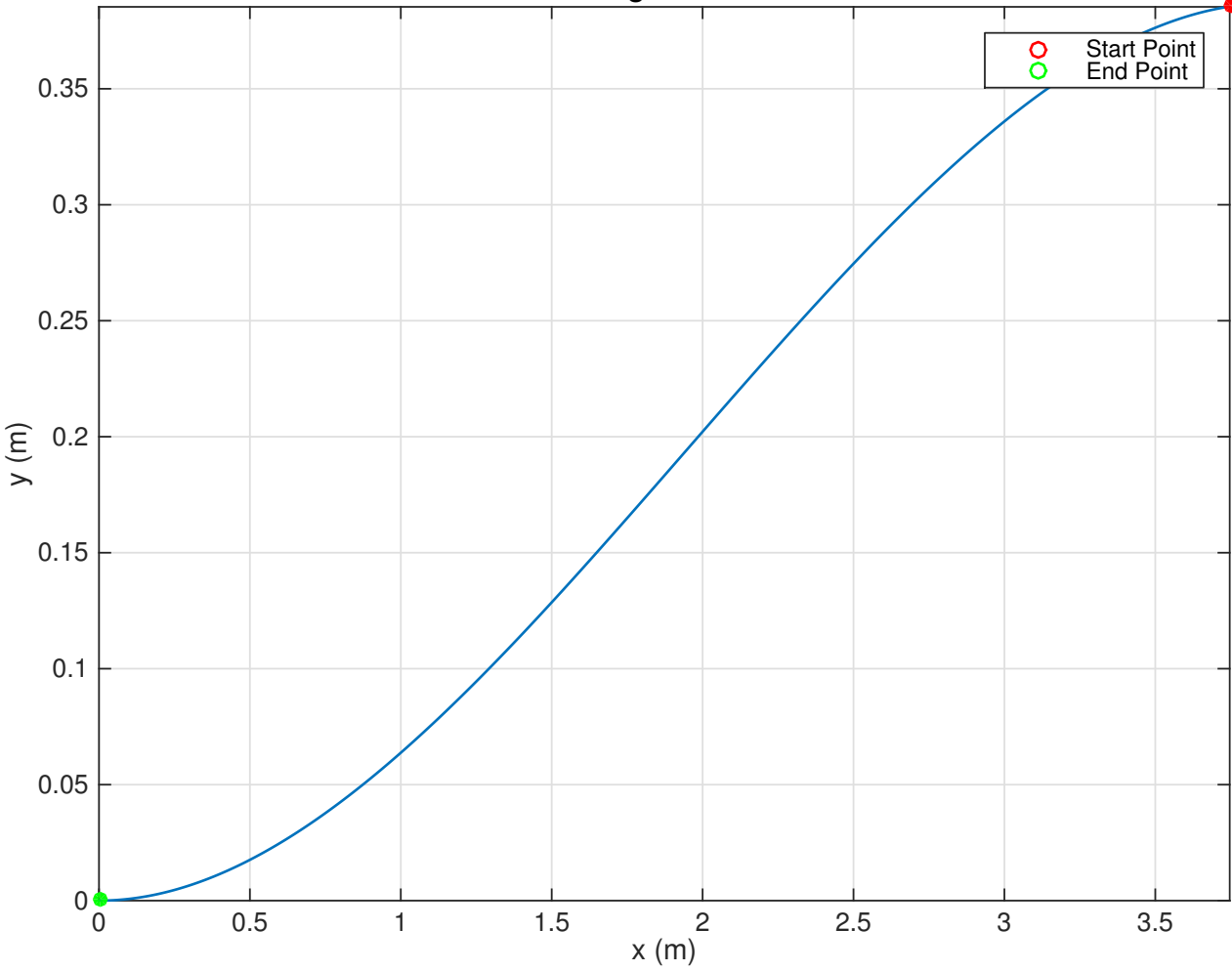


OtherAngle2 All Paths



