

Deep Neural Network Topology

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Blackbox

- Change input and observe output



Figure 1: From wikipedia

Neural Network

- ▶ Neural Network is called blackbox for several reasons.
- ▶ We have no idea how neural network is doing prediction.
- ▶ We cannot interpret weight of neural network.
- ▶ Neural network is not identifiable.

Open Blackbox

- Instead of observing how a single image change through layers, observe whole data set.

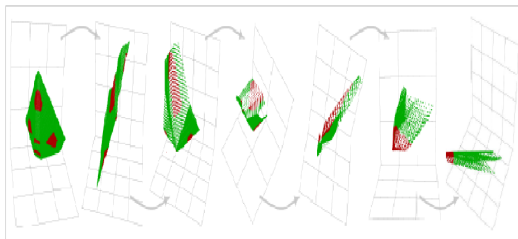


Figure 2: From Topology of Deep Neural Networks

Track manifold M

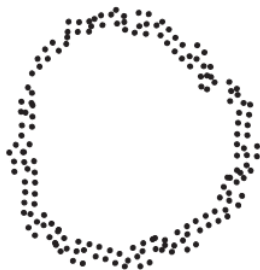
- ▶ Consider supervised binary classification problem with $M = M_a \cup M_b$
- ▶ Suppose the neural network is fully trained with very low generalization error.
- ▶ Observe how topology of M changes within output of each layer.
- ▶ Think of kernel method.

Two Problems

- ▶ How to quantify topology of manifold?
- ▶ Use Betti numbers that capture the shape of a space.
- ▶ For $M \in \mathbb{R}^d$, Betti numbers $\beta_k(M)$ represents the number of k -dimensional holes in M .
- ▶ For d -dimensional space $k = 0, 1, \dots, d - 1$ and β_0 represents the number of connected components.
- ▶ This quantity is topologically invariant and intuitively, higher the Betti numbers, the more complex its topology.

Two Problems

- ▶ We do not have whole manifold.
- ▶ Instead only have finite number of points sampled from manifold with some noises.
- ▶ We need to estimate $\beta(M)$ from a point cloud data set.
- ▶ Betti numbers of M are estimated by constructing a simplicial complex from a point cloud data set.



Methodology

- ▶ Generate Data sets from topologies known in advance.
- ▶ Supervised train neural network.
- ▶ Track the topology of the respective point cloud data set.
- ▶ Change neural network structure and repeat.

Results of Experiment

- ▶ All Betti numbers decrease across the layers.
- ▶ Using ReLU layers, result in most rapid decreases in all Betti numbers compared to tanh layers.
- ▶ As depth of neural network decreases, most of change in topology occurs at final layers.
- ▶ Overall, fully trained neural network makes prediction by reducing complex manifold of dataset to simple structure.

Three Questions Asked?

- ▶ Why non smooth activation works better than smooth activation?
- ▶ Homeomorphic map preserves topology so \tanh cannot work well compared to ReLU.
- ▶ Universal Approximation Theorem but why deep network is trained well?
- ▶ For complex dataset, more layers are required to make topological changes.

How to characterize shape



Figure 4: From Topological Pattern Recognition for Point Cloud Data

- ▶ Characterize spaces by pattern occurrence.
- ▶ Intuitively, there is one loop.
- ▶ But there are infinitely many loops.
- ▶ Consider equivalence class.

Homotopy

- ▶ Intuitively, loop can be defined by $f : S^1 \rightarrow X$ continuous.
- ▶ However, counting occurrence (f) is not possible.
- ▶ We use homotopy as equivalence relation.
- ▶ Two continuous map $f, g : X \rightarrow Y$ are homotopic if there exists continuous $H : X \times [0, 1] \rightarrow Y$ such that $H(x, 0) = f(x)$ and $H(x, 1) = g(x)$ for all x .
- ▶ Based maps are maps with additional constraint such that $f(x_0) = y_0$.
- ▶ $\pi_n(Y, y_0)$ is a group of equivalence class of f from $S^n \rightarrow Y$

Homology

- ▶ Homotopy groups are easy to define but difficult to calculate
- ▶ On the other hand, homology is easy to calculate but difficult to define.
- ▶ Homology is also topologically invariant.
- ▶ It is initially defined for simplicial complexes.

