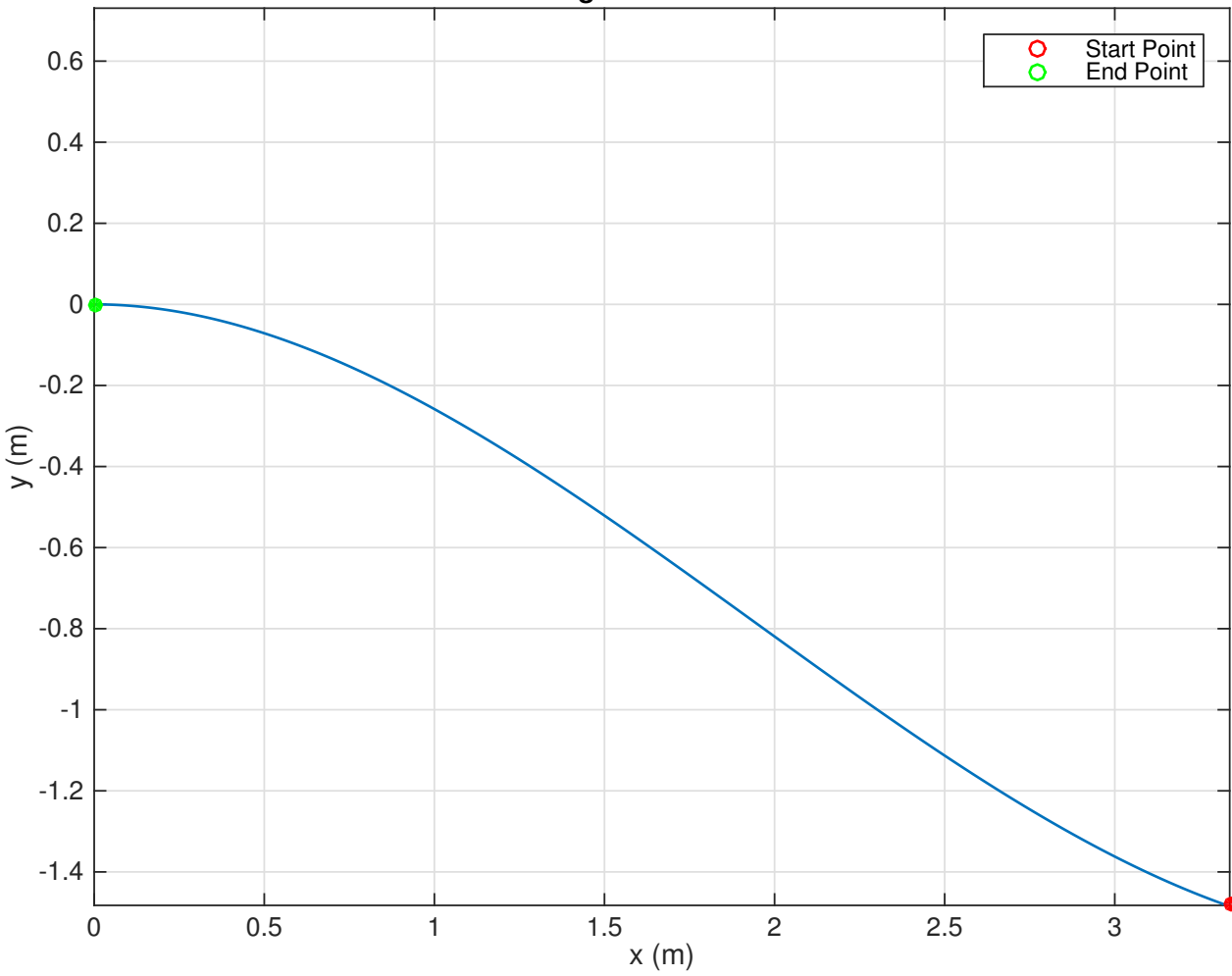


Angled4 All Paths



