



183. The maximum value of the determinant among all 2×2 real symmetric matrices with trace 14 is _____.

(GATE-14-EC-SET2)

trace of a matrix is sum of principal diagonal elements

$$A = \begin{bmatrix} a & b \\ b & c \end{bmatrix} \quad \left| \begin{array}{l} |A| = ac - b^2 \\ \text{To get max value of } |A|, \text{ we need } b^2 = 0 \Rightarrow b = 0 \end{array} \right.$$

$$a + c = 14$$

$$\left| \begin{array}{l} |A| = ac \\ \text{max } ac \\ \text{such that } a + c = 14 \\ \Rightarrow c = 14 - a \\ |A| = a(14 - a) \end{array} \right.$$

$$\left| \begin{array}{l} |A| = 14a - a^2 \rightarrow f(a) \\ f'(a) = 14 - 2a = 0 \\ a = 7 \\ f''(a) = -2 \quad f''(7) = -2 < 0 \\ \text{we get max value at } a = 7 \quad |A| = 14 \times 7 - 7^2 = 49 \end{array} \right.$$



Inverse of a Matrix

- ✓ ► Only non-singular matrices are invertible.
- **B** is called as Inverse of matrix **A** if

$$\mathbf{AB} = \mathbf{BA} = \mathbf{I} \implies \mathbf{B} = \mathbf{A}^{-1}$$

$$\mathbf{A}^{-1} = \frac{\text{Adj}(\mathbf{A})}{\det(\mathbf{A})}$$

where $\text{Adj}(\mathbf{A})$ is the cofactor matrix transpose.

$$\text{Adj}(\mathbf{A}) = (\text{cofactor matrix})^T$$

$$\mathbf{A}^{-1} = \frac{\text{Adj}(\mathbf{A})}{|\mathbf{A}|}$$

$$\text{Adj}(\mathbf{A}) = (\text{cofactor matrix of } \mathbf{A})^T$$

$$\boxed{\mathbf{AA}^{-1} = \mathbf{A}^{-1}\mathbf{A} = \mathbf{I}}$$



Find the inverse of the following matrix

$$\mathbf{A} = \begin{bmatrix} -1 & -2 & -2 \\ 2 & 1 & -2 \\ 2 & -2 & 1 \end{bmatrix}$$

Cofactor
matrix
of A

$$= \begin{bmatrix} -3 & -6 & -6 \\ 6 & 3 & -6 \\ 6 & -6 & 3 \end{bmatrix}$$

$$\text{Adj}(\mathbf{A}) = \begin{bmatrix} -3 & 6 & 6 \\ -6 & 3 & -6 \\ -6 & -6 & 3 \end{bmatrix}, \quad \mathbf{A}^{-1} = \frac{1}{27} \begin{bmatrix} -3 & 6 & 6 \\ -6 & 3 & -6 \\ -6 & -6 & 3 \end{bmatrix}$$

