

# Solution Of Exercise 3

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1. Consider the linear mapping

$$\phi = R^3 \rightarrow R^4$$

$$\phi\left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}\right) = \begin{bmatrix} 3x_1 + 2x_2 + x_3 \\ x_1 + x_2 + x_3 \\ x_1 - 3x_2 \\ 2x_1 + 3x_2 + x_3 \end{bmatrix}$$

- (a) Find the transformation matrix  $A_\phi$
- (b) Determine  $rk(A_\phi)$
- (c) Compute the kernel and image of  $\phi$ . What are  $\dim(\ker(\phi))$  and  $\dim(\text{Im}(\phi))$

Solution:

From the coefficients on the right, we have  $A_\Phi = \begin{bmatrix} 3 & 2 & 1 \\ 1 & 1 & 1 \\ 1 & -3 & 0 \\ 2 & 3 & 1 \end{bmatrix}$ .

Using Gaussian elimination, we can compute that  $rank(A_\Phi) = 3$ . From this we deduce that the kernel is trivial (i.e. only  $(0, 0, 0)$ ), and clearly  $\text{Im}(\Phi) = \{(3x_1 + 2x_2 + x_3, x_1 + x_2 + x_3, x_1 - 3x_2, 2x_1 + 3x_2 + x_3)^\top : x_1, x_2, x_3 \in R\}$ . We have  $\dim(\ker(\Phi)) = 0$ , and  $\dim(\text{Im}(\Phi)) = rank(A_\Phi) = 3$ .

2. Find the matrix to rotate the vectors

$$x_1 := \begin{bmatrix} 2 \\ 3 \end{bmatrix}, x_2 := \begin{bmatrix} 0 \\ -1 \end{bmatrix} \text{ by } \pi/6$$

Solution:

I will assume we need to rotate these vectors anticlockwise. A rotation about an angle  $\theta$  is given by the matrix  $\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$ . Thus for

$$\theta = 30^\circ, \text{ we have } R = \begin{bmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{\sqrt{3}}{2} \end{bmatrix} = \frac{1}{2} \begin{bmatrix} \sqrt{3} & -1 \\ 1 & \sqrt{3} \end{bmatrix}.$$

$$\text{Therefore, } Rx_1 = \frac{1}{2} \begin{bmatrix} 2\sqrt{3}-3 \\ 2+3\sqrt{3} \end{bmatrix} \text{ and } Rx_2 = \frac{1}{2} \begin{bmatrix} 1 \\ -\sqrt{3} \end{bmatrix}.$$

3. Are the following mappings linear:

$$(a) \phi : R \rightarrow R \\ x \rightarrow \phi(x) = \cos(x)$$

$$(b) \phi : R^3 \rightarrow R^2 \\ x \rightarrow \begin{bmatrix} 1 & 2 & 3 \\ 1 & 4 & 3 \end{bmatrix} x$$

Solution

(a) This is not linear –  $\Phi$  doesn't even map 0 to 0, indeed!

(b) We know that any matrix transformation like this is indeed linear.  
This comes from distributive properties of matrix multiplication.

4. Consider an endomorphism  $\phi : R^3 \rightarrow R^3$  whose transformation matrix (with respect to the standard basis in  $R^3$  is :

$$A_\phi = \begin{bmatrix} 1 & 1 & 0 \\ 1 & -1 & 0 \\ 1 & 1 & 1 \end{bmatrix}$$

(a) Determine  $\ker(\phi)$  and  $\text{Im}(\phi)$

(b) Determine the transformation matrix  $C_\phi$  with respect to the basis

$$B = \left( \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right)$$

perform a basis change toward the new basis  $B$

Solution

(a) Note that  $\text{rank}(A_\Phi) = 3$ , so  $\ker(\Phi) = \{0\}$  and  $\text{Im}(\Phi) = R^3$

- (b) Let  $P$  be the change of basis matrix from the standard basis of  $B$  to  $R^3$ . Then  $P = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 0 \\ 1 & 1 & 0 \end{bmatrix}$ .

The matrix  $C_\phi$  is given by  $P^{-1}A_\Phi P = \begin{bmatrix} 6 & 9 & 1 \\ -3 & -5 & 0 \\ -1 & -1 & 0 \end{bmatrix}$ .

