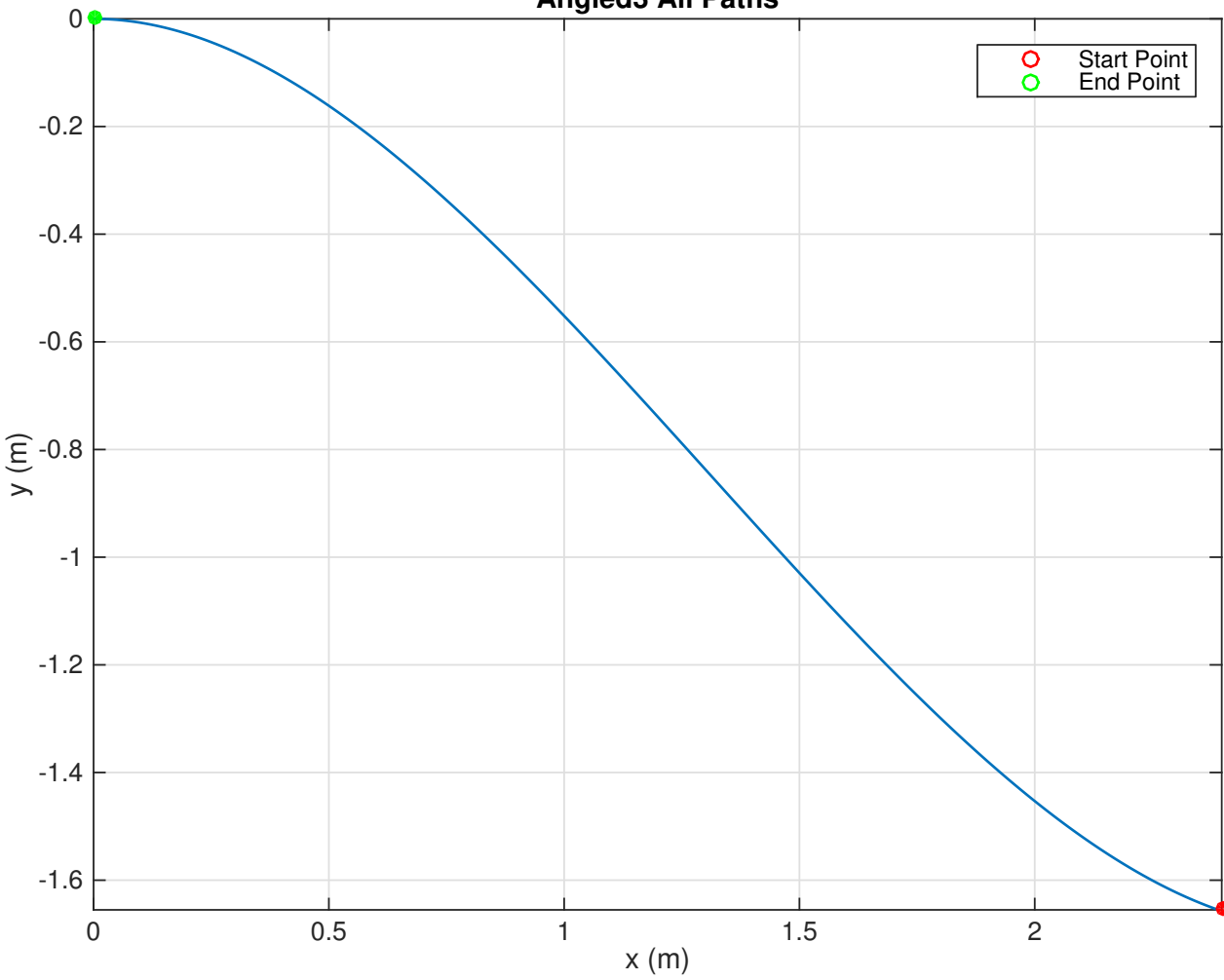


Angled3 All Paths



