

Number\_Of\_Unique\_Paths

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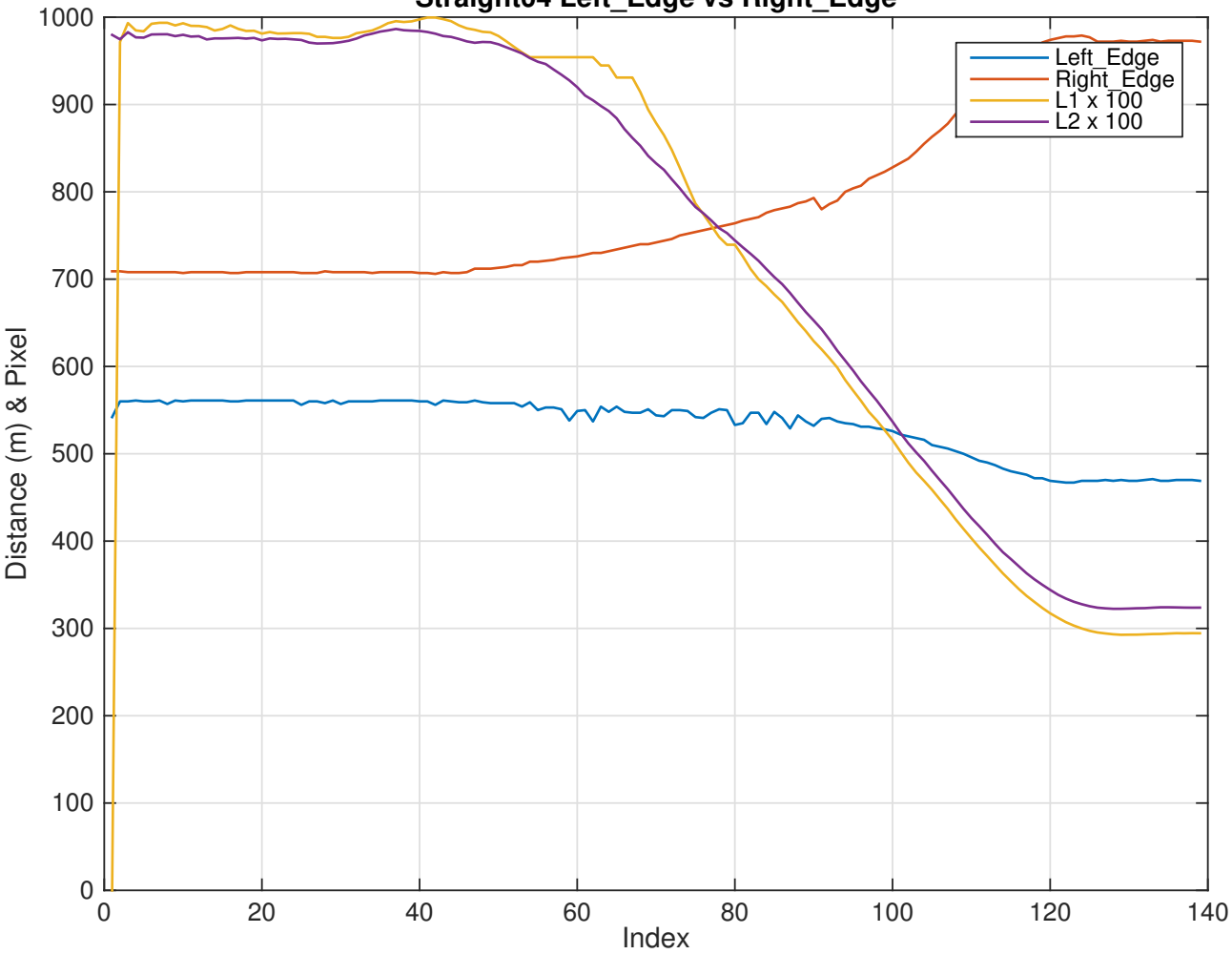
30

