

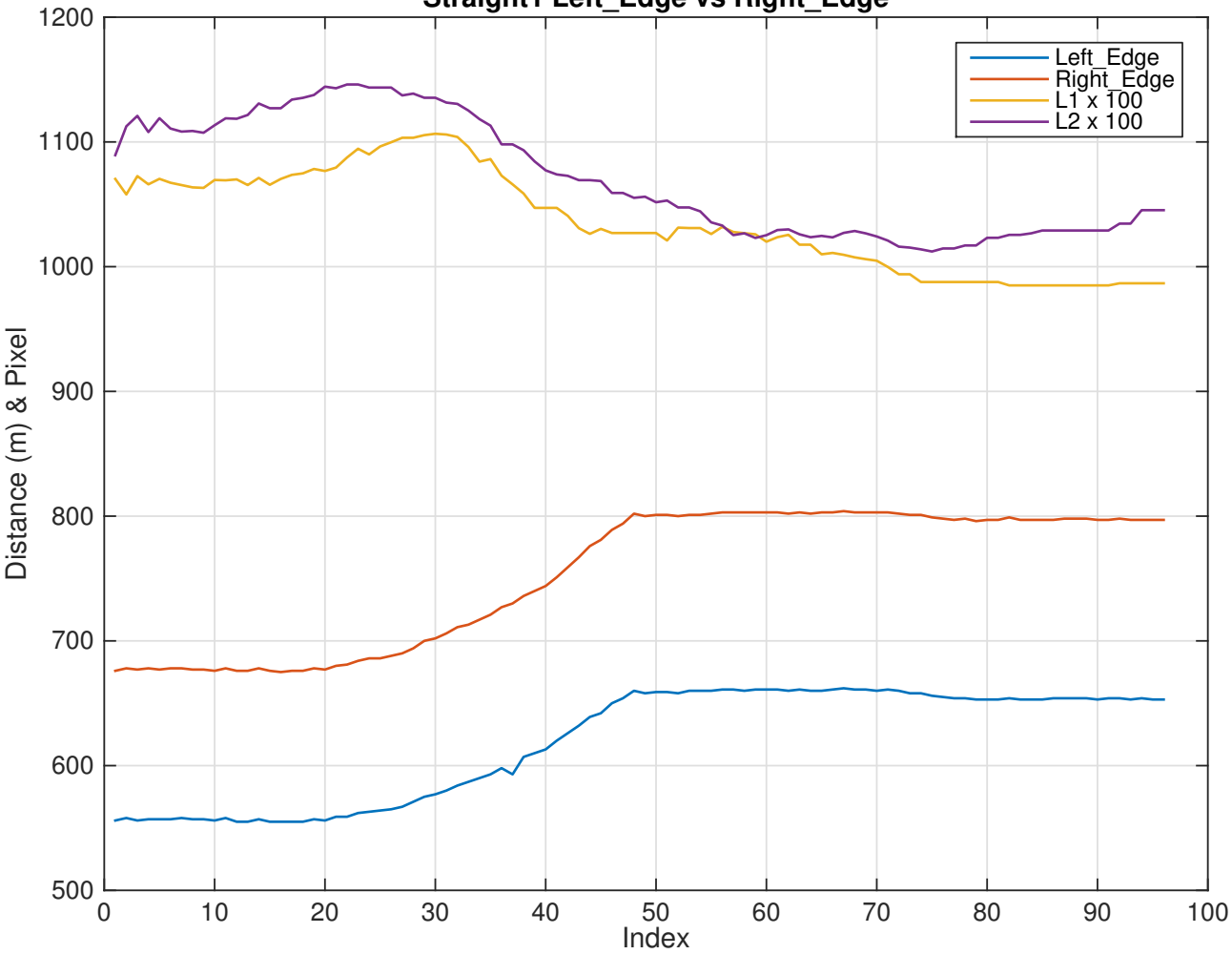
Number_Of_Unique_Paths

King_Pin_Detected