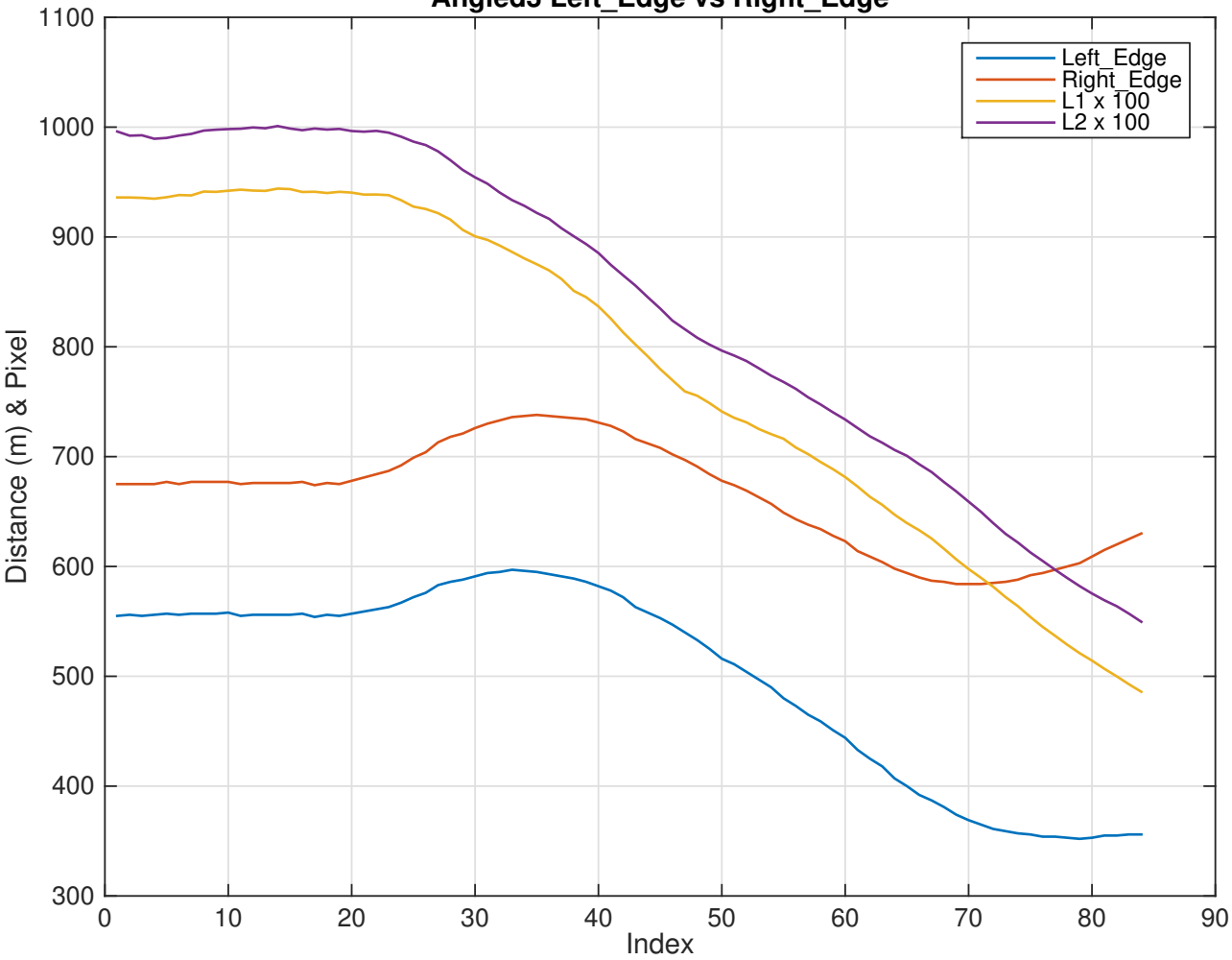
Number_Of_Unique_Paths

King_Pin_Detected

