

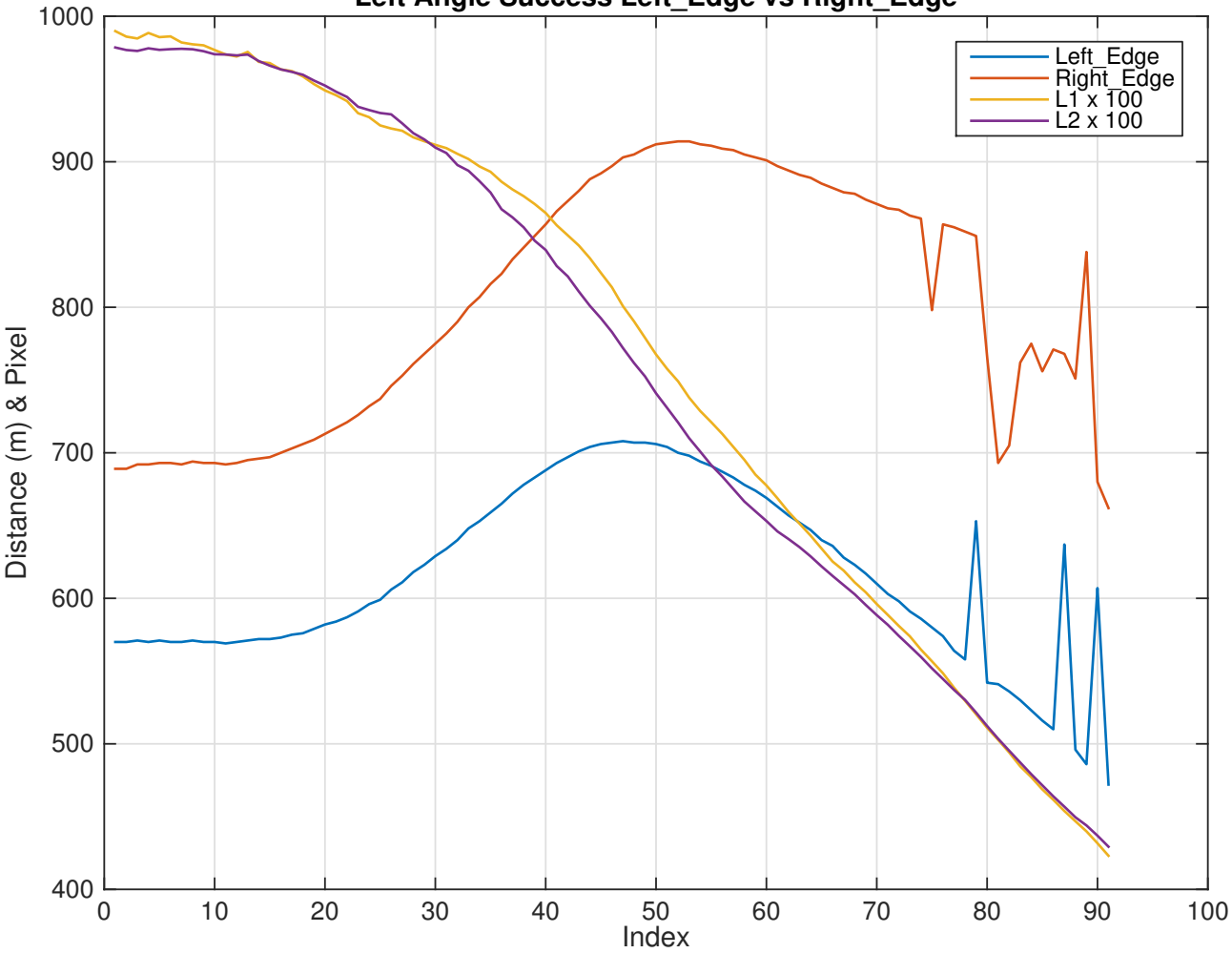
Number_Of_Unique_Paths

King_Pin_Detected

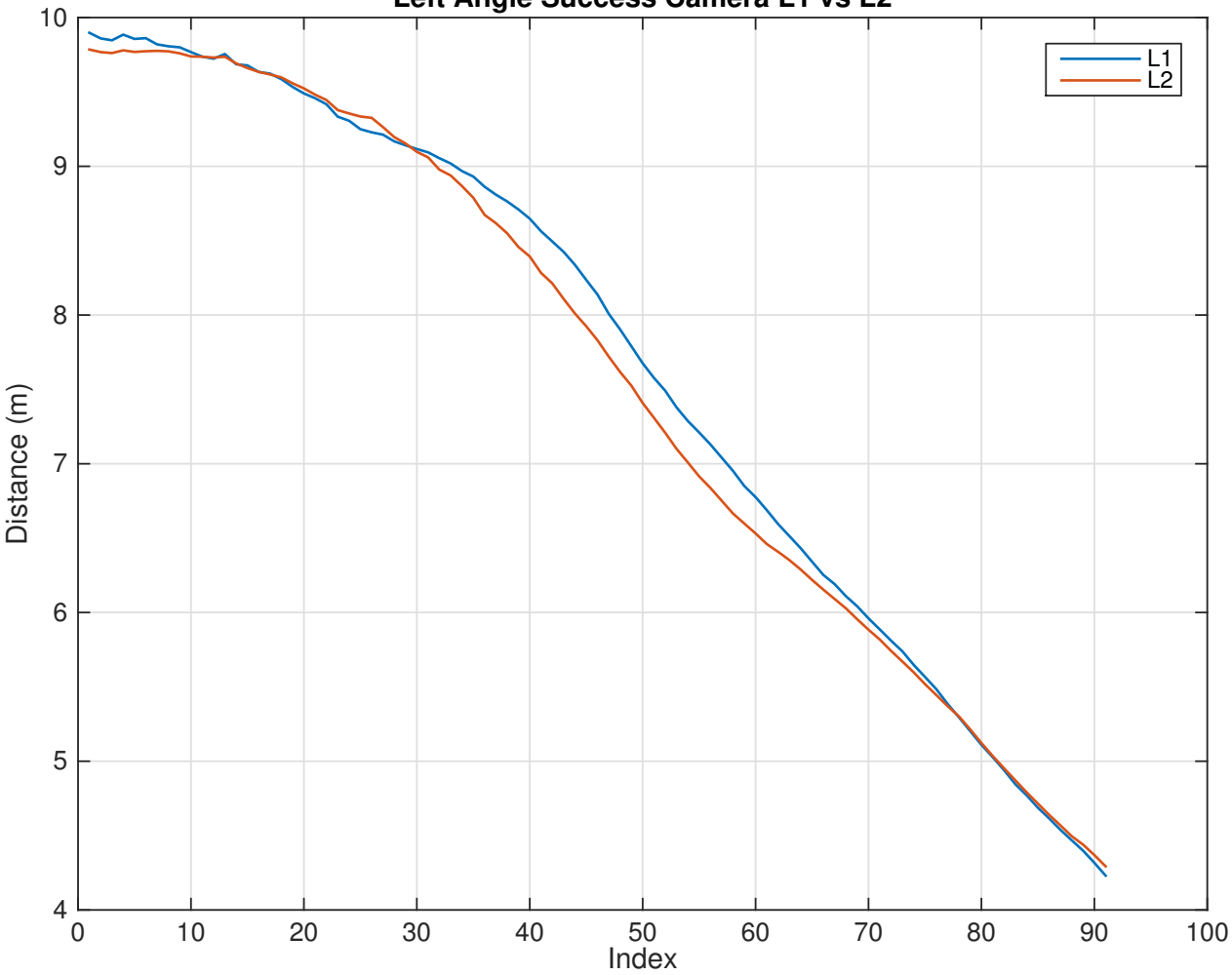
