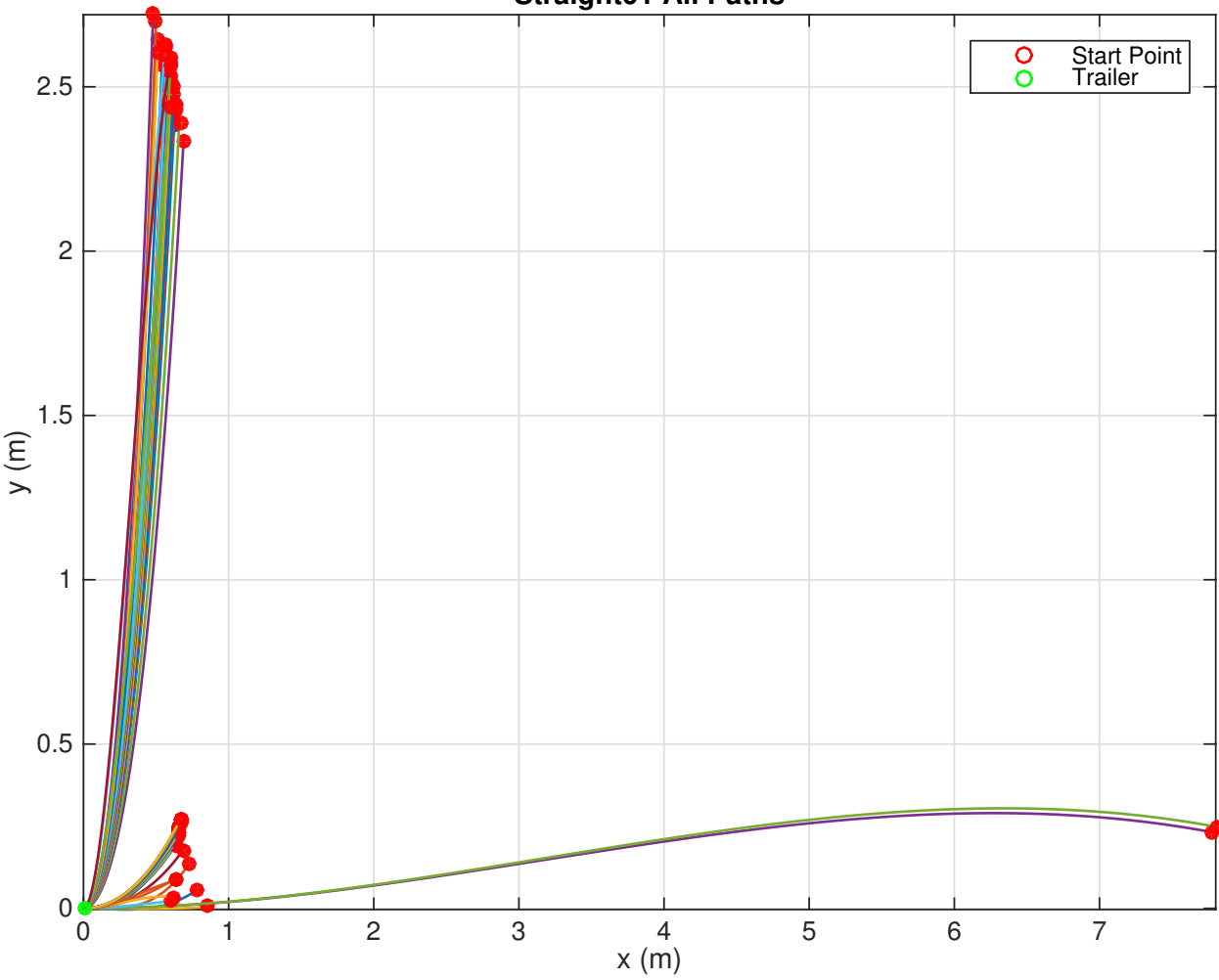


Straight01 All Paths



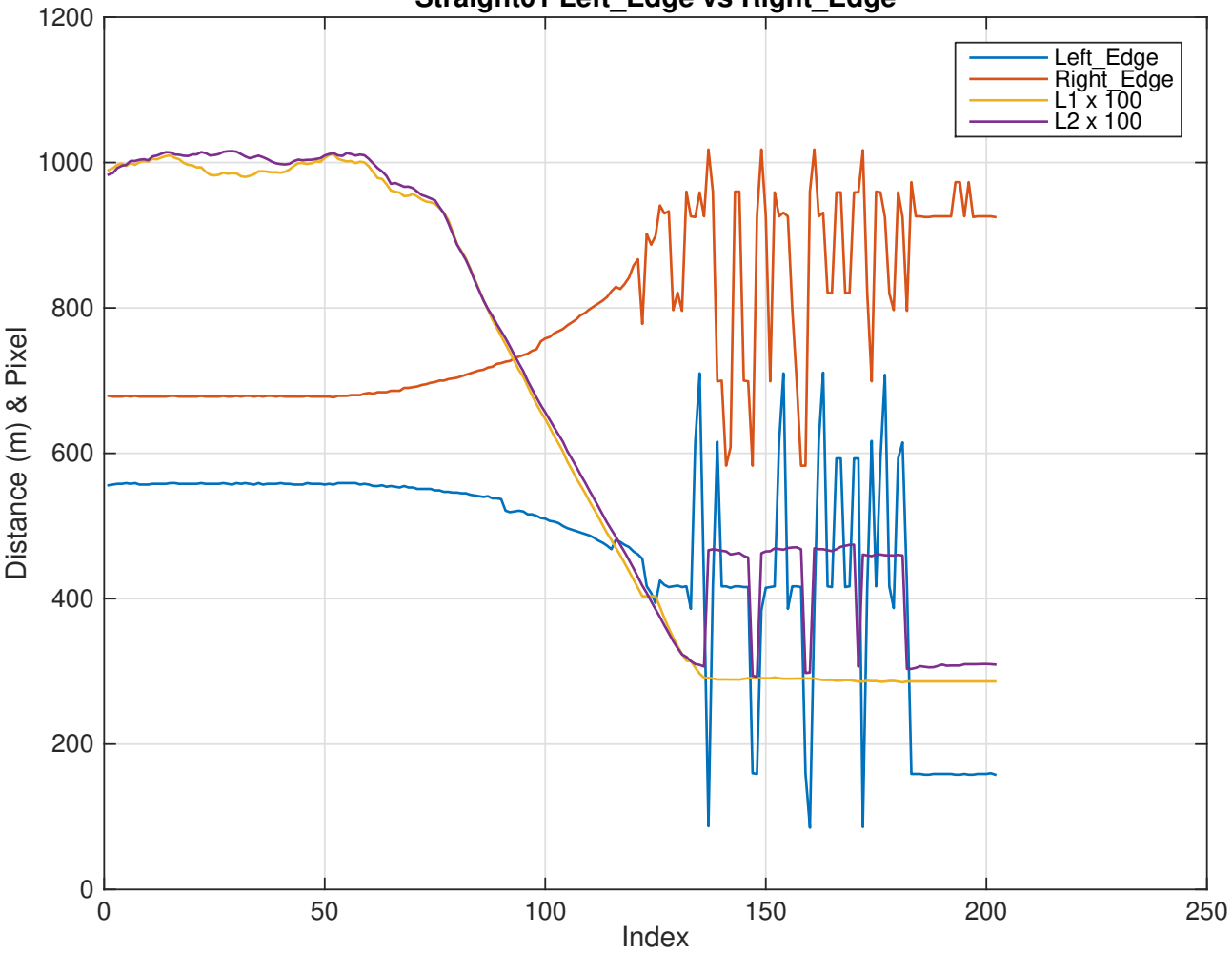
