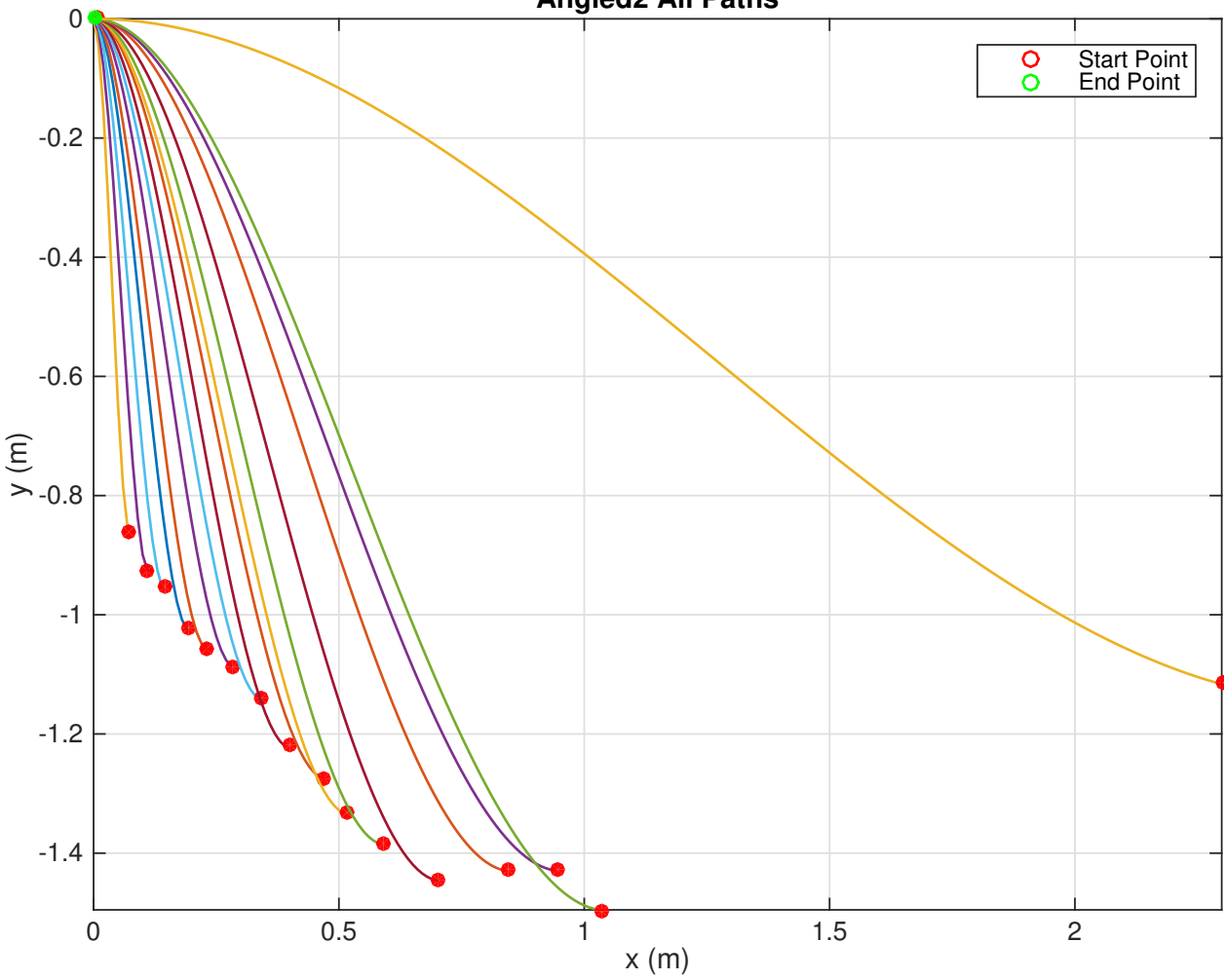


Angled2 All Paths



