

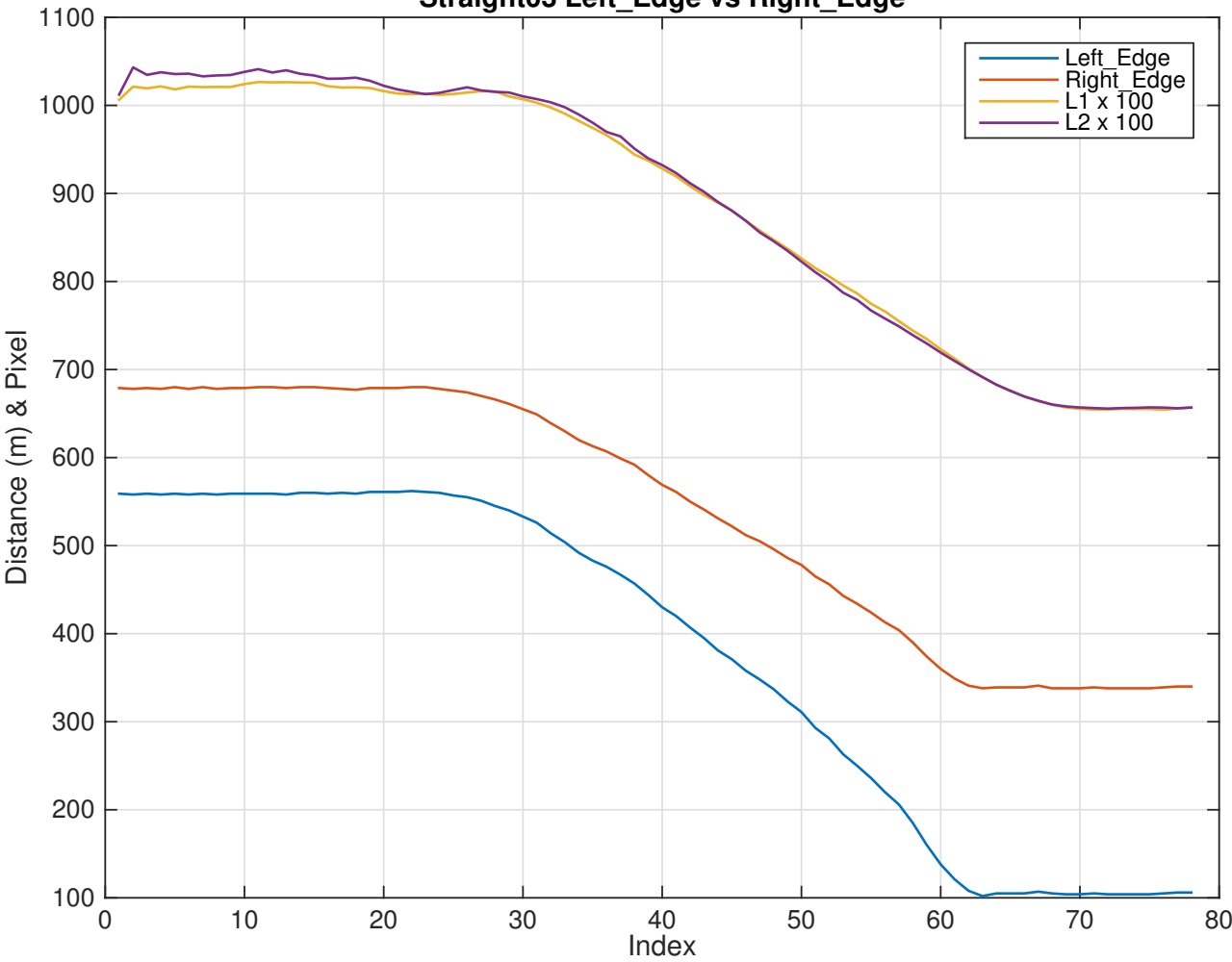
Number_Of_Unique_Paths

King_Pin_Detected

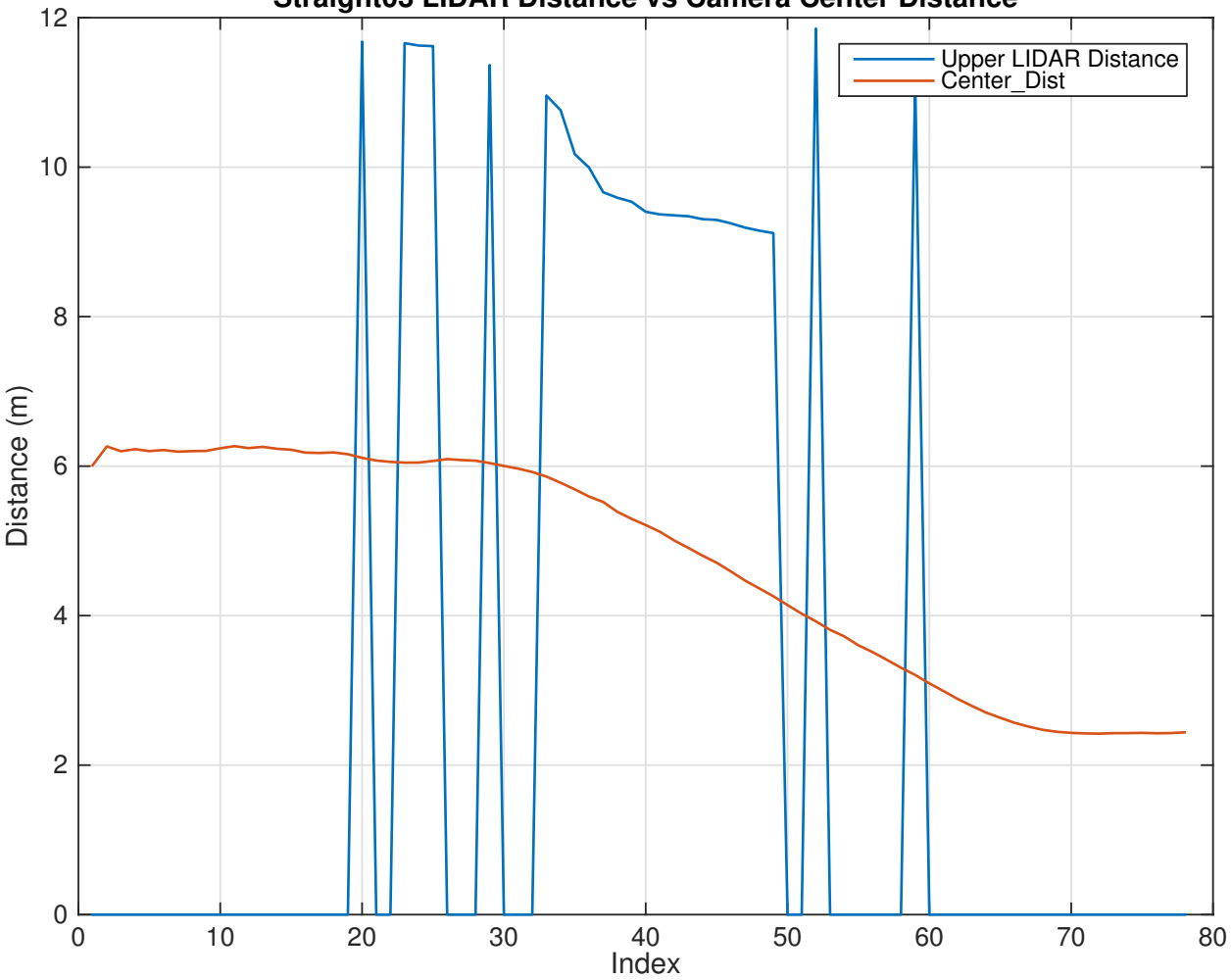
24

false