5. Let us consider  $b_1, b_2, b'_1, b'_2$ , 4 vectors of  $R^2$  expressed in the standard basis of  $R^2$  as:

$$b_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}, b_2 = \begin{bmatrix} -1 \\ -1 \end{bmatrix}, b'_1 = \begin{bmatrix} 2 \\ -2 \end{bmatrix}, b'_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

and let us define two ordered bases  $B = (b_1, b_2), B' = (b'_1, b'_2)$  of  $R^2$

- (a) Show that  $B$  and  $B'$  are two bases of  $R^2$  and draw those basis vectors.
- (b) . Compute the matrix  $P_1$  that performs a basis change from  $B'$  to  $B$

- (c) We consider  $c_1, c_2, c_3$  three vectors of  $R^3$  defined in the standard basis of  $R^3$  as:

$$c_1 = \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}, c_2 = \begin{bmatrix} 0 \\ -1 \\ 2 \end{bmatrix}, c_3 = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$$

and we define  $C = (c_1, c_2, c_3)$

- i. Show that  $C$  is a basis of  $R^3$ , e.g., by using determinants
- ii. Let us call  $C' = (c'_1, c'_2, c'_3)$  the standard basis of  $R^3$ . Determine the matrix  $P_2$  that performs the basis change from  $C$  to  $C'$

- (d) We consider a homomorphism  $\phi : R^2 \rightarrow R^3$ , such that:

$$\phi(b_1 + b_2) = c_2 + c_3$$

$$\phi(b_1 - b_2) = 2c_1 - c_2 + 3c_3$$

where  $B = (b_1, b_2)$  and  $C = c_1, c_2, c_3$  are ordered bases of  $R^2$  and  $R_3$  respectively.

Determine the transformation matrix  $A_\phi$  of  $\phi$  with respect to the ordered bases  $B$  and  $C$

- (e) Determine  $A'$ , the transformation matrix of  $\phi$  with respect to the bases  $B'$  and  $C'$

Solution

- (a) Each set  $B$  and  $B'$  has the correct number of (clearly!) linearly independent vectors, so they are both bases of  $R^2$ .
- (b) We write the old basis vectors ( $B'$ ) in terms of the new ( $B$ ), and then transpose the matrix of coefficients. We have  $b'_1 = 4b_1 + 6b_2$ , and  $b'_2 = 0b_1 - b_2$ . Thus  $P_1 = \begin{bmatrix} 4 & 0 \\ 6 & -1 \end{bmatrix}$ .
- (c) Let  $M = [c_1|c_2|c_3]$ , and observe that  $\det M = 4 \neq 0$ , so the vectors are linearly independent. Since  $R^3$  had dimension 3, and we have three linearly independent vectors,  $C$  must indeed be a basis. Indeed, such an  $M$  is the change of basis matrix from  $C$  to  $C'$  (write the old vectors in terms of the new!) and this is thus the  $P_2$  we require. Thus  $P_2 = \begin{bmatrix} 1 & 0 & 1 \\ 2 & -1 & 0 \\ -1 & 2 & -1 \end{bmatrix}$ .
- (d) Observe that by adding the given results, we find that  $\Phi(b_1) = c_1 + 2c_3$ ; by subtracting, we have  $\Phi(b_2) = -c_1 + c_2 - c_3$ . Then  $A_\Phi$  is given by the transpose of the matrix of coefficients, so  $A_\Phi = \begin{bmatrix} 1 & -1 \\ 0 & 1 \\ 2 & -1 \end{bmatrix}$ .
- (e) We first need to apply  $P_1$  to change from basis  $B'$  to  $B$ . Then  $A_\Phi$  will map us to  $(R^3, C)$ , before  $P_2$  will take us to  $C'$ . Remember that matrices are acting like functions here, so they are applied to (column) vectors from right to left. Therefore the multiplication we require is  $A' = P_2 A_\Phi P_1$ . (This is what part f is asking us to recognise.)

We have  $A' = \begin{bmatrix} 0 & 2 \\ -10 & 3 \\ 12 & -4 \end{bmatrix}$ .