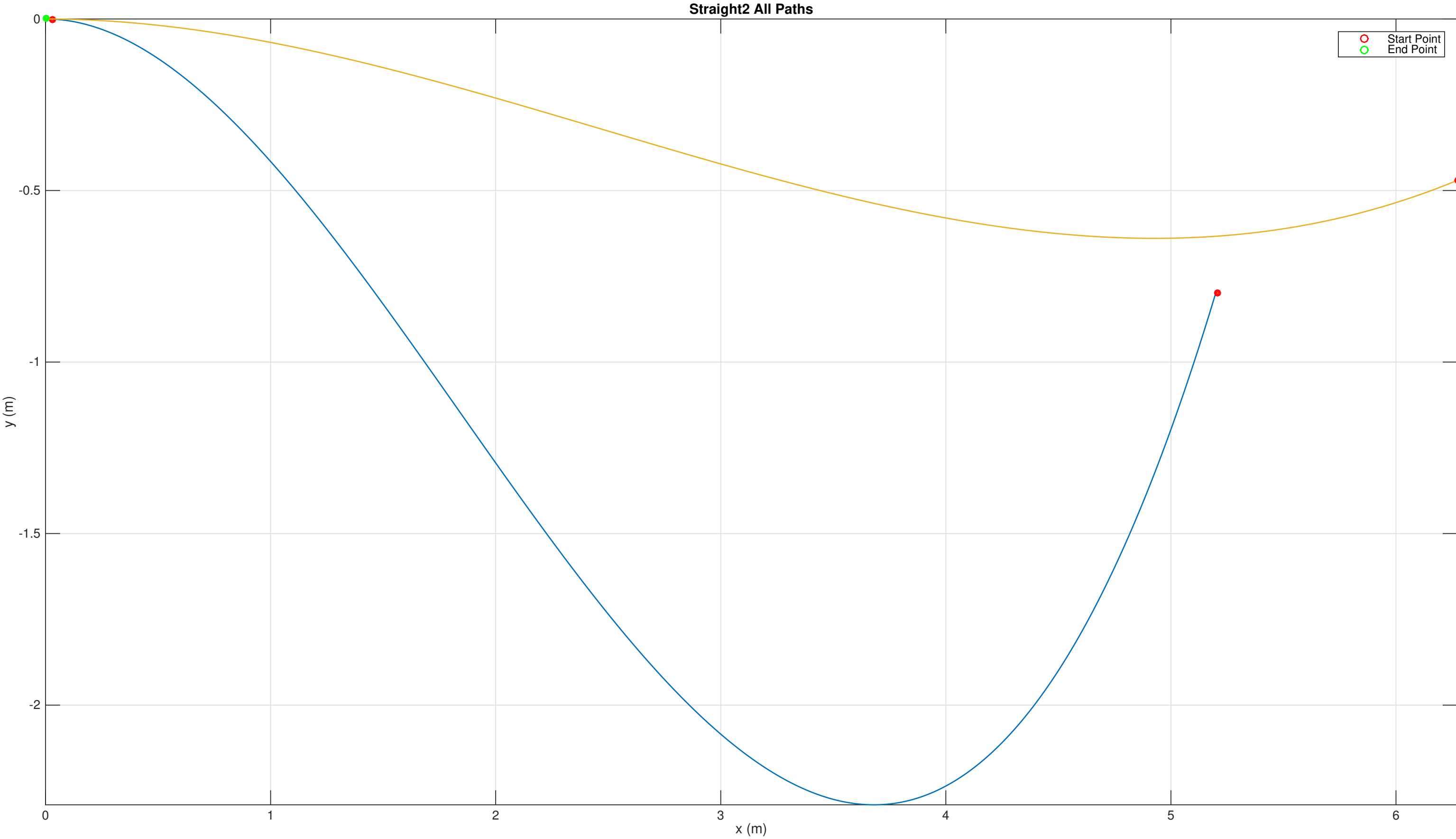


Straight2 All Paths



