Bandits

Multi-armed adversarial bandits, stochastic bandits, contextual bandits

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With many slides derived from Haipeng Lou, David Silver, Emma Brunskill, and

Outline

- 1. Adversarial bandit
- 2. Stochastic bandit
- 3. Bayesian bandit
- 4. Contextual bandit

Setting - Notation

 $w_t \in \Delta(K)$ - Action in "Expert advice" problem

 $f_t(a_t) = \langle l_t, a_t \rangle$ - Loss in "Expert advice" problem

- Action at time t: $a_t \in [K]$ —— Special case of $w_t = [0,...,1,...,0]$
- Loss at time t: $l_t \in [0,1]^K$
 - **Remark**: Only know $l_t(a_t)$ —Partial information
- Setting: Adversarial

Setting - Regret

$$R_T = \sum_{t=1}^{I} \langle w_t, l_t \rangle - \min_{w \in \Omega} \langle w_t, l_t \rangle$$
 - Regret in "Expert advice" problem

Regret:
$$\mathbb{E}[R_T] = \mathbb{E}\left[\sum_{t=1}^T l_t(a_t)\right] - \min_{a \in [K]} \sum_{t=1}^T l_t(a)$$

Remark: The expectation due to randomness of the algorithm

Setting - Exploration vs Exploitation

- Applications: Clinical trials, recommendation systems, etc.
- Foundation model of Exploration-Exploitation:
 - Exploitation: Select a_t to minimize losses in the past
 - Exploration: Select a_t leading to even smaller losses

Algorithm - Motivation

- Question: Since problem setting is very similar to Expert problem setting, can we use Hedge algorithm to solve?
- Answer: Yes (with modifications)

1. Adversarial bandit Algorithm - Exp3

Algorithm 2: Hedge

Input: learning rate $\eta > 0$ (also called step size, temperature, etc.) Initialization: let $L_0 \in \mathbb{R}^N$ be the all-zero vector

$$_{ extsf{J}}$$
 for $t=1,\ldots,T$ do

compute $p_t \in \Delta(N)$ such that $p_t(i) \propto \exp(-\eta L_{t-1}(i))$ play p_t and observe loss vector $\ell_t \in [0,1]^N$ update $L_t = L_{t-1} + \ell_t$

- Estimator $\hat{l}_t \in \mathbb{R}_+^K$:
 - **Purpose**: Only know $l_t(a_t)$, while Hedge requires full l_t
 - Inverse importance weighted estimator: Pick $a_t \sim p_t \in \Delta(K)$, $\hat{l}_t(a) = \frac{l_t(a)}{p_t(a)} \mathbb{1}\{a = a_t\}$
 - Algorithm:
 - Initialize $L_0 = (0,...,0)$
 - For t = 1,...,T
 - Compute $p_t \in \Delta(K)$ such that $p_t(a) \propto \exp(-\eta \sum_{s < t} \hat{l}_s(a)), \forall a \in [K]$
 - Play $a_t \sim p_t \in \Delta(K)$ and observe $l_t(a_t)$
 - . Calculate $\hat{l}_t(a) = \frac{l_t(a)}{p_t(a)} \mathbb{1}\{a = a_t\}, \forall a \in [K]$

Algorithm - Exp3

• Estimator $\hat{l}_t \in \mathbb{R}_+^K$:

. Unbiased:
$$\mathbb{E}[\hat{l}_t(a_t)] = p_t(a_t) \times \frac{l_t(a_t)}{p_t(a_t)} + (1 - p_t(a_t)) \times 0 = l_t(a_t)$$

Variance (2nd moment):

$$\mathbb{E}[\hat{l}_t(a_t)^2] = p_t(a_t) \times \frac{l_t(a_t)^2}{p_t(a_t)^2} + (1 - p_t(a_t)) \times 0^2 = \frac{l_t(a_t)^2}{p_t(a_t)} < \frac{1}{p_t(a_t)}$$

Small $p_t(a_t)$ leads to high variance

Algorithm - Exp3

Algorithm:

• Calculate
$$p_t(a) \propto \exp(-\eta \sum_{s < t} \hat{l}_s(a)), \forall a \in [K]$$
• Pick $a_t \sim p_t \in \Delta(K)$
• Calculate $\hat{l}_t(a) = \frac{l_t(a)}{p_t(a)} 1\{a = a_t\}, \forall a \in [K]$

- Exploitation: Choose the action that has smallest summation of previous losses.
- **Exploration: Only** the loss of $a = a_t$ is non-zero, while the loss of others is **zero**. Therefore, the probability of seeing the **same action** next time is **decreased**. In other words, it encourages exploration.
 - Remark: l_t cannot be negative!

Algorithm - Exp3

- Regret bound:
 - Hedge: $R_T = \mathcal{O}(\sqrt{T \ln K})$ with a condition $l_t \in [0,1]^K$
 - Exp3: $\hat{l}_t(a_t)=\frac{l_t(a_t)}{p_t(a_t)}<\frac{1}{p_t(a_t)}$, which can be large and the regret bound does not hold.

. Theorem 1: With
$$\eta=\sqrt{\frac{\ln K}{TK}}$$
, Exp3 ensures $\mathbb{E}[R_T]=\mathcal{O}(\sqrt{TK\ln K})$
 The price of knowing $\frac{1}{K}$ information

Algorithm - Exp3

Regret bound:

. Theorem 1: With
$$\eta = \sqrt{\frac{\ln K}{TK}}$$
, Exp3 ensures $\mathbb{E}[R_T] = \mathcal{O}(\sqrt{TK \ln K})$

• Proof:

$$\mathbb{E}[R_T] \leq \frac{\ln K}{\eta} + \eta \sum_{t=1}^{T} \sum_{a=1}^{K} p_t(a) \mathbb{E}[\hat{l}_t(a)^2]$$

$$= \frac{\ln K}{\eta} + \eta \sum_{t=1}^{T} \sum_{a=1}^{K} p_t(a) \frac{l_t(a)^2}{p_t(a)} \leftarrow Variance cancellation$$

$$= \frac{\ln K}{\eta} + \eta \sum_{t=1}^{T} \sum_{a=1}^{K} l_t(a)^2$$

$$\leq \frac{\ln K}{\eta} + \eta TK$$

Lower bound

- Theorem: For any learning algorithm, we can achieve $\Omega(\sqrt{TK})$
- Notation:
 - . Loss of random action $l_t(a) \sim Ber(\frac{1}{2}), \forall a \neq a'$, Loss of "good" action $l_t(a') \sim Ber(\frac{1}{2} \epsilon)$, with $\epsilon \in (0, \frac{1}{4}]$
 - $P_{a'}$: Probability conditioned on a'-th action is good (Similar for $\mathbb{E}_{a'}$)
 - P_{unf} : Probability with respect to uniformly random choice of loss for all actions (Similar for \mathbb{E}_{unf})
 - a_t : Action at time t
 - l_t : loss at time t: Losses for all arms are generated independently and uniformly $\{0,1\}$, i.e $Ber(\frac{1}{2})$
 - n_a : # times action a is selected ($n_a = \sum_{t=1}^{T} 1(a_t = a)$)

Lower bound

$$\mathbb{E}[l_t] = \mathbb{E}[l_t(a_t) \mid a_t = a']P(a_t = a') + \mathbb{E}[l_t(a_t) \mid a_t \neq a']P(a_t \neq a') = (\frac{1}{2} - \epsilon)P(a_t = a') + \frac{1}{2}P(a_t \neq a')$$

Proof:

$$\begin{split} E_{a'}[L_A - L_{min}] & \geq \frac{1}{K} \sum_{a=1}^K \mathbb{E}_{a'}[L_A] - T(\frac{1}{2} - \epsilon) \qquad E_{a'}[L_{min}] \leq \sum_{t=1}^T E_{a'}[l_t(a_t = a')] = T(\frac{1}{2} - \epsilon) \\ & = \frac{1}{K} \sum_{a'=1}^K \sum_{t=1}^T \mathbb{E}_{a'}[l_t] - T(\frac{1}{2} - \epsilon) \\ & = \frac{1}{K} \sum_{a'=1}^K \sum_{t=1}^T \left[(\frac{1}{2} - \epsilon) P_a(a_t = a') + \frac{1}{2} P_a(a_t \neq a') \right] - T(\frac{1}{2} - \epsilon) \\ & = \frac{1}{K} \sum_{a'=1}^K \left[\frac{T}{2} - \epsilon \mathbb{E}_{a'}[n_{a'}] \right] - T(\frac{1}{2} - \epsilon) \\ & = T\epsilon - \frac{\epsilon}{K} \sum_{a'=1}^K \mathbb{E}_{a'}[n_{a'}] \end{split} \qquad \text{Change from regret bound to action selection bound}$$

