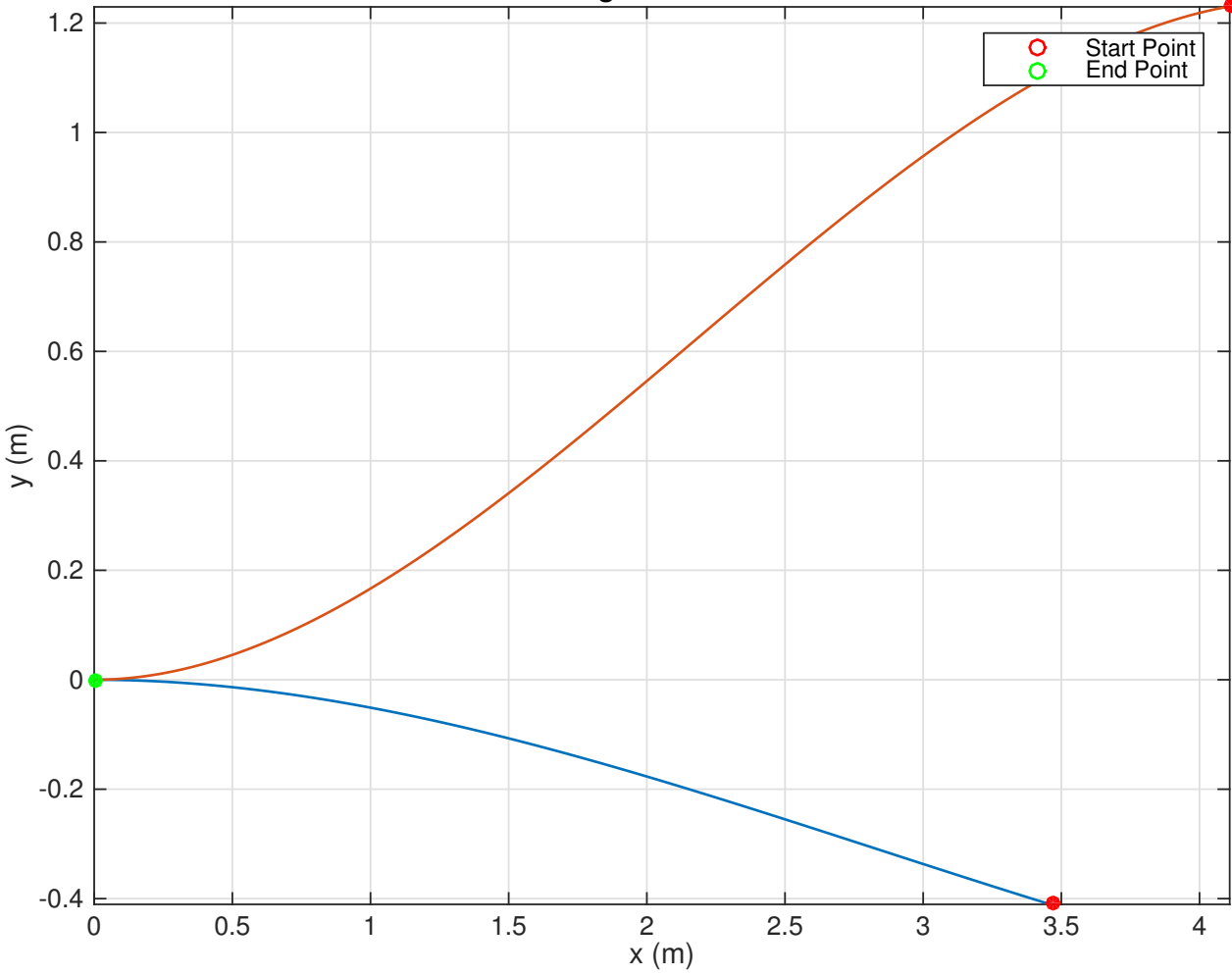
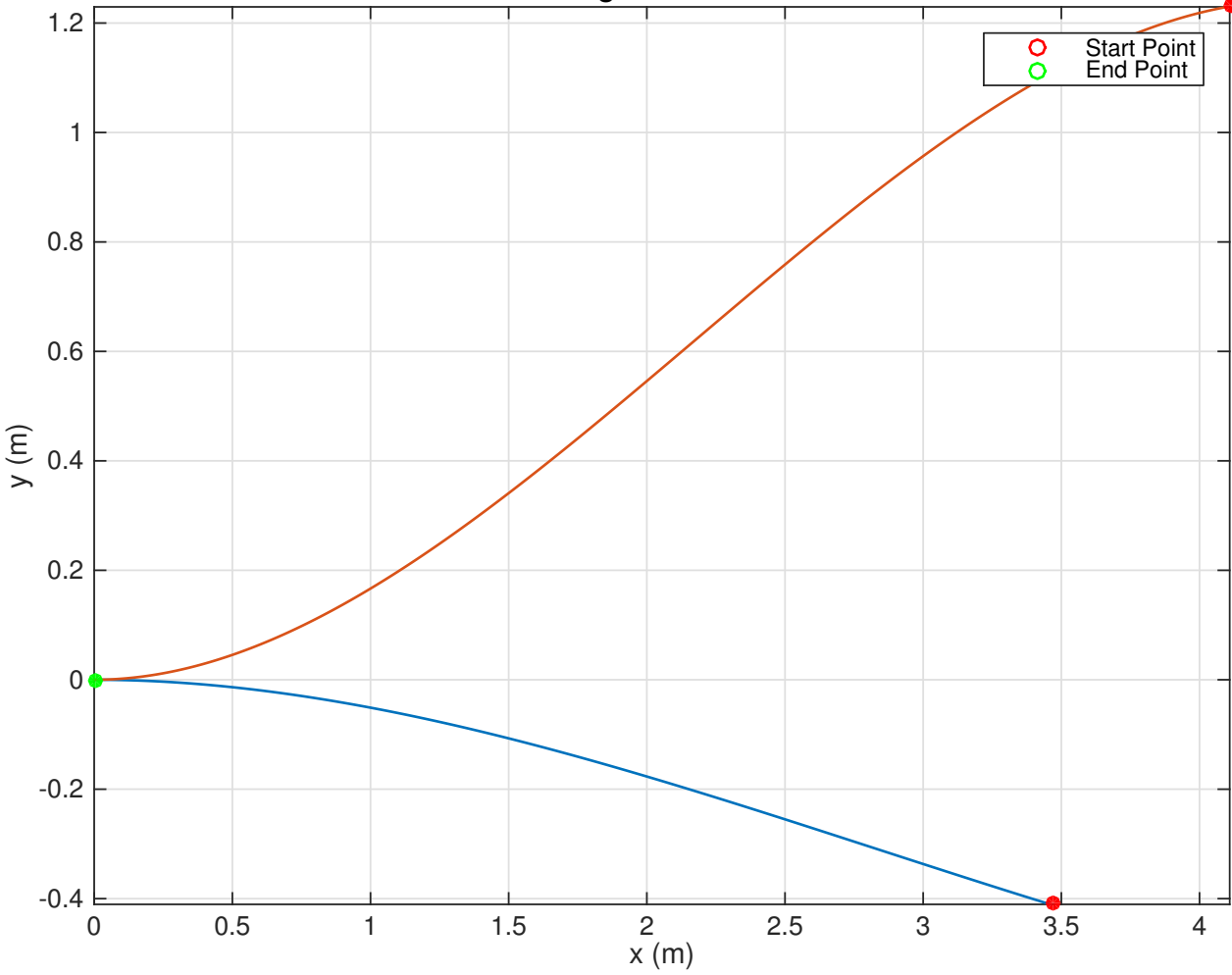


