# 

March 16, 2022

### Task 1

$$K_1(x,y) = (\langle x,y \rangle + c)^m \tag{1}$$

We know that the inner product  $\langle x, y \rangle$  is a kernel. By the binomial theorem we get

$$\sum_{k=0}^{m} \binom{m}{k} \langle x, y \rangle^{m-k} c^k \tag{2}$$

Since we know that

- 1. A conic combination of kernels is a kernel
- 2.  $c \geq 0$  and  $\binom{m}{k} \geq 0$
- 3. The product of a kernel is a kernel

We can see that the polynomial kernel is a conic combination of the inner product to a power and thus a kernel:

$$\sum_{k=0}^{m} {m \choose k} \langle x, y \rangle^{m-k} c^k \tag{3}$$

$$= \sum_{k=0}^{m} C\langle x, y \rangle^{m-k}, \qquad C = \binom{m}{k} c^{k}$$
(4)

Additionally the last term, then the exponent is 0, is a constant. Hence we can re-write the sum as a sum of kernal and a constant:

$$K_{sum}(x,y) = \langle \phi(x), \phi(y) \rangle + C_m, \qquad C_m = \binom{m}{m} c^m = c^m$$
 (5)

Hence  $K_1$  is a kernel.

### Task 2

$$h(x) = \operatorname{sgn}\left(\sum_{i=1}^{n} \alpha_i k(x, x_i) + b\right), \quad k(x, x_i) = \langle \phi(x), \phi(x_i) \rangle$$
 (6)

$$=sgn(||\phi(x) - c_{-}||^{2} - ||\phi(x) - c_{+}||^{2})$$
(7)

$$||\phi(x) - c_{-}||^{2} = \langle \phi(x) - c_{-}, \phi(x) - c_{-} \rangle$$
 (8)

$$= \langle \phi(x), \phi(x) \rangle - \langle \phi(x), c_{-} \rangle - \langle \phi(x), c_{-} \rangle + \langle c_{-}, c_{-} \rangle \tag{9}$$

$$||\phi(x) - c_{+}||^{2} = \langle \phi(x) - c_{+}, \phi(x) - c_{+} \rangle \tag{10}$$

$$= \langle \phi(x), \phi(x) \rangle - \langle \phi(x), c_{+} \rangle - \langle \phi(x), c_{+} \rangle + \langle c_{+}, c_{+} \rangle \tag{11}$$

$$||\phi(x) - c_{-}||^{2} - ||\phi(x) - c_{+}||^{2} = \langle \phi(x), \phi(x) \rangle - \langle \phi(x), c_{-} \rangle - \langle \phi(x), c_{-} \rangle + \langle c_{-}, c_{-} \rangle$$
(12)

$$-\langle \phi(x), \phi(x) \rangle + \langle \phi(x), c_{+} \rangle + \langle \phi(x), c_{+} \rangle - \langle c_{+}, c_{+} \rangle \tag{13}$$

$$= -2\langle \phi(x), c_{-} \rangle + \langle c_{-}, c_{-} \rangle + 2\langle \phi(x), c_{+} \rangle - \langle c_{+}, c_{+} \rangle \tag{14}$$

$$=2\langle \phi(x), c_{+}\rangle - 2\langle \phi(x), c_{-}\rangle + \langle c_{-}, c_{-}\rangle - \langle c_{+}, c_{+}\rangle \tag{15}$$

Since the sign-function is unaffected by a positive scalar multiplier we will divide the expression with 2.

The definition of  $c_{-}$  and  $c_{+}$  are

$$c_{-} = \frac{1}{m_{-}} \sum_{i \in I^{-}} \phi(x_{i}) \tag{16}$$

$$c_{+} = \frac{1}{m_{+}} \sum_{i \in I^{+}} \phi(x_{i}) \tag{17}$$

We can write the above inner products as

$$\langle \phi(x), c_{-} \rangle = \left\langle \phi(x), \frac{1}{m_{-}} \sum_{i \in I^{-}} \phi(x_{i}) \right\rangle$$
 (18)

$$= \frac{1}{m_{-}} \sum_{i \in I^{-}} \langle \phi(x), \phi(x_i) \rangle \tag{19}$$

$$= \frac{1}{m_{-}} \sum_{i \in I^{-}} k(x, x_{i}) \tag{20}$$

And similarly we get for the + side

$$\langle \phi(x), c_{+} \rangle = \frac{1}{m_{+}} \sum_{i \in I^{+}} k(x, x_{i}) \tag{21}$$