Number\_Of\_Unique\_Paths

King\_Pin\_Detected

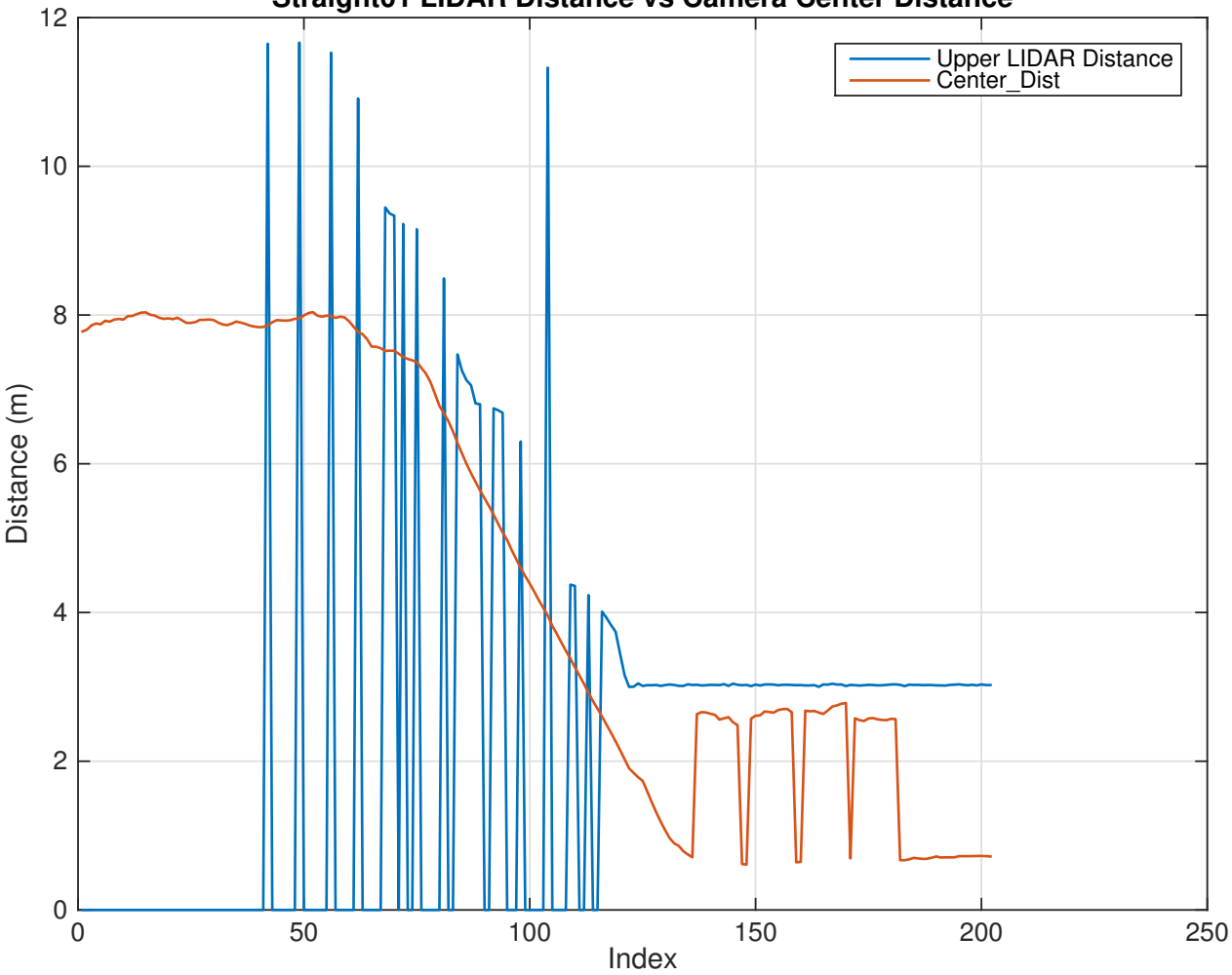
