# **Quantum Optics Assignment 1**

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```
In [ ]: import numpy as np
   import matplotlib.pyplot as plt

In [ ]: ### constants ###
   c = 299792458
   h_si = 6.626e-34 # J s
   h_ev = 4.136e-15 # eV s
   kB = 1.381e-23 # J / K
```

#### **Problem 1a**

```
In []: wl = 852e-9 # wavelength of cesium in nm
f = c / wl
E_joules = h_si * f # J
E_ev = h_ev * f # eV
T = E_joules / kB

print("Problem 1a")
print(f"Photon energy: {E_joules:.03} J or {E_ev:.03} eV")
print(f"Photon frequency: {f*1e-12:.04n} THz")
print(f"Temperature: {T:.03} K")
```

Problem 1a
Photon energy: 2.33e-19 J or 1.46 eV
Photon frequency: 351.9 THz
Temperature: 1.69e+04 K

### **Problem 1b**

```
In [ ]: wl = 589e-9  # wavelength of sodium in nm
u = 1.66e-27  # kg
m = 22.99 * u

f = c / wl
E = f * h_si
v = np.sqrt(2 * E / m)
print(f"Velocity: {v:.03} m/s")
```

Velocity: 4.2e+03 m/s

### Problem 1c

```
In [ ]: p = h_si / wl
v = p / m
E = 1/2 * m * v**2
print(f"Recoil velocity: {v:.03} m/s")
```