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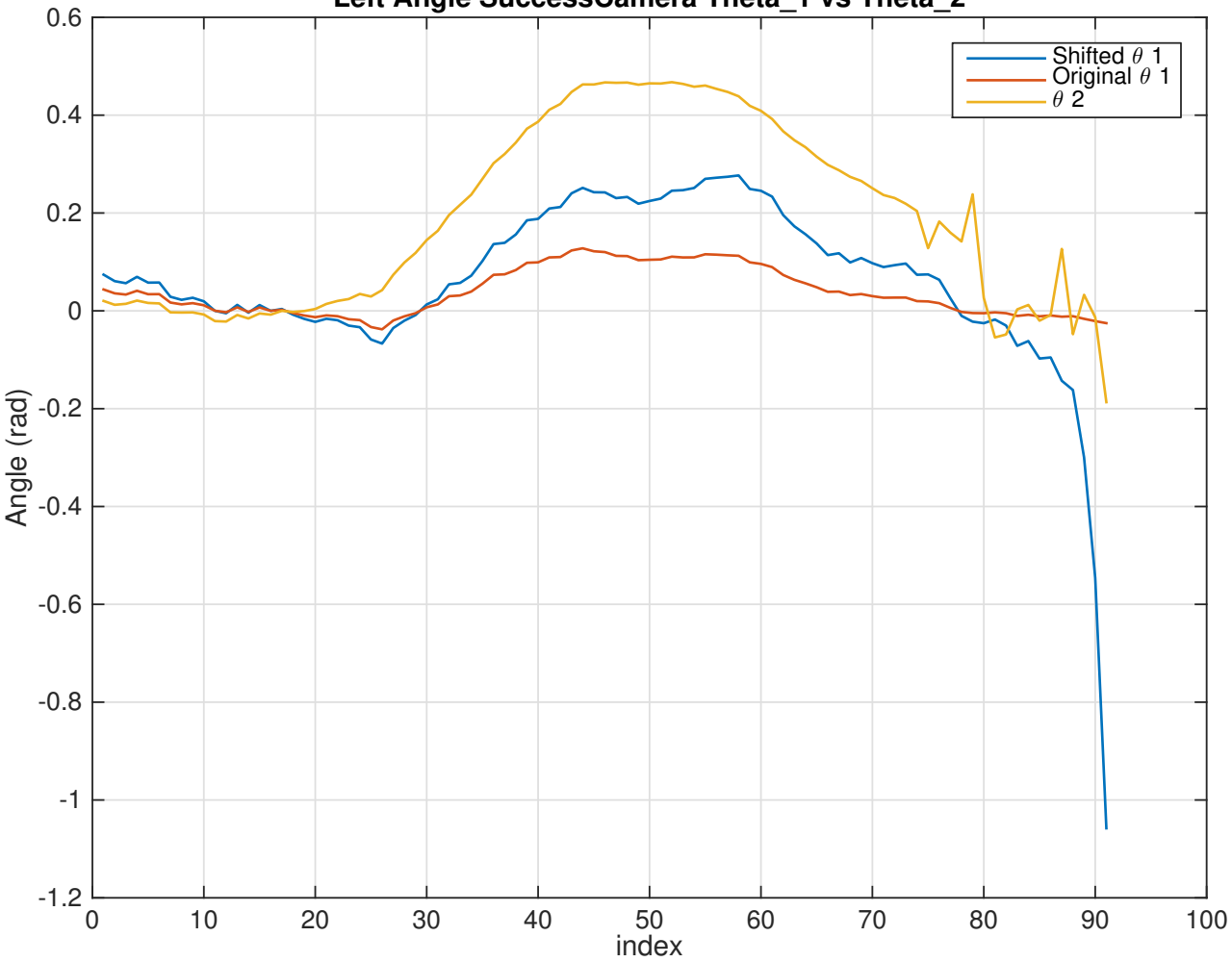
Left Angle Success Left_Edge vs Right_Edge