Straight5 All Paths



Straight5 All Paths



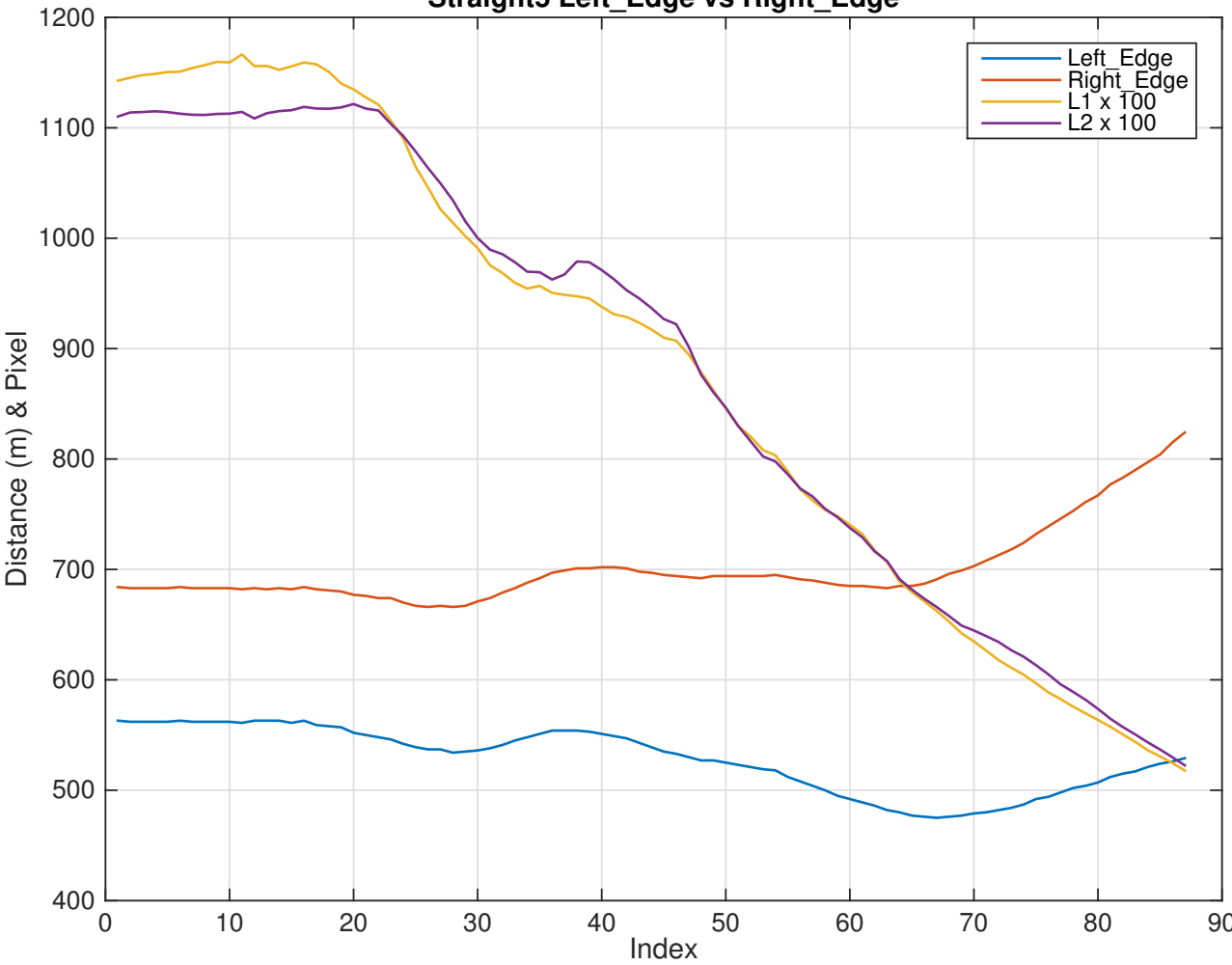
Number_Of_Unique_Paths

King_Pin_Detected

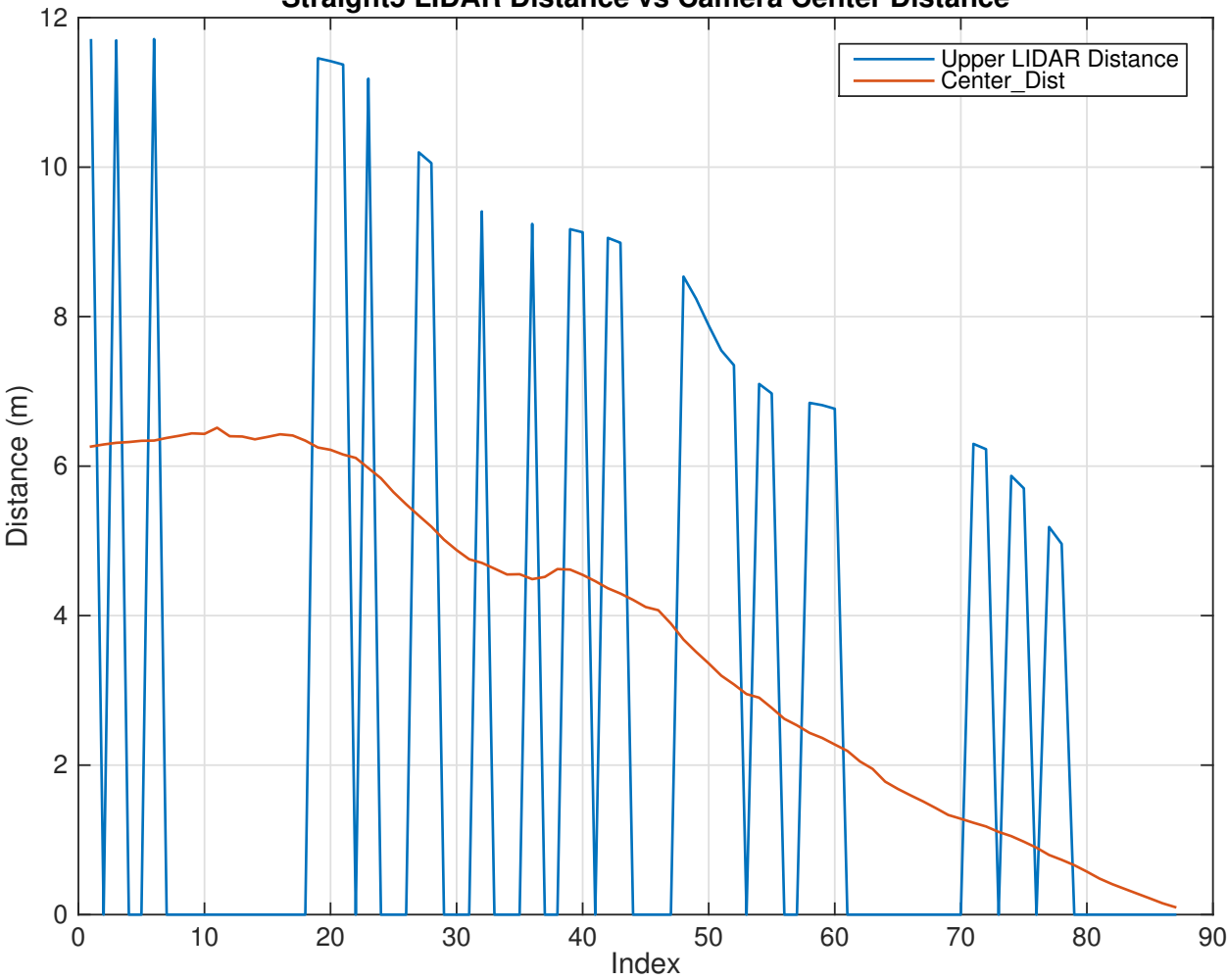
2

