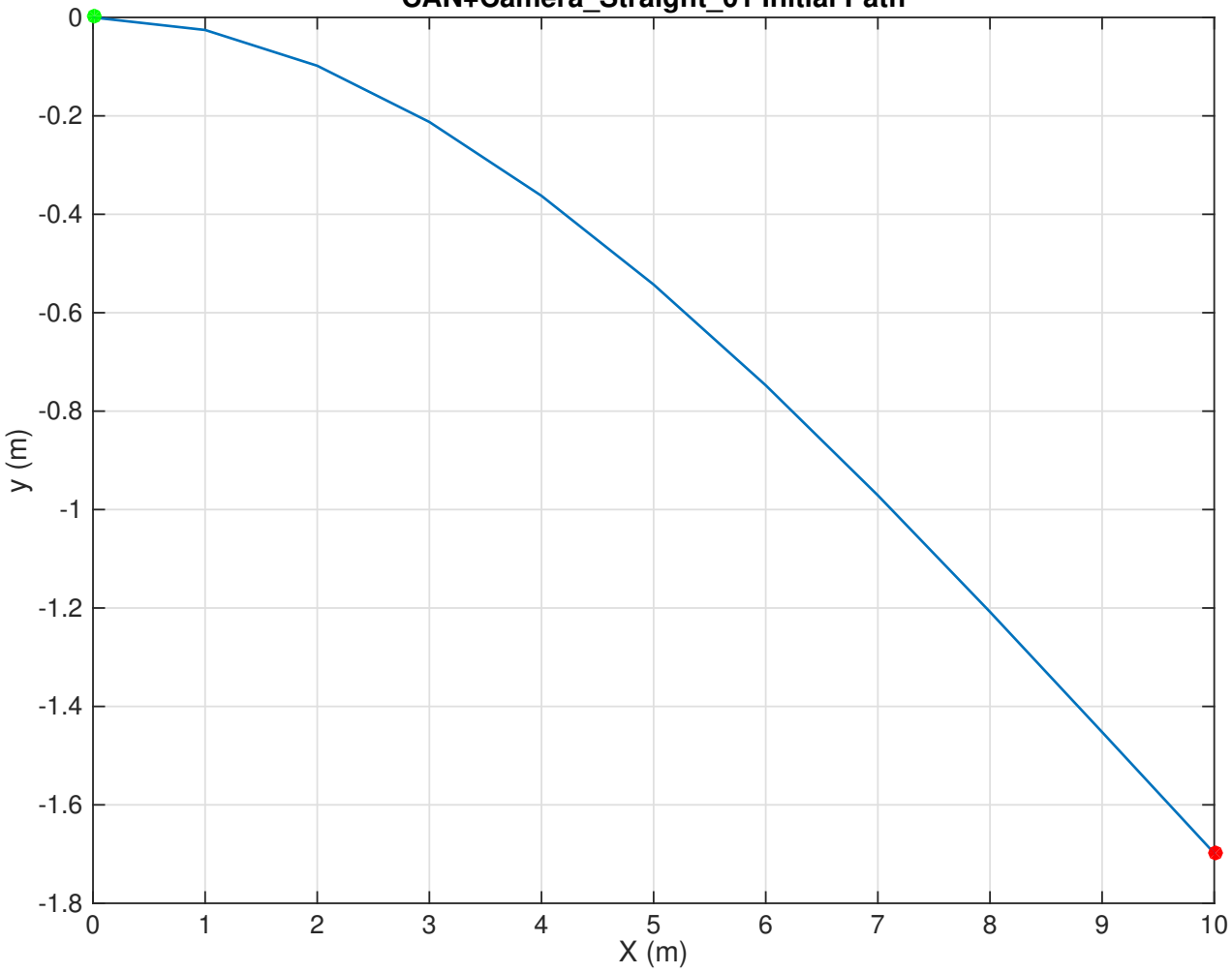
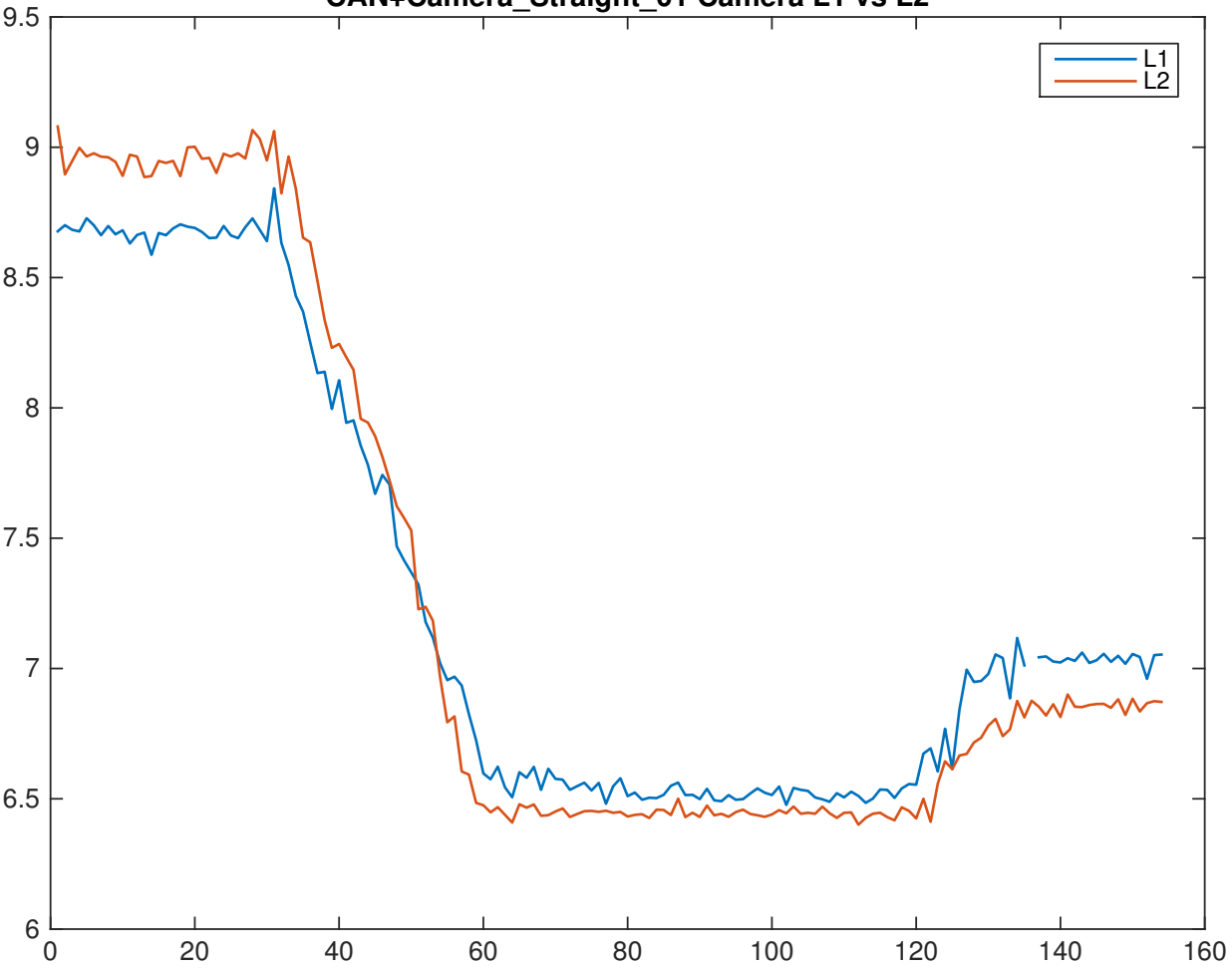


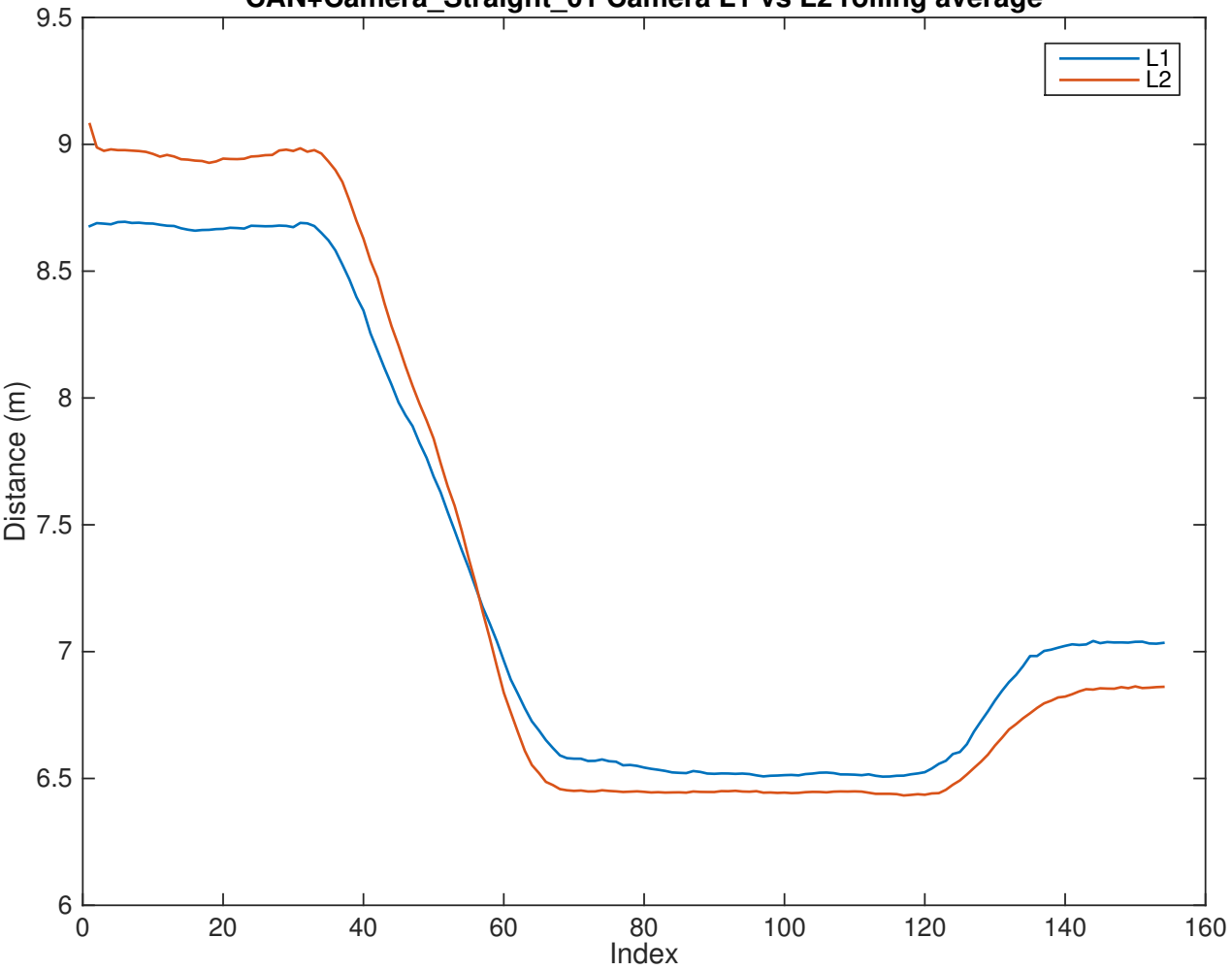
