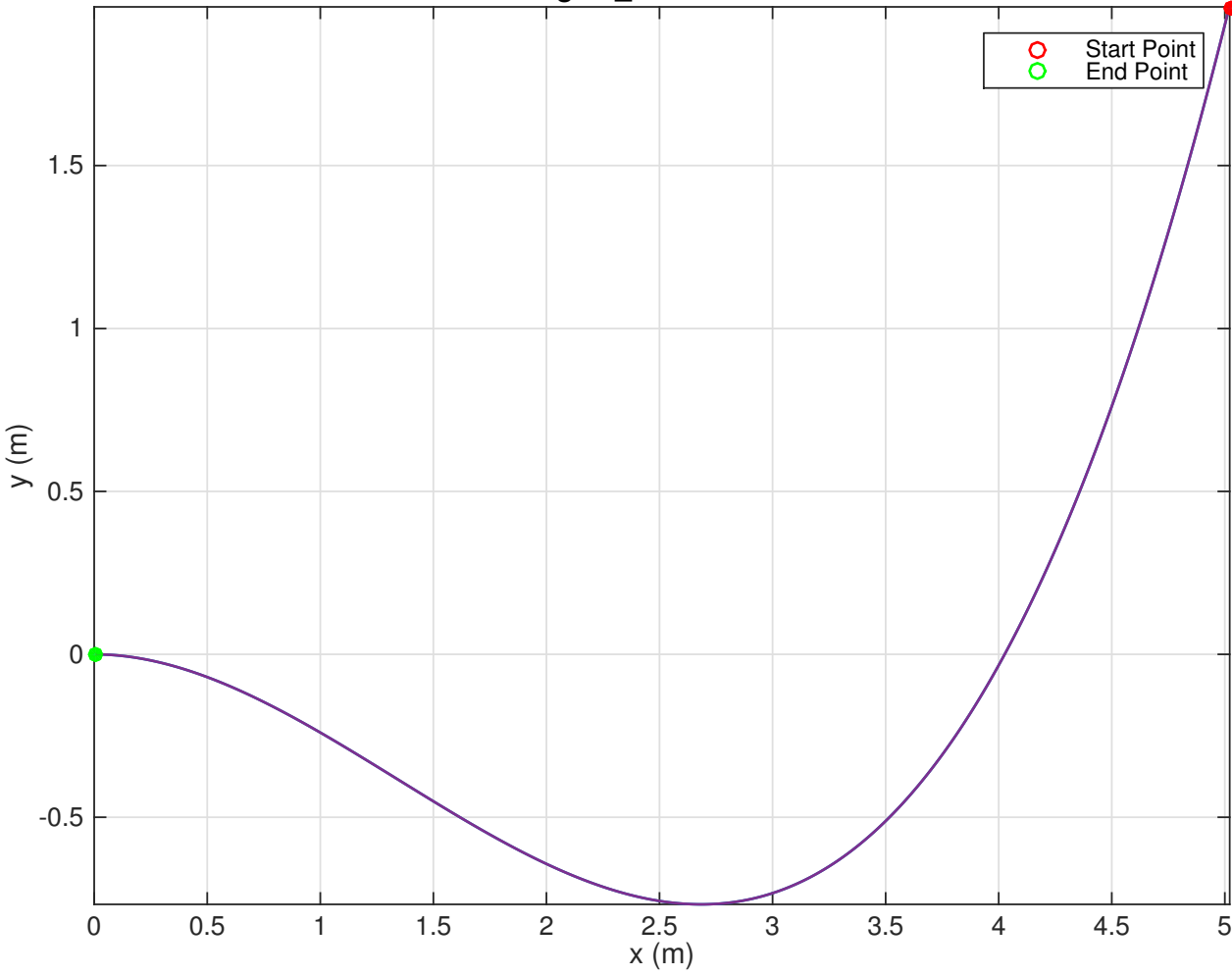


Angled\_left All Paths



Number\_Of\_Unique\_Paths

King\_Pin\_Detected

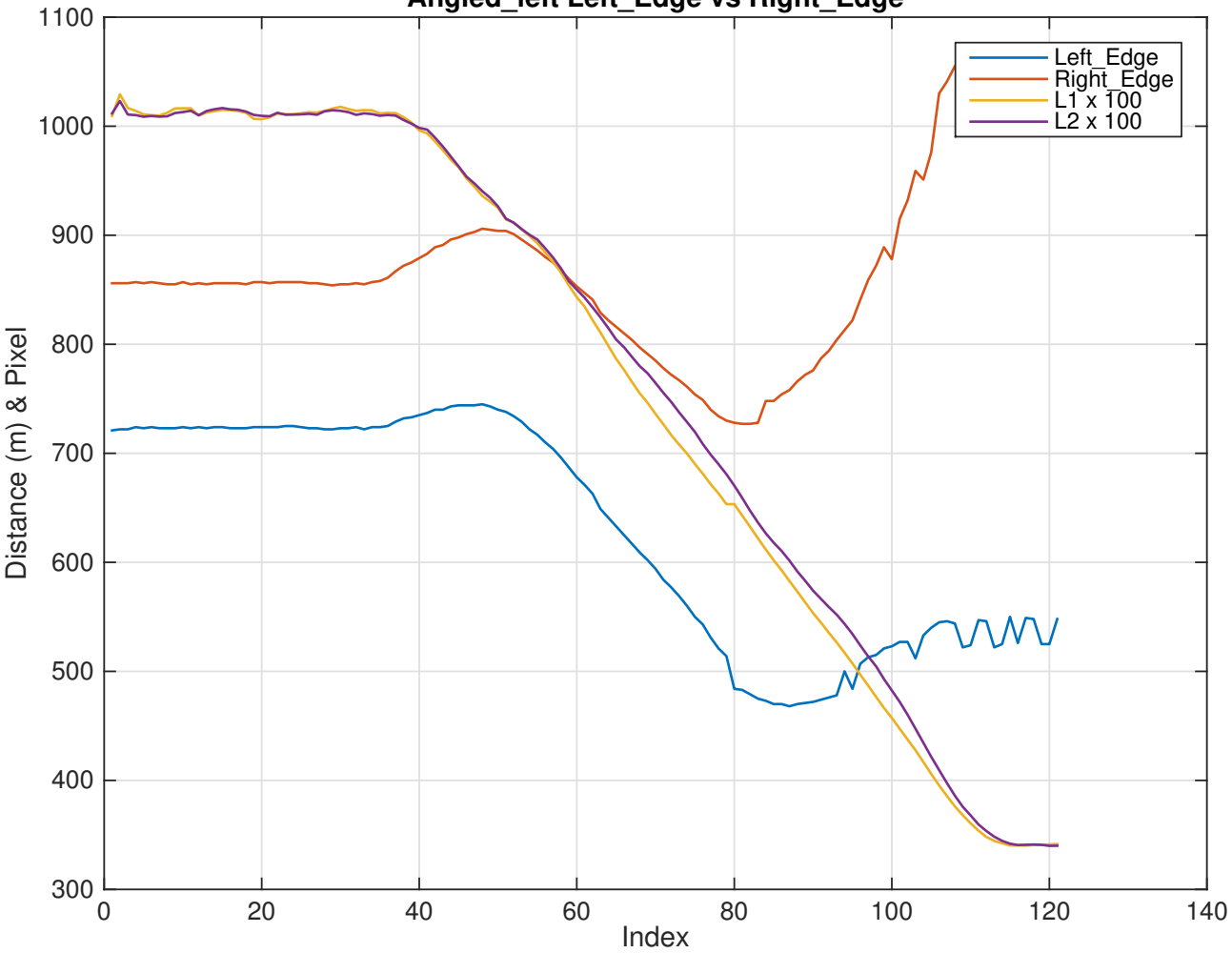
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17

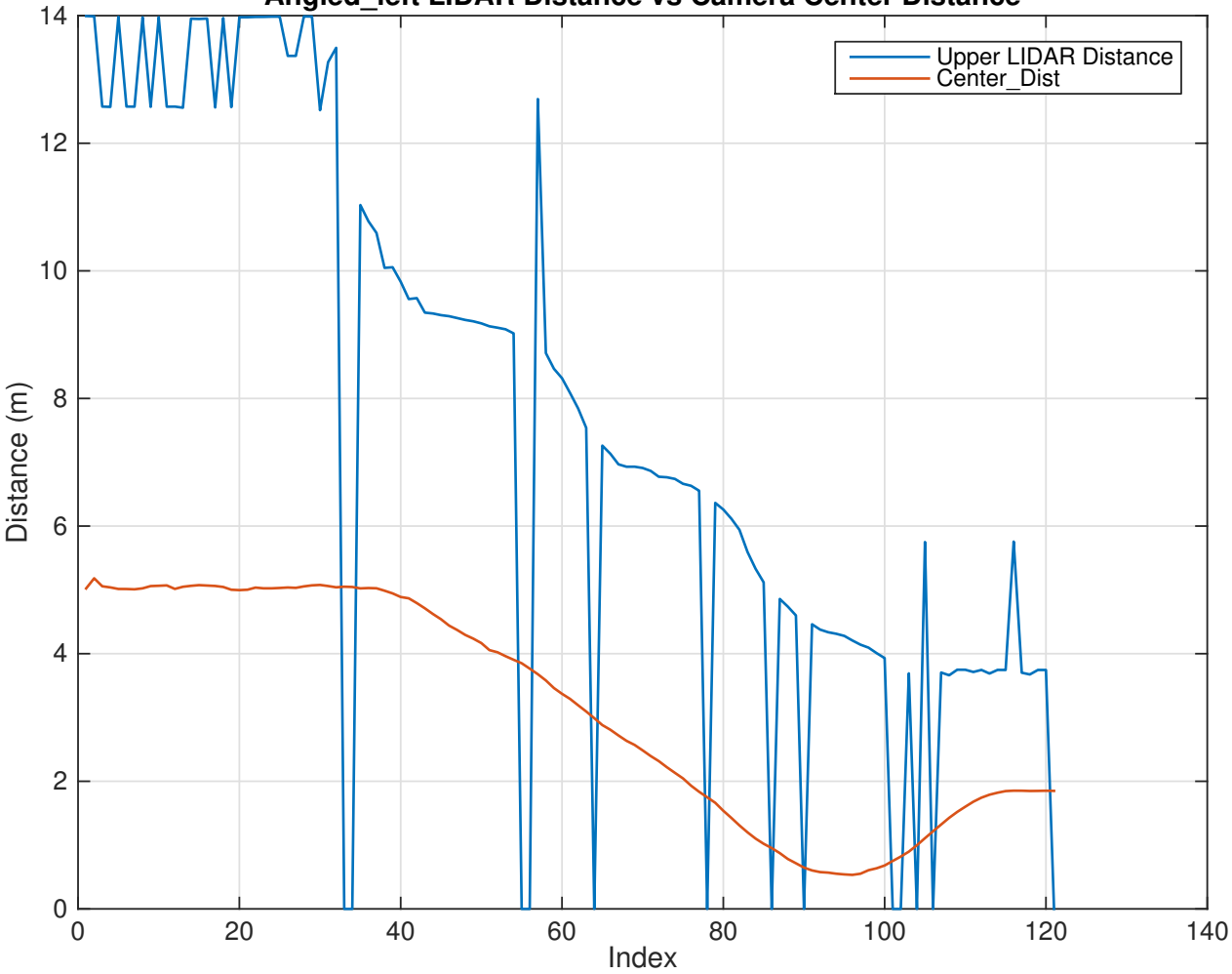
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false

