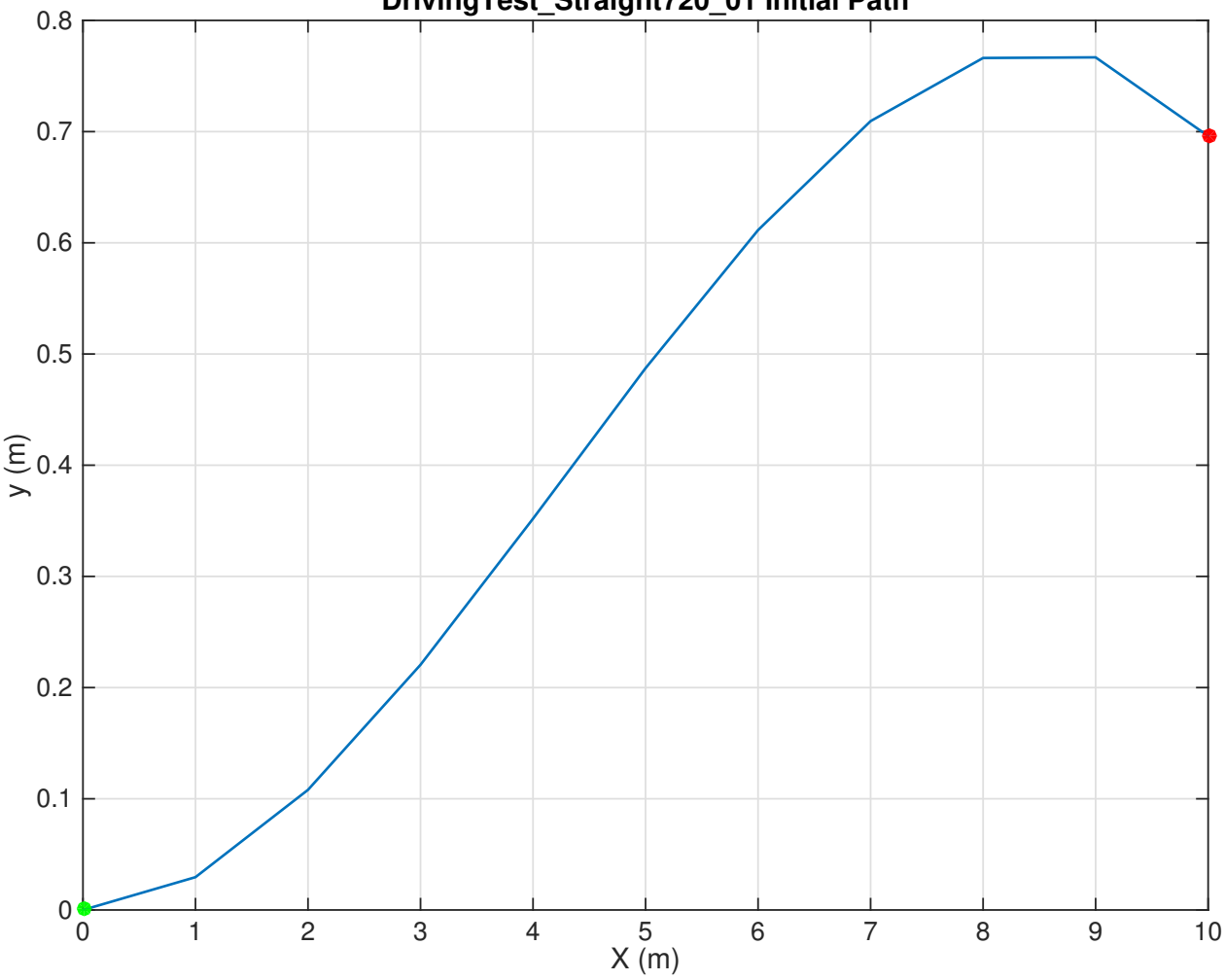
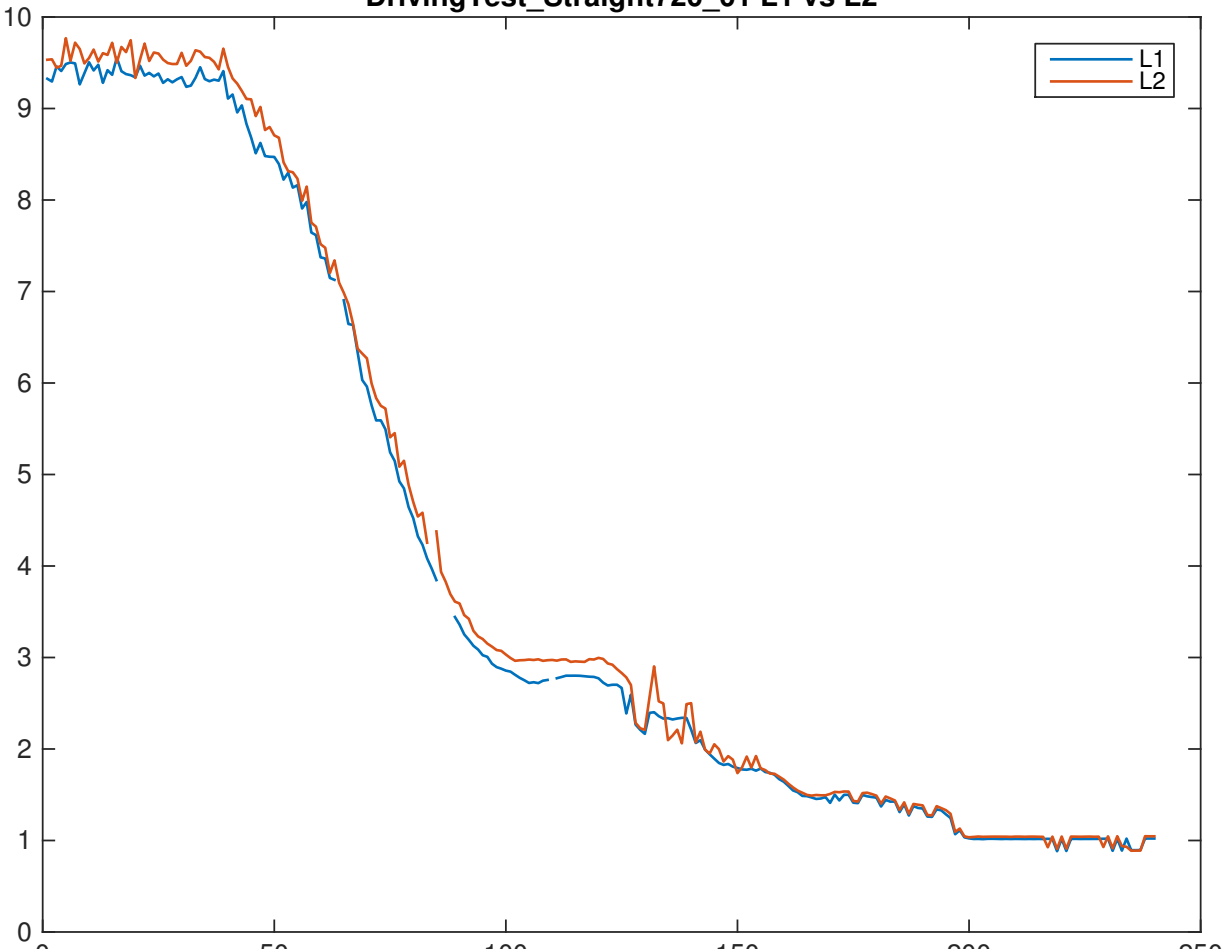


