

Vector Calculus (cont.)

1. Parallelogram of maximum area

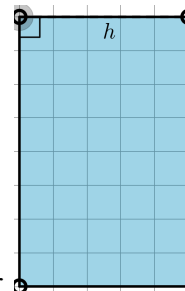
- a. Find parallelogram of maximum area with a given perimeter

$$\begin{array}{l} \max_{a,b,h} ah \\ 2a + 2b = \ell \\ h \leq b \\ a, b, h \geq 0 \end{array}$$

b.

- c. Clearly, given
- $a, b, h = b$
- is an obvious solution

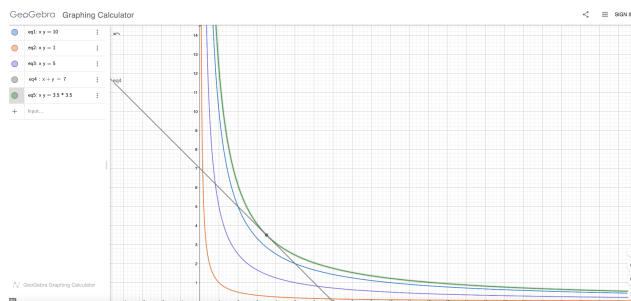
- d. Thus, we get the following equivalent problem:



- e. Find parallelogram of maximum area with a given perimeter

$$\begin{array}{l} \max_{a,b} ab \\ 2a + 2b = \ell \\ a, b \geq 0 \end{array}$$

f.

2. Optimal solution $a = b = \ell / 4$ ($h = b$)

a.

3. Transportation problem

- a. Minimize the cost of goods transported from

i. A set of m sources to... a set of n destinations

ii. Subject to the supply and demand of the sources and destination respectively

b. Given

i. a_1, \dots, a_m : units to transfer from sources

ii. b_1, \dots, b_n : units to receive by destinations

iii. c_{ij} : cost of transferring a unit from source i to destination j

c. Find the quantities x_{ij} to be transferred from source i to destination j for $i = 1, \dots, m$
 $j = 1, \dots, n$

$$\begin{aligned} \min \quad & \sum_{i=1}^m \sum_{j=1}^n c_{ij} x_{ij} \\ & \sum_{j=1}^n x_{ij} = a_i, \quad i = 1, \dots, m \\ & \sum_{i=1}^m x_{ij} = b_j, \quad j = 1, \dots, n \\ & x_{ij} \geq 0 \end{aligned}$$

i.

Lec 23

$$f: \mathbb{R}^n \rightarrow \mathbb{R} \quad (\nabla f)^{1 \times n}$$

$$f: \mathbb{R}^n \rightarrow \mathbb{R}^{n^2} \quad (\nabla f)^{n^2 \times n}$$

input output

$$f(x) = x x^T \quad x \in \mathbb{R}^n$$

$$f: \mathbb{R}^n \rightarrow \mathbb{R}^{n \times n}$$

n^2 elements

$$f(x_1, \dots, x_n) = f(x) = \begin{bmatrix} x_1^2 & x_1 x_2 & \dots & x_1 x_n \\ x_2 x_1 & x_2^2 & \dots & x_2 x_n \\ \vdots & \vdots & \ddots & \vdots \\ x_n x_1 & x_n x_2 & \dots & x_n^2 \end{bmatrix}$$

$$f(x_1+h, \dots, x_n) = \begin{bmatrix} (x_1+h)^2 & \dots & (x_1+h)x_n \\ \vdots & & \vdots \\ (x_n+h)x_1 & \dots & (x_n+h)^2 \end{bmatrix} \rightarrow \text{first row changes}$$

first column changes

$$\lim_{h \rightarrow 0} \frac{f(x_1+h, \dots, x_n) - f(x_1, \dots, x_n)}{h} = \lim_{h \rightarrow 0} \frac{1}{h} \begin{bmatrix} (x_1+h)^2 - x_1^2 & h x_2 & \dots & h x_n \\ \vdots & 0 & \dots & 0 \\ h x_1 & \dots & \dots & 0 \end{bmatrix}$$

$$= \lim_{h \rightarrow 0} \begin{bmatrix} \frac{(x_1+h)^2 - x_1^2}{h} & x_2 & \dots & x_n \\ \vdots & 0 & \dots & 0 \\ x_1 & \dots & \dots & 0 \end{bmatrix}$$

$$\nabla f = \left[\frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n} \right]$$