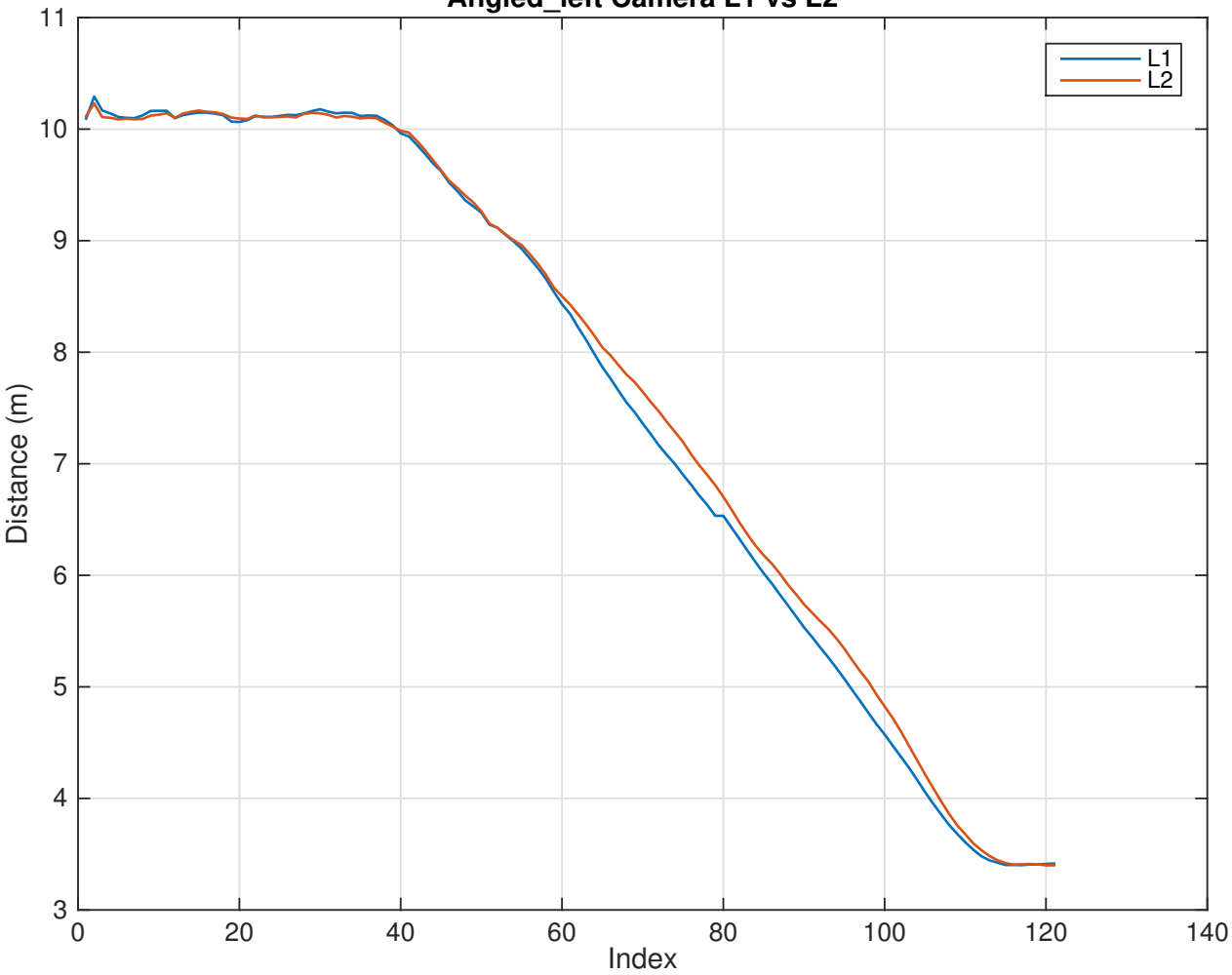
# Angled\_left Left\_Edge vs Right\_Edge



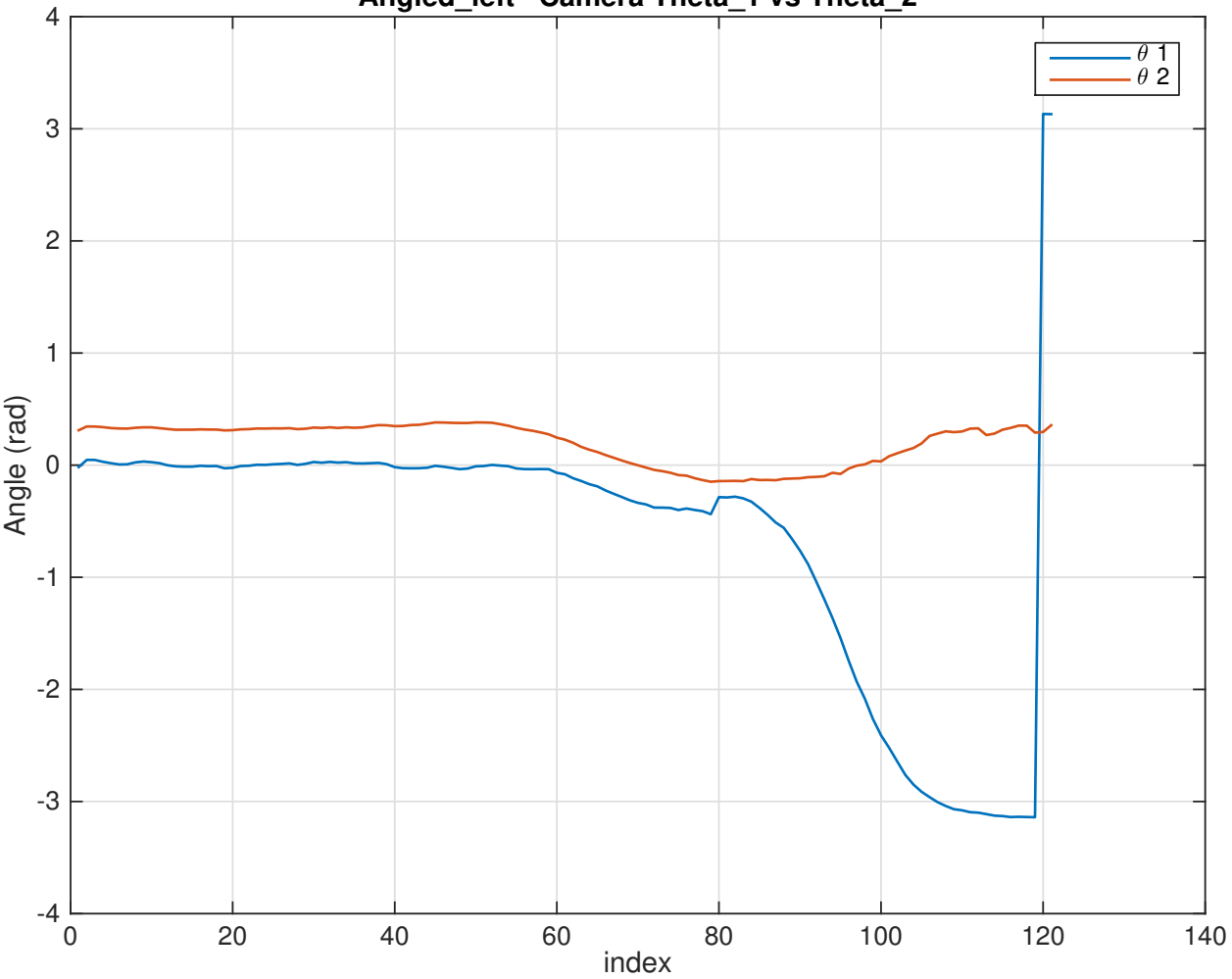
Angled\_left LIDAR Distance vs Camera Center Distance