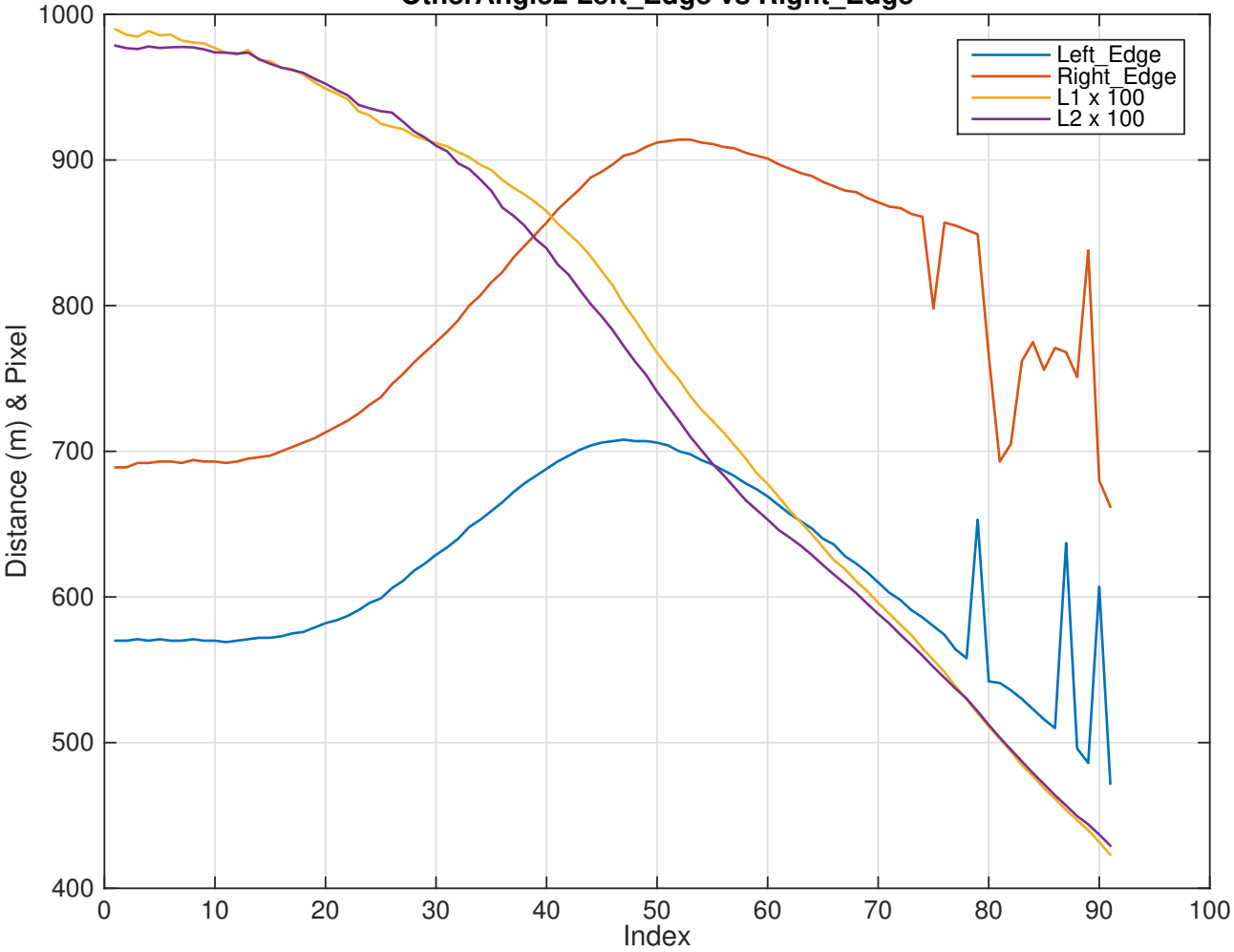
Number_Of_Unique_Paths

King_Pin_Detected