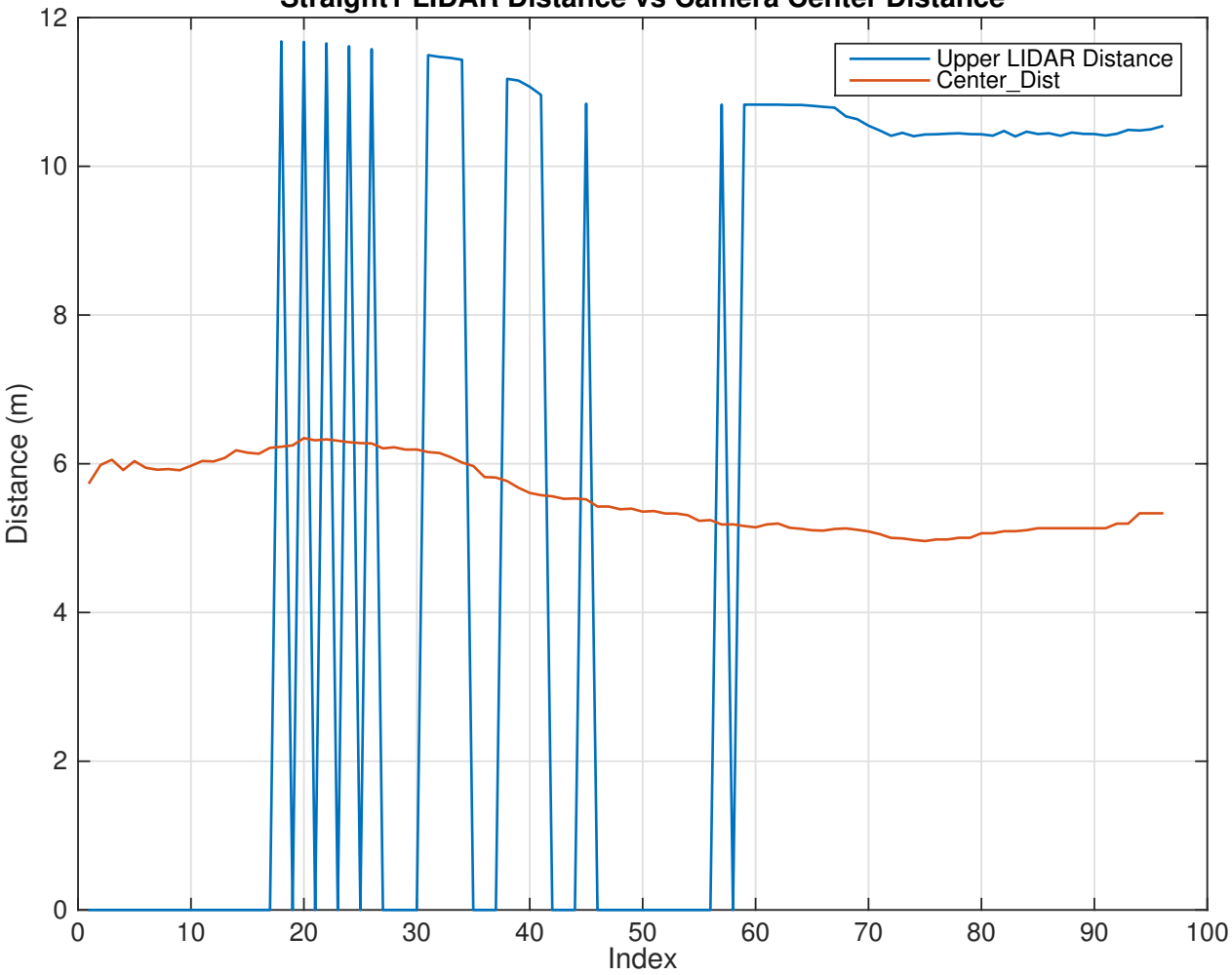
2

false

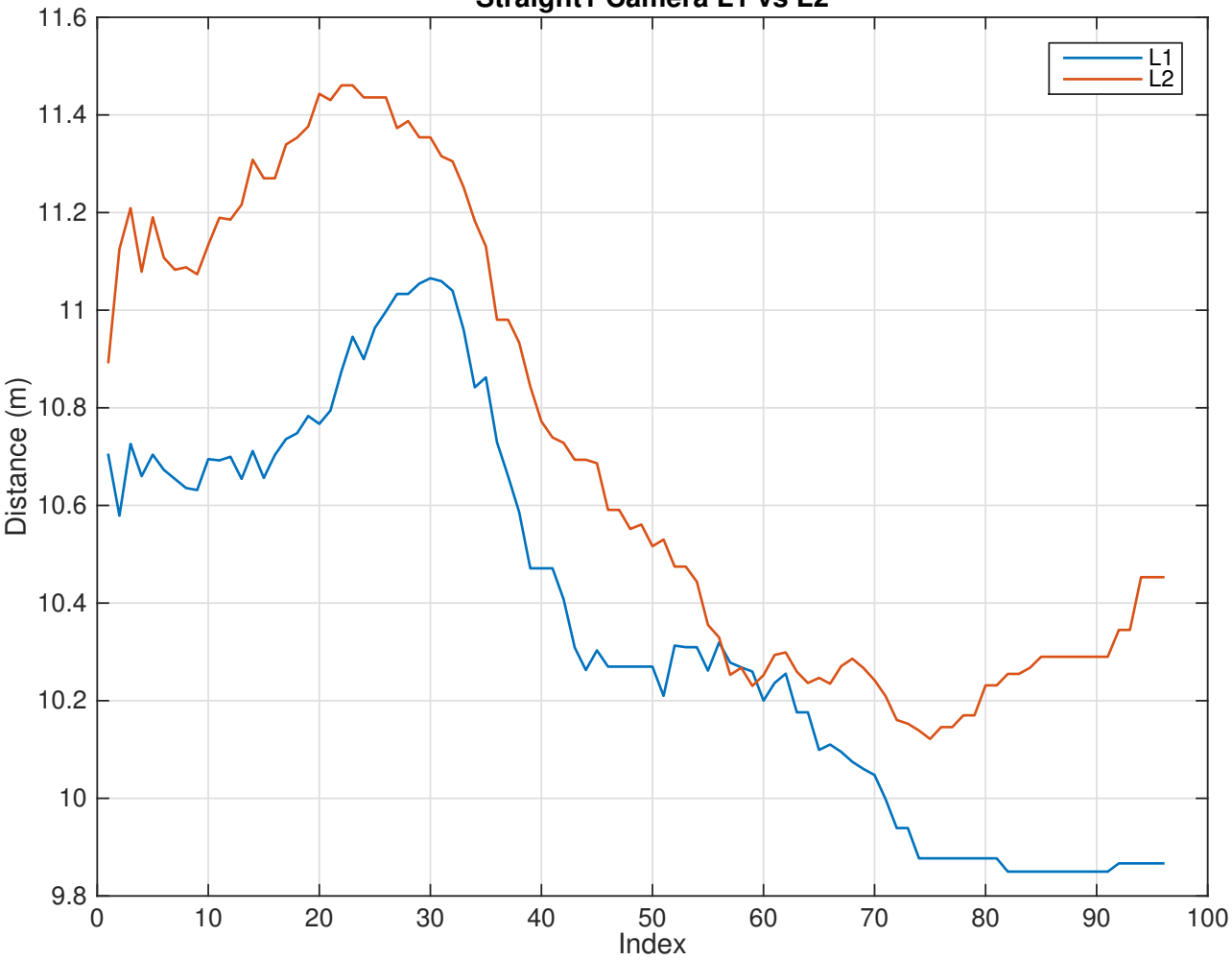
Straight1 Left_Edge