CAN+Camera_Straight_01 Initial Path



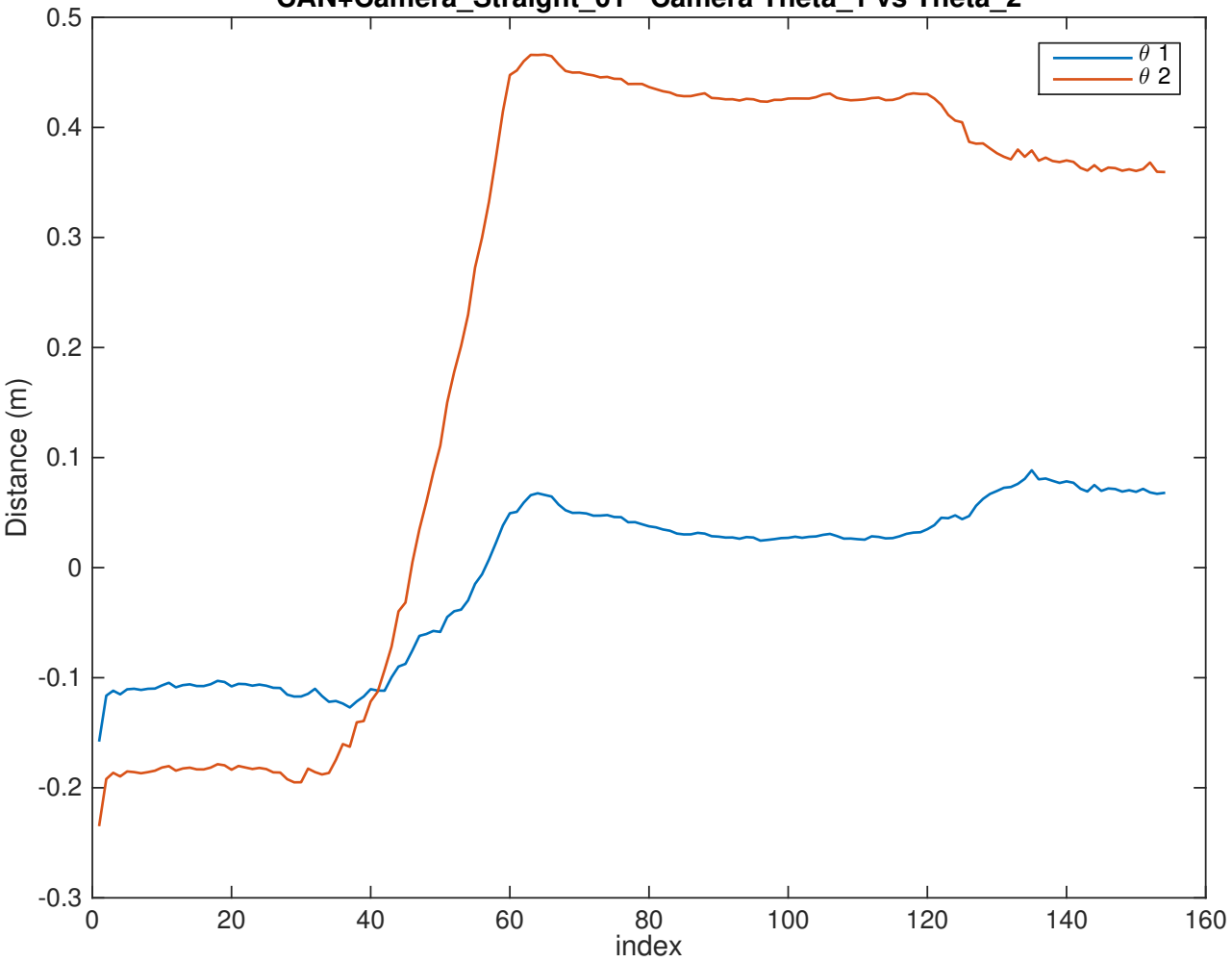
CAN+Camera_Straight_01 Camera L1 vs L2



