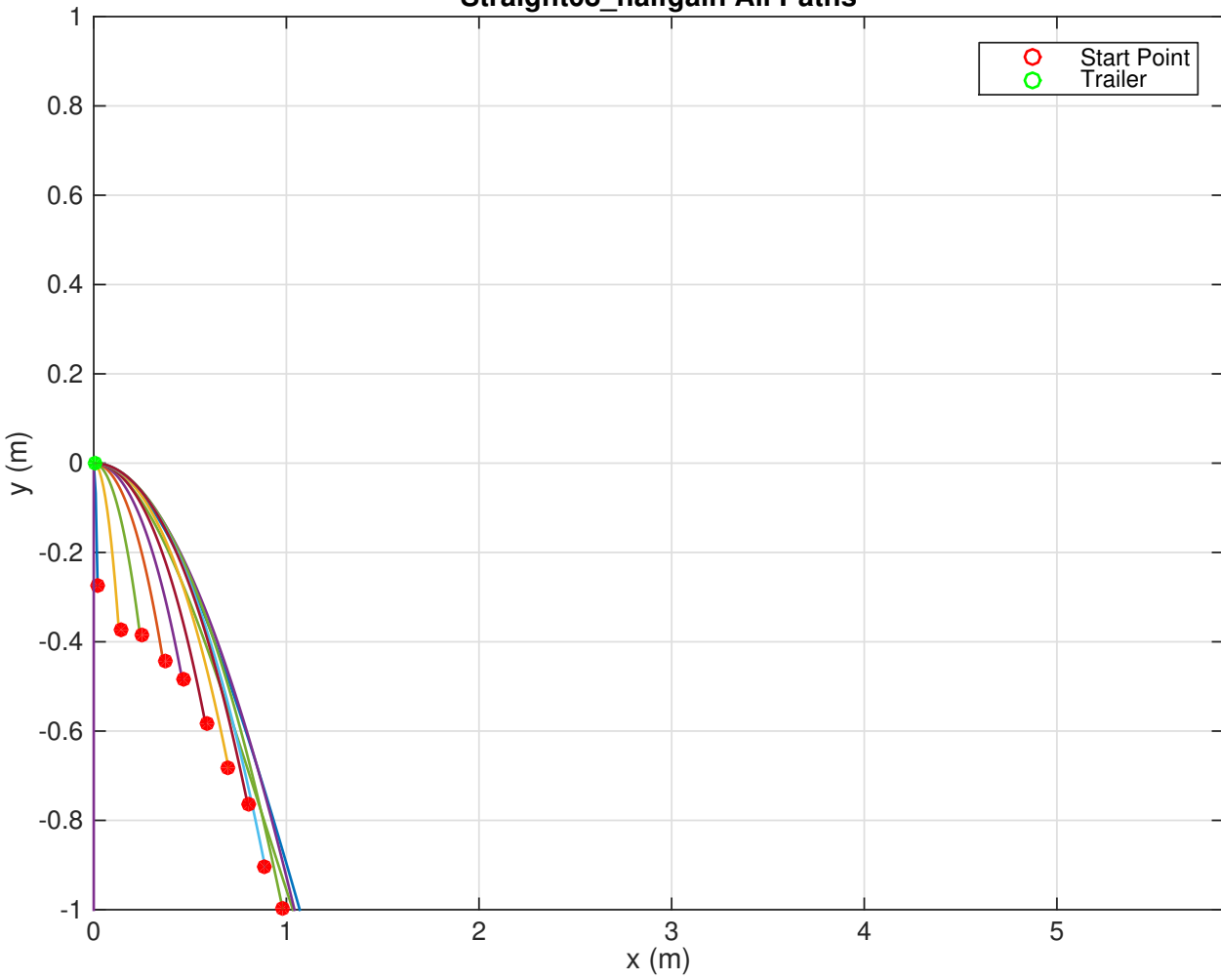Straight08_halfgain All Paths
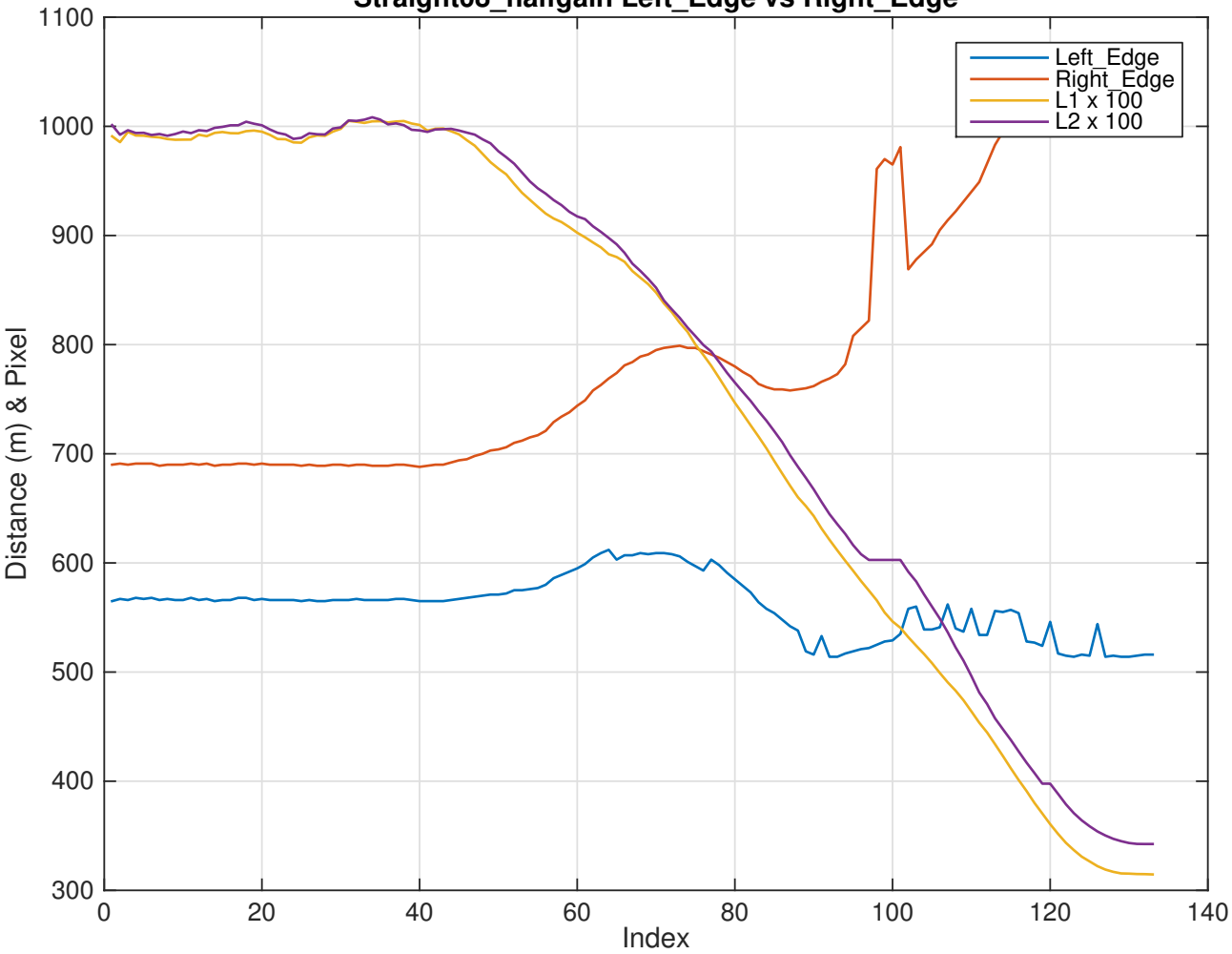
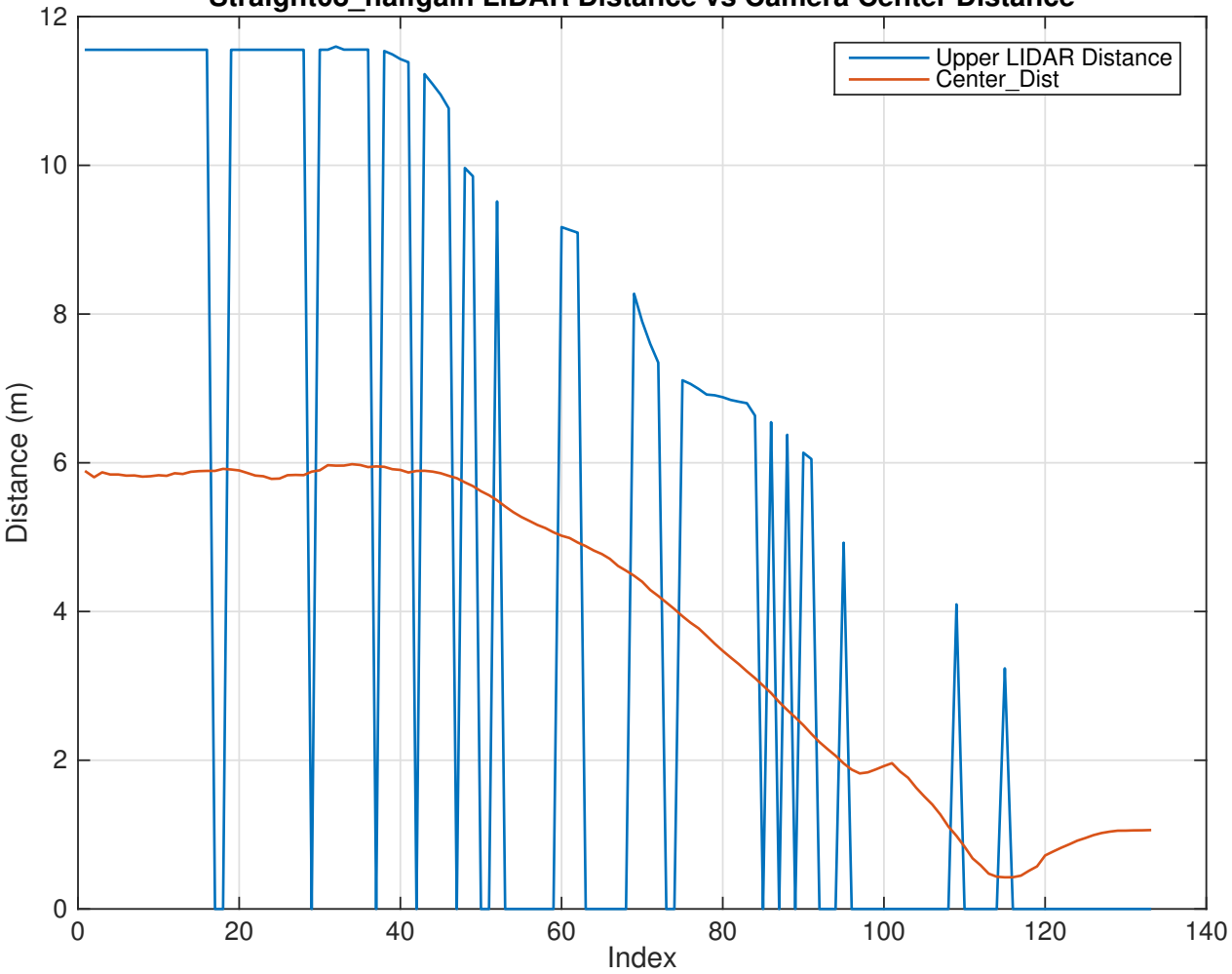