vs Right_Edge



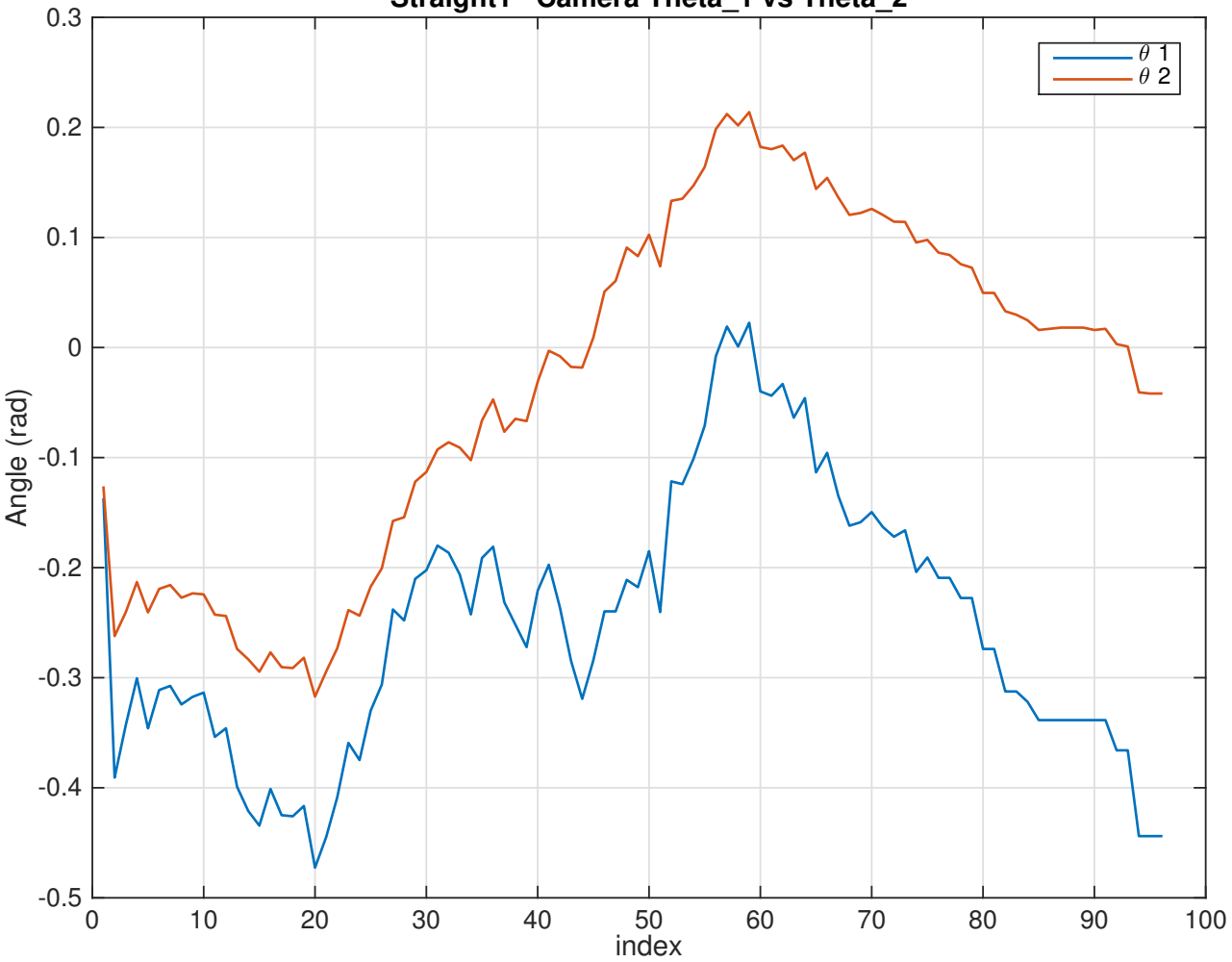
Straight1 LIDAR Distance vs Camera Center Distance



