1

i
$$\vec{u} = x\hat{\mathbf{i}} + y\hat{\mathbf{j}} + z\hat{\mathbf{k}}$$

Ser først på divergensen

$$\nabla \cdot \vec{u} = \frac{\partial}{\partial x} x + \frac{\partial}{\partial y} y + \frac{\partial}{\partial z} z$$
$$\nabla \cdot \vec{u} = 1 + 1 + 1$$
$$\nabla \cdot \vec{u} = 3$$

Ser så på virvlingen

$$\nabla \times \vec{u} = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x & y & z \end{vmatrix}$$

$$\nabla \times \vec{u} = \left(\frac{\partial}{\partial y} z - \frac{\partial}{\partial z} y \right) \hat{\mathbf{i}} + \left(\frac{\partial}{\partial z} x - \frac{\partial}{\partial x} z \right) \hat{\mathbf{j}} + \left(\frac{\partial}{\partial x} y - \frac{\partial}{\partial y} x \right) \hat{\mathbf{k}}$$

$$\nabla \times \vec{u} = \vec{0}$$

i
i $\vec{u}=r\cos(\theta)\hat{\bf i}_r+r\sin(\theta)\hat{\bf i}_\theta+z\hat{\bf k}$ Ser først på divergensen

$$\begin{split} \nabla \cdot \vec{u} &= \frac{1}{r} \left(\frac{\partial}{\partial r} \left(r \left(r \cos(\theta) \right) \right) + \frac{\partial}{\partial \theta} \left(r \sin(\theta) \right) \right) + \frac{\partial}{\partial z} z \\ \nabla \cdot \vec{u} &= \frac{1}{r} \left(\cos(\theta) \frac{\partial}{\partial r} r^2 + r \frac{\partial}{\partial \theta} \sin(\theta) \right) + 1 \\ \nabla \cdot \vec{u} &= \frac{1}{r} \left(2r \cos(\theta) + r \cos(\theta) \right) + 1 \\ \nabla \cdot \vec{u} &= 2 \cos(\theta) + \cos(\theta) + 1 \\ \nabla \cdot \vec{u} &= 3 \cos(\theta) + 1 \end{split}$$

Ser så på virvlingen

$$\nabla \times \vec{u} = 0\hat{\mathbf{i}}_r + 0\hat{\mathbf{i}}_\theta + \frac{1}{r} \left(\frac{\partial}{\partial r} \left(r \left(r \sin(\theta) \right) \right) - \frac{\partial}{\partial \theta} \left(r \cos(\theta) \right) \right) \hat{\mathbf{k}}$$

$$\nabla \times \vec{u} = \frac{1}{r} \left(\sin(\theta) \frac{\partial}{\partial r} \left(r^2 \right) - r \frac{\partial}{\partial \theta} \left(\cos(\theta) \right) \right) \hat{\mathbf{k}}$$

$$\nabla \times \vec{u} = \frac{1}{r} \left(2r \sin(\theta) + r \sin(\theta) \right) \hat{\mathbf{k}}$$

$$\nabla \times \vec{u} = \left(2 \sin(\theta) + \sin(\theta) \right) \hat{\mathbf{k}}$$

$$\nabla \times \vec{u} = 3 \sin(\theta) \hat{\mathbf{k}}$$

iii $\vec{u} = \hat{\mathbf{i}}_r + \hat{\mathbf{i}}$

Konverterer først over til rene sylinder koordinater

$$\hat{\mathbf{i}} = \cos(\theta)\hat{\mathbf{i}}_r - \sin(\theta)\hat{\mathbf{i}}_\theta$$

$$\vec{u} = \hat{\mathbf{i}}_r + \cos(\theta)\hat{\mathbf{i}}_r - \sin(\theta)\hat{\mathbf{i}}_\theta$$
$$\vec{u} = (1 + \cos(\theta))\hat{\mathbf{i}}_r - \sin(\theta)\hat{\mathbf{i}}_\theta$$

Ser først på divergensen

$$\begin{split} \nabla \cdot \vec{u} &= \frac{1}{r} \left(\frac{\partial}{\partial r} \left(r \left(1 + \cos(\theta) \right) \right) \frac{\partial}{\partial \theta} \left(-\sin(\theta) \right) \right) \\ \nabla \cdot \vec{u} &= \frac{1}{r} \left(1 + \cos(\theta) - \cos(\theta) \right) \\ \nabla \cdot \vec{u} &= \frac{1}{r} \end{split}$$