And for the two components containing only the centroids we get

$$\langle c_{-}, c_{-} \rangle = \left\langle \frac{1}{m_{-}} \sum_{i \in I^{-}} \phi(x_{i}), \frac{1}{m_{-}} \sum_{j \in I^{-}} \phi(x_{j}) \right\rangle$$
 (22)

$$= \frac{1}{m_{-}} \sum_{i \in I^{-}} \frac{1}{m_{-}} \sum_{j \in I^{-}} \langle \phi(x_{i}), \phi(x_{j}) \rangle$$
 (23)

$$= \frac{1}{m_{-}^{2}} \sum_{i \in I^{-}} \sum_{j \in I^{-}} k(x_{i}, x_{j})$$
 (24)

$$\langle c_+, c_+ \rangle = \frac{1}{m_+^2} \sum_{i \in I^+} \sum_{j \in I^+} k(x_i, x_j)$$
 (25)

$$b = \frac{1}{2} \langle c_{-}, c_{-} \rangle - \frac{1}{2} \langle c_{+}, c_{+} \rangle = \frac{1}{2m_{-}^{2}} \sum_{i \in I^{-}} \sum_{j \in I^{-}} k(x_{i}, x_{j}) - \frac{1}{2m_{+}^{2}} \sum_{i \in I^{+}} \sum_{j \in I^{+}} k(x_{i}, x_{j})$$
(26)

The remaining terms then become

$$\langle \phi(x), c_{+} \rangle - \langle \phi(x), c_{-} \rangle = \frac{1}{m_{+}} \sum_{i \in I^{+}} k(x, x_{i}) - \frac{1}{m_{-}} \sum_{i \in I^{-}} k(x, x_{i})$$
 (27)

From which we can see that if x is part of the positive cluster,  $\alpha_i$  has to be  $\frac{1}{m_+}$  and if part of the negative cluster  $-\frac{1}{m_-}$ . We can thus write Equation 15 as

$$\sum_{i=1}^{n} \alpha_i k(x, x_i) + b, \qquad \alpha_i = \begin{cases} \frac{1}{m_+}, & y = 1\\ -\frac{1}{m_-}, & y = -1 \end{cases}$$
 (28)

$$\implies h(x) = \operatorname{sgn}\left(\sum_{i=1}^{n} \alpha_i k(x, x_i) + b\right) \tag{29}$$

## Task 3

$$K_2(x,y) = \cos(x+y) \tag{30}$$

We prove that  $K_2$  is not a kernel by contradiction. Assume that  $K_2$  is a kernel, i.e. it has to be positive definite. This means that any point should fulfill the criteria that

$$\sum_{i=1}^{n} \sum_{j=1}^{n} \alpha_i \alpha_j k(x_i, x_j) \ge 0 \tag{31}$$

for all  $n \ge 1$ ,  $\alpha \in \mathcal{R}^n$ ,  $x \in \mathcal{X}^n$ . Let's take the example  $\alpha_i = \alpha_j = a \ne 0$  and  $x_i = x_j = 2\pi$  This gives us  $a^2 \cos(\frac{2\pi}{2}) = a^2 \cdot -1 = -a^2$ . Since a is real and non-zero  $-a^2 < 0$ , which mean that the function is not positive definite. I.e.  $\cos(x + y)$  is not a kernel!

### Task 4

$$K_3(x,y) = \frac{1}{1-xy}, \quad x,y \in (-1,1)$$
 (32)

Since  $|xy| < 1, \frac{1}{1-xy}$  can be written as the series expansion

$$\frac{1}{1 - xy} = 1 + xy + x^2y^2 + x^3y^3... (33)$$

Since products and conic sums of kernals are kernals and the sum of a kernel and a constant is a kernel as well can we conclude that  $K_3(x, y)$  is a kernel.

# Exercise 01

### Kernel Methods in Machine Learning (CS-E4830)

**Tasks:** 1. [Implement kernel matrix calculation](#task\_1) 1. [Linear kernel](#task\_1\_a) (\*\*1 Point\*\*) 2. [Gaussian kernel](#task\_1\_b) (\*\*2 Point\*\*) 2. [Implement the Parzen Window Classifier](#task\_2) (\*\*2 Point\*\*) 3. [Application of the Parzen Window Classifier](#task\_3) 1. [Implement the hyper parameter optimization](#task\_3\_a) (\*\*2 Point\*\*) 2. [Plot validation score for different hyper parameters] (#task\_3\_b)(\*\*1 Point\*\*)

Optional Tasks: 4. [Model visualization: Non-linear vs. Linear](#task\_4) (\*\*no points\*\*)

Version: 1.0

### Version history:

1.0: Initial version

Please add your student number and email address to the notebook into the corresponding cell.

EMAIL: christian.segercrantz@aalto.fi

STUDENT\_NUMBER: 481056

# Import required python packages

All tasks in this exercise can be solved by using only function and packages imported below. Please **do not** use any other imports.

### In [1]:

```
import numpy as np
import matplotlib.pyplot as plt
import matplotlib.colors as colors
plt.set_cmap("RdBu_r")

from sklearn.base import BaseEstimator, ClassifierMixin
from sklearn.datasets import make_blobs, make_moons
from sklearn.model_selection import KFold, ParameterGrid, BaseCrossValidator, train_tes
t_split
from sklearn.base import clone
```

<Figure size 432x288 with 0 Axes>

### 1. Kernel matrix calculation

Your task is to **implement two functions to calculate Linear- and Gaussian-kernel matrices** for two sets of feature vectors  $\mathbf{X}_A \in \mathbb{R}^{n_A \times d}$ ,  $\mathbf{X}_B \in \mathbb{R}^{n_B \times d}$ , where d is the dimension of the feature vectors, and  $n_a$  and  $n_B$  are the number of examples in set A respectively B.