```
print(f"Recoil energy: {E:.03} J or {E/h_si*1e12} THz")
print(f"Recoil temperature: {E/kB*1e6:.03n} uK")
```

Recoil velocity: 0.0295 m/s

Recoil energy: 1.66e-29 J or 2.5023254157294932e+16 THz

Recoil temperature: 1.2 uK

#### Problem 2a

Functions of  $\mathbf{r}$  commute with  $\mathbf{r}$ , and likewise with  $\mathbf{p}$ .

$$[\mathbf{r}, \mathbf{A}(\mathbf{r}, t)] = 0$$
  
 $[\mathbf{r}, U(\mathbf{r}, t)] = 0$ 

### **Problem 2b**

$$H=rac{1}{2m}\sum_{i=x,y,z}\left[p_{i}^{2}+q^{2}A_{i}^{2}\left(\mathbf{r},t
ight)-qp_{i}A_{i}\left(\mathbf{r},t
ight)-qA_{i}\left(\mathbf{r},t
ight)p_{i}
ight]+qU\left(\mathbf{r},t
ight)$$

$$egin{aligned} \left[x,H
ight] &= rac{1}{2m} \sum_{i=x,y,z} \left\{ \left[x,p_i^2
ight] - q\left[x,p_iA_i\left(\mathbf{r},t
ight)
ight] - q\left[x,A_i\left(\mathbf{r},t
ight)p_i
ight] 
ight\} \ &= rac{1}{2m} \left\{ p_x \left[x,p_x
ight] + \left[x,p_x
ight]p_x - q\left[x,p_x
ight]A_x\left(\mathbf{r},t
ight) - qA_i\left(\mathbf{r},t
ight)\left[x,p_x
ight] 
ight\} \ &= rac{1}{2m} \left\{ 2i\hbar p_x - 2qi\hbar A_x\left(\mathbf{r},t
ight) 
ight\} \ &= rac{i\hbar}{m} \left\{ p_x - qA_x\left(\mathbf{r},t
ight) 
ight\} \end{aligned}$$

$$egin{aligned} rac{d}{dt}\langle x
angle &=rac{1}{i\hbar}\langle [x,H]
angle +\left\langle rac{\partial}{\partial t}x
ight
angle \ &=rac{1}{m}\langle p_x-qA_x\left(\mathbf{r},t
ight)
angle \end{aligned}$$

Similarly for y and  $z_t$ 

$$egin{aligned} rac{d}{dt}\langle y
angle &=rac{1}{m}ig\langle p_y-qA_y\left(\mathbf{r},t
ight)ig
angle \ rac{d}{dt}\langle z
angle &=rac{1}{m}\langle p_z-qA_z\left(\mathbf{r},t
ight)
angle \end{aligned}$$

The velocity is therefore

$$\langle \mathbf{v} 
angle = rac{1}{m} \langle \mathbf{p} - q \mathbf{A} \left( \mathbf{r}, t 
ight) 
angle$$

### **Problem 2c**

$$\begin{split} \frac{d}{dt}\langle\mathbf{v}\rangle &= \frac{1}{i\hbar}\langle[\mathbf{v},H]\rangle + \left\langle\frac{\partial}{\partial t}\mathbf{v}\right\rangle \\ &= \frac{1}{i\hbar}\langle[\mathbf{v},qU\left(\mathbf{r},t\right)]\rangle - \frac{q}{m}\left\langle\frac{\partial}{\partial t}\mathbf{A}\left(\mathbf{r},t\right)\right\rangle \\ &= \frac{1}{i\hbar}\left\langle\left[\frac{\mathbf{p}}{m},qU\left(\mathbf{r},t\right)\right]\right\rangle - \frac{q}{m}\left\langle\frac{\partial}{\partial t}\mathbf{A}\left(\mathbf{r},t\right)\right\rangle \end{split}$$

Using  $[p,f(x)]=-i\hbar\partial_x f(x)$ , this is

$$egin{aligned} rac{d}{dt}\langle\mathbf{v}
angle &= rac{q}{m}rac{1}{i\hbar}\langle -i\hbar
abla U\left(\mathbf{r},t
ight)
angle - rac{q}{m}\left\langlerac{\partial}{\partial t}\mathbf{A}\left(\mathbf{r},t
ight)
ight
angle \\ &= -rac{q}{m}\langle
abla U\left(\mathbf{r},t
ight)
angle - rac{q}{m}\left\langlerac{\partial}{\partial t}\mathbf{A}\left(\mathbf{r},t
ight)
ight
angle \end{aligned}$$

According to physics stackexchange,  ${f E}=-rac{\partial {f A}}{\partial t}$ . This means that our force  $mrac{d}{dt}\langle {f v} \rangle$  has a clear classical analogue.

$$m\mathbf{a} = -q\nabla U\left(\mathbf{r},t\right) + q\mathbf{E}$$

### **Problem 3a**

$$egin{align} |\psi
angle &= egin{pmatrix} \sqrt{3/4} \ -i/2 \end{pmatrix} \ |\langle\psi| &= ig(\sqrt{3/4} \quad i/2ig) \ |
ho_{
m pure} &= |\psi
angle \langle\psi| &= egin{pmatrix} 3/4 & i\sqrt{3}/4 \ -i\sqrt{3}/4 & 1/4 \end{pmatrix} \end{aligned}$$

## **Problem 3b**

$$ho_1=rac{3}{4}|g
angle\left\langle g
ight|=rac{3}{4}egin{pmatrix}1&0\0&0\end{pmatrix} \ 
ho_2=rac{1}{4}|e
angle\left\langle e
ight|=rac{1}{4}egin{pmatrix}0&0\0&1\end{pmatrix}$$

$$ho_{ ext{impure}} = 
ho_1 + 
ho_2 = \left(egin{array}{cc} 3/4 & 0 \ 0 & 1/4 \end{array}
ight)$$

In the pure ensemble, all atoms are in a definite state  $|\psi\rangle$ . In the impure ensemble, a proportion of atoms are in each state. Therefore, if we could devise an experiment to determine the likelihood of an atom being in  $|\psi\rangle$ , we would get different answers for the two ensembles. For (a), we would get unity. For (b), we would get an answer based on the projection of the component states onto  $|\psi\rangle$ . Let  $A=|\psi\rangle\,\langle\psi|$  be the observable that we can measure.

$$\langle A 
angle_{ ext{(pure)}} = \operatorname{Tr}\left[
ho_{ ext{pure}}A
ight] = \operatorname{Tr}\left[
ho_{ ext{pure}}^2
ight] = 1$$

$$\langle A 
angle_{
m (impure)} = {
m Tr} \left[ 
ho_{
m impure} A 
ight] = {
m Tr} \left[ \left( egin{array}{cc} (3/4)^2 & i 3^{3/2}/16 \ -i \sqrt{3}/16 & 1/16 \end{array} 
ight) 
ight] = 10/16$$

### Problem 3d

If we use a basis in which  $\rho$  is diagonal, the entropy is simply

$$S = -k_B {
m Tr} \left[ 
ho \ln 
ho 
ight] = -k_B \sum_k 
ho_k^{
m (diag)} \ln 
ho_k^{
m (diag)}.$$

For the pure state, the eigenvalues are 1 and 0.

$$S_{ ext{pure}} = -k_B \left[ 1 \cdot \ln 1 + \lim_{x o 0^+} x \ln x 
ight].$$

We can evaluate the limit using L'hopital's rule. Note that we have to write it as a fraction.

$$\lim_{x o 0^+} x \ln x = \lim_{x o 0^+} rac{\ln x}{1/x} = \lim_{x o 0^+} -rac{1/x}{1/x^2} = \lim_{x o 0^+} -x = 0$$

So the entropy of a pure state is zero!

$$S_{
m pure}=0$$

For the mixed state,

$$S_{\text{impure}} = -k_B \left[ 3/4 \cdot \ln 3/4 + 1/4 \cdot \ln 1/4 \right] \approx 0.562 k_B$$

Entropy: 0.562 kB

#### Problem 3e

In this case, we only consider two states |g
angle and |e
angle , with energy 0 and 1.

$$ho = rac{1}{Z} \Big( \ket{g}ra{g} + e^{-1/k_BT}\ket{e}ra{e} \Big)$$

At  $T=0,~e^{-1/k_BT} o 0$  and the population is purely in the ground state. As  $T o \infty,~e^{-1/k_BT} o 1$  and the density matrix is a statistical mixture of ground and excited.

$$ho_{T o\infty}=egin{pmatrix} 1/2 & 0 \ 0 & 1/2 \end{pmatrix}$$

# **Appendices**

Commutator of momentum and a position-dependent function

$$egin{aligned} \left\langle x \right| \left[ \hat{p}, f(\hat{x}) \right] \left| \psi \right
angle &= \left\langle x \right| \left( \hat{p} f(\hat{x}) - f(\hat{x}) \hat{p} \right) \left| \psi \right
angle \\ &= -i \hbar \partial_x \left( f(x) \psi(x) \right) - i \hbar f(x) \partial_x \psi(x) \\ &= -i \hbar \left( \partial_x f(x) \right) \psi(x) \end{aligned}$$