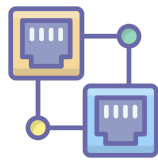
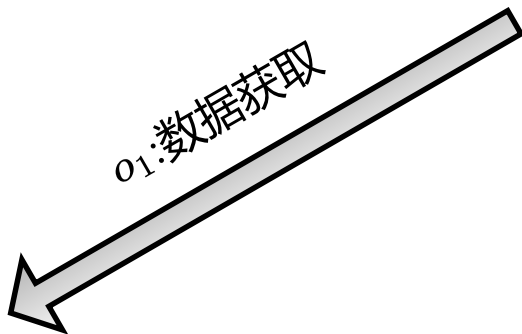


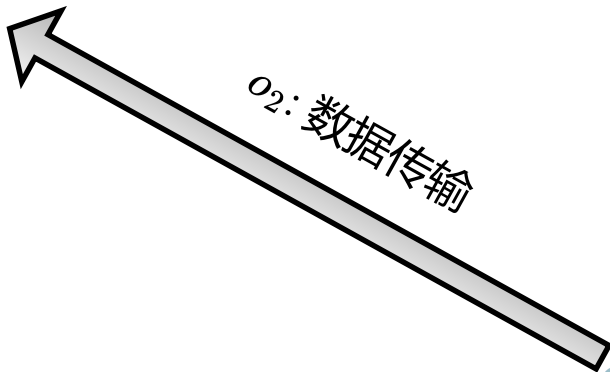
网络集线器



01: 数据获取

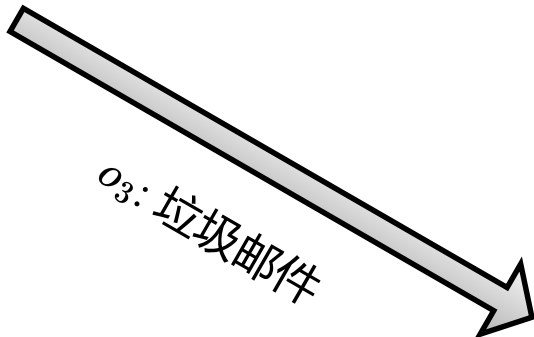


02: 数据传输



受攻击web服务器

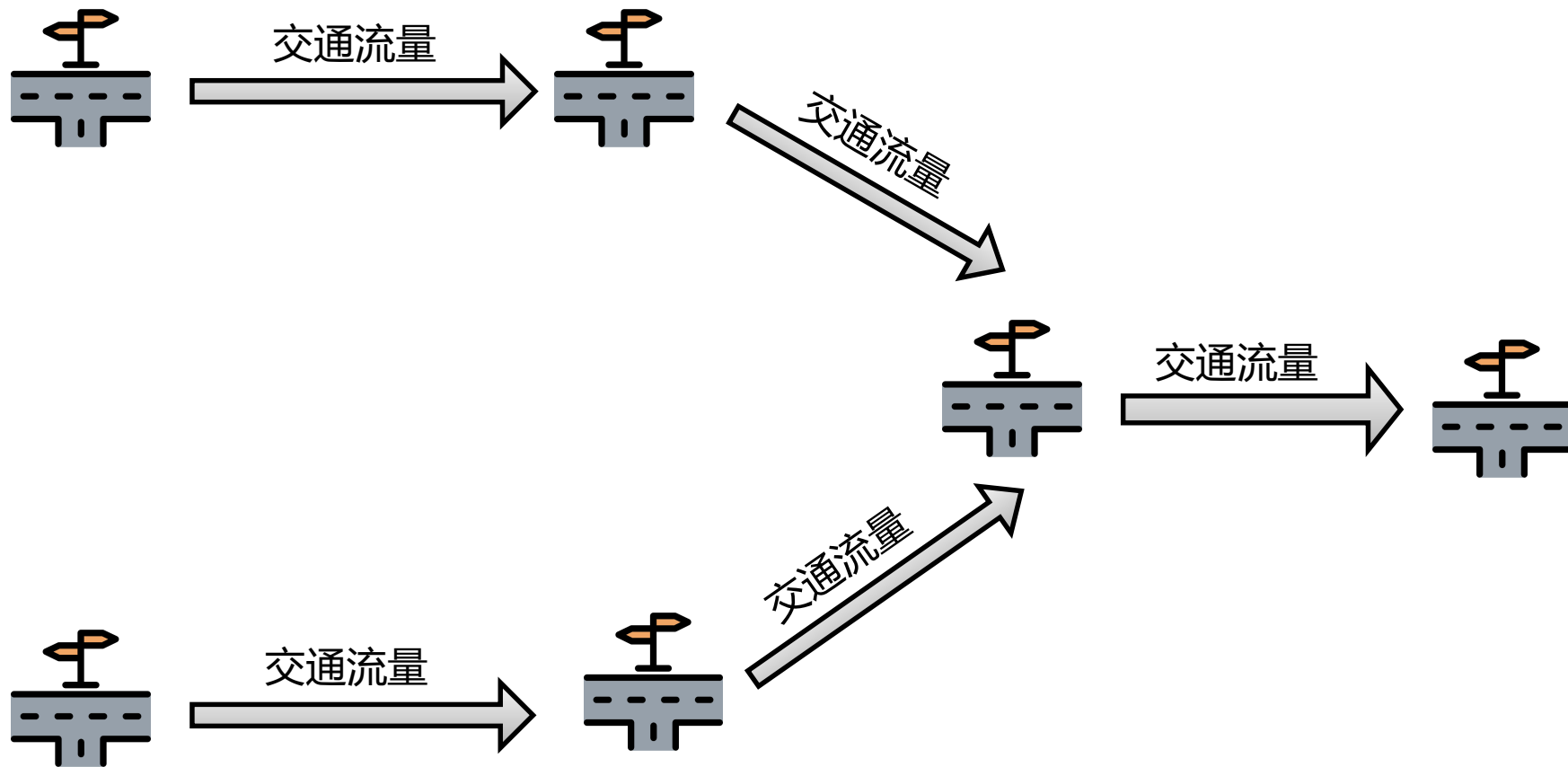
03: 垃圾邮件



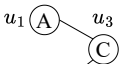
邮件服务器



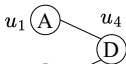
数据库



$$\Phi : \{u_1, u_2, u_3, u_4\}$$

