

1. Chain rule

a. dz/dt of the following functions

1. $z = f(x, y) = 4x^2 + 3y^2, x = x(t) = \sin t, y = y(t) = \cos t$

b. 2. $z = f(x, y) = \sqrt{x^2 - y^2}, x = x(t) = e^{2t}, y = y(t) = e^{-t}$

i. 1. $2 \sin t \cos t$
2. $\frac{2e^{6t} + 1}{e^t \sqrt{e^{6t} - 1}}$

2. Chain rule for two variables

a. Calculate partial derivatives using the following functions

b. $z = f(x, y) = 3x^2 - 2xy + y^2, x = x(u, v) = 3u + 2v, y = y(u, v) = 4u - v$

i. $\frac{\partial z}{\partial u} = 38u + 18v$
 $\frac{\partial z}{\partial v} = 18u + 34v$

3. Gradient (partial derivative)

a. Direction of the greatest change of a function (value is the same as partial derivative)

b. Find the gradient of the following function

c. $f(x, y) = x^2 - xy + 3y^2$

i. $\nabla f(x, y) = [2x - y, -x + 6y]$

4. More about Gradient

a. Find the gradient of the following

b. $f(x, y, z) = e^{-2z} \sin 2x \cos 2y$

i. $\nabla f(x, y, z) = 2e^{-2z} \cdot [\cos 2x \cos 2y, -\sin 2x \sin 2y, -\sin 2x \cos 2y]$

5. Directional derivative

a. Let $\theta = \arccos(\frac{3}{5})$, find the directional derivative of

$f(x, y) = x^2 - xy + 3y^2$ In the direction of $v = (\cos \theta, \sin \theta)$

i. Partial derivative of f is $[2x - y, -x + 6y]$
 $\nabla_v f(x, y) = (2x - y)\frac{3}{5} + (-x + 6y)\frac{4}{5} = \frac{2x + 21y}{5}$

6. Gradient of a least-square loss in a linear model

- a. Consider the linear model $y = X \cdot \theta$ where θ is a parameter vector of length D , X is an n by D input feature matrix and y are the corresponding observations of length n

- b. Optimizing such a model can be considered as solving $\min_{\theta \in \mathbb{R}^D} (||y - X \cdot \theta||^2)$

- c. This can be solved by computing the gradient of $L = ||e||^2$, $e = y - X \cdot \theta$

$$\frac{\partial L}{\partial e} = 2e^T \qquad \frac{\partial e}{\partial \theta} = -X$$

$$\frac{\partial L}{\partial \theta} = \frac{\partial L}{\partial e} \frac{\partial e}{\partial \theta} = -2(y^T - \theta^T X^T) X$$

d.

- e. Solving derivative equals 0 is sufficient to minimize the loss since the Hessian of L equals $X^T X$ is PSD