## ESE-615 - Autonomous Racing

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## Scan Matching

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Problem Lab Assignment

(points)

## Theoretical Questions

1.  $B_i$ 

(a) 
$$B_i = M_i^T M_i = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ p_{i0} & p_{i1} \\ -p_{i1} & p_{i0} \end{pmatrix} \begin{pmatrix} 1 & 0 & p_{i0} & -p_{i1} \\ 0 & 1 & p_{i1} & p_{i0} \end{pmatrix} = \begin{pmatrix} 1 & 0 & p_{i0} & -p_{i1} \\ 0 & 1 & p_{i1} & p_{i0} \\ p_{i0} & p_{i1} & p_{i0}^2 + p_{i1}^2 & 0 \\ -p_{i1} & p_{i0} & 0 & p_{i0}^2 + p_{i1}^2 \end{pmatrix}$$

Proof ends.

2. Optimization Problem

(a) 
$$W = \begin{bmatrix} 0_{2\times2} & 0_{2\times2} \\ 0_{2\times2} & I_{2\times2} \end{bmatrix}$$
,  $M = \sum_i M_i^T C_i M_i$   $g = \sum_i -2\pi_i^T C_i M_i$ , where  $C_i = n_i n_i^T$ 

(b) 
$$\forall x, x^T M x = \sum_i x^T M_i^T n_i n_i^T M_i x = \sum_i x^T M_i^T n_i (x^T M_i^T n_i)^T \ge 0$$

$$\forall x,\, \text{we have}\,\, x^TWx = x_3^2 + x_4^2 = 1 \geq 0$$