Process Management

Process Scheduling

Lecture 4

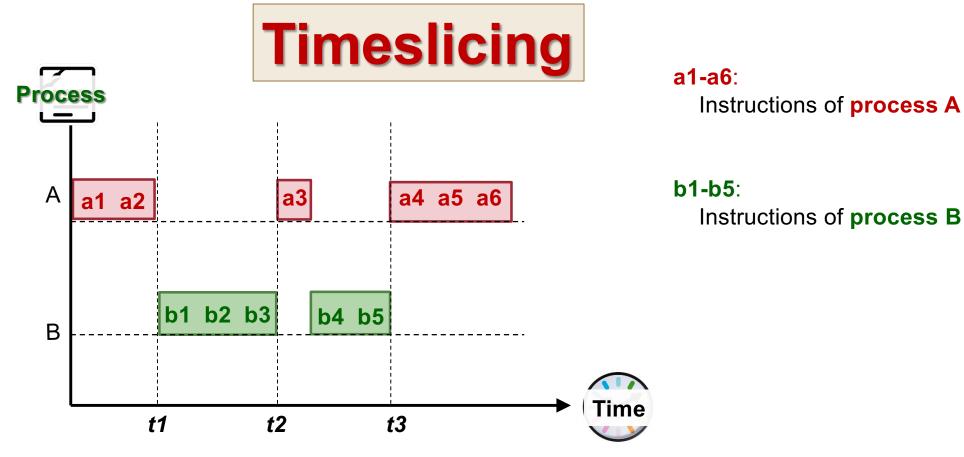
Overview

- Concurrent Execution
- Process Scheduling
 - Definition
 - Process behavior
 - Processing environment
 - Criteria for good scheduling
 - Procedure of process scheduling
- Scheduling Algorithms
 - For Batch Processing System
 - For Interactive System

Concurrent Execution

- Processes P1 and P2 execute concurrently if they both make progress within a short window of time (i.e., they run "in parallel")
 - Could be virtual parallelism
 - Illusion of parallelism, pseudo-parallelism
 - Could be physical parallelism
 - Multiple execution units (cores, CPUs, ...) available in hardware
- You can assume the two forms of parallelisms are not distinguished in the following discussion

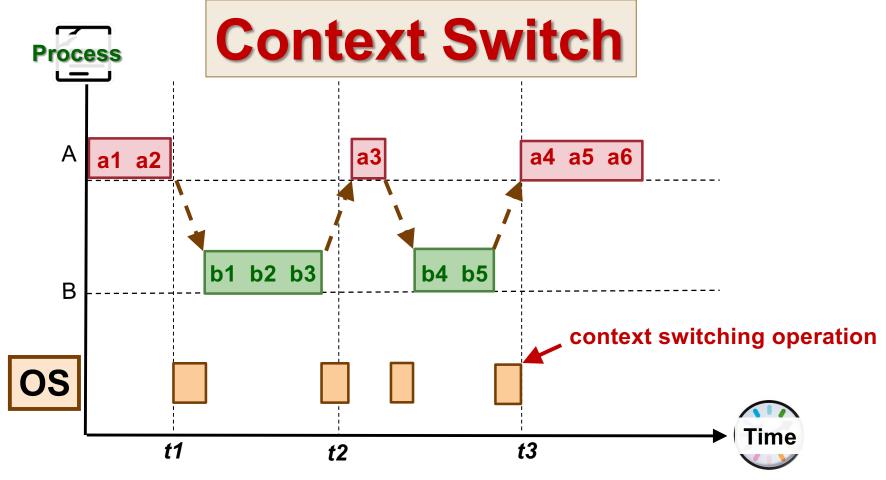
Concurrency Example (Simplistic)



Concurrent execution on 1 CPU: interleaving of instructions from both processes

Also called time-slicing

Interleaved Execution (context switch)