$$|\mathbf{A}| = 27$$



If $\mathbf{A}_{n \times n}$ is a non-singular then

$$|\mathbf{A}^{-1}| = \frac{1}{|\mathbf{A}|}$$

$$|\text{Adj}(\mathbf{A})| = |\mathbf{A}|^{n-1}$$

$$\text{H/w } \text{Adj}(\text{Adj}(\mathbf{A})) = \underline{\hspace{2cm}}$$

$$\text{H/w } |\text{Adj}(\text{Adj}(\mathbf{A}))| = \underline{\hspace{2cm}}$$

$$\mathbf{A}\mathbf{A}^{-1} = \mathbf{I}$$

$$|\mathbf{A}\mathbf{A}^{-1}| = |\mathbf{I}|$$

$$|\mathbf{A}| |\mathbf{A}^{-1}| = 1$$

$$|\mathbf{A}^{-1}| = \frac{1}{|\mathbf{A}|}$$

$$|\mathbf{AB}| = |\mathbf{A}| |\mathbf{B}|$$

$$\mathbf{C} = \alpha \mathbf{A}$$

$$|\mathbf{C}| = \alpha^n |\mathbf{A}|$$

$$\left. \begin{aligned} \mathbf{A}^{-1} &= \frac{\text{Adj}(\mathbf{A})}{|\mathbf{A}|} \\ \text{Adj}(\mathbf{A}) &= |\mathbf{A}| \mathbf{A}^{-1} \end{aligned} \right\} \begin{aligned} |\text{Adj}(\mathbf{A})| &= (|\mathbf{A}| |\mathbf{A}^{-1}|) \\ &= |\mathbf{A}|^n |\mathbf{A}^{-1}| \\ &= |\mathbf{A}|^n \cdot \frac{1}{|\mathbf{A}|} = |\mathbf{A}|^{n-1} \end{aligned}$$



03. If $A = \begin{bmatrix} 1 & -1 & 0 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$ and $B = A^{-1}$, then the element in the second row and third column of $B =$ _____.

- (a) 0 (b) $\frac{1}{2}$
 (c) $-\frac{1}{2}$ (d) 1

$$A^{-1} = \frac{\text{Adj}(A)}{|A|} = B \Rightarrow b_{23}$$

Cofactor matrix of $A = \begin{bmatrix} - & - & - \\ - & - & - \\ - & - & - \end{bmatrix}_{3 \times 3}$

$\text{Adj}(A) = \begin{bmatrix} - & - & - \\ - & - & - \\ - & - & - \end{bmatrix}_{3 \times 3}$ $b_{23} = \frac{1}{|A|}$

cofactor of $a_{32} = (-1)^{3+2} \begin{vmatrix} 1 & 0 \\ 1 & 1 \end{vmatrix} = -1$

$|A| = 0(1) + 0(1) + 1(-1) = -1$
 $b_{23} = -1/-1 = 1$



291. Consider a 2×2 matrix $M = [v_1, v_2]$, where, v_1 and v_2 are the column vectors.

Suppose $M^{-1} = \begin{bmatrix} u_1^T \\ u_2^T \end{bmatrix}$, where u_1^T and u_2^T are the row vectors.

Consider the following statements:

Statement 1: $u_1^T v_1 = 1$ and $u_2^T v_2 = 1$

Statement 2: $u_1^T v_2 = 0$ and $u_2^T v_1 = 0$

Which of the following options is correct?

(GATE-19-EE)

- (a) Statement 2 is true and statement 1 is false
- (b) Both the statements are false
- (c) Statement 1 is true and statement 2 is false
- (d) Both the statements are true

$$M = [v_1 \ v_2]_{2 \times 2} = \begin{bmatrix} 1 & 1 \end{bmatrix}$$

$$M^{-1} = \begin{bmatrix} u_1^T \\ u_2^T \end{bmatrix} = \begin{bmatrix} \text{---} \\ \text{---} \end{bmatrix}$$

$$\begin{bmatrix} \text{---} \\ \text{---} \end{bmatrix} \begin{bmatrix} 1 & 1 \end{bmatrix}$$

$$u_1^T \cdot v_1 = (\text{---}) \begin{pmatrix} 1 \\ 1 \end{pmatrix} = ()$$

$$M^{-1} \cdot M = I$$

$$M M^{-1} = I$$

$$\begin{bmatrix} \text{---} \\ u_1^T \\ u_2^T \end{bmatrix} \begin{bmatrix} v_1 & v_2 \end{bmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$u_1^T v_1 = 1 \quad u_1^T v_2 = 0$$

$$u_2^T v_1 = 0 \quad u_2^T v_2 = 1$$



297. The inverse of the matrix $\begin{bmatrix} 2 & 3 & 4 \\ 4 & 3 & 1 \\ 1 & 2 & 4 \end{bmatrix}$ is

(GATE-19-CE-SET2)

(a) $\begin{bmatrix} -10 & 4 & 9 \\ 15 & -4 & -14 \\ -5 & 1 & 6 \end{bmatrix}$

(b) $\begin{bmatrix} 2 & -\frac{4}{5} & -\frac{9}{5} \\ -3 & \frac{4}{5} & \frac{14}{5} \\ 1 & -\frac{1}{5} & -\frac{6}{5} \end{bmatrix}$

