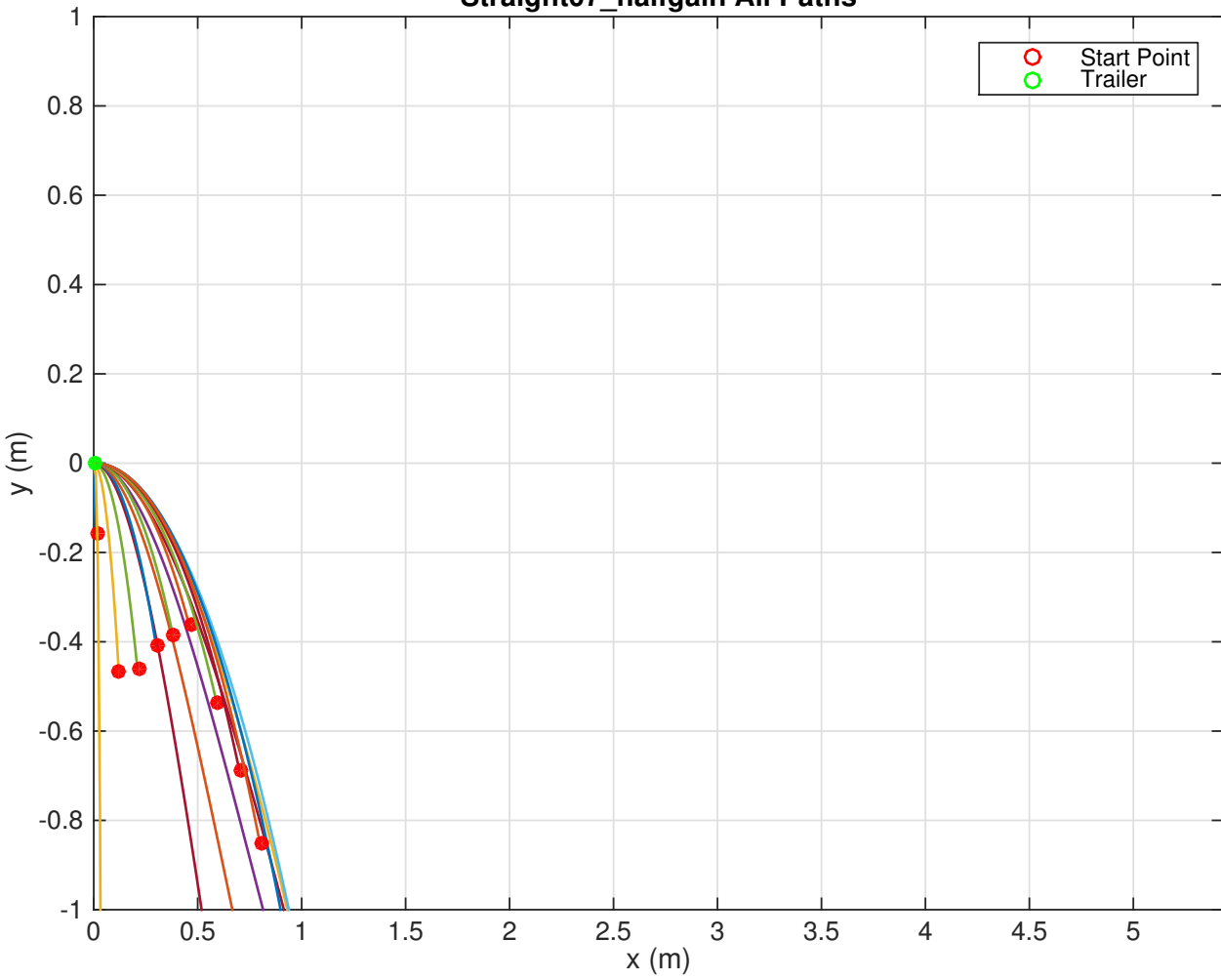


Straight07_halfgain All Paths



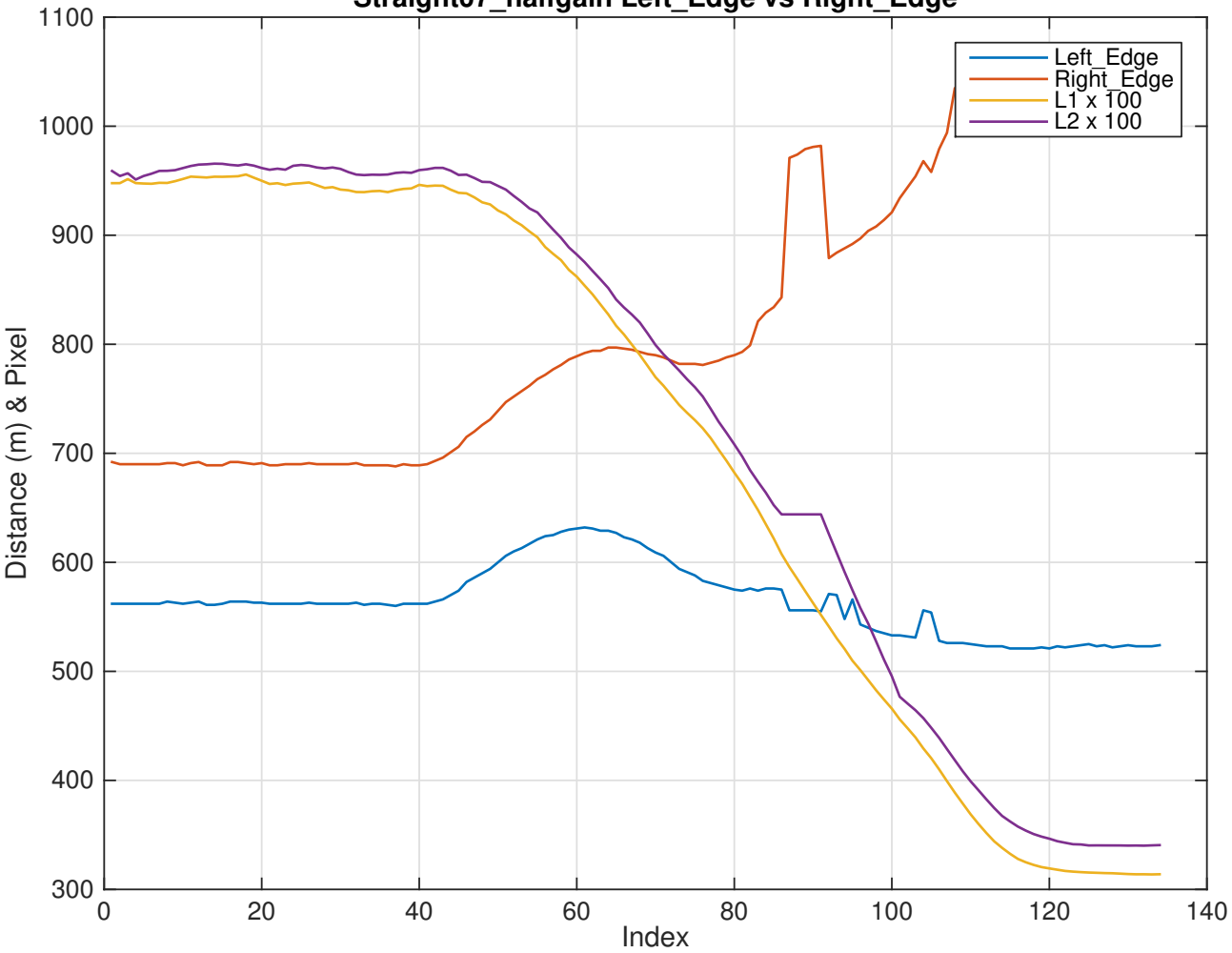