Ser så på virvlingen

$$\nabla \times \vec{u} = 0\hat{\mathbf{i}}_r + 0\hat{\mathbf{i}}_\theta + \frac{1}{r} \left(\frac{\partial}{\partial r} \left(r \left(-\sin(\theta) \right) \right) - \frac{\partial}{\partial \theta} \left(1 + \cos(\theta) \right) \right) \hat{\mathbf{k}}$$

$$\nabla \times \vec{u} = \frac{1}{r} \left(-\sin(\theta) + \sin(\theta) \right) \hat{\mathbf{k}}$$

$$\nabla \times \vec{u} = \vec{0}$$

 $\mathbf{2}$

 \mathbf{a}

For å finne enhetsvektorene så må man først finne skaleringsfaktorene. Starter med skaleringsfaktoren til u

$$h_{u} = \left| \frac{\partial \vec{r}}{\partial u} \right|$$

$$h_{u} = \left| a \cos(v) \frac{\partial}{\partial u} \cosh(u) \hat{\mathbf{i}} + a \sin(v) \frac{\partial}{\partial v} \sinh(u) \hat{\mathbf{j}} \right|$$

$$a = 1$$

$$h_{u} = \left| \cos(v) \sinh(u) \hat{\mathbf{i}} + \sin(v) \cosh(u) \right|$$

$$h_{u} = \sqrt{\left(\cos(v) \sinh(u)\right)^{2} + \left(\sin(v) \cosh(u)\right)^{2}}$$

$$h_{u} = \sqrt{\cos^{2}(v) \sinh^{2}(u) + \sin^{2}(v) \cosh^{2}(u)}$$

$$\cosh^{2}(u) = 1 + \sinh^{2}(u)$$

$$h_{u} = \sqrt{\cos^{2}(v) \sinh^{2}(u) + \sin^{2}(v) \left(1 + \sinh^{2}(u)\right)}$$

$$h_{u} = \sqrt{\cos^{2}(v) \sinh^{2}(u) + \sinh^{2}(u) \sin^{2}(v) + \sin^{2}(v)}$$

$$h_{u} = \sqrt{\sinh^{2}(u) \left(\cos^{2}(v) + \sin^{2}(v)\right) + \sin^{2}(v)}$$

$$h_{u} = \sqrt{\sinh^{2}(u) + \sin^{2}(v)}$$

Finner så skaleringsfaktoren til v

$$h_{v} = \left| \frac{\partial \vec{r}}{\partial v} \right|$$

$$h_{v} = \left| \cosh\left(u\right) \frac{\partial}{\partial v} \cos(v) \hat{\mathbf{i}} + \sinh\left(u\right) \frac{\partial}{\partial v} \sin(v) \hat{\mathbf{j}} \right|$$

$$h_{v} = \left| -\cosh\left(u\right) \sin(v) \hat{\mathbf{i}} + \sinh\left(u\right) \cos(v) \hat{\mathbf{j}} \right|$$

$$h_{v} = \sqrt{\left(-\cosh\left(u\right) \sin(v)\right)^{2} + \left(\sinh\left(u\right) \cos(v)\right)^{2}}$$

$$h_{v} = \sqrt{\cosh^{2}\left(u\right) \sin^{2}\left(v\right) + \sinh^{2}\left(u\right) \cos^{2}\left(v\right)}$$

$$h_{v} = \sqrt{\left(1 + \sinh^{2}\left(u\right)\right) \sin^{2}\left(v\right) + \sinh^{2}\left(u\right) \cos^{2}\left(v\right)}$$

$$h_{v} = \sqrt{\sin^{2}\left(v\right) + \sinh^{2}\left(u\right) \sin^{2}\left(v\right) + \sinh^{2}\left(u\right) \cosh^{2}\left(v\right)}$$

$$h_{v} = \sqrt{\sin^{2}\left(v\right) + \sinh^{2}\left(u\right) \left(\sin^{2}\left(v\right) + \cos^{2}\left(v\right)\right)}$$

$$h_{v} = \sqrt{\sinh^{2}\left(u\right) + \sinh^{2}\left(u\right)}$$

Ser da at $h_u = h_v$ Enhetsvektorer er da gitt ved

$$\mathbf{e}_{u} = \frac{1}{h_{u}} \frac{\partial \vec{r}}{\partial u}$$

$$\mathbf{e}_{u} = \frac{1}{\sqrt{\sinh^{2}(u) + \sin^{2}(v)}} \left(\cos(v) \sinh(u) \,\hat{\mathbf{i}} + \sin(v) \cosh(u) \,\hat{\mathbf{j}}\right)$$