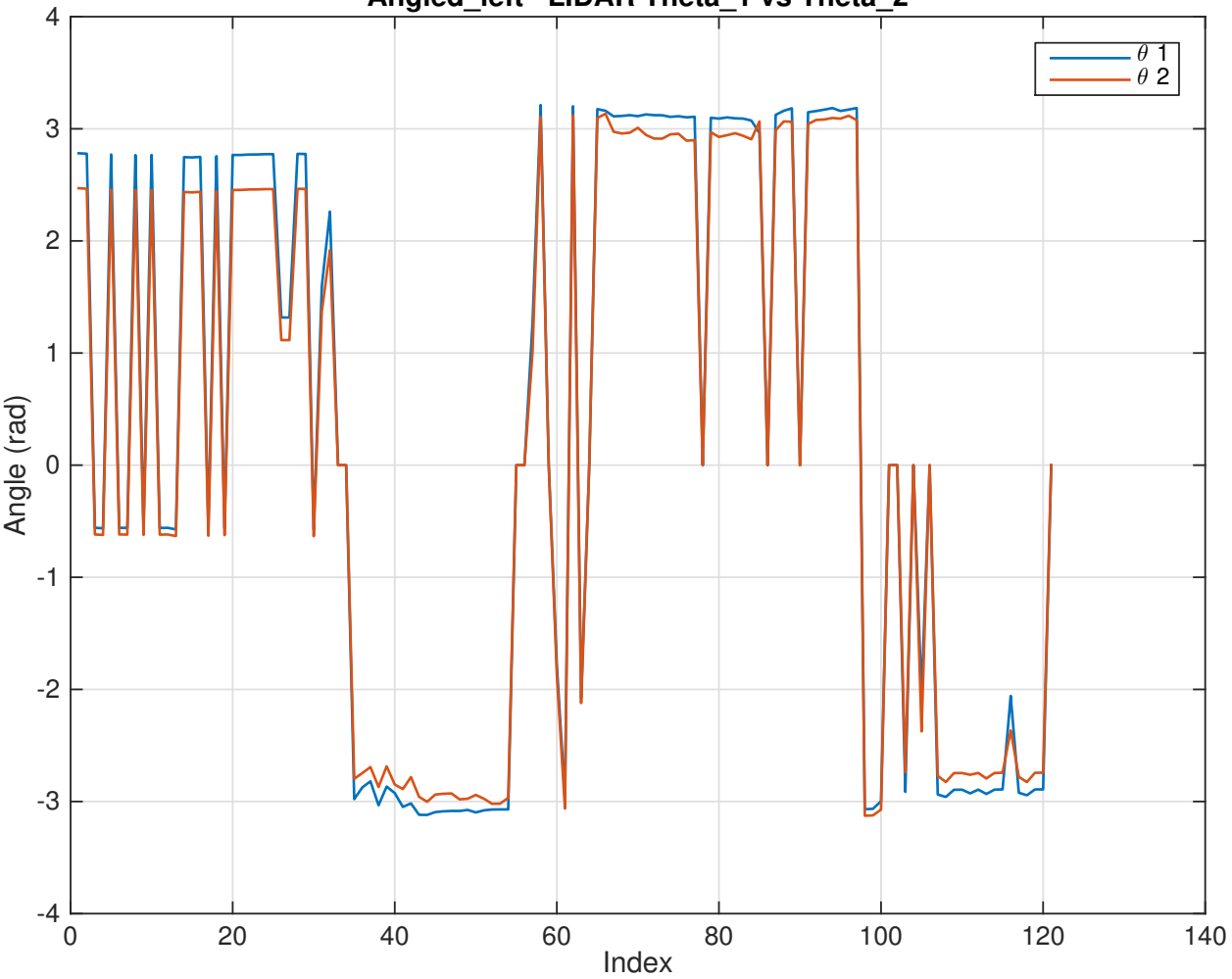
Angled\_left Camera L1 vs L2



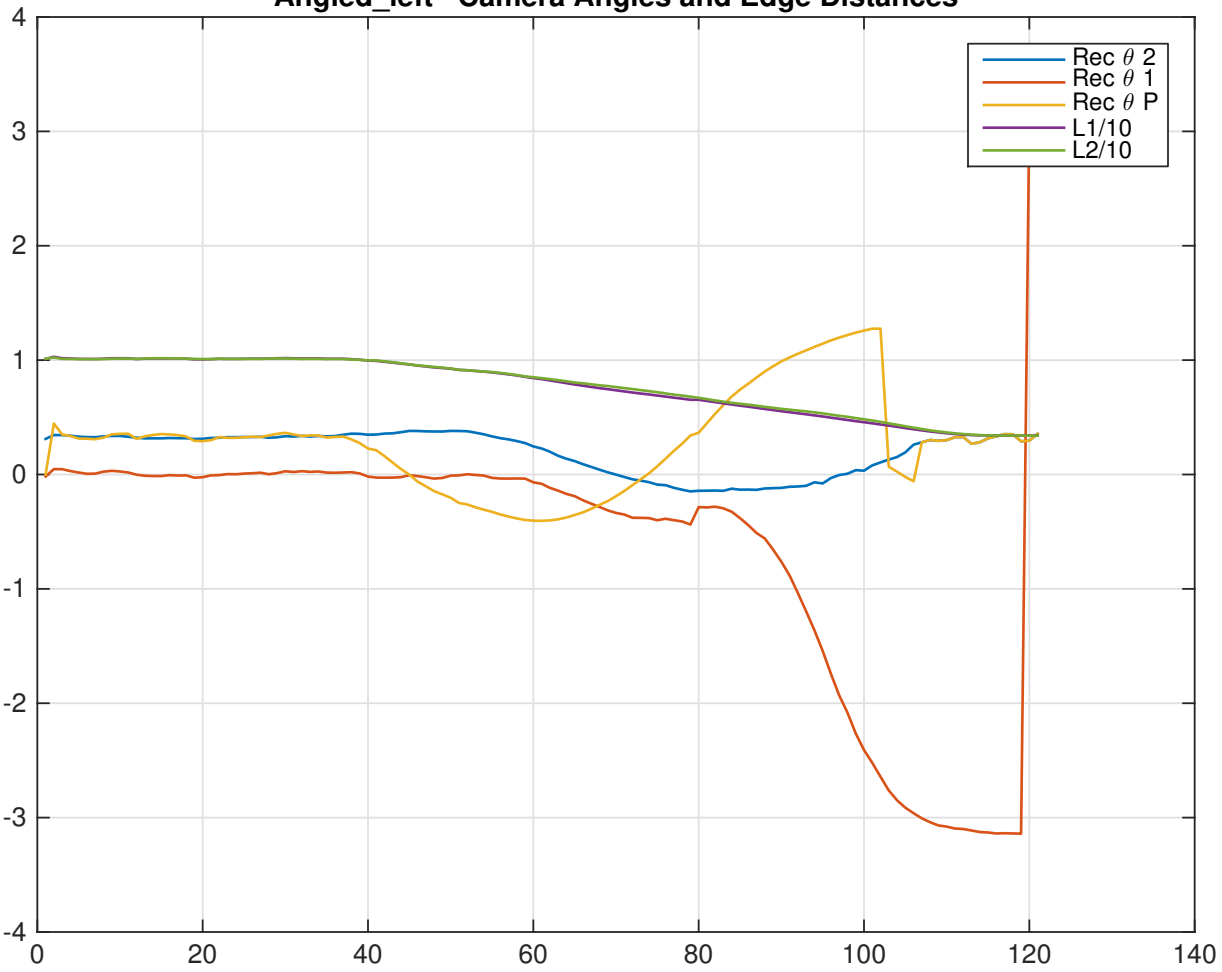
Angled\_left Camera Theta\_1 vs Theta\_2



