Machine Learning Exercise 2

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1 Getting Started with Ridge Regression (10 Points)

In the appendix you find starting-point implementations of basic linear regression for Python, C++, and Matlab. These include also the plotting of the data and model. Have a look at them, choose a language and understand the code in detail.

On the course webpage there are two simple data sets dataLinReg2D.txt and dataQuadReg2D.txt. Each line contains a data entry (x, y) with $x \in \mathbb{R}^2$ and $y \in \mathbb{R}$; the last entry in a line refers to y.

- a) The examples demonstrate plain linear regression for dataLinReg2D.txt. Extend them to include a regularization parameter λ . Report the squared error on the full data set when trained on the full data set. (3 P)
- b) Do the same for dataQuadReg2D.txt while first computing quadratic features. (4 P)
- c) Implement cross-validation (slide 02:17) to evaluate the *prediction error* of the quadratic model for a third, noisy data set dataQuadReg2D_noisy.txt. Report 1) the squared error when training on all data (=training error), and 2) the mean squared error $\hat{\ell}$ from cross-validation. (3 P)

Repeat this for different Ridge regularization parameters λ . (Ideally, generate a nice bar plot of the generalization error, including deviation, for various λ .)

Python (by Stefan Otte)

```
#!/usr/bin/env python
# encoding: utf-8
NOTE: the operators + - * / are element wise operation. If you want
matrix multiplication use dot or mdot!
from __future__ import print_function
import numpy as np
from numpy import dot
from numpy.linalg import inv
from numpy.linalg import multi_dot as mdot
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d.axes3d import Axes3D
# 3D plotting
# Helper functions
def prepend_one(X):
    """prepend a one vector to X."""
   return np.column_stack([np.ones(X.shape[0]), X])
def grid2d(start, end, num=50):
    ""Create an 2D array where each row is a 2D coordinate.
   np.meshgrid is pretty annoying!
   dom = np.linspace(start, end, num)
   X0, X1 = np.meshgrid(dom, dom)
   return np.column_stack([X0.flatten(), X1.flatten()])
```

```
# load the data
data = np.loadtxt("dataLinReg2D.txt")
print("data.shape:", data.shape)
# split into features and labels
X, y = data[:, :2], data[:, 2]
print("X.shape:", X.shape)
print("y.shape:", y.shape)
# 3D plotting
fig = plt.figure()
ax = fig.add_subplot(111, projection='3d') # the projection arg is important!
ax.scatter(X[:, 0], X[:, 1], y, color="red")
ax.set_title("raw data")
plt.draw()
# show, use plt.show() for blocking
# prep for linear reg.
X = prepend_one(X)
print("X.shape:", X.shape)
# Fit model/compute optimal parameters beta
beta_ = mdot([inv(dot(X.T, X)), X.T, y])
print("Optimal beta:", beta_)
# prep for prediction
X_grid = prepend_one(grid2d(-3, 3, num=30))
print("X_grid.shape:", X_grid.shape)
# Predict with trained model
y_grid = dot(X_grid, beta_)
print("Y_grid.shape", y_grid.shape)
# vis the result
fig = plt.figure()
ax = fig.add_subplot(111, projection='3d') # the projection part is important
{\tt ax.scatter(X\_grid[:, 1], X\_grid[:, 2], y\_grid) \# dont \ use \ the \ 1 \ infront}
ax.scatter(X[:, 1], X[:, 2], y, color="red") # also show the real data
ax.set_title("predicted data")
plt.show()
```

C++

(by Marc Toussaint)

```
//install https://github.com/MarcToussaint/rai in $HOME/git and compile 'make -C rai/Core'
//export LD_LIBRARY_PATH=$LD_LIBRARY_PATH:$HOME/git/rai/lib
//g++ -I$HOME/git/rai/rai -L$HOME/git/rai/lib -fPIC -std=c++0x main.cpp -lCore
#include <Core/array.h>
//========
                       -----
void gettingStarted() {
  //load the data
  arr D = FILE("dataLinReg2D.txt");
  //plot it
 FILE("z.1") <<D;</pre>
  gnuplot("splot 'z.1' us 1:2:3 w p", true);
  //decompose in input and output
  uint n = D.d0; //number of data points
  arr Y = D.sub(0,-1,-1,-1).reshape(n);
                                               //pick last column
  arr X = \text{catCol}(\text{ones}(n,1), D.\text{sub}(0,-1,0,-2)); //\text{prepend 1s to inputs}
  cout <<"X dim = " <<X.dim() <<endl;</pre>
  cout <<"Y dim = " <<Y.dim() <<endl;</pre>
  //compute optimal beta
  arr beta = inverse_SymPosDef(~X*X)*~X*Y;
  cout <<"optimal beta=" <<beta <<endl;</pre>
```

Matlab

(by Peter Englert)

```
clear;
% load the date
load('dataLinReg2D.txt');
% plot it
figure(1); clf; hold on;
plot3(dataLinReg2D(:,1),dataLinReg2D(:,2),dataLinReg2D(:,3),'r.');
% decompose in input X and output Y
n = size(dataLinReg2D,1);
X = dataLinReg2D(:,1:2);
Y = dataLinReg2D(:,3);
% prepend 1s to inputs
X = [ones(n,1),X];
beta = inv(X'*X)*X'*Y;
[a b] = meshgrid(-2:.1:2,-2:.1:2);
Xgrid = [ones(length(a(:)),1),a(:),b(:)];
Ygrid = Xgrid*beta;
Ygrid = reshape(Ygrid,size(a));
h = surface(a,b,Ygrid);
view(3);
grid on;
```