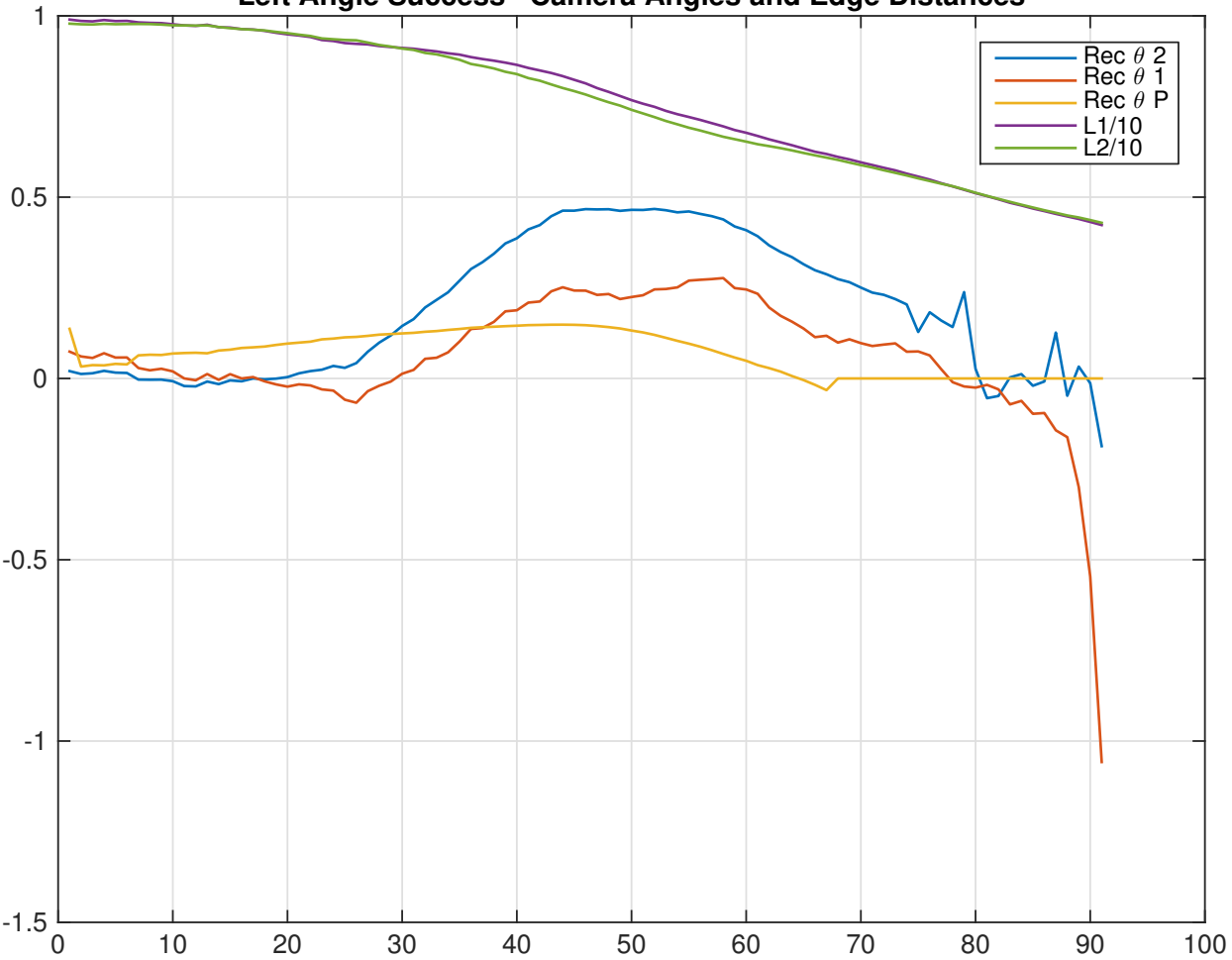
Left Angle Success Camera L1 vs L2



Left Angle SuccessCamera Theta_1 vs Theta_2



Left Angle Success Camera Angles and Edge Distances



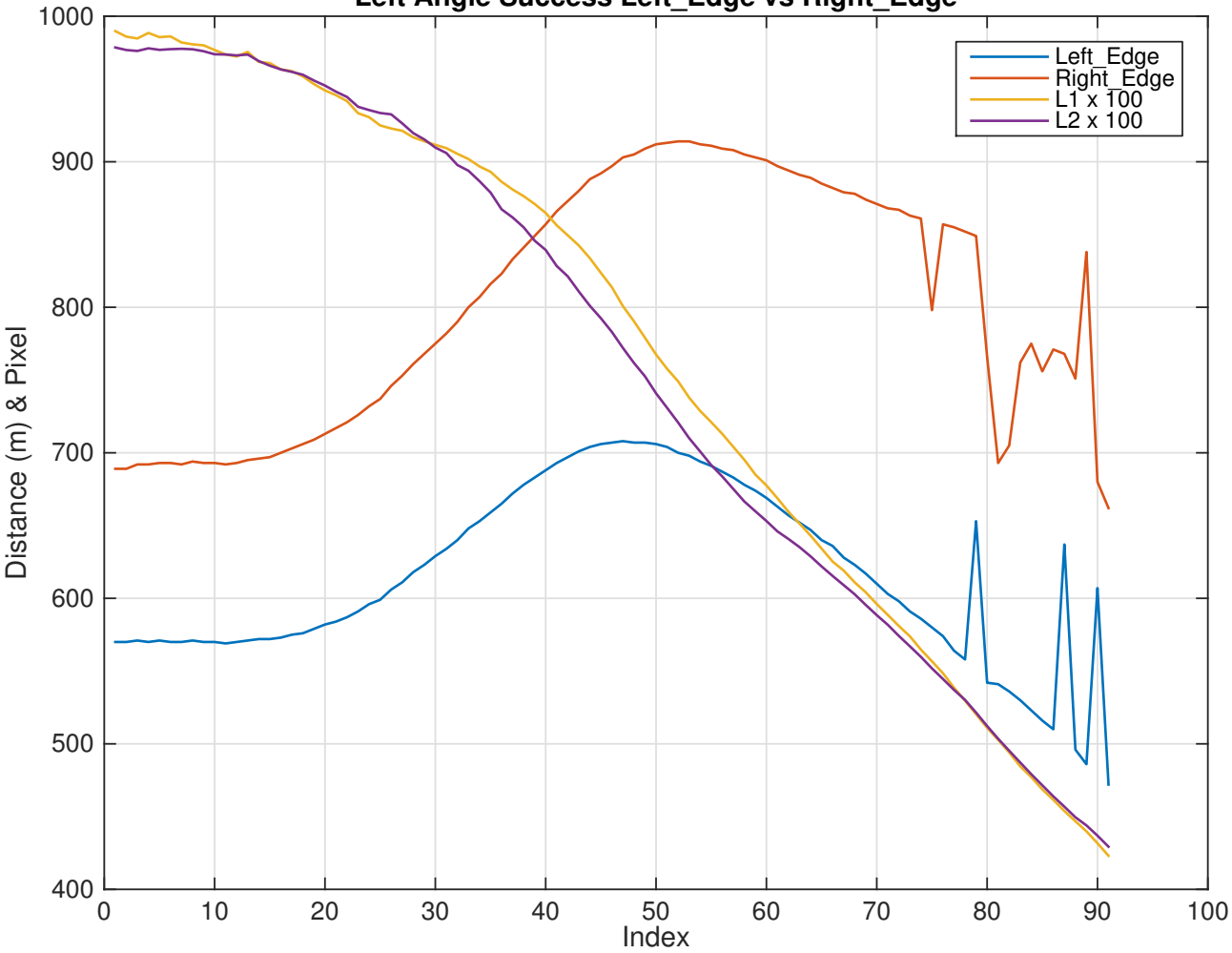