# Angled\_left LIDAR Theta\_1 vs Theta\_2

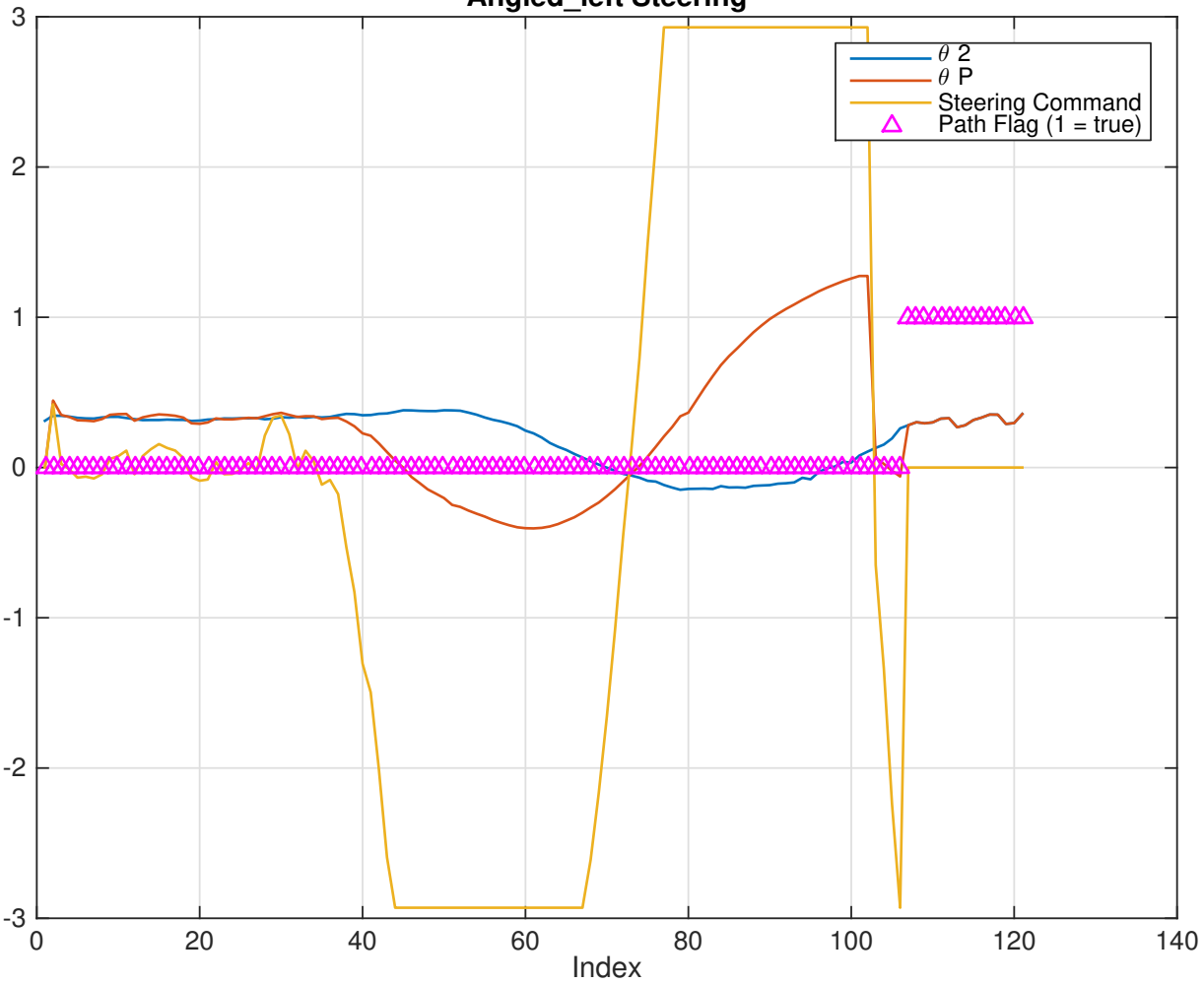


Angled\_left Camera Angles and Edge Distances

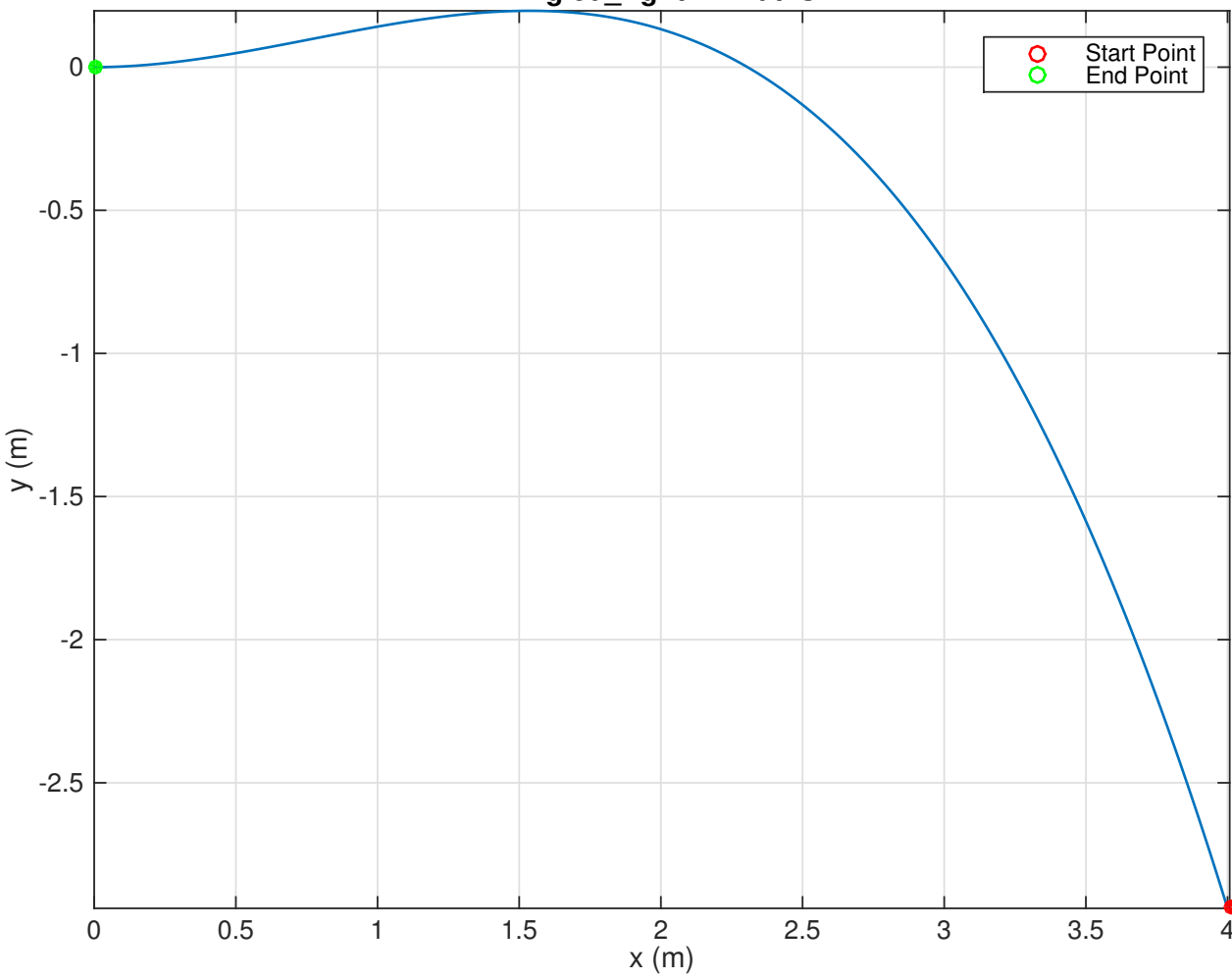




Angled\_left Steering



Angled\_right All Paths



Number\_Of\_Unique\_Paths

King\_Pin\_Detected

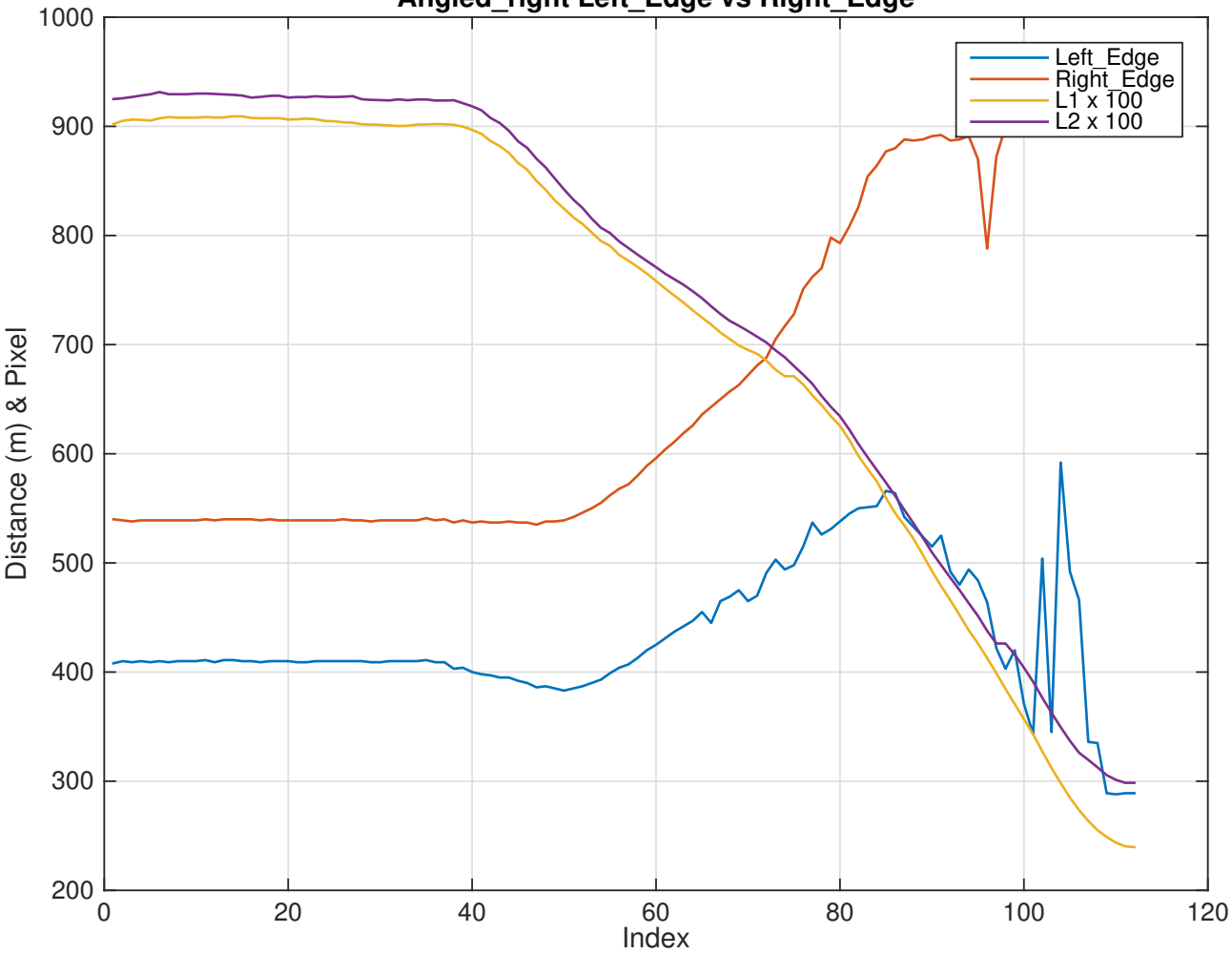
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1

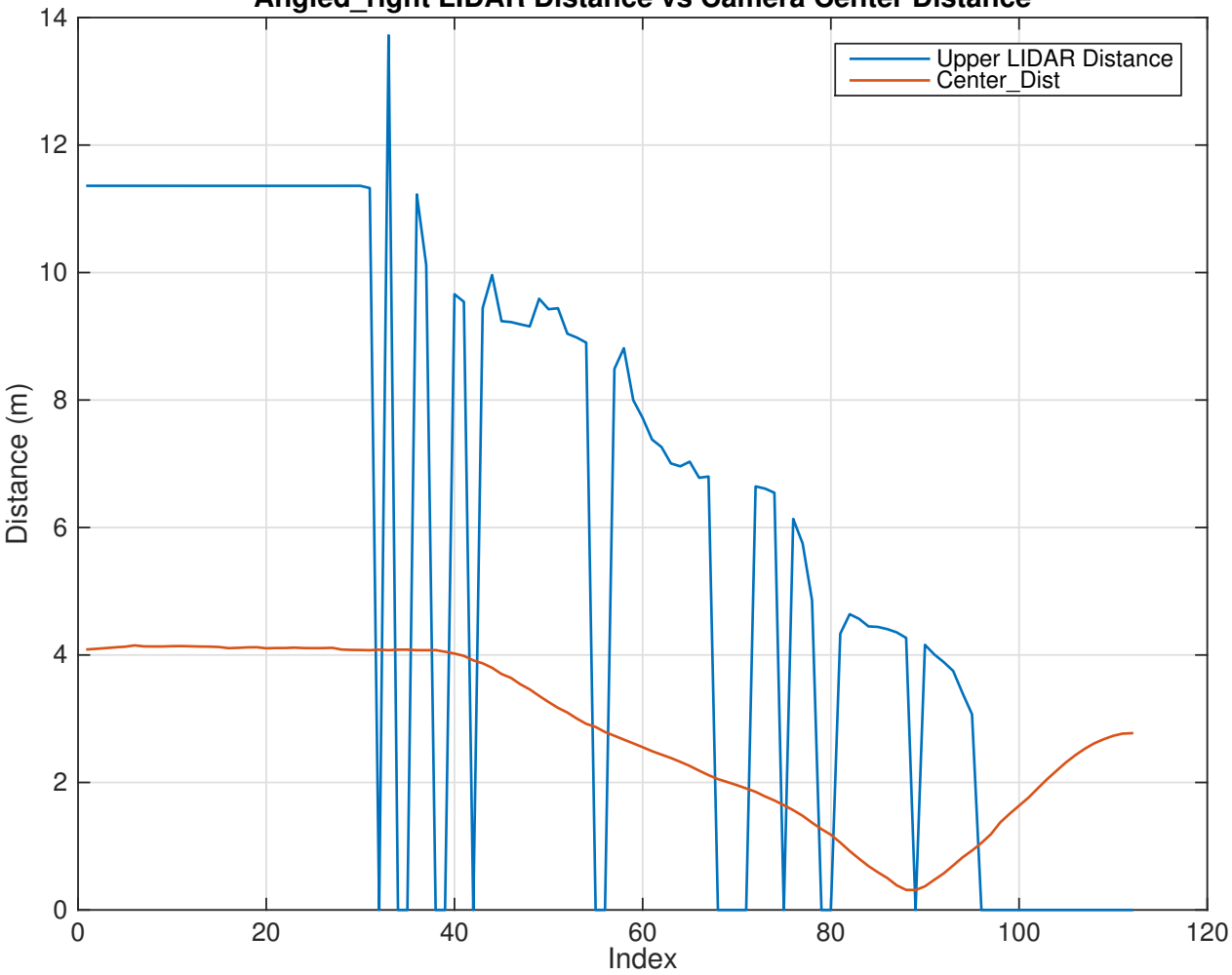
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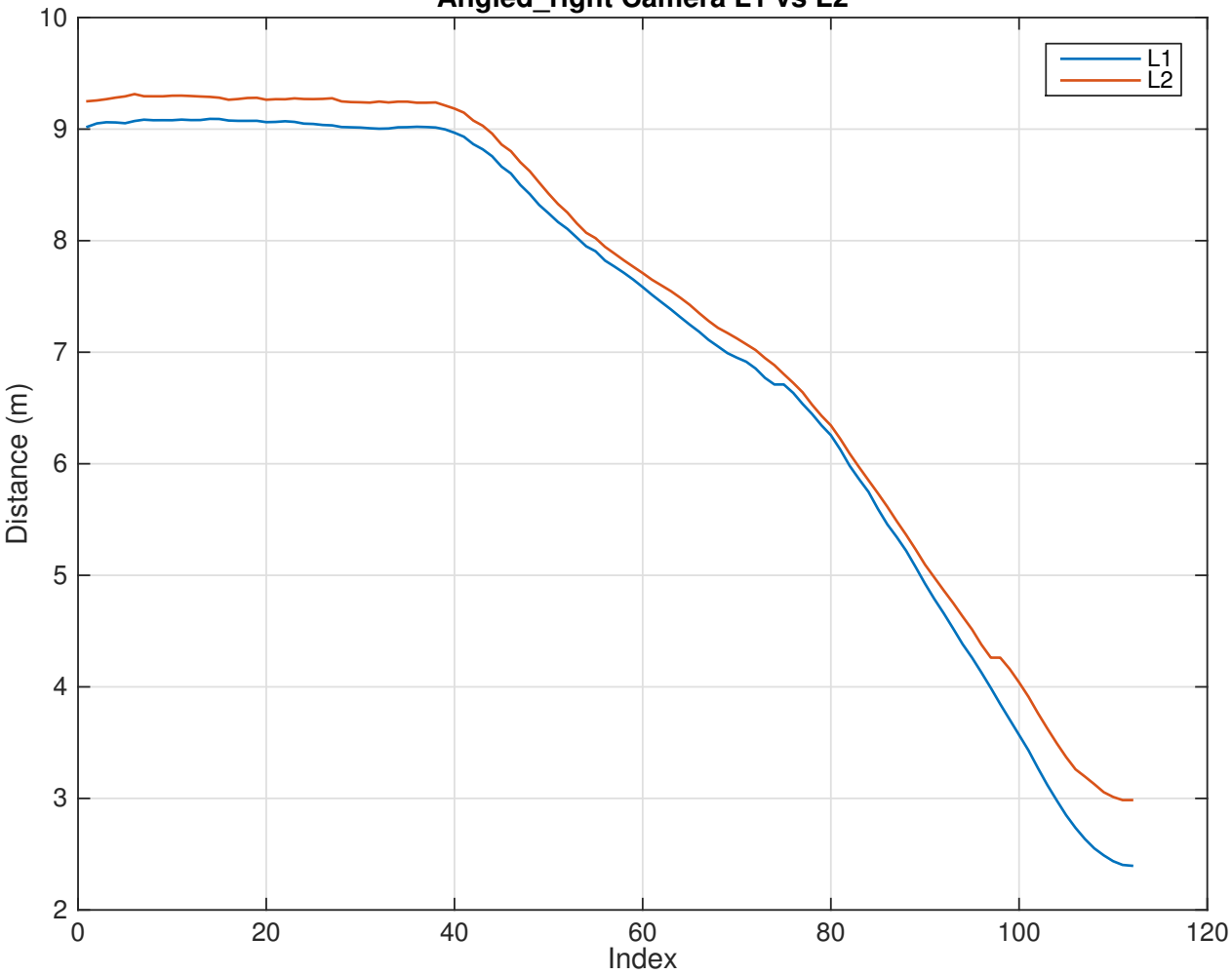
# Angled\_right Left\_Edge vs Right\_Edge