70

false

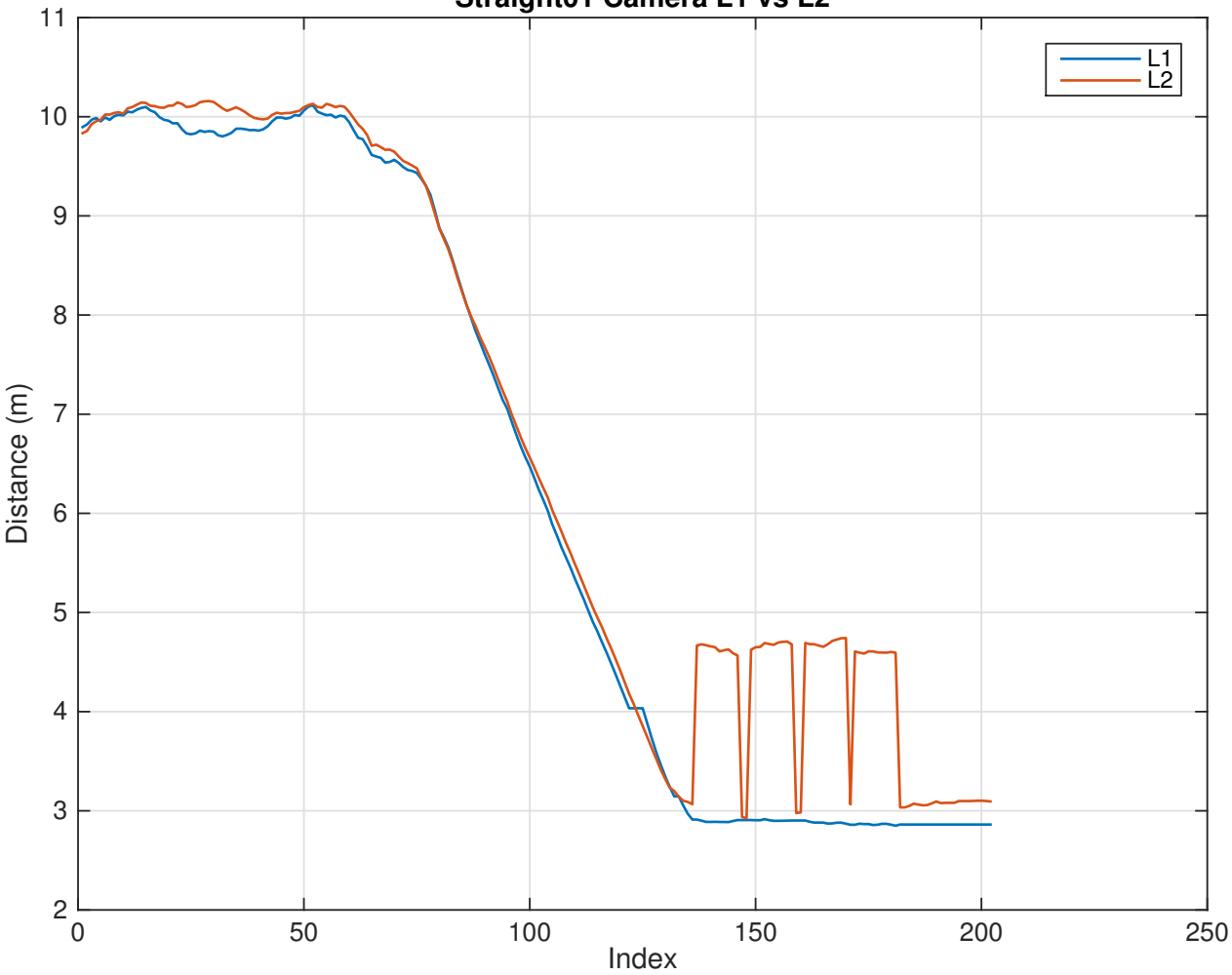
Straight01 Left\_Edge vs Right\_Edge