### A. Linear kernel (1 Point)

**Task:** Implement missing code parts of the function calculation the linear kernel matrix given two feature vector matrices  $\mathbf{X}_A$  and  $\mathbf{X}_B$ . The resulting kernel matrix  $\mathbf{K}_{lin}$  must have dimension  $n_A \times n_B$ . For a single entry in the kernel matrix it must hold:

$$[\mathbf{K}_{lin}]_{ij} = \kappa_{lin}(\mathbf{x}_i, \mathbf{x}_j) = \langle \mathbf{x}_i, \mathbf{x}_j \rangle,$$

with  $\mathbf{x}_i, \mathbf{x}_j \in \mathbb{R}^d$  being two examples from set A respecively B.

### In [2]:

```
def linear_kernel(X_A, X_B=None):
    """
    Calculate Linear kernel matrix between two sets of feature-vectors, so that:
        k_ij = <x_i, x_j>
        :param X_A: array-like, shape=(n_samples_A, d), feature-matrix of set A
        :param X_B: array-like, shape=(n_samples_B, d), feature-matrix of set B or None, th
an Y = X
        :return: array-like, shape=(n_samples_A, n_samples_B), kernel matrix
        """
        if X_B is None:
            X_B = X_A
        K_AB = X_A @ X_B.T
        return K_AB
```

### In [3]:

```
X_A = np.array([[1], [2], [3], [4]])
X_B = np.array([[0], [2], [1]])
# Test size
np.testing.assert_equal(linear_kernel(X_A, X_B).shape, (4, 3))
np.testing.assert_equal(linear_kernel(X_A).shape, (4, 4))
# Test values
np.testing.assert_equal(linear_kernel(X_A)[0, 0], 1)
np.testing.assert_equal(linear_kernel(X_A)[1, 1], 4)
np.testing.assert_equal(linear_kernel(X_A)[0, 2], 3)
np.testing.assert_equal(linear_kernel(X_A)[2, 0], 3)
np.testing.assert_equal(linear_kernel(X_A, X_B)[0, 0], 0)
np.testing.assert_equal(linear_kernel(X_A, X_B)[0, 1], 2)
# Test performance
import time
time_tolerance = 1 # in seconds
size = 3000
t0 = time.time()
a = linear_kernel(np.random.rand(size), np.random.rand(size))
t1 = time.time()
total = t1 - t0
print('Time to run with size {} = {:.4f} seconds'.format(size, total))
assert total < time_tolerance, 'Time limit exceeded'</pre>
```

Time to run with size 3000 = 0.0009 seconds

### B. Gaussian kernel (1 Point)

**Task:** Implement missing code parts of the function calculation the Gaussian kernel matrix given two feature vector matrices  $\mathbf{X}_A$  and  $\mathbf{X}_B$ . The resulting kernel matrix  $\mathbf{K}_{gau}$  must have dimension  $n_A \times n_B$ . For a single entry in the kernel matrix it must hold:

$$[\mathbf{K}_{gau}]_{ij} = \kappa_{gau}(\mathbf{x}_i,\mathbf{x}_j) = \exp\!\left(-rac{\|\mathbf{x}_i - \mathbf{x}_j\|^2}{2\sigma^2}
ight)$$

with  $\mathbf{x}_i, \mathbf{x}_j \in \mathbb{R}^d$  being two examples from set A respectively B, and  $\gamma > 0$  being the bandwidth parameter.

### In [4]:

```
def gaussian_kernel(X_A, X_B=None, sigma=None):
    Calculate the Gaussian kernel matrix, so that
        k_{ij} = exp(-||x_i - x_j||^2 / (2 * sigma^2))
    :param X_A: array-like, shape=(n_samples_A, n_features), feature-matrix of set A
    :param X_B: array-like, shape=(n_samples_B, n_features), feature-matrix of set B or
None, than X_B = X_A
    :param sigma: scalar, bandwidth parameter
    :return: array-like, shape=(n_samples_A, n_samples_B), kernel matrix
    if X_B is None:
        X_B = X_A
    n_A = X_A.shape[0]
    n_B = X_B.shape[0]
    if sigma is None:
        sigma = np.sqrt(X_A.shape[1] / 2.0)
    X_A_n, X_A_m = X_A.shape
   X_B_n, Y_B_m = X_B.shape
   X_A_{sqrd} = np.power(X_A, 2) @ np.ones((X_A_m, X_B_n))
   X_B_{qrd} = np.ones((X_A_n, Y_B_m)) @ np.power(X_B, 2).T
   X_A_X_B = X_A @ X_B.T
    K_AB = np.exp(-(X_A\_sqrd + X_B\_sqrd - 2*X_A_X_B)/(2*sigma**2))
    #print("Res:\n", K_AB)
    return K_AB
```

