

Decision making and problem solving – Lecture 1

- Decision trees
- Elicitation of probabilities

Motivation

- ☐ You have just revised some key concepts of probability calculus
 - o Conditional probability
 - Law of total probability
 - o Bayes' rule

☐ This time:

- How to build a probability-based model to support decision-making under uncertainty?
- How to elicitate the probabilities needed for these models?

Why probabilities for modeling uncertainty?

- ☐ Decisions are often made under uncertainty
 - "How many train drivers should be trained, when future traffic is uncertain?"
 - "Should I buy an old or a new car, given that I only need an operational one and want to minimize costs = purchase price, maintenance & repair costs, selling price, etc.?"
 - "Should I buy my first my apartment now or postpone the decision, given that future interest rates, mortgage costs, personal income and apartment prices are uncertain?"
- □ Probability theory dominates the modeling of uncertainty in decision analysis
 - Well established rules for computations, understandable
 - Other models (e.g., evidence theory, fuzzy sets) exist, too

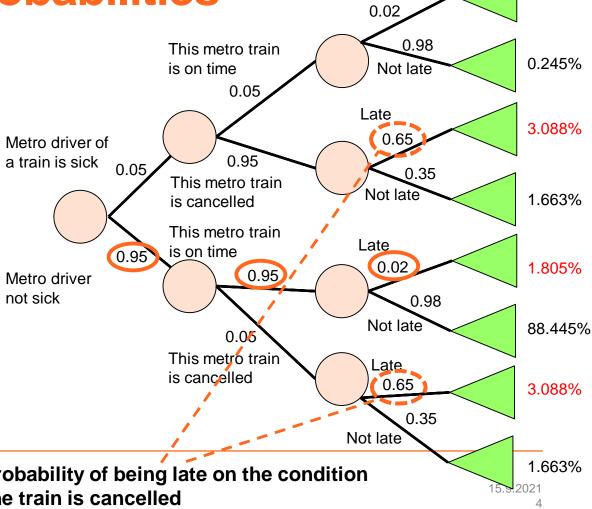


Conditional probabilities

- The probabilities of sequential, mutually exclusive and collectively exhaustive events can be represented in form of a tree
- The probability of a sequence of events is obtained my multiplying the probabilities on the path

 $0.95 \times 0.95 \times 0.02 = 1.805 \%$

The total probability of being late is 7.985 %



Passengers are

0.005%

late from ...

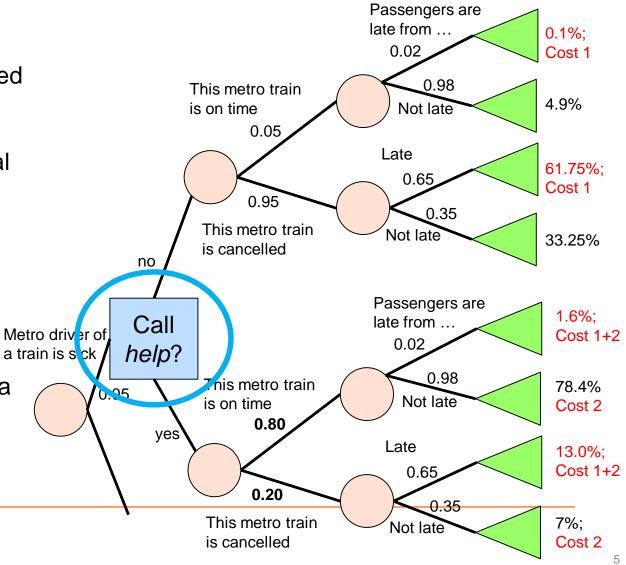


The probability of being late on the condition that the train is cancelled

What if...

