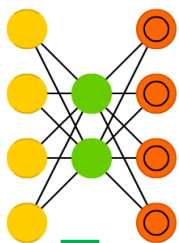
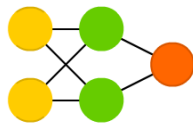


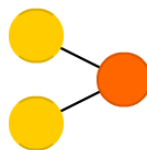
Auto Encoder (AE)

2015  
CDL

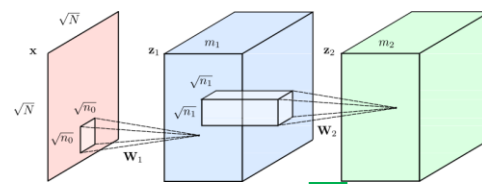
Feed Forward (FF)



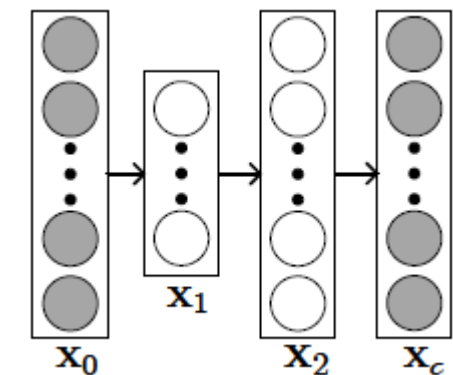
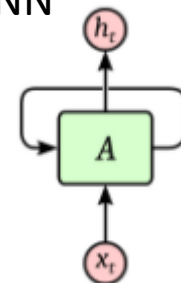
Perceptron (P)



CNN

2015  
CCPM

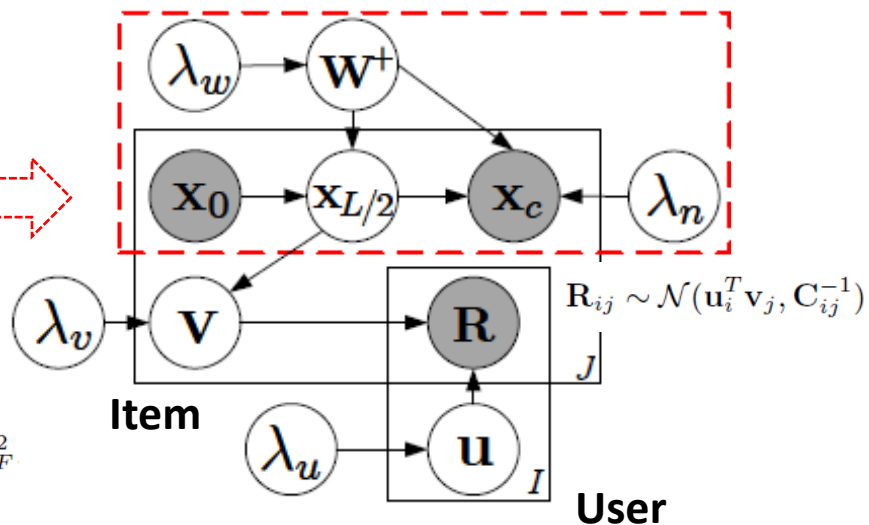
RNN



$$\min_{\{W_l\}, \{b_l\}} \|X_c - X_L\|_F^2 + \lambda \sum_l \|W_l\|_F^2$$

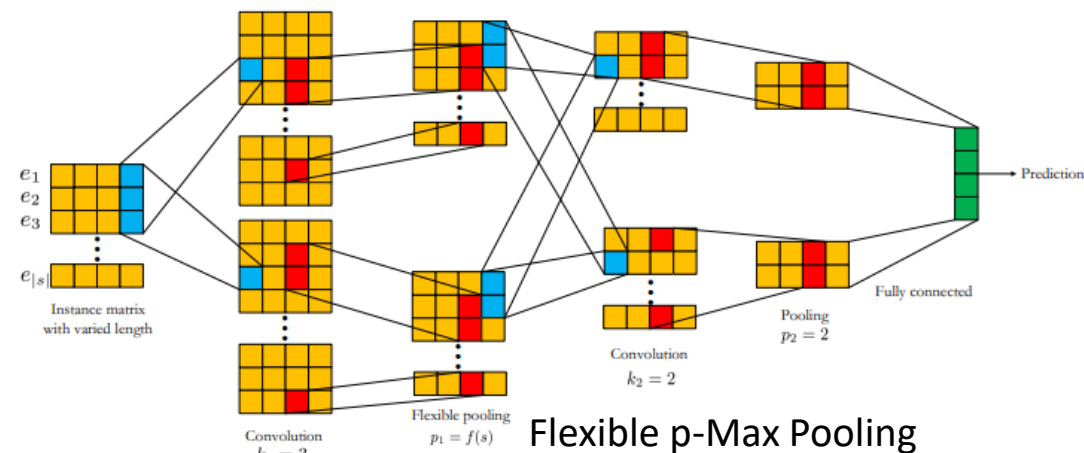
Stacked Denoising  
Autoencoder (SDAE)

$$W_{l,*n} \sim \mathcal{N}(0, \lambda_w^{-1} \mathbf{I}_{K_l}).$$



$$R_{ij}^* \approx (u_j^*)^T (f_e(X_{0,j*}, W^{+*})^T + \epsilon_j^*) = (u_i^*)^T v_j^*$$

Collaborative Deep Learning, CDL



Flexible p-Max Pooling

$$p_i = \begin{cases} (1 - (i/l)^{l-i})n, & i = 1, \dots, l-1 \\ 3, & i = l \end{cases}$$

Convolutional Click Prediction Model (CCPM)