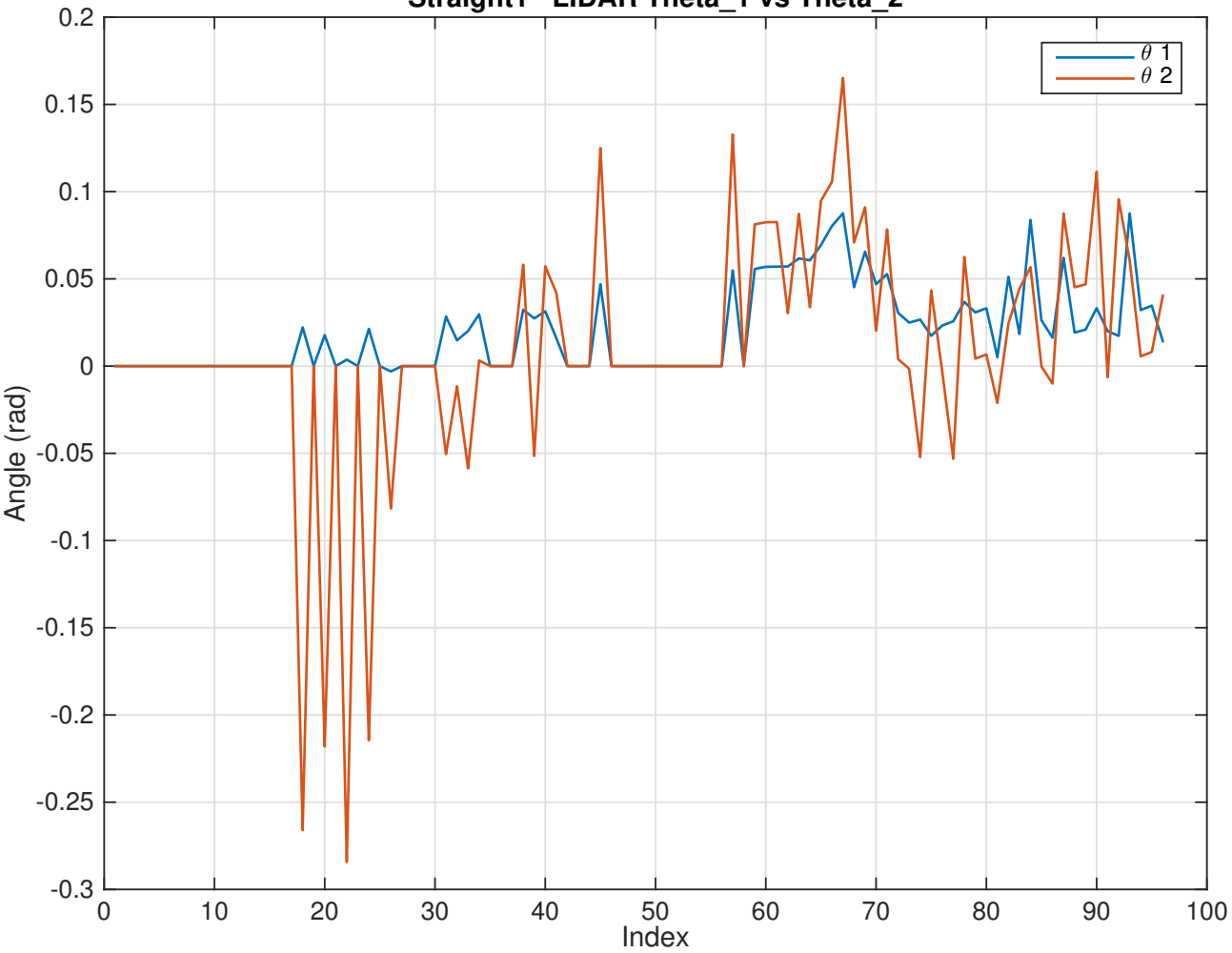
Straight1 Camera L1 vs L2