Og

$$\mathbf{e}_{v} = \frac{1}{h_{v}} \frac{\partial \vec{r}}{\partial v}$$

$$\mathbf{e}_{v} = \frac{1}{\sqrt{\sinh^{2}(u) + \sin^{2}(v)}} \left(-\cosh(u)\sin(v)\hat{\mathbf{i}} + \sinh(u)\cos(v)\hat{\mathbf{j}} \right)$$

Hvis de er ortogonale så må $\mathbf{e}_u \cdot \mathbf{e}_v = 0$

$$\begin{aligned} \mathbf{e}_{u} \cdot \mathbf{e}_{v} &= \frac{1}{\sqrt{\sinh^{2}(u) + \sin^{2}(v)}} \begin{pmatrix} \cos(v) \sinh(u) \\ \sin(v) \cosh(u) \end{pmatrix} \cdot \frac{1}{\sqrt{\sinh^{2}(u) + \sin^{2}(v)}} \begin{pmatrix} -\cosh(u) \sin(v) \\ \sinh(u) \cos(v) \end{pmatrix} \\ \mathbf{e}_{u} \cdot \mathbf{e}_{v} &= \frac{1}{\sinh^{2}(u) \sin^{2}(v)} \left(-\cos(v) \sinh(u) \cosh(u) \sin(v) + \sin(v) \cosh(u) \sinh(u) \cos(v) \right) \\ \mathbf{e}_{u} \cdot \mathbf{e}_{v} &= \left(-\sin(v) \cos(v) \sinh(u) \cosh(u) + \sin(v) \cos(v) \sinh(u) \cosh(u) \right) \\ \mathbf{e}_{u} \cdot \mathbf{e}_{v} &= 0 \end{aligned}$$

Med dette så observeres det at enhetsvektorene er ortogonale

b

Siden ingen f har blitt oppgitt så tar jeg utgangspunkt i en helt generell f. Gradienten blir da

$$\nabla f = \frac{1}{h_u} \frac{\partial f}{\partial u} \mathbf{e}_u + \frac{1}{h_v} \frac{\partial f}{\partial v} \mathbf{e}_v$$
$$h_u = h_v = h$$
$$\nabla f = \frac{1}{h} \left(\frac{\partial f}{\partial u} \mathbf{e}_u + \frac{\partial f}{\partial v} \mathbf{e}_v \right)$$

Veit ikke hva w_u og w_v inneholder så blir generell divergens

$$\nabla \cdot \vec{w} = \frac{1}{h_u h_v} \left(\frac{\partial}{\partial u} \left(w_u \mathbf{e}_u h_v \right) + \frac{\partial}{\partial v} \left(w_v \mathbf{e}_v h_u \right) \right)$$

Laplace operatoren blir

$$\nabla^{2} = \frac{1}{h_{u}h_{v}} \left[\frac{\partial}{\partial u} \left(\frac{h_{u}}{h_{v}} \frac{\partial}{\partial u} \right) + \frac{\partial}{\partial v} \left(\frac{h_{v}}{h_{u}} \frac{\partial}{\partial v} \right) \right]$$

$$\left[\frac{h_{v} = h_{u} = h}{h^{2}} \right]$$

$$\nabla^{2} = \frac{1}{h^{2}} \left[\frac{\partial}{\partial u} \frac{\partial}{\partial u} + \frac{\partial}{\partial v} \frac{\partial}{\partial v} \right]$$

$$\nabla^{2} = \frac{1}{h^{2}} \left[\frac{\partial^{2}}{\partial u^{2}} + \frac{\partial^{2}}{\partial v^{2}} \right]$$

