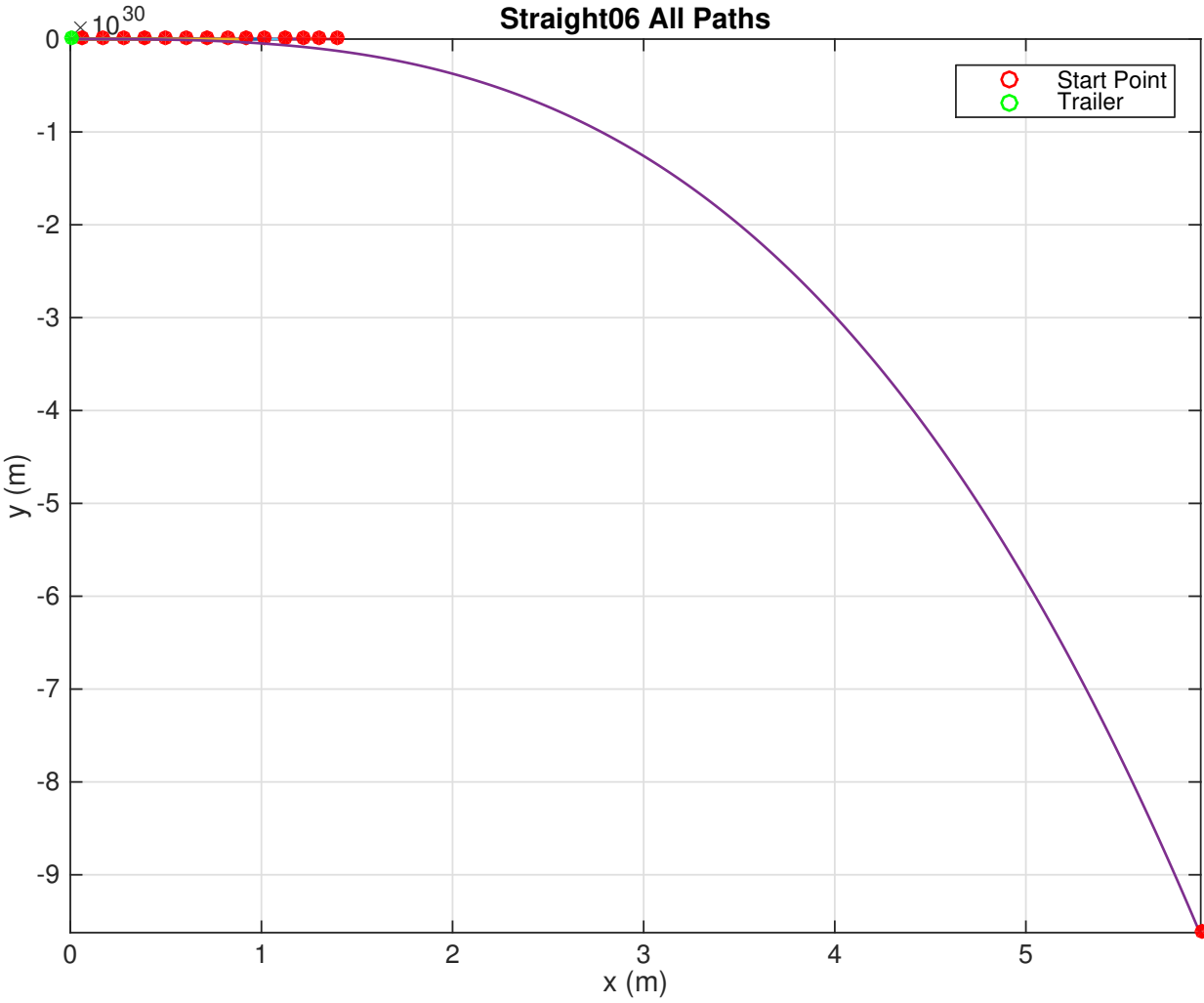


Straight06 All Paths



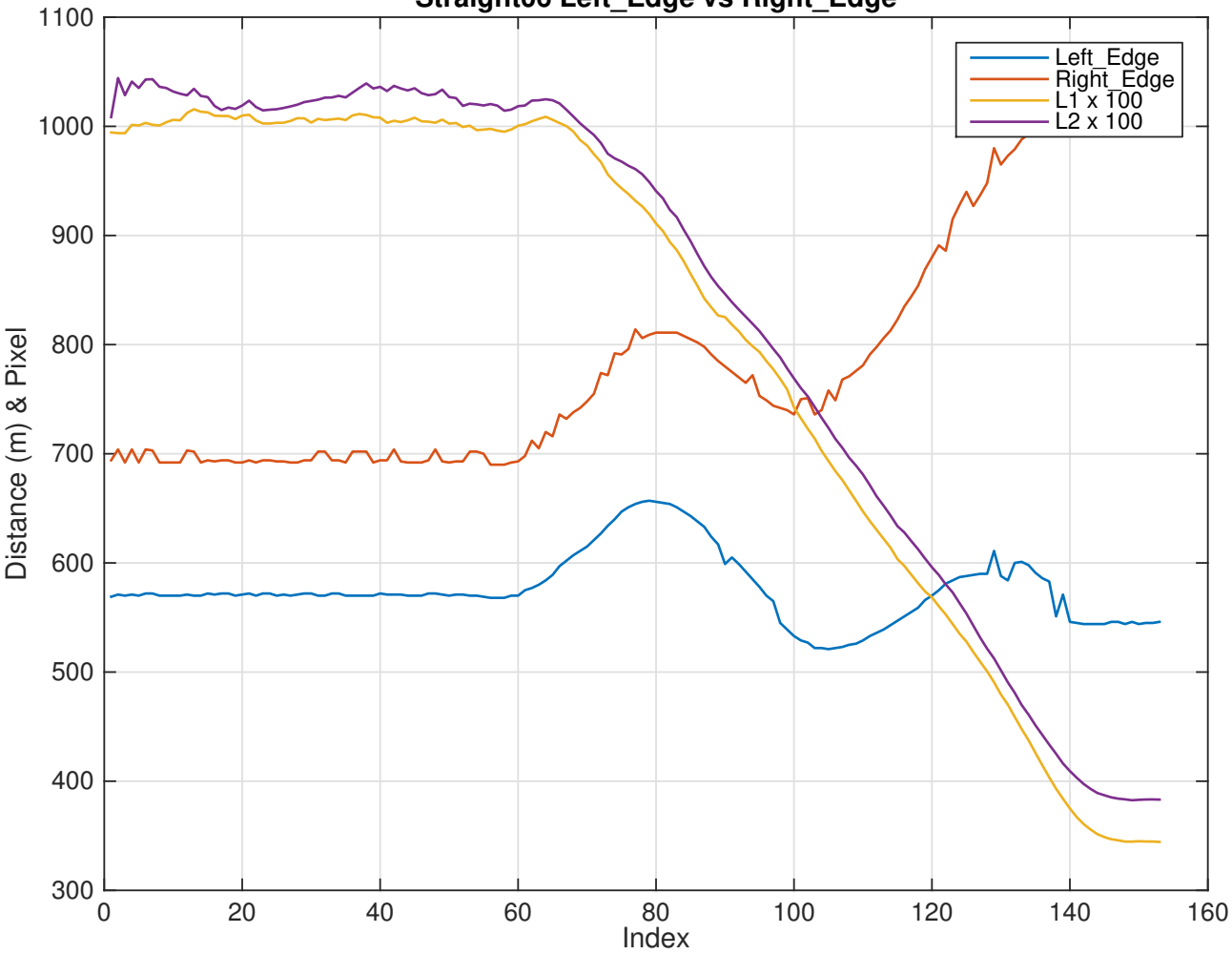