Lower bound

Proof (continue): Let focus on the term $\sum_{a'}^{\Lambda} \mathbb{E}_{a'}[n_{a'}]$.

$$\mathbb{E}_{a'}[n(a')] - E_{unf}[n(a')] = \sum_{l_{1:T}} n(a')(P_{a'}(l_{1:T}^{a=1}) - P_{unf}(l_{1:T}))$$

$$\leq T \sum_{l_{1:T}} P_{a'}(l_{1:T}) - P_{unf}(l_{1:T})$$

$$= T ||P_{a'} - P_{unf}||_{1}$$

$$\leq T_{\sqrt{2}}KL(P_{unf}||P_{a'})$$

Pinsker's inequality

Change from action selection bound to KL divergence

Lower bound

$$\mathbb{E}[n_{a'}] = \mathbb{E}[\sum_{t=1}^{T} 1_{a_t = a'}] = \sum_{t=1}^{T} P(a_t = a')$$

Proof (continue):

$$\begin{split} \mathbb{E}_{a}[n_{a'}] - E_{unf}[n_{a'}] &\leq \sqrt{2KL(P_{unf}||P_{a'})} \\ &= T\sqrt{2\sum_{t=1}^{T} KL(P_{unf}(l_{t}||l_{1:t-1})||P_{a}(l_{t}||l_{1:t-1}))} \\ &= T\sqrt{2\sum_{t=1}^{T} P(a_{t} \neq a')KL(Ber(\frac{1}{2})||Ber(\frac{1}{2})) + P(a_{t} = a')KL(Ber(\frac{1}{2})||Ber(\frac{1}{2} - \epsilon))} \\ &= T\sqrt{2\sum_{t=1}^{T} P(a_{t} = a')\frac{1}{2}\ln\frac{1}{1 - 4\epsilon^{2}}} \\ &= T\sqrt{16\epsilon^{2}E \cdot \{n_{t}\}} \end{split}$$

Chain rule for KL divergence

$$\ln \frac{1}{1-x} \le 4x, \forall x \le \frac{1}{2}$$

Change KL divergence selection bound to action selection bound

Lower bound

Proof (continue):

$$\sum_{a'=1}^{K} \mathbb{E}_{a'}[n_{a'}] \le \sum_{a'=1}^{K} E_{unf}[n_{a'}] + \sum_{a'=1}^{K} T \sqrt{16\epsilon^2 E_{unf}[n_{a'}]}$$
$$\le T + T \sqrt{16\epsilon^2 TK}$$
$$= T + 4T\epsilon \sqrt{TK}$$

$$\text{Adding } \sum_{a'=1}^K \text{ on both sides}$$

$$\sum_{a'=1}^K E_{unf}[n_{a'}] = T, \text{ then } \sum_{a'=1}^K \sqrt{E_{unf}[n_{a'}]} \leq K \sqrt{\frac{T}{K}} = \sqrt{TK}$$

Lower bound

• Proof (continue): Then, we have

$$E_{a'}[L_A - L_{min}] \ge T\epsilon - \frac{\epsilon}{K} \sum_{a'=1}^{K} \mathbb{E}_{a'}[n_{a'}]$$

$$\ge T\epsilon - \epsilon \left(\frac{T}{K} + 4T\epsilon \sqrt{\frac{T}{K}}\right)$$

$$= T\epsilon - \frac{T\epsilon}{K} - 4T\epsilon^2 \sqrt{\frac{T}{K}}$$

$$\ge \frac{T\epsilon}{2} - 4T\epsilon^2 \sqrt{\frac{T}{K}}$$

$$= \Omega(\sqrt{TK})$$

Setting
$$\epsilon = \frac{1}{16} \sqrt{\frac{K}{T}}$$

Minimax optimal MAB - Intuition

- **Problem**: Gap $\sqrt{\ln K}$ between lower bound and upper bound.
- **Observation**: Hedge is FTRL with entropy regularizer. Exp3 is Hedge with loss estimator. Therefore, Exp3 is FTRL with entropy regularizer and loss estimator. Can we change the regularizer to close the gap?
- Solution: FTRL with Tsallis regularization function

Minimax optimal MAB - Tsallis function

. Tsallis function:
$$\psi(p) = \frac{1 - \sum_{a=1}^K p(a)^{\beta}}{1 - \beta}$$

Remark: Generalization of Shannon entropy function!
$$\lim_{\beta \to 1} \psi(p) = \lim_{\beta \to 1} \frac{1 - \sum_{a=1}^{K} p(a)^{\beta}}{1 - \beta} = \lim_{\beta \to 1} \frac{-\sum_{a=1}^{K} p(a)^{\beta} \ln p(a)}{-1} = \sum_{a=1}^{K} p(a) \ln p(a)$$

Minimax optimal MAB - Algorithm

• FTRL:
$$p_{t+1} = \arg\min_{p \in \Delta(K)} \langle p, \sum_{s < t+1} \hat{l}_s \rangle + \frac{1}{\eta} \psi(p)$$

- Use OMD framework to solve for p_{t+1} and obtain regret bound
- Remark: FTRL framework is possible, but more difficult!

Minimax optimal MAB - OMD

$$\psi(p) = \frac{1 - \sum_{a=1}^{K} p(a)^{\beta}}{1 - \beta}$$

OMD framework

(1)
$$\nabla \psi(p'_{t+1}) = \nabla \psi(p_t) - \eta \hat{l}_t$$
 \longrightarrow $\frac{1}{p'_{t+1}(a)^{1-\beta}} = \frac{1}{p_t(a)^{1-\beta}} + \frac{1-\beta}{\beta} \eta \hat{l}_t(a)$

(2) $p_{t+1} = \arg\min_{p \in \Delta(K)} D_{\psi}(p, p'_{t+1})$ \longrightarrow $\frac{1}{p_{t+1}(a)^{1-\beta}} = \frac{1}{p'_{t+1}(a)^{1-\beta}} + \lambda$
 $= \arg\min_{p \in \Delta(K)} \psi(p) - \psi(p'_{t+1}) - \langle \nabla \psi(p'_{t+1}), p - p'_{t+1} \rangle$ Lagrange multiplier

$$= \arg\min_{p \in \Delta(K)} \frac{1}{1 - \beta} \sum_{a=1}^{K} (p'_{t+1}(a)^{\beta} - p(a)^{\beta} + \frac{\beta}{p'_{t+1}(a)^{1-\beta}} (p(a) - p'_{t+1}(a)))$$

Minimax optimal MAB - Update rule

• FTRL:
$$p_{t+1} = \arg\min_{p \in \Delta(K)} \langle p, \sum_{s < t+1} \hat{l}_s \rangle + \frac{1}{\eta} \psi(p)$$
• $\frac{1}{p_{t+1}'(a)^{1-\beta}} = \frac{1}{p_t(a)^{1-\beta}} + \frac{1-\beta}{\beta} \eta \hat{l}_t(a)$
• $\frac{1}{p_{t+1}(a)^{1-\beta}} = \frac{1}{p_{t+1}'(a)^{1-\beta}} + \lambda$
Update rule: $\frac{1}{p_{t+1}(a)^{1-\beta}} = \frac{1-\beta}{\beta} (\lambda' + \eta \sum_{s < t+1} \hat{l}_t(a))$

$$= \frac{1}{p_t(a)^{1-\beta}} + \frac{1-\beta}{\beta} \eta \hat{l}_t(a) + \lambda$$

$$= \frac{1}{p_t'(a)^{1-\beta}} + \frac{1-\beta}{\beta} \eta \hat{l}_t(a) + 2\lambda$$
• (Recursion)
• $\frac{1-\beta}{\beta} \eta \sum_{s < t+1} \hat{l}_t(a) + \lambda'$