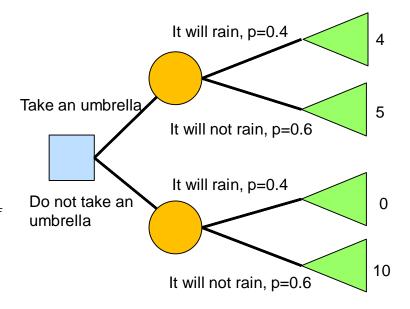
- We, the operator is interested in financial aspects and assume that being late results in unwanted financial consequences (Cost 1)?
 - numerical *outcomes* for states (consequences)
- We had a possibility to influence the probability p(this metro train is on time | metro driver of this a train is sek/ train is sick) by use of extra personnel (help) at a cost (Cost 2)?
 - Now the event probabilities depend on our decision





Decision trees

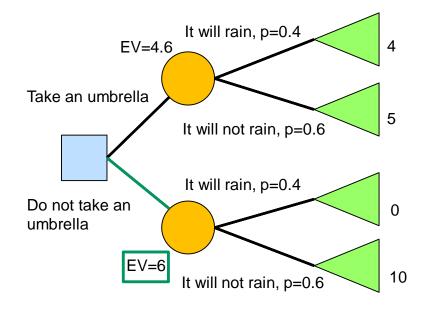
- Decision-making under uncertainty can be modeled by a decision tree
- ☐ Decision trees consist of
 - Decision nodes (squares) DM can choose which arc to follow
 - Chance nodes (circles; cf. states of nature) chance represented by probabilities dictates which arc will be followed (states of nature). The probabilities following a chance node must sum up to 1
 - Consequence nodes (triangles; resulting consequences) at the end of the tree; describe the consequence (e.g., profit, cost, revenue, utility) of following the path leading to this node
- Decisions and chance events are displayed in a logical temporal sequence from left to right
 - Only chance nodes whose results are known can precede a decision node
- Each chain of decisions and chance events represents a possible outcome





Solving a decision tree

- □ A decision tree is solved by starting from the leaves (consequence nodes) and going backward toward the root:
 - At each chance node: compute the expected value at the node
 - At each decision node: select the arc with the highest expected value
- ☐ The optimal strategy consists of the arcs selected at decision nodes

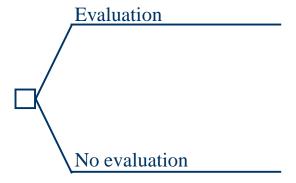


Example: Decision tree (1/12)

- Your uncle is going to buy a tractor. He has two alternatives:
 - 1. A new tractor (17 000 €)
 - 2. A used tractor (14 000 €)
- The engine of the old tractor may be defect, which is hard to ascertain. Your uncle estimates a 15 % probability for the defect.
- If the engine is defect, he has to buy a new tractor and gets 2000 € for the old one.
- Before buying the tractor, your uncle can take the old tractor to a garage for an evaluation, which costs 1 500 €.
 - If the engine is OK, the garage can confirm it without exception.
 - If the engine is defect, there is a 20 % chance that the garage does not notice it.
- Your uncle maximizes expected monetary value

Example: Decision tree (2/12)

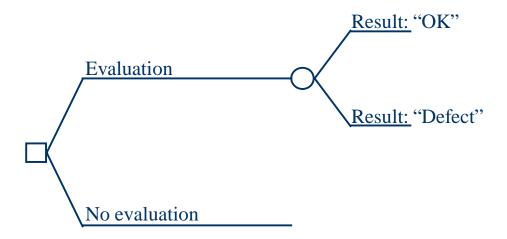
- Before making the buying decision and before you get to know the result of any uncertain event, you must <u>decide</u> upon taking the old tractor to a garage for an <u>evaluation</u>.
- The decision node 'evaluation' is placed leftmost in the tree





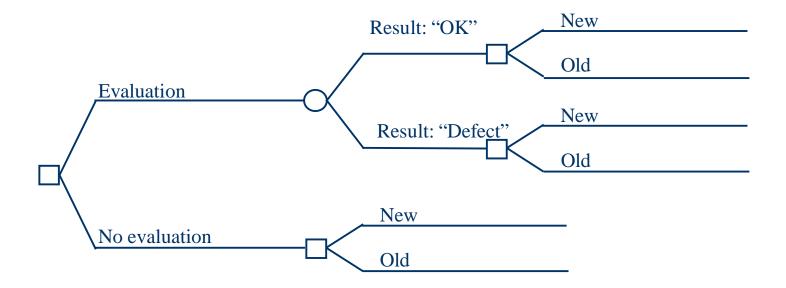
Example: Decision tree (3/12)

