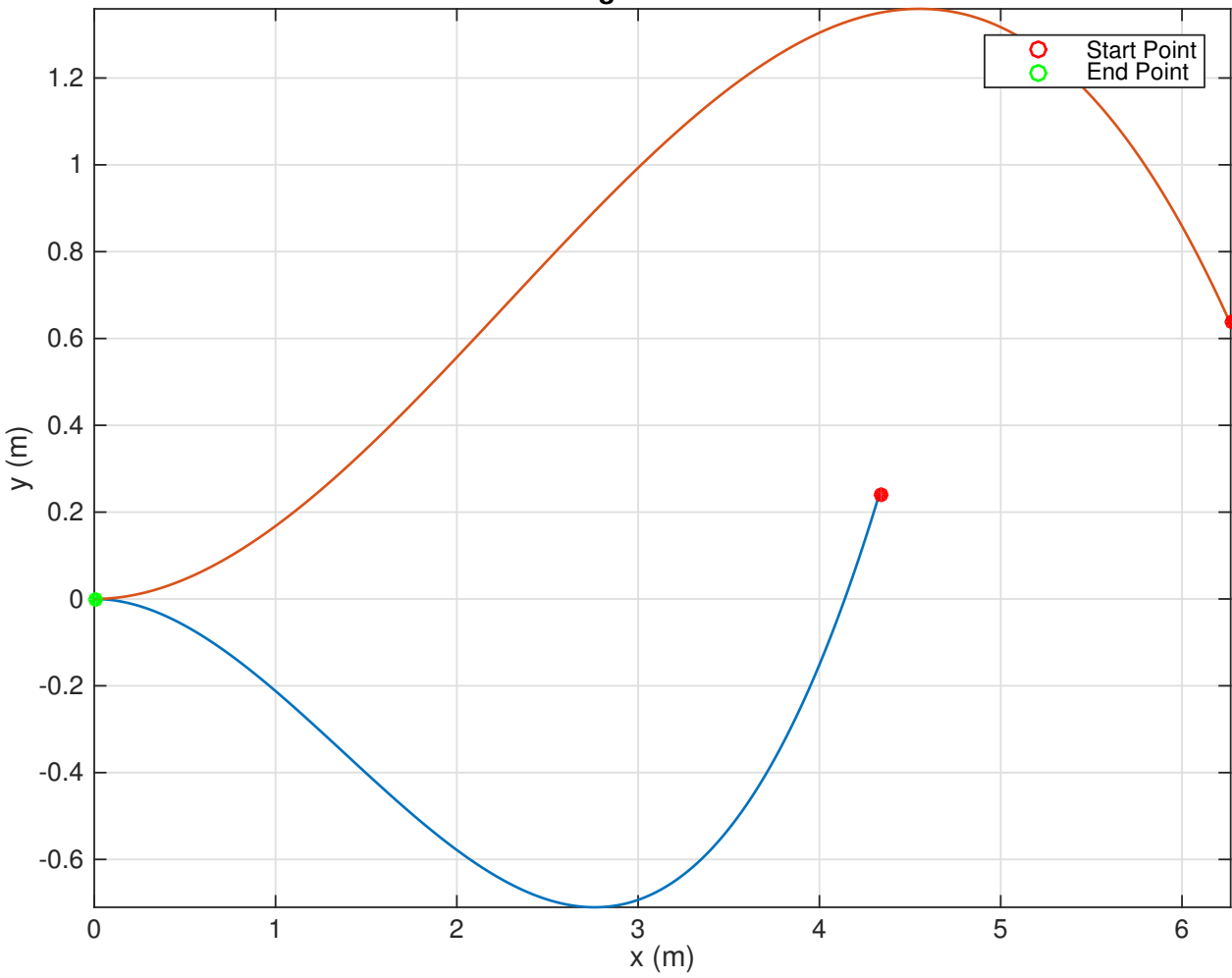


Straight4 All Paths



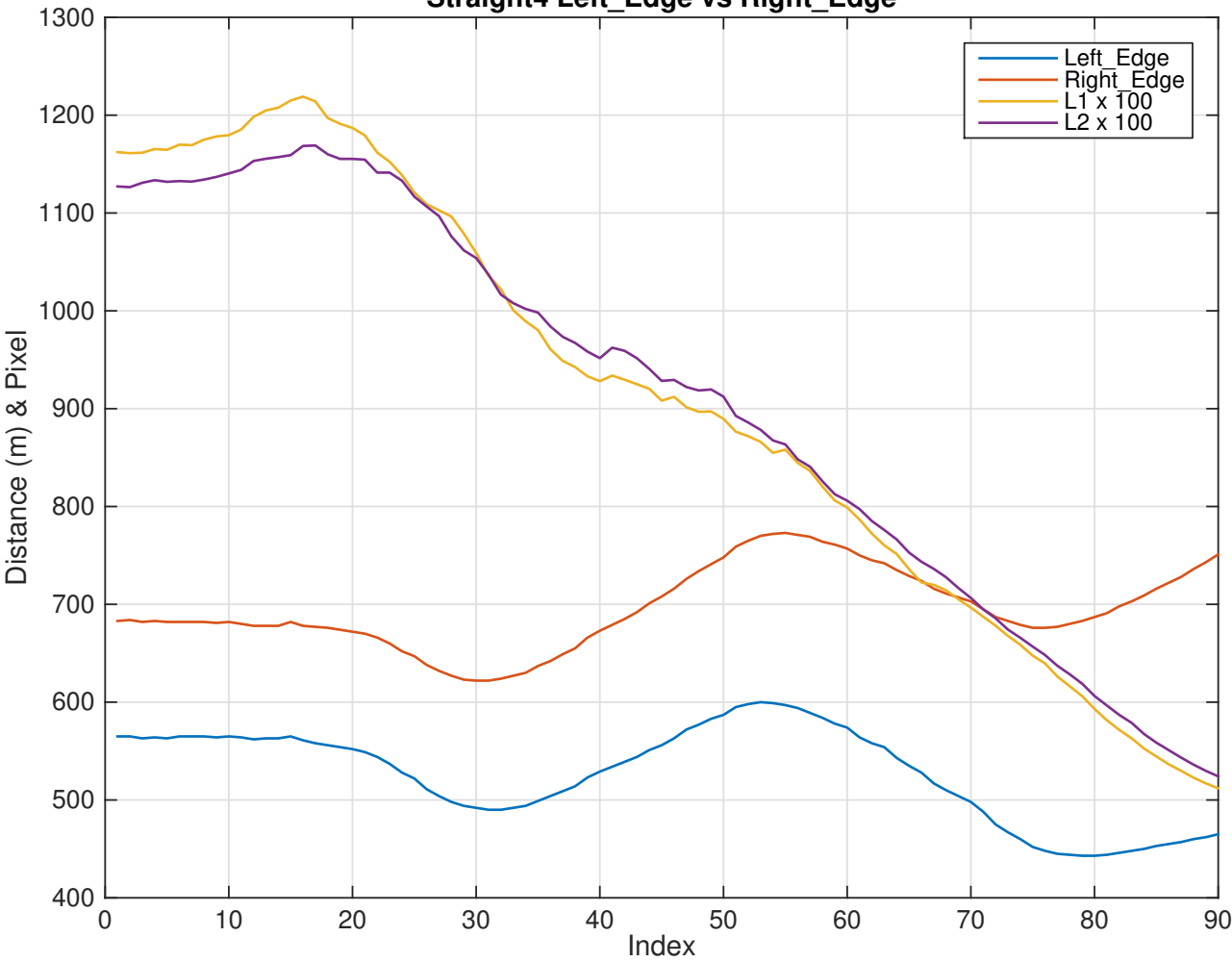