Minimax optimal MAB - Regret

$$\begin{split} \bullet & \text{ For } q \in \Delta(K) \\ R_T &= \sum_{t=1}^T \left\langle p_t, \hat{l}_t \right\rangle - \sum_{t=1}^T \left\langle q, \hat{l}_t \right\rangle \\ &= \sum_{t=1}^T \left\langle p_t - q, \hat{l}_t \right\rangle \\ &= \frac{1}{\eta} \sum_{t=1}^T D_{\psi}(q, p_t) - D_{\psi}(q, p'_{t+1}) + D_{\psi}(p_t, p'_{t+1}) \qquad \text{Three-point inequality} \\ &\leq \frac{1}{\eta} \sum_{t=1}^T D_{\psi}(q, p_t) - D_{\psi}(q, p_{t+1}) + D_{\psi}(p_t, p'_{t+1}) \qquad \qquad \text{Definition of } p_{t+1} \\ &= \frac{D_{\psi}(q, p_1)}{\eta} + \frac{1}{\eta} \sum_{t=1}^T D_{\psi}(p_t, p'_{t+1}) \\ &= \frac{K^{1-\beta} - 1}{1 - \beta} + \frac{1}{\eta} \sum_{t=1}^T D_{\psi}(p_t, p'_{t+1}) \qquad \qquad \text{Range of } \psi(p) \end{split}$$

Minimax optimal MAB - Regret

• For $q \in \Delta(K)$

$$\begin{split} R_T &= \frac{K^{1-\beta}-1}{1-\beta} + \frac{1}{\eta} \sum_{i=1}^T \sum_{a=1}^K p_{i+1}'(a)^\beta - p_i(a)^\beta + \eta p_i(a)\hat{l}_i(a) \\ &= \frac{K^{1-\beta}-1}{1-\beta} + \frac{1}{\eta} \sum_{i=1}^T \sum_{a=1}^K \left(p_i(a)^\beta \Big(1 + \frac{1-\beta}{\beta} \eta p_i(a)^{1-\beta}\hat{l}_i(a) \Big)^{\frac{\beta}{\beta-1}} - p_i(a)^\beta + \eta p_i(a)\hat{l}_i(a) \right) \\ &= \frac{K^{1-\beta}-1}{1-\beta} + \frac{1}{\eta} \sum_{i=1}^T \sum_{a=1}^K \left(p_i(a)^\beta \Big(1 - \eta p_i(a)^{1-\beta}\hat{l}_i(a) + \frac{\eta^2}{\beta} p_i(a)^{2-2\beta}\hat{l}_i(a)^2 \Big) - p_i(a)^\beta + \eta p_i(a)\hat{l}_i(a) \right) \\ &= \frac{K^{1-\beta}-1}{1-\beta} + \frac{\eta}{\beta} \sum_{i=1}^T \sum_{a=1}^K \left(p_i(a)^\beta \Big(1 - \eta p_i(a)^{1-\beta}\hat{l}_i(a) + \frac{\eta^2}{\beta} p_i(a)^{2-2\beta}\hat{l}_i(a)^2 \Big) - p_i(a)^\beta + \eta p_i(a)\hat{l}_i(a) \right) \\ &= \frac{K^{1-\beta}-1}{1-\beta} + \frac{\eta}{\beta} \sum_{i=1}^T \sum_{a=1}^K p_i(a)^{2-\beta}\hat{l}_i(a)^2 \end{split}$$

Minimax optimal MAB - Regret

Regret bound:

$$\begin{split} E[R_T] & \leq \frac{K^{1-\beta}-1}{1-\beta} + \frac{\eta}{\beta} \sum_{t=1}^T \sum_{a=1}^K p_t(a)^{1-\beta} \\ & \leq \frac{K^{1-\beta}-1}{1-\beta} + \frac{\eta}{\beta} \sum_{t=1}^T \big(\sum_{a=1}^K (p_t(a)^{1-\beta})^{\frac{1}{1-\beta}} \big)^{1-\beta} \big(\sum_{a=1}^K 1^{\frac{1}{\beta}} \big)^{\beta} \\ & = \frac{K^{1-\beta}-1}{1-\beta} + \frac{\eta}{\beta} TK^{\beta} \\ & \bullet \beta = \frac{1}{2}, \eta = \frac{1}{\sqrt{T}}, \text{ then } E[R_T] \leq 4\sqrt{TK} \end{split}$$

Holder's inequality

1. Adversarial bandit Summary

- MAB: Partial information feedback
- EXP3: Hedge with unbiased, but large variance, loss estimator
 - Regret of EXP3: $\Omega(\sqrt{TK})$, $\mathcal{O}(\sqrt{TK \ln K})$
- Minimax optimal MAB: FTRL with Tsallis regularizer, $\mathcal{O}(\sqrt{TK})$

Setting - Notation

- Action at time t: $a_t \in [K]$
- Loss at time t: $l_t \in [0,1]^K$
 - Remark: Only know $l_t(a_t)$
- Setting: Stochastic
 - Each arm has unknown loss distribution D_a and $\mu(a)$
 - I.i.d: Does not depend on t
 - Example: D_a are Bernoulli distribution (0/1 loss)

Setting - Regret

Regret:
$$\mathbb{E}[R_T] = \mathbb{E}\left[\sum_{t=1}^T l_t(a_t)\right] - \min_{a \in [K]} \sum_{t=1}^T l_t(a)$$

Pseudo-Regret:
$$\bar{R}_T = \max_{a \in K} \mathbb{E}\left[\sum_{t=1}^T l_t(a_t) - \sum_{t=1}^T l_t(a)\right]$$

- Stochasticity: Algorithm choice and environment
- Remark: Pseudo-regret is always smaller than expected regret

Another version:
$$\bar{R}_T = \mathbb{E}\left[\sum_{t=1}^T \left(\mu(a_t) - \mu(a^*)\right)\right]$$
 with $a^* = \arg\min_a \mu(a)$

• Remark: Possible to ignore the deviation between $l_t(a)$ and $\mu(a)$

Setting - Non-adaptive vs adaptive algorithm

- Trade-off between exploration and exploitation!
- Non-adaptive versus adaptive: Previous experience to guide exploration
- Non-adaptive algorithm: Explore-then-Exploit and ϵ -greedy
- Adaptive algorithm: Successive elimination and UCB

Setting - Lemma

Radius r: key component for every proof!

- **Lemma**: For stochastic bandit setting, $n\phi$ matter the learning strategy is, we have that $\Pr(|\hat{\mu}_t(a) \mu(a)| \le 2\sqrt{\frac{\log T}{n_t(a)}}) \ge 1 \frac{2K}{T}$ High probability event
- Intuition: Among T rounds, if $n_t(a) \approx T$, then $\hat{\mu}_t(a) \approx \mu(a)$ with high probability
- Proof: Hoeffding's inequality

$\Pr(|\hat{\mu}(a) - \mu(a)| \le 2\sqrt{\frac{\log T}{n_t(a)}}) \ge 1 - \frac{2K}{T}$

Algorithm - Explore-then-Exploit

- Intuition: Try each arms multiple times to estimate $\hat{\mu}(a)$ for every a. Then, repeatedly select the lowest estimated arm.
- Algorithm: Among T rounds, select at least N rounds for each arm. Each arm will have $\hat{\mu}(a) = \frac{1}{N} \sum_{t=1}^{N} l_t(a)$. Then, choose the arm with lowest estimation for the rest T NK rounds.

$$\Pr(|\hat{\mu}(a) - \mu(a)| \le 2\sqrt{\frac{\log T}{n_t(a)}}) \ge 1 - \frac{2K}{T}$$

Algorithm - Explore-then-Exploit - Regret analysis

• Assume we have K=2, a and a^* , $n_t(a)=n_t(a^*)=N$

•
$$\mu(a) \in [\hat{\mu}_t(a) - r_t(a), \hat{\mu}_t(a) + r_t(a)] \text{ with } r_t(a) = 2\sqrt{\frac{\log T}{n_t(a)}}$$

• If we choose a^* instead of a (exploitation), then

$$\mu(a^*) - r_t(a^*) < \hat{\mu}_t(a^*) < \hat{\mu}_t(a) < \mu(a) + r_t(a)$$

- . In other words, $\mu(a^*) \mu(a) \le 4\sqrt{\frac{\log T}{N}}$
 - Remark: Not bad if we select non-optimal arm with large N

$$\Pr(|\hat{\mu}(a) - \mu(a)| \le 2\sqrt{\frac{\log T}{n_t(a)}}) \ge 1 - \frac{2K}{T}$$