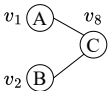


$Q_{star}(3)$

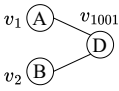


$Q_{star}(4)$

$$g : \{v_1, v_2, v_8, v_{1001}\}$$



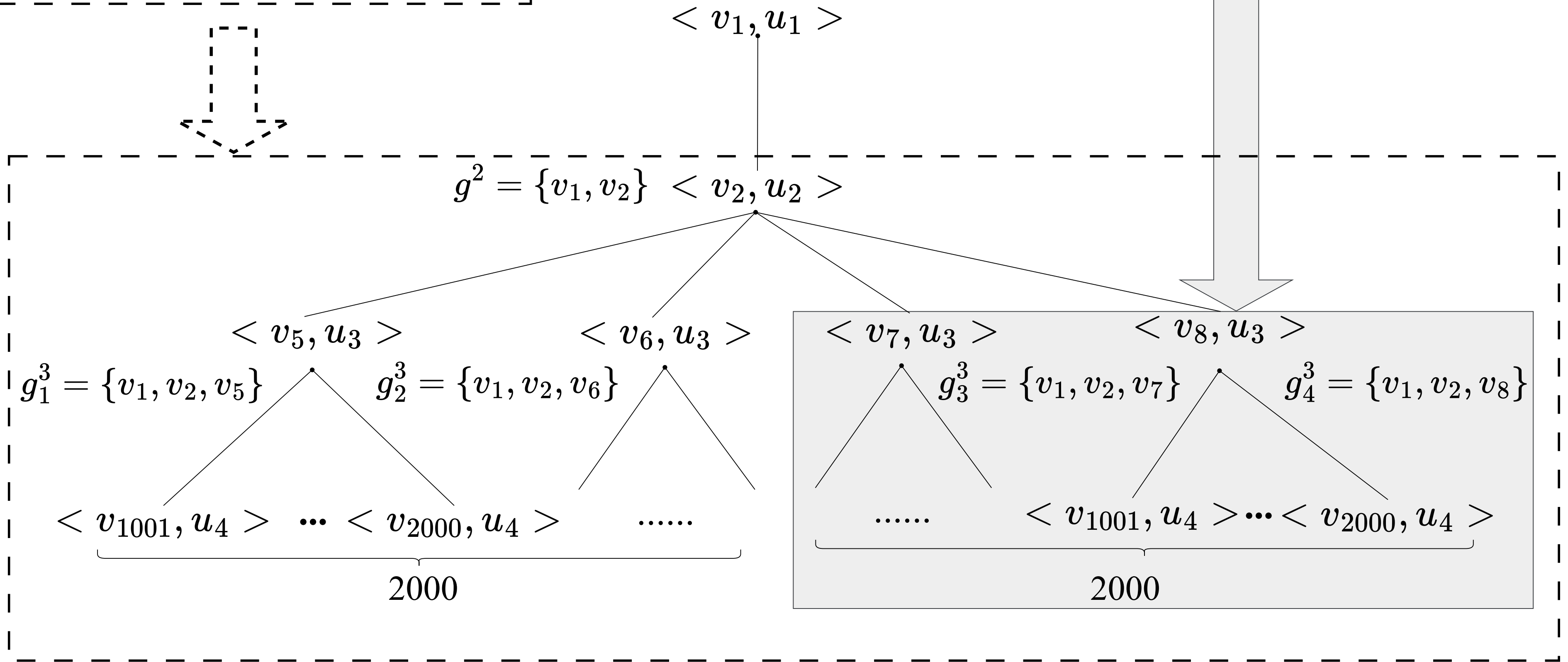
$$D_{star}(g, 3)$$

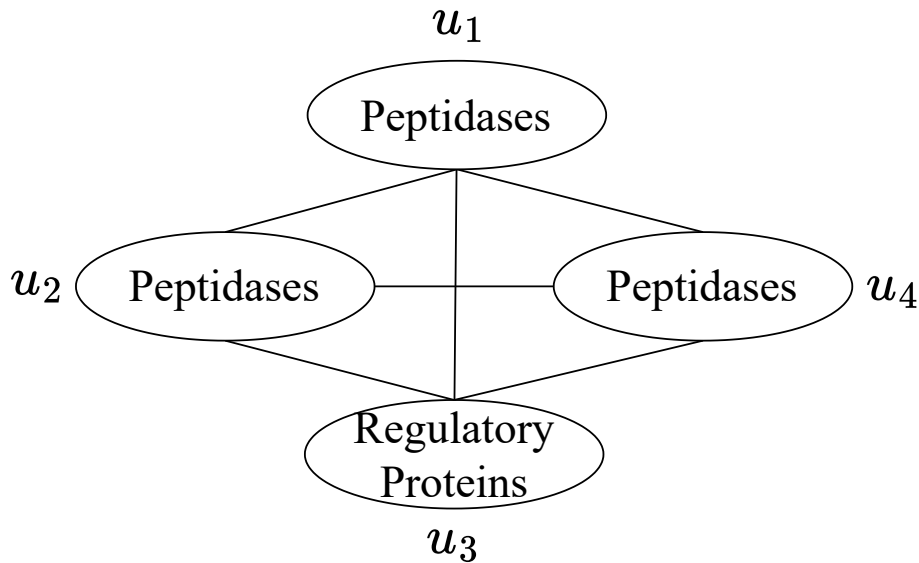


$$D_{star}(g, 4)$$

Local MWstar based pruning
 $den(Qstar(3), C_{g^2}(u_3)) = 40$
 $den(Qstar(4), C_{g^2}(u_4)) = 20$

Global MWstar based pruning
 $den(Qstar(4)) = 60$





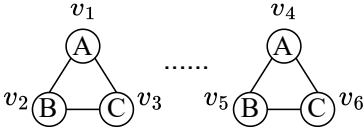
(a) 查询图 Q_1

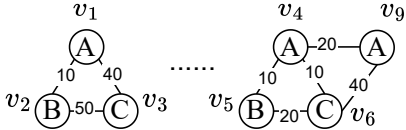
匹配序列: $\{u_1, u_2, u_3, u_4\}$

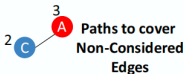
$g_0 : \langle SIRT1, EP300, p53, MDM2 \rangle$
$g_1 : \langle PIK3R1, PIK3CA, PTEN, PTK2 \rangle$
$g_2 : \langle CHEK1, CHEK2, ATR, CDC7 \rangle$

.....