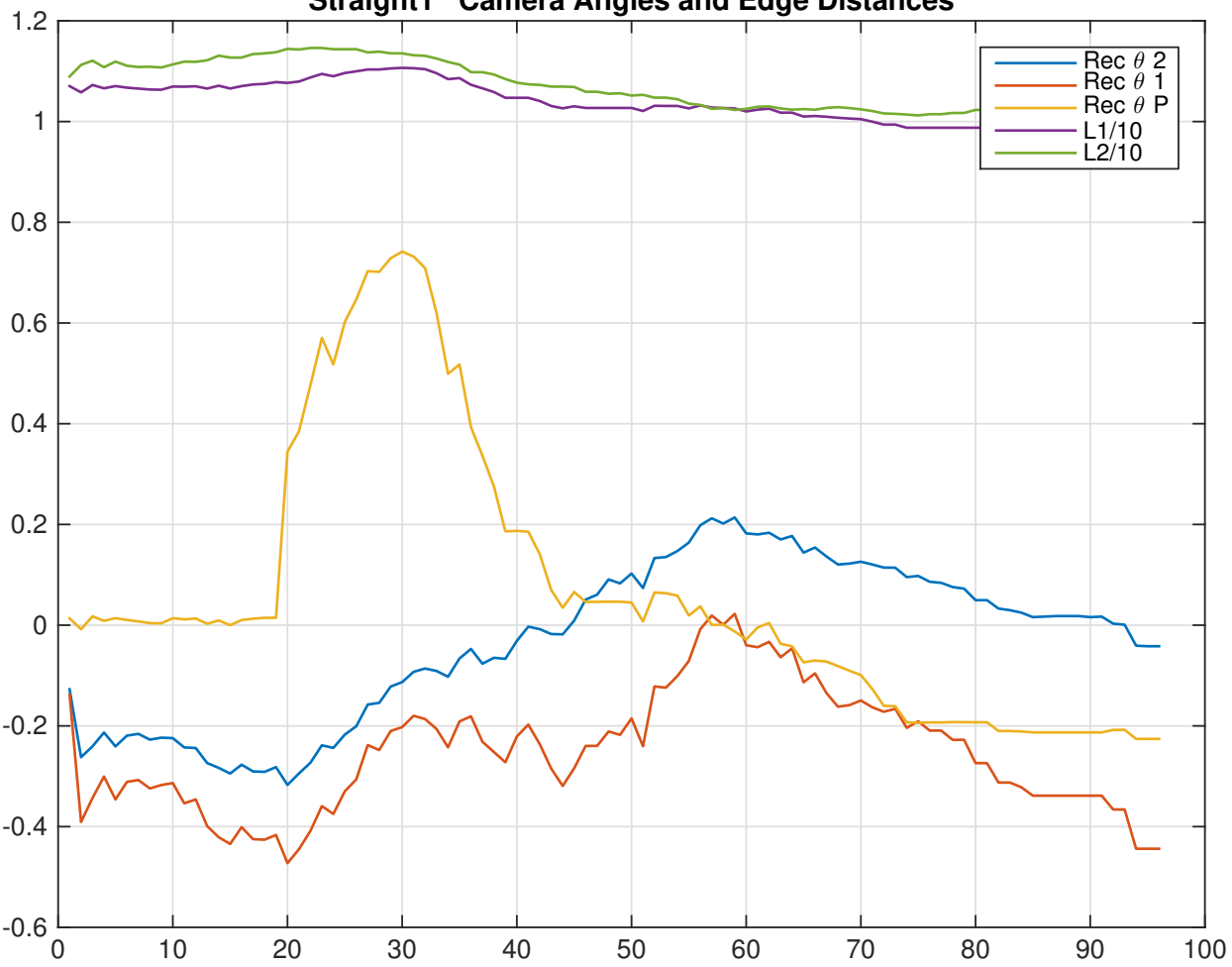
Straight1 Camera Theta_1 vs Theta_2

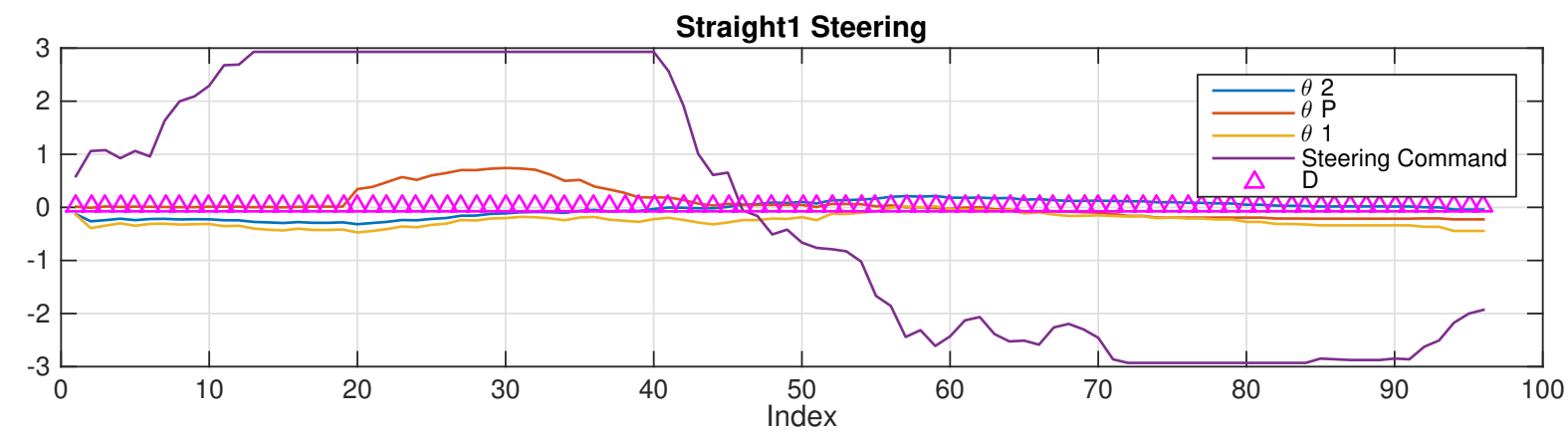