Simplicial Complexes

- ▶ k -simplex σ is the convex hull of $k+1$ affinely independent points $v_0, v_1, \dots, v_k \in \mathbb{R}^d$
- ▶ k -simplex is represented by its vertices and denoted by $\sigma = [v_0, \dots, v_k]$
- ▶ Faces of a k -simplex σ are simplices of dimensions 0 to $k-1$ formed by subset of vertex of σ .

Geometrical Simplicial Complex K

- ▶ m -dimensional simplicial complex K is a finite collection of simplices with dimension at most m .
- ▶ Any intersection between two simplices in K is a face of both of them.
- ▶ Include all faces of all its simplices.
- ▶ Geometrical realization of abstract simplicial complex.

Abstract Simplicial Complex

- ▶ For every geometrical simplicial complex K , there is abstract simplicial complex behind it.
- ▶ List of simplices $K = \sigma_1, \sigma_2, \dots, \sigma_n$ with the property that if $\tau \subset \sigma \in K$ then $\tau \in K$
- ▶ Note given abstract simplicial complex, it might not be geometrical simplicial complex.
- ▶ We may need to embed vertex set to higher dimension to ensure vertex are affinely independent.
- ▶ Called geometrical realization $|K|$

Example of 3d simplicial complex

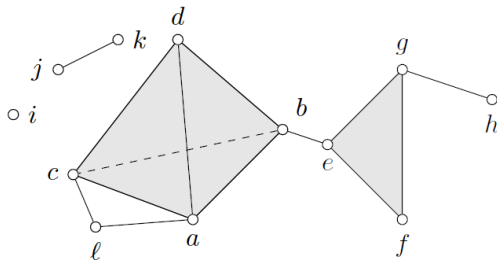


Figure 5: From Topology of Deep Neural Network

Geometrical Representation $|K|$

- ▶ Any simplicial complex is homeomorphic to geometric realization of abstract simplicial complex.
- ▶ A map of abstract simplicial complexes f from X to Y is map such that $f : V(X) \rightarrow V(Y)$ such that if $\sigma \in \Sigma(X)$ then $f_v(\sigma) \in \Sigma(Y)$
- ▶ Geometric realization is functorial in a sense that if f, g are abstract complexes map, it induces map $|f| : |X| \rightarrow |Y|$ such that $|f \circ g| = |f| \circ |g|$

Definition of the Betti number

- ▶ For simplicity restrict field to the field of two elements.
- ▶ Let C_0, C_1, \dots, C_d be vector spaces over finite field. Also $C_{d+1}, C_{-1} = 0$
- ▶ Let $\partial_k : C_k \rightarrow C_{k-1}$ be linear maps called boundary such that $\partial_k \circ \partial_{k+1} = 0$.

$$0 \xrightarrow{\partial_{d+1}} C_d \xrightarrow{\partial_d} C_{d-1} \xrightarrow{\partial_{d-1}} \dots \xrightarrow{\partial_{k+1}} C_k \xrightarrow{\partial_k} C_{k-1} \xrightarrow{\partial_{k-1}} \dots \xrightarrow{\partial_2} C_1 \xrightarrow{\partial_1} C_0 \xrightarrow{\partial_0} 0,$$

- ▶ Such sequence is called chain complex.
- ▶ Image of ∂_k is called boundaries and kernel of ∂_{k-1} is called cycles.

Definition of the Betti number

- ▶ kernel and image of linear map are subspace.

$$B_k := \text{im}(\partial_{k+1}) \subset \text{ker}(\partial_k) =: Z_k$$

- ▶ We can form the quotient vector space $H_k = Z_k/B_k$ where we treat B_k as zero vector.
- ▶ Equivalence Class is defined as $[z] = z + B_k$
- ▶ Note vector space is also abelian group with addition. H_k as group is called kth homology group.
- ▶ As vector space consider $\dim(H_k)$ called β_k
- ▶ If a chain complex considered is associated with a simplicial complex K , β_k is called the kth Betti number of K .

Connected Components of simplicial complex K

- ▶ Consider vertex set of K $K^{(0)}$
- ▶ Define equivalence relation of vertex by $v \sim v'$ if $(v, v') \in K$
- ▶ Then, number of connected components equal number of equivalence class.