→ find x that minimizes the function

$\min f(x)$ subject to $x \in Q$

$f: \mathbb{R}^n \rightarrow \mathbb{R}$, $Q \subseteq \mathbb{R}^n$

↳ subspace of \mathbb{R}^n

* minimizing = $-\max(-f(x))$

Case I $Q = \mathbb{R}^n$

unconstrained

Case II $Q \subset \mathbb{R}^n$

constrained

ex) $f: \mathbb{R}^2 \rightarrow \mathbb{R}$

$$\min 6(x_1 - x_2)^2 + (x_1 + x_2)^2$$

such that $x_1 \geq 2x_2$

$$x_1^3 + x_2^3 - 2x_1x_2 = 0$$

Global min

x^* is global minimum of f on Q if $f(x^*) \leq f(x) \forall x \in Q$

Strict global min

$$f(x^*) < f(x) \quad \forall x \in Q \setminus \{x^*\}$$

Local min

$\exists \epsilon > 0$ such that $\forall x \|x - x^*\| \leq \epsilon$, $f(x) \geq f(x^*)$

Strict local min

$\exists \epsilon > 0$, such that $\forall x \|x - x^*\| \leq \epsilon$, $f(x) > f(x^*)$

$\min 10 - x \quad x \in [0, 7] \rightarrow Q$

↳ Suppose there exists a minimum $x^* = 7 - \delta$, for some

$$\delta > 0 \quad (x^* \in Q)$$

$$x' = 7 - \frac{\delta}{2} \in Q$$

$$f(x') = 10 - x' = 3 + \frac{\delta}{2}$$

$$f(x^*) = 3 + \delta > f(x')$$

$$f: \mathbb{R}^n \rightarrow \mathbb{R}$$

x^* to be a local minimum is $\nabla f(x^*) = 0$

Proof

Suppose x^* is a local min $\nabla f(x^*) \neq 0$

$$x(a) = x^* - a \nabla f(x^*), a > 0$$

$$\begin{aligned} f(x(a)) &= f(x^*) + (\nabla f(x^*))^T (-x^* + x(a)) \\ &= f(x^*) + \nabla f(x^*)^T (x^* - a(\nabla f(x^*))^T - x^*) \\ &= f(x^*) - a(\nabla f(x^*))^T (\nabla f(x^*)) \\ &= f(x^*) - a \|\nabla f(x^*)\|_2^2 < f(x^*) \end{aligned}$$

↳ contradiction

$$S = \{x \in \mathbb{Q} : \nabla f(x) = 0\}$$

is the set of stationary points

If f is continuous and twice differentiable, for any local minimum $x^* : \nabla f(x^*) = 0$, $y^T H_f(x^*) y \geq 0$

$$\forall y \in \mathbb{R}^n$$

$H_f(x^*)$ is positive semidefinite



eigenvalues ≥ 0

$$\text{Let } A = \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$A \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} = 0 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$A \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$y^T A y = \begin{bmatrix} y_1 & y_2 \end{bmatrix} \begin{bmatrix} y_1 - y_2 \\ -y_1 + y_2 \end{bmatrix}$$

$$= y_1(y_1 - y_2) + y_2(-y_1 + y_2)$$

$$= (y_1 - y_2)^2 \quad \forall y$$

$$f(x_1, x_2) = 3(x_1 - x_2)^2 + (x_1 + x_2)^3$$

$$\nabla f(x) = 0 \Rightarrow \begin{bmatrix} \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} \end{bmatrix} = 0$$

$$\frac{\partial f}{\partial x_1} = 6(x_1 - x_2) + 3(x_1 + x_2)^2$$

$$\frac{\partial f}{\partial x_2} = -6(x_1 - x_2) + 3(x_1 + x_2)^2$$

$$x^* = \begin{bmatrix} 0 \\ 0 \end{bmatrix} (\nabla f(x^*) = 0)$$

$$H_f(x) = \begin{bmatrix} 6 + 6(x_1 + x_2) & -6 + 6(x_1 + x_2) \\ -6 + 6(x_1 + x_2) & 6 + 6(x_1 + x_2) \end{bmatrix}$$

$$\frac{\partial^2 f}{\partial x_1^2} = 6 + 6(x_1 + x_2)$$

$$\frac{\partial^2 f}{\partial x_1 \partial x_2} = -6 + 6(x_1 + x_2)$$

$$\frac{\partial^2 f}{\partial x_2^2} = 6 + 6(x_1 + x_2)$$