If the old tractor is evaluated, your uncle receives the <u>results of the evaluation</u>



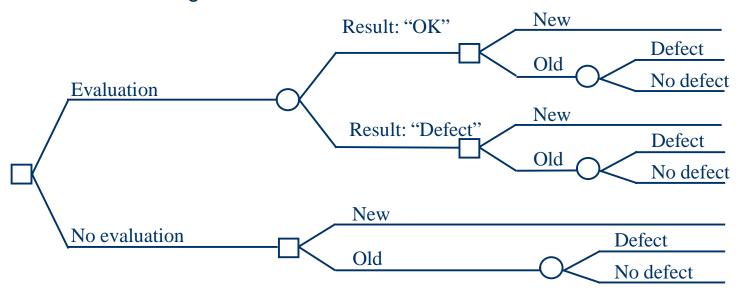
Example: Decision tree (4/12)

■ The next step is to **decide which tractor** to buy



Example: Decision tree (5/12)

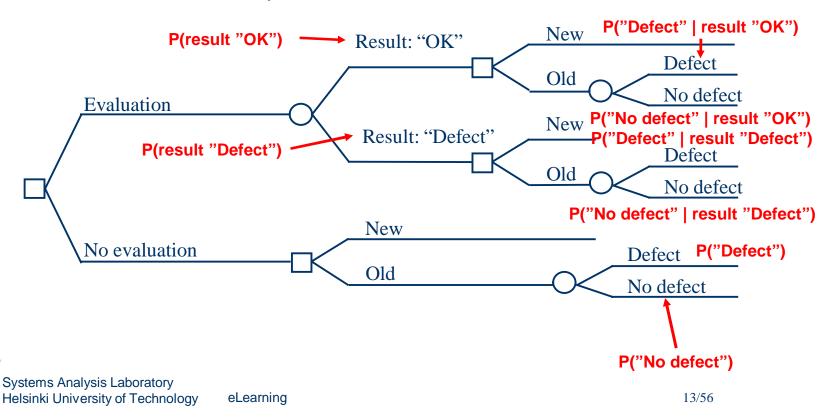
...But the engine of the old tractor can be defect



 Now all chance nodes and decisions are in chronological order such that in each node, we can follow the path to the left to find out what we know

Example: Decision tree (6/12)

We next need the probabilities for all outcomes of the chance nodes



Remember: Law of total probability

 \Box If $E_1,...,E_n$ are mutually exclusive and $A = \bigcup_i E_i$, then

$$P(A)=P(A|E_1)P(E_1)+...+P(A|E_n)P(E_n)$$

- ☐ Most frequent use of this law:
 - Probabilities P(A|B), $P(A|B^c)$, and P(B) are known
 - These can be used to compute $P(A)=P(A|B)P(B)+P(A|B^c)P(B^c)$

Remember: Bayes' rule

- \square Bayes' rule: $P(A|B) = \frac{P(B|A)P(A)}{P(B)}$
- ☐ Follows from
 - 1. The definition of conditional probability: $P(A|B) = \frac{P(A \cap B)}{P(B)}$, $P(B|A) = \frac{P(B \cap A)}{P(A)}$,
 - 2. Commutative laws: $P(B \cap A) = P(A \cap B)$.

Example: Bayes' rule

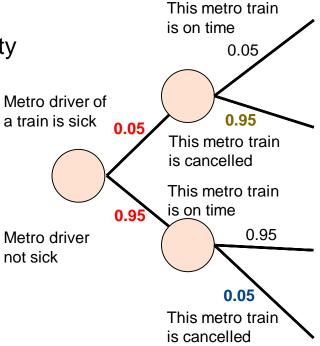
A metro train is cancelled (event C) and we have not had the opportunity to *call help*. What is the probability that the driver originally allocated to drive the train is sick (event S)? = What is P(S|C)?