Number_Of_Unique_Paths

King_Pin_Detected

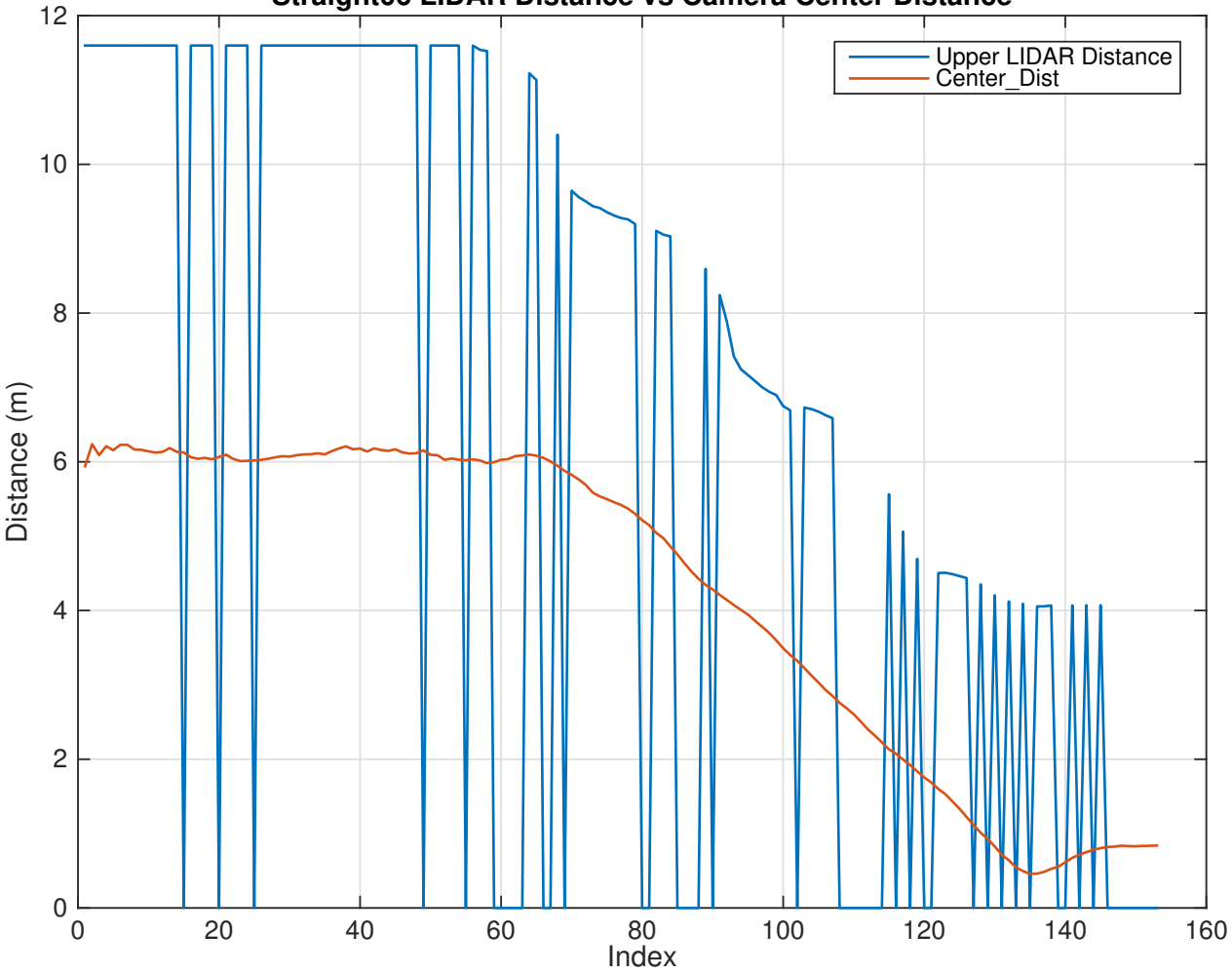
