

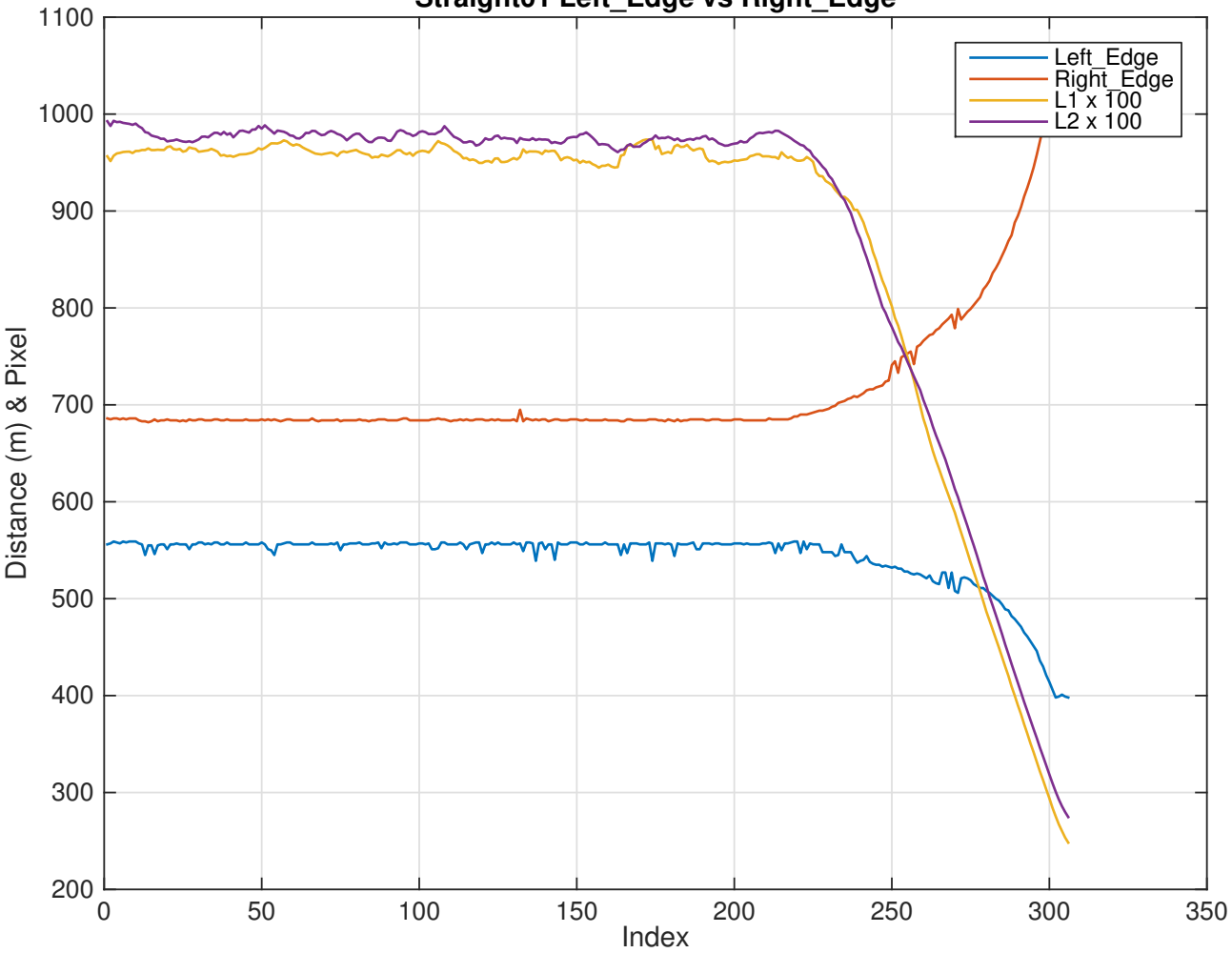
Number_Of_Unique_Paths

King_Pin_Detected

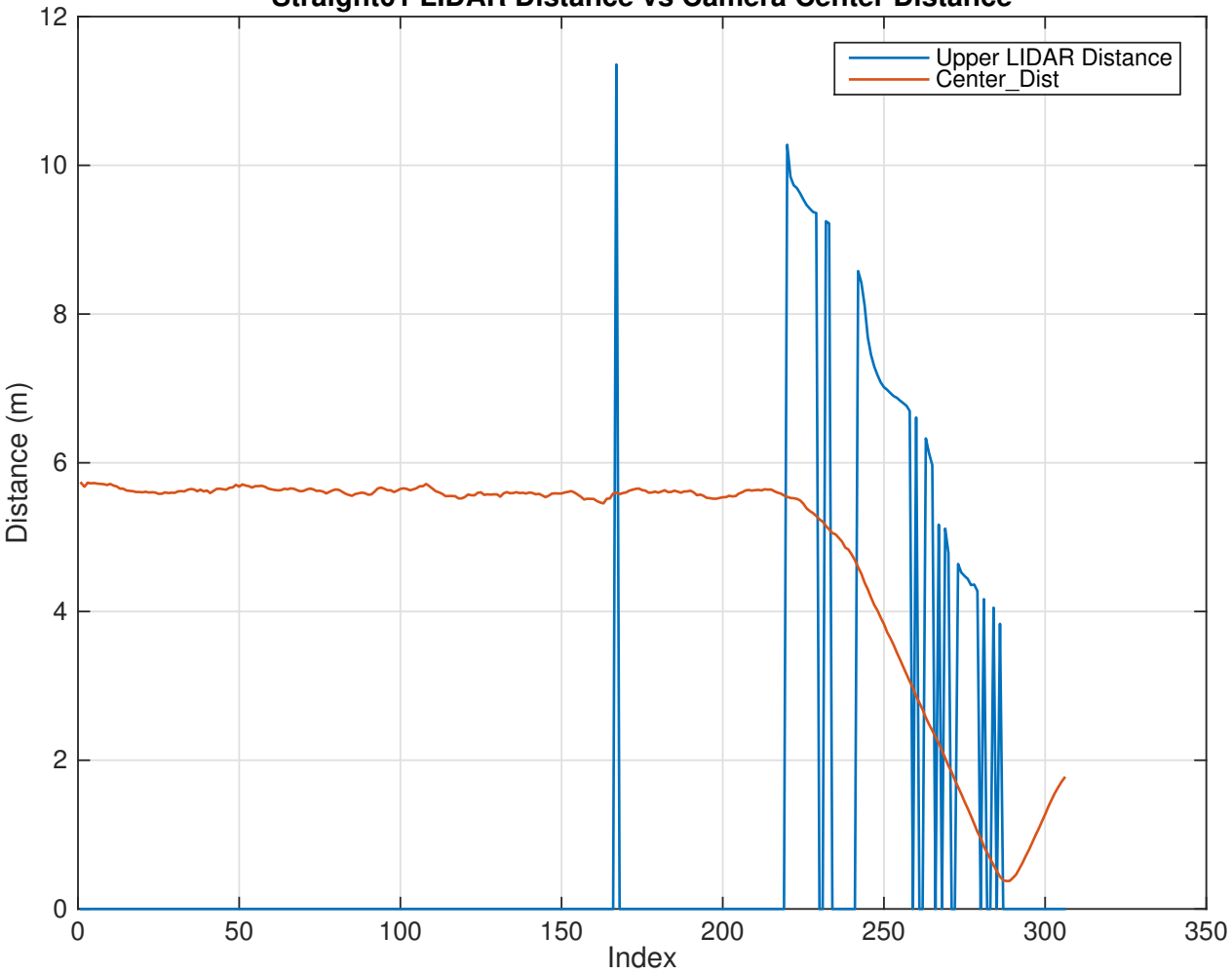
113

false

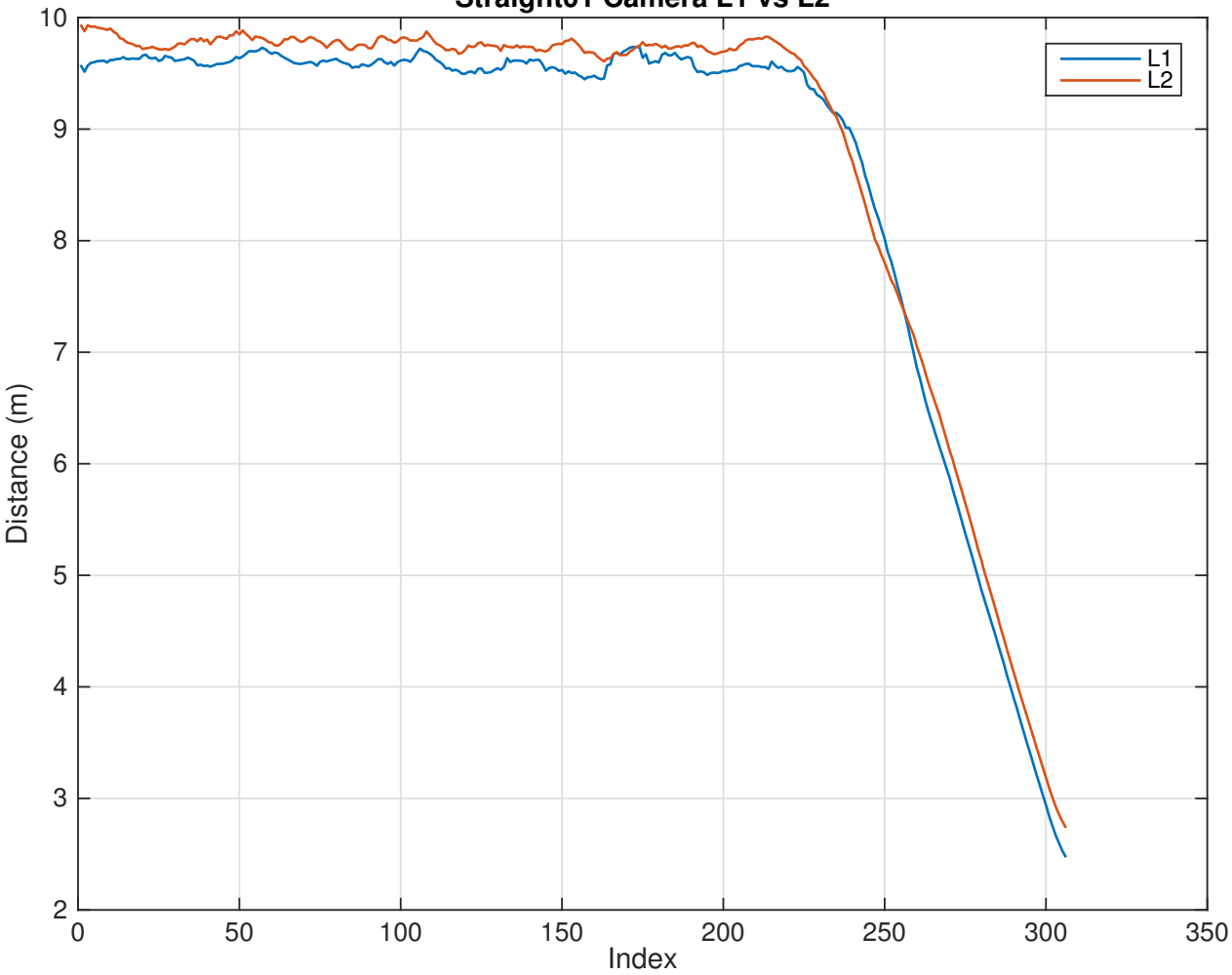
Straight01 Left_Edge vs Right_Edge



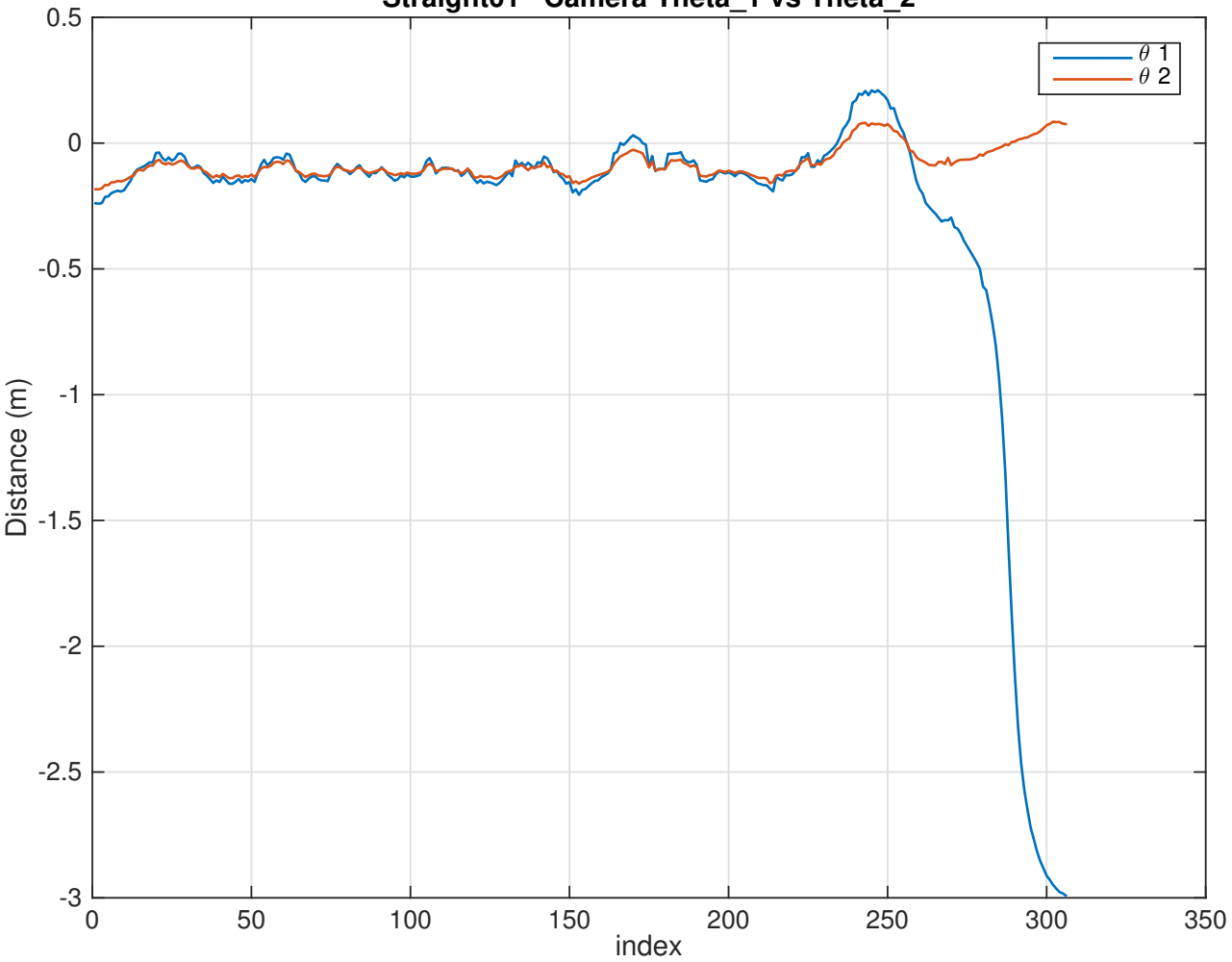
Straight01 LIDAR Distance vs Camera Center Distance



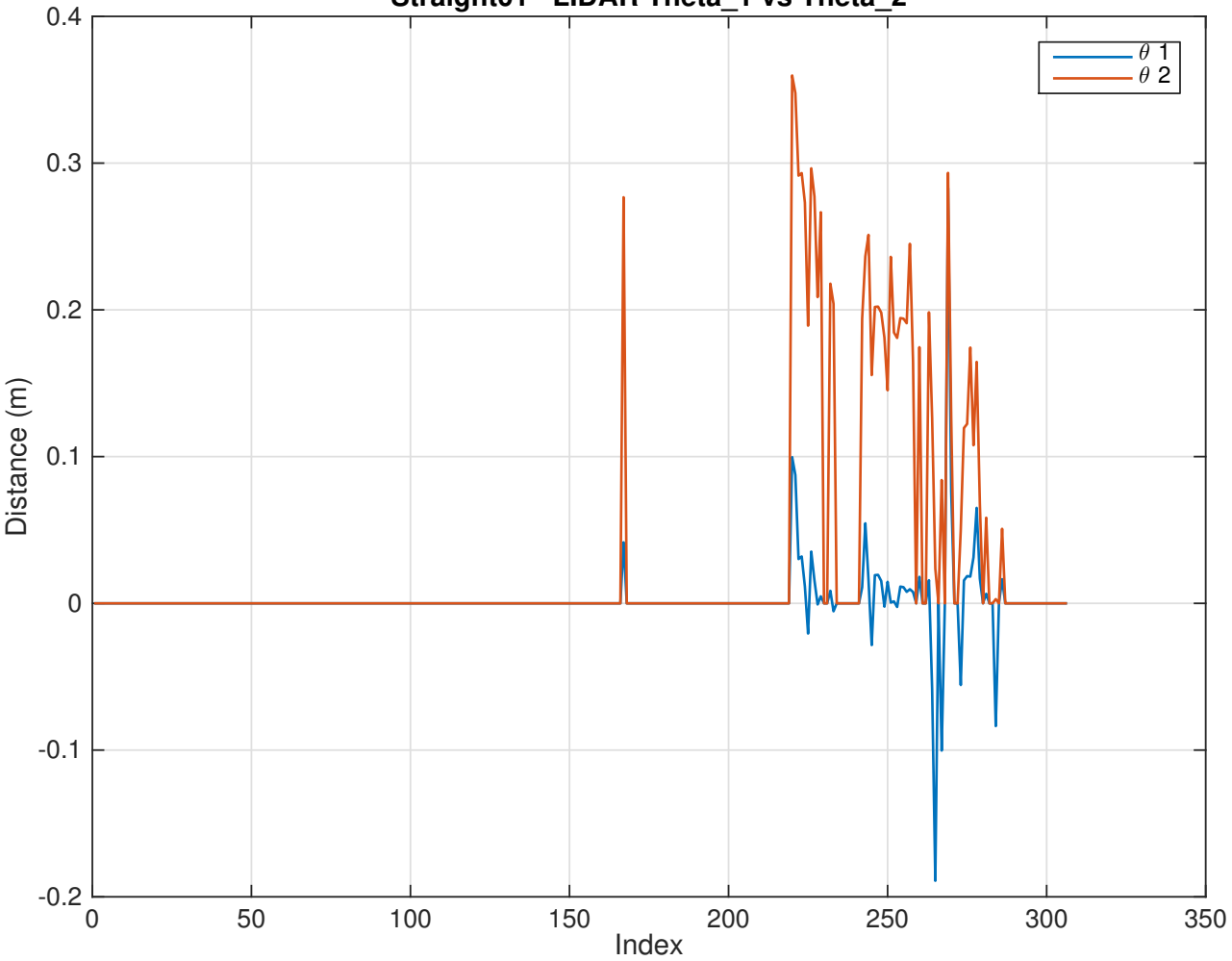
Straight01 Camera L1 vs L2



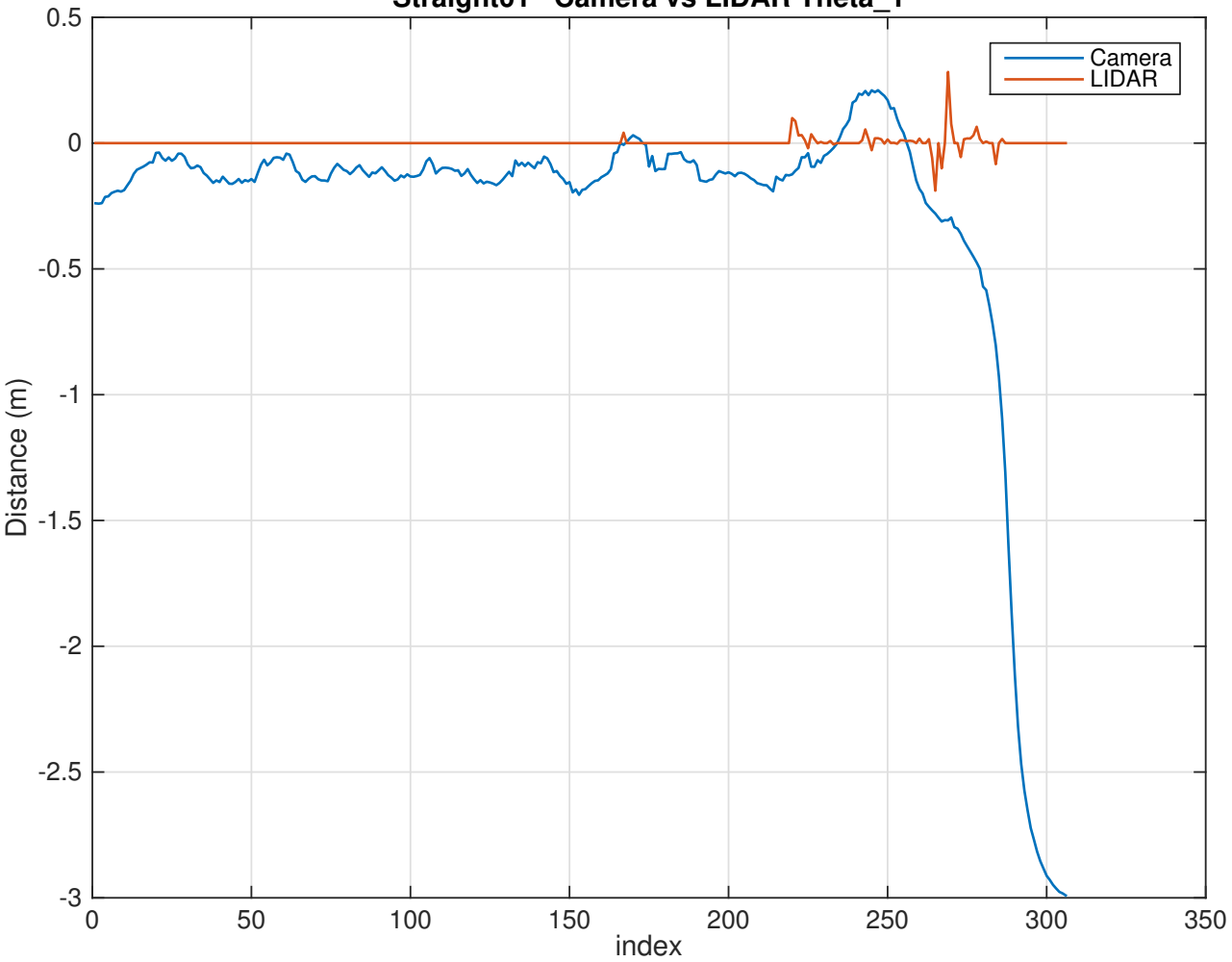
Straight01 Camera Theta_1 vs Theta_2



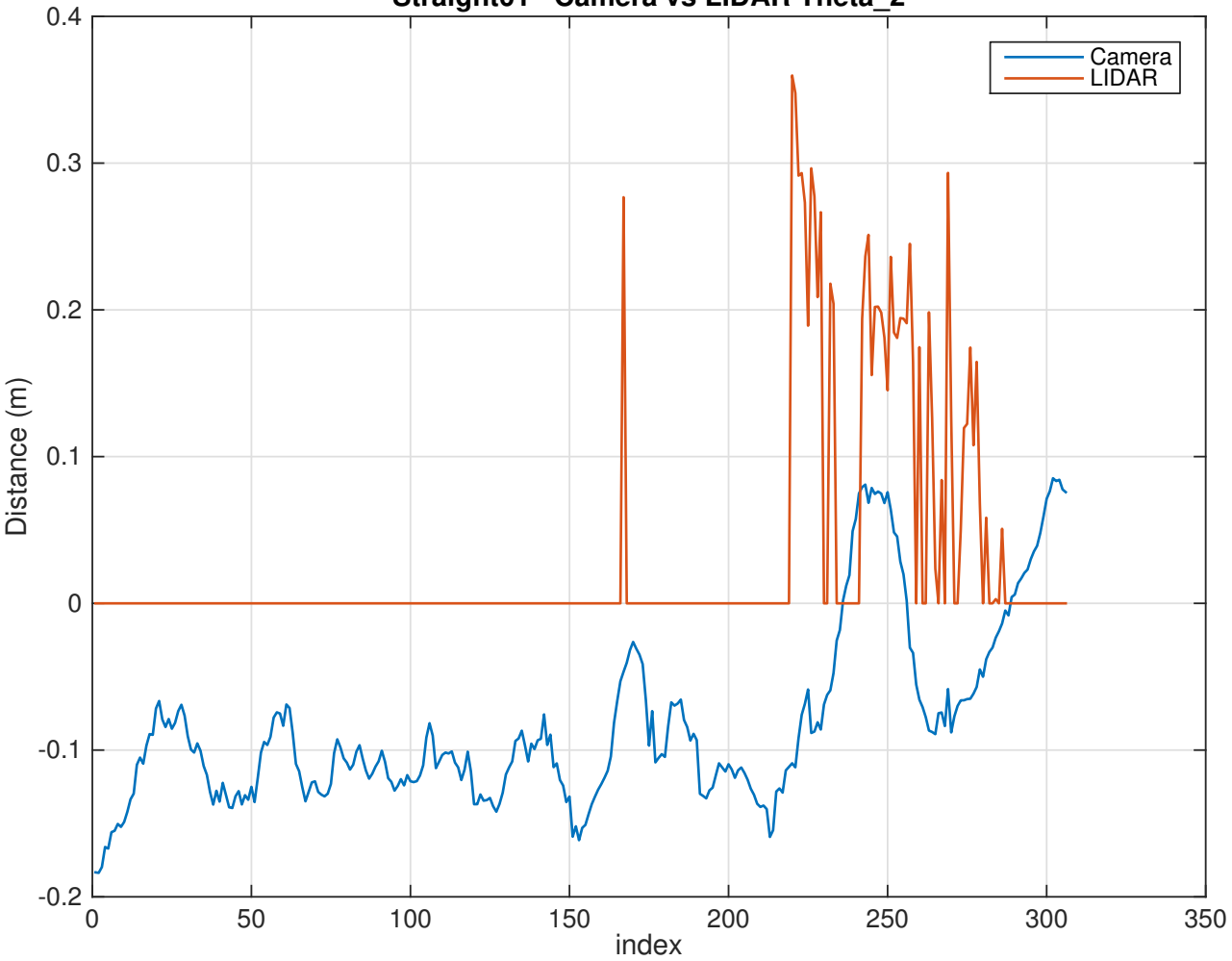
Straight01 LIDAR Theta_1 vs Theta_2



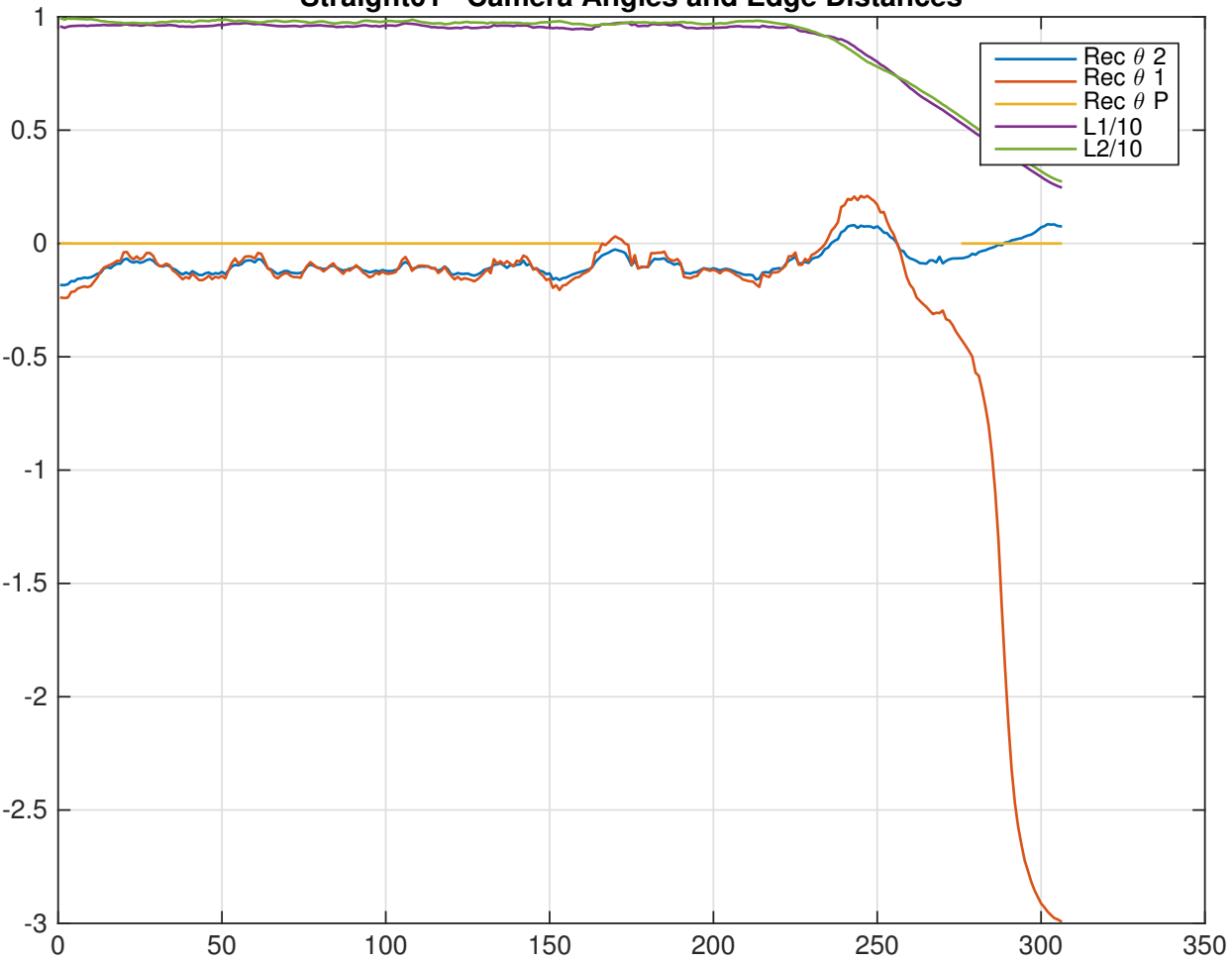
Straight01 Camera vs LIDAR Theta_1



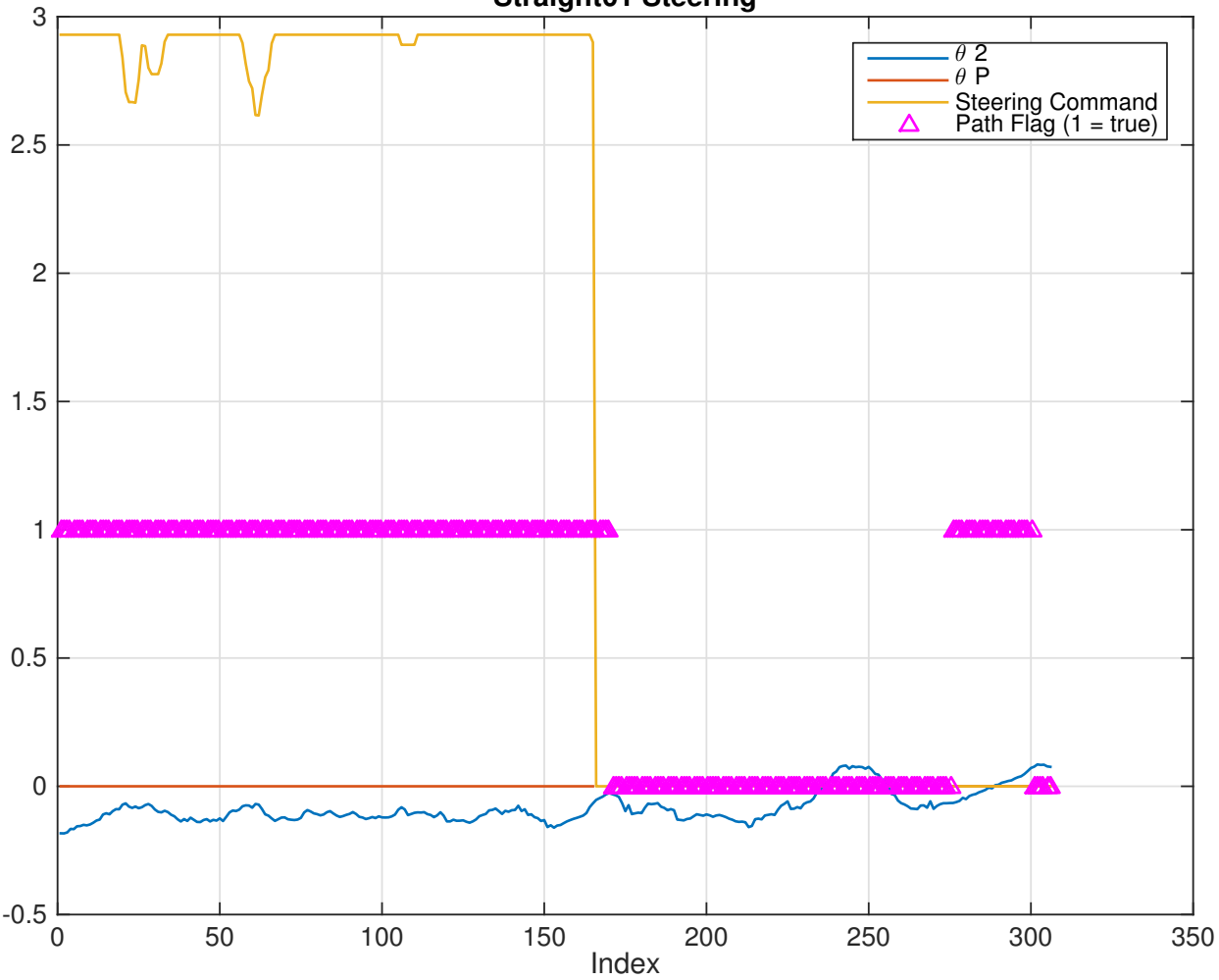
Straight01 Camera vs LIDAR Theta_2



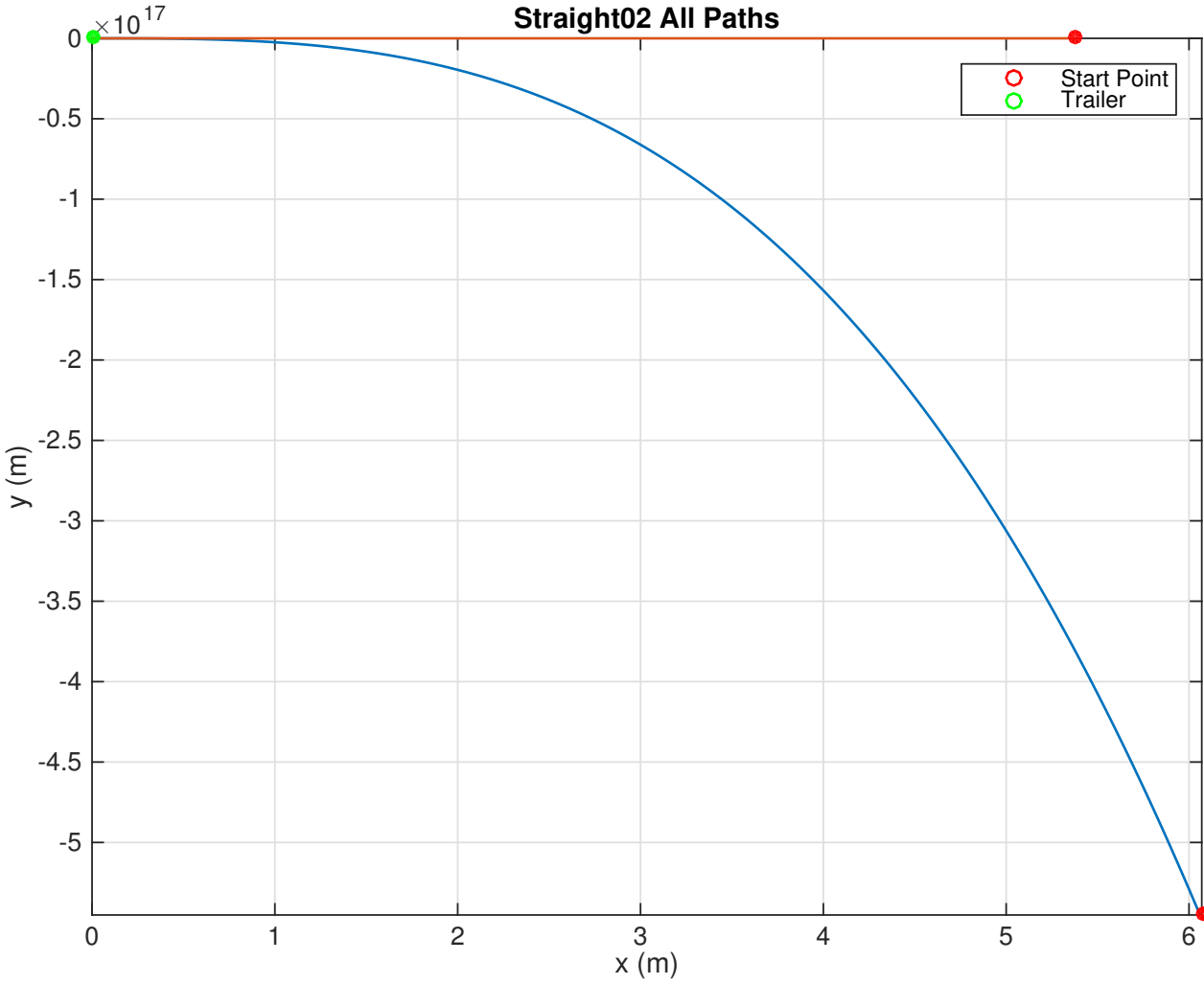
Straight01 Camera Angles and Edge Distances