Solution:

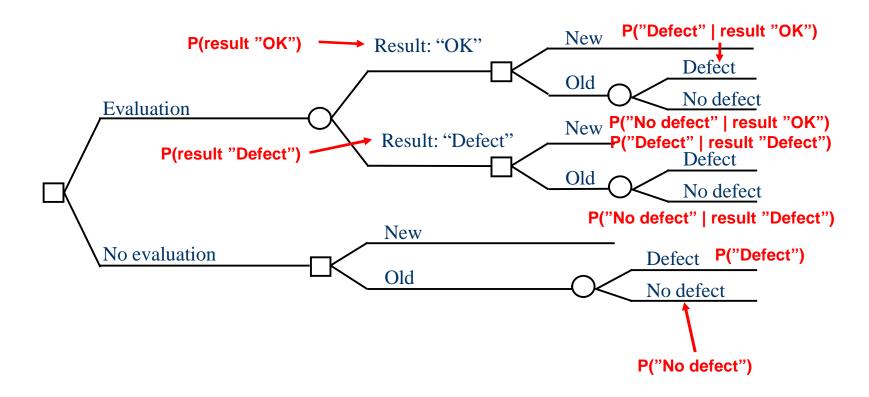
 \square P(S)=0.05, P(S^c)=0.95, P(C|S)=0.95, P(C|S^c)=0.05

Law of total probability: $P(C)=P(C|S)P(S)+P(C|S^c) P(S^c)=0.95 \times 0.05 + 0.05 \times 0.95 = 0.095$

Bayes' rule:
$$P(S|C) = \frac{P(C|S)P(S)}{P(C)} = \frac{0.95 \cdot 0.05}{0.095} = 50\%$$



Example: Decision tree (6/12)



Example: Decision tree (7/12)

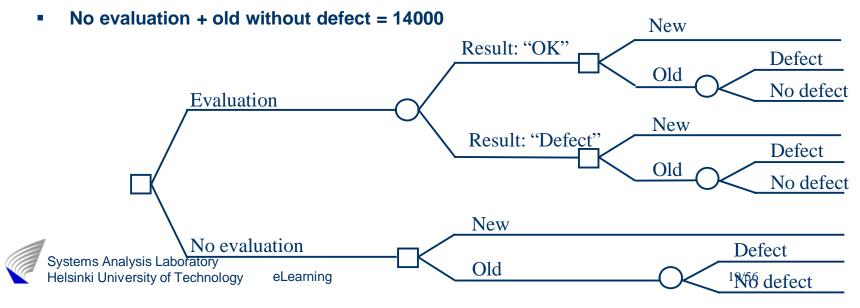
- Solve all probabilities. You know that
 - "Your uncle estimates a 15 % probability for the defect." => P(Defect)=0.15
 - "If the engine is OK, the garage can confirm it without exception." => P(result "OK" | No defect)=1
 - "If the engine is defect, there is a 20 % chance that the garage does not notice it." => P(result "OK" | Defect)=0.20

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P(\text{result "OK"}) = P(\text{result "OK"} | \text{No defect}) \cdot P(\text{No defect}) + P(\text{result "OK"} | \text{Defect}) \cdot P(\text{Defect})
= 1.0 \cdot 0.85 + 0.20 \cdot 0.15 = 0.88
P(\text{result "defect"}) = 1 - P(\text{result "OK"}) = 0.12
P(\text{Defect} | \text{result "OK"}) = \frac{P(\text{result "OK"} | \text{Defect}) \cdot P(\text{Defect})}{P(\text{result "OK"})} = \frac{0.20 \cdot 0.15}{0.88} \approx 0.034
P(\text{No defect} | \text{result "OK"}) = 1 - 0.034 = 0.966
P(\text{Defect} | \text{result "defect"}) = \frac{P(\text{result "defect"} | \text{Defect}) \cdot P(\text{Defect})}{P(\text{result "defect"})} = \frac{0.80 \cdot 0.15}{0.12} = 1.00
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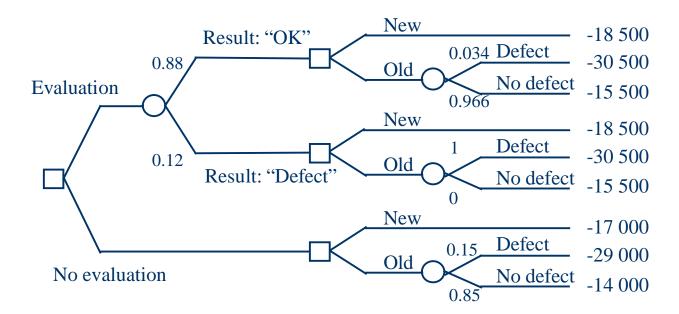
Example: Decision tree (8/12)