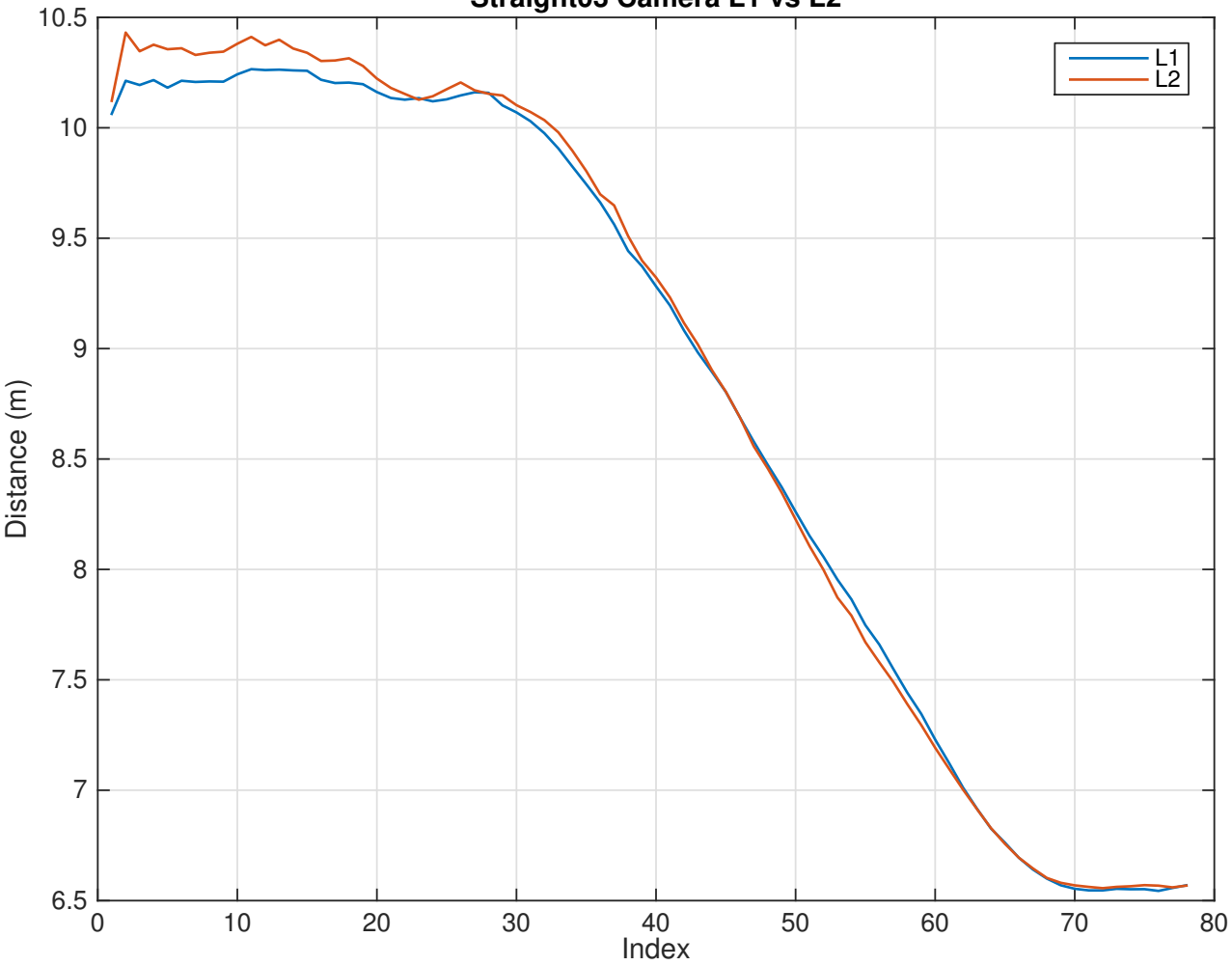
Straight03 Left_Edge vs Right_Edge



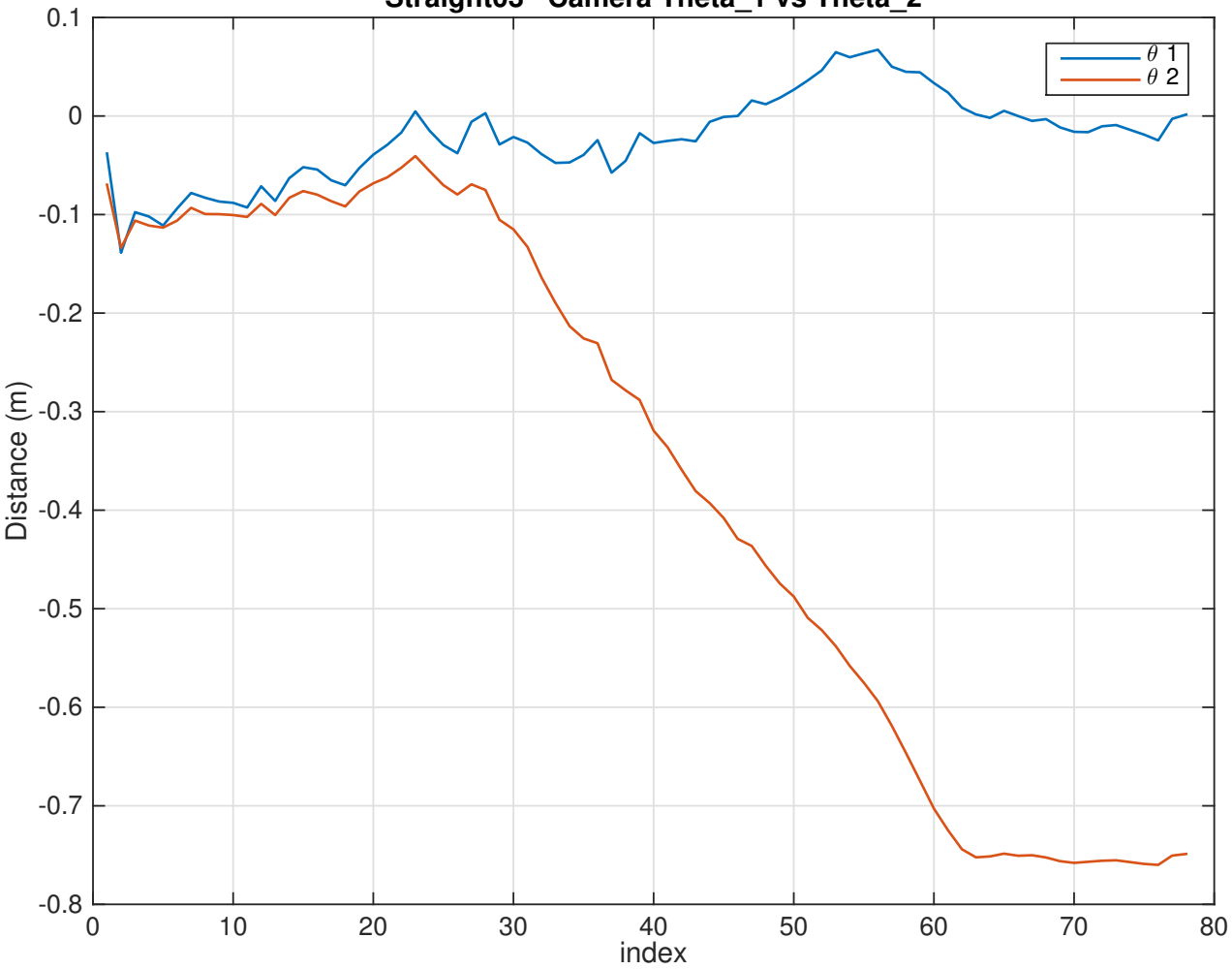
Straight03 LIDAR Distance vs Camera Center Distance