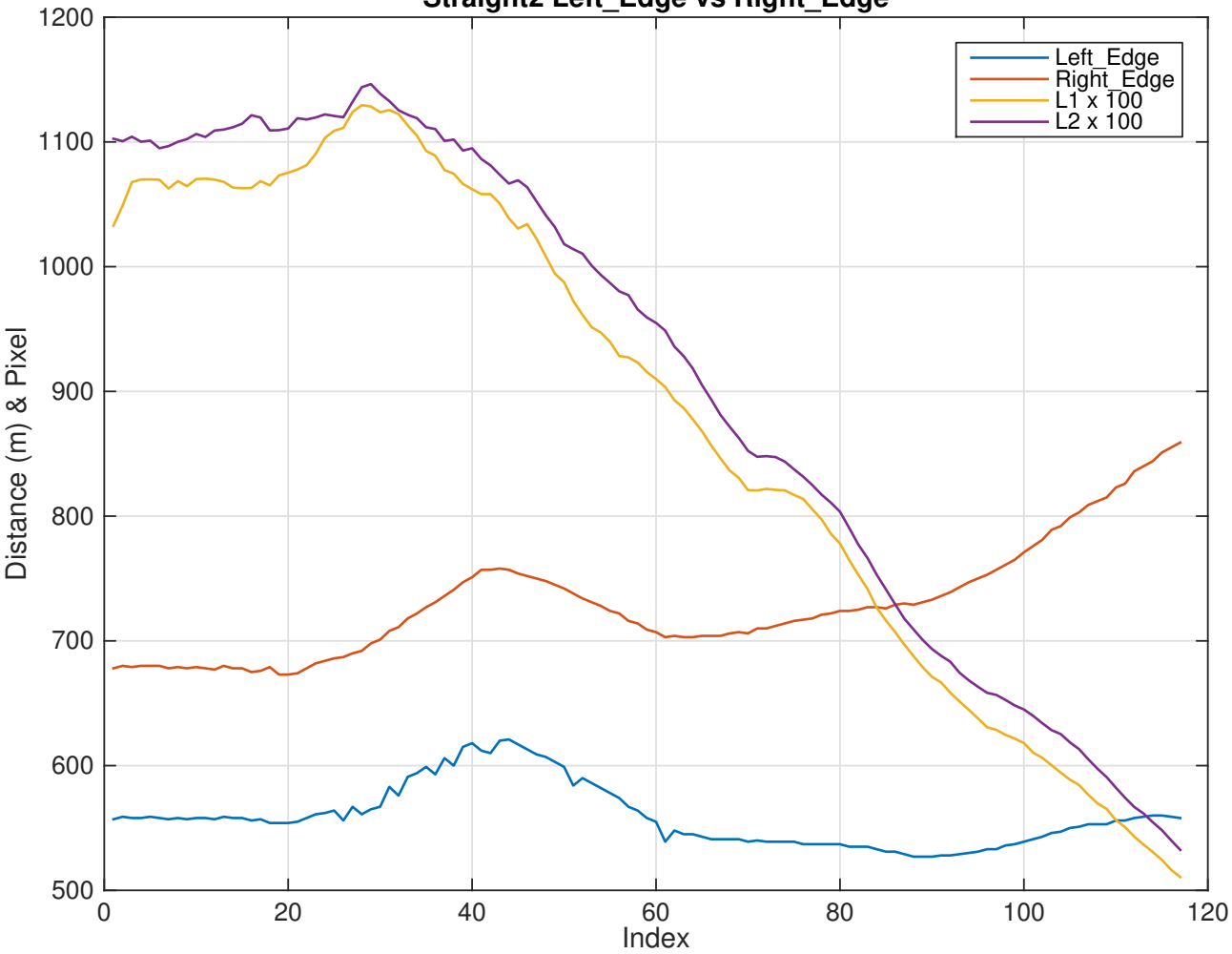
Number_Of_Unique_Paths

King_Pin_Detected

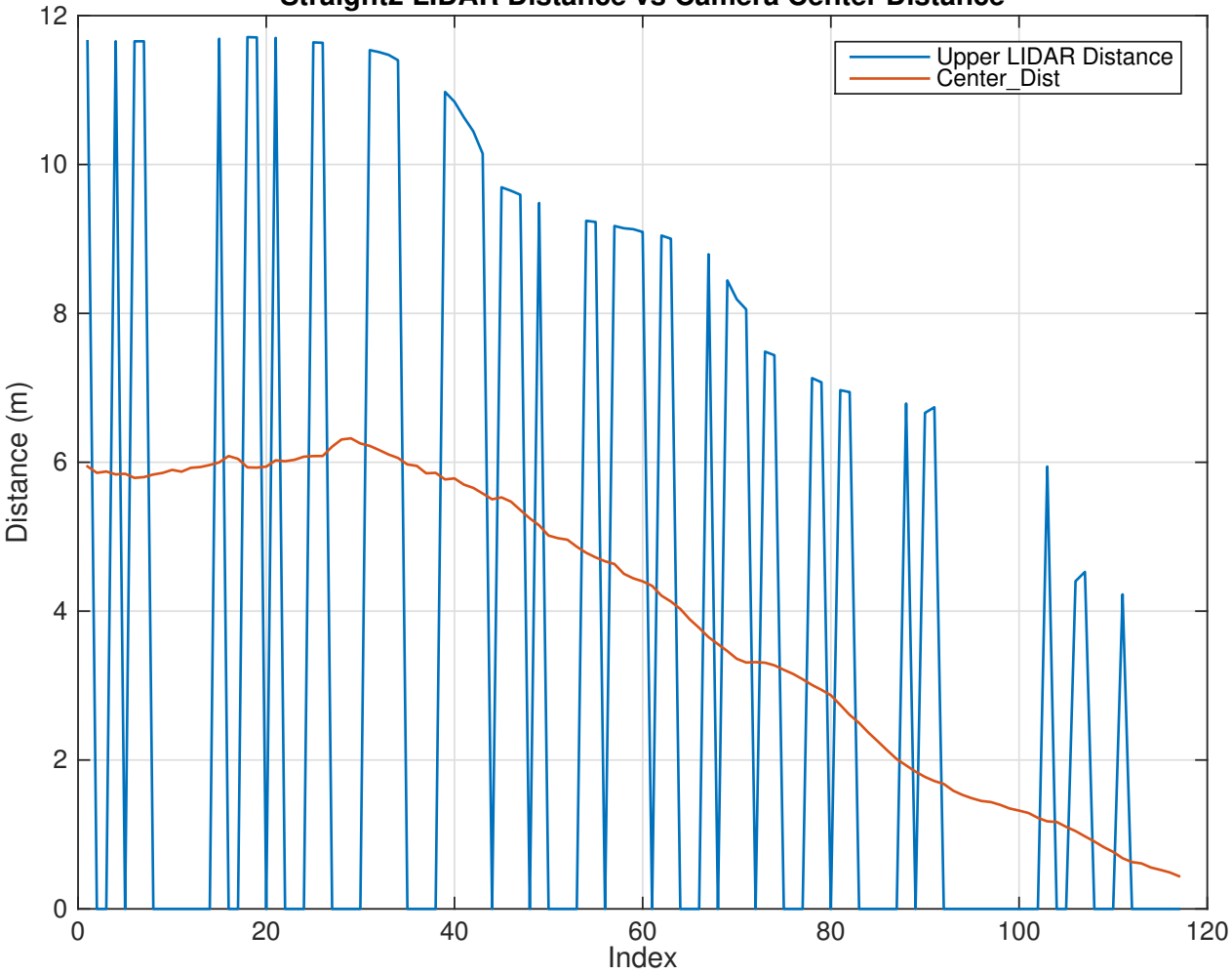