- Compute monetary values for each end node
 - Evaluation + new = 1500 + 17000 = 18500
 - Evaluation + old with defect = 1500 + 14000 2000 + 17000 = 30500
 - Evaluation + old without defect = 1500 + 14000 = 15500
 - No evaluation + new = 17000
 - No evaluation + old with defect = 14000 2000 + 17000 = 29000



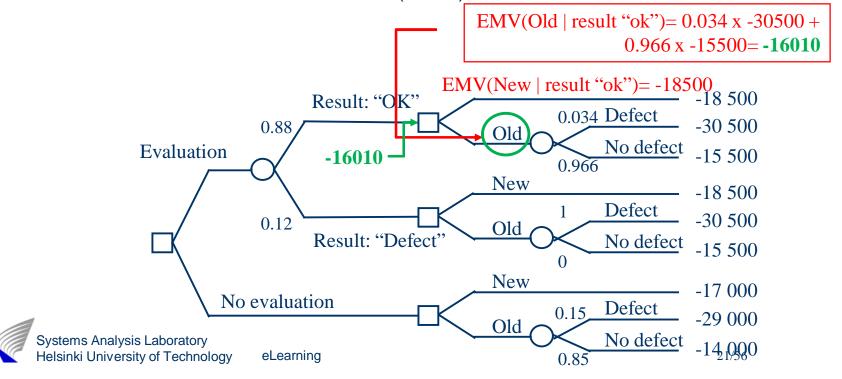
Example: Decision tree (9/12)

We now have a decision tree presentation of the problem



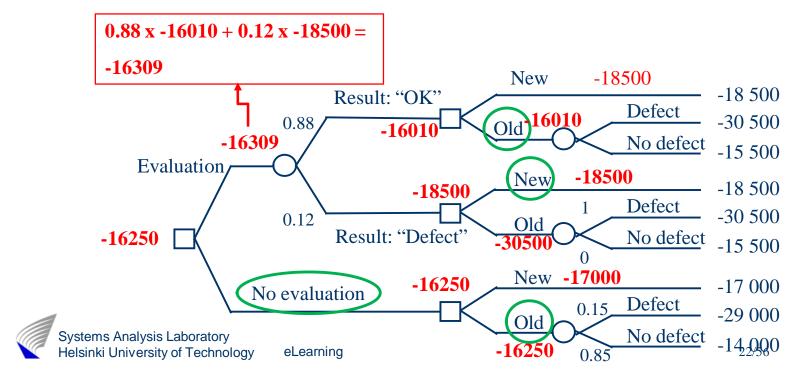
Example: Decision tree (10/12)

- Starting from the right, compute expected monetary values for each decision
- Place the value of the better (=best) decision to the decision node