### In [5]:

```
X_A = np.array([[1], [2], [3], [4]])
X_B = np.array([[0], [2], [1]])
# Test size
np.testing.assert_equal(gaussian_kernel(X_A, X_B).shape, (4, 3))
np.testing.assert_equal(gaussian_kernel(X_A).shape, (4, 4))
# Test values
np.testing.assert_equal(gaussian_kernel(X_A, sigma=1)[0, 0], 1)
np.testing.assert_equal(gaussian_kernel(X_A, sigma=1)[1, 1], 1)
np.testing.assert_equal(gaussian_kernel(X_A, sigma=1)[0, 2], np.exp(-2))
np.testing.assert_equal(gaussian_kernel(X_A, sigma=1)[2, 0], np.exp(-2))
np.testing.assert_equal(gaussian_kernel(X_A, X_B, sigma=1)[0, 0], np.exp(-0.5))
np.testing.assert_equal(gaussian_kernel(X_A, X_B, sigma=1)[0, 1], np.exp(-0.5))
# Test performance
import time
time_tolerance = 1 # in seconds
size = 3000
features = 10
t0 = time.time()
a = gaussian_kernel(np.random.rand(size, features), np.random.rand(size, features))
t1 = time.time()
total = t1 - t0
print('Time to run with size {} = {:.4f} seconds'.format(size, total))
assert total < time_tolerance, 'Time limit exceeded'</pre>
```

Time to run with size 3000 = 0.3487 seconds

# 2. Parzen Window Classifier implementation (2 Points)

The Parzen Window Classifier prediction model can be written as:

$$h(\mathbf{x}) = ext{sign}(g(\mathbf{x})) = ext{sign}\left(\sum_{i=1}^n lpha_i \kappa(\mathbf{x}_i, \mathbf{x}) + b
ight),$$

with:

- $g: \mathbb{R}^d o \mathbb{R}$  being the decision function
- $b \in \mathbb{R}$  being the **bias term** defined as:

$$b = rac{1}{2n_-^2} \sum_{i,j \in I^-} \kappa(\mathbf{x}_i,\mathbf{x}_j) - rac{1}{2n_+^2} \sum_{i,j \in I^+} \kappa(\mathbf{x}_i,\mathbf{x}_j),$$

•  $\alpha_i$ 's  $\in \mathbb{R}$  being the **dual variables** for all training examples  $\mathbf{x}_i$  defined as:

$$lpha_i = \left\{ egin{array}{ll} rac{1}{n_+} & ext{if } y_i = +1 \ -rac{1}{n_-} & ext{if } y_i = -1 \end{array} 
ight..$$

We denote the number of positive / negative training examples as  $n_+$  /  $n_-$ , and  $n=n_++n_-$ , and  $I^+$  /  $I^-$  are the indices of the positive / negative training examples.

Below you find the class-template for the Parzen Window Classifier. It's functionality is split into three parts:

### 1. Intialization of Classifier Object using init()

A Parzen Window Classifier instance can be created using its constructor and the kernel to be used can be specified, e.g.:

est = ParzenWindowClassifier(kernel="gaussian").

# 2. Model Training using fit()

This function takes as input the features of the training examples  $\mathbf{X}_{train}$  and their corresponding labels  $\mathbf{y}_{train} \in \{-1,1\}^{n_{train}}$  and estimates the  $\alpha_i$ 's and b. The necessary kernel values between the training examples, i.e.  $\kappa(\mathbf{x}_i,\mathbf{x}_j)$  are calculated during the fitting process.

# 3. Prediction for new Examples using predict() and decision\_function()

When the model parameters, i.e. b and  $\alpha_i$ s, are fitted, than we can make predictions for a new example  $\mathbf{x}$  using the function  $h(\mathbf{x})$ .

**Task:** Implement the missing code parts of fit(), decision\_function() and predict(). Make use of the provided formulas (see above).

