Vector Calculus (cont.)

1. Gradient of a scalar field

a. Partial derivative at $x = (x_1, ..., x_n)$

$$rac{\partial f}{\partial x_i} = \lim_{h o 0} rac{f(x_1,\,\ldots,x_i+h,\ldots,x_n)-f(x_1,\,\ldots,x_i,\ldots,x_n)}{h},\,i=1,\ldots,n$$

c. We collect them at the row vector known as the gradient of the function f

$$\int_{\mathrm{d}} \nabla f(x) =
abla_x f = \mathrm{grad} f = egin{pmatrix} rac{\partial f}{\partial x_1} & rac{\partial f}{\partial x_2} & \dots & rac{\partial f}{\partial x_n} \end{pmatrix} \in \mathbb{R}^{1 imes n}$$

e. Remark: the gradient collects the slopes in the positive x_i direction for all i = 1...n

2. Directional derivative

- a. Instead of computing the slopes in the positive x_i directions for all i=1...n, we can compute the derivative along any direction
- b. Directional derivative

$$abla_v f(x) = D_v f(x) = \lim_{h o 0} rac{f(x+hv) - f(x)}{h} =
abla f(x) \cdot v$$

3. Hessian of a scalar field

a. If all second partial derivatives of f exist and are continuous over the domain of the function, then the Hessian matrix is a square matrix, usually defined and arranged as follows:

$$\mathbf{H}_{f} = \begin{bmatrix} \frac{\partial^{2} f}{\partial x_{1}^{2}} & \frac{\partial^{2} f}{\partial x_{1} \partial x_{2}} & \cdots & \frac{\partial^{2} f}{\partial x_{1} \partial x_{n}} \\ \frac{\partial^{2} f}{\partial x_{2} \partial x_{1}} & \frac{\partial^{2} f}{\partial x_{2}^{2}} & \cdots & \frac{\partial^{2} f}{\partial x_{2} \partial x_{n}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^{2} f}{\partial x_{n} \partial x_{1}} & \frac{\partial^{2} f}{\partial x_{n} \partial x_{2}} & \cdots & \frac{\partial^{2} f}{\partial x_{n}^{2}} \end{bmatrix}$$

4. Example

a. Compute the Hessian of f(x,y) = xy*(x+y) at (1,1)

$$H_f(x,y)=egin{pmatrix} 2y&2(x+y)&xy&(x+y)&t&(1,1)\ 2(x+y)&2x \end{pmatrix},\, H_f(1,1)=egin{pmatrix} 2&4\4&2 \end{pmatrix}$$

b. The symmetry of H is not coincidence; of (x,y) is a twice continuously

differentiable function, then
$$\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x}$$

Lec 21 $\int_{\Omega} x^{2}x = x_{1}^{2} + \dots + x_{n}^{2}$ f(x)=11x11,2 f: R">R Gradient Vf(x) Lywhat are the dimensions olxn $\nabla f(x) = \left(\frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2}\right) + \frac{\partial f}{\partial x_1} + \frac{\partial f}{\partial x_2} +$ greater changes lim f(x2 + hu2) - f(x2) + directional derivative - it is a real number, not rector 3 ER, 110112=1 ex) v= (-1/2, 1/2)] orthogonal to (2,2) V(xtx)= 2xT Evaluate at (1,1) $\nabla f(x)$ $(1,1) = \nabla f(1,1)$ = (2,2) $o(1)^{-3}$ $o(1)^{-1}$ $o(1,1) = (2,2) \cdot (\frac{1}{\sqrt{2}}) = 0$ This means that if we move in direction pointed by vector (tz, tr), this means that we don't change much. 3x'(1) + h(-1/52) $\lim_{h \to 0} f(xt) - f(x)$

$$f(x') = ||x'||_{2}^{2}$$

$$= (|+\frac{h}{\sqrt{2}})^{2} + (|-\frac{h}{\sqrt{2}})^{2}$$

$$= 1 + \frac{h^2}{2} + 1 + \frac{h^2}{2}$$

$$= 2 + h^2$$

$$\lim_{h \to 0} \frac{f(x') - f(x)}{h} = \frac{2 + h^2 - 2}{h} = h = 0$$

Move little or thogonal to gradient Move maximum o parallel to gradient

& make the derivative unit vector!

