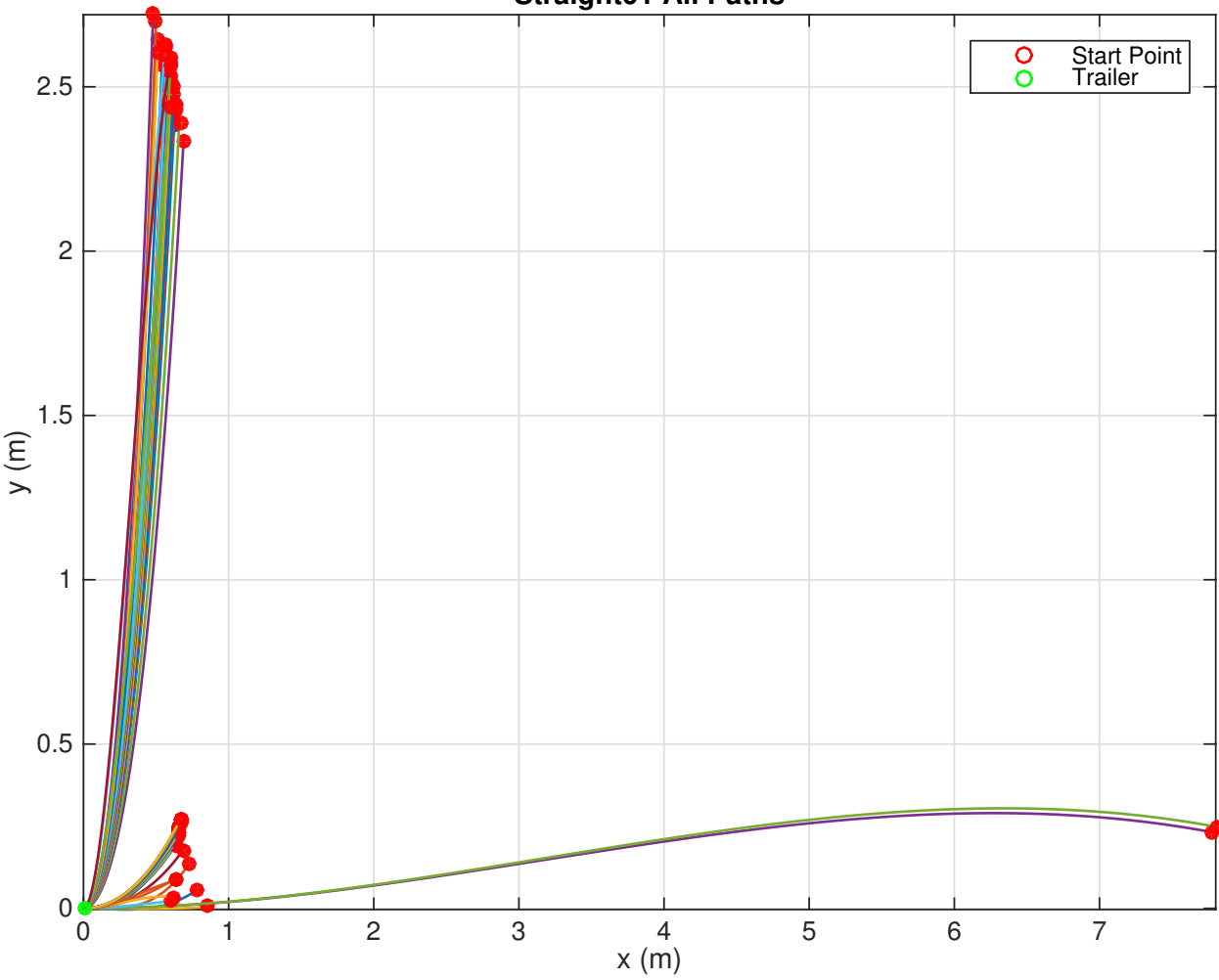


Straight01 All Paths



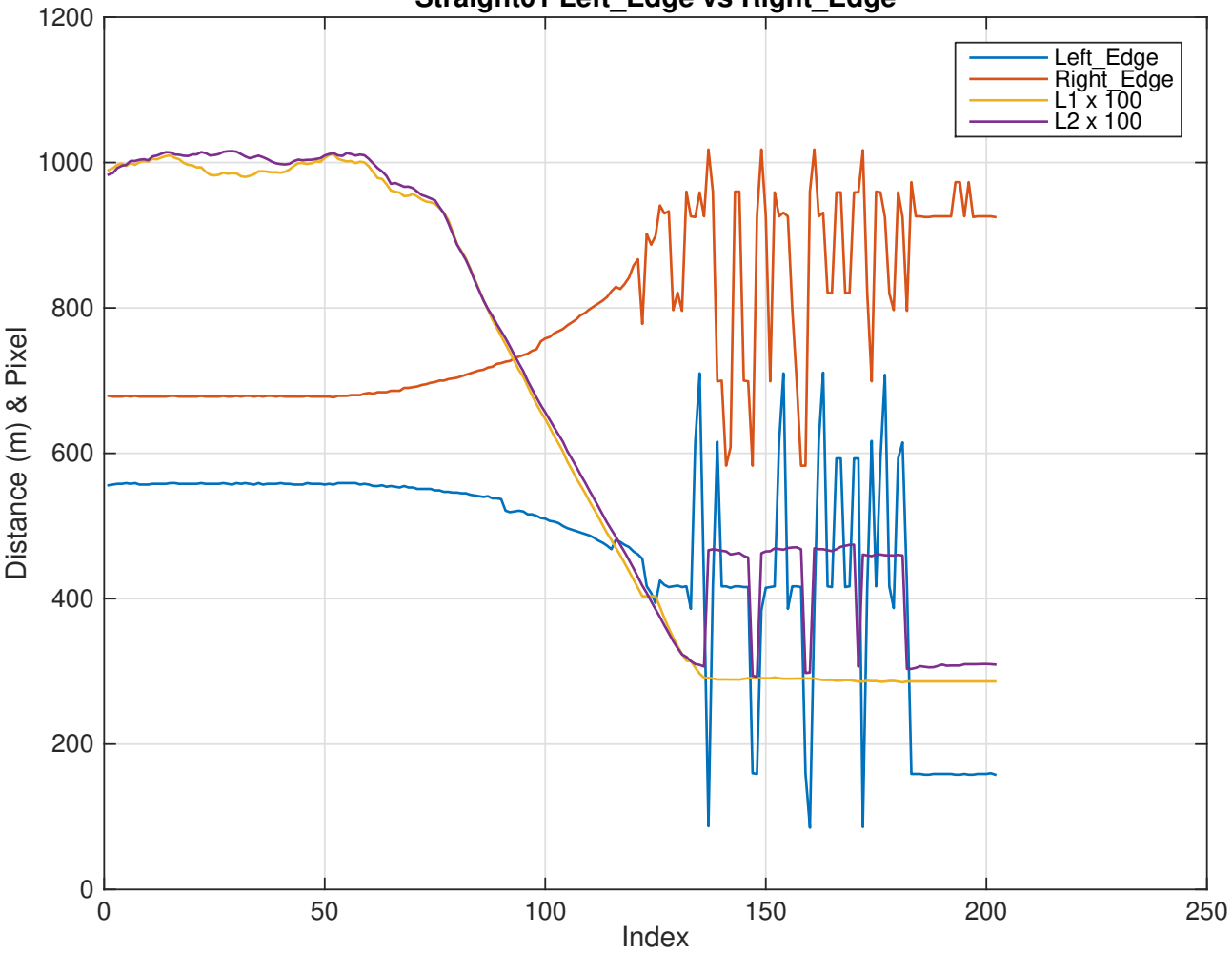
Number_Of_Unique_Paths

King_Pin_Detected

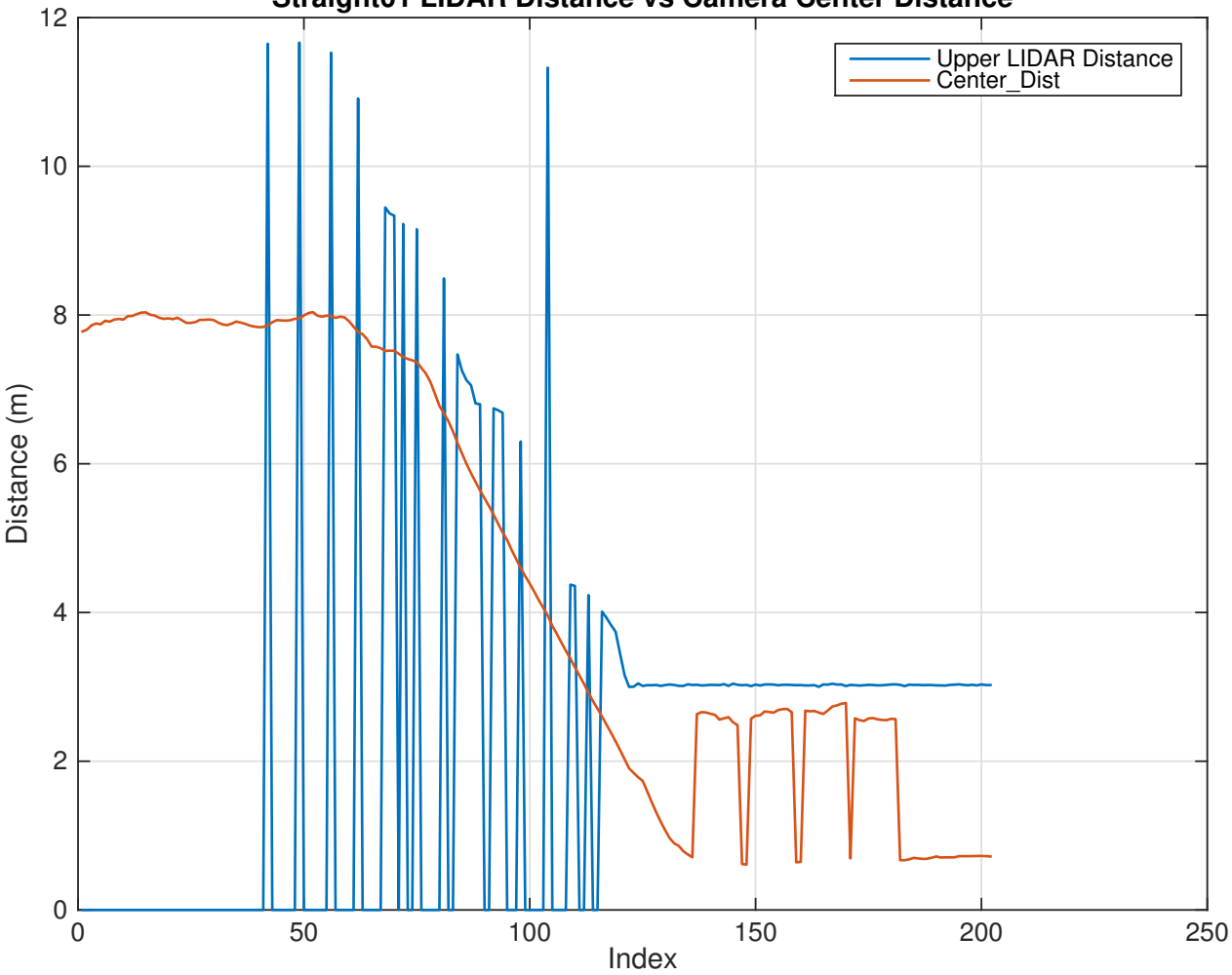
42

false

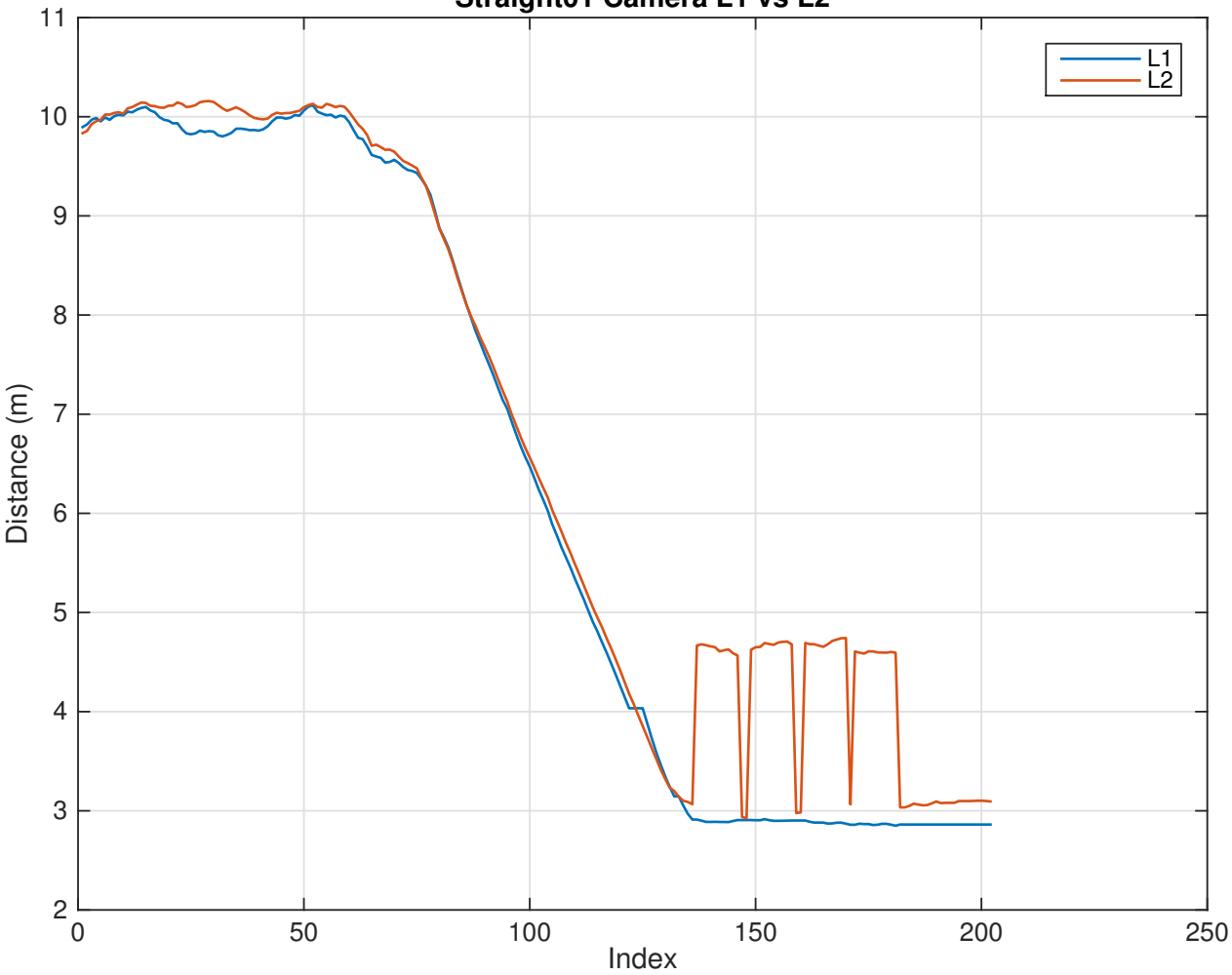
Straight01 Left_Edge vs Right_Edge



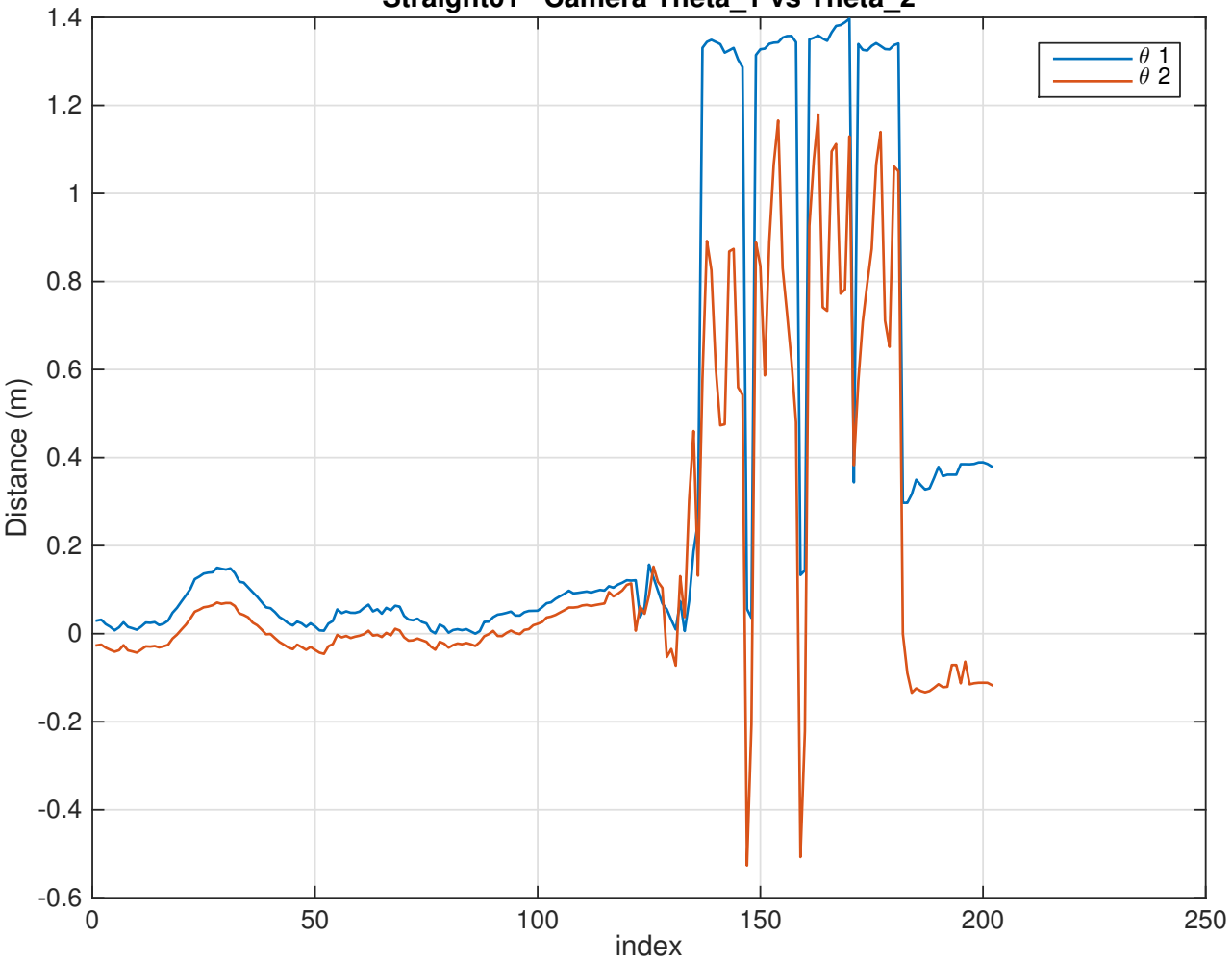
Straight01 LIDAR Distance vs Camera Center Distance