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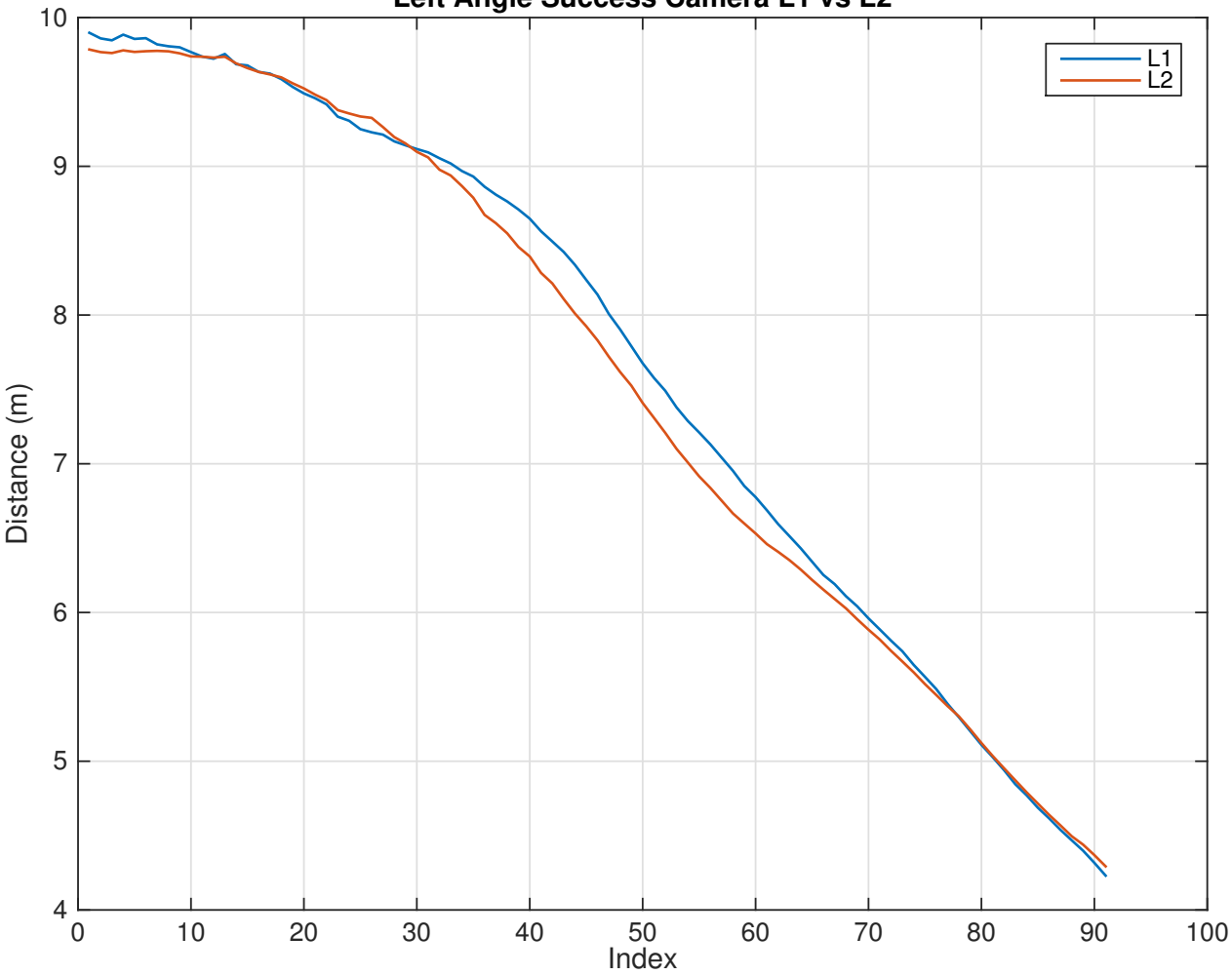
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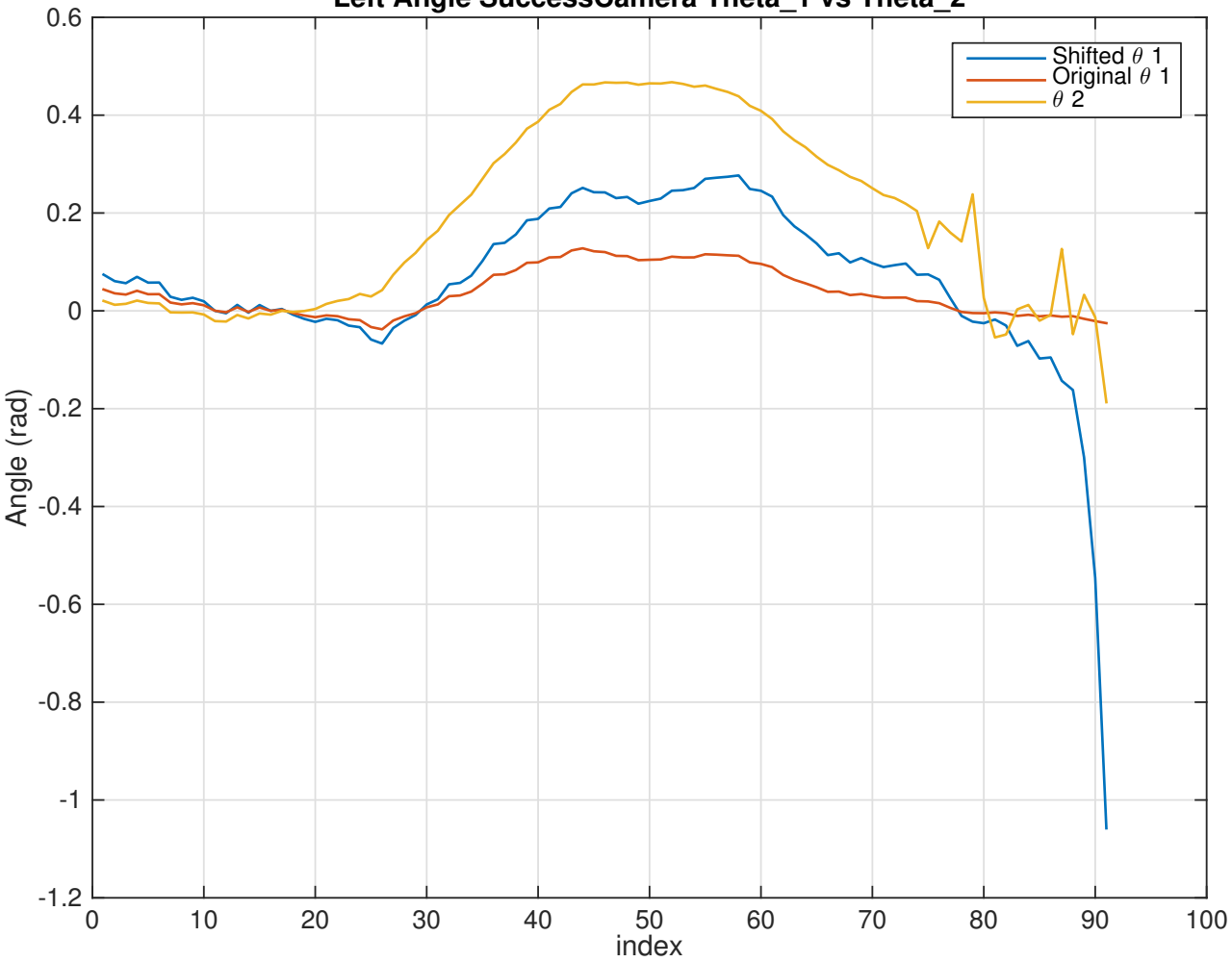