Number_Of_Unique_Paths

King_Pin_Detected

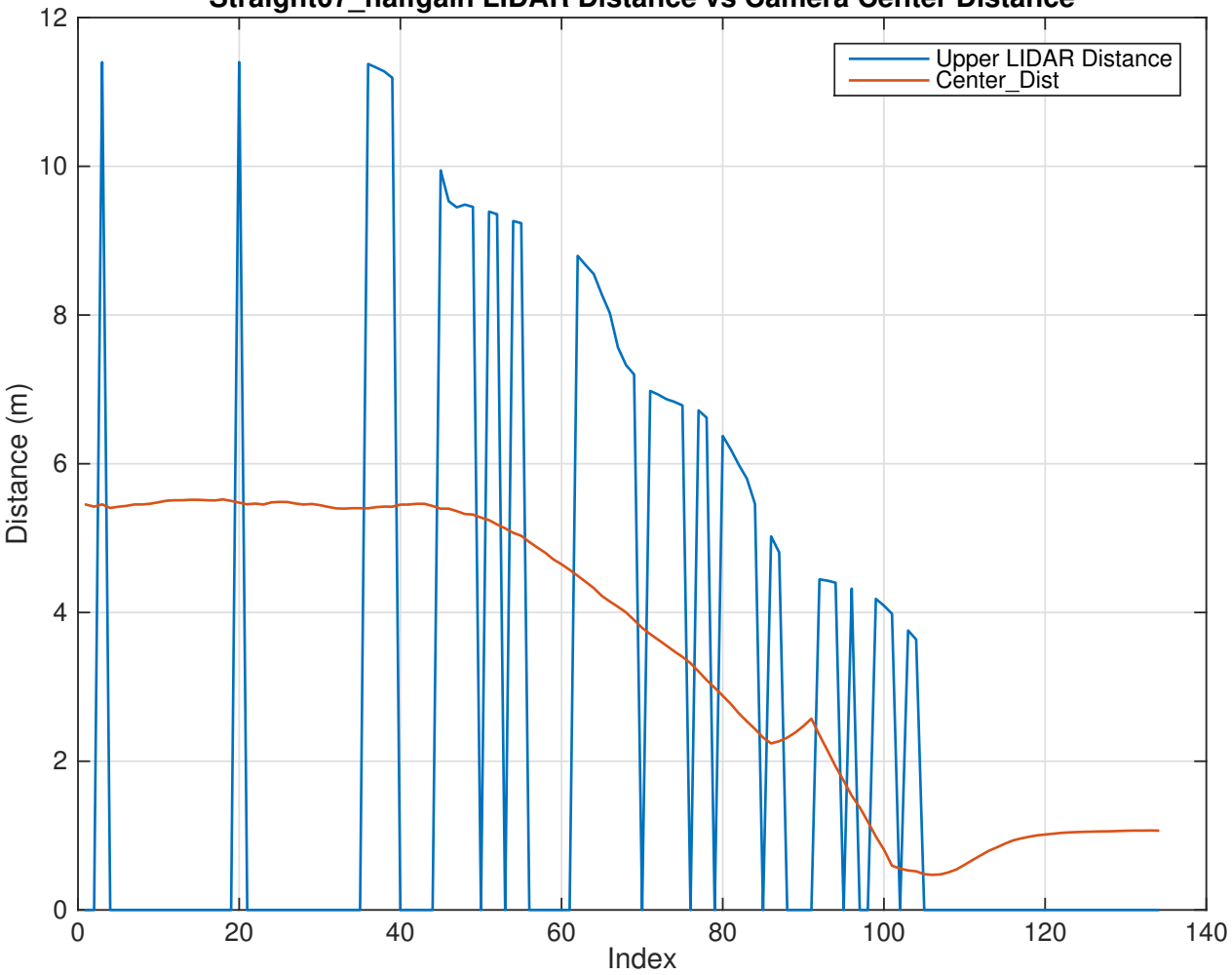