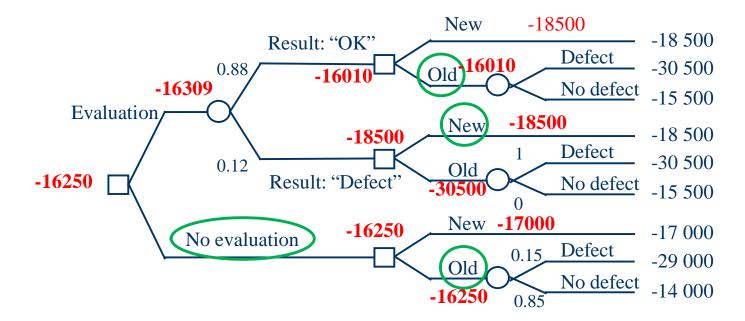
Example: Decision tree (11/12)

- Starting from the right, compute expected monetary values for each decision
- Place the value of the better decision to the decision node



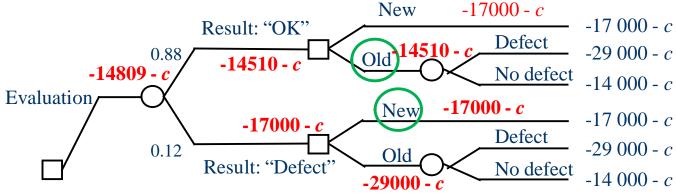
Example: Decision tree (12/12)

The optimal solution is to buy the old tractor without evaluating it



... How much should we pay for the sample information by the garage?

- ☐ The expected monetary value was higher without evaluating the old tractor
- ☐ Determine evaluation cost *c* so that you are <u>indifferent</u> between
 - 1. Not taking the old tractor for an evaluation (EMV = -16250€)
 - 2. Taking the old tractor for an evaluation



- □ Indifference, when EMVs equal: -16250 = -14809 $-c \Rightarrow c = 1441$ €
 - Expected value of sample information = Expected value with sample information = Expected value without sample information = -14809€ (-16250€) = 1441€



Expected value of perfect information

You are participating in a gambling game, where Mia has tossed a coin. Mia knows the result of the toss.

You can choose between *heads* or *tails*. If you choose correctly, Bernard will pay you 50€ Otherwise you pay Bernard 50€ You are maximizing EMV.

Mia suggests that you could offer her money and she'd tell you the correct choice. How much would you at most pay her?

https://presemo.aalto.fi/coin





Expected value of perfect information

You can choose between *heads* or *tails*. If you choose correctly, Bernard will pay you 50€ Otherwise you pay Bernard 50€ You are maximizing EMV.

EMV without perfect information = 0.5 x 50€+ 0.5 x (-50€) = 0€

Mia suggests that you could offer her money and she'd tell you the correct choice. How much should you at most pay her?

EMV with perfect information = 1 x 50 €+ 0 x (-50€) = 50€

You should pay at most 50€- 0€= 50 €

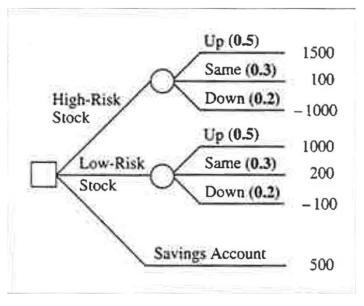


Example: expected value of <u>perfect</u> information

- You are considering between three investment alternatives: high-risk stock, lowrisk stock, and savings account
- Savings account: certain payoff of 500€
- ☐ Stocks:
 - 200€ brokerage fee
 - Payoffs depend on market conditions

	Up	Same	Down
High-risk	1700	300	-800
Low-risk	1200	400	100
Probability	0.5	0.3	0.1

Decision tree

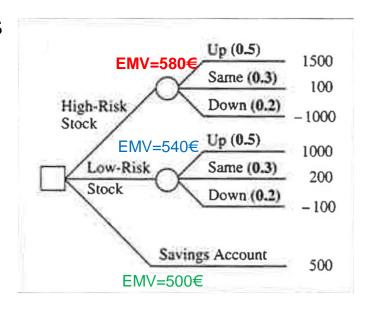


Source: Clemen, R.T. (1996): Making Hard Decisions: An Introduction to Decision Analysis, 2nd edition, Duxbury Press, Belmont.