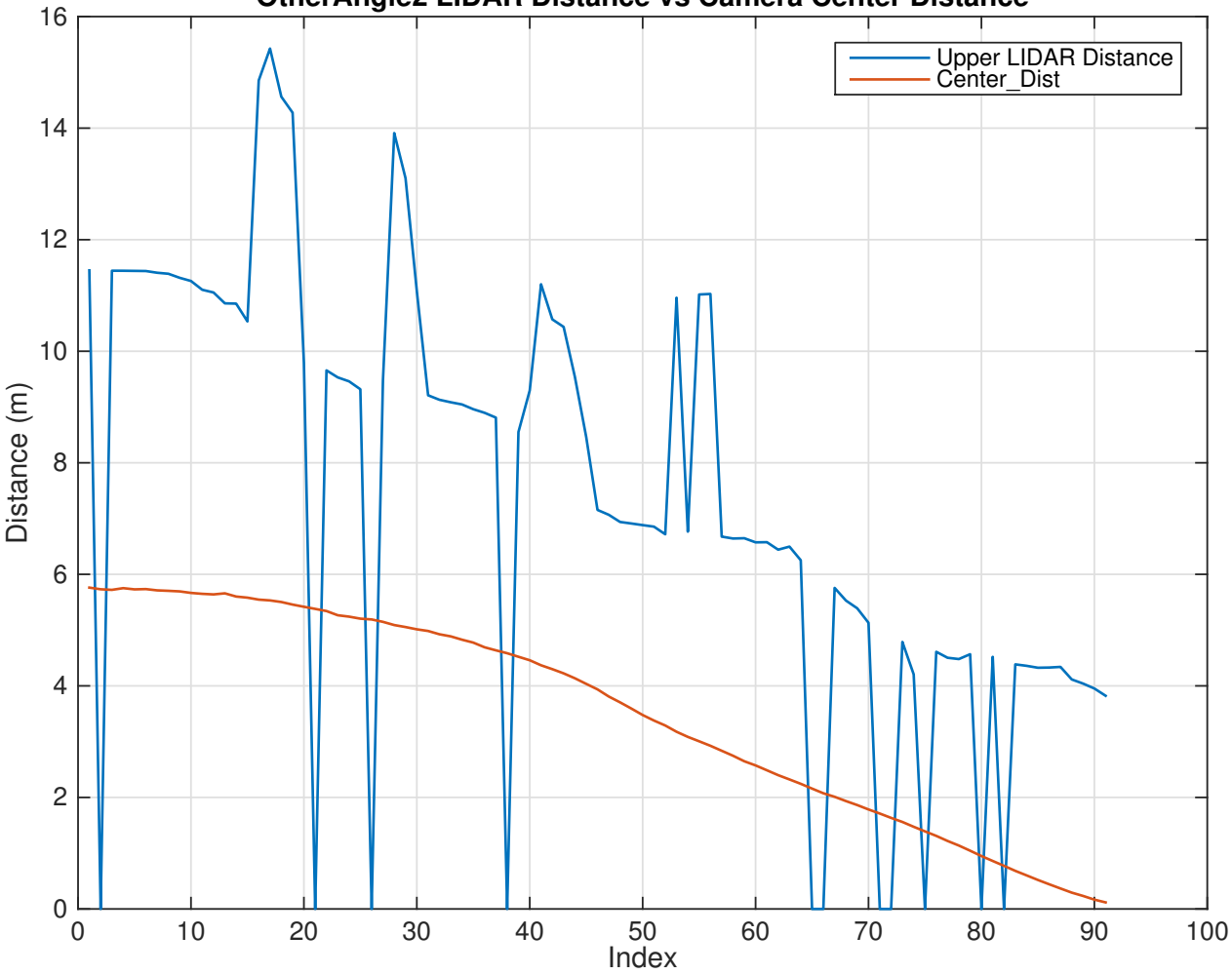
1

false

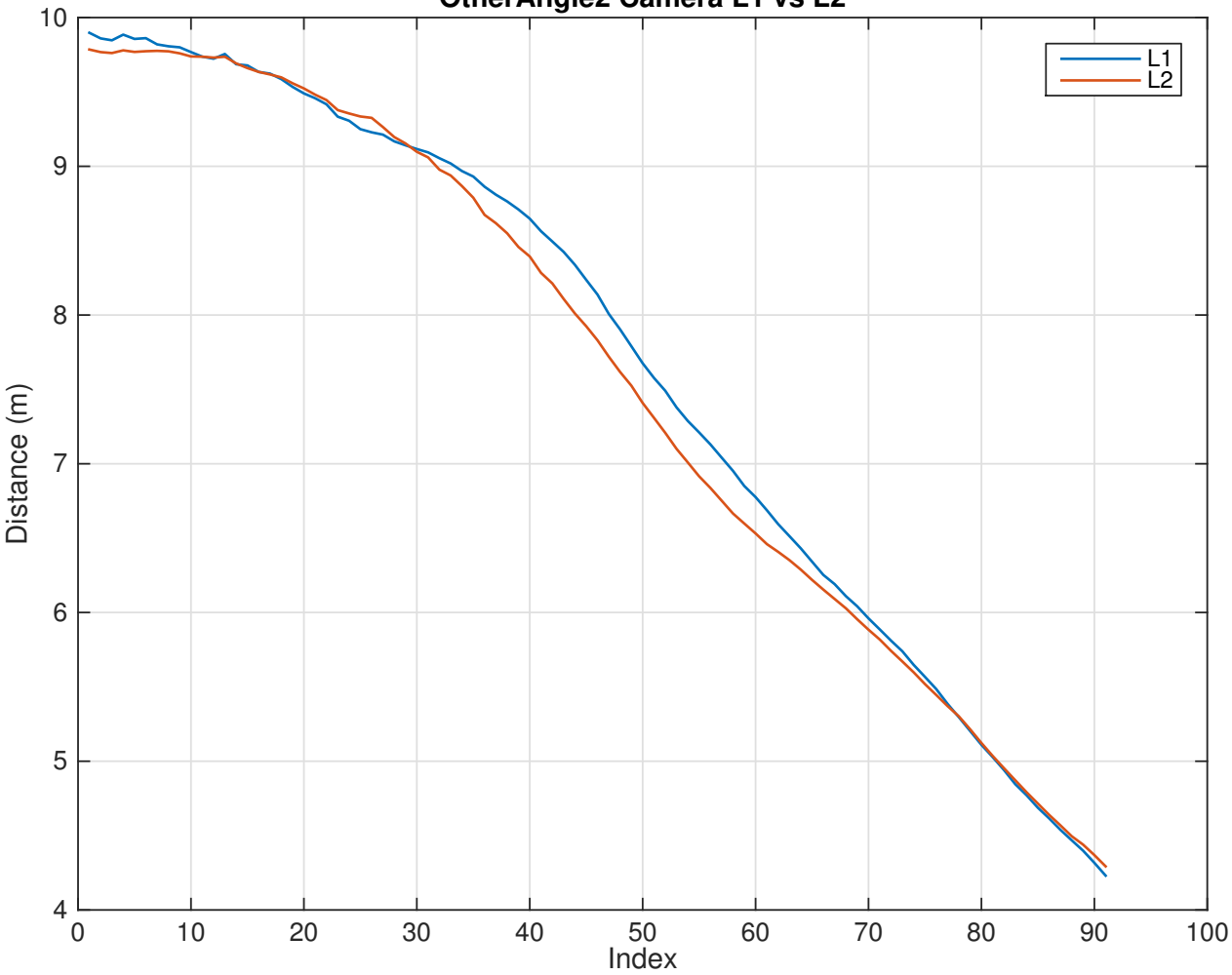