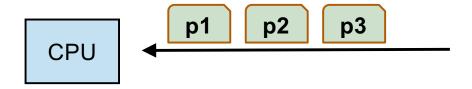


Multitasking requires switching contexts between A and B

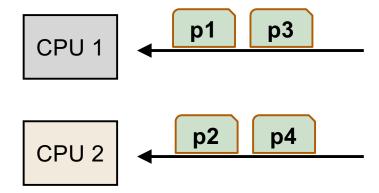
OS incurs some overhead in the switching processes

Multitasking OS

1 CPU: time-sliced execution of tasks



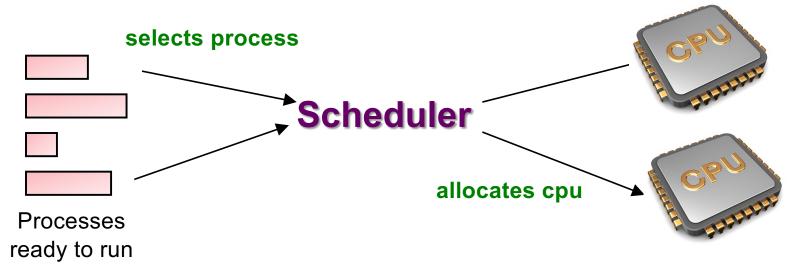
Multi-processor: time-slicing on *n* CPUs



Scheduling in OS: A definition

- Problems with having multiple processes:
 - If [#ready-to-run processes] > [#available_CPUs], which process should be chosen?
 - Known as the scheduling problem
- Terminology:
 - Scheduler
 - the OS component that makes scheduling decisions
 - Scheduling algorithm
 - The algorithm used by scheduler

Scheduling: Illustration



- Each process requires different amount of CPU time
 - Process behavior
- Multiple ways to allocate CPU time
 - Defined by scheduling algorithms
 - Influenced by the processing environment (batch, interactive, real-time...)
- A number of criteria to evaluate schedulers

Process Behavior

A typical process goes through phases of:

CPU-Activity:

- Computation
- E.g., number crunching
- Compute-Bound Process spends majority of its time here

IO-Activity:

- Requesting and receiving service from I/O devices
- E.g., Print to screen, read from file, wait for a key
- IO-Bound Process spends majority of its time here

3 Types of Processing Environment

1. Batch Processing:

- Usually long-running without user intervention
- No user → No interaction required → No need to be responsive
 - E.g., training deep neural networks on a supercomputer

2. Interactive:

- With active user(s) interacting with system (e.g., MS Word)
- Should be responsive, consistent in response time

3. Real-time processing:

- Have a strict deadline to meet (e.g., aircraft controller)
- Tasks are usually periodic

Criteria for Scheduling Algorithms

Many criteria to evaluate a scheduling algorithm

- Different processing environment have different criteria
- Some criteria may be mutually conflicting

Criteria for all processing environments:

- Fairness:
 - Ensuring fair sharing of CPU time
 - on a per-process basis OR
 - on a per-user basis
 - Also mean no starvation
- Balanced Utilization of the System Resources:
 - All components of the computing system should be utilized
 - In a balanced manner, without bottlenecks

When to perform scheduling?

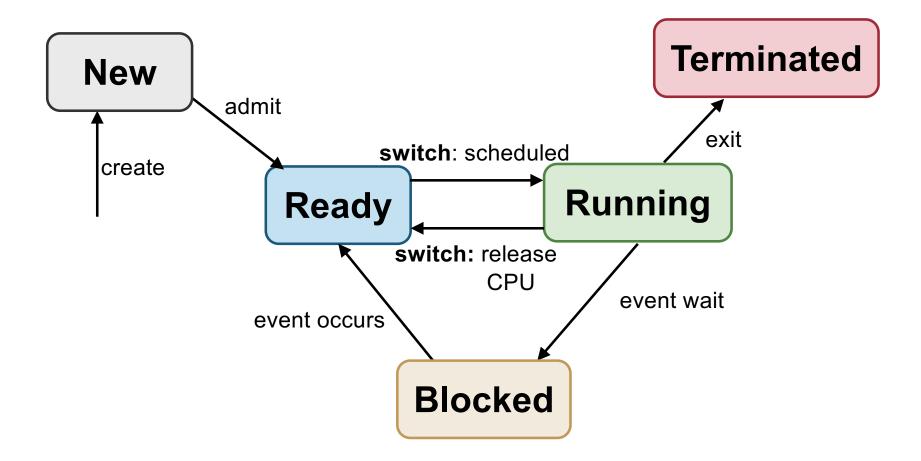
Two types of scheduling policies:

- Defined by when scheduling is triggered
- Non-preemptive (a.k.a. cooperative)
 - A process stayed scheduled (in **RUNNING** state) until:
 - it blocks, OR (going to the BLOCKED state)
 - 2. gives up the CPU voluntarily (going to the **READY** state)

Preemptive

- CPU can be taken (preempted) from the running process at ANY time
 Typically, a process is given a time quota to run:
- At the end of the time quota the process is suspended (goes to READY state)
 - Another process gets picked if available
- It is possible for a process to block or finish/give up CPU early

Generic 5-State Process Model



Scheduling a Process: Step-by-Step

1

Scheduler is triggered (OS takes over)

2

If Context switch is needed:

Context of current running process is saved and placed on blocked queue / ready queue

3

Pick a suitable process P to run based on scheduling algorithm

4

Setup the context for P

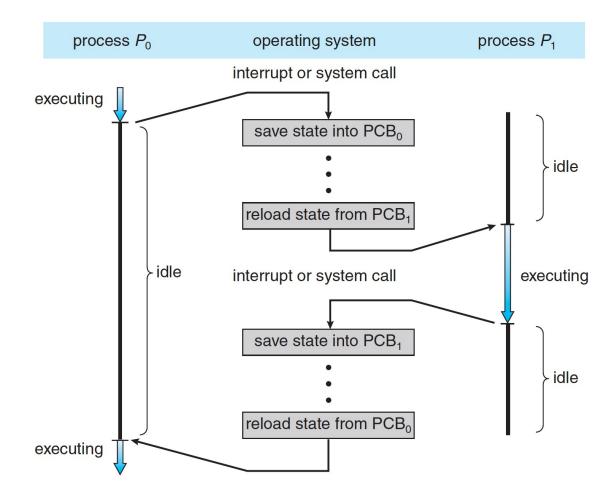
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Let process P run

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Scheduling a Process: Step By Step



SCHEDULING FOR BATCH PROCESSING

Overview – Batch Processing

- On batch processing system:
 - No user interaction
 - Non-preemptive scheduling is predominant
- Scheduling algorithms are generally easier to understand and implement
 - □ There are variants/improvements are specialized for certain use cases
- Three algorithms covered:
 - First-Come First Served (FCFS)
 - Shortest Job First (SJF)
 - Shortest Remaining Time Next (SRT)

Criteria for batch processing

Throughput:

Number of tasks finished per unit time (rate of task completion)

Turnaround time:

- Total wall clock time taken, i.e., finish_time start_time
- Related to waiting time: time spent waiting for CPU
- Average turnaround time matters more than individual

CPU utilization:

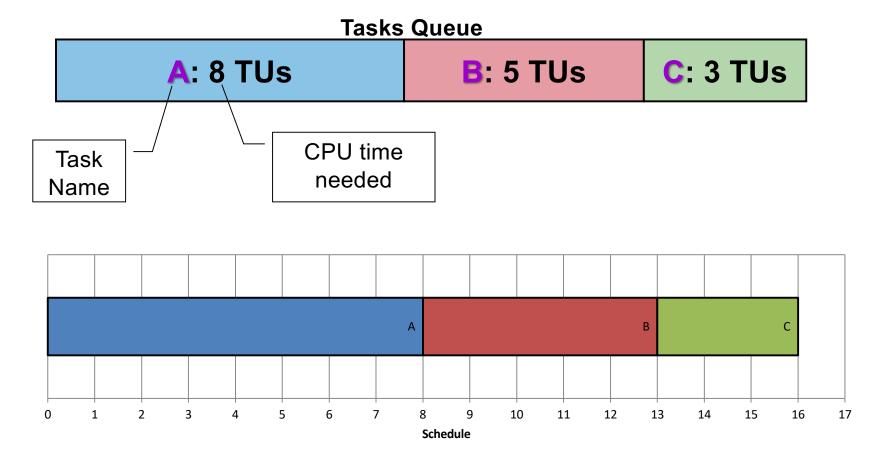
Percentage of time when CPU is working on a task (as opposed to being idle)

First-Come First-Served: FCFS

General Idea:

- Tasks are stored on a First-In-First-Out (FIFO) queue
 - based on arrival time
- Pick the first task in queue to run until:
 - The task is done OR the task is blocked
 - Blocked task is removed from the FIFO queue
 - When it is ready again, it is placed at the back of queue
 - Just like a newly arrived task
- Guaranteed to have no starvation:
 - The number of tasks in front of task X in FIFO is always decreasing
 - → task X will get its chance eventually

First-Come First-Served: Illustration



The average total waiting time for 3 tasks: (0 + 8 + 13)/3 = 7 time units

First-Come First-Served: Shortcomings

Simple reordering can reduce the average waiting time!

Convoy Effect:

- First task (task A) is CPU-Bound and followed by a number IO-Bound tasks X₁, X₂, ..., X_n
- Tasks A running
 - All tasks X_i waiting in ready queue (I/O device sitting idle)
- Tasks A blocked on I/O
 - All tasks X_i execute quickly and blocked on I/O (CPU sitting idle)

Shortest Job First: SJF

- General Idea:
 - Select task that needs the shortest amount of CPU time
 - Before it blocks or releases CPU or terminates

Notes:

- Need to know total CPU time for a task in advance
 - Have to "guess" if this info is not available
- Given a fixed set of tasks:
 - Minimizes average waiting time
- Starvation is possible:
 - Biased towards short jobs
 - Long job may never get a chance

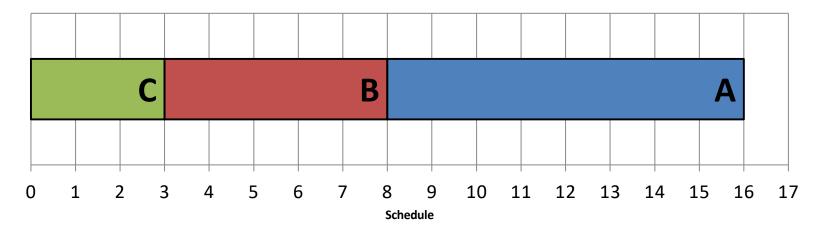
Shortest Job First: Illustration

Tasks Queue

A: 8 TUs

B: 5 TUs

C: 3 TUs



- The average total waiting time for 3 tasks
 - \bigcirc (0 + 3 + 8)/3 = **3.66** Time Units
- Can be shown that SJF guarantees smallest average waiting time

Shortest Job First: Predicting CPU Time

- Guess the future CPU time by the previous CPU-Bound phases
 - A task usually goes through several phases of CPU-Activity
 - Possible to guess the future CPU time requirement by the previous
 CPU-Bound phases

CPU ilo CPU ilo

Common approach (Exponential Average):