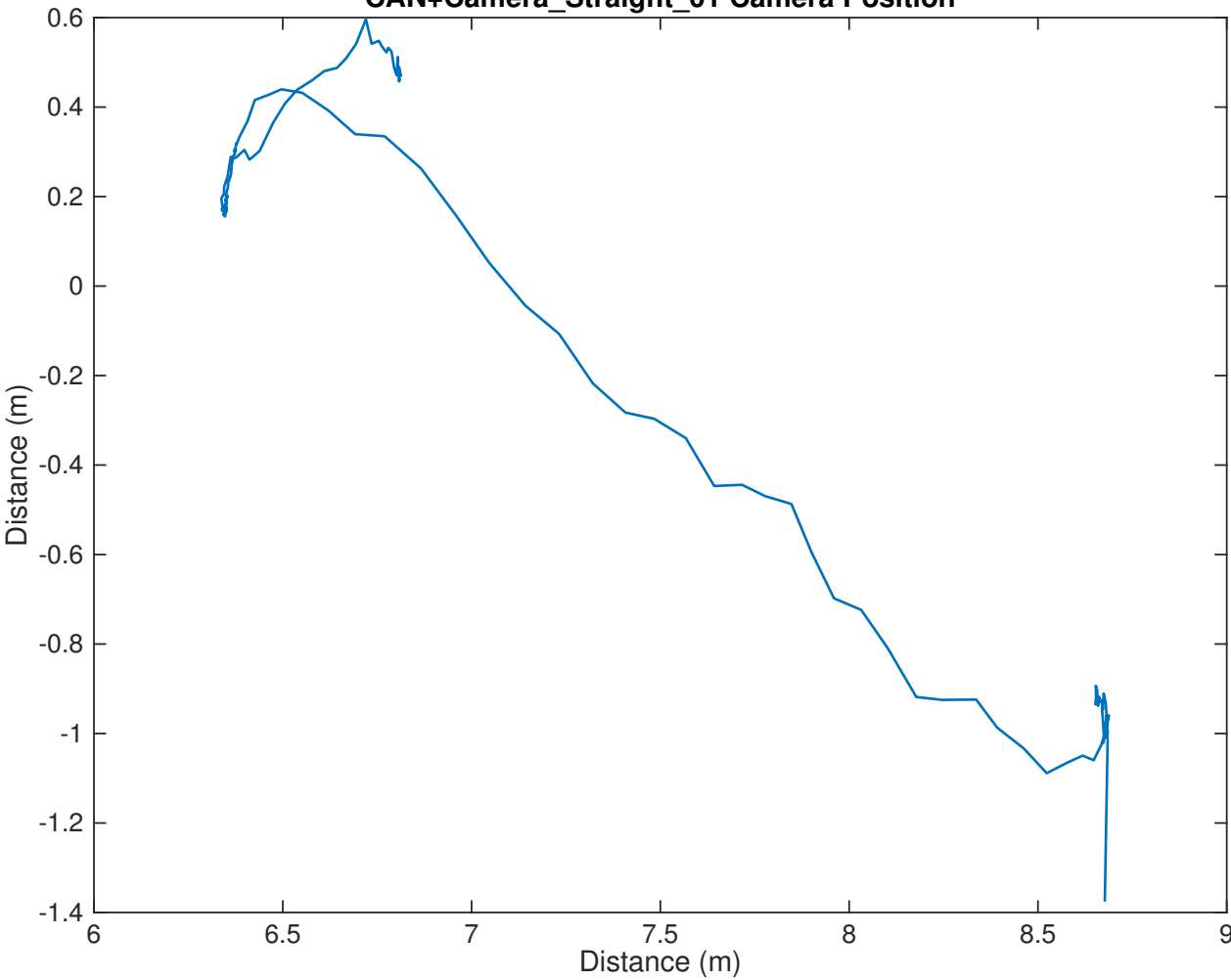
CAN+Camera_Straight_01 Camera L1 vs L2 rolling average



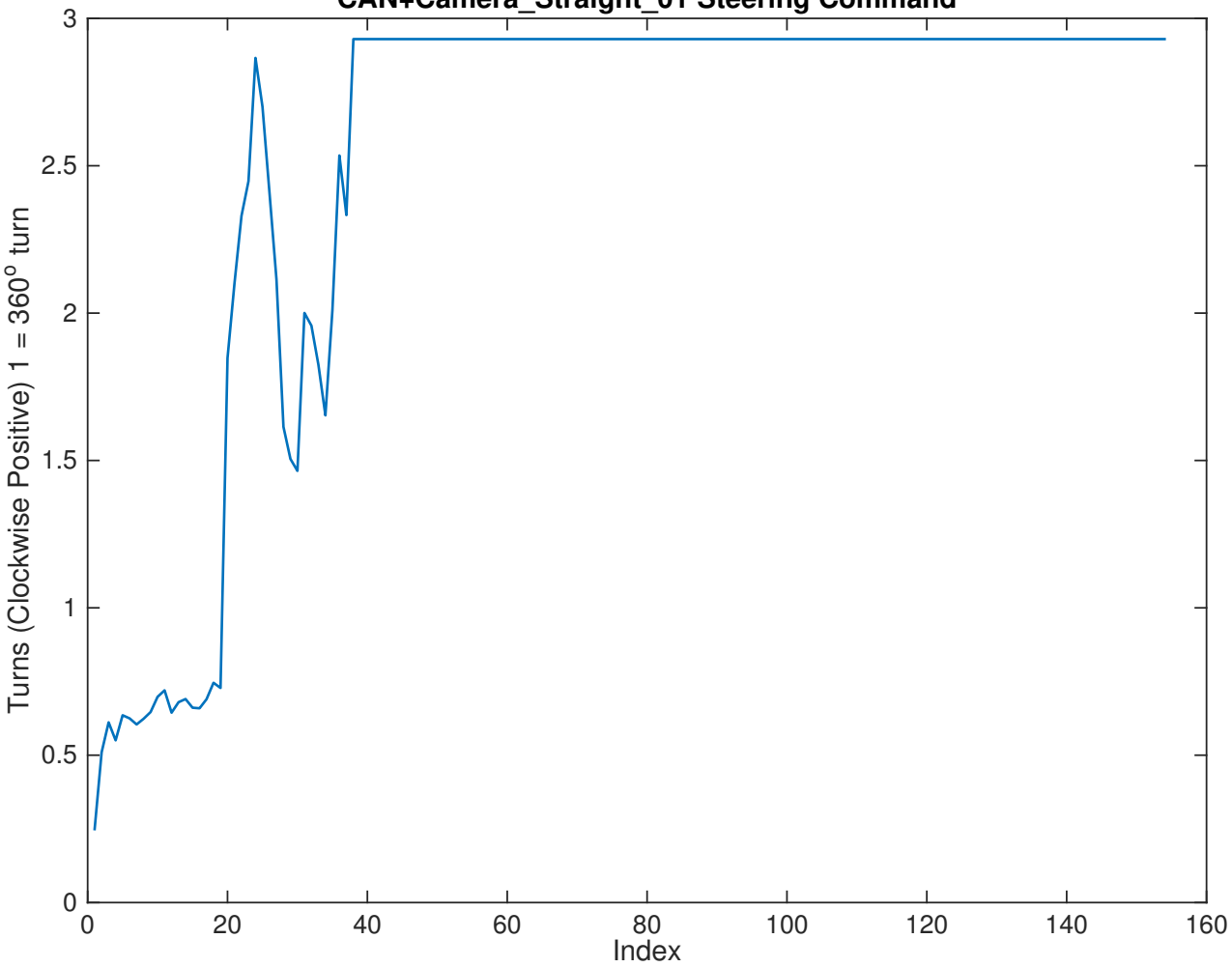