Free Vector Space $V(S)$

- ▶ When S is finite set, we want to form vector space with S as basis.
- ▶ We consider a formal linear combination (it is not actual linear combination)
- ▶ If $S = \{v_0, v_1, \dots, v_n\}$, then $V(S) = \sum_{j=0}^n n_j v_j$ where $n_j = 0$ or 1
- ▶ Can think of it as one hot encoding φ_{v_k} .
- ▶ Dimension of $V(S)$ is number of elements in S

Free vector space of relation

- ▶ Given binary relationship, R on X , we can define $V(R) \subset V(X)$
- ▶ $V(R)$ is defined as linear span of $\{\varphi_{v_j} - \varphi_{v_i} | (v_i, v_j) \in R\}$
- ▶ Note as field considered as the field of two elements,
$$\varphi_{v_j} - \varphi_{v_i} = \varphi_{v_j} + \varphi_{v_i}$$
- ▶ There is an isomorphism between $V(X)/V(R) \cong V(X/R)$

An Example

$$\partial_1 = \begin{array}{c} \text{A} \\ \text{B} \\ \text{C} \\ \text{D} \\ \text{E} \end{array} \begin{bmatrix} \text{AB} & \text{AC} & \text{BC} & \text{DE} \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

- ▶ Note each column describes $V(R)$ where $R = \{(v_i, v_j) | (v_i, v_j) \in K\}$
- ▶ $V(K)/V(R) = V(K)/\text{col}(\partial_1) \cong V(K/R)$
- ▶ Note ∂_1 maps span of 1-simplicies in K to 0-simplicies in K .
- ▶ By above explanation, $\beta_0 =$ number of connected component
= number of equivalence class = dimension of $K/R =$
dimension of $V(K)/\text{col}(\partial_1) =$ dimension of $\ker(\partial_0)/\text{col}(\partial_1)$

How to form a chain complex for a simplicial complex

- ▶ Given an abstract simplicial complex K , define vector space $C_k(K)$ as a formal linear combination of $K^{(k)}$ be the set of all k -dimensional simplices in K .
- ▶ Note we can define $\partial_k : C_k(K) \rightarrow C_{k-1}(K)$ on a k -simplex σ by

$$\partial_k(\sigma) := \sum_{j=0}^k \sigma^{(j)}$$

where $\sigma^{(j)}$ is $k-1$ simplex obtained by removing one vertex from σ

- ▶ Note $\partial_k \circ \partial_{k+1} = 0$ as each vertex appears twice so sum becomes 0. (we are still in finite field)
- ▶ Now the k th Betti number can be found by $\text{nullity}(\partial_k) - \text{rank}(\partial_{k+1})$
- ▶ As each ∂_k can be expressed as matrices, we can calculate them.

How to form a simplicial complex from a point cloud data set

- ▶ A point cloud data set is a finite set of n points X .
- ▶ After some noise reduction steps, we can form the simplicial complex whose vertex set is X
- ▶ One commonly used method is Vietoris-Rips Complex.
- ▶ Suppose a measure δ is given and scale ϵ

Vietoris-Rips Complex

- ▶ Vietoris-Rips complex at scale ϵ is defined as

$$VR_{\epsilon}(X) := \{[x_0, \dots, x_k] \mid \delta(x_i, x_j) \leq 2\epsilon\}$$

- ▶ Note this complex depends on ϵ and δ
- ▶ There is a theorem that for a dense enough sample, and at sufficiently small scale, the topology recovers the true topology.

Persistent Barcode

- ▶ At scale of 0, $VR_0(X)$ is a collection of 0-dimension simplicies with each points in X being a 0-dimension simplicies.
- ▶ On the other hand, if ϵ goes to infinity, we get only one big simplex.
- ▶ The true answer lies somewhere in between.
- ▶ Persistence barcodes provide a summary of the evolution of topology across all scales.
- ▶ As ϵ increases, $VR(X, \epsilon_j)$ forms the chain of a nested simplicial complexes.
- ▶ Generally speaing, a persistence barcode is tracking of when new homology group appears and dies.