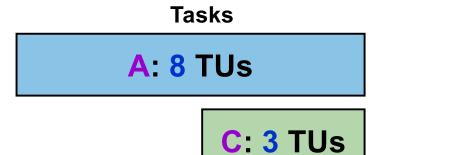
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Predicted_{n+1} = \alpha Actual_n + (1-\alpha) Predicted_n
```

- Actual_n = The most recent CPU time consumed
- □ Predicted_n = The past history of CPU Time consumed
- \square **Predicted**_{n+1} = Latest prediction

Shortest Remaining Time: SRT

- General Idea:
 - Variation of SJF:
 - Use remaining time
 - Preemptive
 - Select job with shortest remaining time (or the expectation thereof)
- Notes:
 - New job with shorter remaining time can preempt currently running job
 - Provides good service for short job even when it arrives late

Shortest Remaining Time First: Illustration



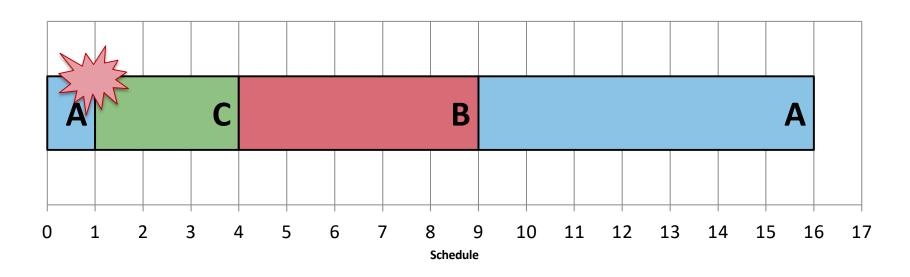
B: **5** TUs

Arrival Time

Time 0

Time 1

Time 2



SCHEDULING FOR INTERACTIVE SYSTEMS

Criteria for interactive environment

Response time:

Time between request and response by system

Predictability:

- Variation in response time; less variation → better predictability
- Predictability even more important in real-time environments

Preemptive scheduling algorithms are used to ensure good response time

→ Scheduler needs to run periodically

Ensuring Periodic Scheduler Invocation

Questions:

- How can the scheduler "take over" the CPU periodically?
- How to ensure that user program cannot prevent the scheduler from executing?
- Ingredients for answer:
 - Timer interrupt = Interrupt that goes off periodically (based on a hardware clock)
 - OS ensures timer interrupt cannot be intercepted by any other program (or any other interrupt!)
 - → Timer interrupt handler invokes the scheduler

Terminology: Timer & Time Quantum

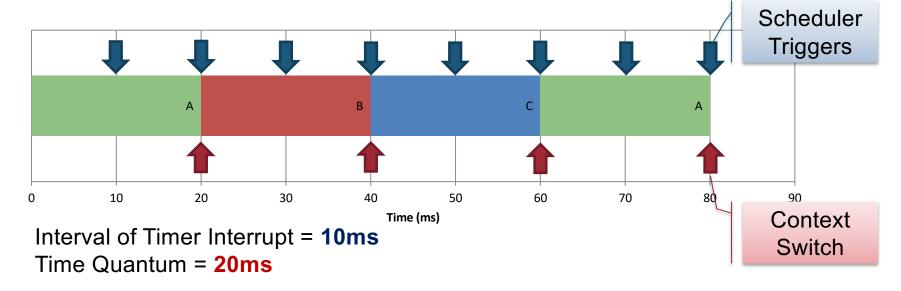
Interval of Timer Interrupt (ITI):

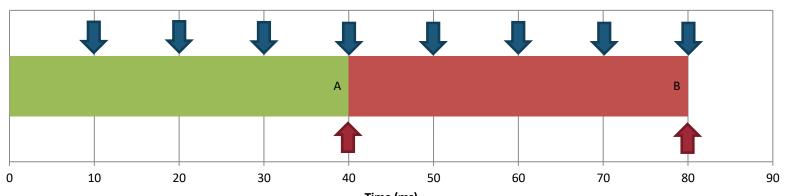
- i.e., the timer period
- OS scheduler is triggered every timer interrupt
- Typical values (1ms to 10ms)

Time Quantum:

- Execution duration given to a process