(c) $\begin{bmatrix} -2 & \frac{4}{5} & \frac{9}{5} \\ 3 & -\frac{4}{5} & -\frac{14}{5} \\ -1 & \frac{1}{5} & \frac{6}{5} \end{bmatrix}$

(d) $\begin{bmatrix} 10 & -4 & -9 \\ -15 & 4 & 14 \\ 5 & -1 & -6 \end{bmatrix}$

a)

$$\begin{bmatrix} 2 & 3 & 4 \\ 4 & 3 & 1 \\ 1 & 2 & 4 \end{bmatrix} \begin{vmatrix} -10 \\ 15 \\ -5 \end{vmatrix}$$

$$AA^{-1} = I = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$= -20 + 45 - 20 = -5 \neq 1$$

b)

$$\begin{bmatrix} 2 & 3 & 4 \\ 4 & 3 & 1 \\ 1 & 2 & 4 \end{bmatrix} \begin{vmatrix} 2 \\ -3 \\ 1 \end{vmatrix}$$

$$= 4 - 9 + 4 = -1 \neq 1$$

$$\begin{bmatrix} 2 & 3 & 4 \\ 4 & 3 & 1 \\ 1 & 2 & 4 \end{bmatrix} \begin{vmatrix} 10 \\ -15 \\ 5 \end{vmatrix} =$$

$$20 - 45 + 20$$

$$= -5 \neq 1$$

c)

$$\begin{bmatrix} 2 & 3 & 4 \\ 4 & 3 & 1 \\ 1 & 2 & 4 \end{bmatrix} \begin{vmatrix} -2 \\ 3 \\ -1 \end{vmatrix}$$

$$= -4 + 9 - 4 = 1$$

Ans : (C)

#w

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 3 & 6 & 9 \end{pmatrix} .$$

$$|A| = 0$$

$$\text{Adj } A = \bigcirc$$



Rank of a matrix

For a matrix $A_{m \times n}$

- ▶ $\text{rank}(\mathbf{A})$ denotes the number of nonzero rows in any row echelon form that is row equivalent to \mathbf{A} .
 - ▶ $\text{rank}(\mathbf{A})$ denotes the number of pivots obtained in reducing \mathbf{A} to a row echelon form with row operations.
 - ▶ $\text{rank}(\mathbf{A})$ denotes the size of the largest nonzero minor of \mathbf{A} .
 - ▶ $\text{rank}(\mathbf{A})$ denotes the number of linearly independent rows or columns of A
-



Use determinants to compute the rank of

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 4 & 5 & 6 & 1 \\ 7 & 8 & 9 & 1 \end{bmatrix}_{3 \times 4}$$

$$\begin{vmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{vmatrix}_{3 \times 3} = 0$$

$$\begin{vmatrix} 1 & 2 & 1 \\ 4 & 5 & 1 \\ 7 & 8 & 1 \end{vmatrix}_{3 \times 3} = 0$$

$$\begin{vmatrix} 1 & 3 & 1 \\ 4 & 6 & 1 \\ 7 & 9 & 1 \end{vmatrix}_{3 \times 3} = 0$$

$$\begin{vmatrix} 2 & 3 & 1 \\ 5 & 6 & 1 \\ 8 & 9 & 1 \end{vmatrix}_{3 \times 3} = 0$$

$$R(\mathbf{A}) \neq 3$$

$$\begin{vmatrix} 1 & 2 \\ 4 & 5 \end{vmatrix} = 5 - 8 = -3 \neq 0$$

$$R(\mathbf{A}) = 2$$



Let \mathbf{A} be $m \times n$ matrix

- ✓ ▶ $\text{rank}(\mathbf{A}) \leq \min(m, n)$.
- ▶ $\text{rank}(\mathbf{A} + \mathbf{B}) \leq \text{rank}(\mathbf{A}) + \text{rank}(\mathbf{B})$.
- ▶ If \mathbf{A} is $m \times n$ and \mathbf{B} is $n \times p$, then $\text{rank}(\mathbf{AB}) \leq \min \{ \text{rank}(\mathbf{A}), \text{rank}(\mathbf{B}) \}$
- ✓ ▶ $\text{rank}(\mathbf{AA}^T) = \text{rank}(\mathbf{A}) = \text{rank}(\mathbf{A}^T\mathbf{A}) \Rightarrow$ appeared multiple times in GATE
- ▶ The rank of a non-zero matrix is non-zero.
- ▶ The rank of a null matrix is zero.
- ▶ The rank of non-singular matrix is its order.
- ▶ The rank of singular matrix is less than its order.