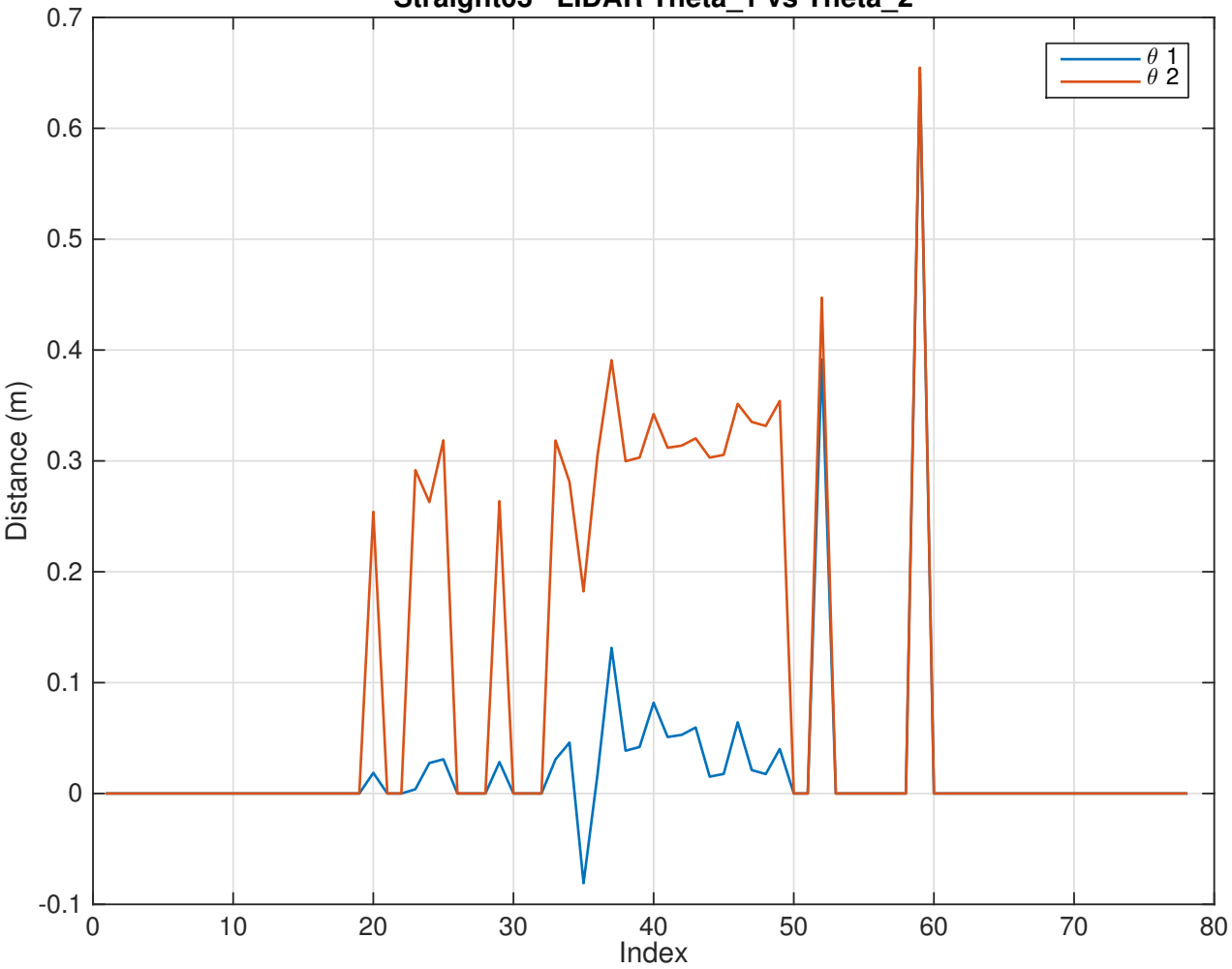
Straight03 Camera L1 vs L2



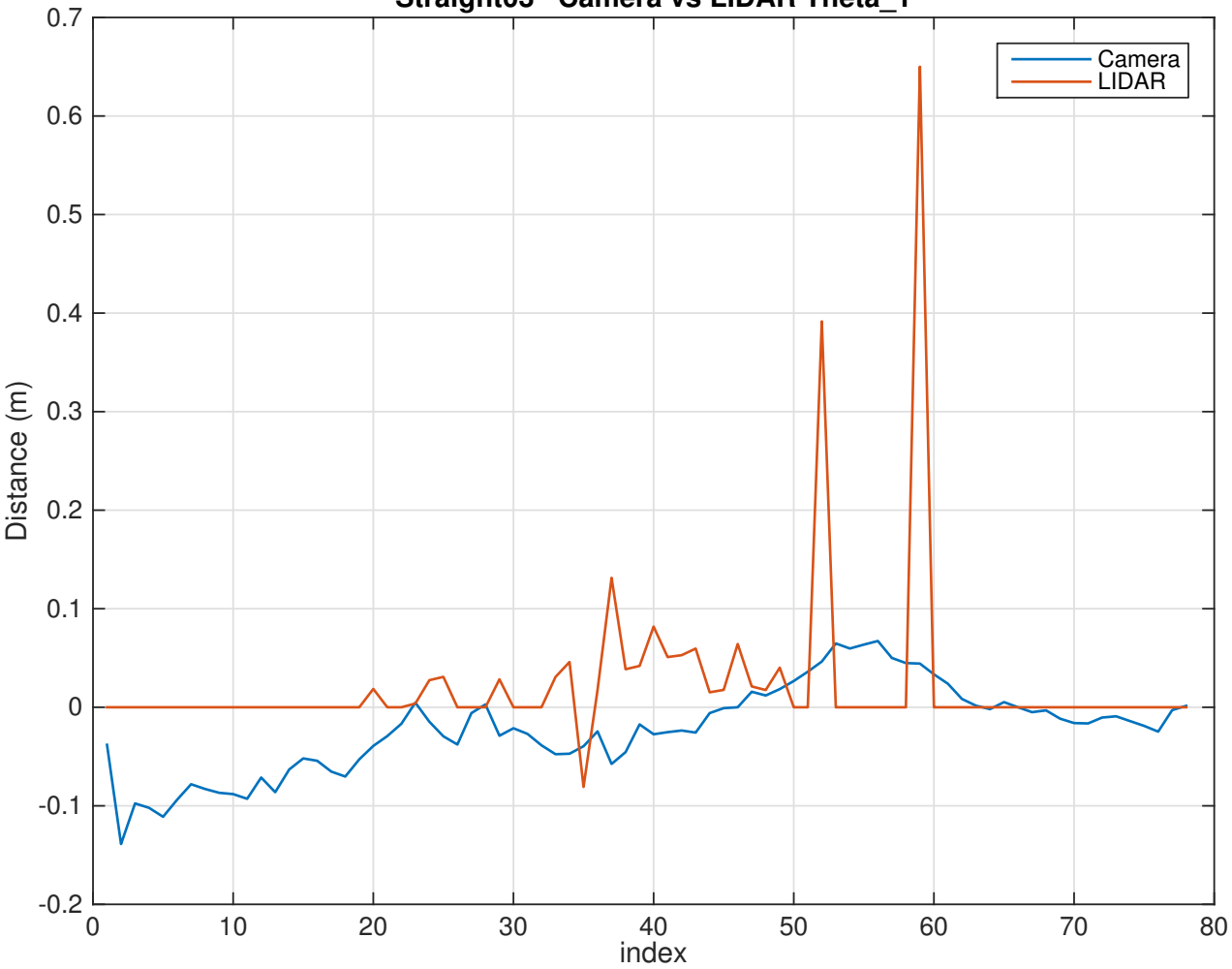