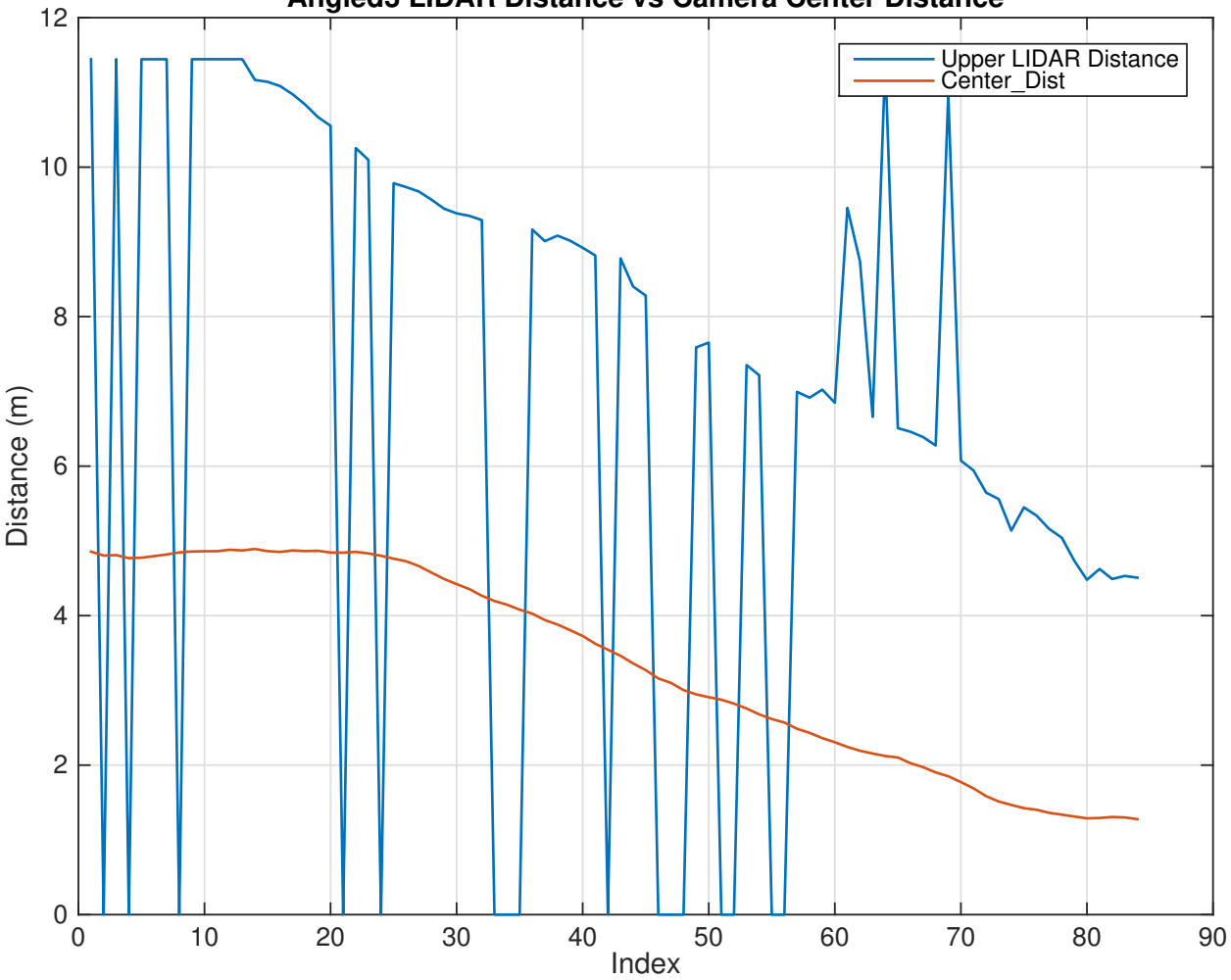
1

false

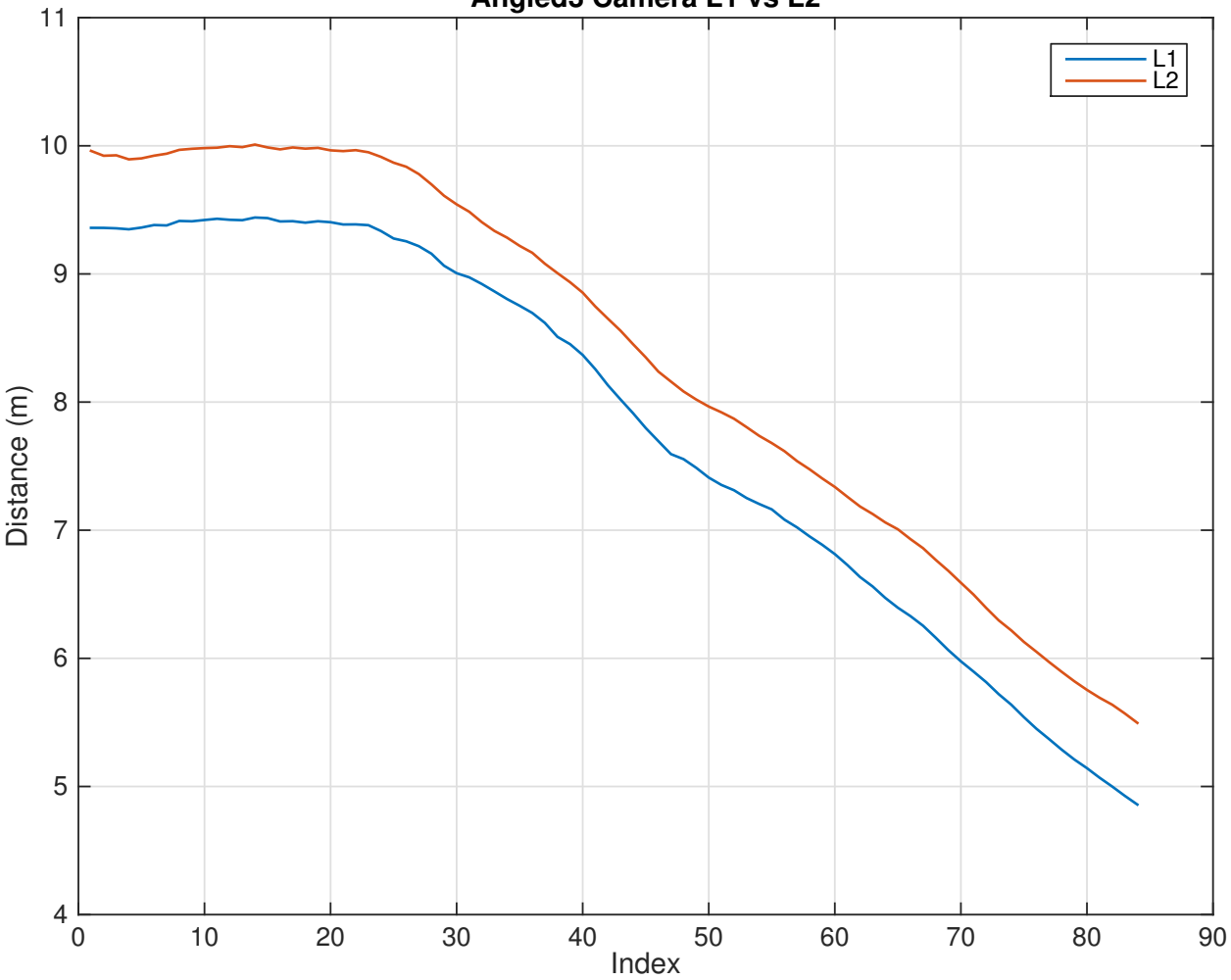