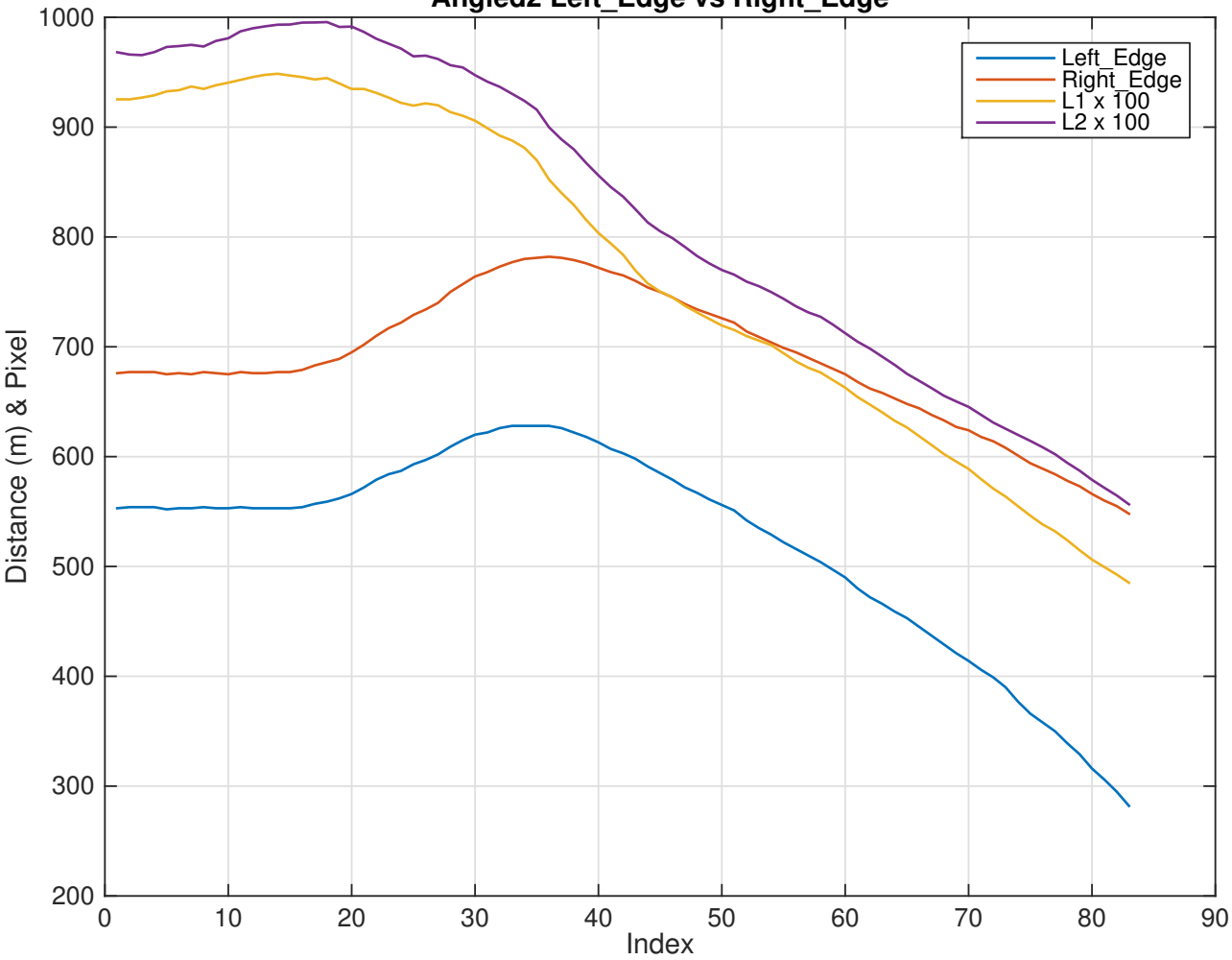
Number_Of_Unique_Paths

King_Pin_Detected

