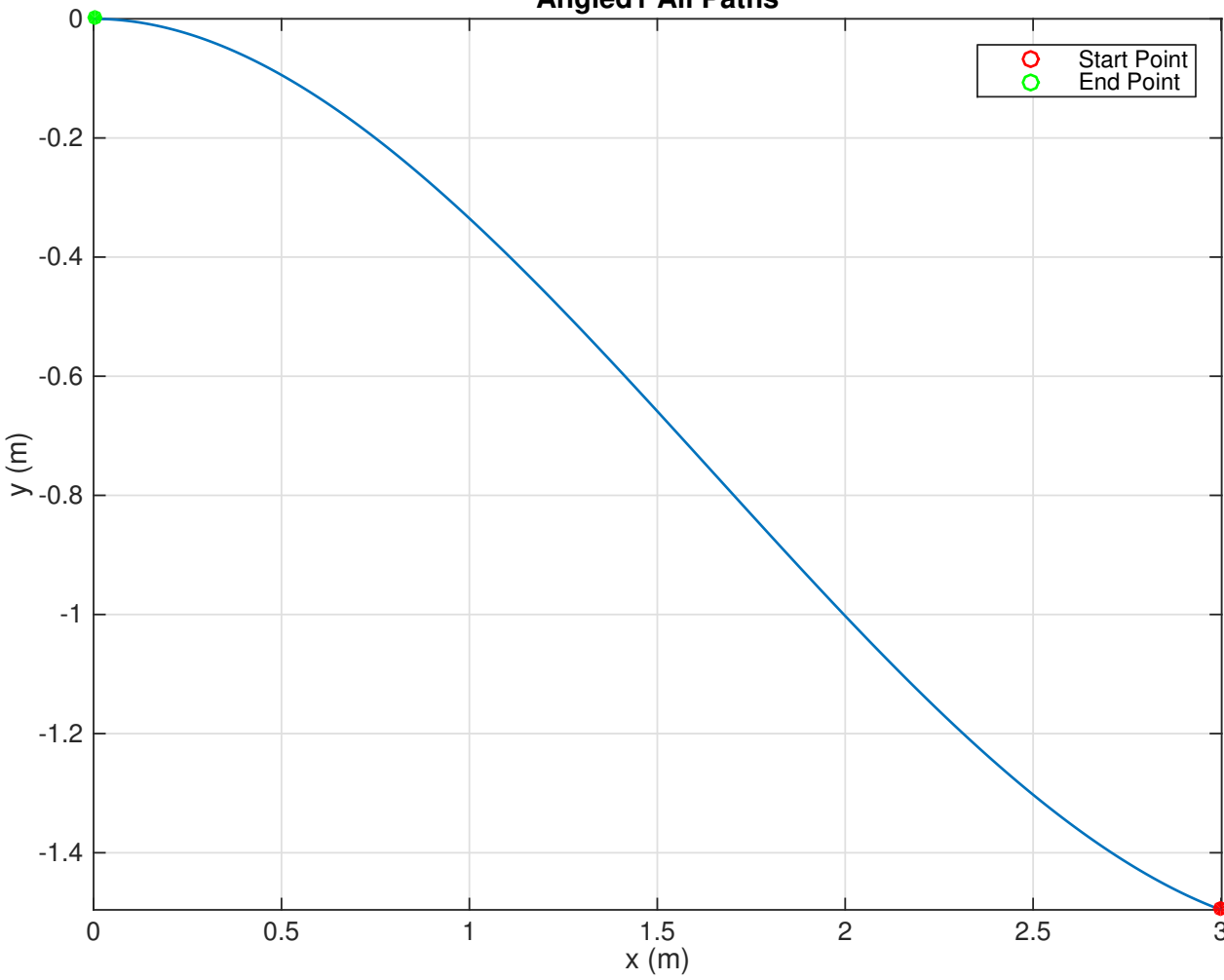


Angled1 All Paths