3

false

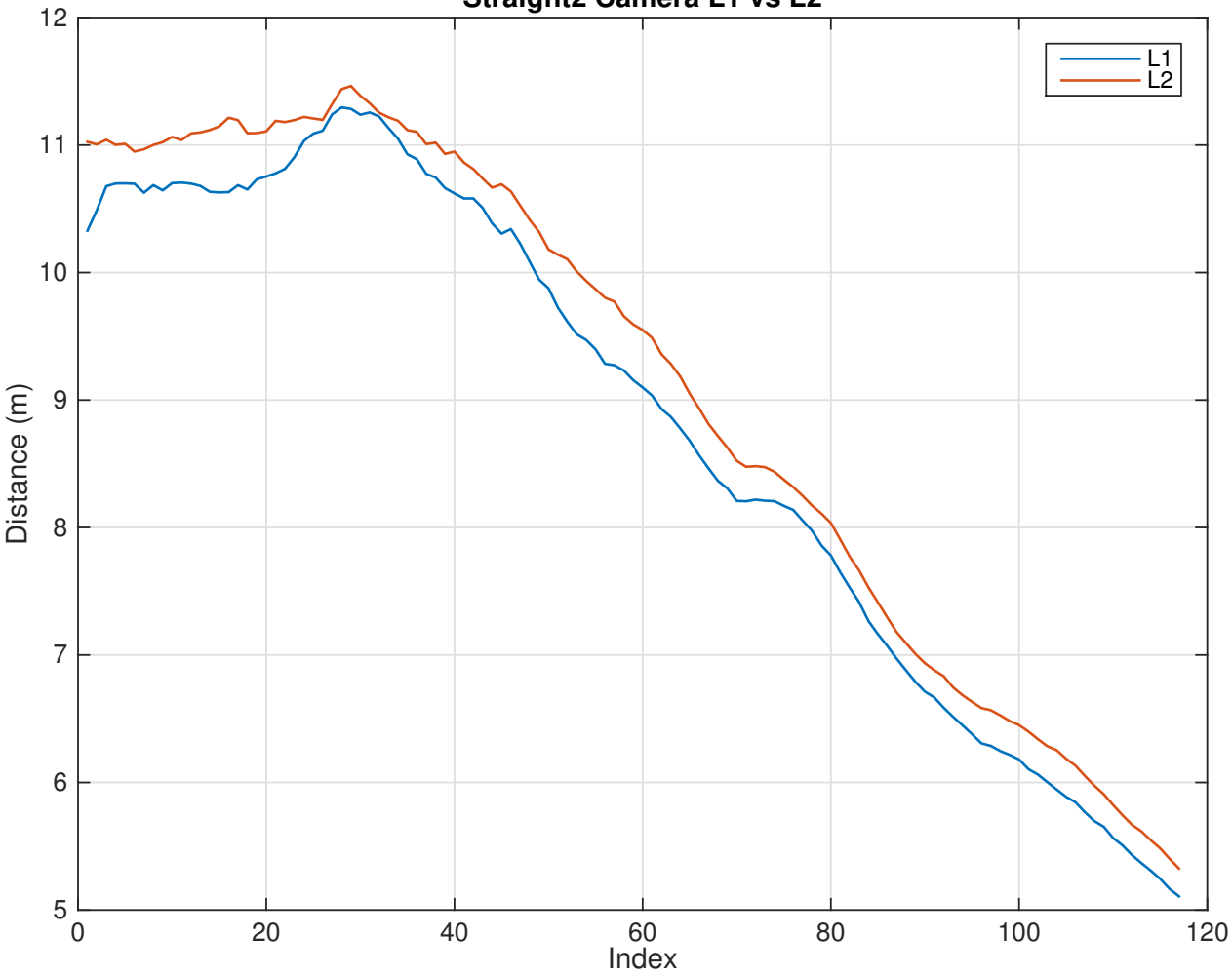
Straight2 Left_Edge