Number_Of_Unique_Paths

King_Pin_Detected

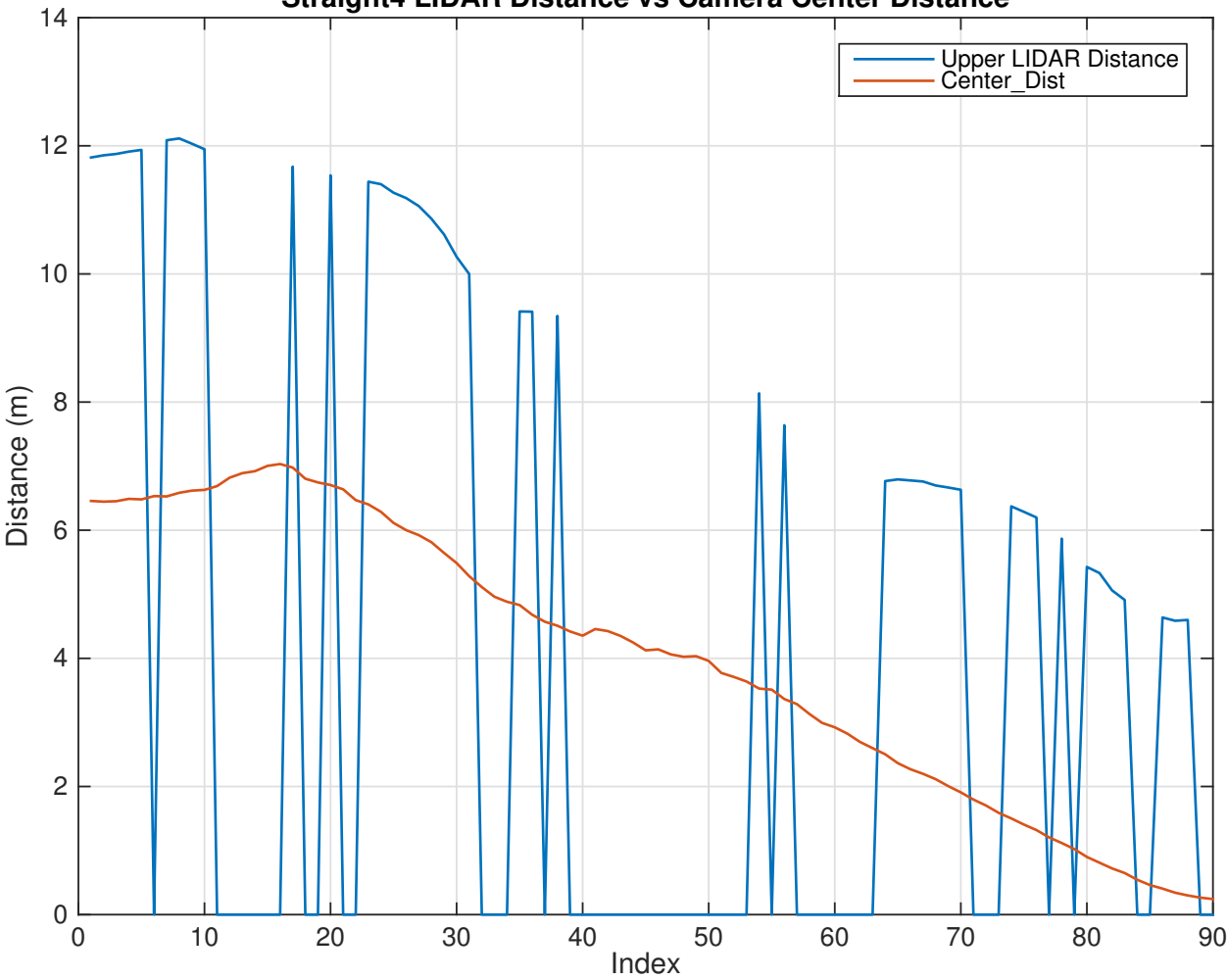