King\_Pin\_Detected

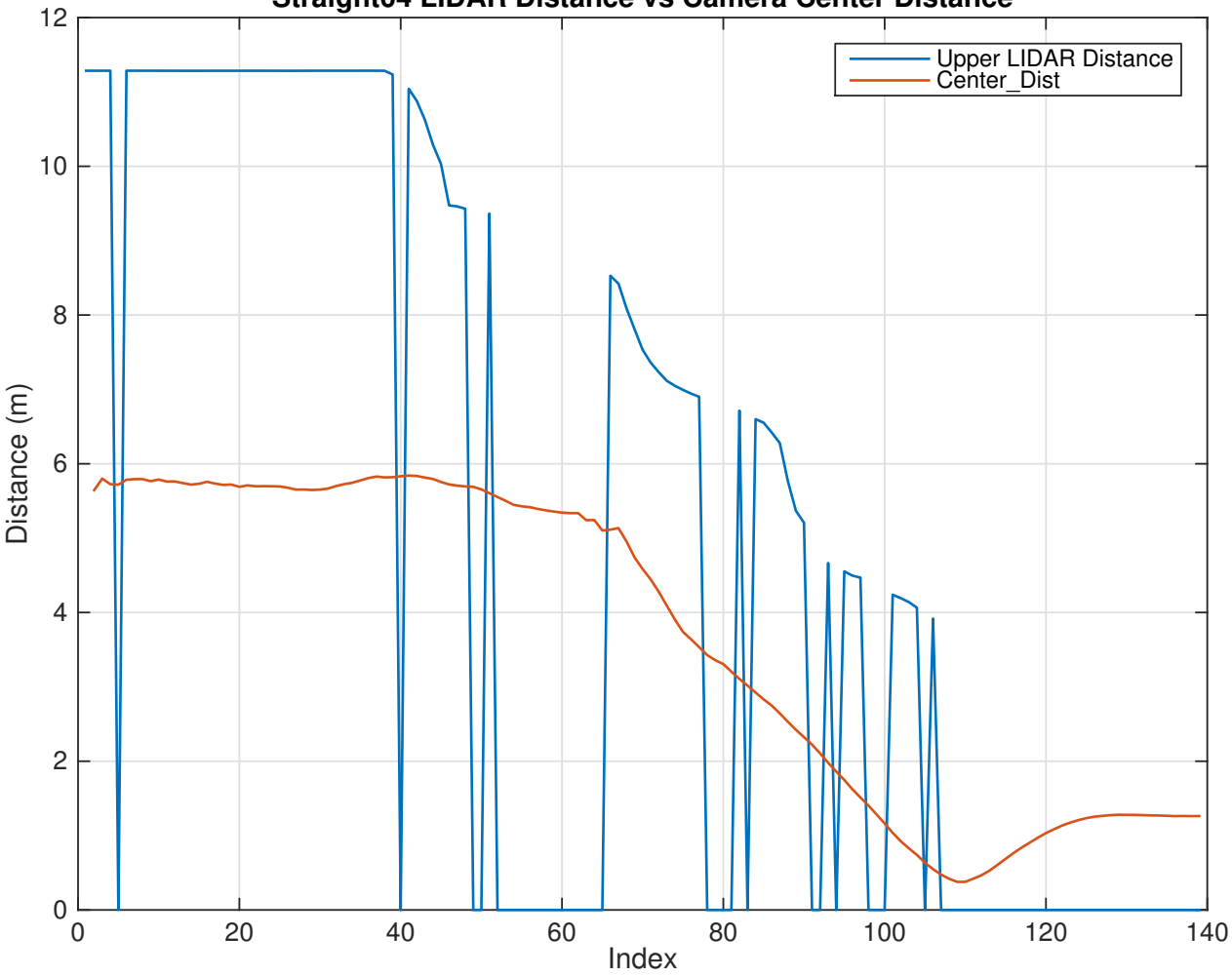
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