$$A_{3 \times 4}$$

$$R(A) \leq \min(3, 4)$$

$$\boxed{R(A) \leq 3}$$

$$|A_{n \times n}| \neq 0 \quad R(A) = \underline{\underline{n}}$$

$$|A| = 0 \quad R(A) < \underline{\underline{n}}$$



Nullity of a matrix is defined as the difference between order and rank of the matrix.

Nullity of a non-singular matrix of any order is always zero.



01. Let $A = \begin{bmatrix} 3 & P & P \\ P & 3 & P \\ P & P & 3 \end{bmatrix}$. If rank of A is 1, then

$$P = \underline{3}.$$

$$A = \begin{pmatrix} 3 & 3 & 3 \\ 3 & 3 & 3 \\ 3 & 3 & 3 \end{pmatrix}$$
$$R_2 \rightarrow R_2 - R_1$$
$$R_3 \rightarrow R_3 - R_1$$
$$\begin{pmatrix} 3 & 3 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$



04. Suppose that $A_{n \times n}$ is upper triangular matrix such that $\underline{a_{ii}} = 0, i = 1, 2, \dots, n$.
Then rank of $A^n =$ _____.

(a) 0

(b) $n - 1$

(c) 1

(d) n

A is upper triangular matrix
verification $\underline{n=2}$

$$A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

$$A^2 = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

(a)



10. Let $A = \begin{bmatrix} 0 & a & b \\ -a & 0 & c \\ -b & -c & 0 \end{bmatrix}$

A is skew sym
matrix of odd order

$$|A| = 0$$

$$\underline{\underline{R(A) < 3}}$$

$$\begin{vmatrix} 0 & a \\ -a & 0 \end{vmatrix} = a^2 \neq 0$$

where a, b, c are non-zero real numbers.

Then Rank of $A =$

(a) 0

(b) 1

(c) 2

(d) 3

$$\underline{\underline{R(A) = 2}}$$



The rank of the matrix

$$\begin{bmatrix} 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 \\ 0 & 1 & -1 & 0 & 0 \\ -1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & -1 \end{bmatrix} \text{ is } \underline{\hspace{2cm}}.$$

5x5

(GATE - 17-EC)

Reduce the given
matrix to row echelon

$$R(A) = \underline{\hspace{2cm}}$$



277. Consider matrix $A = \begin{bmatrix} k & 2k \\ k^2 - k & k^2 \end{bmatrix}$ and vector $x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$. The number of distinct real values of k for which the equation $Ax = 0$ has infinitely many solutions is _____.
(GATE-18-EC)

$$AX = 0$$

Infinitely many solutions

$$R(A) < \infty$$

$$R(A) < 2 \quad |A| = 0$$

$$\begin{vmatrix} k & 2k \\ k^2 - k & k^2 \end{vmatrix} = 0$$

$$k^3 - 2k^3 + 2k^2 = 0$$

$$-k^3 + 2k^2 = 0$$

$$-k^2(k - 2) = 0$$

$$k = 0, 0, 2$$

$$\text{Ans} = 2$$



Linearly Independent and Dependent vectors

Ex 1 Consider the vectors $v_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$
 $v_2 = \begin{pmatrix} 2 \\ 0 \end{pmatrix}$. Are the vectors Linearly independent?

