

# **ABOUT THIS WEBINAR**

### Goal

Introduce viewers to performance optimization using NVIDIA Nsight Systems

### **Target Audience**

Beginner and advanced users of GPU

### Software

NVIDIA Nsight Systems 2018.3.1.

Download from <a href="http://developer.nvidia.com/nsight-systems">http://developer.nvidia.com/nsight-systems</a>



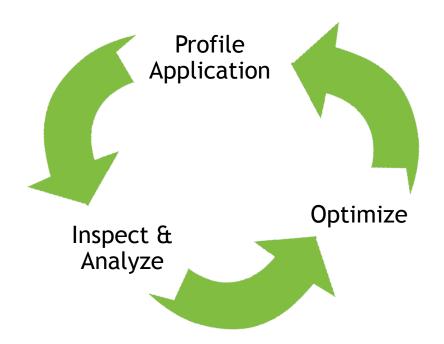
# **AGENDA**

- Introduction to Nsight Systems
- Features
- Report navigation demo
- Case studies
- Common optimization opportunities
- Tools comparison
- Beyond Nsight Systems





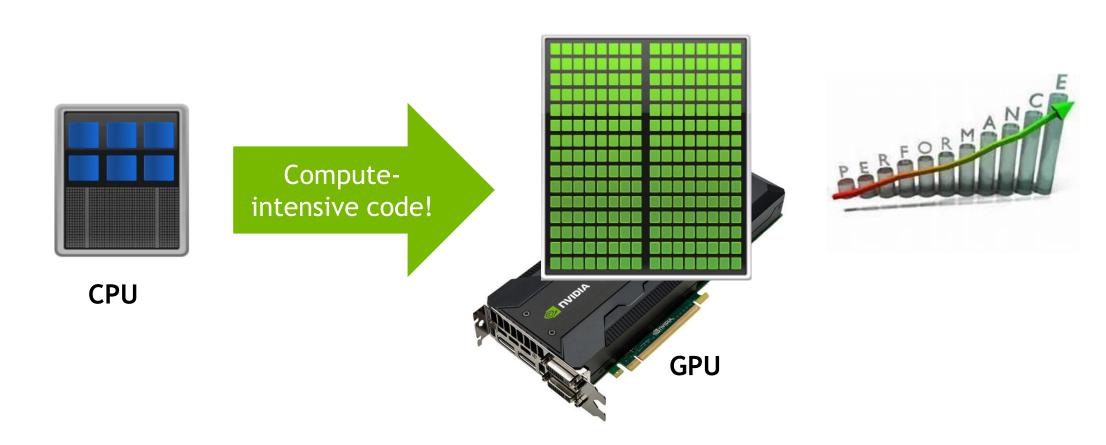
# TYPICAL OPTIMIZATION WORKFLOW



Iterative process continues until desired performance is achieved



# **ACCELERATED PERFORMANCE WITH GPU**



# INTRODUCING NSIGHT SYSTEMS

### System-wide Performance Analysis Tool

Focus on the application's algorithm - a unique perspective

Scale your application efficiently across any number of CPUs & GPUs



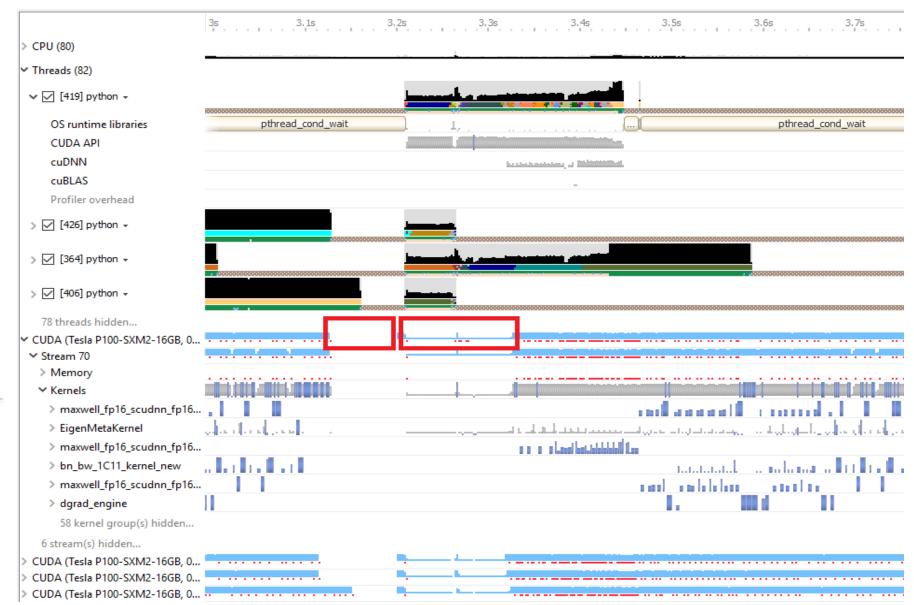
# **NSIGHT SYSTEMS**

### Maximize your GPU investment

- Balance your workload across multiple CPUs and GPUs
- Find the right optimization opportunities
- Improve application's performance
- Support for Linux & Windows



