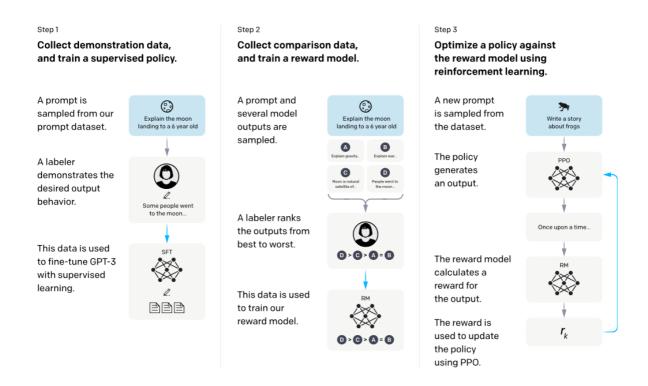
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Training language models to follow instructions with human feedback (2022) 187

Goal: align language models with user intent

- 1. collect a dataset of labeler demonstrations of the desired model behavior, which we use to fine-tune GPT-3 using supervised learning
- 2. collect a dataset of **rankings** of model outputs, which we use to further fine-tune this supervised model using reinforcement learning from human feedback

Result: improvements in truthfulness and reductions in toxic output generation



Step 1: human data → supervised fine-tuning (SFT)

Step 2: model outputs \rightarrow reward modeling (RM)

Step 3: model after SFT + RM rewards → reinforcement learning (RL)

Reward modeling (RM): ranking ightarrow score pairwise ranking loss for K responses

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$$ext{loss}(heta) = -rac{1}{{k \choose 2}} E_{x,y_w,y_l \sim D} \left[\log(\sigma(r_{ heta}(x,y_w)) - r_{ heta}(x,y_l))
ight]$$

where $r_{\theta}(x, y)$ is the scalar output of the reward model for prompt x and completion y with parameters θ , y_w is the preferred completion out of the pair of y_w and y_l , and D is the dataset of human comparisons.

Reinforcement learning (RL): Proximal Policy Optimization (PPO)

$$egin{aligned} ext{objective}(\phi) &= E_{(x,y) \sim D_{\pi_{\phi}^{ ext{RL}}}}[r_{ heta}(x,y) - eta \log(\pi_{\phi}^{ ext{RL}}(y \mid x)/\pi^{ ext{SFT}}(y \mid x))] + \\ \gamma E_{x \sim D_{ ext{pretrain}}}[\log(\pi_{\phi}^{ ext{RL}}(x))] \end{aligned}$$

where $\pi_\phi^{\rm RL}$ is the learned RL policy, $\pi^{\rm SFT}$ is the supervised trained model, and $D_{\rm pretrain}$ is the pretraining distribution.

- $r_{ heta}(x,y)$: expected reward for the new model
- $\log(\pi_\phi^{\rm RL}(y\mid x)/\pi^{\rm SFT}(y\mid x))]$: KL divergence to avoid going too far away from the original model
- ullet $E_{x\sim D_{
 m pretrain}}[\log(\pi_\phi^{
 m RL}(x))]$: objective for GPT3 on the original data

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