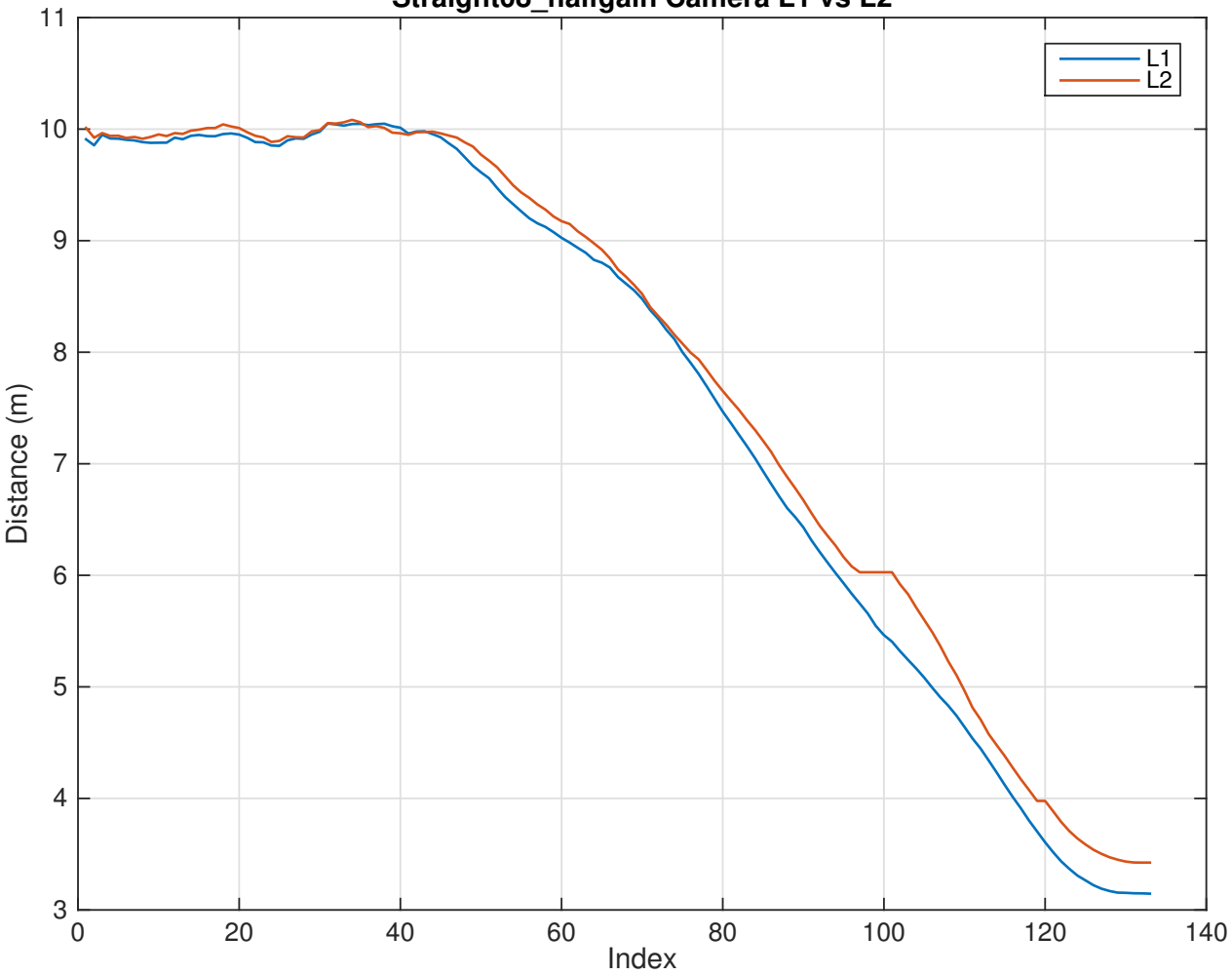| Number_Of_Unique_Paths	King_Pin_Detected
32	false

Straight08_halfgain Left_Edge vs Right_Edge