Algorithm - Explore-then-Exploit - Regret analysis

- . Exploitation: $\Delta_a = \mu(a^*) \mu(a) \le 4\sqrt{\frac{\log T}{N}}$ Exploration
- Regret (2 arms): $R(T) \le 2N + 4(T 2N)\sqrt{\frac{\log T}{N}}$.
 - With $N = T^{2/3} (\log T)^{2/3}$, then $R(T) \le \mathcal{O}(T^{2/3} (\log T)^{1/3})$

$$\begin{split} \bar{R}_T &= \mathbb{E}[R(T)] = \mathbb{E}[R(T) \,|\, \text{Good event}] \, \text{Pr}(\text{Good event}) + \mathbb{E}[R(T) \,|\, \text{Bad event}] \, \text{Pr}(\text{Bad event}) \\ &\leq \mathbb{E}[R(T) \,|\, \text{Good event}] + T \times O(T^{-1}) \\ &\leq \mathcal{O}(T^{2/3} (\log T)^{1/3}) & \qquad \qquad \text{Worse than } \sqrt{T} \end{split}$$

- Generalized regret: $\bar{R}_T \le \mathcal{O}(T^{2/3}(K\log T)^{1/3})$ Every-instance regret
 - Remark: Worse than the bound obtained by EXP3 in MAB $\mathcal{O}(\sqrt{TK \log K})$

Algorithm - Explore-then-Exploit - Regret analysis

• Exploitation:
$$\Delta_a = \mu(a^*) - \mu(a) \le 4\sqrt{\frac{\log T}{N}} \to N \le 16\frac{\log T}{\Delta_a^2}$$
 (Change the order)

• Generalized regret:
$$R(T) \leq \sum_{a} 16 \frac{\log T}{\Delta_a^2} + \sum_{a} T\Delta_a$$
.

• Remark: If Δ_a is small, then Δ_a^2 is even smaller and R(T) is loose.

Algorithm - ϵ -Greedy

- Motivation: If arm have large Δ , then a lot of redundant exploration.
- Solution: Spread the exploration more uniformly over time.
- Algorithm:

```
for each round t = 1, 2, ... do

Toss a coin with success probability \epsilon_t; Change over time!

if success then

| explore: choose an arm uniformly at random

else

| exploit: choose the arm with the lowest average loss so far

end
```

Algorithm - ϵ -Greedy - Regret Analysis

```
for each round t=1,2,\ldots do

Toss a coin with success probability \epsilon_t;

if success then

| explore: choose an arm uniformly at random

else

| exploit: choose the arm with the lowest average loss so far

end
```

- Intuition: ϵ_t Decreasing sequence. Less exploration per arm!
- Regret: With $\epsilon_t = t^{-1/3} (K \log t)^{1/3}$, then $\mathbb{E}[R(T)] \leq \mathcal{O}(t^{2/3} (K \log t)^{1/3})$
 - Remark: This regret bound is stronger since it holds for all rounds $t \in [T]$

Algorithm - Successive elimination

- Motivation: Previous algorithms are non-adaptive since they do not use previous experience to prevent useless exploration!
- Solution: Use previous experience to eliminate the useless arms as soon as possible!

Algorithm:

```
All arms are initially designated as active

loop {new phase}

play each active arm once

deactivate all arms a' such that, letting t be the current round,

UCB<sub>t</sub>(a) < LCB<sub>t</sub>(a') for some other arm a' {deactivation rule}

end loop
```

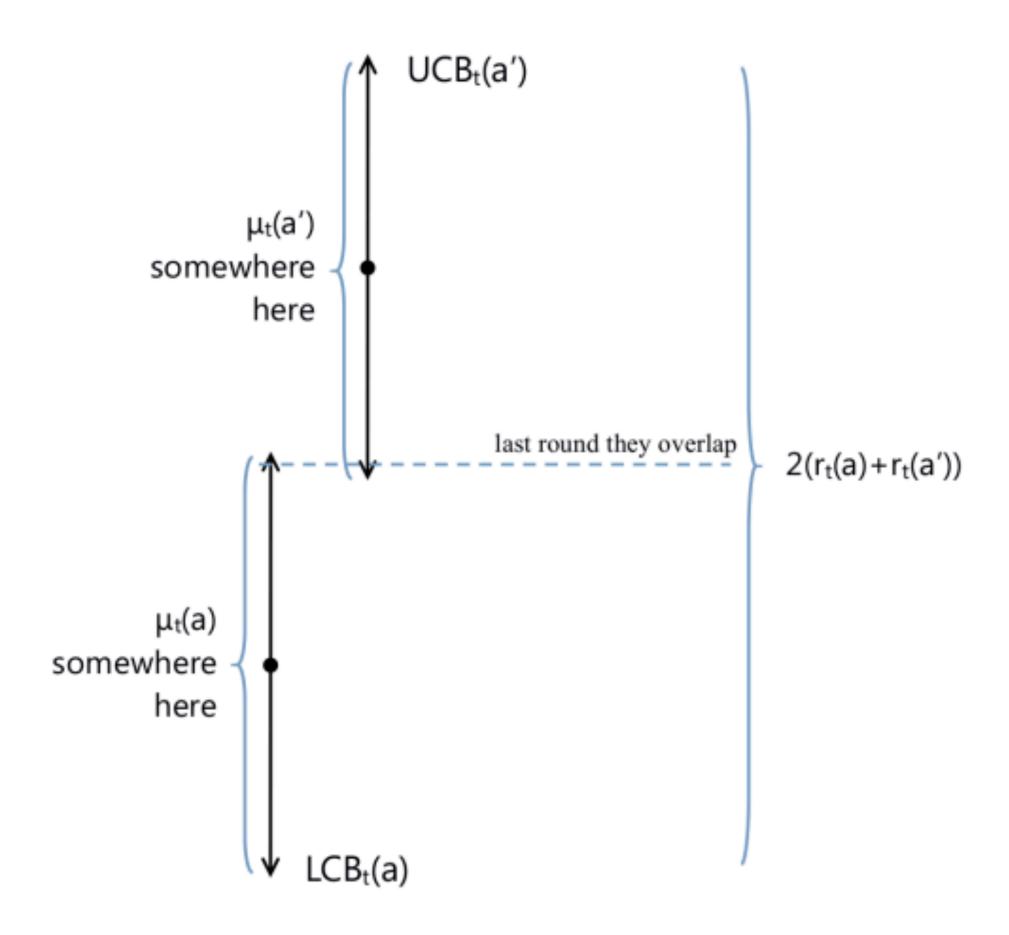
Algorithm - Successive elimination

$$LCB_{t}(a) = \hat{\mu}_{t}(a) - r_{t}(a)$$

$$UCB_{t}(a) = \hat{\mu}_{t}(a) + r_{t}(a)$$

All arms are initially designated as active \mathbf{loop} {new phase} \mathbf{play} each active arm once $\mathbf{deactivate}$ all arms a such that, letting t be the current round, $\mathbf{UCB}_t(a) < \mathbf{LCB}_t(a')$ for some other arm a' {deactivation rule} \mathbf{end} loop

• Intuition: Since $\mu(a) \in \hat{\mu}_t(a) \pm r_t(a)$, then UCB(a) < LCB(a') means $\mu(a) < \mu(a')$ with high probability.



$$R_T = \sum_{t=1}^{T} (\mu(a_t) - \mu(a^*))$$

Algorithm - Successive elimination - Regret analysis

$$\Delta_a = \mu(a^*) - \mu(a) \le 2(\sqrt{\frac{\log T}{n_t(a)}} + \sqrt{\frac{\log T}{n_t(a^*)}}) \le 4\sqrt{\frac{\log T}{n_t(a)}}$$
 Key equation! Hint: Previous pic

- $R_T(a) = n_T(a)\Delta_a \le 4\sqrt{n_T(a)\log T}$
- $R_T = \sum_a R_T(a) \le \sum_a 4\sqrt{n_T(a)\log T} \le \mathcal{O}(\sqrt{KT\log T})$ where the last inequality is obtained by Cauchy-Schwarz's inequality $\frac{1}{n}\sum_{i=1}^n f(x_i) \le f(\frac{1}{n}\sum_{i=1}^n x_i)$
- $\bar{R}_T = \mathbb{E}[R_T] = \mathcal{O}(\sqrt{TK\log T})$ This is every-instance bound!

$$R_T = \sum_{t=1}^{T} (\mu(a_t) - \mu(a^*))$$

Algorithm - Successive elimination - Regret analysis

•
$$\Delta_a \le 4\sqrt{\frac{\log T}{n_t(a)}} \to n_t(a) \le 16\frac{\log T}{\Delta_a^2}$$
 (Change the order)

$$R_T(a) = n_T(a)\Delta_a \le 16 \frac{\log T}{\Delta_a}$$

$$R_T = \sum_a R_T(a) = \sum_a 16 \frac{\log T}{\Delta_a} \le \mathcal{O}(\sum_{a:\Delta_a>0} \frac{\log T}{\Delta_a}) - \text{instance-dependence bound!}$$

- Intuition: If all arms are similar, which means it is hard to distinguish the best arm, then Δ_a will be small and regret bound will be large!
- Remark: but for the worst-case instance, the maximum regret is $\mathcal{O}(\sqrt{TK\log T})$

$LCB_t(a) = \hat{\mu}_t(a) - r_t(a)$

Algorithm - Upper Confidence Bound (UCB)

 Motivation: Assume each arm is as good as it possibly be given the observations so far, and choose the best arm based on the optimistic estimates!