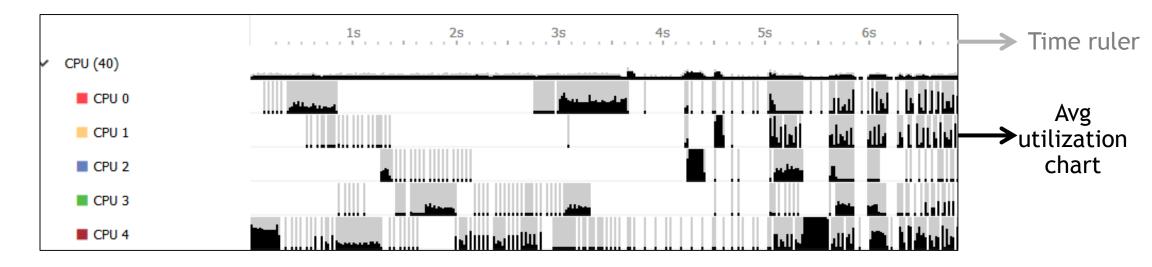






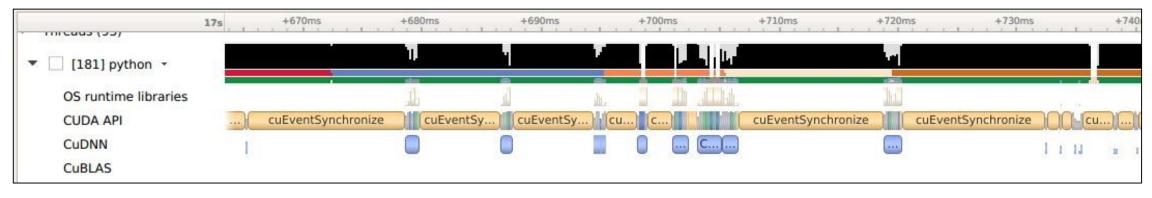
### CPU CORES WORKLOAD

- See CPU core utilization by application's threads
- Locate idle time on CPU cores



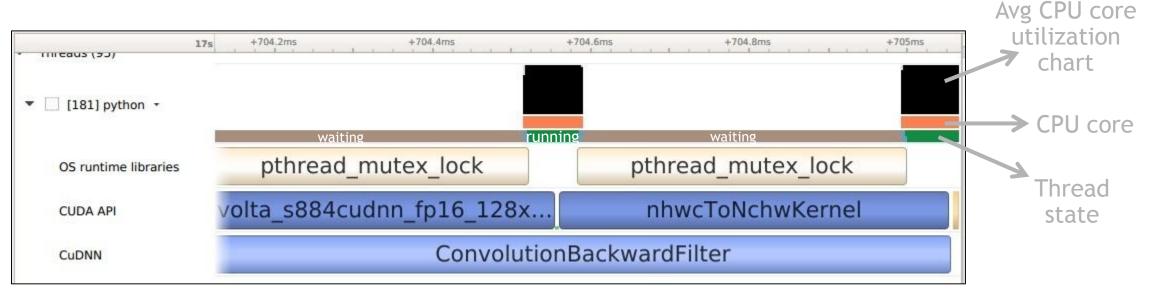
# **THREADS**

- Get an overview of each thread's activities
  - OS runtime libraries usage
- API usage: CUDA, CuDNN, CuBLAS, OpenACC, OpenGL, DX12 (More to come!)



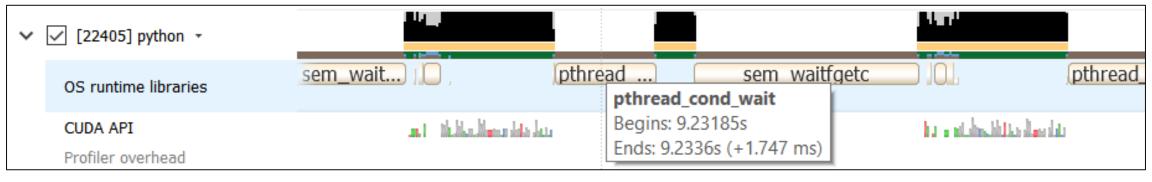
# **THREADS**

- Get an overview of each thread's activities
  - OS runtime libraries usage
- API usage: CUDA, CuDNN, CuBLAS, OpenACC, OpenGL, DX12 (More to come!)



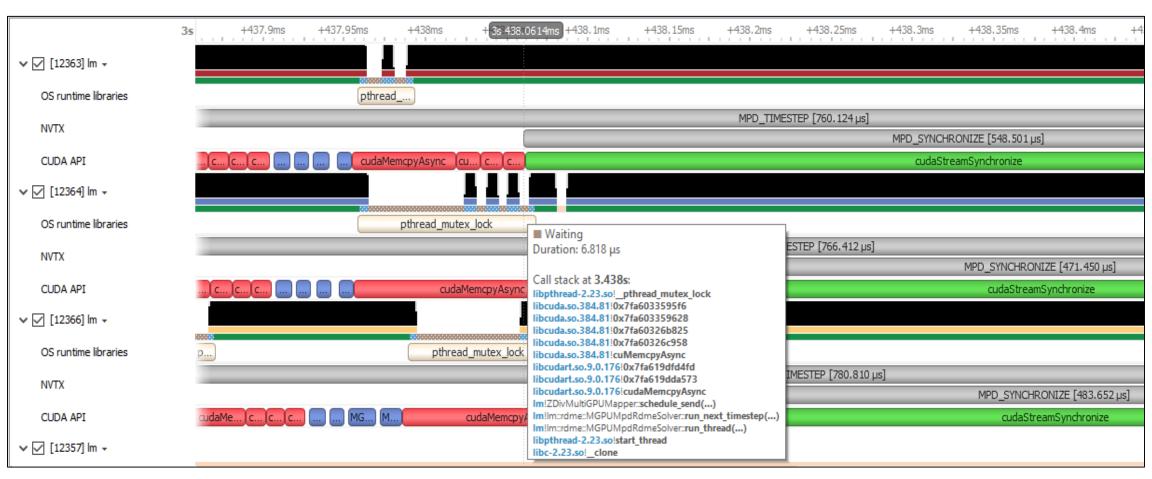
# OS RUNTIME LIBRARIES

- Identify time periods where threads are blocked
- See the block reason
- Locate redundant synchronizations