2

false

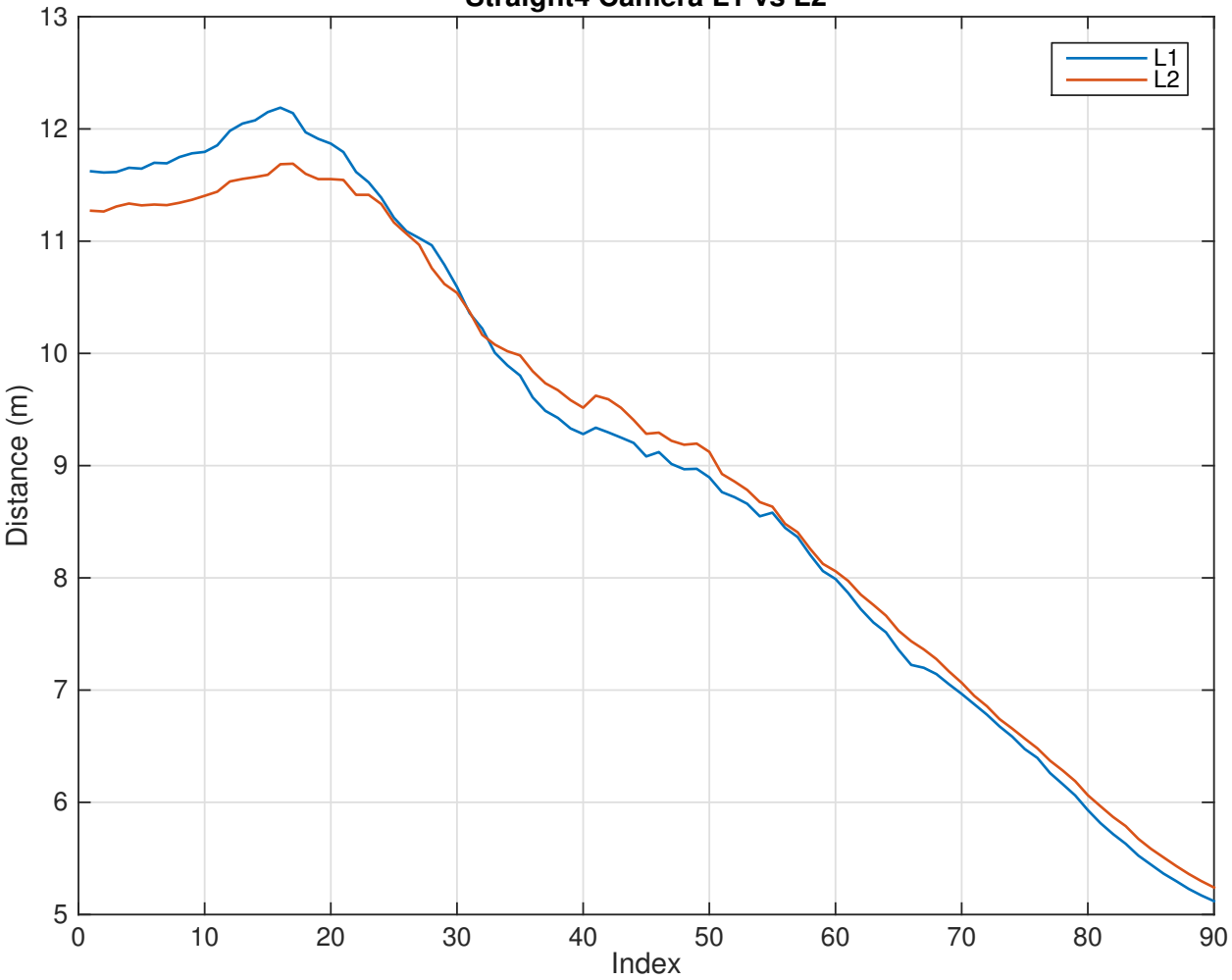
Straight4 Left_Edge vs Right_Edge