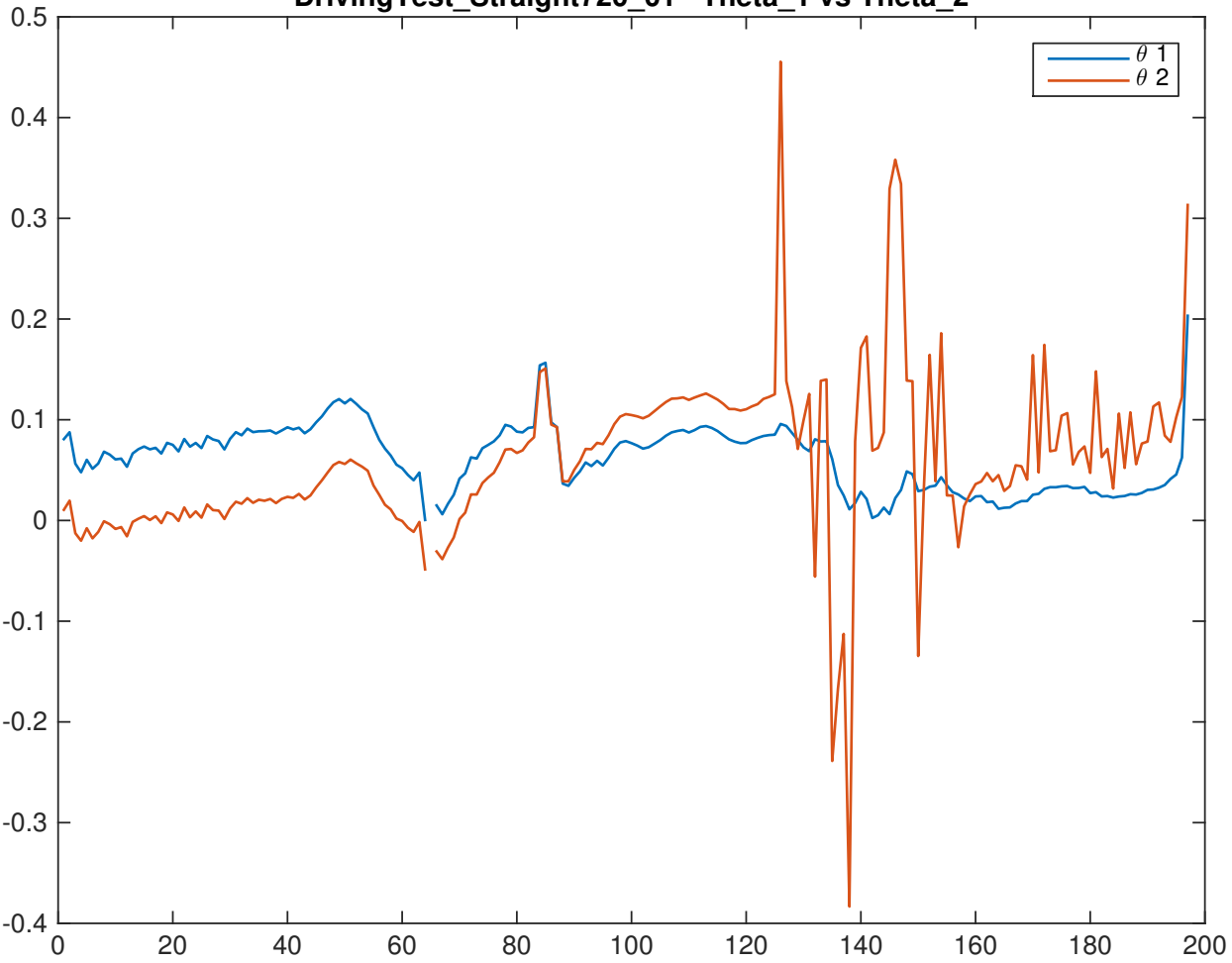
DrivingTest_Straight720_01 Initial Path



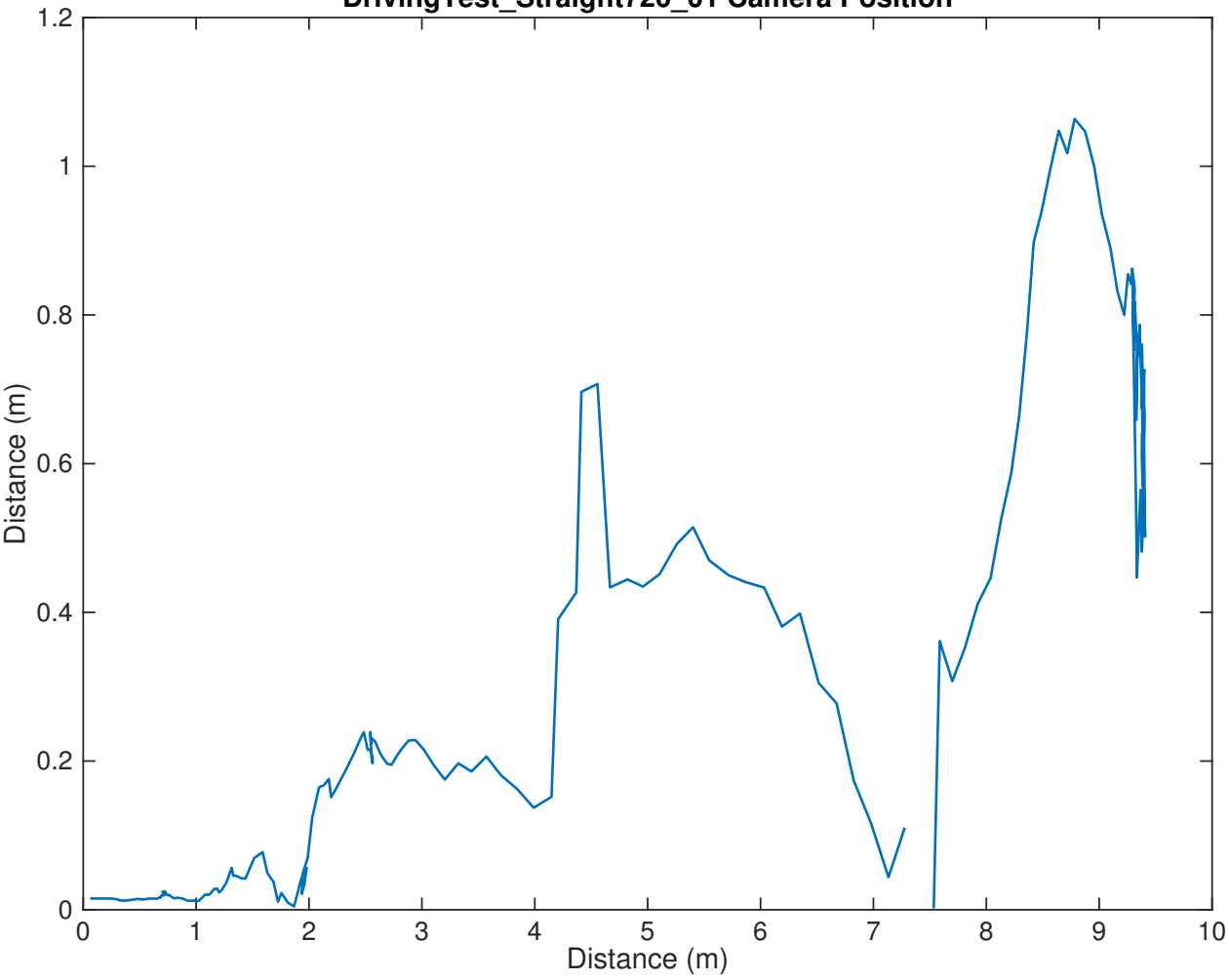
DrivingTest_Straight720_01 L1 vs L2



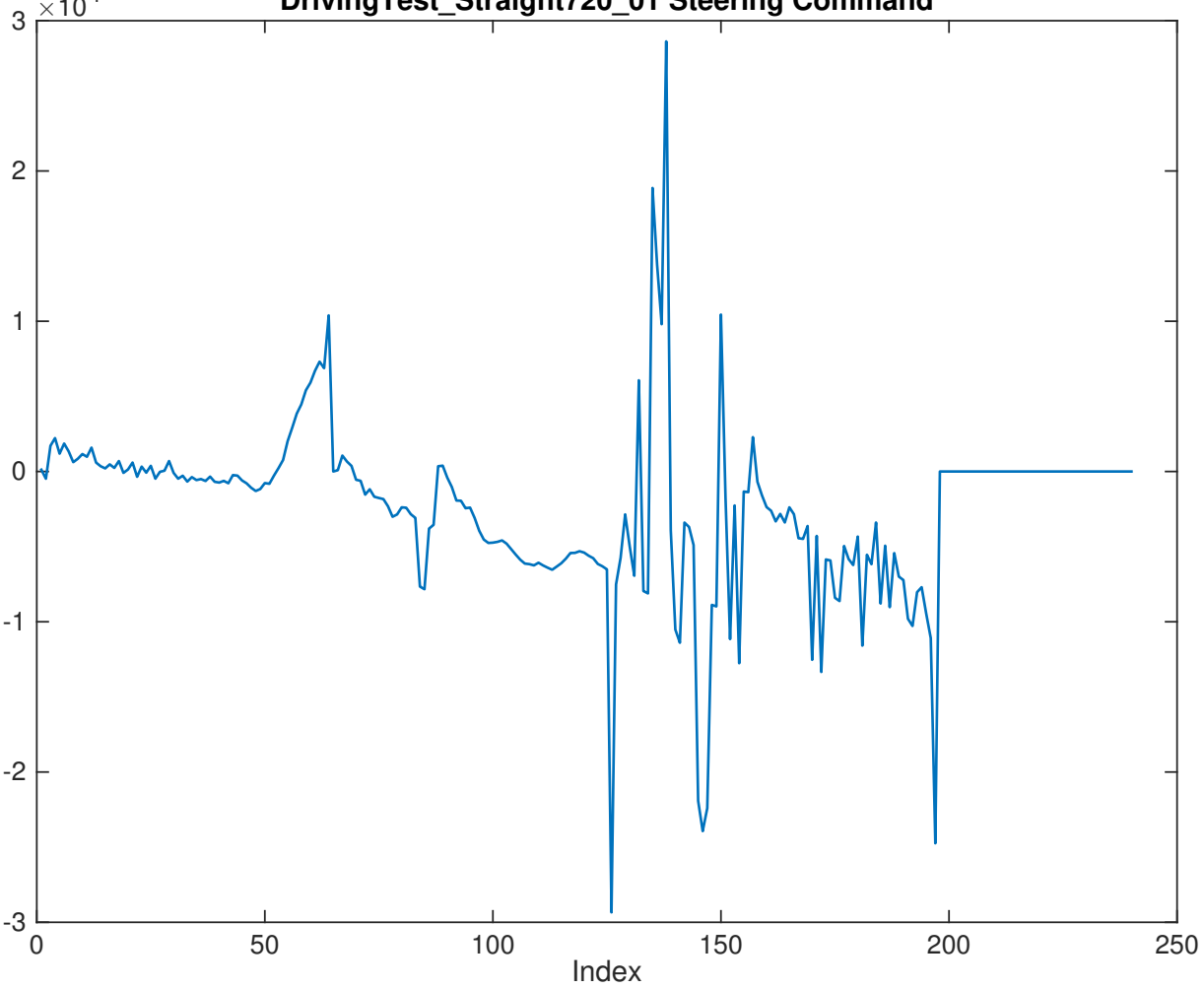
DrivingTest_Straight720_01 Theta_1 vs Theta_2



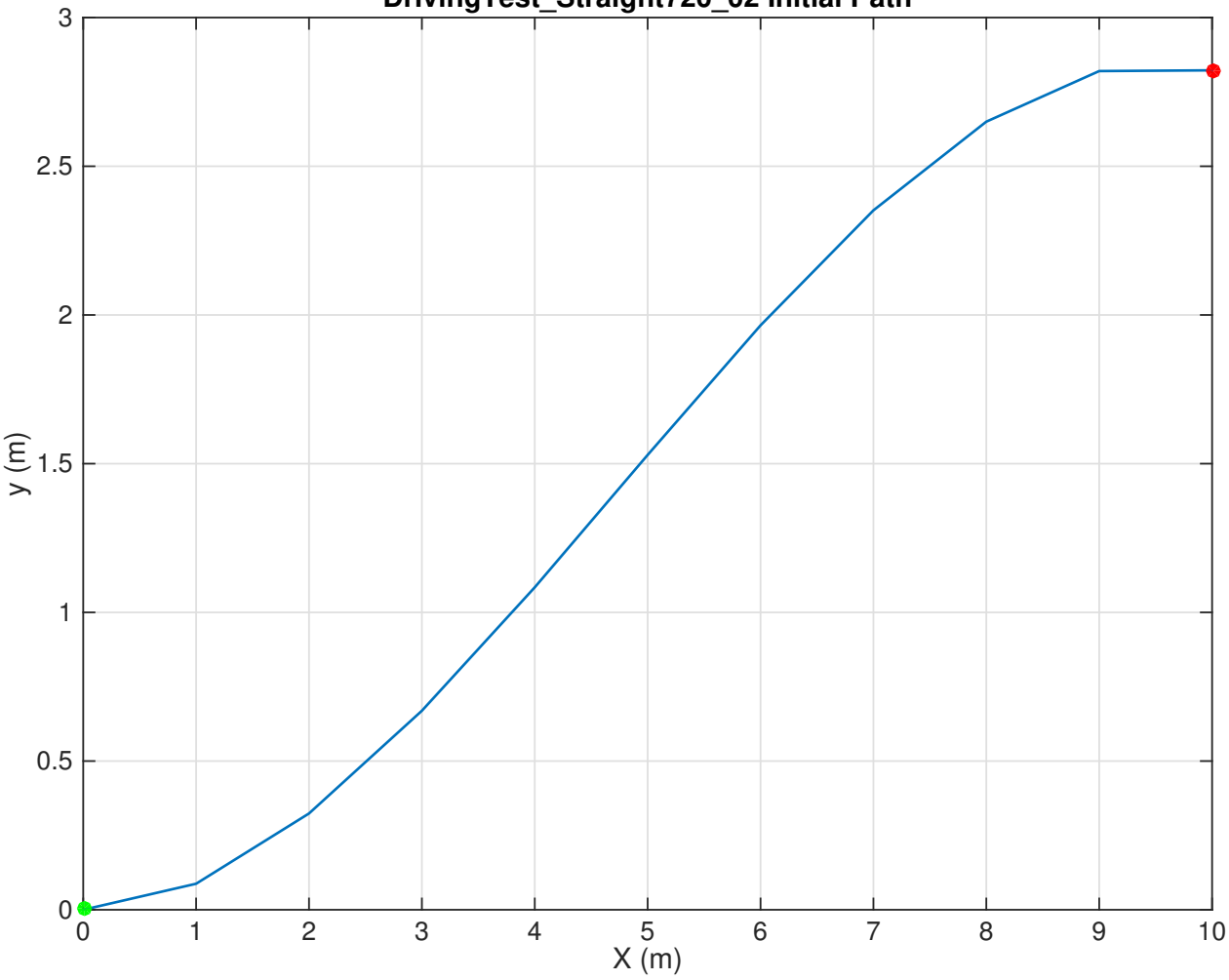
DrivingTest_Straight720_01 Camera Position



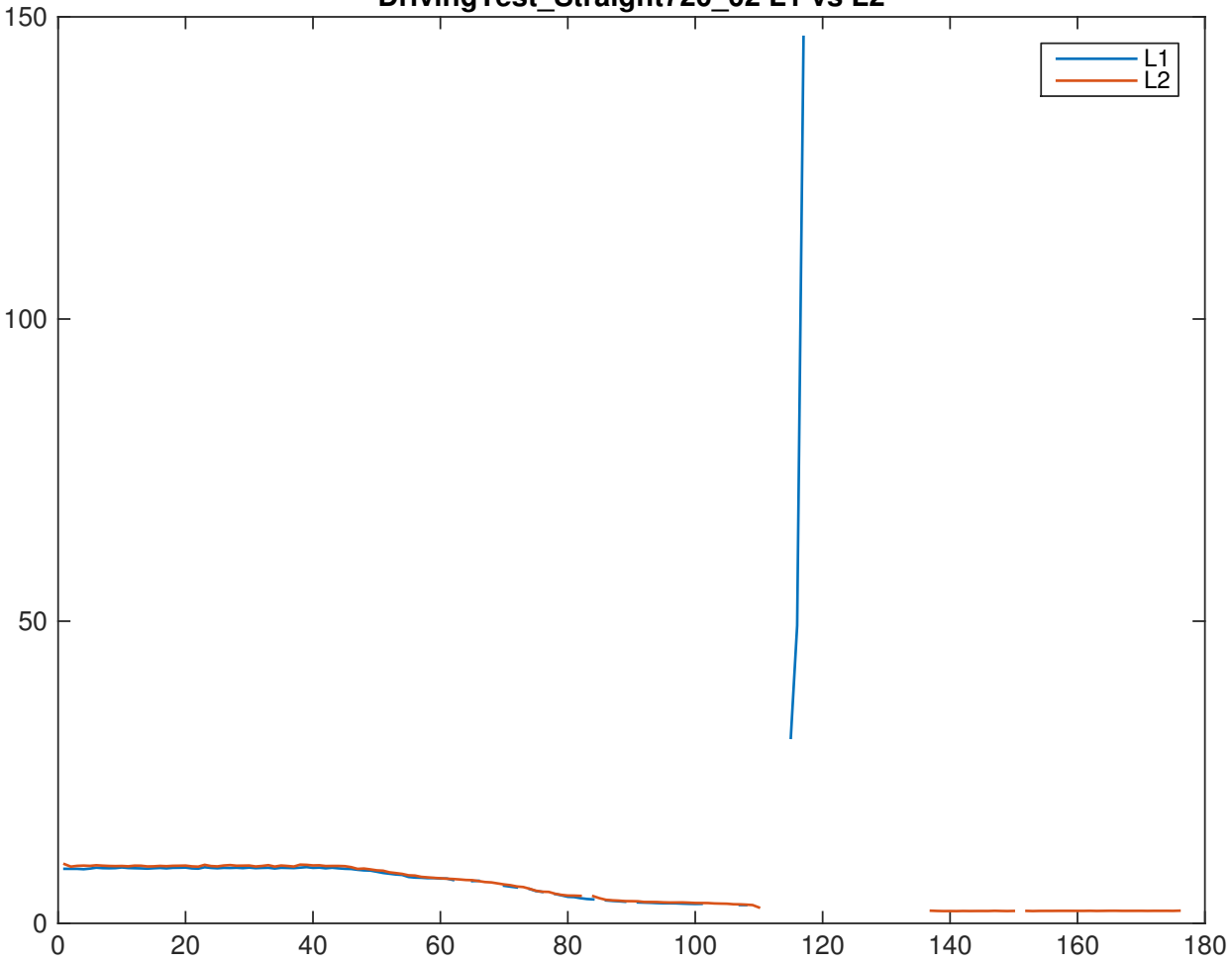
DrivingTest_Straight720_01 Steering Command