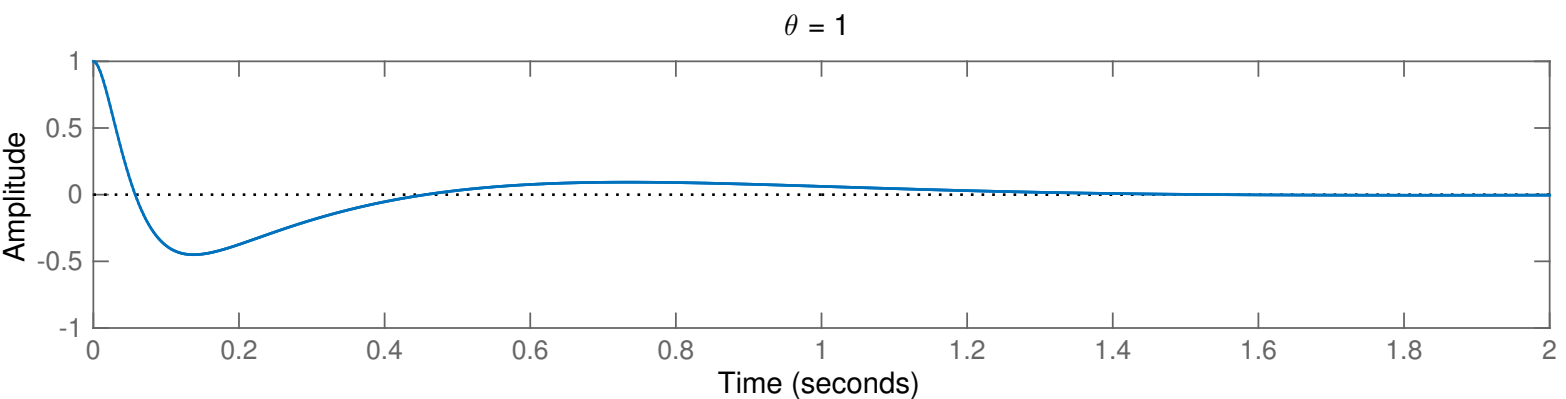
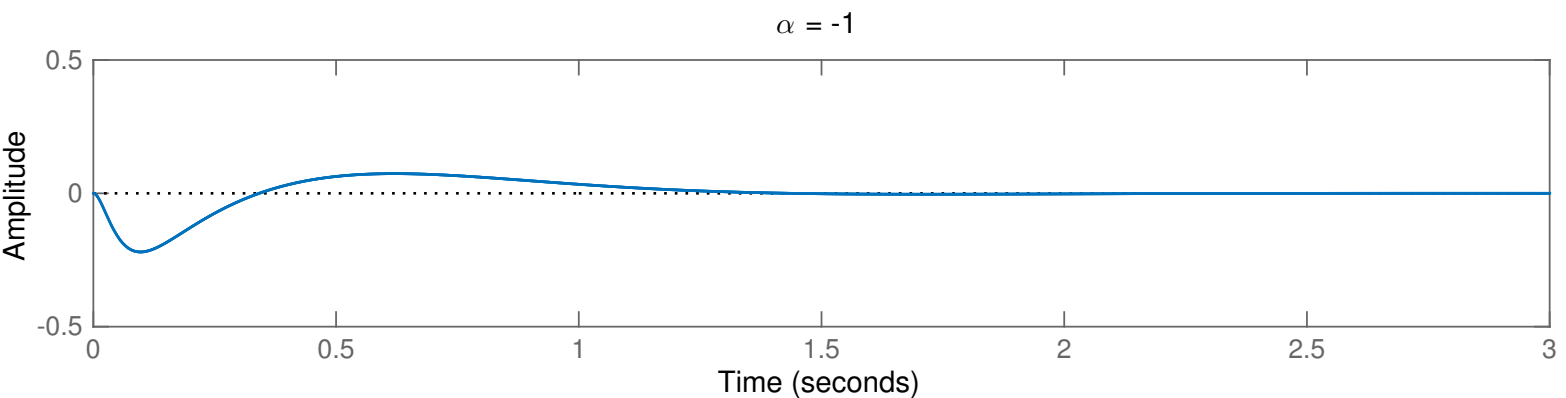