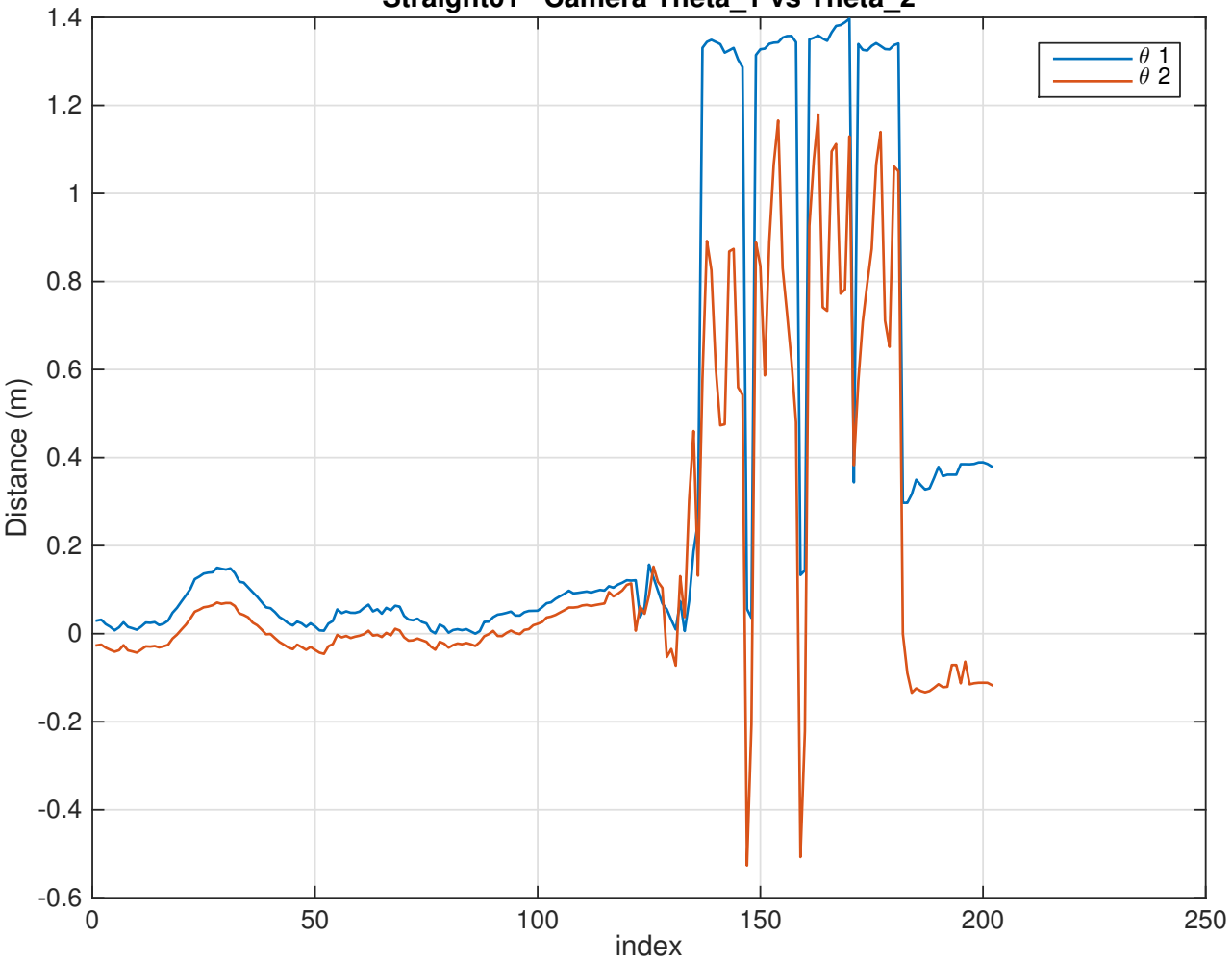
Straight01 LIDAR Distance vs Camera Center Distance