45

false

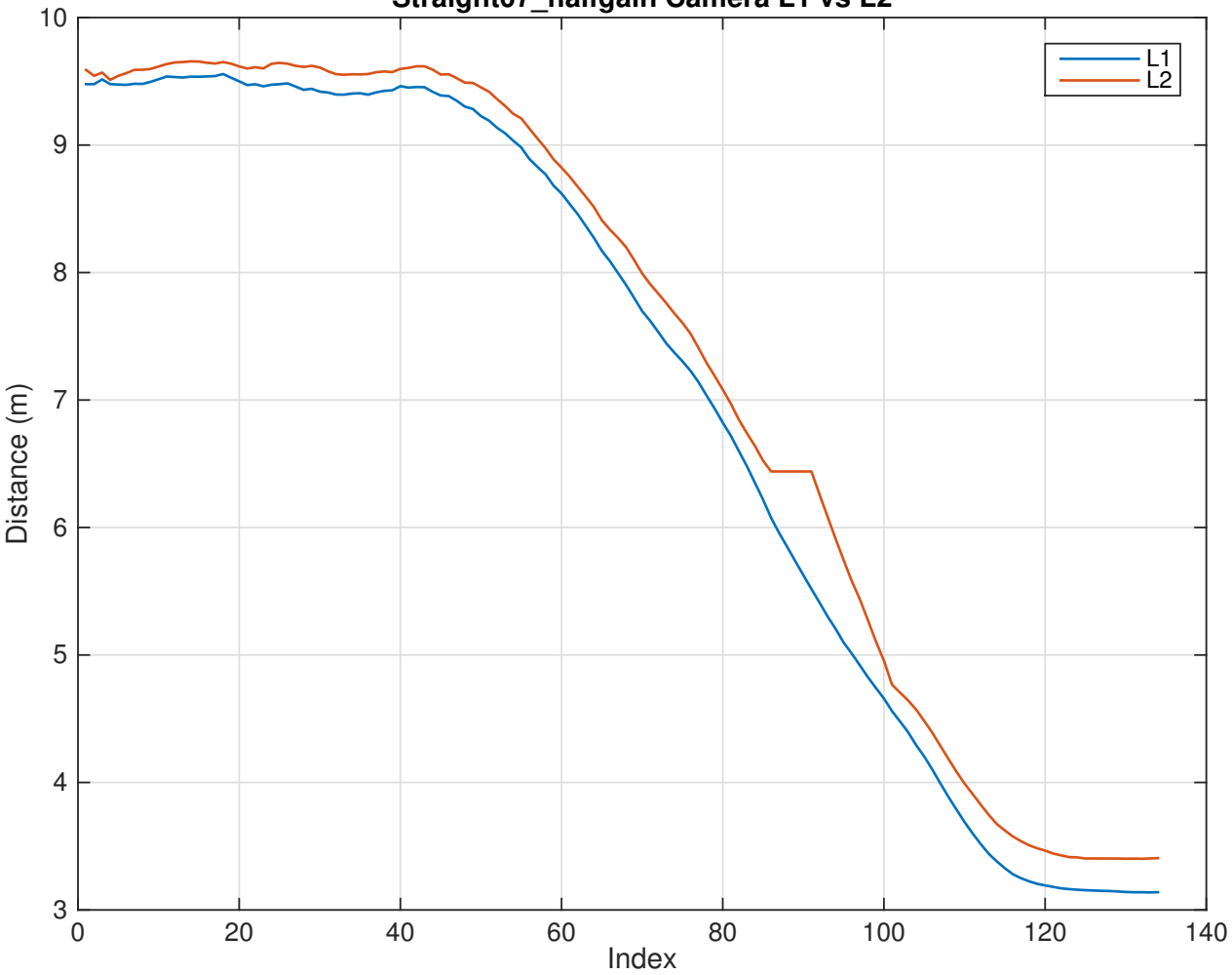
Straight07_halfgain Left_Edge vs Right_Edge