Straight08_halfgain LIDAR Distance vs Camera Center Distance

Legend:
- Upper LIDAR Distance
- Center_Dist

X-axis: Index
Y-axis: Distance (m)

Straight08_halfgain Camera L1 vs L2

Straight08_halfgain   Camera Theta_1 vs Theta_2
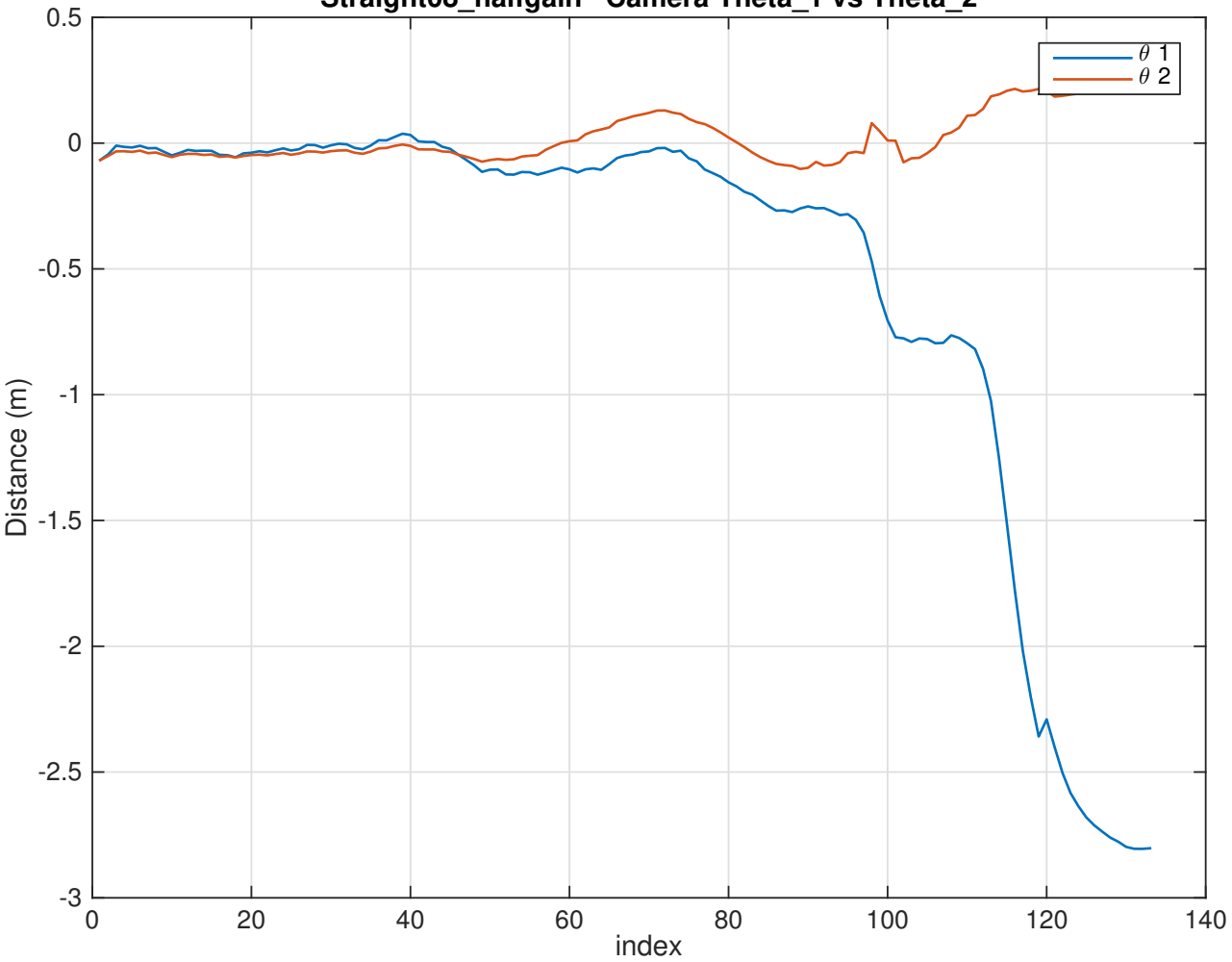