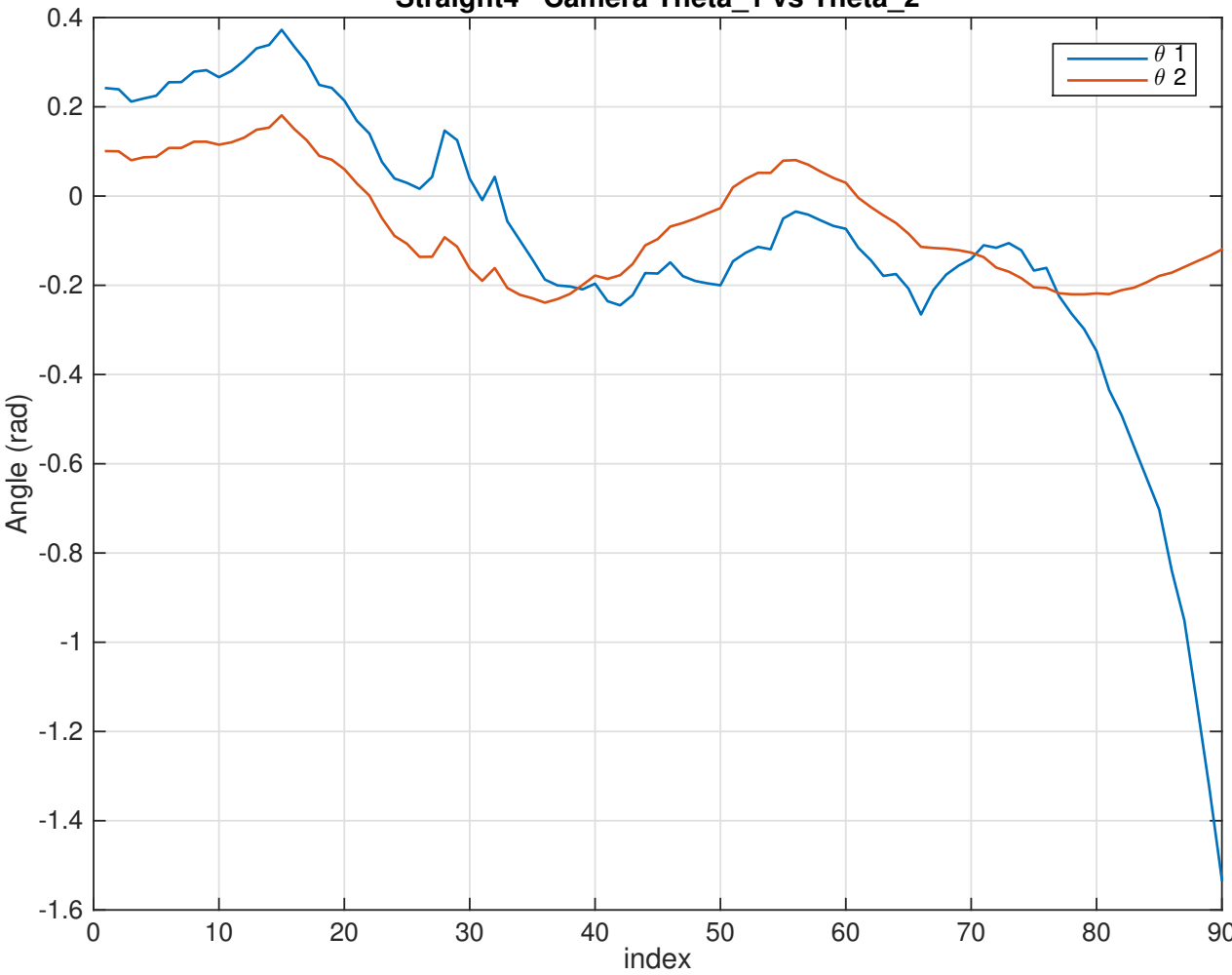
Straight4 LIDAR Distance vs Camera Center