$$v_2 = 2v_1$$

v_1 & v_2 are
Linearly dependent

$$\begin{aligned} v_2 &= 2v_1 \\ 2v_1 - v_2 &= 0 \\ \alpha_1 v_1 + \alpha_2 v_2 &= 0 \Rightarrow \text{Homogeneous eqn} \\ \alpha_1 &= 2 \quad \alpha_2 = -1 \\ \alpha_1 &= 4 \quad \alpha_2 = -2 \\ \alpha_1 &= 6 \quad \alpha_2 = -3 \\ &\vdots \end{aligned}$$



$$\begin{aligned} \text{method 2} \\ |v_1 v_2| &= \begin{vmatrix} 1 & 2 \\ 0 & 0 \end{vmatrix} \\ &= 0 \\ v_1 \text{ \& } v_2 &\text{ are} \\ &\text{L.D} \end{aligned}$$



Ex 2 Consider the vectors $V_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$, $V_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$
 $V_3 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$. Are the vectors Linearly independent?

$$V_3 = \underline{V_1 + V_2}$$

V_1, V_2 & V_3
are L.D

$$V_1 + V_2 - V_3 = 0$$

$$\alpha_1 V_1 + \alpha_2 V_2 + \alpha_3 V_3 = 0 \quad \checkmark$$

$$\alpha_1 = 1 \quad \alpha_2 = 1 \quad \alpha_3 = -1$$

$$\alpha_1 = 2 \quad \alpha_2 = 2 \quad \alpha_3 = -2$$

\vdots



method 2

$$|V_1 \ V_2 \ V_3| = \begin{vmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{vmatrix}$$

$$= 0$$

V_1, V_2 & V_3 are
L.D



Ex 3 Consider the vectors $v_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$
 $v_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$. Are the vectors Linearly independent?

$$\alpha_1 v_1 + \alpha_2 v_2 = 0$$

$$\alpha_1 = \alpha_2 = 0$$

Trivial
solution

method 2

$$|v_1 \ v_2| = \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} = 1 \neq 0$$

v_1 & v_2 are
Linearly independent



Ex 4 Consider the vectors $v_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$, $v_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$
 $v_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$. Are the vectors Linearly independent?

$$\alpha_1 v_1 + \alpha_2 v_2 + \alpha_3 v_3 = 0$$

only one solution

$$\alpha_1 = \alpha_2 = \alpha_3 = 0$$

Trivial
solution

$$|v_1 \ v_2 \ v_3| = \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix} = 1 \neq 0$$

v_1, v_2 and v_3 are
 L.I



Ex 5 Consider the vectors $v_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$, $v_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$, $v_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$, $v_4 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$. Are the vectors Linearly independent?

$$[v_1 \ v_2 \ v_3 \ v_4] = \begin{bmatrix} \textcircled{1} & 0 & 0 & 1 \\ 0 & \textcircled{1} & 0 & 1 \\ 0 & 0 & \textcircled{1} & 1 \end{bmatrix}_{3 \times 4}$$

$$\text{Rank} = 3$$

v_1, v_2, v_3 & v_4 are L.D

$$v_1 + v_2 + v_3 = v_4$$

$$\text{Rank} = \underline{\underline{2}}$$



- ▶ Linear Independence: A set of vectors $\mathcal{S} = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ is said to be a linearly independent set whenever the only solution for the scalars α_i in the homogeneous equation $\alpha_1\mathbf{v}_1 + \alpha_2\mathbf{v}_2 + \dots + \alpha_n\mathbf{v}_n = \mathbf{0}$ is the trivial solution $\alpha_1 = \alpha_2 = \dots = \alpha_n = 0$.
- ▶ Whenever there is a nontrivial solution for the α (i.e., at least one $\alpha_i \neq 0$), the set \mathcal{S} is said to be a linearly dependent set.