ex)
$$f(x,y)=x^2y$$

gradient of $f:$
 $\nabla f(x,y)=(2xy,x^2)$
gradient at $(3,2)$
 $\nabla f(3,2)=(12,9)$
The decivative of f in direction of $(1,2)$ at point $(3,2)$

$$\nabla(x_5, 2/x_5) f(2,3) = (12,9) {x_5 \choose 2/x_5} = \frac{30}{\sqrt{5}}$$
 $f(x) = w^7 x \quad \nabla f(x) = w^7 \quad \text{enoned to prove}$

$$f(x_1, x_2) = 3x_1 - 10x_2$$

 $w^{T} = (3, -10)$

$$\nabla f(x)^{kn} = \left(\frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2}\right) = \left(\omega_1, \omega_n\right) = \omega^T$$

$$\omega^T \cdot v = ||\omega|| \cdot (os \theta)$$

$$f: \mathbb{R}^n \to \mathbb{R}$$

$$\nabla^2 f(x) : H_f(x) \leftarrow \text{Hessian} \to \frac{\delta^2 f}{\delta x_1^2} \frac{\delta^2 f}{\delta x_1 \delta^2}$$

$$\frac{-\delta^2 f}{\delta x_1^2}$$

Vf ER IXN

$$f(x,y) = \chi^{2}y$$

$$f(x,y) = (2xy, x^{2})$$

$$\frac{\partial^{2}f}{\partial x^{2}} = 2y$$

$$\frac{\partial^{2}f}{\partial x^{2}} = 2x = \frac{\partial^{2}f}{\partial y^{2}} = 2x$$

$$\frac{\partial^{2}f}{\partial x^{2}} = 0$$

$$+ \dots + \frac{f''(x_0)}{N!} \left(x - x_0\right)^{n}$$

$$= \sum_{k=0}^{\infty} \frac{f^k(x_0)}{K!} \left(x - x_0\right)^{k}$$

$$= \sum_{k=0}^{\infty} \frac{f^k(x_0)}{K!} \left(x - x_0\right)^{n}$$

Taylor Approximation Theorem

Suppose at least
$$(n+1)$$
 differentiable in $(a,b]$

$$\forall x \in (a,b) \ T(x) = \sum_{k=0}^{n} \frac{f^{k}(a)}{k!} (x-a)^{k}$$

$$\max_{\alpha \leq x \leq b} \left| f^{(n+1)}(x) \right| \left| x - \alpha \right|^{n+1}$$

$$= 1 + 4(x-1) + 6(x-1)^{2} + 4(x-1)^{3} + (x-1)^{4}$$

$$\begin{cases} (x_{1}, x_{2}) = \lambda_{1}^{q} + x_{2}^{q} + 3x_{1}x_{2}^{3} + e^{x_{1} + e^{x_{2}}} \\ f(x_{1}, x_{2}) = f(l_{1}x) + \nabla f(l_{1}x) \begin{pmatrix} x_{1} - l_{1} \\ x_{2} - 2 \end{pmatrix} \\ + (x_{1} - l_{1}x_{2} - 2) H_{f} \begin{vmatrix} x_{1} - l_{1} \\ x_{2} - 2 \end{pmatrix} + \\ e(x) f(x_{1}x_{2}) = x^{2} + 2x_{2} + 1^{3} + Cl_{1}x^{2} \\ \nabla f(x_{1}x_{2}) = (2x + 2y_{1}, 2x + 2y^{2}) \\ H_{f} = \begin{pmatrix} 2 & 2 \\ 2 & 6y \end{pmatrix} \\ \nabla f(l_{1}x_{2}) = \begin{pmatrix} 2 & 2 \\ 2 & 12 \end{pmatrix} \\ H_{f}(l_{1}x_{2}) = \begin{pmatrix} 2 & 2 \\ 2 & 12 \end{pmatrix} \\ Y_{f}(l_{1}x_{2}) + \nabla f(l_{1}x_{2}) \begin{pmatrix} x_{1} - l_{1} \\ y_{2} \end{pmatrix} + (x_{1} - l_{1} - y_{2} - 2) \begin{pmatrix} x_{1} - l_{1} \\ y_{2} \end{pmatrix} \\ = 13 + (6, l_{1}x_{1}) \begin{pmatrix} x_{1} - l_{1} \\ y_{2} \end{pmatrix} + (x_{1} - l_{1} - y_{2} - 2) \begin{pmatrix} x_{1} - l_{1} \\ y_{2} \end{pmatrix} \\ = 13 + ((x_{1} - l_{1}) + l_{1}x_{1} + (y_{2} - l_{2}) + (x_{2} - l_{2} - y_{2} - q_{2}) \begin{pmatrix} x_{1} - l_{1} \\ y_{2} - 2 \end{pmatrix} \\ = 13 + ((x_{1} - l_{1}) + l_{2}x_{1} + (y_{2} - l_{2}) + (x_{2} - l_{2} - y_{2} - q_{2}) \begin{pmatrix} x_{1} - l_{2} \\ y_{2} - 2 + l_{2}x_{2} -$$

T(x)= f/p)+ \(\nabla f(p)(x-p) + (x-p) H_f(p) (x-p)