Distance



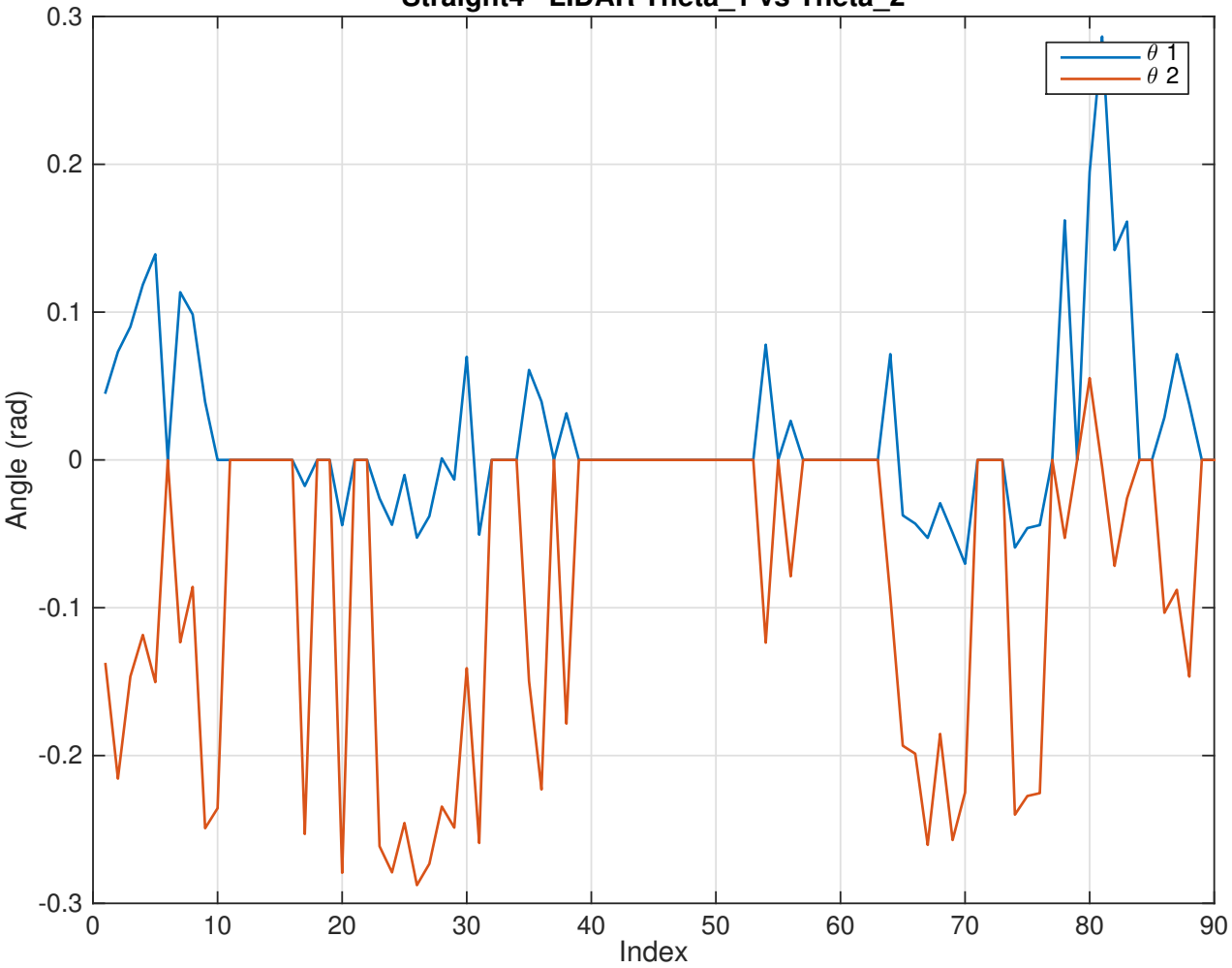
Straight4 Camera L1 vs L2