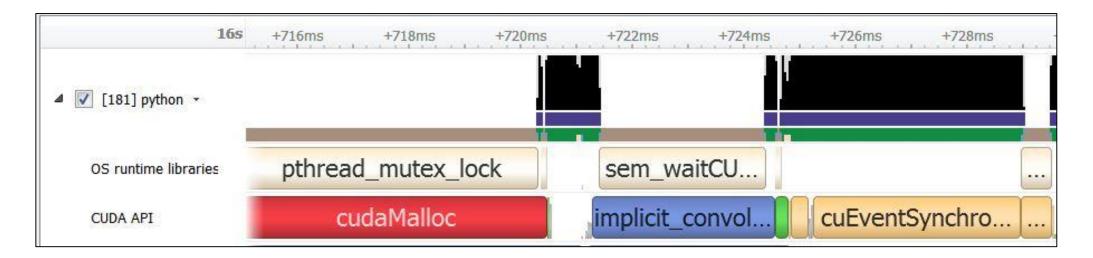
### OS RUNTIME LIBRARIES

### Backtrace for time-consuming calls to OS runtime libs



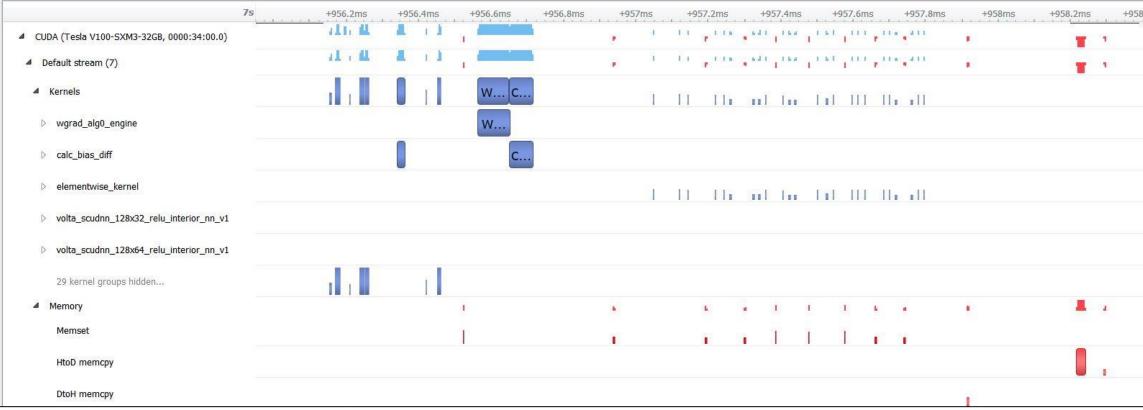
# **CUDA API**

- Trace CUDA API Calls on OS thread
- See when kernels are dispatched
- See when memory operations are initiated
- Locate the corresponding CUDA workload on GPU



# **GPU WORKLOAD**

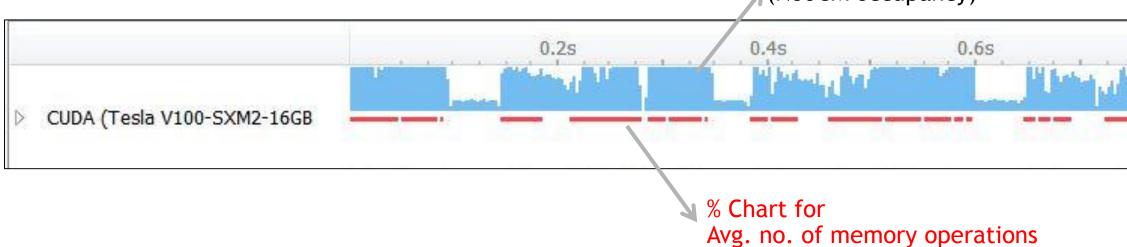
- See CUDA workloads execution time
- Locate idle GPU times



# **GPU WORKLOAD**

- See trace of GPU activity
- Locate idle GPU times

% Chart for Avg. CUDA kernel coverage (Not SM occupancy)



# **GPU WORKLOAD**

- See trace of GPU activity
- Locate idle GPU times



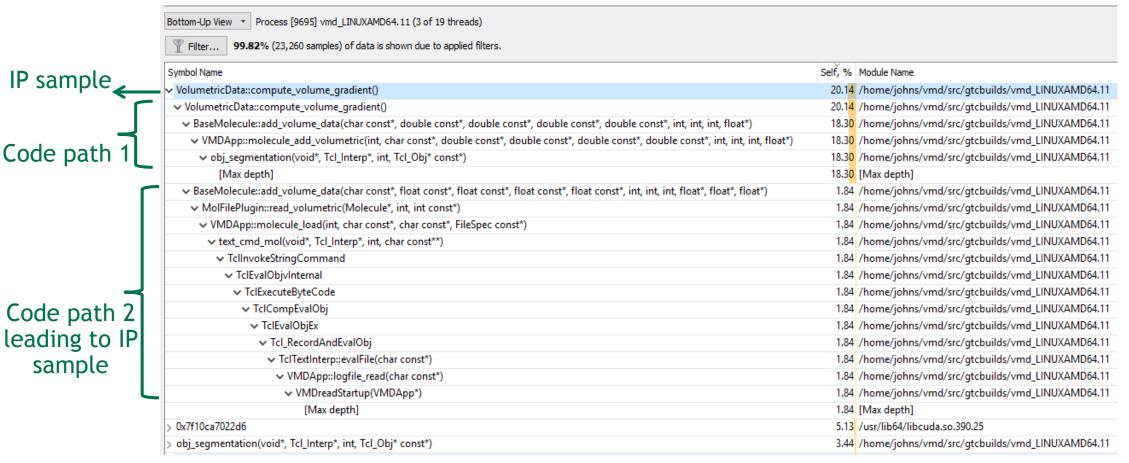
GPU utilization level of detail shows valleys for sparse kernel time coverage