Straight03 Camera Theta_1 vs Theta_2



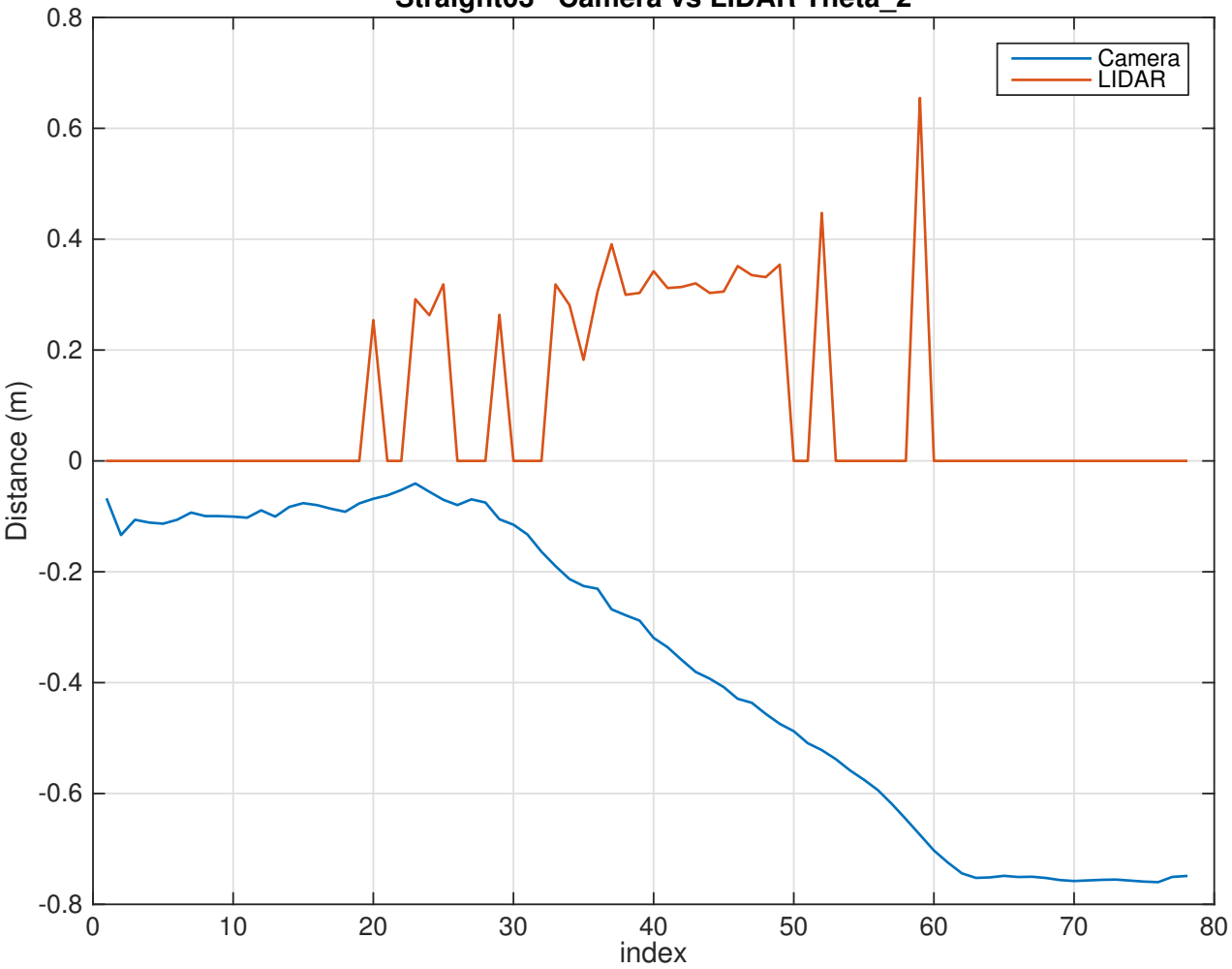
Straight03 LIDAR Theta_1 vs Theta_2