Angled3 Left_Edge vs Right_Edge



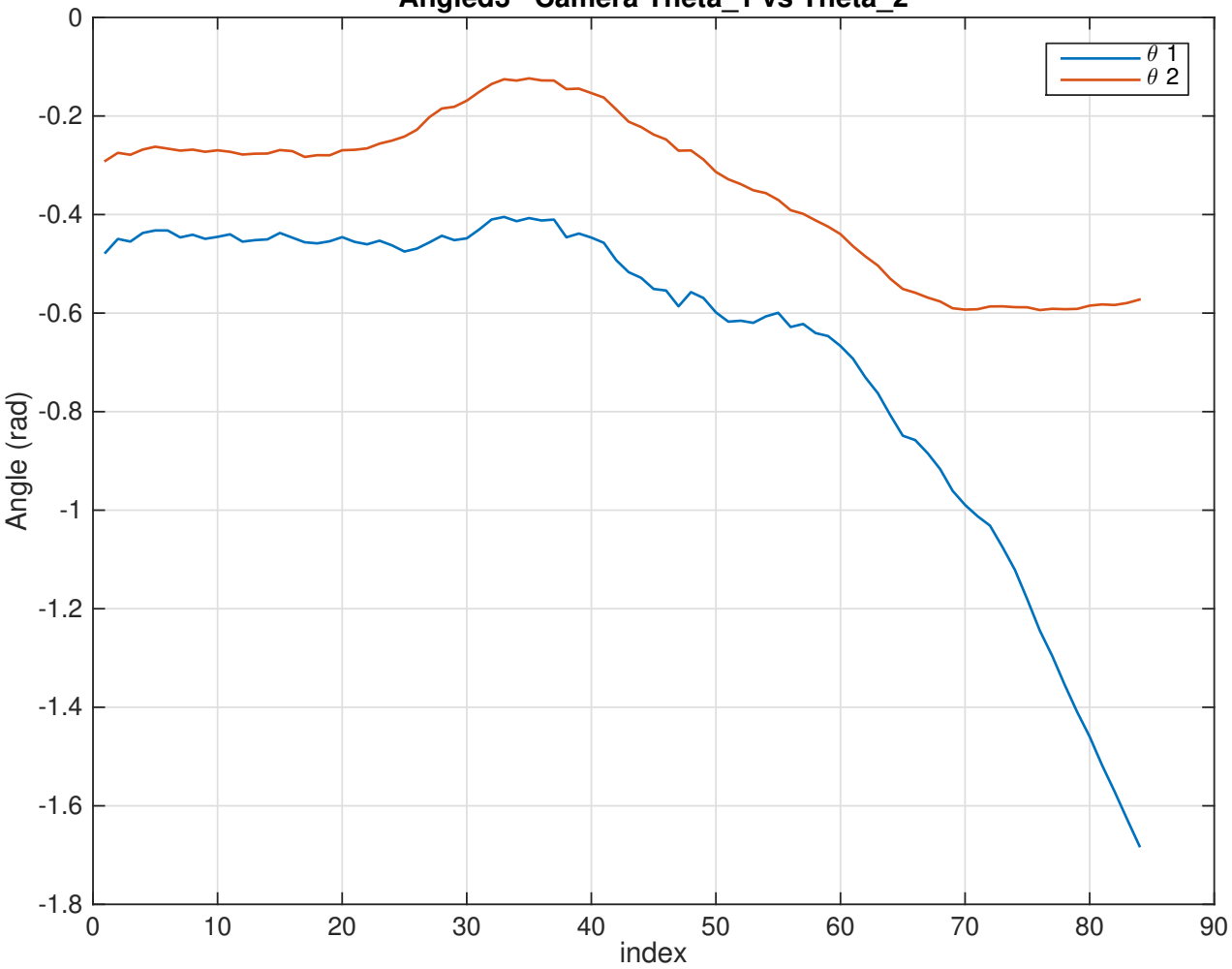
Angled3 LIDAR Distance vs Camera Center Distance