# CORRELATION TIES API TO GPU WORKLOAD



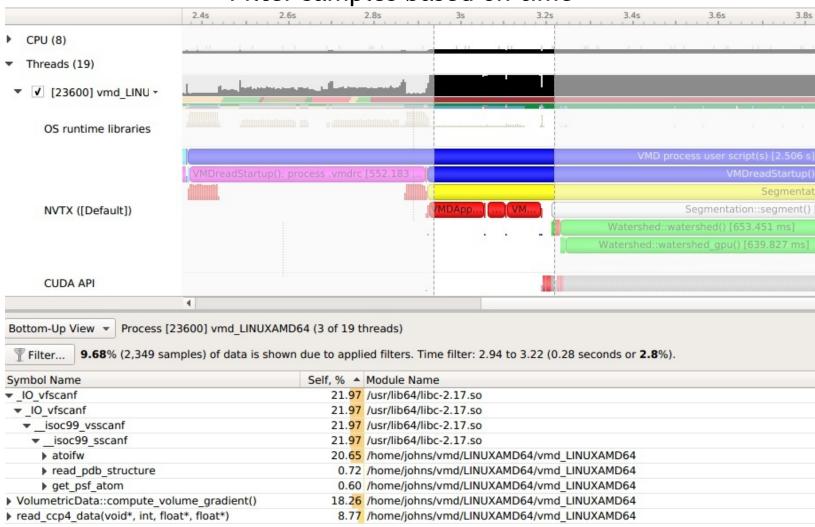
# STATISTICAL SAMPLING

### Periodic sampling of thread's callstack



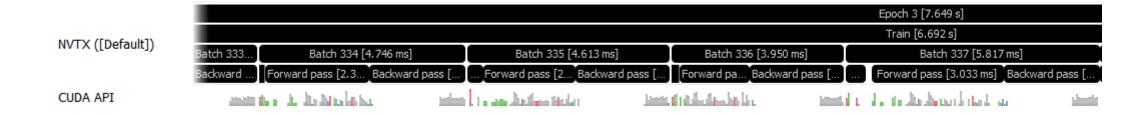
# STATISTICAL SAMPLING

### Filter samples based on time



# **NVTX INSTRUMENTATION**

- NVIDIA Tools Extension (<u>NVTX</u>) to annotate the timeline with application's logic
- Helps understand the profiler's output in app's algorithmic context



### FEATURES SUMMARY

### **User Instrumentation**

NVidia Tools eXtension - aka NVTX

### OS threads timeline with API Tracing

OS runtime, CUDA, CuDNN, CuBLAS, OpenACC, OpenGL

Correlate with GPU workloads

### **Backtrace Collection**

Sampled IPs

Blocked state

# **GUI**





This Photo by Unknown Author is licensed under CC BY-SA-NC

- Fast
- Visualize millions of events
- Incredible level of detail

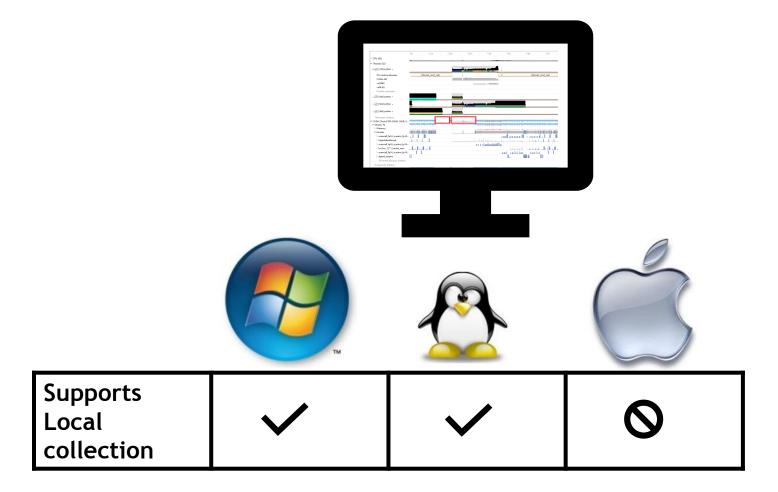
# DATA COLLECTION (GUI)



This Photo by Unknown Author is licensed under CC BY-SA-NC

Host-Target Remote Collection

# DATA COLLECTION (GUI)



# DATA COLLECTION (CLI)





Command Line Interface No connection! Import later

CLI enables easy collection on servers and in containers

# REPORT NAVIGATION DEMO

**Outstanding** Interactive Performance and Level of Detail Available

# **CASE STUDY 1: SIMPLE DNN TRAINING**

# **DATA SET**

### The MNIST database

A database of handwritten digits

Will be used for training a DNN that recognizes handwritten digits



### SIMPLE TRAINING PROGRAM

- A simple DNN training program from <a href="https://github.com/pytorch/examples/tree/master/mnist">https://github.com/pytorch/examples/tree/master/mnist</a>
- Uses PyTorch, accelerated using a Volta GPU
- Training is done in batches and epochs
  - 1. Data is copied to the device
  - 2. Forward pass
  - 3. Backward pass