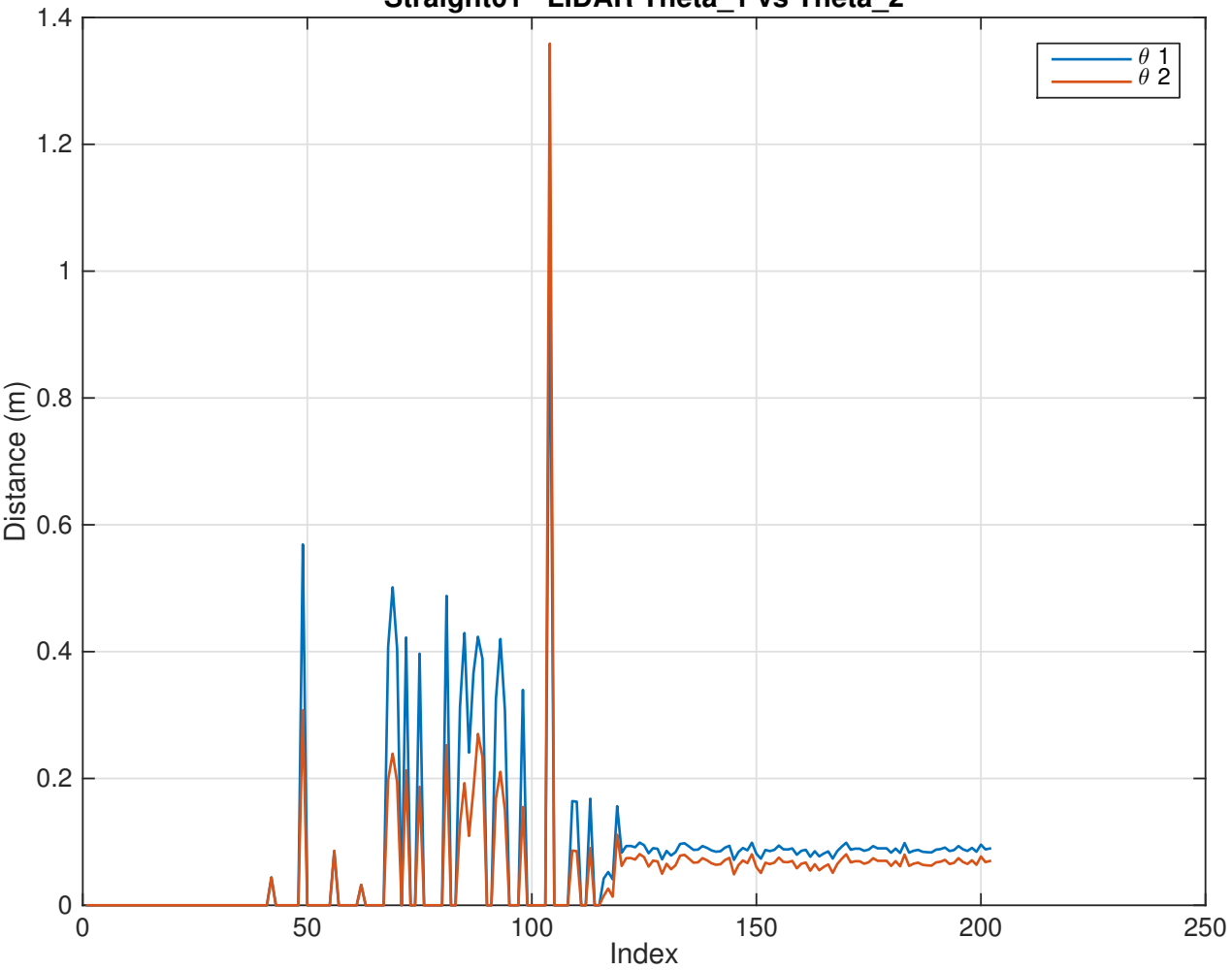
Straight01 Camera L1 vs L2



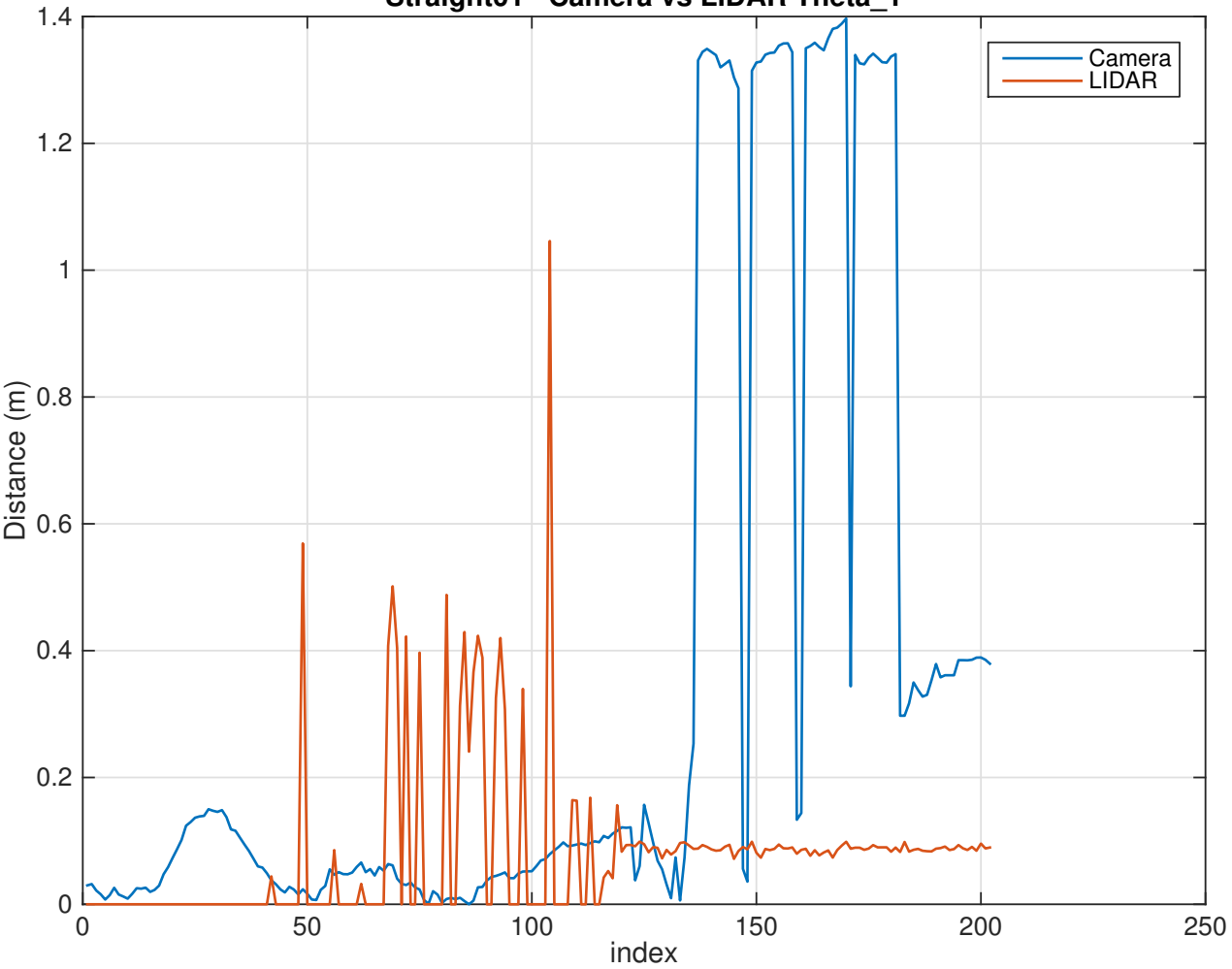
Straight01 Camera Theta_1 vs Theta_2



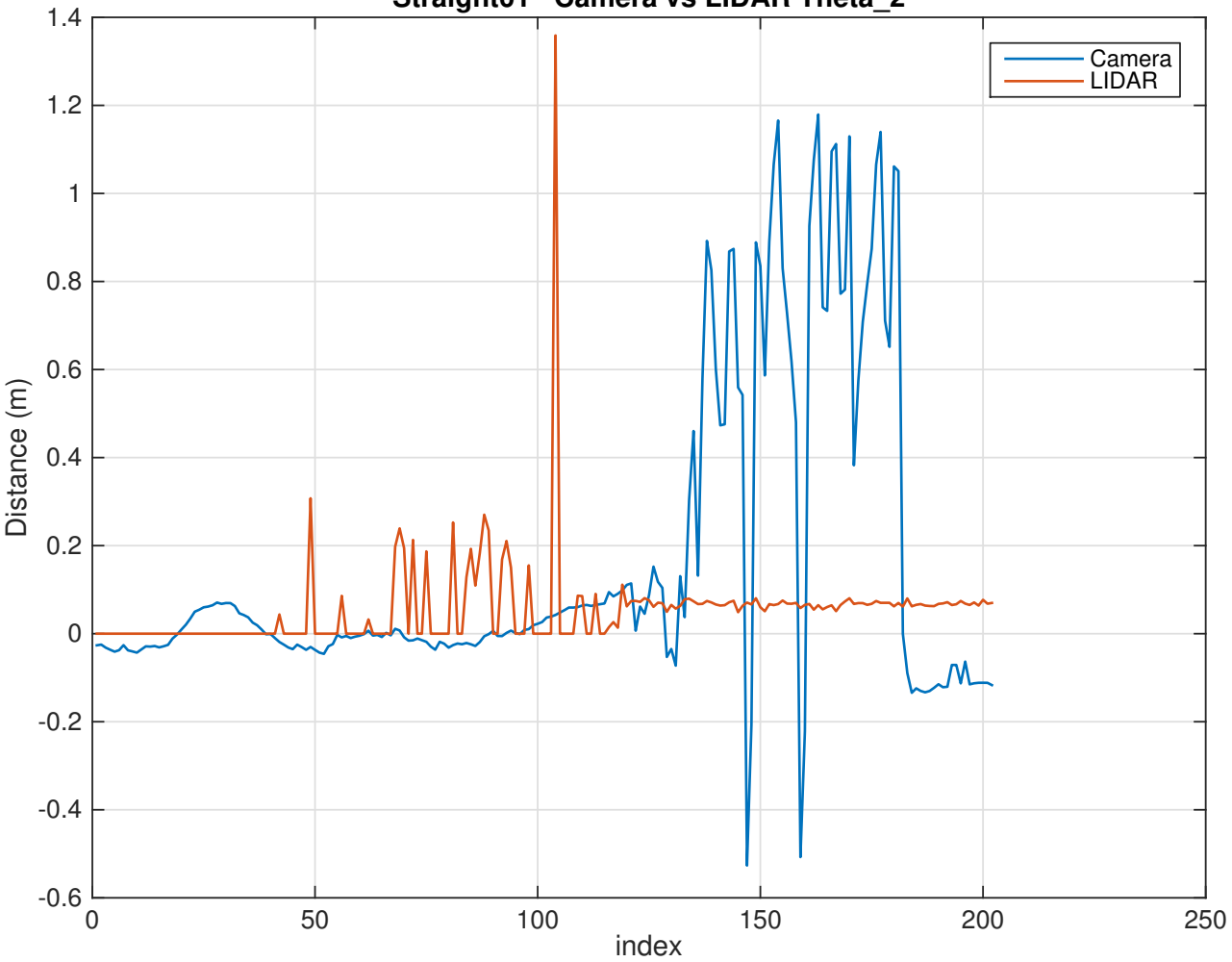
Straight01 LIDAR Theta_1 vs Theta_2



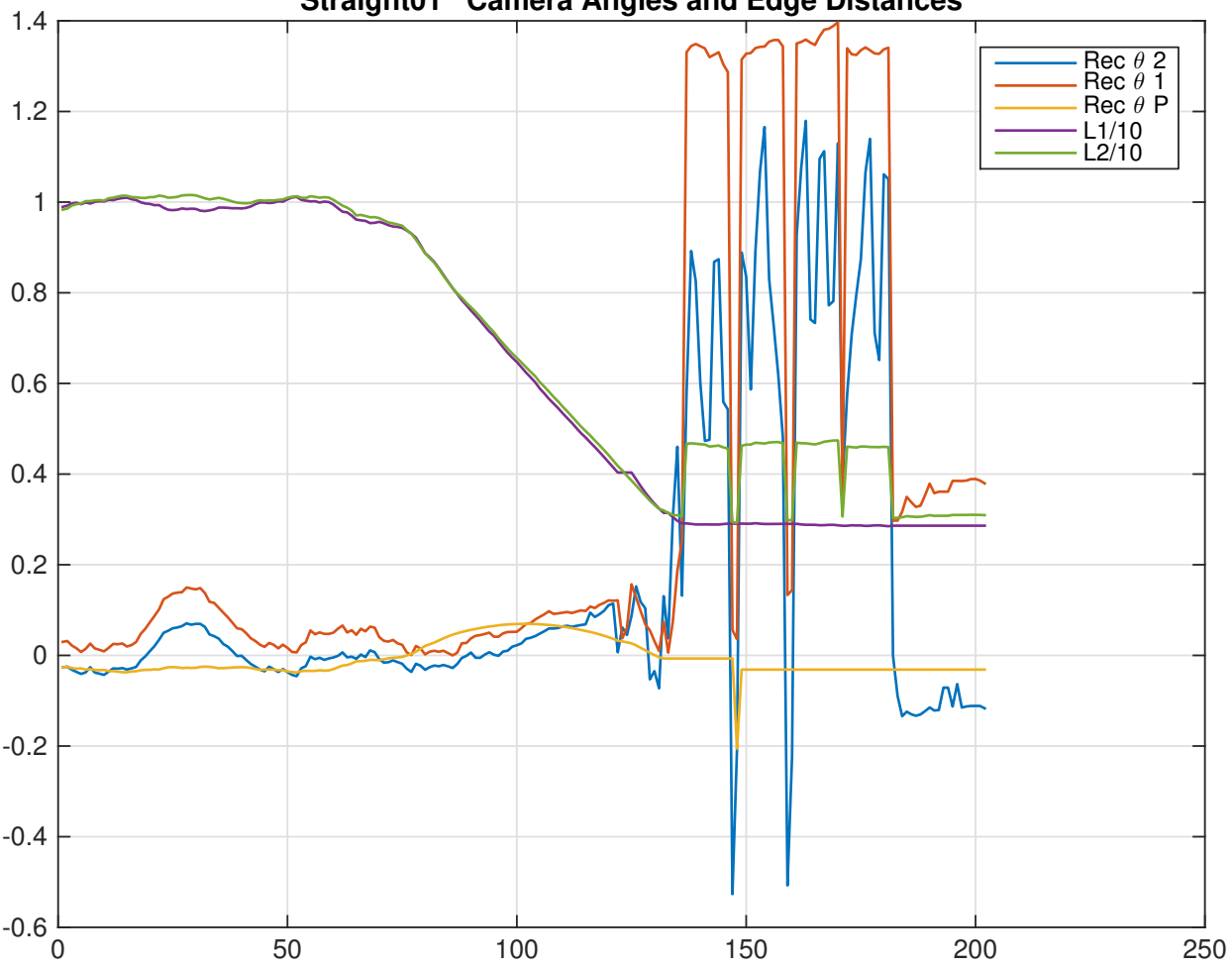
Straight01 Camera vs LIDAR Theta_1



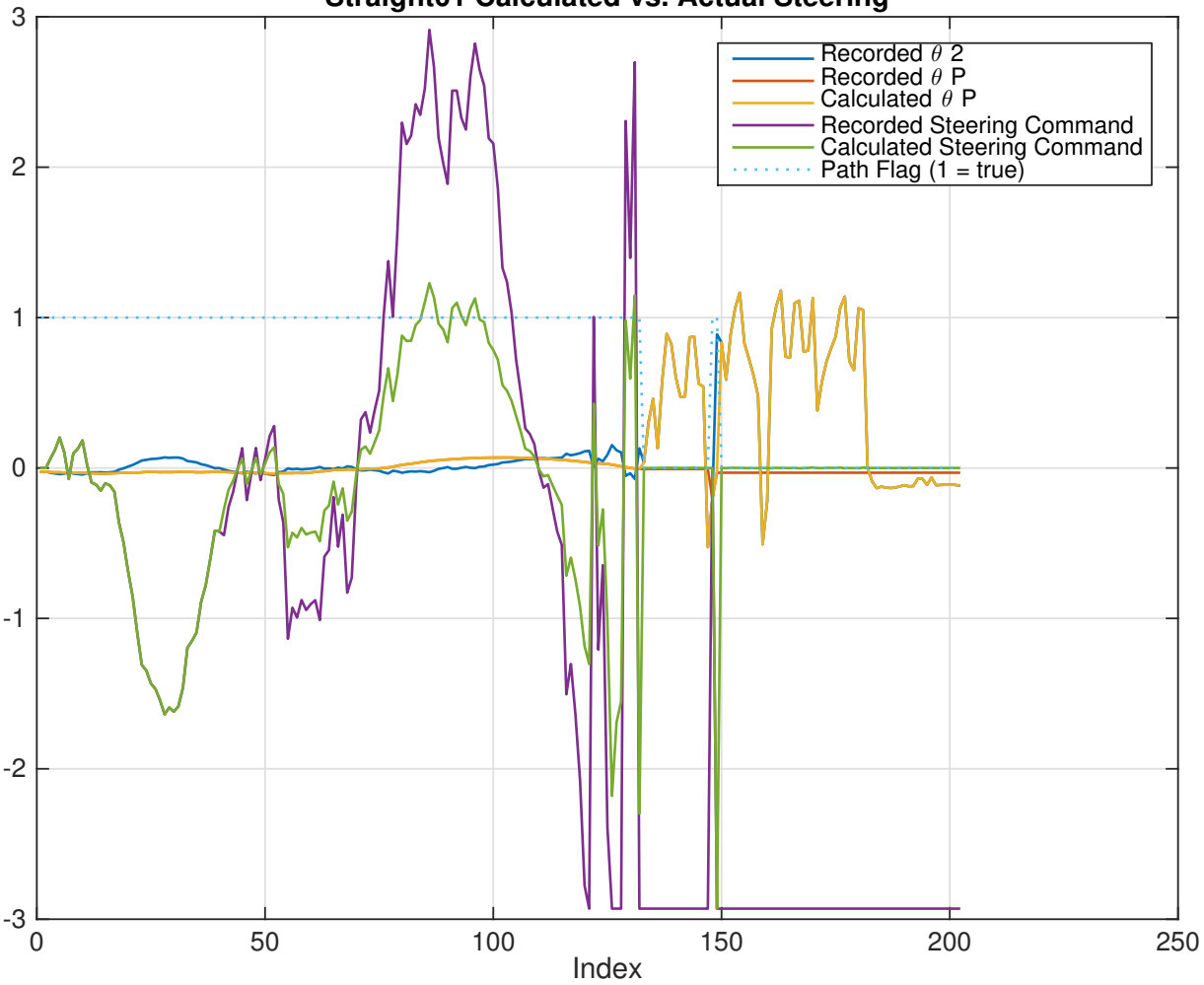
Straight01 Camera vs LIDAR Theta_2



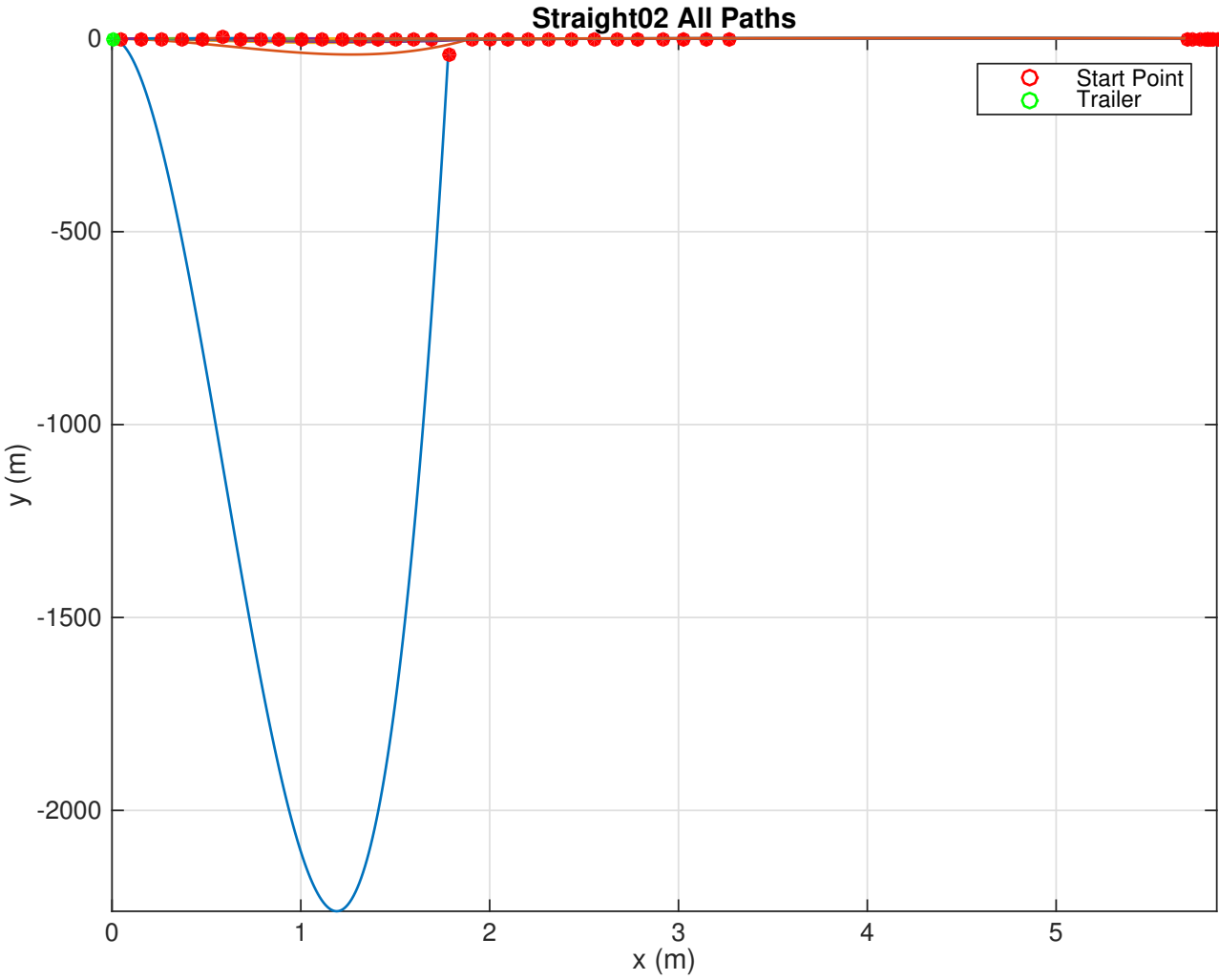
Straight01 Camera Angles and Edge Distances



Straight01 Calculated vs. Actual Steering



Straight02 All Paths



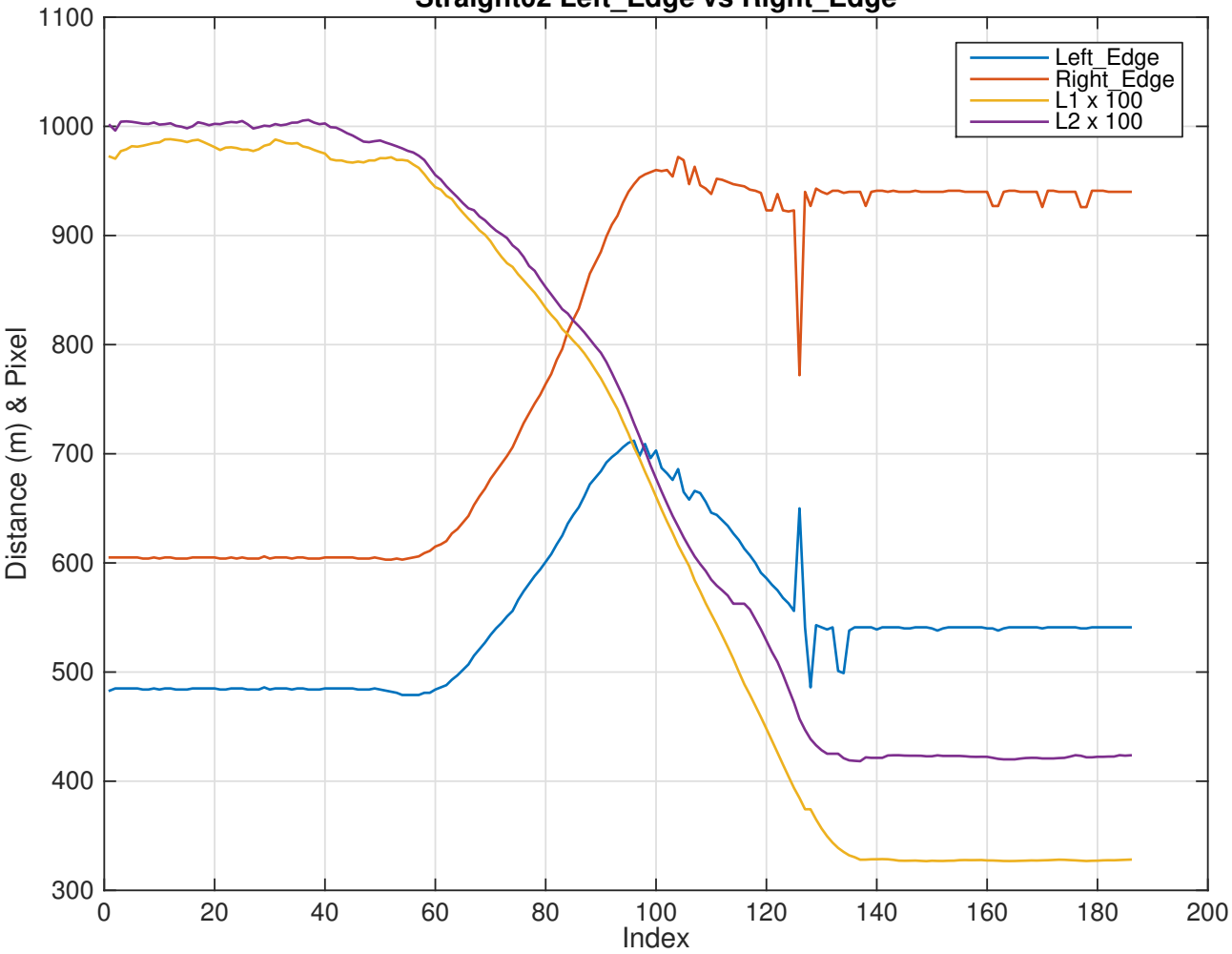
Number_Of_Unique_Paths

King_Pin_Detected

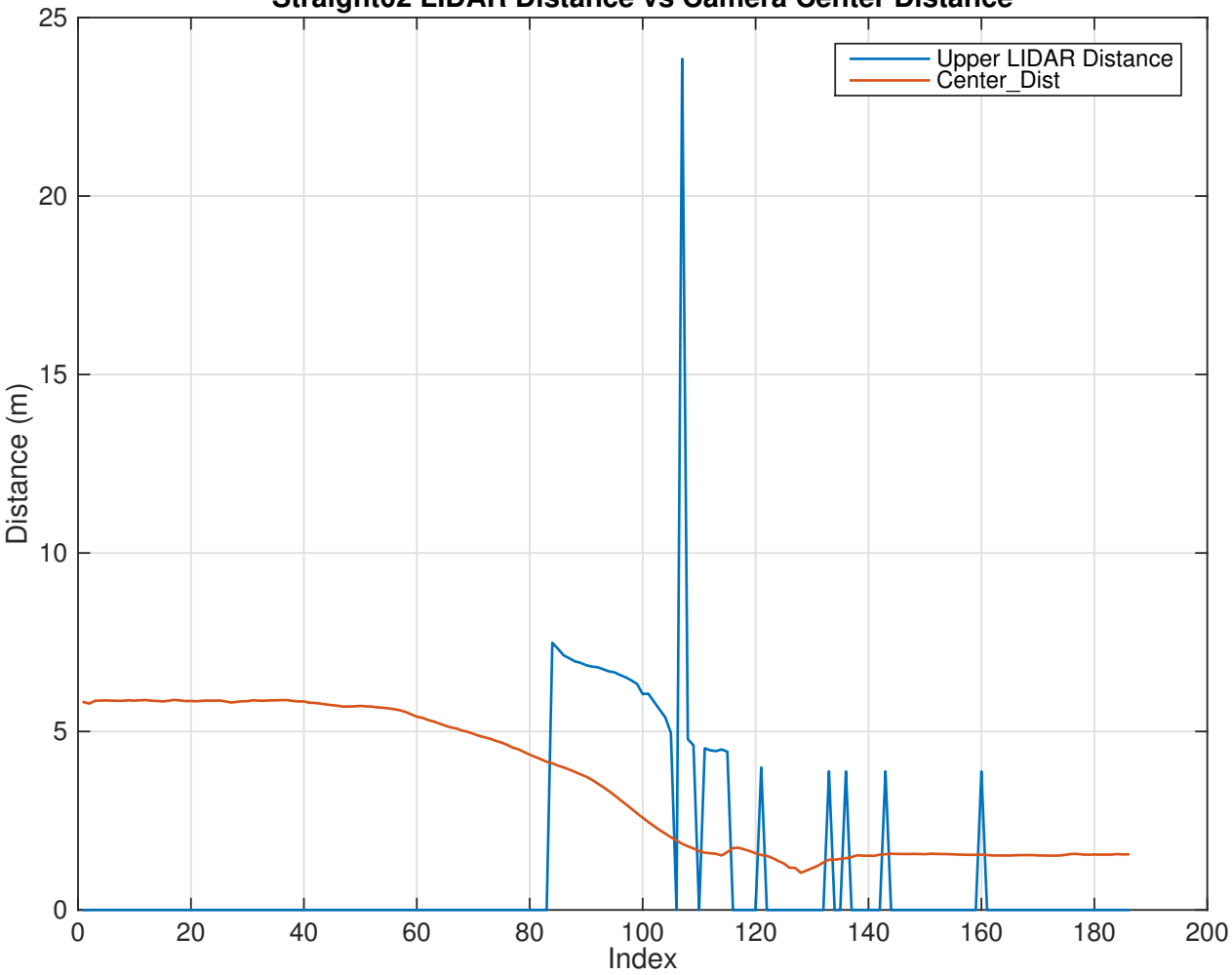
23

false

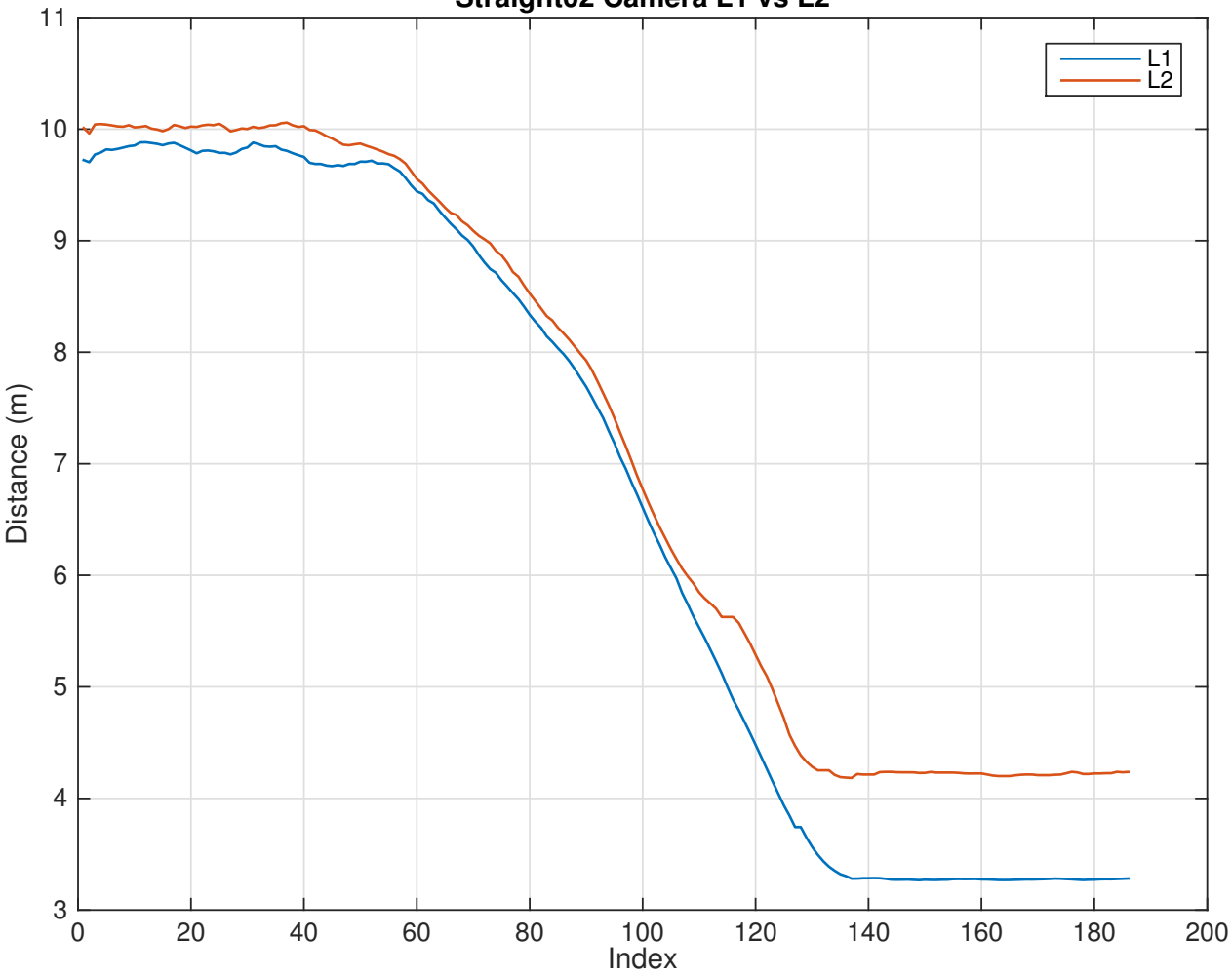
Straight02 Left_Edge vs Right_Edge



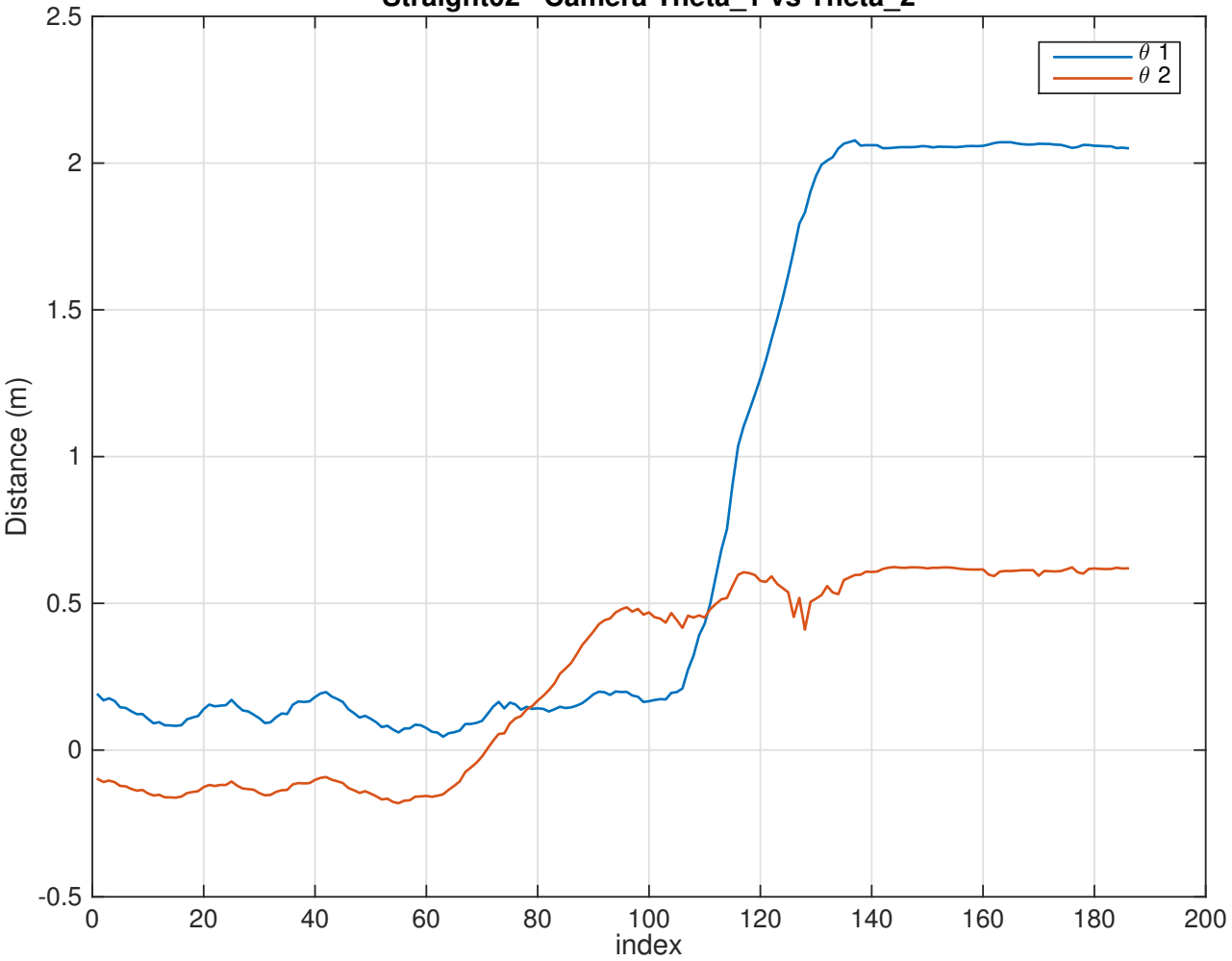
Straight02 LIDAR Distance vs Camera Center Distance