Example: investing in the stock market

- ☐ The expected monetary values (EMVs) for the different alternatives are
 - HRS: 0.5·1500+0.3·100-0.2·1000=580
 - LRS: 0.5·1000+0.3·200-0.2·100=540
 - Savings Account: 500
- → It is optimal* to invest in high-risk stock

Decision tree



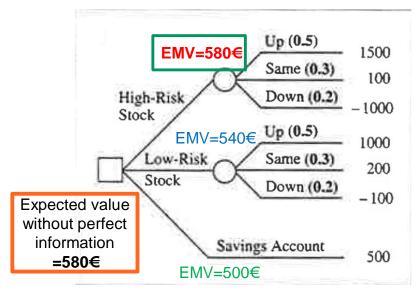
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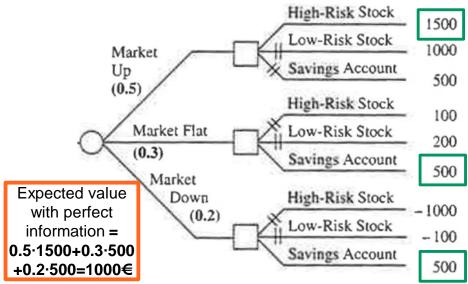
^{*} Assuming you are *risk-neutral* !!! – *risk* attitudes discussed later on this course

Expected value of perfect information

Decision tree



Reversed decision tree: you know the state of the world when making the decision(s)



Expected value of perfect information



= 1000€- 580€= 420€

Expected value of perfect information

- ☐ How much could the expected value be expected to increase, if
 - Additional information about the uncertainties was received before the decision
 - The decision would be made according to this information?
 - Note: this analysis is done <u>before</u> any information is obtained
- □ Perfect information: certain information about how the uncertainties are resolved – "if we could choose after we know the state of the world"
 - Expected value of perfect information = Expected value with perfect information Expected value without perfect information
- Expected value of perfect information is computed through a reversed decision tree in which <u>all chance nodes precede all</u> decision nodes



Probability assessment

- ☐ Go to the course's MyCourses site
 - □ https://mycourses.aalto.fi/course/view.php?id=29666
- ☐ Use a few minutes to answer
 - 9 probability assessment questions
 - Either questionnaire sheet A or B
 - To the Fractile assessment task
- Do not communicate with others
- ☐ Do not look up the answers on the internet



Question 2 should read (the text is too long for the MyCourses module)

Consider two bags X and Y. Bag X contains 30 white balls and 10 black balls, whereas bag Y contains 30 black balls and 10 white balls. Suppose that you select one of these bags at random, and randomly draw five balls one-by-one by replacing them in the bag after each draw. Suppose you get four white balls and one black. What is the probability that you selected bag X with mainly white balls?



Estimation of probabilities

- ☐ How to obtain the probabilities needed in decision models?
 - 1. If possible, use *objective* data
 - If objective data is not available, obtain subjective probability estimates from experts through
 - Betting approach
 - o Reference lottery
 - o Direct judgement

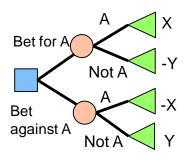
Estimation of probabilities: Betting approach

- ☐ Goal: to estimate the probability of event A
 - E.g., A="GDP growth is above 3% next year" or A="Sweden will join NATO within the next five years"

□ Betting approach:

- Bet for A: win X € if A happens, lose Y € if not
 - Expected monetary value $X \cdot P(A) Y \cdot [1 P(A)]$
- Bet against A: lose X € if A happens, win Y € if not
 - Expected monetary value $-X \cdot P(A) + Y \cdot [1 P(A)]$
- Adjust X and Y until the respondent is indifferent between betting for or against A
- Assuming risk-neutrality^(*), the expected monetary values of betting for or against A must be equal:

$$X \cdot P(A) - Y \cdot [1 - P(A)] = -X \cdot P(A) + Y \cdot [1 - P(A)] \Rightarrow P(A) = \frac{Y}{X + Y}$$



Estimation of probabilities: Reference lottery

Lottery

Ref.