# SIMPLE TRAINING PROGRAM

```
def train(args, model, device, train loader, optimizer, epoch):
   model.train()
   for batch idx, (data, target) in enumerate(train loader):
       optimizer.zero_grad()
      output = model(data)
                                     Forward pass
      loss = F.nll_loss(output, target)_
      loss.backward()
optimizer.step()
Backward pass
       if batch_idx % args.log_interval == 0:
          print('Train Epoch: {} [{}/{} ({:.0f}%)]\tLoss: {:.6f}'.format(
              epoch, batch_idx * len(data), len(train_loader.dataset),
              100. * batch idx / len(train loader), loss.item()))
```

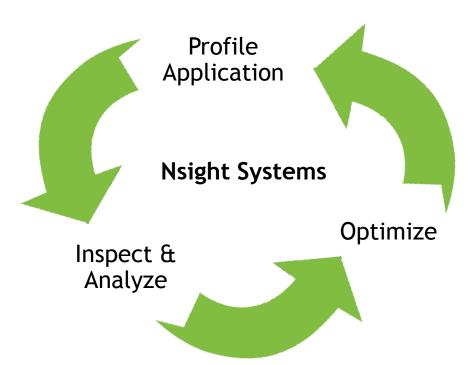
### TRAINING PERFORMANCE

Execution time

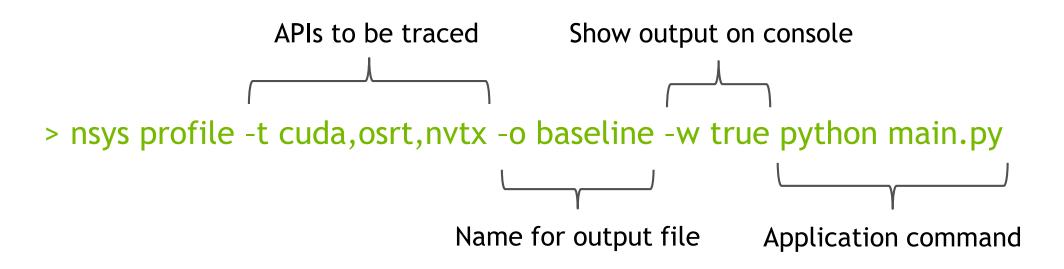
> python main.py

Takes 89 seconds on a Quadro Volta GPU

# **OPTIMIZATION WORKFLOW**

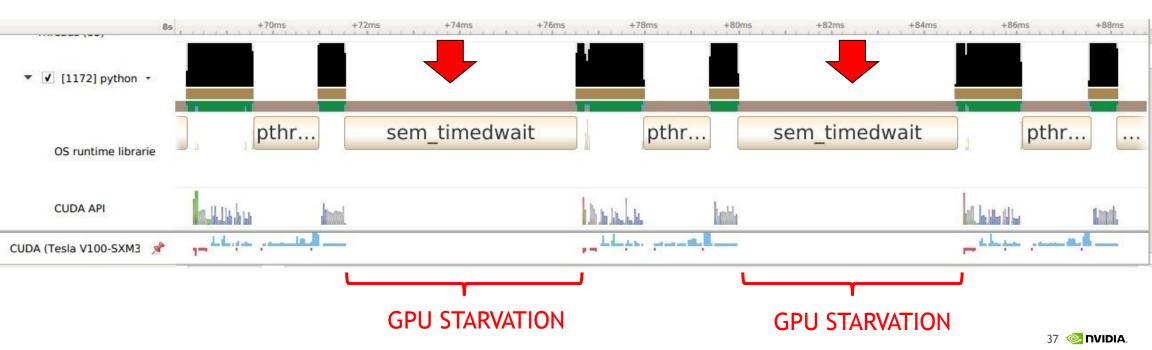


# STEP 1: PROFILE



# **BASELINE PROFILE**

- Training time = 89 seconds
- CPU waits on a semaphore and starves the GPU!

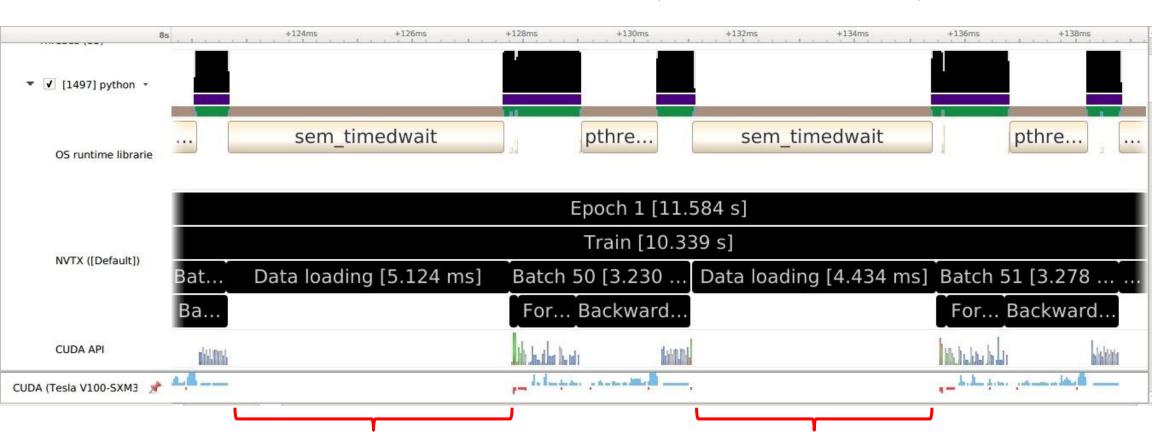


#### **NVTX ANNOTATIONS**

Add NVTX to annotate the timeline with application logic

```
def train(args, model, device, train loader, optimizer, epoch):
    model.train()
    for batch idx, (data, target) in enumerate(train loader):
        nvtx.range push("Batch " + str(batch idx))
        nvtx.range push("Copy to device")
        data, target = data.to(device), target.to(device)
        nvtx.range pop()
        nvtx.range push("Forward pass")
        optimizer.zero grad()
        output = model(data)
        loss = F.nll loss(output, target)
        nvtx.range pop()
```