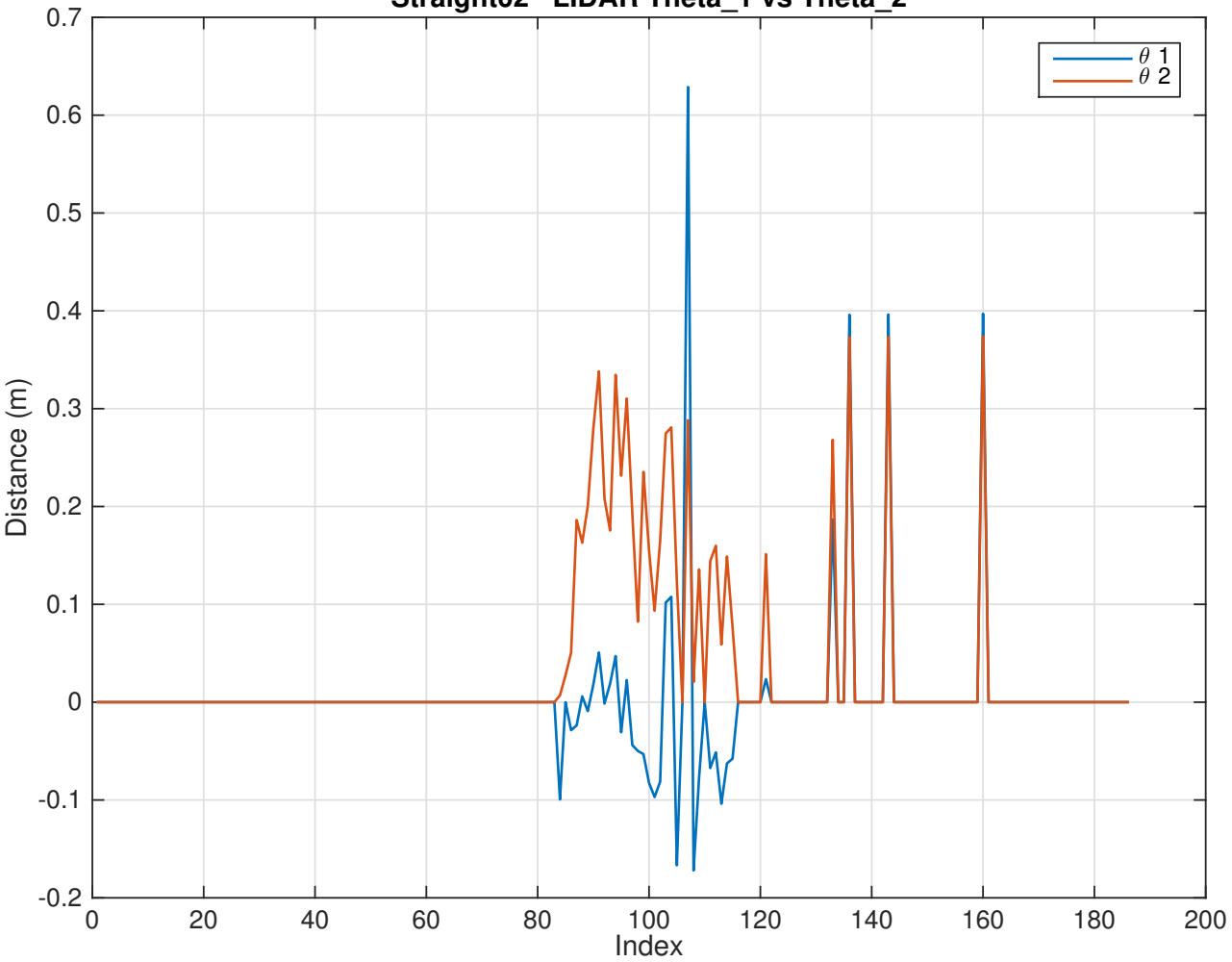
Straight02 Camera L1 vs L2



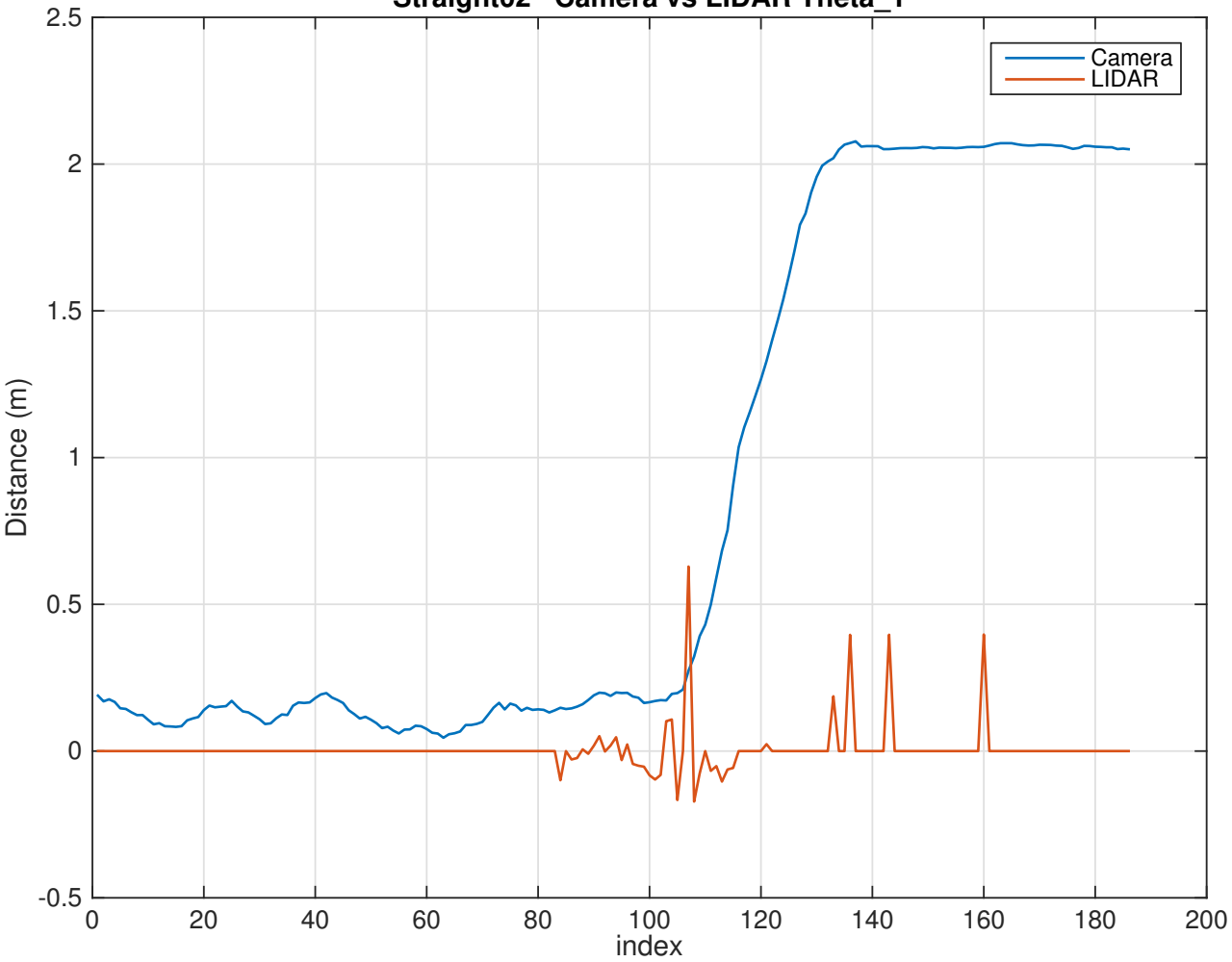
Straight02 Camera Theta_1 vs Theta_2



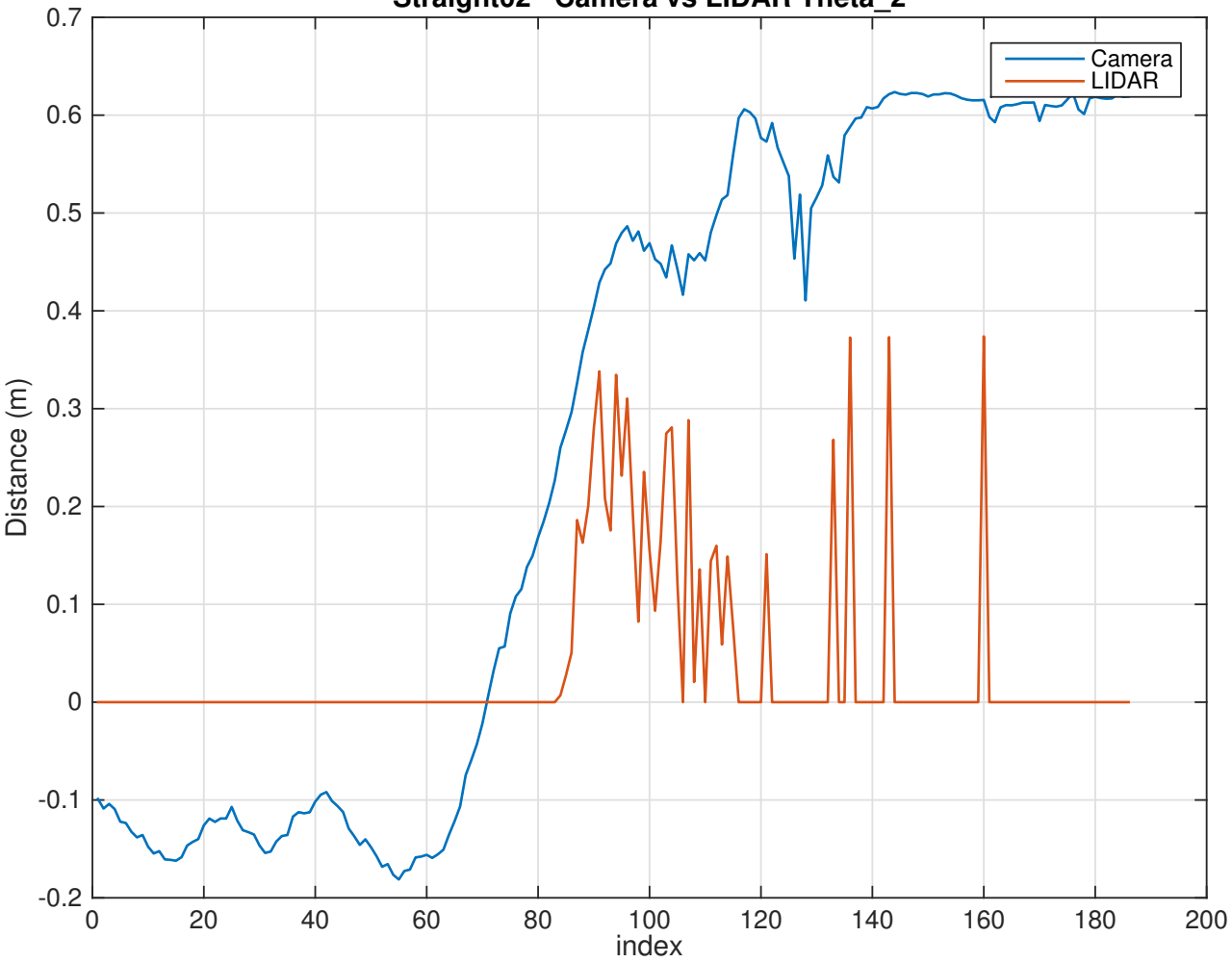
Straight02 LIDAR Theta_1 vs Theta_2



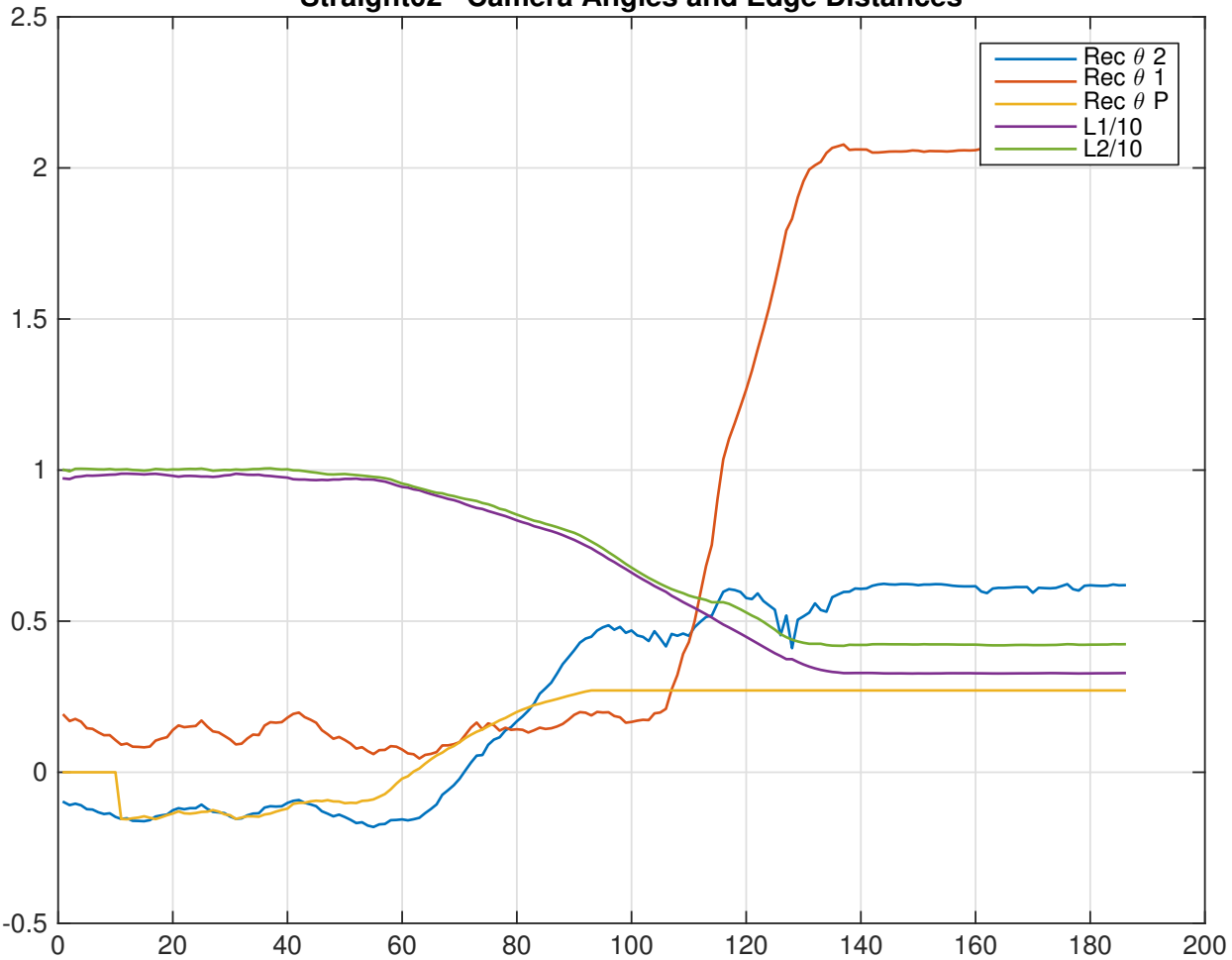
Straight02 Camera vs LIDAR Theta_1



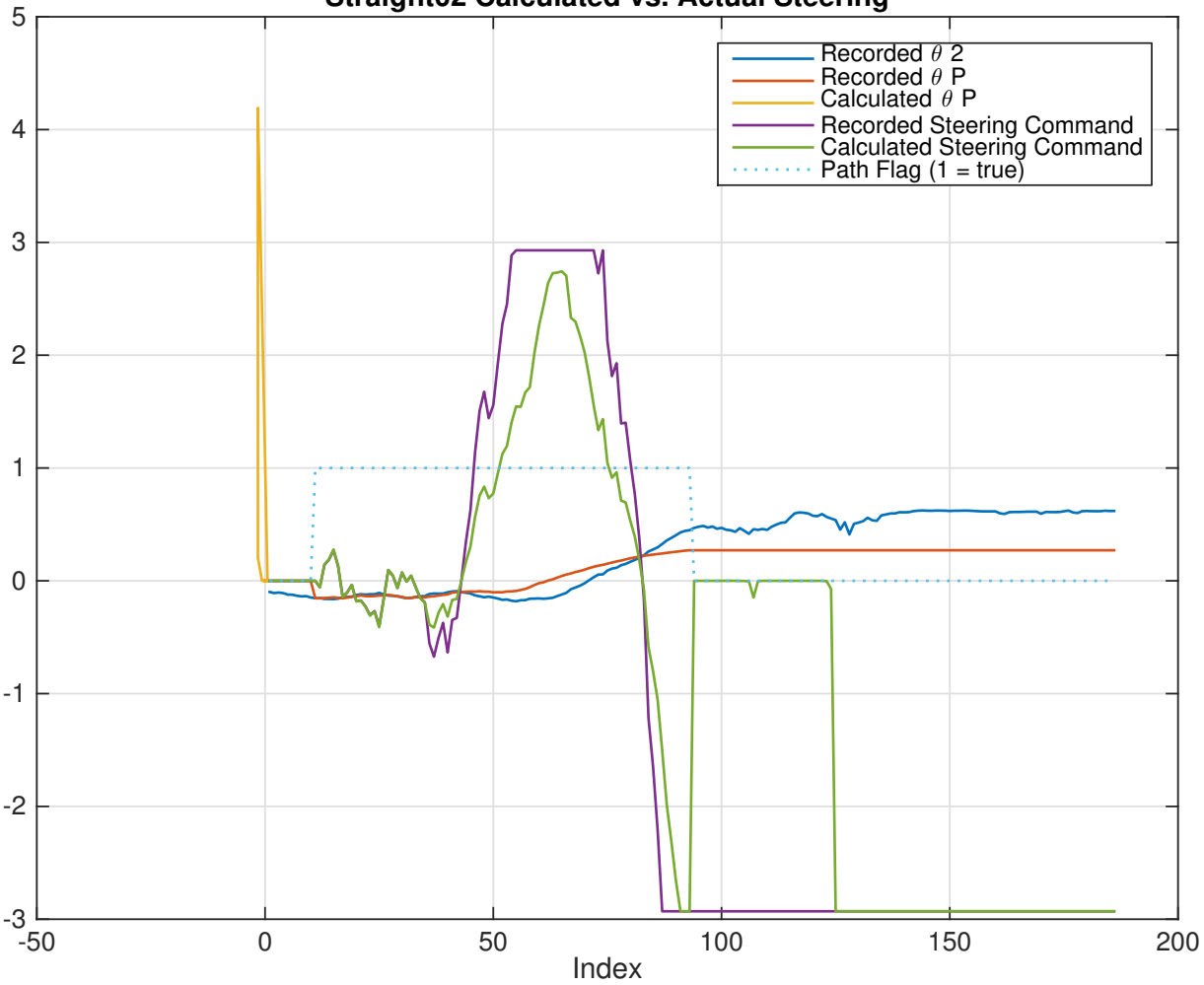
Straight02 Camera vs LIDAR Theta_2



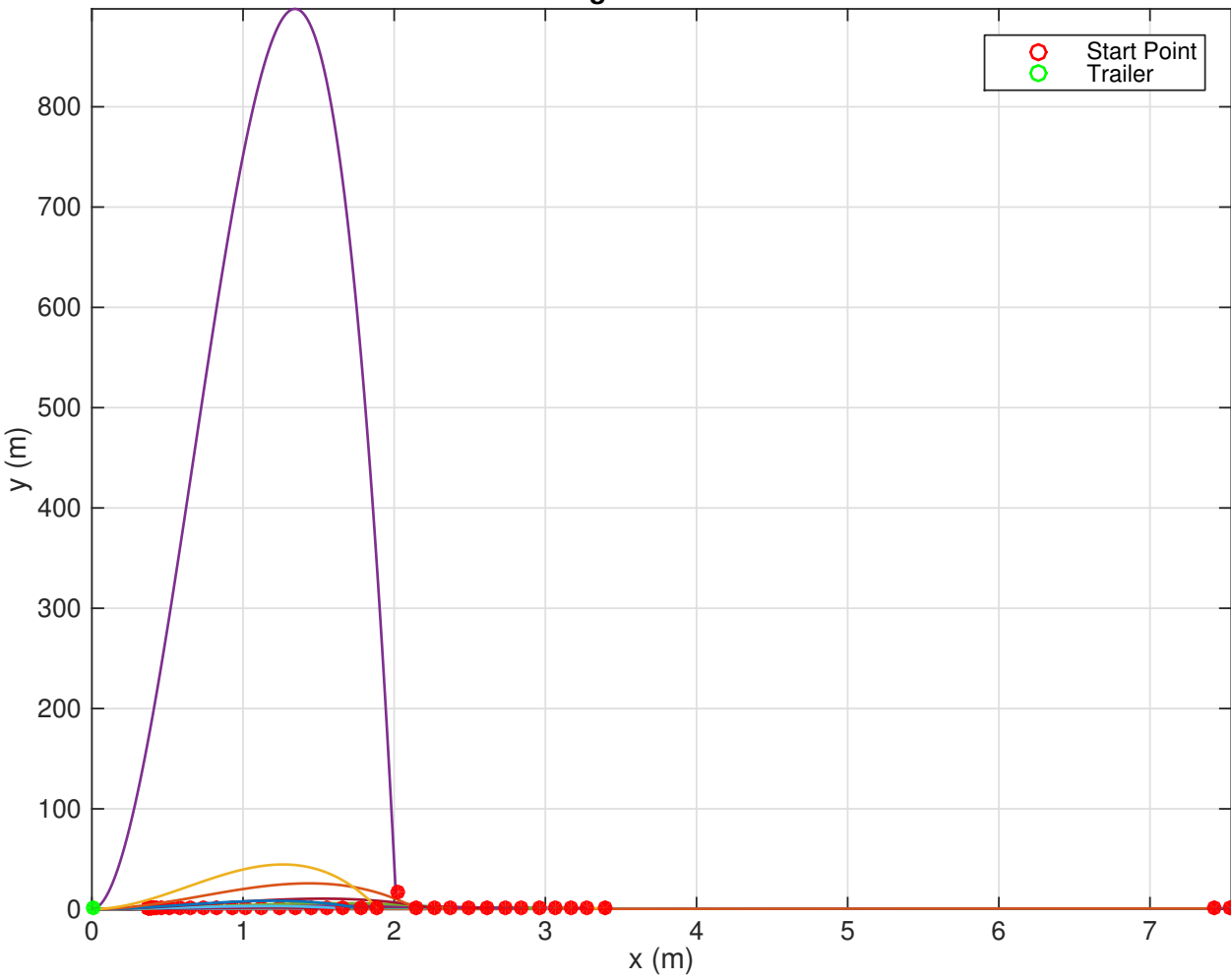
Straight02 Camera Angles and Edge Distances



Straight02 Calculated vs. Actual Steering



Straight03 All Paths



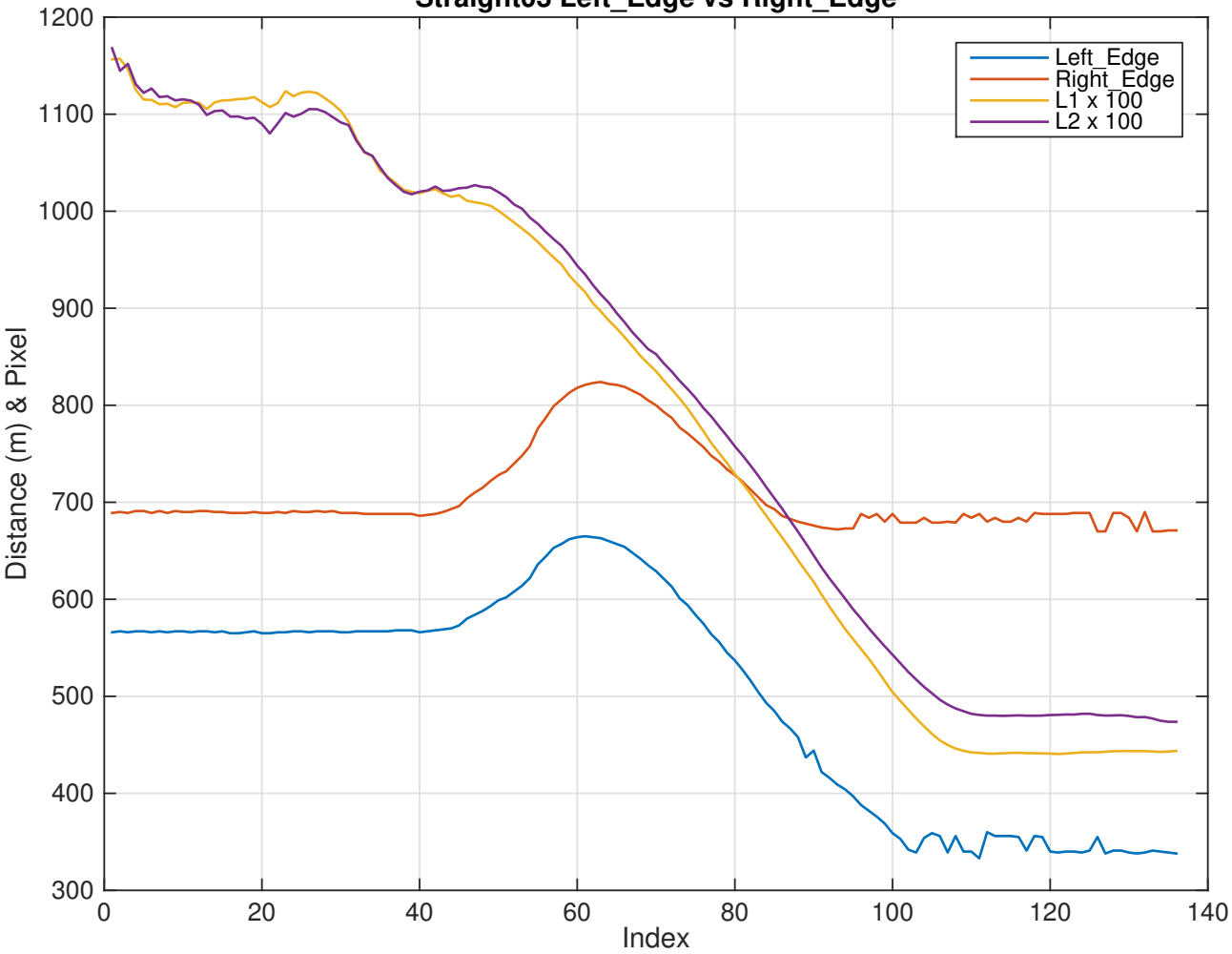
Number_Of_Unique_Paths

King_Pin_Detected

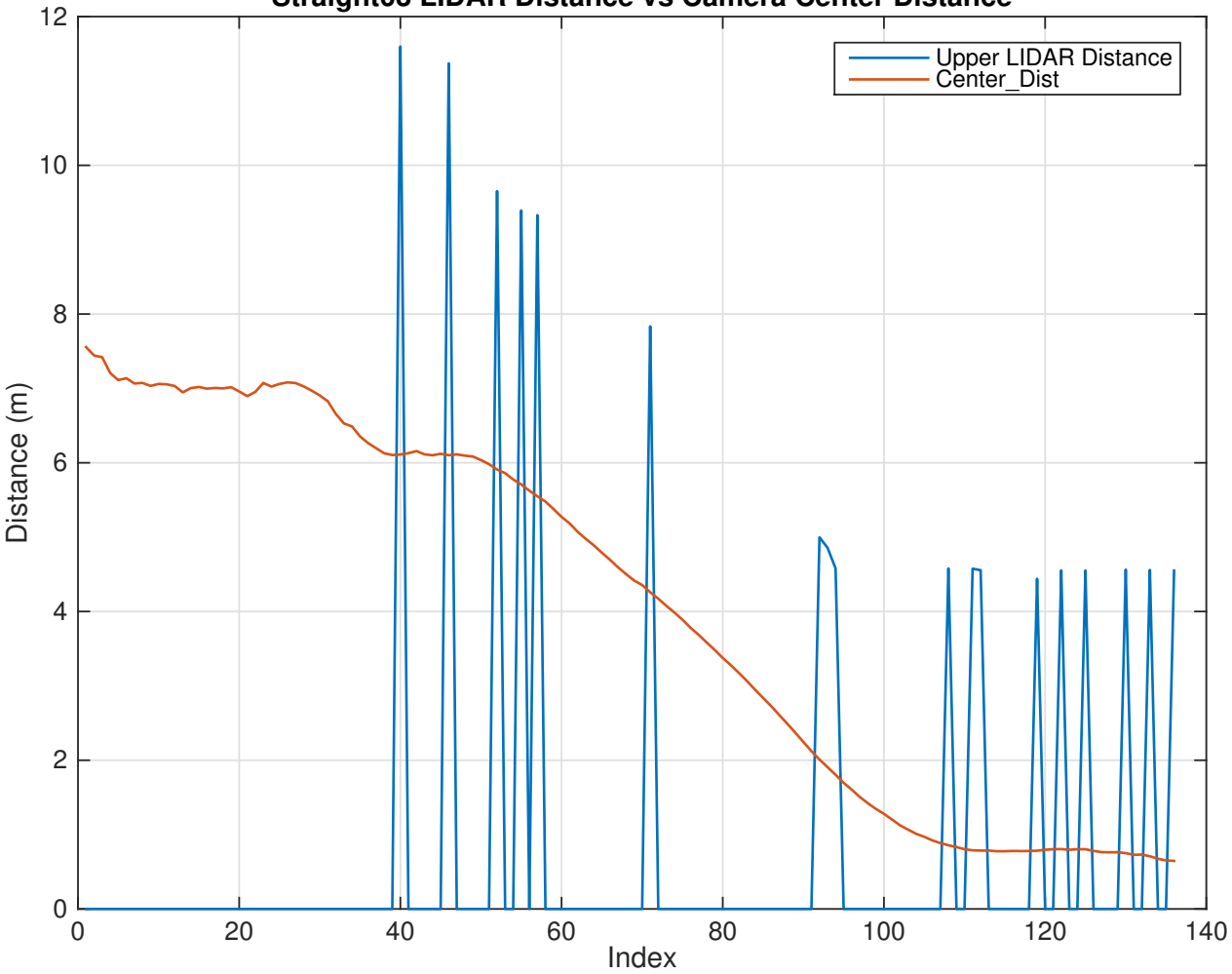
16

false

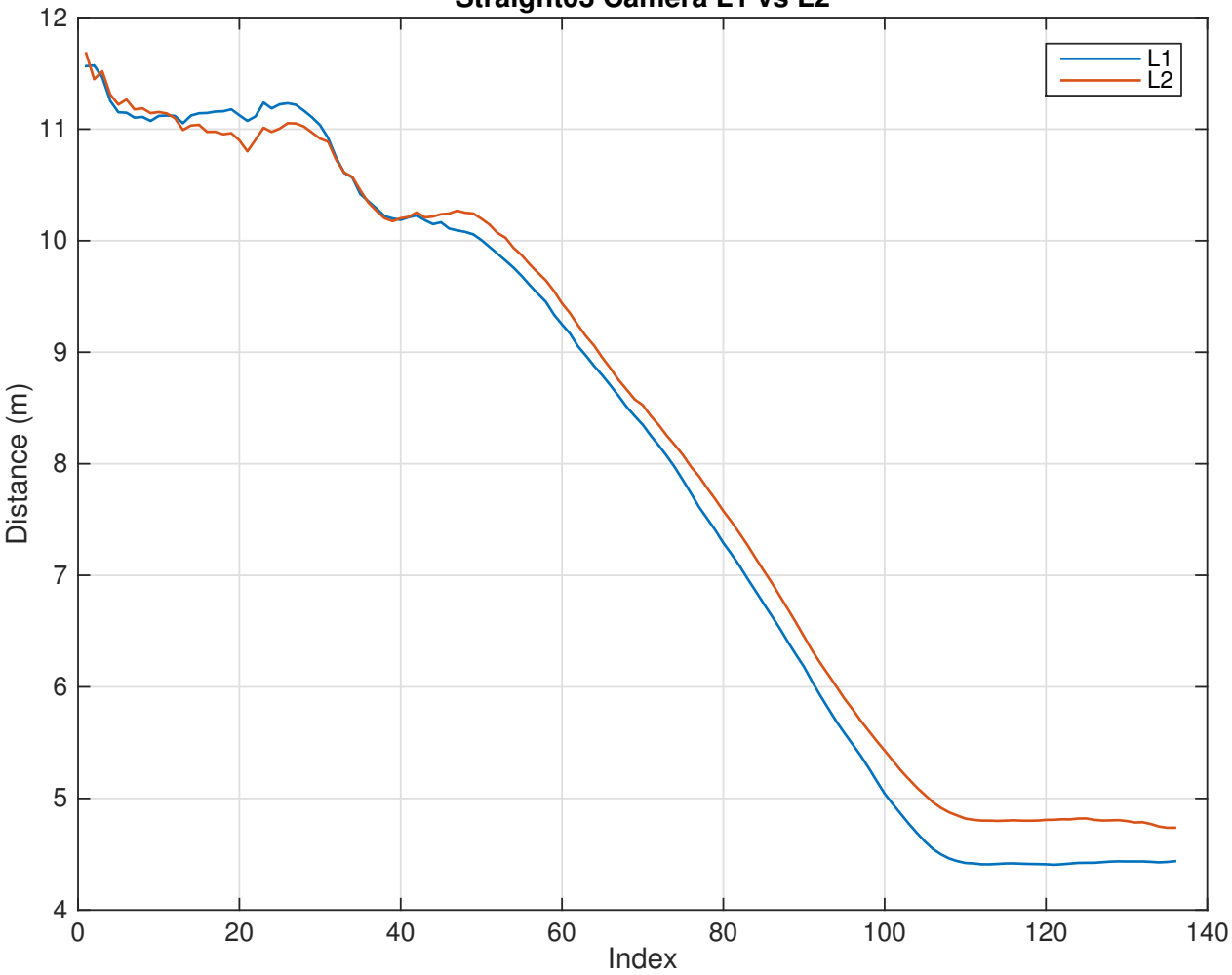
Straight03 Left_Edge vs Right_Edge



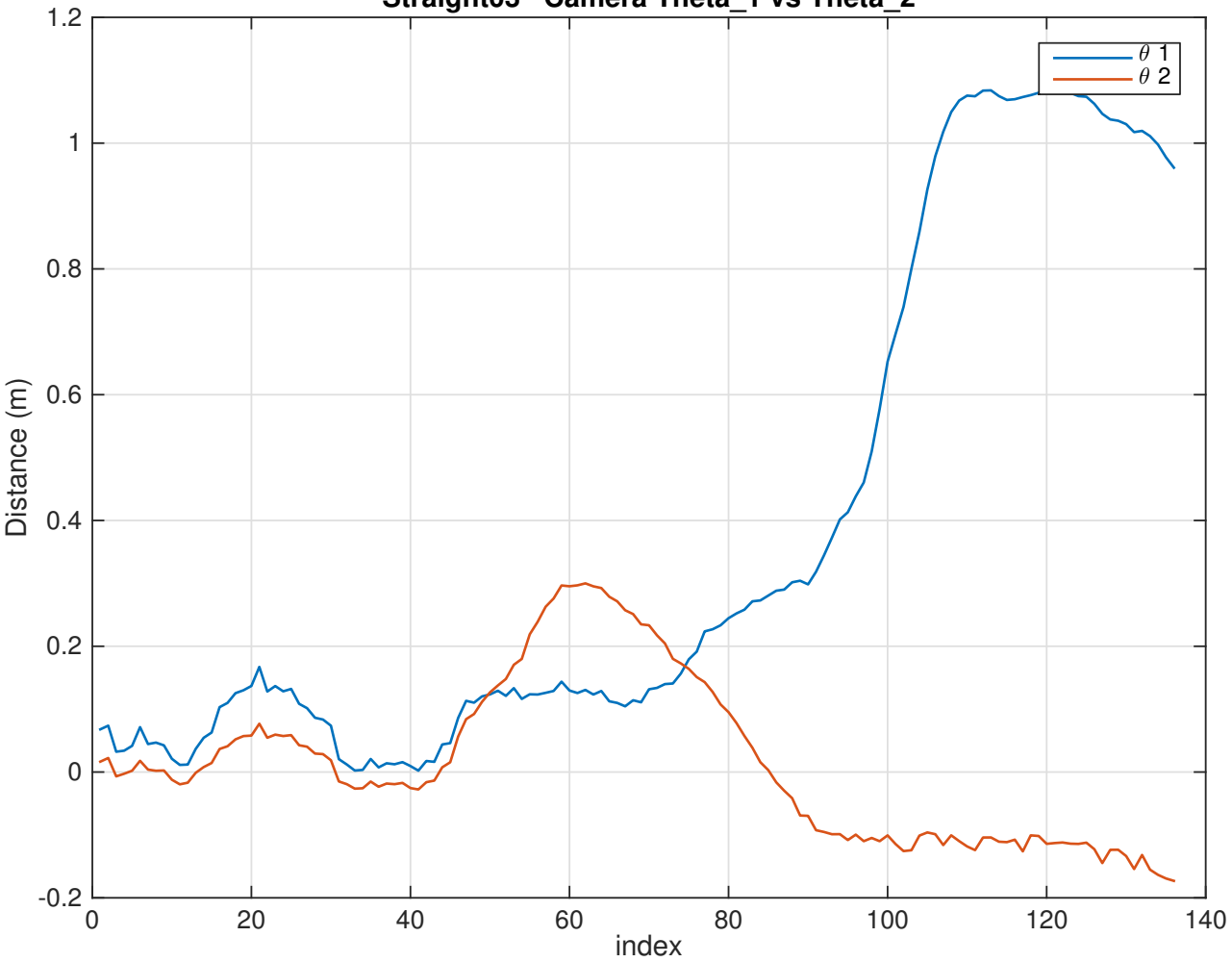
Straight03 LIDAR Distance vs Camera Center Distance