32

false

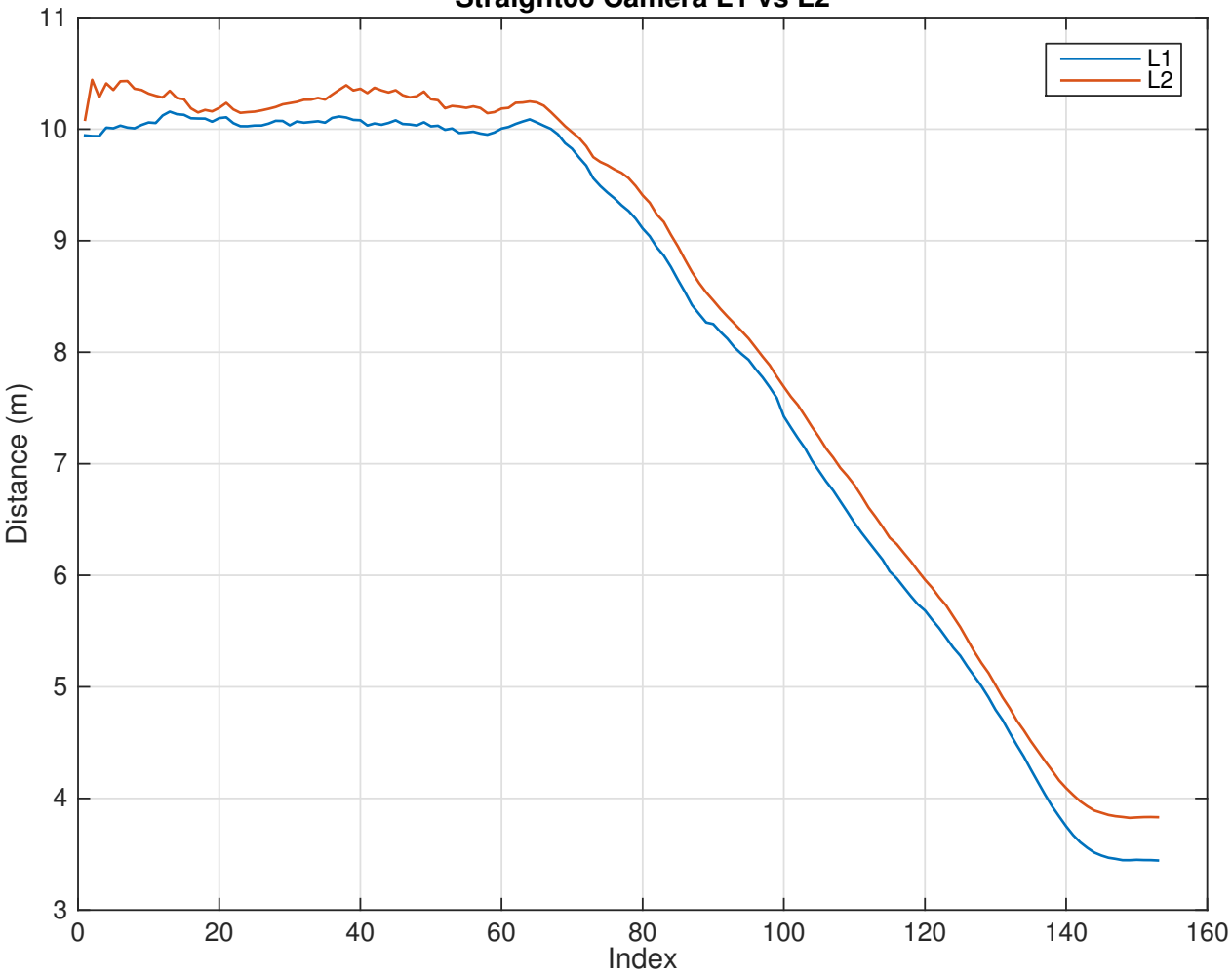
Straight06 Left_Edge vs Right_Edge



