Theory of Computer Games 2022 – Project 2 plus

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Network Design

我的 N-tuple network 和 project 2 一樣

可以看到下圖是依照 4×6 -tuple network 並且有 8 種 isomorphic patterns 需要去儲存(也就是旋轉 0° , 90° , 180° , 270° 以及水平鏡射後的旋轉 0° , 90° , 180° , 270°)

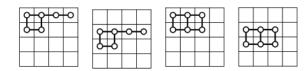


Fig. 2. The four 6-tuples by Wu et al. [11]

Method Used

Take action

跟上次不同的地方在於

Project 2: The player takes actions based on the rewards and the afterstate values, rt+V(st')

而我這次 improved methodology 是 The player takes actions based on the rewards and the expectation values, $r_t + \mathbb{E}[r_t' + V(s_t'')]$

也就是參考 reference 2 把 expectimax 融入 TD-learning 中:

K.-H. Yeh, I-C. Wu, C.-H. Hsueh, C.-C. Chang, C.-C. Liang, and H. Chiang, "Multistage temporal difference learning for 2048-like games,"

A non-initial new tile is randomly placed at an empty cell on the puzzle border of the opposite side of the last sliding direction.

而 Board 的 hint 會顯示接下來會放的 new tile 是 1-tile, 2-tile or 3-tile 可以看到下圖我會根據 board 的 hint 去計算上述所說 non-initial new tile 可以放的位置的期望值 $E[\mathit{rt'} + \mathit{V}(\mathit{st''})]$

```
float expectationEstimate(const board& after) const {
    float expectation = 0.0;
    int emptySpace = 0;
    std::vector<int> space = spaces[after.last()];
    //std::shuffle(space.begin(), space.end(), engine);
    int bag[3], num = 0;
    for (board::cell t = 1; t <= 3; t++)
         for (size_t i = 0; i < after.bag(t); i++)
bag[num++] = t;
    std::default_random_engine engine;
    std::shuffle(bag, bag + num, engine);
board::cell tile = after.hint() ?: bag[--num];
board::cell hint = bag[--num];
    for (int pos : space) {
  if (after(pos) != 0) continue;
         board b = board(after);
         b.place(pos, tile, hint); // place 1, 2, 3
         int bestReward = -1;
float bestValue = -100000;
         for(int op : opcode){
              board afterstate = b;
              int reward = afterstate.slide(op);
              if(reward == -1) continue;
              float value = valueEstimate(afterstate);
              if(reward + value > bestReward + bestValue){
                  bestReward = reward;
                  bestValue = value;
//bestOP = op;
         expectation += (bestReward + bestValue);
         emptySpace += 1;
    expectation = expectation / emptySpace;
    return expectation;
```

TD-learning

ValueExtract, ValueEstimate, ValueAdjust, training process 都與 project 2 相同 n-tuple network weights 與 project 2 也相同

Result

```
[chungminyu@tcglinux7 pj2+]$ ./threes --total=1000 --block=1000 --limit=1000 --play="alpha=0 load=weights.bin" --save stats.txt
Threes! Demo: ./threes --total=1000 --block=1000 --limit=1000 --play=alpha=0 load=weights.bin --save stats.txt

1000 avg = 277576, max = 711885, ops = 88307 (44869|4045303)

1536 100% (0.1%)
3072 99.9% (93.3%)
6144 6.6% (6.6%)
```