If the vectors $(1.0, -1.0, 2.0)$, $(7.0, 3.0, x)$ and $(2.0, 3.0, 1.0)$ in \mathbb{R}^3 are linearly dependent, the value of x is _____

GATE 2021

(← - - -)

$$\begin{vmatrix} 1 & -1 & 2 \\ 7 & 3 & x \\ 2 & 3 & 1 \end{vmatrix} = 0$$

$$1(3-3x) + 1(7-2x) + 2(21-6) = 0$$

$$3-3x + 7-2x + 30 = 0$$

$$40 = 5x$$

$$\Rightarrow x = \underline{\underline{8}}$$

\mathbb{R} set of real numbers

\mathbb{R}^2 $\begin{pmatrix} - \\ - \end{pmatrix}$, \mathbb{R}^3 $\begin{pmatrix} - \\ - \\ - \end{pmatrix}$ (← - -)



15. Consider the following statements:

S1: If $\{X_1, X_2, X_3, X_4\}$ is a linearly independent set of vectors, then the set $\{X_1, X_2, X_3\}$ is linearly independent.

S2: If $\{X_1, X_2, X_3, X_4\}$ is a linearly dependent set of vectors, then the set $\{X_1, X_2, X_3\}$ is linearly dependent.

Which of the following is true?

- (a) Only S1
- (b) Only S2
- (c) Both S1 and S2
- (d) Neither S1 nor S2



LU Decomposition

If A is an $n \times n$ matrix such that a zero pivot is never encountered when applying Gaussian elimination with Type III operations, then A can be factored as the product $A = LU$, where the following hold.

L is lower triangular and U is upper triangular.

$l_{ij} = 1$ and $u_{ii} \neq 0$ for each $i = 1, 2, \dots, n$.

Below the diagonal of L , the entry $l_{i,j}$ is the multiple of row j that is subtracted from row i in order to annihilate the (i,j) position during Gaussian elimination.

U is the final result of Gaussian elimination applied to A .

The decomposition of A into $A = LU$ is called the LU factorization of A , and the matrices L and U are called the LU factors of A .



Use the LU factorization of A to solve $Ax = b$, where

$$A = \begin{bmatrix} 2 & 1 & 1 \\ 6 & 2 & 1 \\ -2 & 2 & 1 \end{bmatrix}, \quad b = \begin{bmatrix} 1 \\ -1 \\ 7 \end{bmatrix}$$

$$A = LU$$

L = Lower

U = upper

Consider A

$$\begin{pmatrix} 2 & 1 & 1 \\ 6 & 2 & 1 \\ -2 & 2 & 1 \end{pmatrix}$$

$$\begin{aligned} R_2 &\rightarrow R_2 - 3R_1 \\ R_3 &\rightarrow R_3 + R_1 \\ R_3 &\rightarrow R_3 - (-1)R_1 \end{aligned}$$

$$\begin{pmatrix} 2 & 1 & 1 \\ 0 & -1 & -2 \\ 0 & 3 & 2 \end{pmatrix} \begin{aligned} R_3 &\rightarrow R_3 + 3R_2 \\ R_3 &\rightarrow R_3 - (-3)R_2 \end{aligned}$$

$$\begin{pmatrix} 2 & 1 & 1 \\ 0 & -1 & -2 \\ 0 & 0 & -4 \end{pmatrix} = U$$

$$L = \begin{pmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ -1 & -3 & 1 \end{pmatrix}$$



$$L U = \begin{pmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ -1 & -3 & 1 \end{pmatrix} \begin{pmatrix} 2 & 1 & 1 \\ 0 & -1 & -2 \\ 0 & 0 & -4 \end{pmatrix} = \begin{pmatrix} 2 & 1 & 1 \\ 6 & 2 & 1 \\ -2 & 2 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ -1 & -3 & 1 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} \quad A X = b$$

$$L U X = b$$

$$y_1 = b_1$$

$$3y_1 + y_2 = b_2$$

$$y_2$$

$$\underline{\underline{L y = b}}$$

$$U X = y \quad \leftarrow$$



- To solve a nonsingular system $Ax = b$ using the LU factorization $A = LU$, first solve $Ly = b$ for y with the forward substitution algorithm, and then solve $Ux = y$ for x with the back substitution procedure.
- The advantage of this approach is that once the LU factors for A have been computed, any other linear system $Ax = \tilde{b}$ can be solved with only n^2 multiplications/divisions and $n^2 - n$ additions/subtractions.