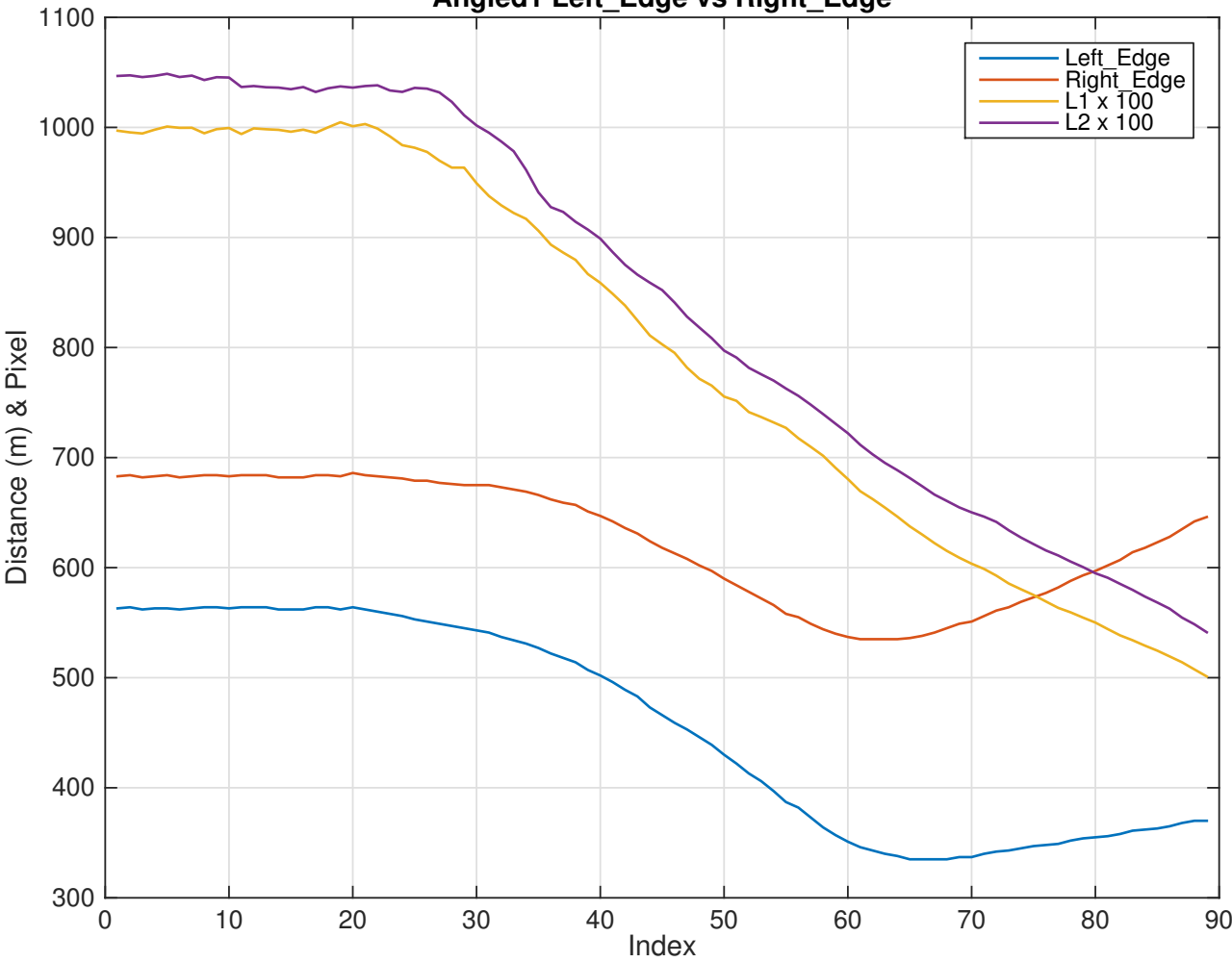
Number\_Of\_Unique\_Paths

King\_Pin\_Detected

