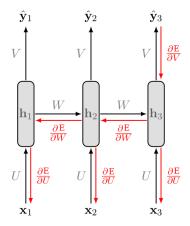
Scalable Machine Learning and Deep Learning - Review Questions 4

Deadline: December 1, 2019

- 1. What's the vanishing problem in RNN?
- 2. Explain the impact of different gates in LSTM?
- 3. Assume the error of the following network is $E = E^{(1)} + E^{(2)}$, then compute the $\frac{\partial E}{\partial n}$.



- 4. Assume we have a stacked autoencoder with three hidden layers h_1 , h_2 , and h_3 , in which each layer applies the following functions respectively, $h_1 = f_1(\mathbf{x})$, $h_2 = f_2(h_1)$, and $h_3 = f_3(h_2)$, and the output of the network will be $\mathbf{y} = f_4(h_3)$. Do you think if it is a good autoencoder if it generates $f_4(f_3(f_2(f_1(\mathbf{x})))) = \mathbf{x}$ for all input instances \mathbf{x} . How can we improve it?
- 5. How does Gibbs sampling work? When do we need to use Gibbs sampling?
- 6. How do you tie weights in a stacked autoencoder? What is the point of doing so?