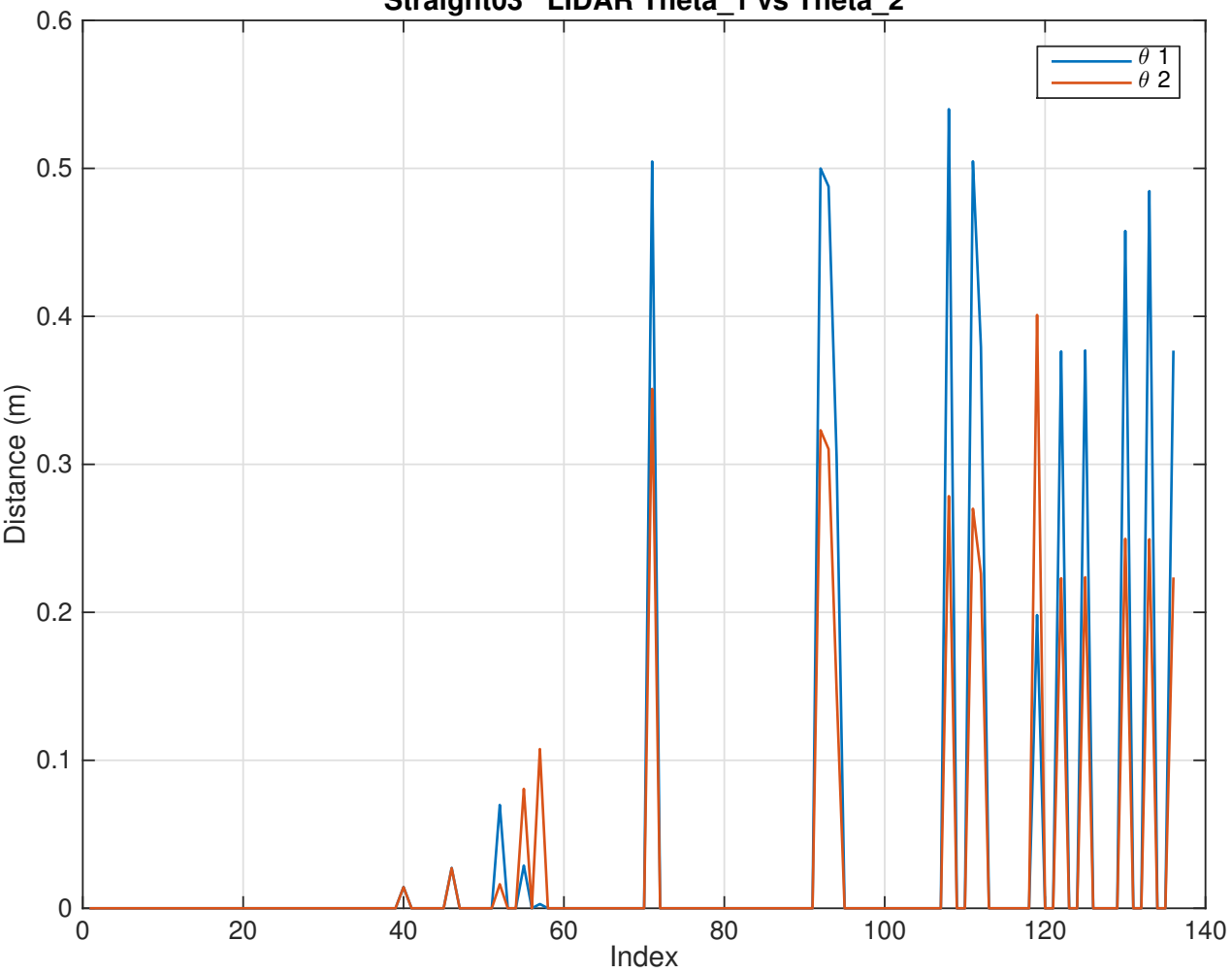
Straight03 Camera L1 vs L2



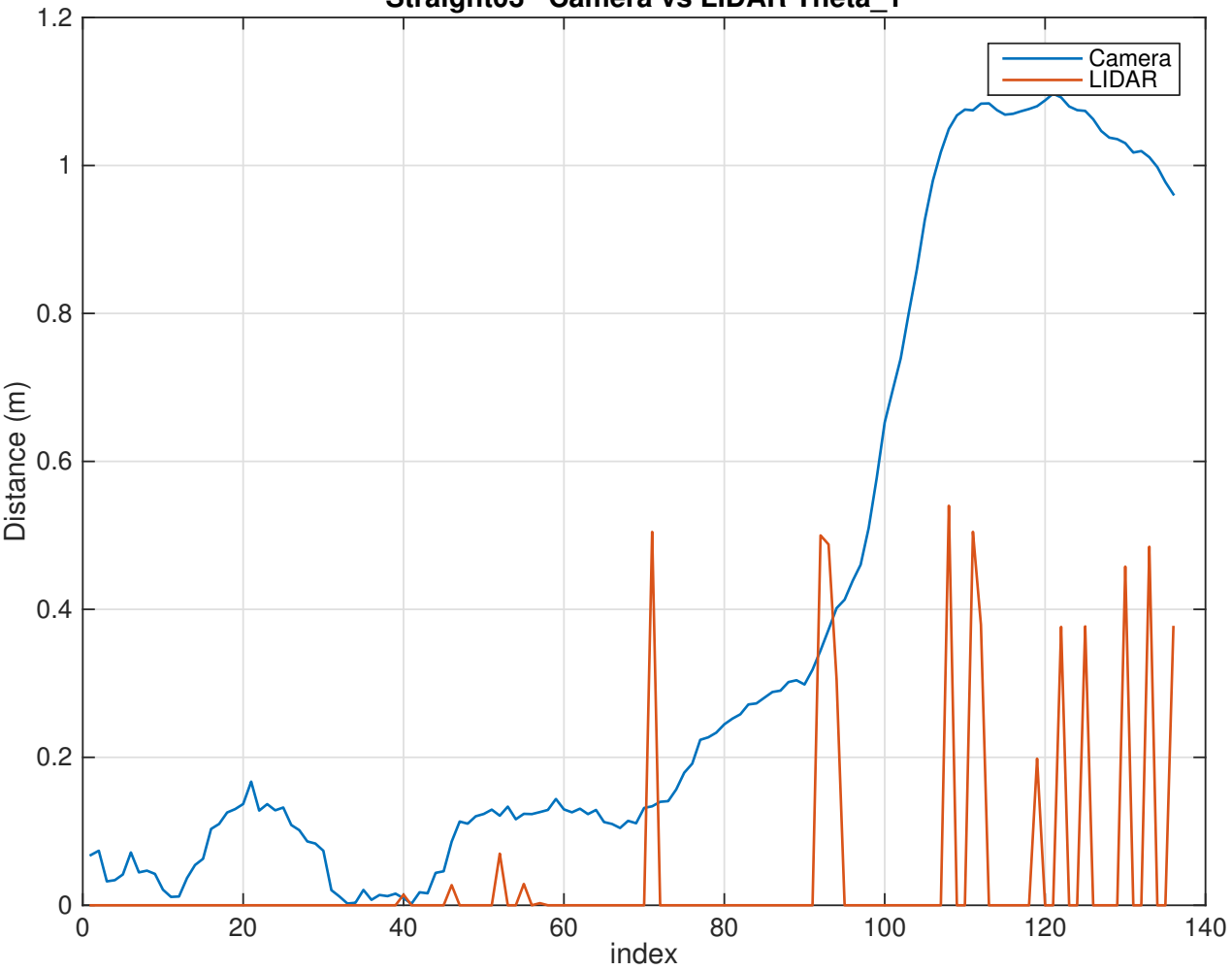
Straight03 Camera Theta_1 vs Theta_2



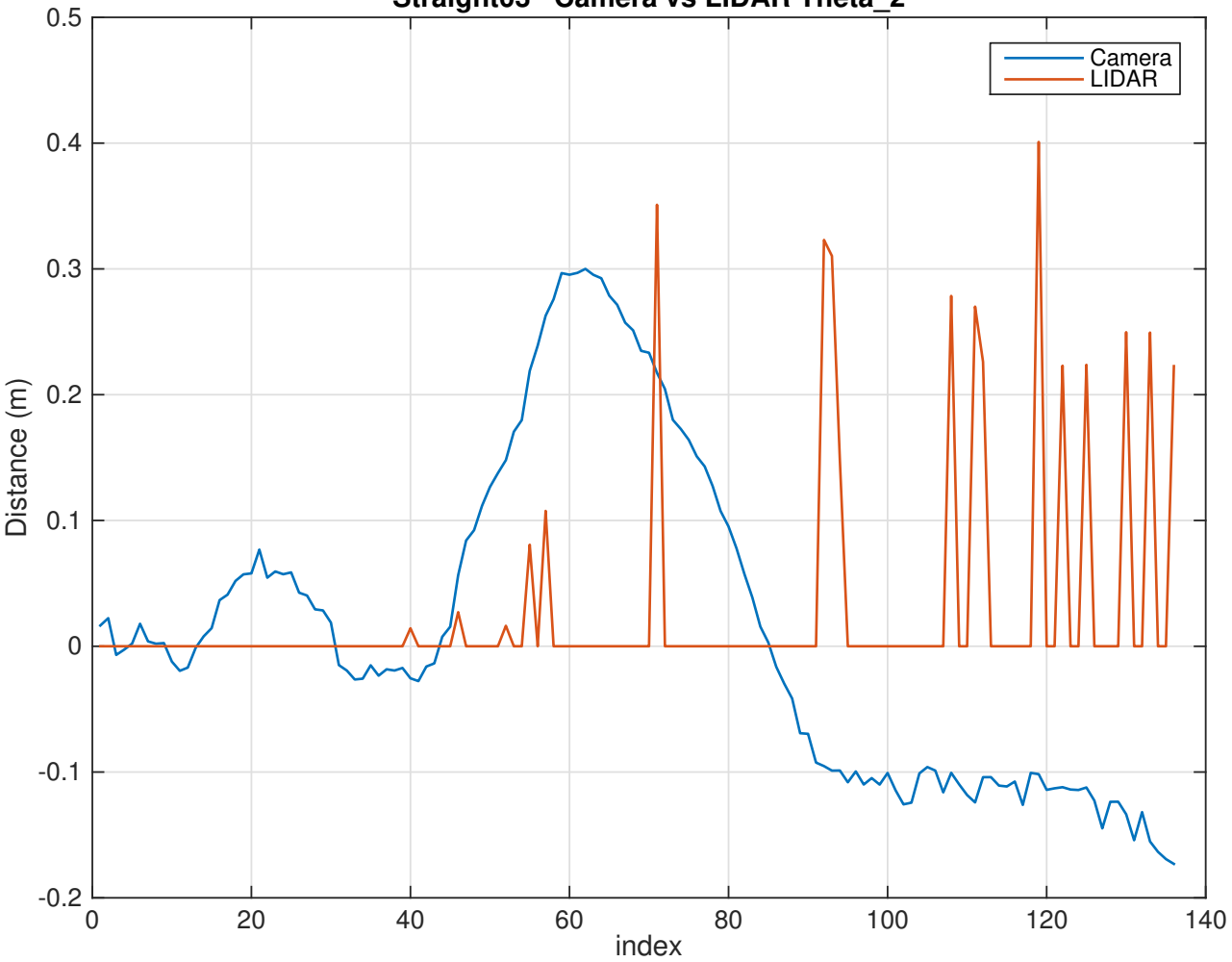
Straight03 LIDAR Theta_1 vs Theta_2



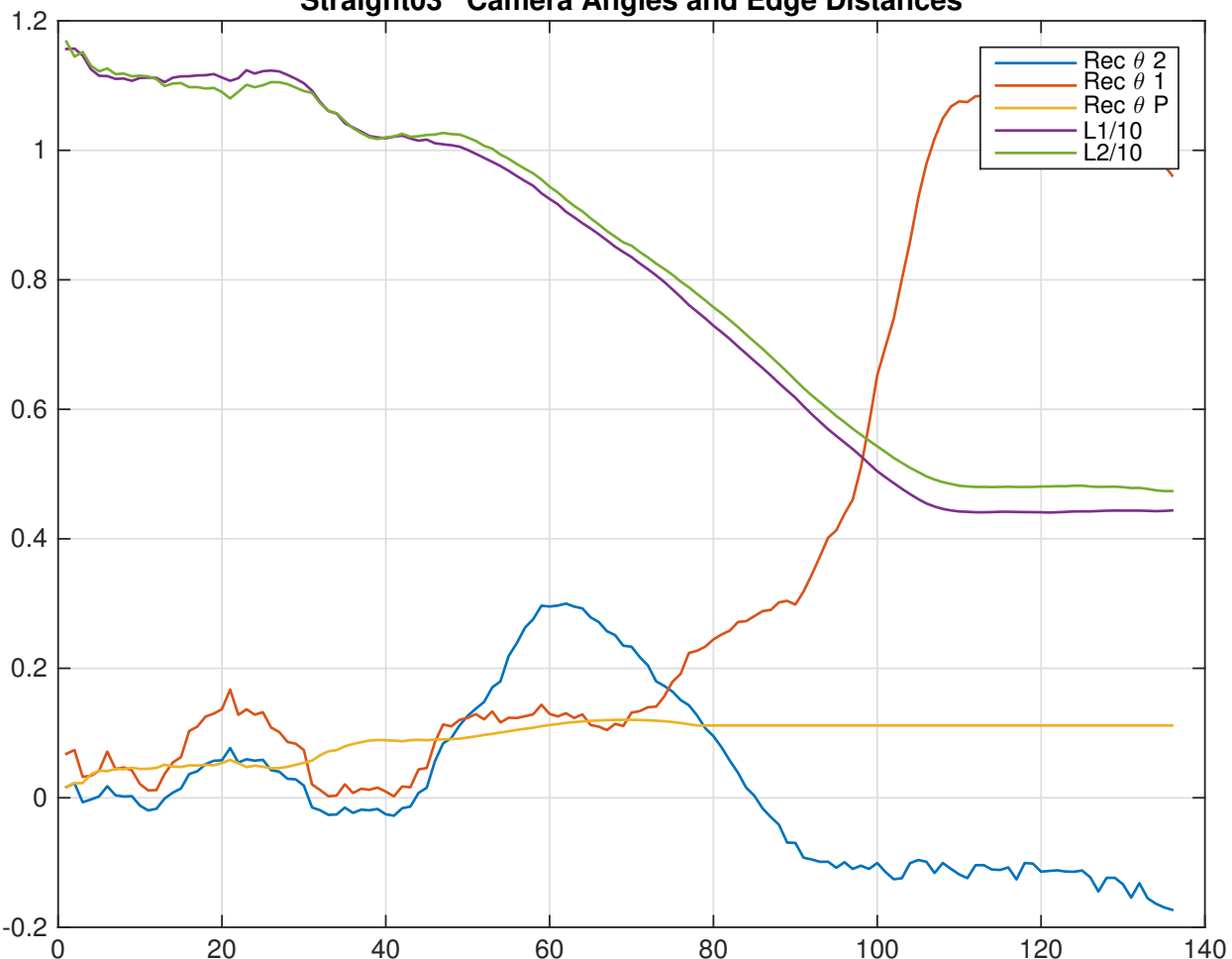
Straight03 Camera vs LIDAR Theta_1



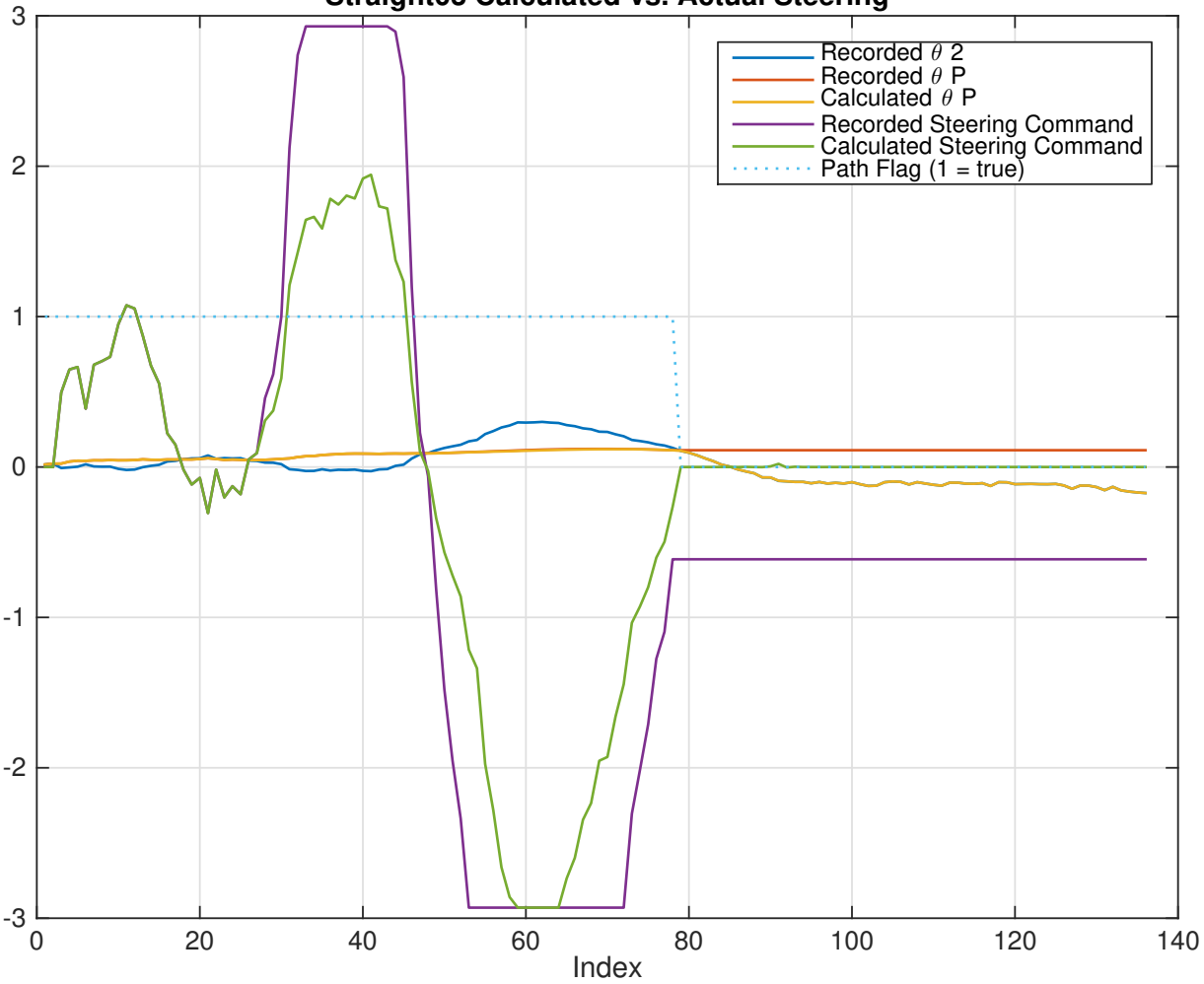
Straight03 Camera vs LIDAR Theta_2



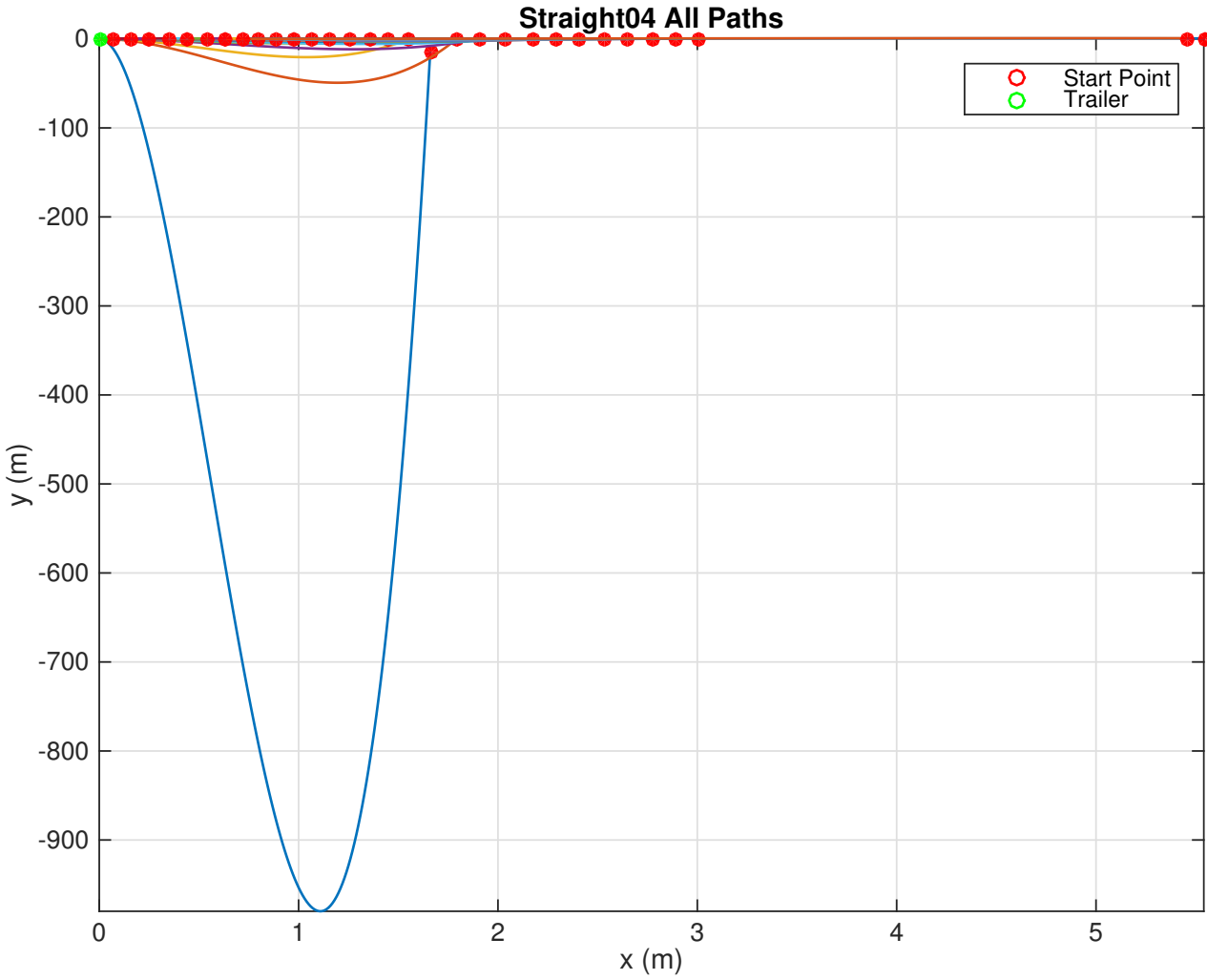
Straight03 Camera Angles and Edge Distances



Straight03 Calculated vs. Actual Steering



Straight04 All Paths



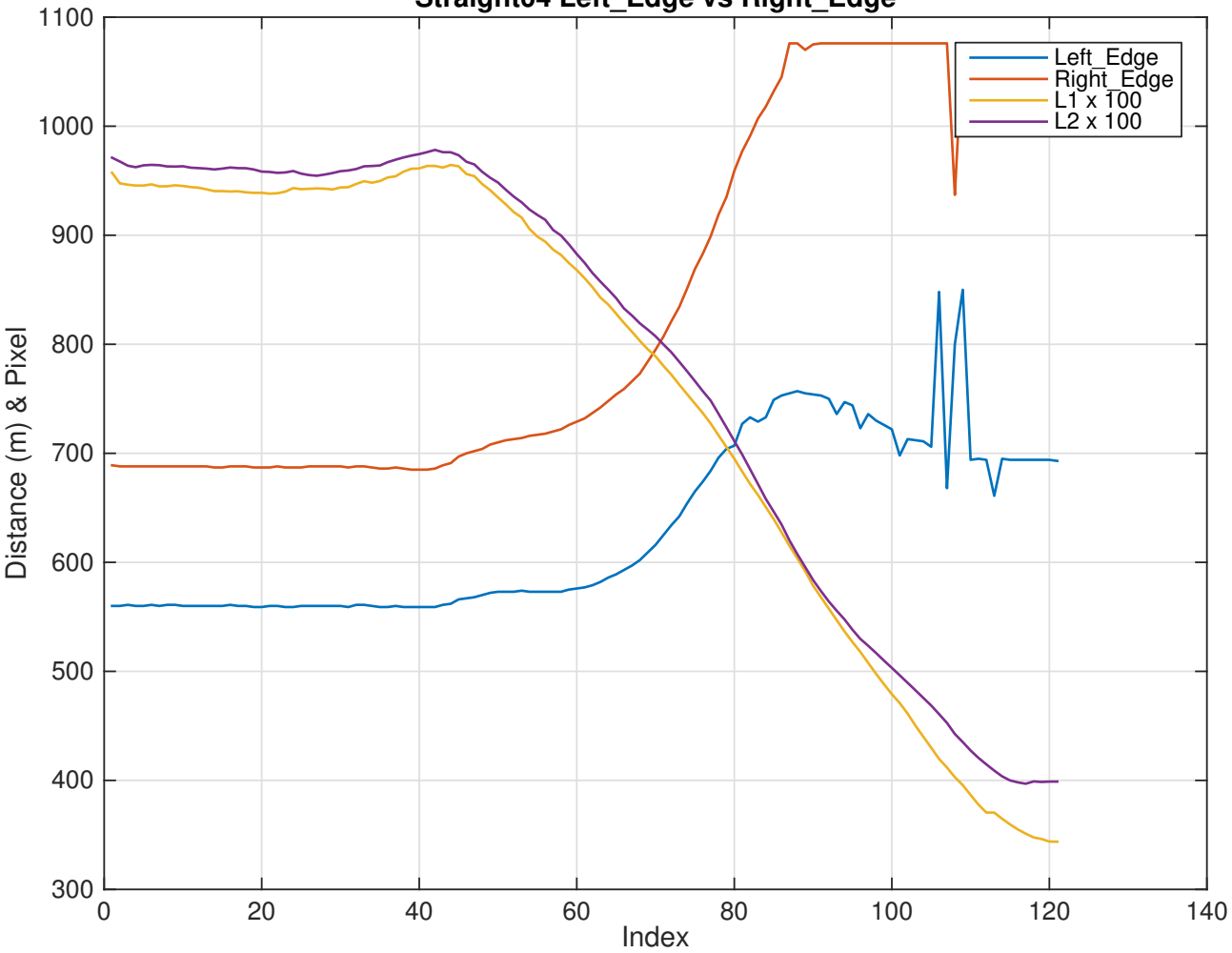
Number_Of_Unique_Paths

King_Pin_Detected

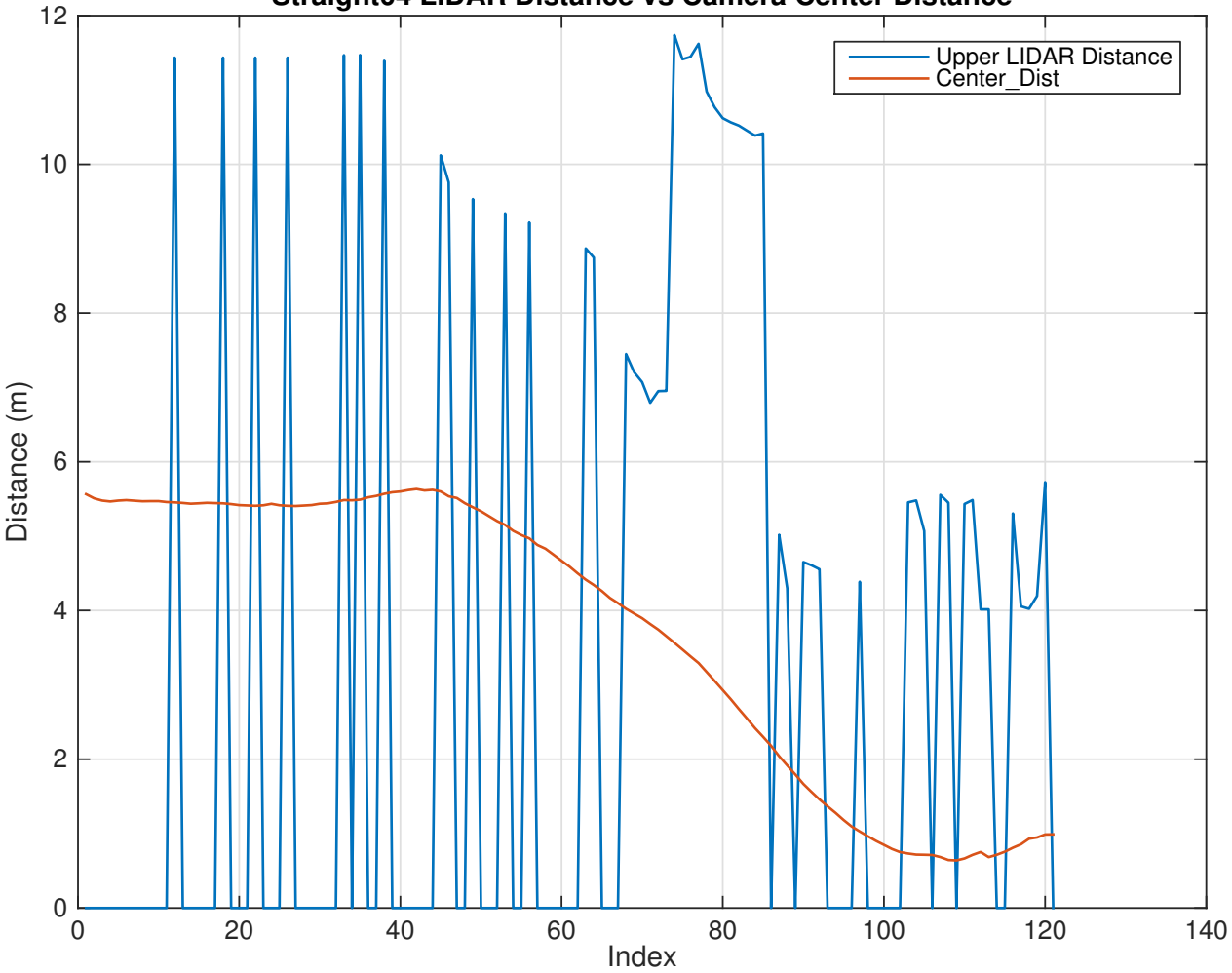
11

false

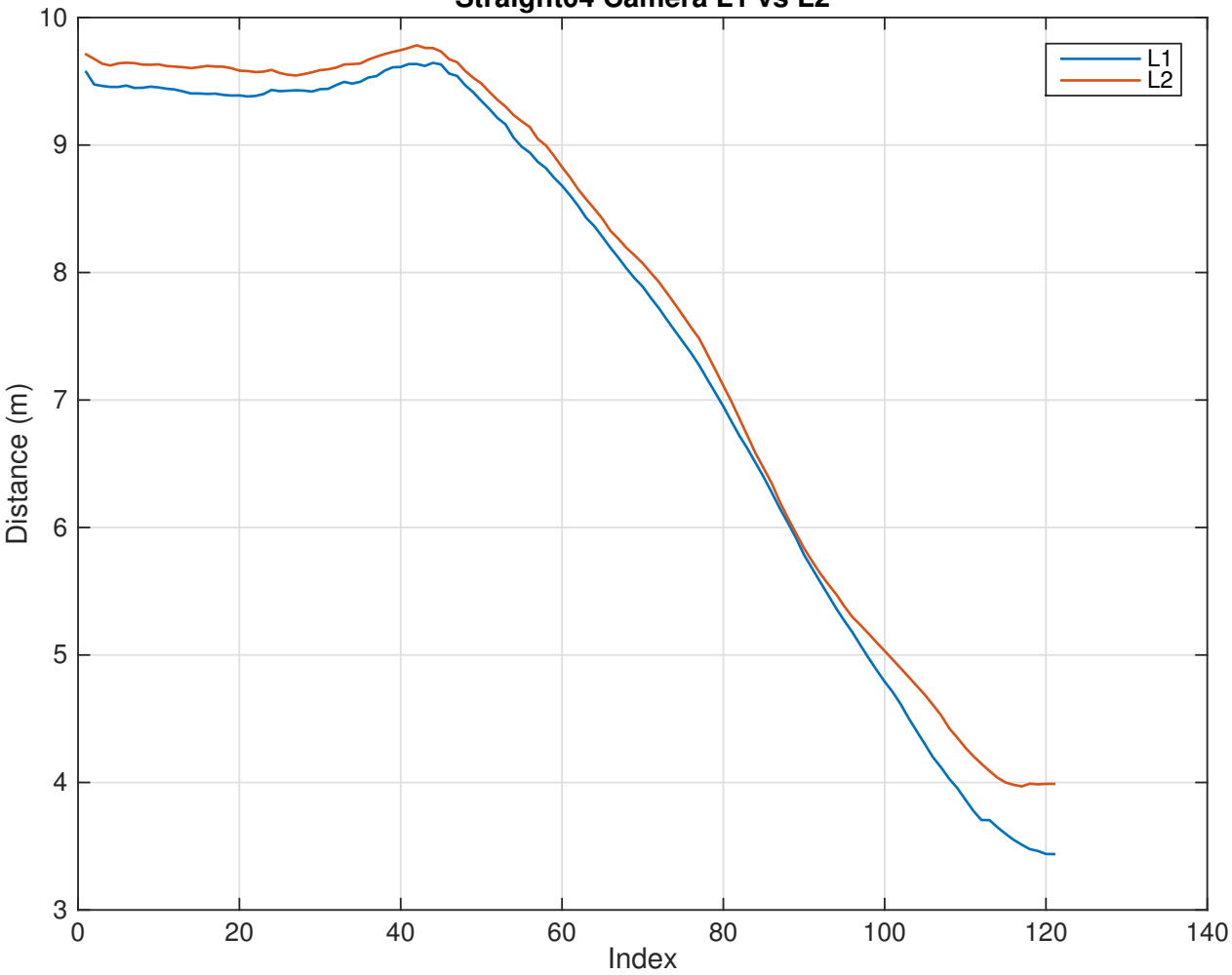
Straight04 Left_Edge vs Right_Edge



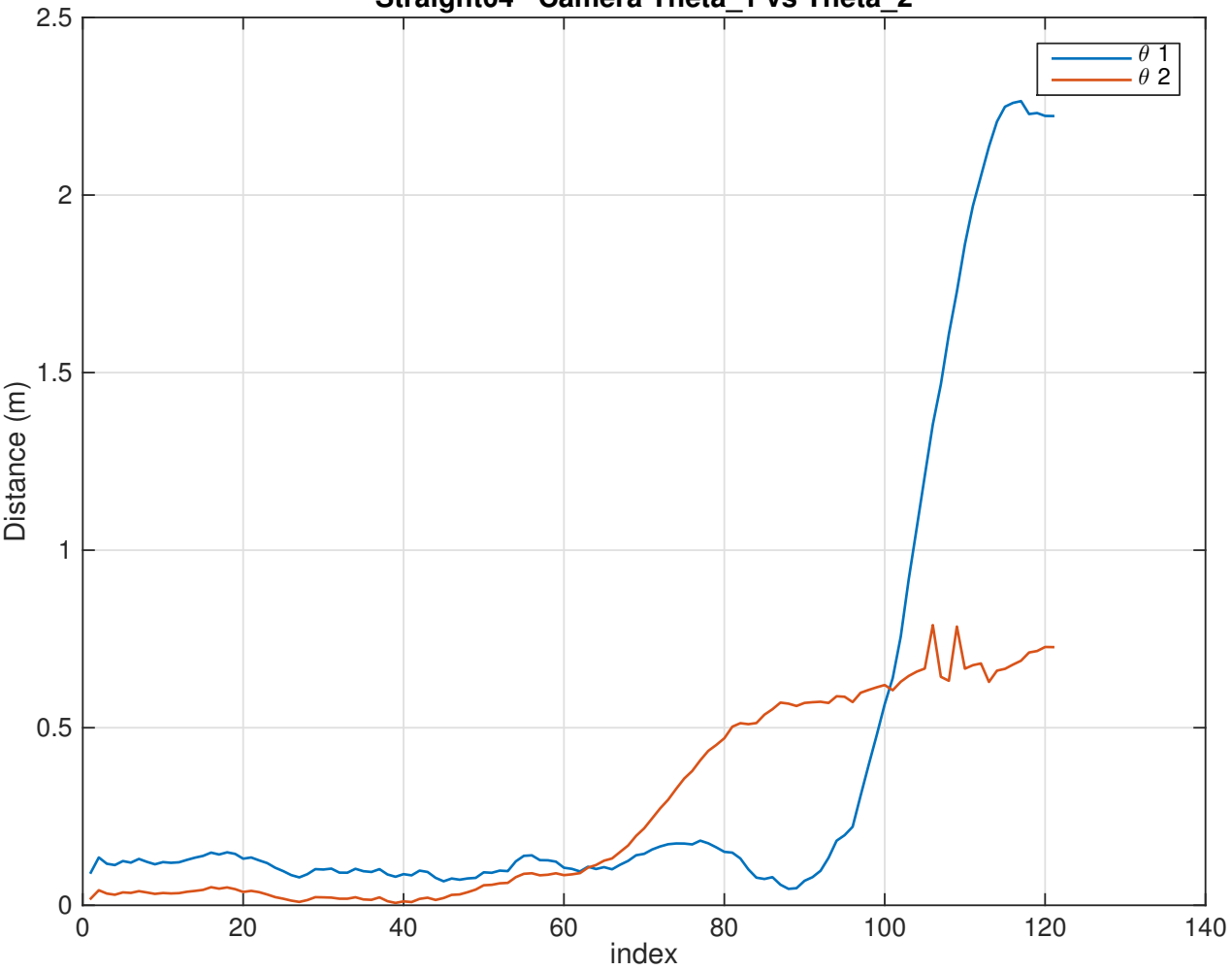
Straight04 LIDAR Distance vs Camera Center Distance