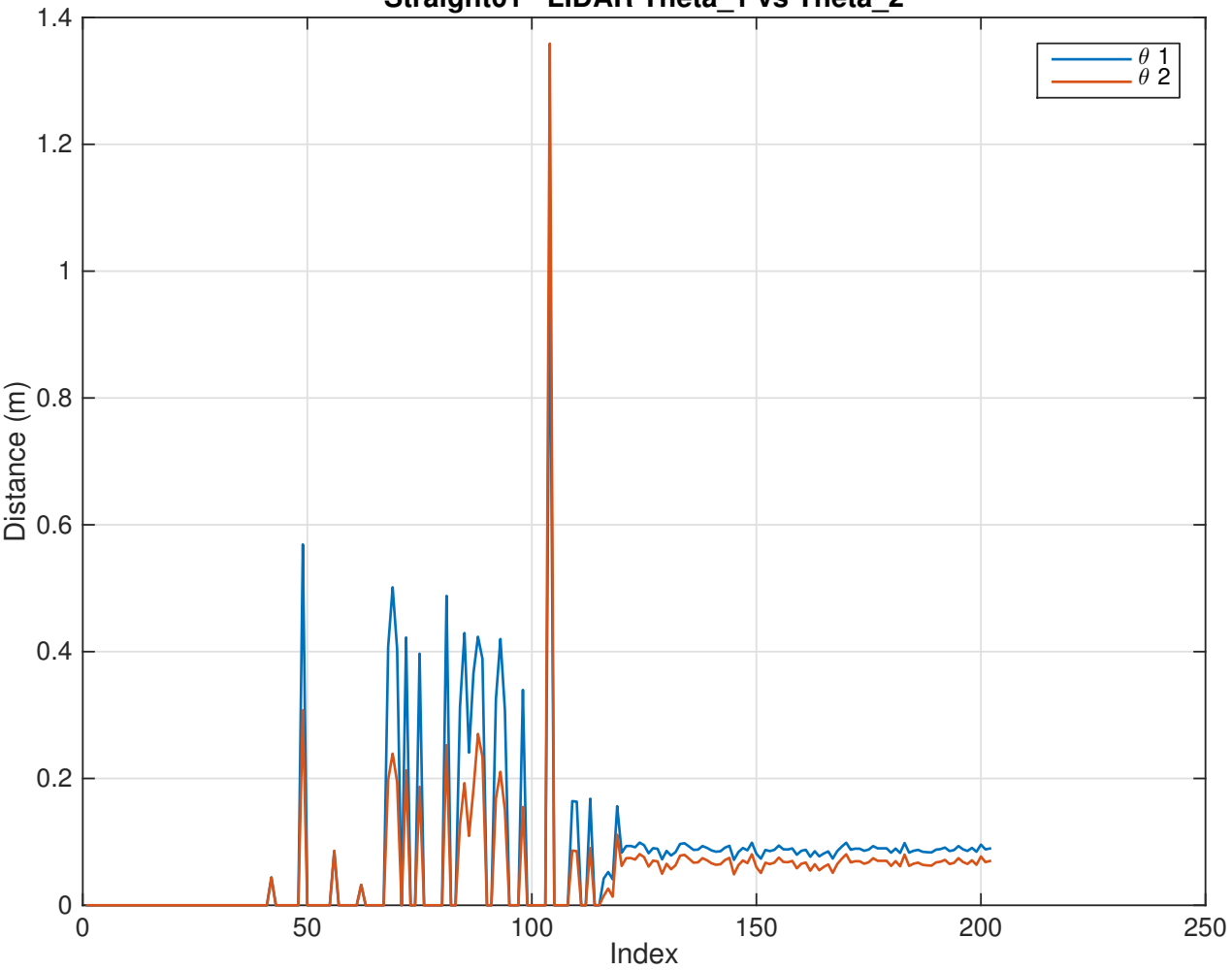
Straight01 Camera L1 vs L2



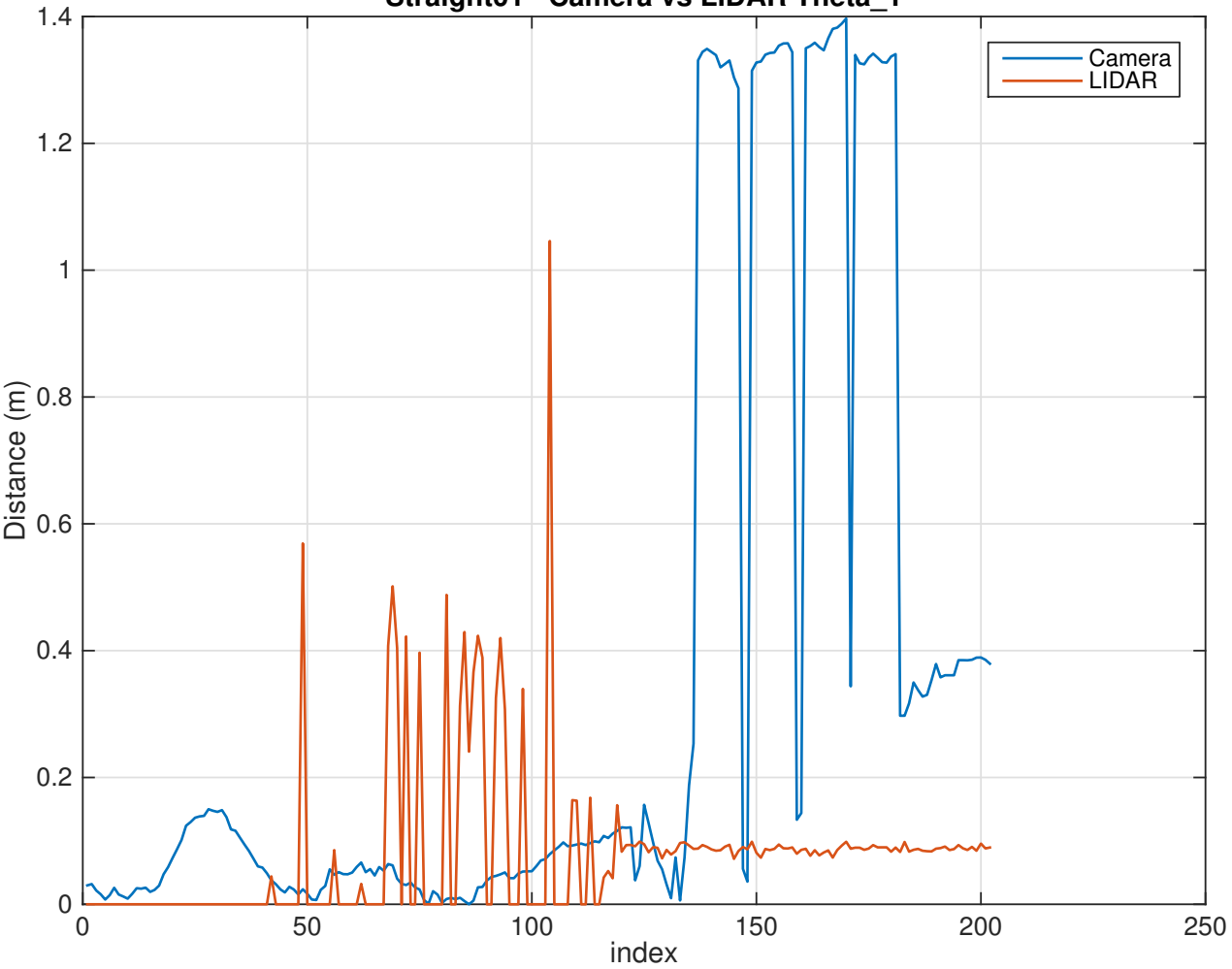