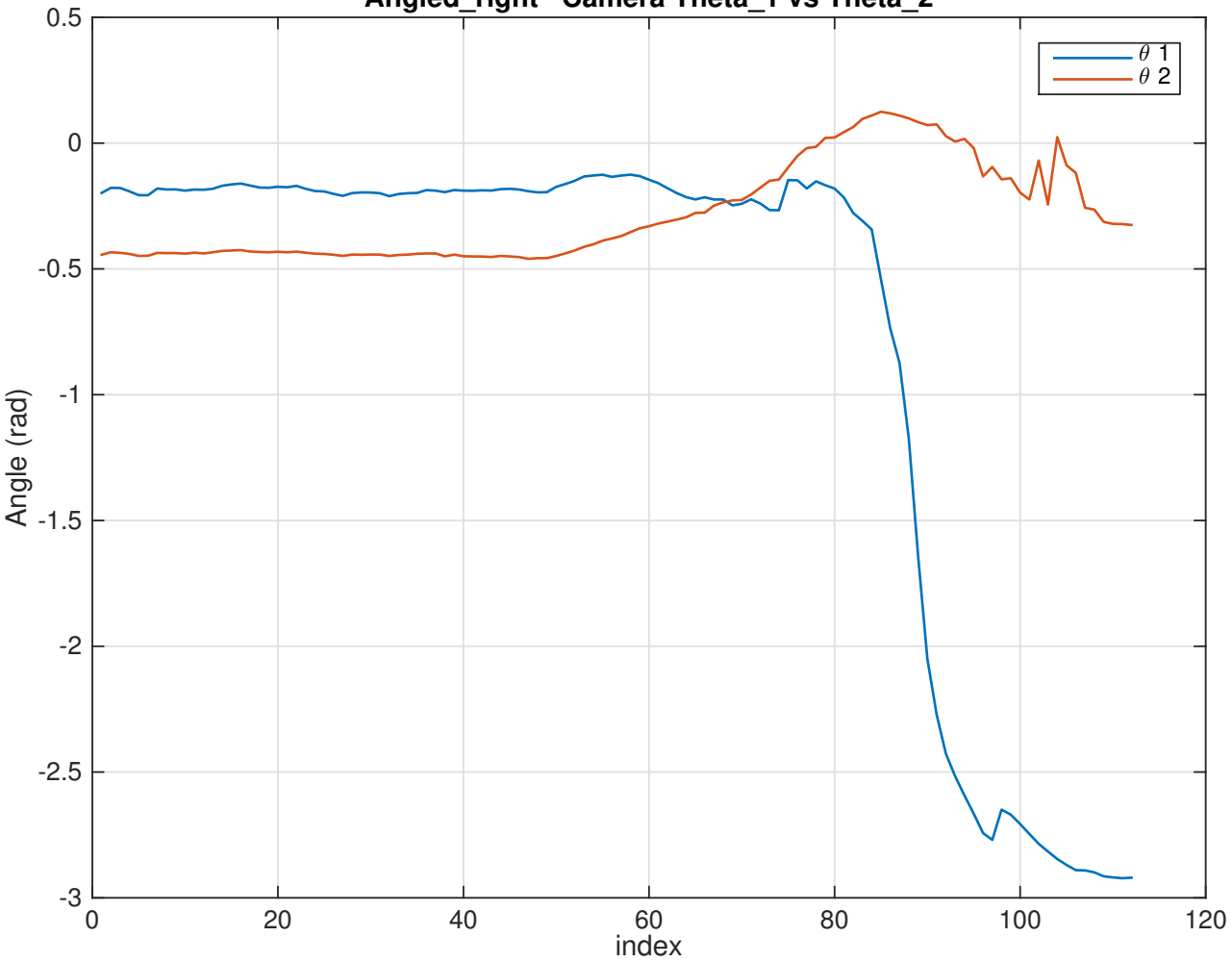
Angled\_right LIDAR Distance vs Camera Center Distance