vs Right_Edge



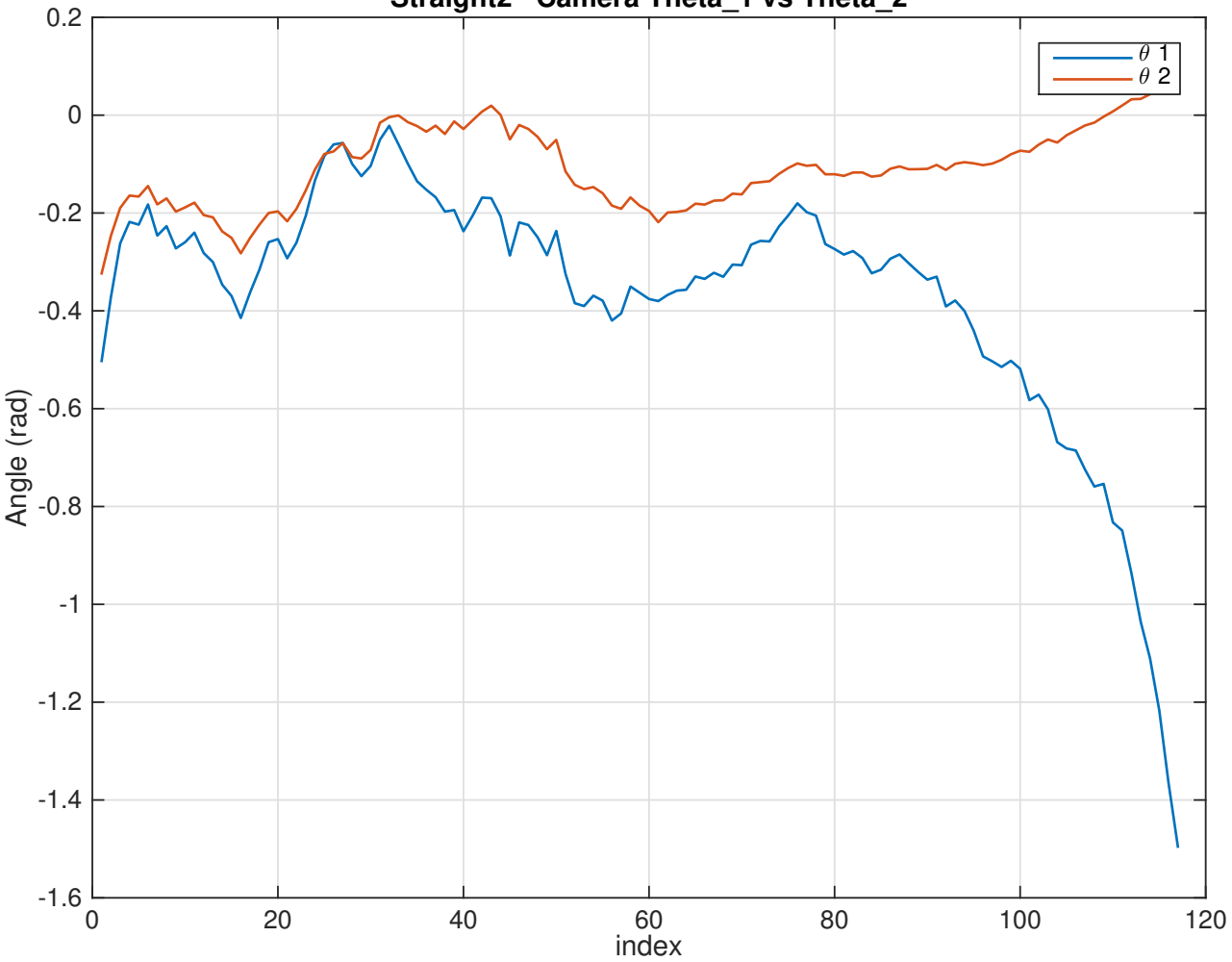
Straight2 LIDAR Distance