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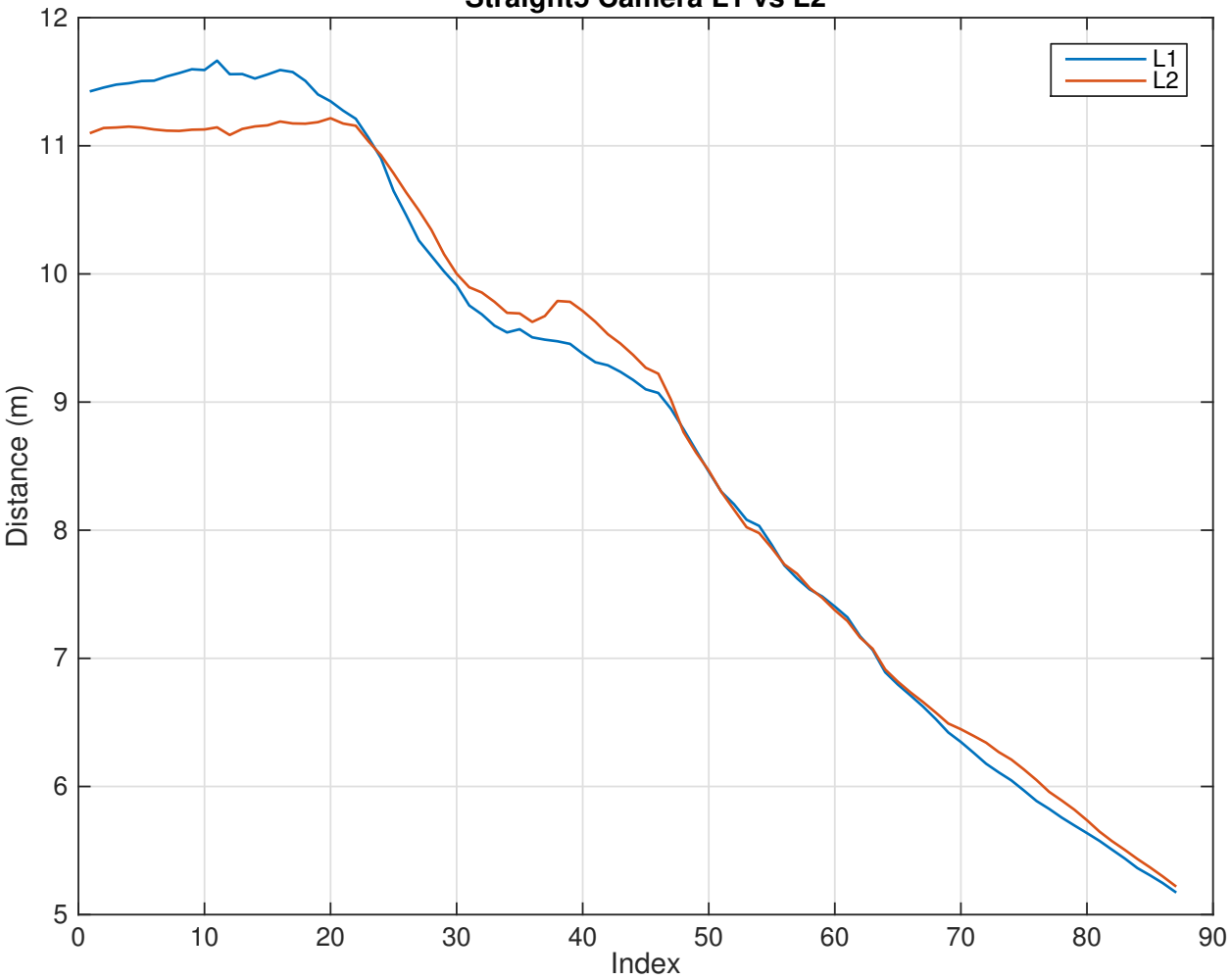
Straight5 Left_Edge vs Right_Edge



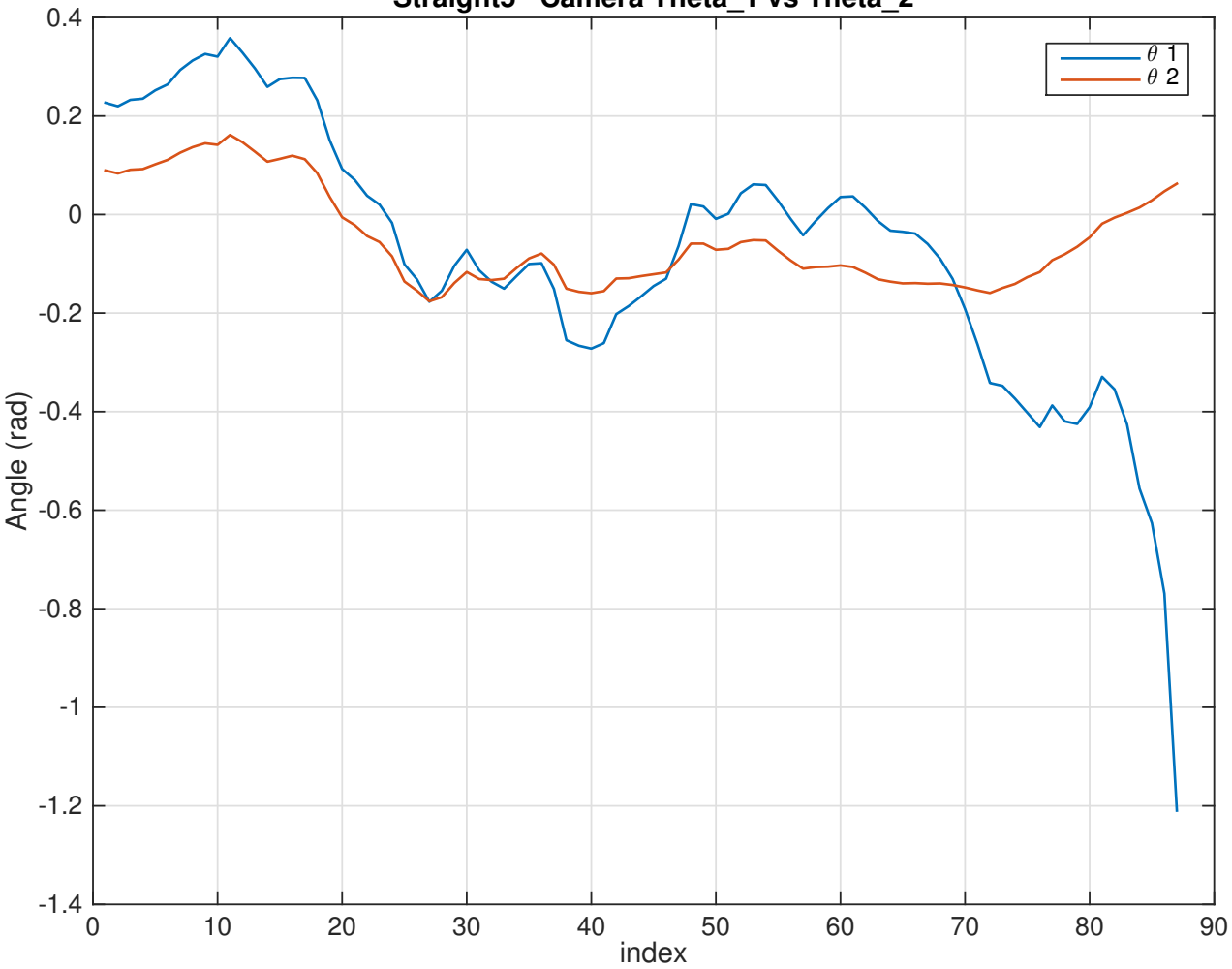
Straight5 LIDAR Distance vs Camera Center Distance