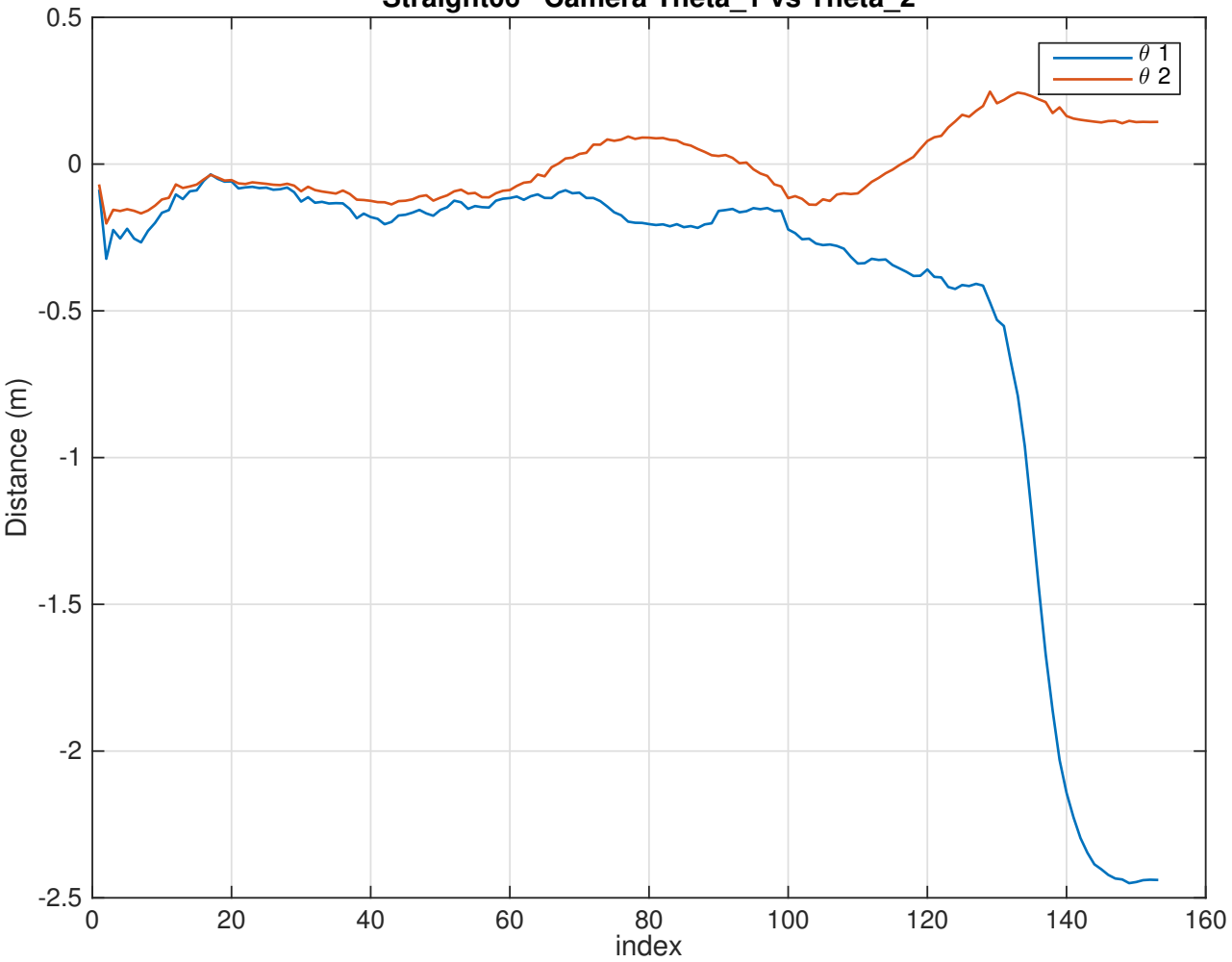
Straight06 LIDAR Distance vs Camera Center Distance