Straight01 Steering



Straight02 All Paths



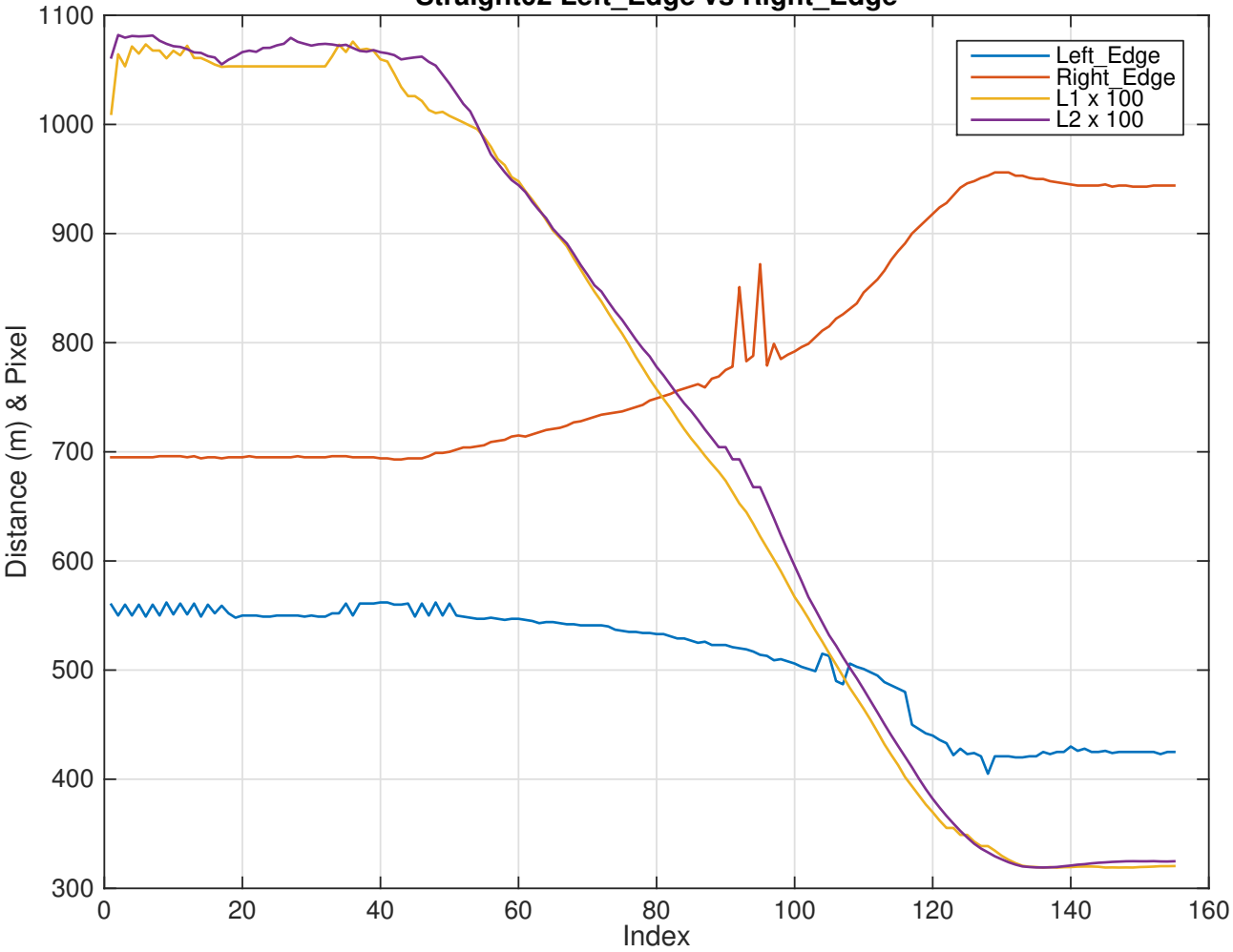
Number_Of_Unique_Paths

King_Pin_Detected

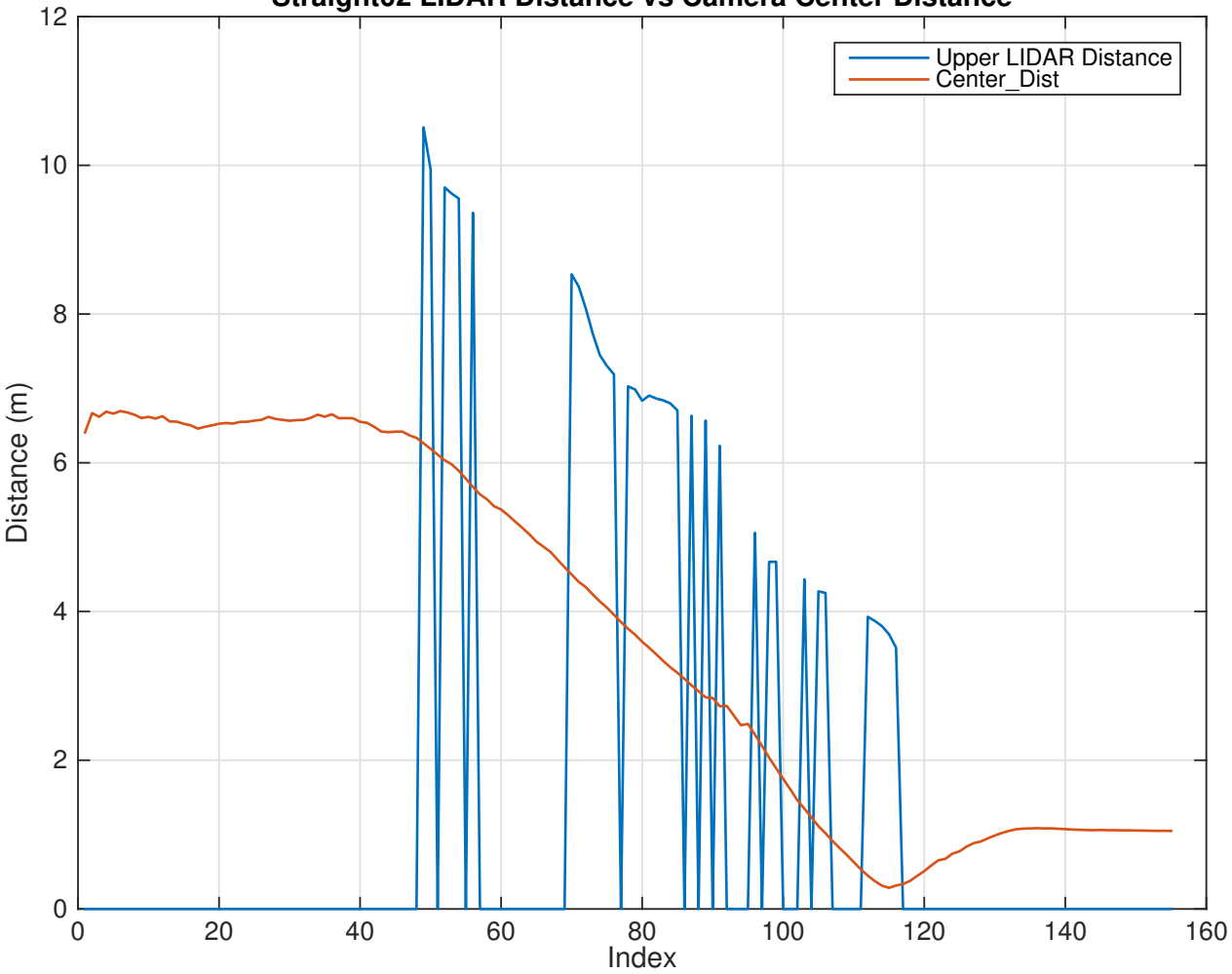
2

false

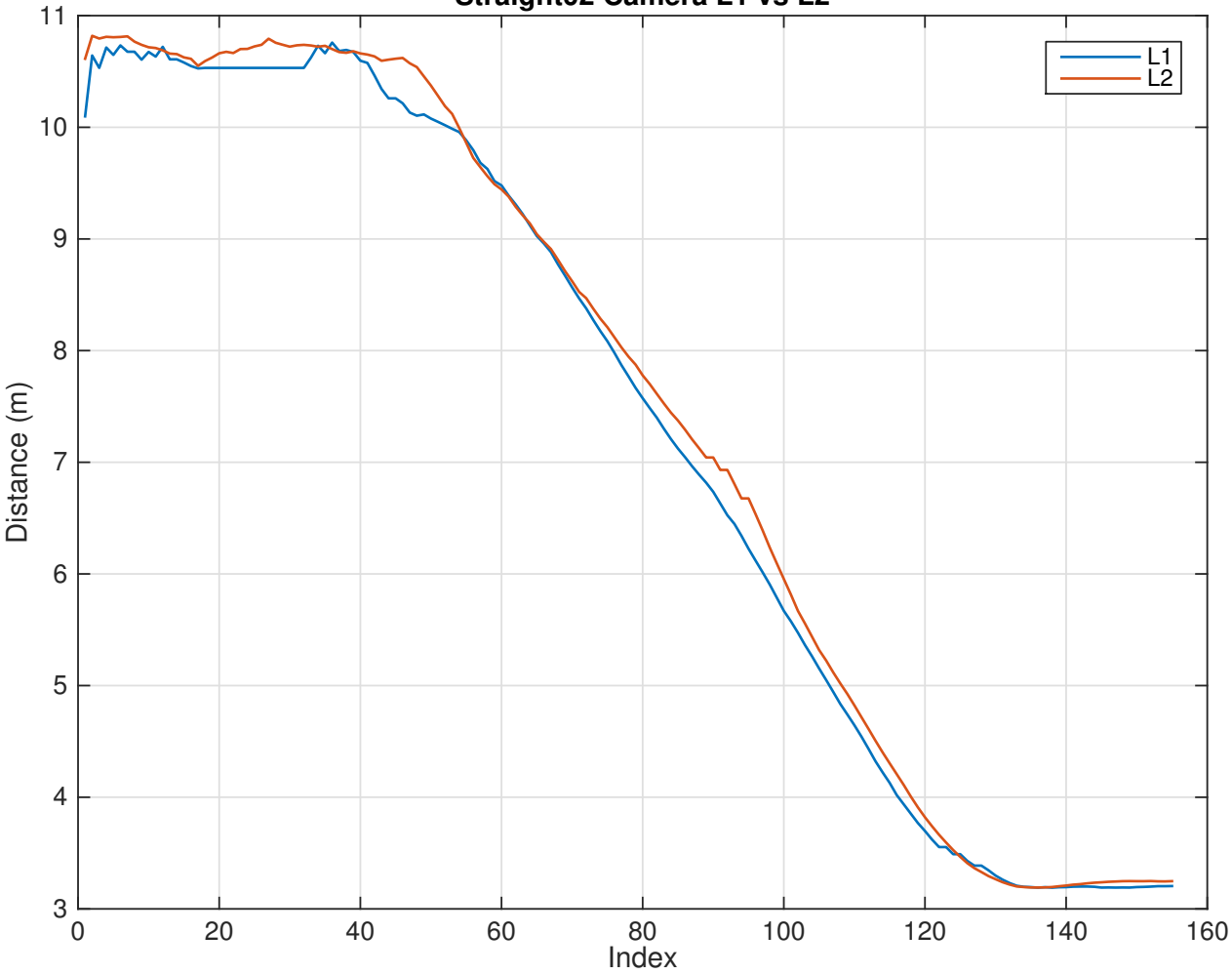
Straight02 Left_Edge vs Right_Edge



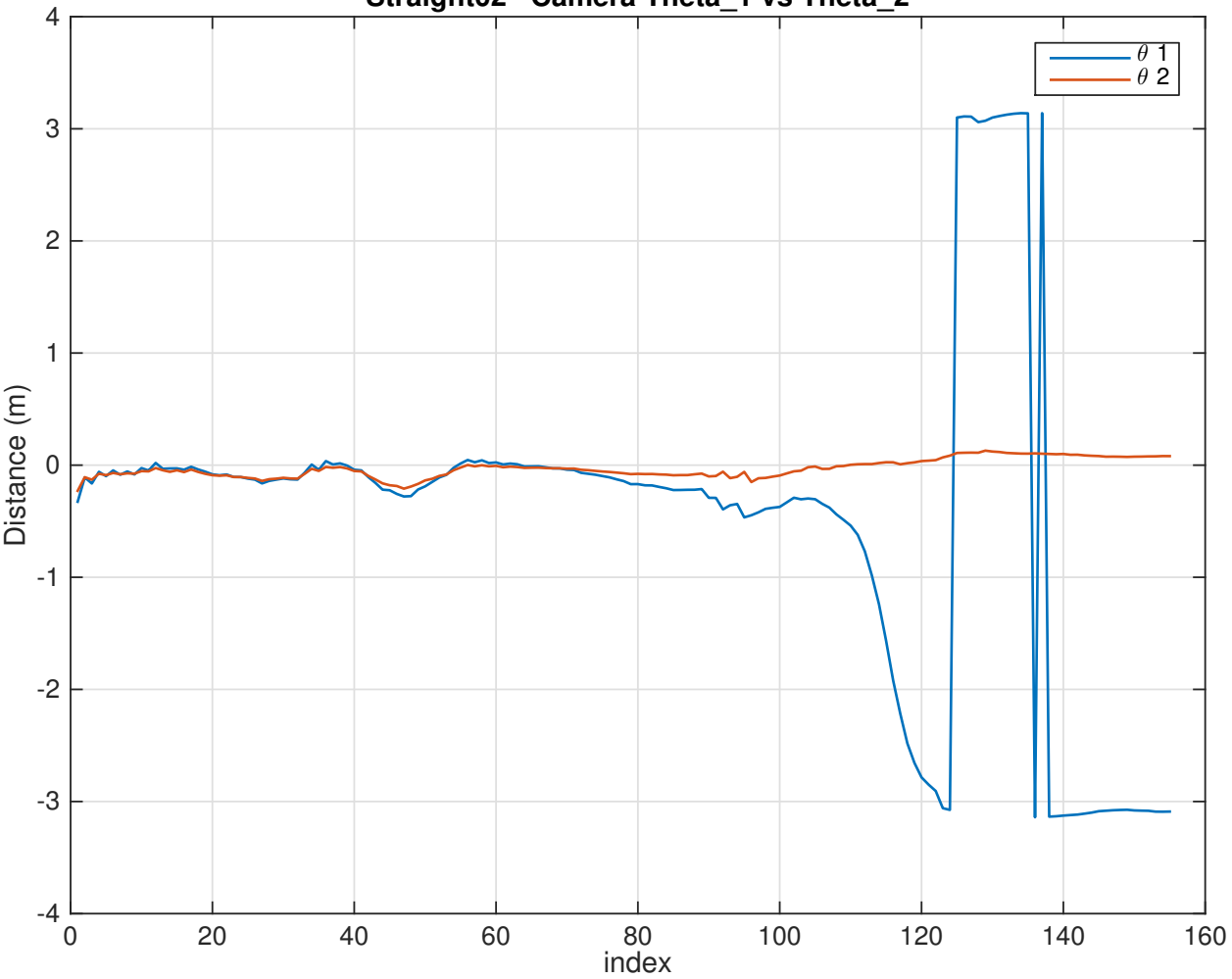
Straight02 LIDAR Distance vs Camera Center Distance



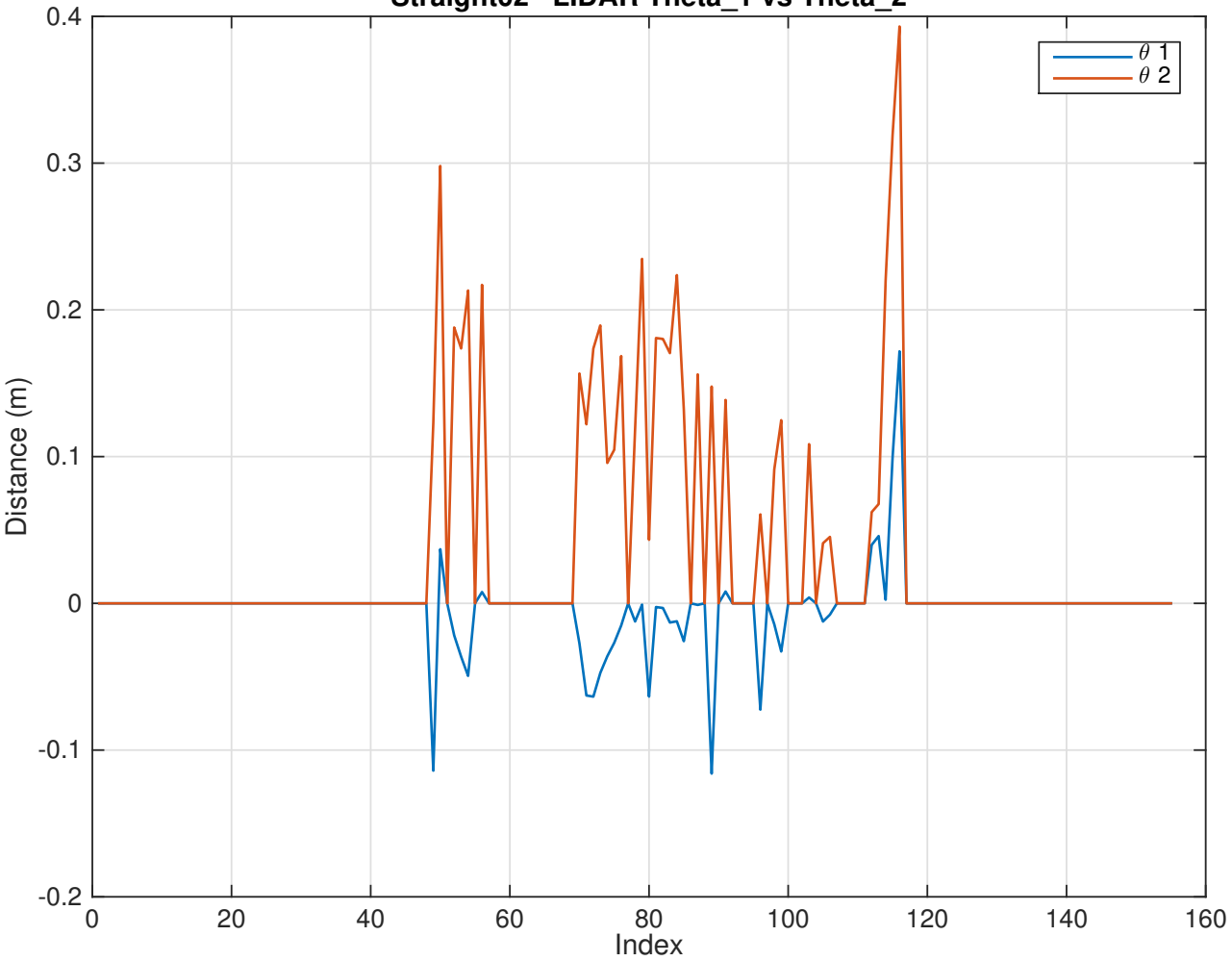
Straight02 Camera L1 vs L2



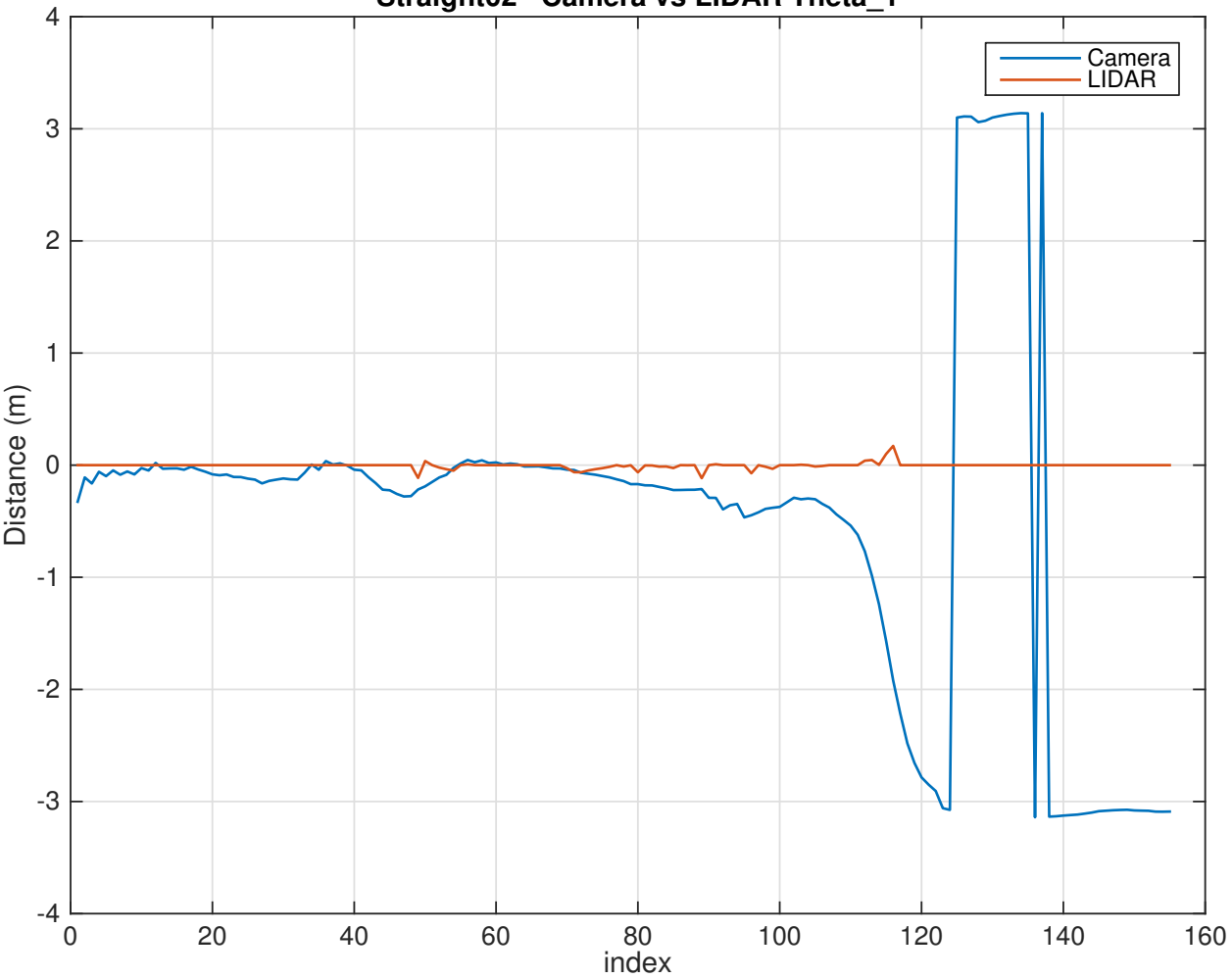
Straight02 Camera Theta_1 vs Theta_2



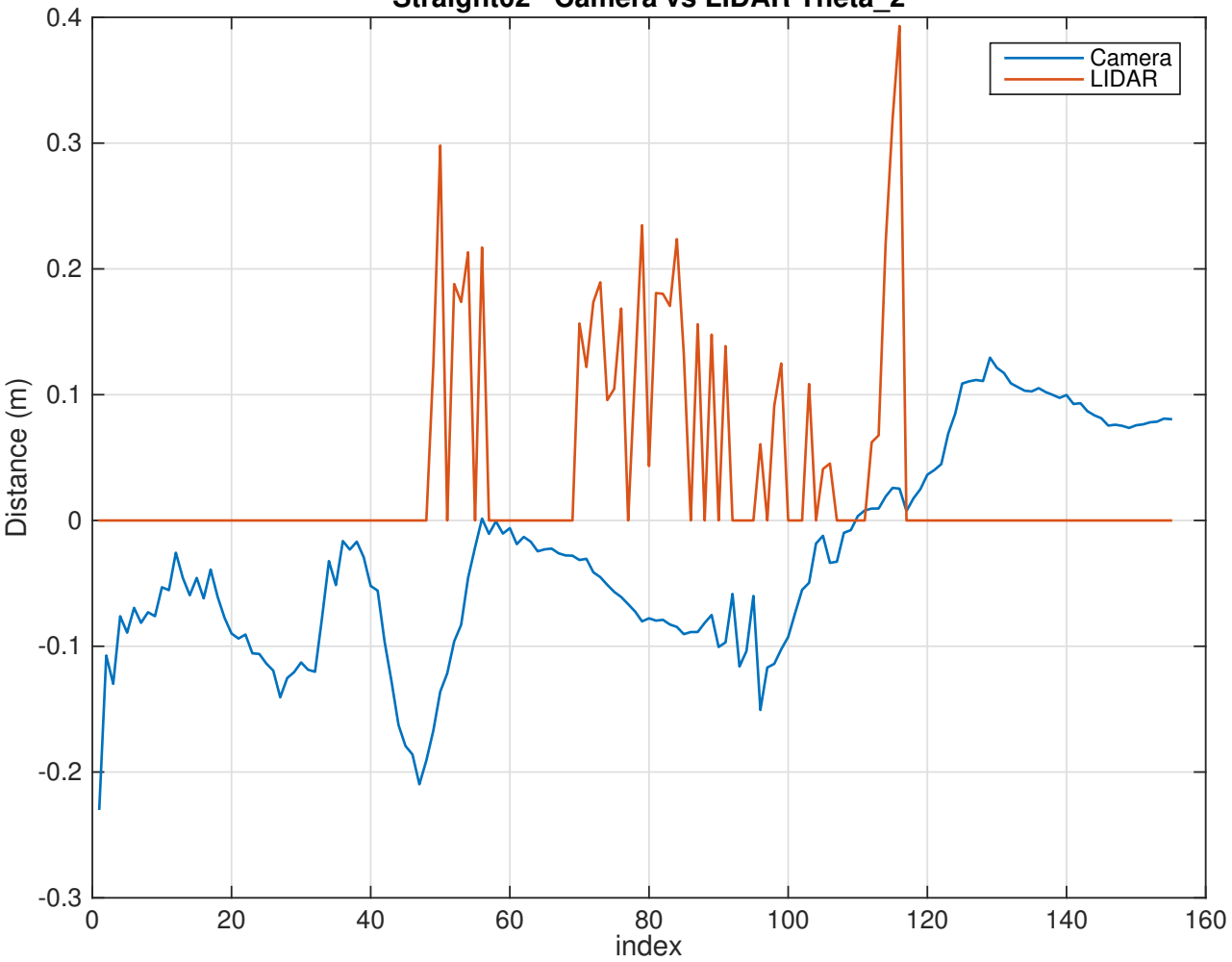
Straight02 LIDAR Theta_1 vs Theta_2



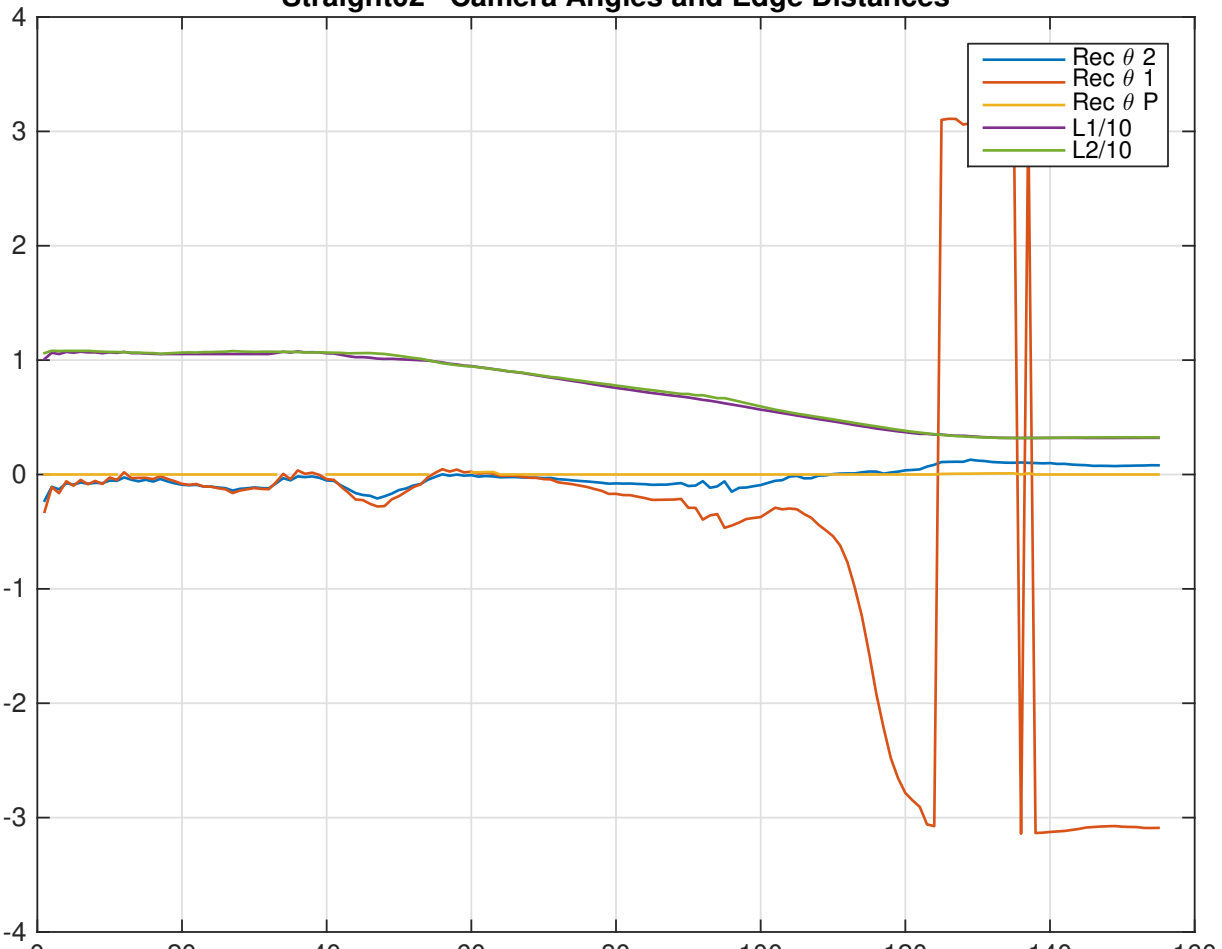
Straight02 Camera vs LIDAR Theta_1



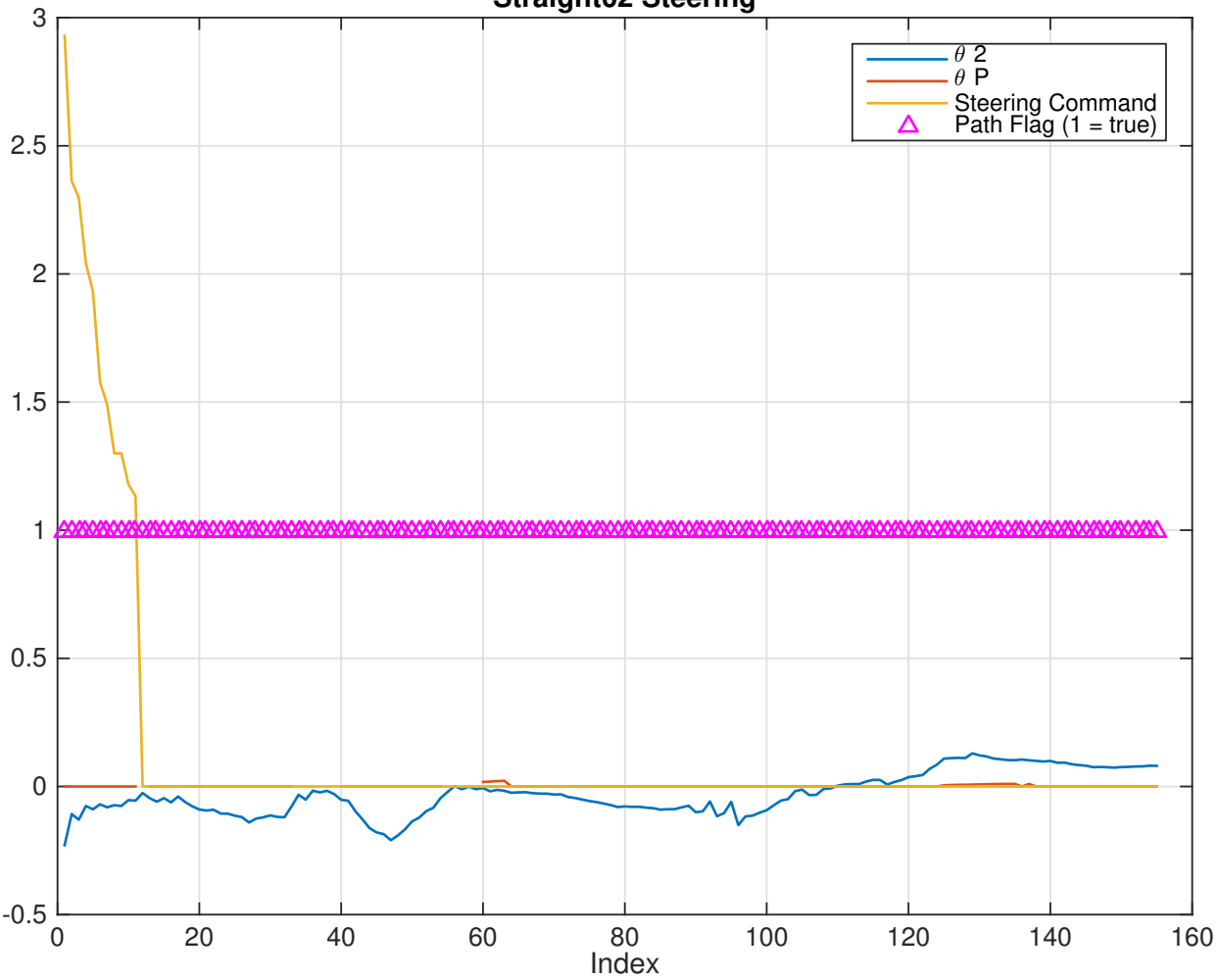
Straight02 Camera vs LIDAR Theta_2

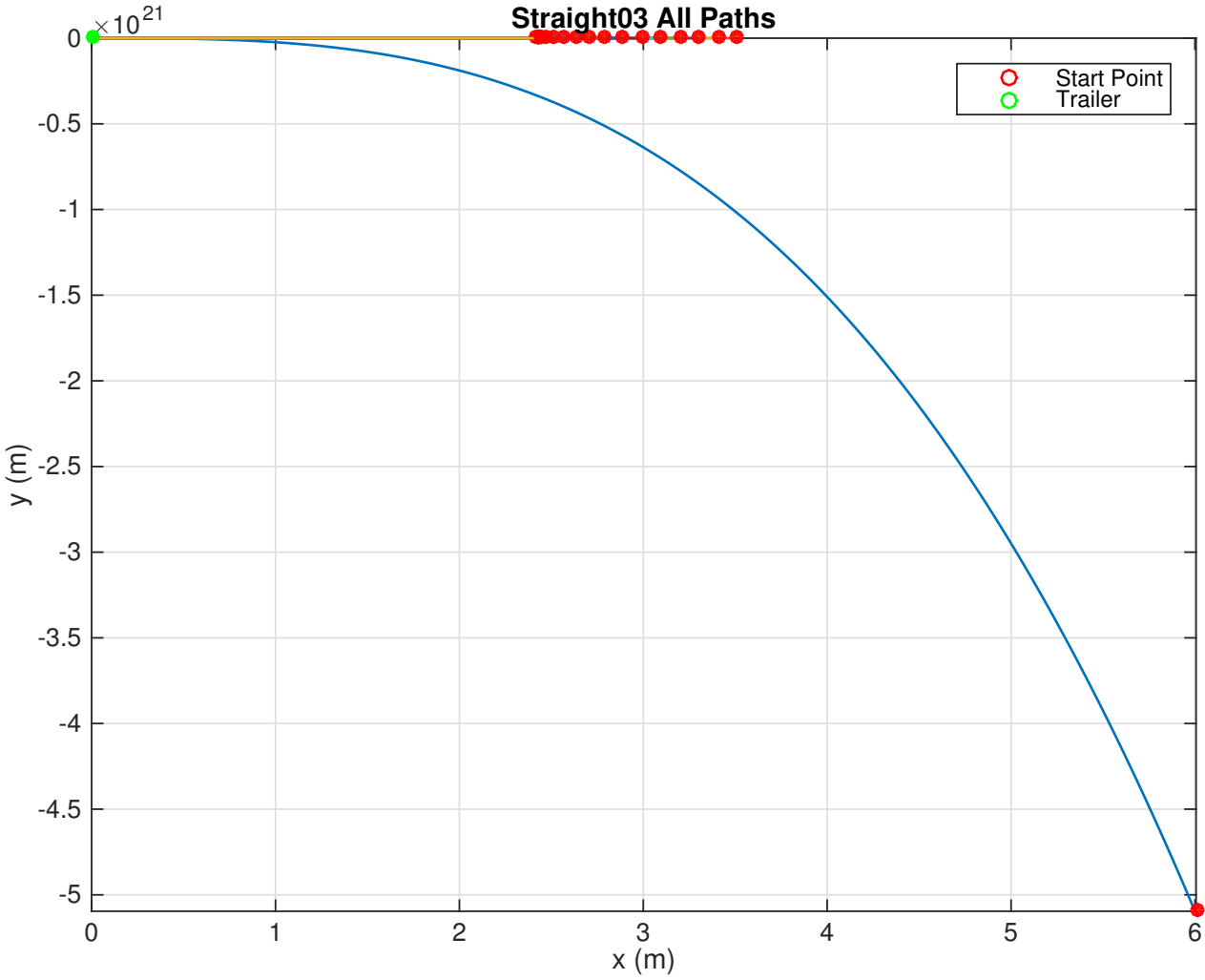


Straight02 Camera Angles and Edge Distances



Straight02 Steering





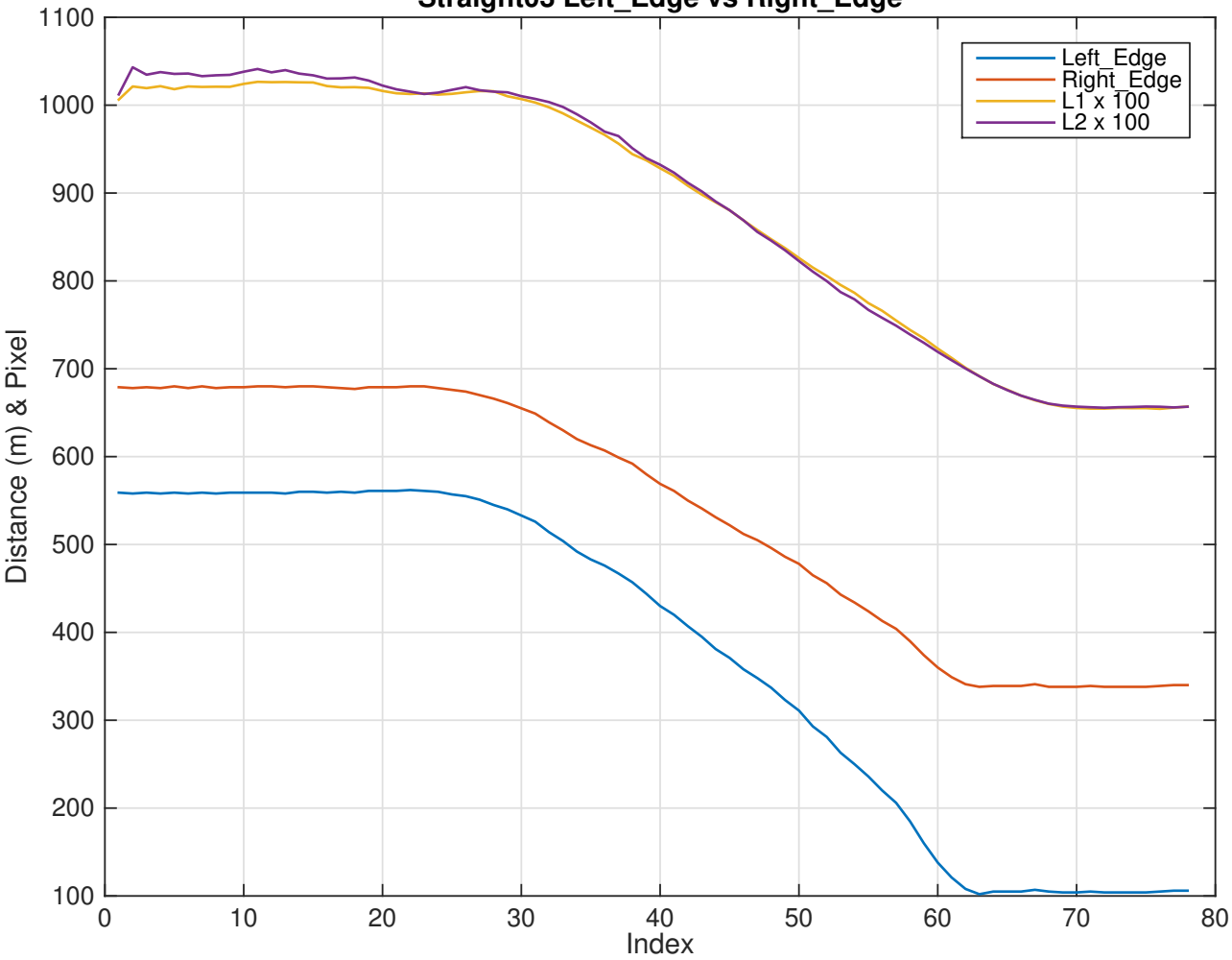
Number_Of_Unique_Paths

King_Pin_Detected

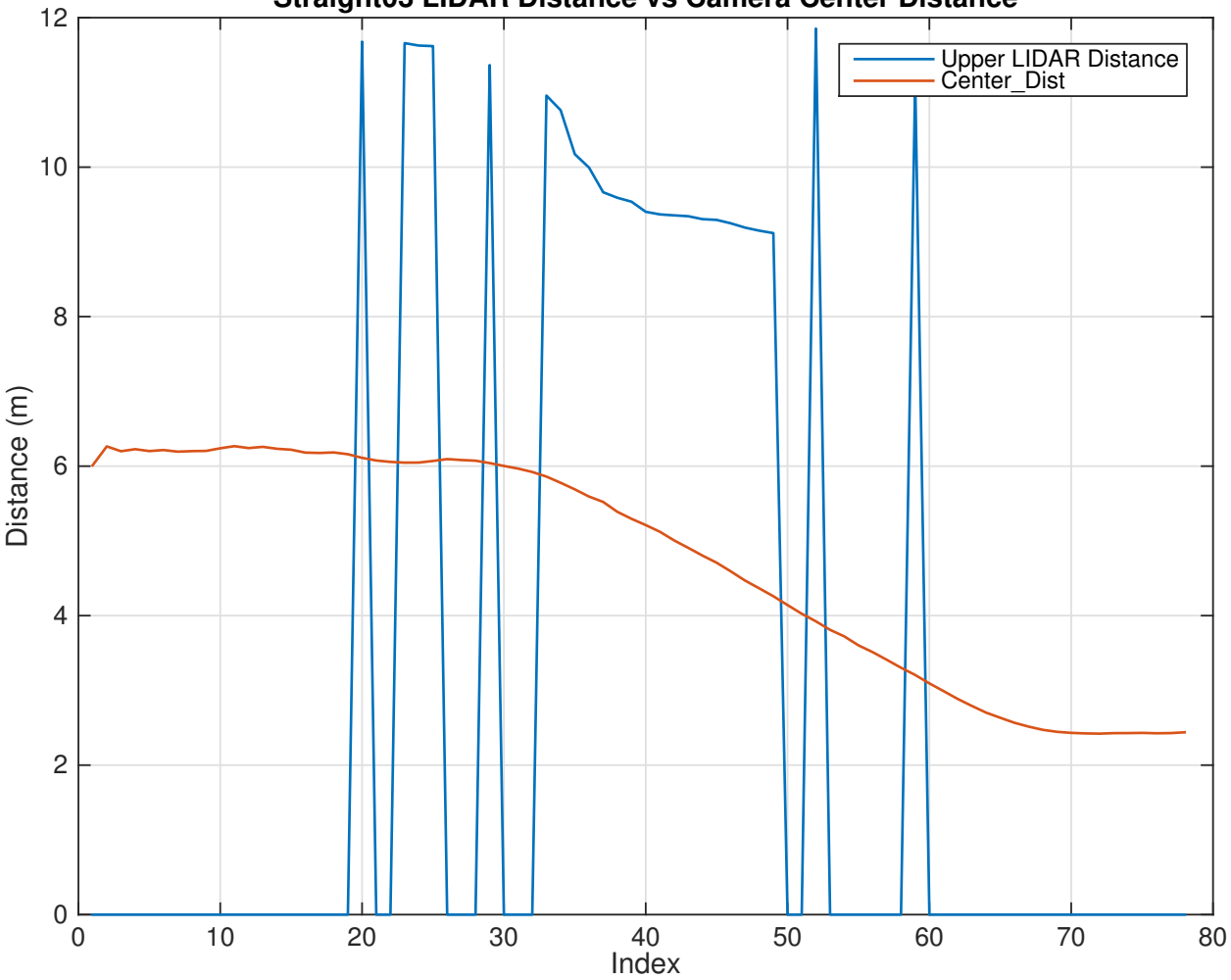
24

false

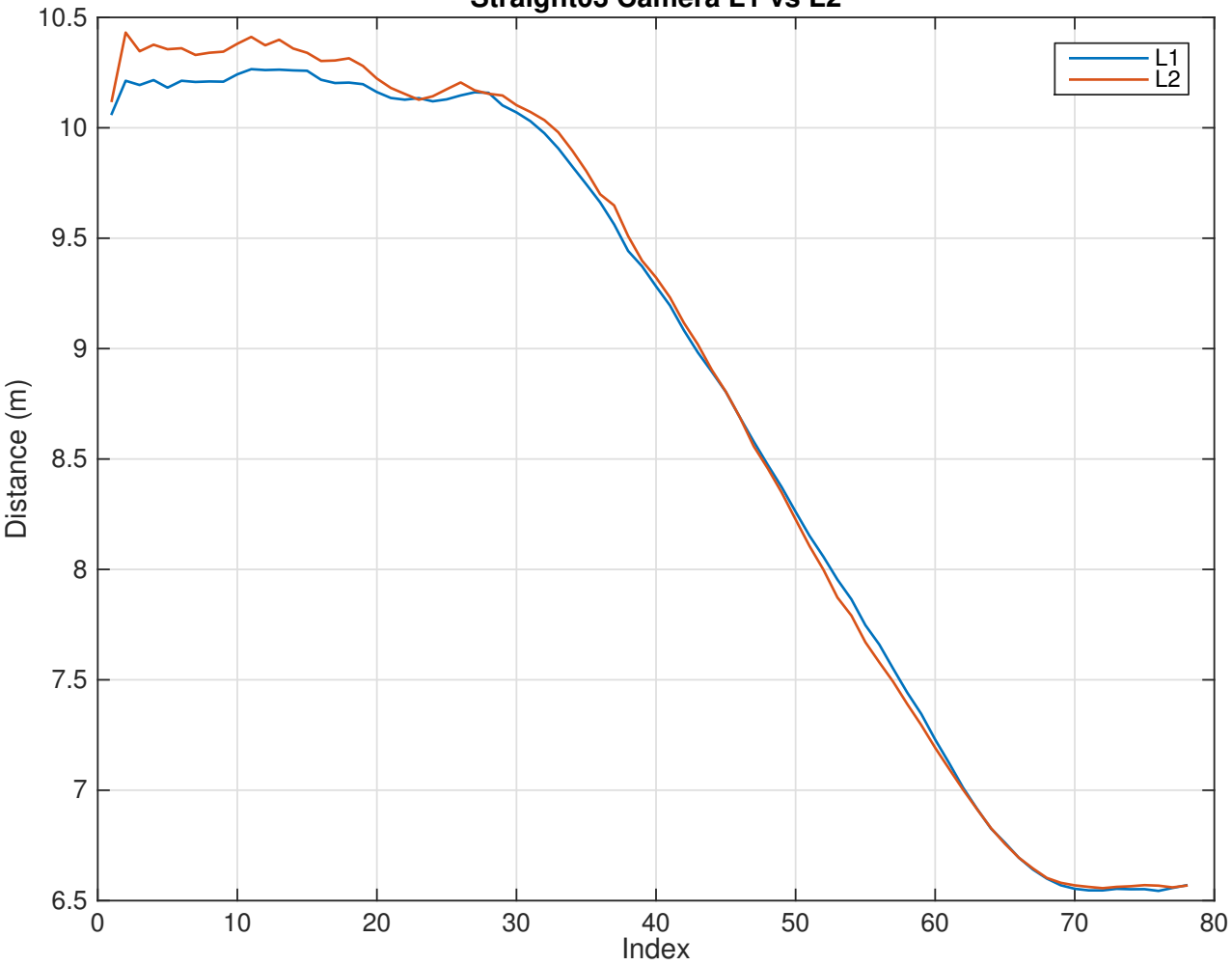
Straight03 Left_Edge vs Right_Edge



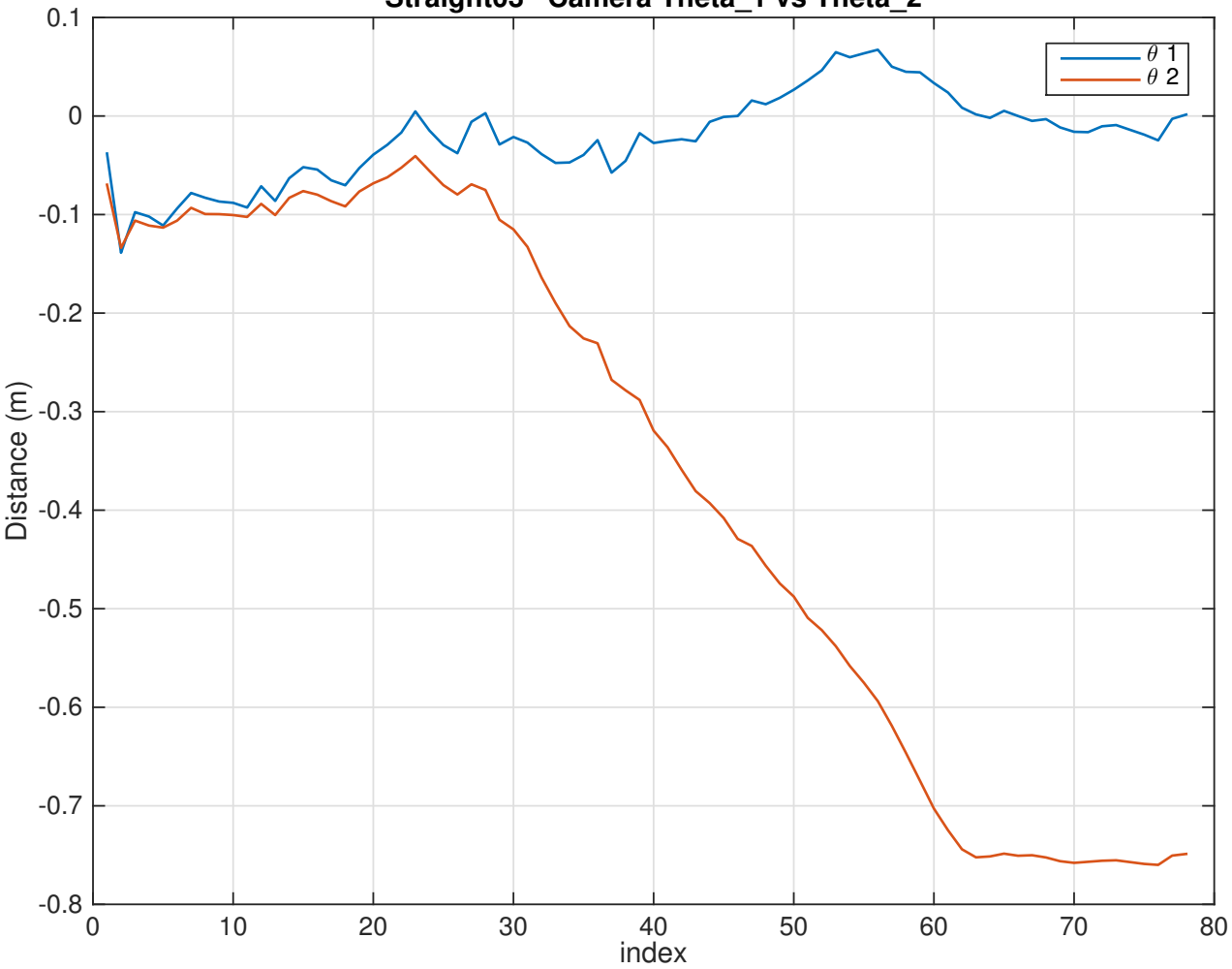
Straight03 LIDAR Distance vs Camera Center Distance