Straight01 Camera Theta\_1 vs Theta\_2



Straight01 LIDAR Theta\_1 vs Theta\_2

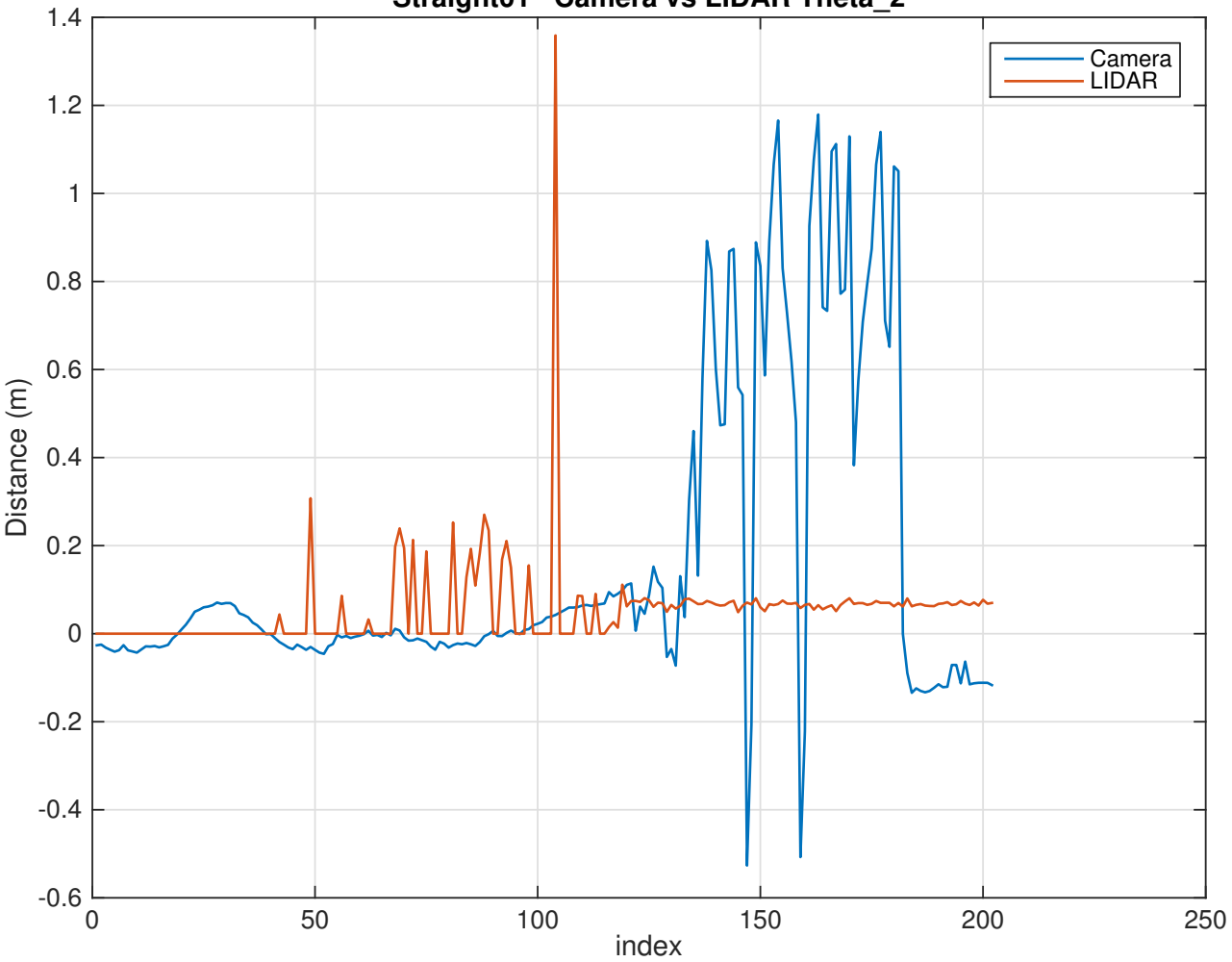