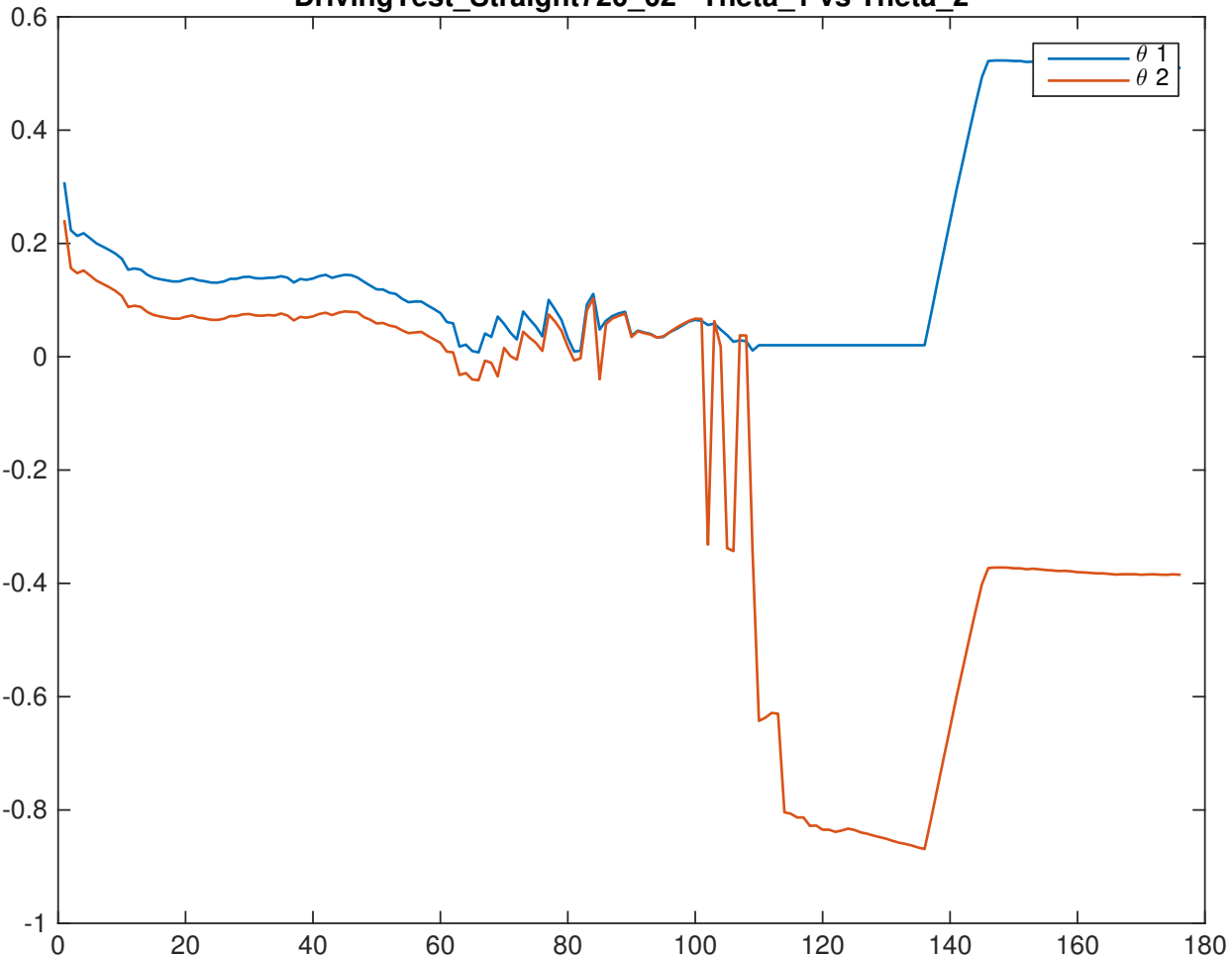
DrivingTest_Straight720_02 Initial Path



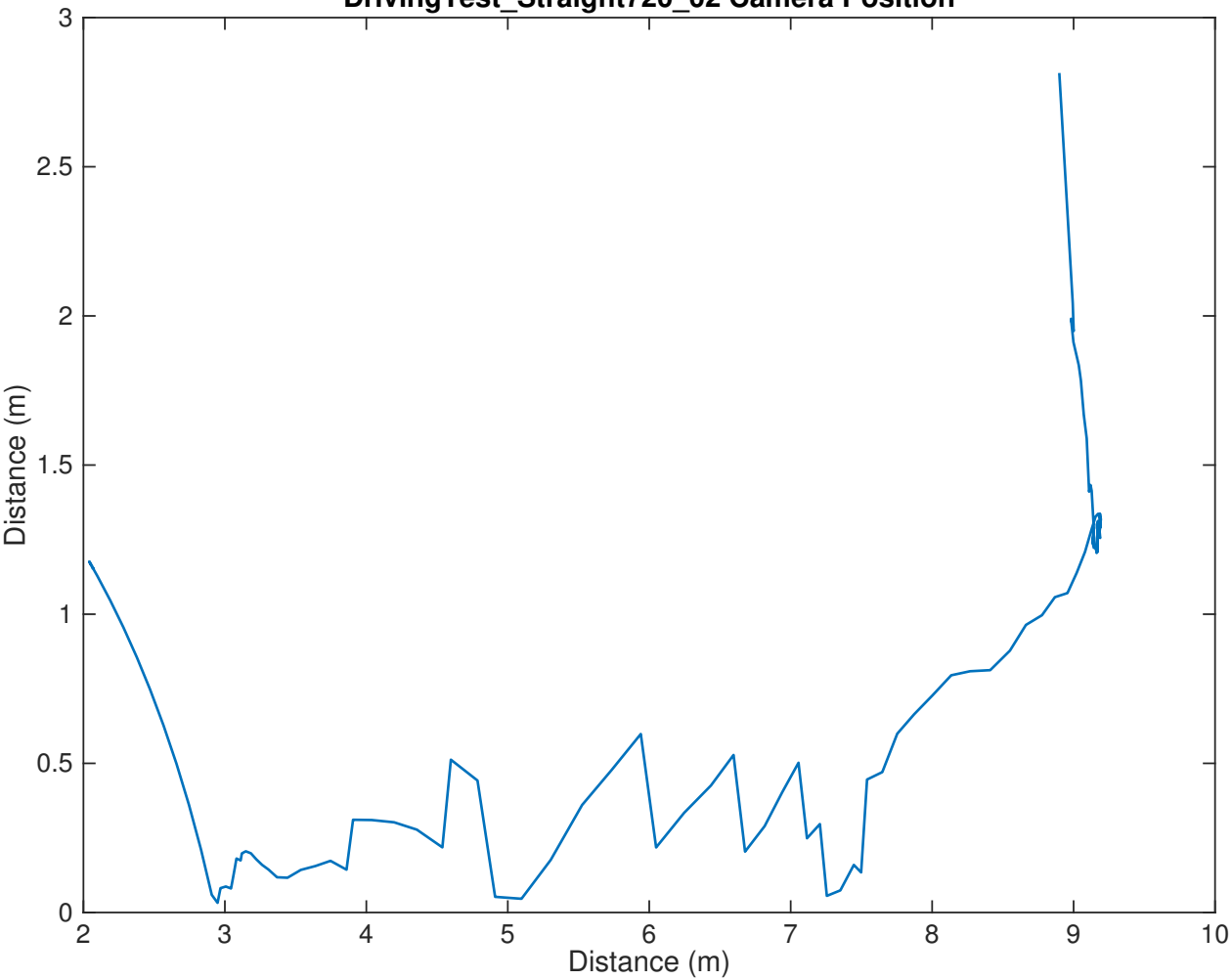
DrivingTest_Straight720_02 L1 vs L2



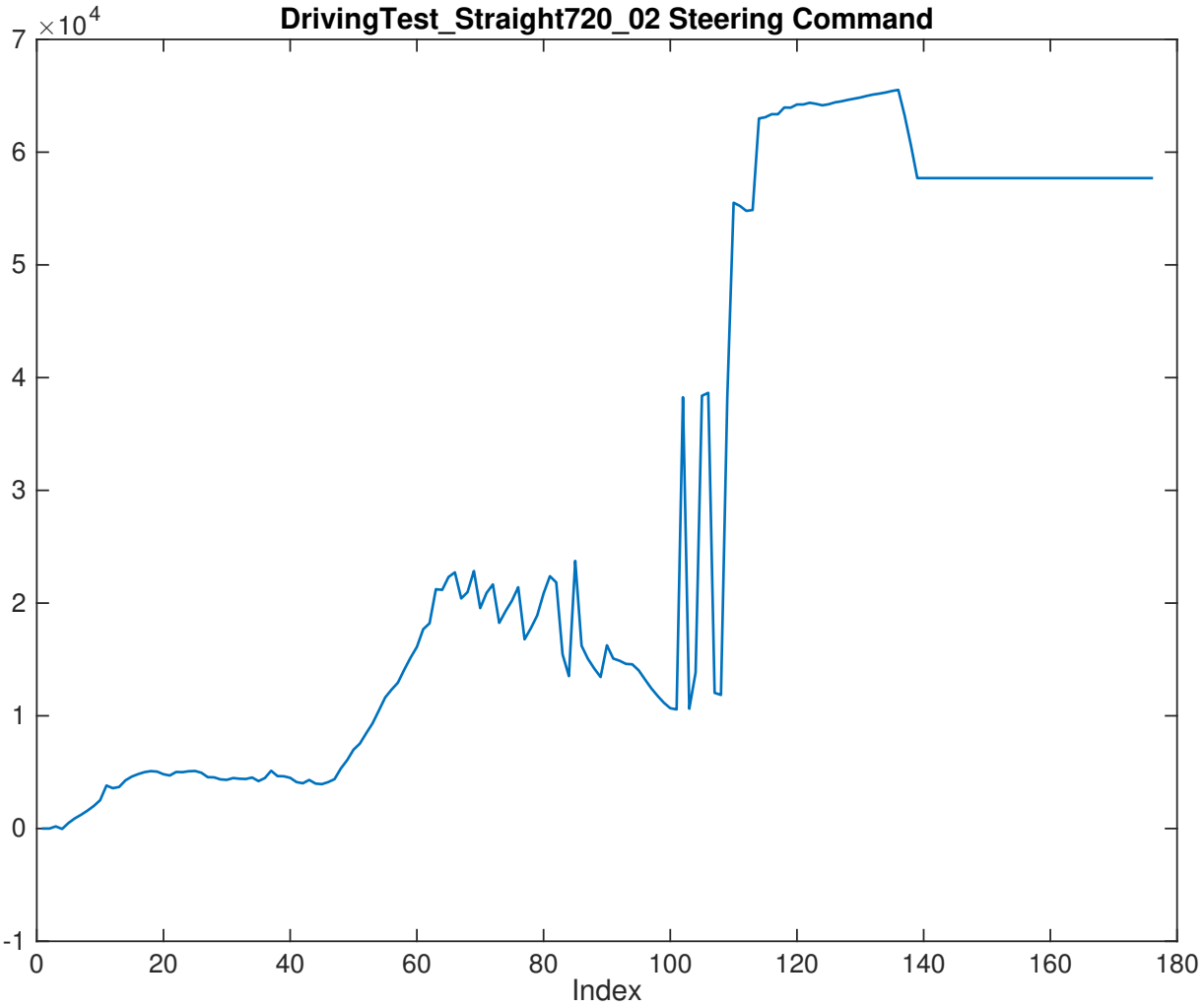
DrivingTest_Straight720_02 Theta_1 vs Theta_2



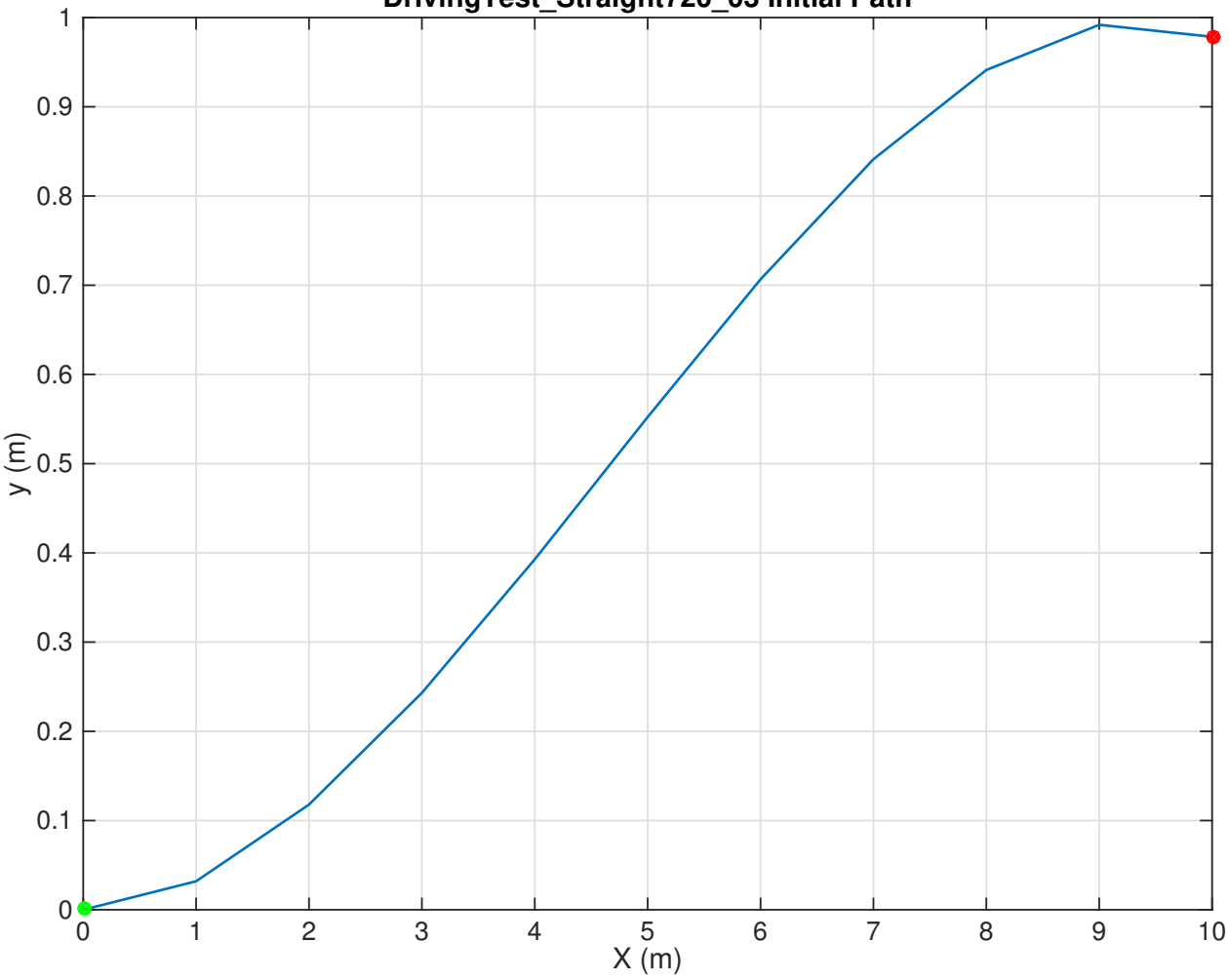
DrivingTest_Straight720_02 Camera Position