vs Camera Center Distance



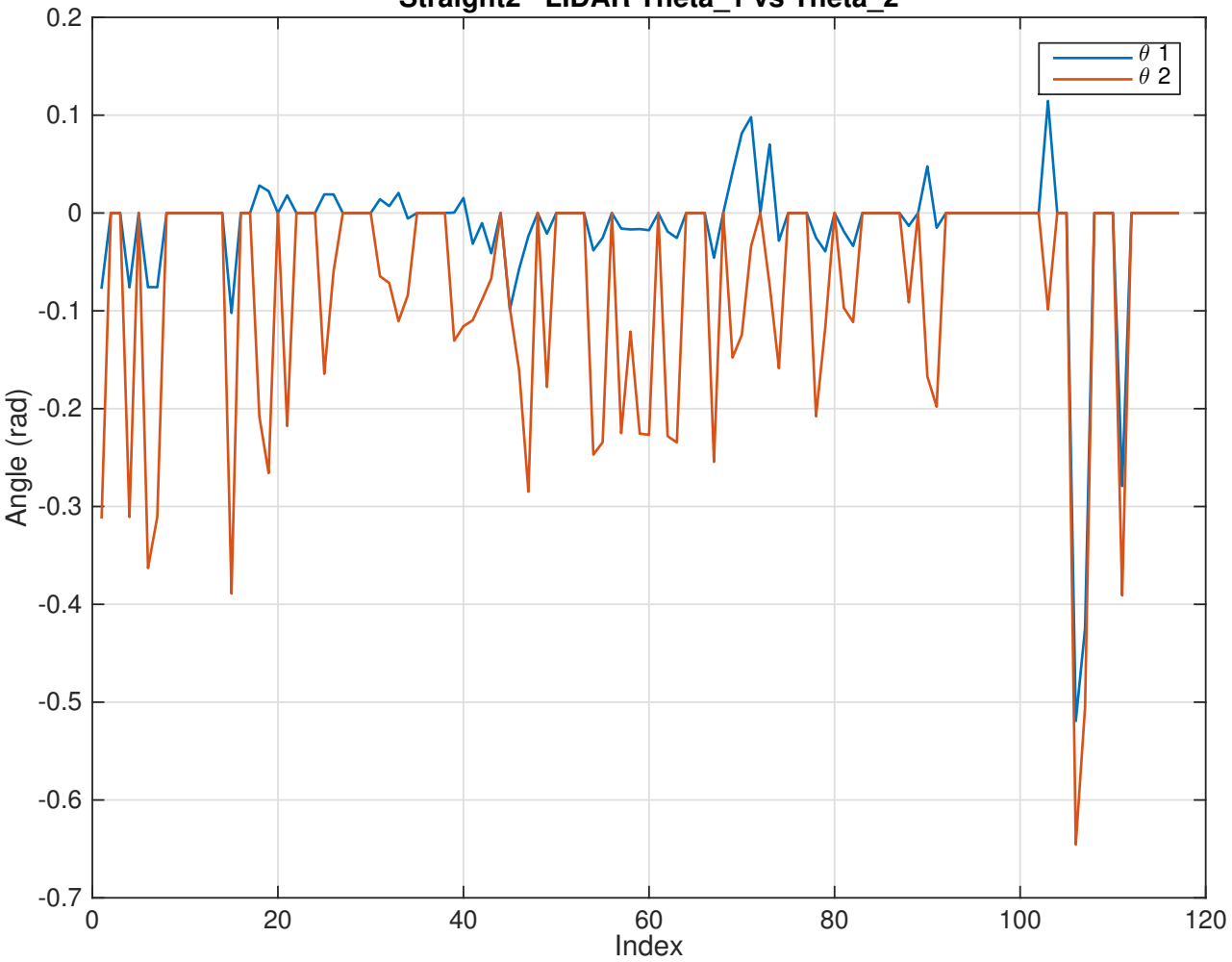
Straight2 Camera L1 vs L2