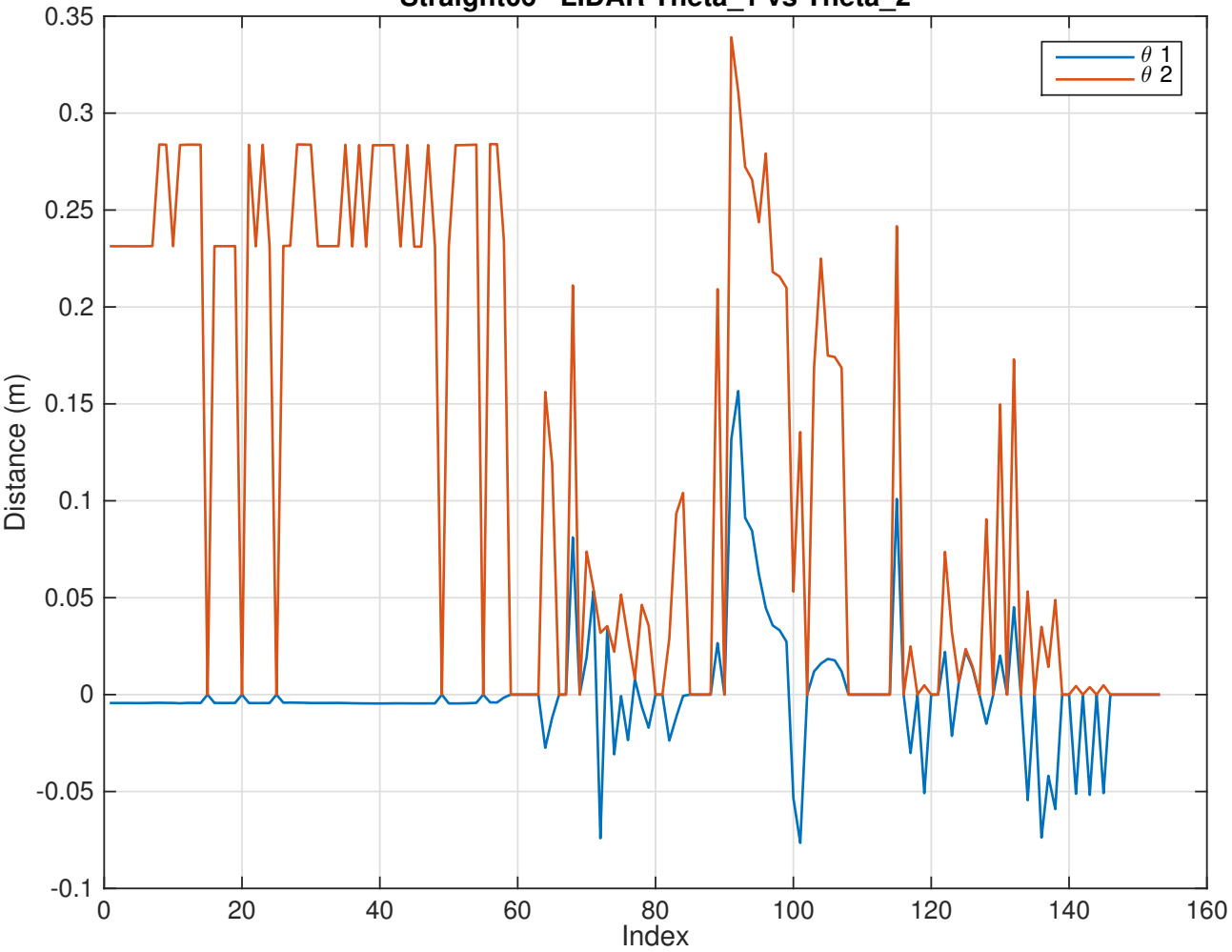
Straight06 Camera L1 vs L2



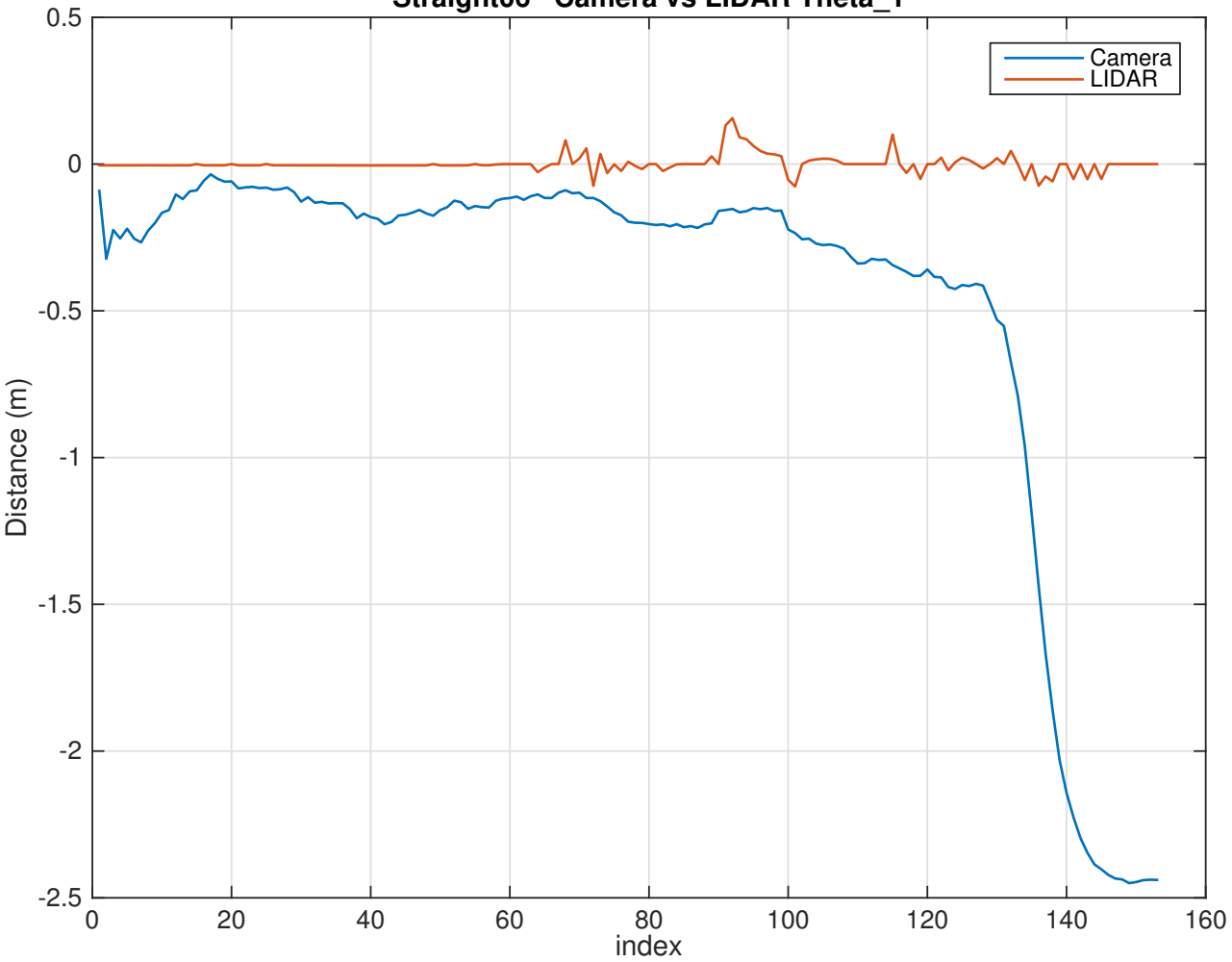