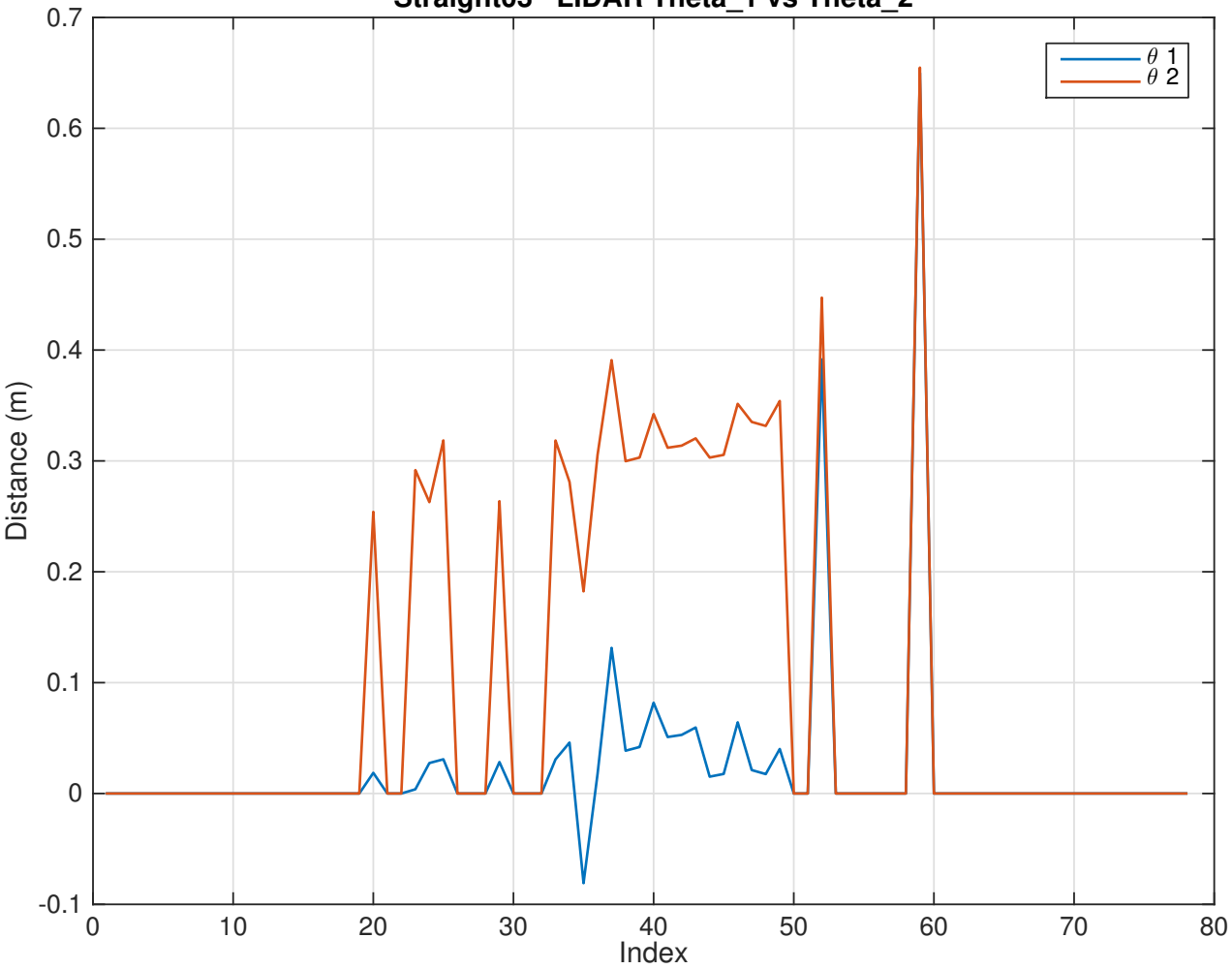
Straight03 Camera L1 vs L2



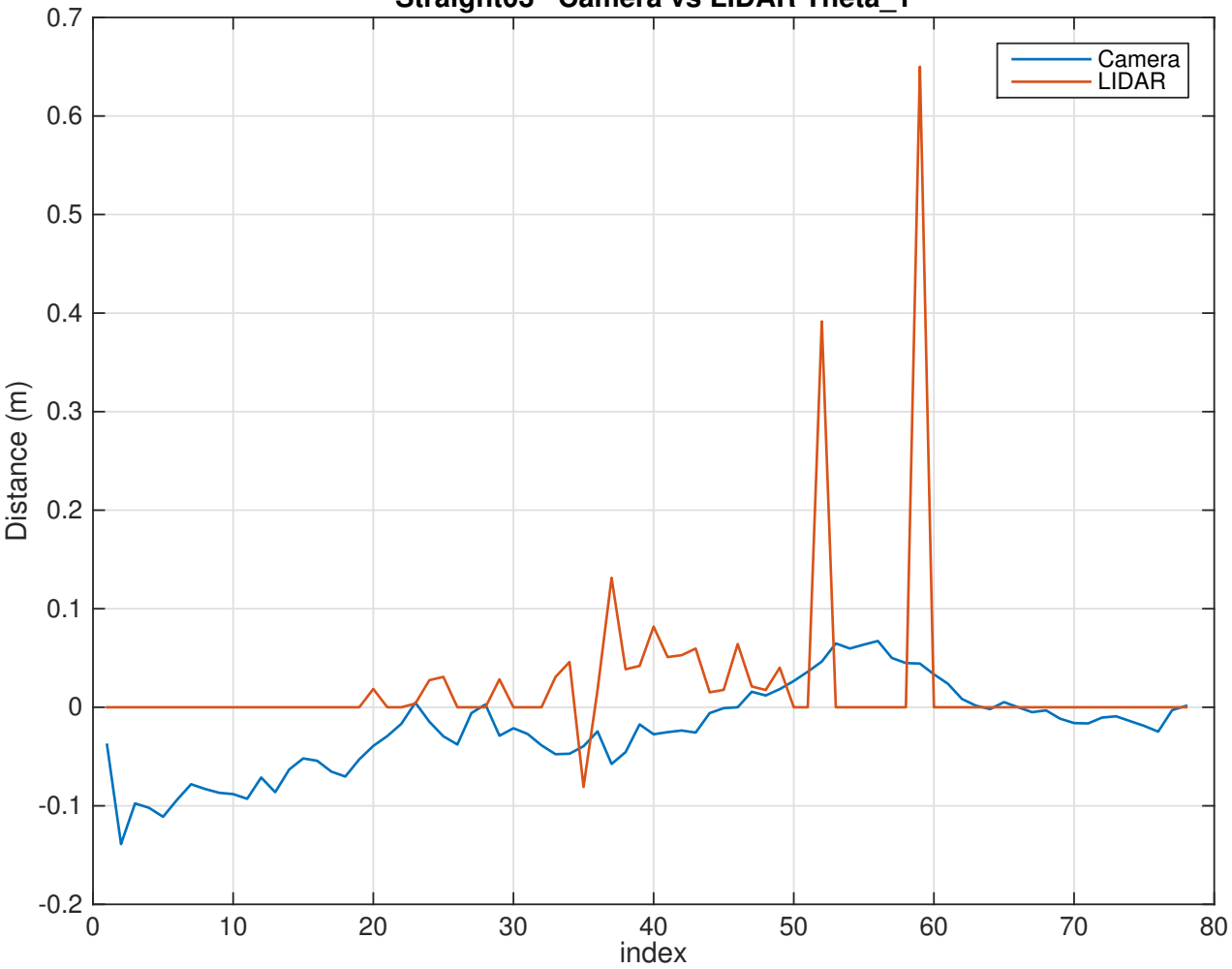
Straight03 Camera Theta_1 vs Theta_2



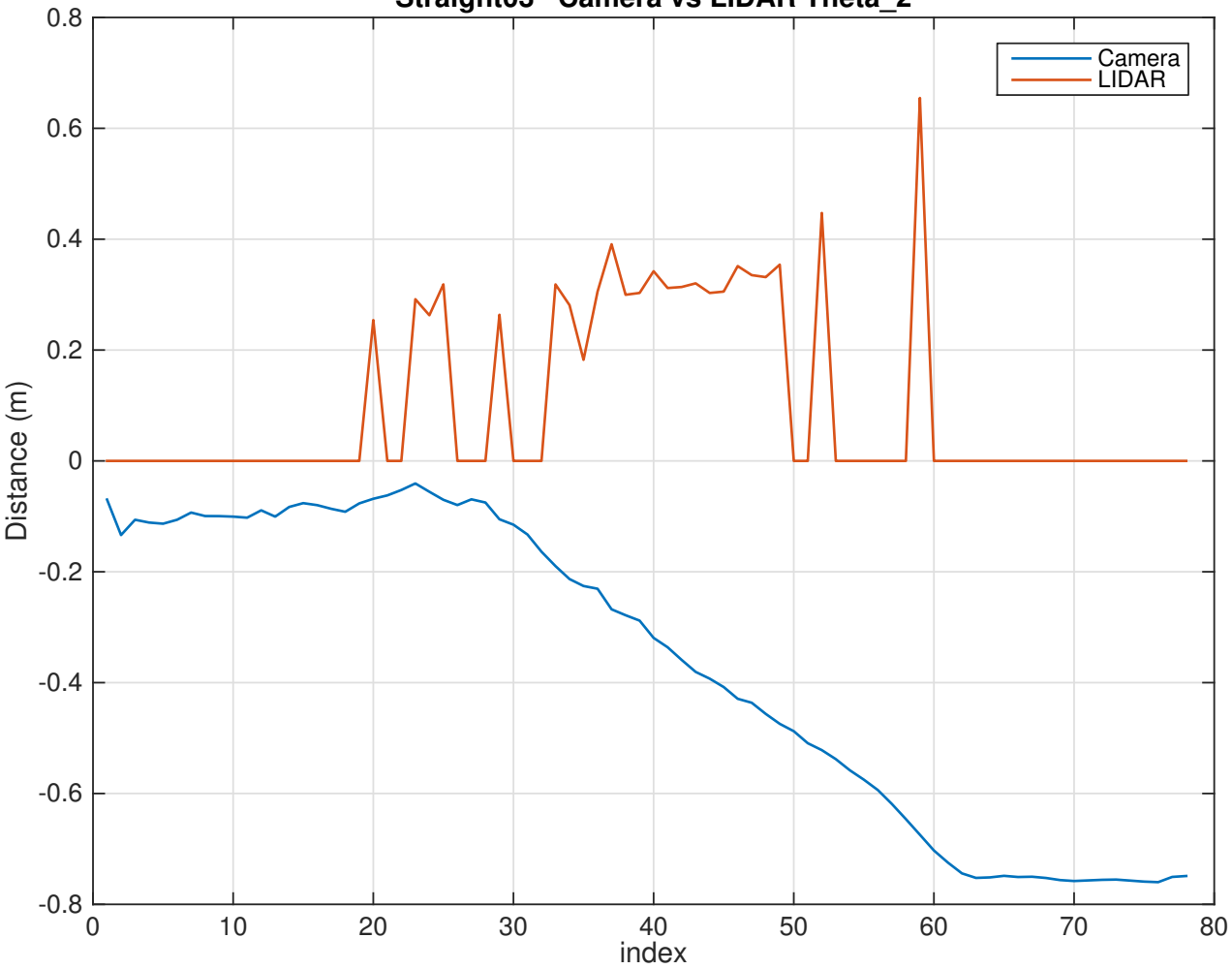
Straight03 LIDAR Theta_1 vs Theta_2



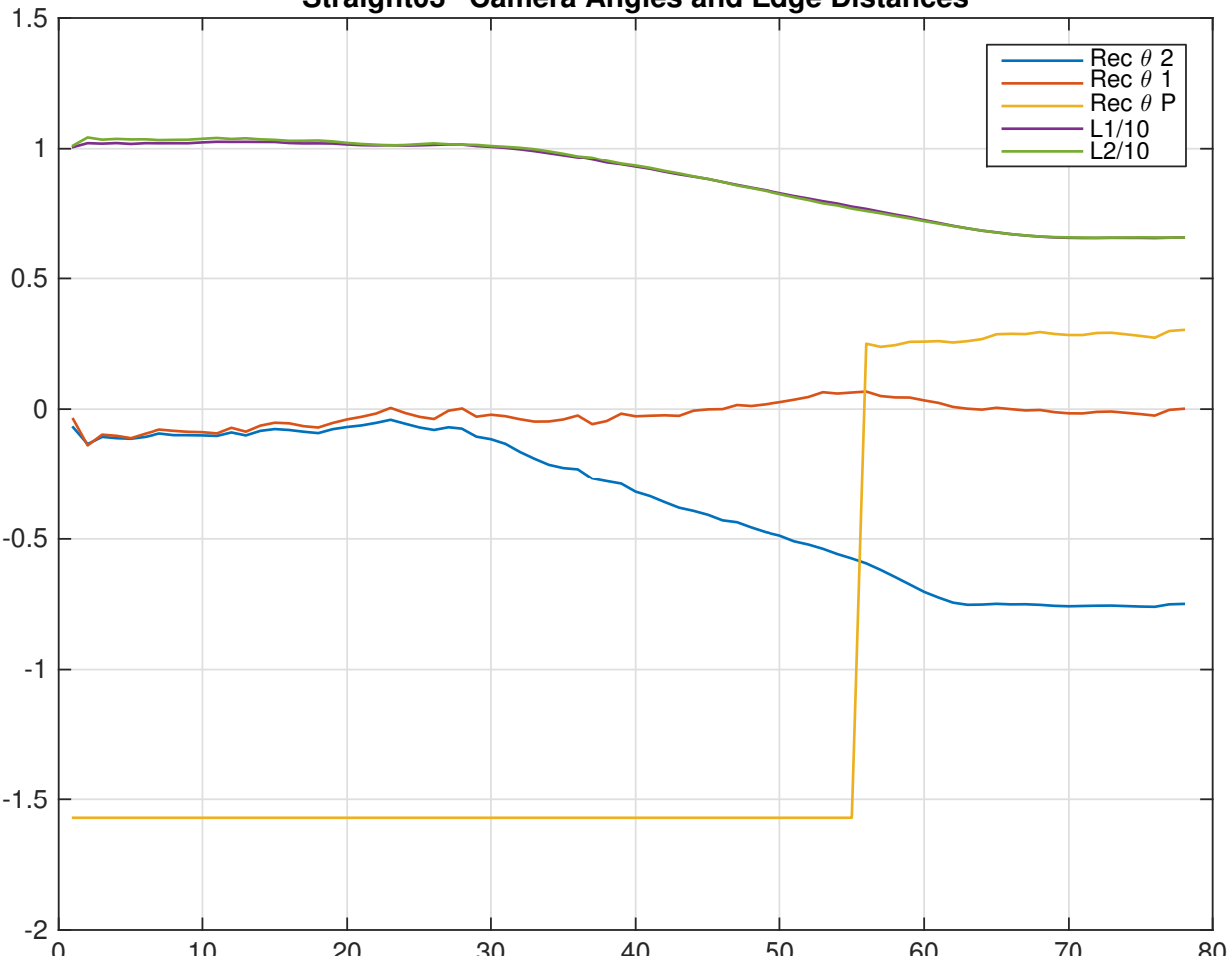
Straight03 Camera vs LIDAR Theta_1



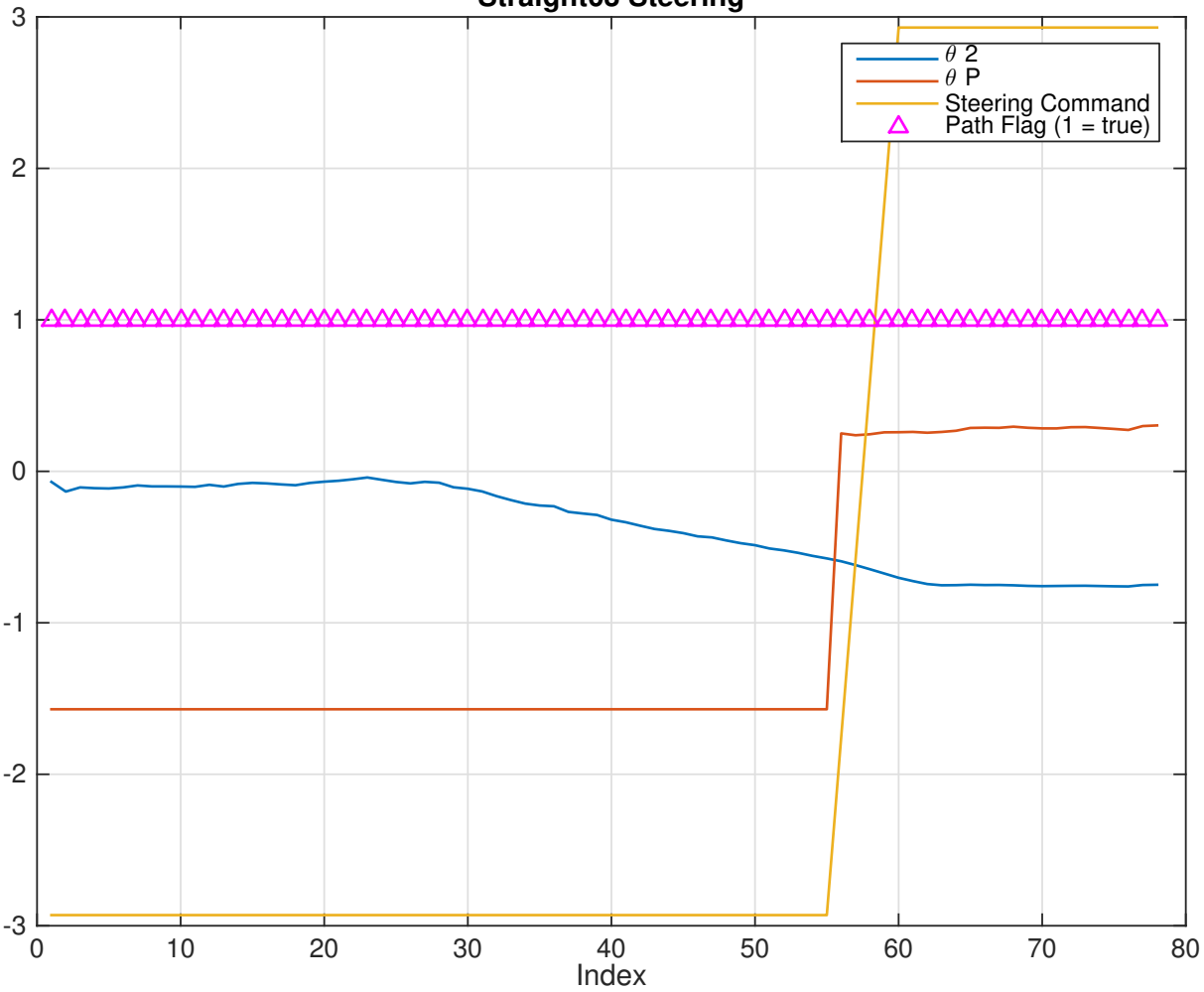
Straight03 Camera vs LIDAR Theta_2

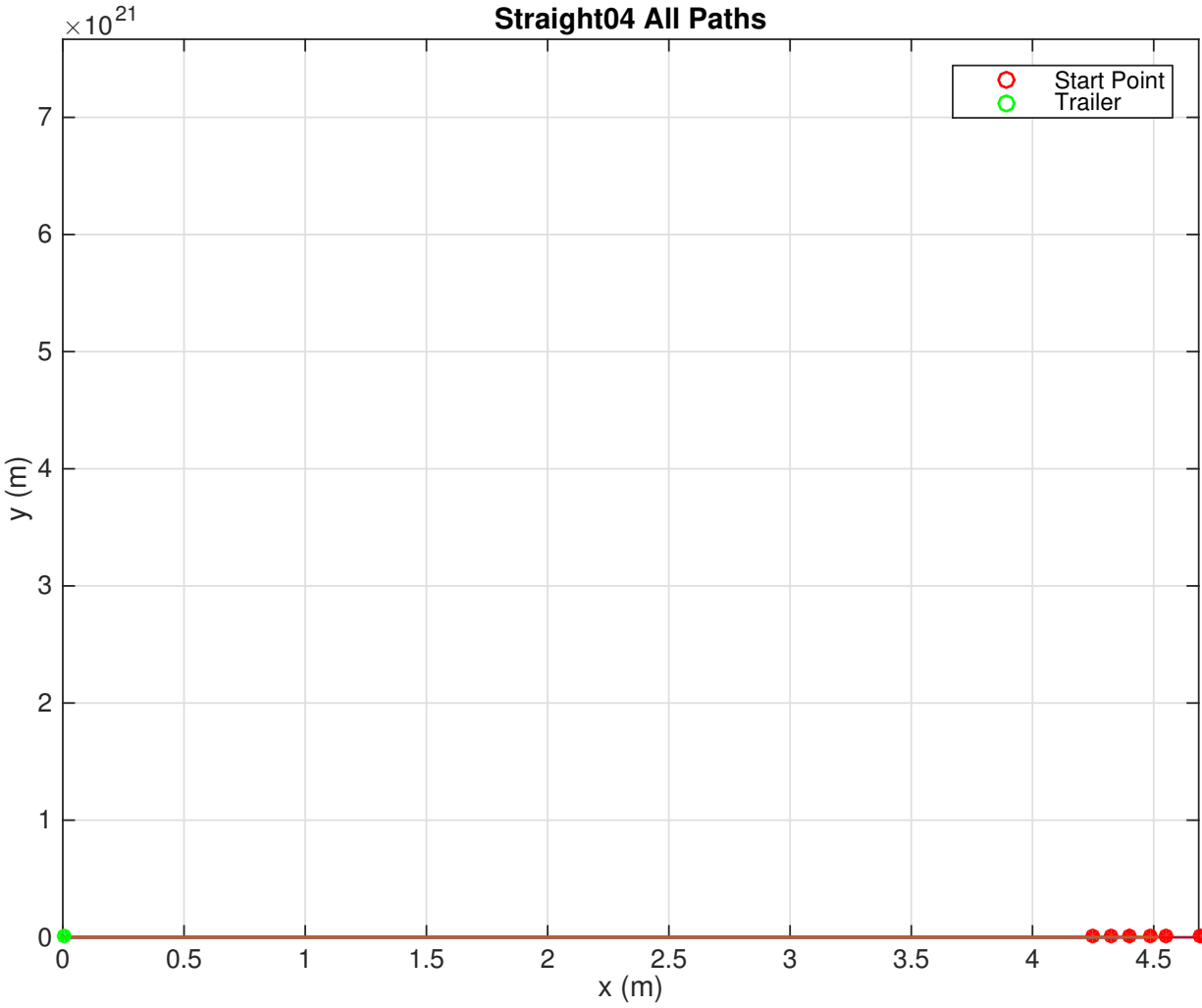


Straight03 Camera Angles and Edge Distances



Straight03 Steering





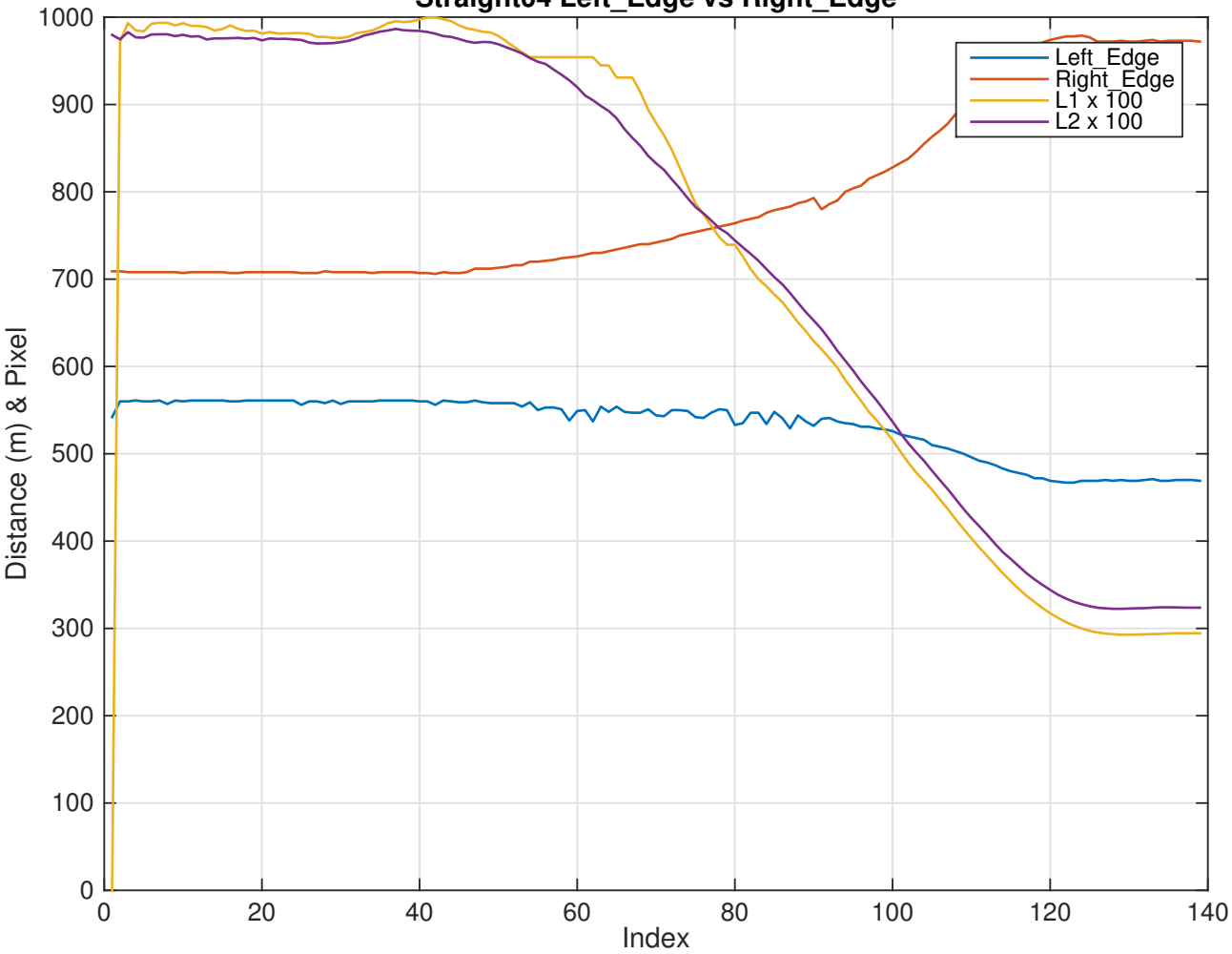
Number_Of_Unique_Paths

King_Pin_Detected

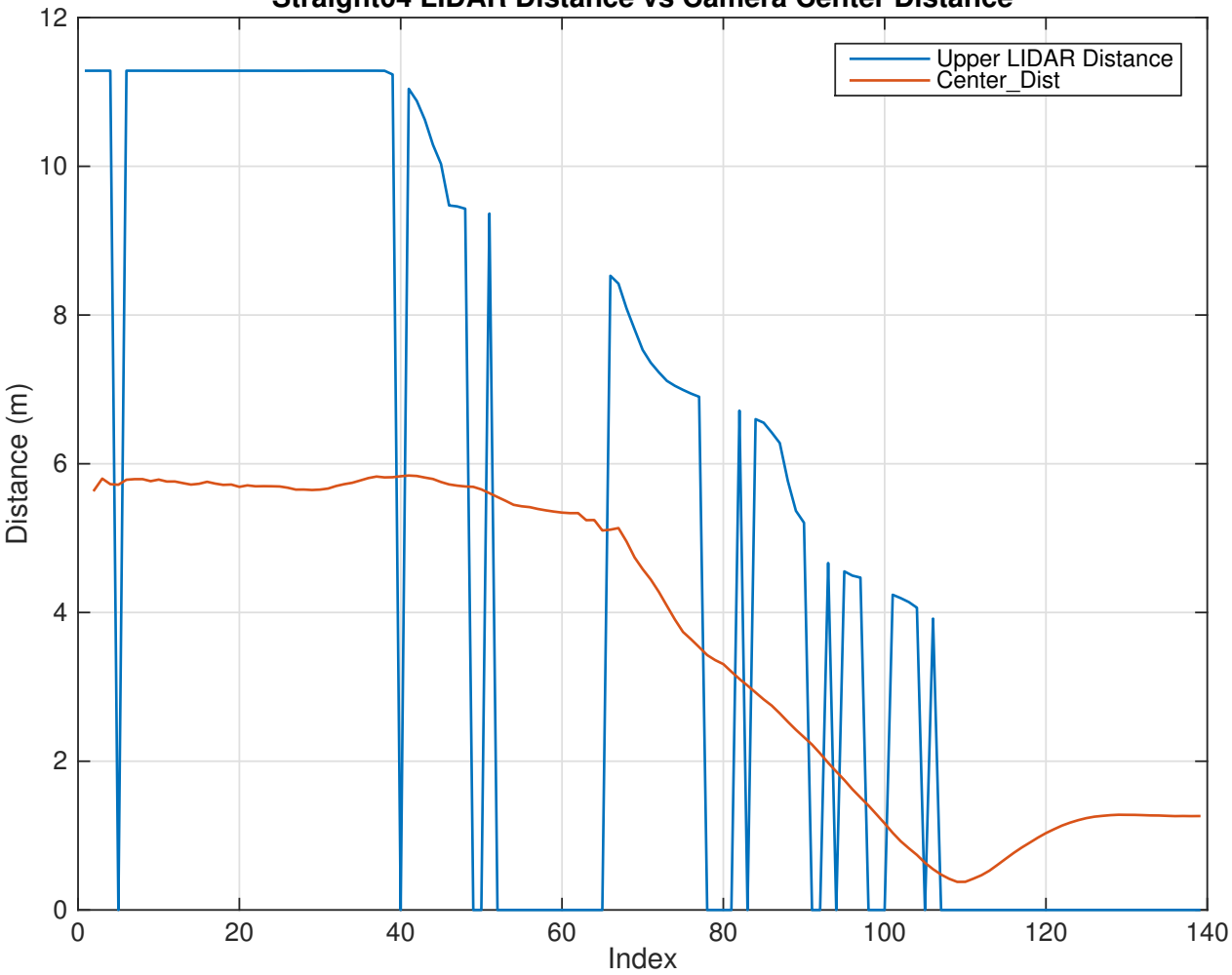
30

false

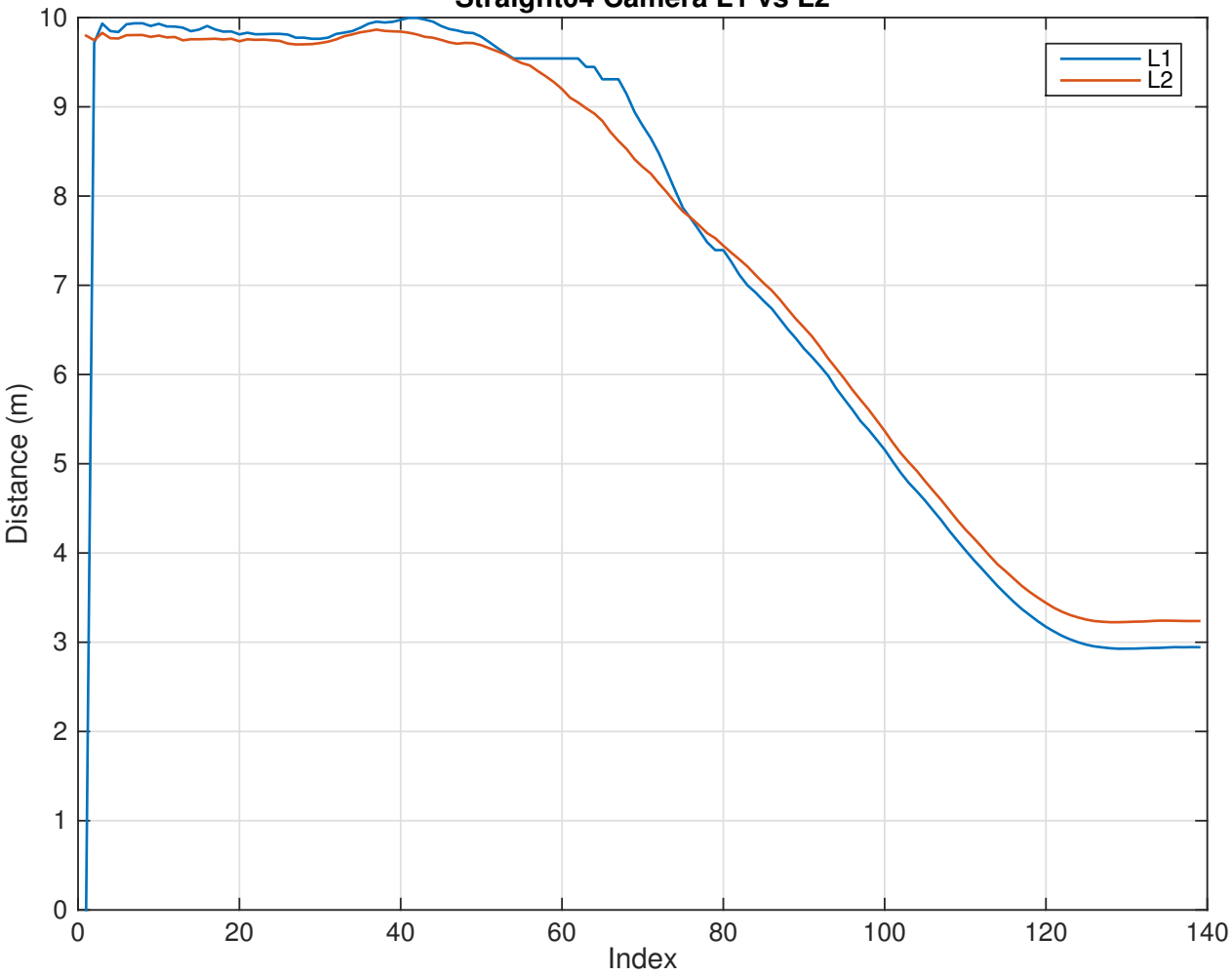
Straight04 Left_Edge vs Right_Edge



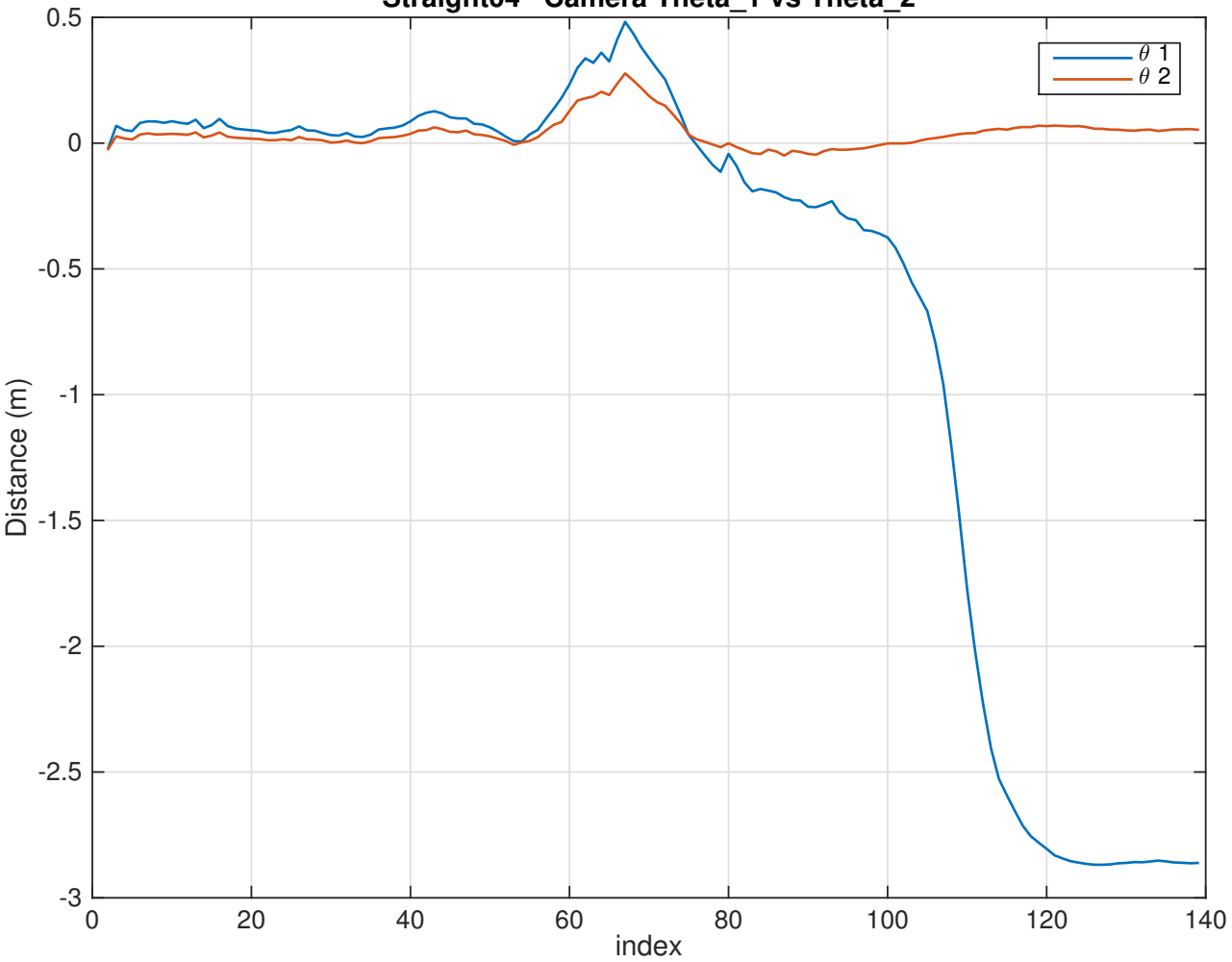
Straight04 LIDAR Distance vs Camera Center Distance