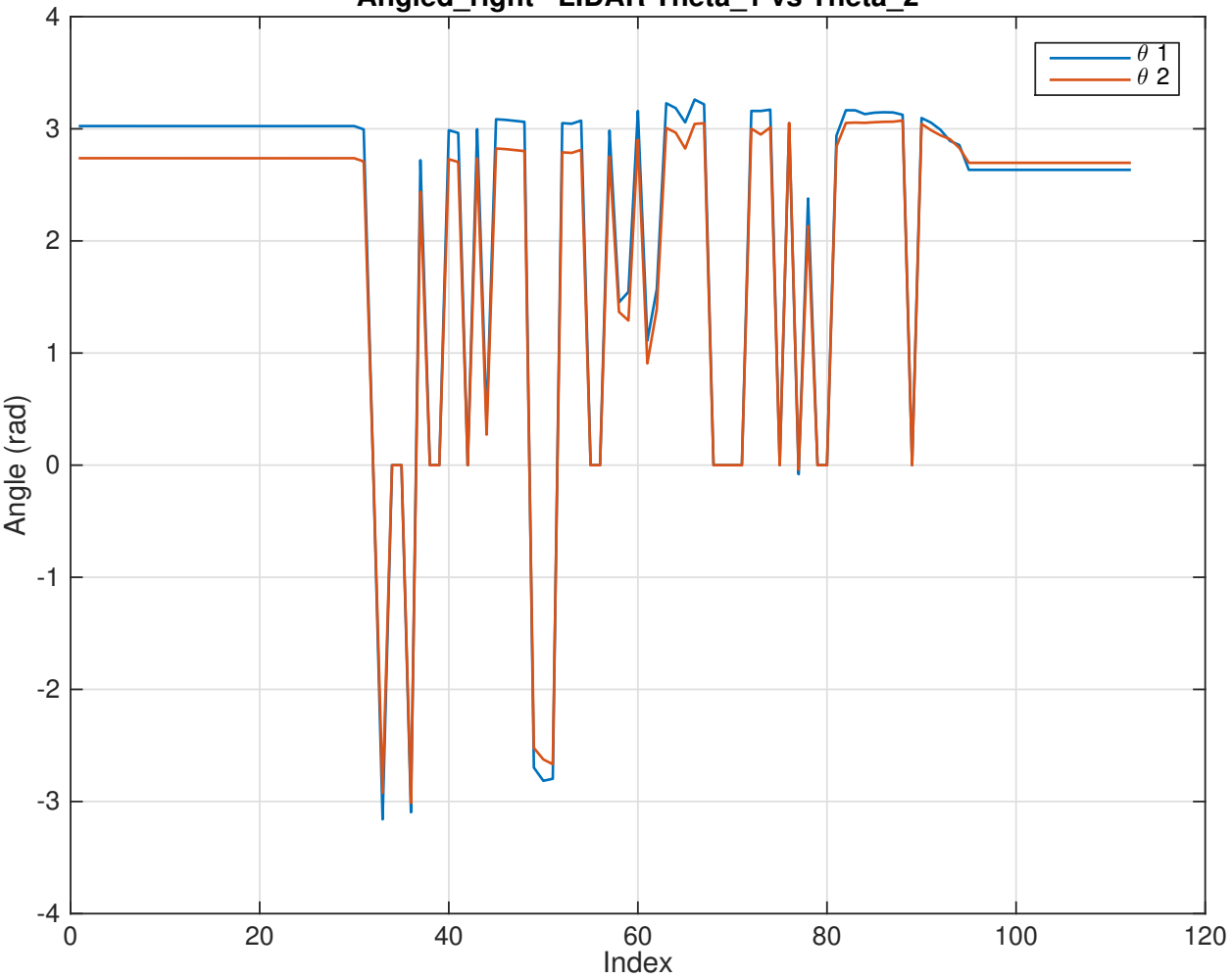
Angled\_right Camera L1 vs L2



Angled\_right Camera Theta\_1 vs Theta\_2

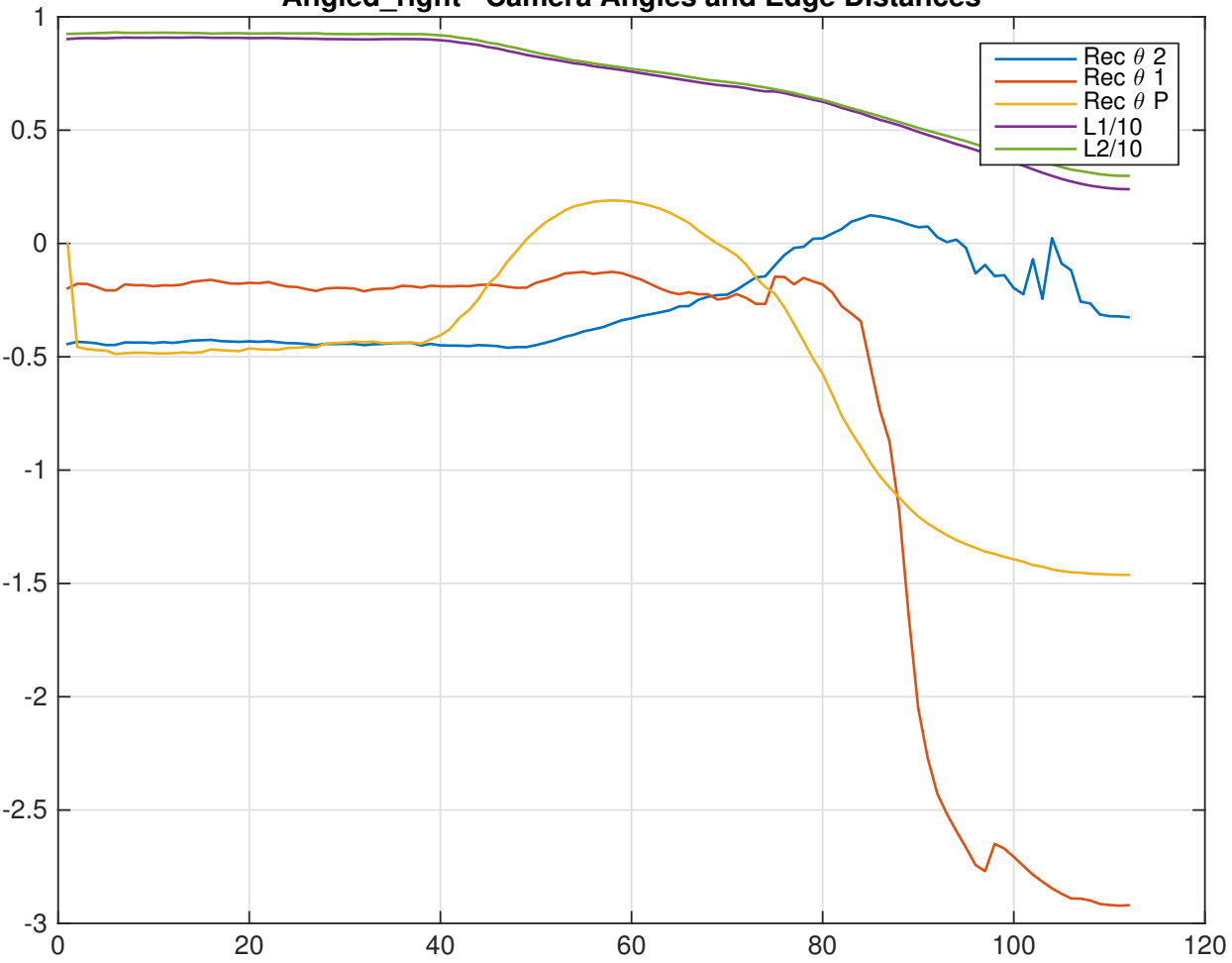


Angled\_right LIDAR Theta\_1 vs Theta\_2

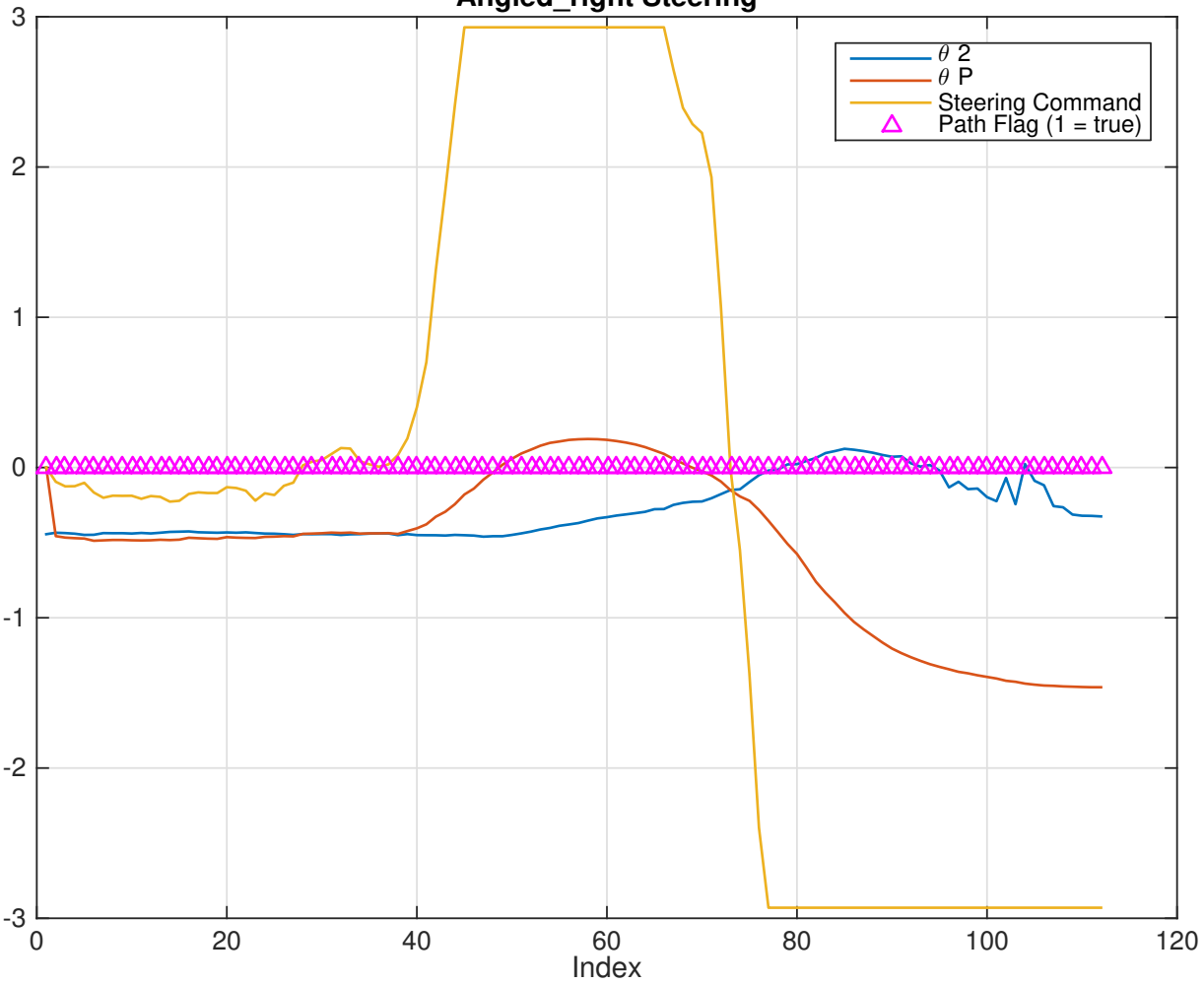




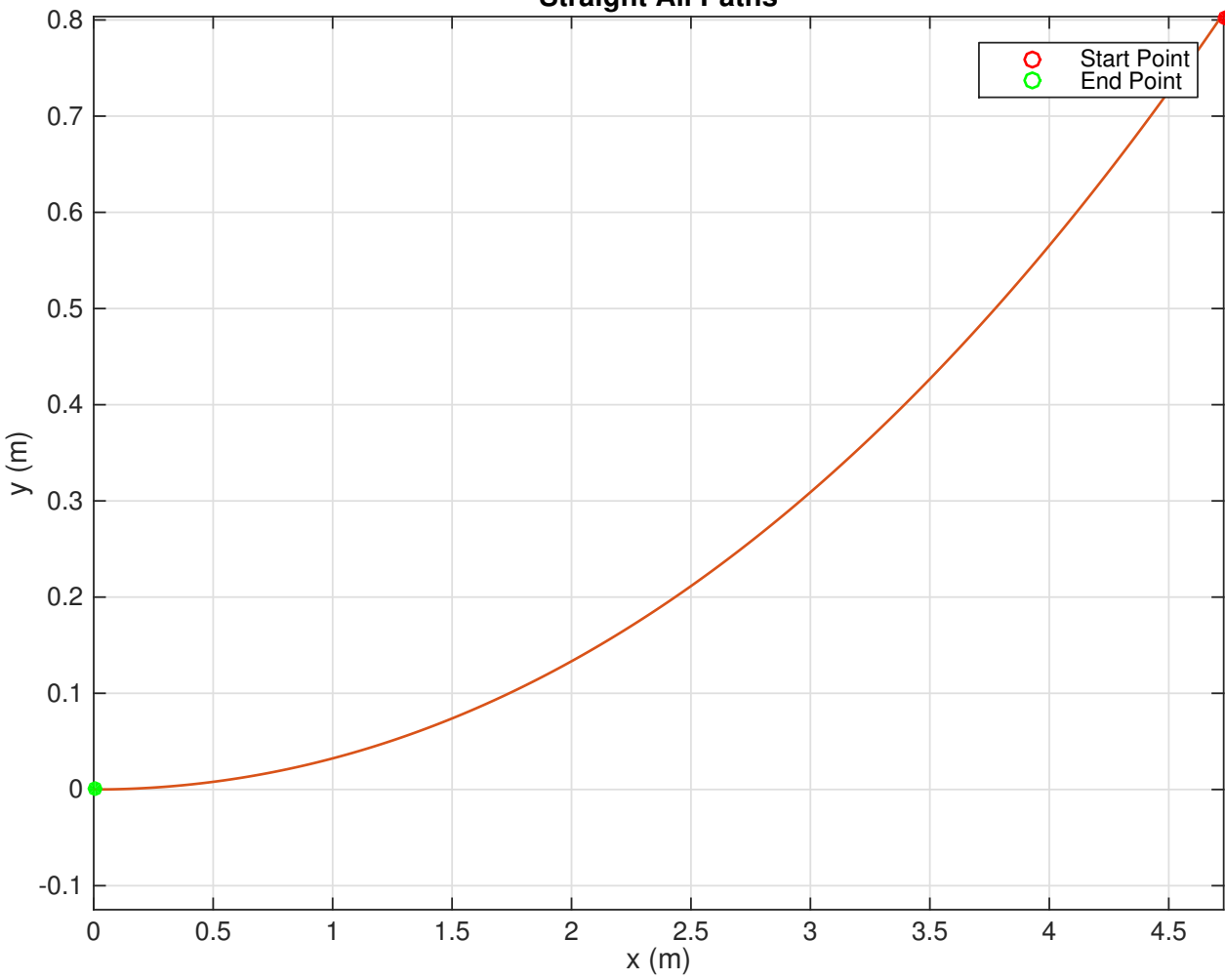
Angled\_right Camera Angles and Edge Distances