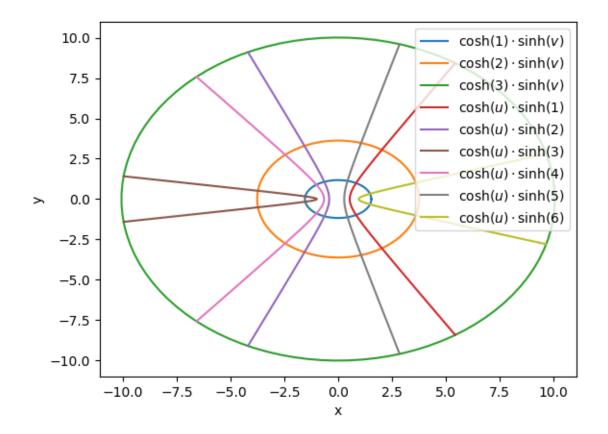
 \mathbf{c}

Python kode til skissen er

```
import numpy as np
import matplotlib.pyplot as plt
                   \begin{array}{l} {\tt N} = 100 \\ {\tt u} = {\tt np.linspace} \left( -3, \ 3, \ {\tt N} \right) \\ {\tt v} = {\tt np.linspace} \left( 0 \,, \ 2 {\tt *np.pi} \,, \ {\tt N} \right) \\ \end{array} 
   6
7
8
9
                 \begin{array}{lll} & \text{for i in } \operatorname{range}\left(1,\ 4\right): \\ & & \text{$x = \operatorname{np.cosh}(i)*\operatorname{np.cos}(v)$} \\ & & \text{$y = \operatorname{np.sinh}(i)*\operatorname{np.sin}(v)$} \\ & & \text{$plt.plot}(x,\ y,\ label=f"\$\backslash \cosh\left(\{\,i\,\}\right)\ \backslash \operatorname{cdot}\ \backslash \sinh\left(v\right)\$")$} \end{array}
10
11
12
                  \begin{array}{lll} & \text{for i in } \text{range}\,(1\,,\,\,7): \\ & \text{$x=\text{np.cosh}\,(u)*\text{np.cos}\,(i)$} \\ & \text{$y=\text{np.sinh}\,(u)*\text{np.sin}\,(i)$} \\ & \text{$plt.plot}\,(x\,,\,\,y\,,\,\,\, label=f"\,\$\backslash \cosh\,(u)\,\,\,\backslash cdot\,\,\,\backslash sinh\,(\{\,i\,\})\,\$"\,) \end{array}
13
14
15
16
17
                plt.xlabel("x")
plt.ylabel("y")
plt.legend()
plt.savefig("2c.png")
plt.show()
19
20
21
```

Som produserer skissen

Figur 1: Skissen til 2c



 \mathbf{d}

Python kode til dette er

```
import numpy as np
import sympy as sp
import matplotlib.pyplot as plt

u, v = psi = sp.symbols("u, v", real=True)
r = (sp.cosh(u)*sp.cos(v), sp.sinh(u)*sp.sin(v))

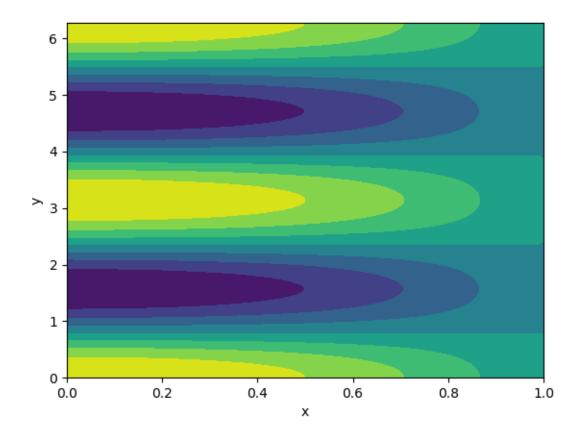
def basisvektor(psi, r):
    b = np.zeros((len(psi), len(r)), dtype=object)
    for i, ui, in enumerate(psi):
        for j, rj in enumerate(r):
            b[i, j] = sp.simplify(rj.diff(ui, 1))

return b

def skaleringsfaktor(b):
    h = np.zeros(b.shape[0], dtype=object)
    for i, s in enumerate(np.sum(b**2, axis=1)):
        h[i] = sp.simplify(sp.sqrt(s))
    return h
```