**Hint:** The NumPy function np.sum can be used to sum over the elements of a matrix.

In [6]:

```
class ParzenWindowClassifier(BaseEstimator, ClassifierMixin):
         def __init__(self, kernel="gaussian", sigma=None):
                  Parzen Window Classifier
                  :param kernel: string, specifying which kernel to use. Can be 'gaussian' or 'li
near'.
                  :param sigma: scalar, gaussian kernel parameter, can be None if the linear kern
el is used.
                  # Parzen Window Classifier model parameter
                  self.b = None # bias term
                  self.alphas = None # dual variables
                  # Training data needed for the prediction phase
                  self.X_train = None
                 # Set up kernel function
                  self.kernel = kernel
                  self.sigma = sigma
         def fit(self, X_train, y_train):
                  Fit a Parzen Window Classifier using training data
                  :param X_train: array-like, shape=(n_samples, n_features), feature-matrix
                  :param y_train: array-like, shape=(n_samples,) or (n_samples, 1), label vector
                  # Calculate the specified kernel
                  self.X_train = X_train
                  KX_train = self._get_kernel(self.X_train)
                  # Get indices of positive and negative examples: I_n, I_p
                  I_n = [i for i, y in enumerate(y_train) if y == -1 ]
                  I_p = [i for i, y in enumerate(y_train) if y == 1 ]
                  # Count the number of postitive and negative examples: n_n, n_p
                  n n = len(I n)
                  n p = len(I p)
                  # Calcualte the bias term: self.b
                  self.b = 1/(2*n_n**2) * np.sum(KX_train[I_n][:, I_n]) - 1/(2*n_p**2) * np.sum(KX_train[I_n][:, I_n]) + 1/(2*n_p**2) * np.sum(KX_train[I_n][:, I_n][:, I_n]) + 1/(2*n_p**2) * np.sum(KX_train[I_n][:, I_n][:, I_n]
X_train[I_p][:, I_p])
                  # Calculate alpha i's: self.alpha
                  self.alphas = np.zeros((n_n + n_p, 1))
                  for i in I_n:
                           self.alphas[i] = -1/n n
                  for i in I p:
                           self.alphas[i] = 1/n p
         def decision_function(self, X):
                  Calculate decision function:
                           g(x) = sum_i a_i k(x_i, x) + b
                  :param X: array-like, shape=(n_samples_test, n_features), feature-matrix of new
```

```
data.
        :return: array-like, shape=(n\_samples\_test,), decision function value g(x) for
all new data points
        if self.alphas is None or self.b is None or self.X_train is None:
            raise RuntimeError("Call fit-function first.")
        # Calculate the specified kernel between the training and test examples
        KX_test_train = self._get_kernel(X, self.X_train)
        # Calculate the value of the decision function for each test example
        #print("alphas: ", self.alphas.shape)
        #print("Data: ", KX_test_train.shape)
        #print("b: ", self.b.shape)
        g_X = KX_test_train @ self.alphas + self.b
        return g_X.flatten() # output a one-dimensional vector
    def predict(self, X):
        Predict labels using Parzen Window Classifier:
            h(x) = sign(g(x)), with g(x) being the decision function
        :param X: array-like, shape=(n_samples_test, n_features), feature-matrix of new
data.
        :return: array-like, shape=(n_samples_test,), predicted labels {-1, 1} for all
new data points
        if self.alphas is None or self.b is None or self.X_train is None:
            raise RuntimeError("Call fit-function first.")
        # Calculate prediction h(x) = sign(g(x))
        h_X = np.sign(self.decision_function(X))
        return h X
   def _get_kernel(self, X, Y=None):
       Calcualte kernel matrix using specified kernel-function and parameters.
        :param X: array-like, shape=(n_samples_A, n_features), feature-matrix of set A
        :param Y: array-like, shape=(n samples B, n features), feature-matrix of set B
or None, than Y = X
        :return: array-like, shape=(n samples A, n samples B), kernel matrix
        if self.kernel == "gaussian":
            return gaussian_kernel(X, Y, self.sigma)
        elif self.kernel == "linear":
            return linear_kernel(X, Y)
        else:
            raise ValueError("Invalid kernel chosen.")
```

### In [7]:

```
X, y = make_blobs(n_samples=50, centers=[[1, 1], [1.5, 1.5]], cluster_std=[0.1, 0.1],
                  random state=80)
y[y==0] = -1
test_est = ParzenWindowClassifier(kernel="linear")
test_est.fit(X, y)
# Test correct shape of self.b and self.alphas
assert(np.isscalar(test est.b))
np.testing.assert_equal(test_est.alphas.shape, (50, 1))
# Test correct shape of the predictions
X_{\text{test}} = \text{np.array}([[1, 1], [1.5, 1.5], [1, 0], [2, 3]])
# Validate predictions
np.testing.assert_equal(test_est.decision_function(X_test).shape, (4,))
np.testing.assert_equal(test_est.predict(X_test).shape, (4,))
np.testing.assert_equal(test_est.predict(X_test), np.array([-1, 1, -1, 1]))
# Validate score
np.testing.assert_equal(test_est.score(X, y), 1.0)
```

# 3. Application of the Parzen Window Classifier

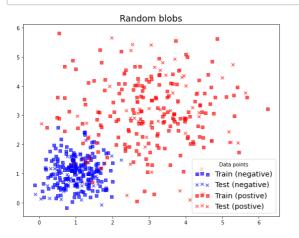
It is time to apply your Parzen Window Classifier to some datasets. For that you are given two synthetic datasets  $\mathbf{X}$ . Each is splitted into a training and test subset:  $\mathbf{X}_{train}$  (75%) and  $\mathbf{X}_{test}$  (25%).