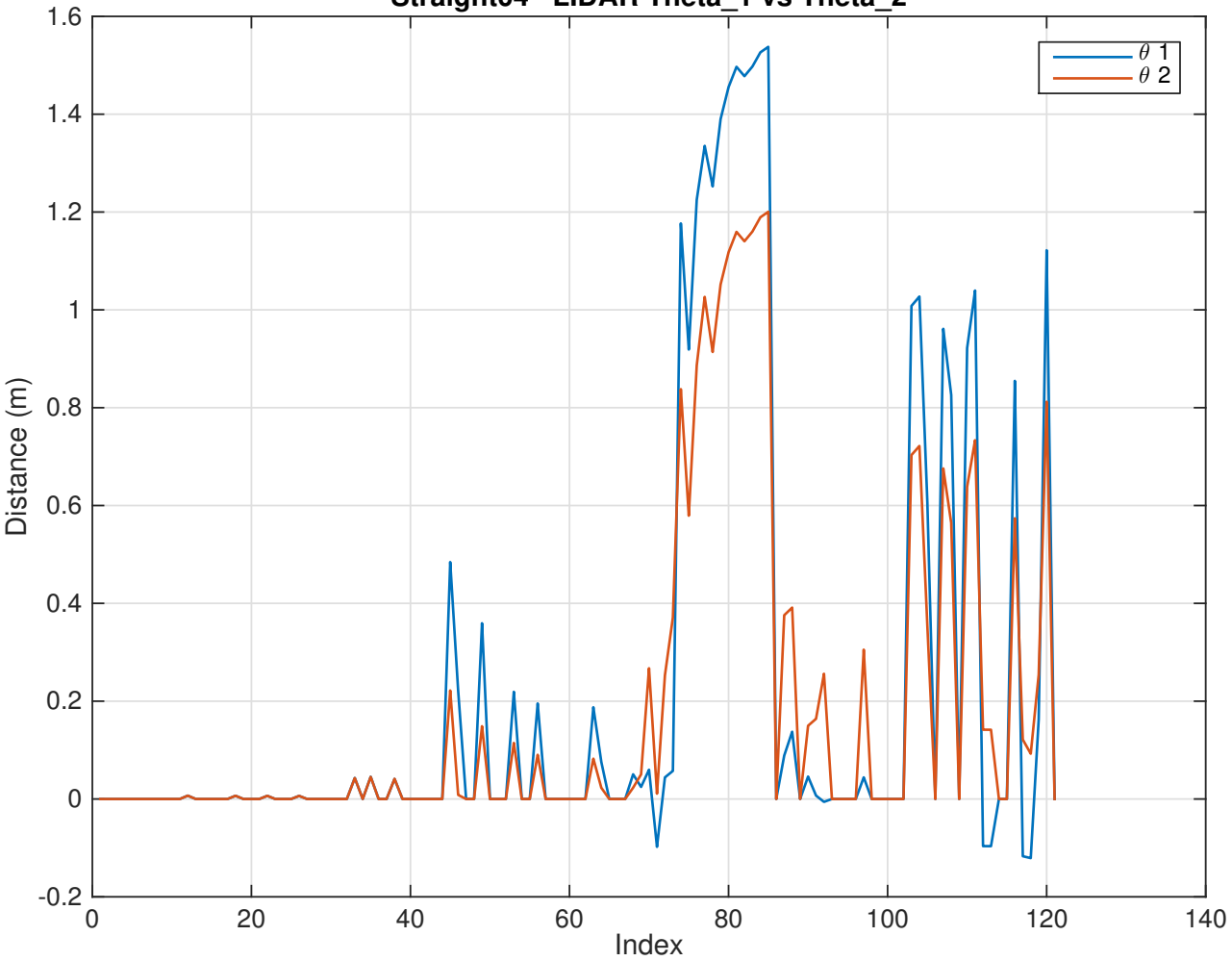
Straight04 Camera L1 vs L2



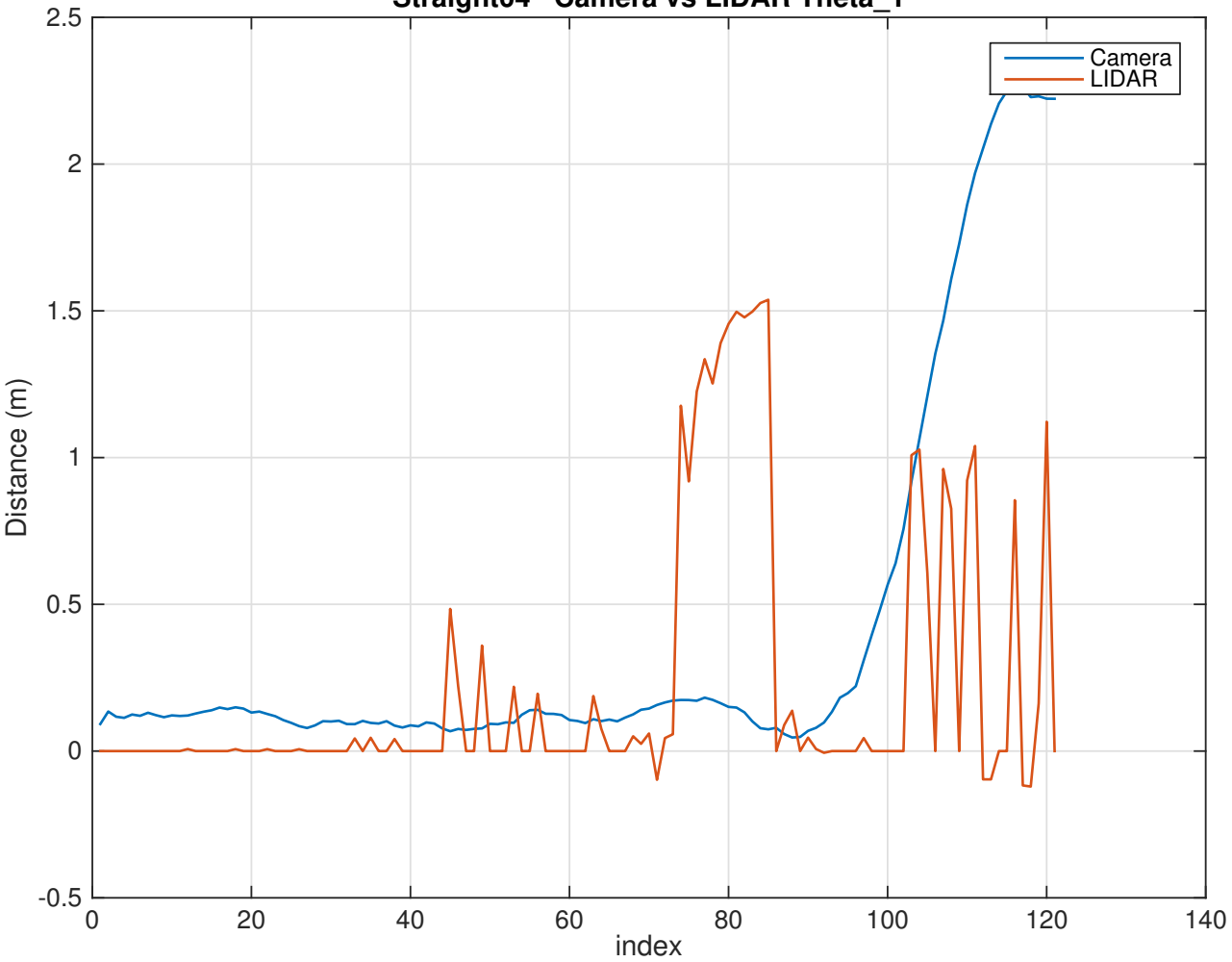
Straight04 Camera Theta_1 vs Theta_2



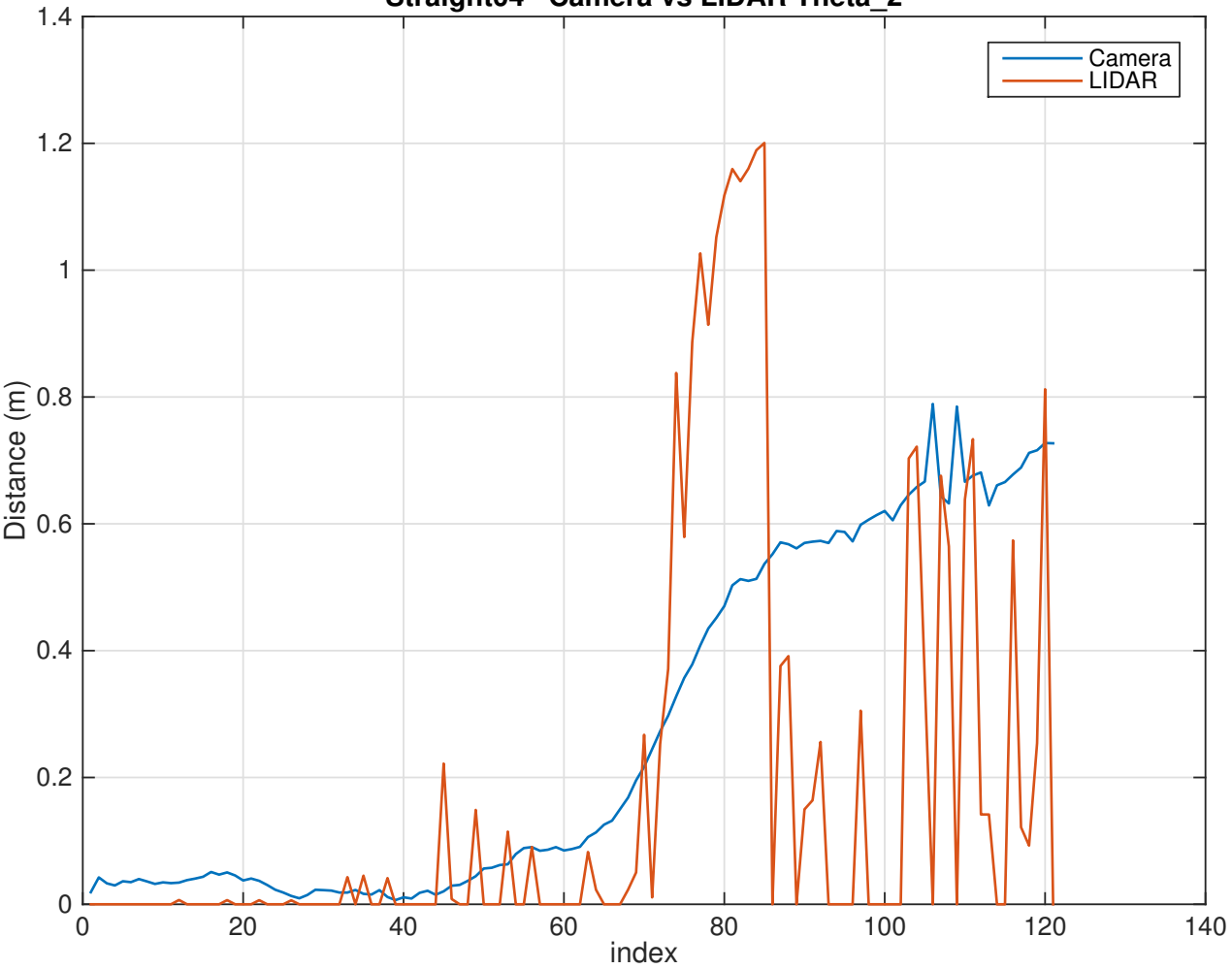
Straight04 LIDAR Theta_1 vs Theta_2



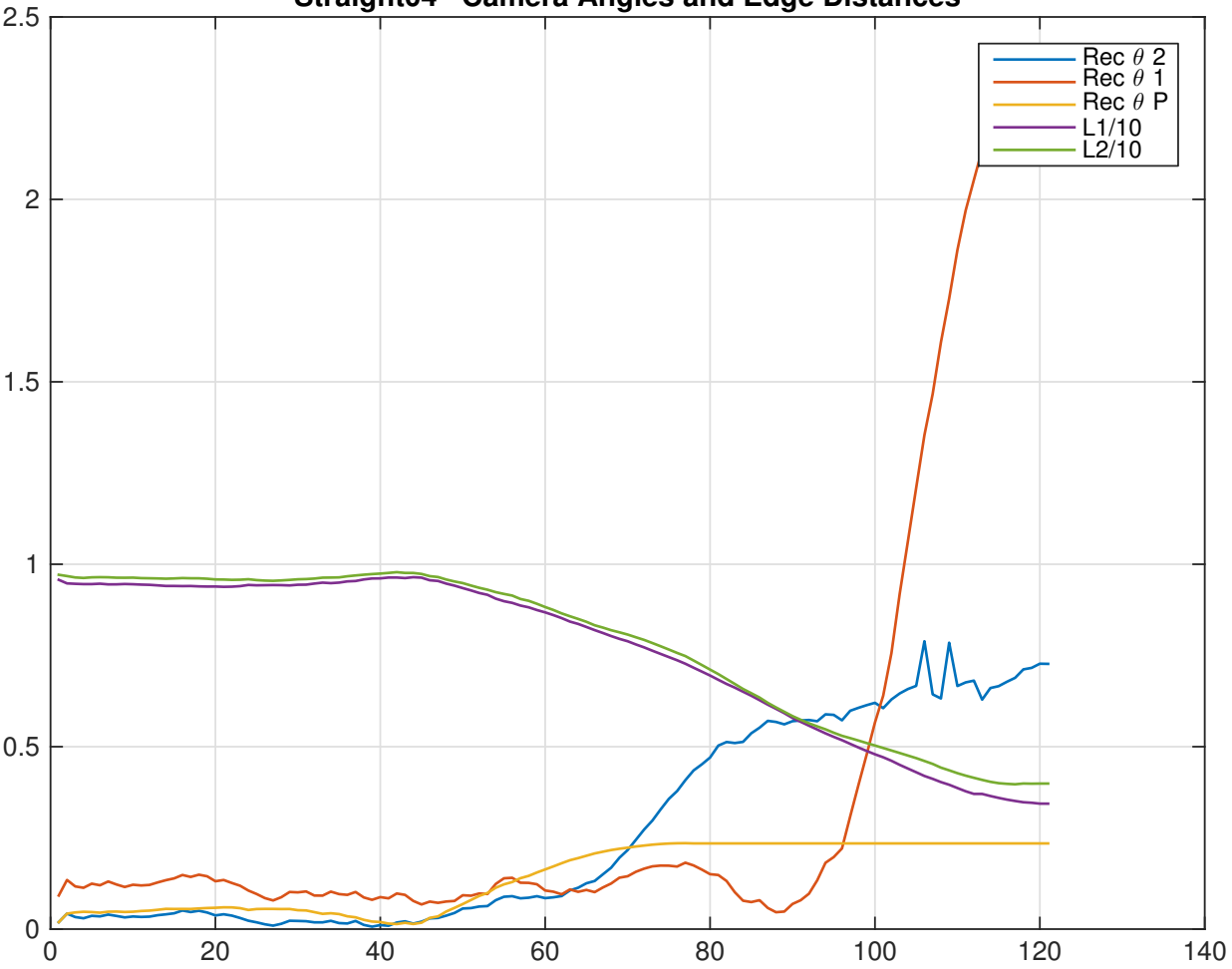
Straight04 Camera vs LIDAR Theta_1



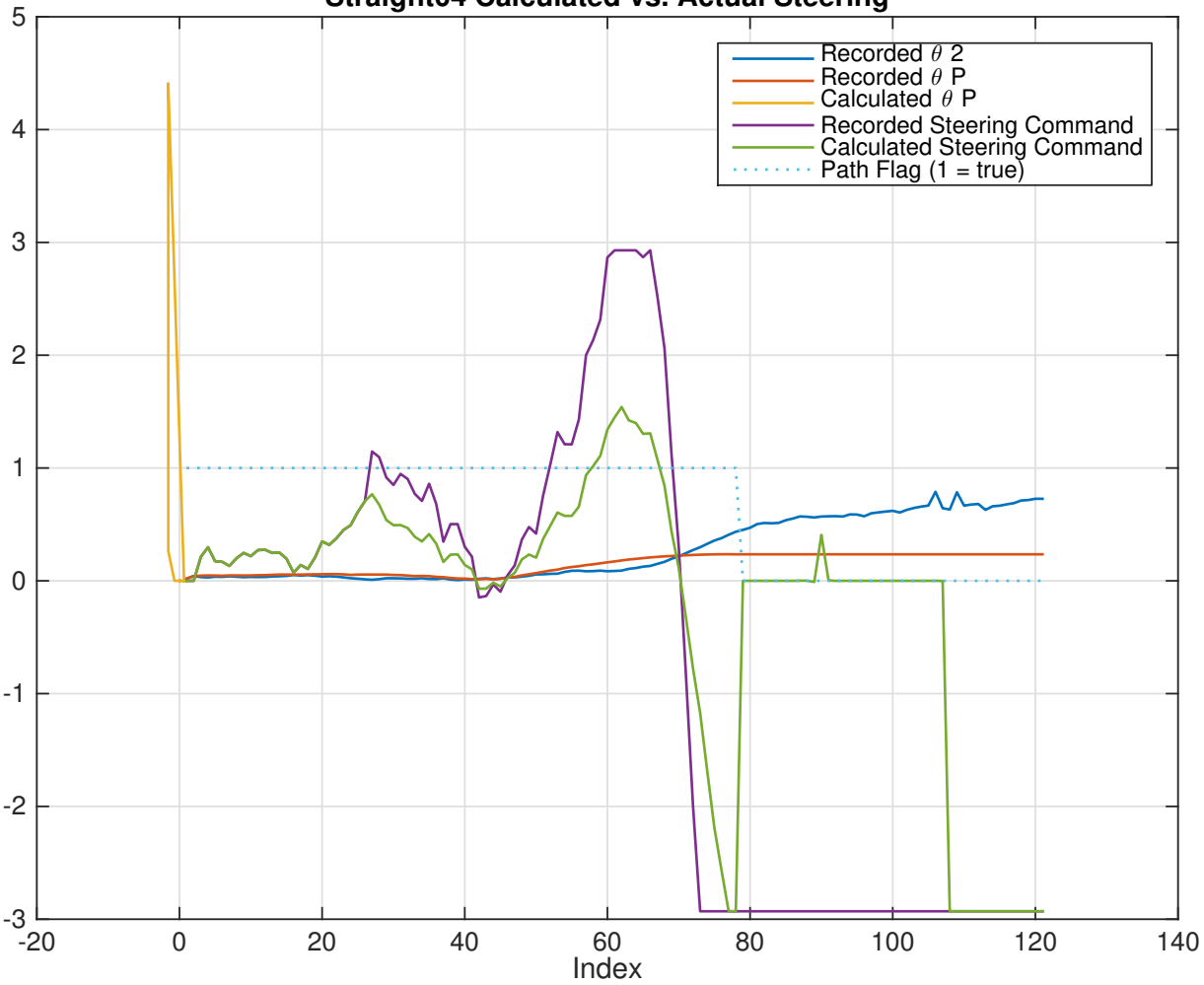
Straight04 Camera vs LIDAR Theta_2



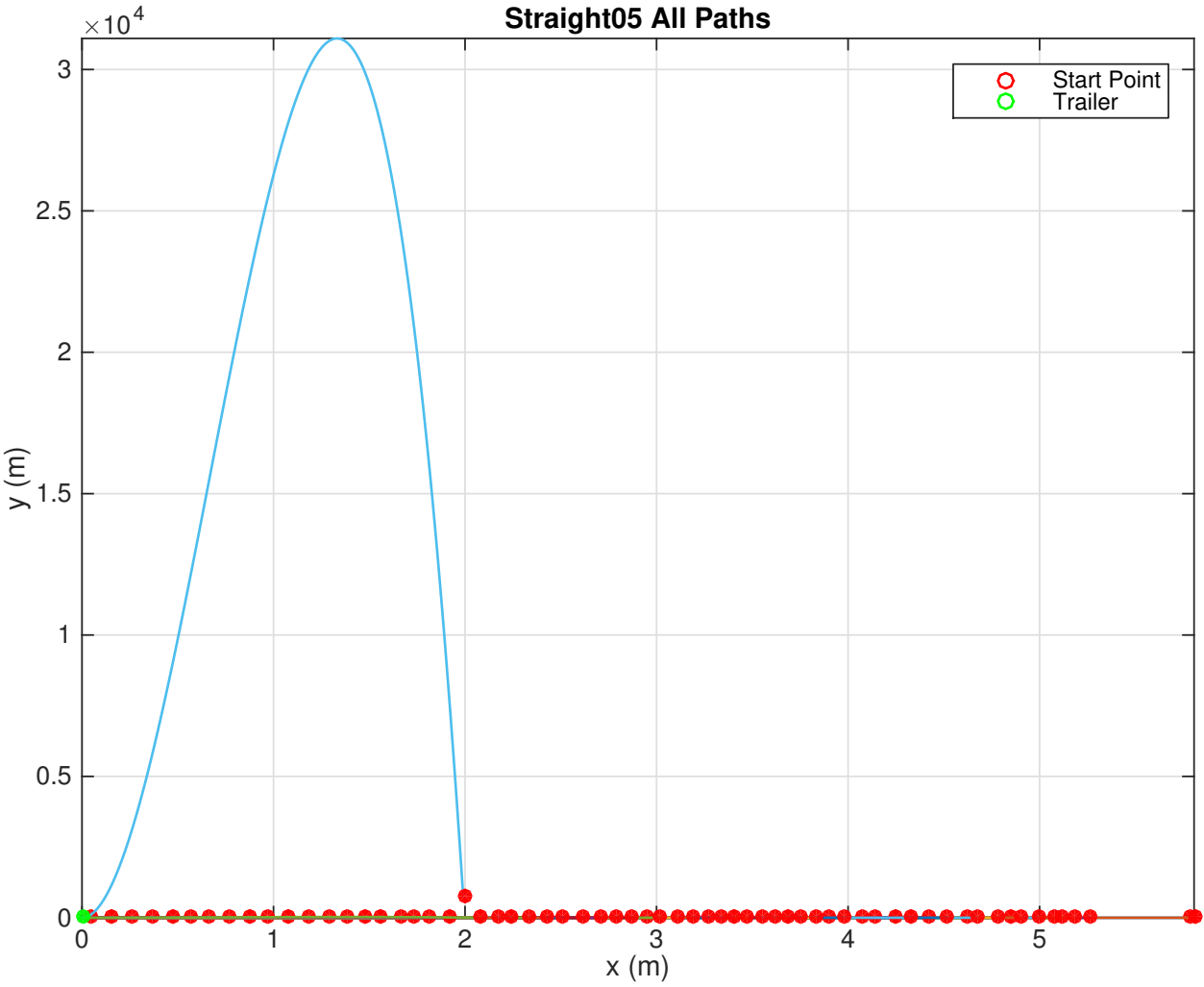
Straight04 Camera Angles and Edge Distances