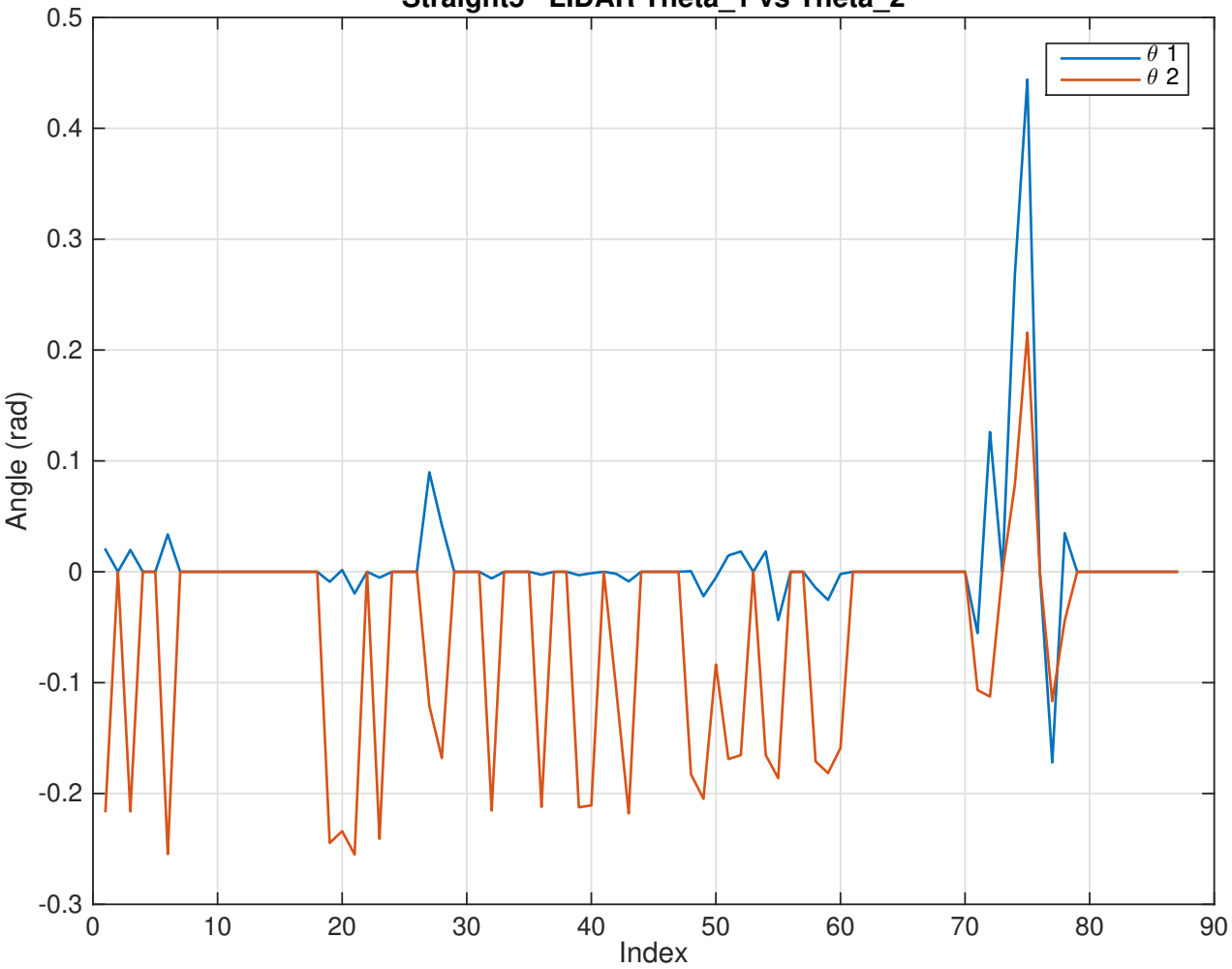
Straight5 Camera L1 vs L2



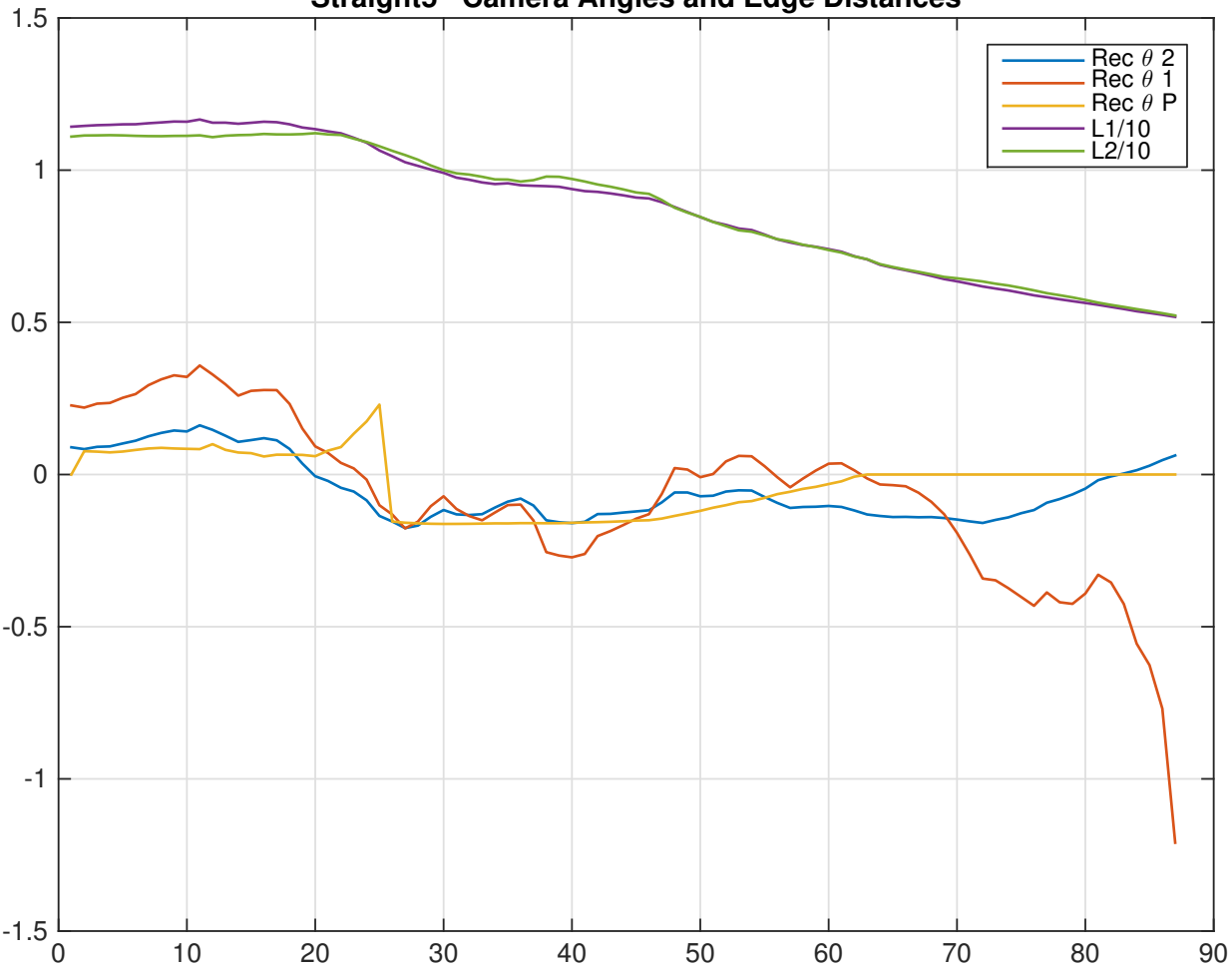
Straight5 Camera Theta_1 vs Theta_2