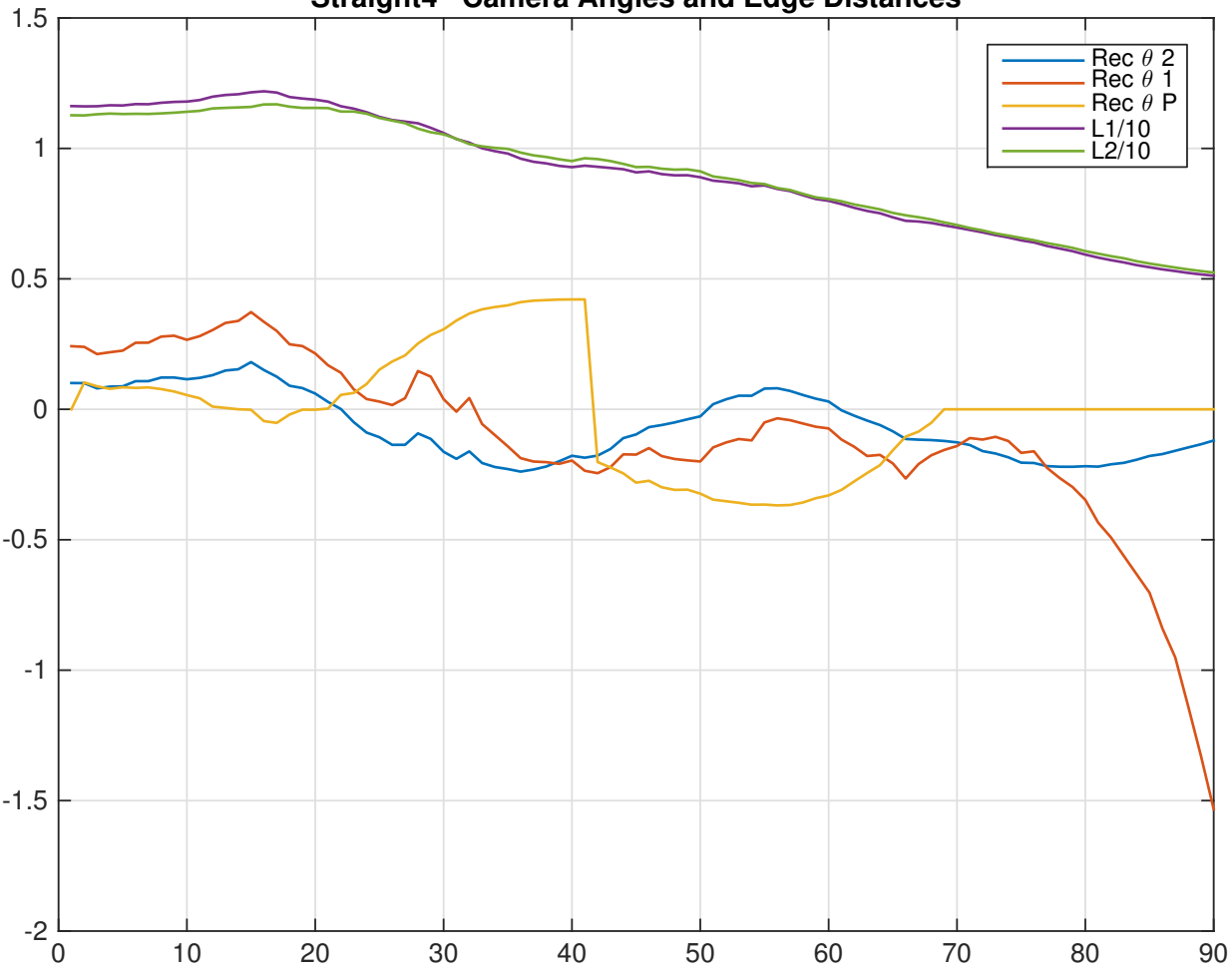
Straight4 Camera Theta_1 vs Theta_2



Straight4 LIDAR Theta_1 vs Theta_2



Straight4 Camera Angles and Edge Distances



Straight4 Steering