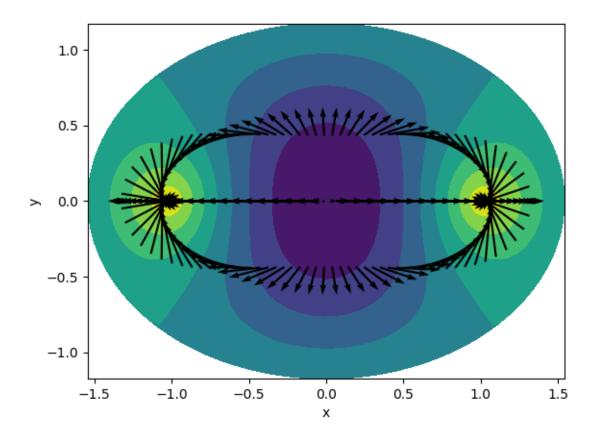
```
\begin{array}{ll} \textbf{d}\,\textbf{e}\, f & \texttt{enhetsvektor}\,(\,\texttt{psi}\,\,,\,\,\,\textbf{r}\,)\, ; \end{array}
21
22
                      b = basisvektor(psi, r)
hi = skaleringsfaktor(b)
return b/ hi[None, :], hi
23
25
^{26}
           {\tt e}\,,\ {\tt h}\,=\,{\tt enhetsvektor}\,(\,{\tt psi}\,,\ {\tt r}\,)
27
28
           f = (1 - u**2)*sp.cos(2*v)
29
30
           N = 100
           32
33
34
           mesh = [] for rj in r:
35
36
37
                     \mathtt{mesh.append} \, (\, \mathtt{sp.lambdify} \, (\, (\, \mathtt{u} \,, \,\,\, \mathtt{v}) \,\,, \,\,\, \mathtt{rj} \,) \, (\, \mathtt{ui} \,\,, \,\,\, \mathtt{vi} \,) \,)
38
39
           {\tt plt.contourf(x, y, fj)}
40
41
42
           {\tt df \, = \, np.array} \, (\, (\, 1 \, / \, h \, [\, 0\,] \, * \, f \, . \, {\tt diff} \, (\, u \, , \quad 1\,) \, \, , \quad 1 \, / \, h \, [\, 1\,] \, * \, f \, . \, {\tt diff} \, (\, v \, , \quad 1\,) \, ) \, )
43
           {\tt gradf} \; = \; {\tt e} \, [\, 0\, ] * {\tt df} \, [\, 0\, ] \; + \; {\tt e} \, [\, 1\, ] * {\tt df} \, [\, 1\, ]
45
          \begin{array}{lll} \texttt{dfdxi} &= \texttt{sp.lambdify}((\texttt{u}, \texttt{v}), \texttt{gradf}\,[0])\,(\texttt{ui}, \texttt{vi}) \\ \texttt{dfdyi} &= \texttt{sp.lambdify}((\texttt{u}, \texttt{v}), \texttt{gradf}\,[1])\,(\texttt{ui}, \texttt{vi}) \\ \texttt{plt.contourf}\,(\texttt{x}, \texttt{y}, \texttt{fj}) \\ \texttt{plt.quiver}(\texttt{x}\,[::50]\,, \texttt{y}\,[::50]\,, \texttt{dfdxi}\,[::50]\,, \texttt{dfdyi}\,[::50]\,, \texttt{scale} = 15, \texttt{pivot} = "middle") \end{array}
46
47
48
49
           plt.xlabel("x")
plt.ylabel("y")
51
52
53
           \begin{array}{l} \texttt{plt.savefig} \left( \text{"}\, 2d \, . \, png \text{"} \right) \\ \texttt{plt.show} \left( \right) \end{array}
54
55
           plt.close()
56
58
           {\tt plt.contourf(ui, vi, fj)}
59
           plt.xlabel("x")
plt.ylabel("y")
60
           plt.savefig("2d_elliptical.png")
plt.show()
61
```

Figur 2: Konturplott i elliptiske koordinater oppgave 2d



Observerer da at vektorene peker ut i fra origo og blir slukt ned i brennpunktene (-1,0) og (1,0)

Figur 3: Pilplott til oppgave 2d



3

 \mathbf{a}

Str#mfunksjon

$$\frac{\partial \psi}{\partial y} = -v_x \qquad \qquad \wedge \qquad \qquad \frac{\partial \psi}{\partial x} = v_y$$

$$\psi(x,y) = -\int \cos(x)\sin(y)\mathrm{e}^{-2vt}\,\mathrm{d}y \qquad \wedge \qquad \psi(x,y) = \int -\sin(x)\cos(y)\mathrm{e}^{-2vt}\,\mathrm{d}x$$

$$\psi(x,y) = -\cos(x)\cos(y)\mathrm{e}^{-2vt} + C \qquad \wedge \qquad \psi(x,y) = -\cos(x)\cos(y)\mathrm{e}^{-2vt} + C$$

 $v_x = \frac{\partial \psi}{\partial y} \wedge v_y = \frac{\partial \psi}{\partial x}$

Ser så om den har ett skalarpotensial. Hvis det har det så må

$$\frac{\partial \phi}{\partial x} = v_x \qquad \wedge \qquad \frac{\partial \phi}{\partial y} = v_y$$

$$\phi(x,y) = \int \cos(x)\sin(y)e^{-2vt} dx \qquad \wedge \qquad \phi(x,y) = \int \left(-\sin(x)\cos(y)e^{-2vt}\right) dy$$