CAN+Camera_Straight_01 Camera Theta_1 vs Theta_2



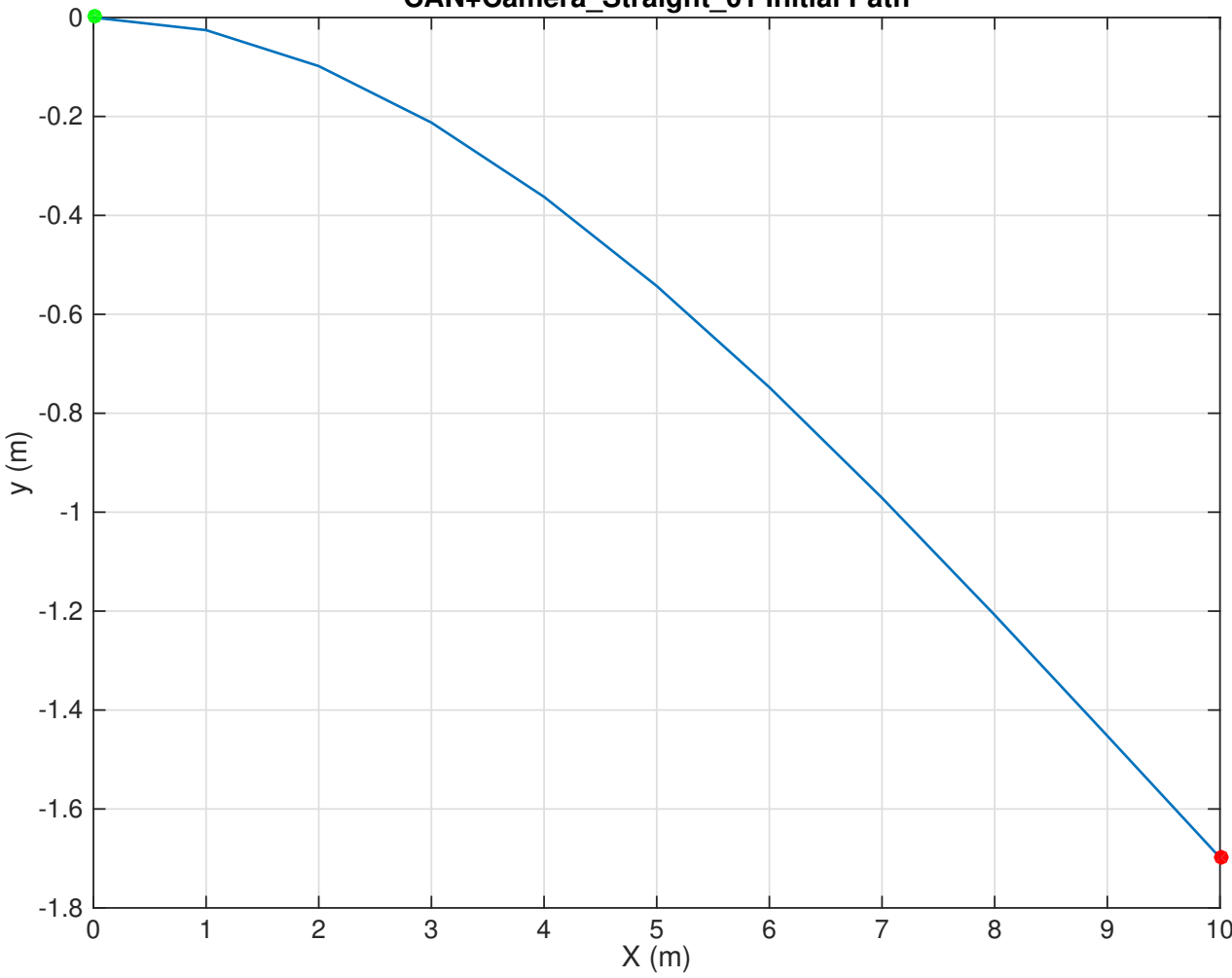
CAN+Camera_Straight_01 