Mechanical switches are one of the most common interfaces to a uC.

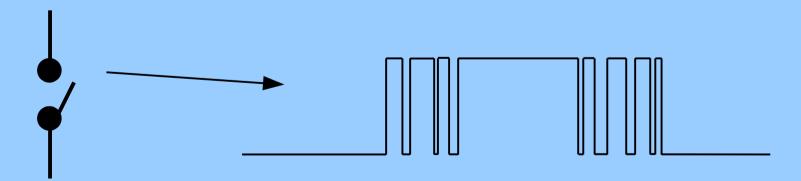
Switch inputs are asynchronous to the uC and are not electrically clean.

Asynchronous inputs can be handled with a *synchronizer* (2 FF's).

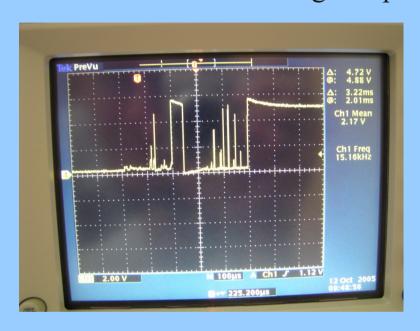
Inputs from a switch are electrically cleansed with a switch debouncer.

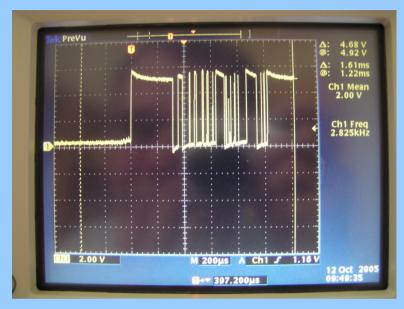
What is switch bounce?

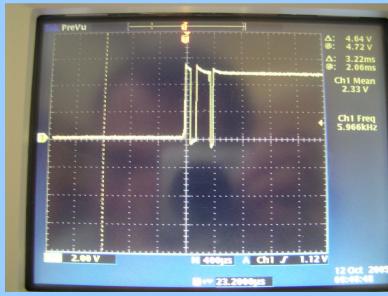
-The non-ideal behavior of the contacts that creates multiple electrical transitions for a single user input.

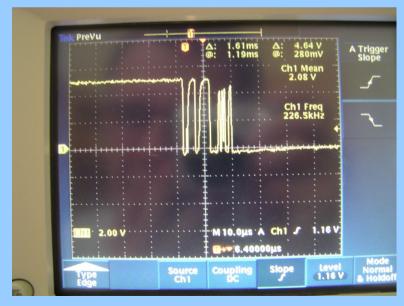


Switch bounce from a single depress/release of mega128 pushbutton switches









The problem is that the uC is usually fast enough to see all the transitions -uC acts on multiple transitions instead of a single one

The oscilloscope traces showed bounce durations of 10-300us

- -our mega128 uC runs at 62.5ns per instruction
- -a 10uS bounce (short) is $(1x10^{-5}/62.5x10^{-9})$ 160 instructions long!
- -a 100uS bounce could be sampled as a valid true or false 100's of times
- -results are incorrect behavior as seen by user

Characteristics of switch bounce:

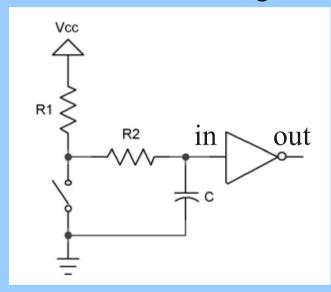
- -nearly all switches do it
- -the duration of bouncing and the period of each bounce varies
- -switches of exactly the same type bounce differently
- -bounce differs depending on user force and speed
- -typical bounce frequency is .1-5ms