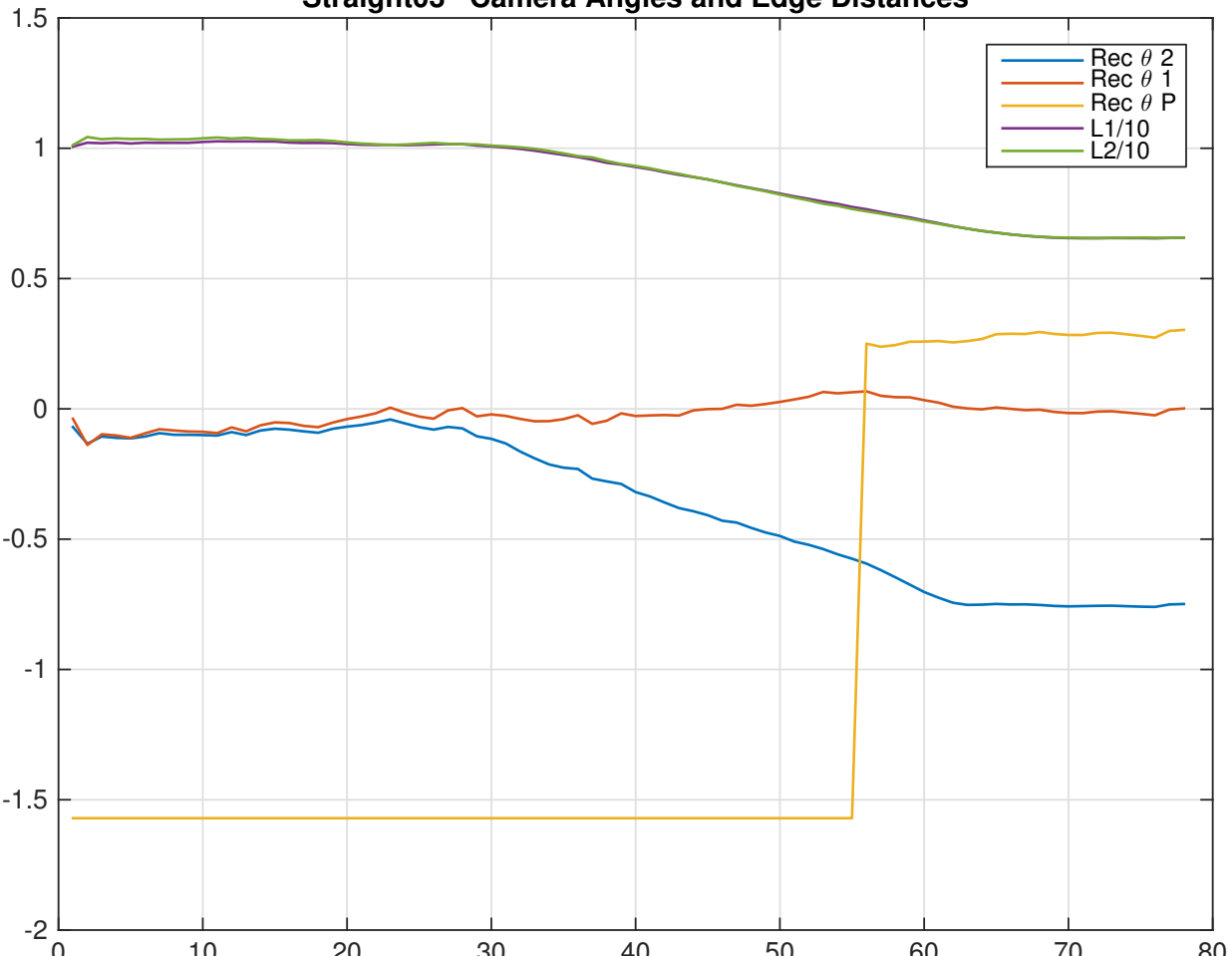
Straight03 Camera vs LIDAR Theta_1



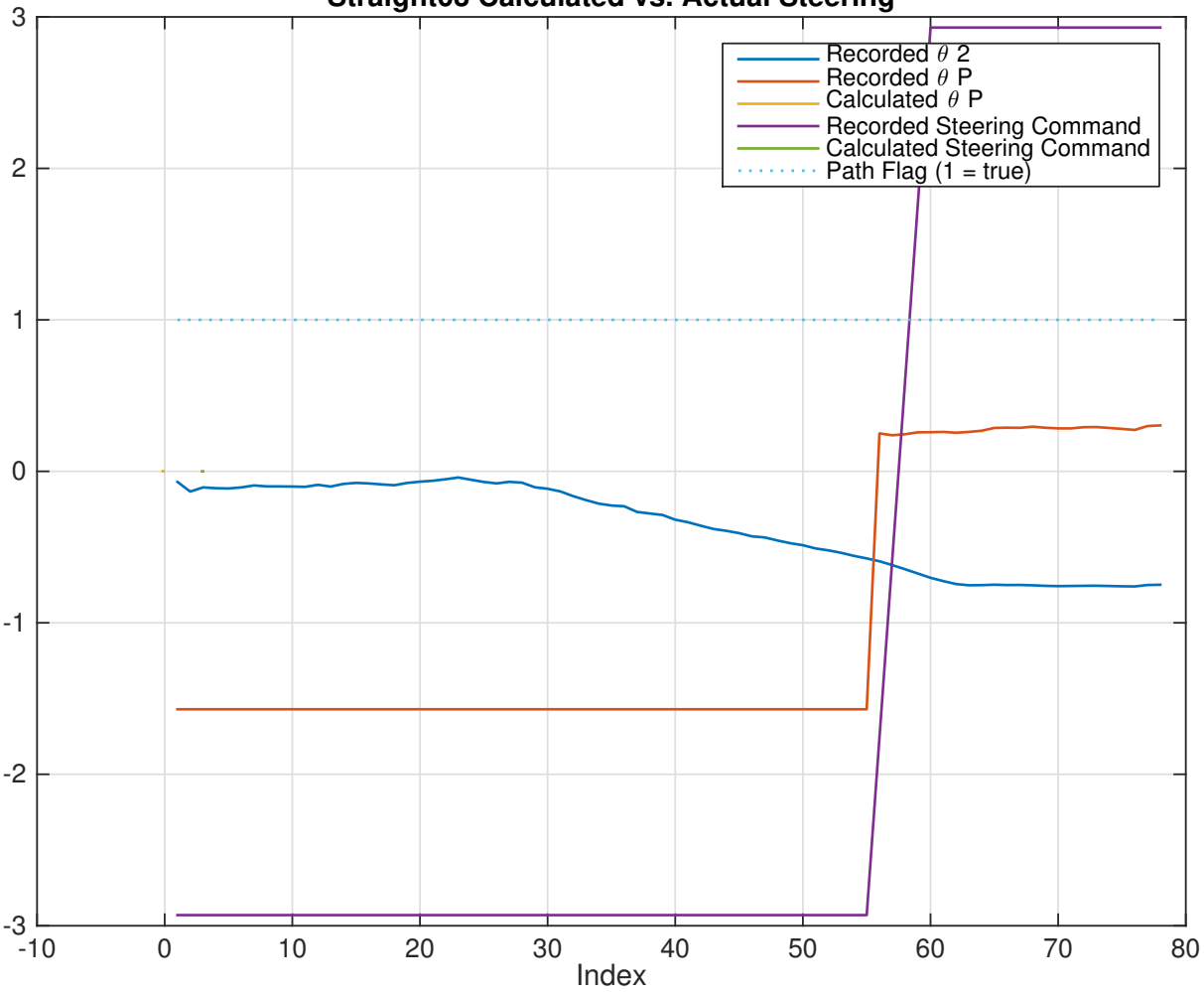