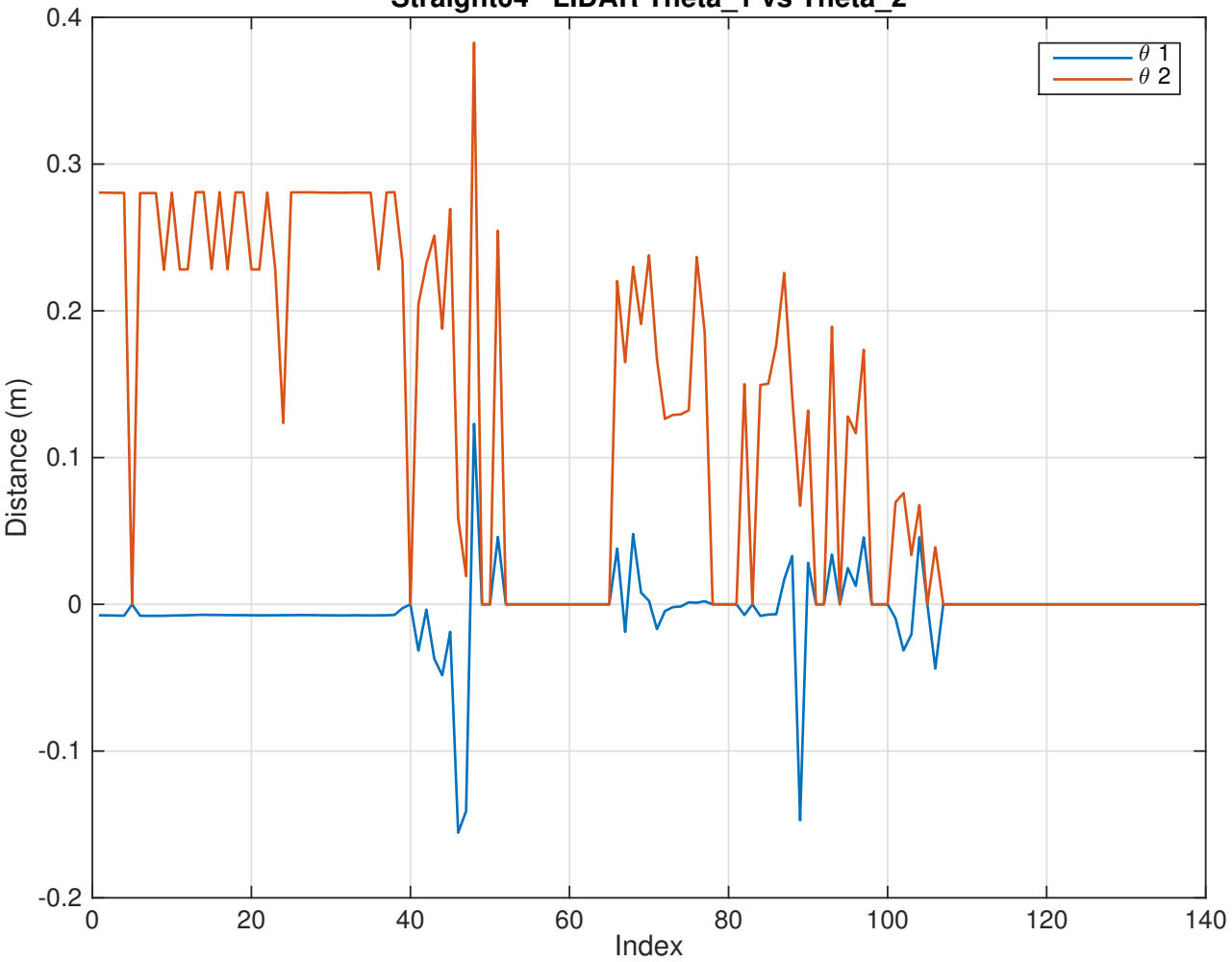
Straight04 Camera L1 vs L2



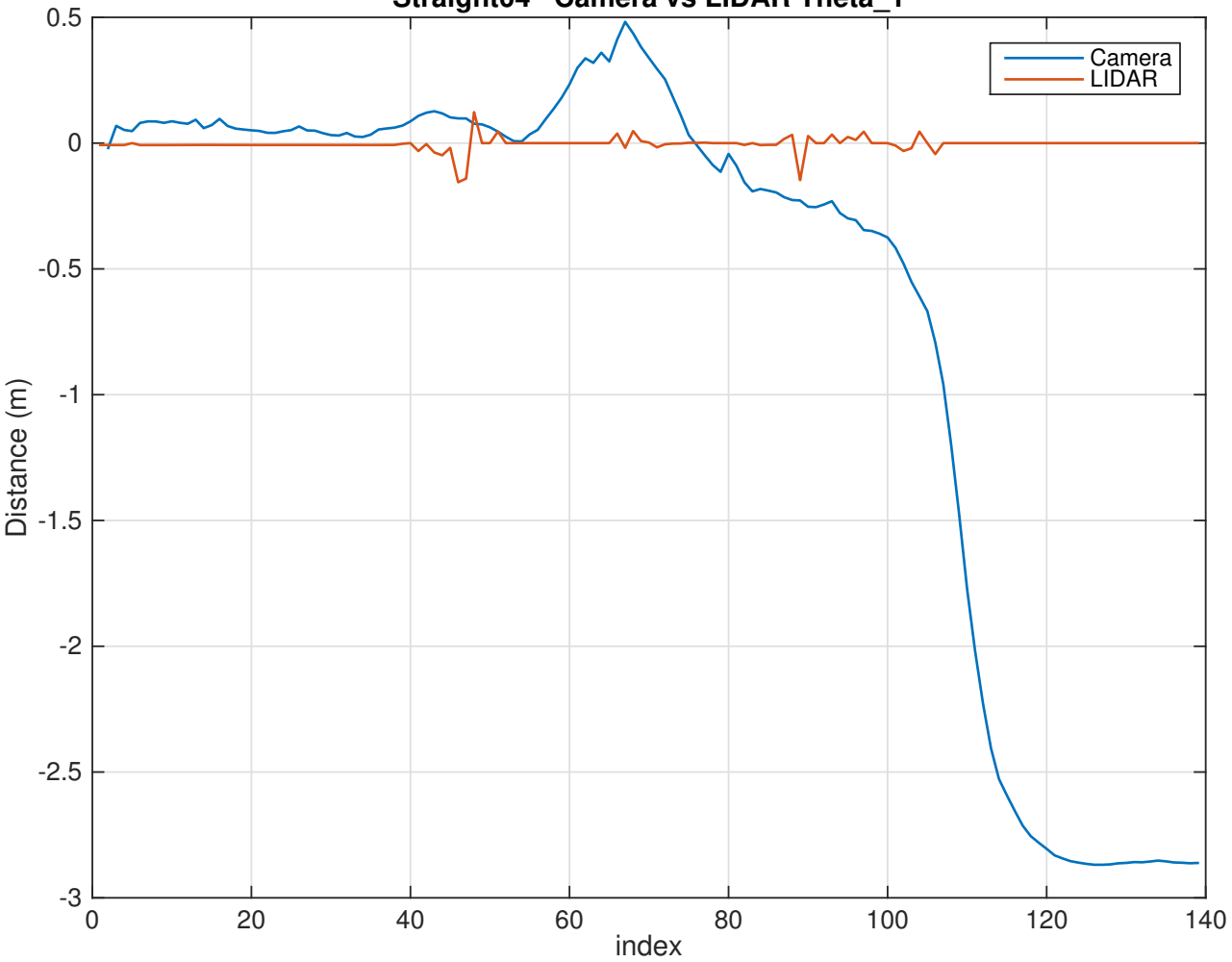
Straight04 Camera Theta_1 vs Theta_2



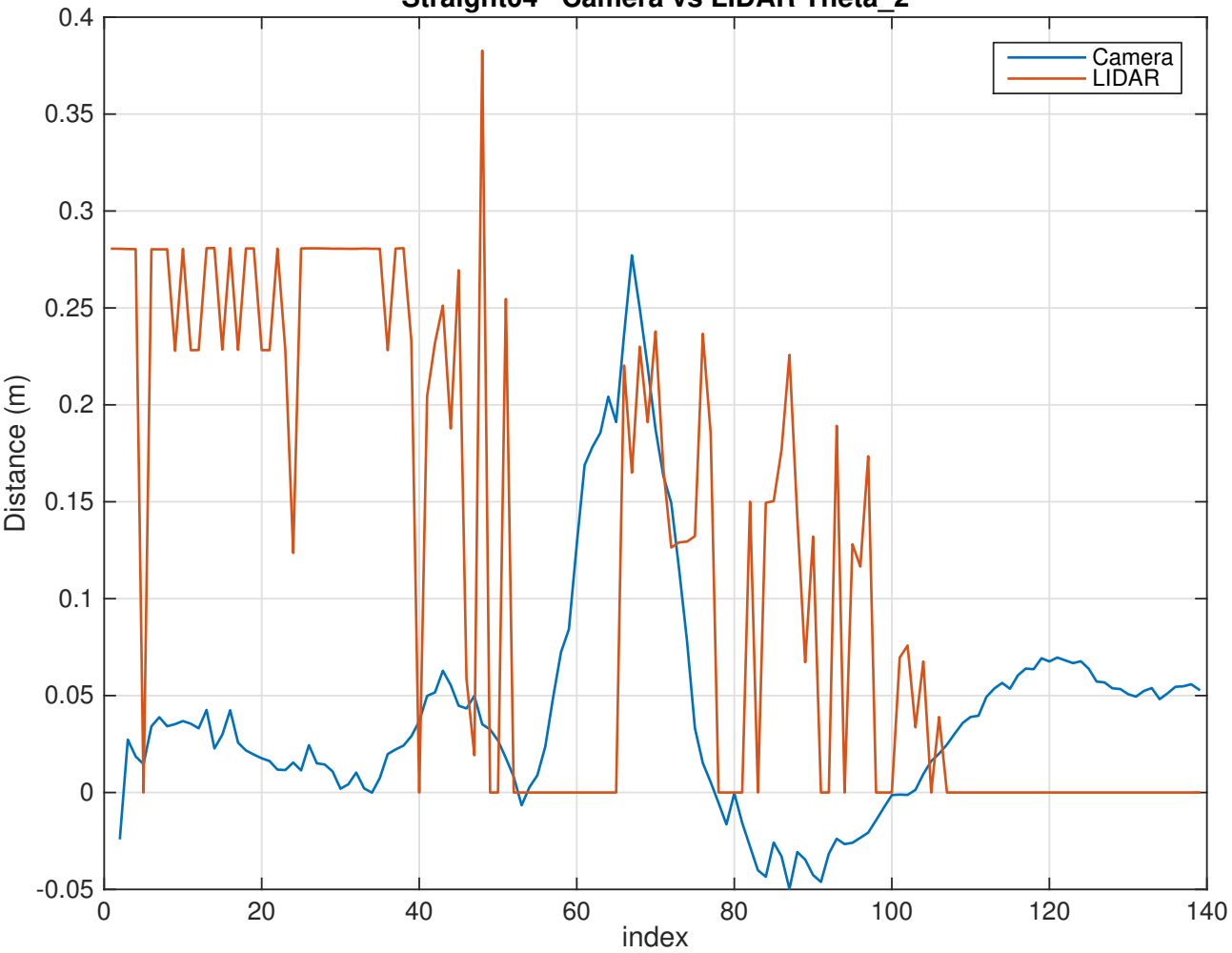
Straight04 LIDAR Theta_1 vs Theta_2



Straight04 Camera vs LIDAR Theta_1



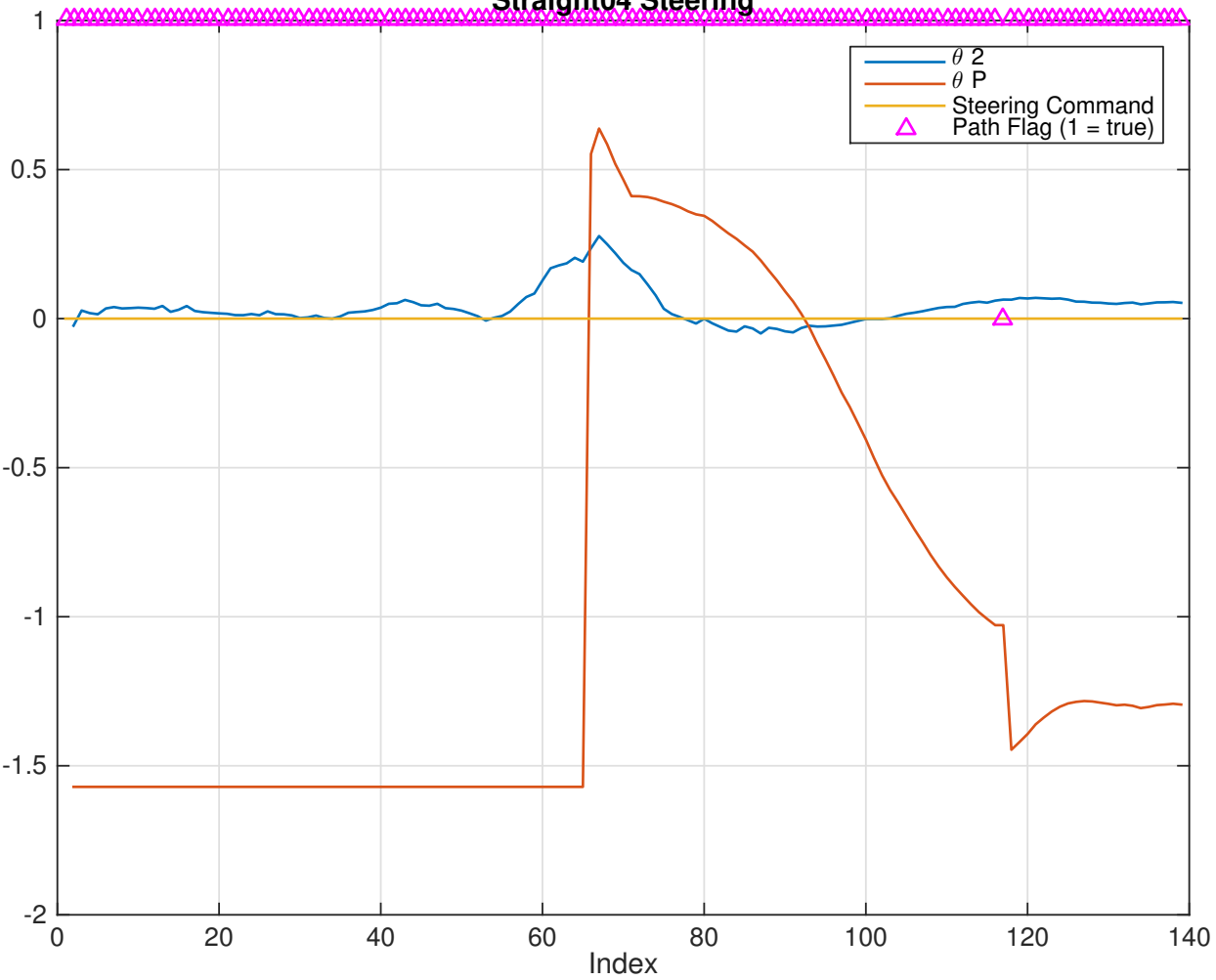
Straight04 Camera vs LIDAR Theta_2



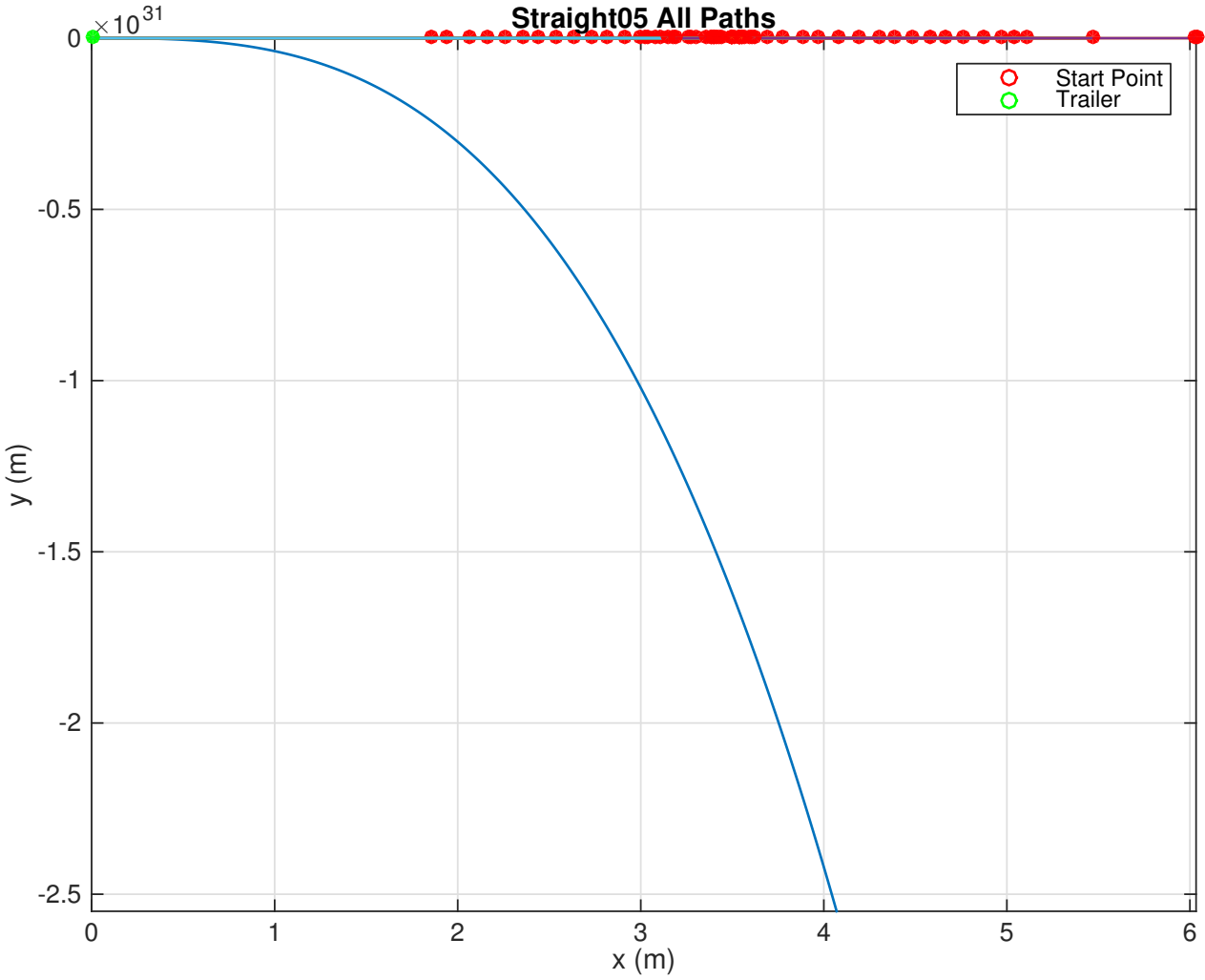
Straight04 Camera Angles and Edge Distances



Straight04 Steering



Straight05 All Paths



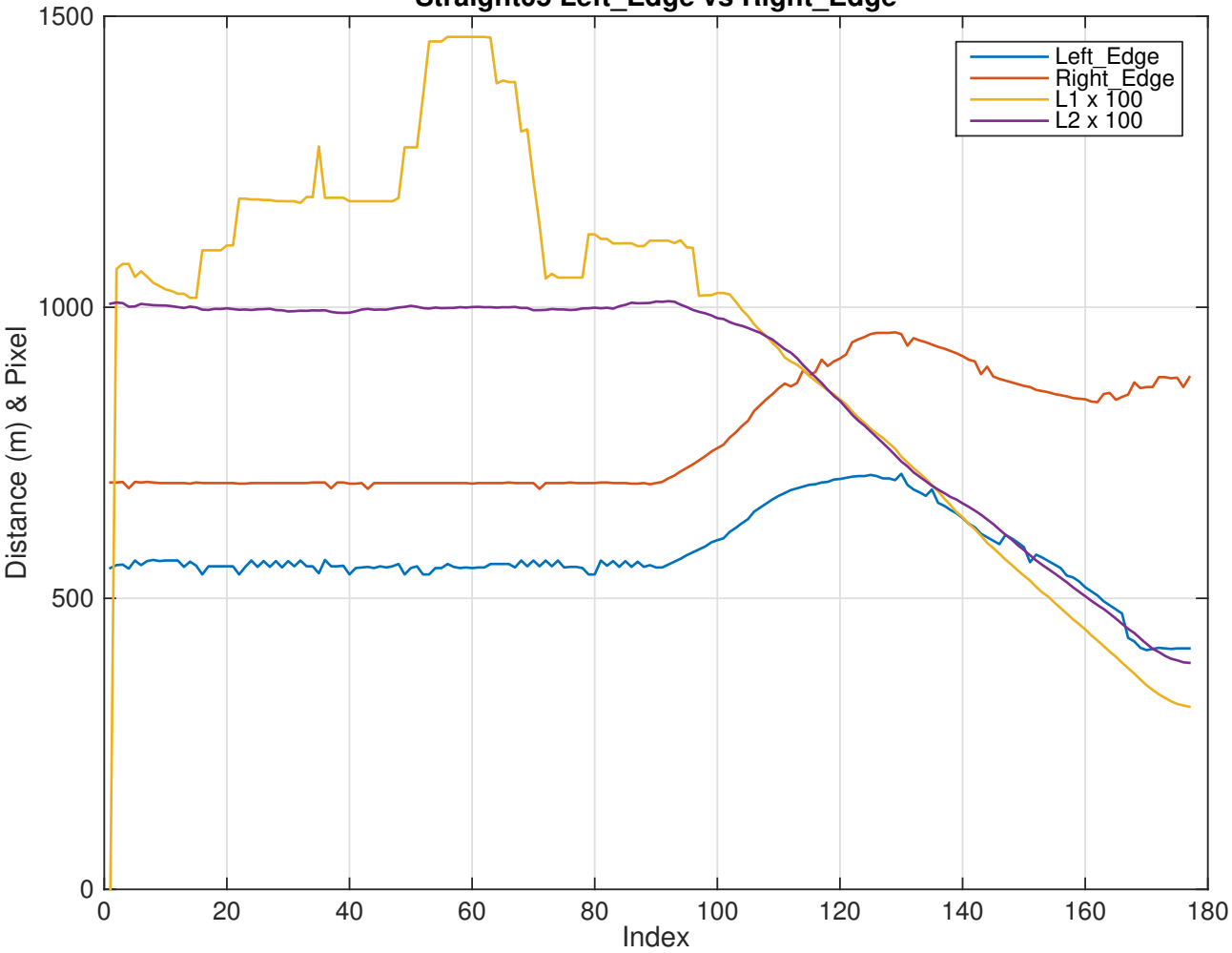
Number_Of_Unique_Paths

King_Pin_Detected

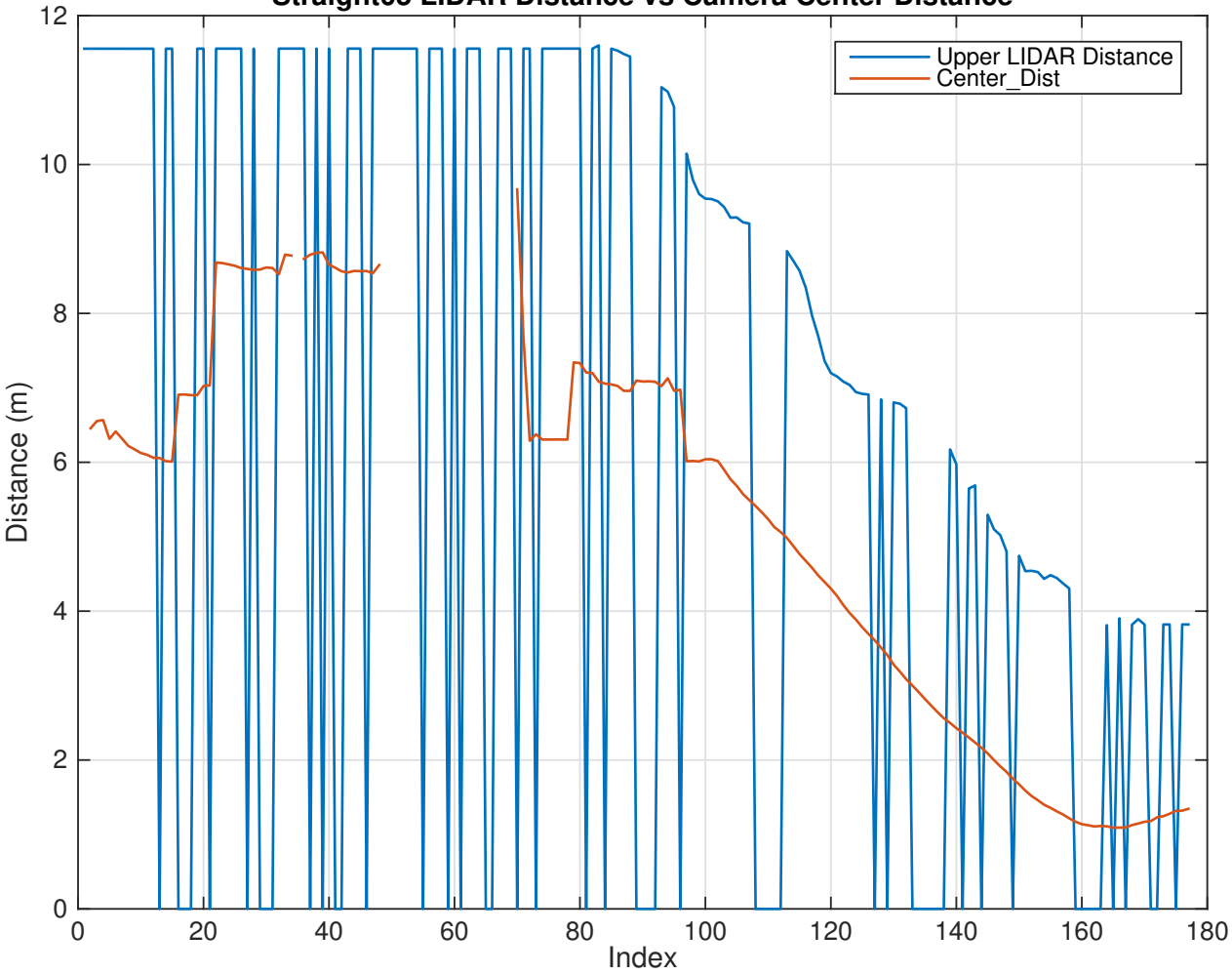
83

false

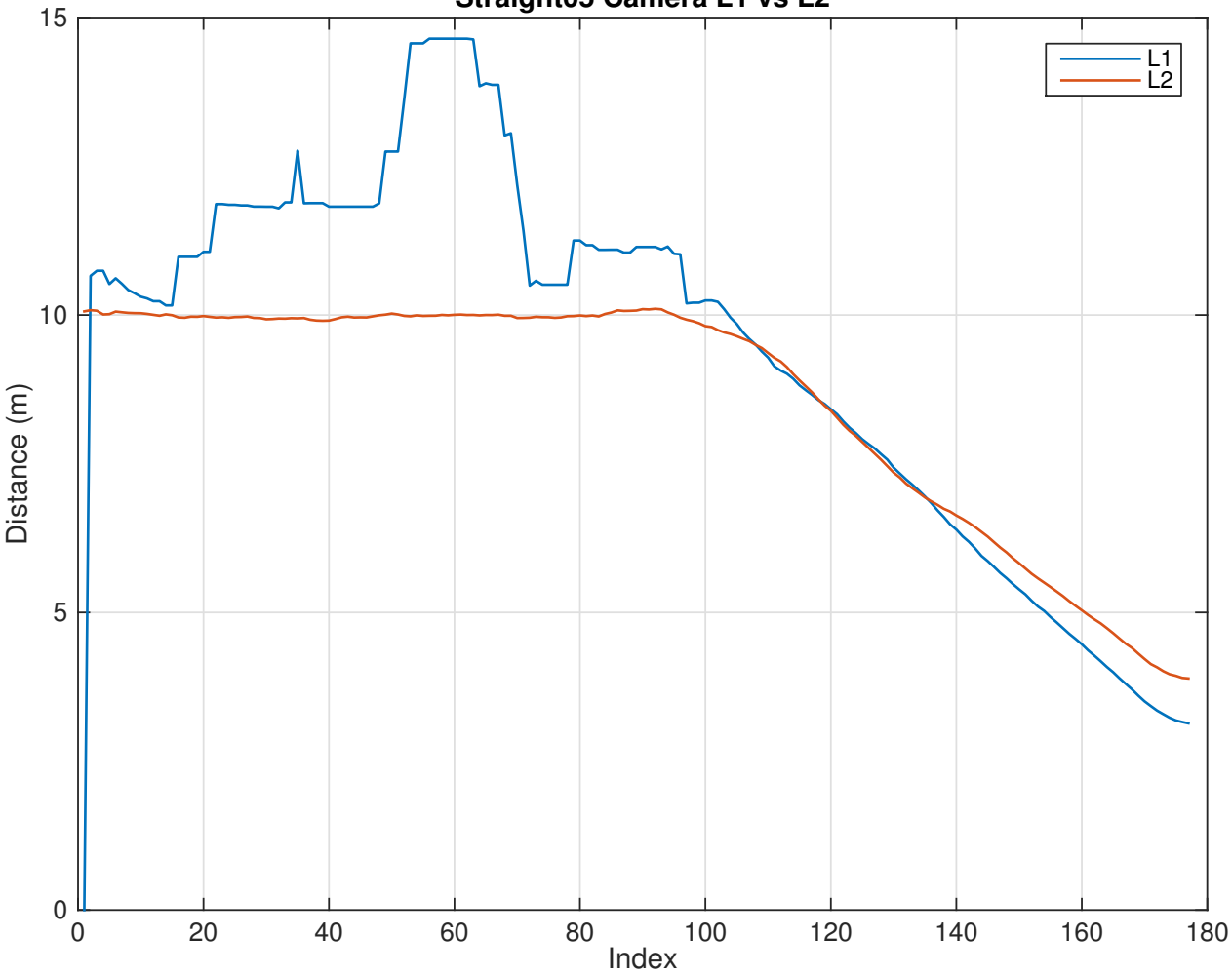
Straight05 Left_Edge vs Right_Edge



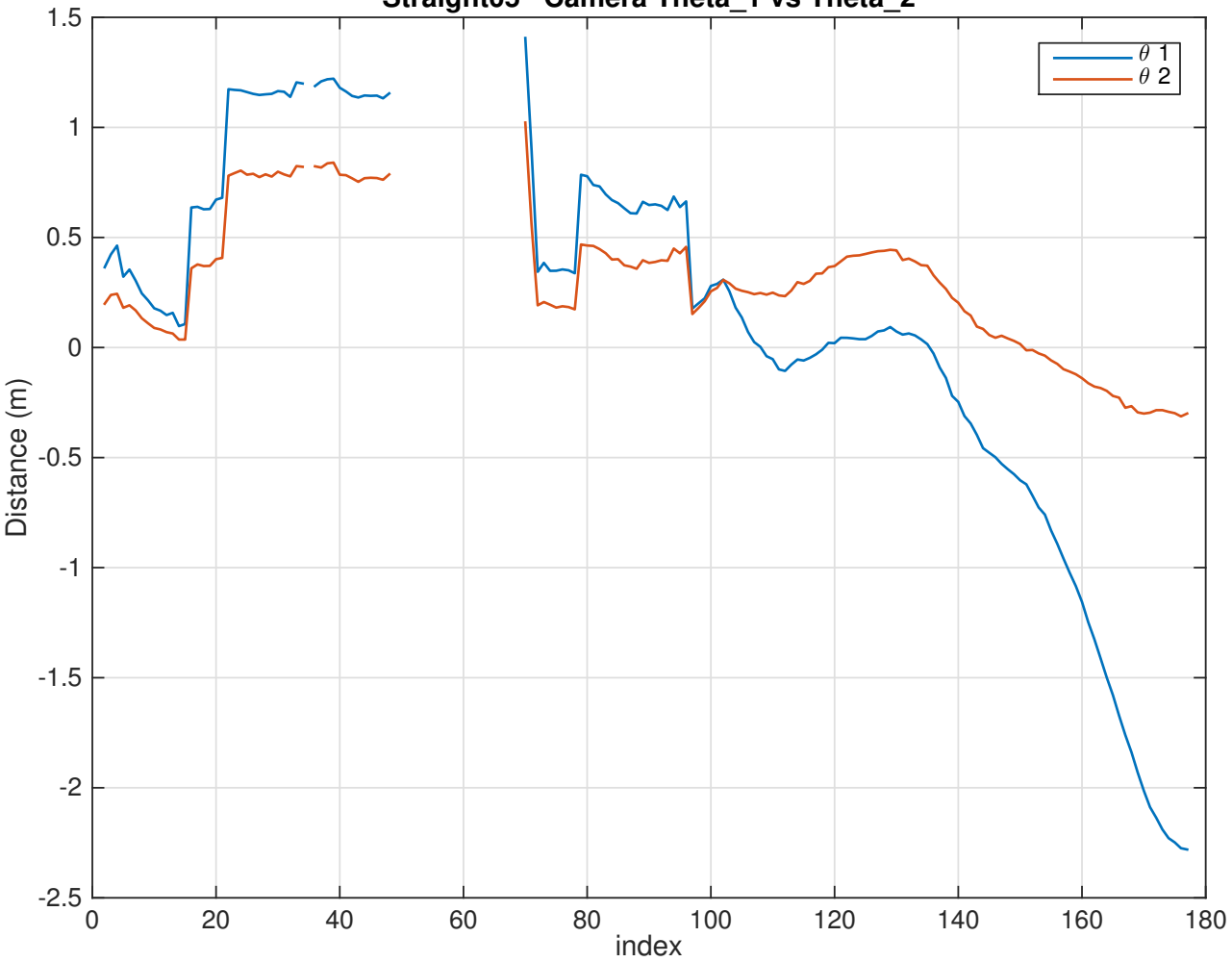
Straight05 LIDAR Distance vs Camera Center Distance



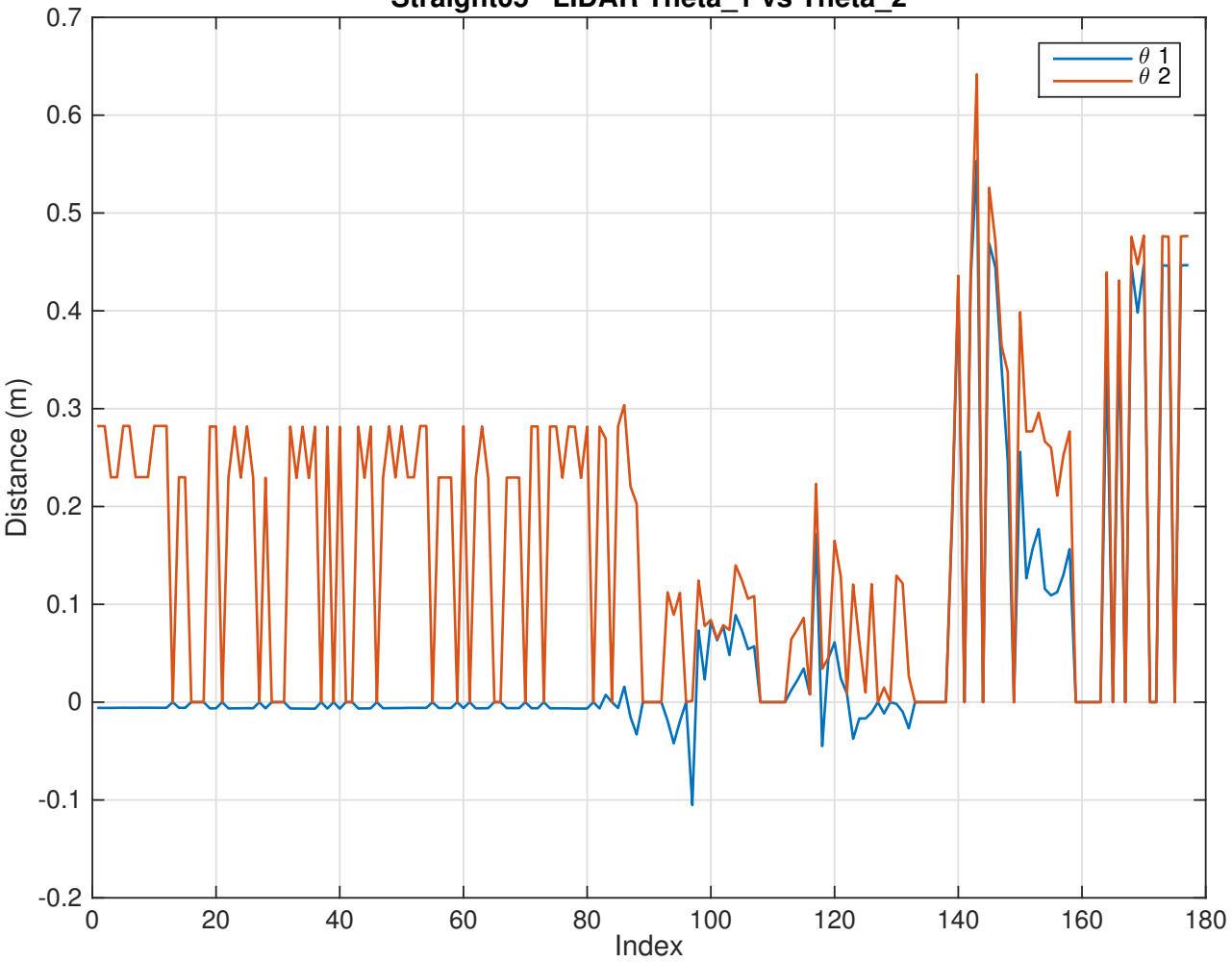
Straight05 Camera L1 vs L2



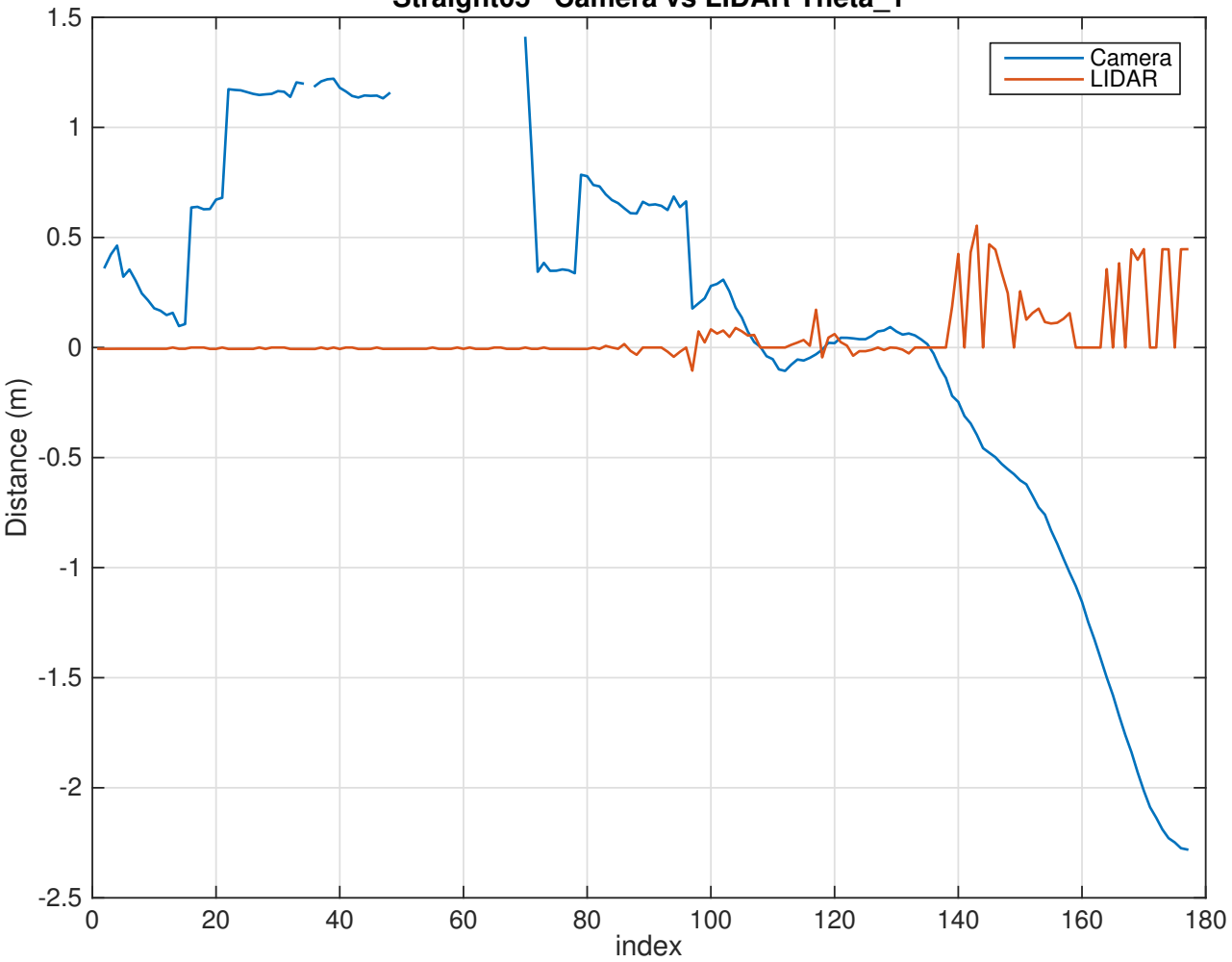
Straight05 Camera Theta_1 vs Theta_2



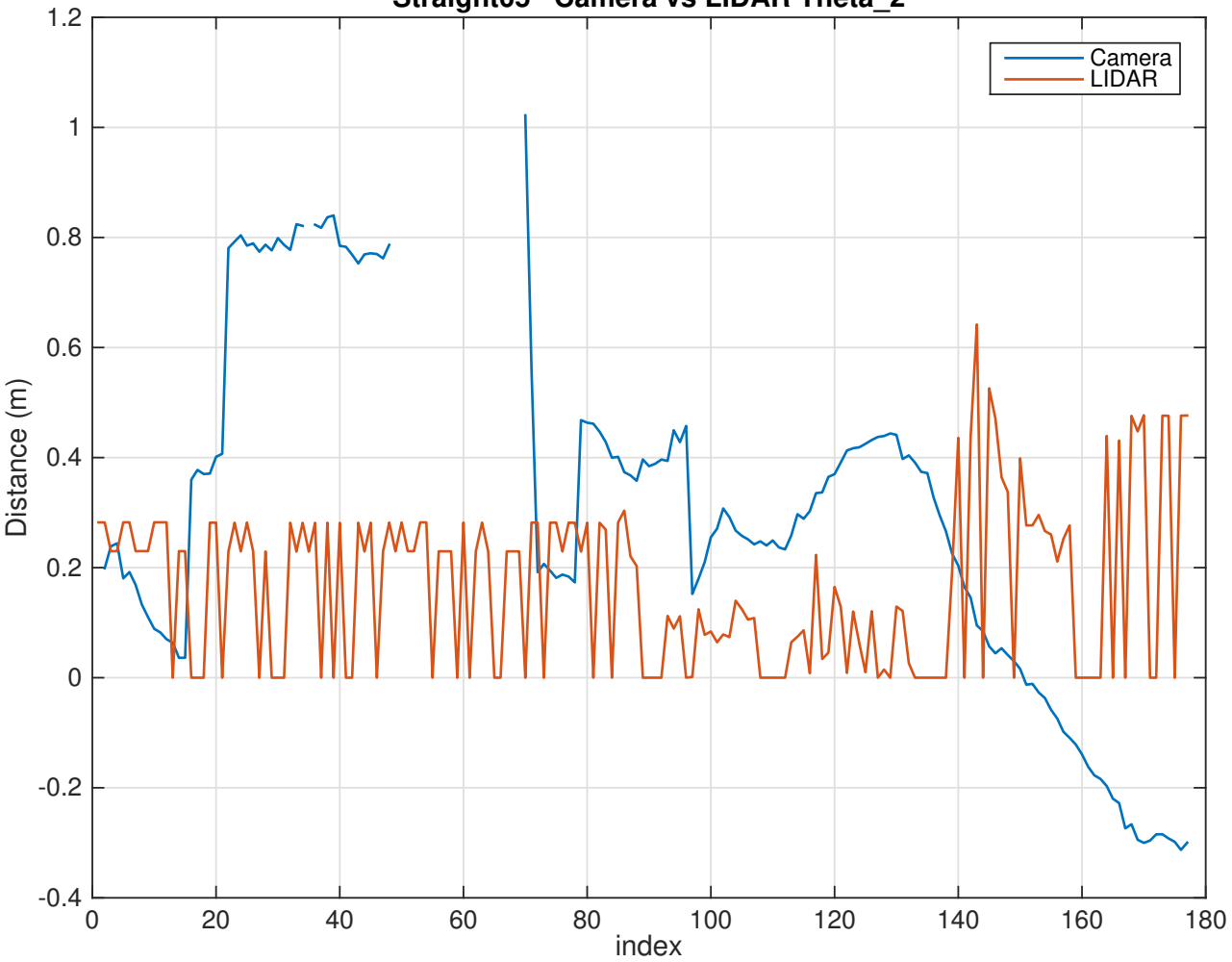
Straight05 LIDAR Theta_1 vs Theta_2



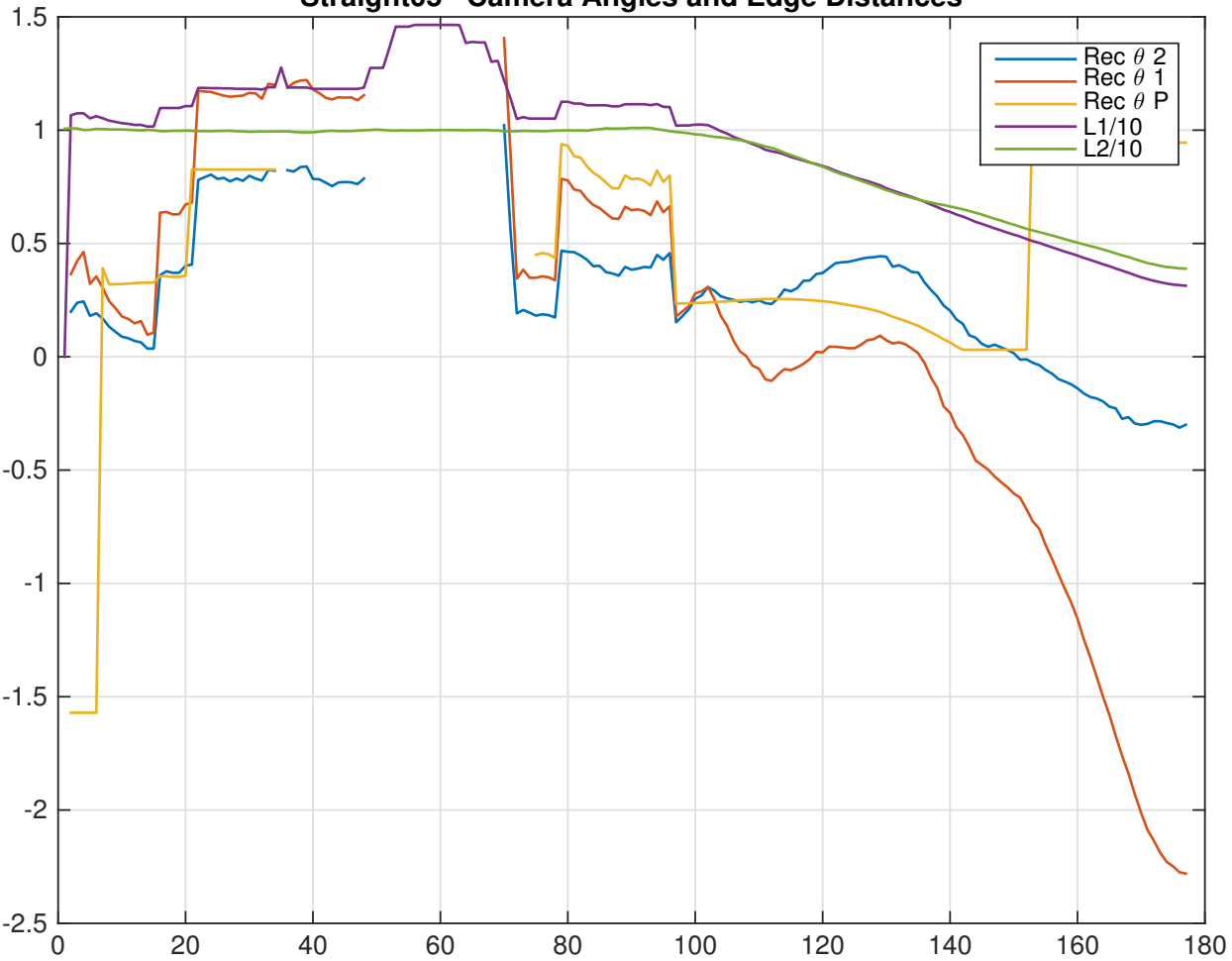
Straight05 Camera vs LIDAR Theta_1



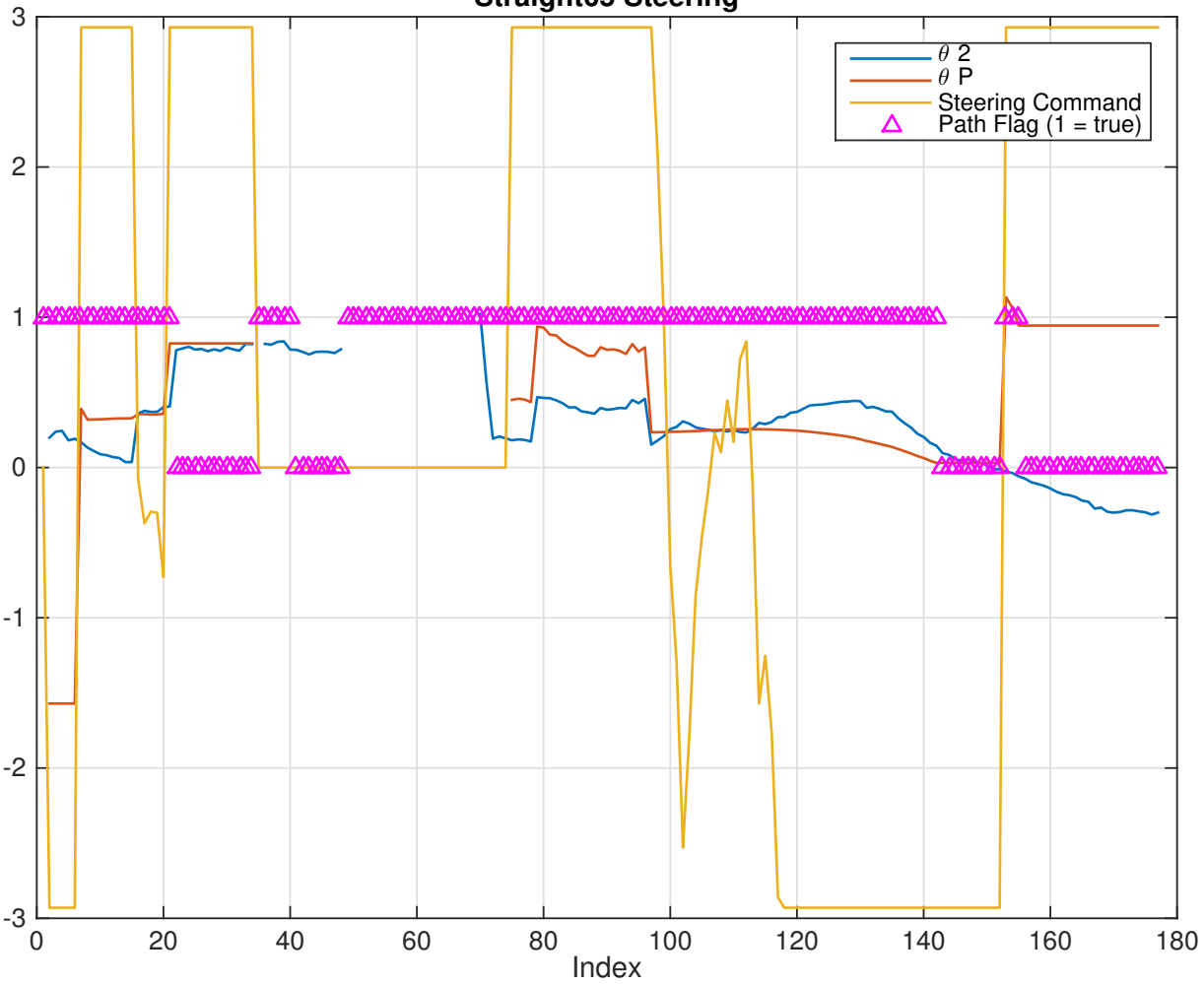
Straight05 Camera vs LIDAR Theta_2



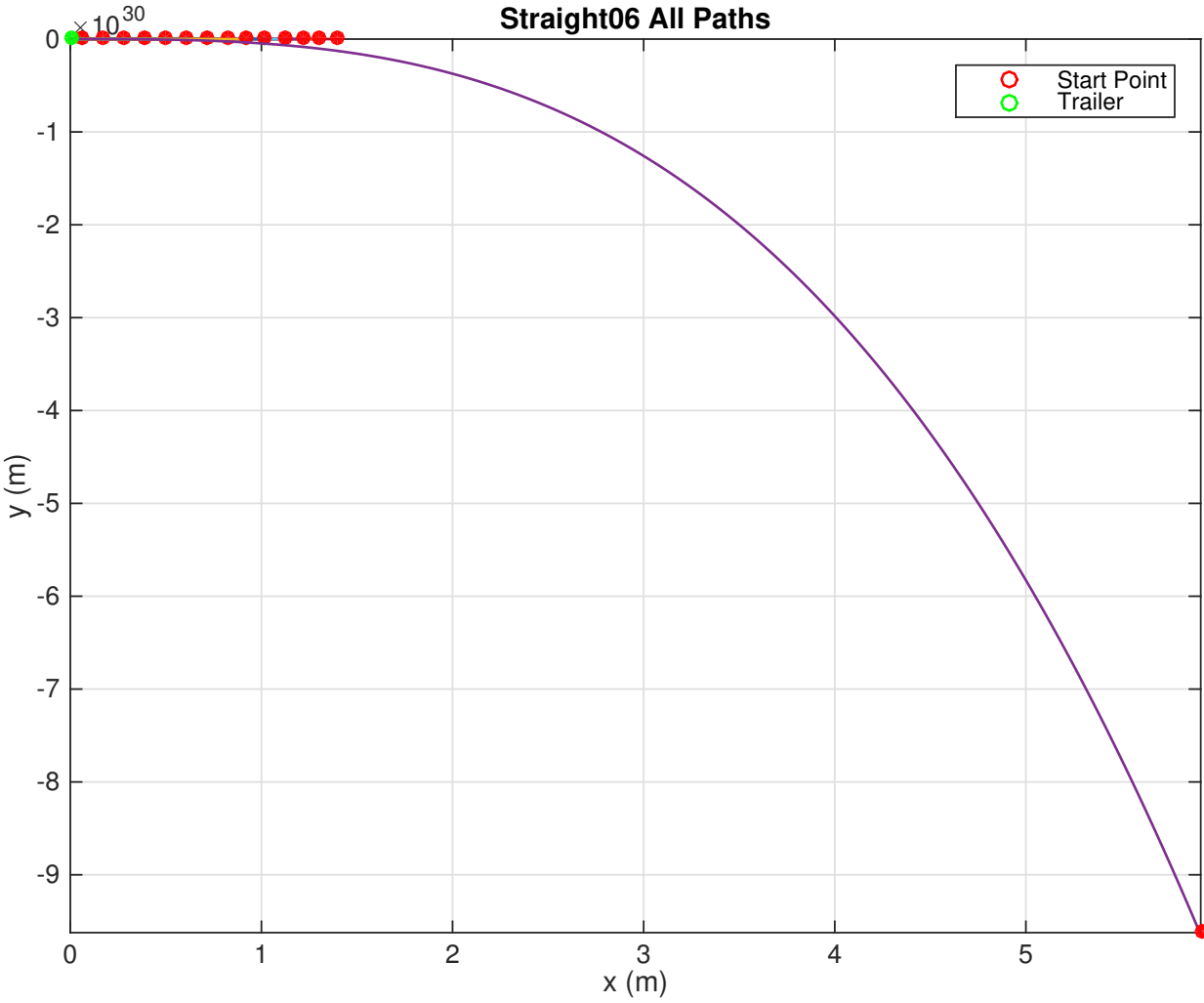
Straight05 Camera Angles and Edge Distances