Camera Position



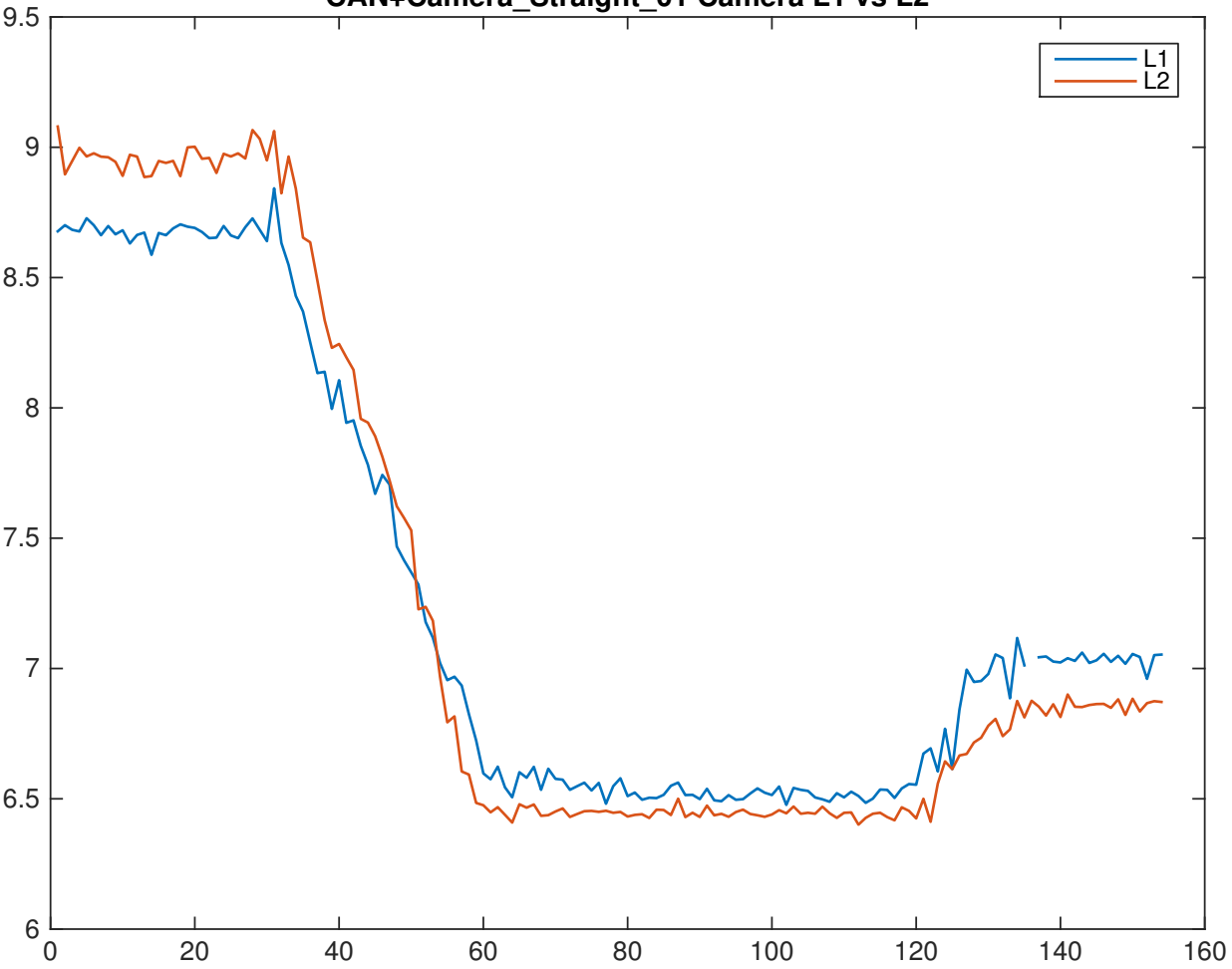
CAN+Camera_Straight_01 Steering Command



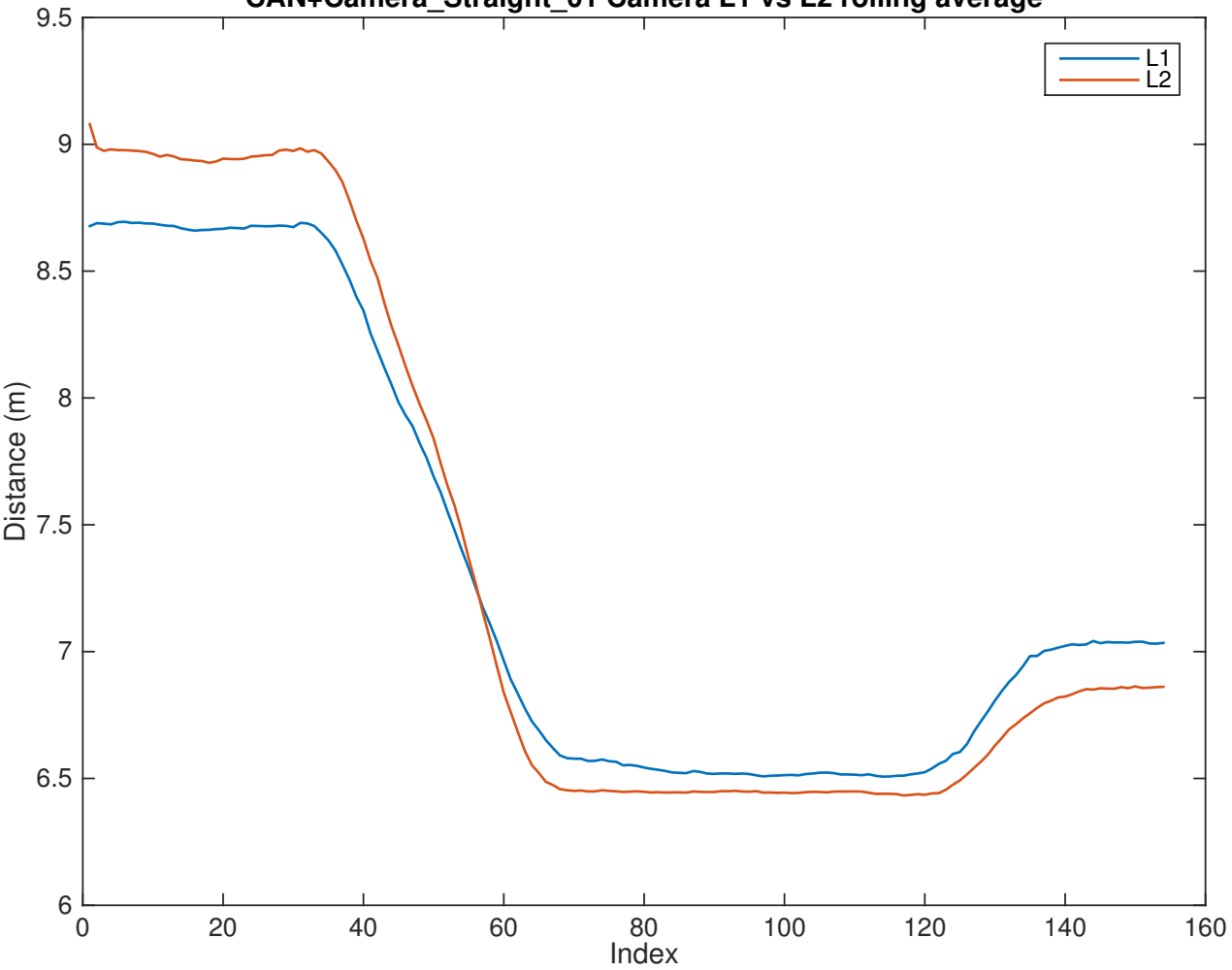
