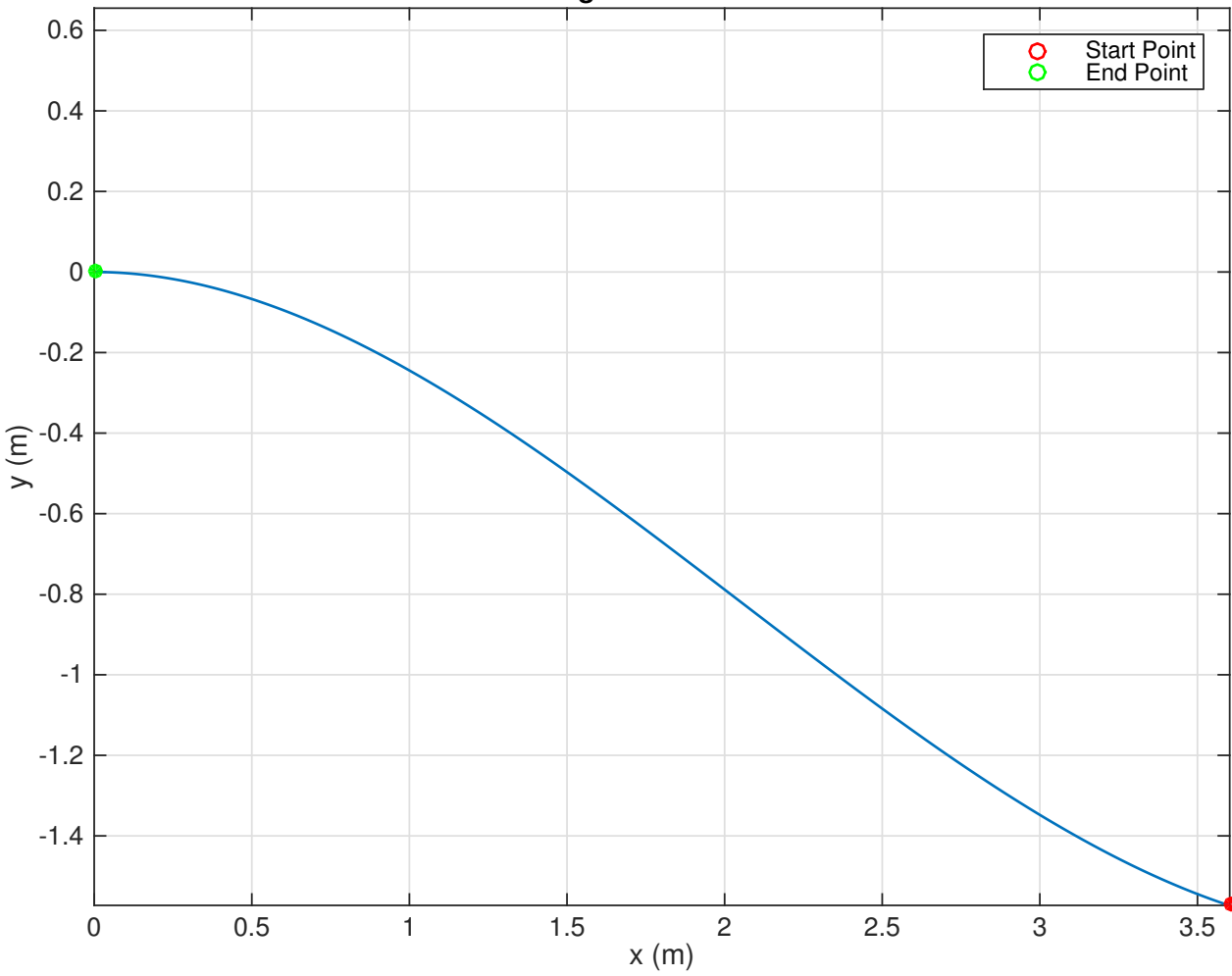


Angled5 All Paths