Algorithm:

```
Try each arm once for each round t=1\,,\,\ldots\,,T do pick arm some a which minimizes {\sf LCB}_t(a). end for
```

• Intuition: Small LCB means either small $\hat{\mu}$ (exploit) or large r_t (explore)

Algorithm - Upper Confidence Bound (UCB) - Regret analysis

```
Try each arm once for each round t=1\,,\,\ldots\,,T do pick arm some a which minimizes {\sf LCB}_t(a). end for
```

- Assume there are 2 arms and the algorithm choose non-optimal arm a_t .
- $\hat{\mu}_t(a_t) r_t(a_t) = LCB(a_t) < LCB(a^*) < \mu(a^*)$ and $\mu(a_t) < \hat{\mu}_t(a_t) + r_t(a_t)$.

Then,
$$\Delta_{a_t} = \mu(a_t) - \mu(a^*) \le 2r_t(a_t) = 4\sqrt{\frac{\log T}{n_t(a_t)}}$$
 Key equation appears **again!**

•
$$\bar{R}_T = \mathcal{O}(\sqrt{TK \log T})$$

Algorithm - Lower bound

- Non-adaptive:
 - Every-instance bound: $\Omega(T^{2/3}K^{1/3})$ Less than $(\log T)^{1/3}$
 - Instance-dependent bound: $\Omega(C^{-2}T^{\lambda}\sum_{a}\Delta(a)) \text{ if } \bar{R}_{T} \leq C \cdot T^{\gamma},$ $\gamma \in [2/3,1), \ C>0 \text{ and } \lambda=2(1-\gamma)$ Less than $\sum_{a}\frac{1}{\Delta(a)^{2}}$
 - Remark: With $\sum \Delta(a)$ sufficiently small, $C=K^{-1/6}$, and $\lambda=2/3$, we have two above bound are equivalent!

Algorithm - Lower bound

Non-adaptive (Proof):

Algorithm - Lower bound

- Adaptive:
 - Every-instance bound: $\Omega(\sqrt{KT})$ Previous result!
 - Instance-dependent bound: Define a problem instance $I = \{\mu(a) \mid a \in K\}$ and any algorithms that satisfies $\bar{R}_t \leq C_{I,\alpha} t^{\alpha}, \quad \forall \alpha > 0$. Then, there exists t_0 such that $\forall t \geq t_0$, we have $\bar{R}_t \geq C_I \ln t$ with $\mu^*(1-\mu^*) < 1$

$$C_I = \begin{cases} \sum_{a:\Delta(a)>0} \frac{\mu^*(1-\mu^*)}{\Delta(a)} & \text{(Easier case)} \\ \sum_{a:\Delta(a)>0} \frac{\Delta(a)}{KL(\hat{\mu}_a|\,|\,\mu_{a^*})} - 2\epsilon & \forall \epsilon > 0 \text{ (Hard case)} \end{cases}$$

Algorithm - Lower bound

- Adaptive: (Proof)
 - Every-instance bound: $\Omega(\sqrt{KT})$ Previous result!
 - Instance-dependent bound: Define a problem instance $I = \{\mu(a) \mid a \in K\}$ and any algorithms that satisfies $\bar{R}_t \leq C_{I,\alpha} t^{\alpha}, \quad \forall \alpha > 0$. Then, there exists t_0 such that $\forall t \geq t_0$, we have $\bar{R}_t \geq C_I \ln t$ with $\mu^*(1-\mu^*) < 1$

$$C_I = \begin{cases} \sum_{a:\Delta(a)>0} \frac{\mu^*(1-\mu^*)}{\Delta(a)} & \text{(Easier case)} \\ \sum_{a:\Delta(a)>0} \frac{\Delta(a)}{KL(\hat{\mu}_a || \mu_{a^*})} - 2\epsilon & \forall \epsilon > 0 \text{ (Hard case)} \end{cases}$$

Algorithm - Lower bound

Adaptive: (Proof)

2. Stochastic Bandit Summary

- Stochastic environment: unknown D_a and μ_a , Pseudo-regret
- Non-adaptive: Explore-then-Exploit, ϵ —greedy
- Adaptive: Successive elimination, UCB

Setting - Motivation

- Previous section shows 2 versions of regret: instance-dependent and all-instance
- Instance-dependent regret: regret is being affected largely by pre-defined instance I.
- Question: What if we pre-define the distribution of I, sample and then update the distribution accordingly?
- Answer: Bayesian bandit!

Setting - Notation

- Prior instance: $I = \{\mu(a) \mid a \in K\}$ as well as \mathcal{D}_a
- t-history: $H_t = ((a_1, l_1), \dots, (a_t, l_t)) \in (\mathcal{A} \times \mathbb{R})^t$
- Feasible t-history: $H = ((a'_1, l'_1), \dots, (a'_t, l'_t)) \in (\mathcal{A} \times \mathbb{R})^t$
- H-consistent algorithm: $Pr(H_t = H) > 0$
- H-induced algorithm: $a_s = a'_s, \forall s \in [t]$ (deterministically)

Setting - Notation

$$\bar{R}_T = \mathbb{E}\left[\sum_{t=1}^T \left(\mu(a_t) - \mu(a^*)\right]\right]$$

• Posterior distribution of $\mathbb P$ given H:

$$\mathbb{P}_{H}(\mathcal{M}) = \Pr(\mu \in \mathcal{M} \mid H_{t} = H), \forall \mathcal{M} \subset [0,1]^{K}$$

Bayesian Regret:
$$BR(T) = \mathbb{E}_{I \sim \mathbb{P}}[\sum_{t=1}^{I} \mu(a_t) - T\mu^*]$$

Setting - Notation

• **Lemma**: Distribution \mathbb{P}_H is the same for all H-consistent bandit algorithm. In other words, \mathbb{P}_H does not depend on which H-consistent bandit algorithm has collected the history.

$$\text{Suppose } \mathscr{M} = \{\tilde{\mu}\} \text{, then } P_H(\tilde{\mu}) = \frac{\mathbb{P}_{H'}(\tilde{u}) \cdot \mathscr{D}_{\tilde{\mu}(a)}(l)}{\sum_{\tilde{\mu}} \mathbb{P}_{H'}(\tilde{u}) \cdot \mathscr{D}_{\tilde{\mu}(a)}(l)} \text{, where }$$

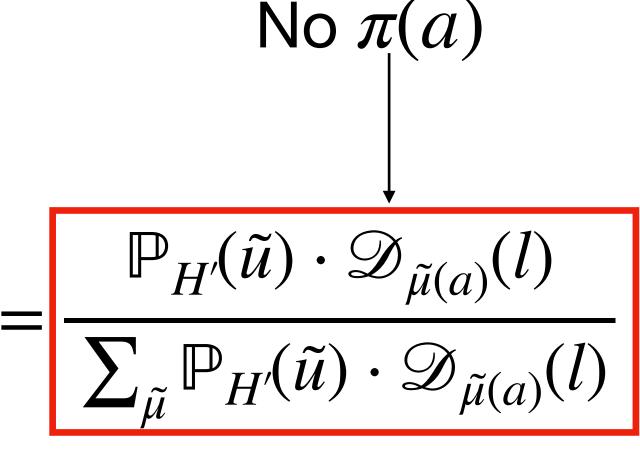
- $\mathbb{P}_{H}(\tilde{\mu}) = P(\mu = \tilde{\mu} \mid H_{t} = H)$
- $\mathscr{D}_{\tilde{\mu}(a)}(l)$ is probability of receive loss I with loss distribution with mean loss $\tilde{\mu}(a)$.
- H': is the previous history of H_{t-1}

Setting - Notation

Proof:
$$P_H(\tilde{\mu}) = \frac{\Pr(\mu = \tilde{\mu} \text{ and } H_t = H)}{\Pr(H_t = H)}$$