Straight03 Camera vs LIDAR Theta_2



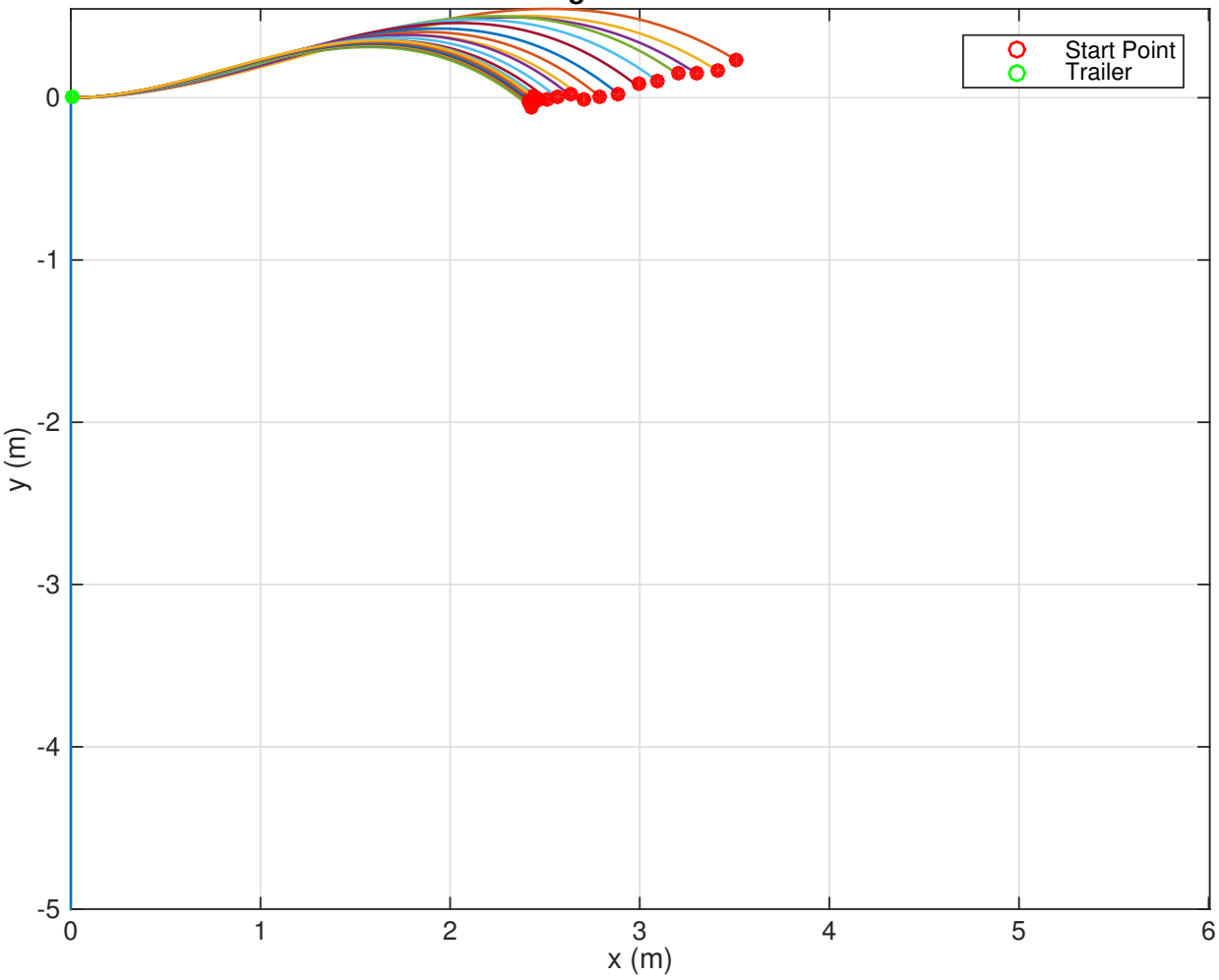
Straight03 Camera