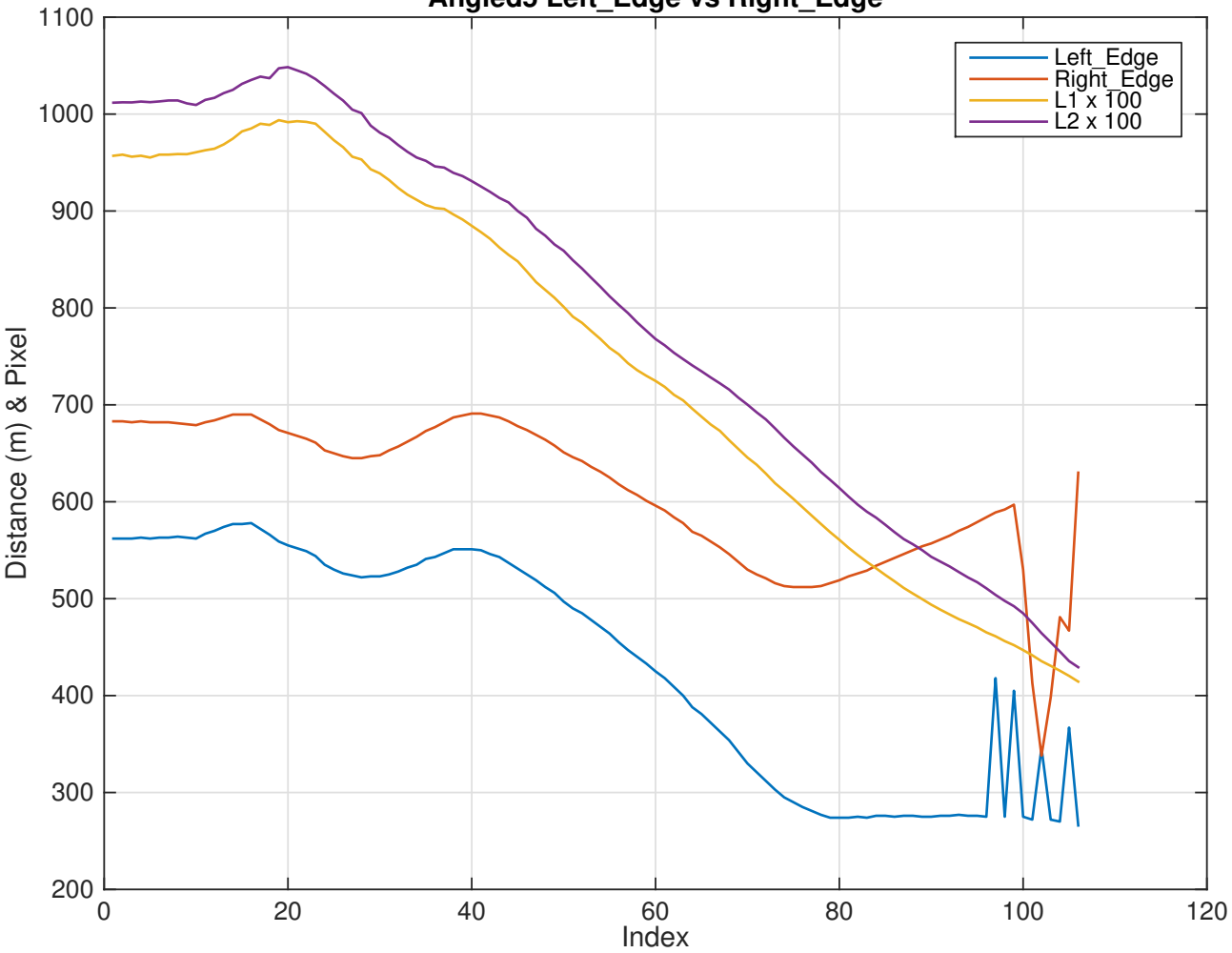
Number\_Of\_Unique\_Paths

King\_Pin\_Detected