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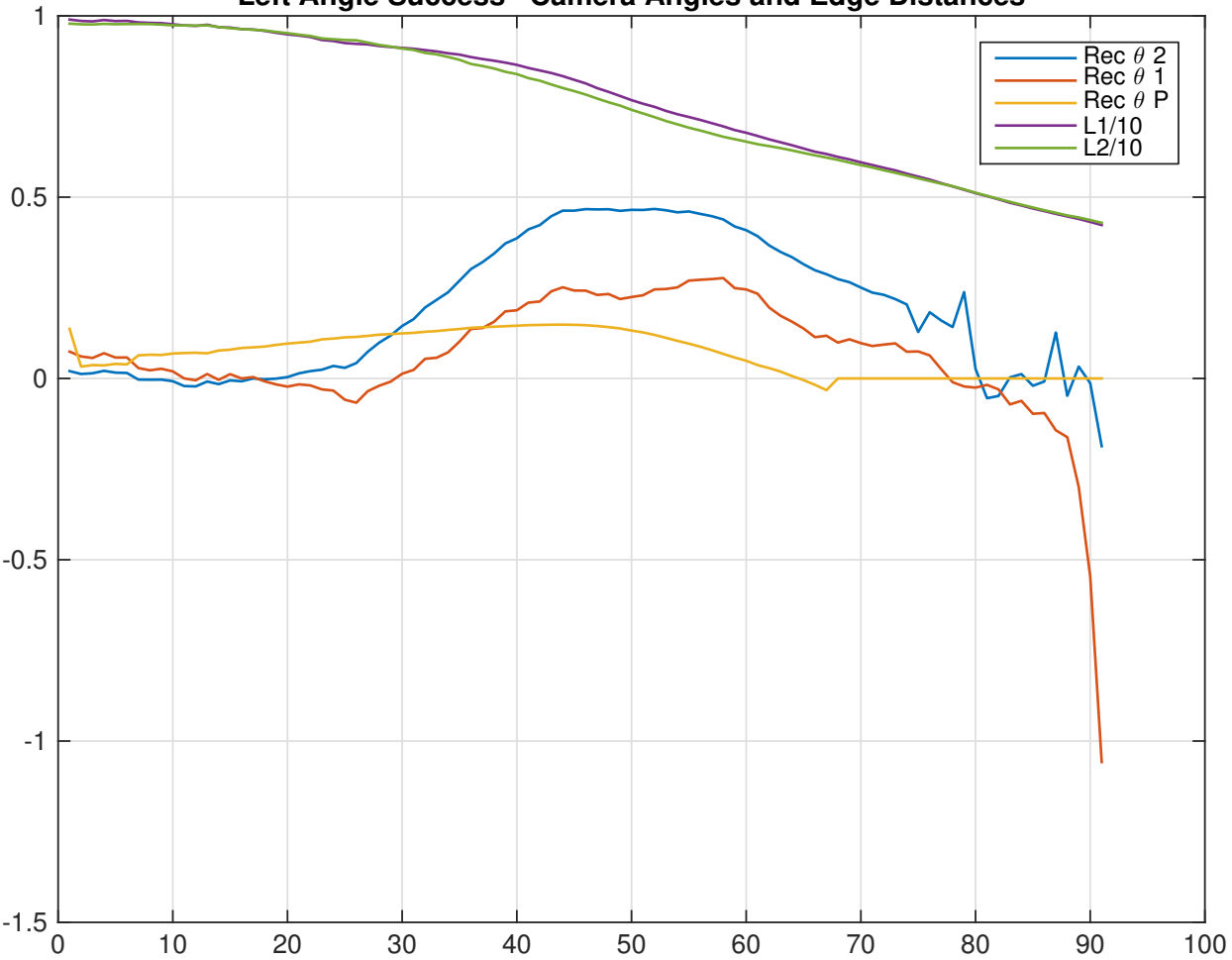
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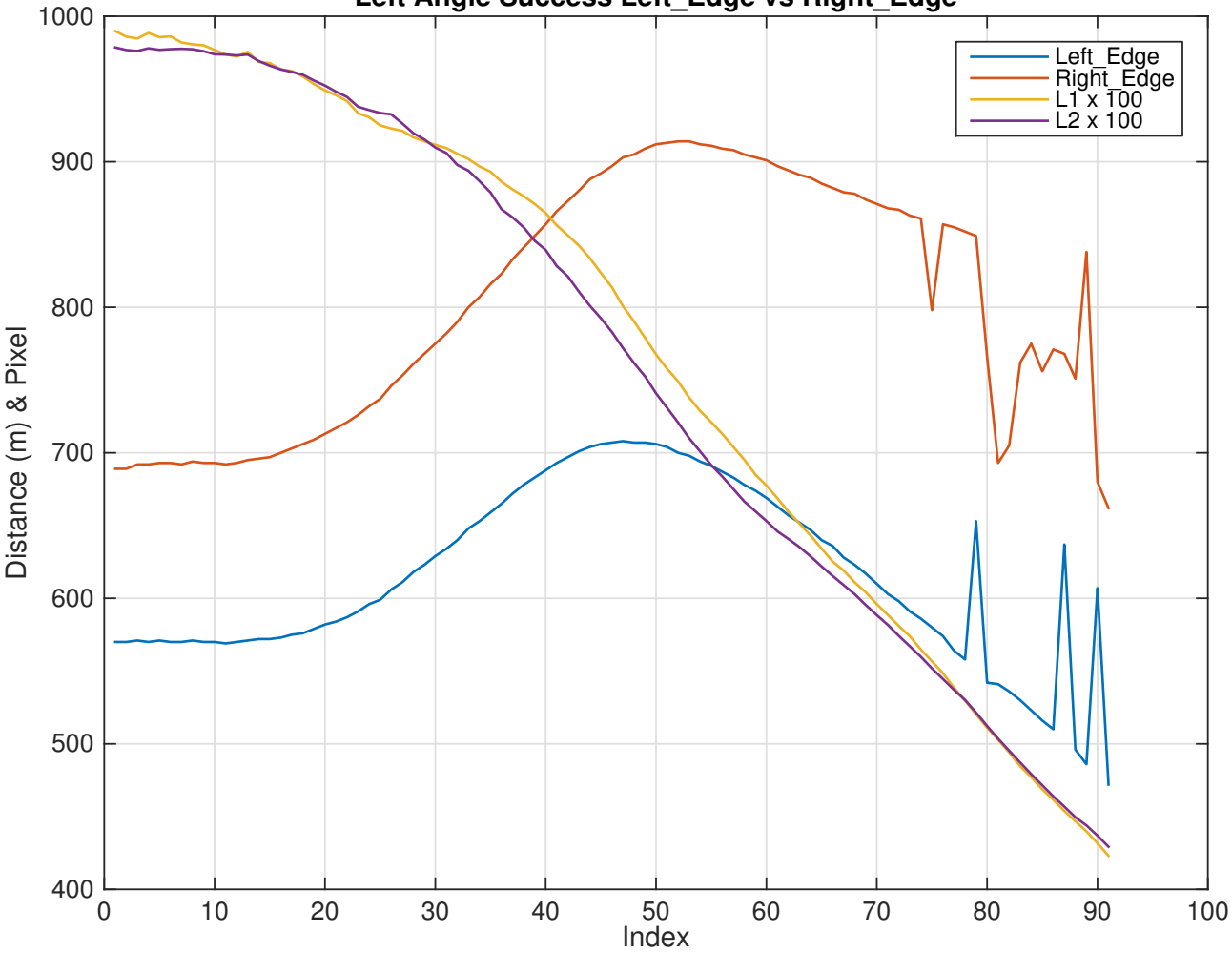