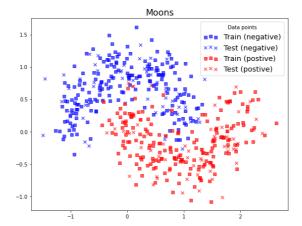
### In [8]:

We can plot the datasets to get an impression what we are dealing with:

### In [9]:

```
# Plot datasets
fig, axrr = plt.subplots(1, 2, figsize=(20, 7))
# BLobs
for l_str, l_num, col in [("negative", -1, "blue"), ("postive", 1, "red")]:
    axrr[0].scatter(
        X_blobs_train[y_blobs_train==l_num, 0], X_blobs_train[y_blobs_train==l_num, 1],
        c=col, alpha=0.65, label="Train (%s)" % l_str, marker="s")
    axrr[0].scatter(
        X_blobs_test[y_blobs_test==l_num, 0], X_blobs_test[y_blobs_test==l_num, 1],
        c=col, alpha=0.65, label="Test (%s)" % l_str, marker="x")
# BLobs
for l_str, l_num, col in [("negative", -1, "blue"), ("postive", 1, "red")]:
    axrr[1].scatter(
        X_moons_train[y_moons_train==l_num, 0], X_moons_train[y_moons_train==l_num, 1],
        c=col, alpha=0.65, label="Train (%s)" % l_str, marker="s")
    axrr[1].scatter(
        X_moons_test[y_moons_test==l_num, 0], X_moons_test[y_moons_test==l_num, 1],
        c=col, alpha=0.65, label="Test (%s)" % l_str, marker="x")
axrr[0].set_title("Random blobs", fontsize="xx-large")
axrr[0].legend(title="Data points", fontsize="x-large", scatterpoints=3)
axrr[1].set_title("Moons", fontsize="xx-large")
axrr[1].legend(title="Data points", fontsize="x-large", scatterpoints=3)
plt.show()
```





# A. Implement the hyper parameter optimization (1 point)

Train (fit) your Parzen Window Classifier with Gaussian kernel on the training examples, i.e.  $X_blobs_train$  and  $X_moons_train$ . To find the optimal Gaussian bandwidth parameter  $\sigma$  we search a grid of different parameter values and score each one using CV.

Task: Implement the missing code parts of the hyper\_parameter\_search\_using\_cv function.

The function gets in a set of training examples and a grid of different parameters, e.g.  $\sigma$ 's, calculates an average validation set score for all of them using cross-validation. Subsequently, a model using all the training data ist used, to train a model with the best set of parameters.

**Hints:** - Make use of the Python tutorial (fetch on JupyterHub), if you want to see the pseudo-code of the parameter search. - Read the documentation of the sklearn [ KFold function](https://scikit-learn.org/stable/modules/generated/sklearn.model\_selection.KFold.html#sklearn.model\_selection.KFold). - You can calculate the performance score using est.score(...) . Read also: https://scikit-learn.org/stable/modules/generated/sklearn.base.ClassifierMixin.html#sklearn.base.ClassifierMixin.score

### In [10]:

```
def hyper_parameter_search_using_cv(estimator, X, y, param_grid, n_cv_folds=5,
                                    random state=None):
    Function calculating the estimator score for a grid of hyper parameters.
    :param estimator: object, subclass of RegressorMixin or ClassifierMixin and BaseEst
imator
    :param X: array-like, shape=(n_samples, n_features), feature-matrix used for traini
ng
    :param y: array-like, shape=(n_samples,) or (n_samples, 1), label vector used for t
raining
    :param param_grid: dictionary,
        keys: different parameter names
        values: grid-values for each parameter
    :param n_cv_folds: scalar, a KFold cross-validation is performed where the number o
f splits is equal the scalar.
    :param random_state: scalar, RandomState instance or None, optional, default=None
        If int, random_state is the seed used by the random number generator;
        If RandomState instance, random_state is the random number generator;
        If None, the random number generator is the RandomState instance used
        by `np.random`.
    :return: tuple = (
            best estimator,
            param grid as list and corresponding evaluation scores,
            score of best parameter
            best parameter
    # Get an iterator over all parameters
    param_grid_iter = ParameterGrid(param_grid)
    # Create cross-validation object
    cv = KFold(n_splits=n_cv_folds, shuffle=True, random_state=random_state)
    # Store the valdidation set performance scores for all folds and parameters
    perf_scores = np.zeros((cv.get_n_splits(), len(param_grid_iter)))
    for fold, (train set, val set) in enumerate(cv.split(X, y)):
        # Separate training and validation set from X and y,
        # i.e. X_train, X_val, y_train and y_val
        X_train = X[train_set]
        X \text{ val} = X[\text{val set}]
        y train = y[train set]
        y val = y[val set]
        for idx, param in enumerate(param_grid_iter):
            # Clone the estimator object to get an un-initialized object
            est = clone(estimator)
            # Set model parameters
            est.set_params(**param)
            # Fit the model using training set
            est.fit(X_train, y_train)
            # Calculate the perf. score on validation set for current fold and paramete
```

### In [11]:

# B. Plot validation score for different hyper parameters

With the hyper parameter optimization function at hand, we find the best  $\sigma$  parameter for the two synthetic datasets and also inspect the average validation error for different values of  $\sigma$ .