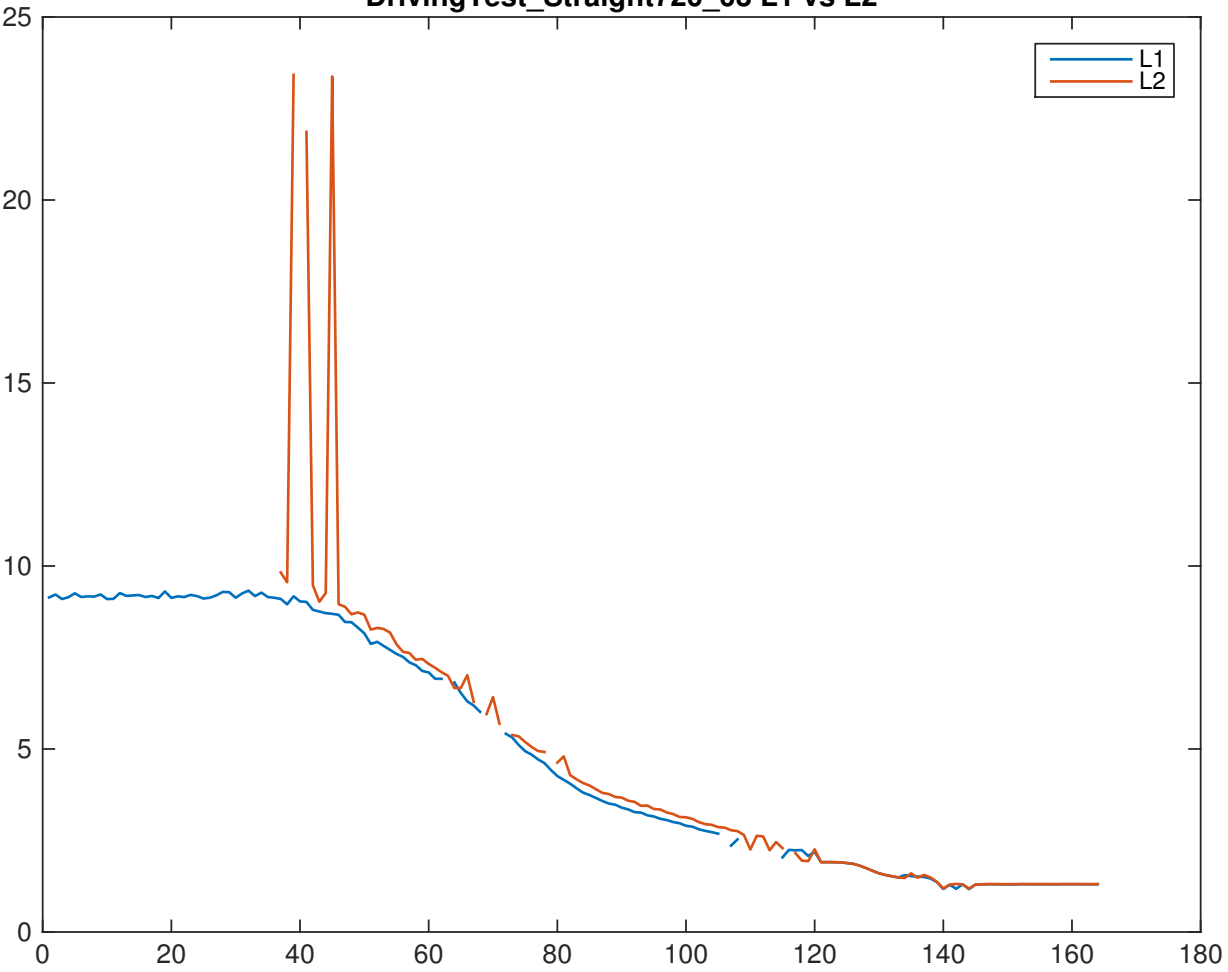
DrivingTest_Straight720_02 Steering Command