Straight06 Camera Theta_1 vs Theta_2



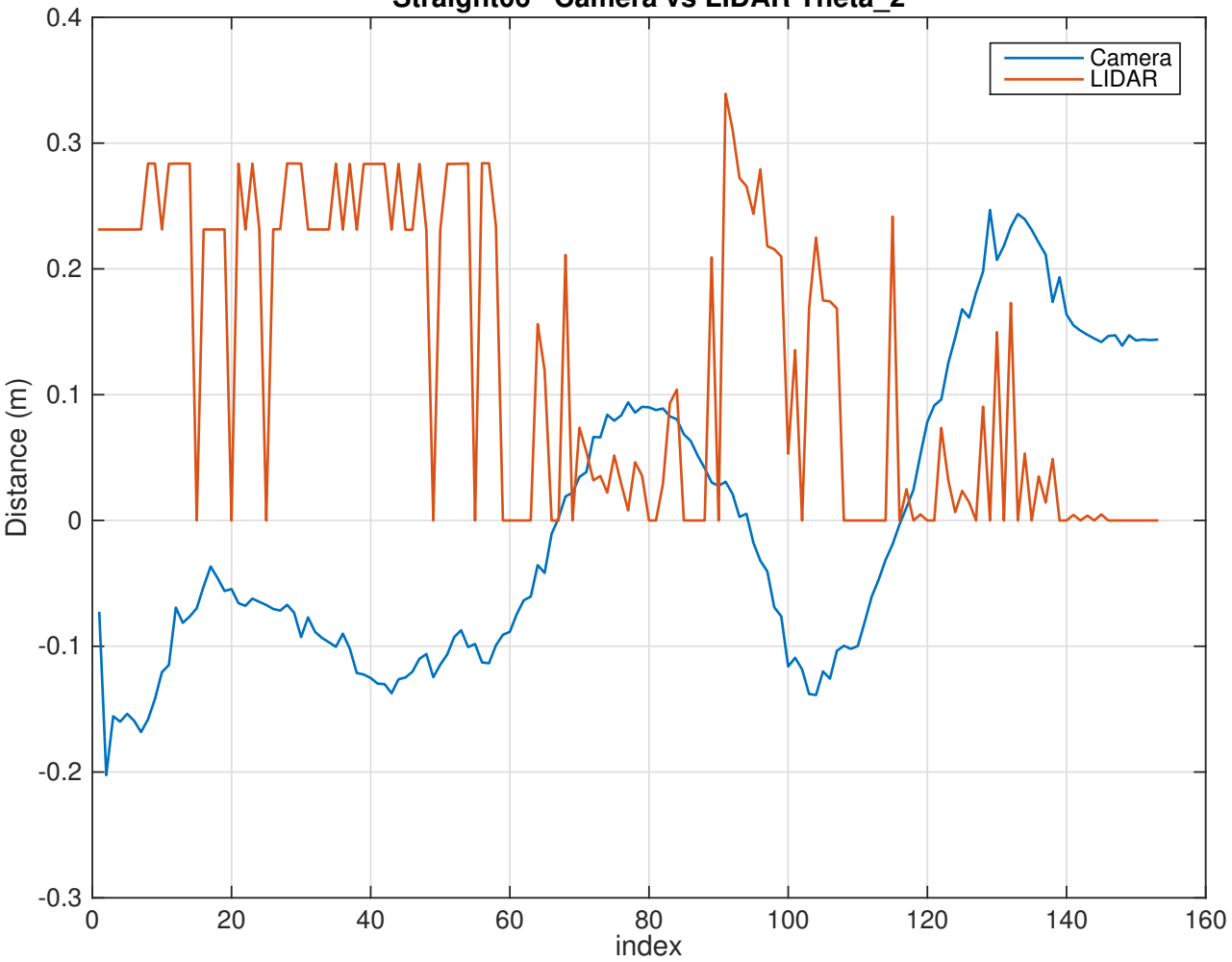
Straight06 LIDAR Theta_1 vs Theta_2