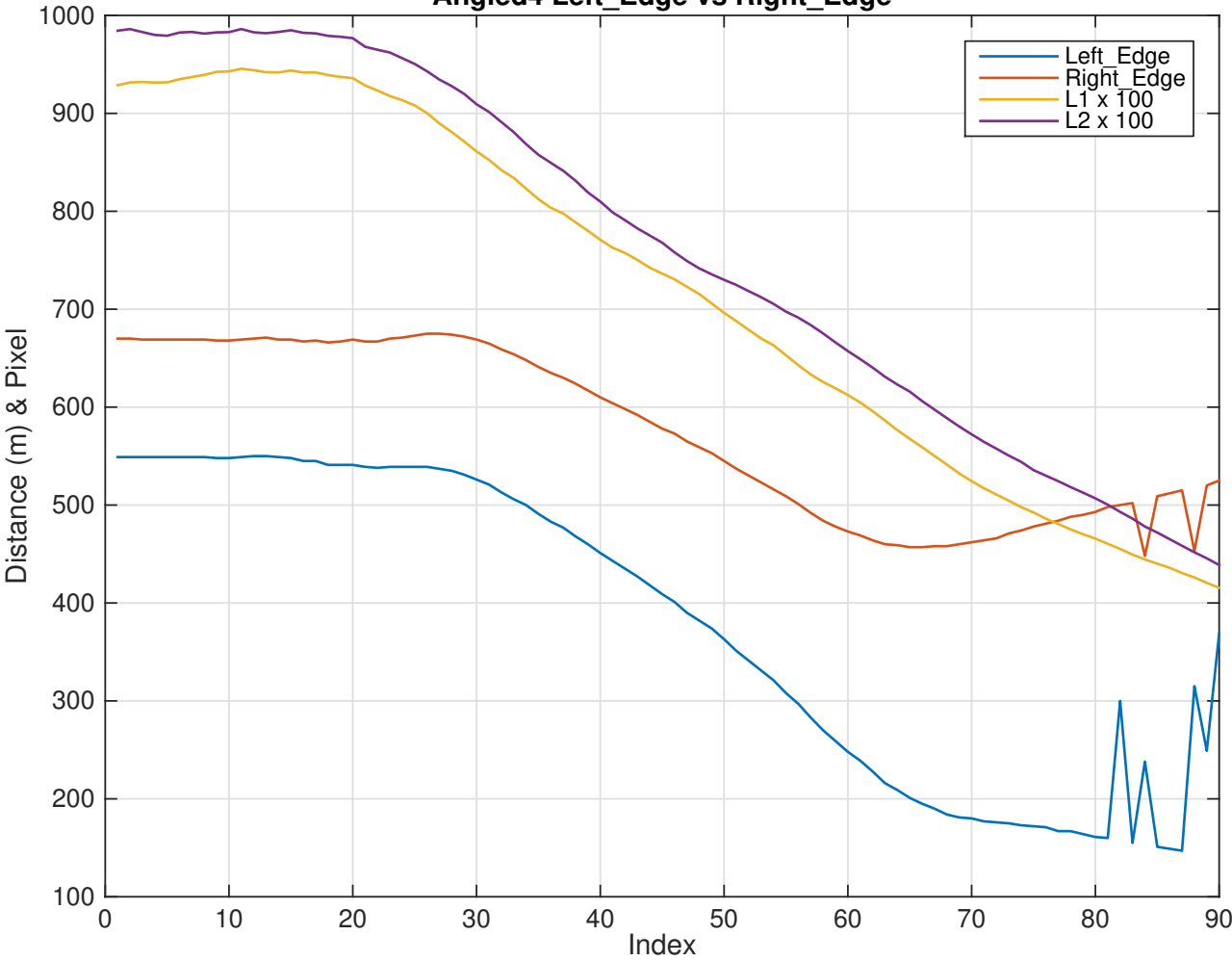
Number_Of_Unique_Paths

King_Pin_Detected