Angled\_right Steering



Straight All Paths



Number\_Of\_Unique\_Paths

King\_Pin\_Detected

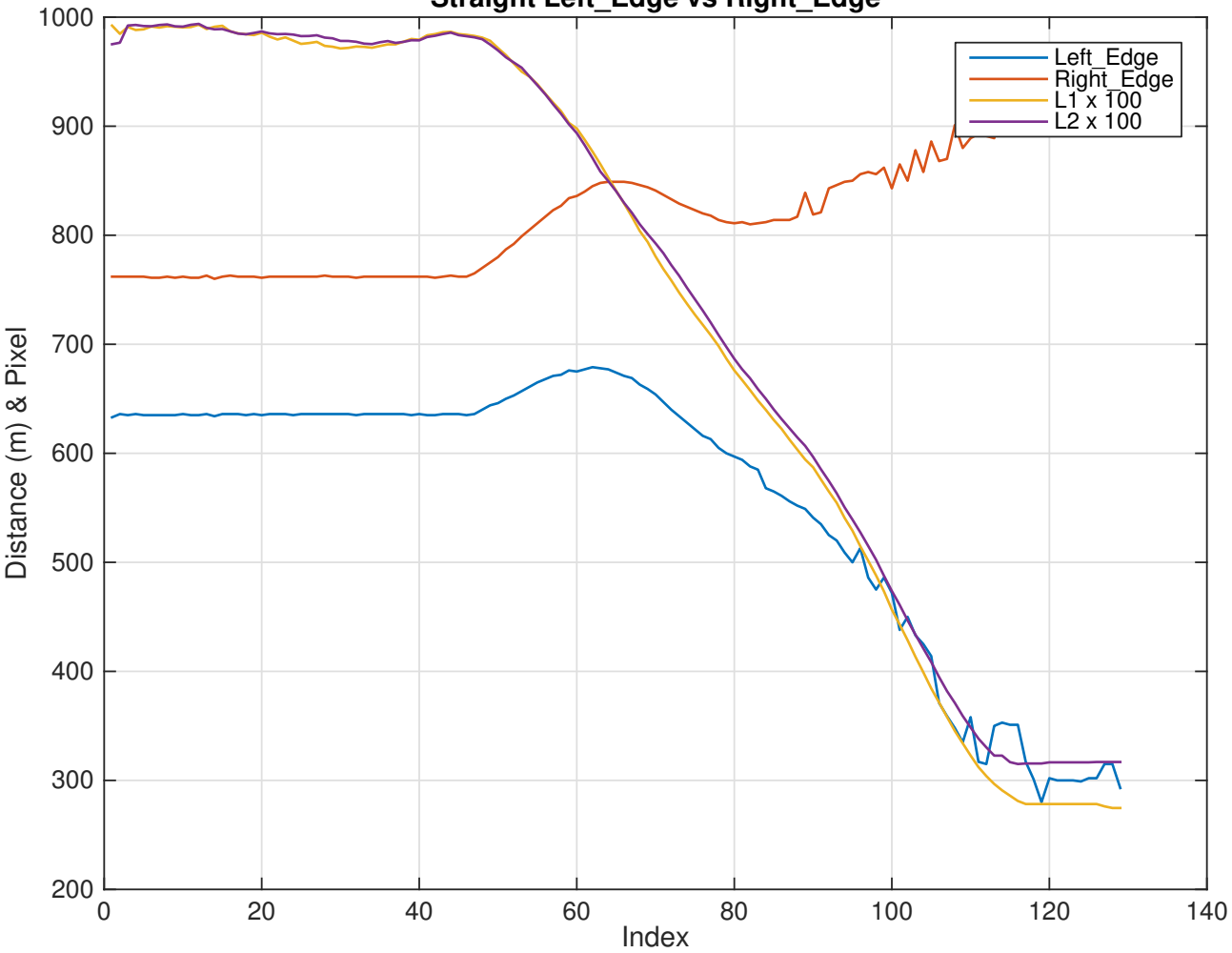
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2

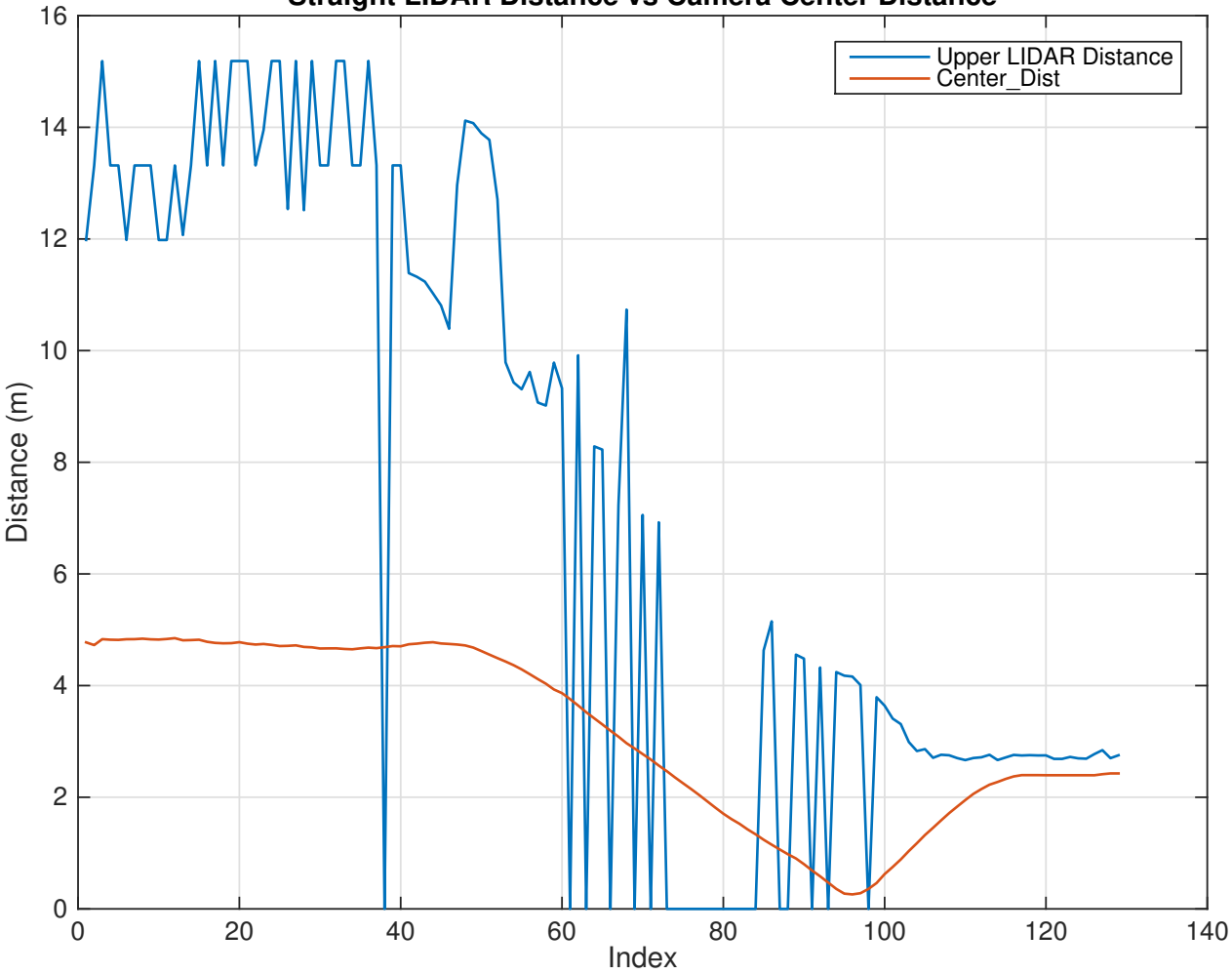
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false