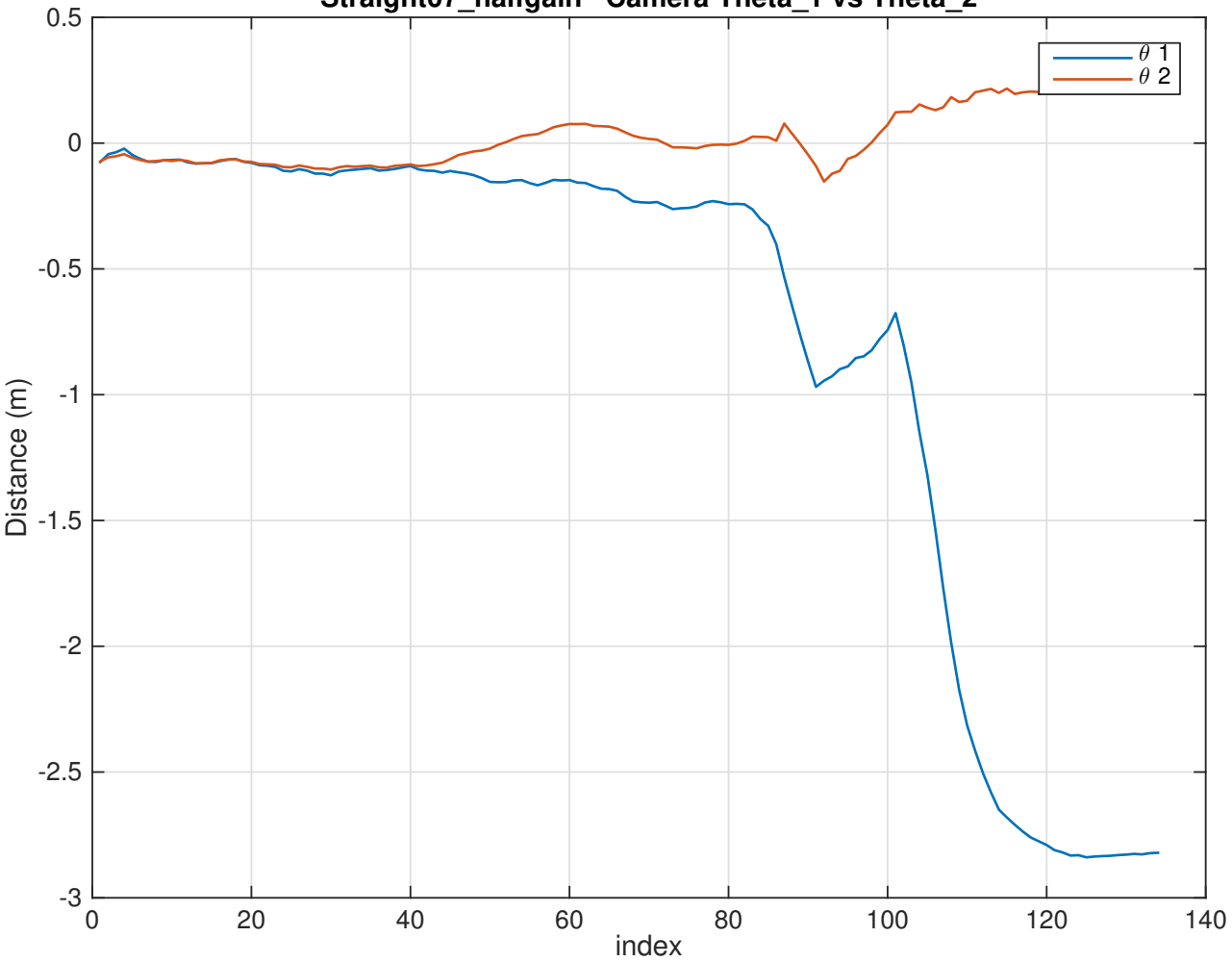
Straight07_halfgain LIDAR Distance vs Camera Center Distance