First let us the parameter grid for the Gaussian kernel bandwidth parameter  $\sigma$ :

```
In [12]:
```

```
param_grid = {"sigma": [0.01, 0.05, 0.1, 0.5, 1, 5, 10, 50]}
```

Now we run the hyper parameter search using cv function for X blobs train and X blobs test:

### In [13]:

```
est_blobs, scores_blobs, best_score_blobs, best_param_blobs = hyper_parameter_search_us
ing_cv(
    ParzenWindowClassifier(kernel="gaussian"), X_blobs_train, y_blobs_train, param_grid
,
    random_state=737)

print("[Blobs] Best average validation score", best_score_blobs)
print("[Blobs] Best parameter", best_param_blobs)

est_moons, scores_moons, best_score_moons, best_param_moons = hyper_parameter_search_us
ing_cv(
    ParzenWindowClassifier(kernel="gaussian"), X_moons_train, y_moons_train, param_grid
,
    random_state=747)

print("[Moons] Best average validation score", best_score_moons)
print("[Moons] Best average validation score", best_score_moons)

[Blobs] Best average validation score 0.968
[Blobs] Best parameter {'sigma': 1}
```

Plot validation score for the different parameter values.

[Moons] Best average validation score 0.944

[Moons] Best parameter {'sigma': 0.1}

**Hint:** Both curves should have a single maxima, if you did not change any random seeds, i.e.  $random\_state$  values, or data generation parameters. Otherwise, it could be that multiple  $\sigma$ 's are equally good. However, overall it should be a function with single maxima (maybe a region).

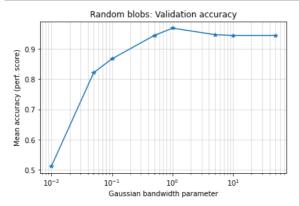
### In [14]:

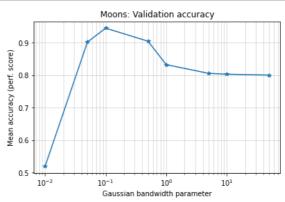
```
fig, axrr = plt.subplots(1, 2, figsize=(14, 4), sharex="row")

axrr[0].plot(param_grid["sigma"], scores_blobs["scores"], '*-')
axrr[0].set_xscale("log")
axrr[0].grid(True, which="both", ls="-", alpha=0.5)
axrr[0].set_title("Random blobs: Validation accuracy")
axrr[0].set_xlabel("Gaussian bandwidth parameter")
axrr[0].set_ylabel("Mean accuracy (perf. score)")

axrr[1].plot(param_grid["sigma"], scores_moons["scores"], '*-')
axrr[1].set_xscale("log")
axrr[1].grid(True, which="both", ls="-", alpha=0.5)
axrr[1].set_title("Moons: Validation accuracy")
axrr[1].set_xlabel("Gaussian bandwidth parameter")
axrr[1].set_ylabel("Mean accuracy (perf. score)")

plt.show()
```





The hyper-parameter optimization was done only using the training data. We now can apply the best model (with the optimal  $\sigma$  parameter) to the training data. We should see a similar performance as for the validation set:

### In [15]:

```
print("[Blobs] Score on test set", est_blobs.score(X_blobs_test, y_blobs_test))
print("[Moons] Score on test set", est_moons.score(X_moons_test, y_moons_test))
```

```
[Blobs] Score on test set 0.936
[Moons] Score on test set 0.912
```

# 4. Model visualization: Non-linear vs. Linear (no points)

**Bonus task:** Here we inspect the decision function and how it separates the two classes in the feature space. For that we will evaluate  $g(\mathbf{x})$  for  $\mathbf{x}$ 's on a regular grid. 1. Set up interval to plot decision function, e.g. min. and max. value of our synthetic datasets. 2. Create grid-points  $\mathbf{x}$  covering the intervall. 3. Evaluate  $z=g(\mathbf{x})$  for all points. 4. Plot the z's for different points and color them according to their sign.

### In [16]:

# **Decision Function for Gaussian Kernel (Model of previous tasks)**

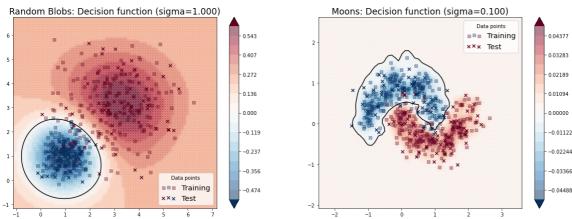
### In [17]:

```
XX_blobs_grid, YY_blobs_grid = get_gridpoints(X_blobs)
Z_blobs_grid = est_blobs.decision_function(np.c_[XX_blobs_grid.ravel(), YY_blobs_grid.ravel()])
Z_blobs_grid = Z_blobs_grid.reshape(XX_blobs_grid.shape)

XX_moons_grid, YY_moons_grid = get_gridpoints(X_moons)
Z_moons_grid = est_moons.decision_function(np.c_[XX_moons_grid.ravel(), YY_moons_grid.ravel()])
Z_moons_grid = Z_moons_grid.reshape(XX_moons_grid.shape)
```