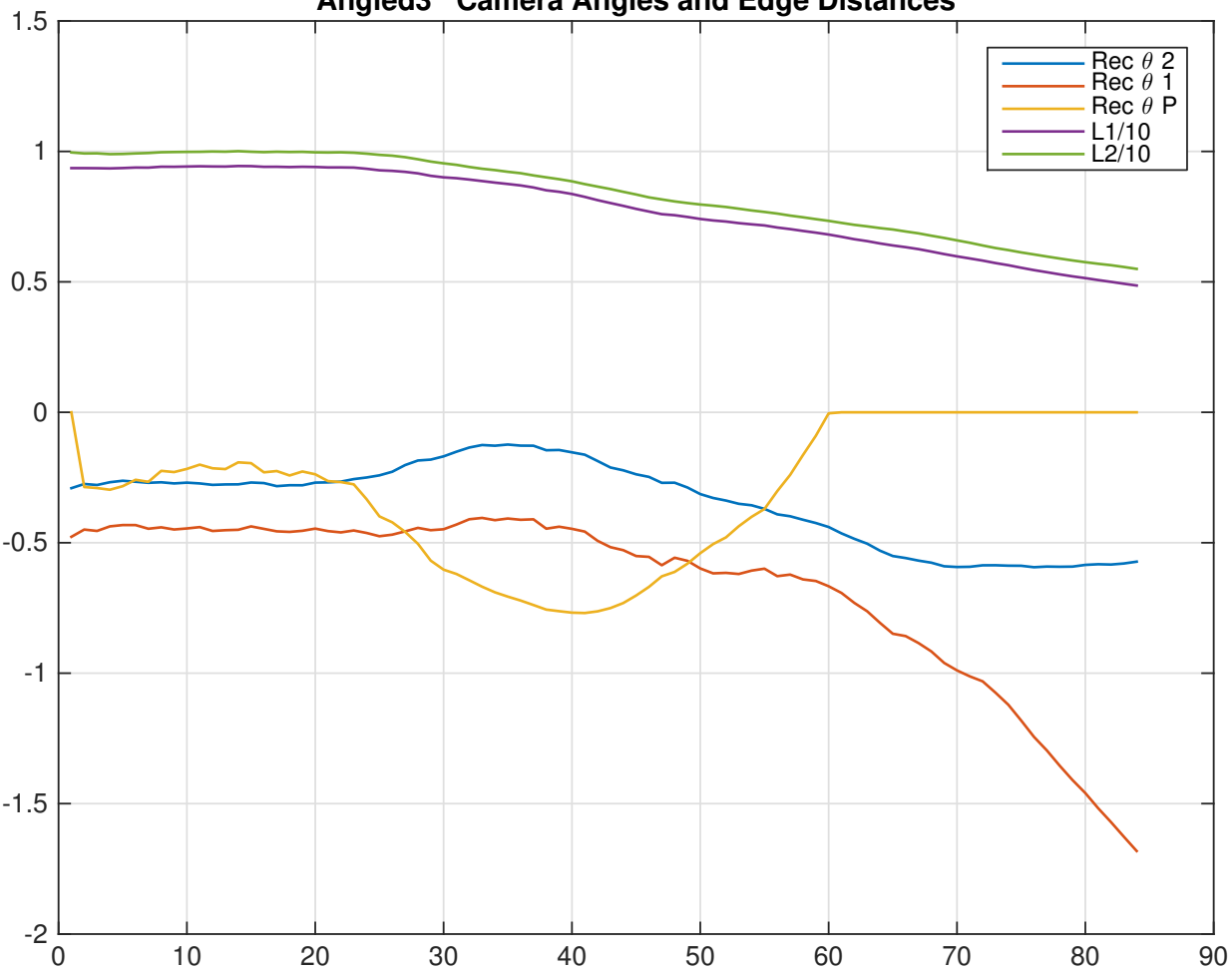
Angled3 Camera L1 vs L2



Angled3 Camera Theta_1 vs Theta_2



Angled3 Camera Angles and Edge Distances



Angled3 Steering