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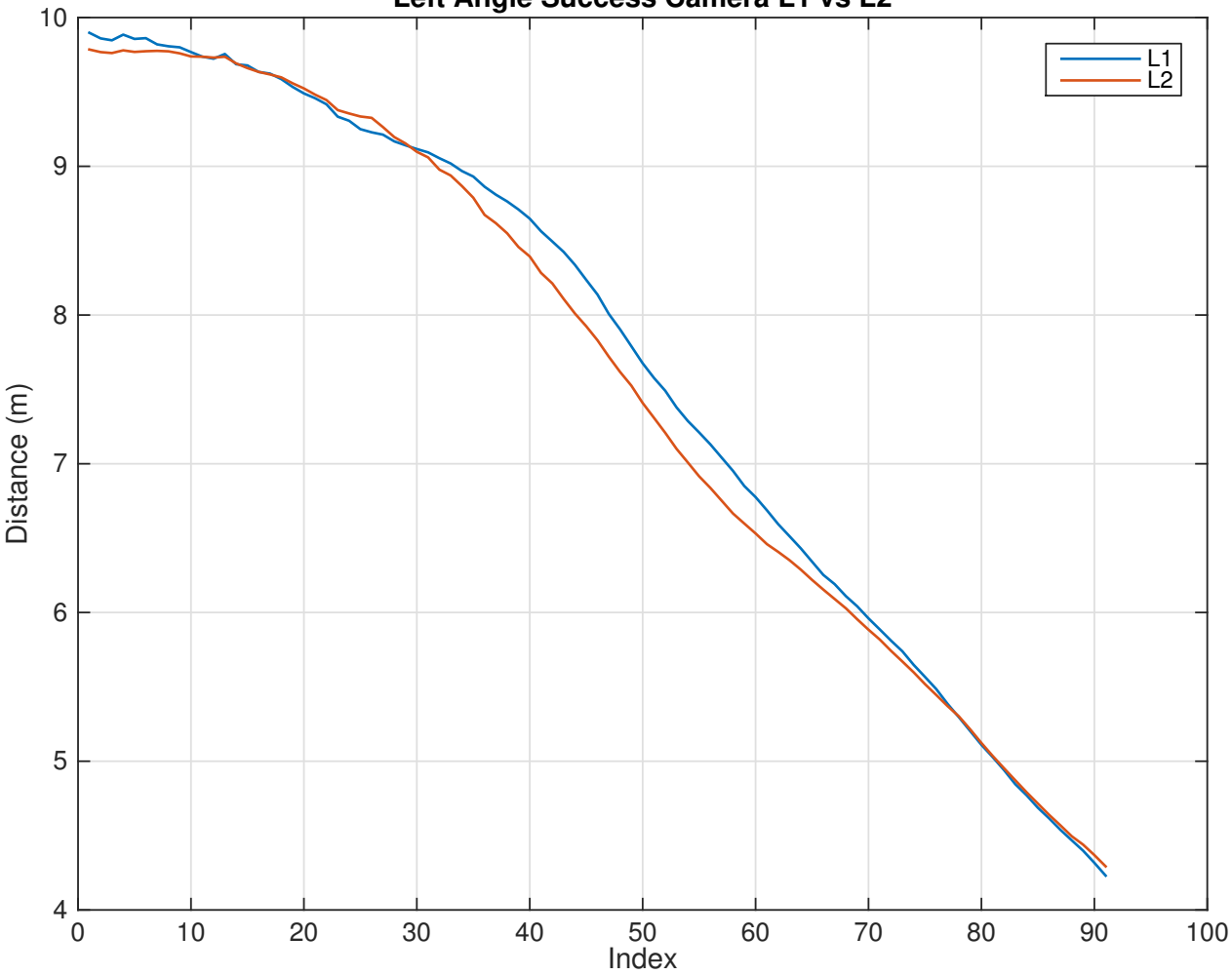
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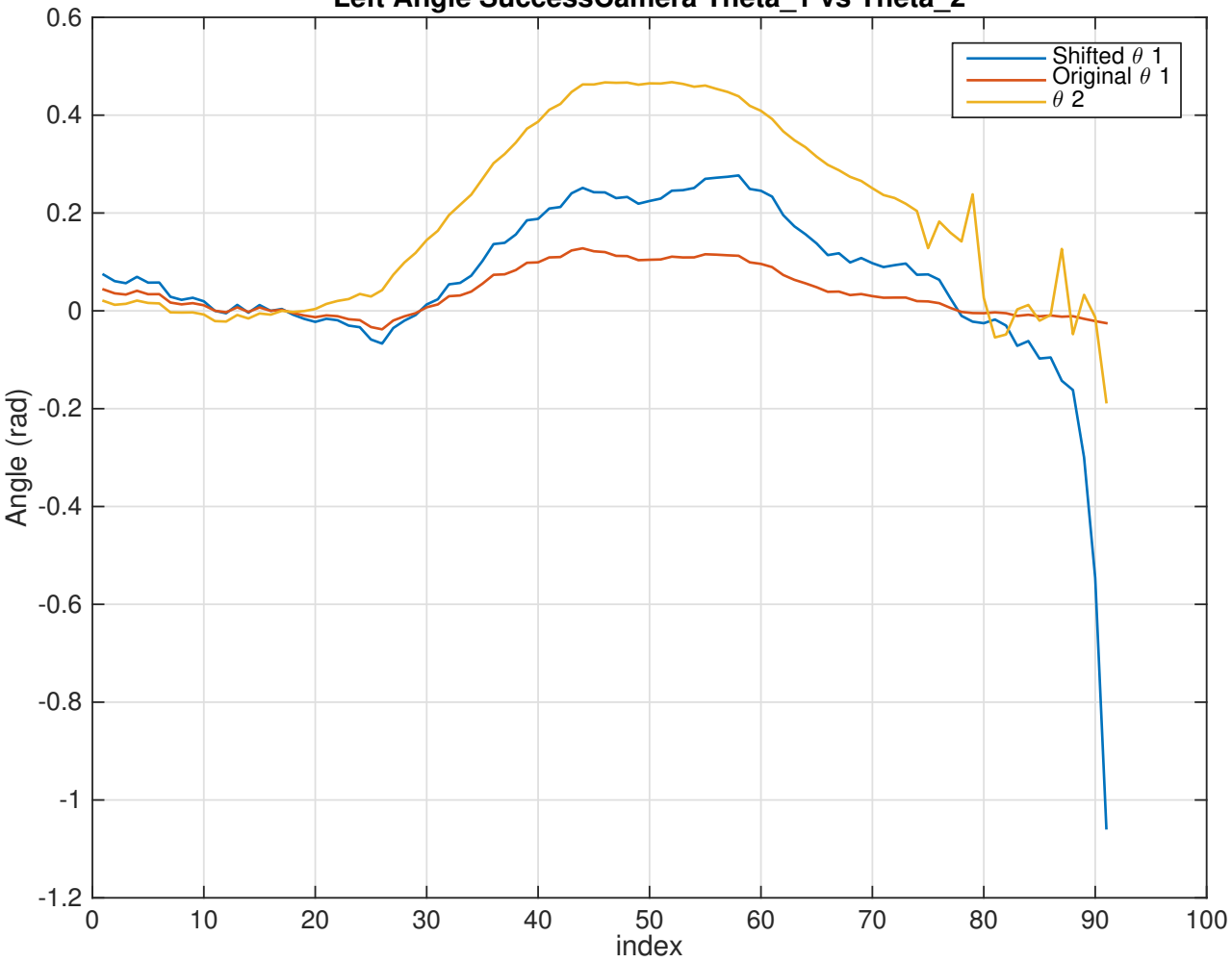
Left Angle Success Left_Edge vs Right_Edge



