

0.1 Transition Rules

In this section some of the transition rules in SPLAD will be explained. The complete list of all the rules can be seen in appendix ???. In the following text we use the following names to represent different syntactic categories.

- $n \in \mathbf{Num}$ - Numerals
- $x \in \mathbf{Var}$ - Variables
- $r \in \mathbf{Arrays}$ - Array names
- $a \in \mathbf{A_{exp}}$ - Arithmetic expression
- $b \in \mathbf{B_{exp}}$ - Boolean expression
- $S \in \mathbf{Stm}$ - Statements

0.1.1 Environment-Store Model

In our project we use the *environment-store model* to represent how a variable is bound to a storage cell (called a *location*), in the computer, and that the value of the variable is the content of the bound location. All the possible locations are denoted by \mathbf{Loc} and a single location as $l \in \mathbf{Loc}$. We assume all locations are integer, and therefore $\mathbf{Loc} = \mathbb{Z}$. Since all locations are integers we can define a function to find the next location: $\mathbf{Loc} \rightarrow \mathbf{Loc}$, where $l = l + 1$.

We define the set of stores to be the mappings from locations to values $\mathbf{Sto} = \mathbf{Loc} \rightarrow \mathbb{Z}$, where sto is an single element in \mathbf{Sto} .

An variable-environment is like a symbol table containing each variable and store the variables address. The store then describe which values that is on each address.

The following names represent the different environments.

- $env_V \in Env_V$ - Variable environment
- $env_A \in Env_A$ - Array environment
- $env_P \in Env_P$ - Procedure environment

0.1.2 Big-step-semantic and small-step-semantic

0.1.3 Abstract Syntax

Here the abstract syntax of SPLAD can be seen. An abstract syntax is bla bla bla...

$$\begin{aligned}
 S &::= x := a \mid r[a_1] := a_2 \mid S_1; S_2 \mid \text{if } b \text{ do } S \mid \text{if } b \text{ do } S_1 \text{ else do } S_2 \mid \text{while } b \text{ do } S \\
 &\quad \mid \text{from } x := a_1 \text{ to } a_2 \text{ step } a_3 \text{ do } S \mid \text{call } p(\vec{x}) \mid \text{begin } D_V D_P S \text{ end} \\
 a &::= n \mid x \mid a_1 + a_2 \mid a_1 - a_2 \mid a_1 * a_2 \mid a_1 / a_2 \mid (a) \\
 b &::= a_1 = a_2 \mid a_1 > a_2 \mid a_1 < a_2 \mid \neg b \mid b_1 \wedge b_2 \mid b_1 \vee b_2 \mid (b) \\
 D_V &::= \text{var } x := a; D_V \mid \varepsilon \\
 D_P &::= \text{proc } p \text{ is } S; D_P \mid \varepsilon \\
 D_A &::= \text{array } r[a_1] := a_2; D_A \mid \varepsilon
 \end{aligned}$$

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hvad det er, og
bruger big-step.
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0.1.4 Statements

The transition rules for the statements are on the form: $env_V, env_P \vdash \langle S, sto \rangle \rightarrow sto'$.

The transition rule for variable assignment in SPLAD can be seen on table 0.1. When a variable is assigned the contents of l is updated to v , where l is the location of x found in the env_V and v is the result of the arithmetic expression a .

$$\begin{array}{c} \text{[VAR-ASS]} \quad env_V, env_P \vdash \langle x \leftarrow a, sto \rangle \rightarrow sto[l \mapsto v] \\ \\ \text{where } env_V, sto \vdash a \rightarrow_a v \\ \text{and } env_V \ x = l \end{array}$$

Table 0.1: Transition rule for variable assignment.

0.1.5 Arithmetic Expressions

The transition rules for the arithmetic expressions are on the form: $env_V, sto \vdash a \rightarrow_a v$.

The transition rule for multiplication in SPLAD can be seen on table 0.2. The rule states, that if a_1 evaluates to v_1 and a_2 evaluates to v_2 , using any of the rules from the arithmetic expressions, then $a_1 \cdot a_2$ evaluates to v where $v = v_1 \cdot v_2$.

0.1.6 Boolean Expression

The transition rules for boolean expressions are on the form: $env_V, sto \vdash b \rightarrow_b t$.

The transition rule for logical-or in SPLAD can be seen on table 0.3. The rules have two parts: [OR-TRUE] and [OR-FALSE]. The [OR-TRUE] rule states that either b_1 or b_2 evaluates to *TRUE*, using any of the rules from the boolean expressions, then the expression $b_1 \text{ OR } b_2$ evaluates to *TRUE*. [OR-FALSE] states that if both b_1 and b_2 evaluate to *FALSE* then the expression $b_1 \text{ OR } b_2$ evaluates to *FALSE*.

$$\begin{array}{c} \text{[OR-TRUE]} \quad \frac{env_V, sto \vdash b_i \rightarrow_b \text{TRUE}}{env_V, sto \vdash b_1 \vee b_2 \rightarrow_b \text{TRUE}} \\ \\ \text{where } i \in 1, 2 \\ \\ \text{[OR-FALSE]} \quad \frac{env_V, sto \vdash b_1 \rightarrow_b \text{FALSE} \quad env_V, sto \vdash b_2 \rightarrow_b \text{FALSE}}{env_V, sto \vdash b_1 \vee b_2 \rightarrow_b \text{FALSE}} \end{array}$$

Table 0.3: Transition rule for the boolean expression logical-or.

0.1.7 Variable Declaration

The transition rules for the variable declarations are on the form: $\langle D_V, env_V, sto \rangle \rightarrow_{DV} (env'_V, sto')$

$$\text{[VAR-DECL]} \quad \frac{\langle D_V, env''_V, sto[l \mapsto v] \rangle \rightarrow_{DV} (env'_V, sto')}{\text{var } x \leftarrow a; D_V, env_V, sto \rangle \rightarrow_{DV} (env'_V, sto')}$$

where $env_V, sto \vdash a \rightarrow_a v$
and $l = env_V \text{ next}$

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$$\text{and } env_V'' = env_V[x \mapsto l][\text{next} \mapsto \text{new } l]$$

Table 0.4: Transition rules for the variable declarations.

0.1.8 Procedure Declaration

The transition rules for the procedure declarations are on the form: $env_V \vdash \langle D_P, env_P \rangle \rightarrow_{DP} env'_P$

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$$[\text{PROC-DECL}] \quad \frac{env_V \vdash \langle D_P, env_P[p \mapsto (S, env_V, env_P)] \rangle \rightarrow_{DP} env'_P}{env_V \vdash \langle \text{proc } p \text{ is } S; D_P, env_P \rangle \rightarrow_{DP} env'_P}$$

Table 0.5: Transition rules for the procedure declarations.

0.1.9 Array Declaration

The transition rules for the variable declarations are on the form: ???

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$$[\text{MULT}] \quad \frac{env_V, sto \vdash a_1 \rightarrow_a v_1 \quad env_V, sto \vdash a_2 \rightarrow_a v_2}{env_V, sto \vdash a_1 \cdot a_2 \rightarrow_a v}$$

where $v = v_1 \cdot v_2$

Table 0.2: The transition rule for the arithmetic multiplication expression.