# **BASELINE PROFILE (WITH NVTX)**



- GPU is idle during data loading
- Data is loaded using a single thread. This starves the GPU!



## **OPTIMIZE SOURCE CODE**

Data loader was configured to use 1 worker thread:

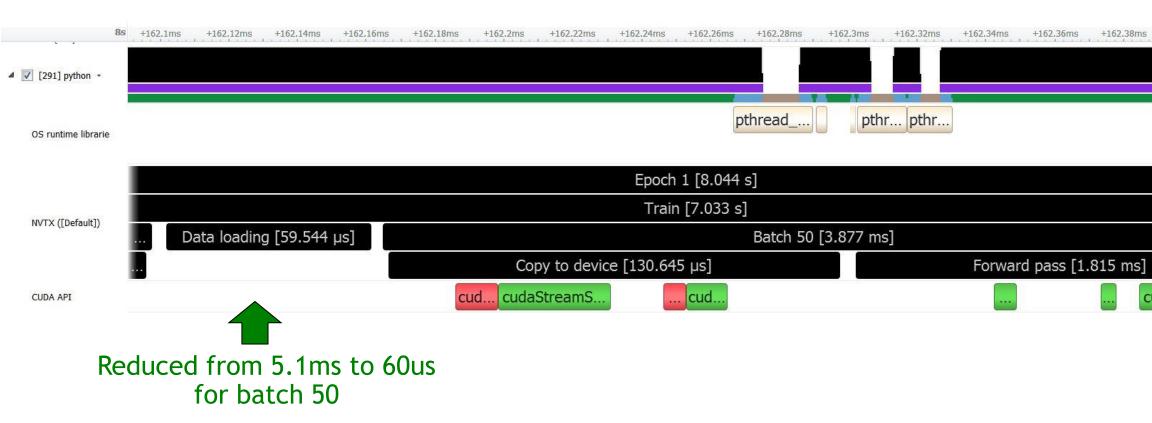
```
kwargs = {'num_workers': 1, 'pin_memory': True} if use_cuda else {}
```

Let's switch to using 8 worker threads:

```
kwargs = {'num_workers': 8, 'pin_memory': True} if use_cuda else {}
```

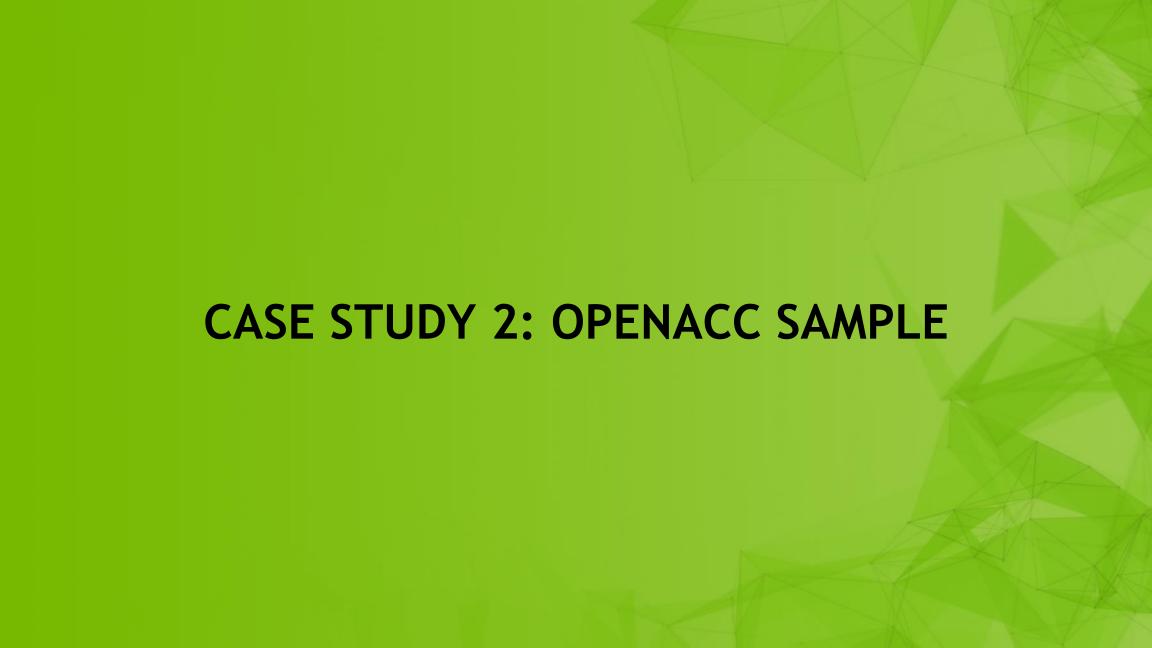


Time for data loading reduced for each batch





4.2x speedup on Tesla V100 GPU!