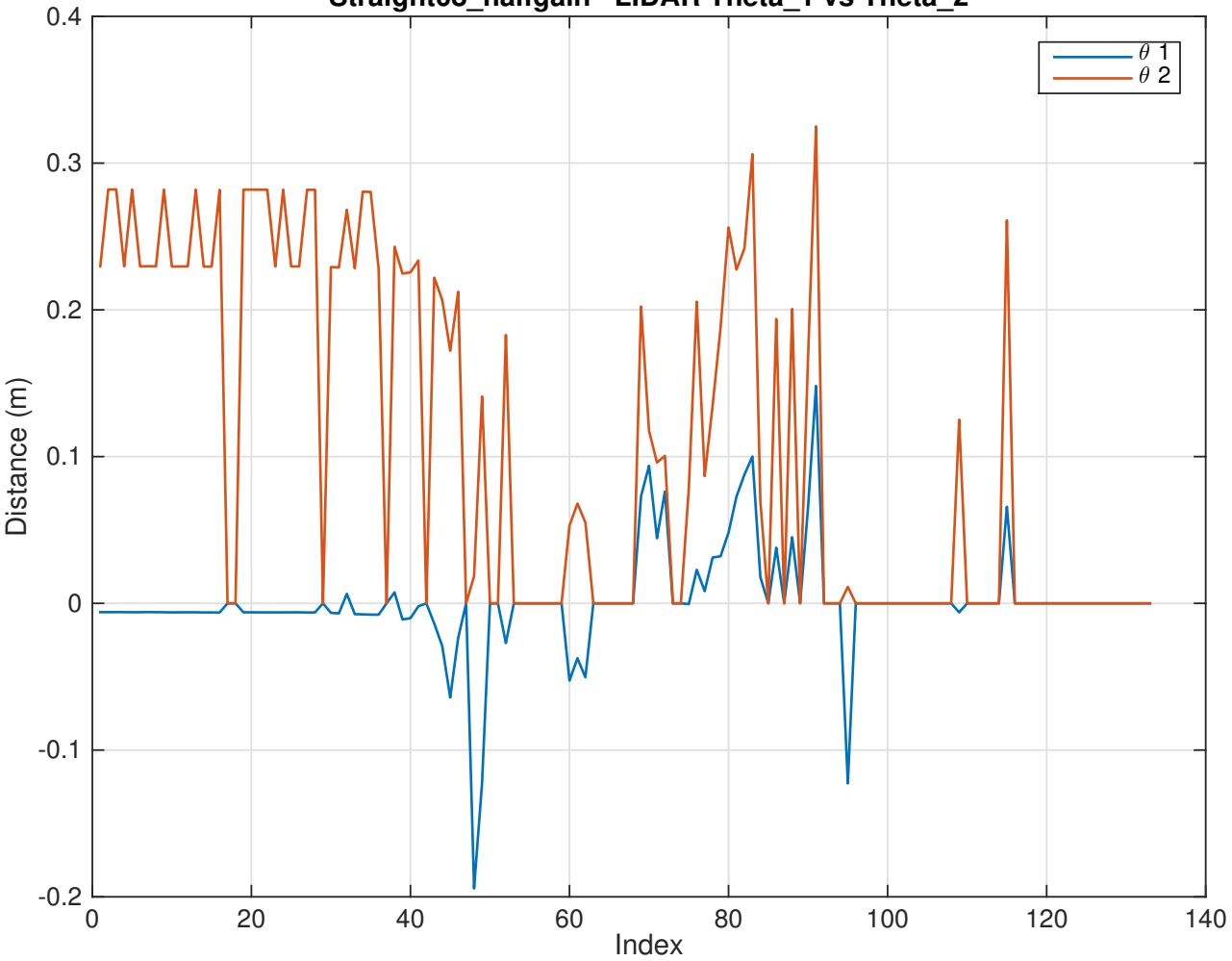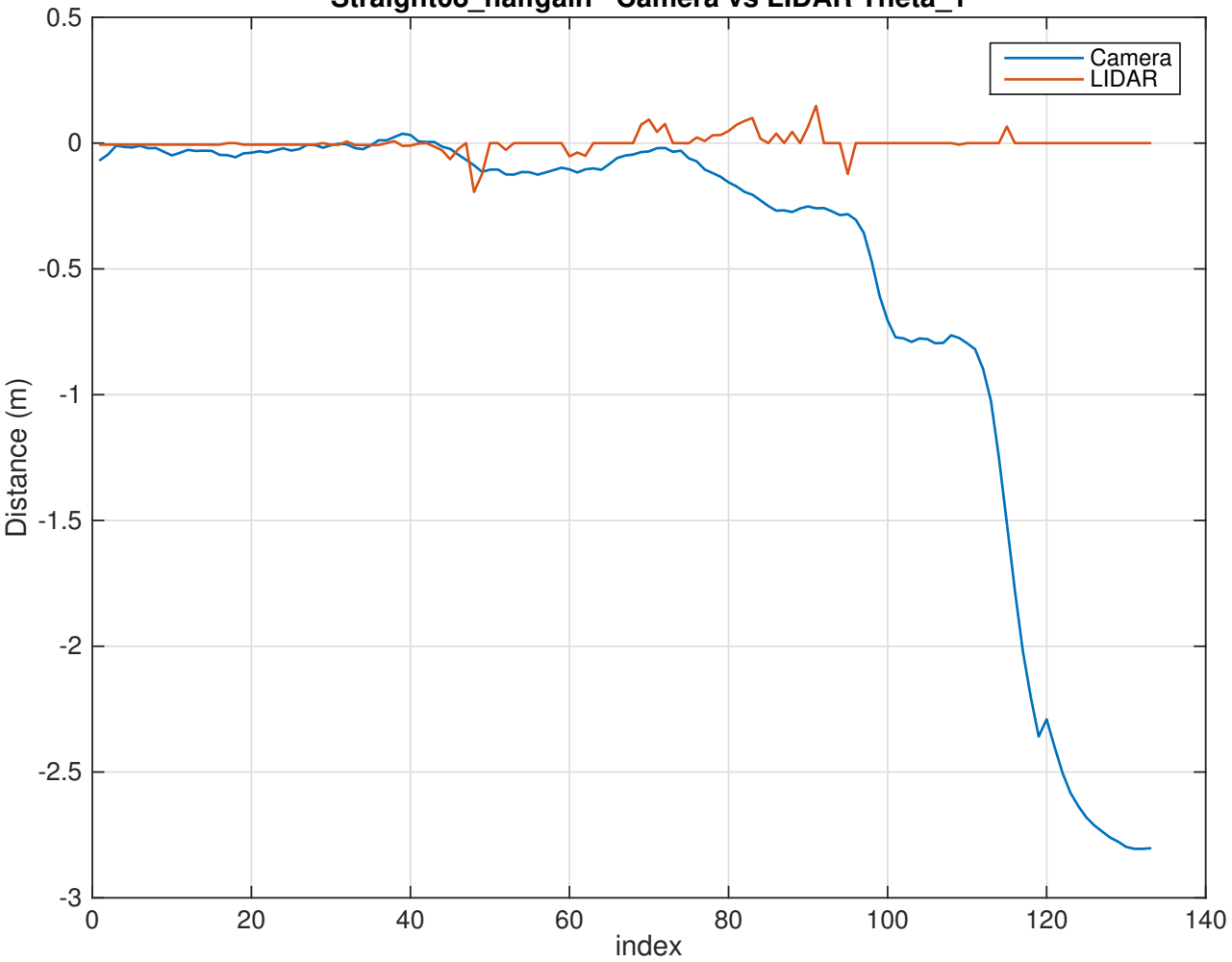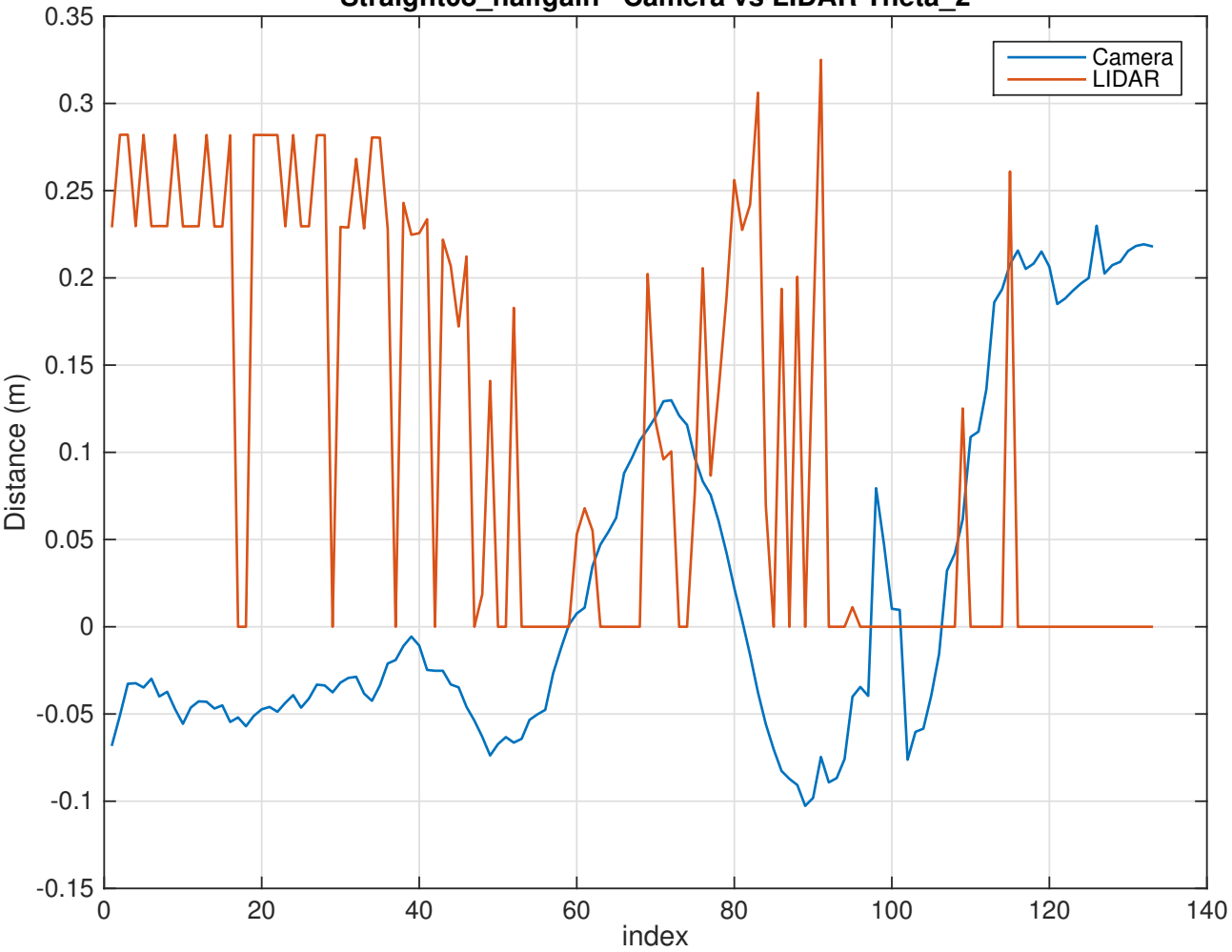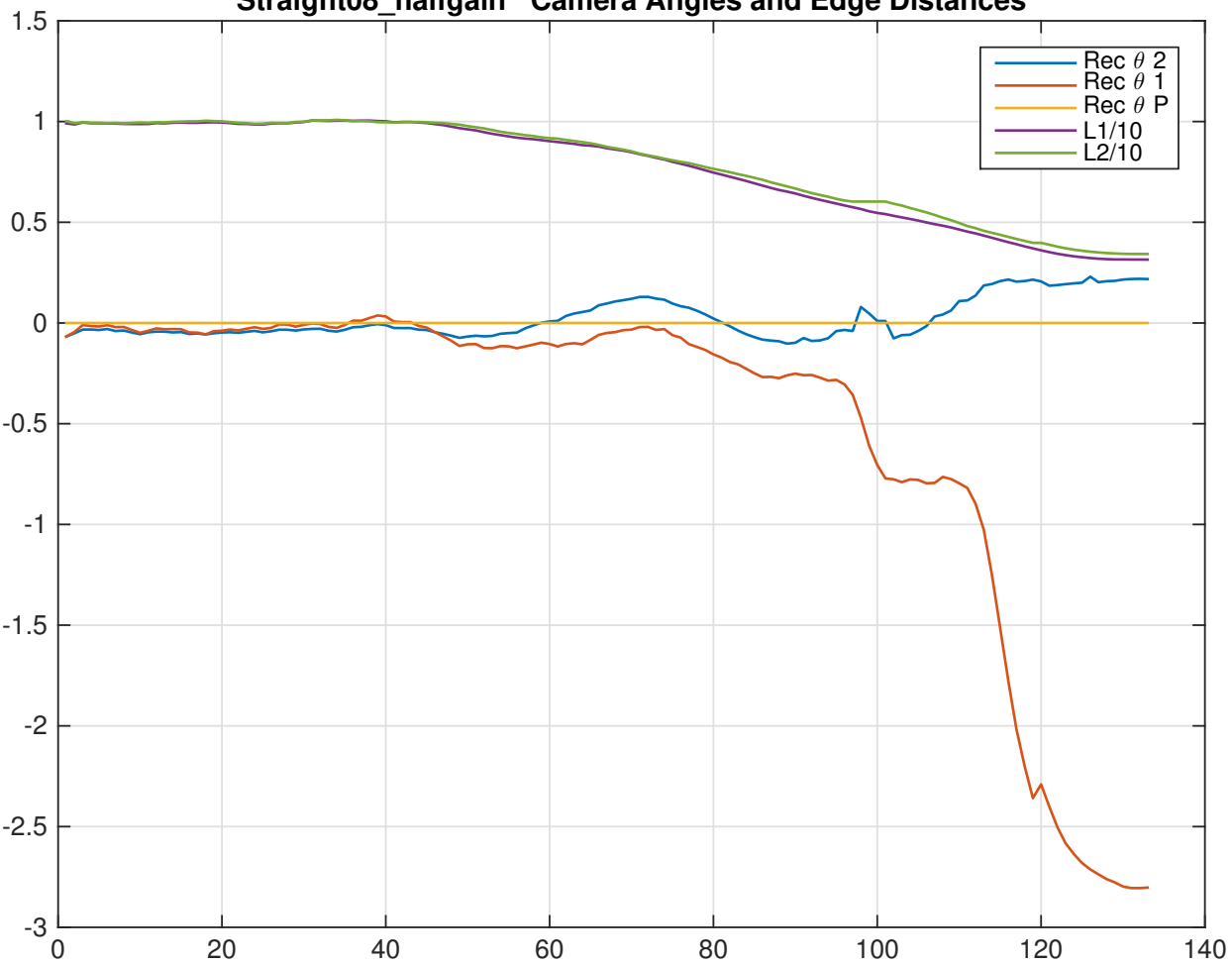**Straight08_halfgain   LIDAR Theta_1 vs Theta_2**

Straight08_halfgain   Camera vs LIDAR Theta_1

Straight08_halfgain   Camera vs LIDAR Theta_2

Straight08_halfgain Camera Angles and Edge Distances

Legend:
- Rec θ 2
- Rec θ 1
- Rec θ P
- L1/10
- L2/10

Straight08_halfgain Calculated vs. Actual Steering

Legend:
- Recorded θ 2
- Recorded θ P
- Recorded Steering Command
- Path Flag (1 = true)
- θ 2