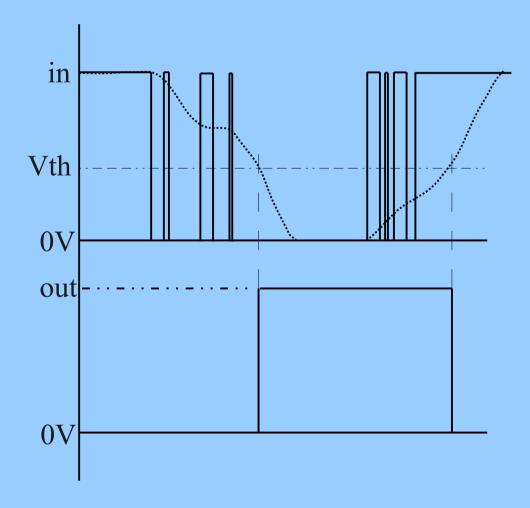
Effective switch debouncing can also reject EMI and static charge effects

- -EMI can be periodic (so don't sample synchronously!)
- -false triggering on static electricity is like a single random input

Solutions

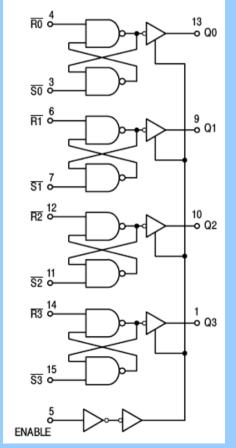
- -Analog filtering
 - -usually an RC delay to filter out the rapid changes in switch output
 - -task is to choose R and C such that the input threshold is not crossed while bouncing is still occurring

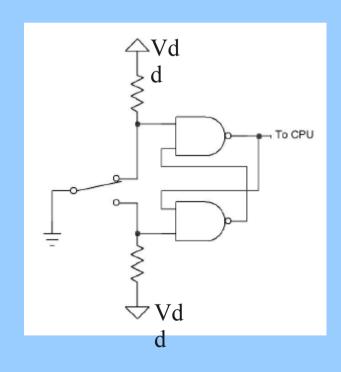




Solutions

- -Cross coupled gates (MC14044)
- -logic gates lock in one transition with a single-pole, double-throw switch
 - -both switch (\$3.69) and chip (\$0.38) are expensive
 - -momenta alial arritches (mega 128 board) are (\$0.12)





Solutions:

- -Software
 - -need to minimize CPU usage
 - -independent of clock speed
 - -do not connect to interrupt pins, only programmed I/O
 - -multiple interrupts will tie up processor
 - -don't scan synchronously to noisy devices
 - -identify initial switch closure quickly (100mS max)

-Two approaches (of many)

-Count based

(identify initial closure AND wait AND check for same value) OR (identify initial closure AND check for same value for X cycles)

risky!

safer!

- -watch for
 - -CPU speed dependencies (use constant defines)
 - -loop execution times (suggesting the use of timer interrupts)
- -Digital filter based
 - -mimics an analog filter with first-order recursive low pass filter
 - -includes a software schmitt trigger
 - -good EMI filtering, quick response

Solutions: -Count based -from Gansel's "Guide to Debouncing" -routine called from timer interrupt or delay loop -check Port D, bit 2, pushbutton depression, (bit will be grounded) -returns "1' only once per button push, "pulsed output" -looks for a falling edge

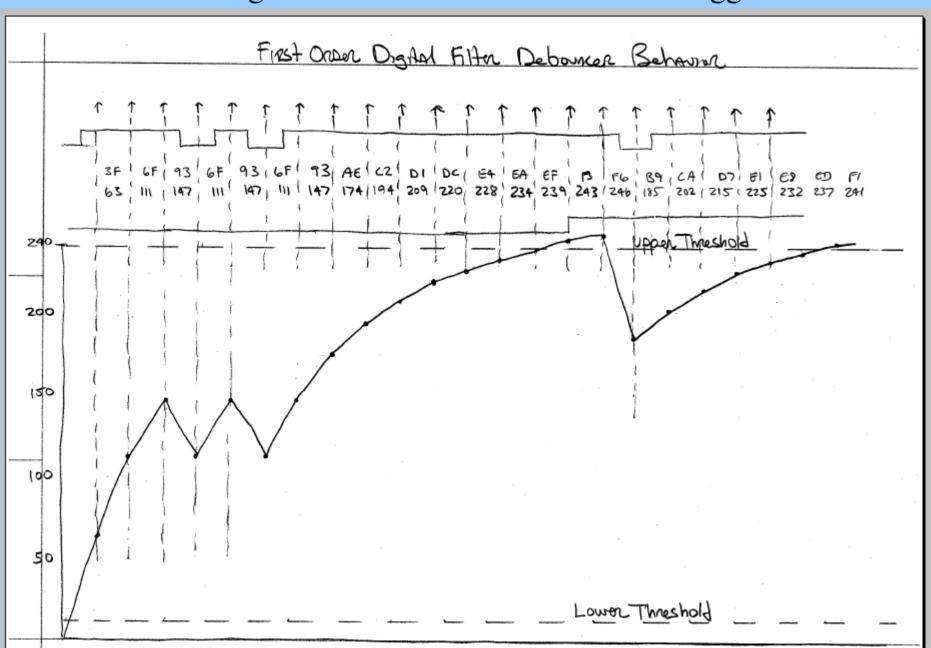
```
int8_t debounce_switch() {
  static uint16_t state = 0; //holds present state
  state = (state << 1) | (! bit_is_clear(PIND, 2)) | 0xE000;
  if (state == 0xF000) return 1;
  return 0;
}</pre>
```