Straight01 Camera vs LIDAR Theta\_1

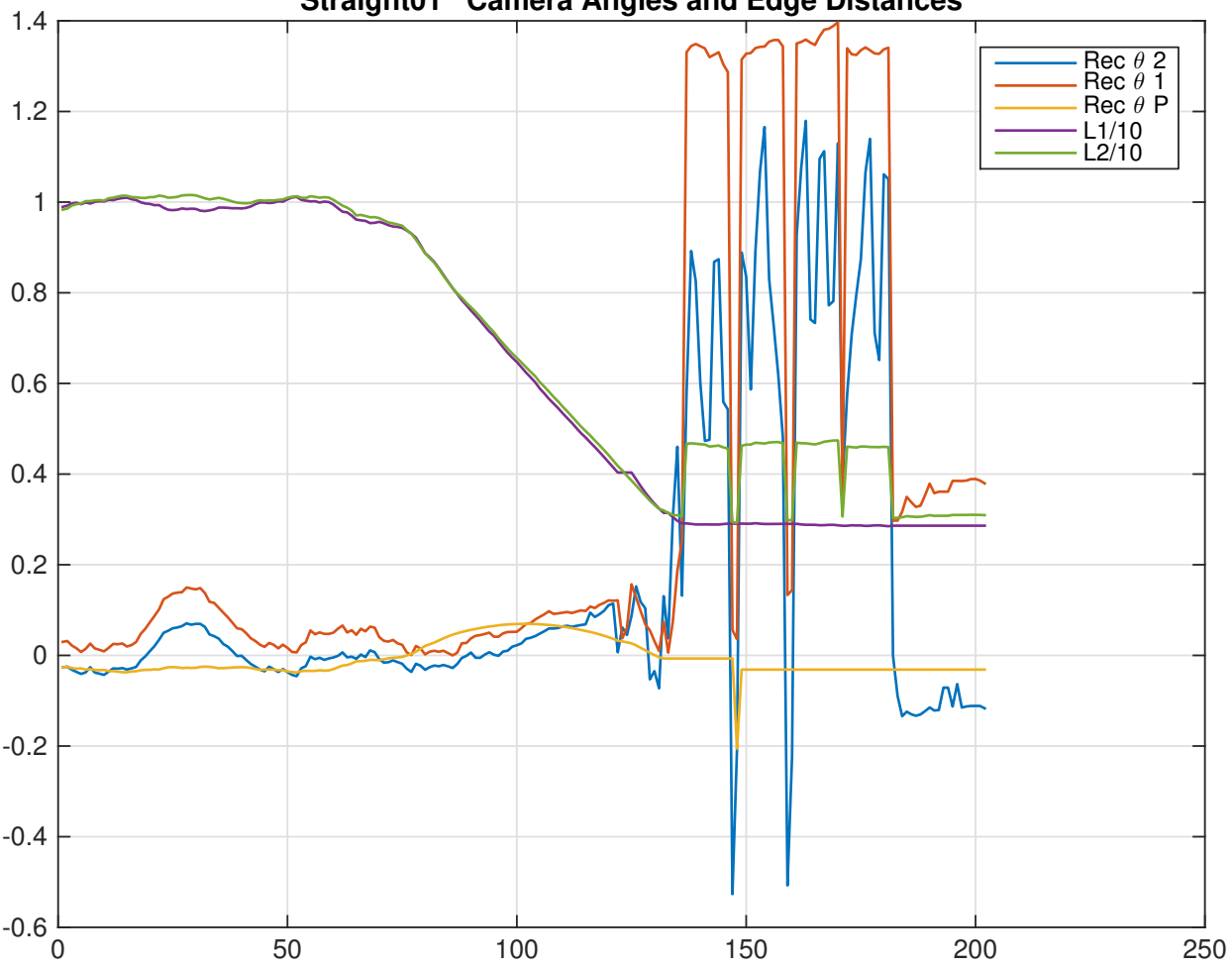




Straight01 Camera vs LIDAR Theta\_2



Straight01 Camera Angles and Edge Distances



**Straight01 Calculated vs. Actual Steering**