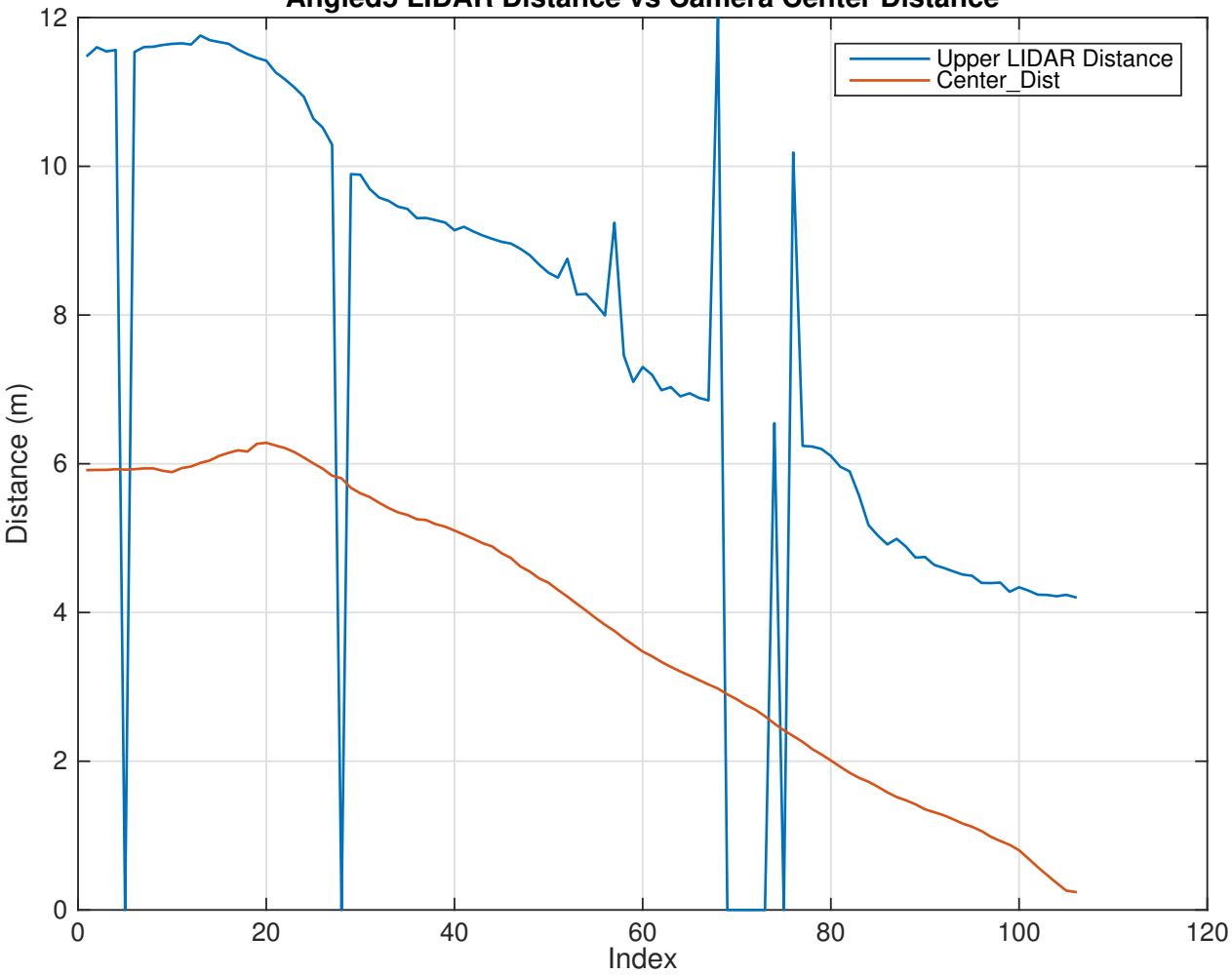
2

false

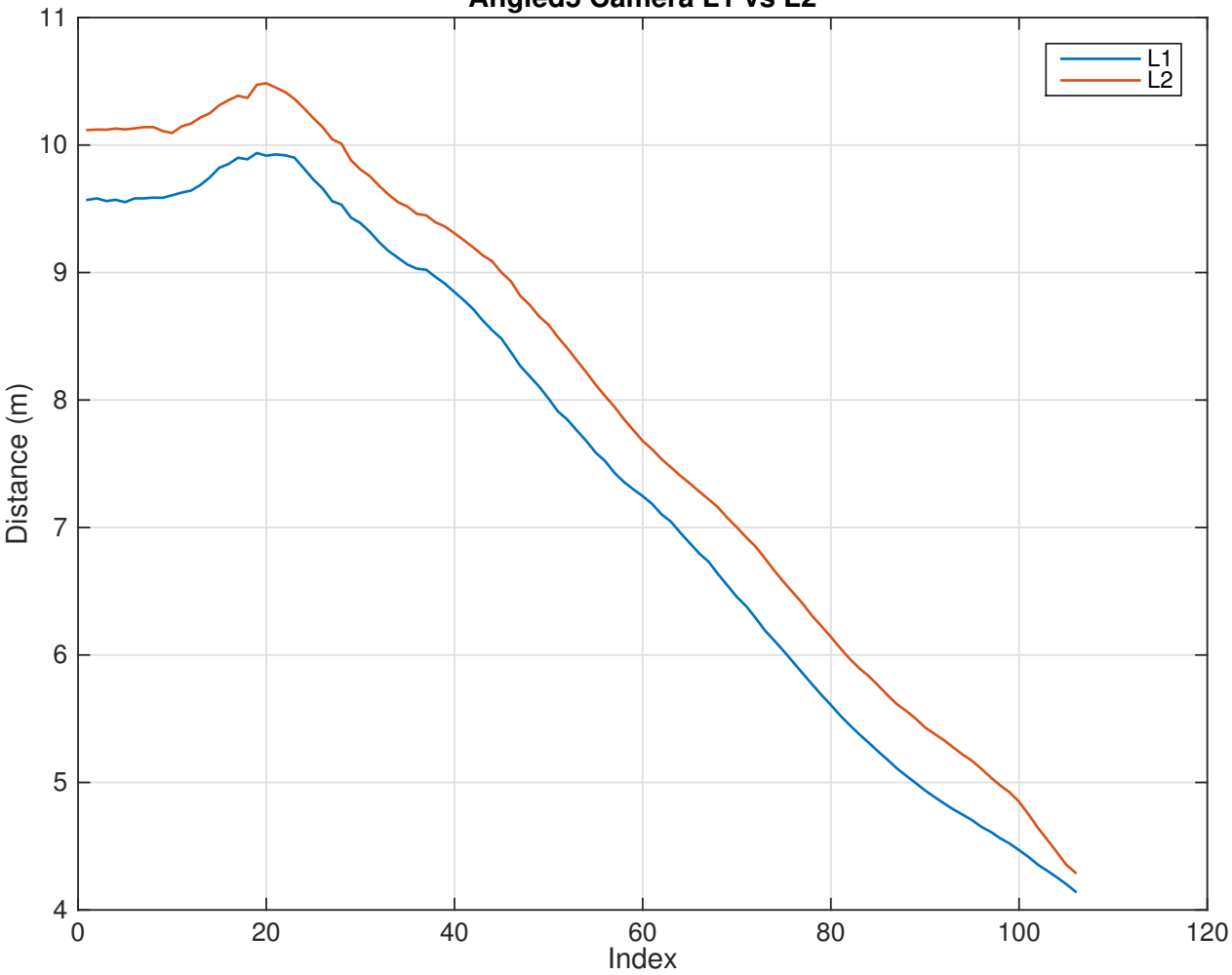
