Package 'seqMC'

June 10, 2017

| Title Sequential Mont | e Carlo | | | | |
|--|---|--|----------------------|---|--|
| Version 0.0.1 | | | | | |
| Description Sequential Monte Carlo for nonlinear/non-Gaussian state-space models. Implementation is based on the Gordon, Salmond and Smith (1993) Novel approach to nonlinear or non-Gaussian Bayesian state estimation Depends R (>= 3.4.0) License Apache License, Version 2.0 Encoding UTF-8 LazyData true | | | | | |
| | | | RoxygenNote 6.0.1 | | |
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| seqMC | Sequential Monte Carlo | | | | |
| Description | | | | | |
| Sequential Monte | Carlo | | | | |
| Usage | | | | | |
| <pre>seqMC(f, prob_y "bootstrap"))</pre> | <pre>v_given_x, x0, y, sample_method = c("systematic", "residual",</pre> | | | | |
| Arguments | | | | | |
| f | function, when called with parameter t (time point) and x_t (state vector at time t), it would return x_t+1 | | | | |
| prob_y_given_x | function, when called with parameter t (time point), y_t (observation vector at time t) and x_t (state vector at time t), it would return the conditional probability/density: $Prob(y_t \mid x_t)$ | | | | |

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| x0 | matrix of N cols, sample of state vector at time 0, one sample vector per col, N is the number of samples. |
|---------------|--|
| У | matrix of T cols, observations, col 1 is observation at time 1, col 2 is observation at time 2, etc. T is the number of time points. |
| sample_method | character, specify sample method in the resample stage. Default systematic, means "systematic resampling". |

Value

sample from posterior distribution of state vectors, a 3D array, with dimension of d x N x T, where d is the length of a state vector, N is the number of samples, T is the number of time steps.

Examples

```
f <- function(t, x) {</pre>
0.5 * x + 25 * x / (1 + x * x) + 8.0 * cos(1.2 * (t-1)) + rnorm(length(x), sd=sqrt(10.0))
prob_y_given_x <- function(t, y, x) {</pre>
as.numeric(dnorm(y - x * x / 20.0))
### simulate true path ###
T = 50
x = rep(0.0, T+1)
for (t in 1:T) {
x[t+1] = f(t, x[t])
x = x[-1]
y = x * x / 20 + rnorm(length(x))
\#\#\# estimate the posterior of state vector \#\#\#\#
N = 4000
x0 = matrix(rnorm(N, sd=sqrt(2)), nrow=1, ncol=N)
xhat = seqMC(f, prob_y\_given_x, x0, matrix(y, nrow=1))
xhat_mean = apply(xhat, 3, mean)
alpha = 0.05
xhat_ci_lower = apply(xhat, 3, quantile, probs=alpha/2)
xhat_ci_upper = apply(xhat, 3, quantile, probs=1-alpha/2)
plot(x[-1], ylim=c(-40, 40), pch='*')
lines(xhat_ci_lower, lty='dotted')
lines(xhat_mean)
lines(xhat_ci_upper, lty='dotted')
```

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