Angles and Edge Distances



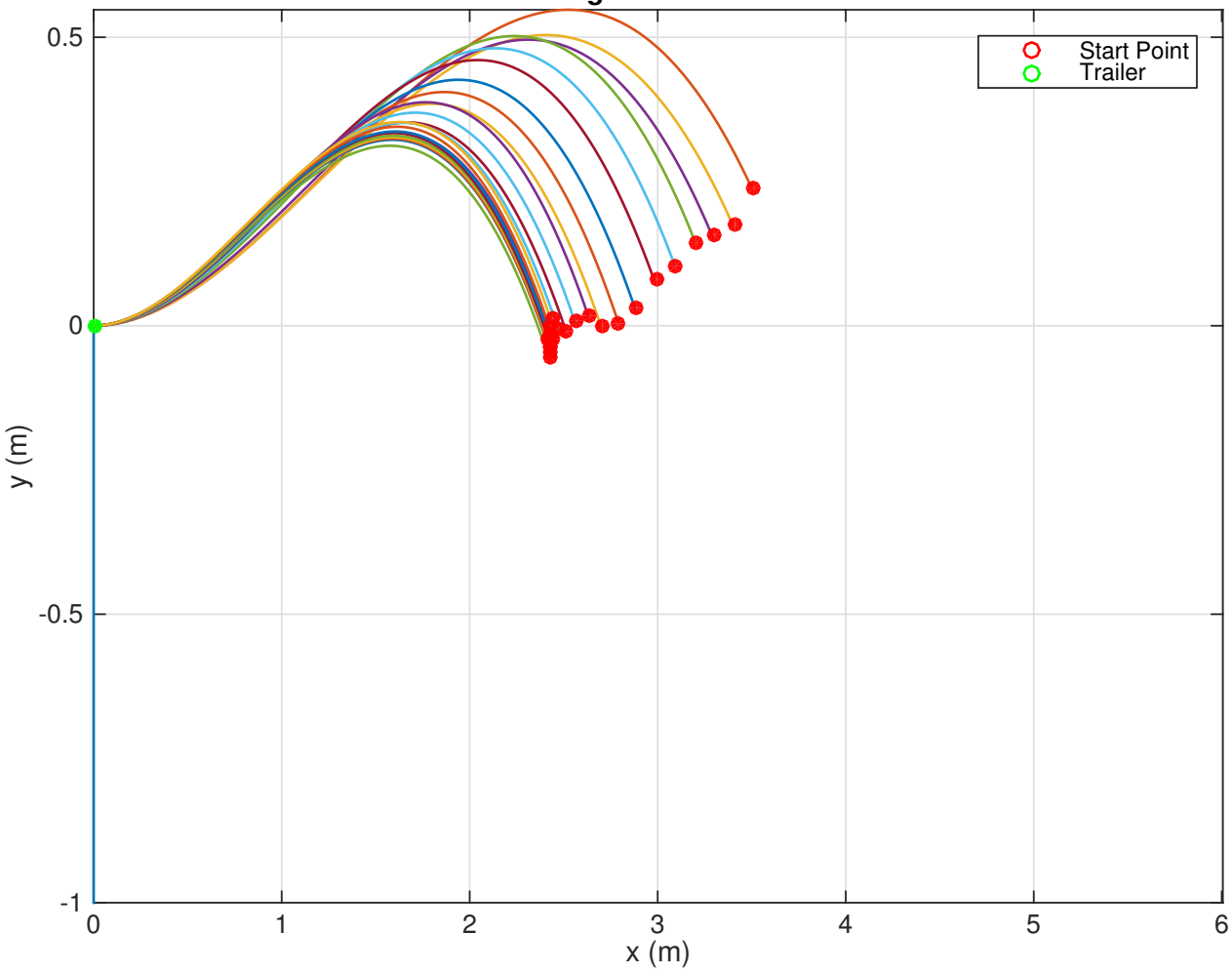
Straight03 Calculated vs. Actual Steering