lottery

Not A

- Lottery:
 - Win X if A happens
 - Win Y if A does not happen
 - X is preferred to Y
- ☐ Reference lottery:
 - Win X with (known) probability p
 - Win Y with (known) probability (1-p)
 - Probability p can be visualized with, e.g., a wheel of fortune
- ☐ Adjust *p* until the respondent is **indifferent** between the **two lotteries**:

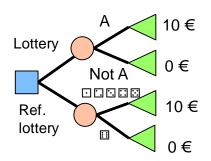
$$X \cdot P(A) + Y \cdot [1 - P(A)] = X \cdot p + Y \cdot [1 - p] \Rightarrow P(A) = p$$

Here, the respondent's risk attitude does not affect the results (shown later)



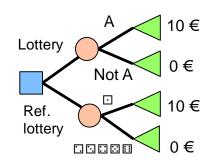
Reference lottery: example

☐ Event A: "HIFK wins Jokerit"



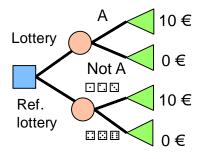
The respondent chooses the reference lottery:

$$10 \cdot P(A) < 10 \cdot \frac{5}{6}$$



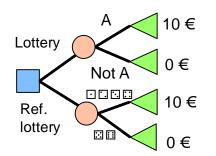
The respondent chooses the lottery:

$$10 \cdot P(A) > 10 \cdot \frac{1}{6}$$



Chooses the lottery:

$$P(A) > \frac{1}{2}$$



Chooses the reference lottery:

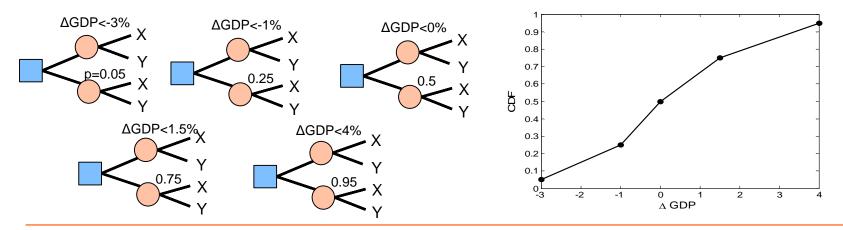
$$P(A)<\frac{2}{3}$$

These four answers revealed the probability estimate of A to be in (0.5, 0.67). Further questions should reveal the respondent's estimate for P(A)

15.9.2021

Estimation of continuous probability distributions

- □ A continuous distribution can be approximated by estimating several event probabilities (X is preferred to Y)
- ☐ Example:
 - Goal: to assess the distribution of the change in GDP (Δ GDP) in Finland next year
 - Means: elicitation of probability p for five different reference lotteries



Estimation of continuous probability distributions

- □ Often experts assess the descriptive statistics of the distribution directly, e.g.,
 - The feasible range (min, max)
 - Median f_{50} (i.e., P(X< f_{50})=0.5)
 - Other quantiles (e.g., 5%, 25%, 75%, 95%)

☐ In the previous example:

- "The 5% and 95% quantiles are $f_5 = -3\%$ and $f_{95} = 4\%$ "
- "The change in GDP is just as likely to be positive as it is to be negative"
- "There is a 25% chance that the change in GDP is below -1%"
- "There is a 25% chance that the change in GDP is above 1.5%"



Summary

- Decision trees are probability-based models to support decisionmaking under uncertainty
 - Which decision alternative should I choose?
 - How much would I be willing to pay for perfect information or (imperfect) sample information about how the uncertainties are resolved?

- ☐ Subjective probability assessments often required
 - Probability elicitation techniques require some effort



Next time

- Are 'experts' capable of giving good (probability) estimates?
 - What kind of elicitation biases should we be aware of?
- How to model the DM's preferences over risky alternatives?
 - What if the DM does not maximize expected monetary value, but has an attitude towards risk?
 - Would you
 - 1. choose 5000 € for sure OR
 - 2. participate in 50-50 lottery between 0 € and 12000 €?
 - What were the magic numbers in the umbrella example?