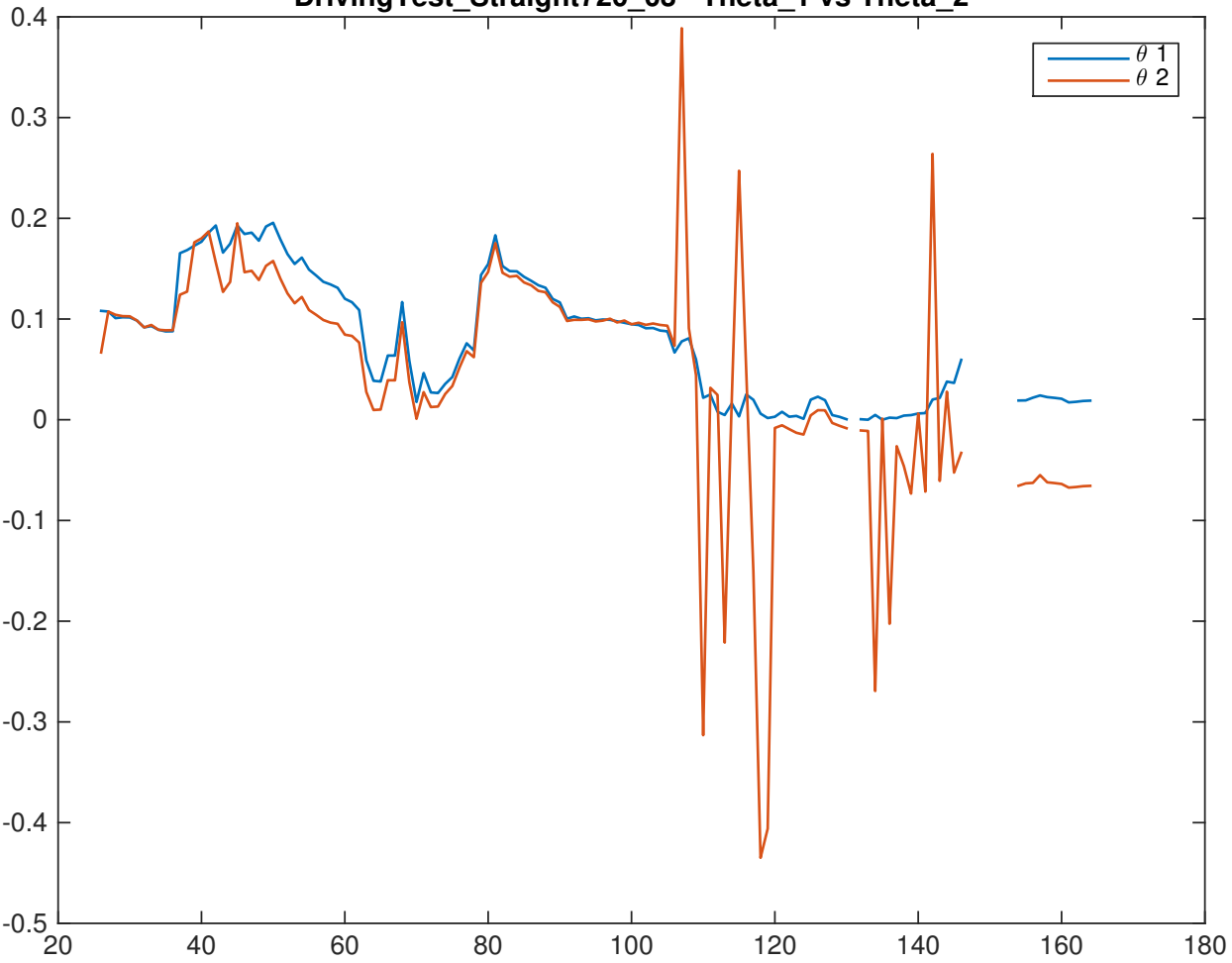
DrivingTest_Straight720_03 Initial Path



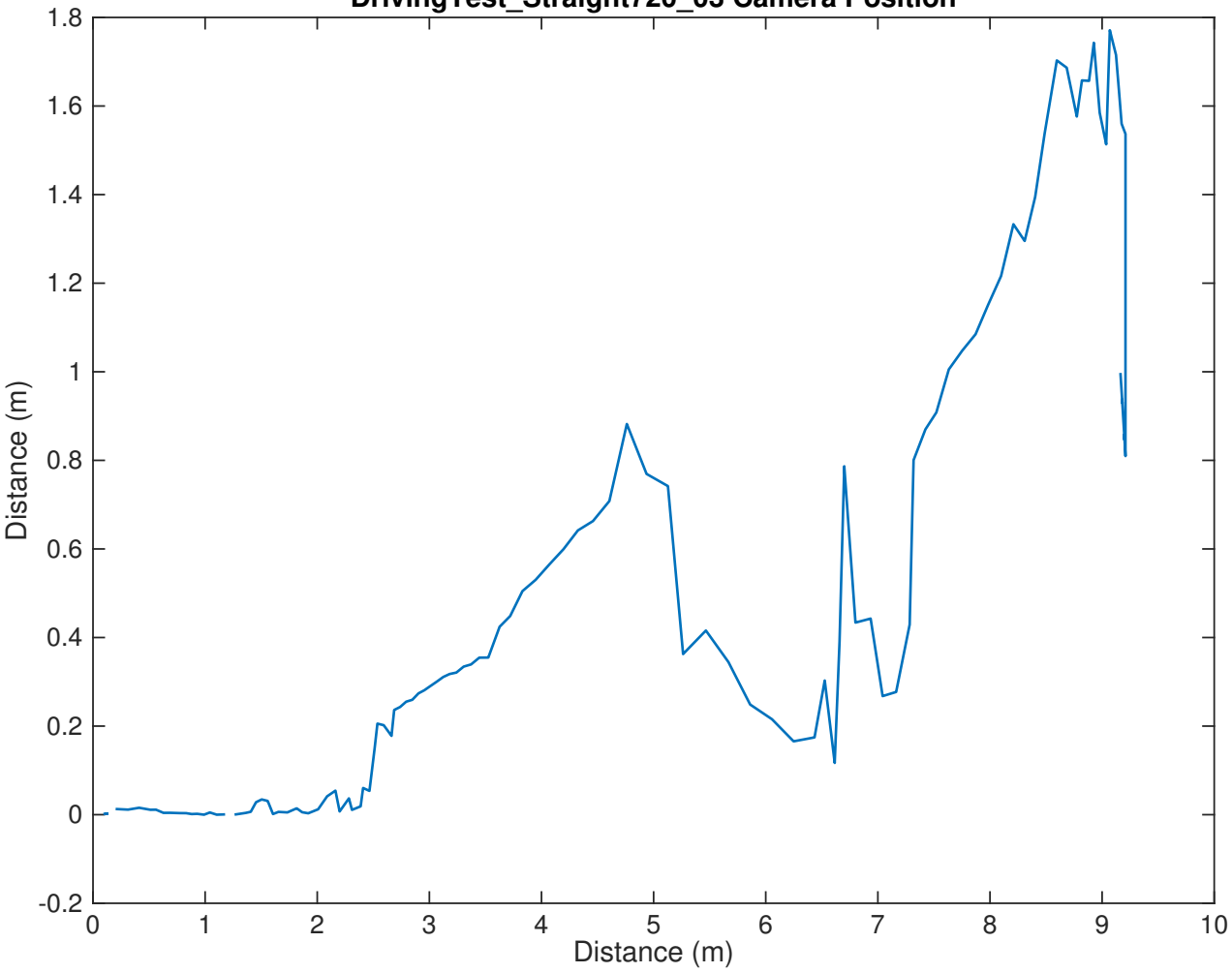
DrivingTest_Straight720_03 L1 vs L2

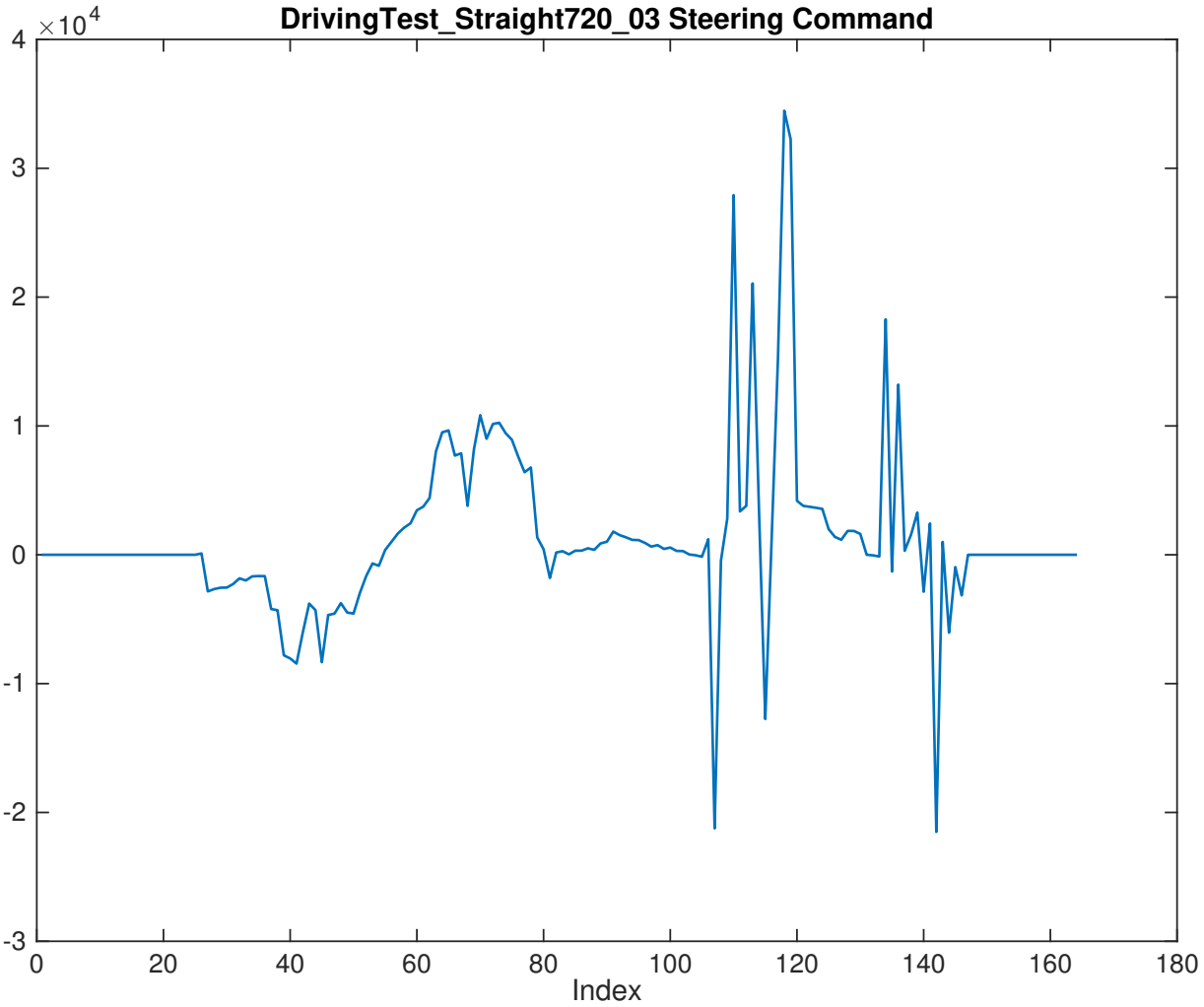


DrivingTest_Straight720_03 Theta_1 vs Theta_2

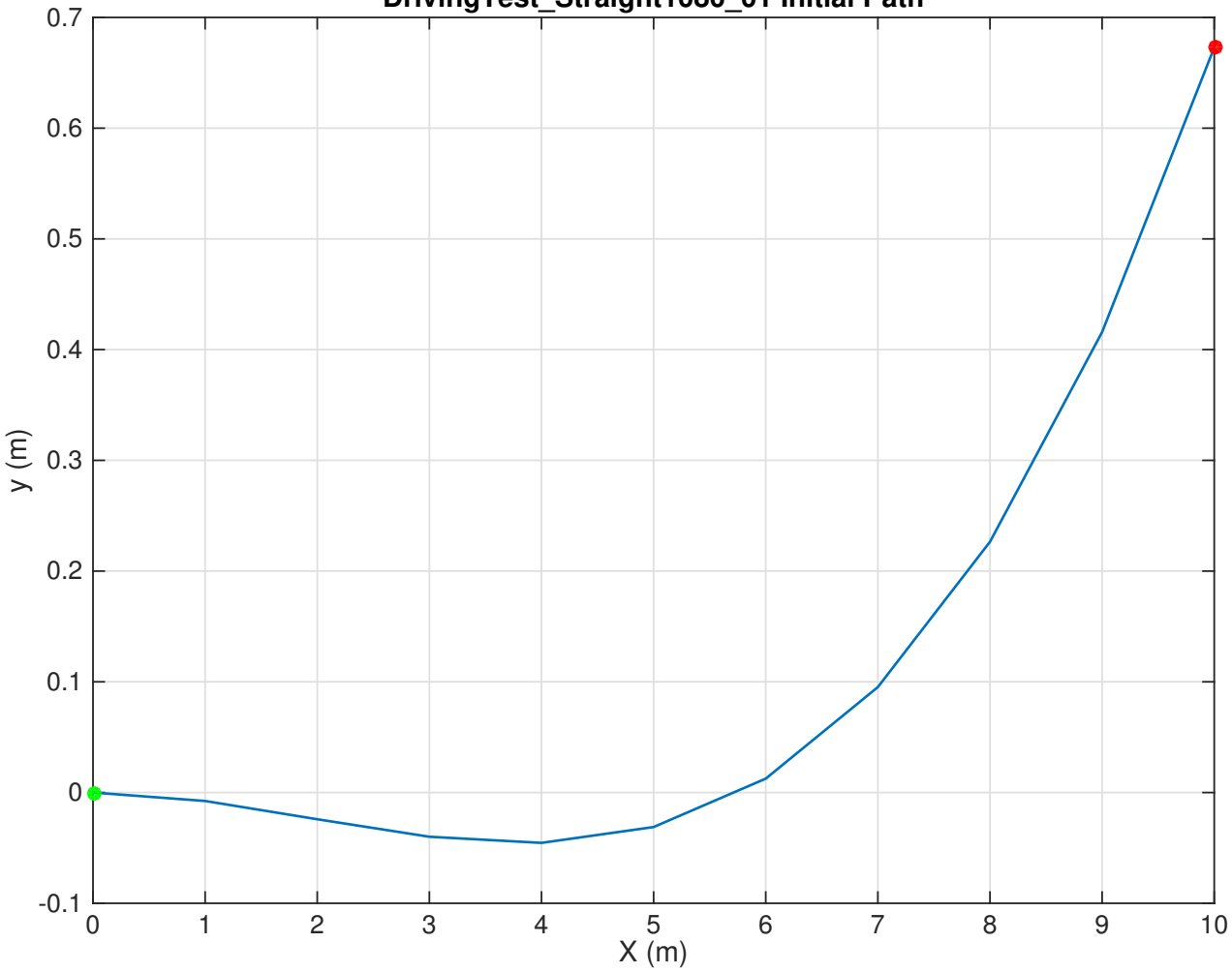


DrivingTest_Straight720_03 Camera Position

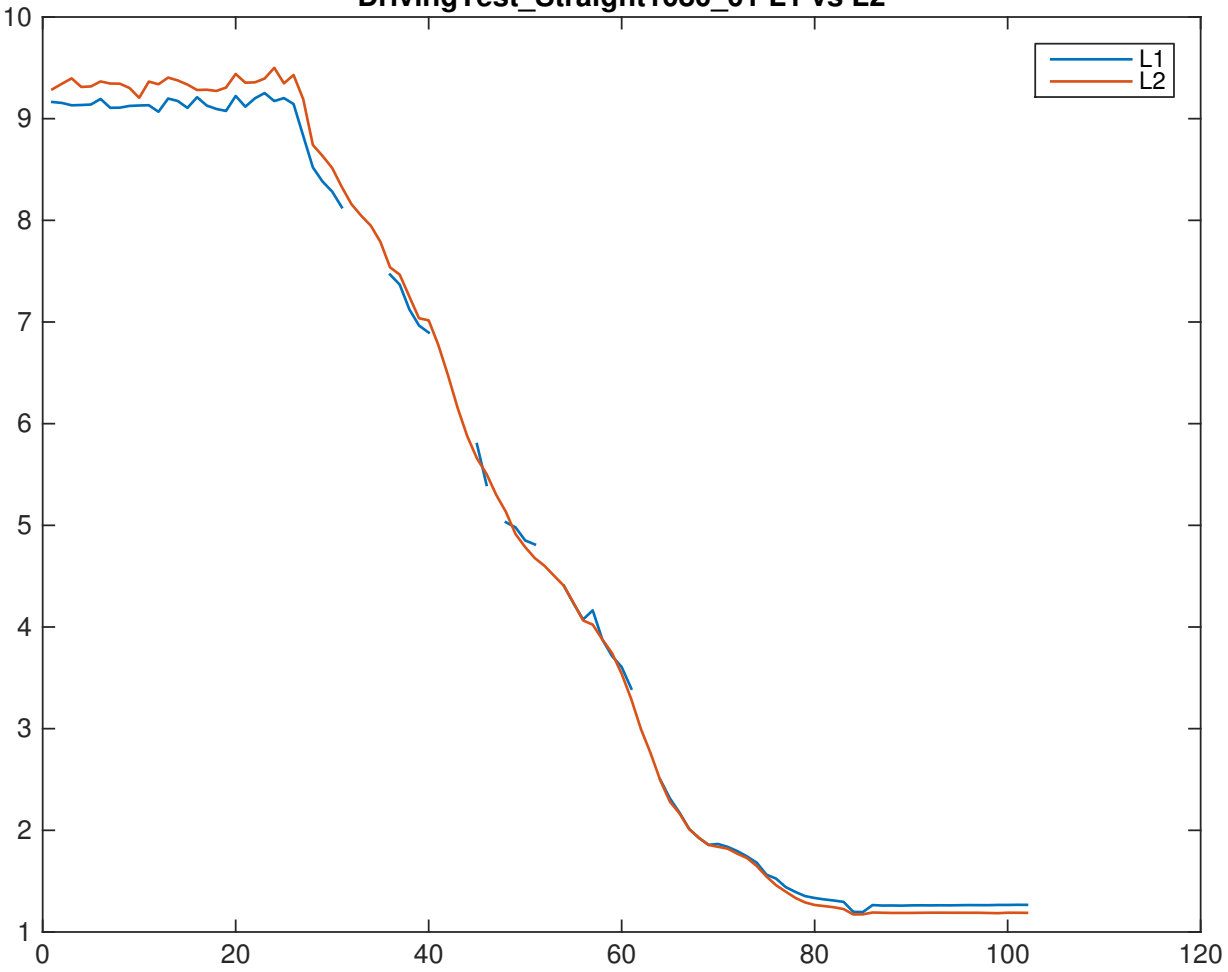




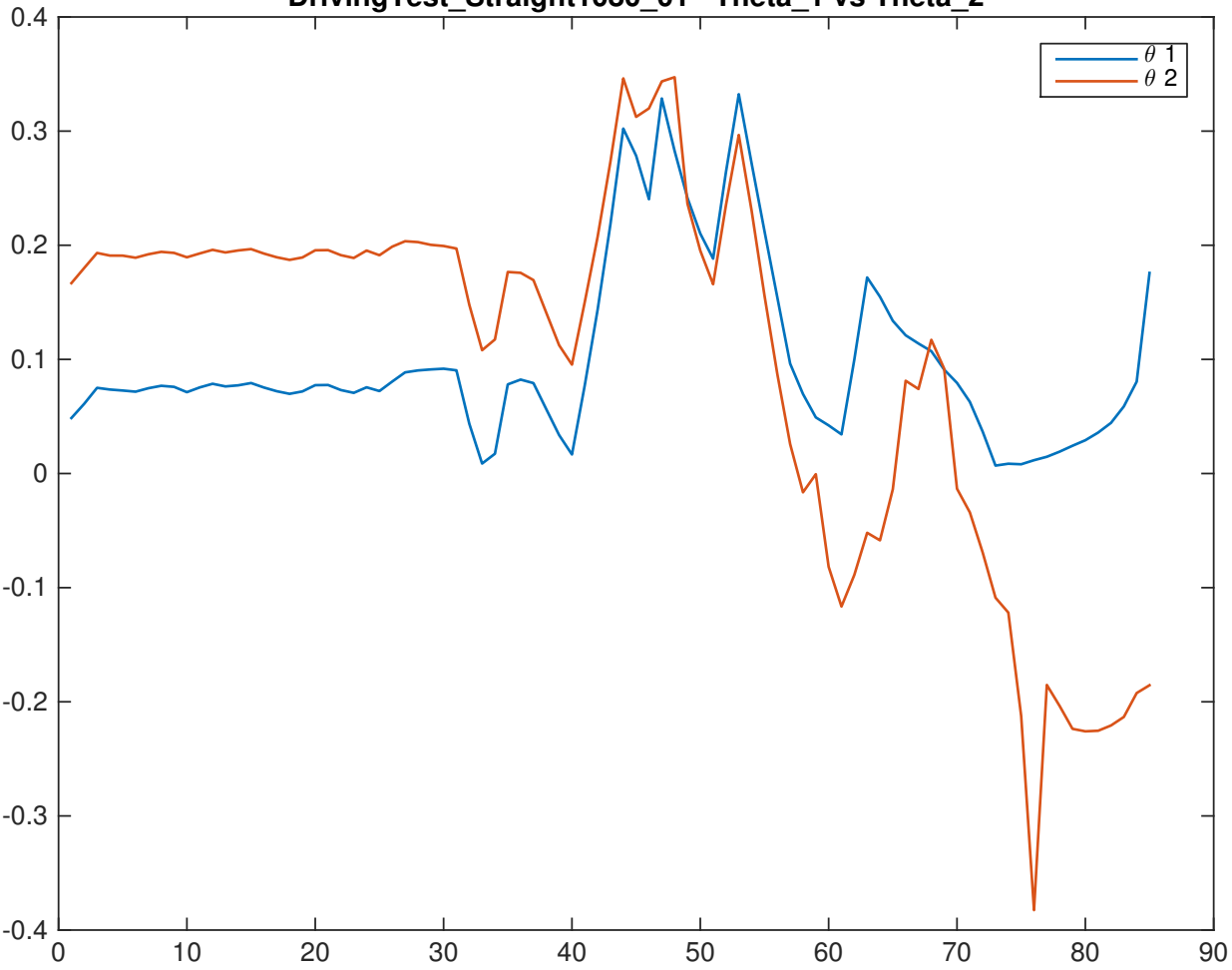
DrivingTest_Straight1080_01 Initial Path



