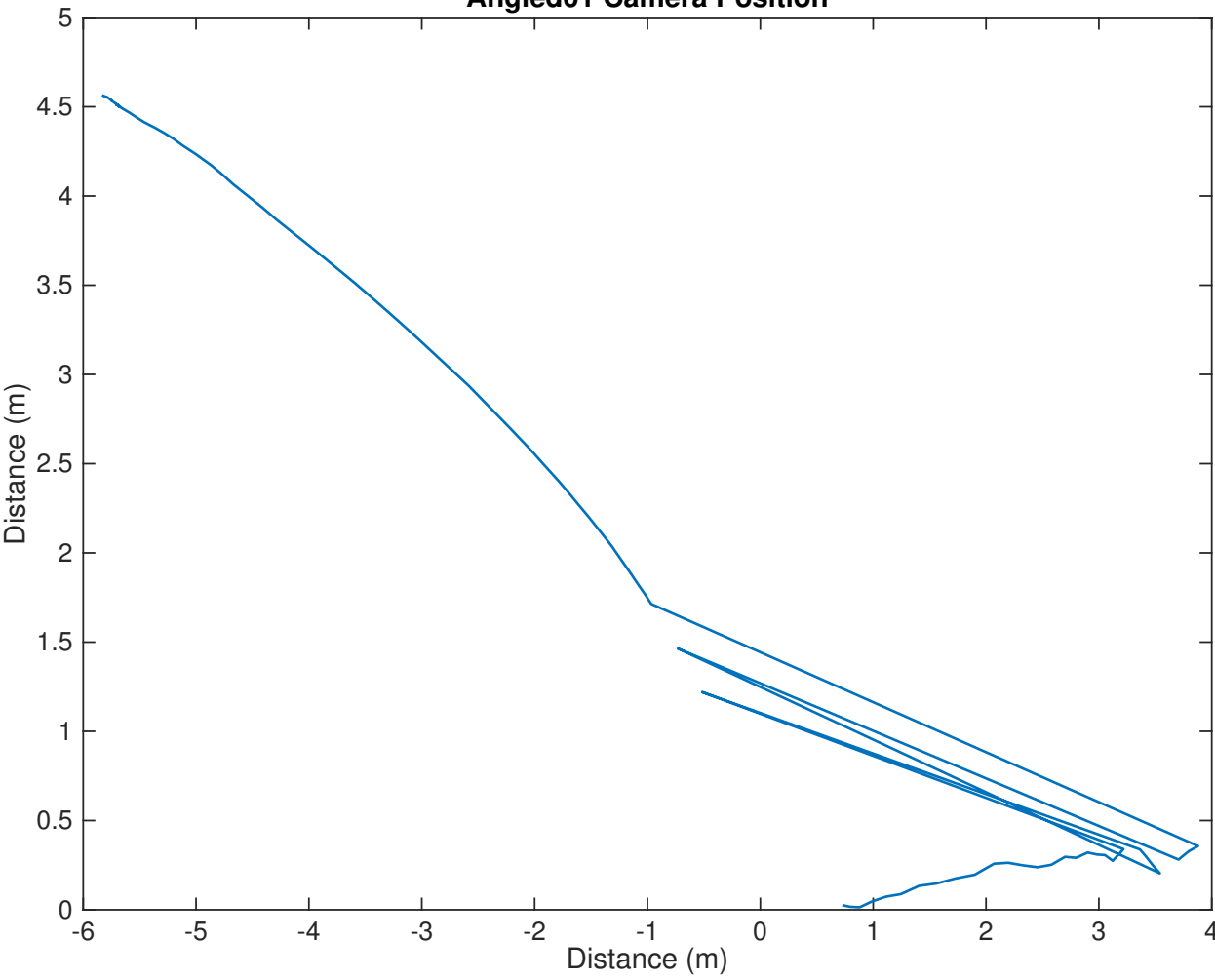
Angled01 Camera vs LIDAR Theta_1



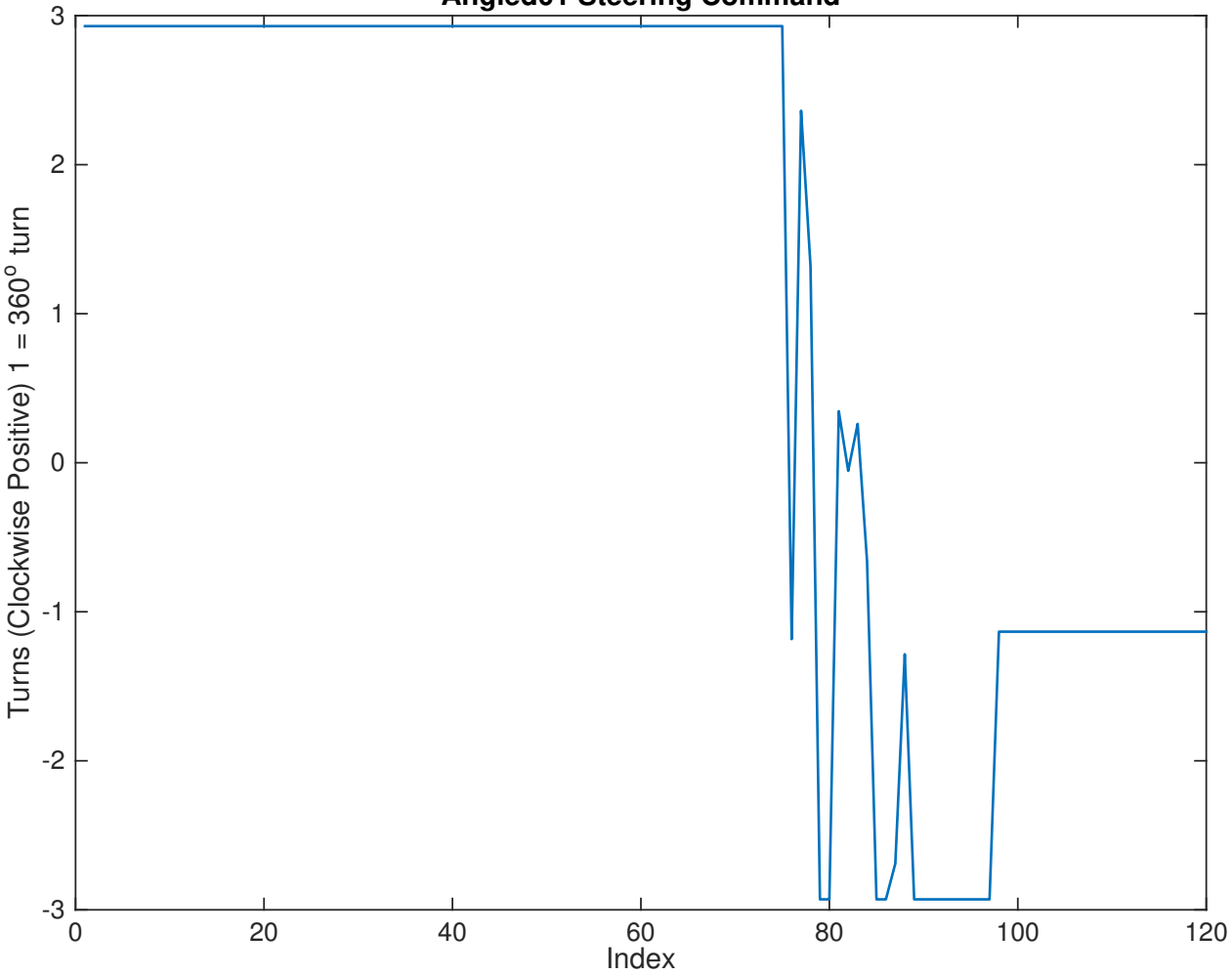
Angled01 Camera vs LIDAR Theta_2



Angled01 Camera Position



Angled01 Steering Command



Angled01 Calculated vs. Actual Steering