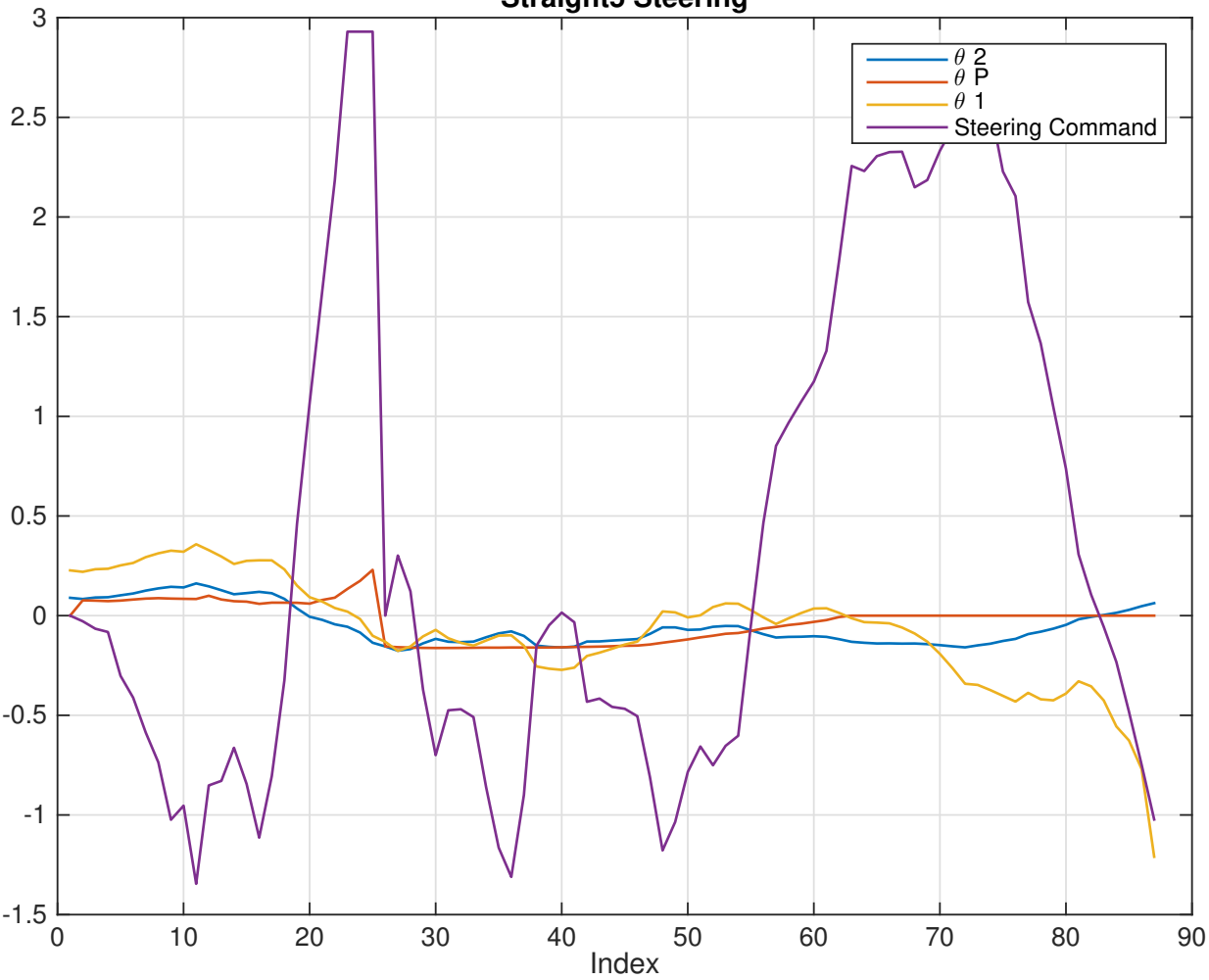
Straight5 LIDAR Theta_1 vs Theta_2



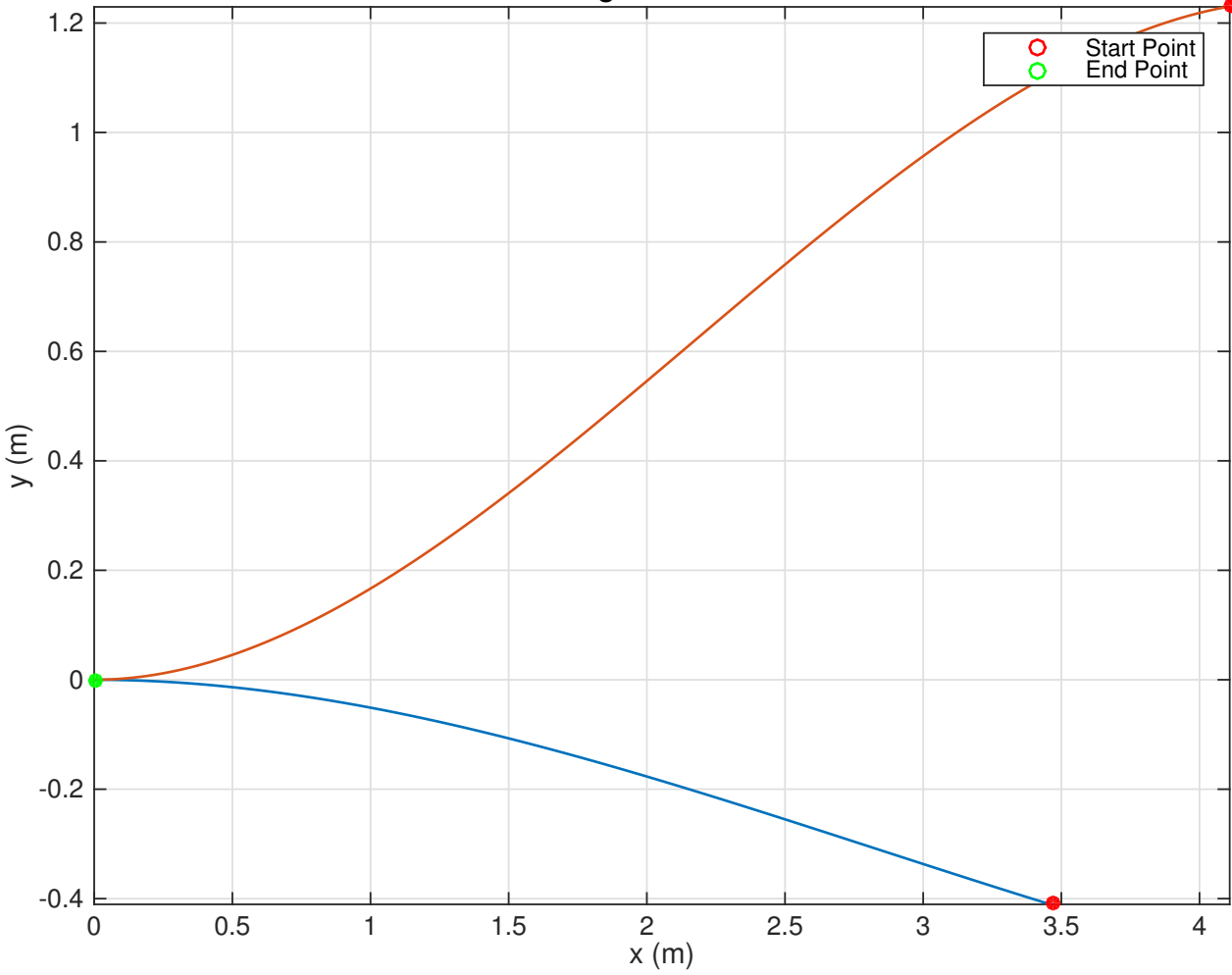
Straight5 Camera Angles and Edge Distances