#### **OPENACC SAMPLE**

- Sample from <a href="https://devblogs.nvidia.com/getting-started-openacc">https://devblogs.nvidia.com/getting-started-openacc</a>
- Solves 2-D Laplace equation with iterative Jacobi solver
- Each iteration
  - 1. A stencil calculation
  - 2. Update the matrix
  - 3. Check if error tolerance is met. If not, go to step 1.

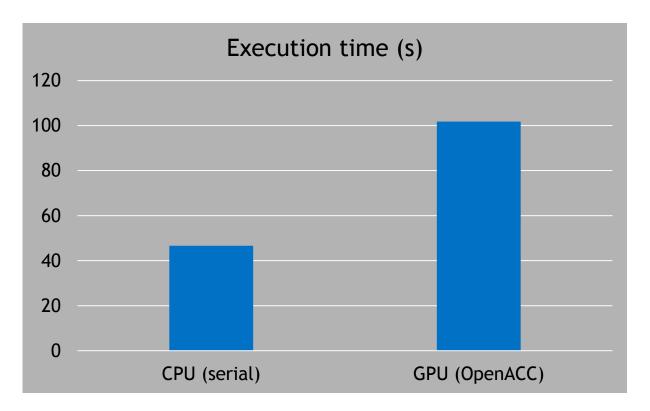
# SAMPLE (CPU VERSION)

```
while ( error > tol && iter < iter_max ) { ────Convergence loop
  error = 0.0;
  for( int j = 1; j < n-1; j++) {
    for( int i = 1; i < m-1; i++ ) {
      Anew[j][i] = 0.25 * (A[j][i+1] + A[j][i-1] +
                                                               -Stencil calculation
                              A[j-1][i] + A[j+1][i]);
      error = fmax( error, fabs(Anew[j][i] - A[j][i]));
  for( int j = 1; j < n-1; j++) {
    for( int i = 1; i < m-1; i++ ) {
   A[j][i] = Anew[j][i];</pre>
  iter++;
```

#### **OPENACC SAMPLE**

```
while ( error > tol && iter < iter_max ) { ────Convergence loop
  error = 0.0;
  #pragma acc kernels
    for( int j = 1; j < n-1; j++) {
      for( int i = 1; i < m-1; i++ ) {
                                                                - Stencil calculation
        Anew[j][i] = ...
        error = fmax( error, fabs(Anew[j][i] - A[j][i]));
    for( int j = 1; j < n-1; j++) {
      for( int i = 1; i < m-1; i++ ) {
    Δ[i][i] = Anew[i][i];
        A[j][i] = Anew[j][i];
  iter++;
```

## **PERFORMANCE**

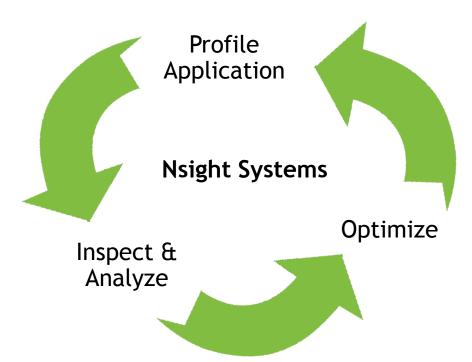


Execution time for 1000 iterations on a system with: Intel® Core™ i7-6850K CPU NVIDIA TITAN X (Pascal) GPU

That is unexpected!



# **OPTIMIZATION WORKFLOW**



## **BASELINE PROFILE**



#### **OPENACC SAMPLE**

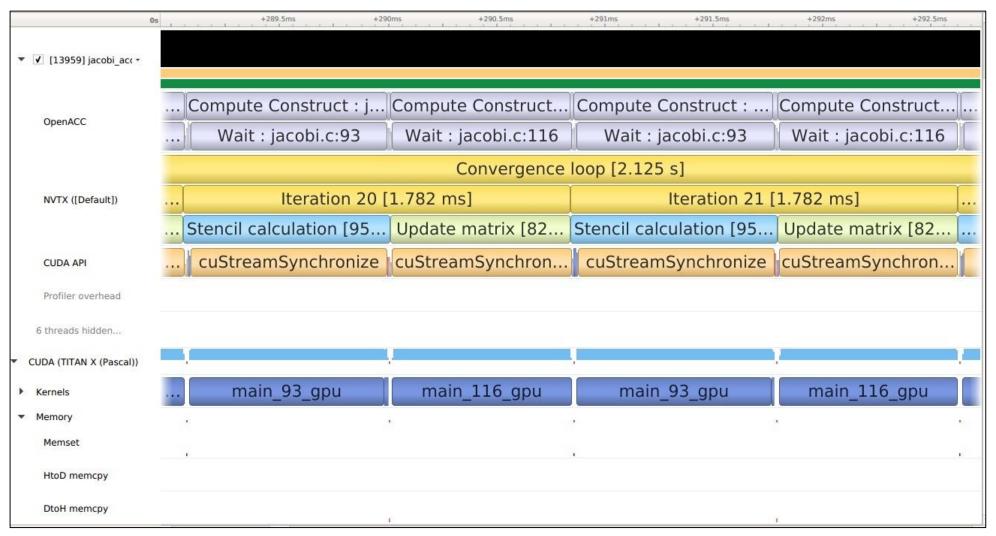
```
while ( error > tol && iter < iter_max ) { ────Convergence loop
  error = 0.0;
  #pragma acc kernels
    for( int j = 1; j < n-1; j++) {
      for( int i = 1; i < m-1; i++ ) {
                                                                - Stencil calculation
        Anew[j][i] = ...
        error = fmax( error, fabs(Anew[j][i] - A[j][i]));
    for( int j = 1; j < n-1; j++) {
      for( int i = 1; i < m-1; i++ ) {
    Δ[i][i] = Anew[i][i];
        A[j][i] = Anew[j][i];
  iter++;
```