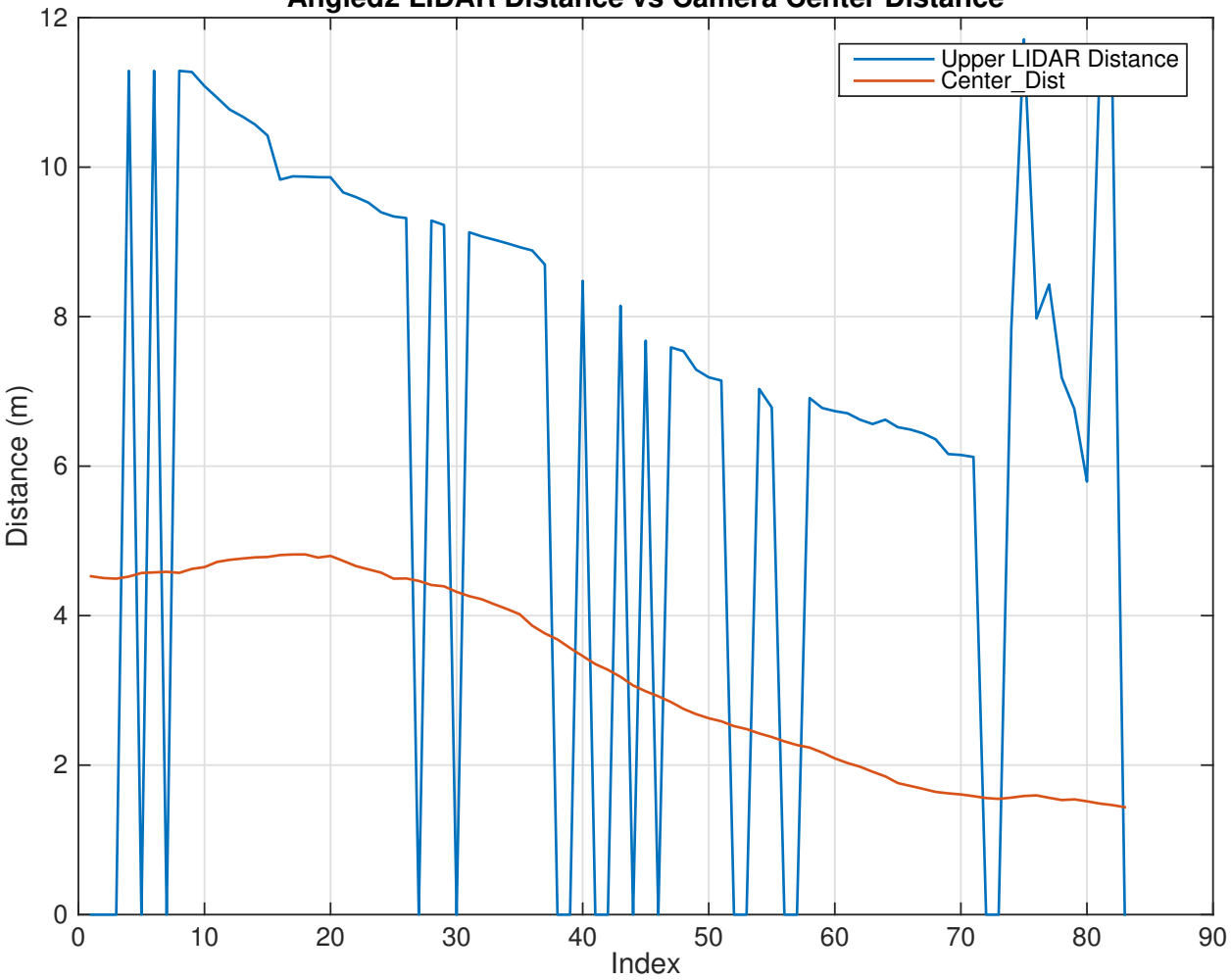
45

false

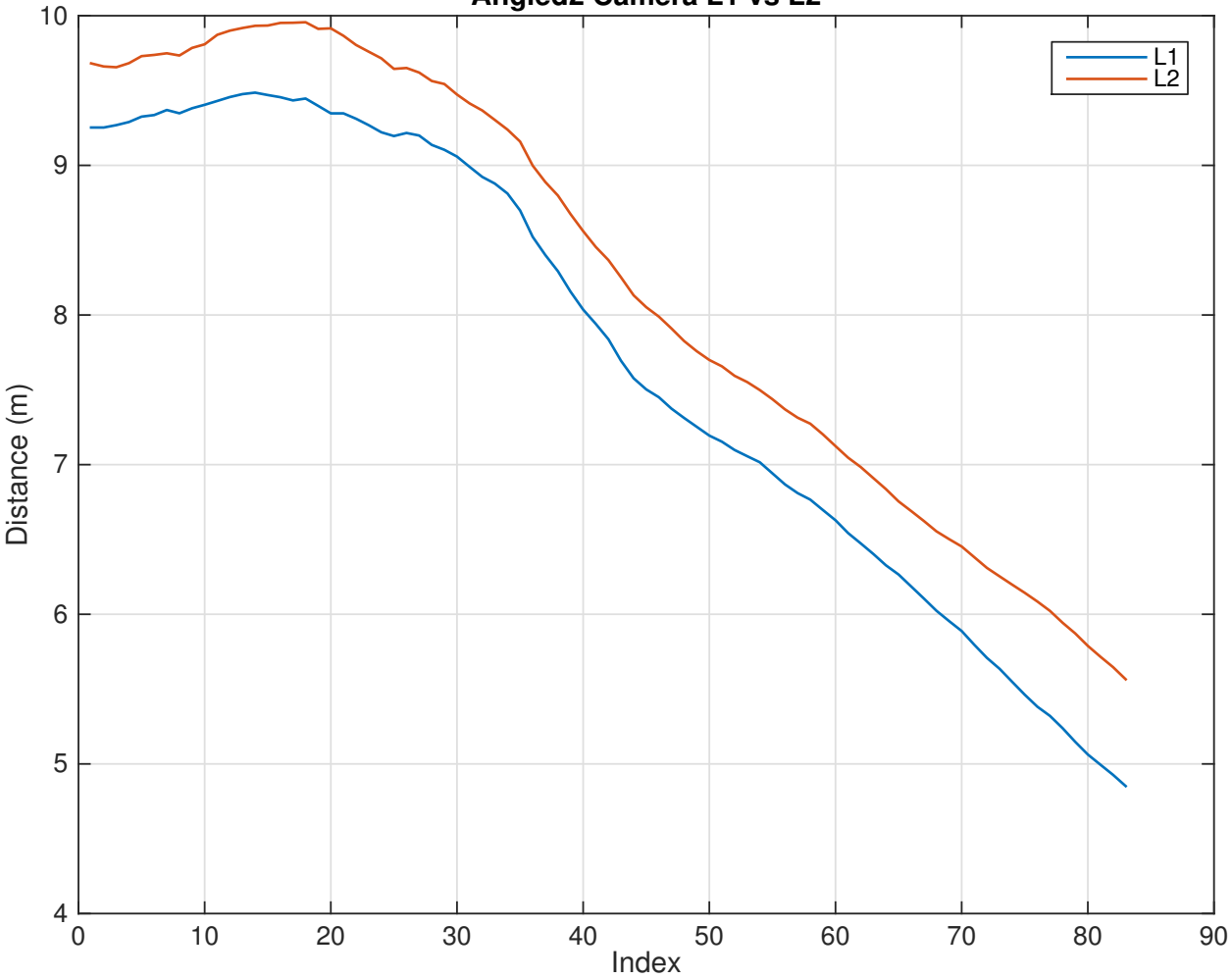