value of state

first pass after reset:	1110	0000	0000	0001	return 0
second pass after reset:	1110	0000	0000	0011	return 0
after 12 false passes:	1111	1111	1111	1111	return 0
after 7 true passes:	1111	1111	1000	0000	return 0
after 12 true passes:	1111	0000	0000	0000	return 1
after many true passes:	1110	0000	0000	0000	return 0
after 5 false passes:	1110	0000	0001	1111	return 0

```
Solutions:
   -Digital filter based
       -acts like analog RC filter followed by schmitt trigger
      -nearly continuous output like an analog circuit
      -0.25 = 0x3F, 0.75 = 0xC0, 1.0 = 0xFF
uint8 t output=0; //external variable indicating switch state
uint8 t debounce switch2() {
  static uint8 t y old=0, flag=0;
  uint8 t temp;
//digital filter part y \text{ old} = x_new*0.25 + y_old*0.75
  temp = (y old >> 2); //this gives y old/4
 y old = y old - temp; //do (y old*0.75) by subtraction
//if button is pushed, add 0.25 (3F) of new value (1.0)
  if(bit is clear(PIND, 2)){y old = y old + 0x3F;} //
//software schmitt trigger
  if((y old > 0xF0)&&(flag==0)){flag=1; output=1;}
  if((y old < 0x0F)&&(flag==1)){flag=0; output=0;}
```

Behavior of the digital filter debounce with schmitt trigger



Using Others Code

I just showed you several code snippets that you can use.

You should understand how they work.

You may (wink, wink) probably be tested on them in the future.

I offer other pieces of code in the coming weeks.

Learn what they do before you use them.

In general, don't use code from somewhere else without knowing how it works.

An exception would be a well used, well tested library of functions (libc).

Types of debouncer output

Sometimes we want a *continuous* output, e.g., organ keyboard.

Other times we want a *pulsed* output, e.g. increment hour alarm.

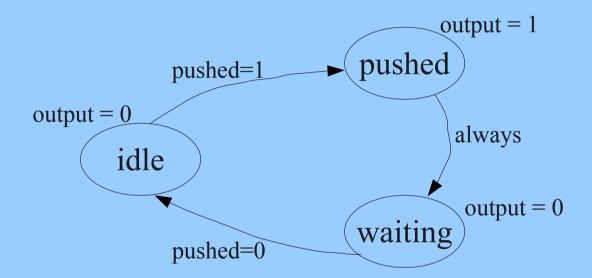
The first counting algorithm (Gansel) gives a pulsed output.

The digital filter algorithm gives a continuous output.

button push	
pulsed output	
continuous output	

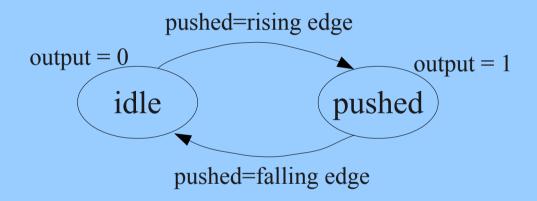
Converting between types of debouncer output

To get a pulsed output, from a continuous debouncer:



Converting between types of debouncer output

To get a *continuous* output, from a pulsed output:



Note that this requires sensing rising and falling edges.