

$A_{G_t, Q}$	$f(u_1)$	$f(u_2)$	$f(u_3)$	$f(u_4)$	$den(\cdot)$
g_0	v_1	v_3	v_4	v_9	180
g_1	v_1	v_3	v_5	v_9	150
g_2	v_1	v_3	v_6	v_9	140