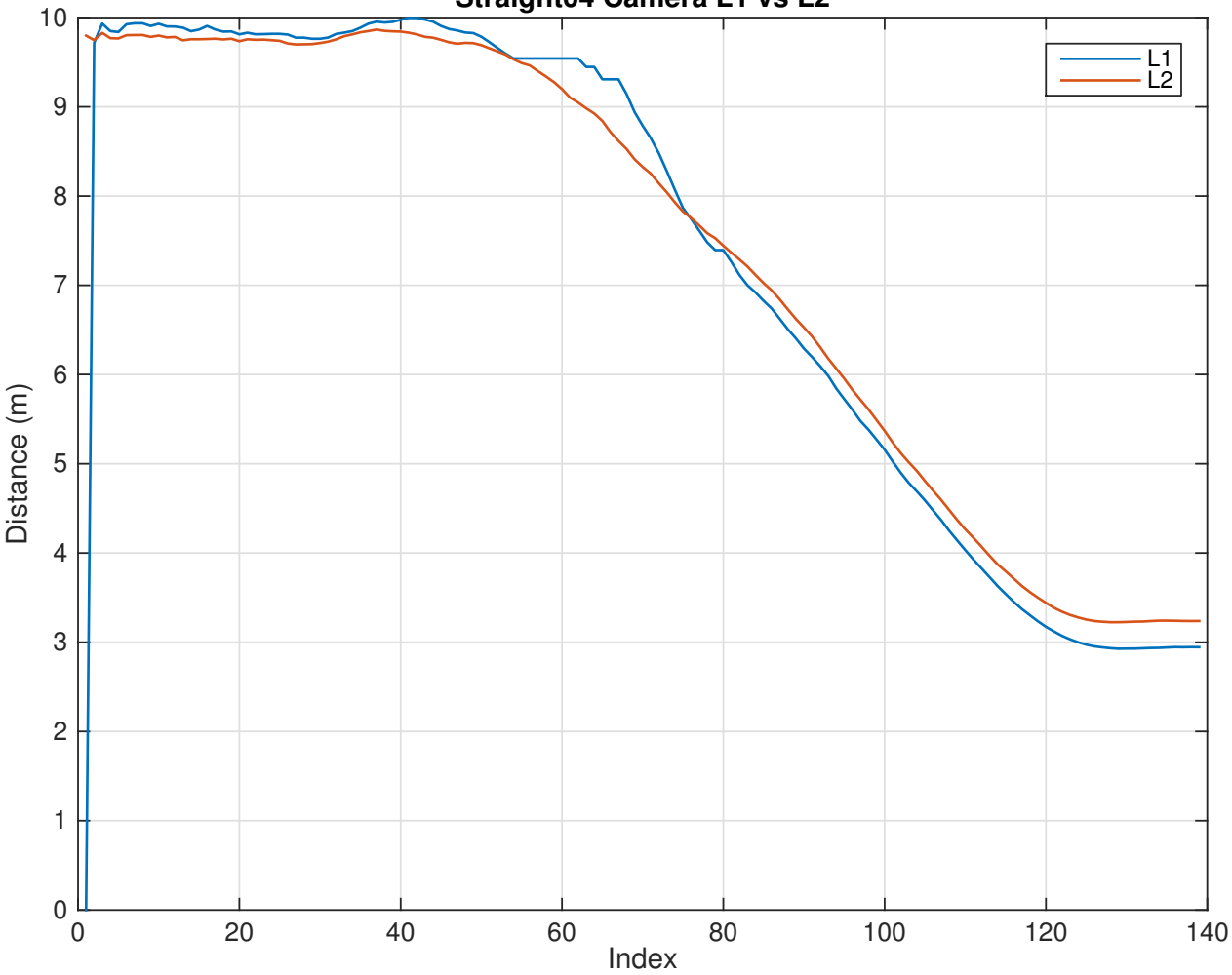
# Straight04 Left\_Edge vs Right\_Edge