Straight5 Steering



Straight5 All Paths



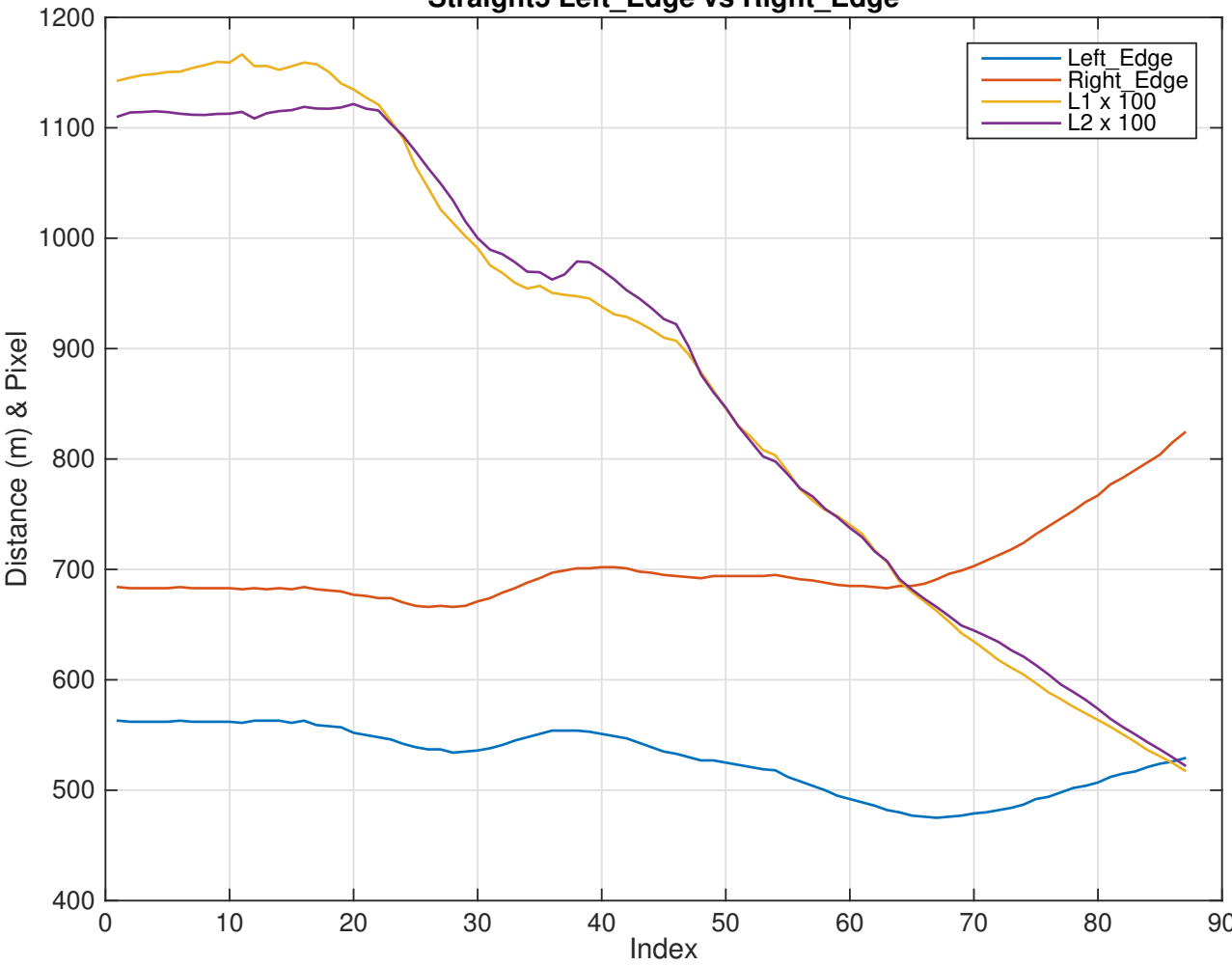
Number_Of_Unique_Paths

King_Pin_Detected

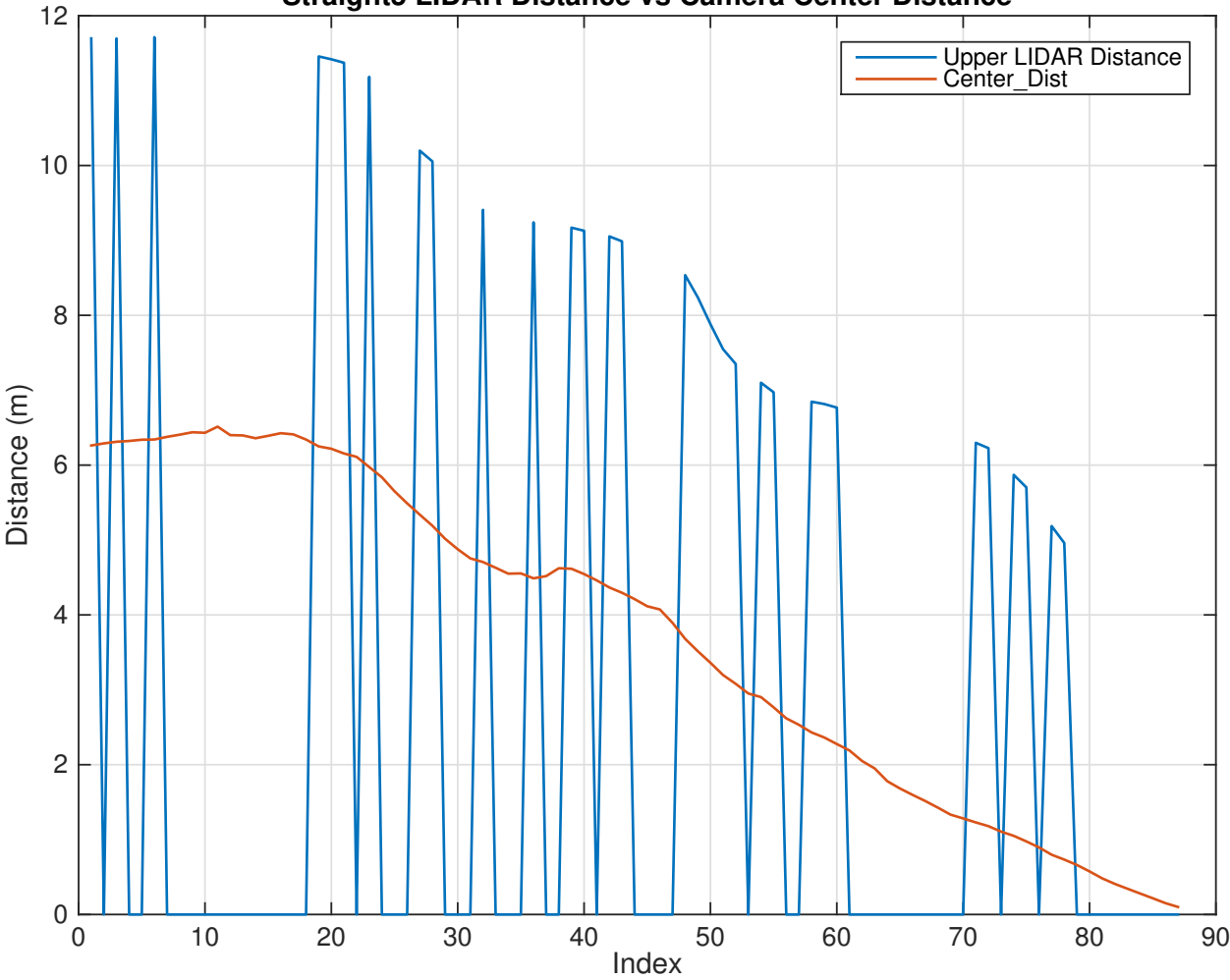