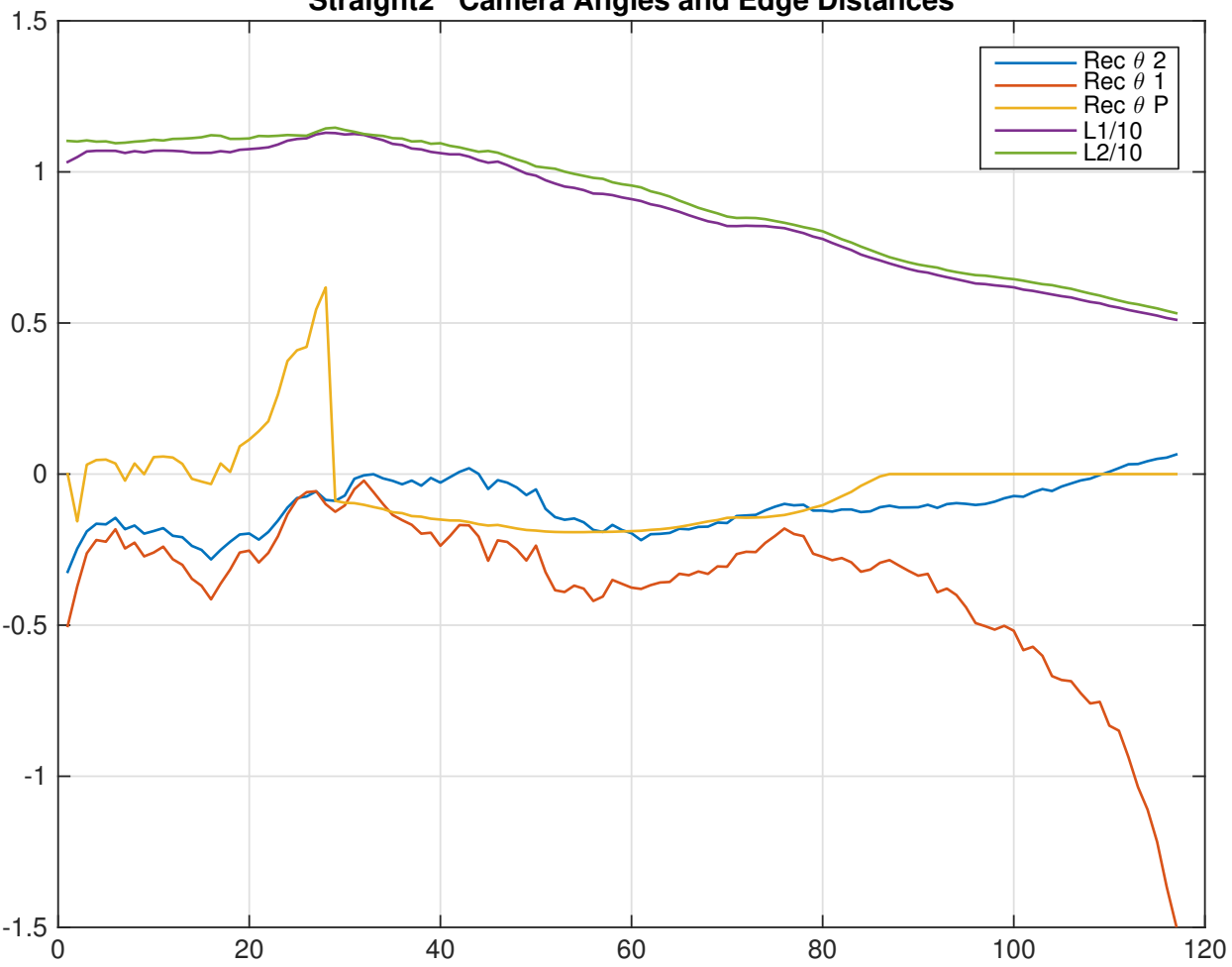
Straight2 Camera Theta_1 vs Theta_2



