MATH 1336: Calculus III

Section 2.4: Cross Product

Cross Product Definition:

The **cross product** of two vectors, $\vec{a} = \langle \overline{a_1, a_2, a_3} \rangle$, $\vec{b} = \langle b_1, b_2, b_3 \rangle$ results in a vector that is orthogonal to both \vec{a} and \vec{b} .

$$\vec{a} \times \vec{b} = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix} = \begin{vmatrix} a_2 & a_3 \\ b_2 & b_3 \end{vmatrix} \hat{\mathbf{i}} - \begin{vmatrix} a_1 & a_3 \\ b_1 & b_3 \end{vmatrix} \hat{\mathbf{j}} + \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix} \hat{\mathbf{k}} = (a_2b_3 - a_3b_2)\hat{\mathbf{i}} - (a_1b_3 - a_3b_1)\hat{\mathbf{j}} + (a_1b_2 - a_2b_1)\hat{\mathbf{k}}$$

The direction of the vector $\vec{a} \times \vec{b}$ is determined using the **right hand rule**, and it's magnitude is given by $||\vec{a} \times \vec{b}|| = ||\vec{a}|| \ ||\vec{b}|| \sin \theta$, where θ is the angle between \vec{a} and \vec{b} .

Right Hand Rule:



Figure 1: Figure used to demonstrate the right hand rule.

To determine the direction of $\vec{a} \times \vec{b}$, point the fingers of your *right hand* in the direction of \vec{a} , then curl them toward \vec{b} . Your thumb will then point in the direction of $\vec{a} \times \vec{b}$!

Note that order matters! (See property 1 on the next page.)

Example 1:

Find $\vec{a} \times \vec{b}$ and verify that it is perpendicular to \vec{a} and \vec{b} .

$$\vec{a} = \langle 1, 2, 3 \rangle, \qquad \vec{b} = \langle 4, 5, 6 \rangle$$

$$\vec{a} \times \vec{b} = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ 1 & 2 & 3 \\ 4 & 5 & 6 \end{vmatrix} = \begin{vmatrix} 2 & 3 \\ 5 & 6 \end{vmatrix} \hat{\mathbf{i}} - \begin{vmatrix} 1 & 3 \\ 4 & 6 \end{vmatrix} \hat{\mathbf{j}} + \begin{vmatrix} 1 & 2 \\ 4 & 5 \end{vmatrix} \hat{\mathbf{k}} = [(2)(6) - (3)(5)] \hat{\mathbf{i}} - [(1)(6) - (3)(4)] \hat{\mathbf{j}} + [(1)(5) - (2)(4)] \hat{\mathbf{k}}$$

$$\vec{a} \times \vec{b} = (12 - 15)\hat{\mathbf{i}} - (6 - 12)\hat{\mathbf{j}} + (5 - 8)\hat{\mathbf{k}} = \langle -3, 6, -3 \rangle$$

To verify that the result is perpendicular to both \vec{a} and \vec{b} , use the dot product!

$$\left(\vec{\boldsymbol{a}}\times\vec{\boldsymbol{b}}\right)\cdot\vec{\boldsymbol{a}}=\langle -3,6,-3\rangle\cdot\langle 1,2,3\rangle=-3+12-9=0$$

$$\left(\vec{\boldsymbol{a}}\times\vec{\boldsymbol{b}}\right)\cdot\vec{\boldsymbol{b}} = \langle -3,6,-3\rangle\cdot\langle 4,5,6\rangle = -12+30-18=0$$

Algebraic Properties of the Cross Product:

 $\vec{a}, \vec{b}, \vec{c}$ are all vectors in either \mathbb{R}^2 or \mathbb{R}^3 , and s is a scalar

1.
$$\vec{a} \times \vec{b} = -\vec{b} \times \vec{a}$$

2.
$$(s\vec{a}) \times \vec{b} = s(\vec{a} \times \vec{b}) = \vec{a} \times (s\vec{b})$$