(b) 匹配答案







d→	1			2								
Node Id↓	A	B	C	AA	BA	CA	AB	BB	CB	AC	BC	CC
1	1		1	1			1		1	1		
2	1	2	1	1	2	1				2	1	1
3	2		2	1		2	2			2		2
4	2	1	1	2	2	1	1			2	1	1

Top k result(k=3)

$\text{den}(g_0)$
$\text{den}(g_1)$
$\text{den}(g_2)$

密度上界

Top k result(k=3)

$\text{den}(g_0)$
$\text{den}(g_1)$

删除

$\text{den}(g_2)$



$\text{den}(g_x)$

插入操作

$\text{den}(g_x) > \text{den}(g_2)$

$\text{den}(g_x)$

插入

$\text{den}(g_x) \leq \text{den}(g_2)$

$\text{den}(g_x)$



删除操作

Top k result(k=3)

$\text{den}(g_0)$

删除

$\text{den}(g_x)$

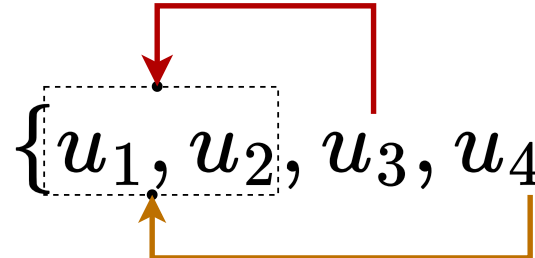
插入

$\text{den}(g_2)$