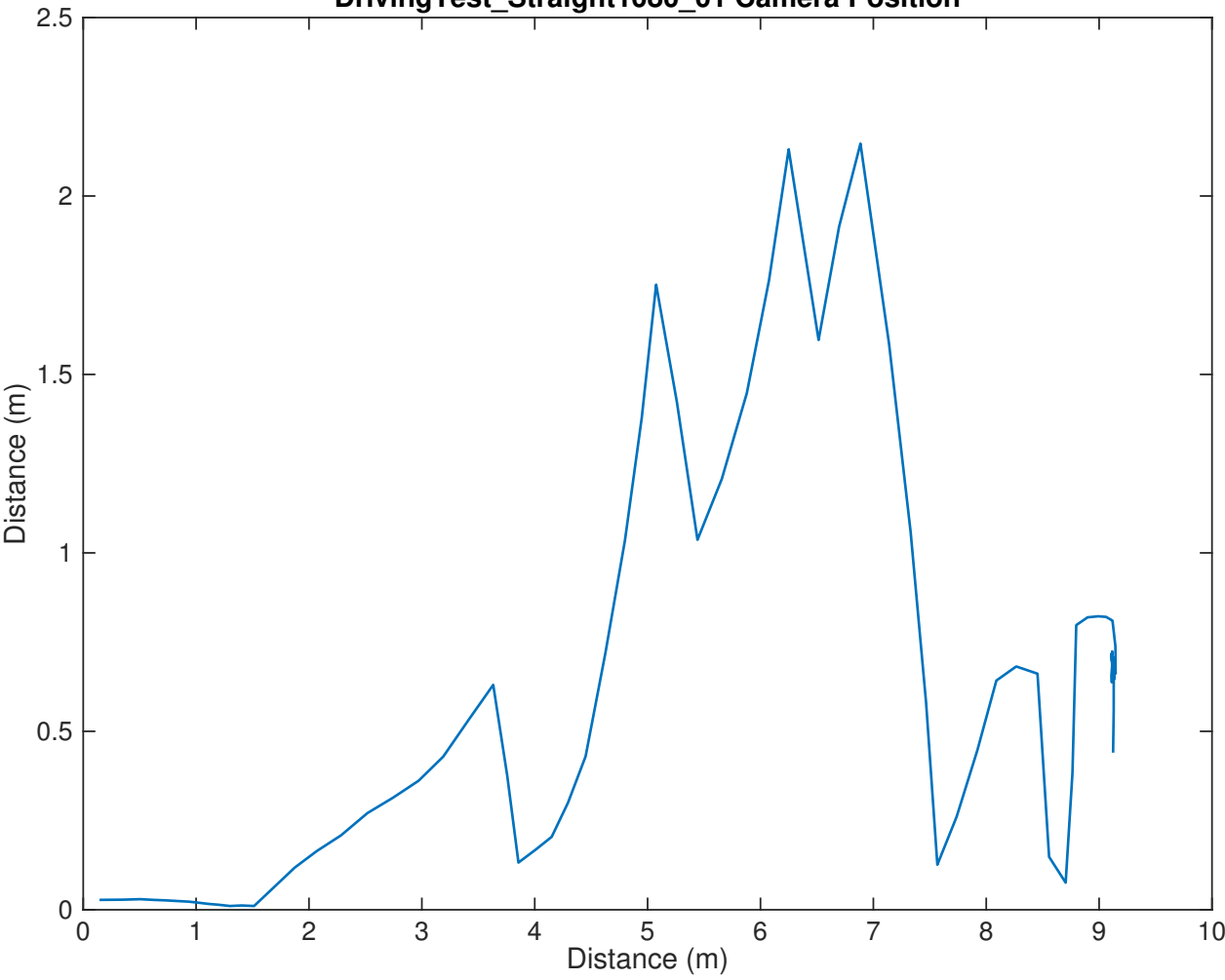
DrivingTest_Straight1080_01 L1 vs L2



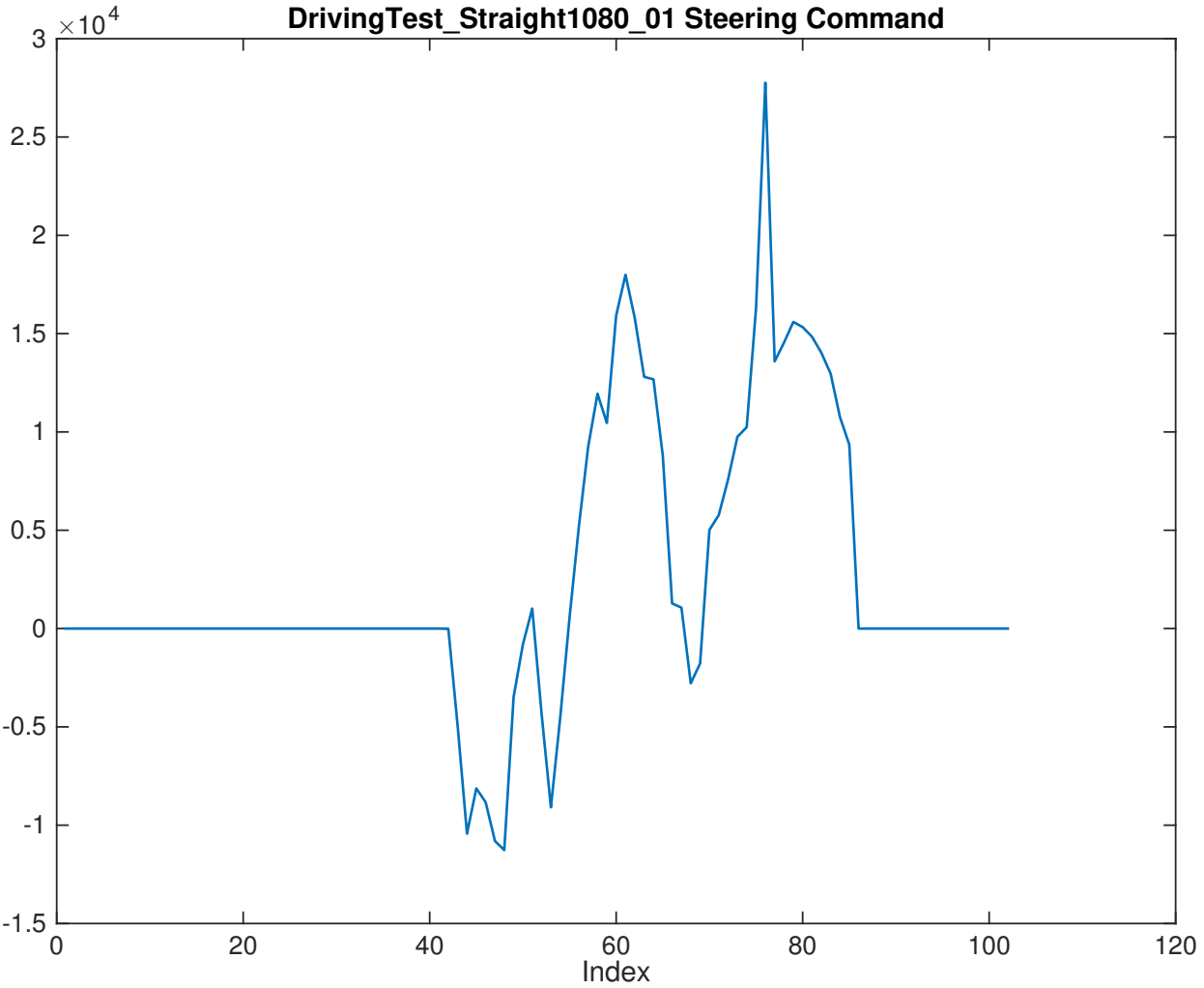
DrivingTest_Straight1080_01 Theta_1 vs Theta_2



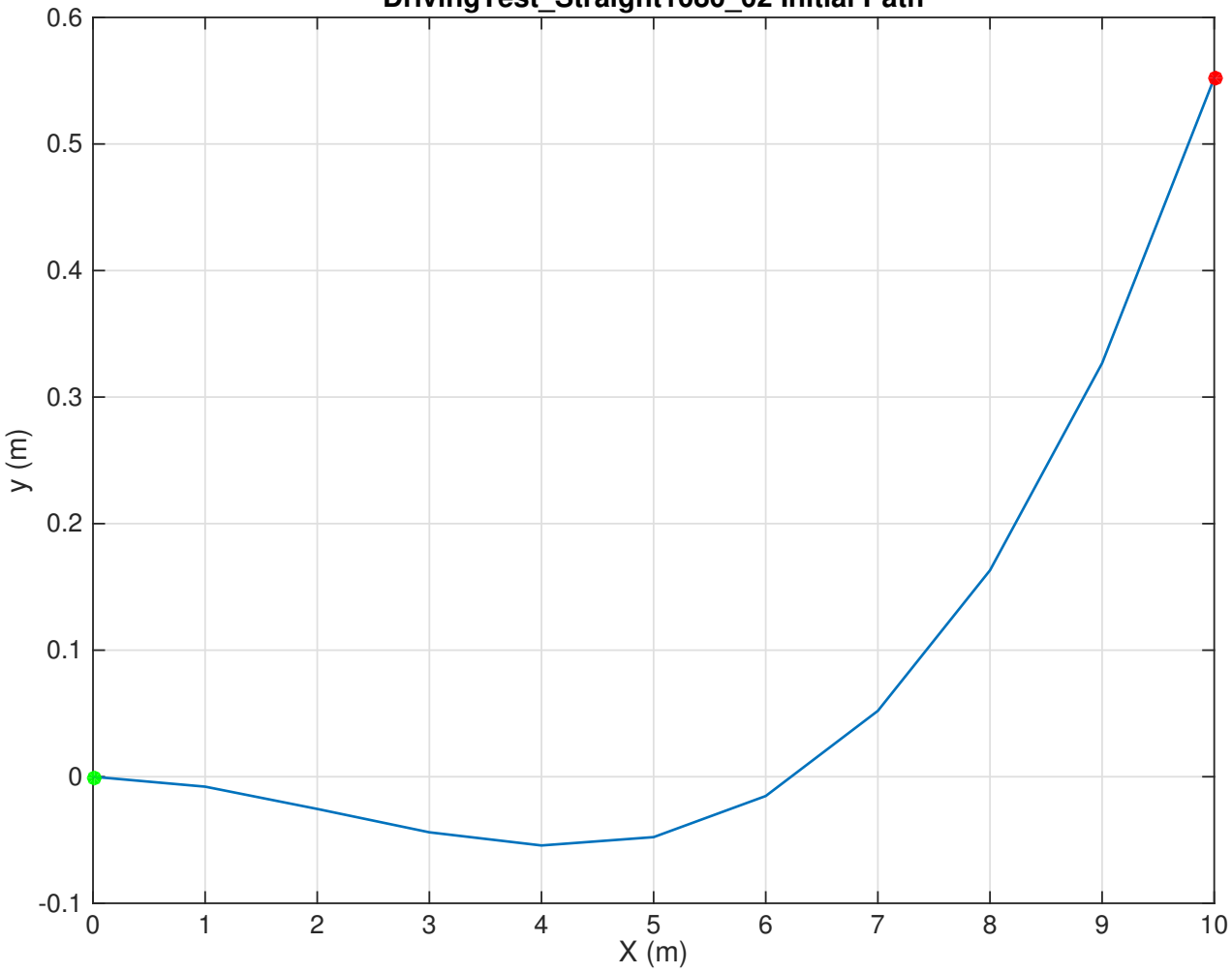
DrivingTest_Straight1080_01 Camera Position



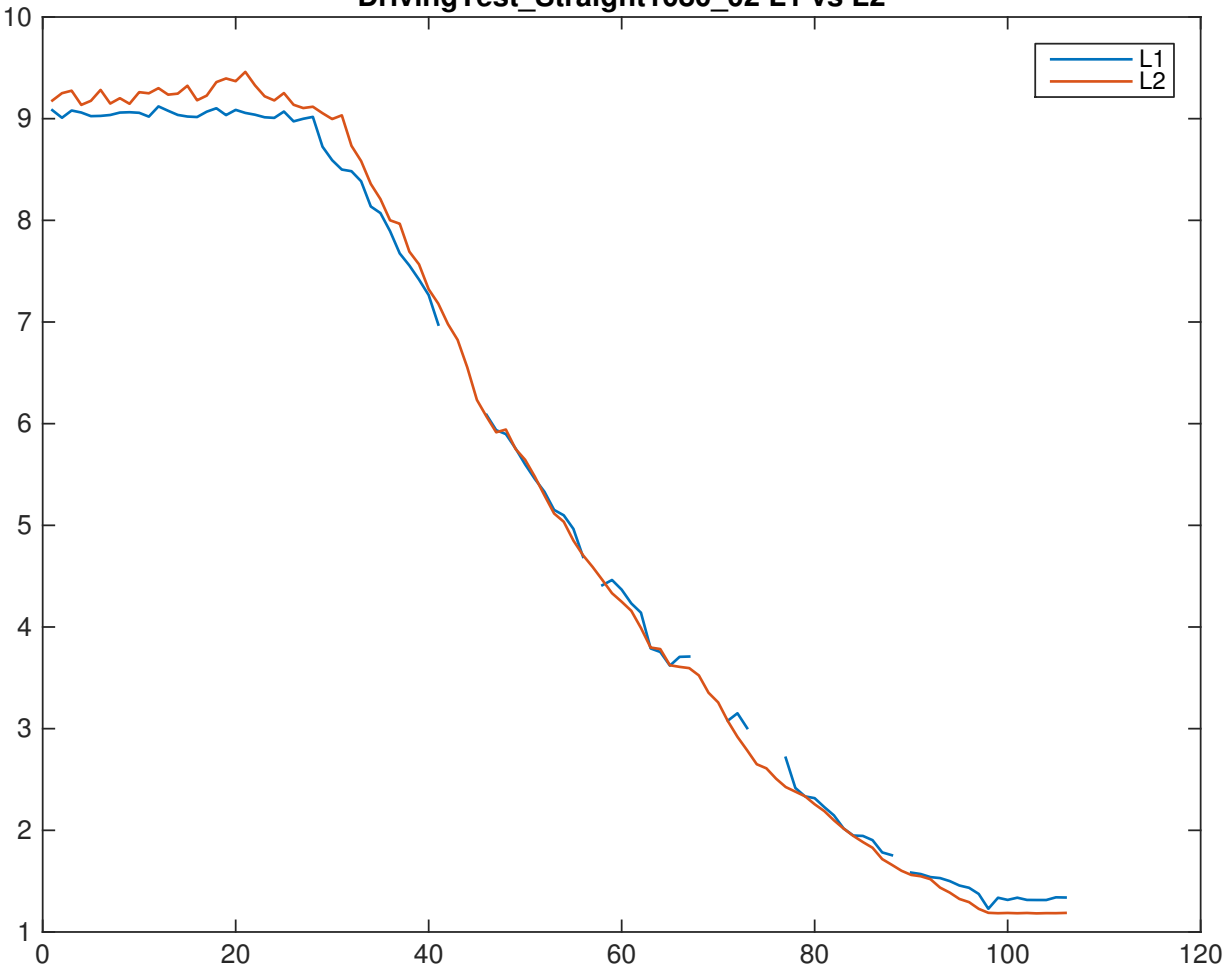
DrivingTest_Straight1080_01 Steering Command



