Simulations
Multi-Task Learning for the Federated Setting

Table 1: Average prediction error: Means and standard errors over 10 random shuffles.

Model	Human Activity	Google Glass	Vehicle Sensor
Global	2.23 (0.30)	5.34 (0.26)	13.4 (0.26)
Local	1.34 (0.21)	4.92 (0.26)	7.81 (0.13)
MTL	**0.46 (0.11)**	**2.02 (0.15)**	**6.59 (0.21)**