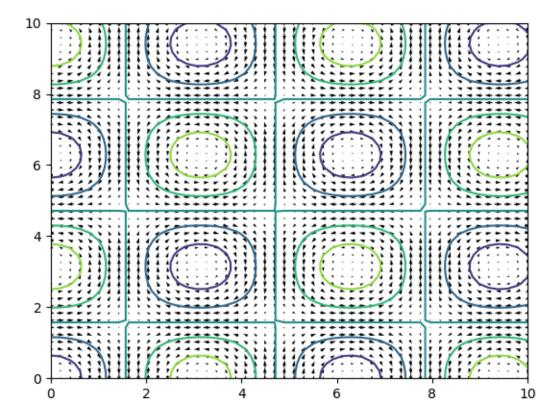
$$\phi = \sin(x)\sin(y)e^{-2vt} + f(y) \qquad \wedge \qquad \phi = -\sin(x)\sin(y)e^{-2vt} + f(x)$$

Disse kan ikke være like så det finnes ikke noe skalarpotensial

b

Python kode til pilplott med strømlinjer Som produserer følgende graf

Figur 4: Pilplott med strømlinjer til 3b



Kan bruke Gauss' divergensteorem siden det er en generalisering av Green Sett inn mer her siden

$$\int\limits_{C} \vec{u} \cdot \vec{n} \, \mathrm{d}s = \iint\limits_{R} \nabla \cdot \vec{u} \, \mathrm{d}x \, \mathrm{d}y$$

Regner ut $\nabla \cdot \vec{u}$

$$\nabla \cdot \vec{u} = \frac{\partial}{\partial x} \left(\cos(x) \sin(y) \right) + \frac{\partial}{\partial y} \left(-\sin(x) \cos(y) \right)$$
$$\nabla \cdot \vec{u} = -\sin(x) \sin(y) + \sin(x) \sin(y)$$
$$\nabla \cdot \vec{u} = 0$$

Følgelig er fluksen da 0 Sirkulasjonen blir da

$$\oint \vec{u} \cdot d\vec{r} = \int_{0}^{\frac{\pi}{2}} \vec{u} \cdot d\vec{r}_{x,0} + \int_{0}^{\frac{\pi}{2}} \vec{u} \cdot d\vec{r}_{y,0} + \int_{\frac{\pi}{2}}^{0} \vec{u} \cdot d\vec{r}_{x,1} + \int_{\frac{\pi}{2}}^{0} \vec{u} \cdot d\vec{r}_{y,1}$$

$$\vec{r}_{x,0}(t') = t'\hat{\mathbf{i}} + 0\hat{\mathbf{j}} \quad \wedge \quad \vec{r}_{y,0}(t') = \frac{\pi}{2}\hat{\mathbf{i}} + t'\hat{\mathbf{j}} \wedge \quad \vec{r}_{x,1}(t') = t'\hat{\mathbf{i}} + \frac{\pi}{2}\hat{\mathbf{j}} \quad \wedge \quad \vec{r}_{y,1}(t') = 0\hat{\mathbf{i}} + t'\hat{\mathbf{j}}$$

$$\vec{r}'_{x,0}(t') = \hat{\mathbf{i}} \qquad \wedge \qquad \vec{r}'_{y,0}(t') = \hat{\mathbf{j}} \wedge \quad \vec{r}'_{x,1}(t') = \hat{\mathbf{i}} \qquad \wedge \qquad \vec{r}'_{y,1}(t') = \hat{\mathbf{j}}$$

$$\oint_{\frac{\pi}{2}} \vec{u} \left(\vec{r}_{x,0}(t') \right) \cdot \vec{r}'_{x,0}(t') \, dt' + \int_{0}^{\frac{\pi}{2}} \vec{u} \left(\vec{r}_{y,0}(t') \right) \cdot \vec{r}'_{y,0}(t') \, dt'$$

$$\oint_{\frac{\pi}{2}} \vec{u} \left(\vec{r}_{x,1}(t') \right) \cdot \vec{r}'_{x,1} \, dt' + \int_{\frac{\pi}{2}}^{0} \vec{u} \left(\vec{r}_{y,1}(t') \right) \cdot \vec{r}'_{y,1} \, dt'$$