Straight04 Calculated vs. Actual Steering



Straight05 All Paths



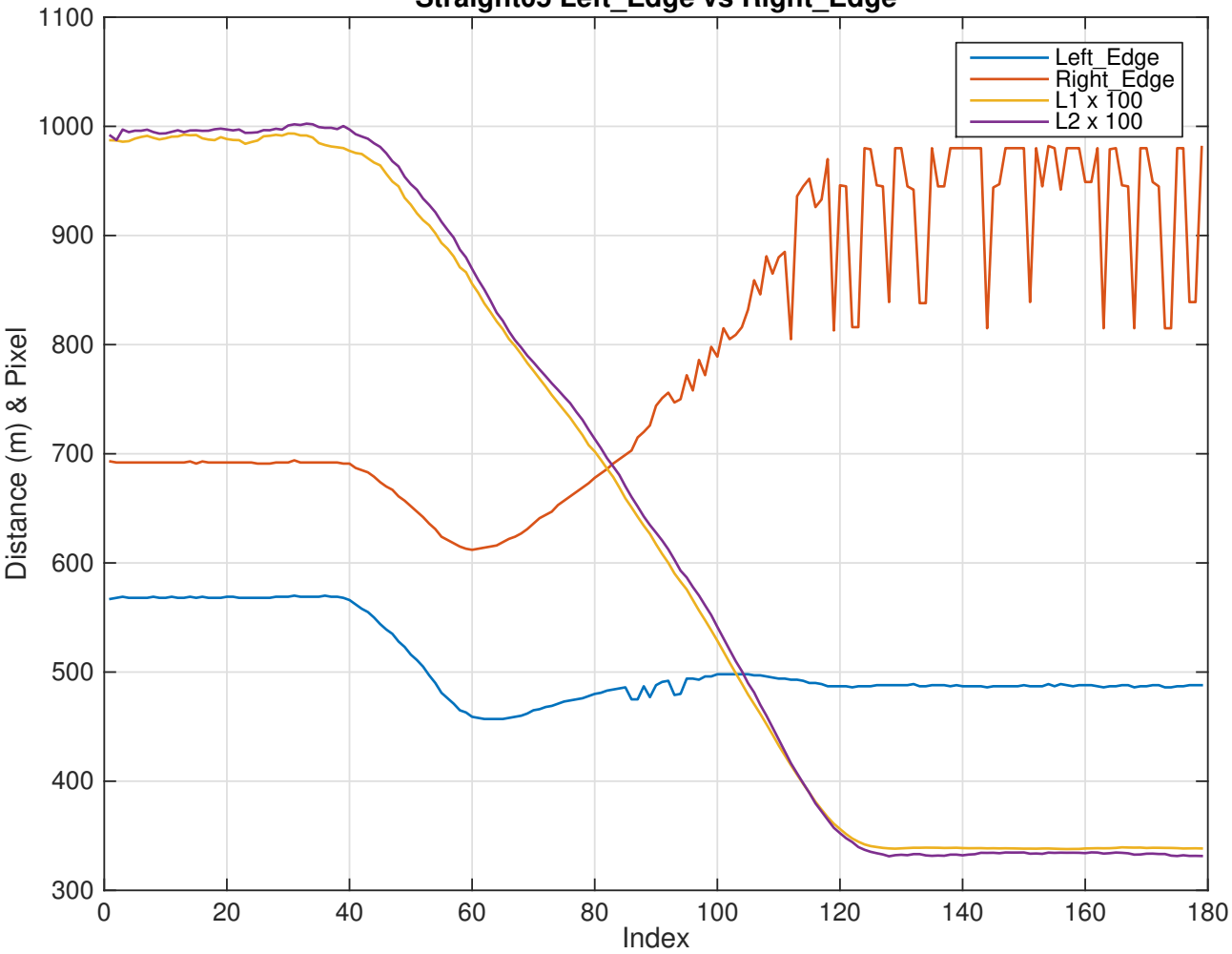
Number_Of_Unique_Paths

King_Pin_Detected

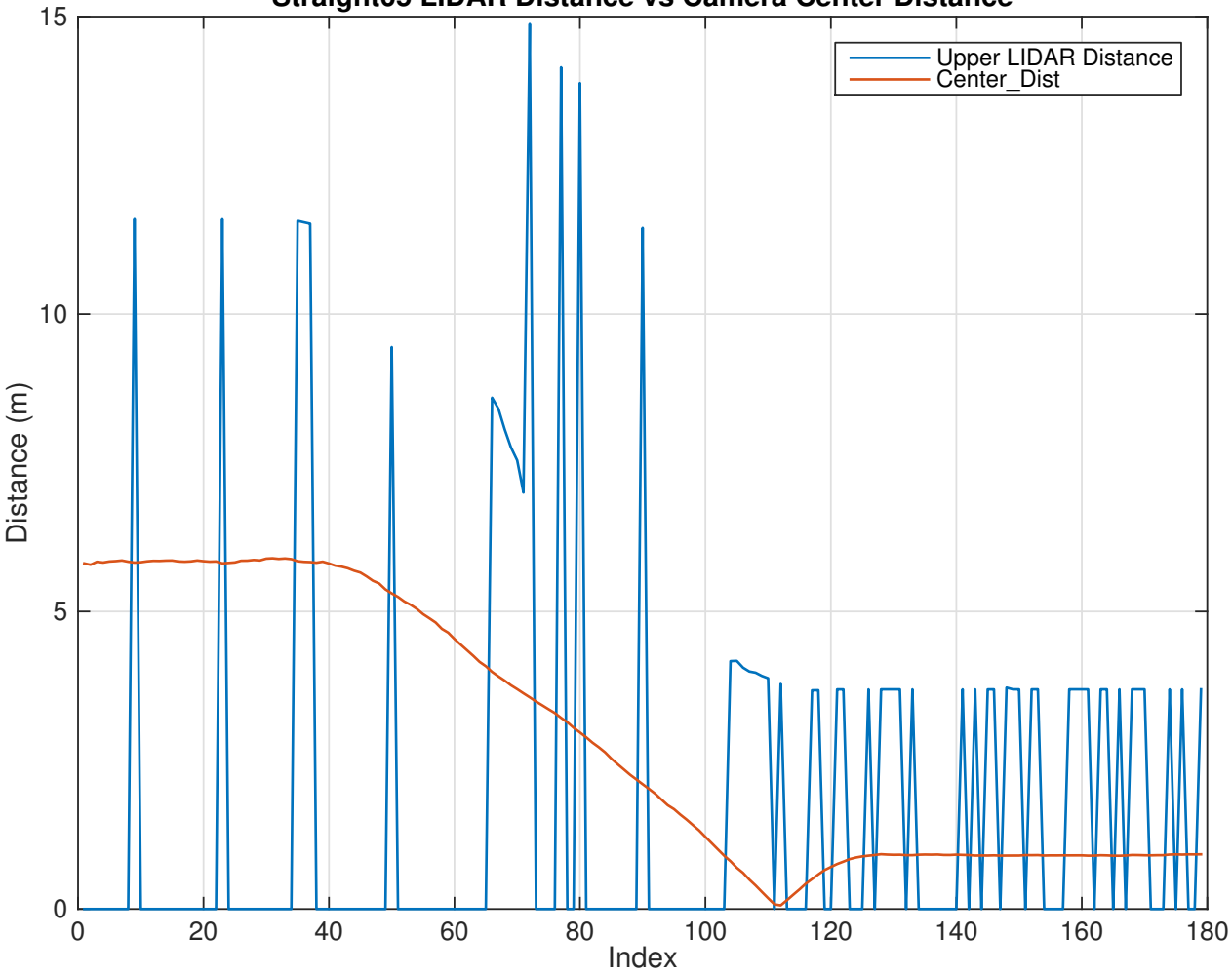
44

false

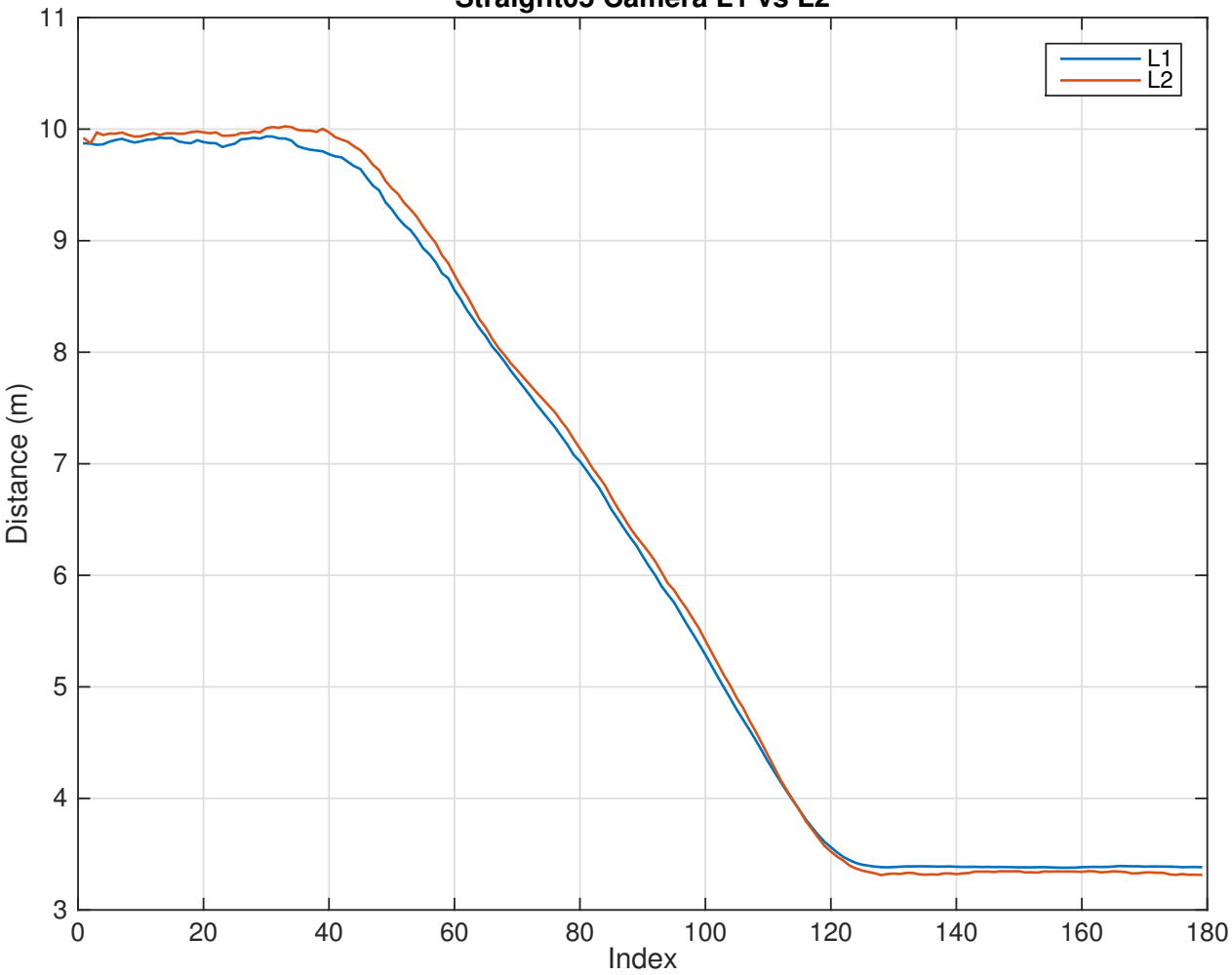
Straight05 Left_Edge vs Right_Edge



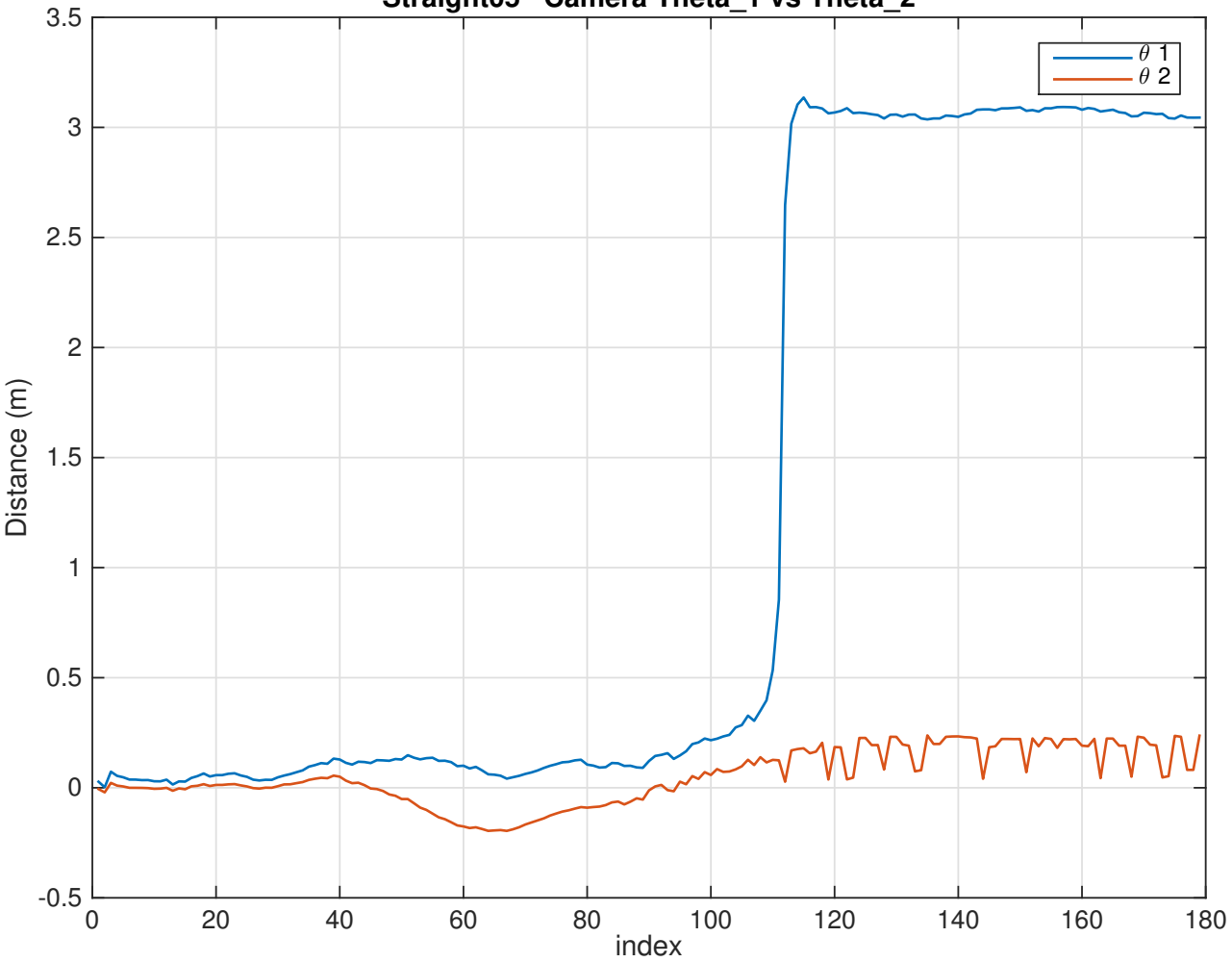
Straight05 LIDAR Distance vs Camera Center Distance



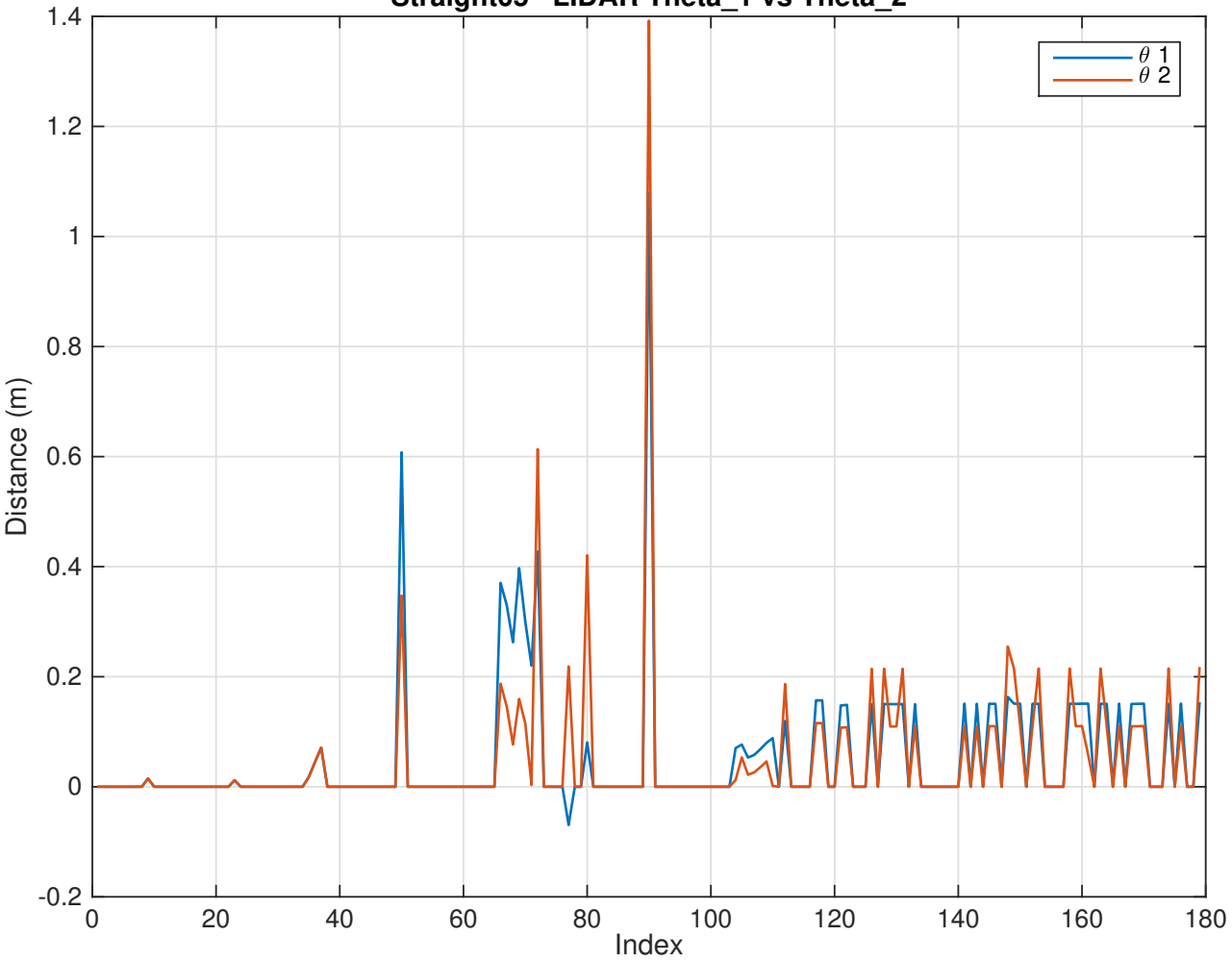
Straight05 Camera L1 vs L2



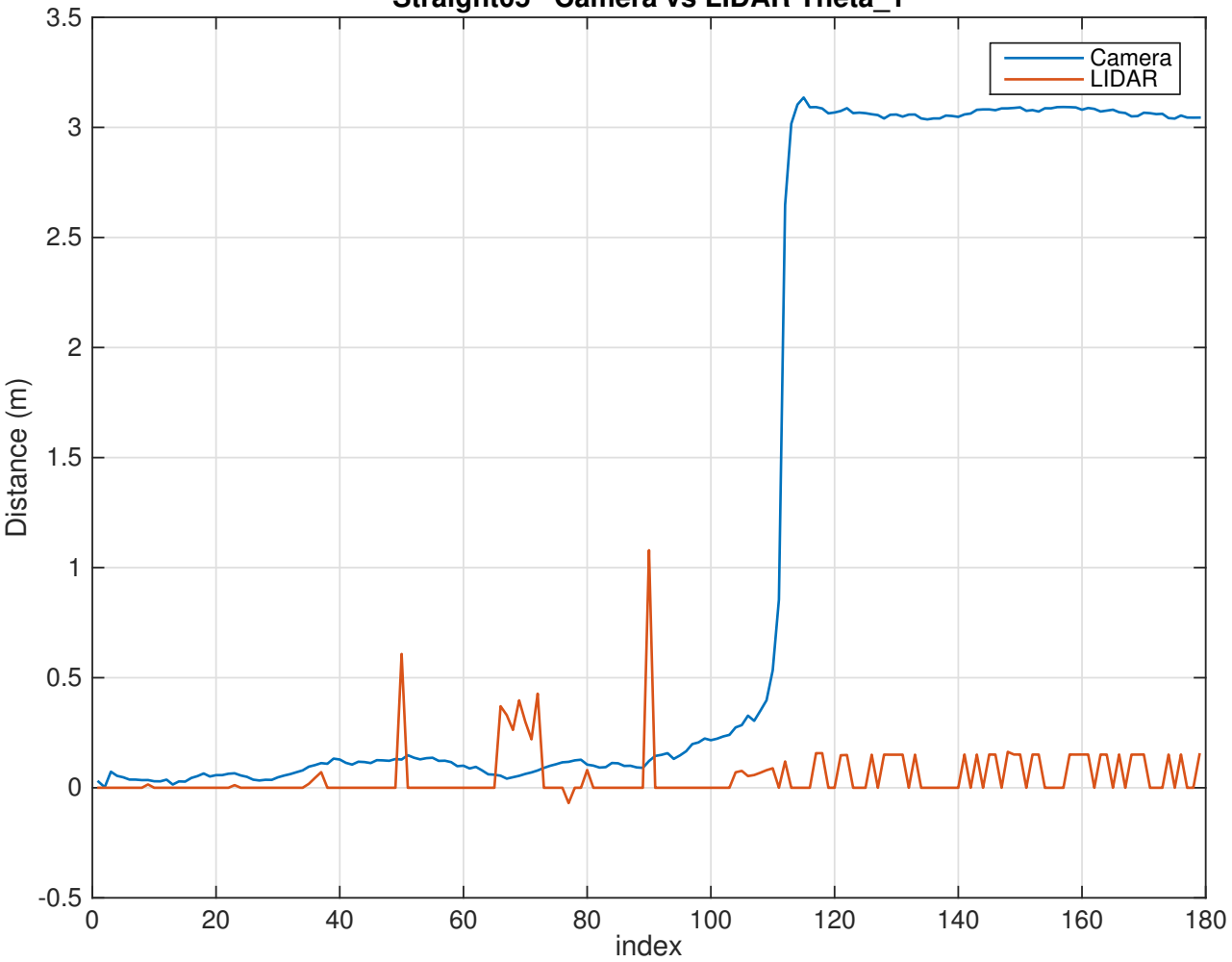
Straight05 Camera Theta_1 vs Theta_2



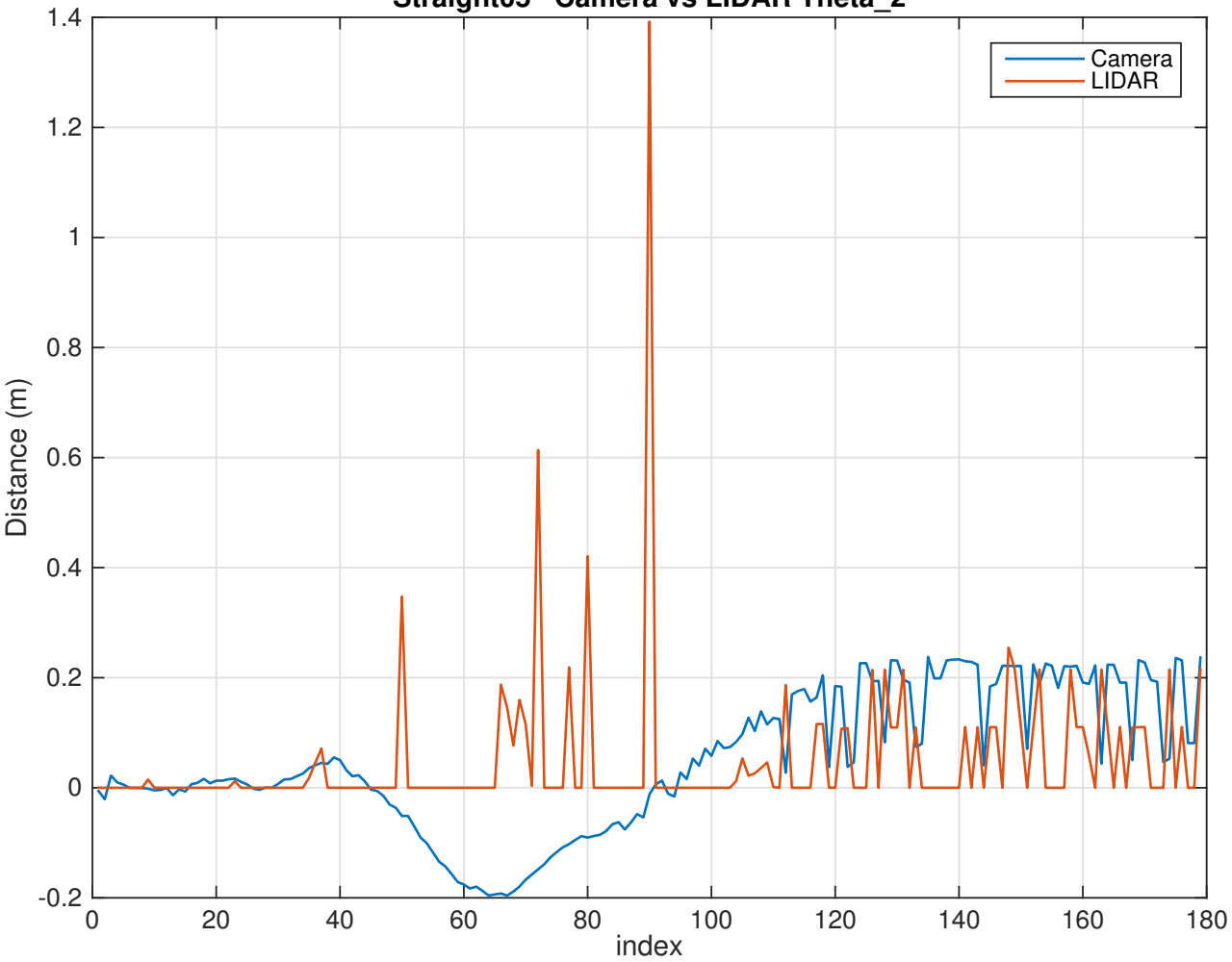
Straight05 LIDAR Theta_1 vs Theta_2



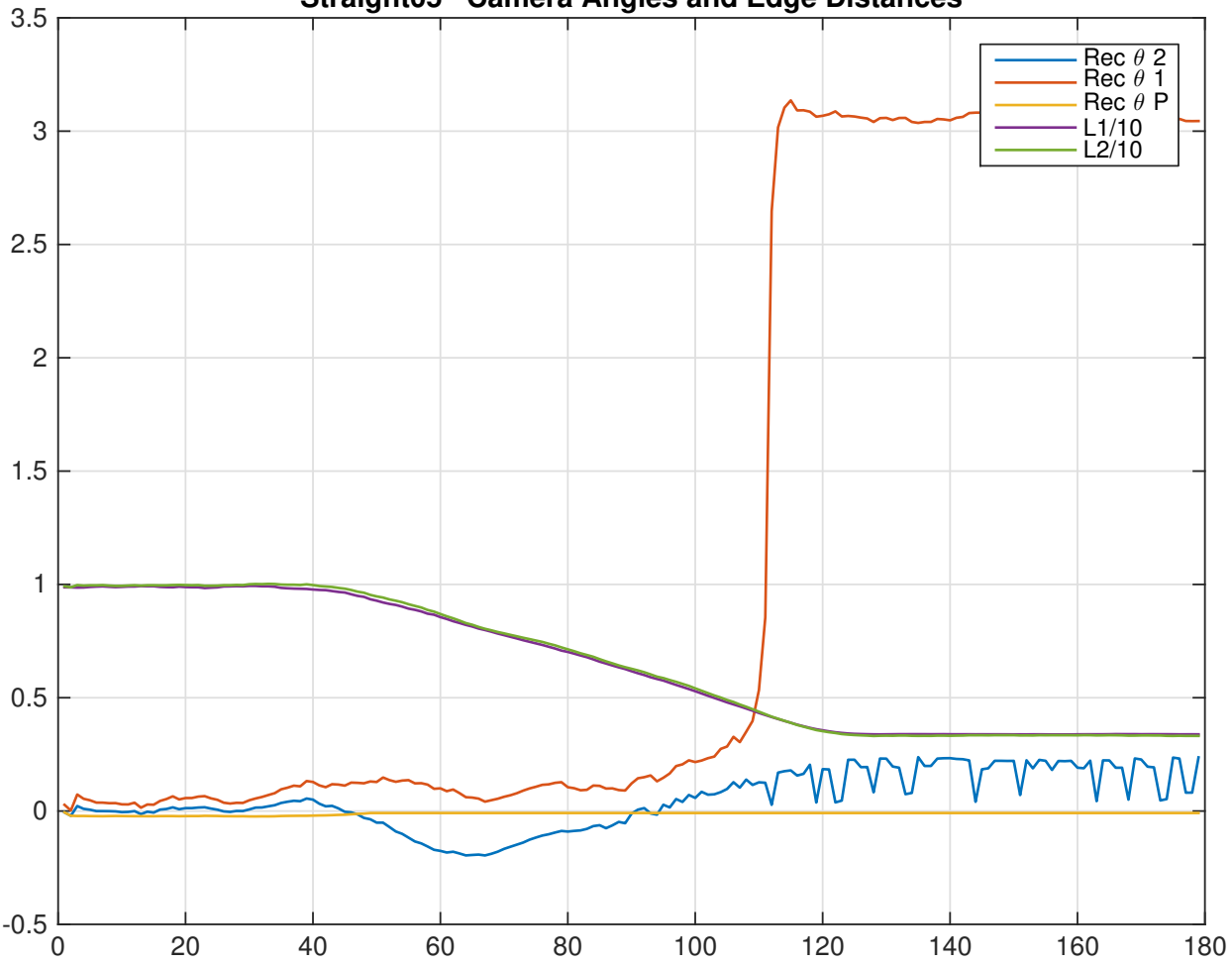
Straight05 Camera vs LIDAR Theta_1



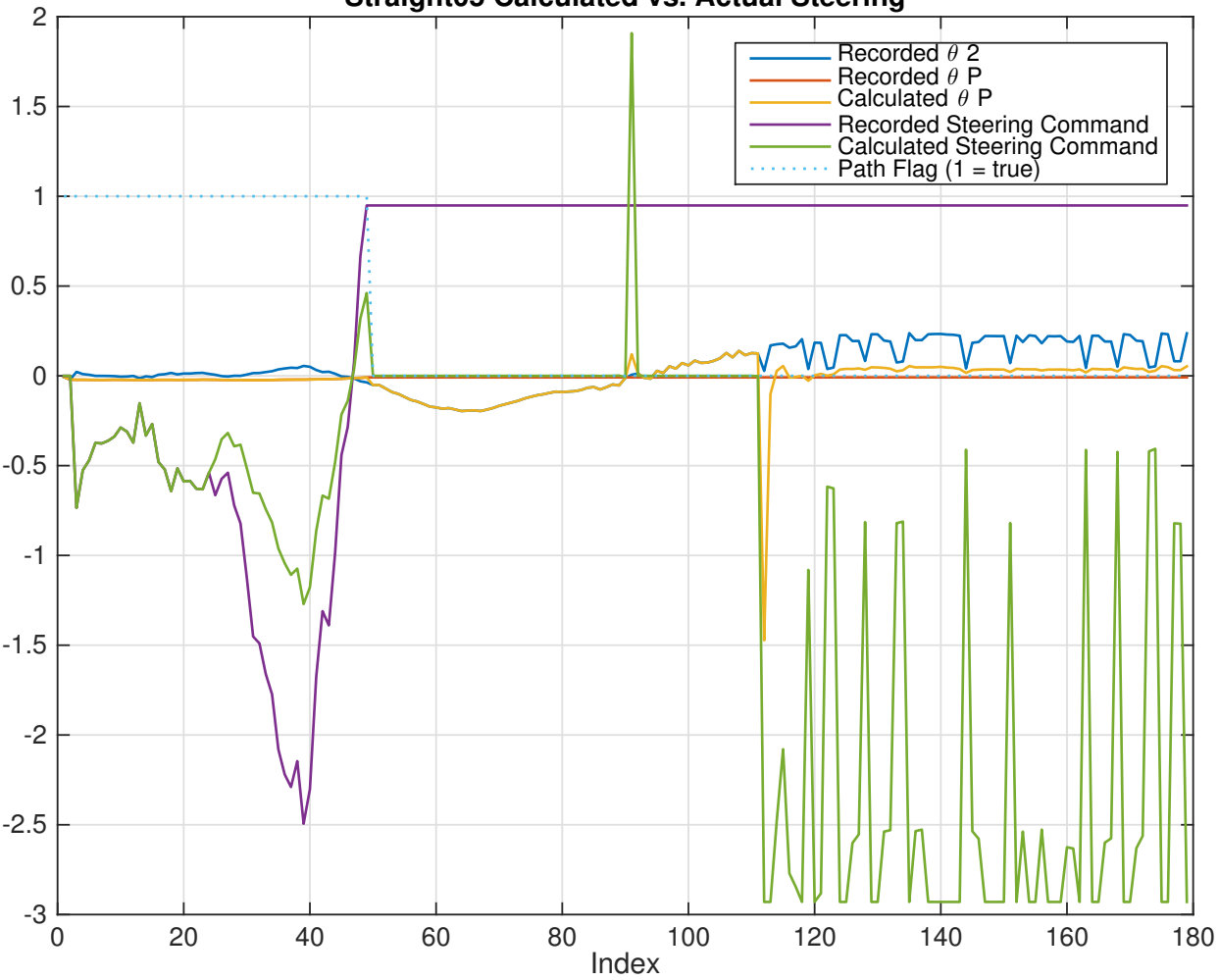
Straight05 Camera vs LIDAR Theta_2



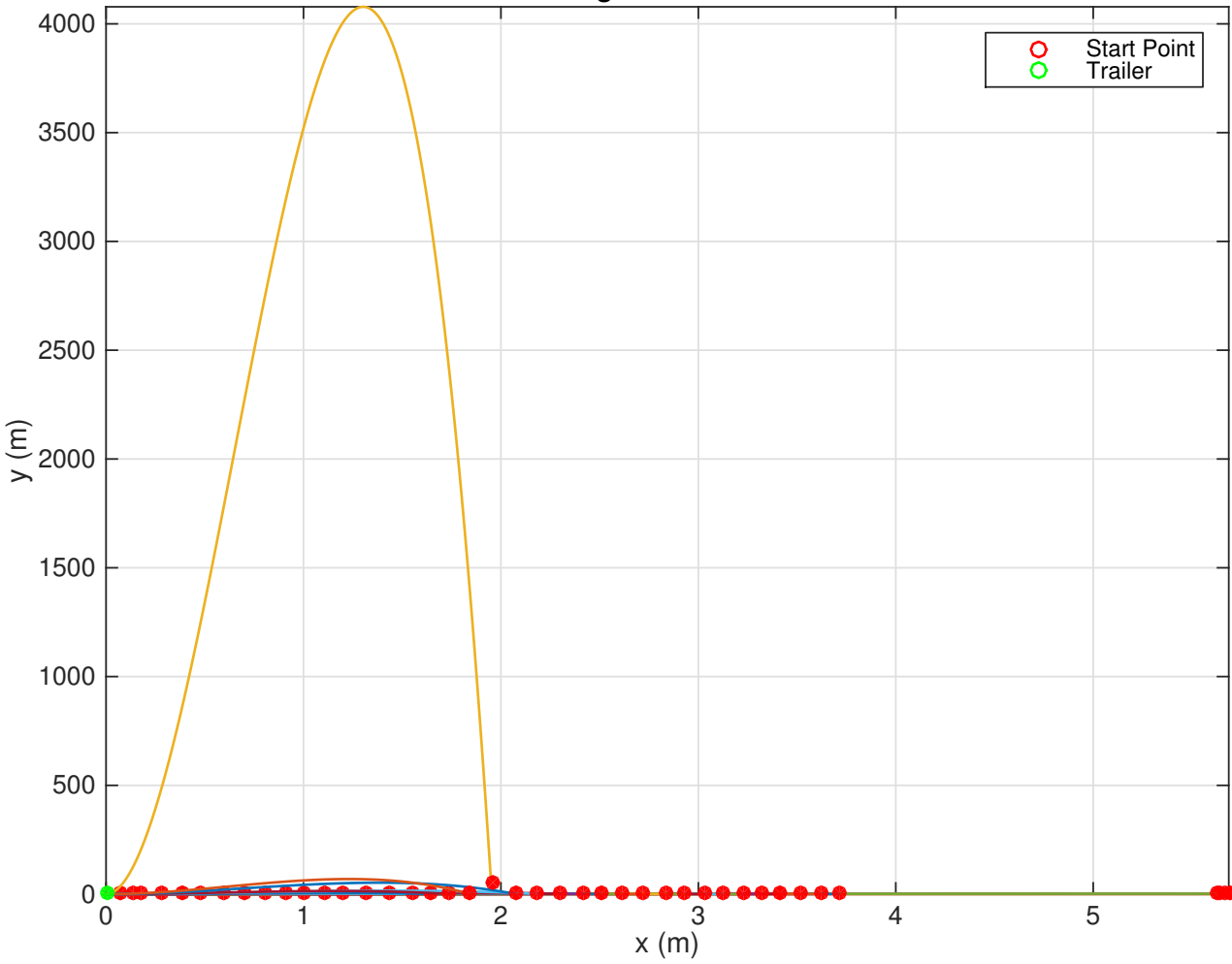
Straight05 Camera Angles and Edge Distances