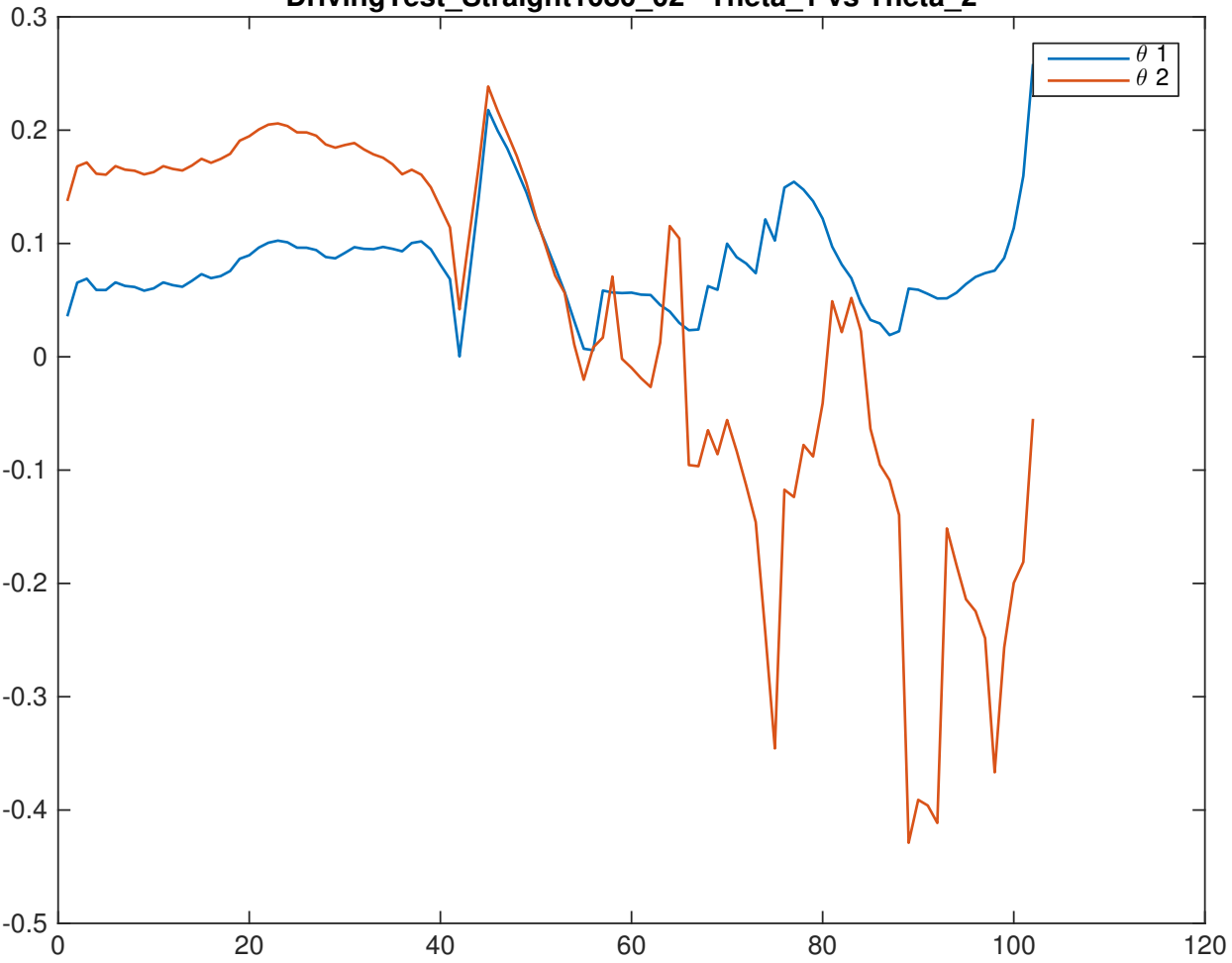
DrivingTest_Straight1080_02 Initial Path



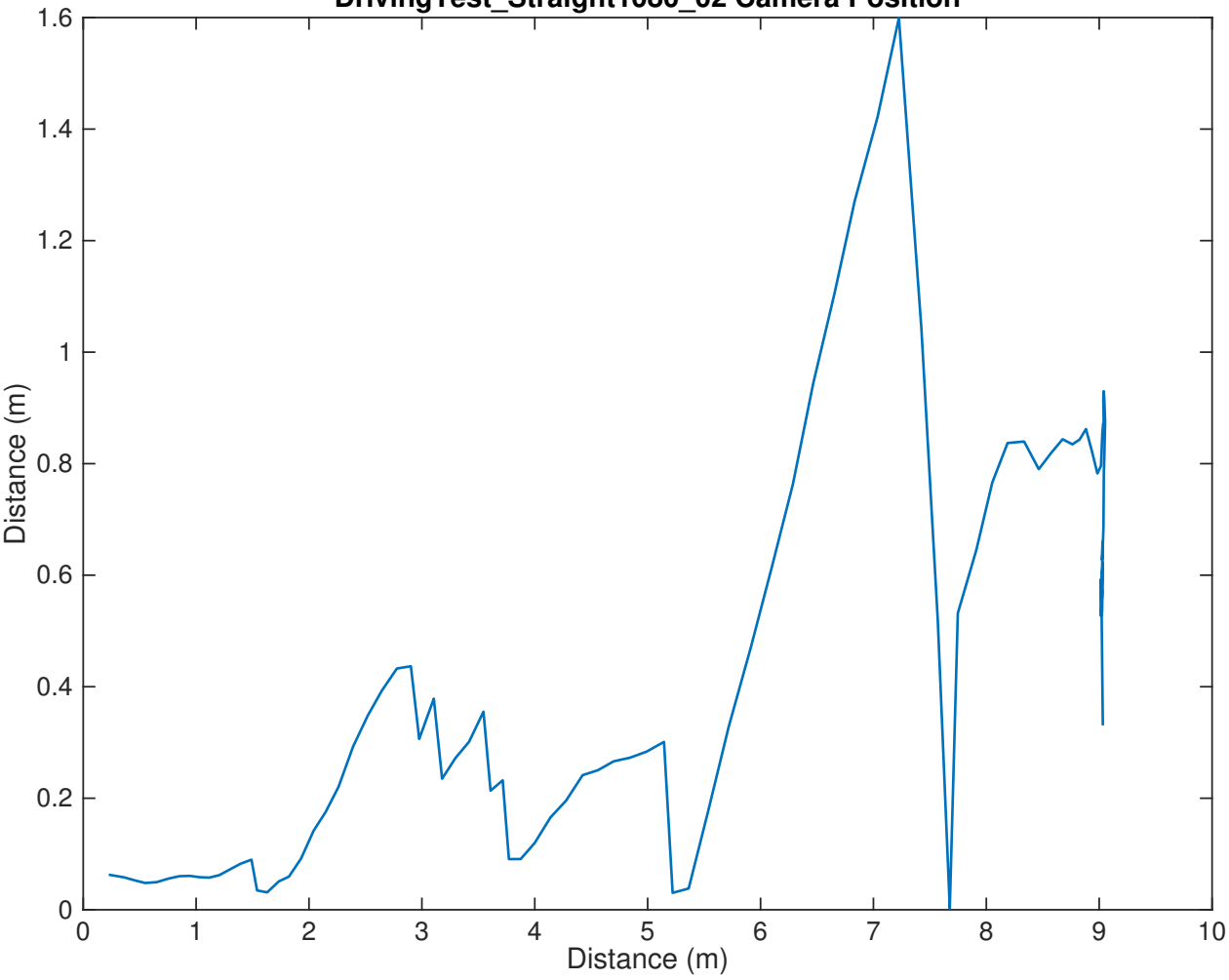
DrivingTest_Straight1080_02 L1 vs L2



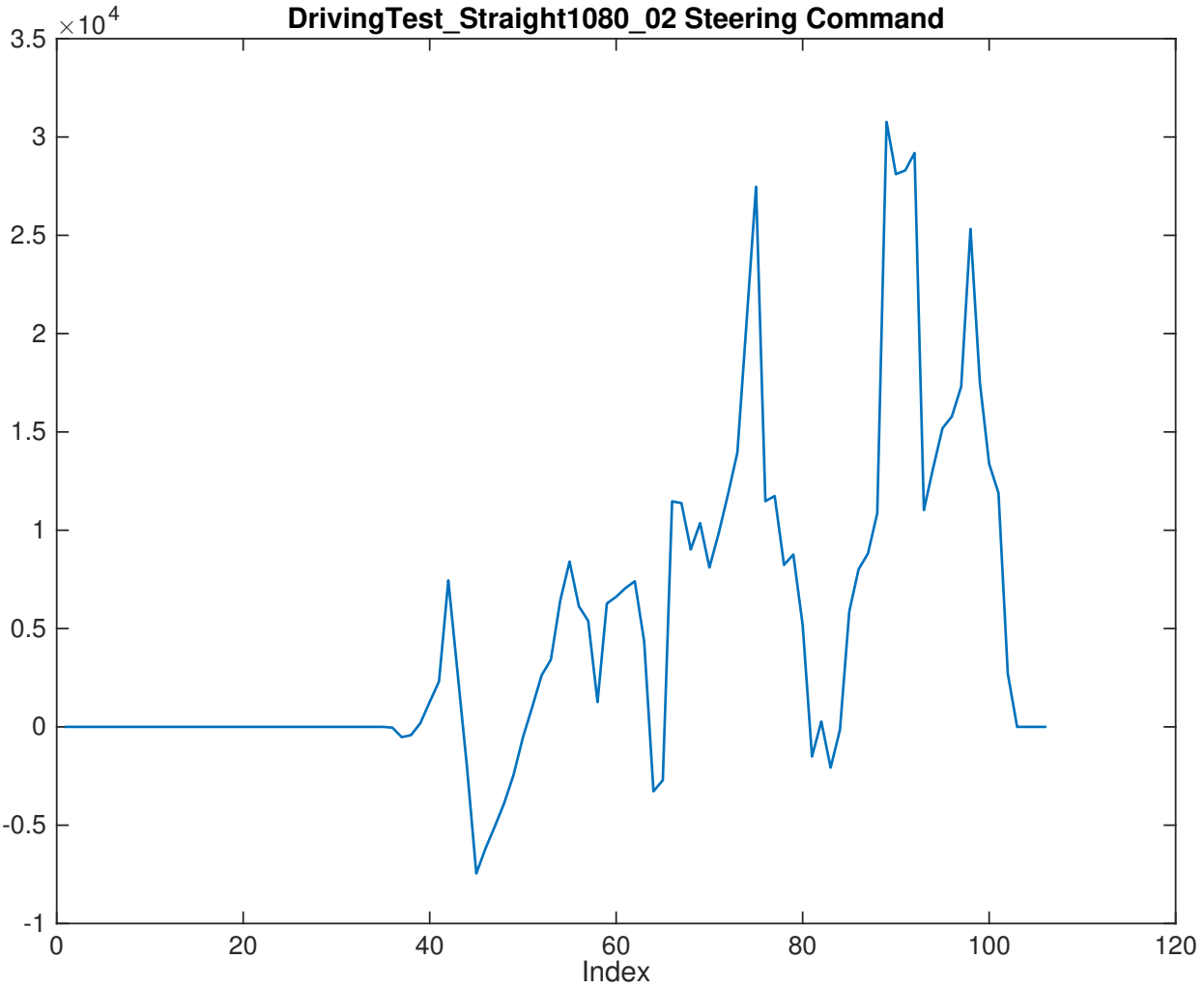
DrivingTest_Straight1080_02 Theta_1 vs Theta_2