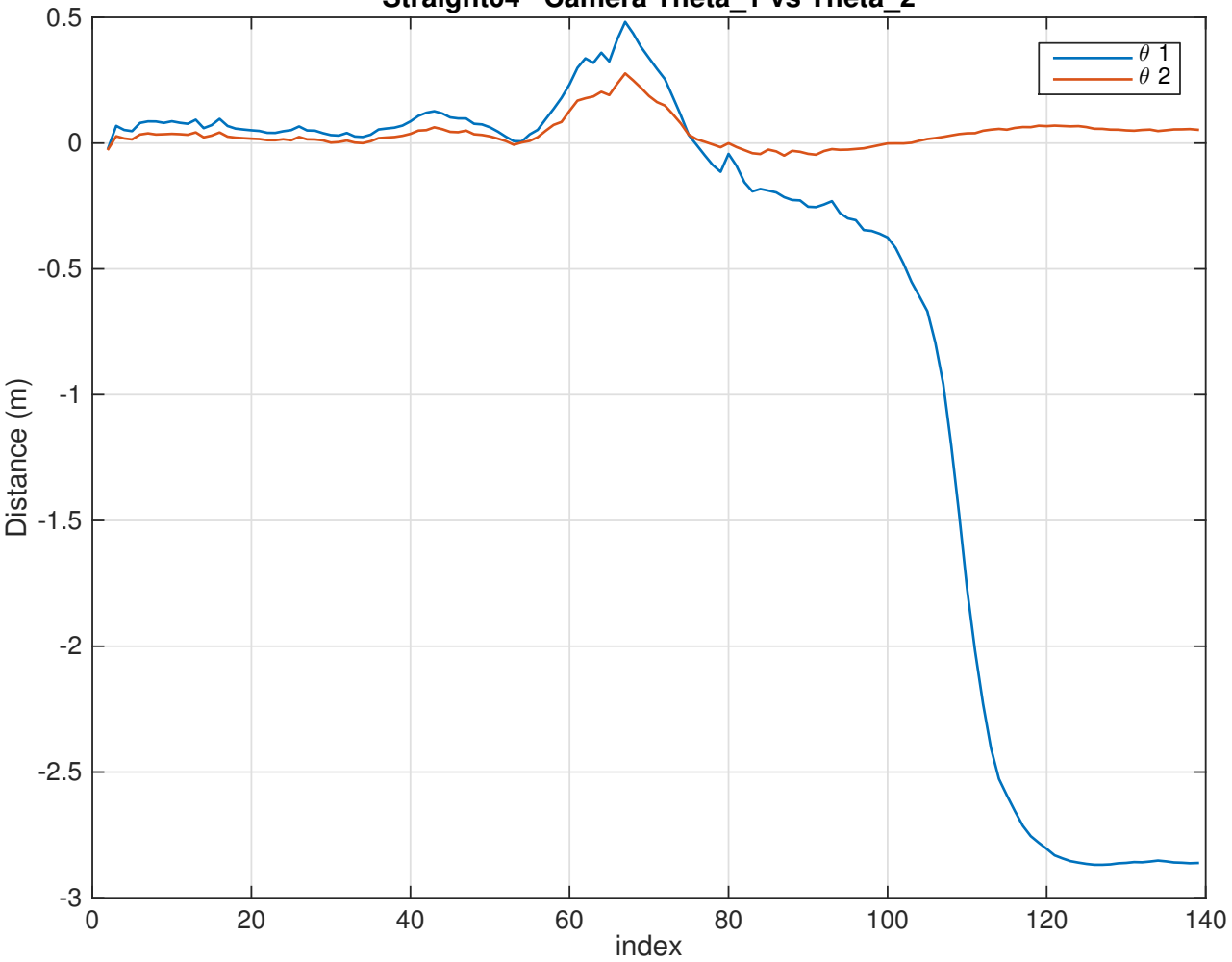
Straight04 LIDAR Distance vs Camera Center Distance