OtherAngle2 Left_Edge vs Right_Edge



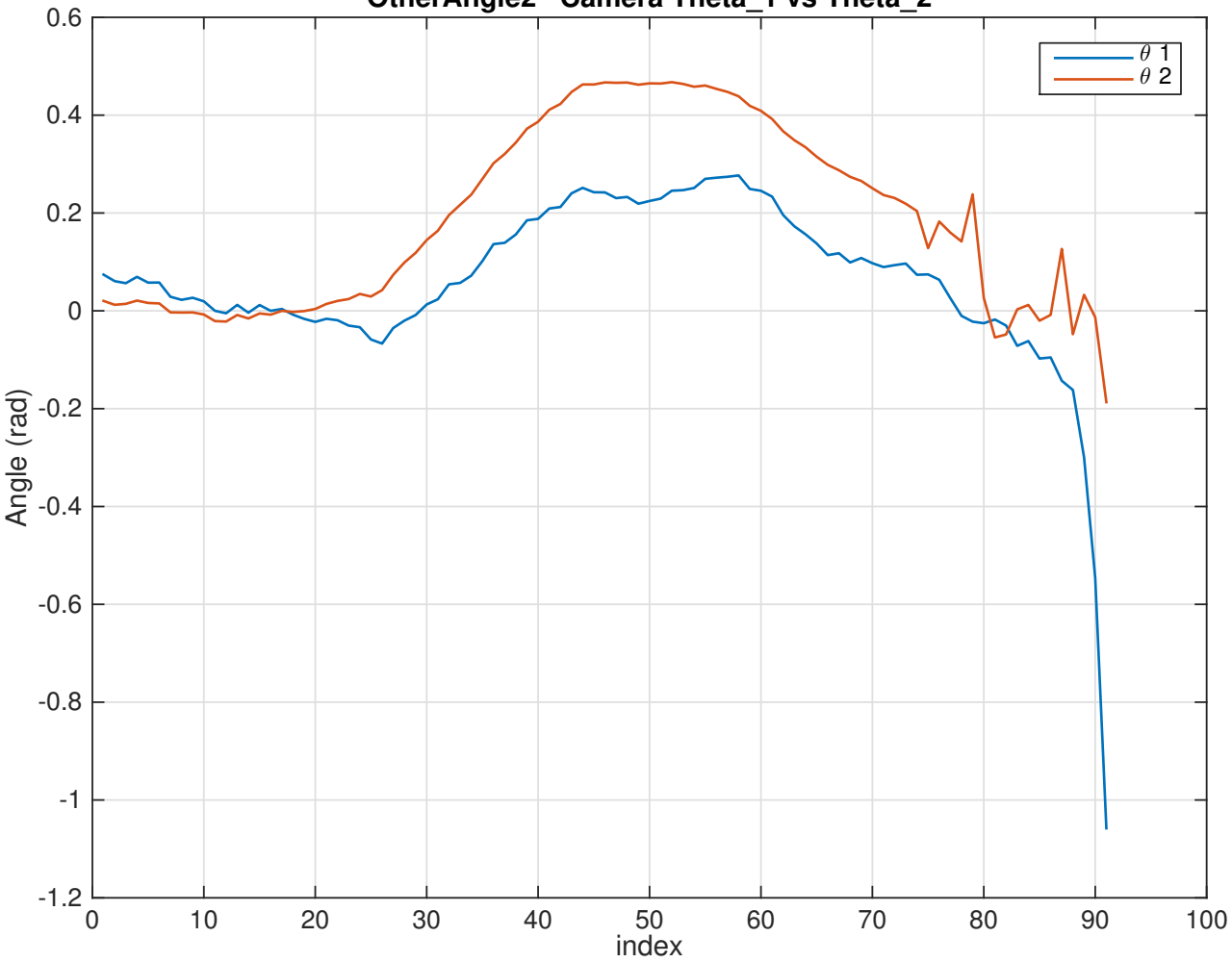
OtherAngle2 LIDAR Distance vs Camera Center Distance