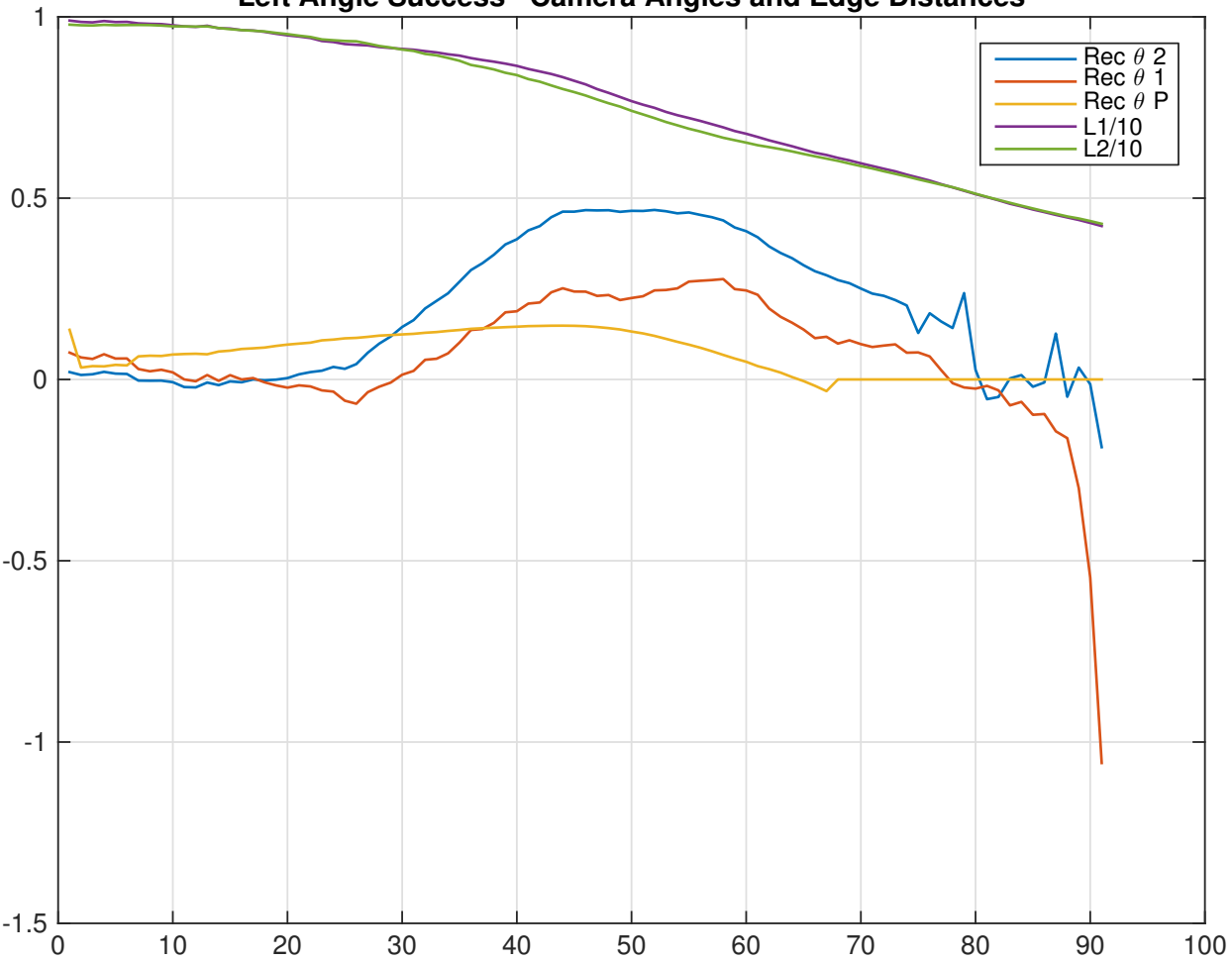
Left Angle Success Camera L1 vs L2



Left Angle SuccessCamera Theta_1 vs Theta_2



Left Angle Success Camera Angles and Edge Distances



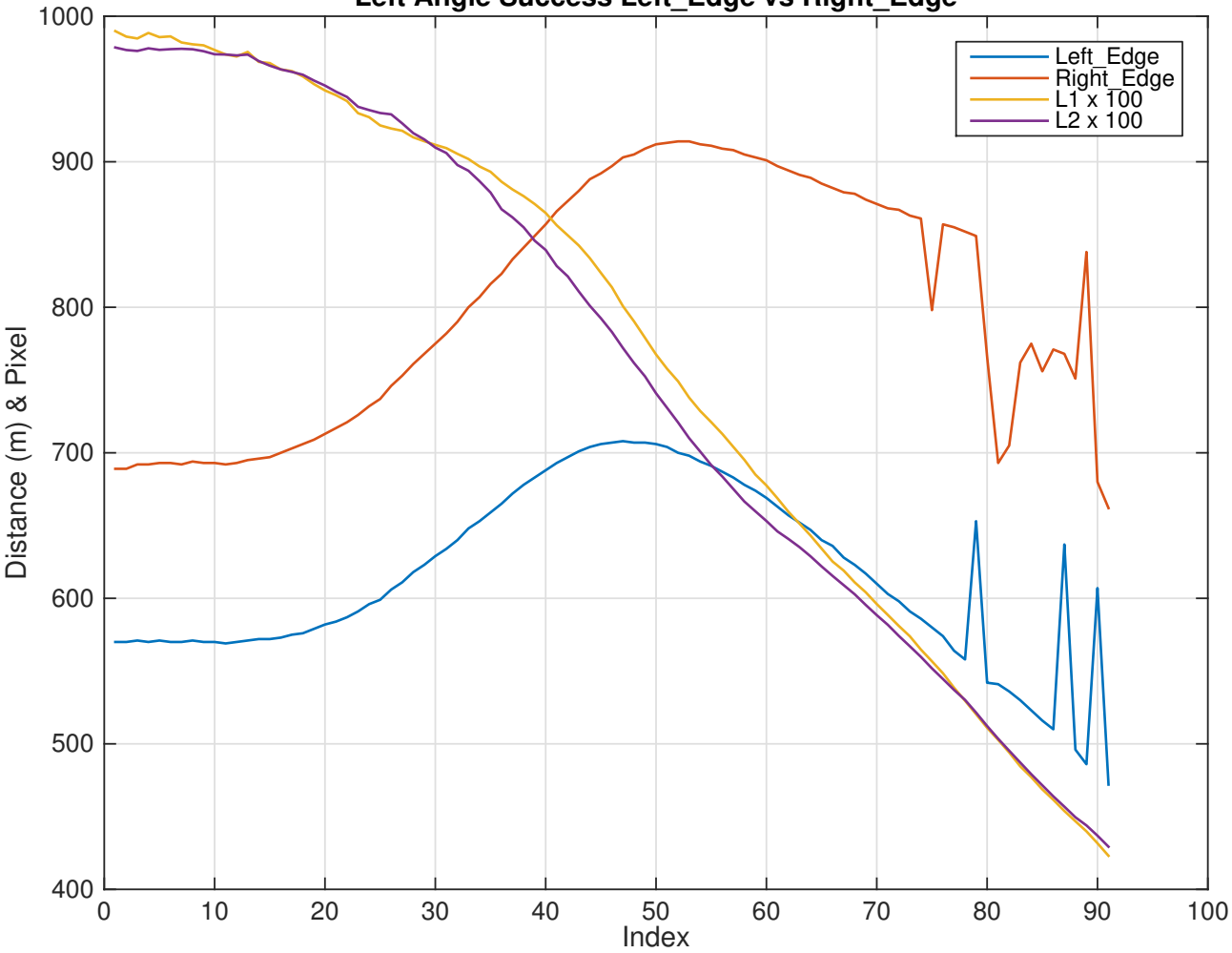
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Left Angle Success Left_Edge vs Right_Edge