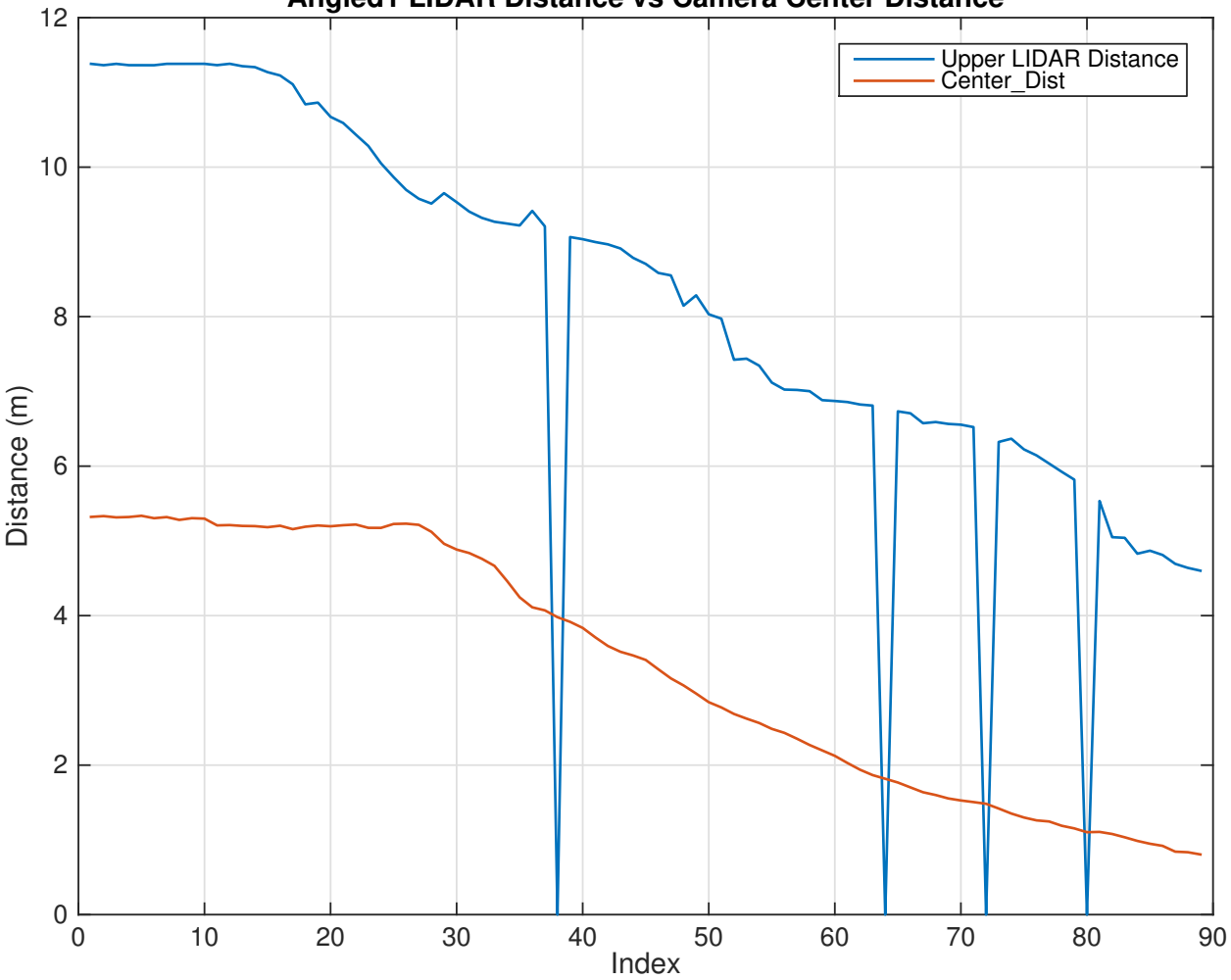
1

false

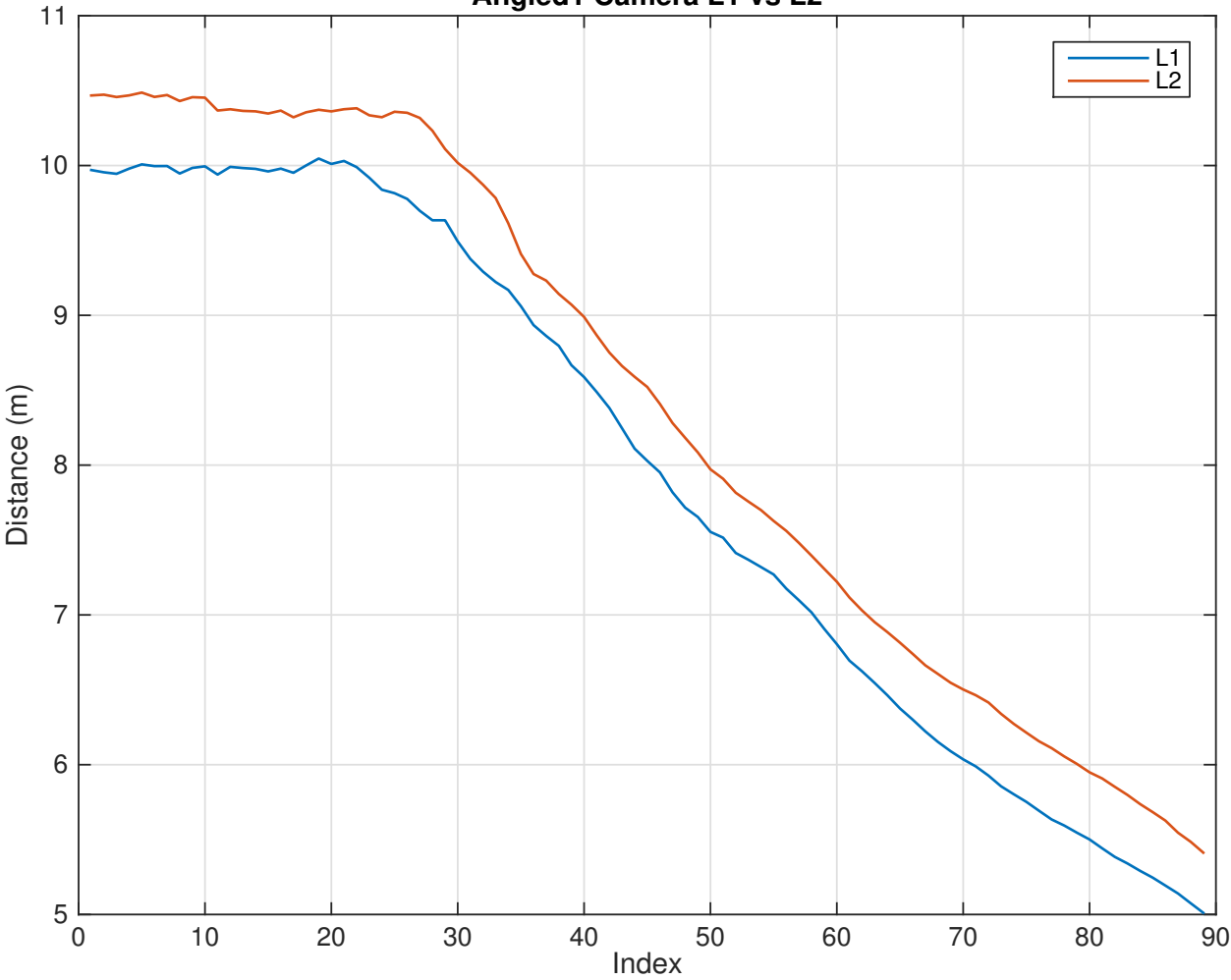