For å få det litt mer oversiktelig så regner jeg ett integral av gangen. Starter med

$$\int_{0}^{\frac{\pi}{2}} \vec{u} \left(\vec{r}_{x,0}(t') \right) \cdot \vec{r}'_{x,0}(t') \, dt' = \int_{0}^{\frac{\pi}{2}} \left(\cos(t') \sin(0) e^{-2vt} \right) \hat{\mathbf{i}} \cdot \hat{\mathbf{i}} \, dt'$$

$$\int_{0}^{\frac{\pi}{2}} \vec{u} \left(\vec{r}_{x,0}(t') \right) \cdot \vec{r}'_{x,0}(t') \, dt' = \int_{0}^{\frac{\pi}{2}} \left(\cos(t') \sin(0) e^{-2vt} \right) \, dt'$$

$$\int_{0}^{\frac{\pi}{2}} \vec{u} \left(\vec{r}_{x,0}(t') \right) \cdot \vec{r}'_{x,0}(t') \, dt' = \int_{0}^{\frac{\pi}{2}} 0 \, dt'$$

$$\int_{0}^{\frac{\pi}{2}} \vec{u} \left(\vec{r}_{x,0}(t') \right) \cdot \vec{r}'_{x,0}(t') \, dt' = 0$$

Ser så på

$$\int_{0}^{\frac{\pi}{2}} \vec{u} \left(\vec{r}_{y,0}(t') \right) \cdot \vec{r}'_{y,0}(t') \, dt' = \int_{0}^{\frac{\pi}{2}} \left(-\sin\left(\frac{\pi}{2}\right) \cos(t') e^{-2vt} \right) \hat{\mathbf{j}} \cdot \hat{\mathbf{j}} \, dt'$$

$$\int_{0}^{\frac{\pi}{2}} \vec{u} \left(\vec{r}_{y,0}(t') \right) \cdot \vec{r}'_{y,0}(t') \, dt' = \int_{0}^{\frac{\pi}{2}} \left(-\sin\left(\frac{\pi}{2}\right) \cos(t') e^{-2vt} \right) \, dt'$$

$$\int_{0}^{\frac{\pi}{2}} \vec{u} \left(\vec{r}_{y,0}(t') \right) \cdot \vec{r}'_{y,0}(t') \, dt' = -e^{-2vt} \int_{0}^{\frac{\pi}{2}} \cos(t') \, dt'$$

$$\int_{0}^{\frac{\pi}{2}} \vec{u} \left(\vec{r}_{y,0}(t') \right) \cdot \vec{r}'_{y,0}(t') \, dt' = -e^{-2vt} \left[\sin(t') \right]_{0}^{\frac{\pi}{2}}$$

$$\int_{0}^{\frac{\pi}{2}} \vec{u} \left(\vec{r}_{y,0}(t') \right) \cdot \vec{r}'_{y,0}(t') \, dt' = -e^{-2vt} \left(1 - 0 \right)$$

$$\int_{0}^{\frac{\pi}{2}} \vec{u} \left(\vec{r}_{y,0}(t') \right) \cdot \vec{r}'_{y,0}(t') \, dt' = -e^{-2vt}$$

Ser så på

$$\int_{\frac{\pi}{2}}^{0} \vec{u} \left(\vec{r}_{x,1}(t') \right) \cdot \vec{r}'_{x,1} \, dt' = \int_{\frac{\pi}{2}}^{0} \left(\cos(t') \sin\left(\frac{\pi}{2}\right) \right) \hat{\mathbf{i}} \cdot \hat{\mathbf{i}} \, dt'$$

$$\int_{\frac{\pi}{2}}^{0} \vec{u} \left(\vec{r}_{x,1}(t') \right) \cdot \vec{r}'_{x,1} \, dt' = e^{-2vt} \int_{\frac{\pi}{2}}^{0} \cos(t') \, dt'$$

$$\int_{\frac{\pi}{2}}^{0} \vec{u} \left(\vec{r}_{x,1}(t') \right) \cdot \vec{r}'_{x,1} \, dt' = e^{-2vt} \left[\sin(t') \right]_{\frac{\pi}{2}}^{0}$$

$$\int_{\frac{\pi}{2}}^{0} \vec{u} \left(\vec{r}_{x,1}(t') \right) \cdot \vec{r}'_{x,1} \, dt' = e^{-2vt} \left(0 - 1 \right)$$

$$\int_{\frac{\pi}{2}}^{0} \vec{u} \left(\vec{r}_{x,1}(t') \right) \cdot \vec{r}'_{x,1} \, dt' = -e^{-2vt}$$