### In [18]:

```
fig, axrr = plt.subplots(1, 2, figsize=(20, 7))
# plot contours, levels, ...
pcm = axrr[0].pcolormesh(XX blobs grid, YY blobs grid, Z blobs grid, alpha=0.5, shading
="gouraud",
                   norm=get_color_normalizer(Z_blobs_grid))
fig.colorbar(pcm, ax=axrr[0], extend="both", orientation="vertical")
axrr[0].contour(XX_blobs_grid, YY_blobs_grid, Z_blobs_grid, colors=['k'], linestyles=[
'-'], levels=[0])
# plot points
axrr[0].scatter(X_blobs_train[:, 0], X_blobs_train[:, 1], c=y_blobs_train, marker="s",
alpha=0.35)
axrr[0].scatter(X_blobs_test[:, 0], X_blobs_test[:, 1], c=y_blobs_test, marker="x")
# plot labels, titles, ...
axrr[0].legend(["Training", "Test"], title="Data points", fontsize="x-large", scatterpo
axrr[0].set_title("Random Blobs: Decision function (sigma=%.3f)" % best_param_blobs["si
gma"],
                 fontsize="xx-large")
pcm = axrr[1].pcolormesh(XX_moons_grid, YY_moons_grid, Z_moons_grid, alpha=0.5, shading
="gouraud",
                   norm=get_color_normalizer(Z_moons_grid))
fig.colorbar(pcm, ax=axrr[1], extend="both", orientation="vertical")
axrr[1].scatter(X_moons_train[:, 0], X_moons_train[:, 1], c=y_moons_train, marker="s",
axrr[1].scatter(X moons test[:, 0], X moons test[:, 1], c=y moons test, marker="x")
axrr[1].legend(["Training", "Test"], title="Data points", fontsize="x-large", scatterpo
ints=3)
axrr[1].set_title("Moons: Decision function (sigma=%.3f)" % best_param_moons["sigma"],
                 fontsize="xx-large")
axrr[1].contour(XX moons grid, YY moons grid, Z moons grid, colors=['k'], linestyles=[
'-'], levels=[0])
plt.show()
```



### **Decision Function for Linear Kernel**

We have seen that the Gaussian kernel leads to a non-linear decision boundary, i.e.  $g(\mathbf{x}) = 0$  (black line in plots). Now we take a look on the linear Parzen Window Classifier, buy using a linear kernel.

### In [19]:

```
est_blobs = ParzenWindowClassifier(kernel="linear")
est_blobs.fit(X_blobs_train, y_blobs_train)

est_moons = ParzenWindowClassifier(kernel="linear")
est_moons.fit(X_moons_train, y_moons_train)
```

### In [20]:

```
XX_blobs_grid, YY_blobs_grid = get_gridpoints(X_blobs)
Z_blobs_grid = est_blobs.decision_function(np.c_[XX_blobs_grid.ravel(), YY_blobs_grid.ravel()])
Z_blobs_grid = Z_blobs_grid.reshape(XX_blobs_grid.shape)

XX_moons_grid, YY_moons_grid = get_gridpoints(X_moons)
Z_moons_grid = est_moons.decision_function(np.c_[XX_moons_grid.ravel(), YY_moons_grid.ravel()])
Z_moons_grid = Z_moons_grid.reshape(XX_moons_grid.shape)
```

### In [21]:

```
fig, axrr = plt.subplots(1, 2, figsize=(20, 7))
# plot contours, levels, ...
pcm = axrr[0].pcolormesh(XX blobs grid, YY blobs grid, Z blobs grid, alpha=0.5, shading
="gouraud",
                   norm=get_color_normalizer(Z_blobs_grid))
fig.colorbar(pcm, ax=axrr[0], extend="both", orientation="vertical")
axrr[0].contour(XX_blobs_grid, YY_blobs_grid, Z_blobs_grid, colors=['k'], linestyles=[
'-'], levels=[0])
# plot points
axrr[0].scatter(X_blobs_train[:, 0], X_blobs_train[:, 1], c=y_blobs_train, marker="s",
alpha=0.35)
axrr[0].scatter(X_blobs_test[:, 0], X_blobs_test[:, 1], c=y_blobs_test, marker="x")
# plot labels, titles, ...
axrr[0].legend(["Training", "Test"], title="Data points", fontsize="x-large", scatterpo
axrr[0].set title("Random Blobs: Decision function (linear kernel)", fontsize="xx-larg
e")
pcm = axrr[1].pcolormesh(XX_moons_grid, YY_moons_grid, Z_moons_grid, alpha=0.5, shading
="gouraud",
                   norm=get_color_normalizer(Z_moons_grid))
fig.colorbar(pcm, ax=axrr[1], extend="both", orientation="vertical")
axrr[1].scatter(X_moons_train[:, 0], X_moons_train[:, 1], c=y_moons_train, marker="s",
alpha=0.35)
axrr[1].scatter(X_moons_test[:, 0], X_moons_test[:, 1], c=y_moons_test, marker="x")
axrr[1].legend(["Training", "Test"], title="Data points", fontsize="x-large", scatterpo
ints=3)
axrr[1].set_title("Moons: Decision function (linear kernel)", fontsize="xx-large")
axrr[1].contour(XX_moons_grid, YY_moons_grid, Z_moons_grid, colors=['k'], linestyles=[
'-'], levels=[0])
plt.show()
```