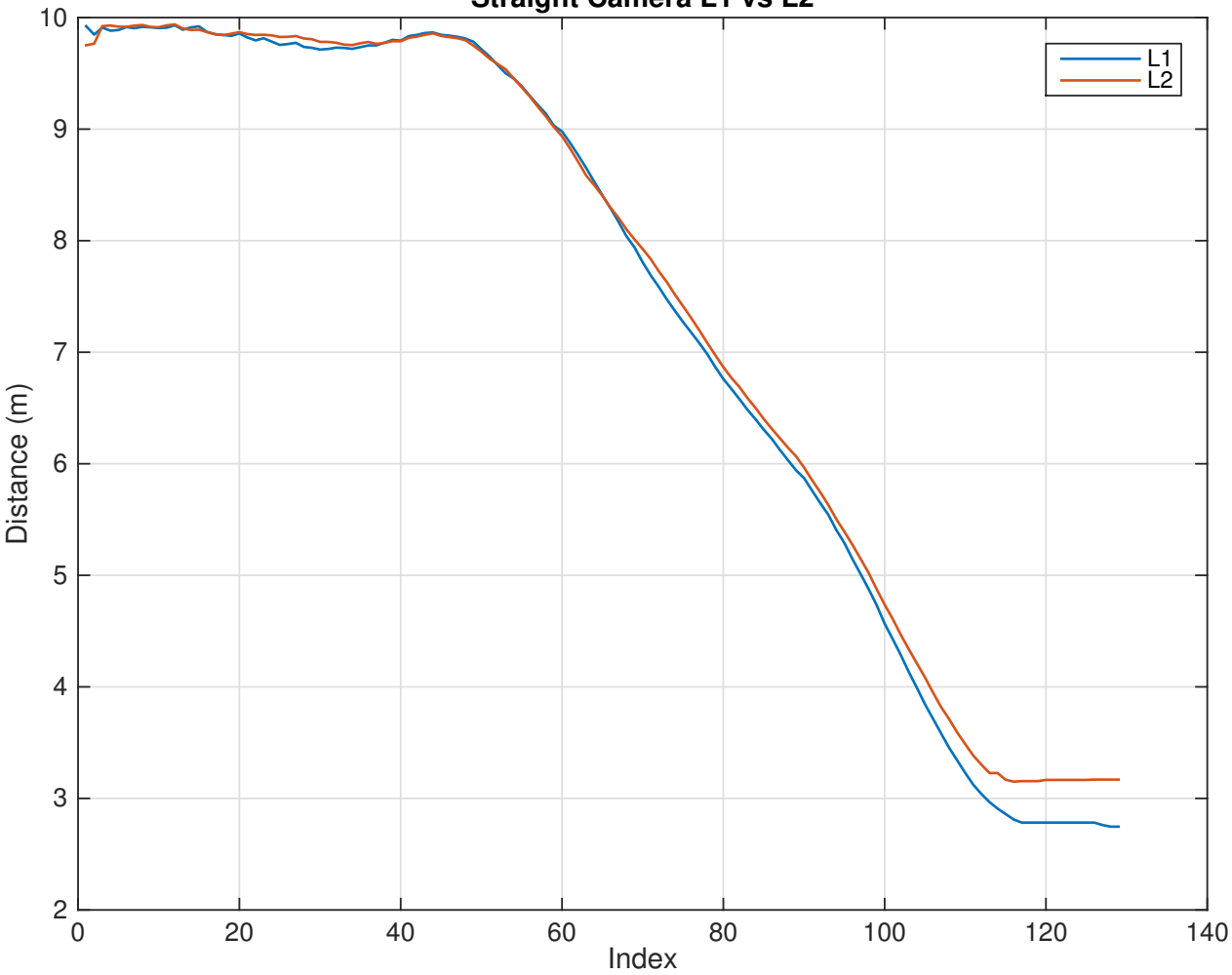
Straight Left\_Edge vs Right\_Edge



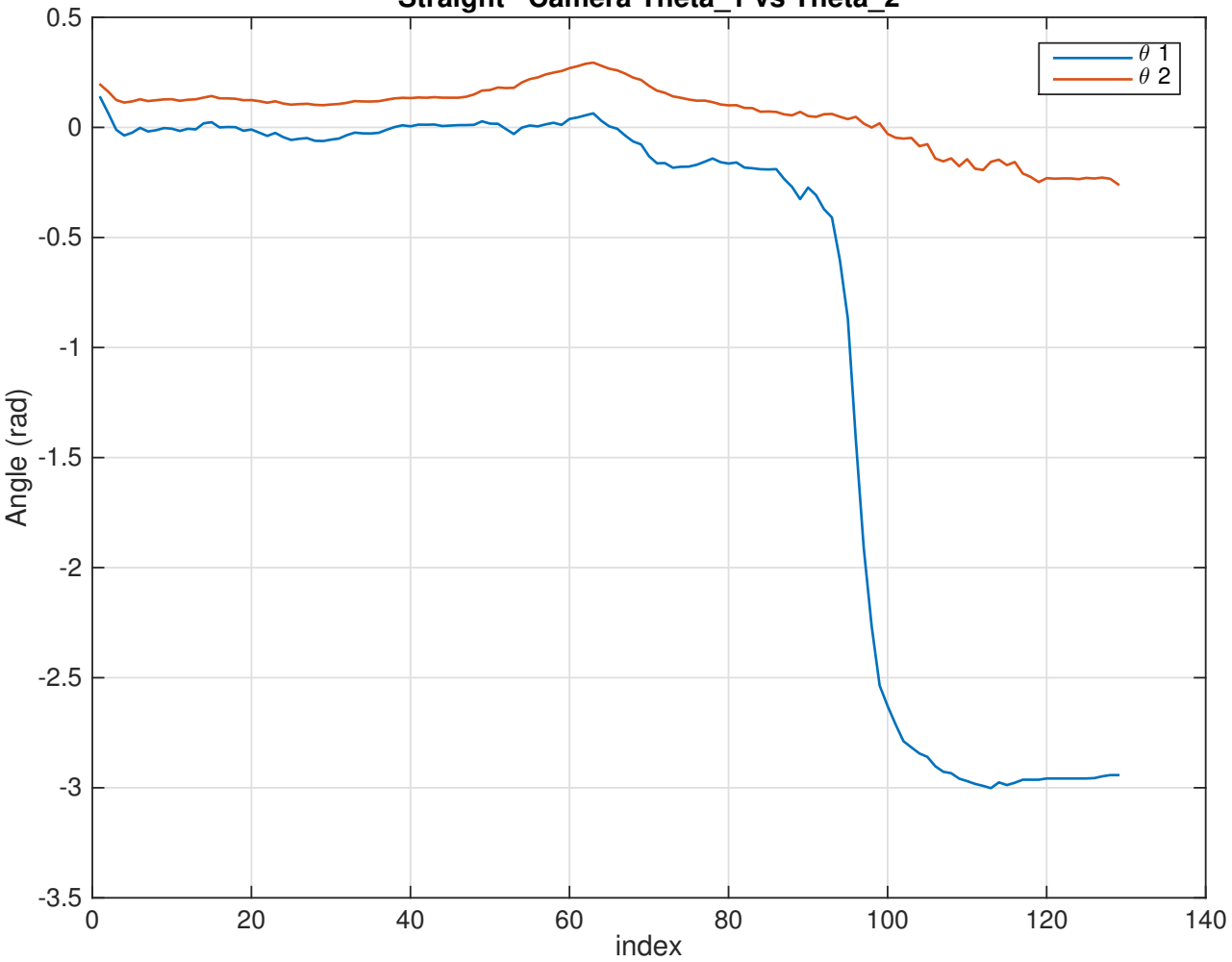
**Straight LIDAR Distance vs Camera Center Distance**



Straight Camera L1 vs L2

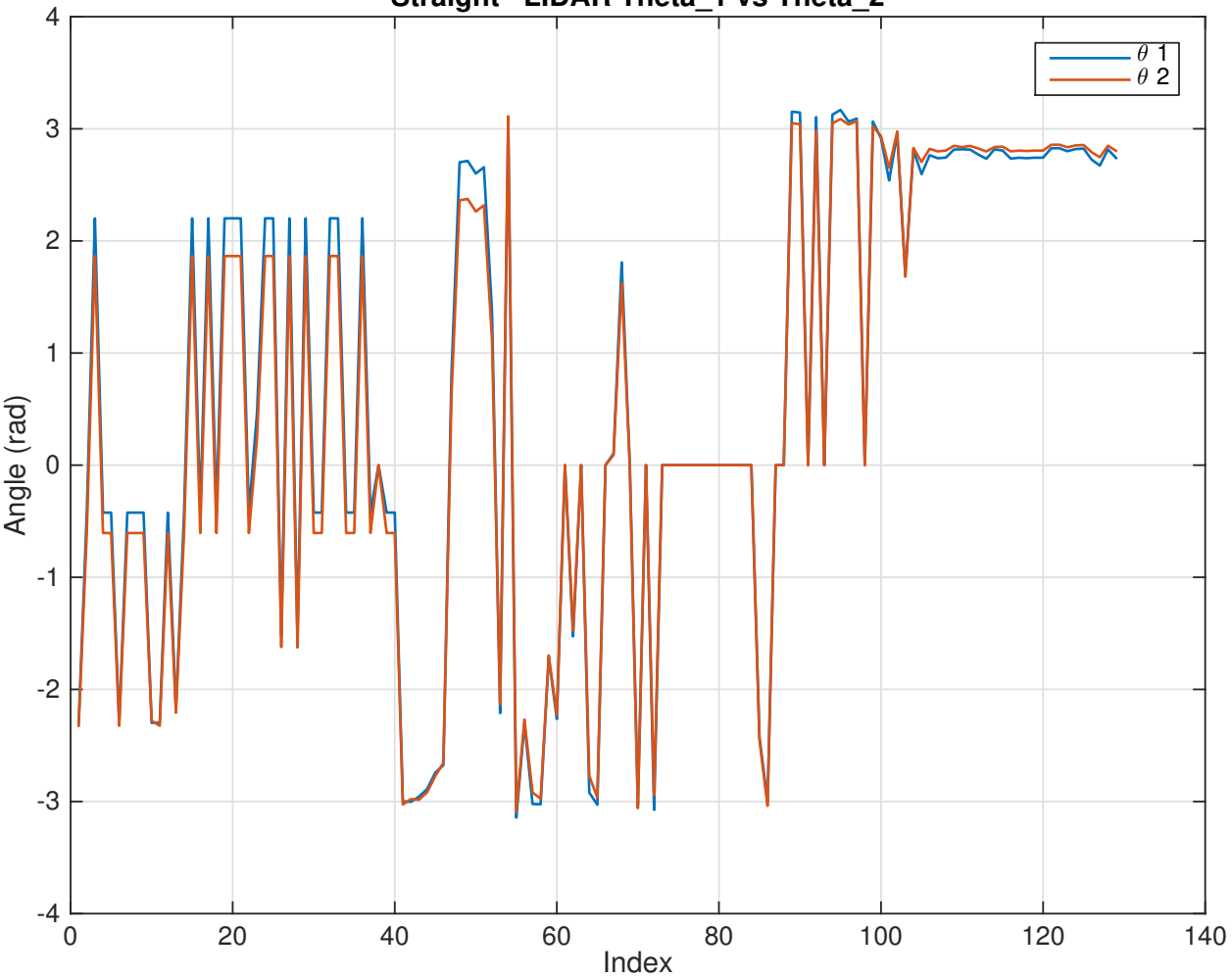


Straight Camera Theta\_1 vs Theta\_2

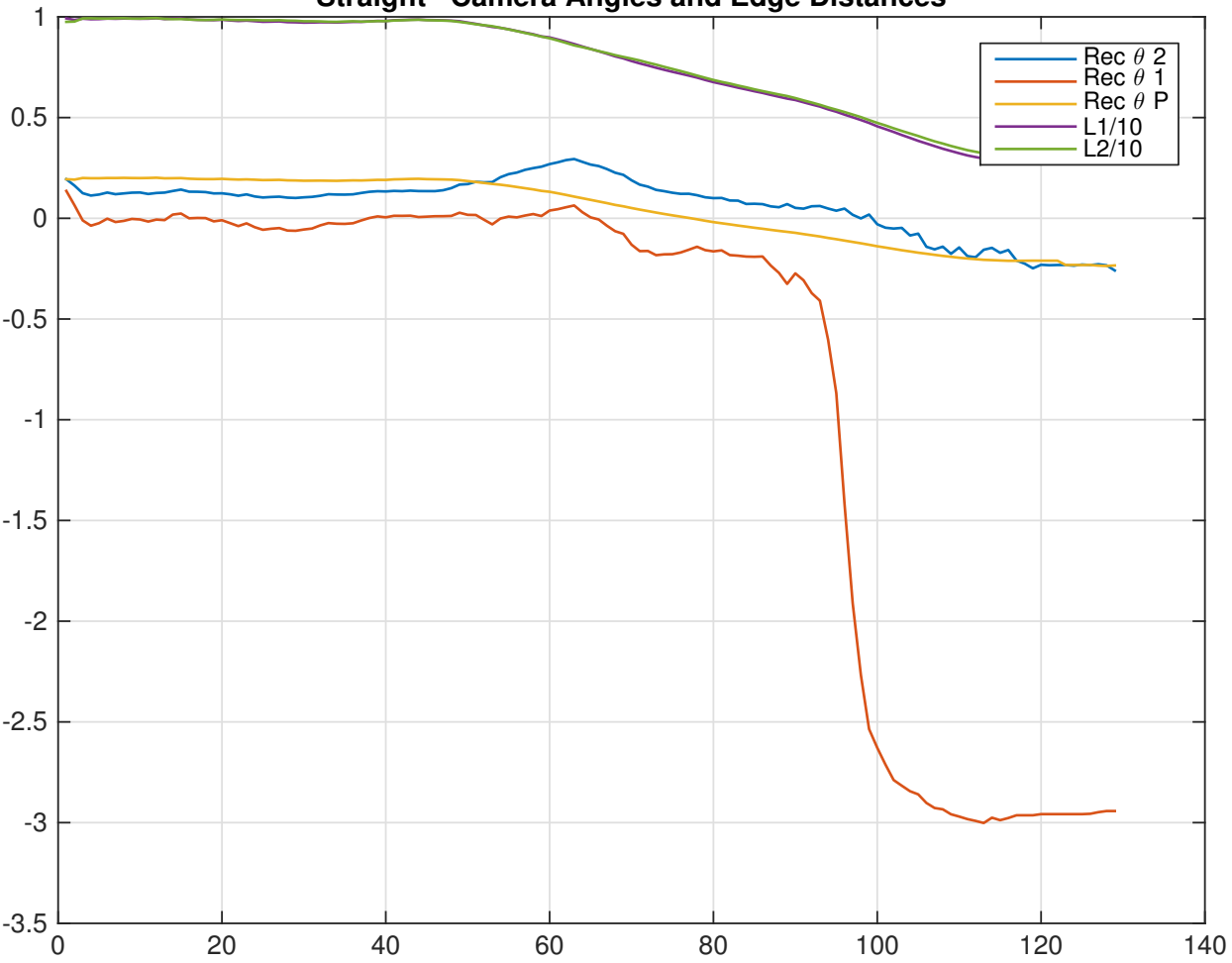




Straight LIDAR Theta\_1 vs Theta\_2



**Straight Camera Angles and Edge Distances**



# Straight Steering