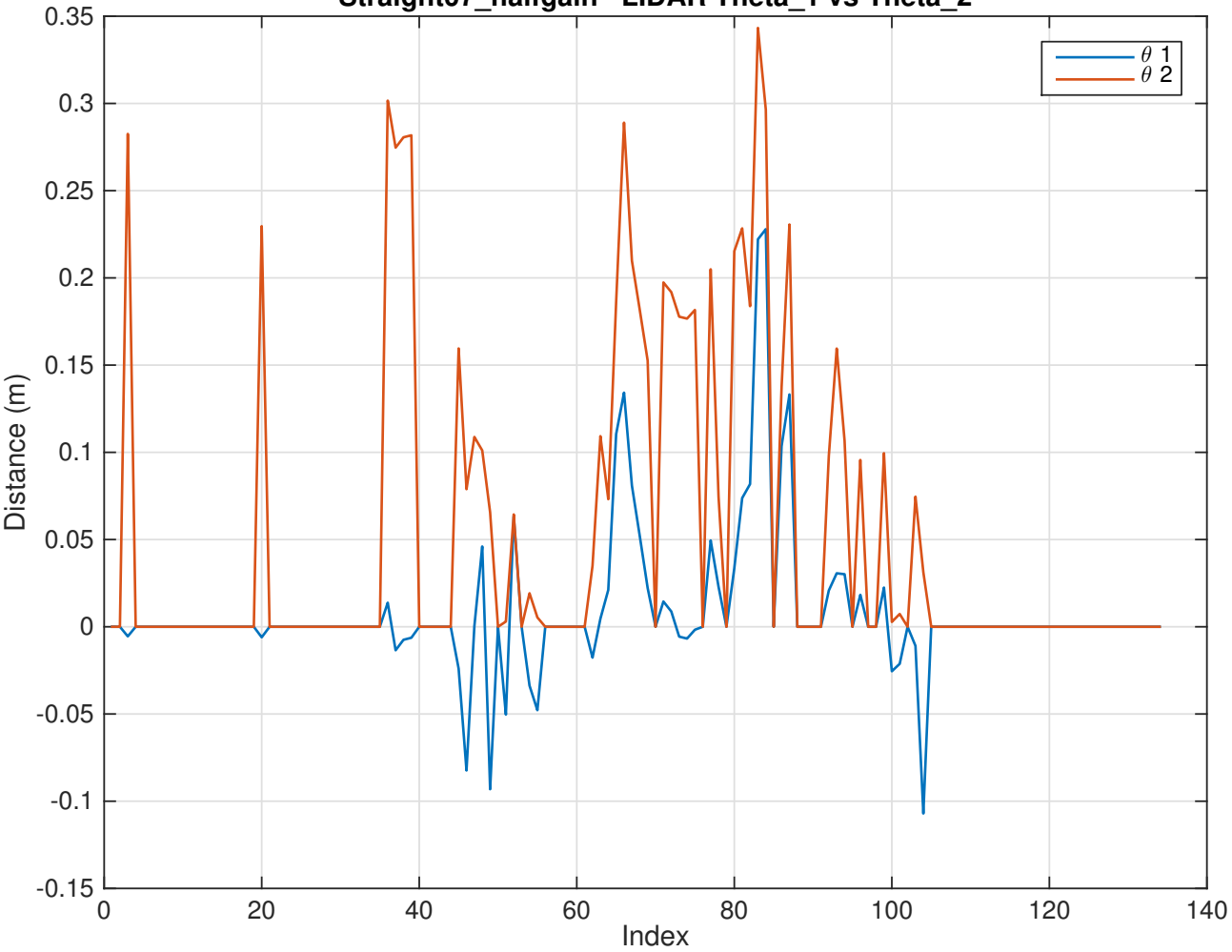
Straight07_halfgain Camera L1 vs L2



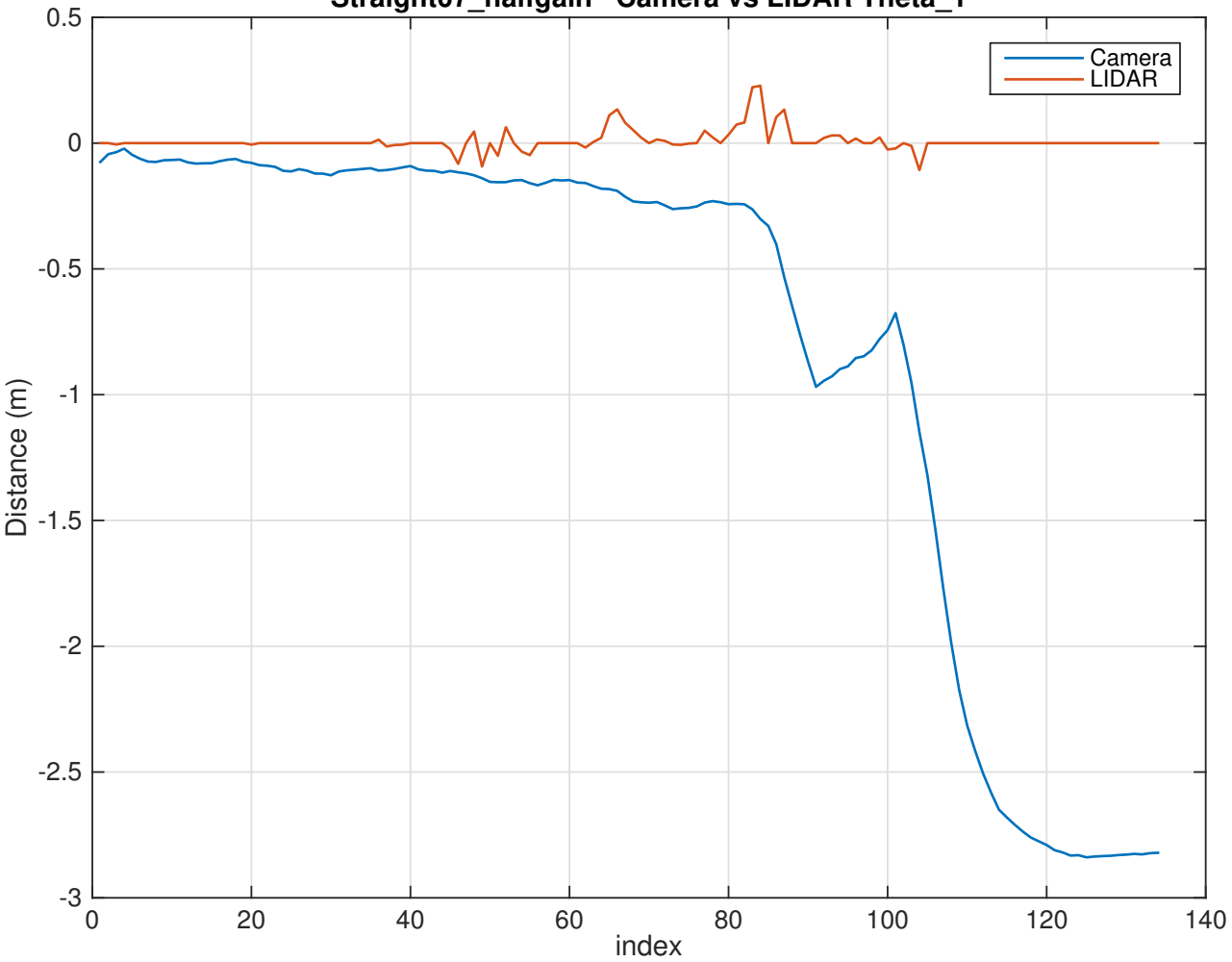
Straight07_halfgain Camera Theta_1 vs Theta_2