Angled1 Left\_Edge vs Right\_Edge



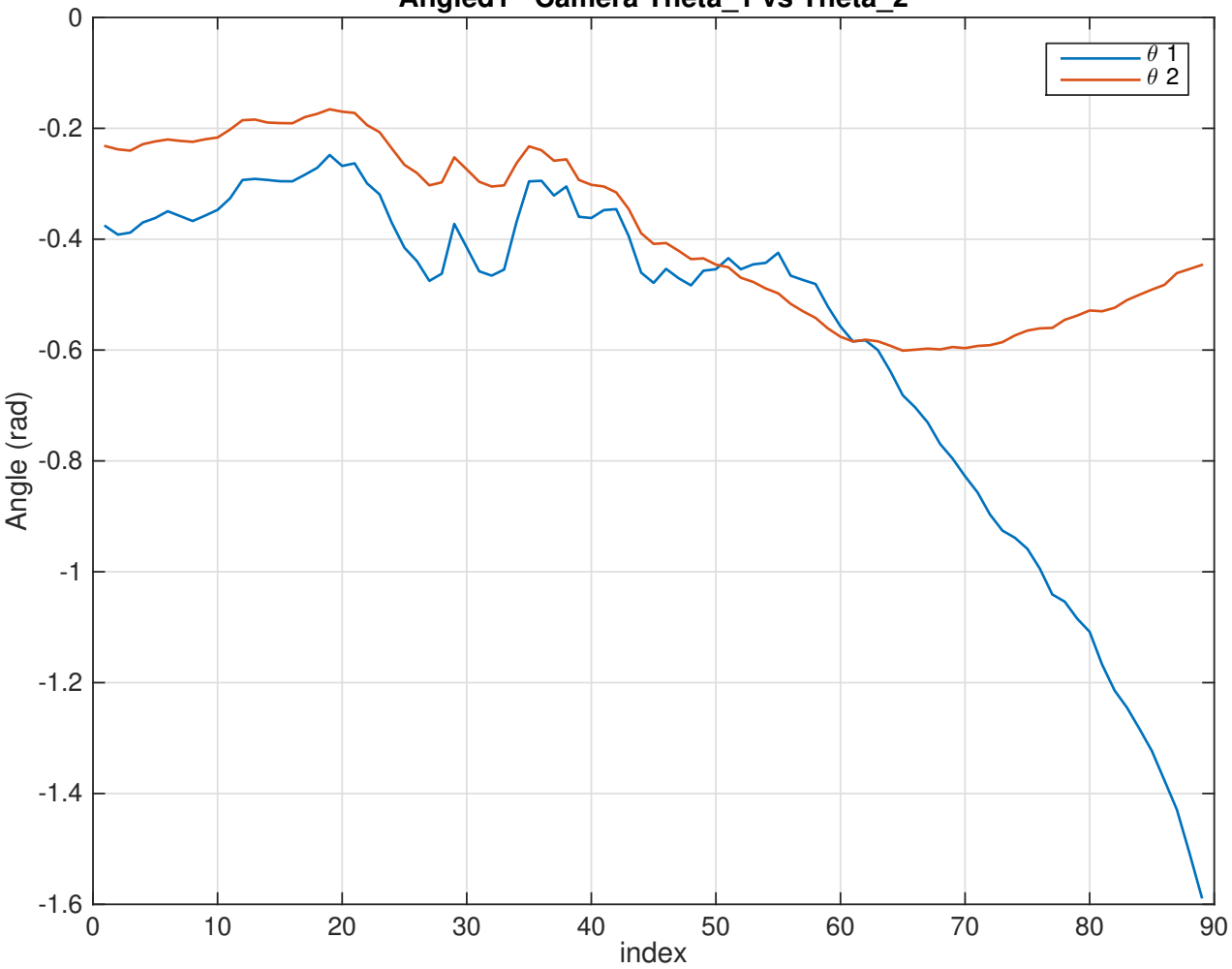
Angled1 LIDAR Distance vs Camera Center Distance