CAN+Camera_Straight_01 Initial Path



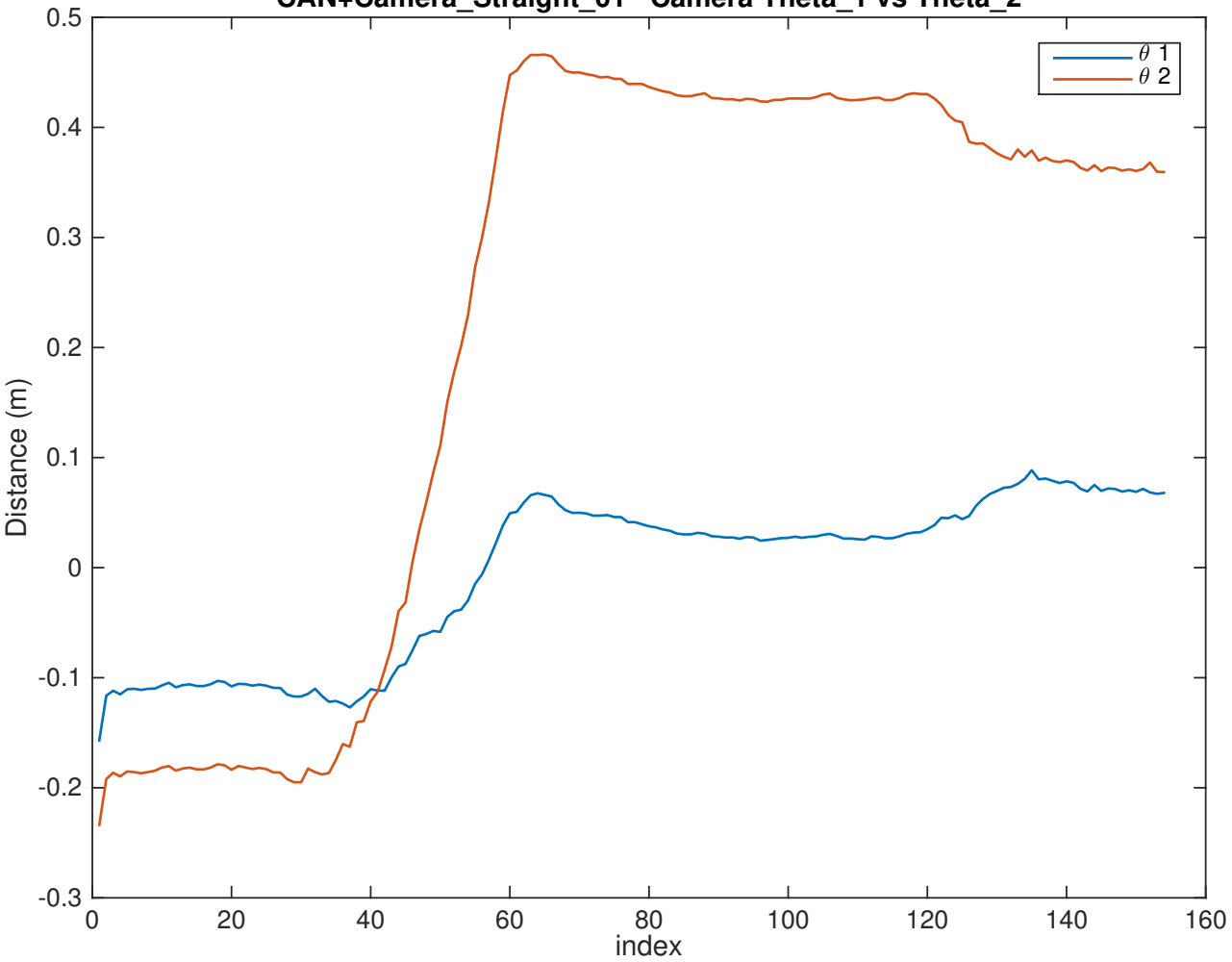
CAN+Camera_Straight_01 Camera L1 vs L2