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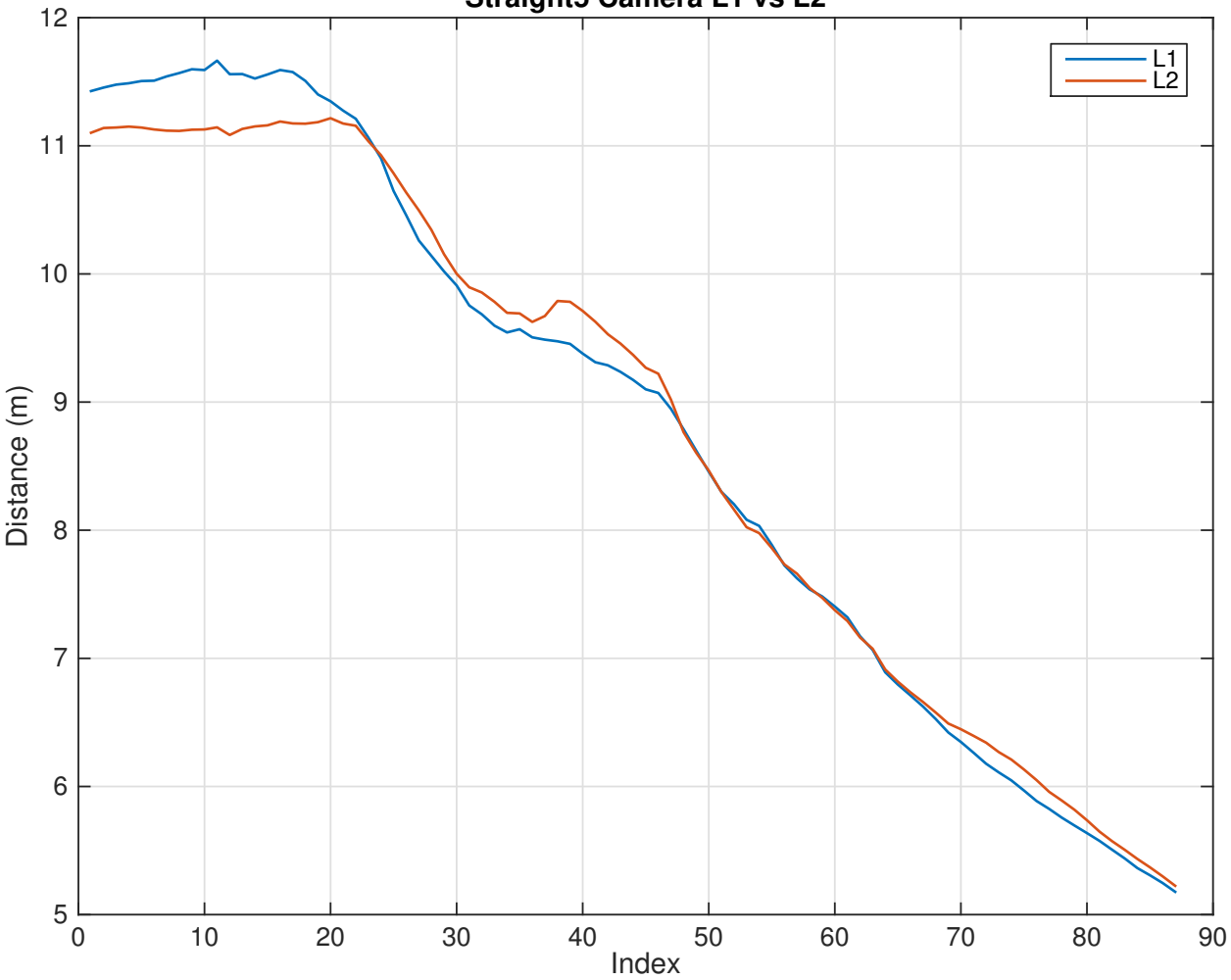
Straight5 Left_Edge vs Right_Edge