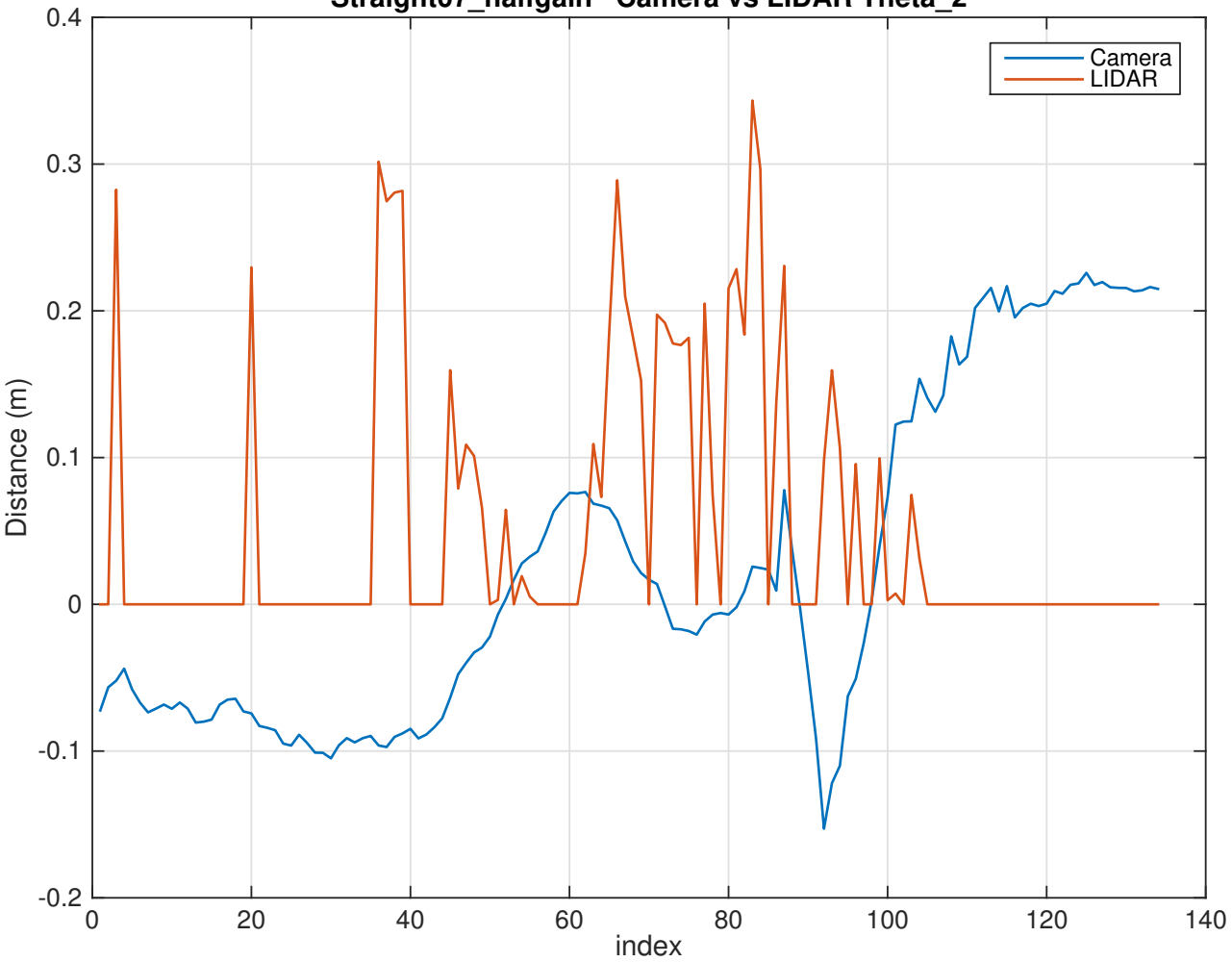
Straight07_halfgain LIDAR Theta_1 vs Theta_2