Ser så på

$$\int_{\frac{\pi}{2}}^{0} \vec{u} \left(\vec{r}_{y,1}(t') \right) \cdot \vec{r}'_{y,1} \, dt' = \int_{\frac{\pi}{2}}^{0} \left(-\sin(0)\cos(t')e^{-2vt} \right) \hat{\mathbf{j}} \cdot \hat{\mathbf{j}} \, dt'$$

$$\int_{\frac{\pi}{2}}^{0} \vec{u} \left(\vec{r}_{y,1}(t') \right) \cdot \vec{r}'_{y,1} \, dt' = \int_{\frac{\pi}{2}}^{0} \left(-\sin(0)\cos(t')e^{-2vt} \right) dt'$$

$$\int_{\frac{\pi}{2}}^{0} \vec{u} \left(\vec{r}_{y,1}(t') \right) \cdot \vec{r}'_{y,1} \, dt' = \int_{\frac{\pi}{2}}^{0} 0 \, dt'$$

$$\int_{\frac{\pi}{2}}^{0} \vec{u} \left(\vec{r}_{y,1}(t') \right) \cdot \vec{r}'_{y,1} \, dt' = 0$$

Kan så gå tilbake til sirkulasjonen

$$\oint \vec{u} \cdot d\vec{r} = 0 - e^{-2vt} - e^{-2vt} + 0 = -2e^{-2vt}$$

Kan også bruke Stokes sats som sier

$$\oint_{C} \vec{u} \cdot d\vec{r} = \int_{\vec{a}} (\nabla \times \vec{u}) \cdot \vec{n} \, d\sigma$$

Der

$$\nabla \times \vec{u} = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \cos(x)\sin(y)e^{-2vt} & -\sin(x)\cos(y)e^{-2vt} & 0 \end{vmatrix}$$

$$\nabla \times \vec{u} = e^{-2vt} \left(\frac{\partial}{\partial x} \left(-\sin(x)\cos(y) \right) - \frac{\partial}{\partial y} \left(\cos(x)\sin(y) \right) \right) \hat{\mathbf{k}}$$

$$\nabla \times \vec{u} = e^{-2vt} \left(-\cos(x)\cos(y) - \cos(x)\cos(y) \right) \hat{\mathbf{k}}$$

$$\nabla \times \vec{u} = -2e^{-2vt}\cos(x)\cos(y) \hat{\mathbf{k}}$$

Og $\vec{n} = \hat{\mathbf{k}}$ siden den har positiv orientering om z. Da blir Stokes

$$\int_{\sigma} (\nabla \times \vec{u}) \cdot \vec{n} \, d\sigma = \int_{\sigma} \left(-2e^{-2vt} \cos(x) \cos(y) \right) \hat{\mathbf{k}} \cdot \hat{\mathbf{k}} \, d\sigma$$

$$\int_{\sigma} (\nabla \times \vec{u}) \cdot \vec{n} \, d\sigma = -2e^{-2vt} \int_{\sigma} \left(\cos(x) \cos(y) \right) d\sigma$$

$$\int_{\sigma} (\nabla \times \vec{u}) \cdot \vec{n} \, d\sigma = -2e^{-2vt} \int_{0}^{\frac{\pi}{2}} \int_{0}^{\frac{\pi}{2}} \cos(x) \cos(y) \, dx \, dy$$

$$\int_{\sigma} (\nabla \times \vec{u}) \cdot \vec{n} \, d\sigma = -2e^{-2vt} \int_{0}^{\frac{\pi}{2}} \cos(y) \left[\sin(x) \right]_{0}^{\frac{\pi}{2}} \, dy$$

$$\int_{\sigma} (\nabla \times \vec{u}) \cdot \vec{n} \, d\sigma = -2e^{-2vt} \int_{0}^{\frac{\pi}{2}} \cos(y) \left(1 - 0 \right) \, dy$$

$$\int_{\sigma} (\nabla \times \vec{u}) \cdot \vec{n} \, d\sigma = -2e^{-2vt} \left[\sin(y) \right]_{0}^{\frac{\pi}{2}}$$

$$\int_{\sigma} (\nabla \times \vec{u}) \cdot \vec{n} \, d\sigma = -2e^{-2vt} \left[\sin(y) \right]_{0}^{\frac{\pi}{2}}$$

$$\int_{\sigma} (\nabla \times \vec{u}) \cdot \vec{n} \, d\sigma = -2e^{-2vt} \left[1 - 0 \right]$$

$$\int_{\sigma} (\nabla \times \vec{u}) \cdot \vec{n} \, d\sigma = -2e^{-2vt} \left[1 - 0 \right]$$