Straight05 Steering



Straight06 All Paths



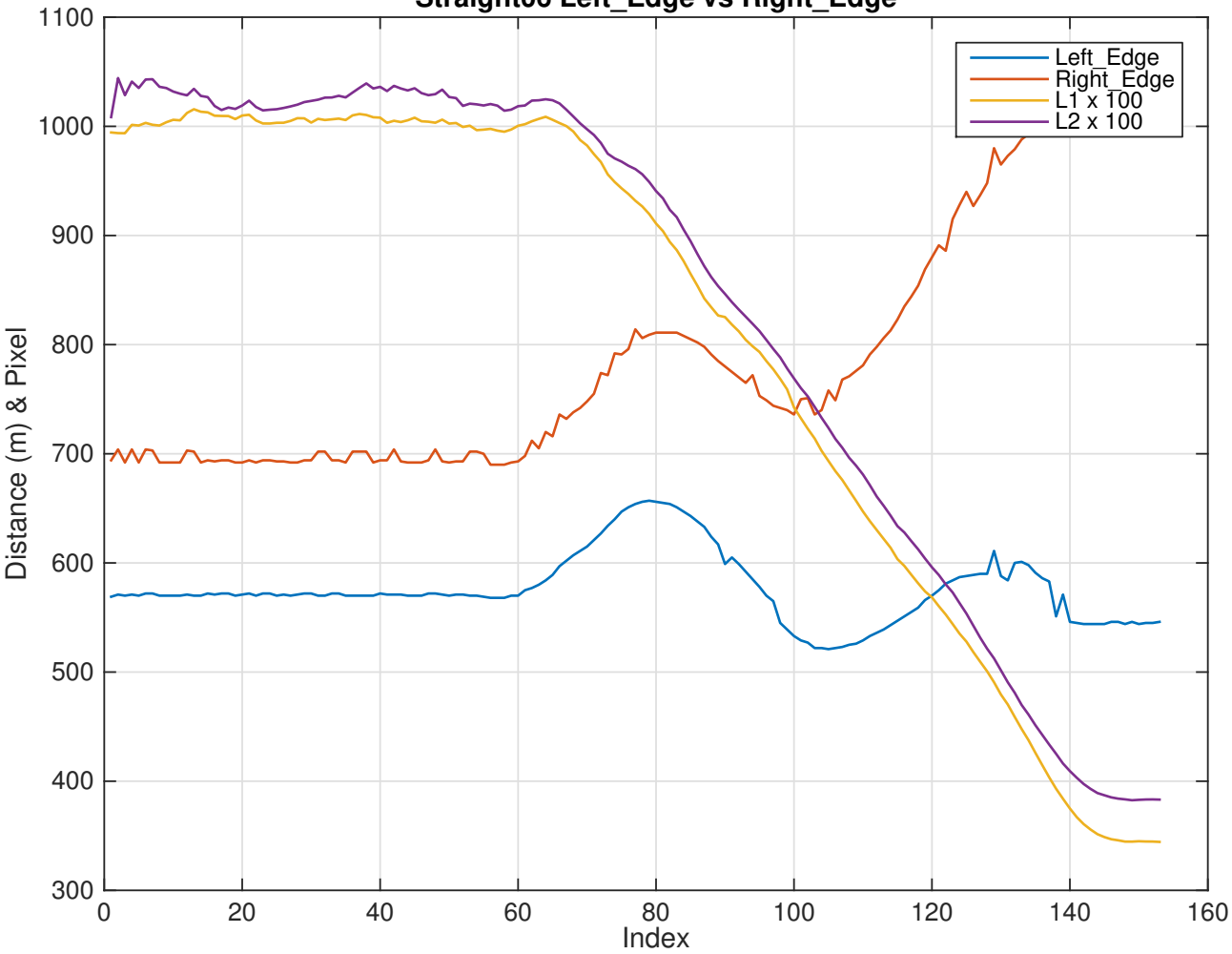
Number_Of_Unique_Paths

King_Pin_Detected

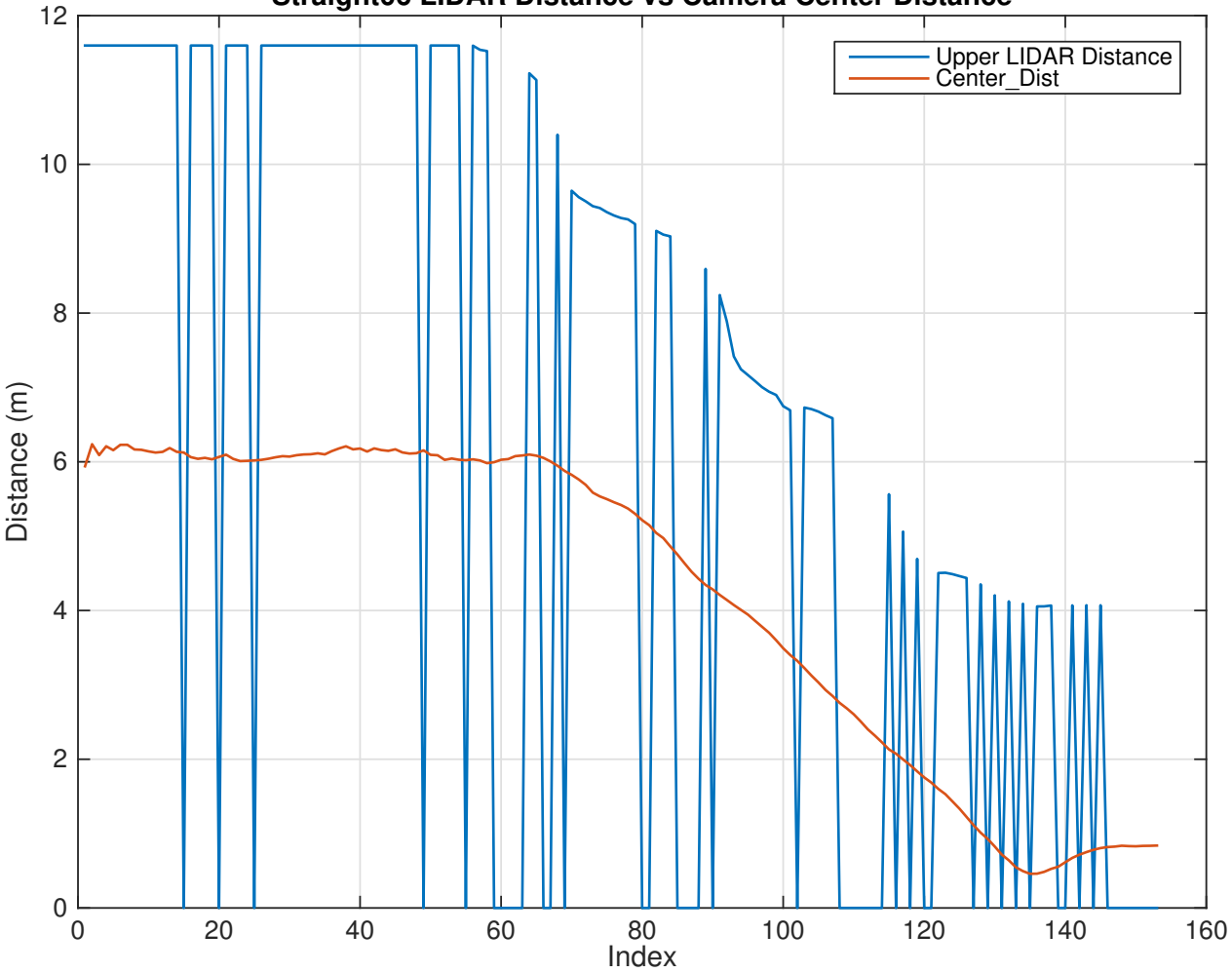
32

false

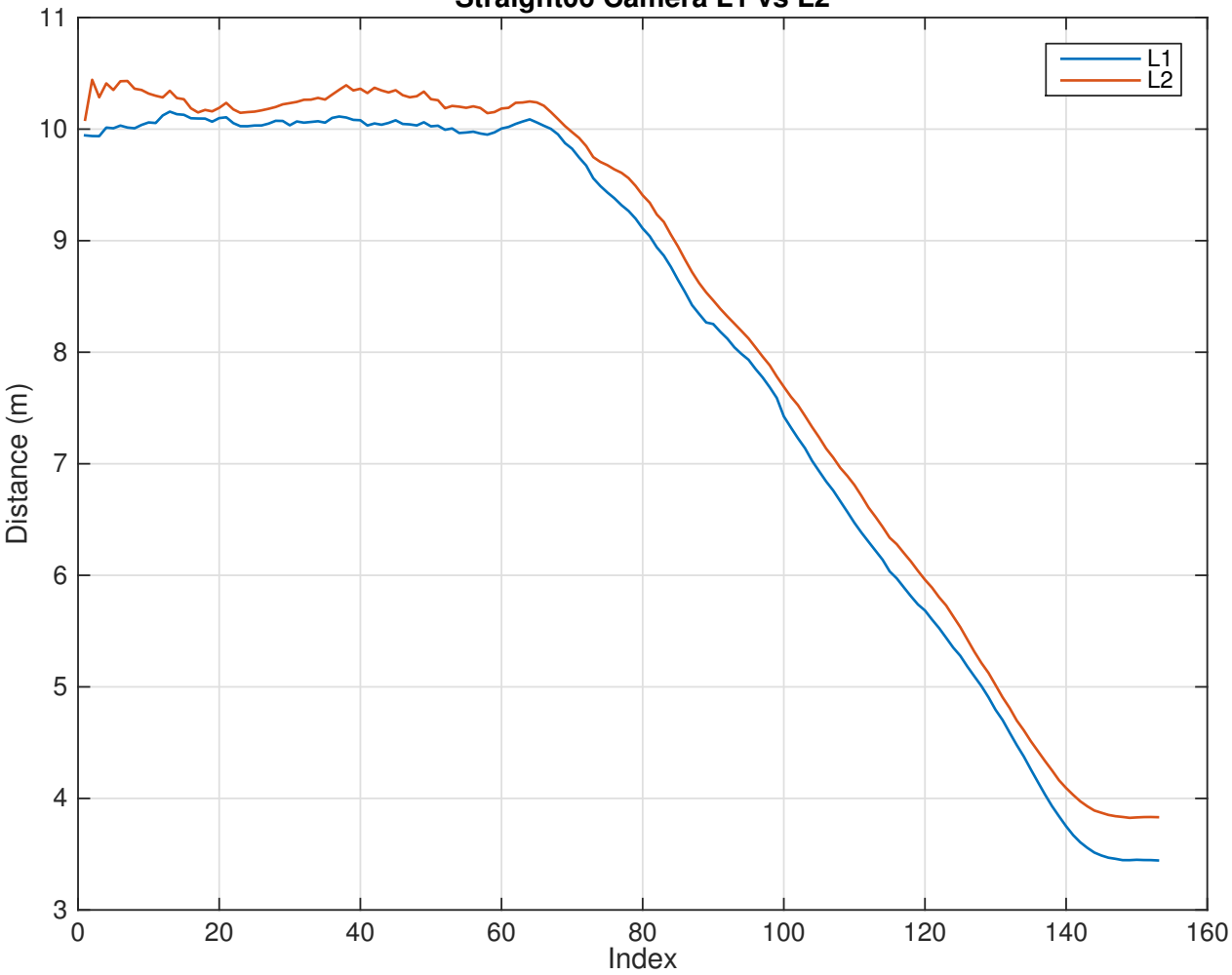
Straight06 Left_Edge vs Right_Edge



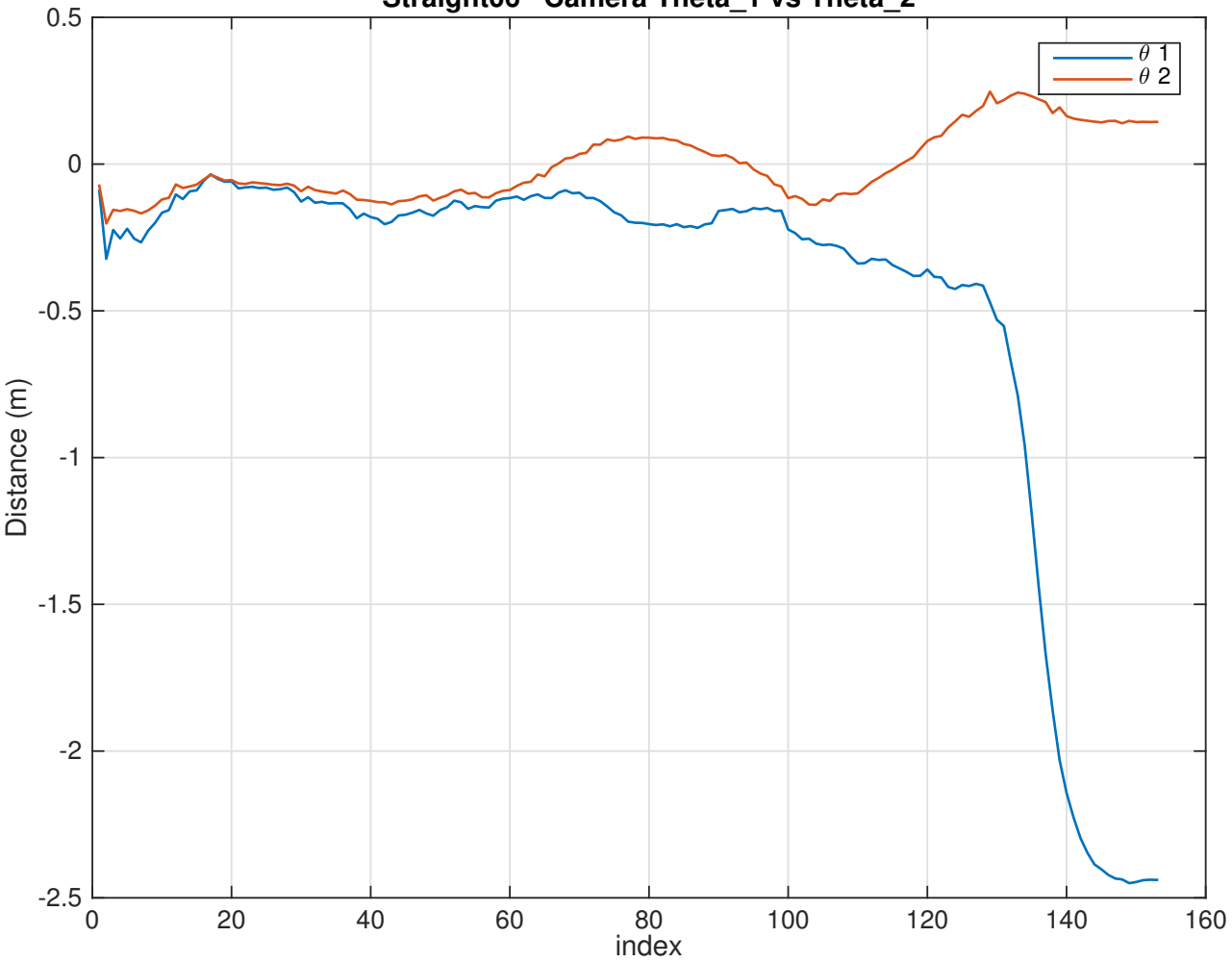
Straight06 LIDAR Distance vs Camera Center Distance



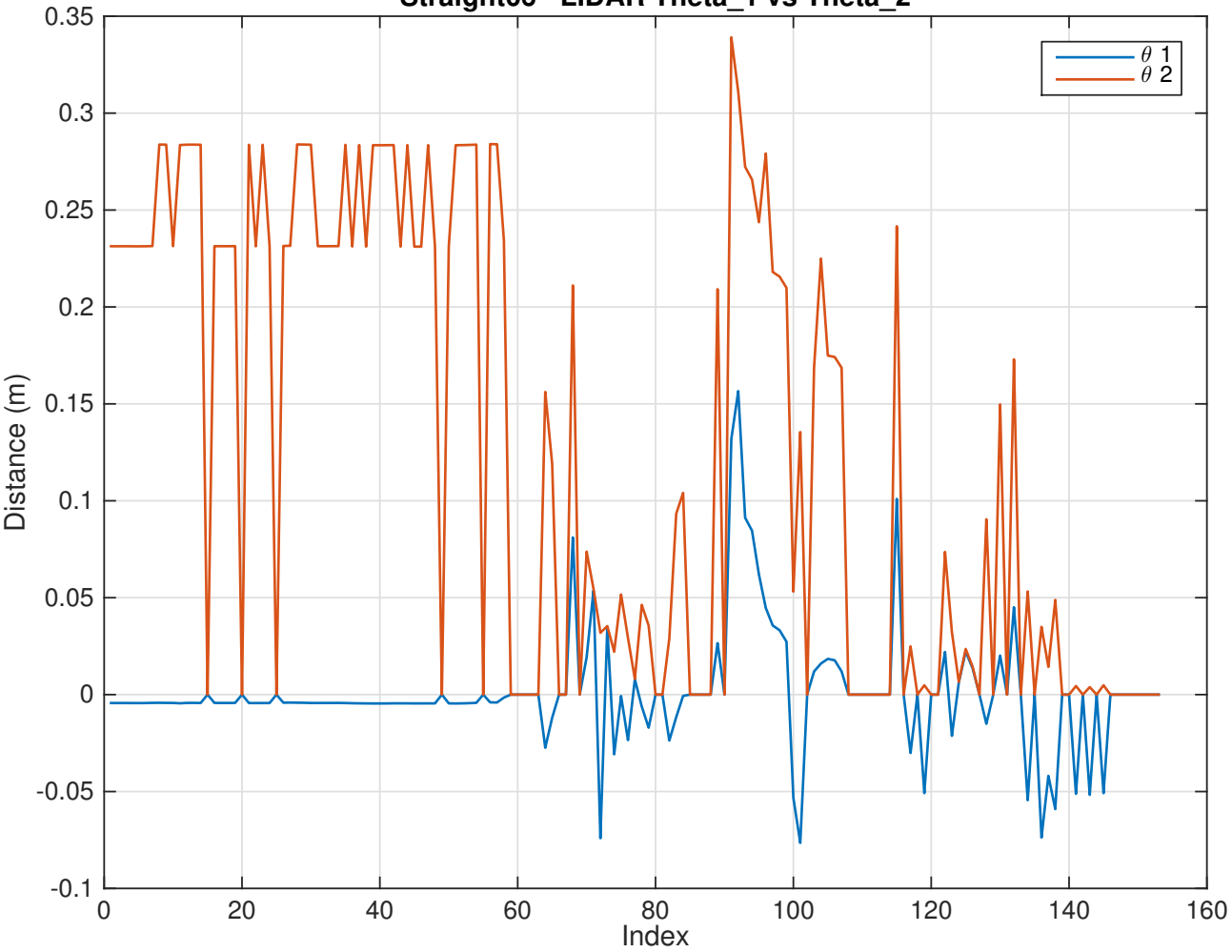
Straight06 Camera L1 vs L2



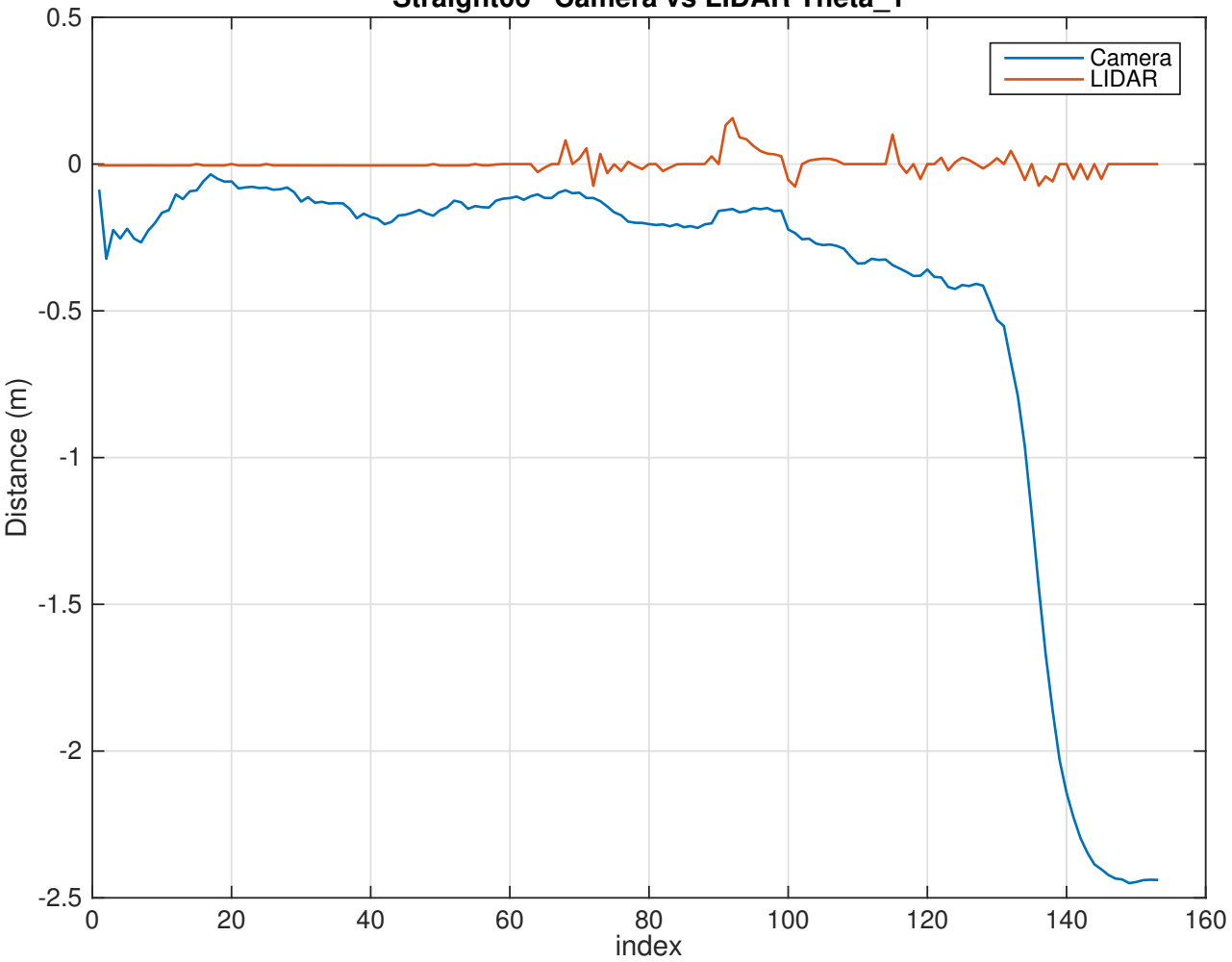
Straight06 Camera Theta_1 vs Theta_2



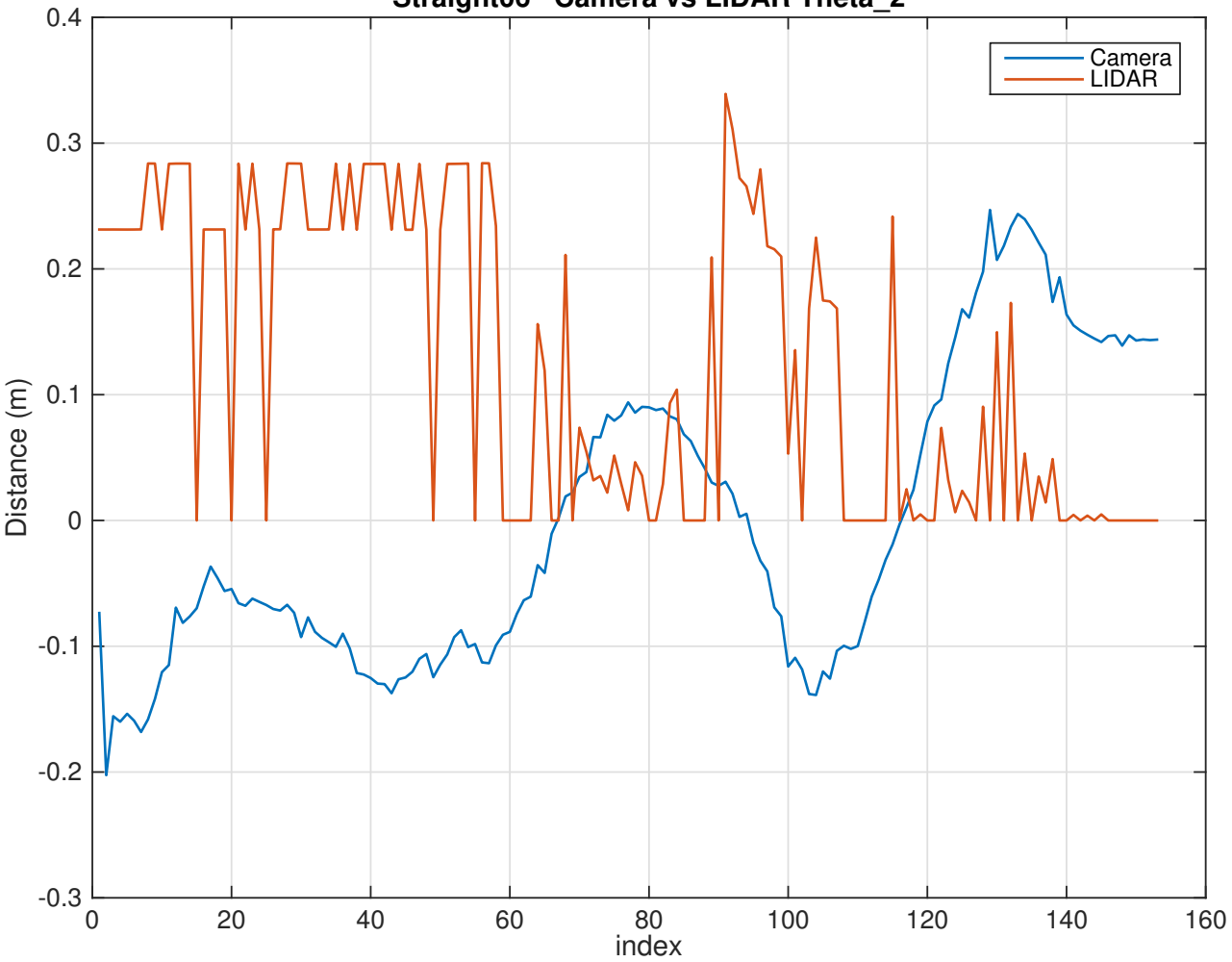
Straight06 LIDAR Theta_1 vs Theta_2



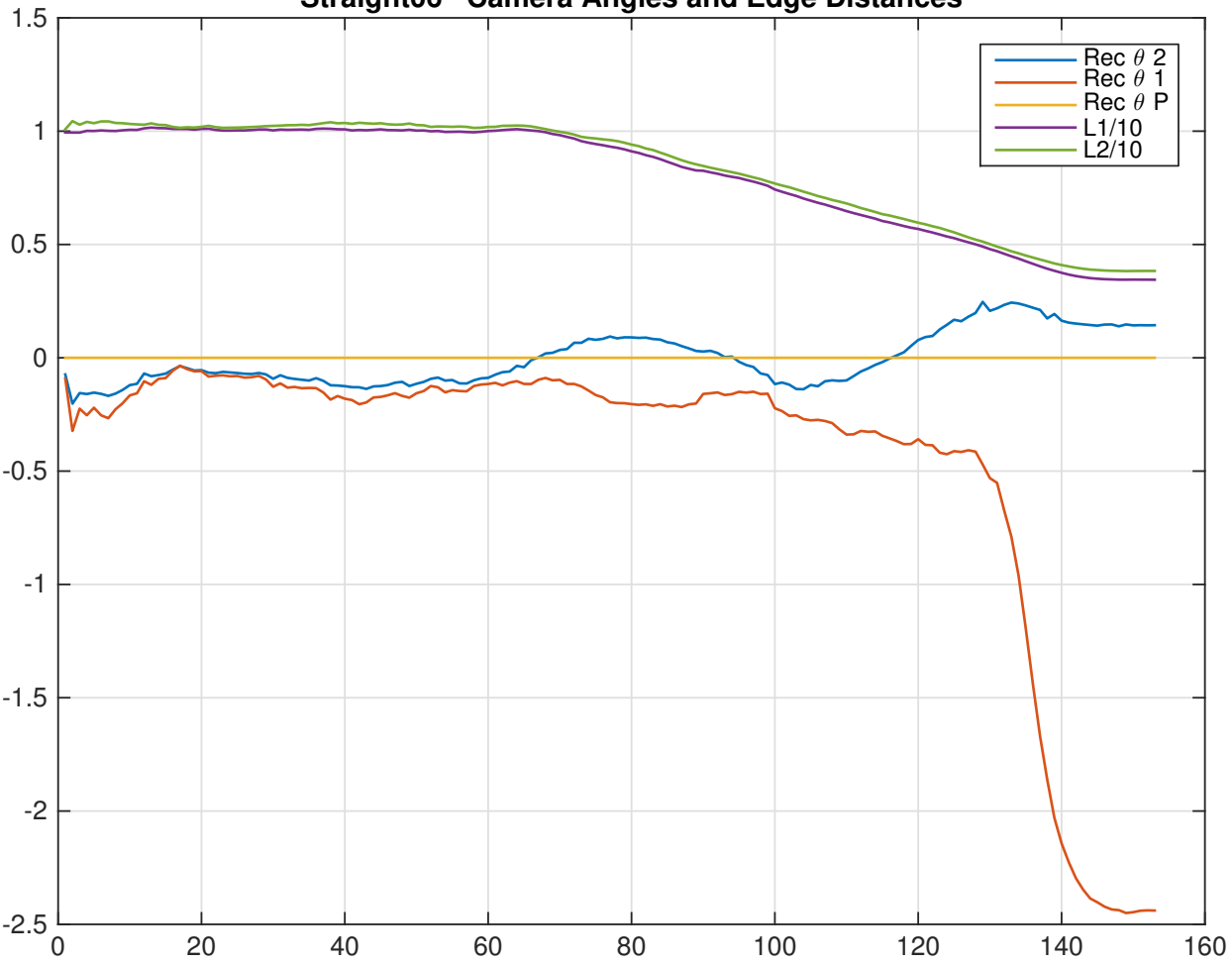
Straight06 Camera vs LIDAR Theta_1



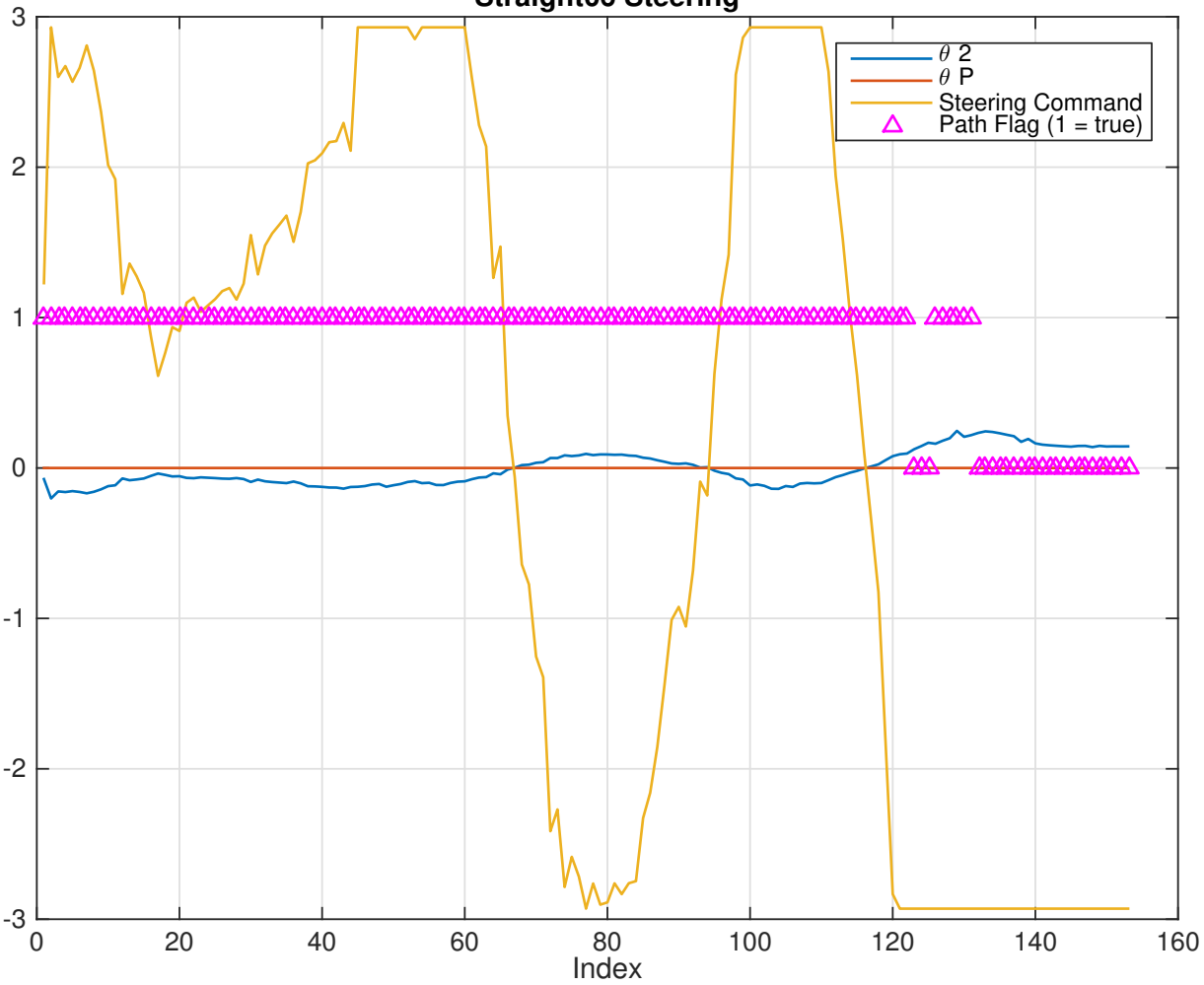
Straight06 Camera vs LIDAR Theta_2



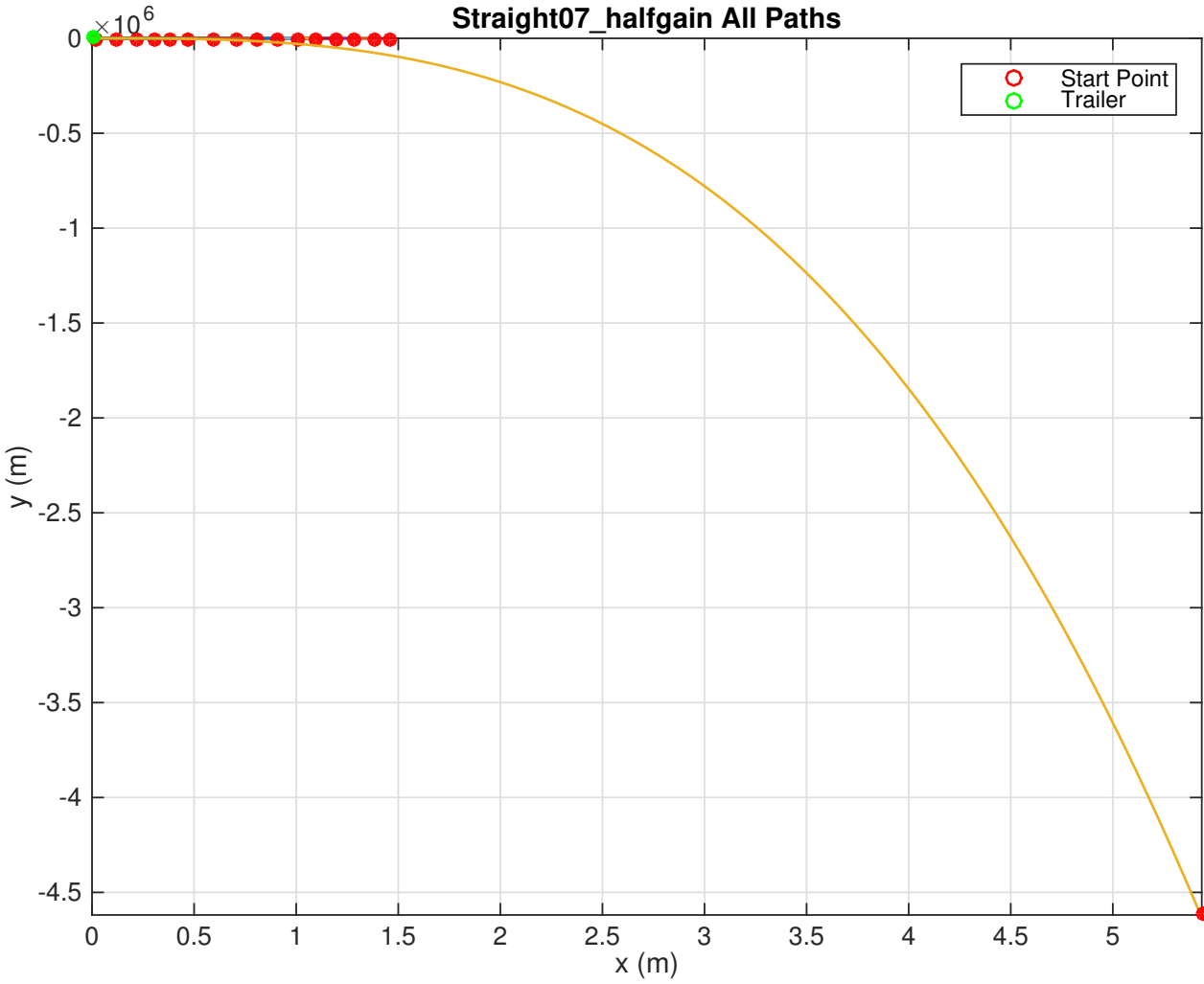
Straight06 Camera Angles and Edge Distances



Straight06 Steering



Straight07_halfgain All Paths



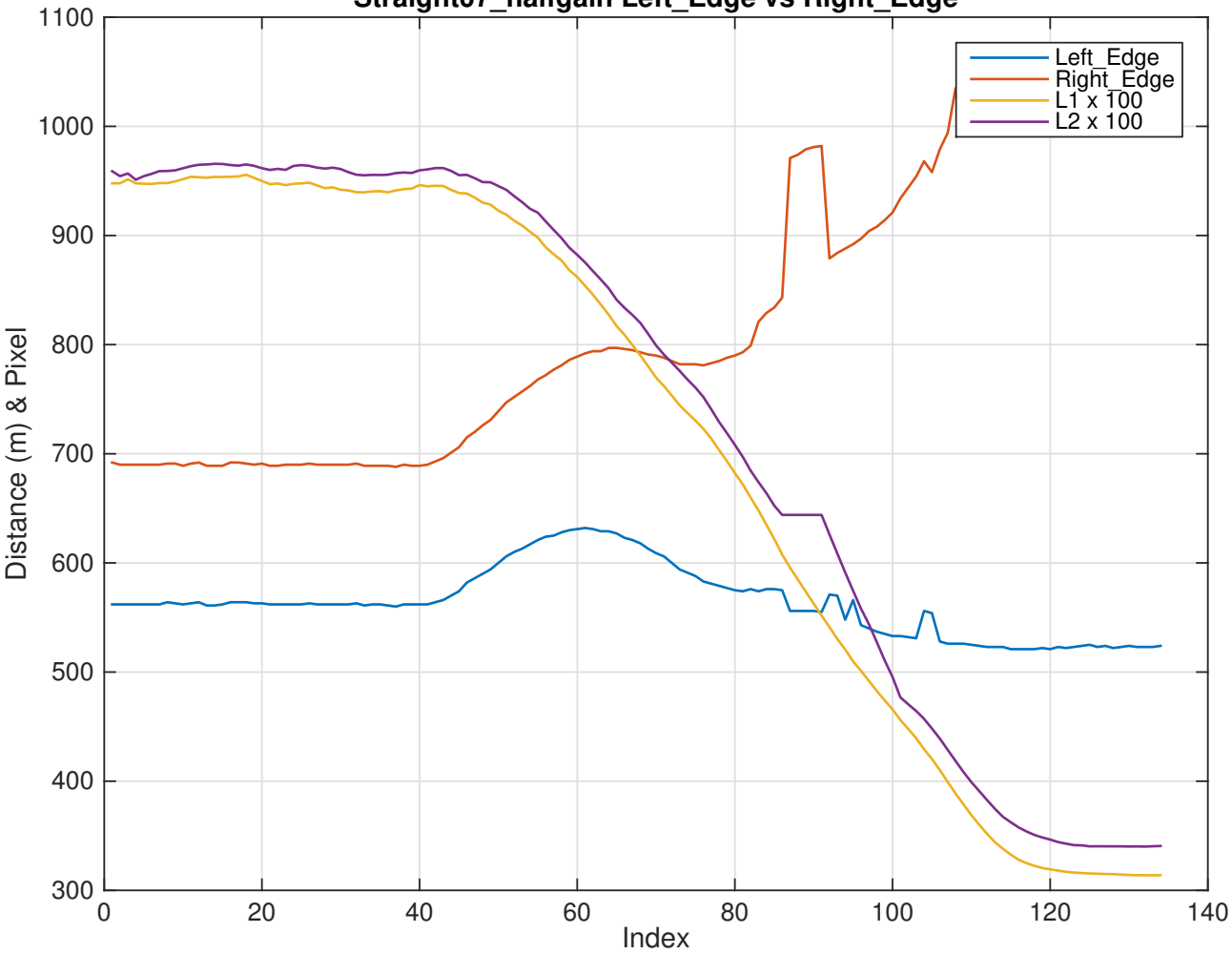
Number_Of_Unique_Paths

King_Pin_Detected

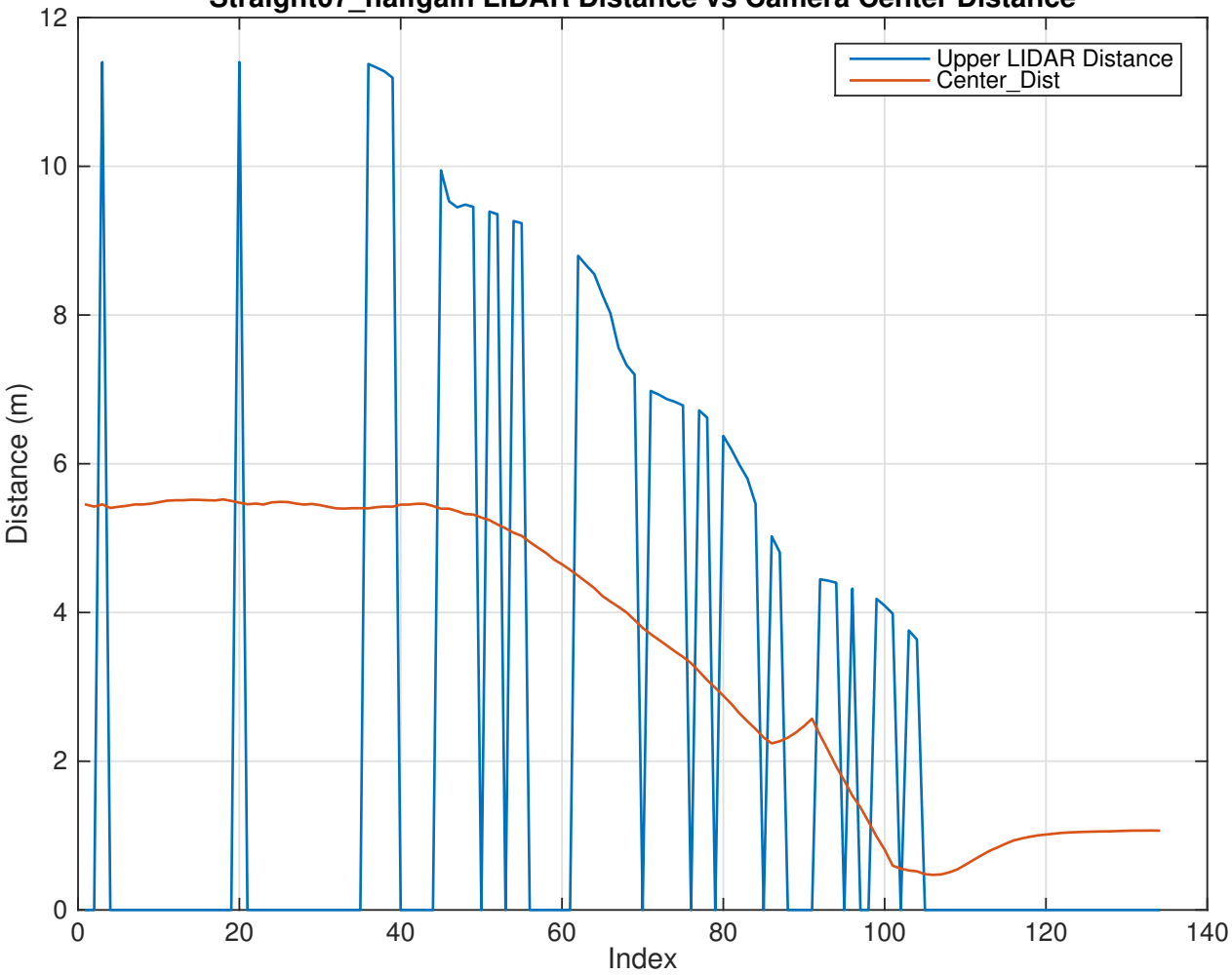
45

false

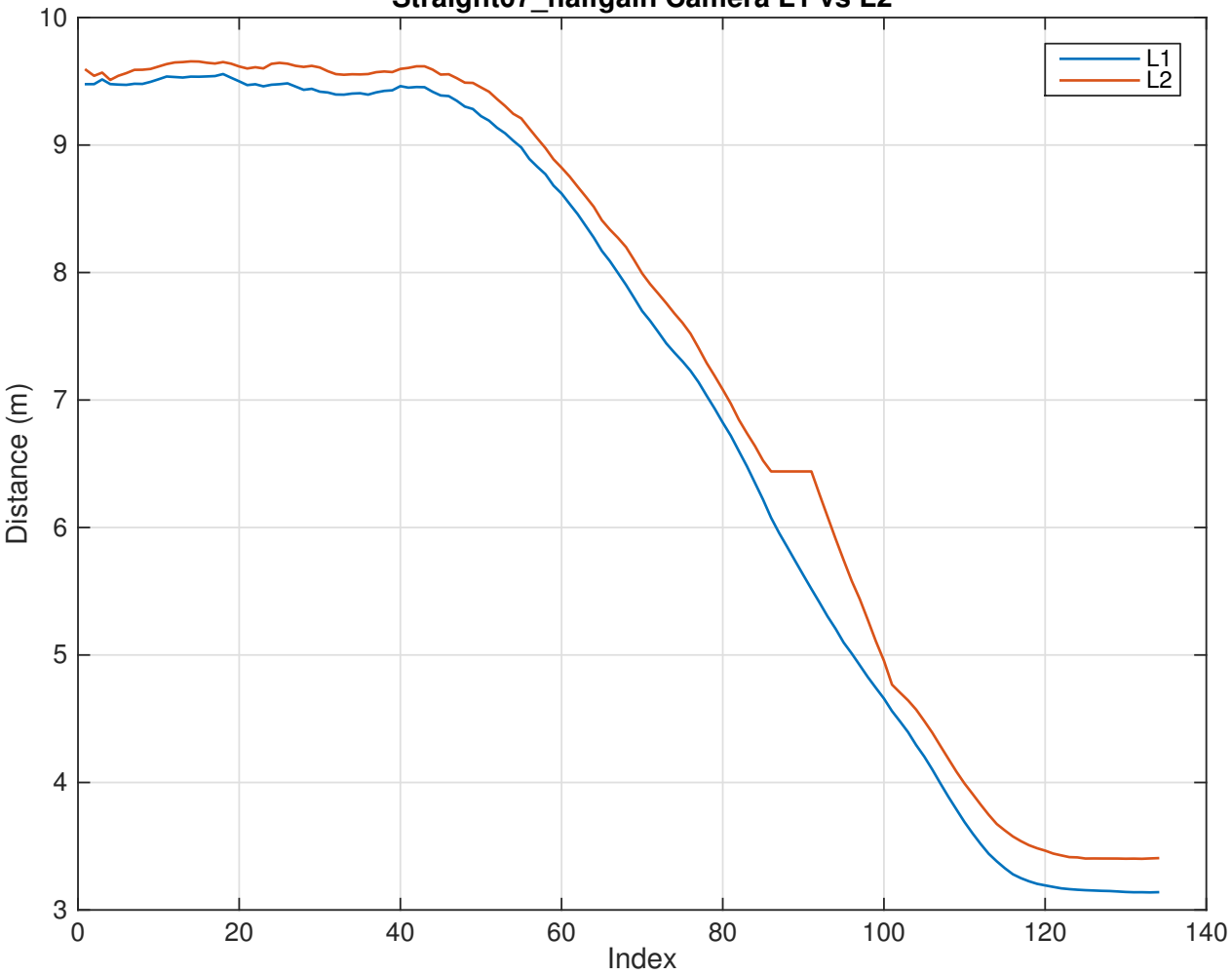
Straight07_halfgain Left_Edge vs Right_Edge