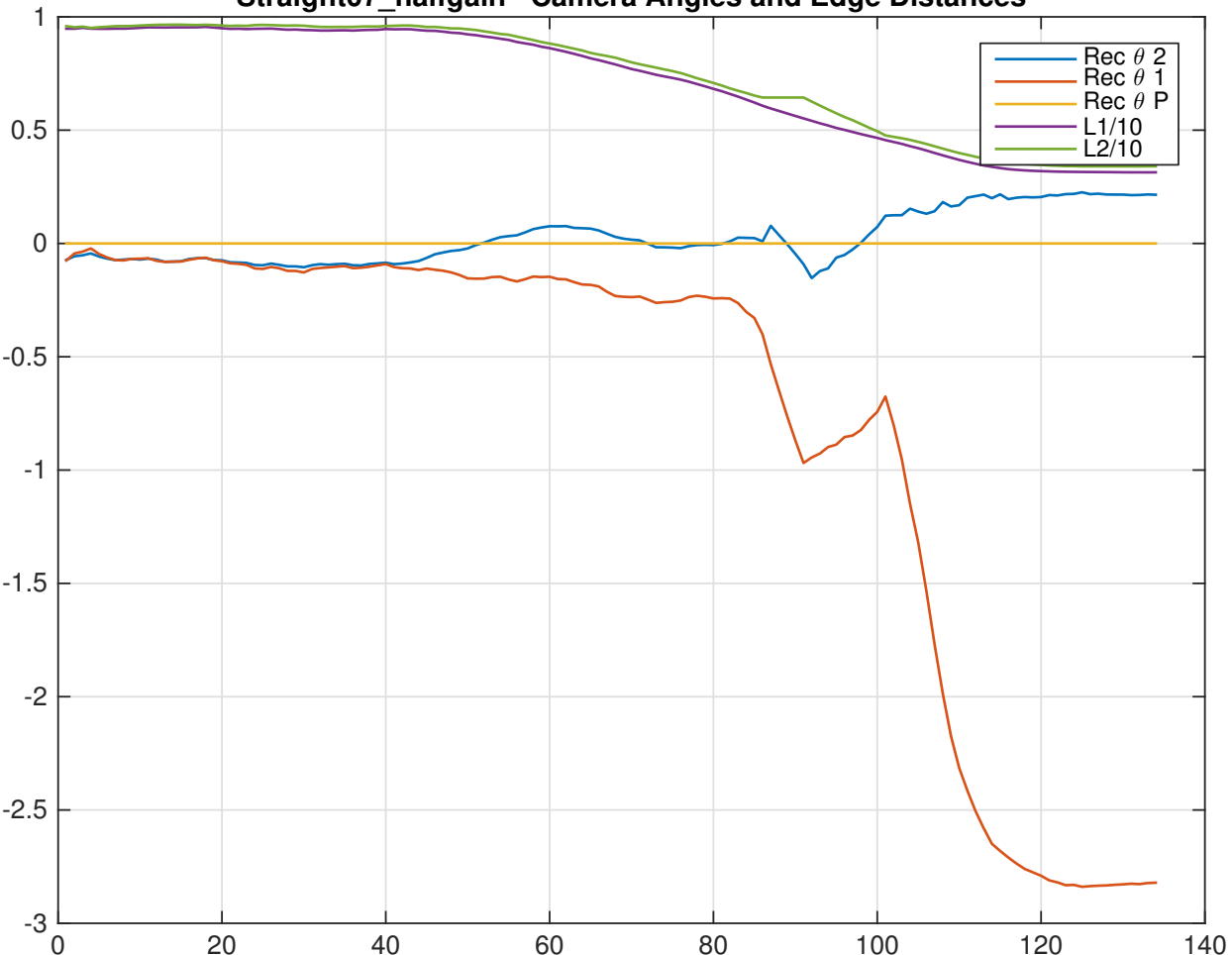
Straight07_halfgain Camera vs LIDAR Theta_1



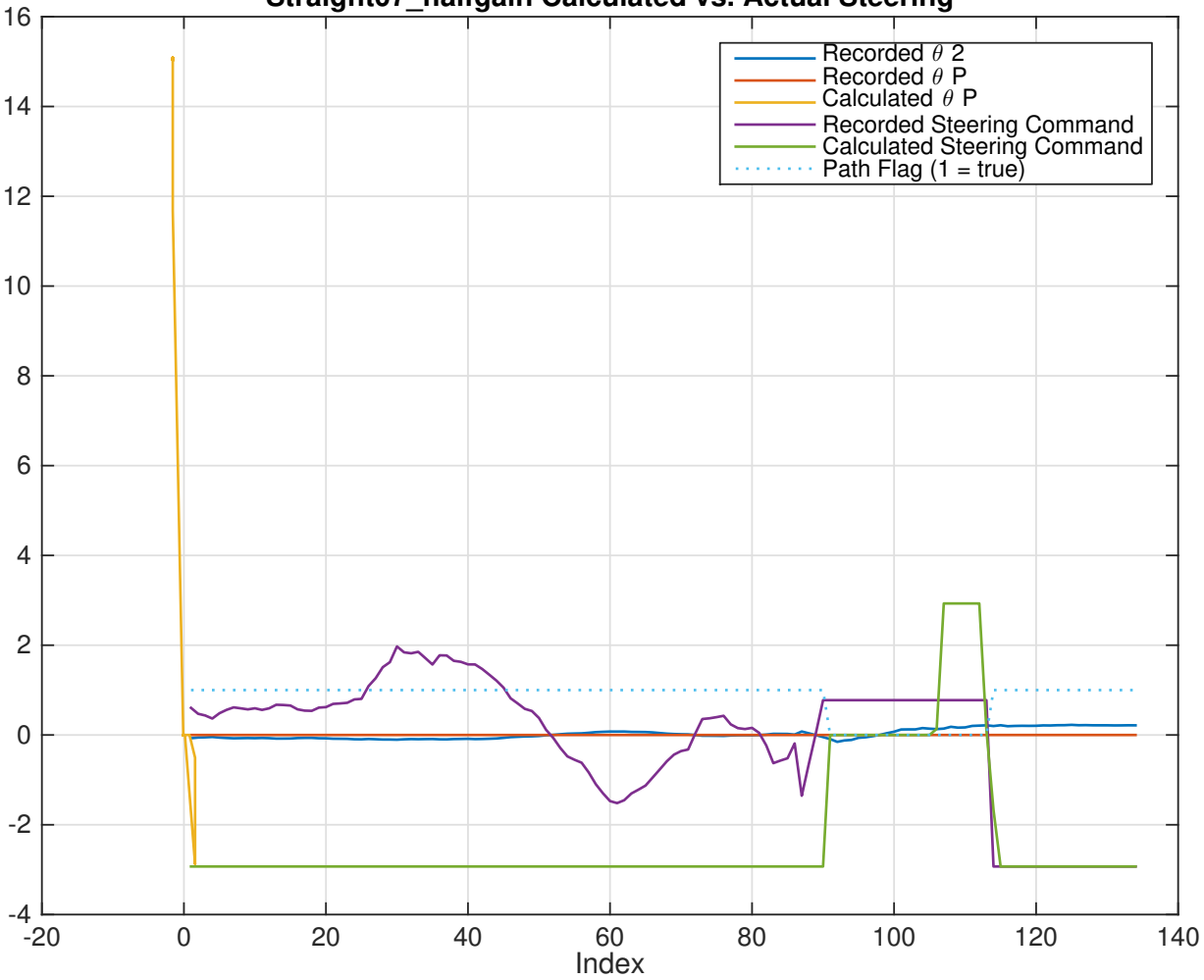
Straight07_halfgain Camera vs LIDAR Theta_2