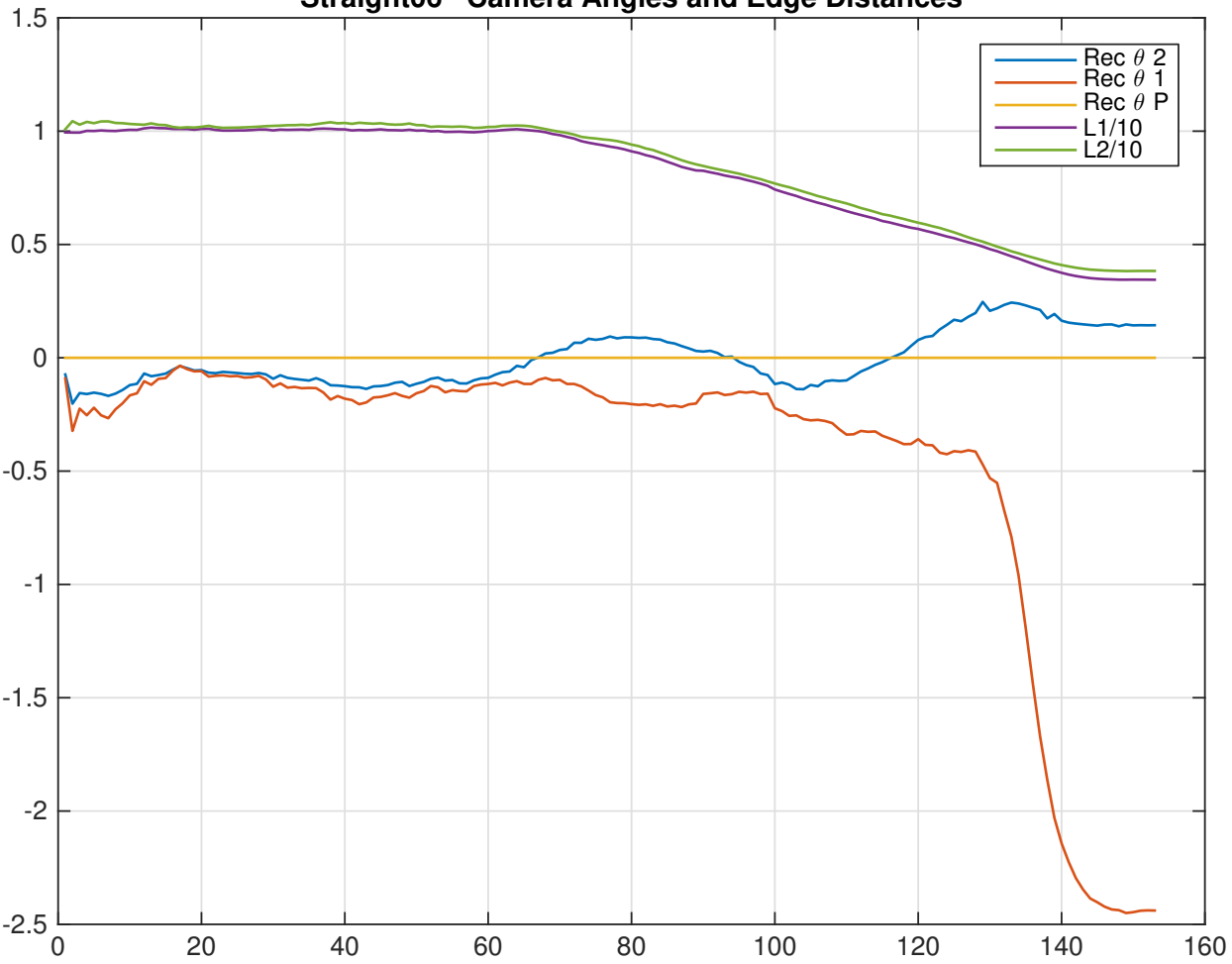
Straight06 Camera vs LIDAR Theta_1



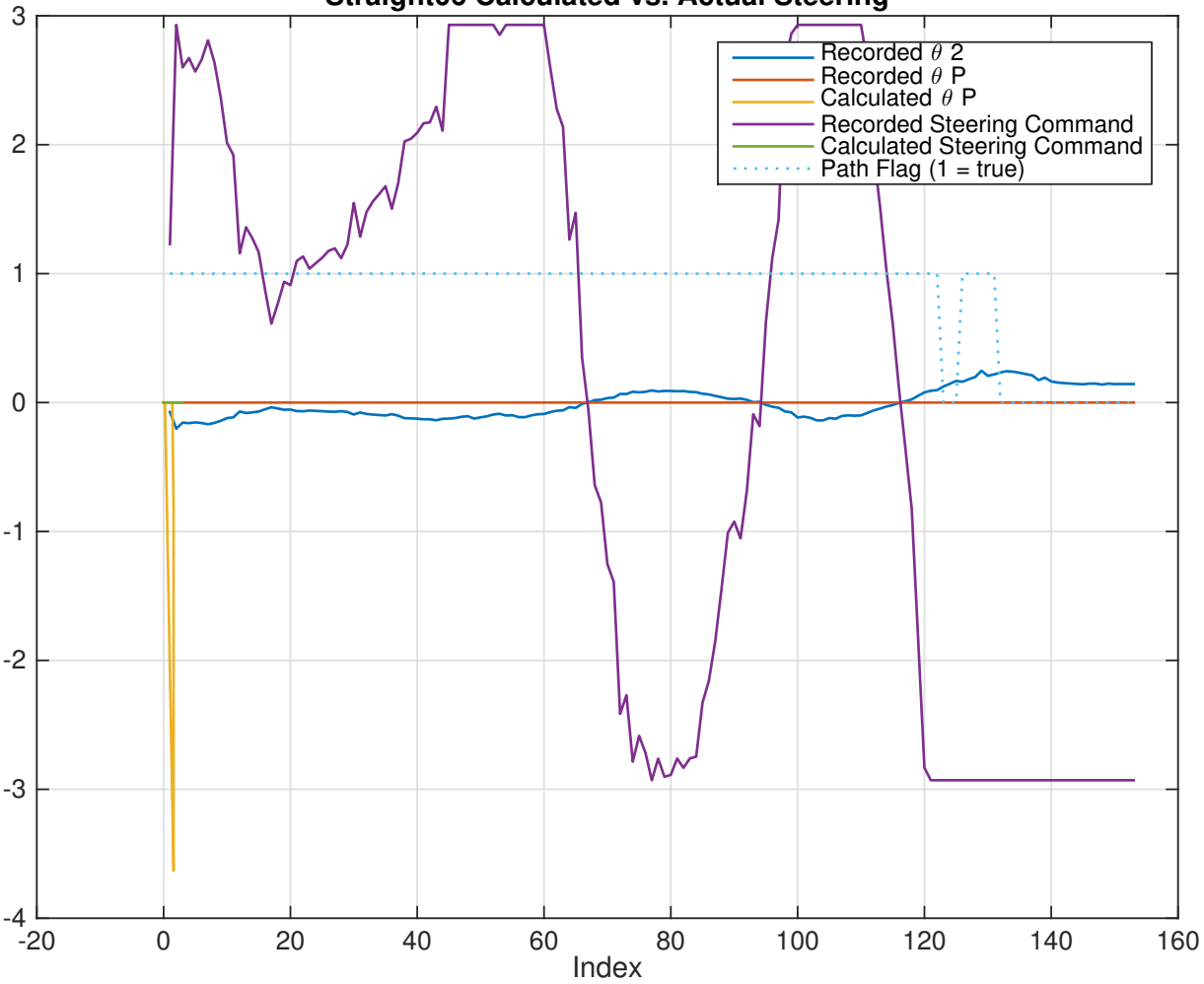
Straight06 Camera vs LIDAR Theta_2



Straight06 Camera Angles and Edge Distances



Straight06 Calculated vs. Actual Steering



Straight06 All Paths