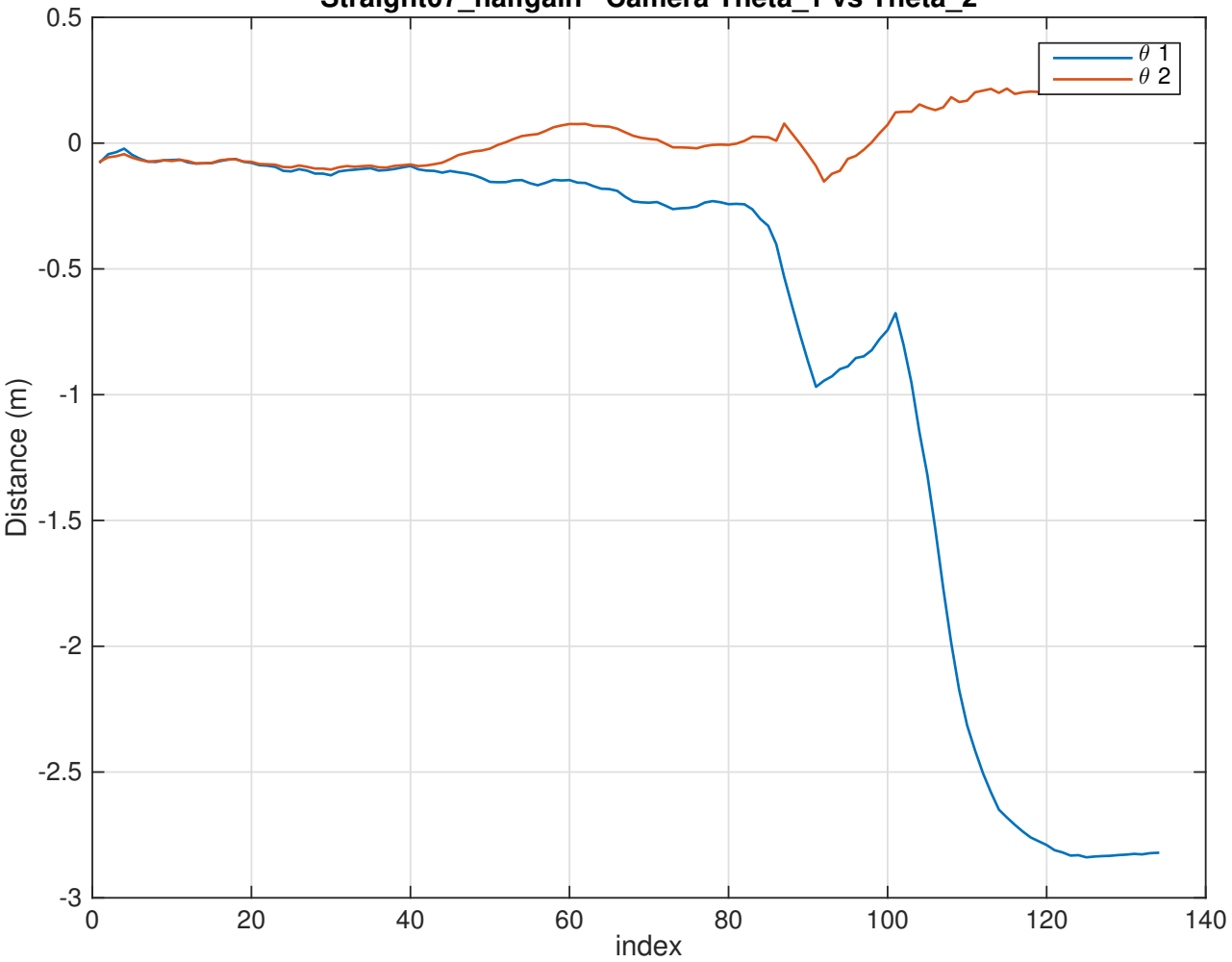
Straight07_halfgain LIDAR Distance vs Camera Center Distance



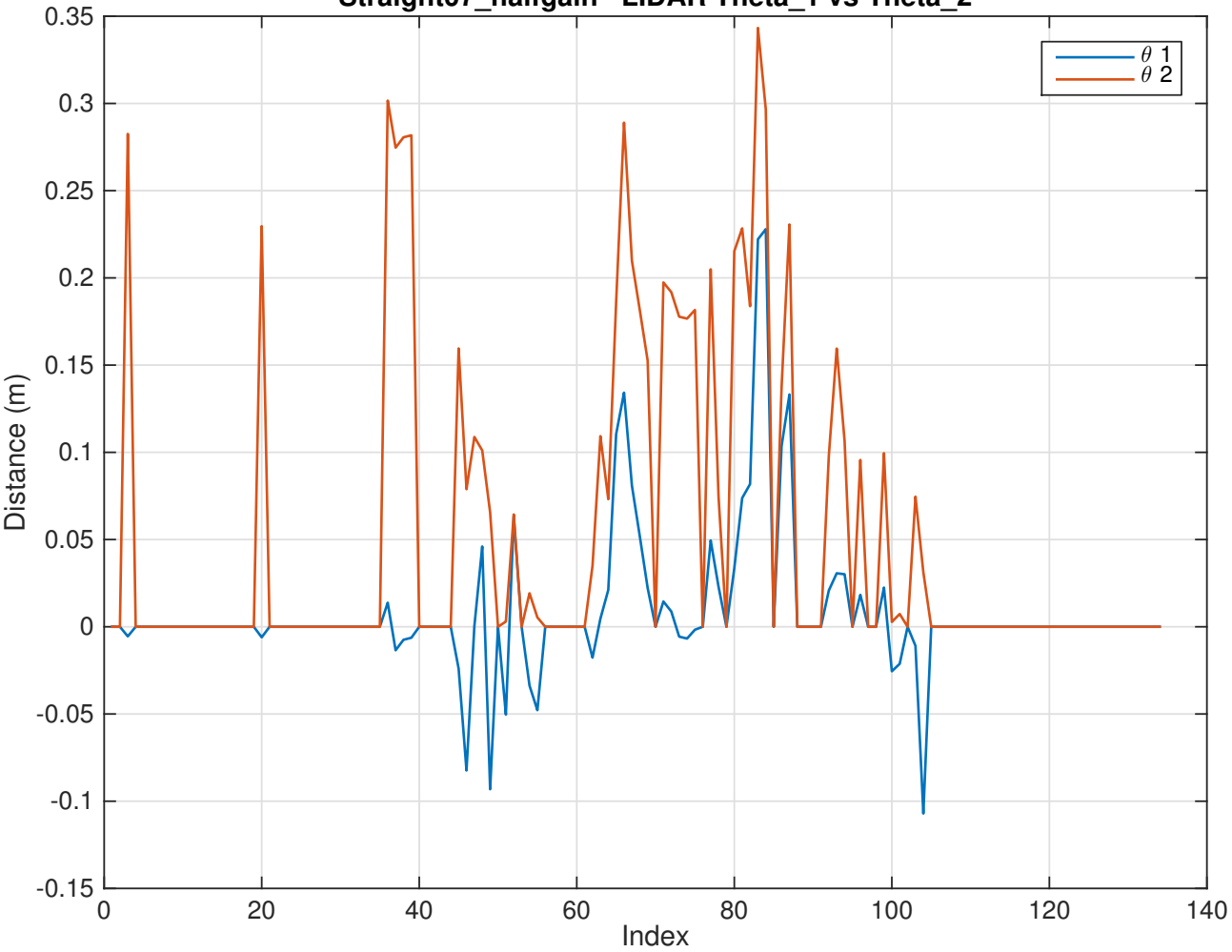
Straight07_halfgain Camera L1 vs L2



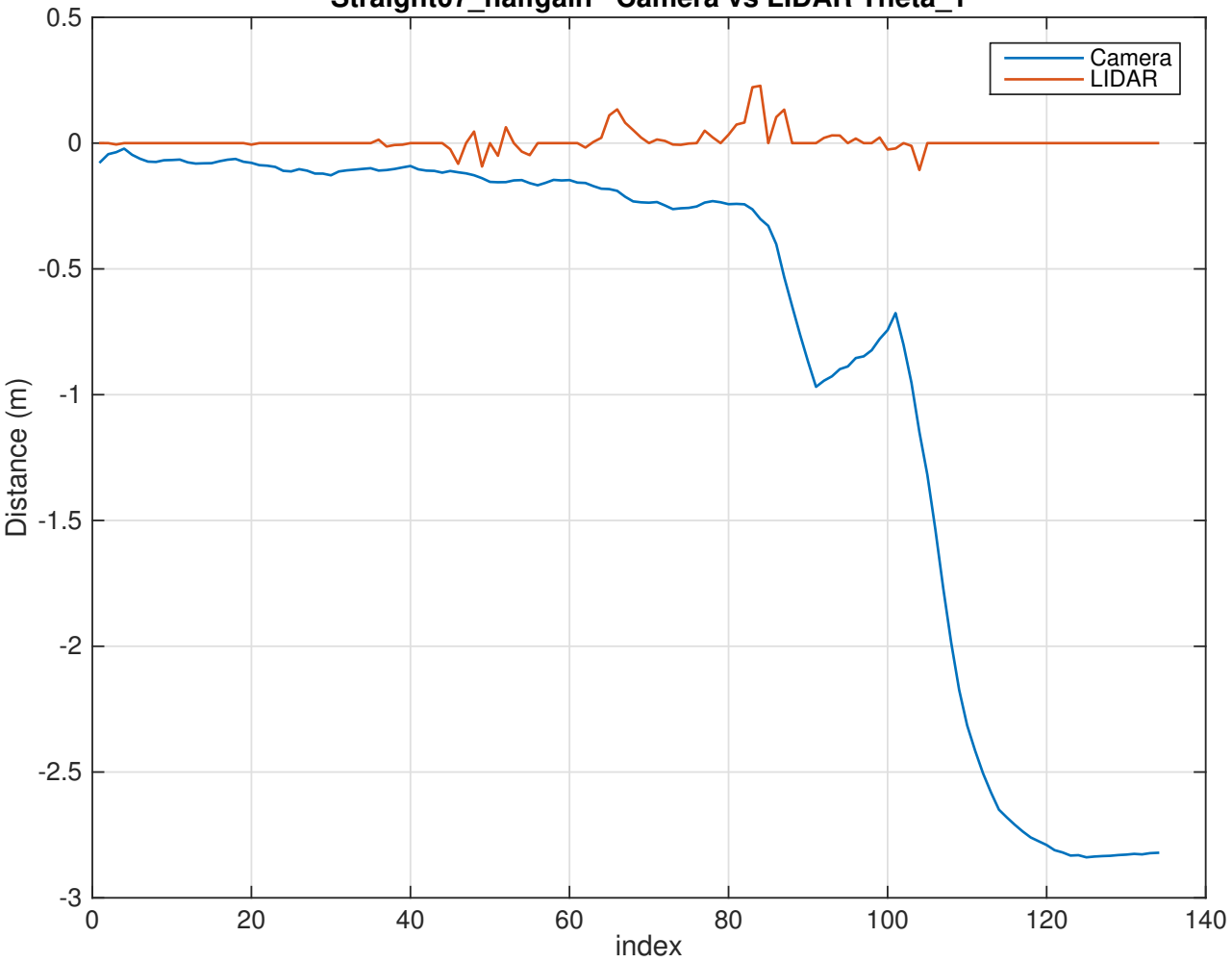
Straight07_halfgain Camera Theta_1 vs Theta_2



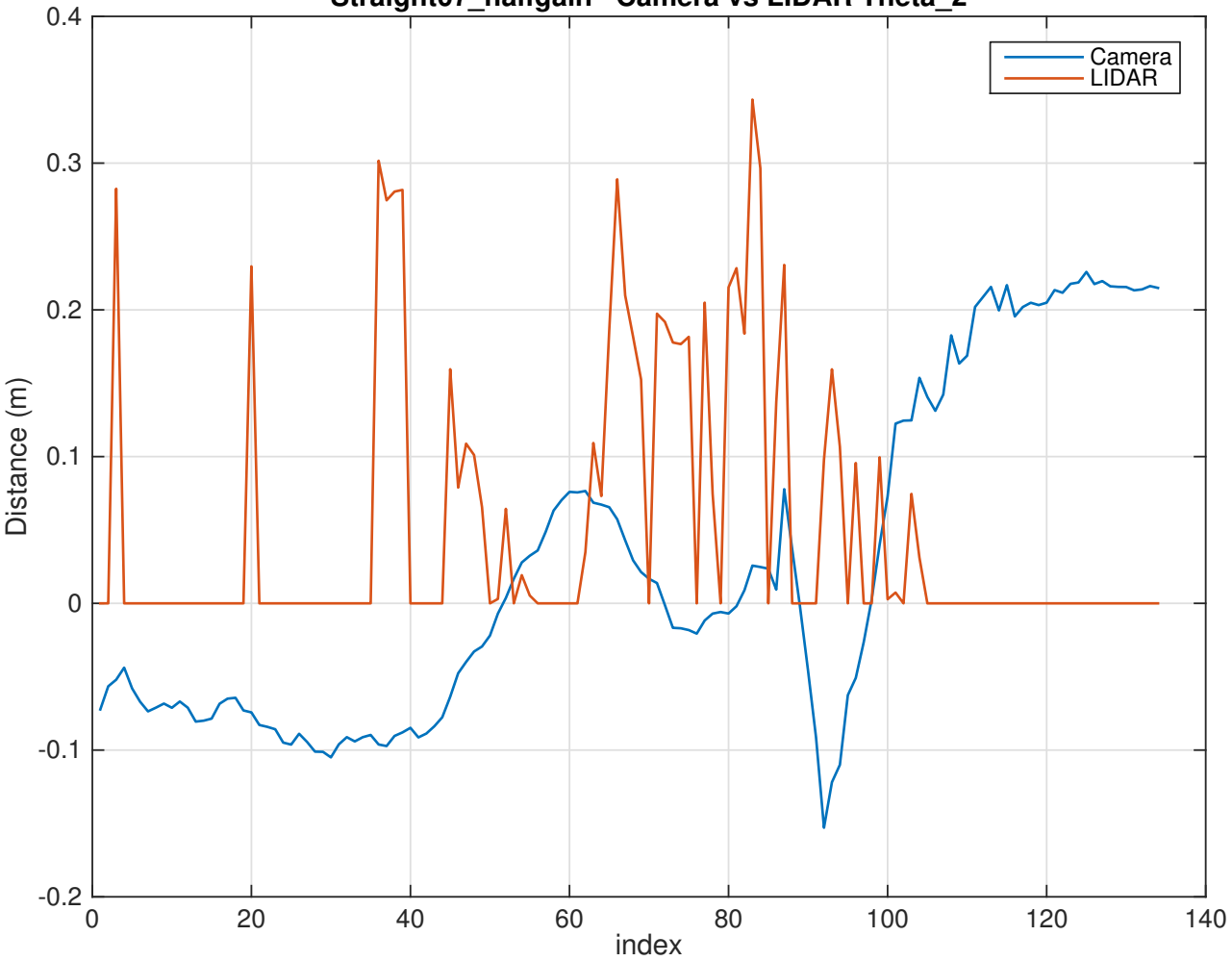
Straight07_halfgain LIDAR Theta_1 vs Theta_2



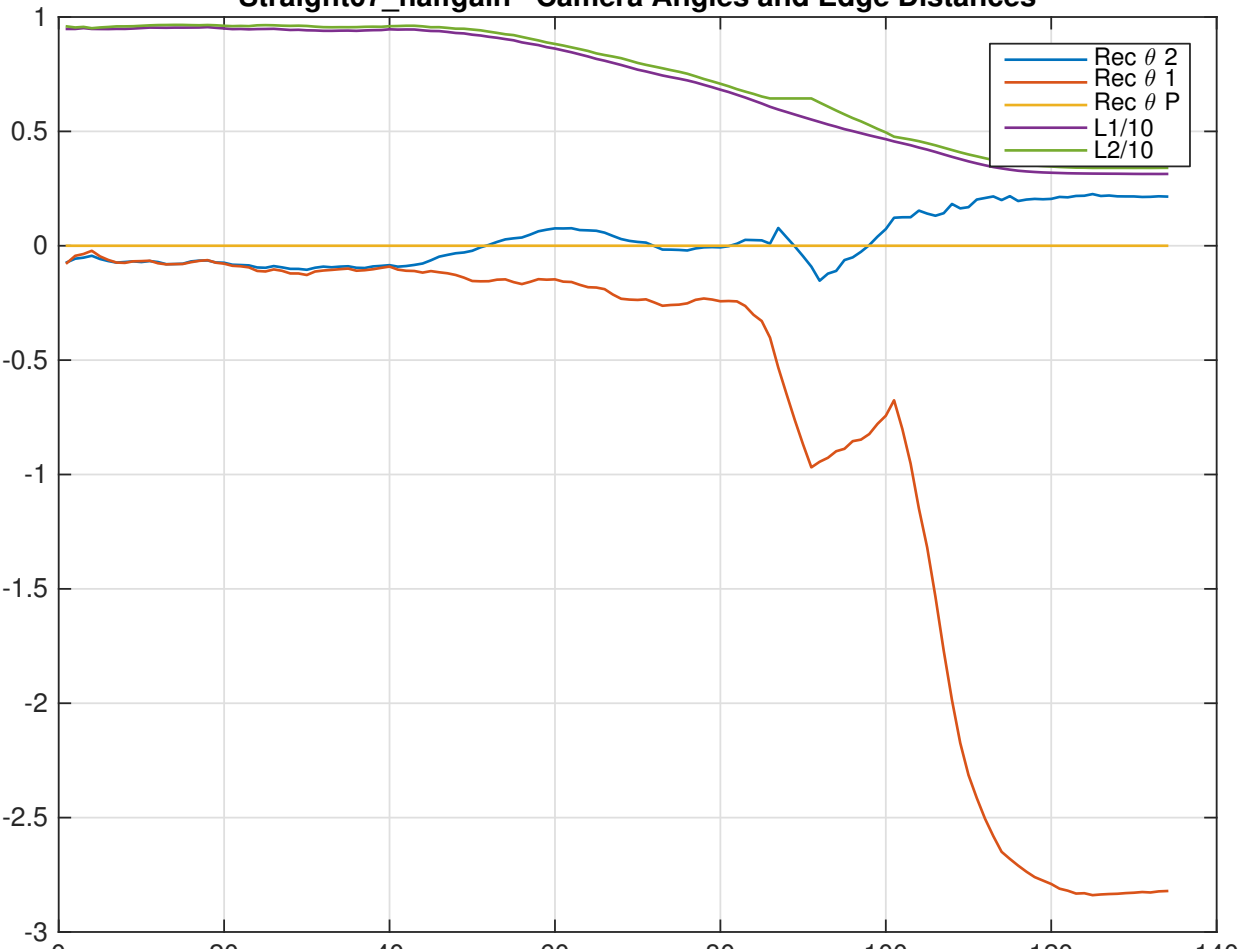
Straight07_halfgain Camera vs LIDAR Theta_1



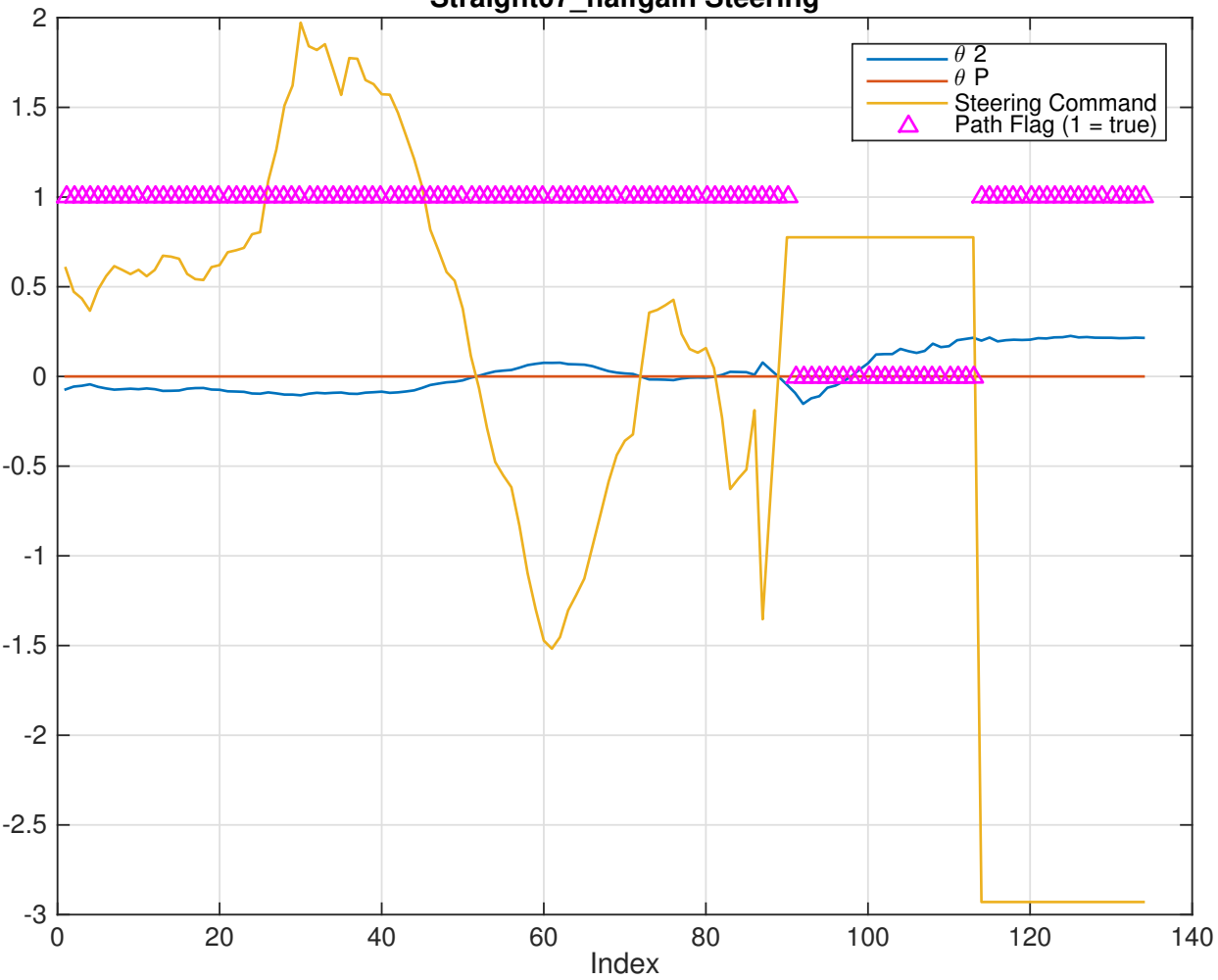
Straight07_halfgain Camera vs LIDAR Theta_2



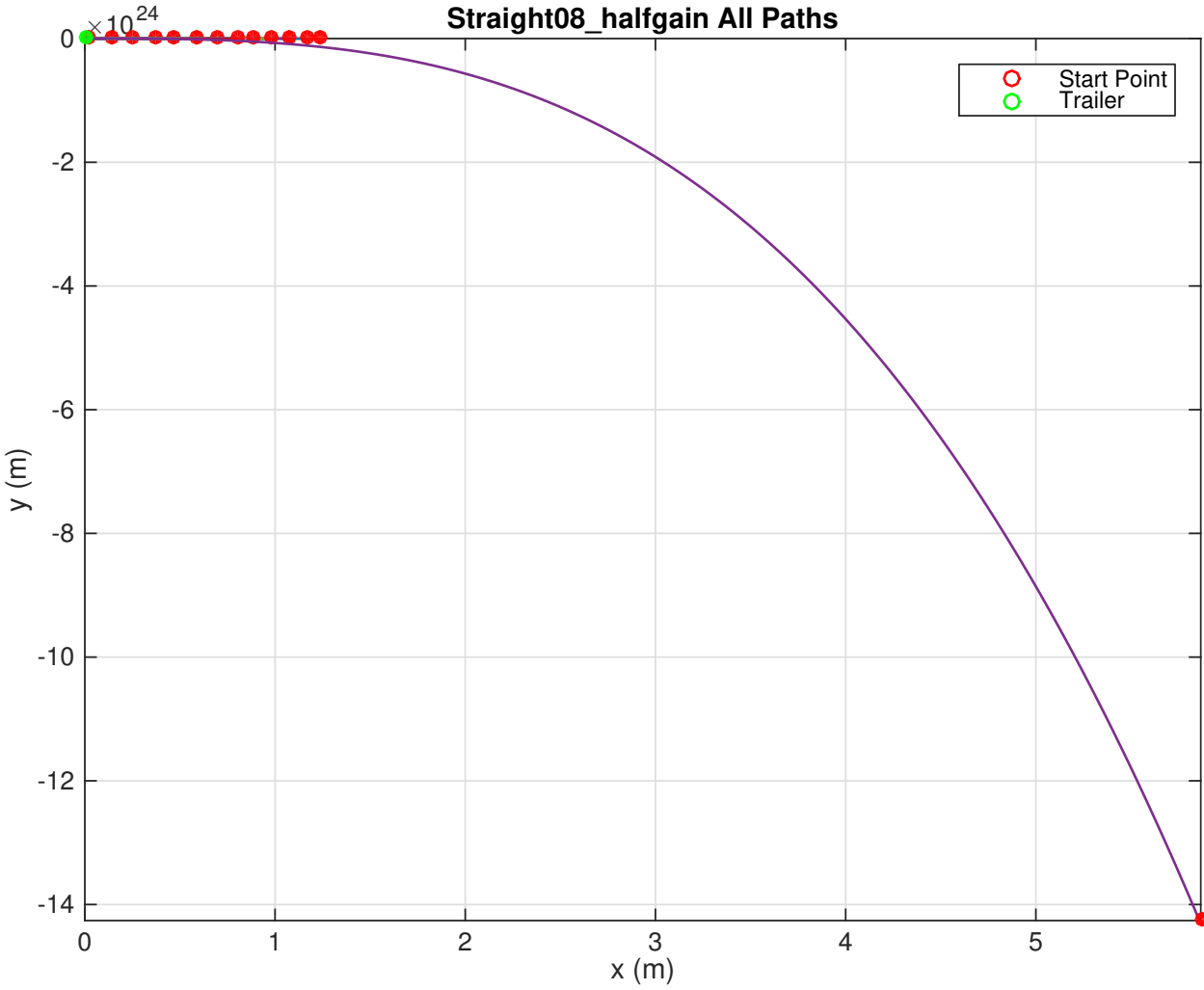
Straight07_halfgain Camera Angles and Edge Distances



Straight07_halfgain Steering



Straight08_halfgain All Paths



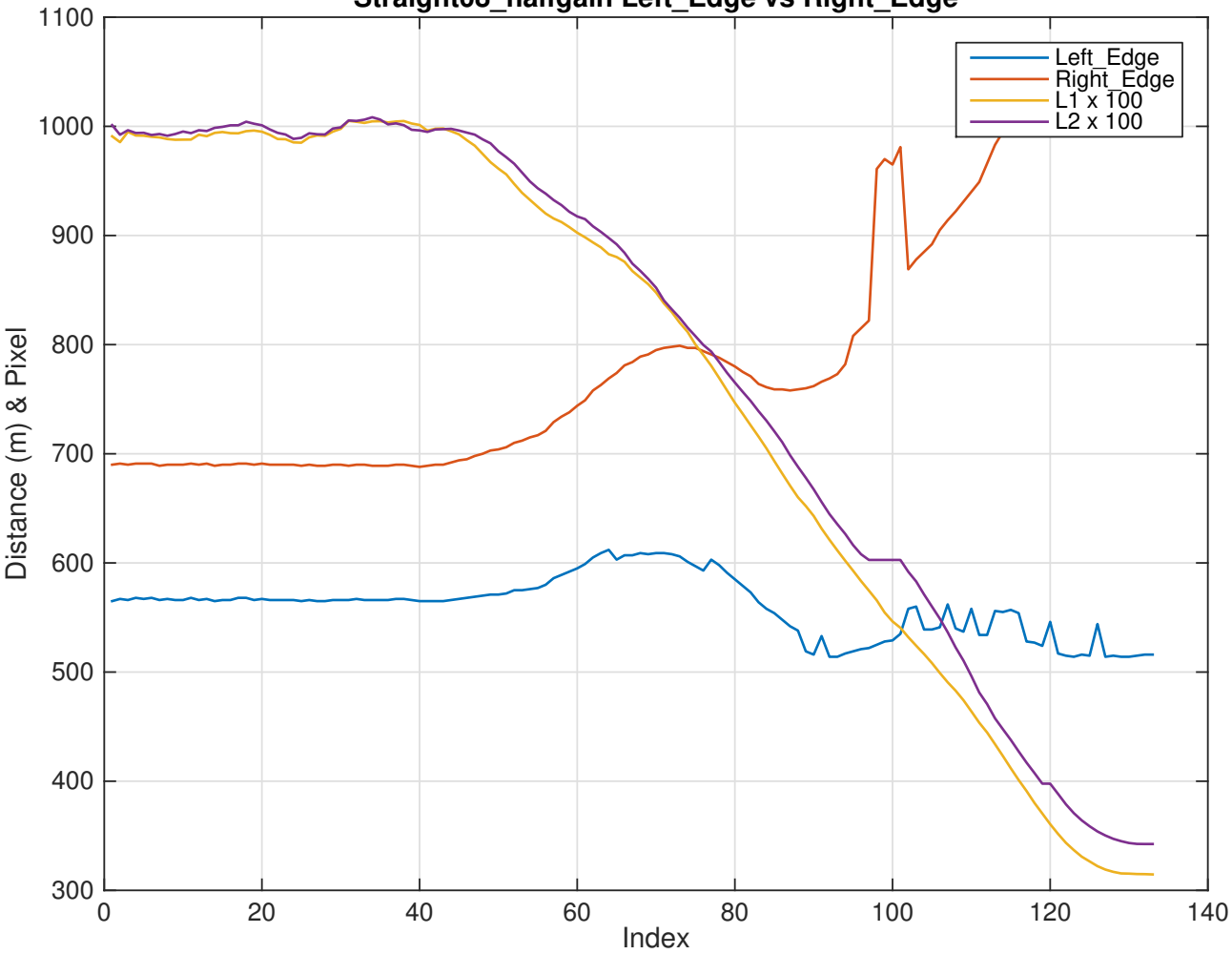
Number_Of_Unique_Paths

King_Pin_Detected

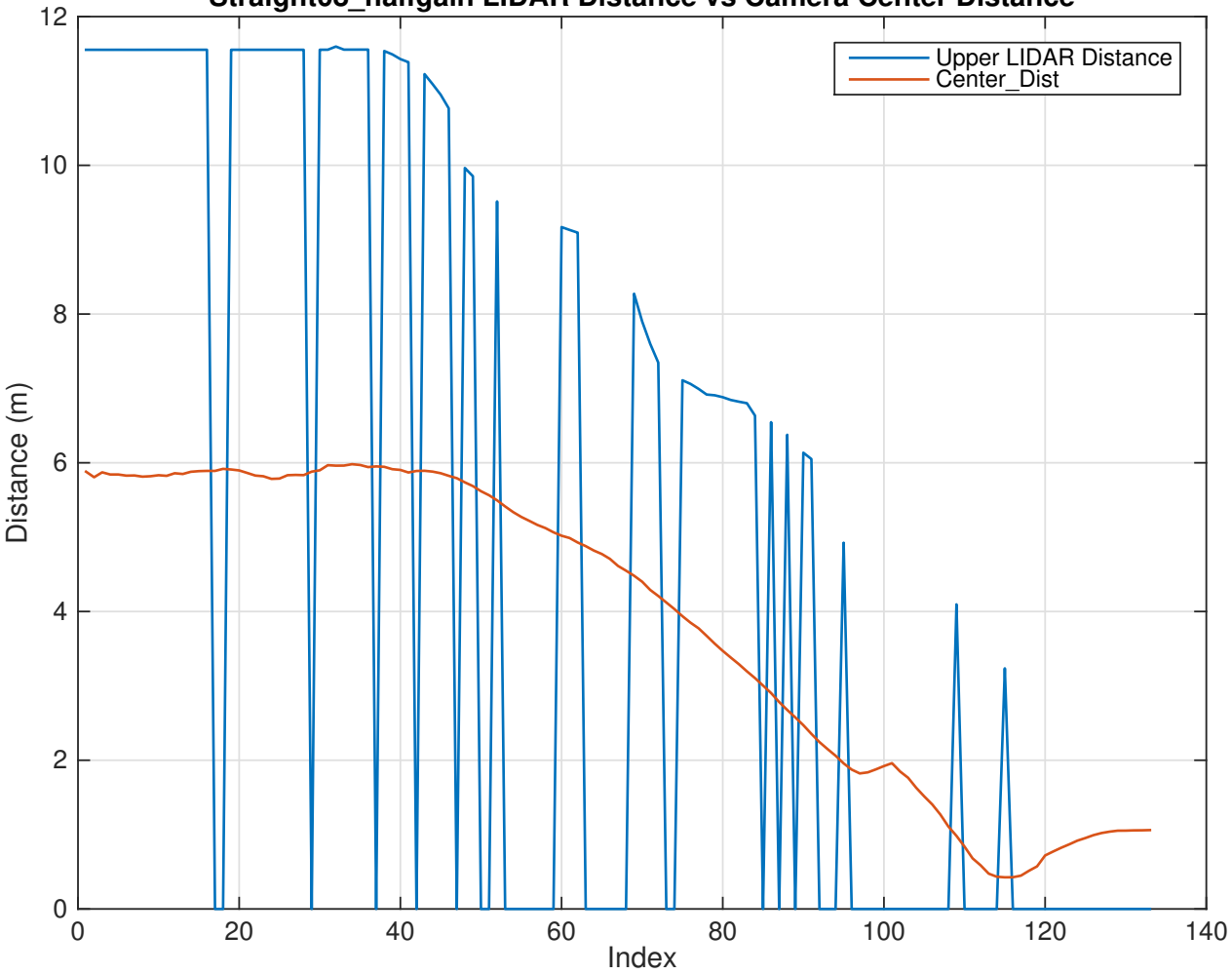
32

false

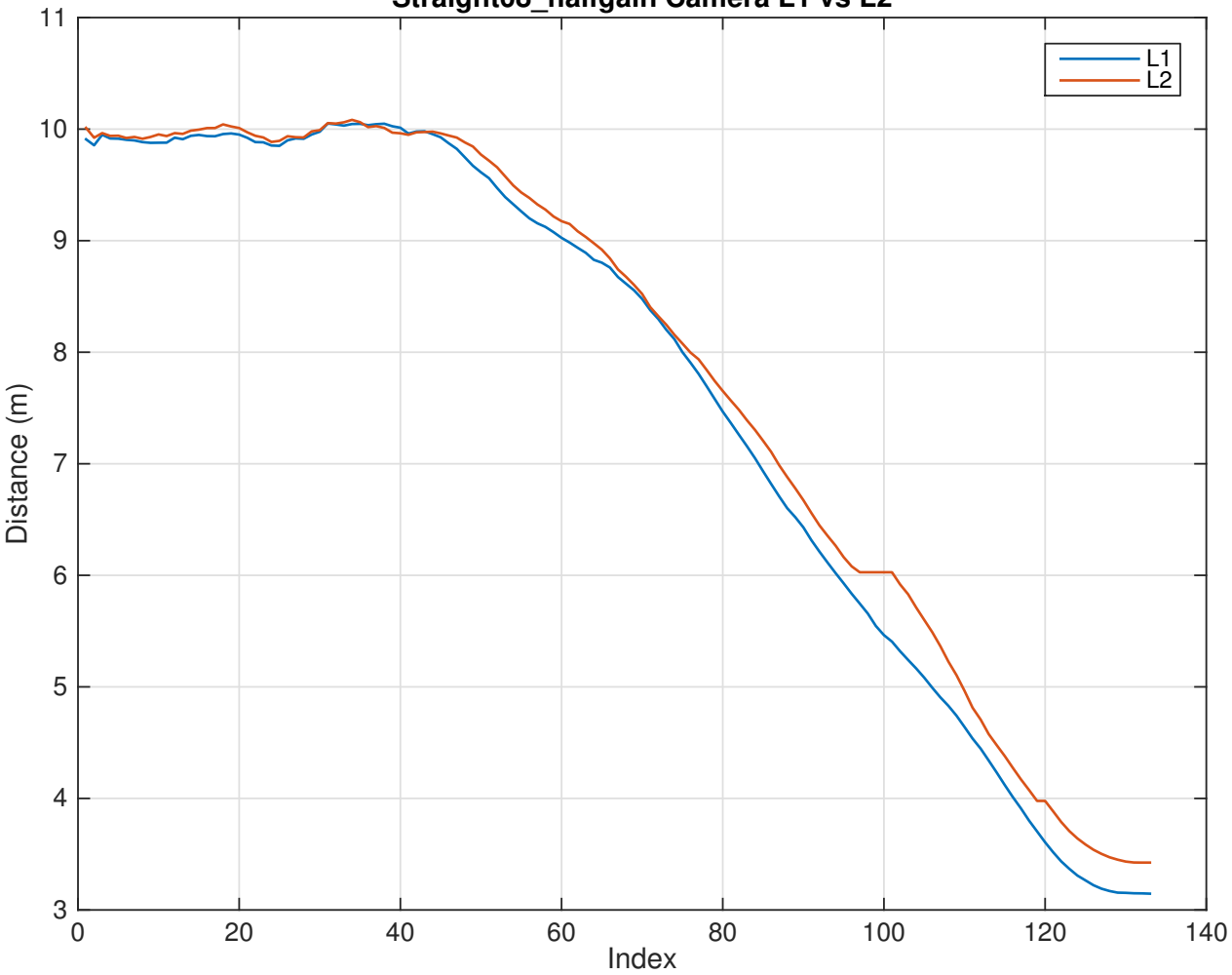
Straight08_halfgain Left_Edge vs Right_Edge



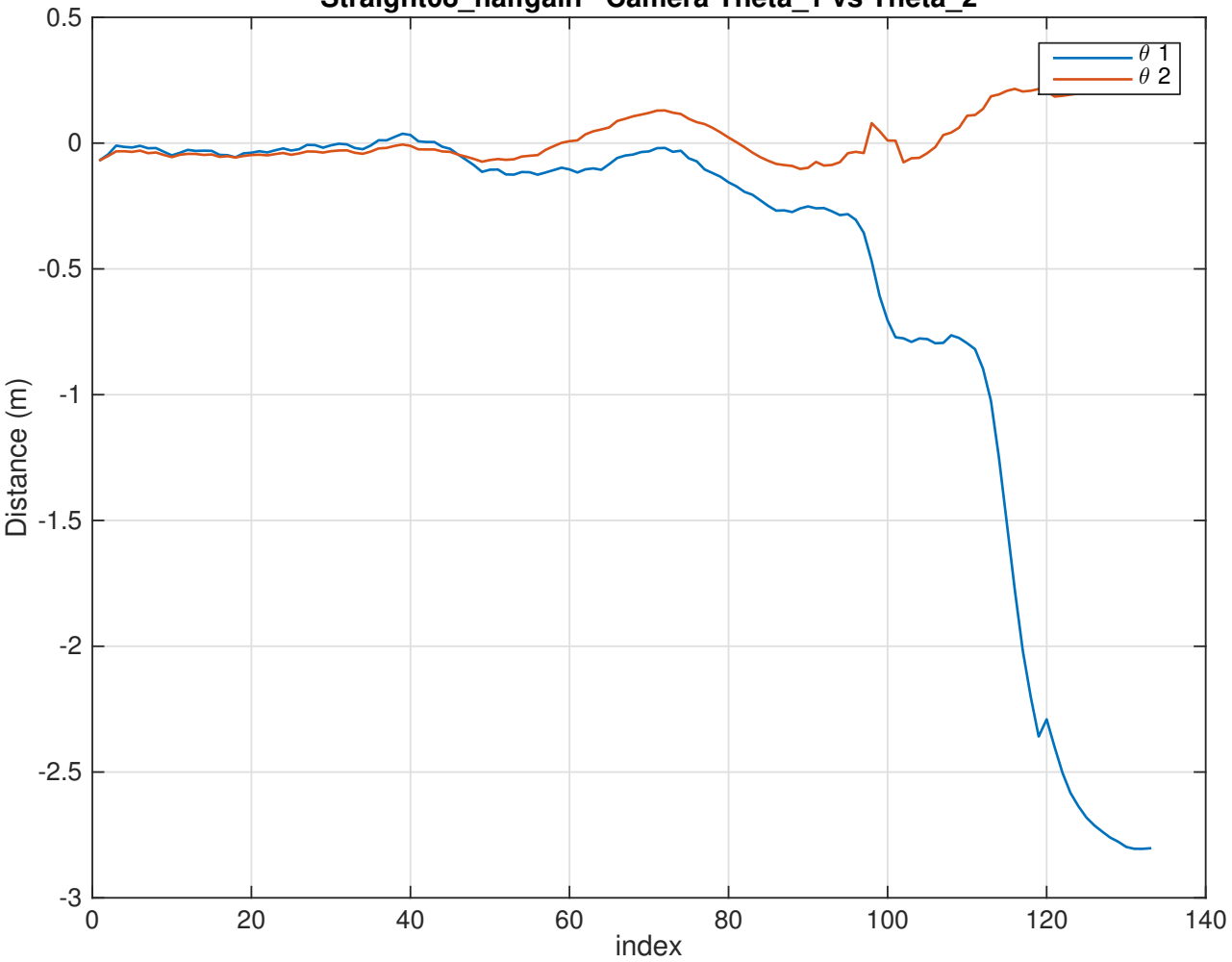
Straight08_halfgain LIDAR Distance vs Camera Center Distance