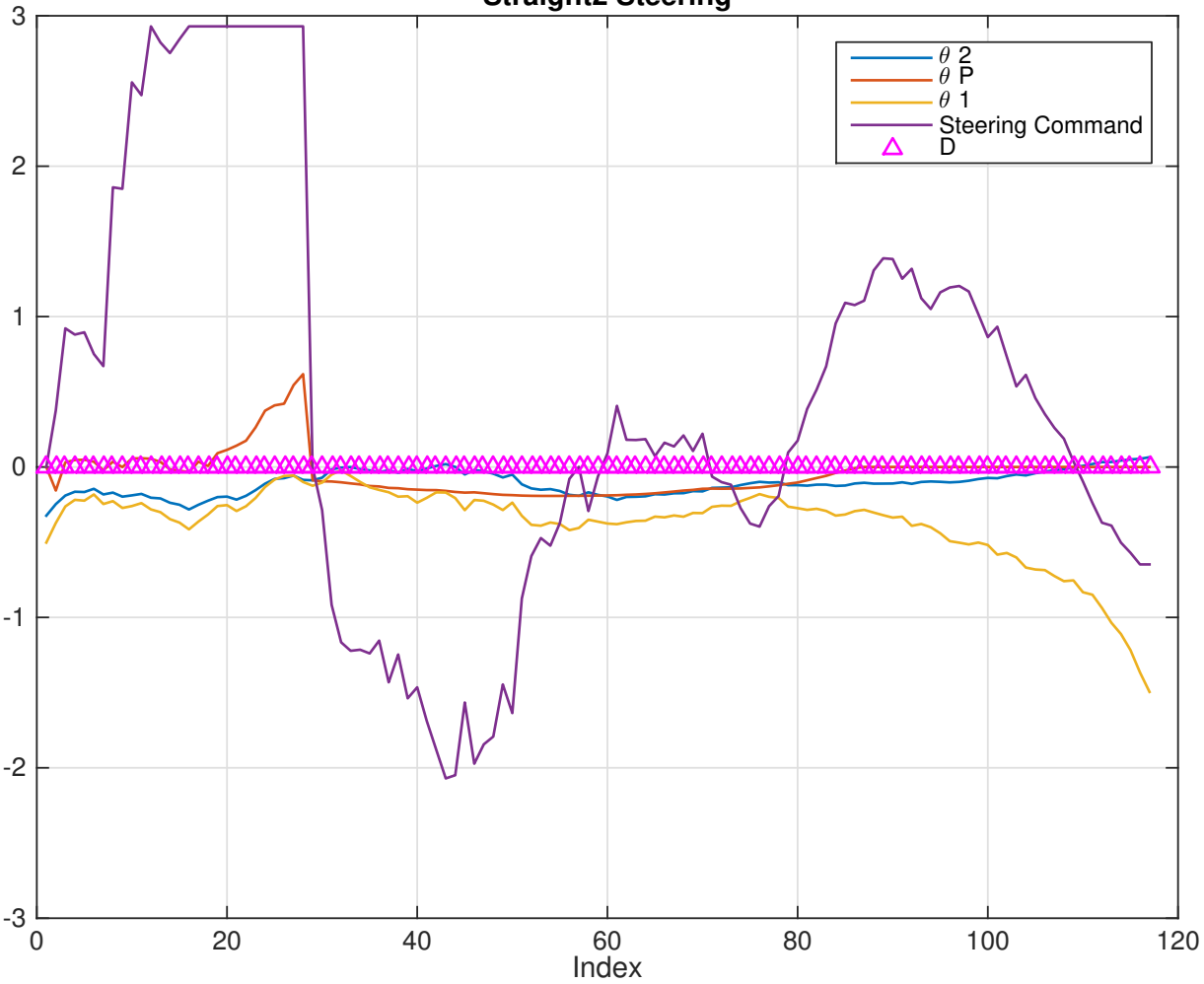
Straight2 LIDAR Theta_1 vs Theta_2



Straight2 Camera Angles and Edge Distances



Straight2 Steering



Straight2 Steering