Straight05 Calculated vs. Actual Steering



Straight06 All Paths



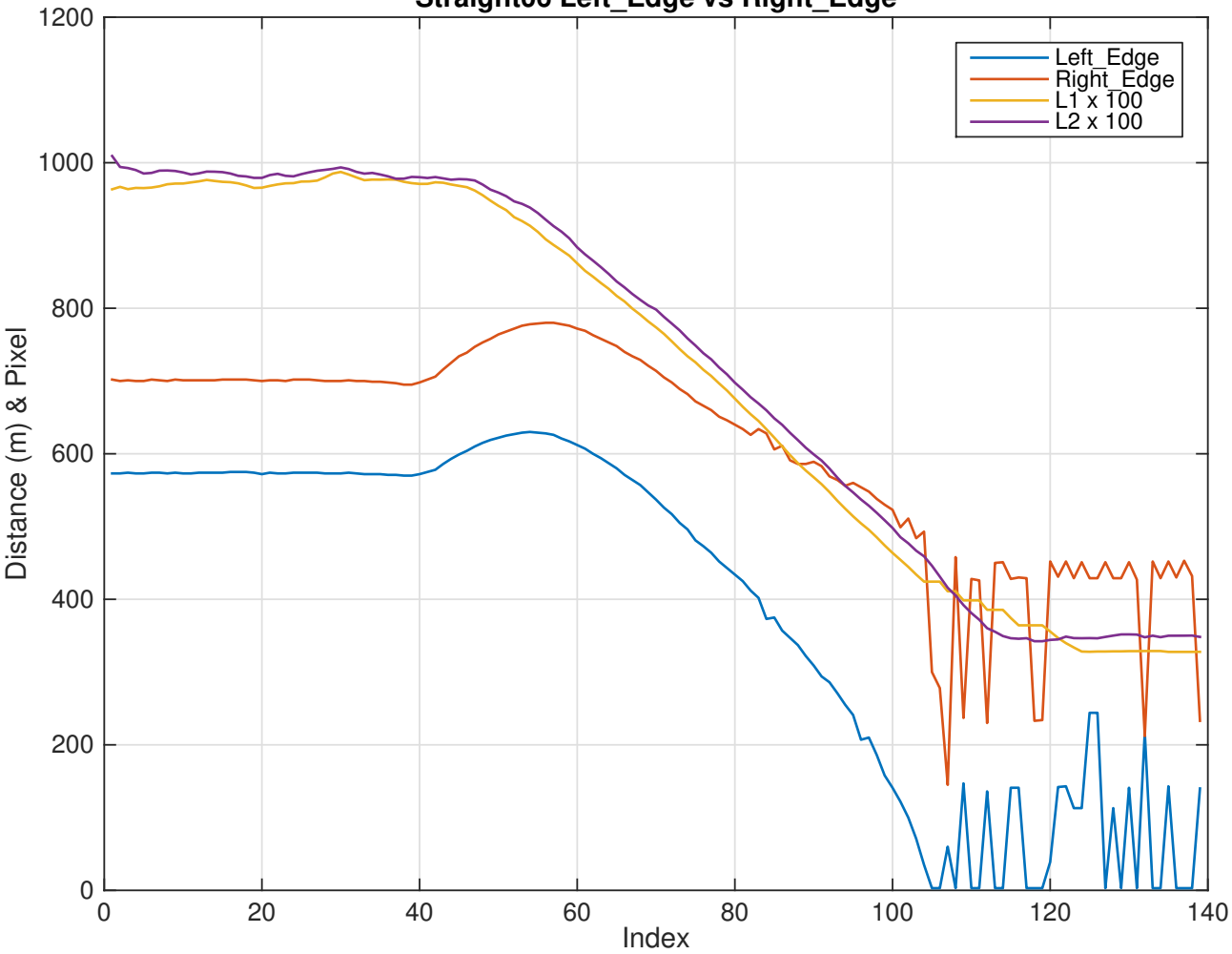
Number_Of_Unique_Paths

King_Pin_Detected

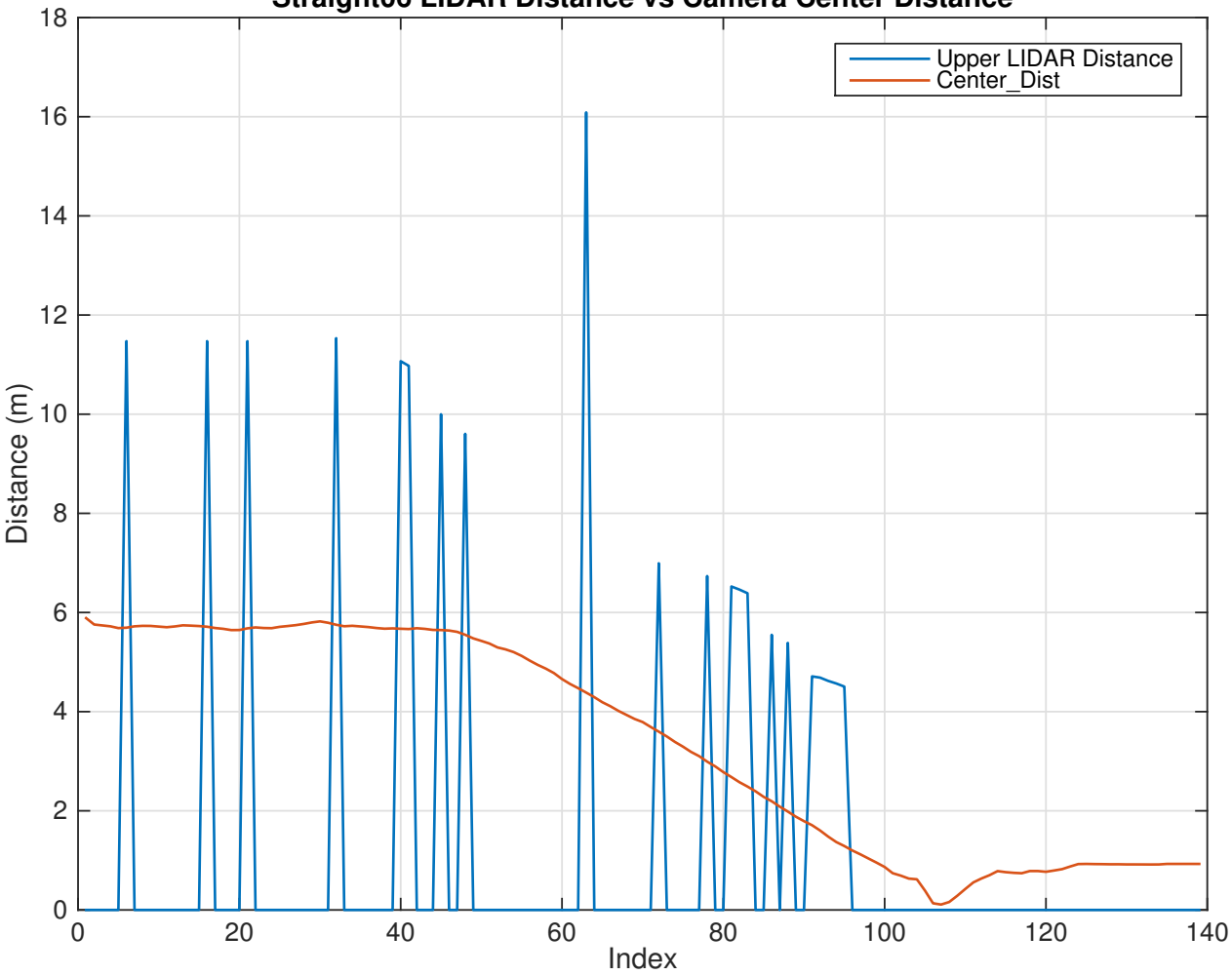
22

false

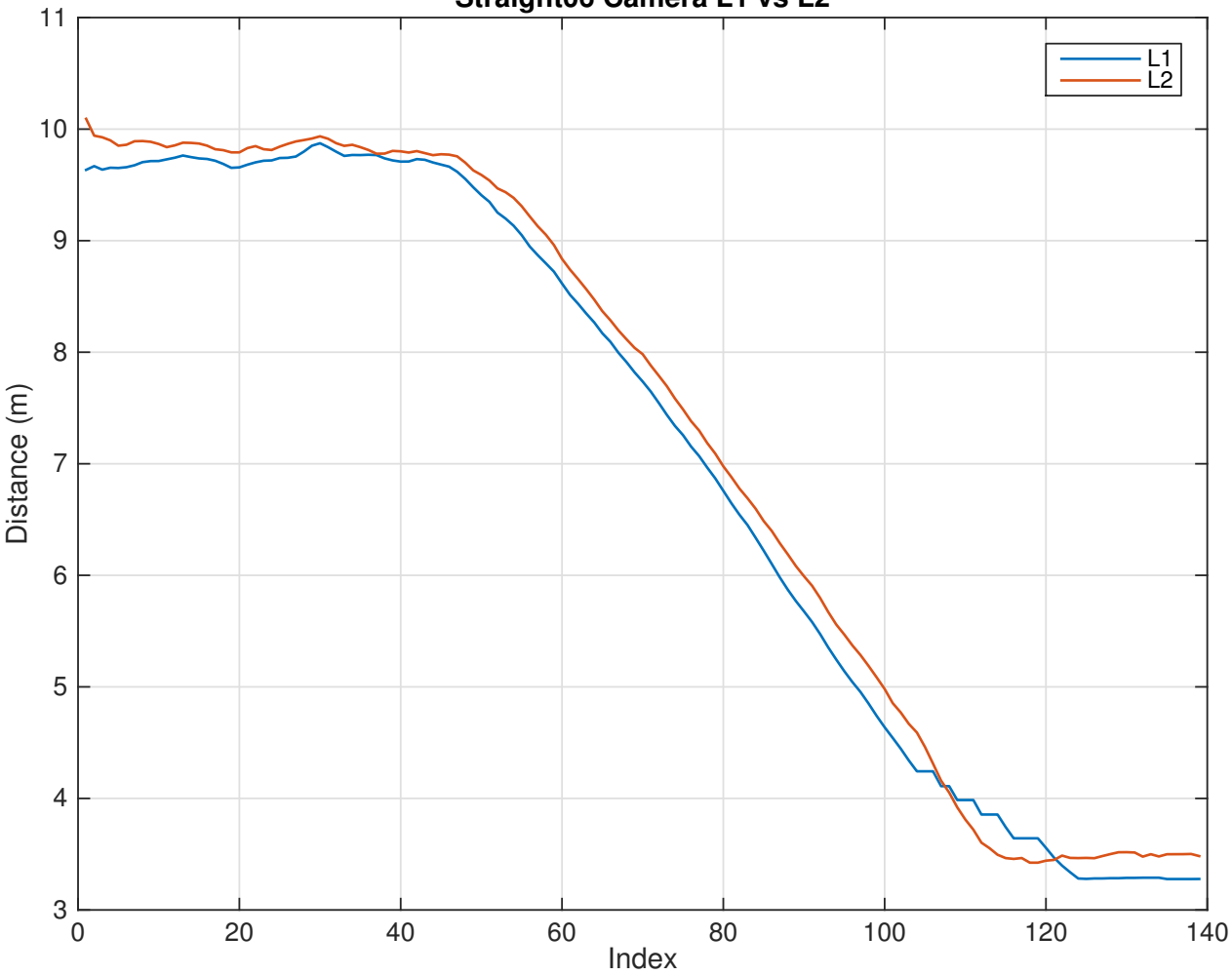
Straight06 Left_Edge vs Right_Edge



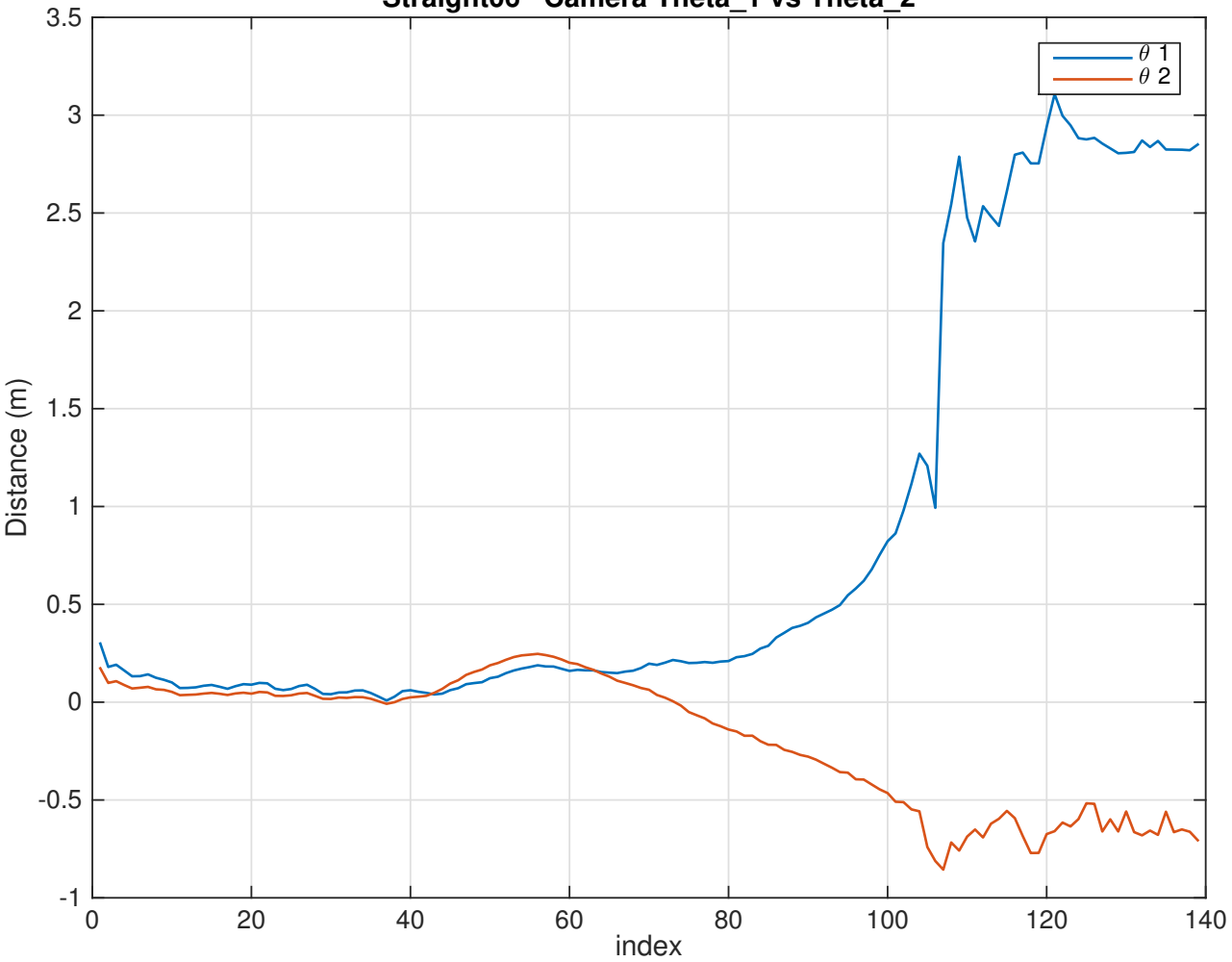
Straight06 LIDAR Distance vs Camera Center Distance



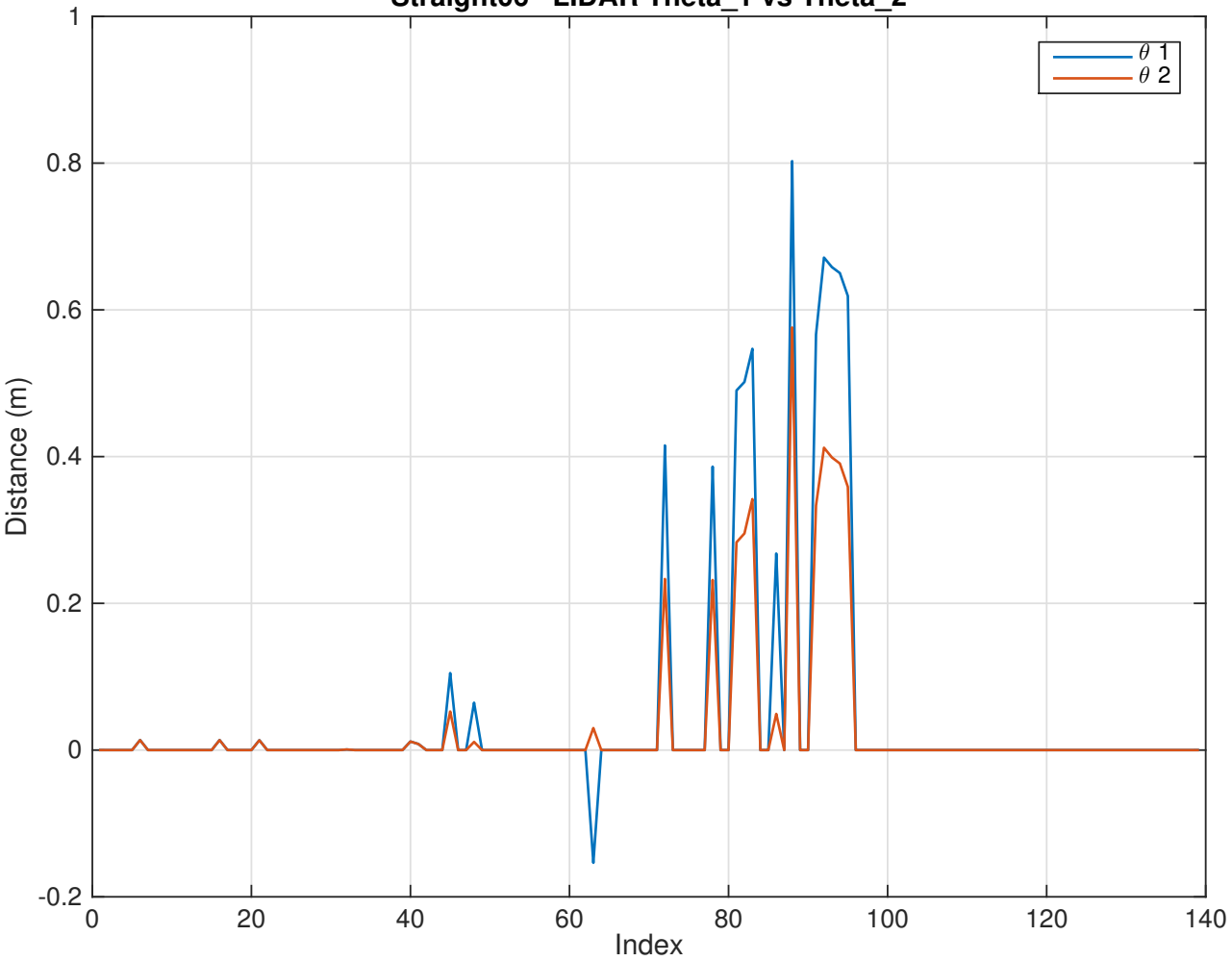
Straight06 Camera L1 vs L2



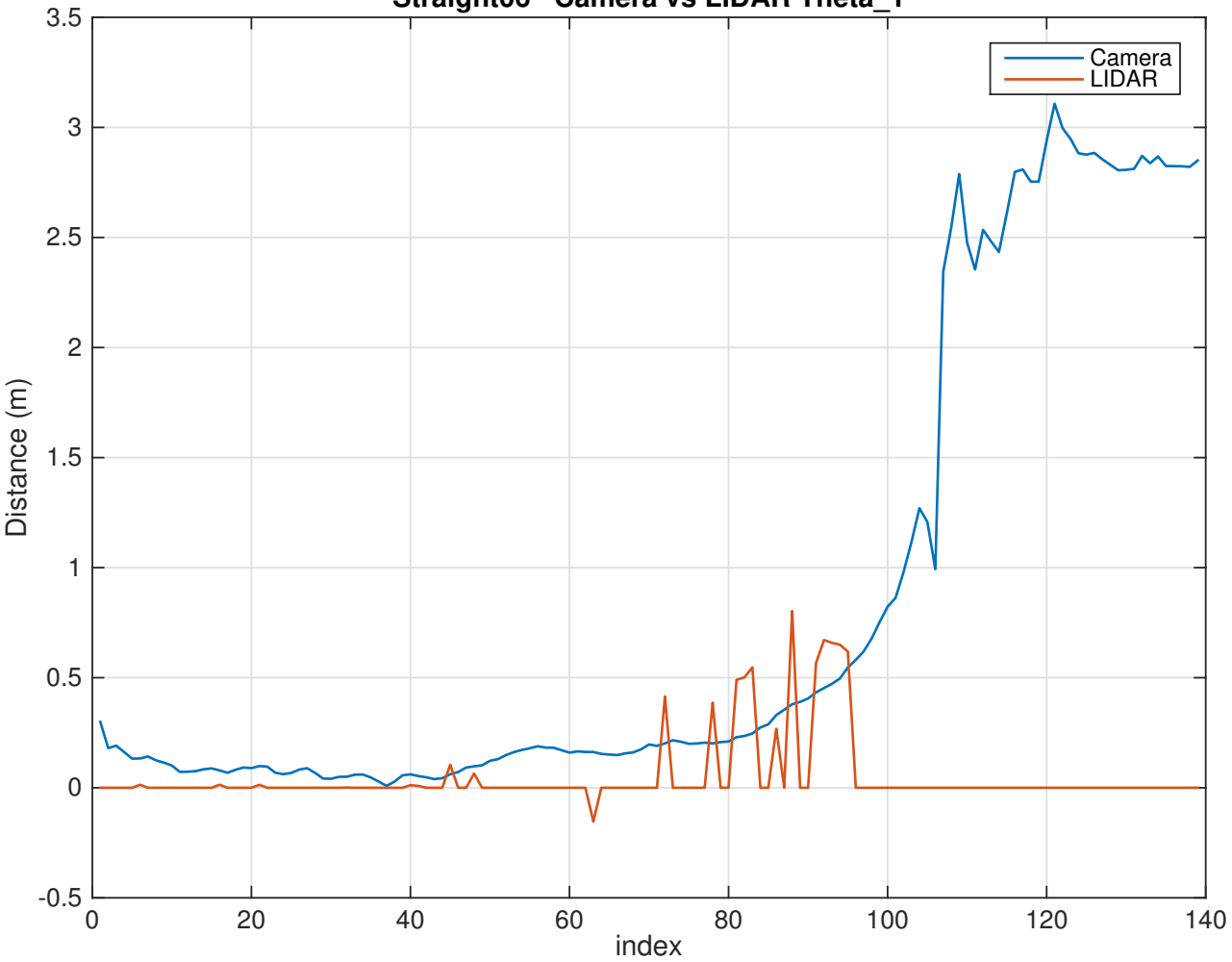
Straight06 Camera Theta_1 vs Theta_2



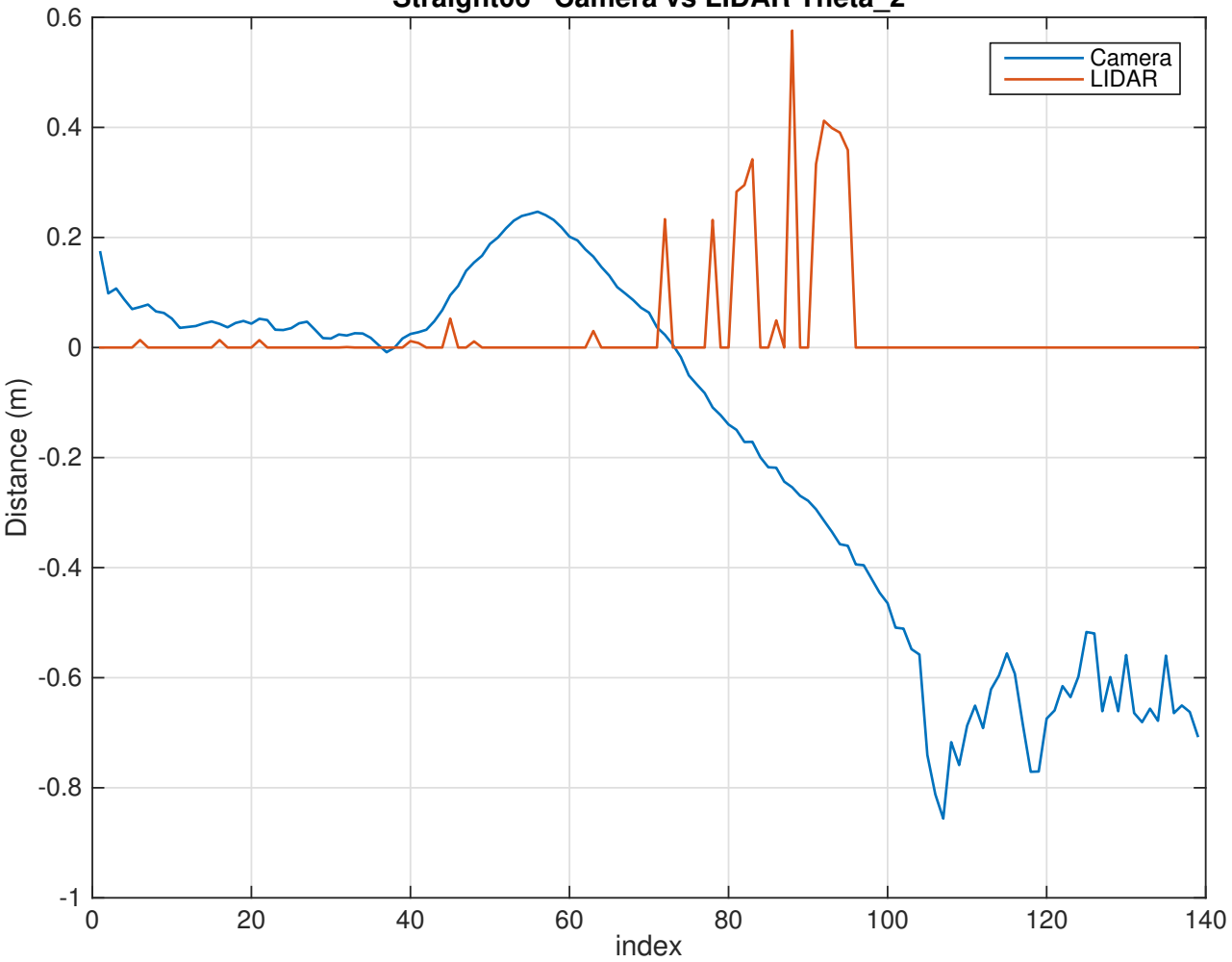
Straight06 LIDAR Theta_1 vs Theta_2



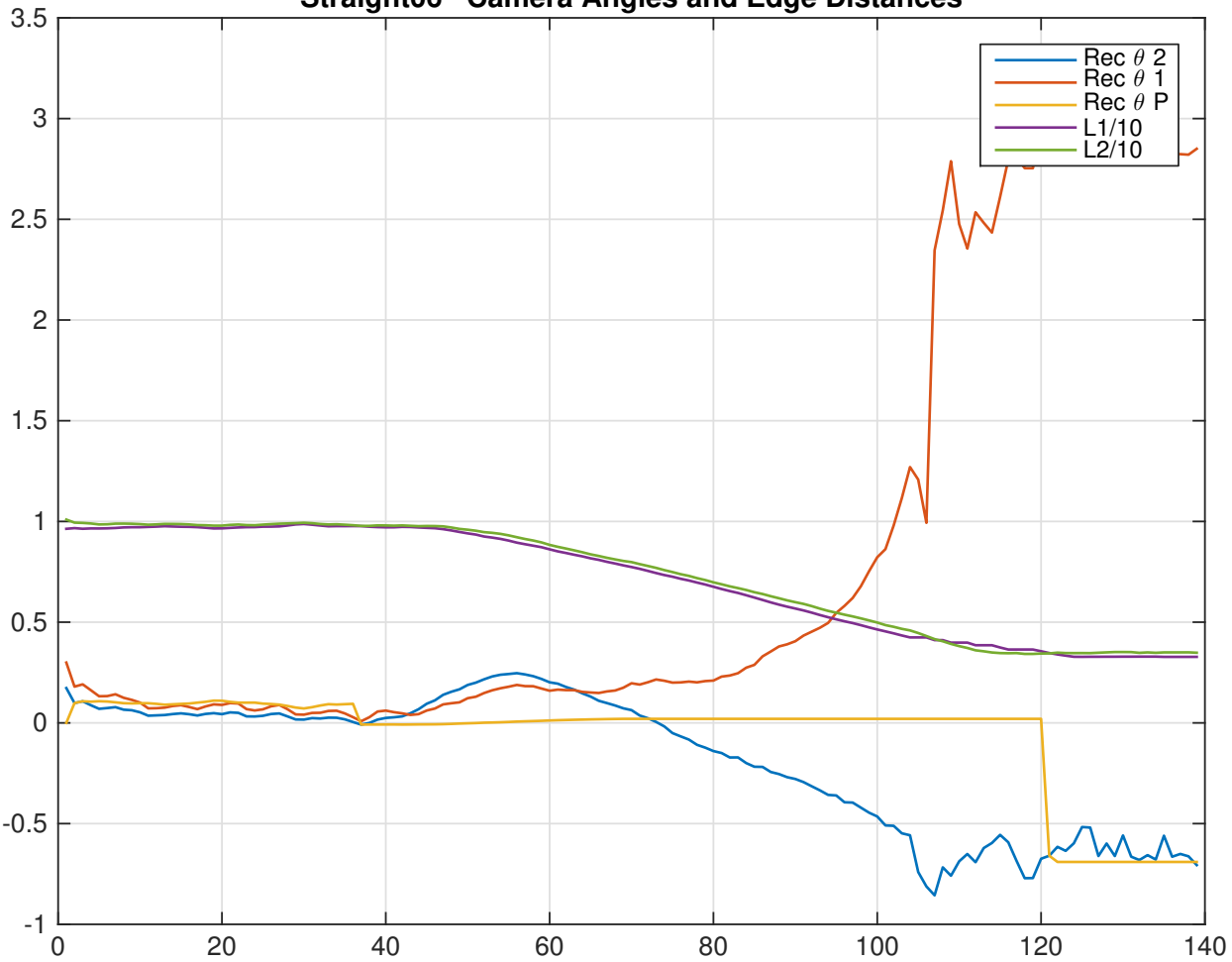
Straight06 Camera vs LIDAR Theta_1



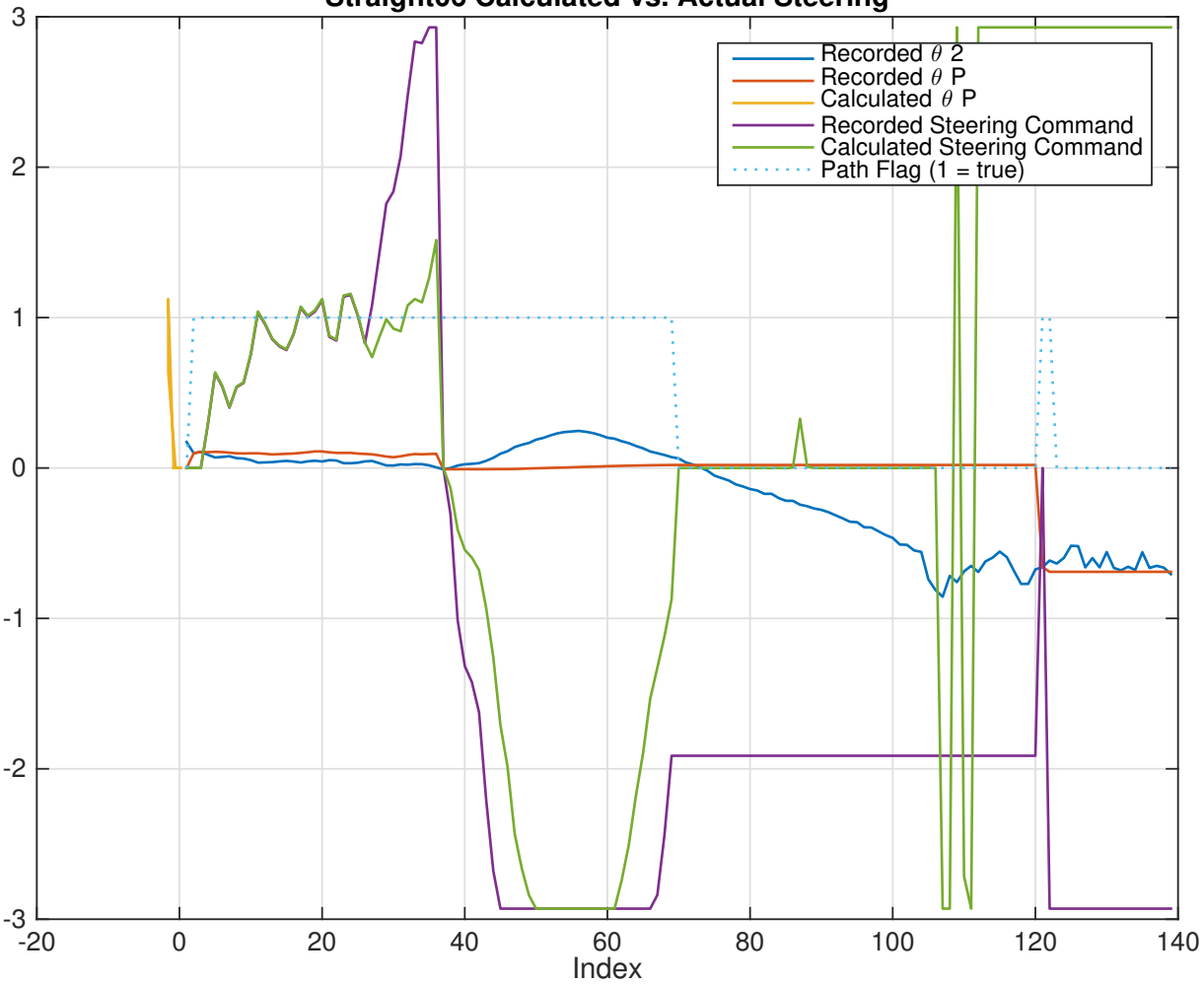
Straight06 Camera vs LIDAR Theta_2



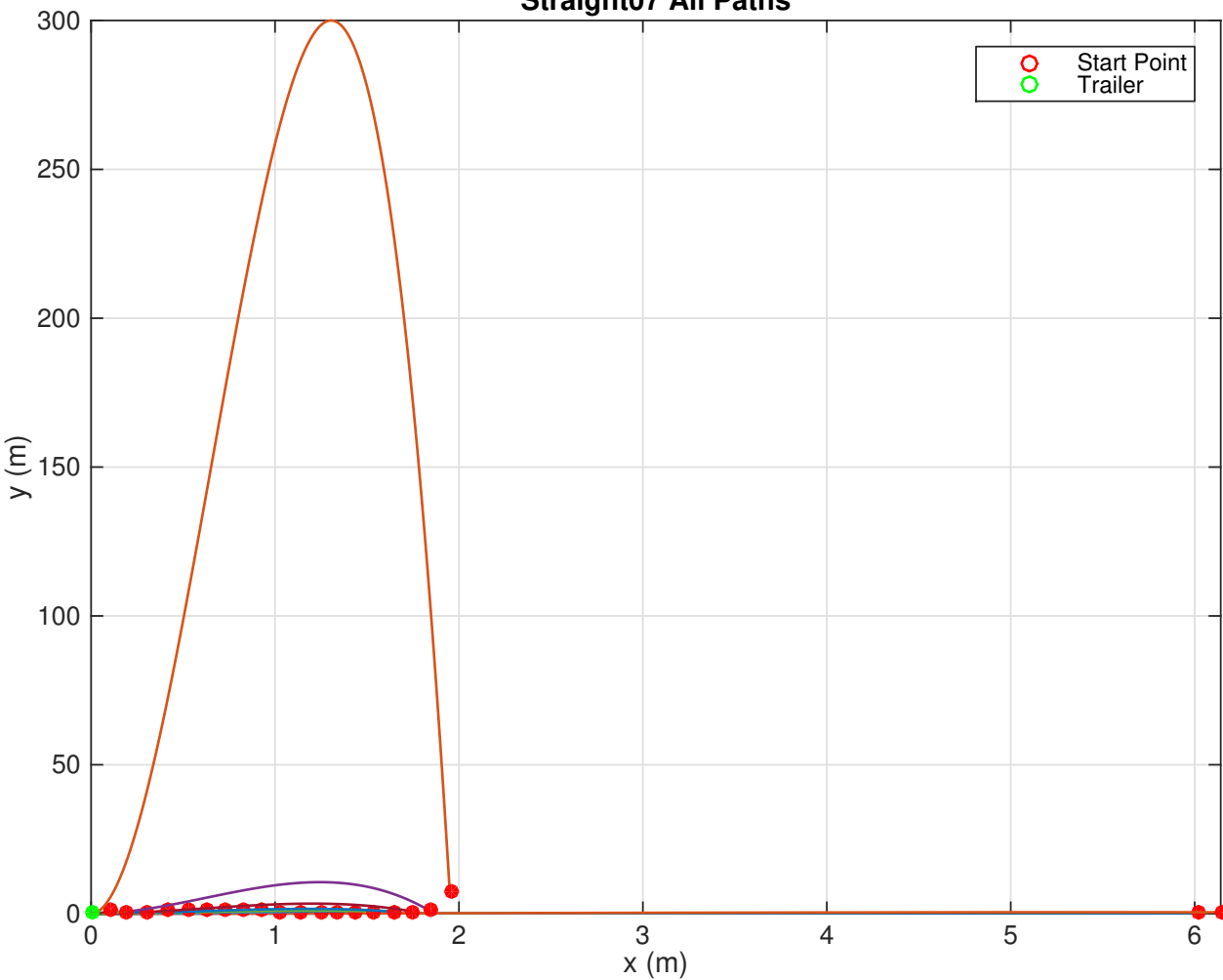
Straight06 Camera Angles and Edge Distances