Angled2 Left_Edge vs Right_Edge



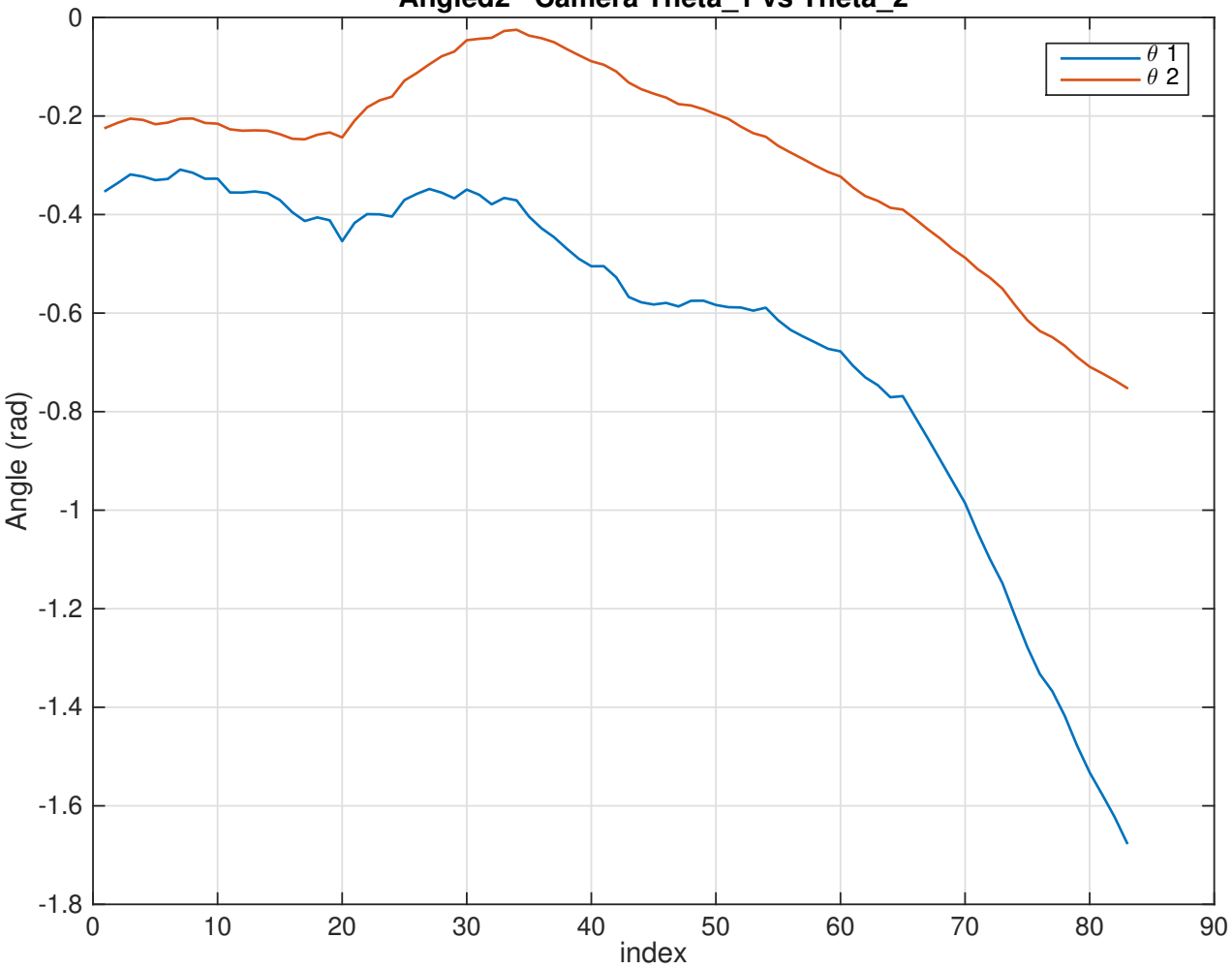
Angled2 LIDAR Distance vs Camera Center Distance