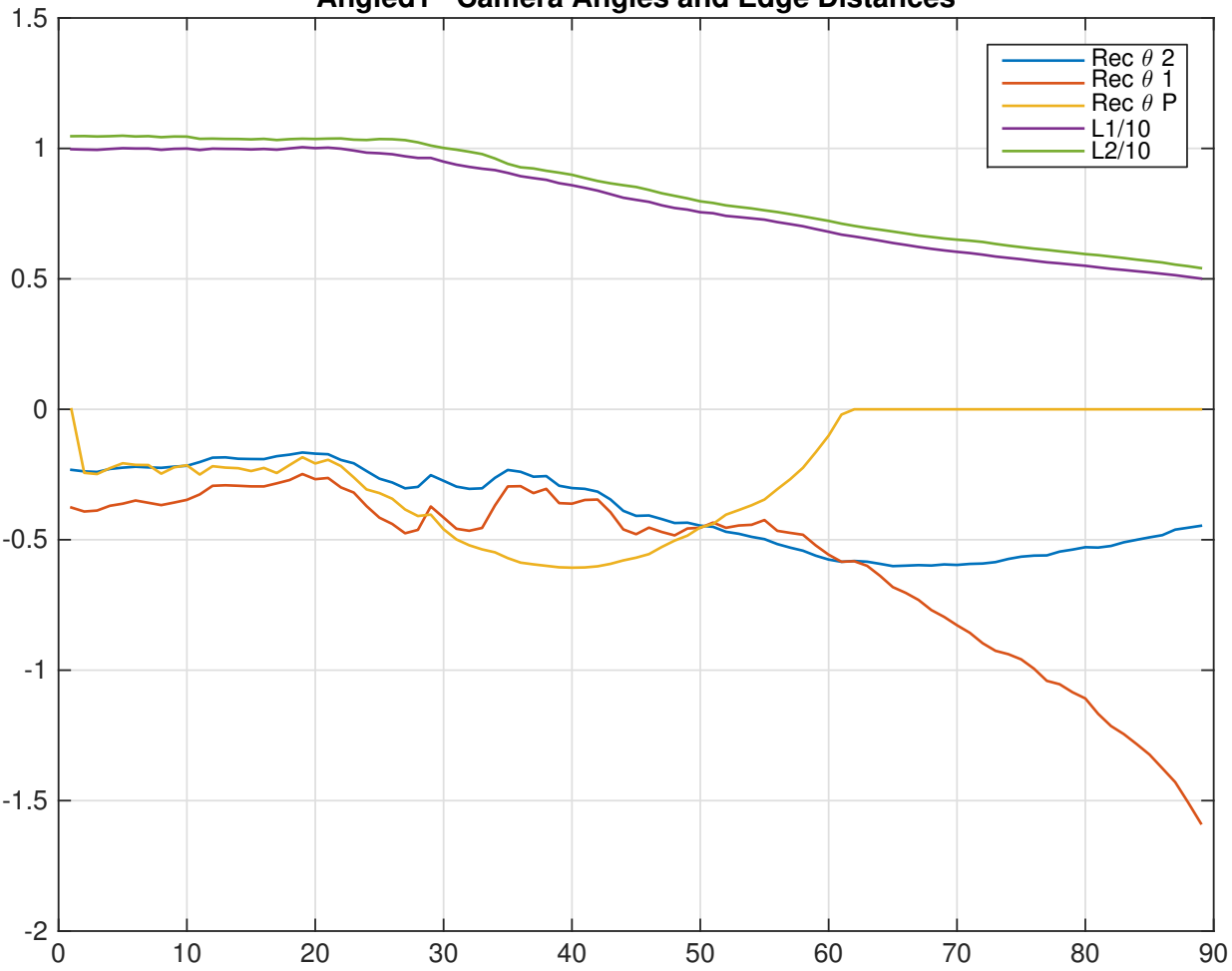
Angled1 Camera L1 vs L2



Angled1 Camera Theta\_1 vs Theta\_2



Angled1 Camera Angles and Edge Distances



Angled1 Steering