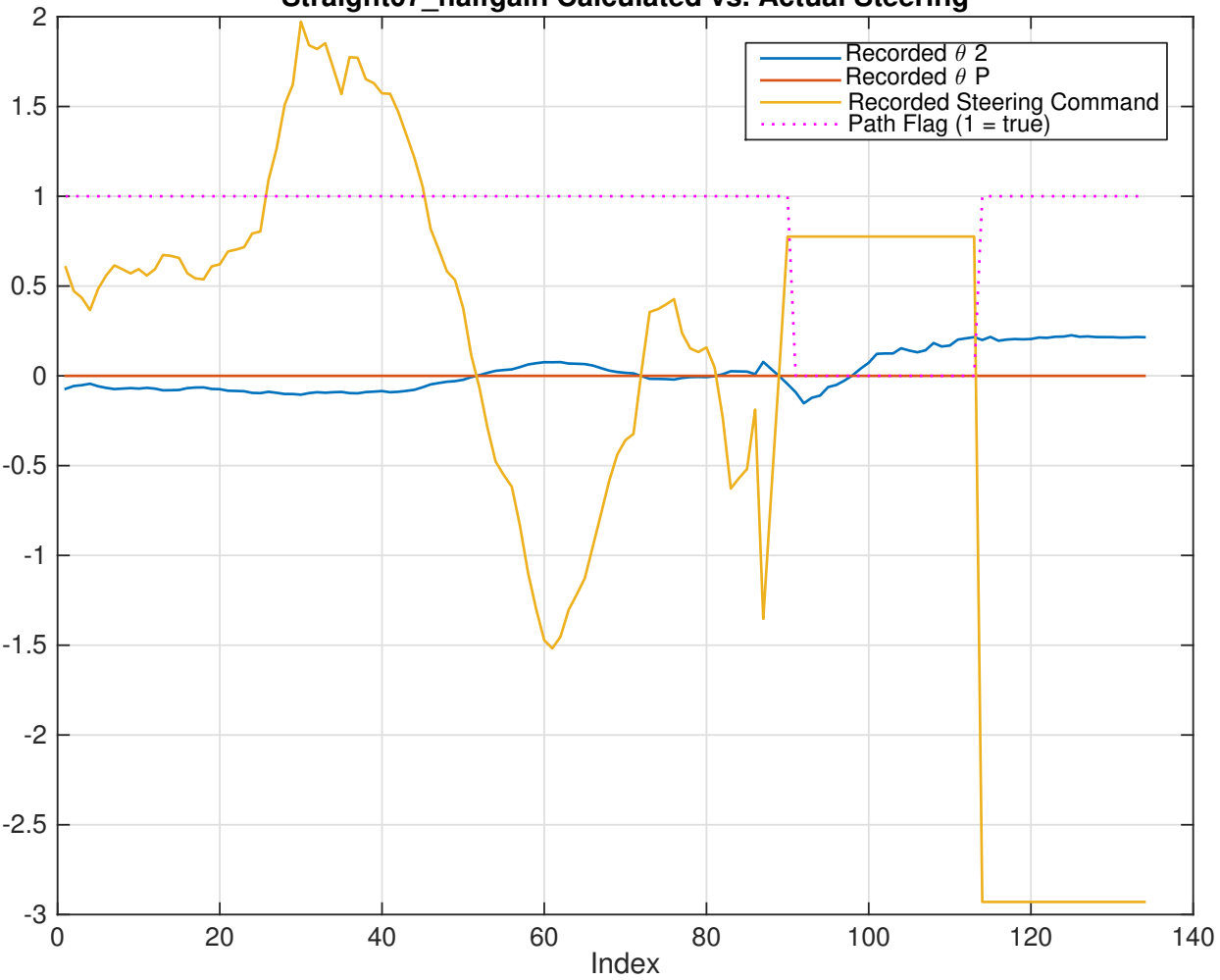
Straight07_halfgain Camera Angles and Edge Distances



Straight07_halfgain Calculated vs. Actual Steering



Straight07_halfgain Calculated vs. Actual Steering



Straight07_halfgain Calculated vs. Actual Steering