Straight06 Calculated vs. Actual Steering



Straight07 All Paths



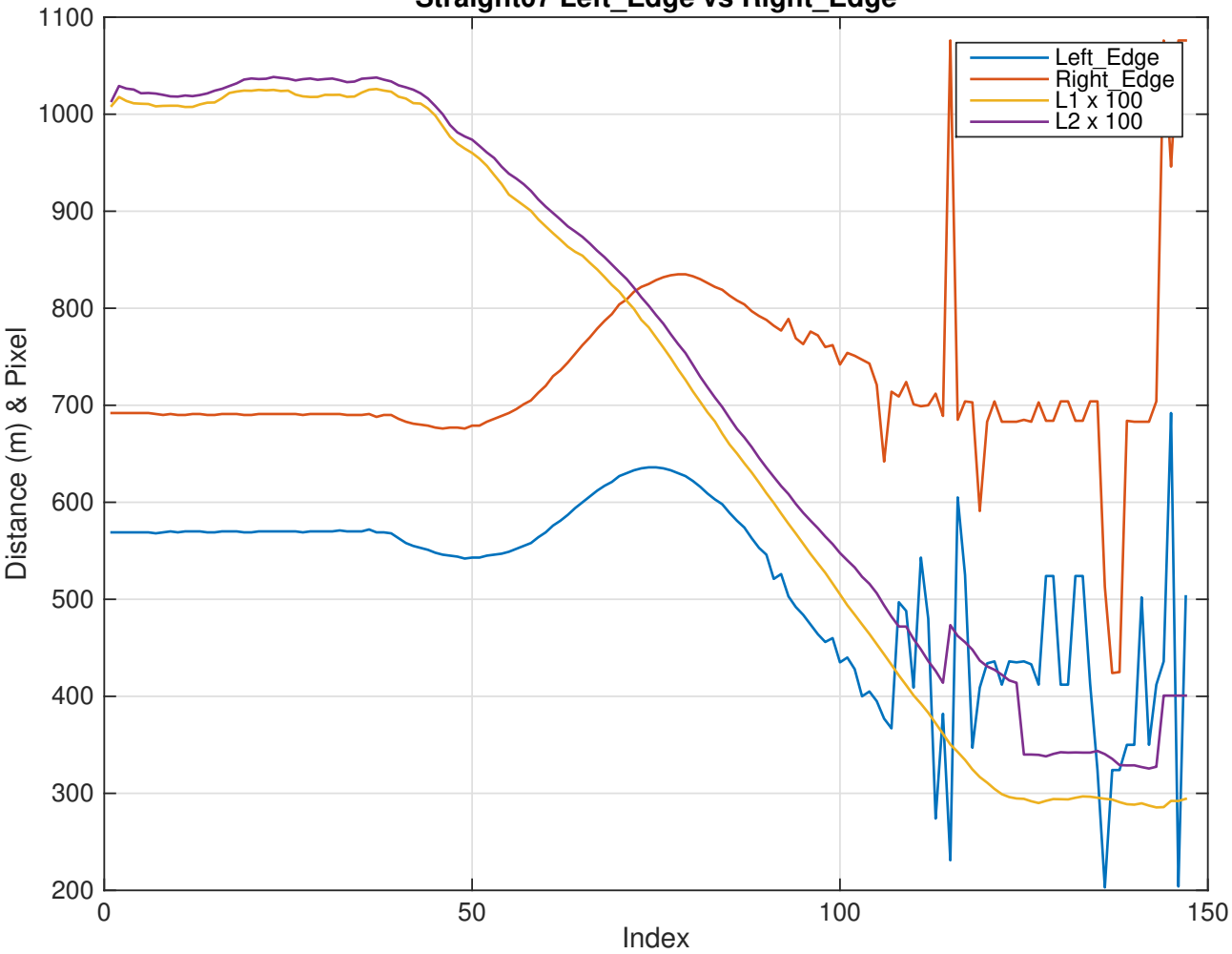
Number_Of_Unique_Paths

King_Pin_Detected

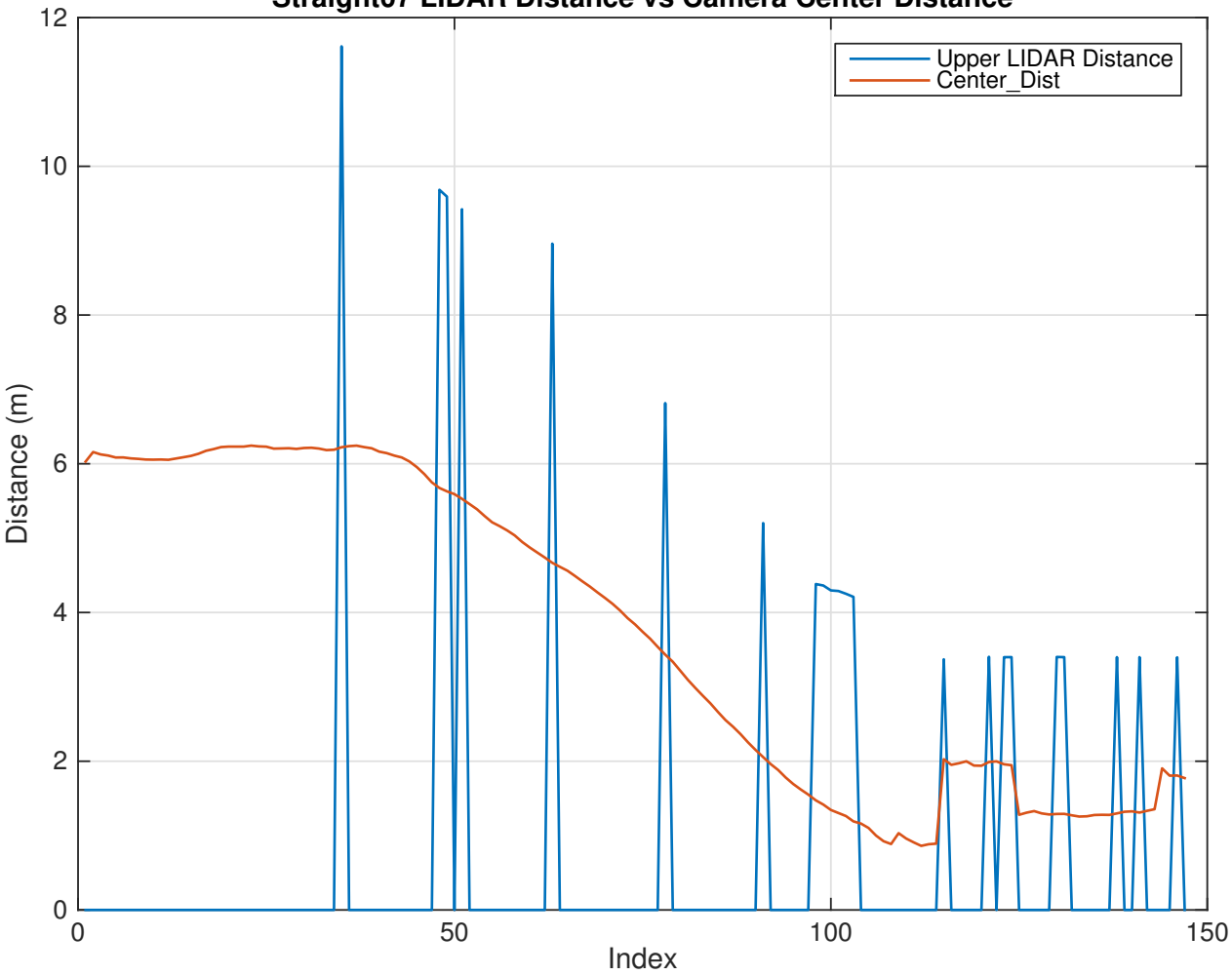
4

false

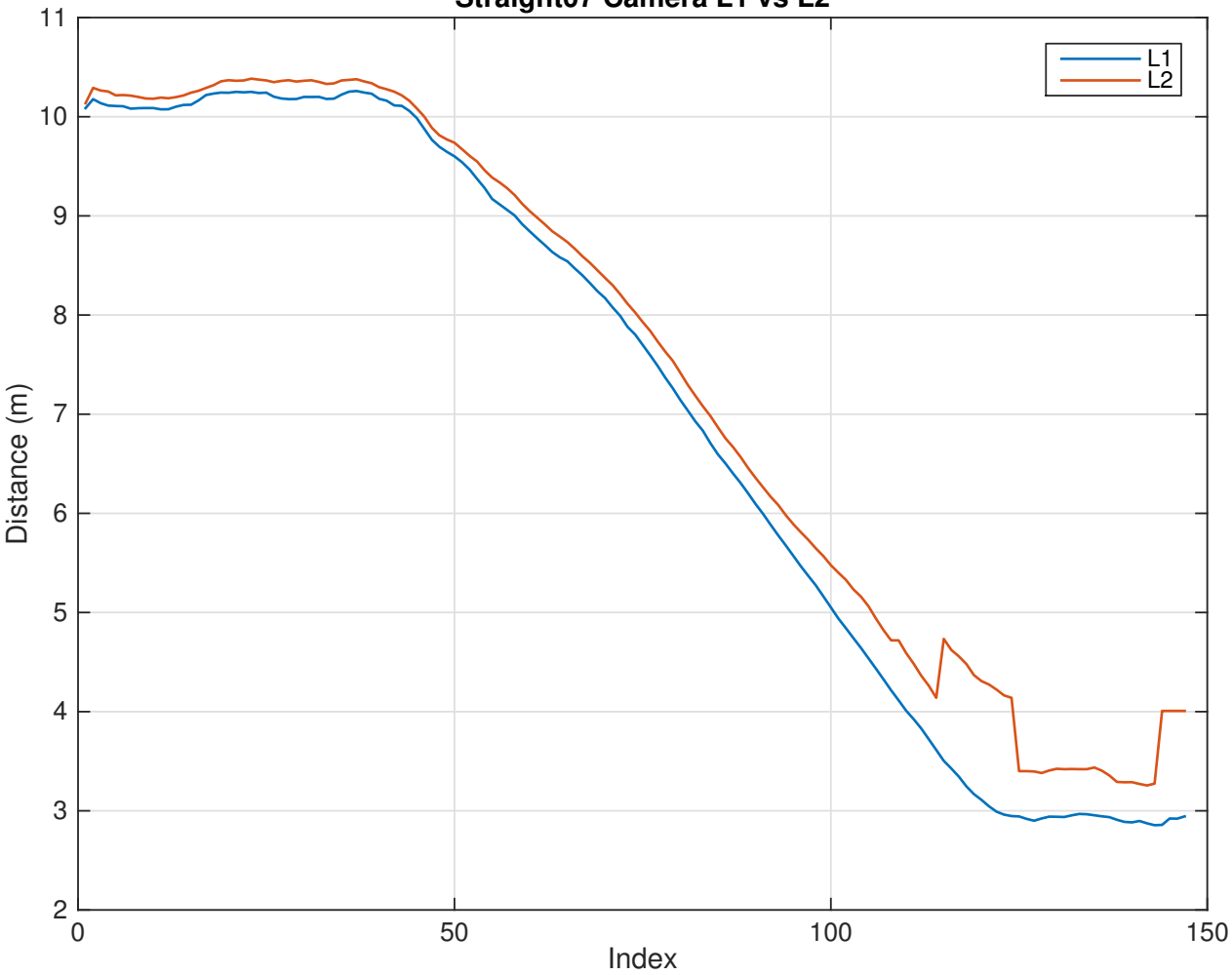
Straight07 Left_Edge vs Right_Edge



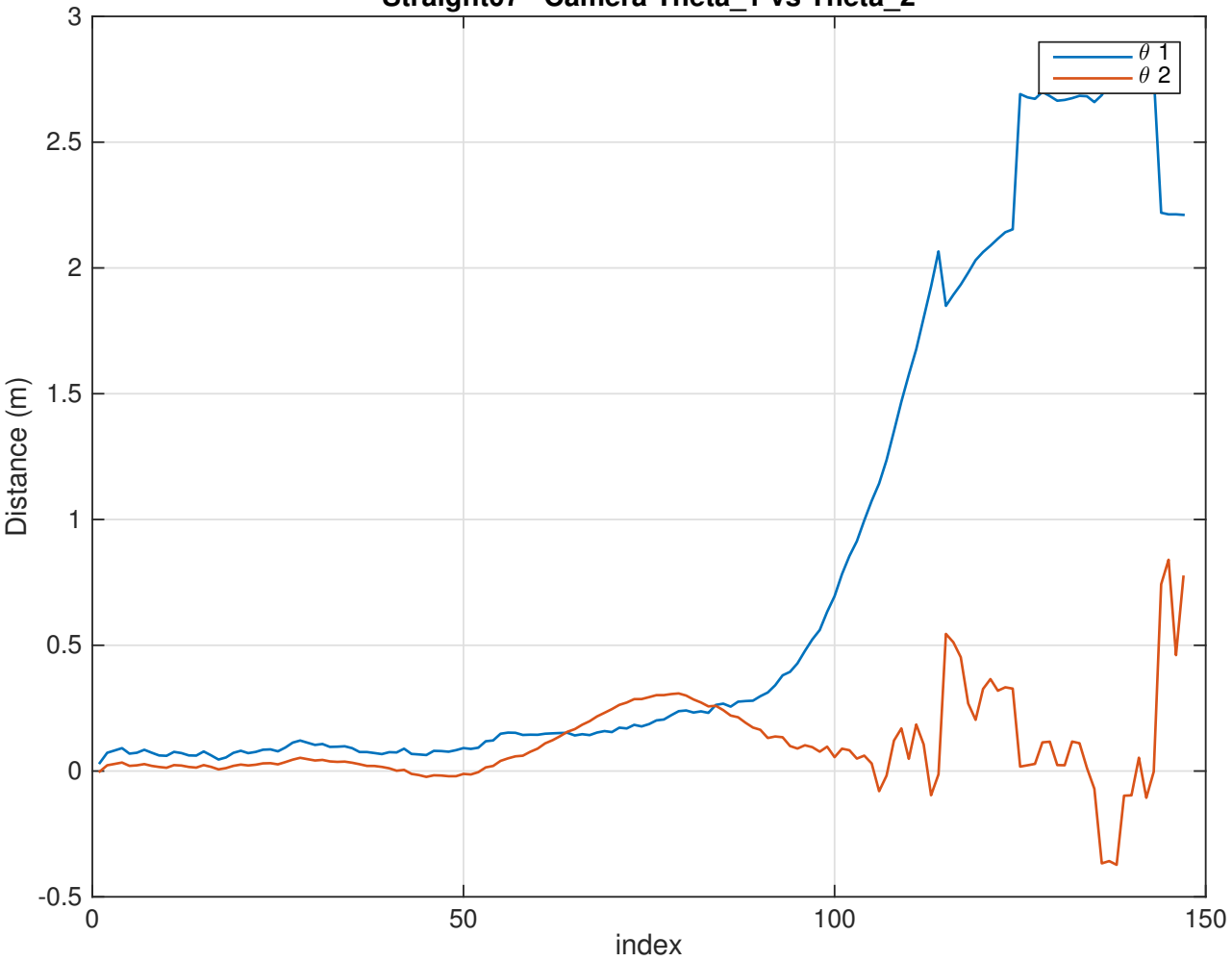
Straight07 LIDAR Distance vs Camera Center Distance



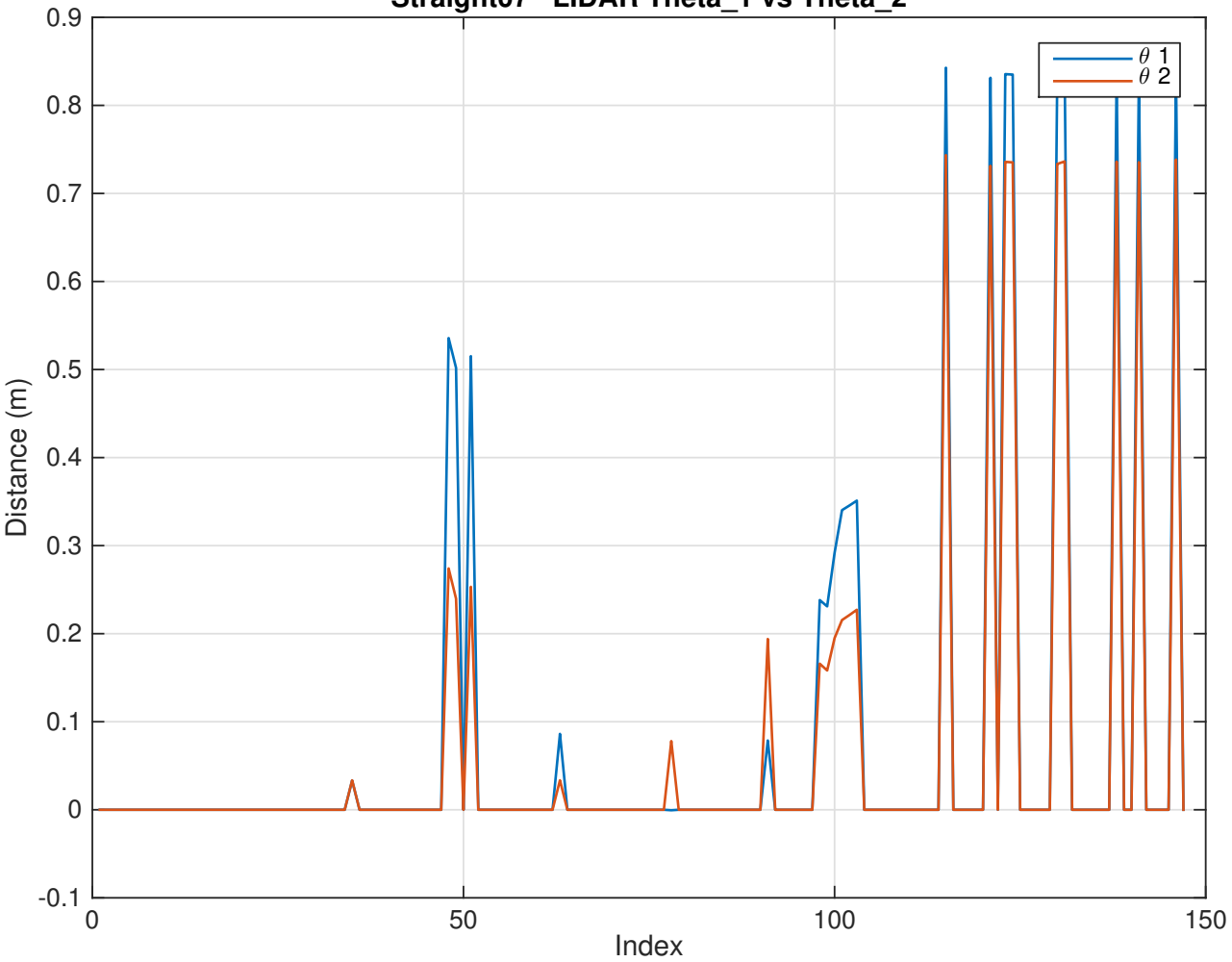
Straight07 Camera L1 vs L2



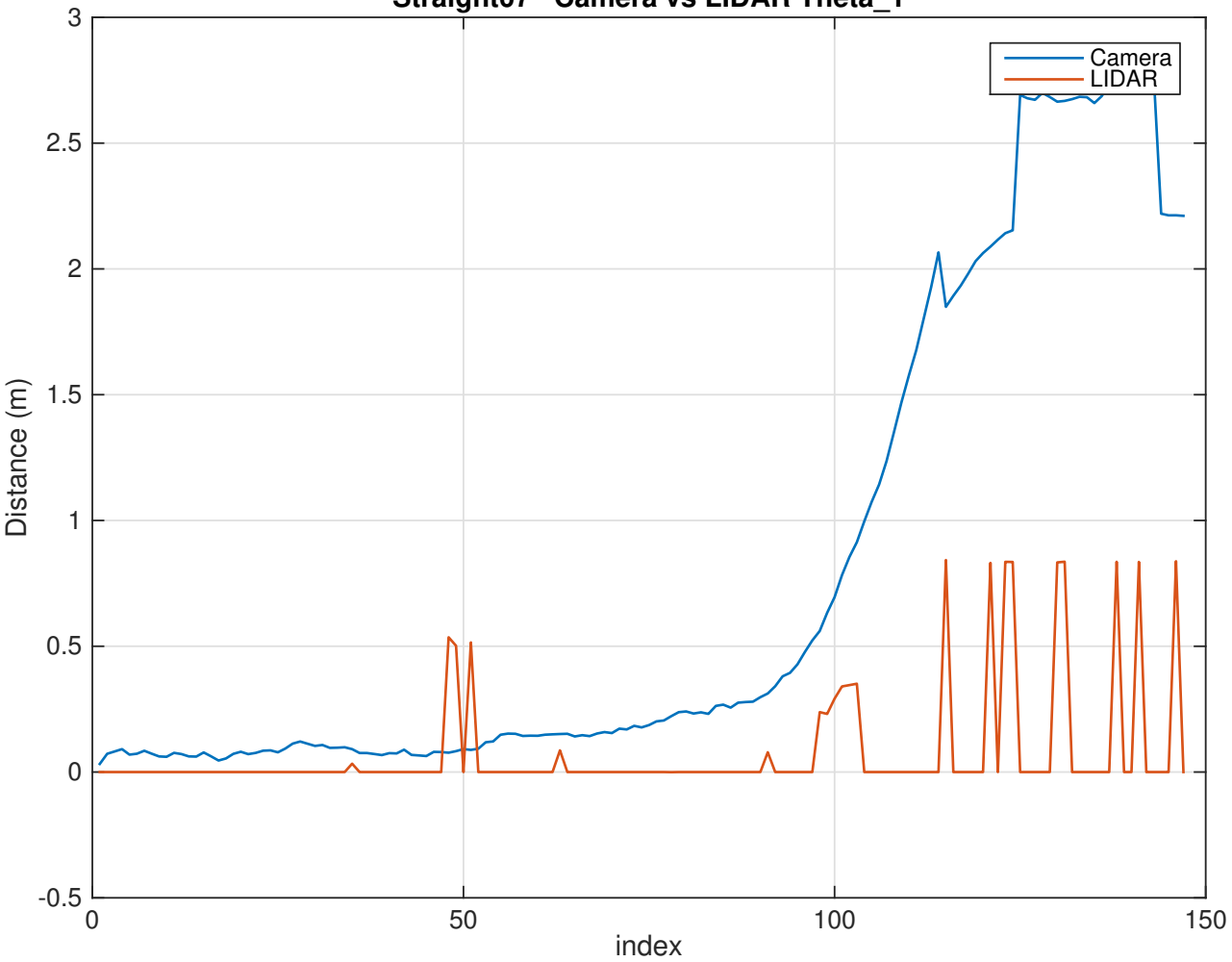
Straight07 Camera Theta_1 vs Theta_2



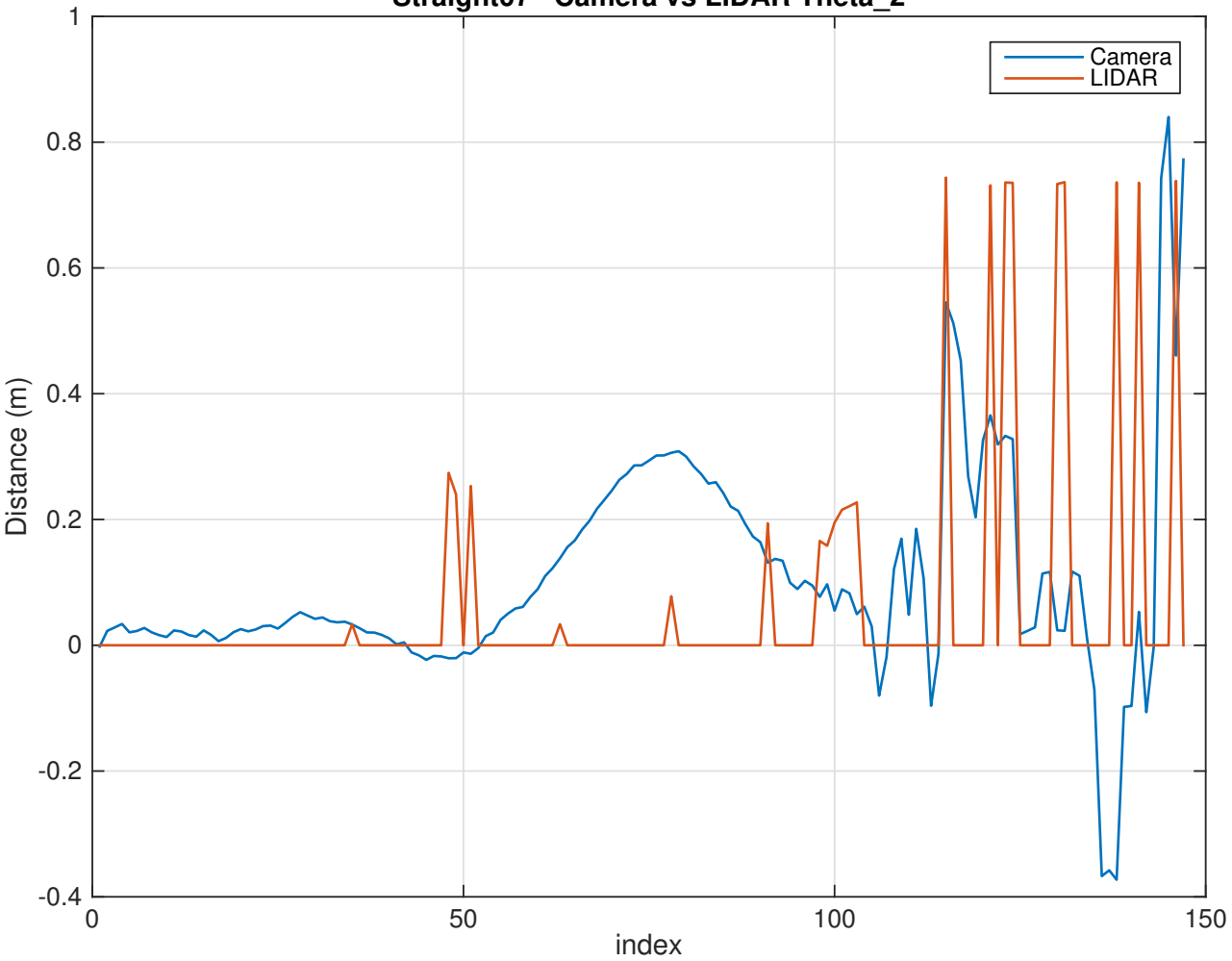
Straight07 LIDAR Theta_1 vs Theta_2



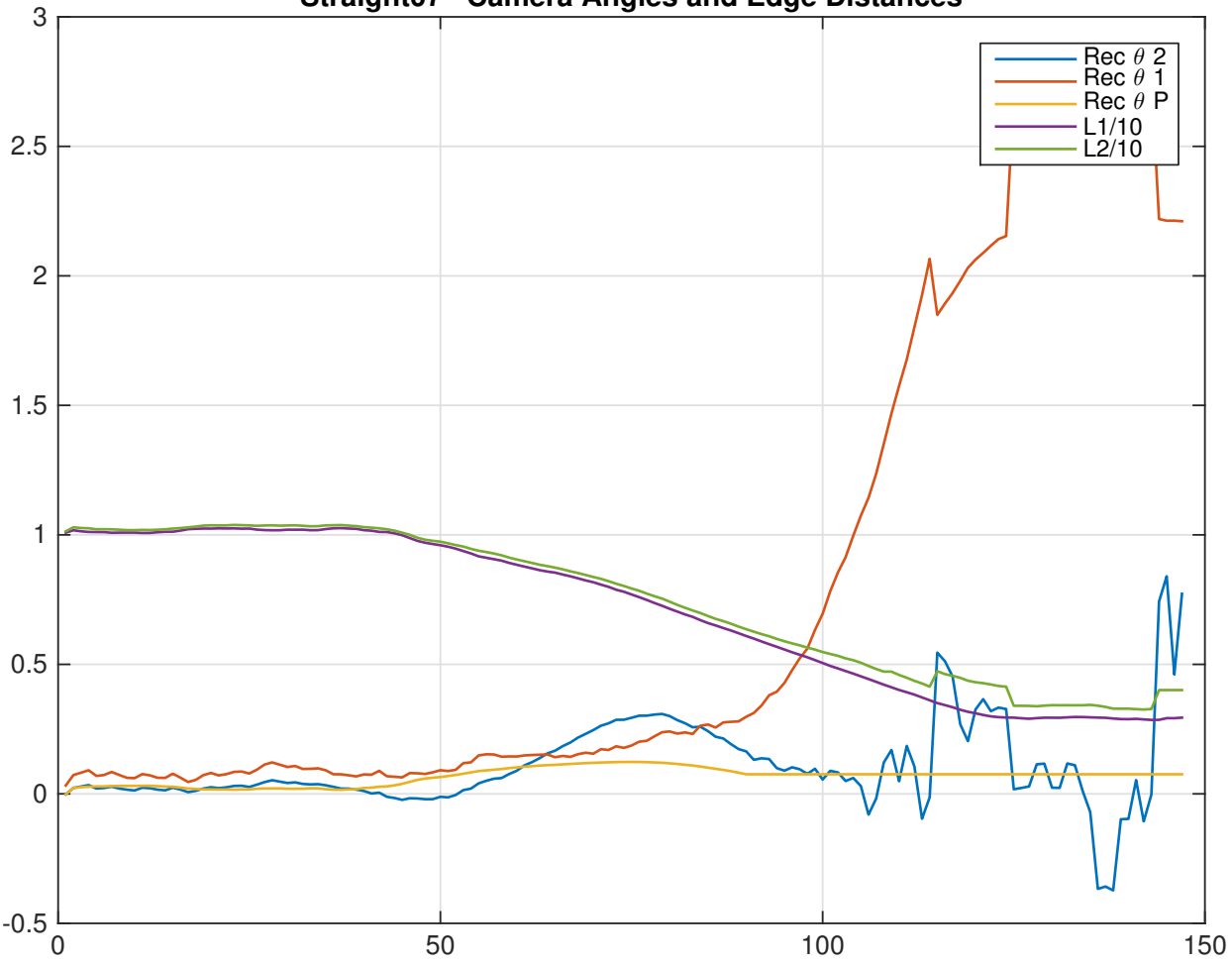
Straight07 Camera vs LIDAR Theta_1



Straight07 Camera vs LIDAR Theta_2



Straight07 Camera Angles and Edge Distances



Straight07 Calculated vs. Actual Steering