#### **OPENACC SAMPLE**

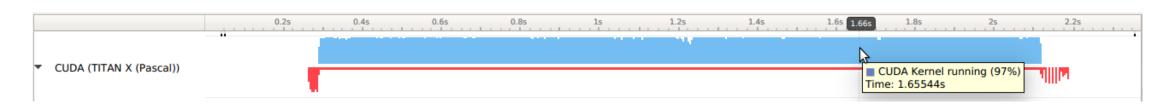
```
#pragma acc data copy(A) create(Anew)
while ( error > tol && iter < iter_max ) { ─────Convergence loop
  error = 0.0;
  #pragma acc kernels
    for( int j = 1; j < n-1; j++) {
      for( int i = 1; i < m-1; i++ ) {

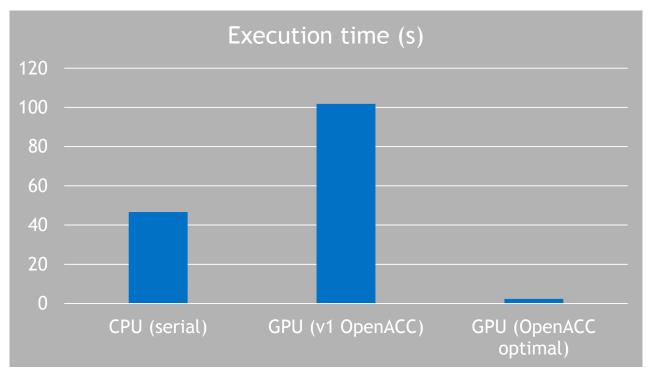
    Stencil calculation

        Anew[j][i] = ...
        error = fmax( error, fabs(Anew[j][i] - A[j][i]));
    for( int j = 1; j < n-1; j++) {
      for( int i = 1; i < m-1; i++ ) {
        A[j][i] = Anew[j][i];
  iter++;
```



#### CUDA kernel coverage on GPU is ~97%





Execution time for 1000 iterations on a system with: Intel® Core™ i7-6850K CPU NVIDIA TITAN X (Pascal) GPU

44x speedup!

## **COMMON OPTIMIZATION OPPORTUNITIES**

#### ► <u>CPU</u>

- Thread synchronization
- Algorithm bottlenecks starve the GPUs (case study 1)

#### Multi GPU

- Communication between GPUs
- Lack of Stream Overlap in memory management, kernel execution

#### Single GPU

- Memory operations blocking, serial, unnecessary (case study 2)
- Too much synchronization device, context, stream, default stream, implicit
- CPU GPU Overlap avoid excessive communication

#### COMMON OPTIMIZATION OPPORTUNITIES

Blog post

https://devblogs.nvidia.com/nsight-systems-exposes-gpu-optimization

- Watch GTC, San Jose 2018 talk
  - By John Stone of UIUC & Robert Knight of NVIDIA
  - 3.2x-4.1x Speedup Achieved on Visual Molecular Dynamics!

# **TOOLS COMPARISON**

	NVIDIA© Nsight™ Systems	NVIDIA© Nsight™ Compute	NVIDIA© Visual Profiler	Intel© VTune™ Amplifier	Linux perf OProfile
Target OS	Linux, Windows	Linux, Windows	Linux, Mac, Windows	Linux, Windows	Linux
GPUs	Pascal+	Pascal+	Kepler+	None	None
CPUs	x86_64	x86_64	x86, x86_64, Power	x86, x86_64	x86, x86_64, Power
Trace	NVTX, OS runtime, CUDA, CuDNN, CuBLAS, OpenACC, OpenGL, DX12	NVTX, CUDA	MPI, CUDA, OpenACC, NVTX	MPI, ITT	Kernel
CPU PC Sampling	High Speed	No	Yes	High Speed	High Speed
NVLINK, GPU Power, Thermal	Future		Yes	No	No
Src Code View	No	Yes	Yes	Yes	No
Compare Sessions	No	Yes	No	Yes	No

## PROFILING ON BLUEWATERS

#### Nsight Systems requirements:

- GLIBC >= v2.14
  - BlueWaters nodes with x86\_64 CPUs have v2.11, so use a Shifter container with newer OS.
- CPU sampling requires Linux kernel version >= 4.3
  - BlueWaters nodes with x86\_64 CPUs have older kernel. No CPU sampling available.

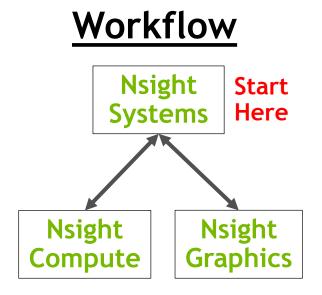
Other requirements in docs

## **NSIGHT PRODUCT FAMILY**

Nsight Systems - System-wide application algorithm tuning

Nsight Compute - Debug/optimize specific CUDA kernel

Nsight Graphics - Debug/optimize specific graphics frame/shader



#### **NSIGHT SYSTEMS**

- Download from <a href="http://developer.nvidia.com/nsight-systems">http://developer.nvidia.com/nsight-systems</a>
- Training
  - Docs at https://docs.nvidia.com/nsight-systems/index.html
  - Blog post
  - GTC, San Jose 2018 <u>talk</u>
  - GTC, Israel 2018 talk
- Questions/Requests/Comments?
  - nsight-systems@nvidia.com
  - Developer Forums