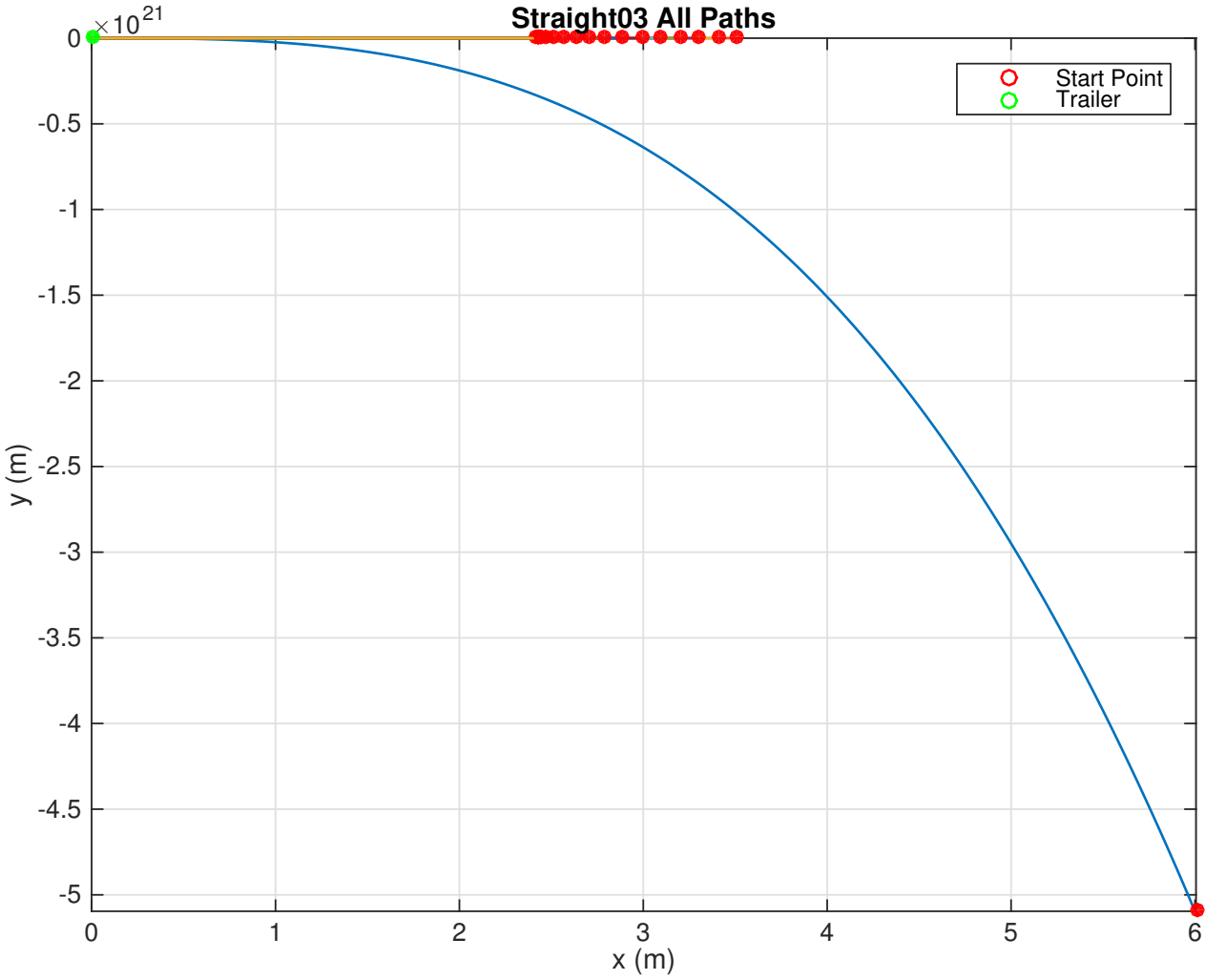


Straight03 All Paths



Straight03 All Paths





Straight03 Calculated vs. Actual Steering