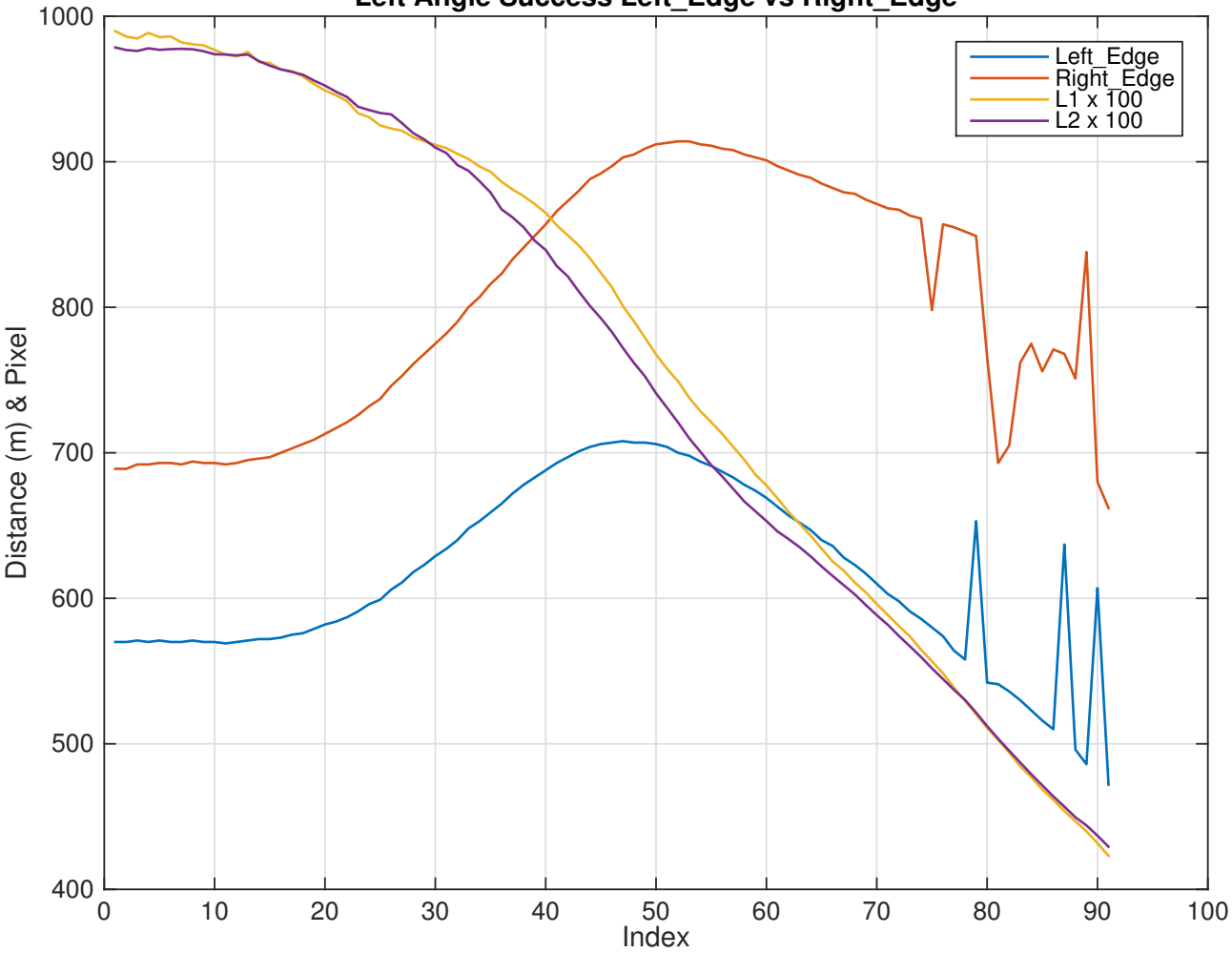
Number_Of_Unique_Paths

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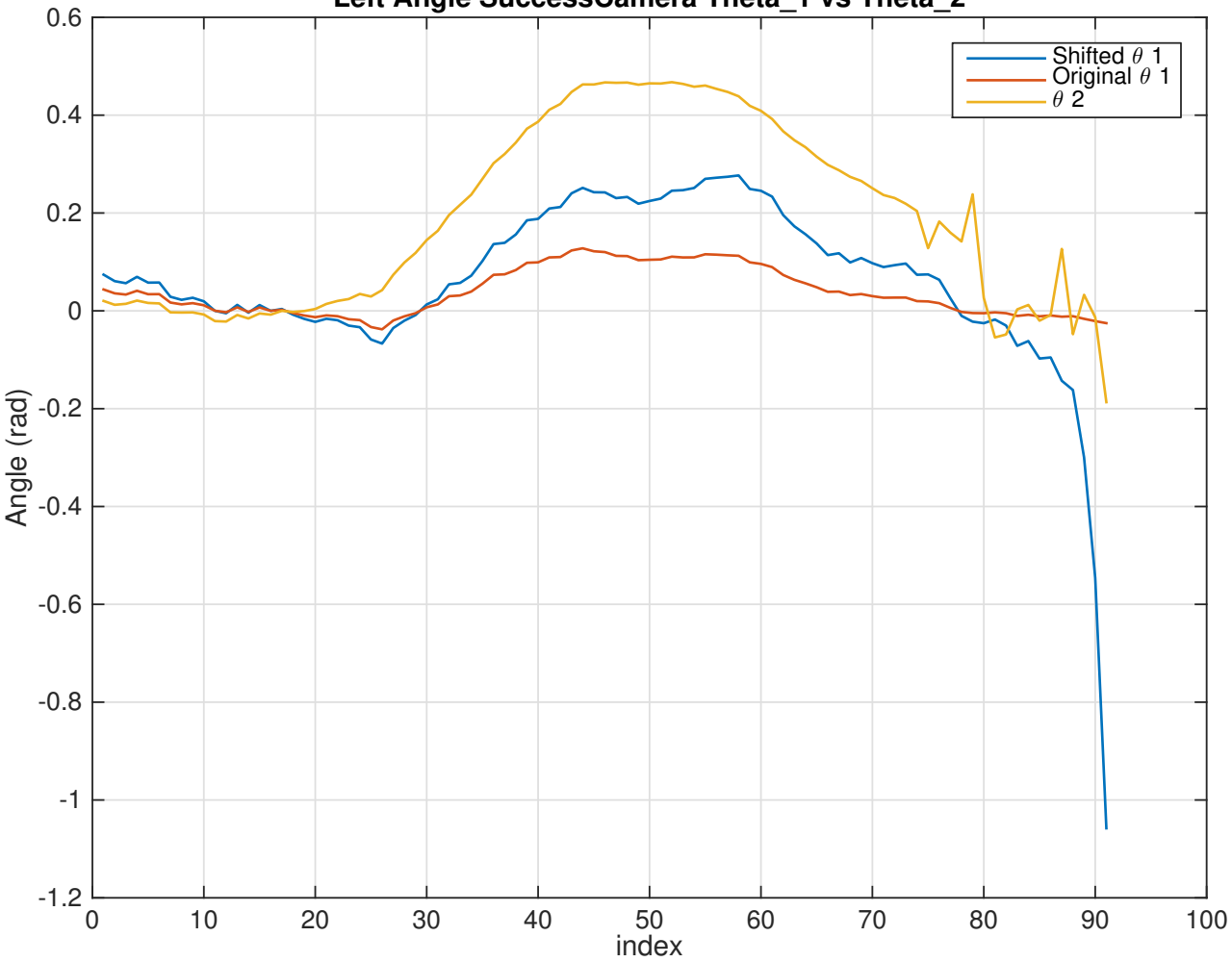
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false

Left Angle Success Left_Edge vs Right_Edge



Left Angle SuccessCamera Theta_1 vs Theta_2



Number_Of_Unique_Paths

King_Pin_Detected

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