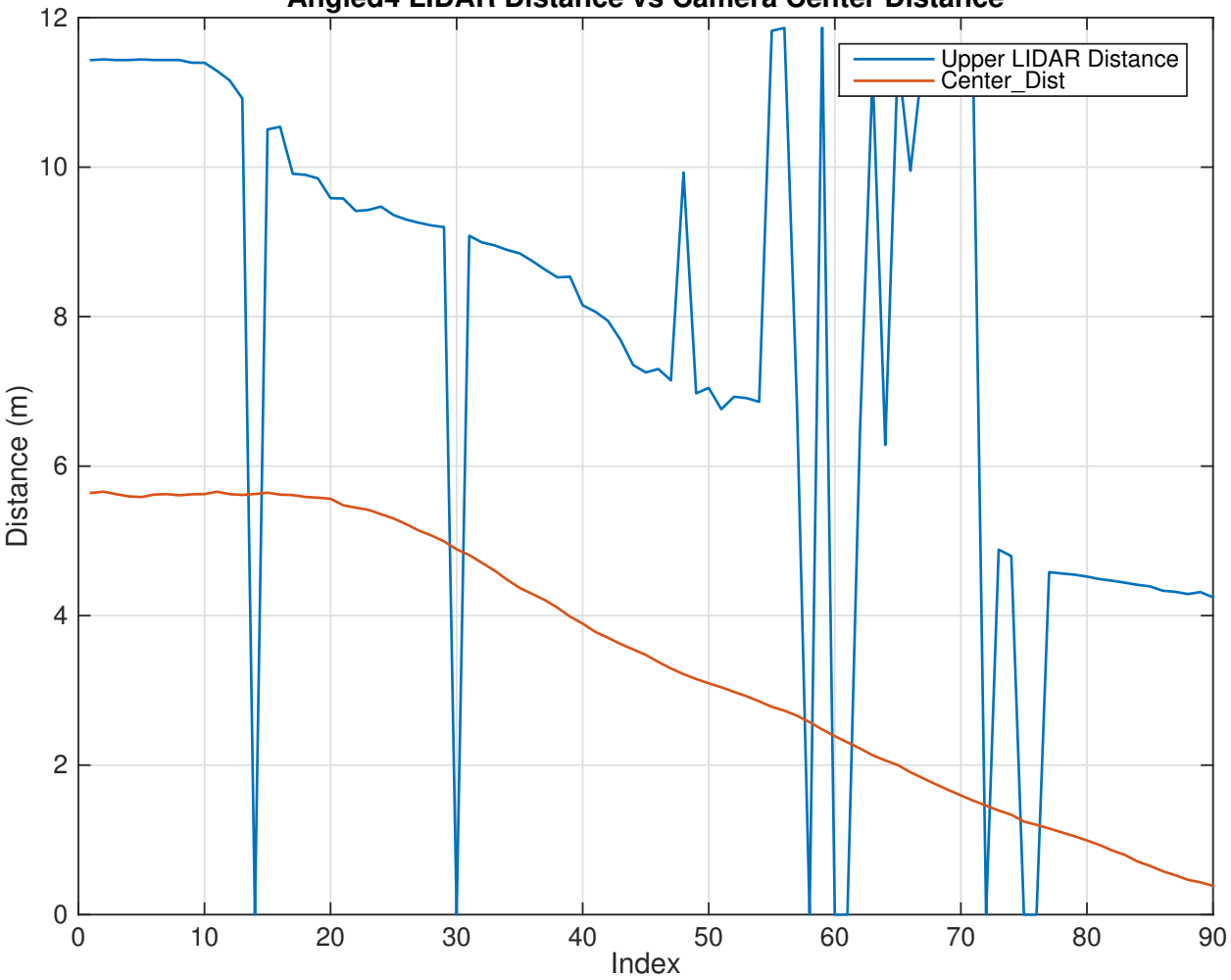
2

false

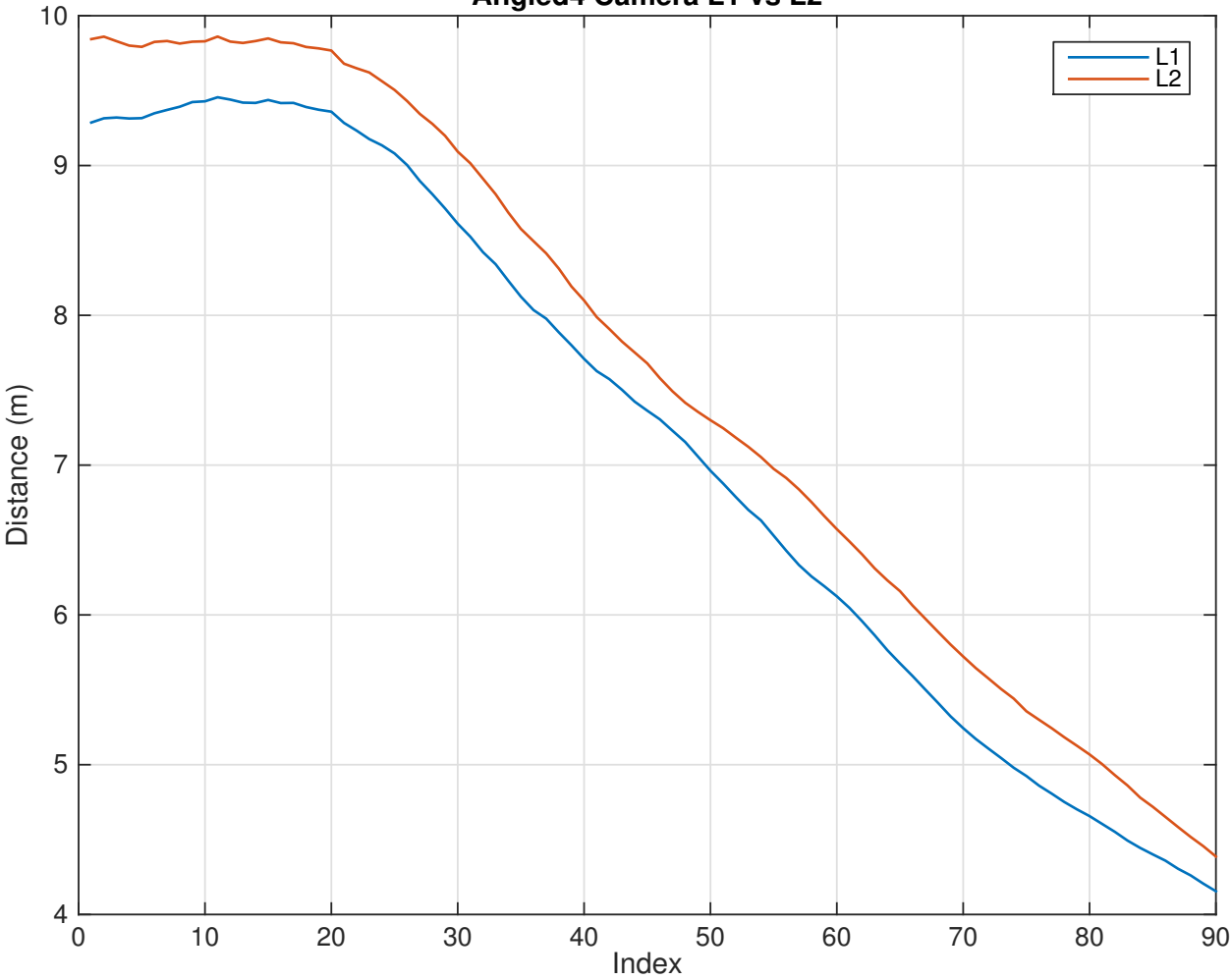