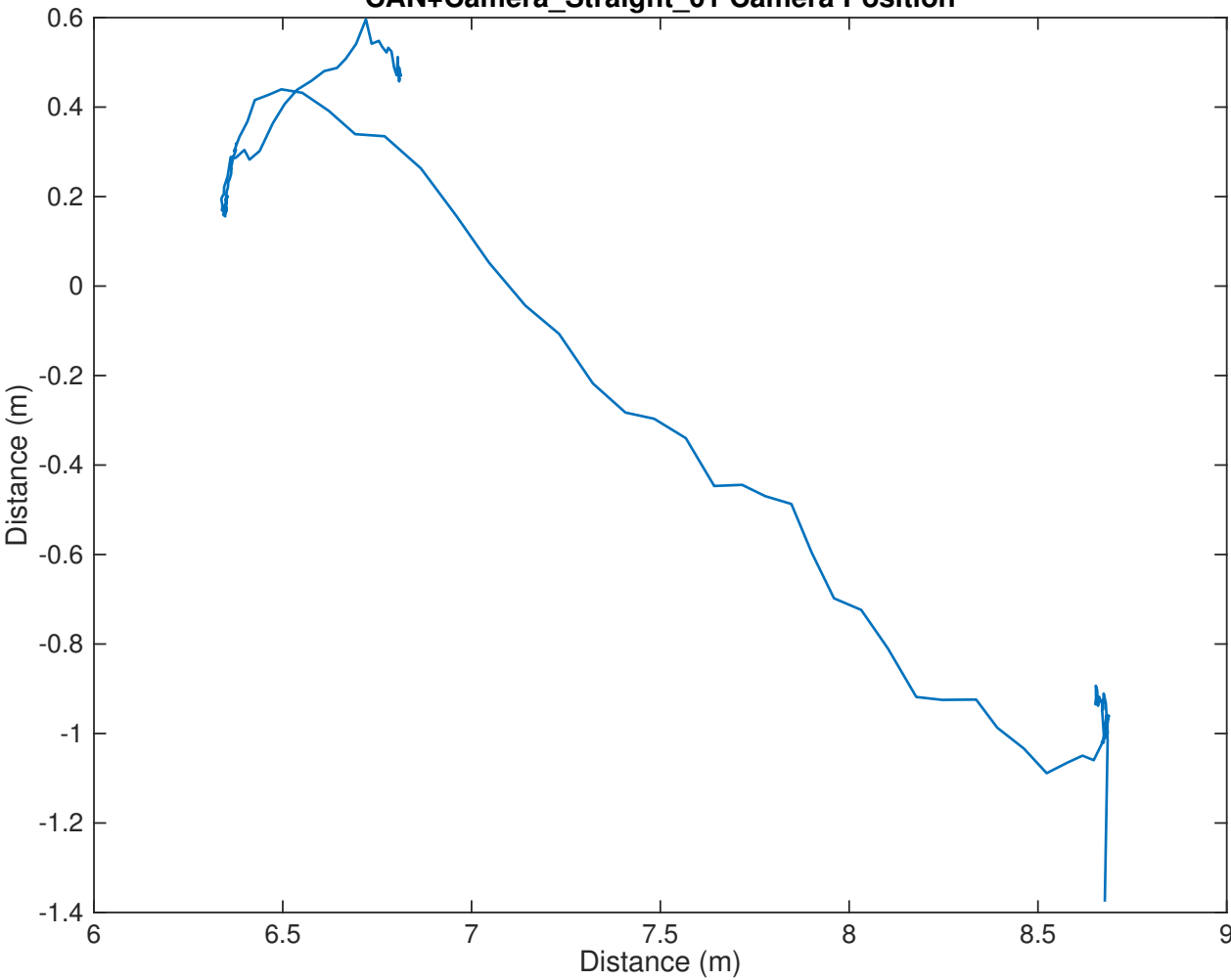
CAN+Camera_Straight_01 Camera L1 vs L2 rolling average



CAN+Camera_Straight_01 Camera Theta_1 vs Theta_2



CAN+Camera_Straight_01 Camera Position



CAN+Camera_Straight_01 Steering Command