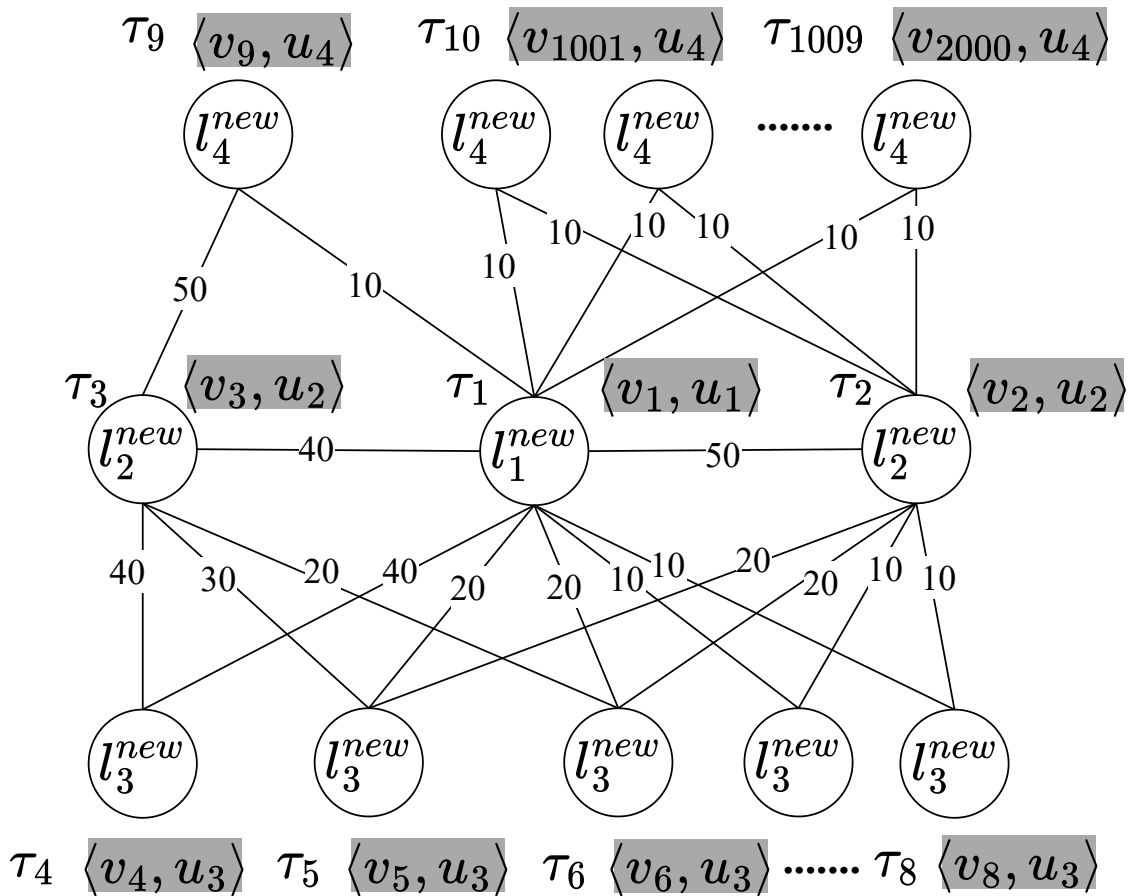
全图搜索

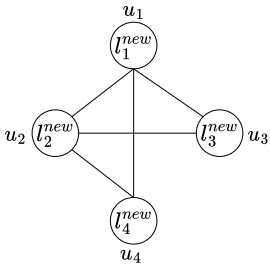
$\text{den}(g_1)$

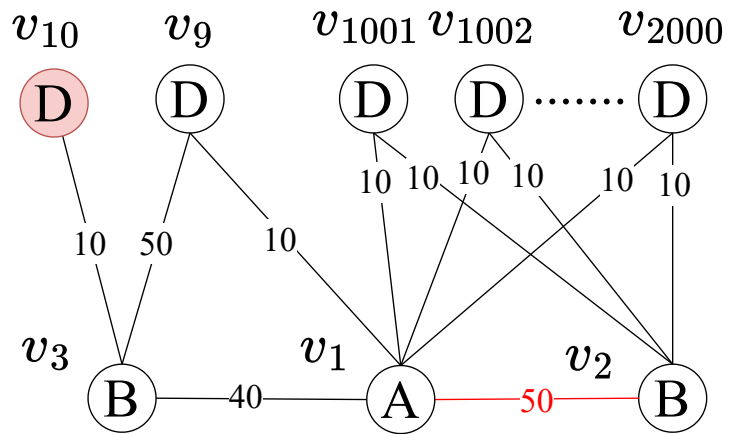


$$\Phi : \{u_1, u_2, u_3, u_4\} \Rightarrow g : \{v_1, v_2, \dots\}$$


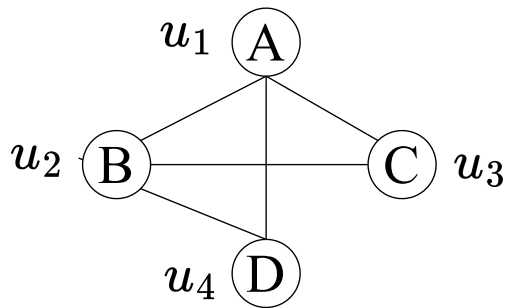
The diagram illustrates a mapping Φ from a set $\{u_1, u_2, u_3, u_4\}$ to a sequence $g : \{v_1, v_2, \dots\}$. The elements u_1 and u_2 are grouped together in a dashed box. A red arrow originates from u_3 , goes up and then down to point at u_1 . A blue arrow originates from u_4 , goes down and then up to point at u_2 .