Angled4 Left_Edge vs Right_Edge



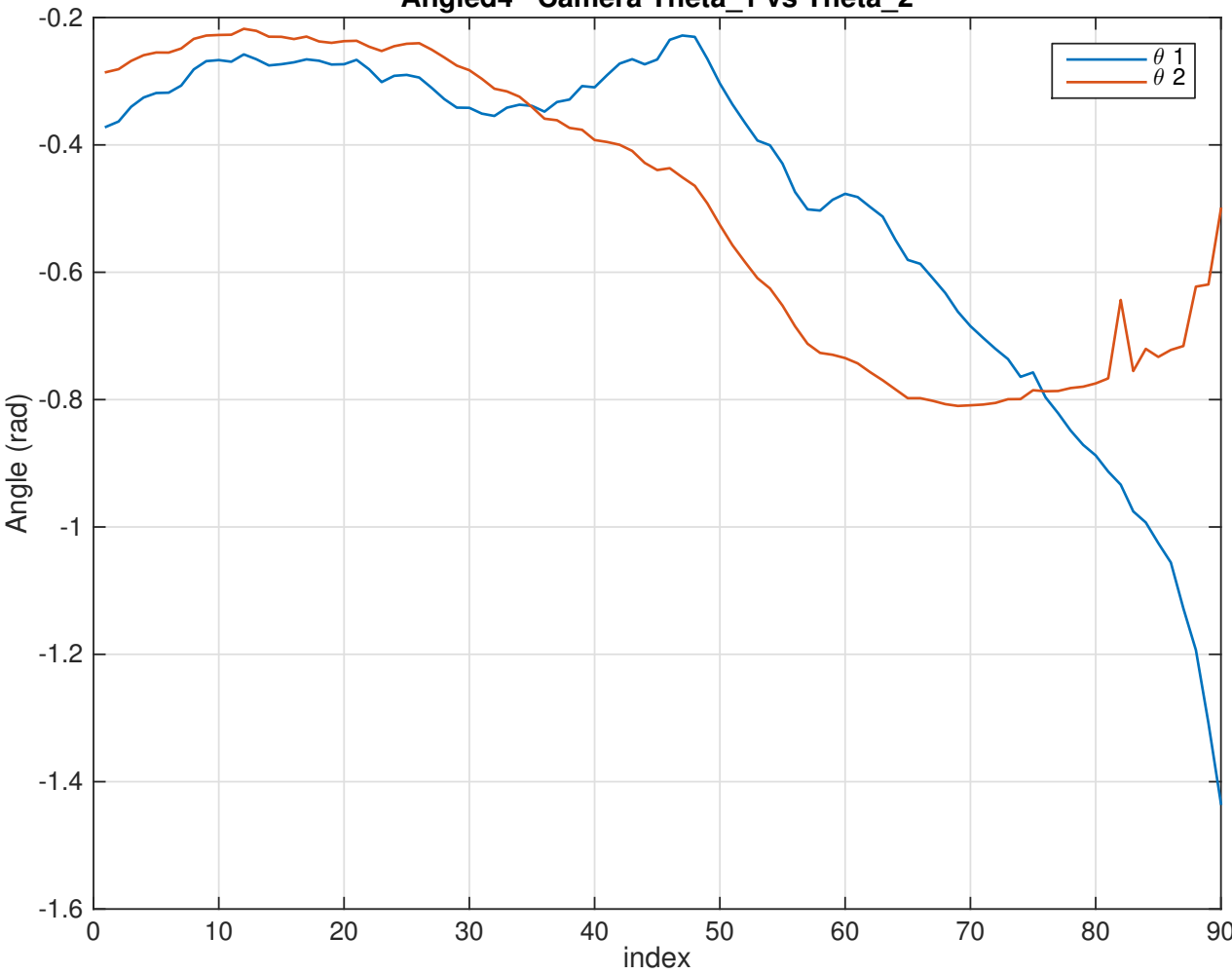
Angled4 LIDAR Distance vs Camera Center Distance