- $\Pr(\mu = \tilde{\mu} \text{ and } H_t = H) = \Pr(\mu = \tilde{\mu}) \mathcal{D}_{\tilde{\mu}(a)}(l) \pi(a) \Pr(H_{t-1} = H')$ where
 - $\mathcal{D}_{\tilde{u}(a)}(l) = \Pr(l_t = l \mid a_t = a \text{ and } \mu = \tilde{\mu} \text{ and } H_{t-1} = H')$
 - $\pi(a) = \Pr(a_t = a \mid H_{t-1} = H')$

$$P_{H}(\tilde{\mu}) = \frac{\Pr(\mu = \tilde{\mu} \text{ and } H_{t} = H)}{\Pr(H_{t} = H)} = \frac{\Pr(\mu = \tilde{\mu} \text{ and } H_{t} = H)}{\sum_{\tilde{\mu}} \Pr(\mu = \tilde{\mu} \text{ and } H_{t} = H)} = \frac{P_{H'}(\tilde{u}) \cdot \mathcal{D}_{\tilde{\mu}(a)}(l)}{\sum_{\tilde{\mu}} P_{H'}(\tilde{u}) \cdot \mathcal{D}_{\tilde{\mu}(a)}(l)}$$



Setting - Notation

Posterior as a new prior:

$$\mathbb{P}_{H \oplus H'}(\mathcal{M}) = P_{\mu \sim \mathcal{P}_H}(\mu \in \mathcal{M} \mid H_{t'} = H') = P_{\mu \sim \mathcal{P}_H}(\mu \in \mathcal{M} \mid H_{t'} = H', H_t = H)$$

- Intuition: Previous information H has encompassed, which means we can forget about past interaction!
- Proof: Very similar to the previous proof!

Algorithm - Thompson Sampling

Thompson Sampling admits an alternative characterization:

Algorithm 3.2: Thompson Sampling: alternative characterization.

$$\mathbf{P}_{H}(\tilde{\mu}) = \frac{P(H_{t} = H | \mu = \tilde{\mu}) \mathbb{P}(\tilde{\mu})}{\sum_{\tilde{\mu}} P(H_{t} = H | \mu = \tilde{\mu}) \mathbb{P}(\tilde{\mu})}$$

- Problem: Mathematically well-defined, but computationally inefficiency!
 - Computation of $P(H_t=H\,|\,\mu=\tilde{\mu})$ is t and the total computation of \mathbb{P}_H is $t\cdot \mid \mathcal{F}\mid$

Algorithm - Thompson Sampling

Thompson Sampling admits an alternative characterization:

Algorithm 3.2: Thompson Sampling: alternative characterization.

Improvement: sequential Bayesian update
$$P_{H'}(\tilde{\mu}) = \frac{\mathbb{P}_{H}(\tilde{u}) \cdot \mathcal{D}_{\tilde{\mu}(a)}(l)}{\sum_{\tilde{\mu}} \mathbb{P}_{H}(\tilde{u}) \cdot \mathcal{D}_{\tilde{\mu}(a)}(l)}$$

• Even faster: Independent prior (independent arms), conjugate prior (Beta-Bernoulli, Guassian-Gaussian)

Algorithm - Regret

• Lemma: If
$$\mathbb{E}[[U(a,H_t)-\mu(a)]^-] \leq \frac{\gamma}{TK}$$
 and $\mathbb{E}[[\mu(a)-L(a,H_t)]^-] \leq \frac{\gamma}{TK}$, then $BR(T) \leq 2\gamma + 2\sum_{t=1}^T \mathbb{E}[l(a_t,H_t)]$ with $l(a_t,H_t) = U(a_t,H_t) - L(a_t,H_t)$

 Remark: Do not depend the structure of prior, or specify how to calculate how to calculate U and L

• Theorem: With radius
$$l(a_t, H_t) = \sqrt{\frac{\log T}{n_t(a)}}$$
 define as above, then $BR(T) \leq O(\sqrt{KT \log T})$

Similar to previous result

Revisted EXP3

• Theorem: Let
$$F_t = \sum p_t(a) \cdot c_t(a) = \mathbb{E}[c_t(a_t) \, | \, w_t]$$
 where $p_t(a) = \frac{w_t(a)}{\sum_a w_t(a)}$, $G_t = \sum_a p_t(a) \cdot c_t(a)^2 = \mathbb{E}[c_t(a_t)^2 \, | \, w_t]$ where $\sum_a \mathbb{E}[G_t] \leq uT$ for some known u. Then, $\alpha = \ln(\frac{1}{1-\epsilon}), \beta = \alpha^2, \epsilon = \sqrt{\frac{\ln K}{3uT}}$,
$$\mathbb{E}[cost(ALG) - cost^*] < 2\sqrt{3}\sqrt{uT\ln K}$$

Revisted Exp3

- Remark: Exp3 does not have experts, only arms (no context). Exp3 is a generalization of Hedge with lost estimator
- Motivation Exp3 does not work well with correlated/dependent arms, large # arms leads to large regret!
- Answer: Exp4 generalization of Exp3
- Exp3 = Exponential-weight algorithm for Exploration and Exploitation
- Exp4 = Exponential-weight algorithm for Exploration and Exploitation using Expert Advices

Notation

- Assumption: $\mathbb{E}[\hat{c}_t(e) | \mathbf{p}_t] = c_t(e)$
- Distribution over experts: $p_t(e) := \Pr(e_t = e)$
- Distribution over arms: $q_t(a) = \Pr(a_t = a \mid p_t)$
- . Fake cost: $\hat{c}_t(a) = \frac{c_t(a_t)}{q_t(a_t)}$ if $a_t = a$ and $\hat{c}_t(e) = \hat{c}_t(a_{t,e})$
- $\mathbb{E}[\hat{c}_t(a) | p_t] = c_t(a)$

Notation

. Regret (refined):
$$R(T) = cost(ALG) - \min_{e \in \mathscr{E}} cost(e)$$
 where $cost(e) = \sum_{t} c_t(a_{t,e}) = \sum_{t} c_t(e)$

Another version:

$$R(T) = cost(ALG) - \sum_{t=1}^{T} \sum_{a=1}^{N} e_{t,i^*}(a)l_t(a) = cost(ALG) - \min_{i} \sum_{t=1}^{T} \sum_{a=1}^{N} e_{t,i}(a)l_t(a)$$

• Remark: Before, we compare the cost of the algorithm versus the best arm, which is unchanged throughout T rounds. However, the "best" experts can change their decision throughout T rounds, which is more flexible notion!

Algorithm

Given: set \mathcal{E} of experts, parameter $\epsilon \in (0, \frac{1}{2})$ for Hedge, exploration parameter $\gamma \in [0, \frac{1}{2})$. In each round t,

- 1. Call Hedge, receive the probability distribution p_t over \mathcal{E} .
- 2. Draw an expert e_t independently from p_t .
- 3. Selection rule: with probability 1γ follow expert e_t ; else pick an arm a_t uniformly at random.
- 4. Observe the cost $c_t(a_t)$ of the chosen arm.
- 5. Define fake costs for all experts e:

$$\widehat{c}_t(e) = \left\{ egin{array}{ll} rac{c_t(a_t)}{\Pr[a_t = a_{t,e} | \vec{p_t}]} & a_t = a_{t,e}, \\ 0 & ext{otherwise.} \end{array}
ight.$$

6. Return the "fake costs" $\widehat{c}(\cdot)$ to Hedge.

Algorithm

Algorithm 1 EXP4 for contextual bandits

Initialize $w_1 = (1, 1, ..., 1);$

for $t = 1 \rightarrow T$ do

EG gives us probability over experts $p_t \in \Delta(M)$: $p_t = \frac{w_t}{\|w_t\|}$;

Compute probability q_t over actions by integrating out expert $i: \forall a, q_t(a) = \sum_{i=1}^{M} p_{t,i} e_{t,i}(a)$;

Draw action $a_t \sim q_t$, and incur loss $l_t(a_t)$;

Build the unbiased estimate for full feedback l_t :

$$\forall a, \hat{l}_t(a) = \begin{cases} l_t(a_t)/q_t(a_t), & \text{if } a = a_t; \\ 0, & \text{otherwise;} \end{cases}$$

Compute the expected loss g_t :

$$\forall i, g_{t,i} = \sum_{a=1}^{A} e_{t,i}(a)l_t(a) = \frac{e_{t,i}(a_t)l_t(a_t)}{q_t(a_t)};$$