Angled5 Left\_Edge vs Right\_Edge



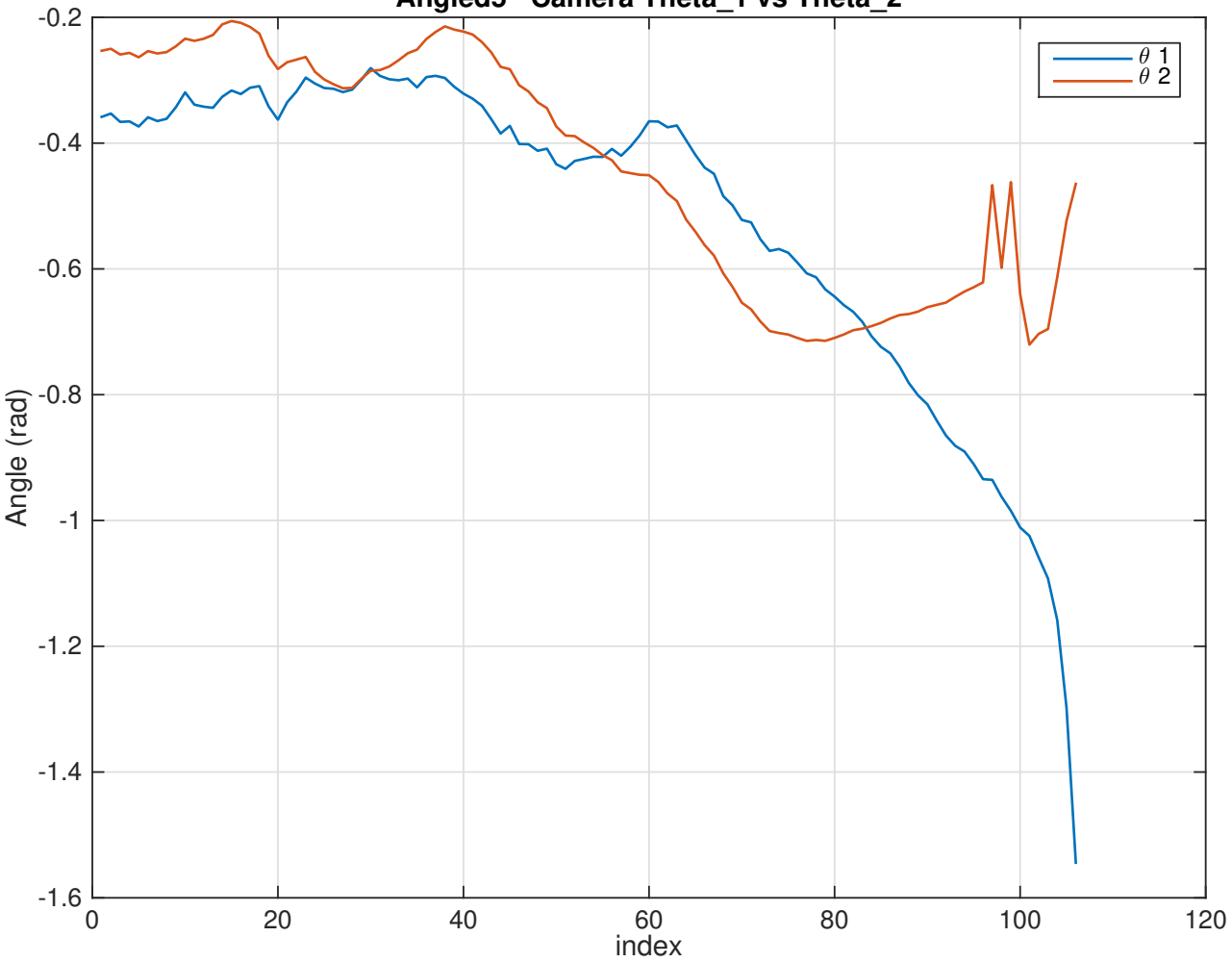
Angled5 LIDAR Distance vs Camera Center Distance