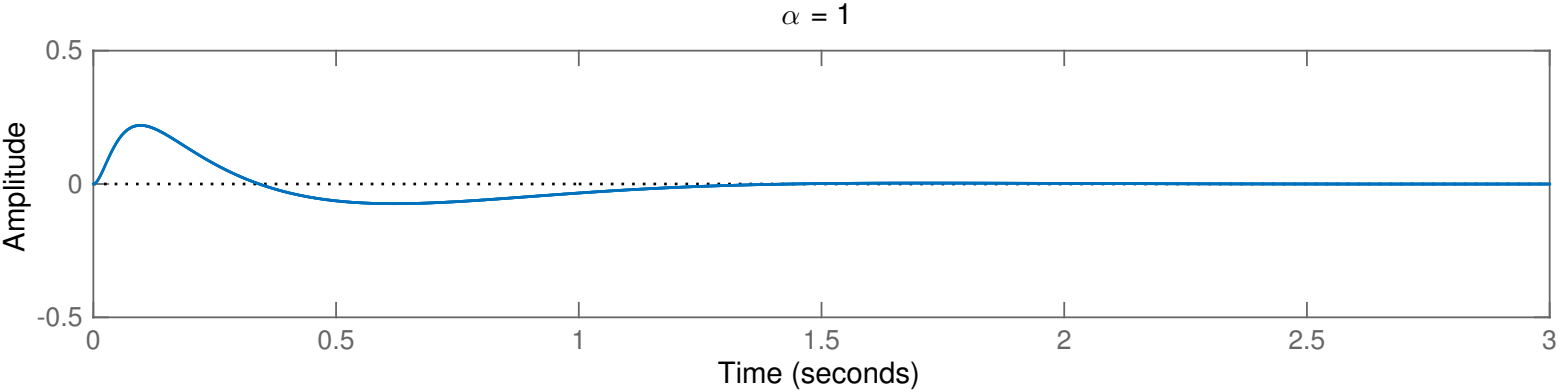


Straight1 LIDAR Theta_1 vs Theta_2

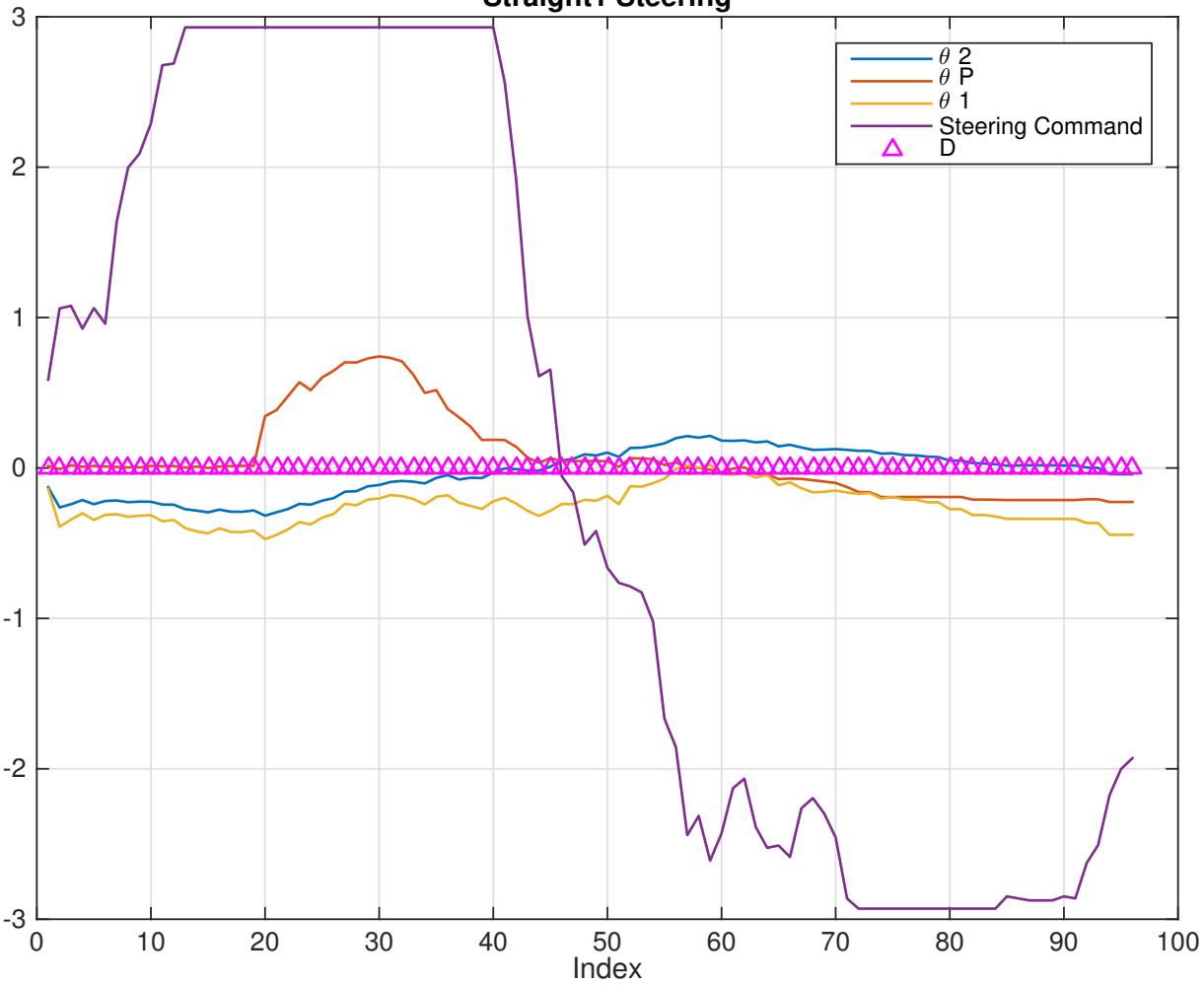


Straight1 Camera Angles and Edge Distances





Straight1 Steering



Straight1 All Paths