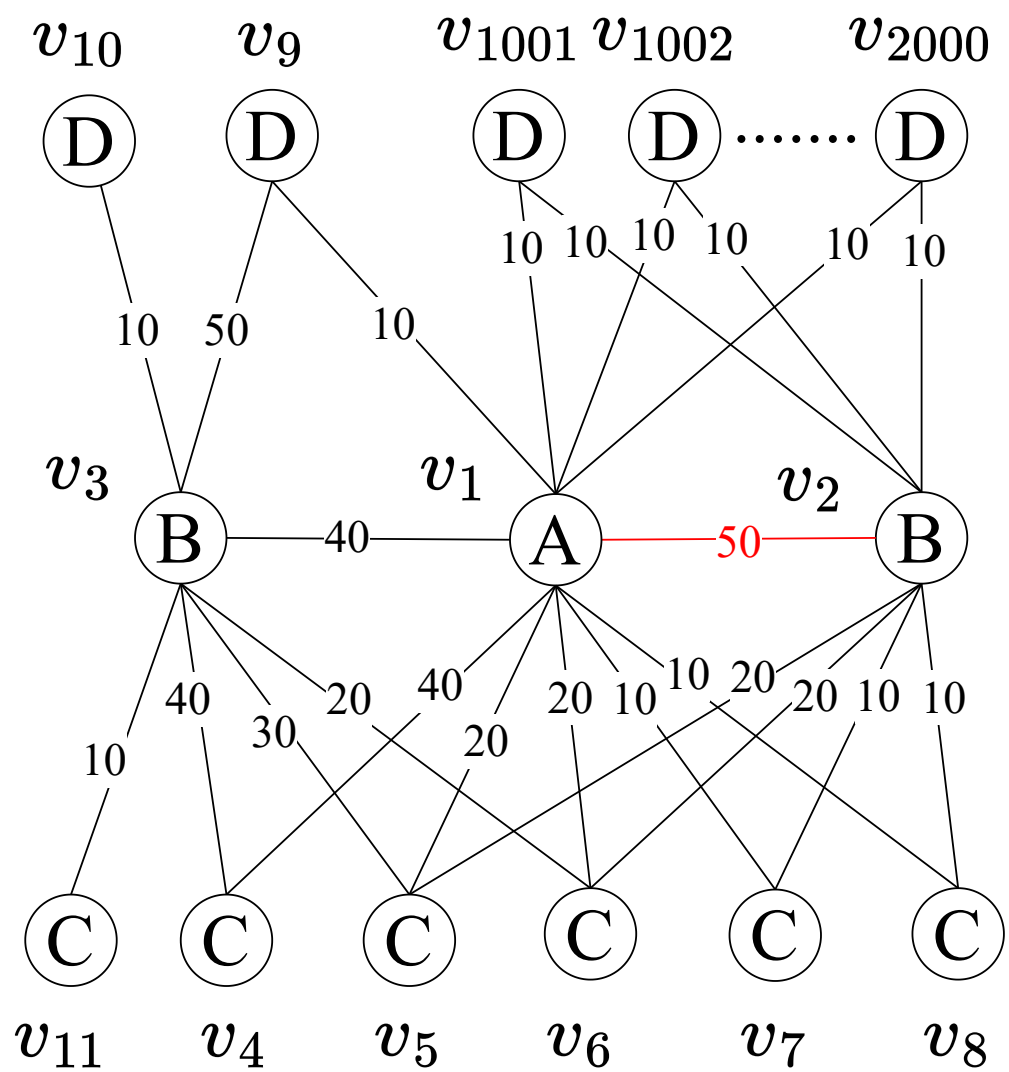




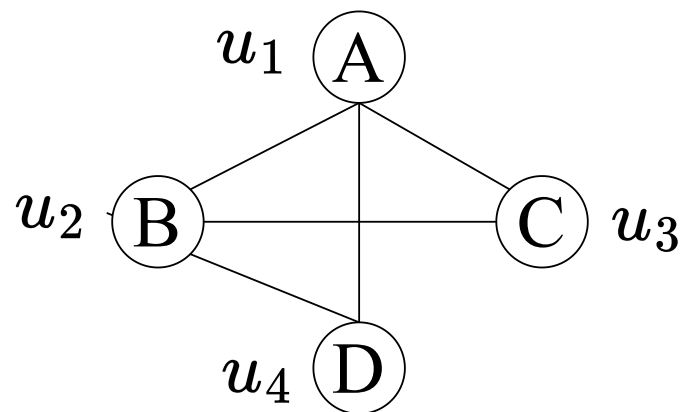
(c) 部分数据图



(b) 查询图 Q



(a) 数据图 G_t

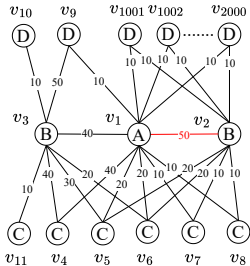


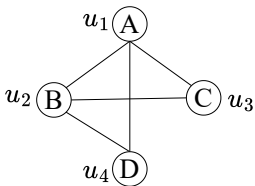
(b) 查询图 Q

匹配序列 $\{u_1, u_2, u_3, u_4\}$

$A_{G_t, Q}$	$f(u_1)$	$f(u_2)$	$f(u_3)$	$f(u_4)$	$den(\cdot)$
g_0	v_1	v_3	v_4	v_9	180
g_1	v_1	v_3	v_5	v_9	150
g_2	v_1	v_3	v_6	v_9	140

(c) 结果





$$\Phi : \{u_1, u_2, u_3, u_4\}$$

$A_{G_t,Q}$	$f(u_1)$	$f(u_2)$	$f(u_3)$	$f(u_4)$	$den(\cdot)$
g_0	v_1	v_3	v_4	v_9	180
g_1	v_1	v_3	v_5	v_9	150
g_2	v_1	v_3	v_6	v_9	140