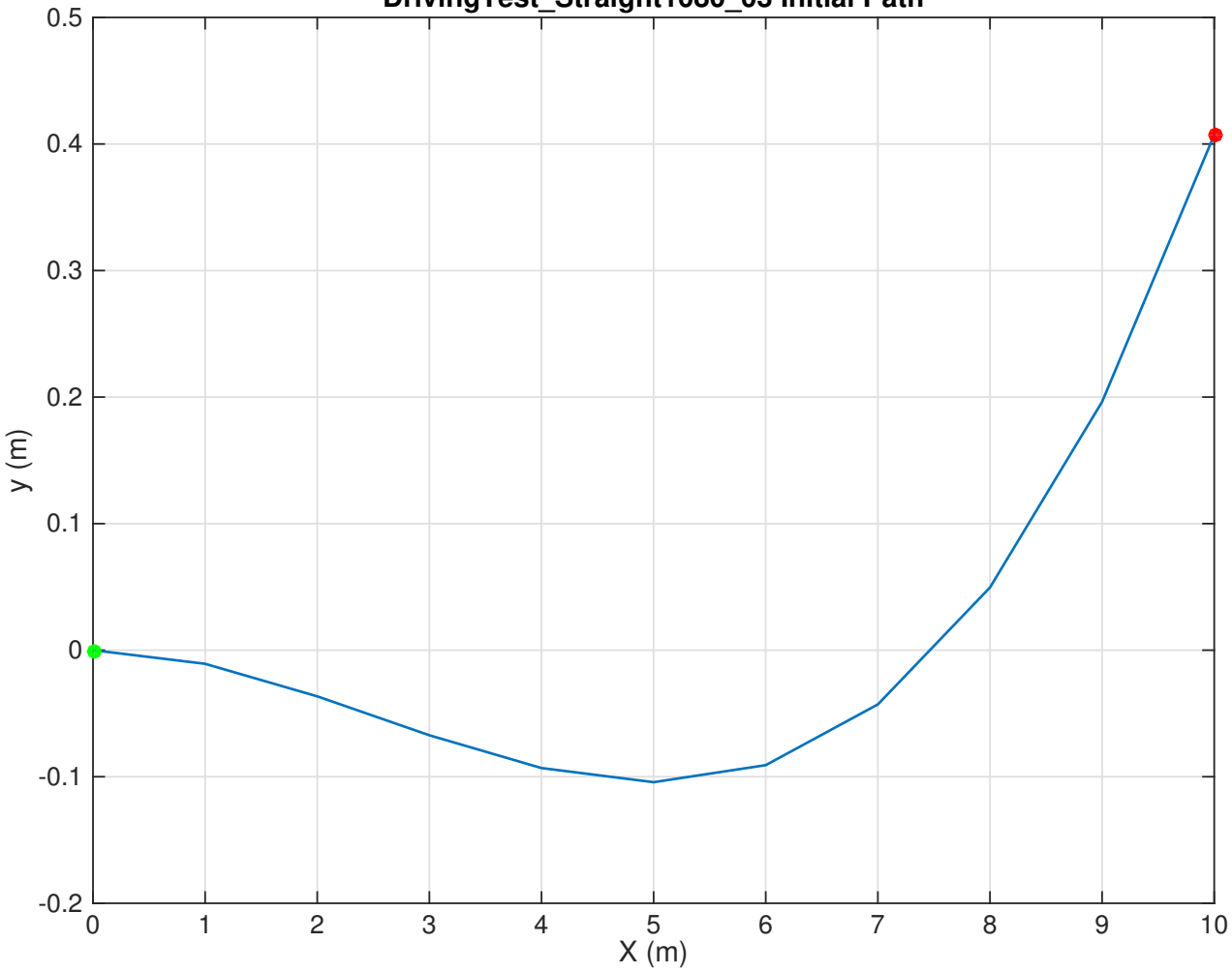
DrivingTest_Straight1080_02 Camera Position



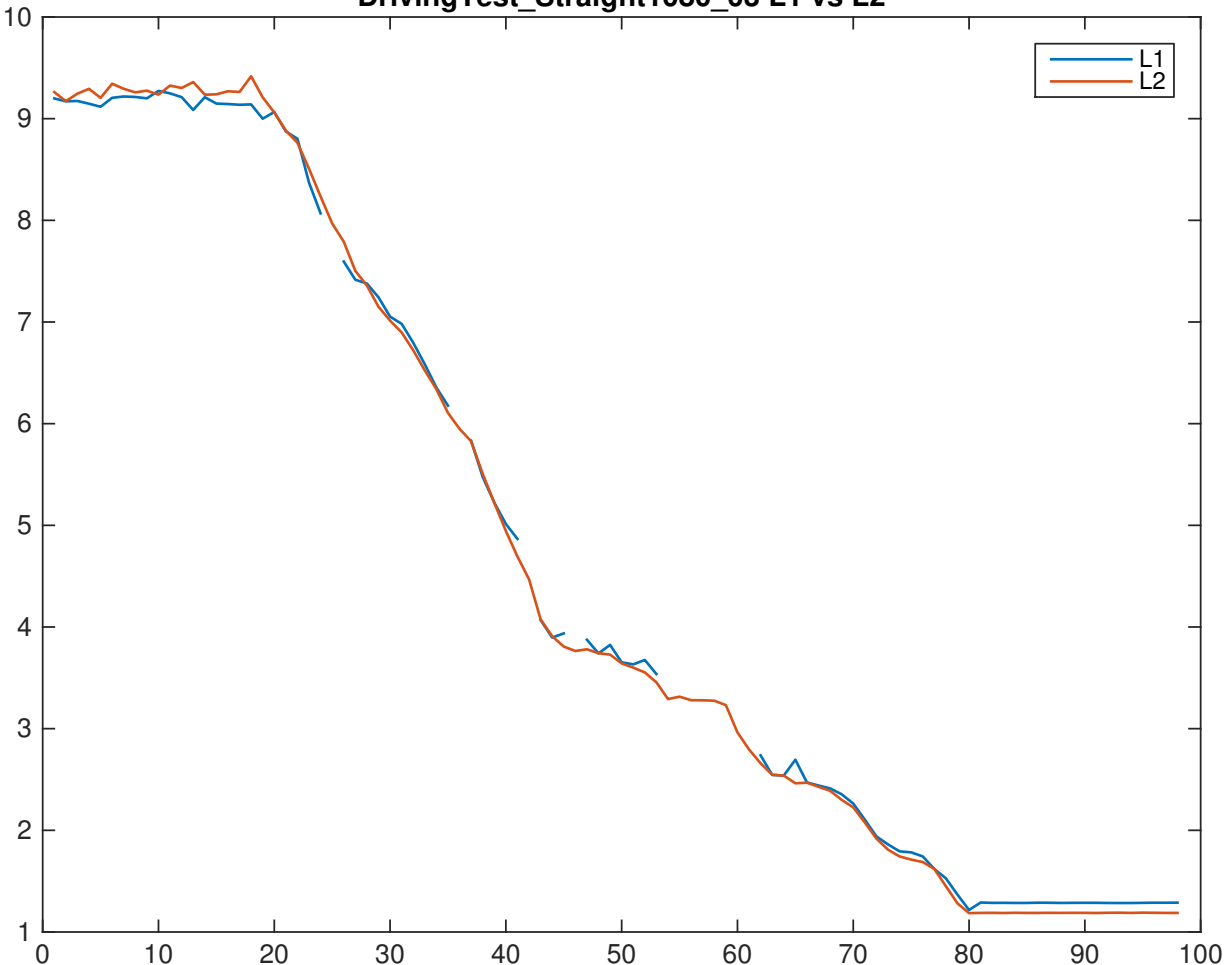
DrivingTest_Straight1080_02 Steering Command



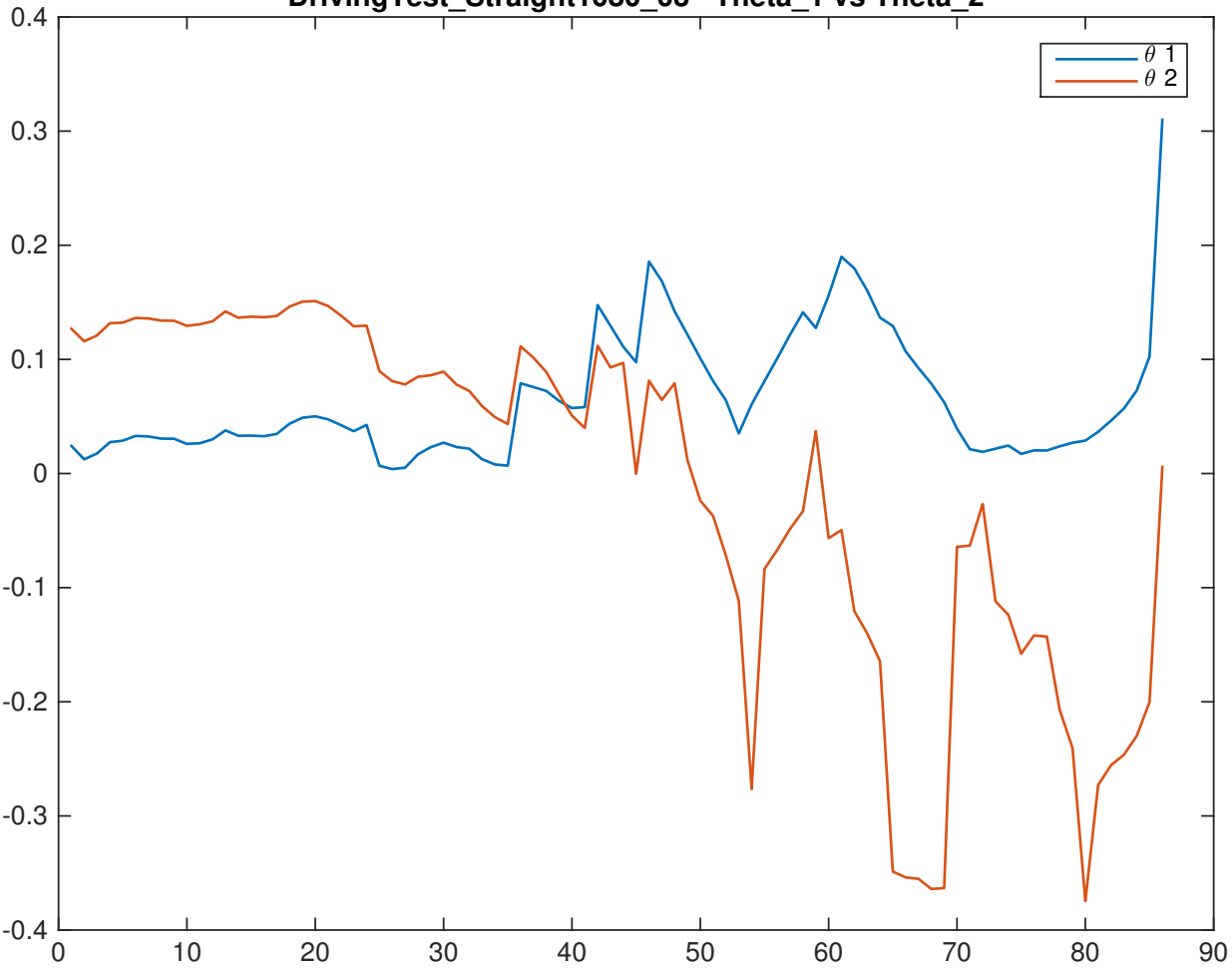
DrivingTest_Straight1080_03 Initial Path



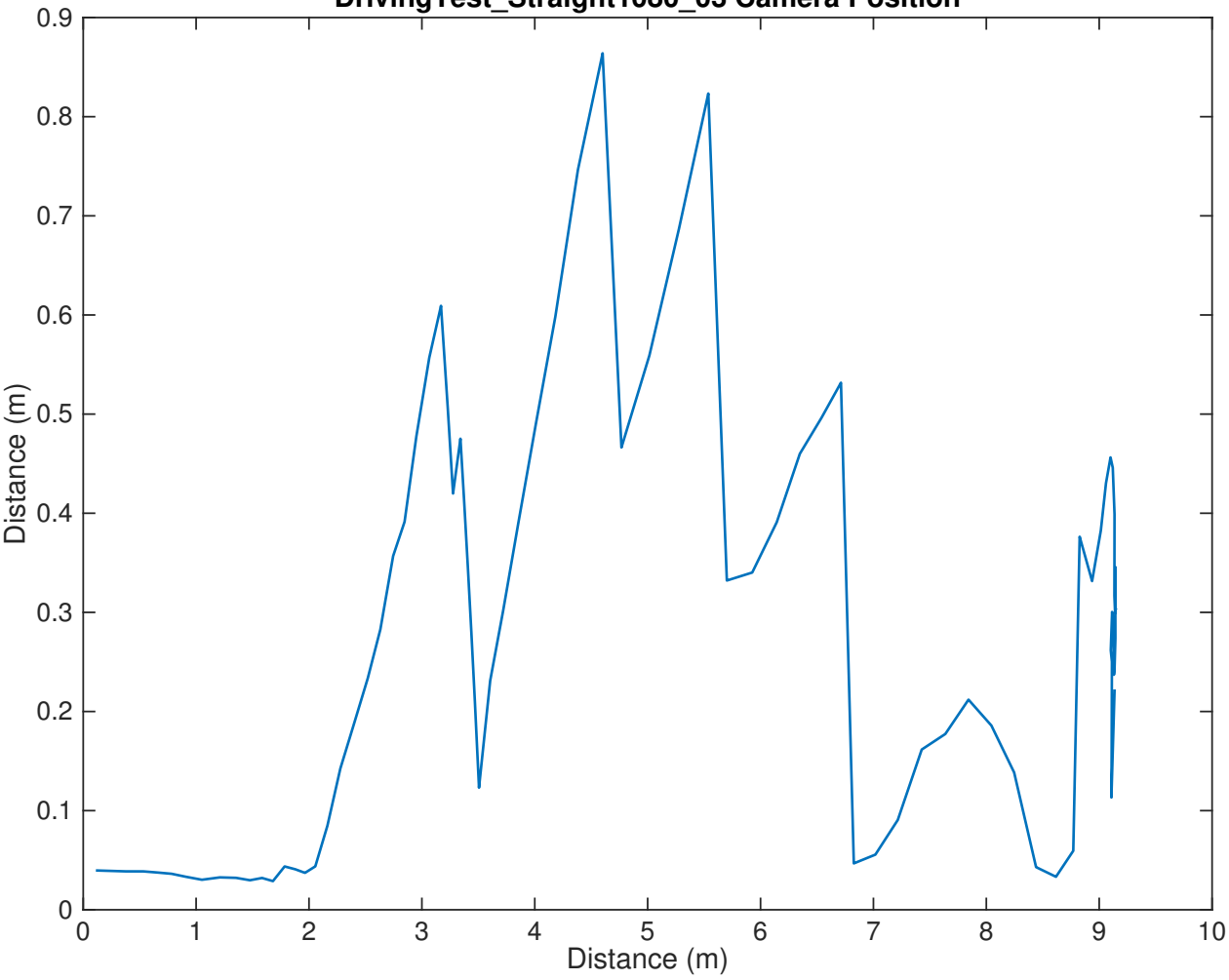
DrivingTest_Straight1080_03 L1 vs L2



DrivingTest_Straight1080_03 Theta_1 vs Theta_2



DrivingTest_Straight1080_03 Camera Position



DrivingTest_Straight1080_03 Steering Command