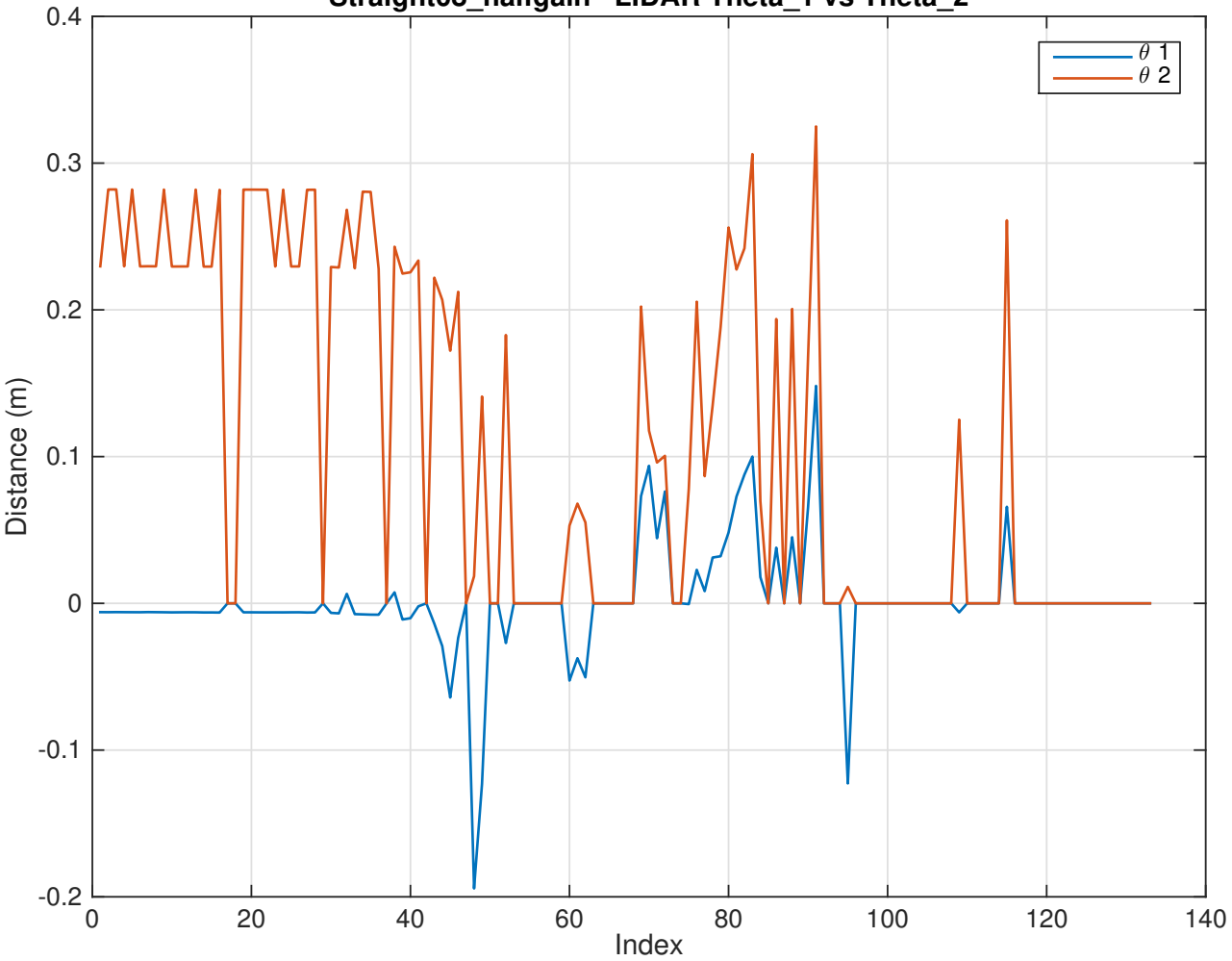
Straight08_halfgain Camera L1 vs L2



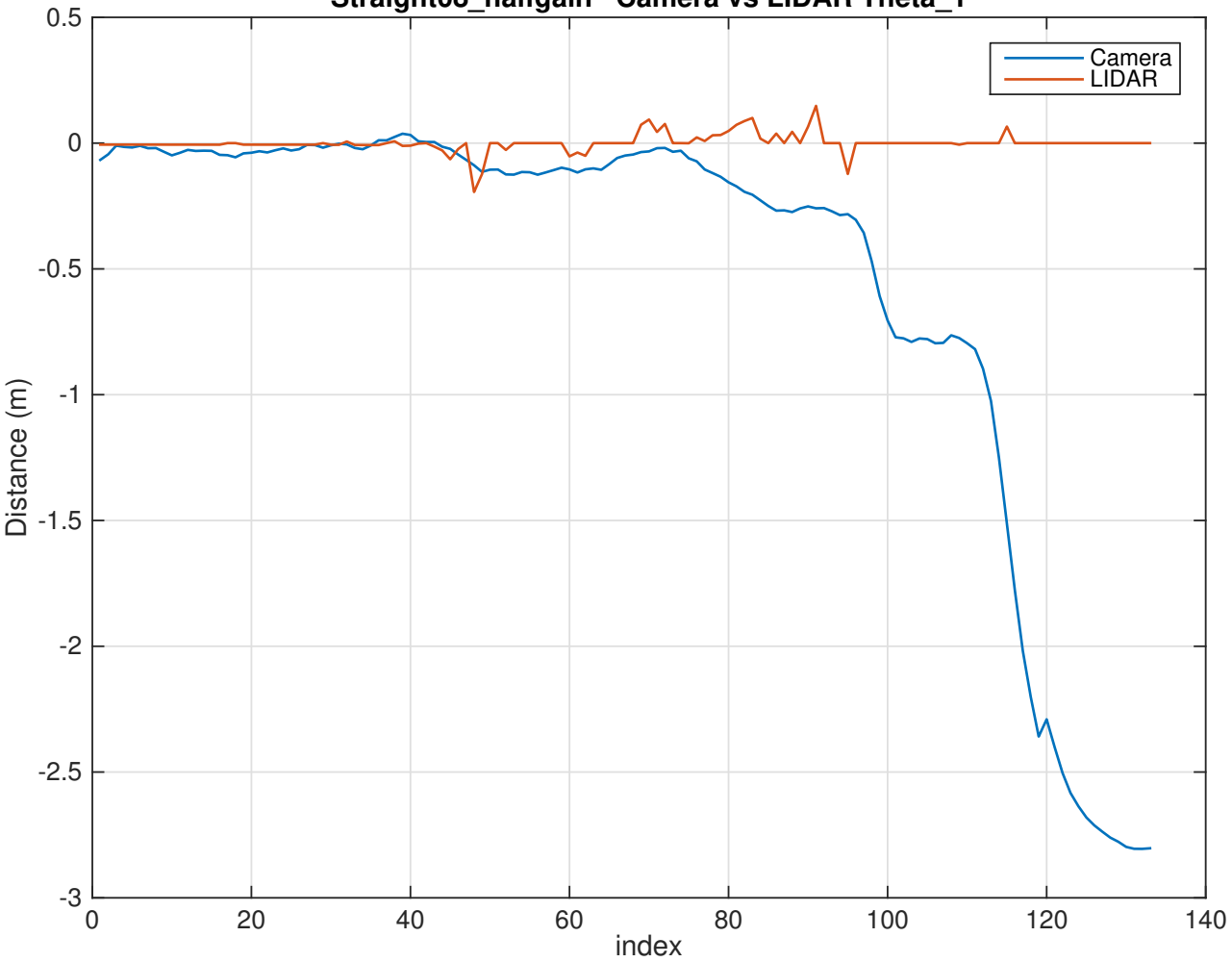
Straight08_halfgain Camera Theta_1 vs Theta_2



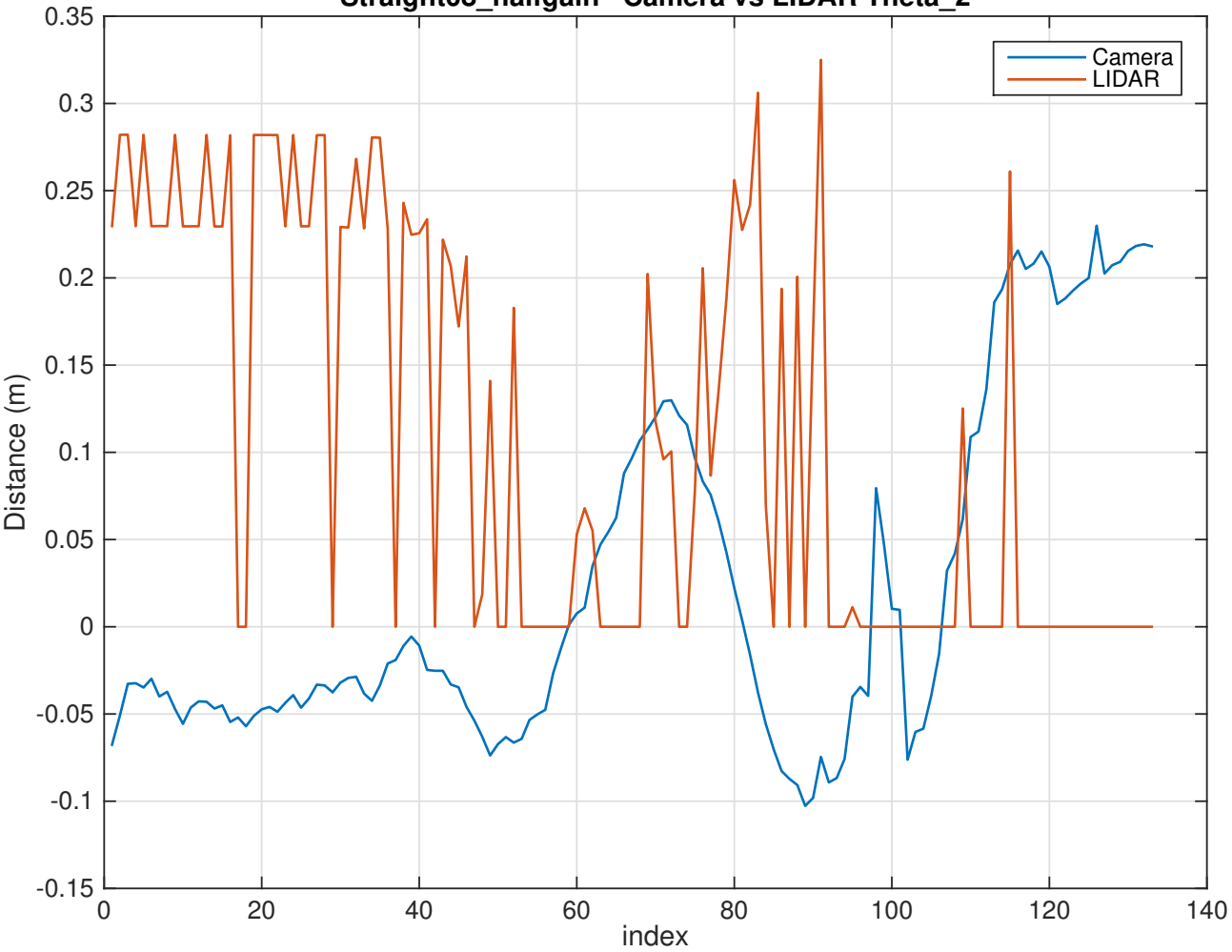
Straight08_halfgain LIDAR Theta_1 vs Theta_2



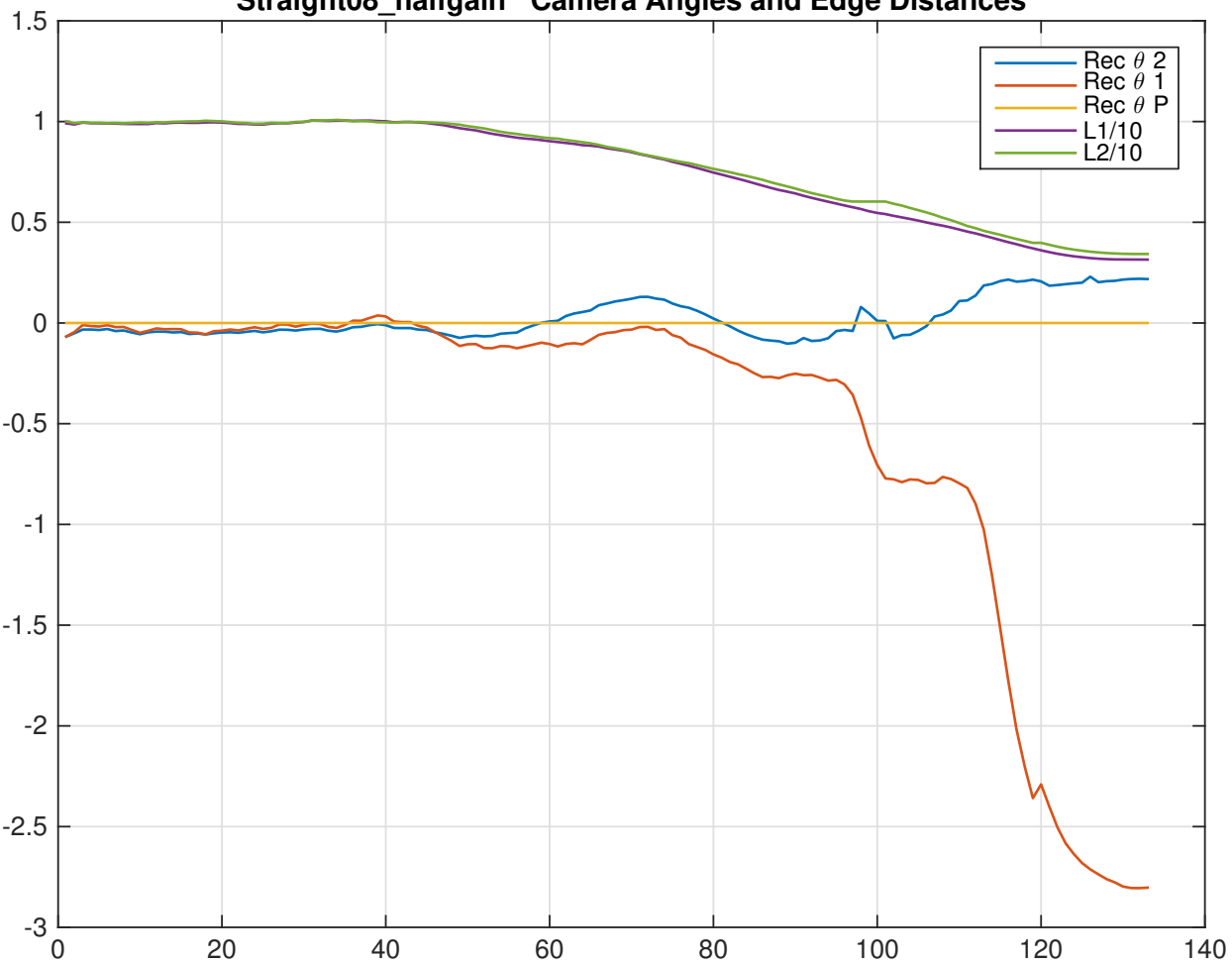
Straight08_halfgain Camera vs LIDAR Theta_1



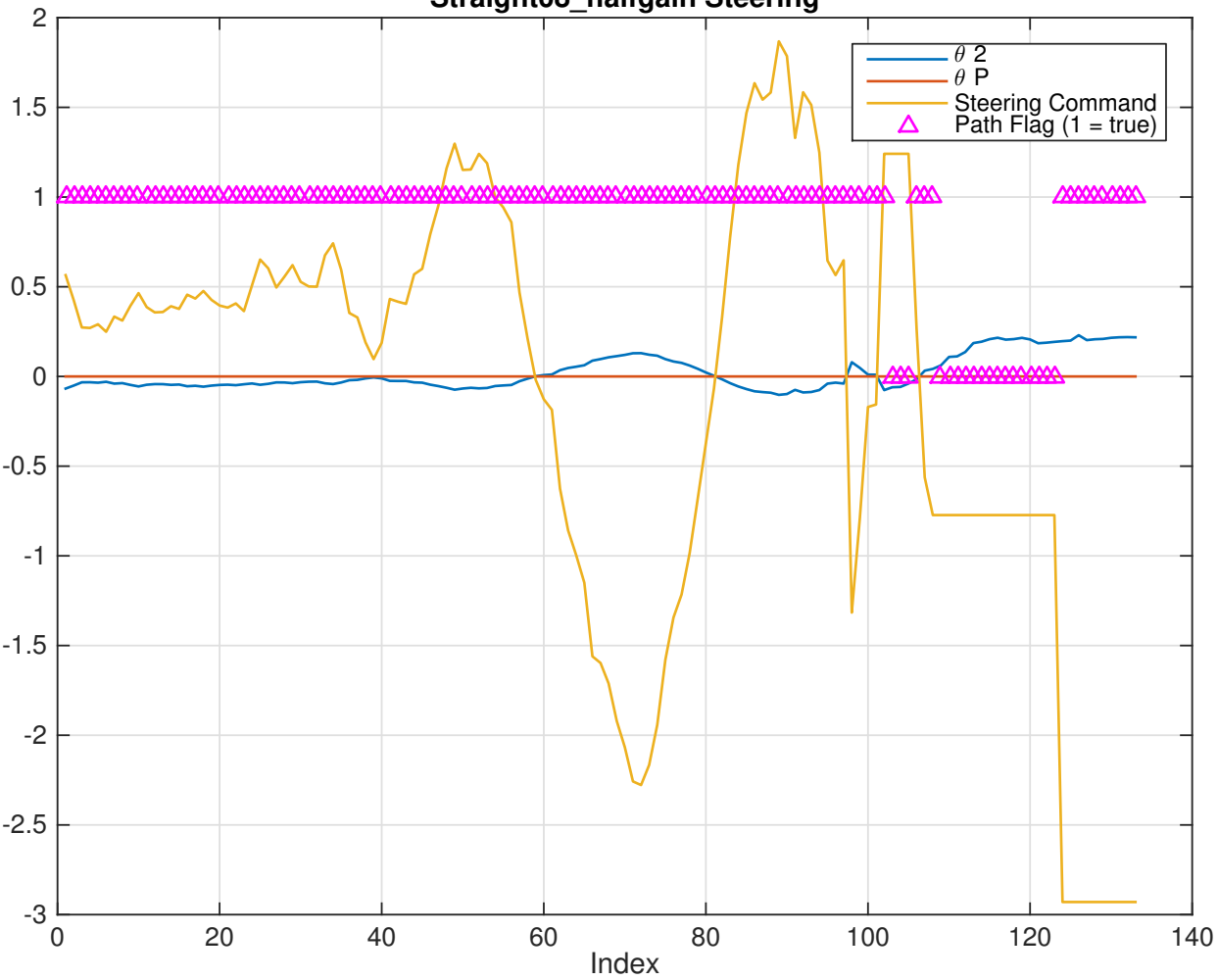
Straight08_halfgain Camera vs LIDAR Theta_2

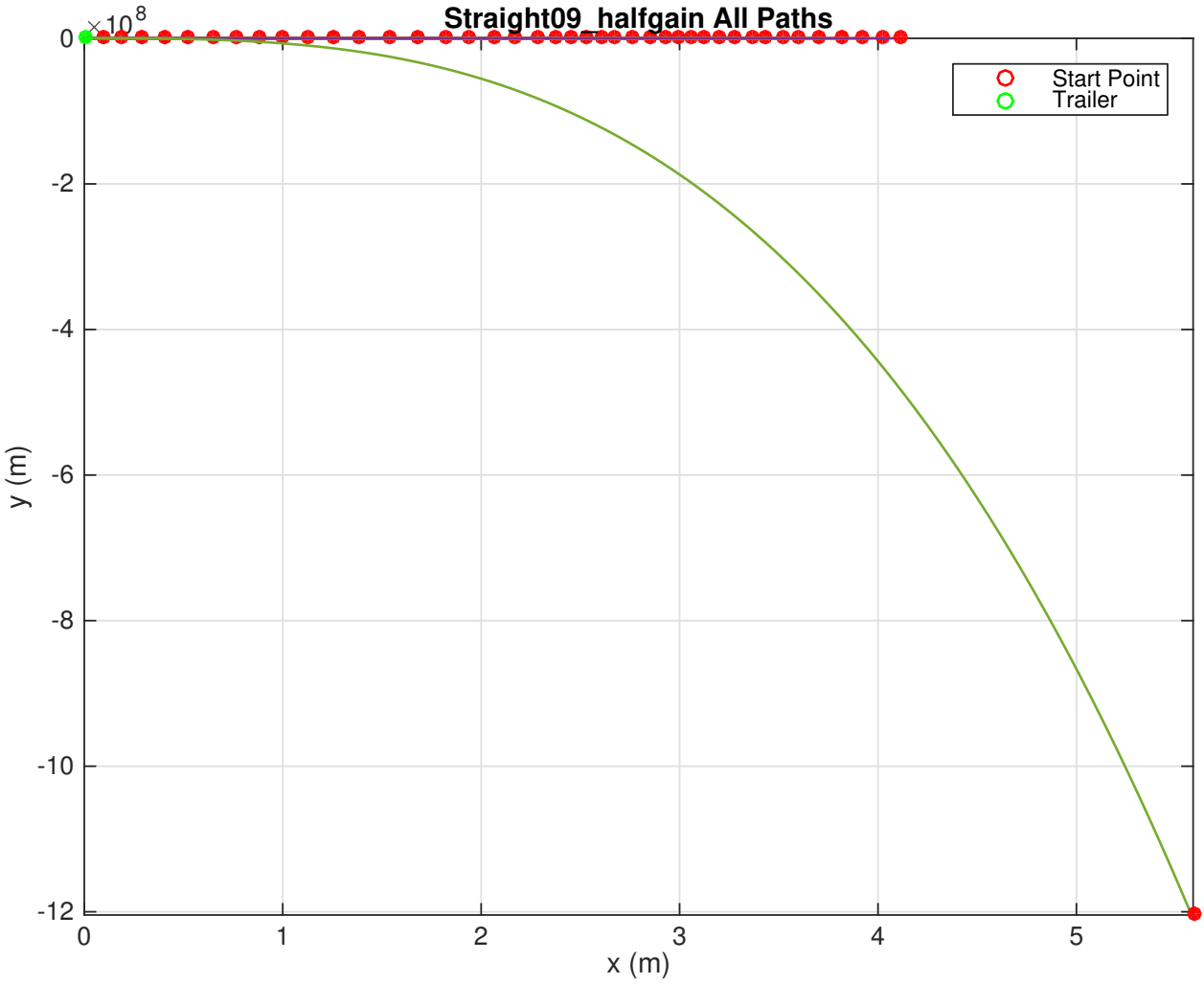


Straight08_halfgain Camera Angles and Edge Distances



Straight08_halfgain Steering





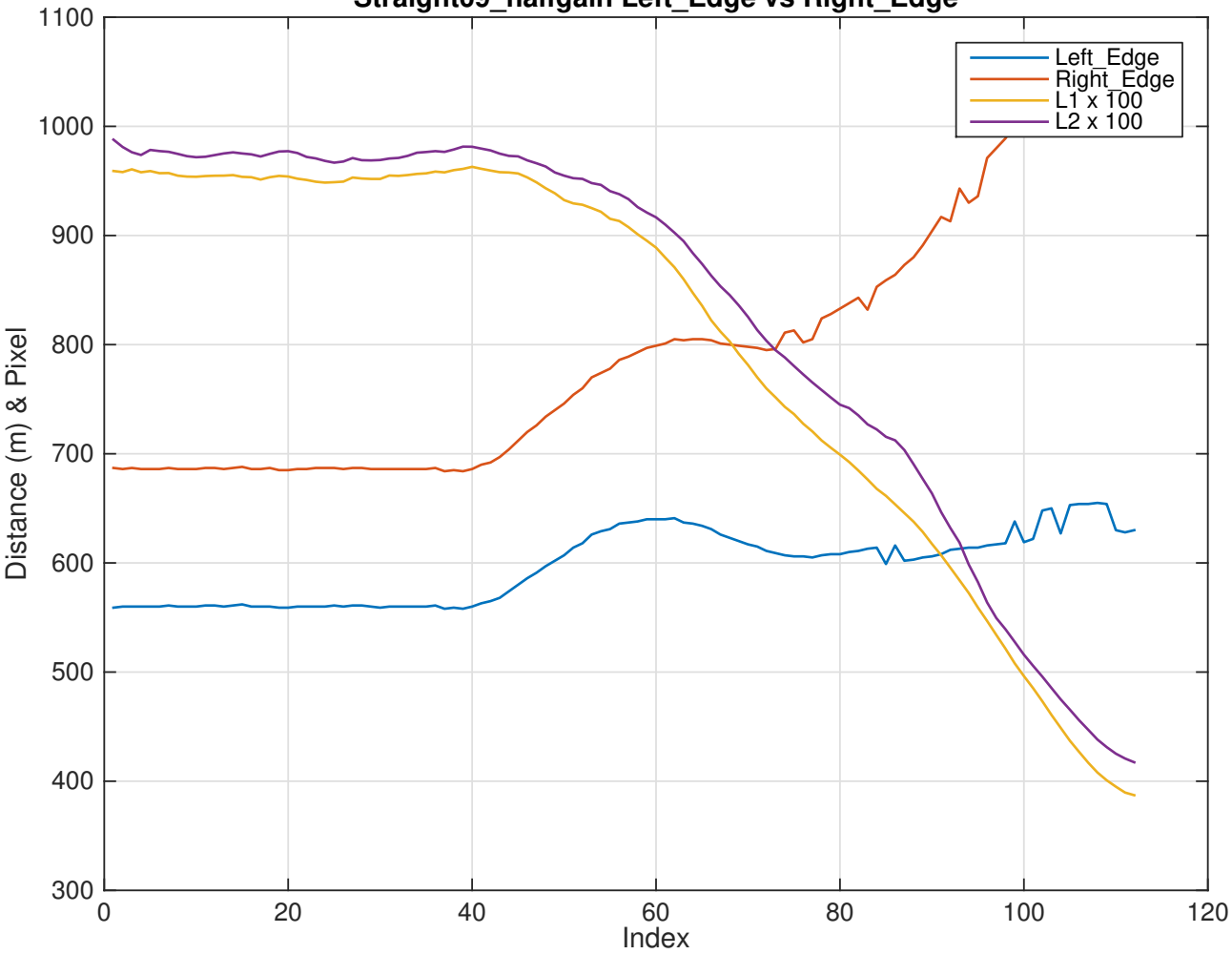
Number_Of_Unique_Paths

47

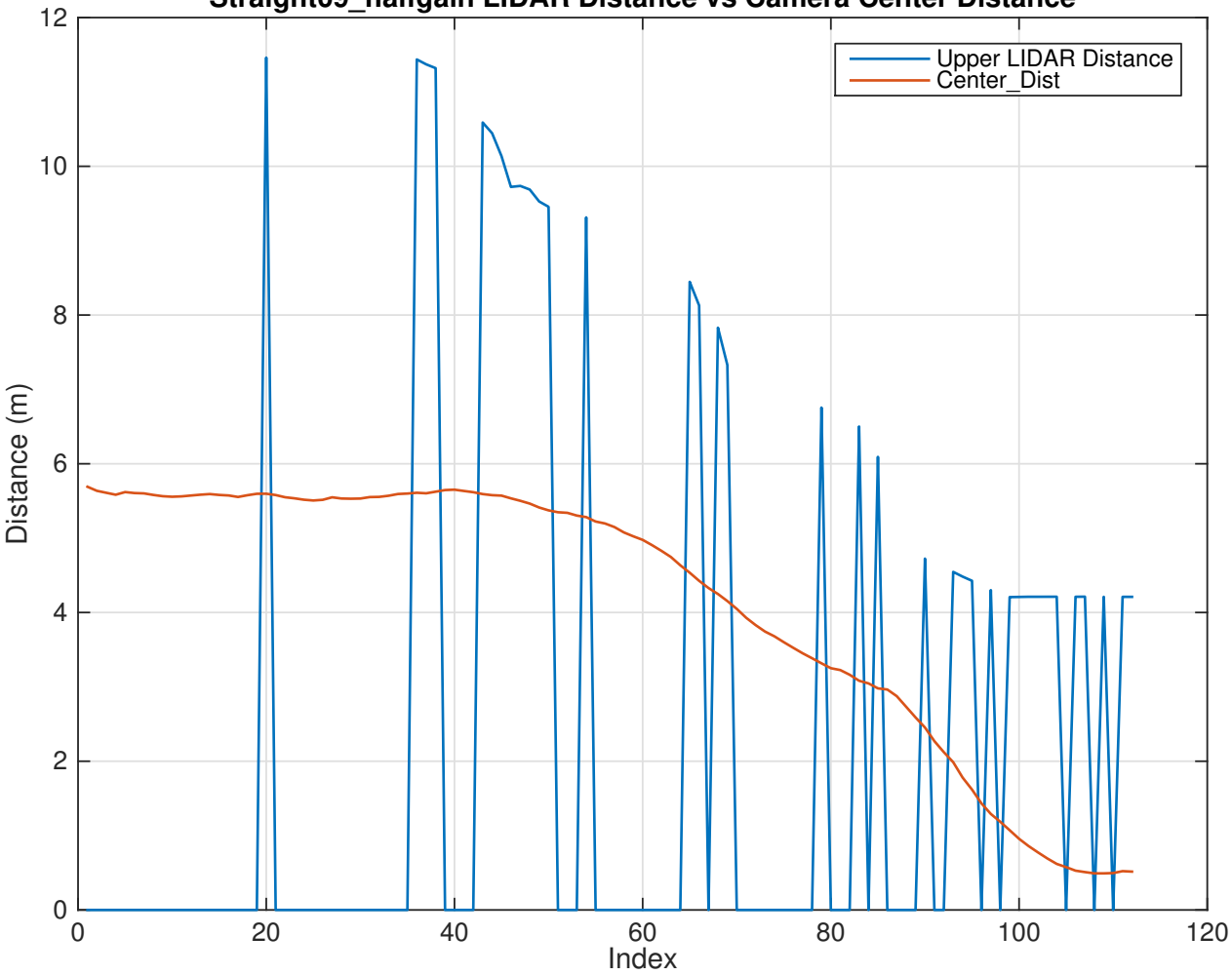
King_Pin_Detected

false

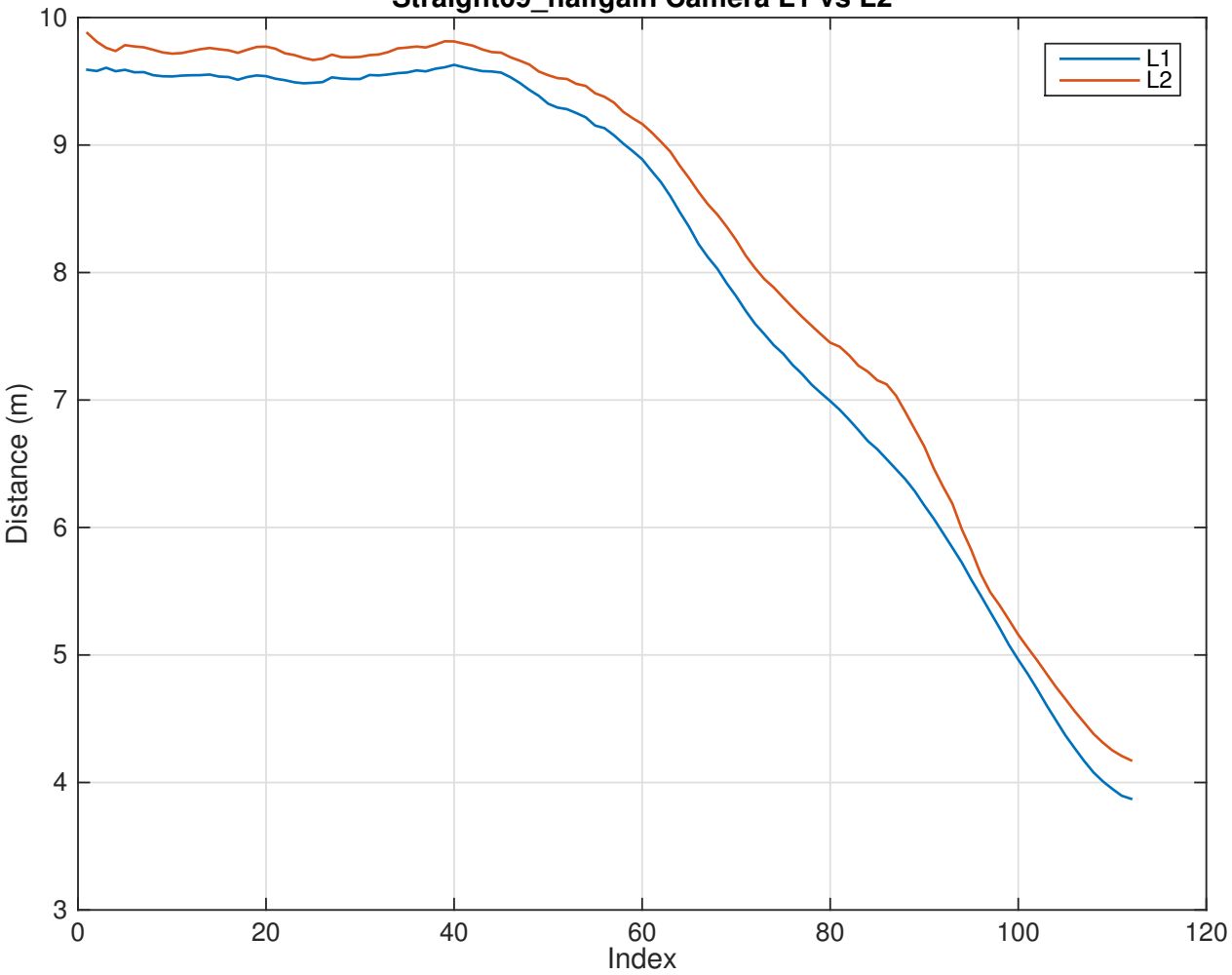
Straight09_halfgain Left_Edge vs Right_Edge



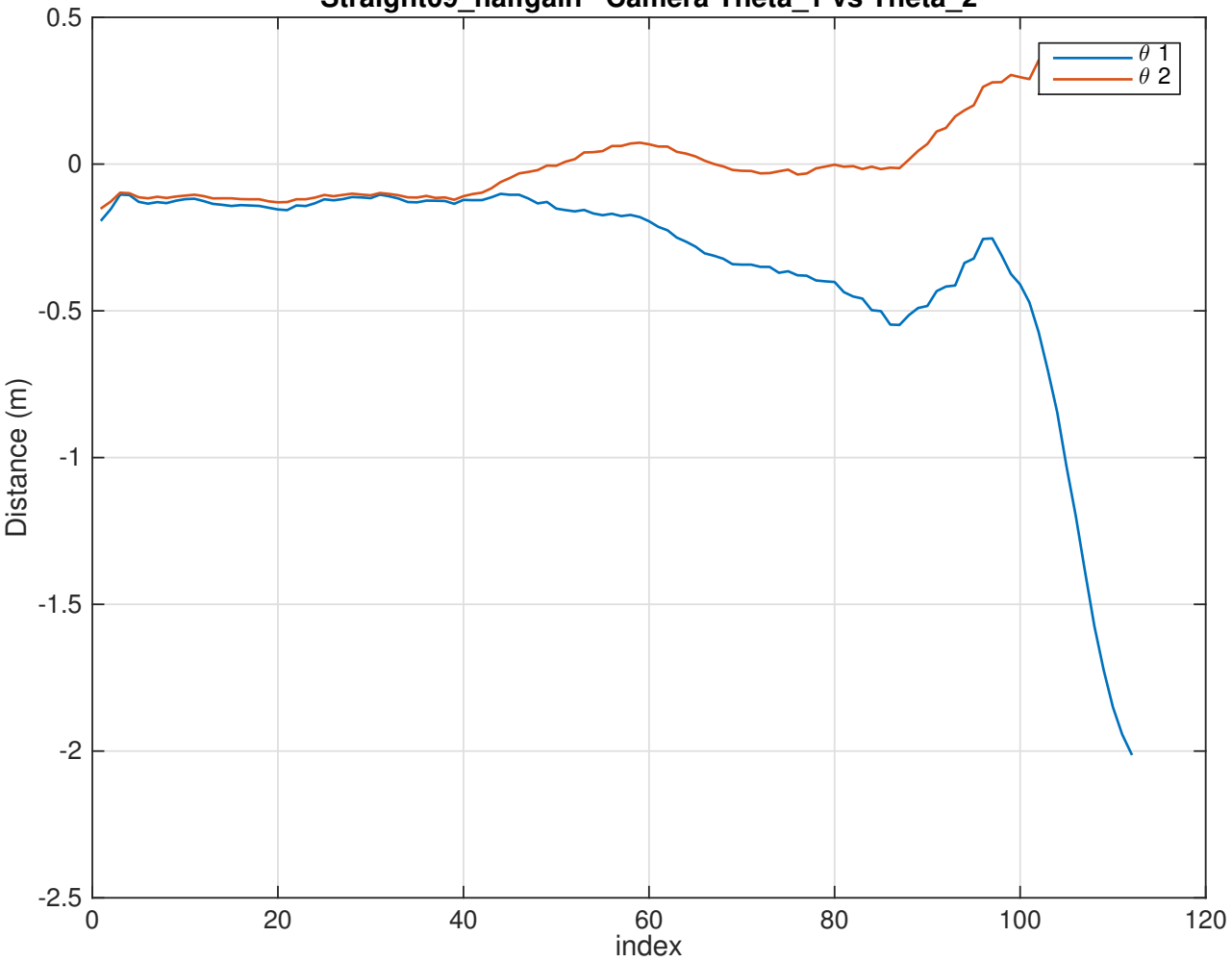
Straight09_halfgain LIDAR Distance vs Camera Center Distance



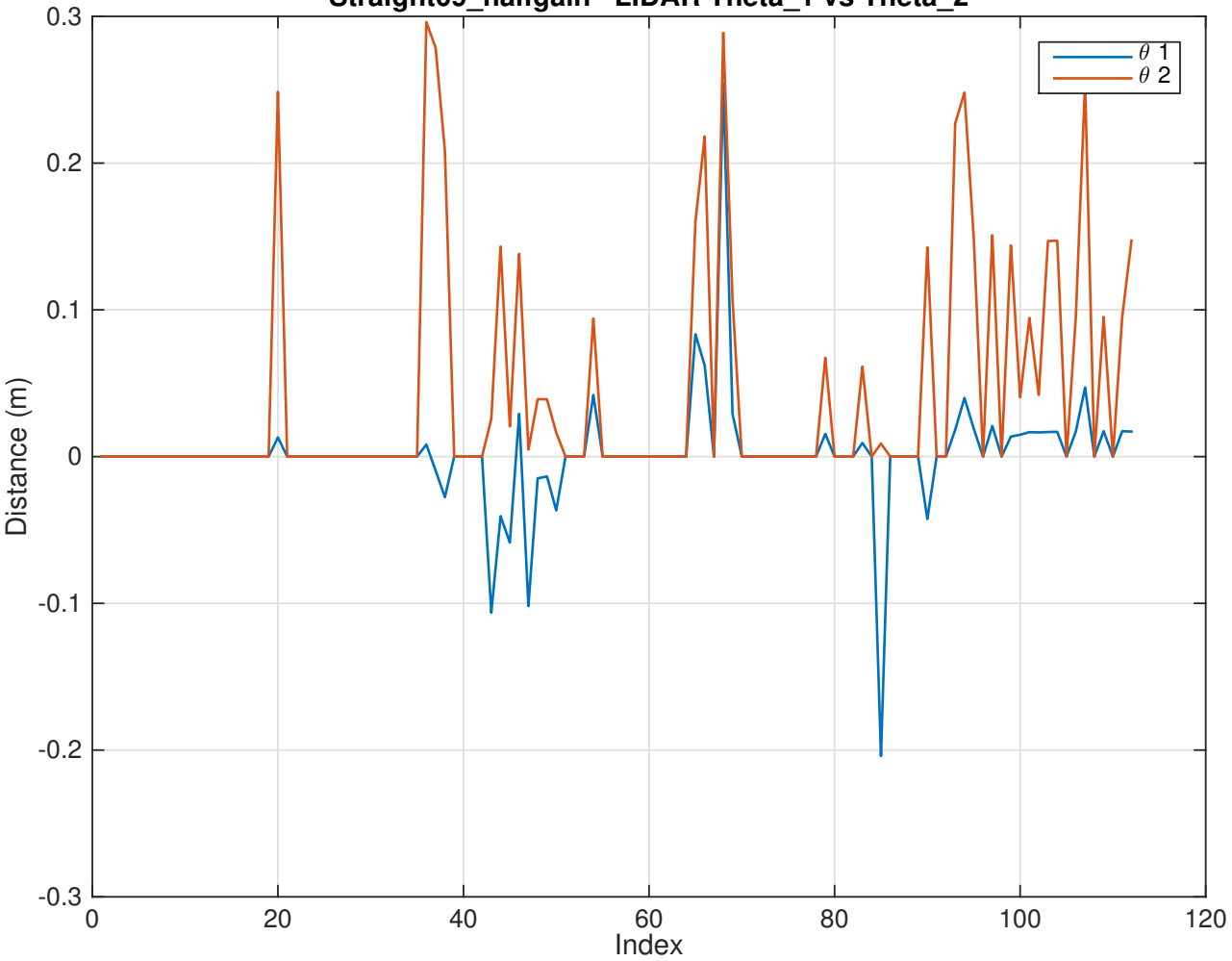
Straight09_halfgain Camera L1 vs L2



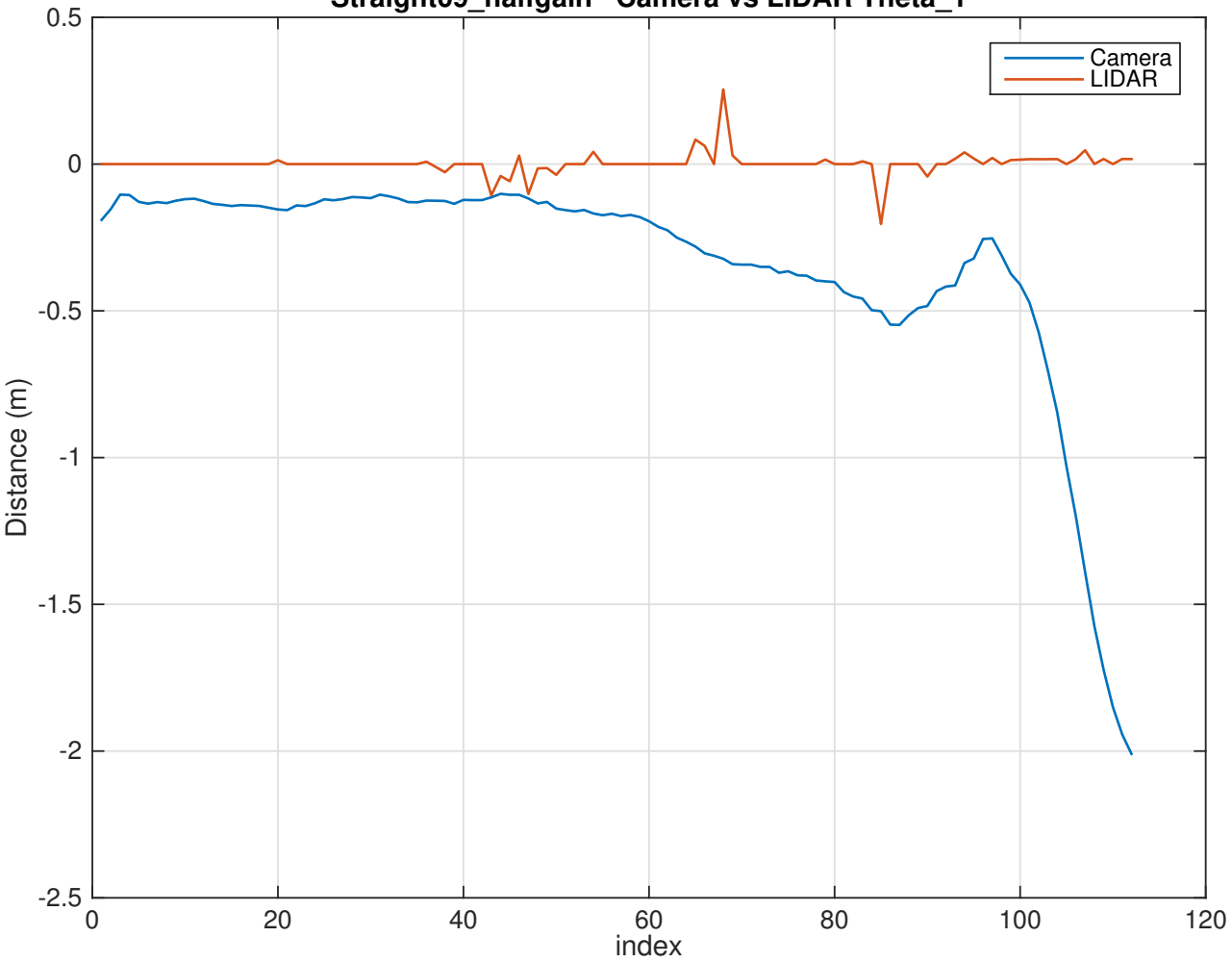
Straight09_halfgain Camera Theta_1 vs Theta_2