EG update w_t from g_t : $\forall i, w_{t+1,i} = w_t \exp \left(-\eta \sum_{s=1}^t g_{t,i}\right)$; end for

Regret Analysis

- Regret: $\mathbb{E}[R(T)] \leq O(\sqrt{KT \log N})$
- Proof:

Proof. For each arm a, let $\mathcal{E}_a = \{e \in \mathcal{E} : a_{t,e} = a\}$ be the set of all experts that recommended this arm. Let

$$p_t(a) := \sum_{e \in \mathcal{E}_a} p_t(e)$$

be the probability that the expert chosen by Hedge recommends arm a. Then

$$q_t(a) = p_t(a)(1-\gamma) + \frac{\gamma}{K} \ge (1-\gamma) \ p_t(a).$$

For each expert e, letting $a=a_{t,e}$ be the recommended arm, we have:

$$\widehat{c}_t(e) = \widehat{c}_t(a) \le \frac{c_t(a)}{q_t(a)} \le \frac{1}{q_t(a)} \le \frac{1}{(1-\gamma) p_t(a)}.$$
 (6.4)

Regret Analysis

- Regret: $\mathbb{E}[R(T)] \leq O(\sqrt{KT \log N})$
- **Proof:** Each realization of \widehat{G}_t satisfies:

$$\begin{split} \widehat{G}_t &:= \sum_{e \in \mathcal{E}} p_t(e) \ \widehat{c}_t^2(e) \\ &= \sum_a \sum_{e \in \mathcal{E}_a} p_t(e) \cdot \widehat{c}_t(e) \cdot \widehat{c}_t(e) \qquad \qquad (\textit{re-write as a sum over arms}) \\ &\leq \sum_a \sum_{e \in \mathcal{E}_a} \frac{p_t(e)}{(1-\gamma) \ p_t(a)} \ \widehat{c}_t(a) \qquad \qquad (\textit{replace one } \widehat{c}_t(a) \ \textit{with an upper bound (6.4)}) \\ &= \frac{1}{1-\gamma} \sum_a \frac{\widehat{c}_t(a)}{p_t(a)} \sum_{e \in \mathcal{E}_a} p_t(e) \qquad \qquad (\textit{move "constant terms" out of the inner sum}) \\ &= \frac{1}{1-\gamma} \sum_a \widehat{c}_t(a) \qquad \qquad (\textit{the inner sum is just } p_t(a)) \end{split}$$

To complete the proof, take expectations over both sides and recall that $\mathbb{E}[\widehat{c}_t(a)] = c_t(a) \leq 1$.

Regret Analysis

- Regret: $\mathbb{E}[R(T)] \leq O(\sqrt{KT \log N})$
- Proof:

Let us complete the analysis, being slightly careful with the multiplicative constant in the regret bound:

$$\mathbb{E}\left[\widehat{R}_{\mathsf{Hedge}}(T)\right] \leq 2\sqrt{3/(1-\gamma)} \cdot \sqrt{TK \log N}$$

$$\mathbb{E}\left[R_{\mathsf{Exp4}}(T)\right] \leq 2\sqrt{3/(1-\gamma)} \cdot \sqrt{TK \log N} + \gamma T \qquad (by Eq. (6.3))$$

$$\leq 2\sqrt{3} \cdot \sqrt{TK \log N} + 2\gamma T \qquad (since \sqrt{1/(1-\gamma)} \leq 1 + \gamma) \qquad (6.5)$$

Motivation

- Motivation: The expert is the context so far!
- **Examples**: "User profile", feature of the environment (day of the week, season, proximity to a major event), features of their own, indicate the set of feasible features.

Notation

- x_t : context, \mathcal{X} : set of contexts
- a_t : action given the context, \mathscr{A} : set of actions, $|\mathscr{A}| = K$
- l_t : loss
- $\pi:\mathcal{X}\to\mathcal{A}$: a policy, Π : a class of policy

• Regret:
$$R(T) = \sum_{t=1}^{T} l_t(a_t) - \min_{\pi \in \Pi} \sum_{t=1}^{T} l_t(\pi(x_t))$$

• Stochastic bandit: $l_t \sim \mathcal{P}(.|x_t, a_t)$

Revisted

- Regret: $\mathbb{E}[R(T)] \leq O(\sqrt{KT \log N})$
- **Drawbacks**: If $|\Pi|$ is continuous, then huge regret! Ignore the structure of the context!

Notation

- θ_a^* : coefficient vector ($|\theta_a^*|_2 \le S$)
- $x_{a,t}$: context for each arm
- $l_{a,t} = x_{a,t}^T \theta_a^* + \epsilon_t$ with $\epsilon_t \sim \text{R-sub-Gaussian}$

$$X_{a,t} = \begin{bmatrix} x_{a,1}^T \\ \cdots \\ x_{a,m}^T \end{bmatrix} \text{ (Suppose pull m times before), } \Gamma_{a,t} = \begin{bmatrix} l_{a,1} \\ \cdots \\ l_{a,m} \end{bmatrix}$$

•
$$b_{a,t} = X_{a,t}^T \Gamma_{a,t}$$

Notation

- Ridge regression estimator: $\hat{\theta}_{a,t} = (X_{a,t}^T X_a + \lambda I)^{-1} b_{a,t}$
- $A_{a,t} = I\lambda + \sum_{s=1}^{t} x_{a,s} x_{a,s}^{T}$ (λ regularization parameter related to sub-Gaussian variable)
- $\theta_a^* \in C_{a,t}$ where

$$C_{a,t} = \{\theta_a^* \in \mathbb{R}^d : ||\hat{\theta}_{a,t} - \theta_a^*||_{A_{a,t}} \le R\sqrt{2\log(\frac{\det(A_{a,t})^{1/2}\det(\lambda I)^{-1/2}}{\delta}} + \lambda^{1/2}S\}$$

$$a_t = \underset{a}{\operatorname{arg max}} \underset{\theta_a \in C_{a,t-1}}{\operatorname{max}} x_{a,t}^T \theta_a$$

Algorithm

```
Algorithm 3 LinUCB with Contextual Bandits
   Input: R \in \mathbb{R}^+, regularization parameter \lambda
   for t = 1, 2, ..., T do
        Observe feature vectors of all arms a \in \mathcal{A}_t: \mathbf{x}_{a,t} \in \mathbb{R}^d
        for all a \in \mathcal{A}_t do
            if a is new then
                \mathbf{A}_a \leftarrow \lambda \mathbf{I}_d (d-dimensional identity matrix)
                \mathbf{b}_a \leftarrow \mathbf{0}_{d \times 1} (d-dimensional zero vector)
            end if
           \hat{\theta}_a \leftarrow \mathbf{A}_a^{-1} \mathbf{b}_a
          C_{a,t} \leftarrow \left\{ \theta_a^* \in \mathbb{R}^d : \left| \left| \hat{\theta}_{a,t} - \theta_a^* \right| \right|_{\mathbf{A}_a} \le R \sqrt{2 \log \left( \frac{\det(\mathbf{A}_a)^{1/2} \det(\lambda I)^{-1/2}}{\delta} \right)} + \lambda^{1/2} S \right\}
           p_{a,t} \leftarrow \arg\max_{\hat{\theta}_a \in C_{a,t}} \mathbf{x}_{a,t}^T \hat{\theta}_a
        end for
        Choose arm a_t = \arg\max_{a \in \mathcal{A}_t} p_{a,t} with ties broken arbitrarily, and observe payoff r_t
        \mathbf{A}_{a_t} \leftarrow \mathbf{A}_{a_t} + \mathbf{x}_{a_t,t} \mathbf{x}_{a_t,t}^T
        \mathbf{b}_{a_t} \leftarrow \mathbf{b}_{a_t} + r_t \mathbf{x}_{a_t,t}
   end for
```

4. Contextual Bandit

Regret analysis

•
$$R_n = O(RS\lambda^{1/2}dK \ln(T/\delta)\sqrt{T})$$

• Proof: Skipped due to martingale properties!

Motivation

- Dynamic pricing:
 - A seller: B copies of an item.
 - A customer: Buy items
 - For round t = 1,...,T
 - A seller put a price p_t on an item, while the customer values v_t on that item.
 - If $v_t \ge p_t$, then the customer will buy the item. Otherwise, there is no sale.
 - If the customer buy the item, the seller will receive p_t as a reward.
 - The algorithm stop when either t=T or no more copies of the item.