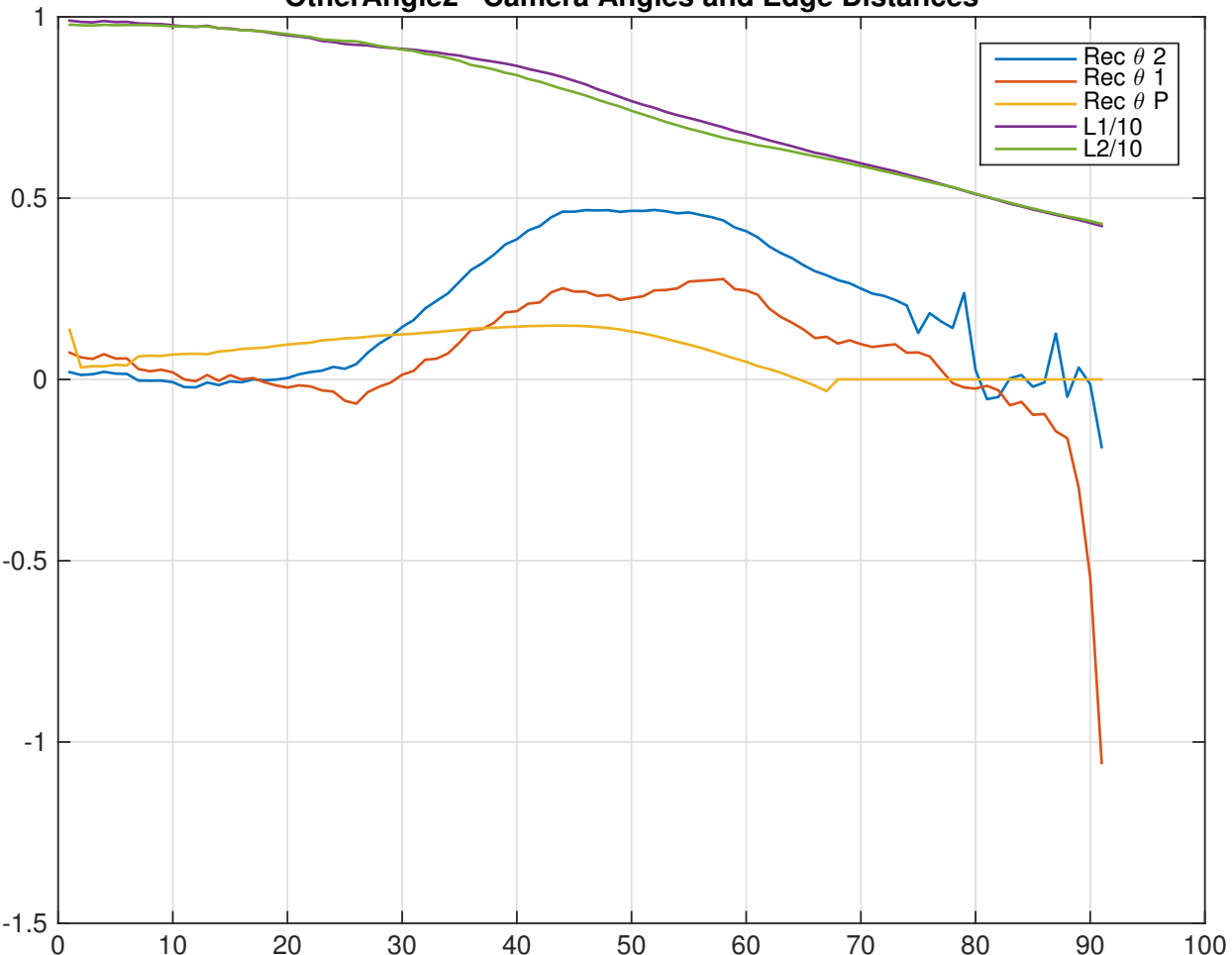
OtherAngle2 Camera L1 vs L2



OtherAngle2 Camera Theta_1 vs Theta_2



OtherAngle2 Camera Angles and Edge Distances



OtherAngle2 Steering