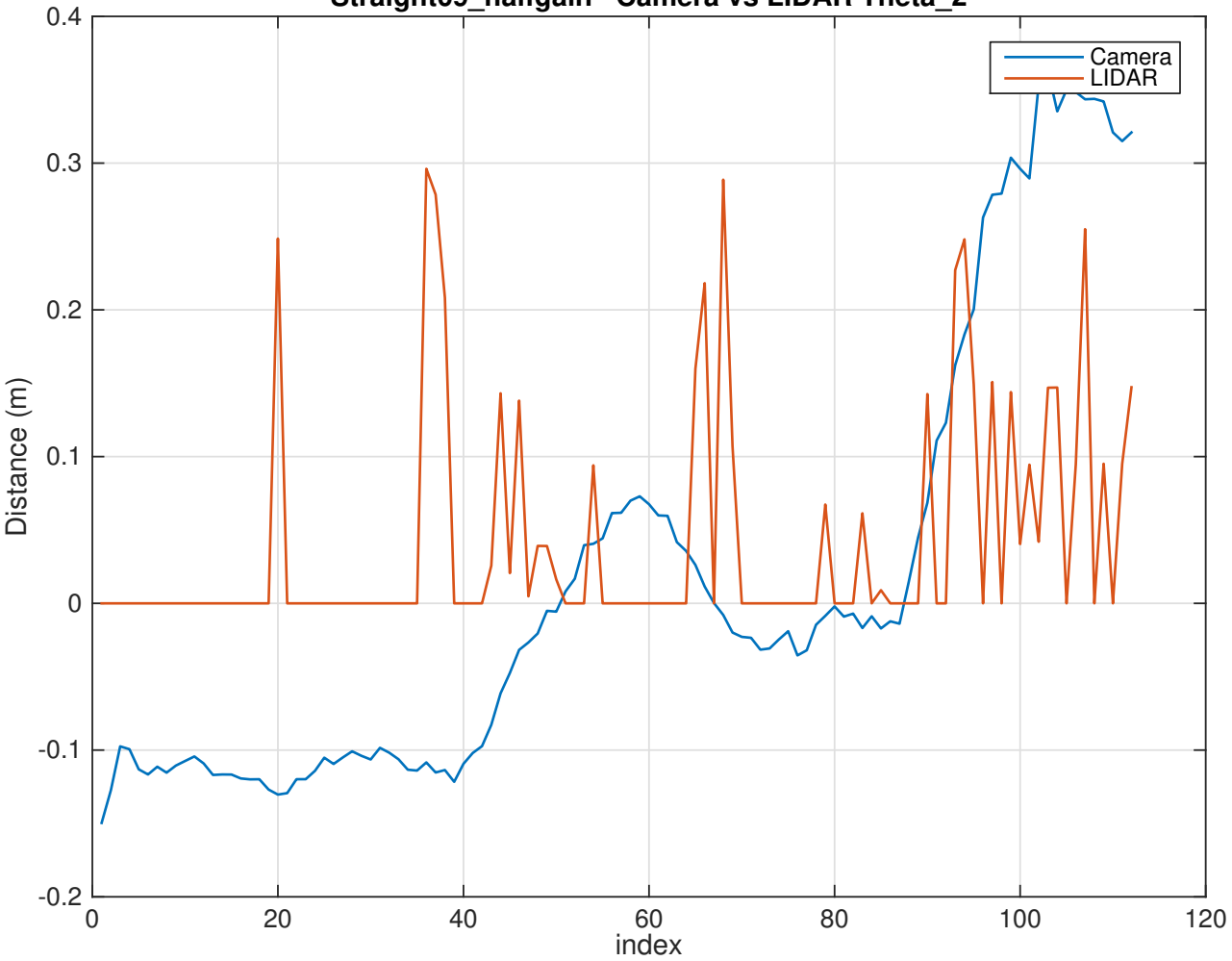
Straight09_halfgain LIDAR Theta_1 vs Theta_2



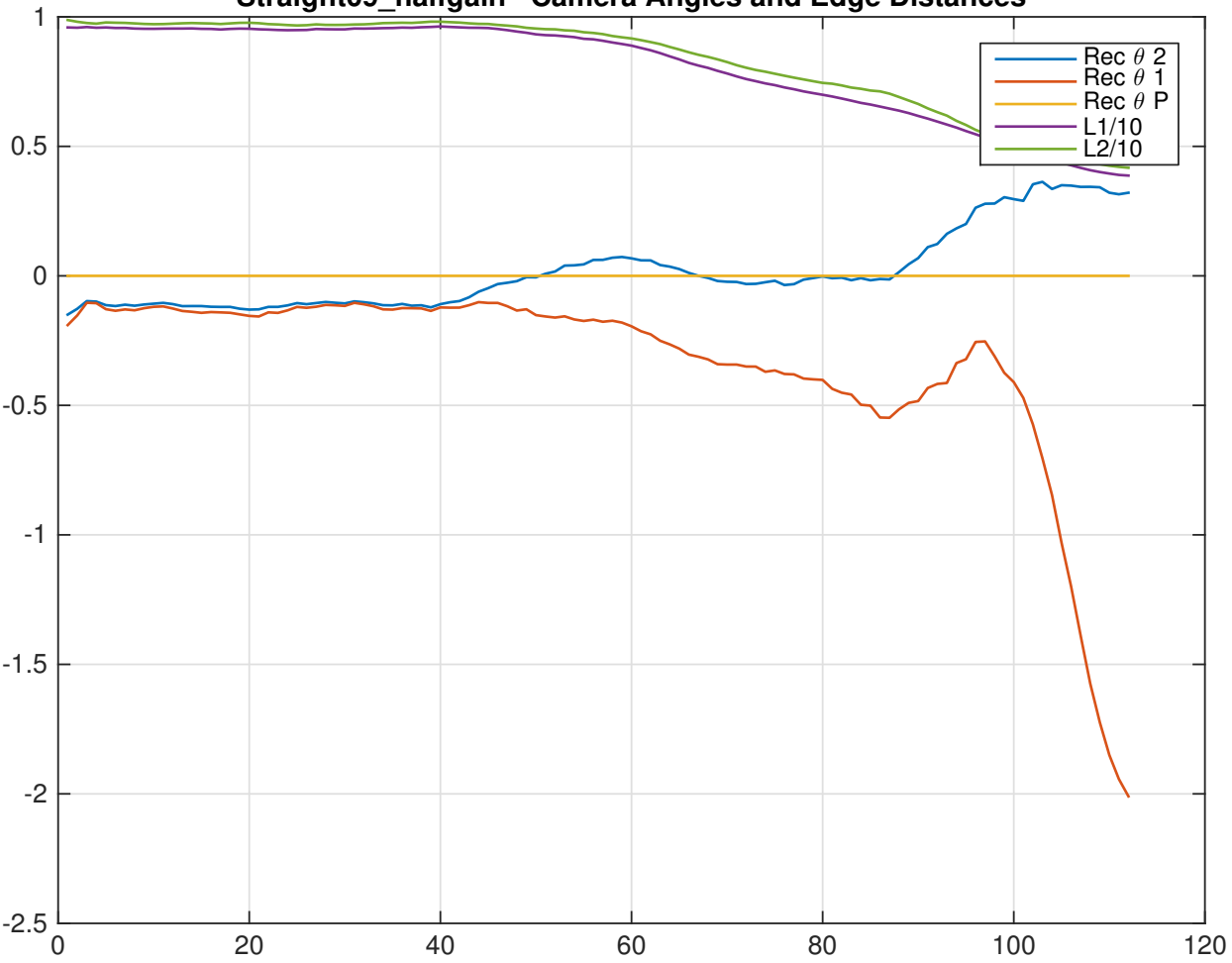
Straight09_halfgain Camera vs LIDAR Theta_1



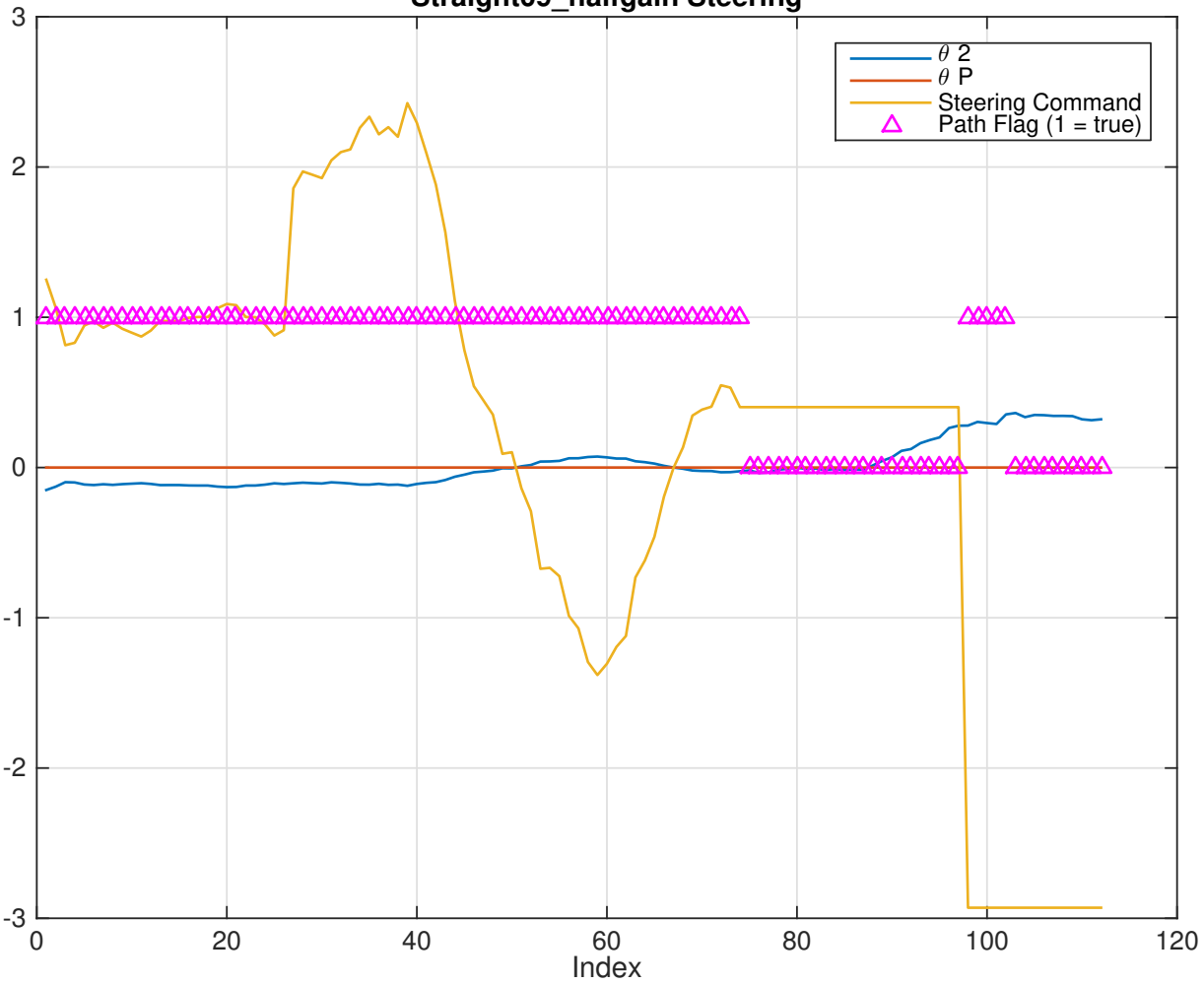
Straight09_halfgain Camera vs LIDAR Theta_2



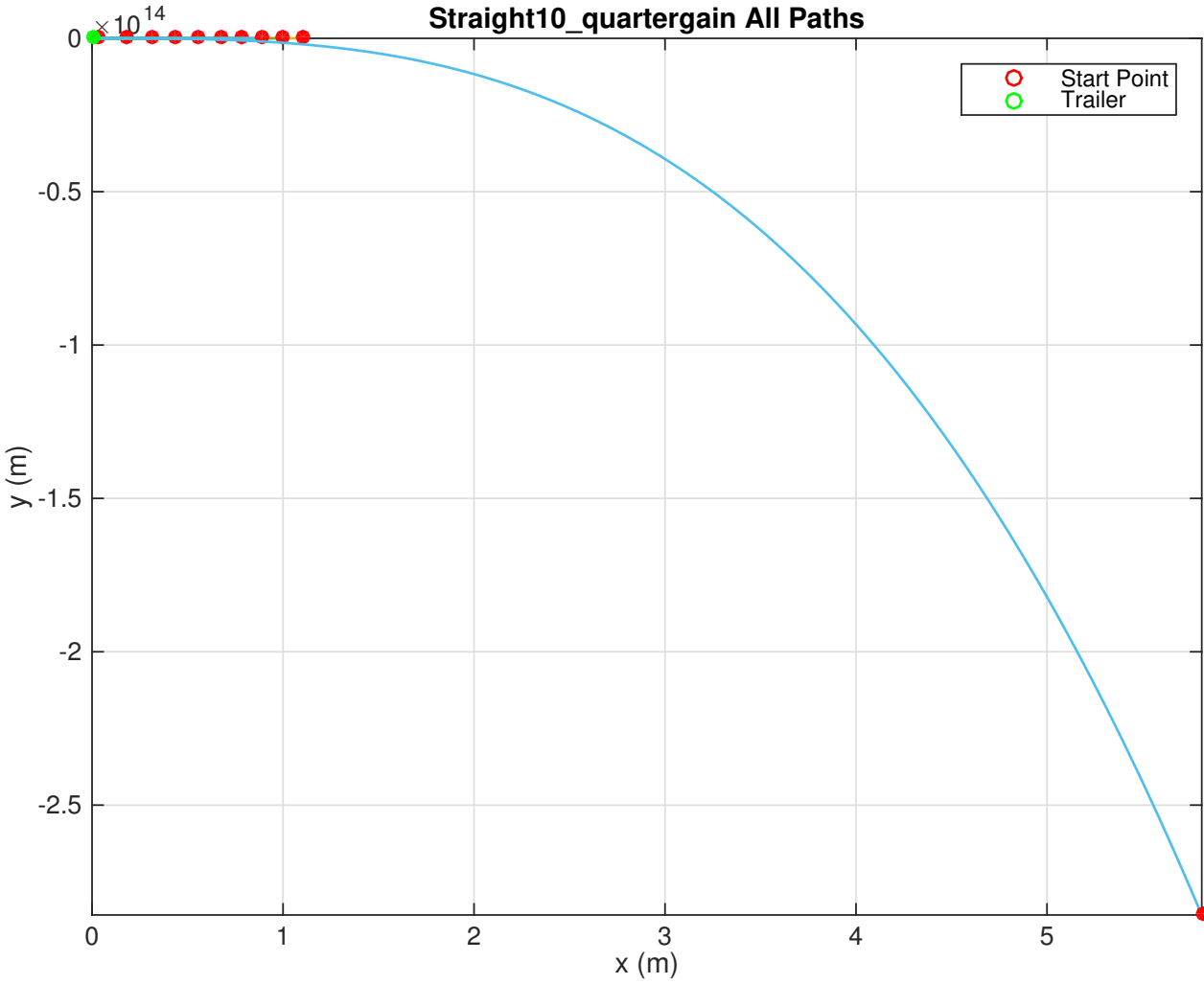
Straight09_halfgain Camera Angles and Edge Distances



Straight09_halfgain Steering



Straight10_quartergain All Paths



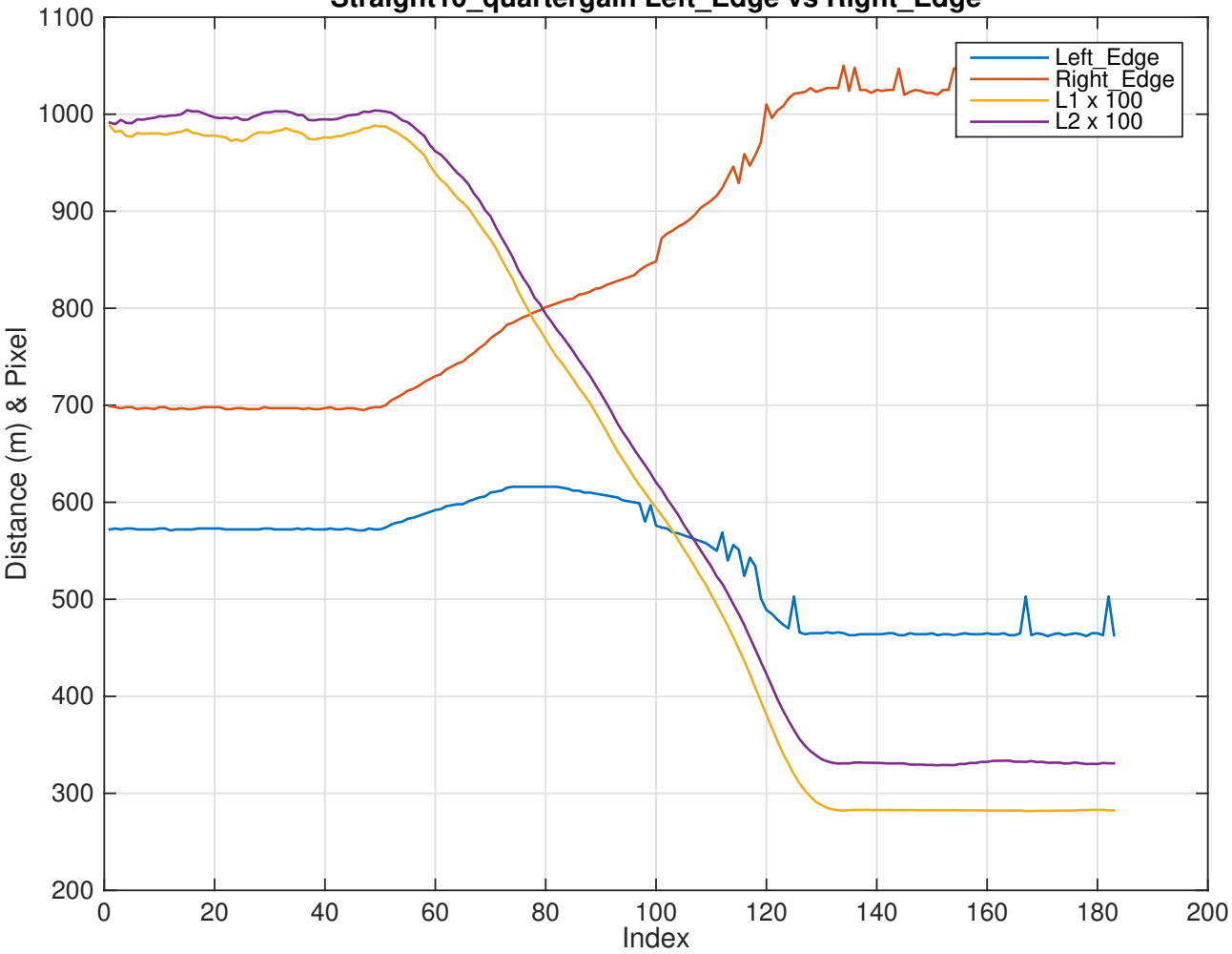
Number_Of_Unique_Paths

King_Pin_Detected

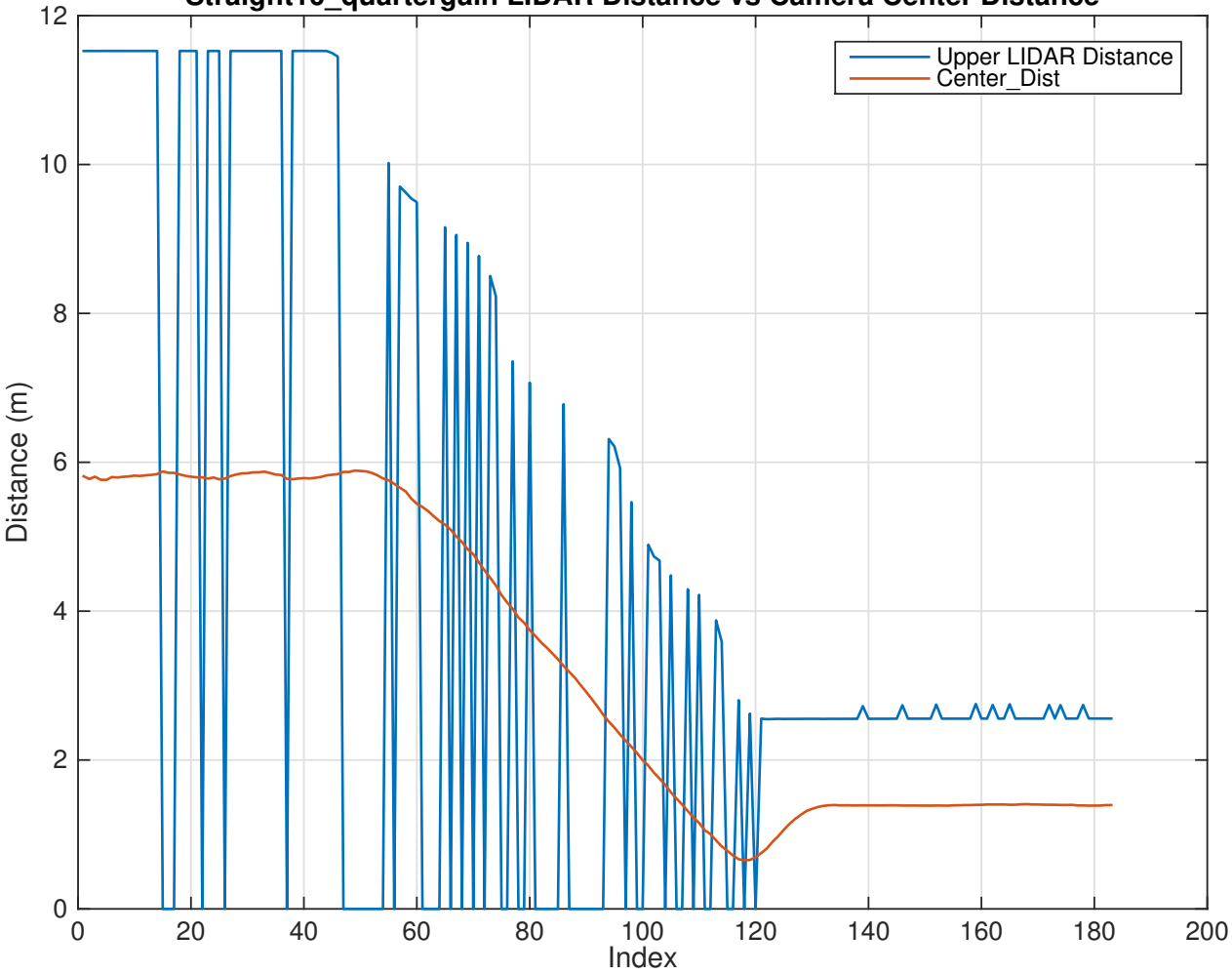
76

false

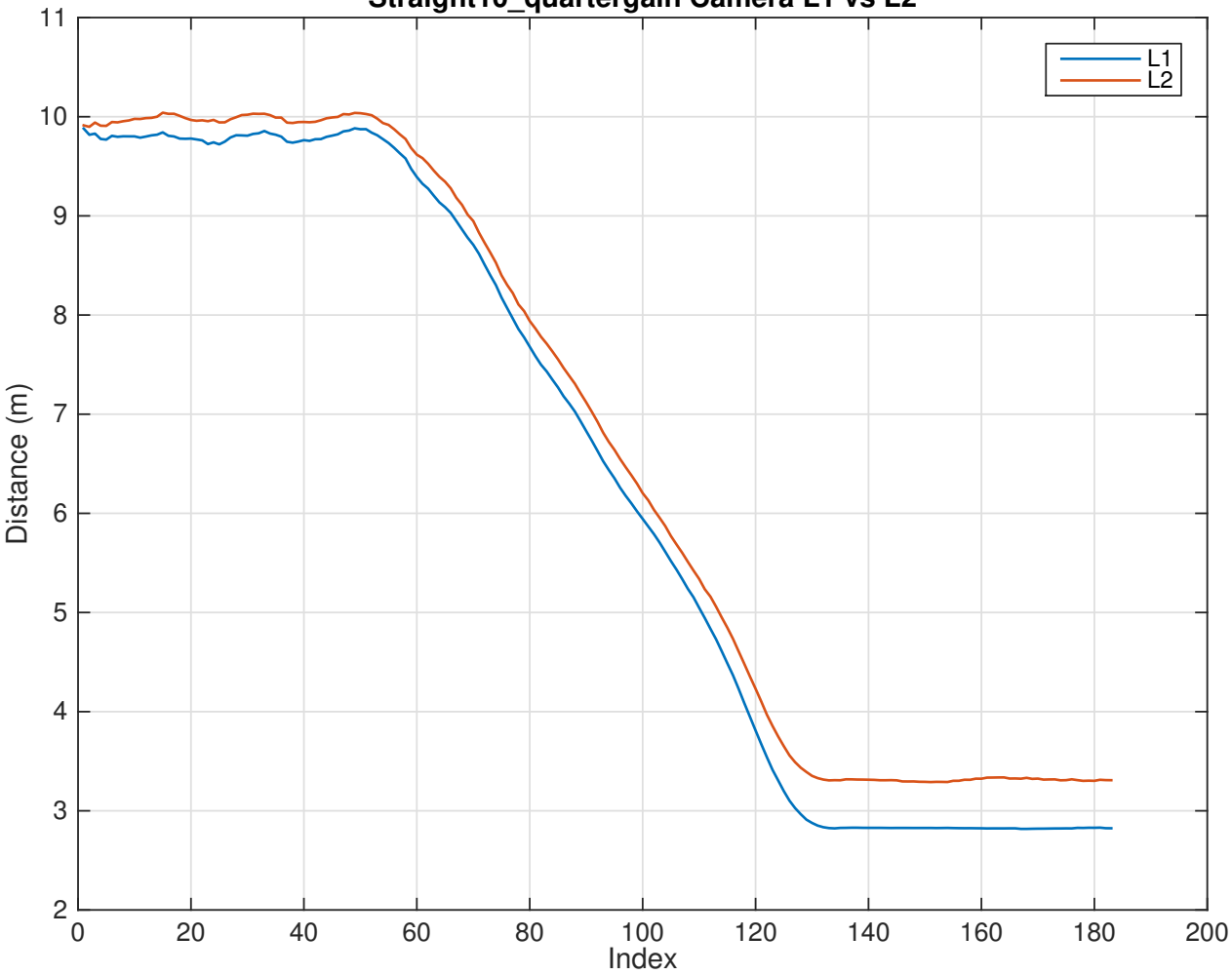
Straight10_quartergain Left_Edge vs Right_Edge



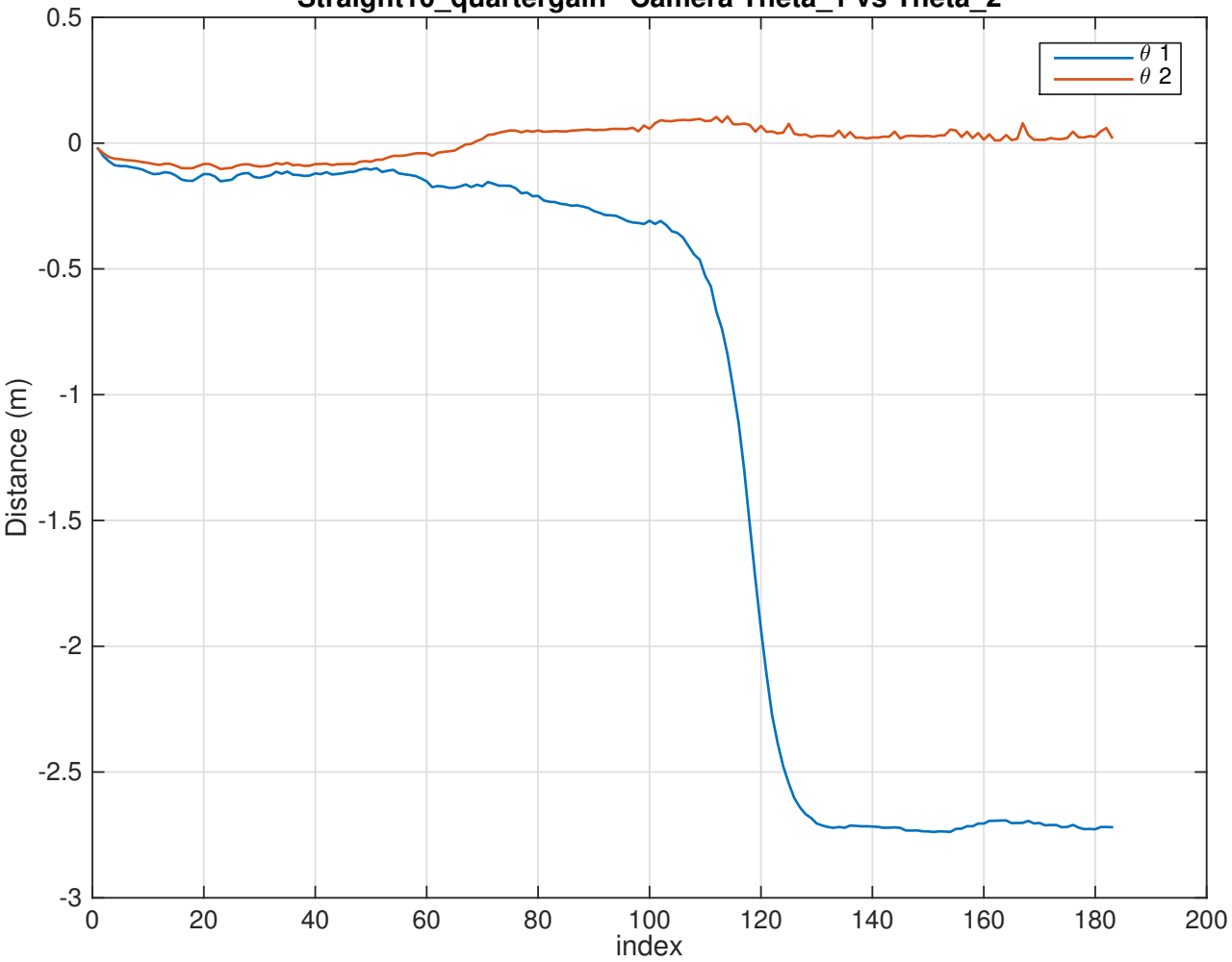
Straight10_quartergain LIDAR Distance vs Camera Center Distance



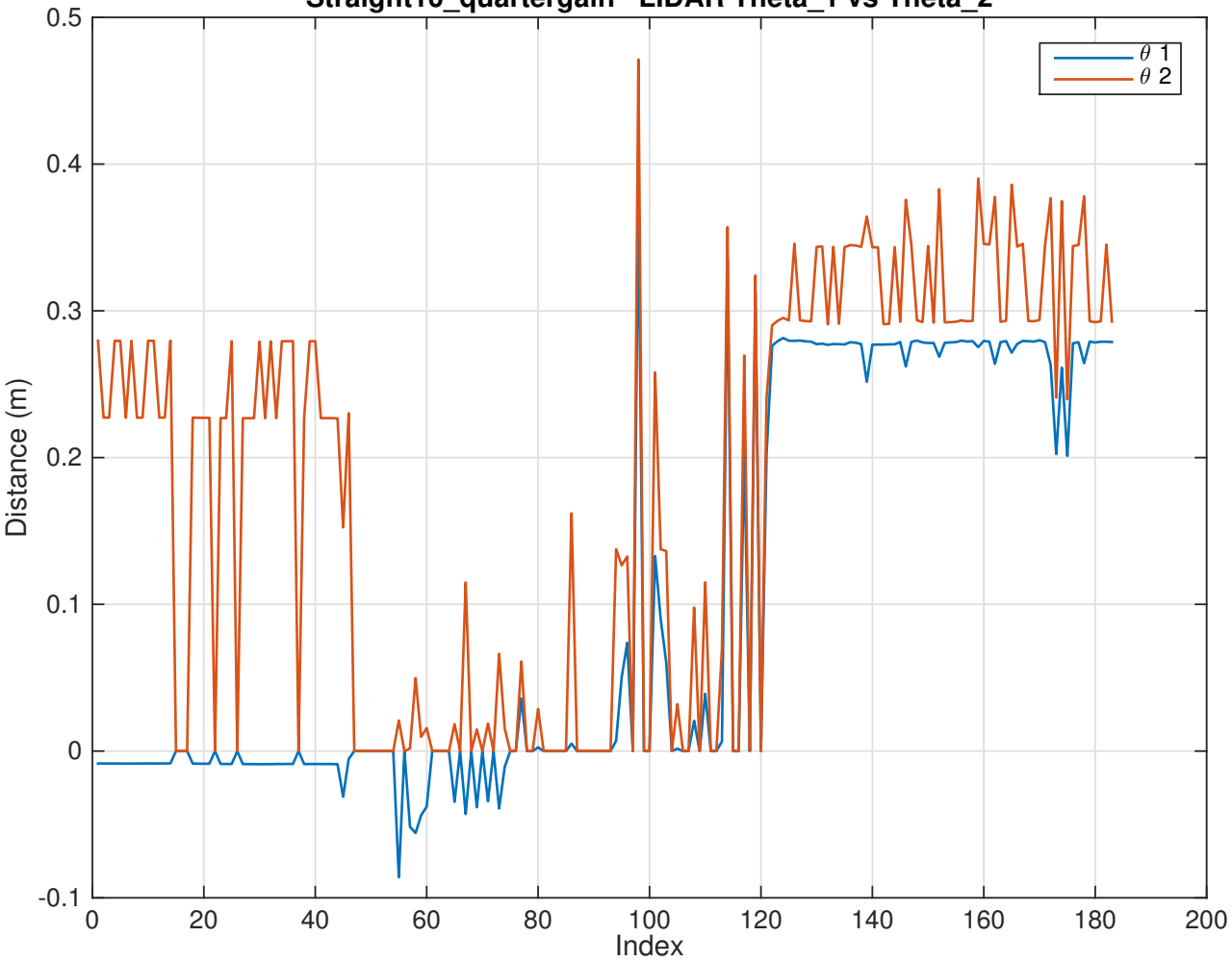
Straight10_quartergain Camera L1 vs L2



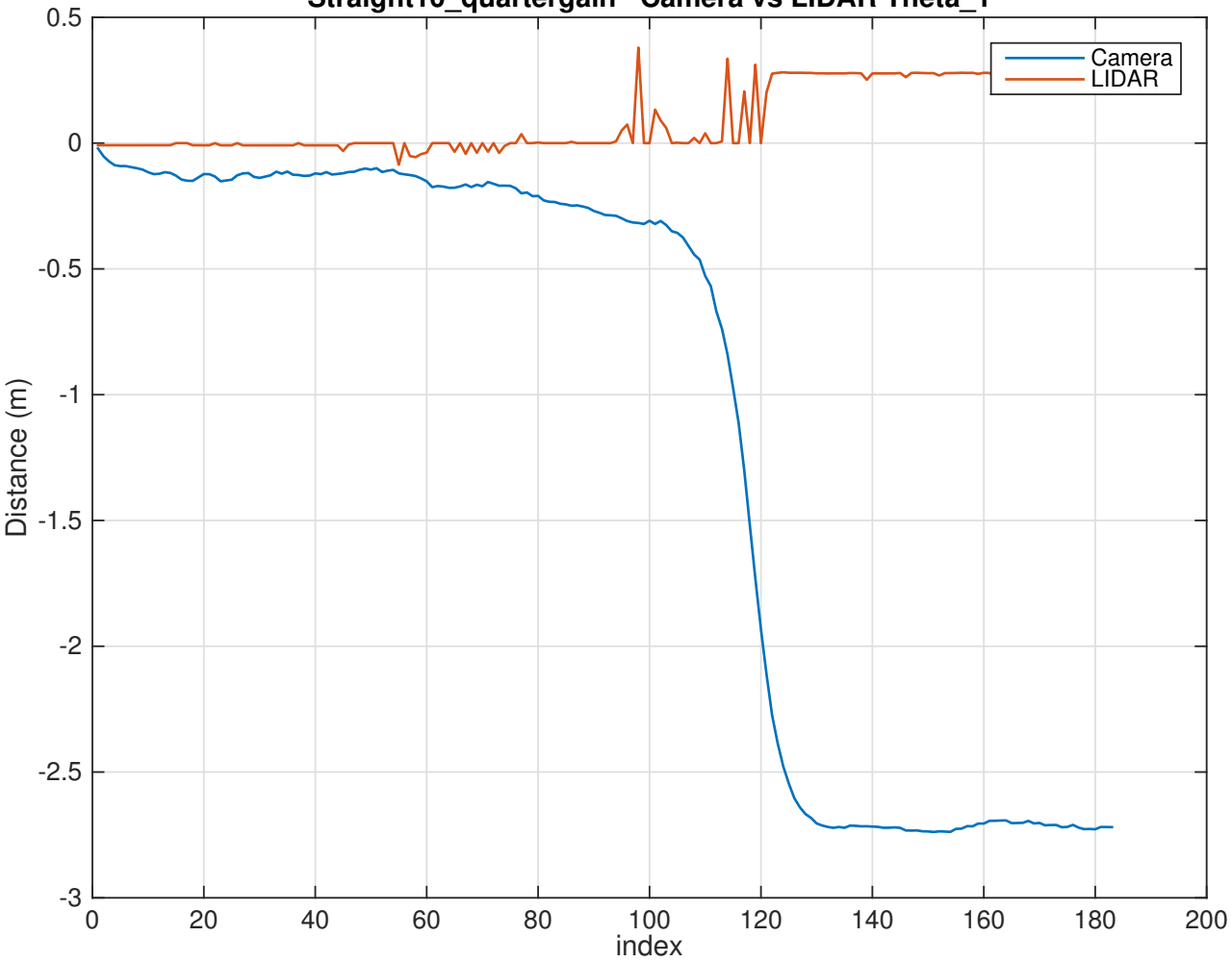
Straight10_quartergain Camera Theta_1 vs Theta_2



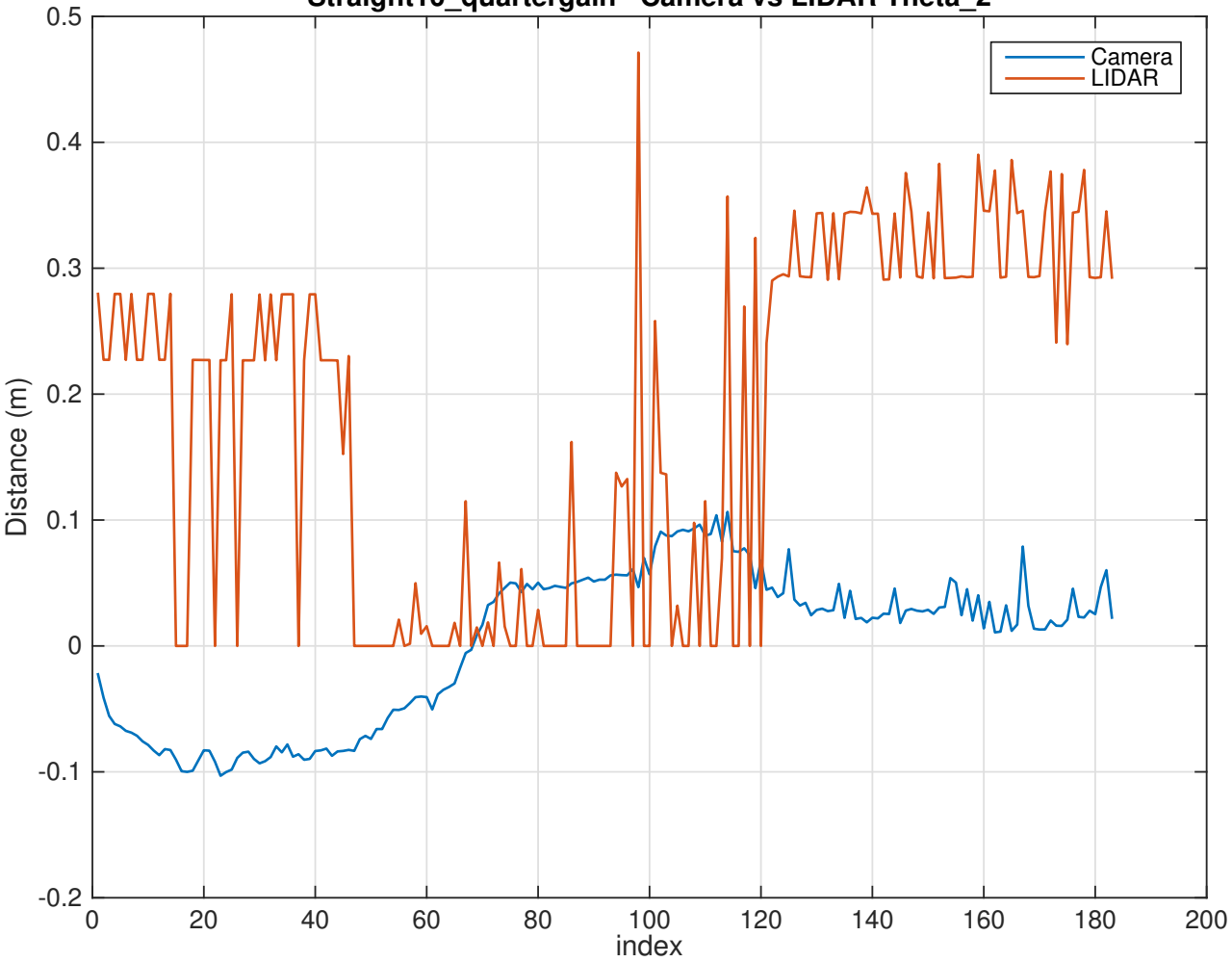
Straight10_quartergain LIDAR Theta_1 vs Theta_2



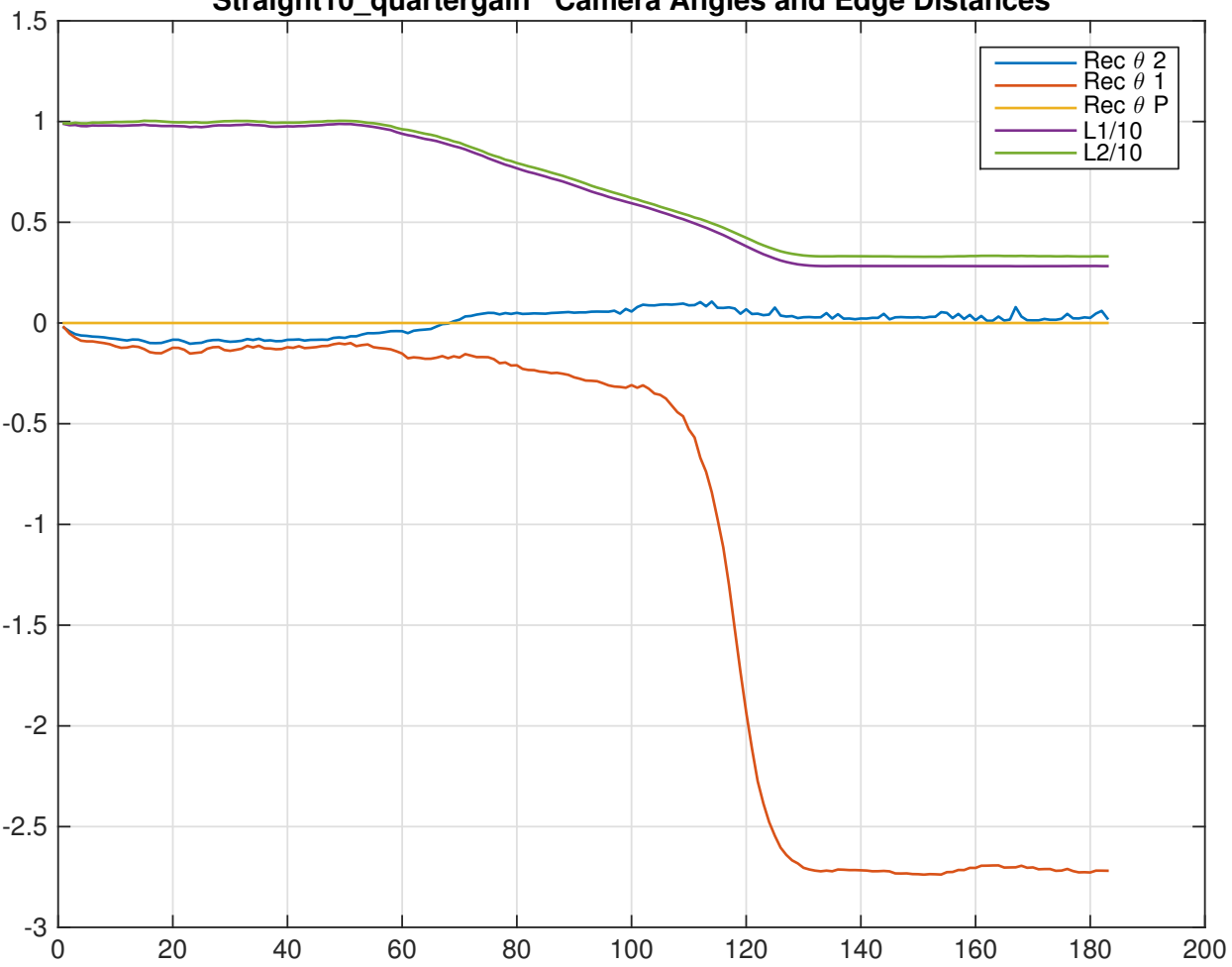
Straight10_quartergain Camera vs LIDAR Theta_1



Straight10_quartergain Camera vs LIDAR Theta_2



Straight10_quartergain Camera Angles and Edge Distances



Straight10_quartergain Steering