3.
$$\vec{a} \times (\vec{b} + \vec{c}) = \vec{a} \times \vec{b} + \vec{a} \times \vec{c}$$

4.
$$(\vec{a} + \vec{b}) \times \vec{c} = \vec{a} \times \vec{c} + \vec{b} \times \vec{c}$$

5.
$$\vec{a} \cdot (\vec{b} \times \vec{c}) = (\vec{a} \times \vec{b}) \cdot \vec{c}$$

6.
$$\vec{a} \times (\vec{b} \times \vec{c}) = (\vec{a} \cdot \vec{c}) \vec{b} - (\vec{a} \cdot \vec{b}) \vec{c}$$

Geometric Properties of the Cross Product:

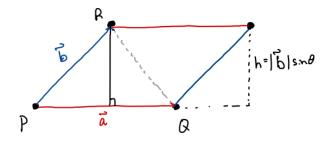


Figure 2: Diagram illustrating the area of a parallelogram determined by vectors a and b.

The area of the parallelogram determined by \vec{a} and \vec{b} is given by

$$A_{\mathsf{parallelogram}} = ||\vec{\boldsymbol{a}} \times \vec{\boldsymbol{b}}|| = ||\vec{\boldsymbol{a}}|| \; ||\vec{\boldsymbol{b}}|| \sin \theta$$

The area of the triangle PQR is half of the area of the parallelogram:

$$A_{\rm triangle} = \frac{1}{2} ||\vec{\boldsymbol{a}} \times \vec{\boldsymbol{b}}||$$

These areas would be zero if the vectors were parallel:

Vectors \vec{a} and \vec{b} are parallel if-and-only-if $\vec{a} \times \vec{b} = \vec{0}$.



Figure 3: Diagram illustrating applied torque using a ratchet on a bolt under Dr. Cole's desk.

Torque:

The **torque**, $\vec{\tau}$, from applying a force \vec{F} to a rigid body at a point given by position vector \vec{r} is calculated using:

$$ec{m{ au}} = ec{m{r}} imes ec{m{F}}$$
 $||ec{m{ au}}|| = ||ec{m{r}}|| \; ||ec{m{F}}|| \sin heta$

 $||\vec{\tau}|| = (\text{length of wrench}) * (\text{component of force perpendicular to wrench})$

"righty-tighty, lefty-loosy" rule ⇔ right hand rule for cross products!

Vector Problems for Group Work:

Problem 1: Evaluate the following cross products. Do the results agree with your intuition?

- a) $\hat{\mathbf{i}} \times \hat{\mathbf{j}}$
- b) $\hat{\mathbf{i}} \times \hat{\mathbf{k}}$
- c) $\langle 1, 1, 0 \rangle \times \langle -1, 1, 0 \rangle$

Problem 2: Compute the area of the triangle determined by $\vec{a} = \langle 1, -2, 6 \rangle$ and $\vec{b} = \langle 4, 3, -1 \rangle$.

Problem 3: Let $\vec{a} = s\vec{b} + t\vec{c}$, where s and t are scalars. Show that $\vec{a} \cdot (\vec{b} \times \vec{c}) = 0$.

Problem 4: Vector, Scalar, or Nonsense?

Some of the expressions below are meaningful, and some are not. Determine which expressions make sense, and if the result is a scalar or a vector:

- a) $\vec{a} \cdot (\vec{b} \times \vec{c})$
- b) $ec{m{a}} imes(ec{m{b}}\cdotec{m{c}})$
- c) $ec{m{a}} imes(ec{m{b}} imesec{m{c}})$
- d) $\vec{a} \cdot (\vec{b} \cdot \vec{c})$
- e) $(\vec{a} \cdot \vec{b}) imes (\vec{c} \cdot \vec{d})$
- f) $(\vec{a} \times \vec{b}) \cdot (\vec{c} \times \vec{d})$

Problem 5: (Fun Geometry Challenge!)

Use vector methods to show that any angle inscribed on a semicircle is a right angle.

(-r,0) (0,0) (r,0)

Figure 4: Diagram for Problem 5.