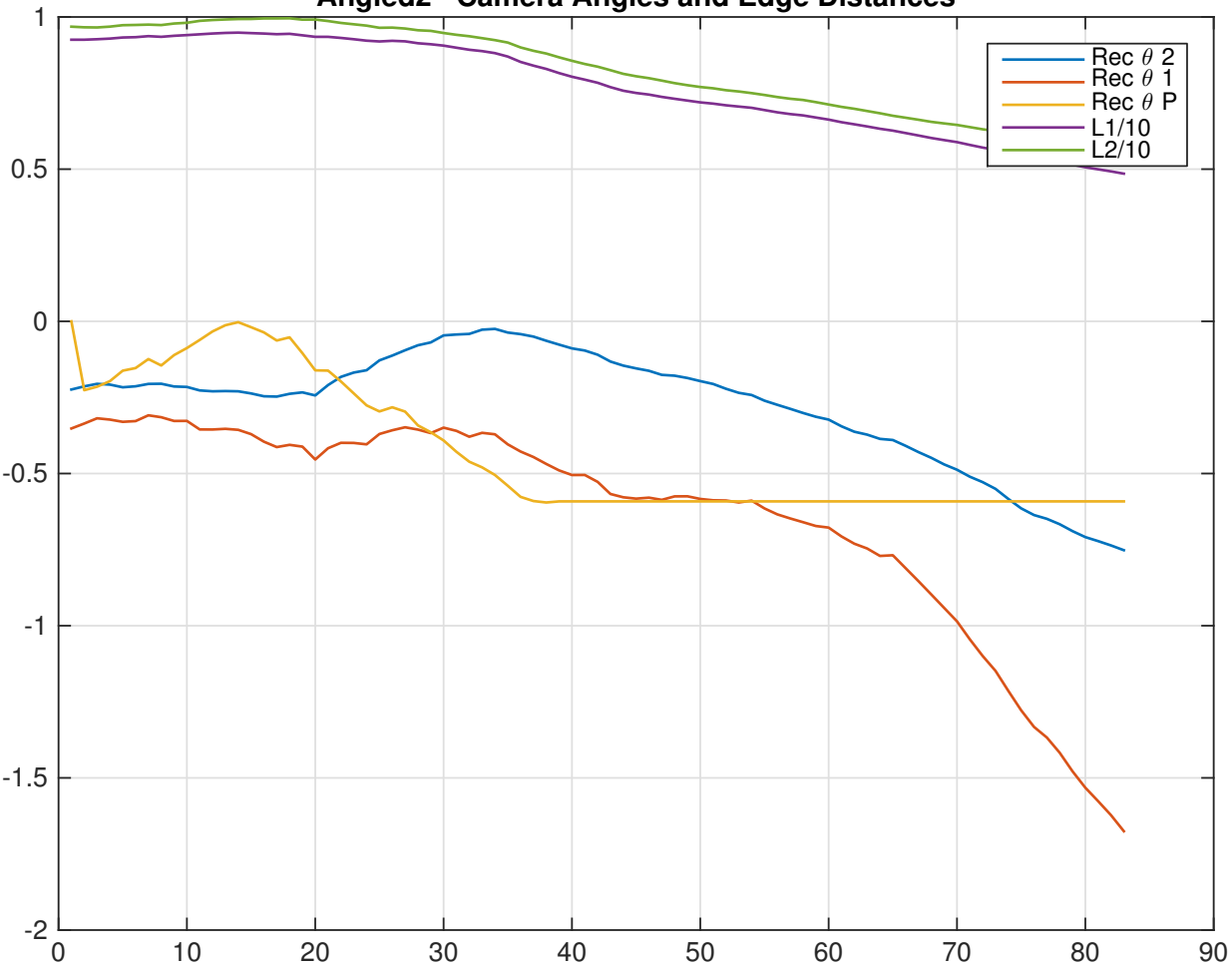
Angled2 Camera L1 vs L2



Angled2 Camera Theta_1 vs Theta_2



Angled2 Camera Angles and Edge Distances



Angled2 Steering