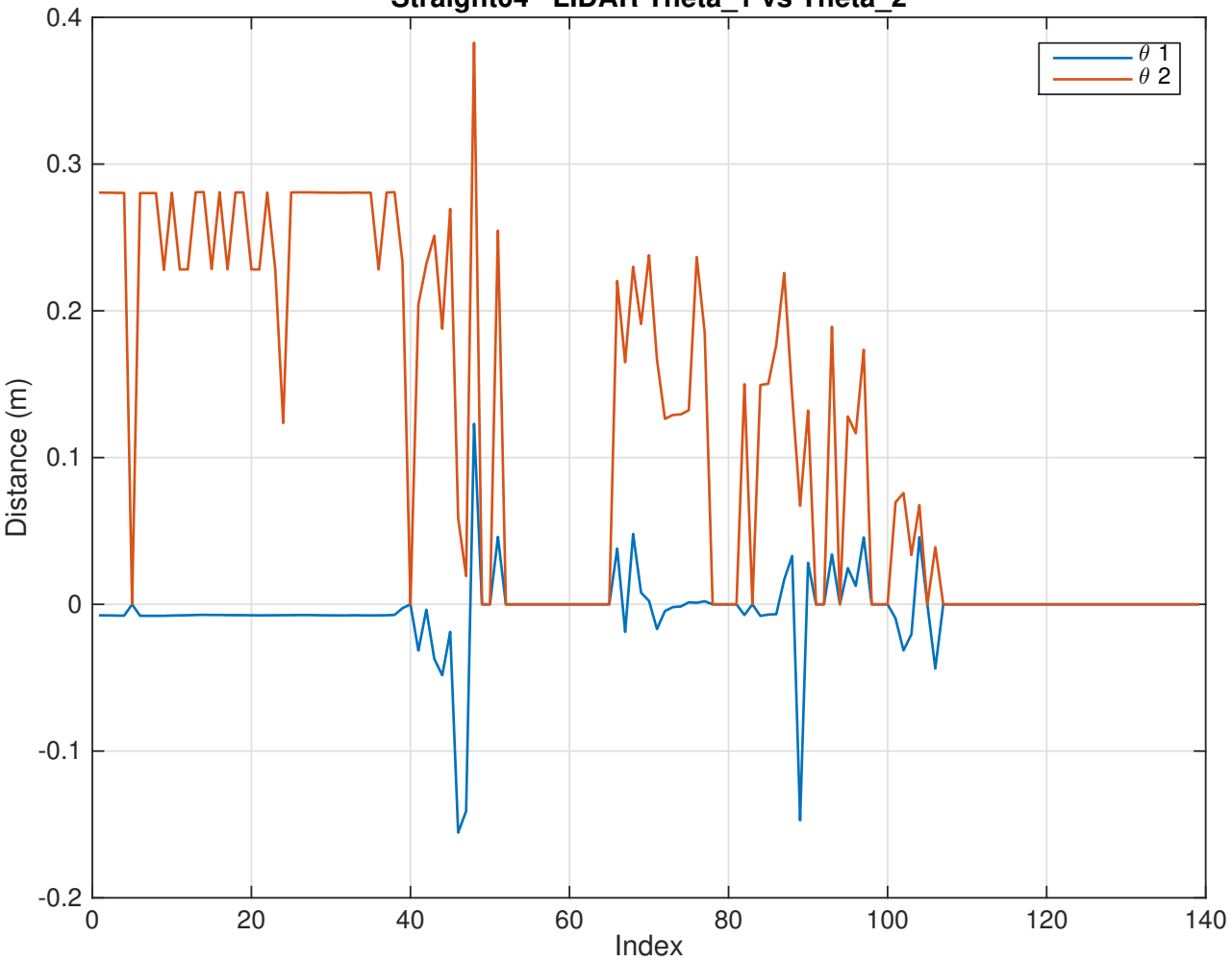
Straight04 Camera L1 vs L2



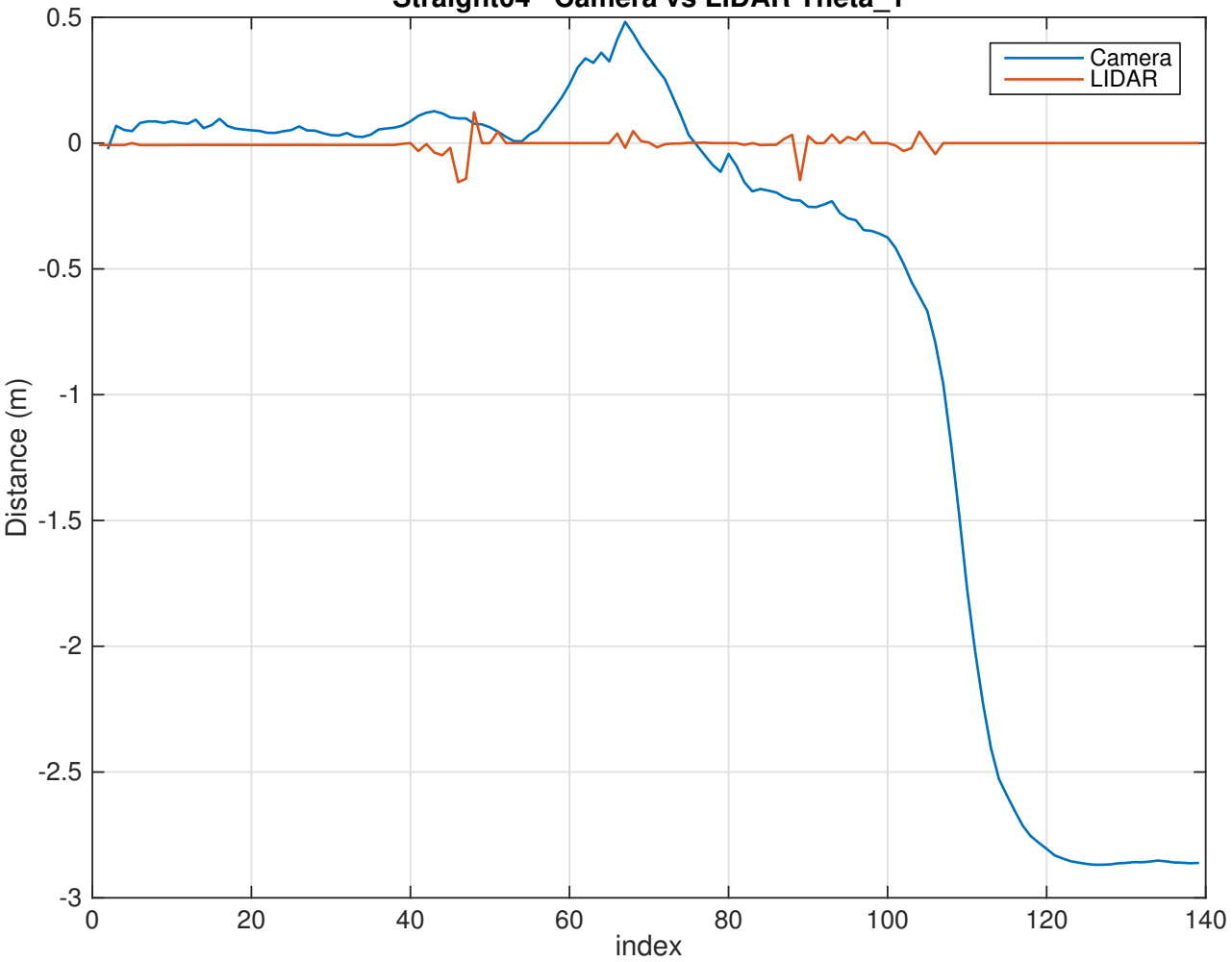
Straight04 Camera Theta\_1 vs Theta\_2