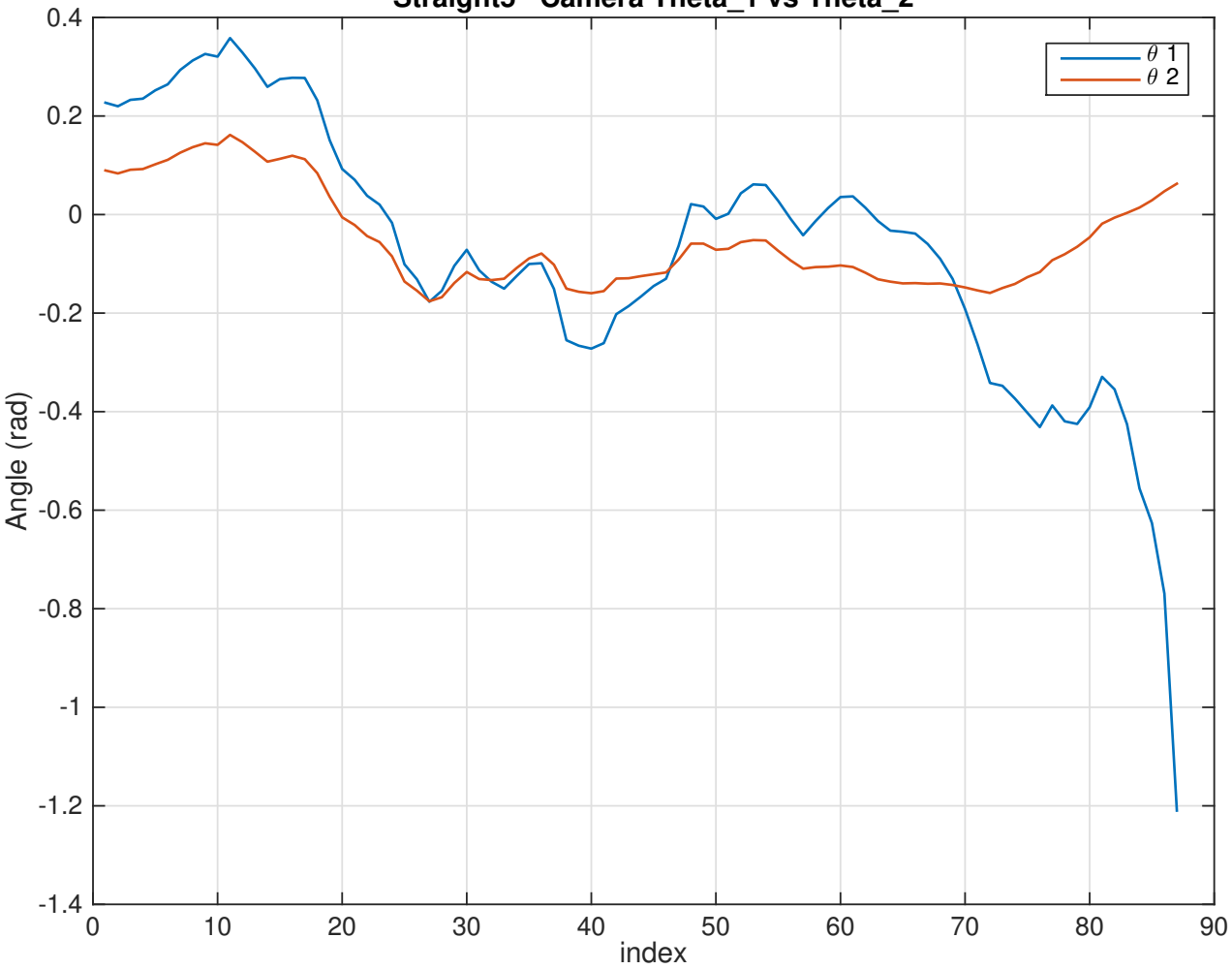
Straight5 LIDAR Distance vs Camera Center Distance



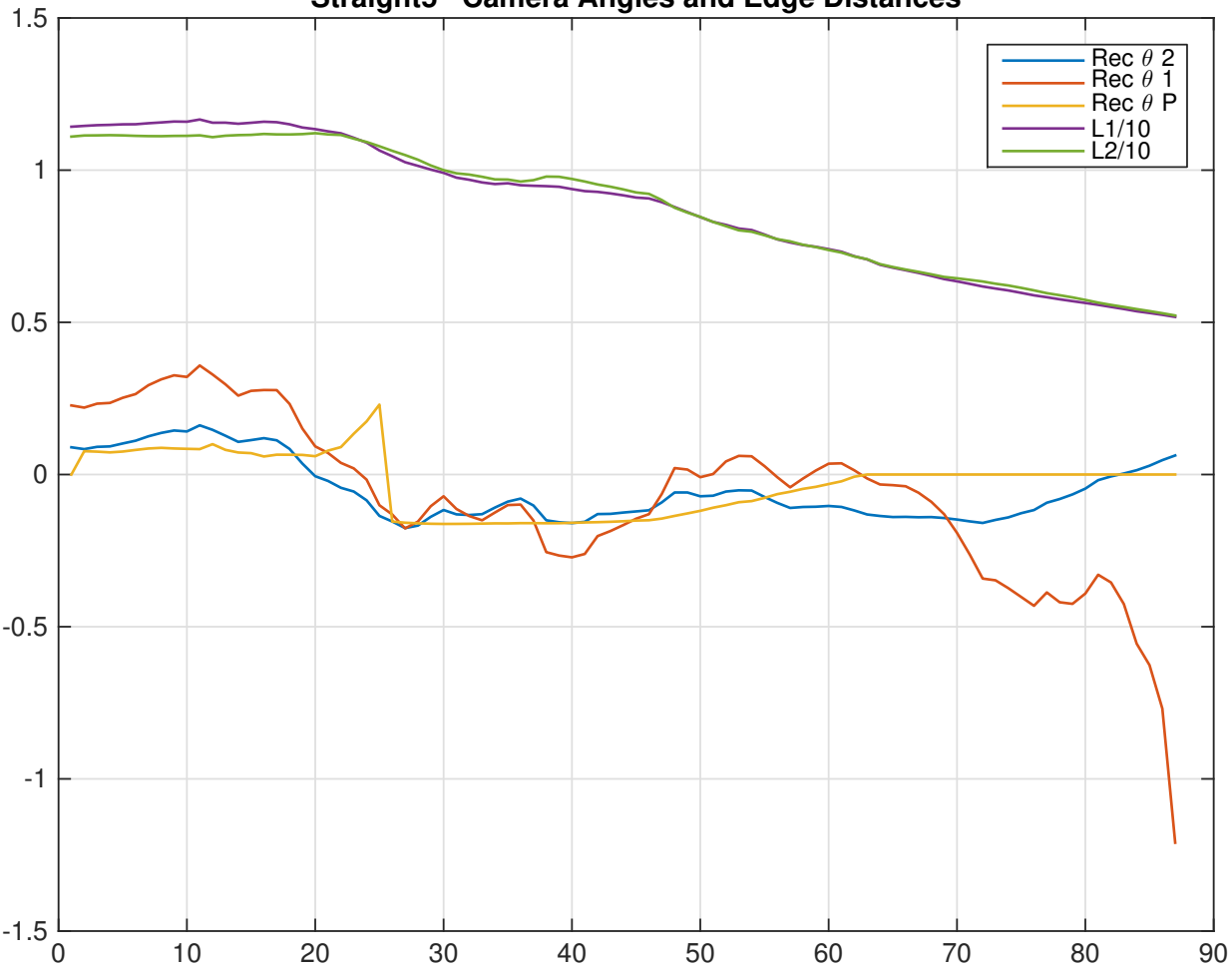
Straight5 Camera L1 vs L2



Straight5 Camera Theta_1 vs Theta_2



Straight5 Camera Angles and Edge Distances



Straight5 Steering