Objective:
$$\max_{t=1}^{T} p_t$$

• Remark: B < T

Formalization

Problem protocol: Bandits with Knapsacks (BwK)

Parameters: K arms, d resources with respective budgets B_1 , ..., $B_d \in [0, T]$. In each round t = 1, 2, 3 ...:

- 1. Algorithm chooses an arm $a_t \in [K]$.
- 2. Outcome vector $\vec{o}_t = (r_t; c_{t,1}, \ldots, c_{t,d}) \in [0,1]^{d+1}$ is observed, where r_t is the algorithm's reward, and $c_{t,i}$ is consumption of each resource i.

Algorithm stops when the total consumption of some resource i exceeds its budget B_i .

- Remark: Outcome vector given a selected arm is sampled i.i.d.
- Remark: Time is also a resource.
- Goal: Maximize the total reward.

Formalization - Different from regular bandit setting

- Example (Motivation): 2 arms, 2 products, each has M budgets, each arm will select one of the product, consume 1 unit and get 1 reward. Assume T > 2M.
 - For regular bandit, we can choose either arm and play repeatedly! The total rewards will be M.
 - However, alternating two arms can lead to 2M rewards!

Key difference:

- Non-systematic exploration at the beginning can be harmful in the long-term due to constraint budget.
- Expected per-round reward is no longer a right objective because of high resource consumption.
- Fixed arm is not longer suitable, rather a distribution of arms.

Examples

• Dynamic pricing: Suppose d=1 with resource is B_1 . K Arms corresponds to K different prices. Goal is to maximize $\sum_{t=1}^{\infty} p_t$

$$o_t = \begin{cases} (p_t, 1) & p_t \ge v_t \\ (0, 0) & \text{Otherwise} \end{cases}$$

• Dynamic pricing for hiring: Suppose d=1 job with budget B_1 . K arms corresponds to K different prices. Goal is to maximize $\sum_{t=1}^T 1[p_t \ge v_t]$

$$o_T = \begin{cases} (1, p_t) & p_t \ge v_t \\ (0, 0) & \text{otherwise} \end{cases}$$

• Pay-per-click ad allocation: Suppose d=1 site with budge B_1 . K arms corresponds to K ads. Goal is to maximize the number of clicks

•
$$o_t = \begin{cases} (r_a, r_a) & \text{if click with probability } q_a \\ (0,0) & \text{Otherwise} \end{cases}$$

Algorithms - Primal-Dual methods

• Linear relaxation: Consider a fixed distribution D and outcomes o equals to expected value of outcomes. Then, optimizing D using linear programming.

$$r(D) = \sum_{a} D(a)r(a), c_i(D) = \sum_{a} D(a)c_i(a)$$

- $\max r(D)$ subject to $D \in \Delta_K$, $T \cdot c_i(d) \leq B \, \forall i \in [d]$
- Corollary: $T \cdot OPT_{LP} \ge OPT$

Algorithms - Primal-Dual methods

Langrange game:

Lagrange function:
$$L(D,\lambda)=r(D)+\sum_{i\in D}\lambda_i(1-\frac{T}{B}c_i(D))$$
 where $\lambda\in\Delta^d$

- Langrange game: zero-sum game, primal player selects action, dual player selects resources, and the payoff $L(a,i)=r(a)+1-\frac{T}{B}c_i(a)$
- Lemma:
 - D^* is optimal for the linear programming.
 - . $1 \frac{T}{B}c_i(D^*) \ge 0$, with the equality if $\lambda_i^* > 0$
 - $L(D^*, \lambda^*) = OTP_{LP}$

Algorithms - Primal-Dual methods

- Repeated Lagrange game: $L_t(a, i) = r_t(a) + 1 \frac{I}{B}c_{t,i}(a)$
 - Remark: $\mathbb{E}[L_t(a,i)] = L(a,i)$

```
Given: time horizon T, budget B, number of arms K, number of resources d.
```

Bandit algorithm ALG_1 : action set [K], maximizes rewards, bandit feedback.

Bandit algorithm ALG_2 : action set [d], minimizes costs, full feedback.

for round
$$t = 1, 2, ...$$
 (until stopping) do

 \mathtt{ALG}_1 returns arm $a_t \in [K]$, algorithm \mathtt{ALG}_2 returns resource $i_t \in [d]$.

Arm a_t is chosen, outcome vector $\vec{o}_t = (r_t(a_t); c_{t,1}(a_t), \ldots, c_{t,d}(a_t)) \in [0, 1]^{d+1}$ is observed.

The payoff $\mathcal{L}_t(a_t, i_t)$ from (10.10) is reported to ALG₁ as reward, and to ALG₂ as cost.

The payoff $\mathcal{L}_t(a_t, i)$ is reported to ALG_2 for each resource $i \in [d]$.

end

Algorithm 10.1: Algorithm LagrangeBwK

Algorithms - Primal-Dual methods

• **Regret:** Suppose ALG_1 is EXP3 and ALG_2 is Hedge, then the regret bound is achieved with the probability at least $1-\delta$

$$OPT - REW \le O(T/B) \sqrt{TK \ln \frac{dT}{\delta}}$$

• Optimal **only** in the region $B=\Omega(T)$

Algorithms - UCB-like methods

Let
$$M_t = \begin{bmatrix} r_t(a_1) & c_{1,t}(a_1) & \dots & c_{d,t}(a_1) \\ \dots & \dots & \dots \\ r_t(a_k) & c_{t,1}(a_k) & \dots & c_{t,d}(a_k) \end{bmatrix}$$

- Define ConfReg is a confidence region around M_t ,
- . $UCB_t(D \mid B) = \sup_D LP(D \mid B, M)$ for some $M \in \text{ConfReg.}$

```
Rescale the budget: B' \leftarrow B(1-\epsilon), where \epsilon = \tilde{\Theta}(\sqrt{K/B})

Initialization: pull each arm once.

for all subsequent rounds t do

| In each round t, pick distribution D = D_t with highest \text{UCB}_t(\cdot \mid B').

| Pick arm a_t \sim D_t.

end
```

Algorithm 10.3: UcbBwK: Optimism under Uncertainty with Knapsacks.

Algorithms - UCB-like methods

• Regret:
$$OPT - \mathbb{E}[REW] \le O(\sqrt{K \cdot OPT} + OPT\sqrt{\frac{K}{B}})$$

- Remark: $\sqrt{K \cdot OPT}$ is similar to stochastic bandit!
- Remark: Optimal for any given triple (K, B, T)

Generalization - Contextual bandits

LagrangeBwK:

•
$$OPT_{\Pi} - \mathbb{E}[REW] \le \tilde{O}(T/B)\sqrt{KT \log |\Pi|}$$

- ALG1 is Exp4, but not computationally efficient.
- Successive elimination and Policy elimination:

•
$$OPT_{\Pi} - \mathbb{E}[REW] \le \tilde{O}(1 + OPT_{\Pi}/B)\sqrt{KT \log |\Pi|}$$

- Not computationally efficient.
- UcbBwK (Linear contextual bandit):

•
$$OPT - \mathbb{E}[REW] \le \tilde{O}(m\sqrt{T})(1 + OPT/B)$$
 in regime $B > mT^{3/4}$

Not computationally efficient.

Generalization - Bandit convex optimization

•
$$o_t = (f_t, g_{t,1}, \dots, g_{t,d})$$
 where $f_t : \mathcal{X} \to [0,1], g_{t,i} : \mathcal{X} \to [0,1]$ and $\mathcal{X} \subset \mathbb{R}^K$

- f_t is a concave function, $g_{t,i}$ is a convex function, \mathcal{X} is a convex set.
- . LagrangeBwK: $\frac{T}{B}\sqrt{T} \cdot poly(K \log T)$

Generalization - Adversarial

- Sequence M_1, \ldots, M_T are fixed, not sampling, before round 1.
- Challenge: How much budget to save for the future, without being able to predict.
- . Competitive ratio: $\frac{OPT_{FD}}{\mathbb{E}[REW]}$
- Modified LagrangeBwK: $(OPT_{FD} reg)/\mathbb{E}[REW] \le O_d(\log T)$

•
$$reg = O(1 + \frac{OPT_{FD}}{dB})\sqrt{TK\log(Td)}$$

- Remark: Time is not include in the outcome matrices
- . Remark: $\frac{T}{B}$ is replaced by $\gamma \in (0, \frac{T}{B}]$, which is sampled at random

Generalization - Best in both worlds

- Corrupted environments: mixed between adversarial and stochastic environment!
- Recent researches seem to focus on this problem (Neurips, ICML, ICLR)