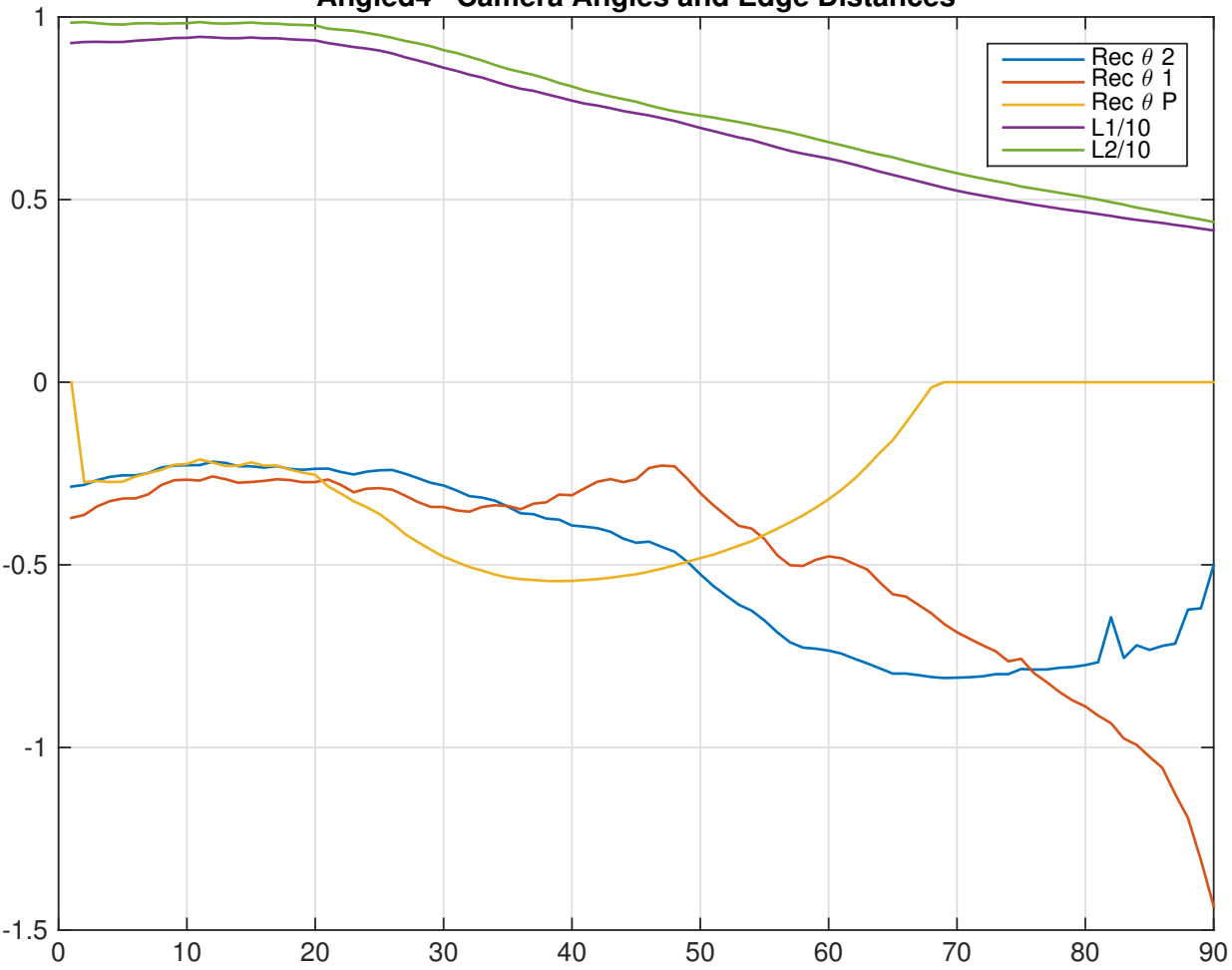
Angled4 Camera L1 vs L2



Angled4 Camera Theta_1 vs Theta_2



Angled4 Camera Angles and Edge Distances



Angled4 Steering