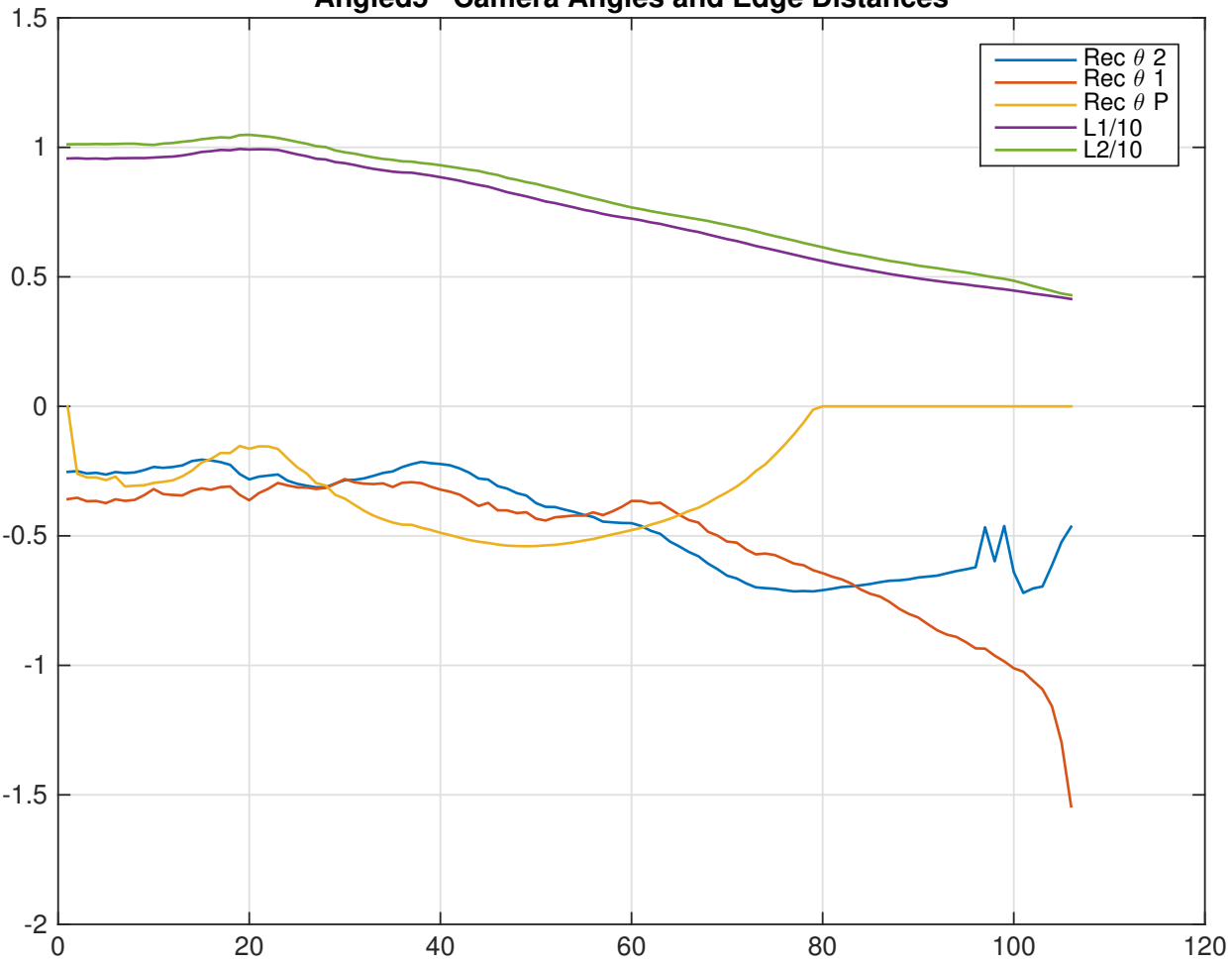
Angled5 Camera L1 vs L2



Angled5 Camera Theta\_1 vs Theta\_2



Angled5 Camera Angles and Edge Distances



Angled5 Steering