Straight04 LIDAR Theta\_1 vs Theta\_2

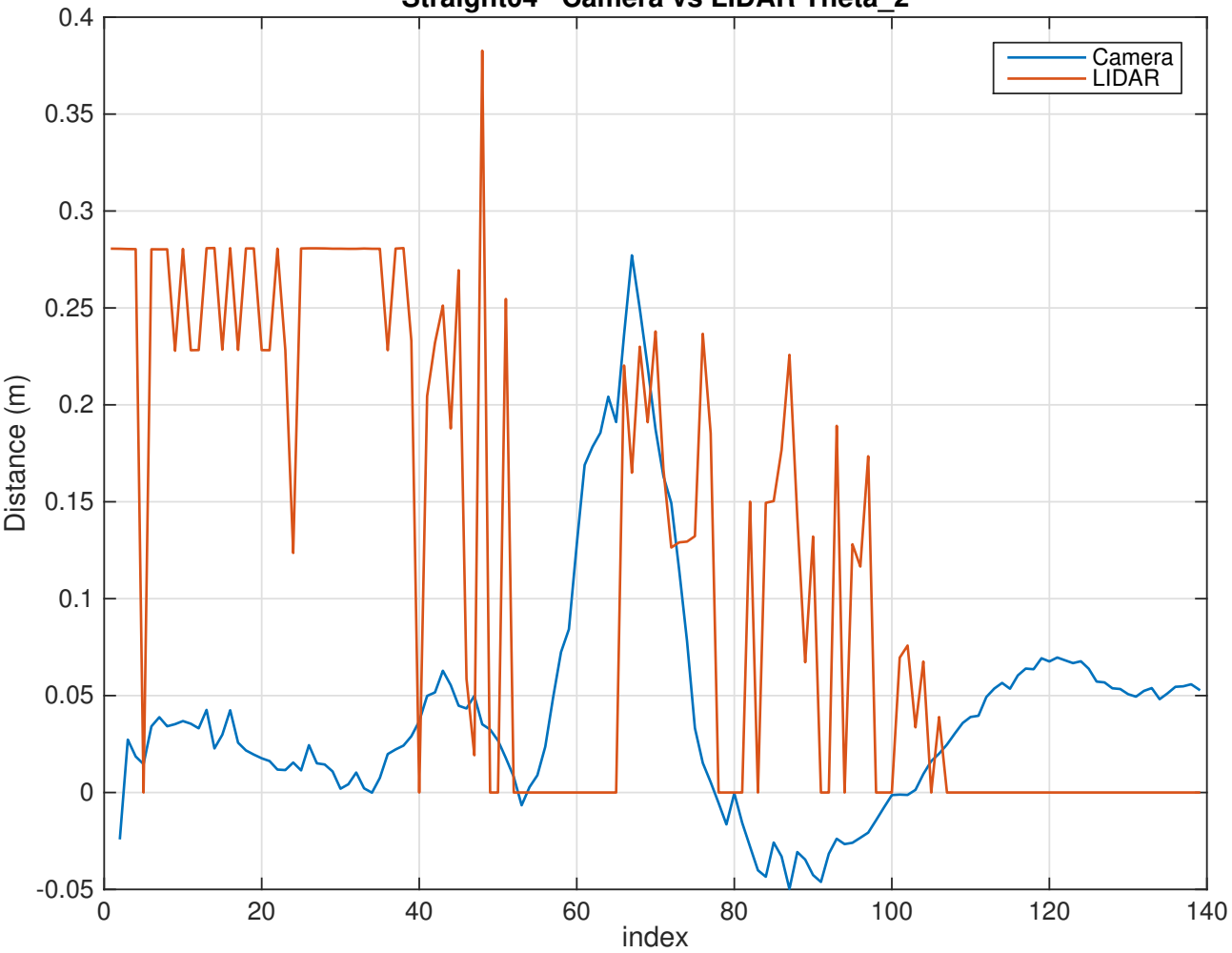


Straight04 Camera vs LIDAR Theta\_1





Straight04 Camera vs LIDAR Theta\_2



Straight04 Camera Angles and Edge Distances



Straight04 Calculated vs. Actual Steering