- Could be constant or variable among the processes
- Must be multiples of interval of timer interrupt
- Large range of values (commonly 5ms to 100ms)

Illustration: ITI vs Time Quantum





Interval of Timer Interrupt = 10ms Time Quantum = 40ms

Scheduling Algorithms:

- Algorithms covered:
 - 1. Round Robin (RR)
 - Priority Based
 - Multi-Level Feedback Queue (MLFQ)
 - 4. **Lottery** Scheduling

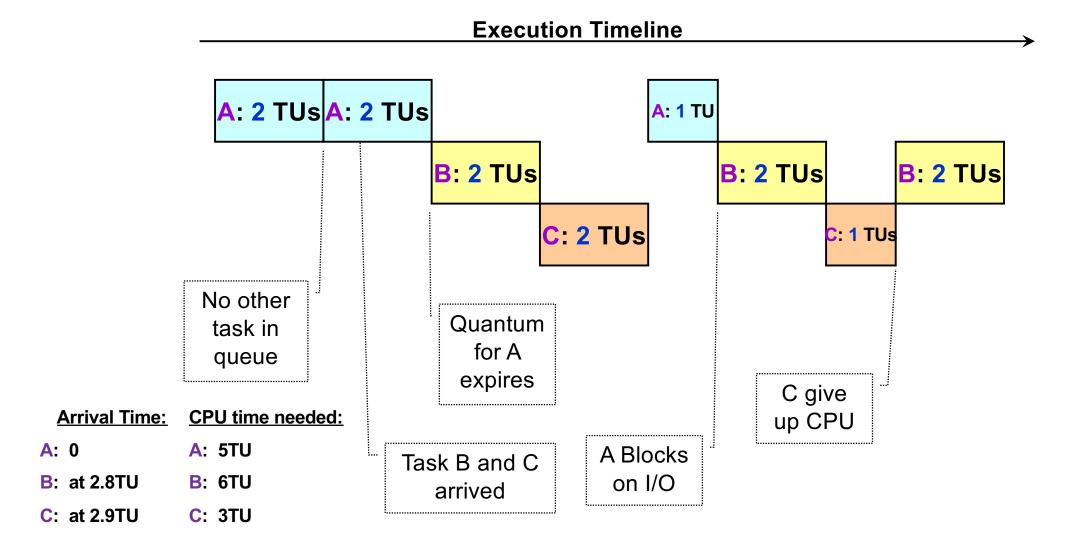
Round Robin: RR

- General Idea:
 - Tasks are stored in a FIFO queue
 - Pick the first task from queue front to run until:
 - The task gives up the CPU voluntarily, or
 - The task blocks, or
 - A fixed time slice (quantum) elapsed // key difference from FCFC
 - The task is then placed at the end of queue to wait for another turn
 - Blocked task will be moved to another queue to wait for its request
 - When blocked task is ready again, it is placed at the end of queue

Round Robin: RR (cont.)

- Notes:
 - Basically a preemptive version of FCFS
 - Response time guarantee:
 - Given n tasks and quantum q
 - Time before a task get CPU is bounded by (n-1) q
 - Timer interrupt needed:
 - For scheduler to check on quantum expiry
 - The choice of time quantum duration is important:
 - Big quantum: Better CPU utilization but longer waiting time
 - Small quantum: Bigger overhead (worse CPU utilization) but shorter waiting time

Round Robin: Illustration



Priority Scheduling

- General Idea:
 - Some processes are more important than others
 - Cannot treat all process as equal
 - Assign a priority value to all tasks
 - Select task with highest priority value
- Variants:
 - Preemptive version:
 - Higher priority process can preempts running process with lower priority
 - Non-preemptive version:
 - Late coming high-priority process has to wait for next round of scheduling

Priority Scheduling: Illustration

Tasks

Arrival Time

Priority (1=highest)

A: 8 TUs

Time 0

3

C: 3 TUs

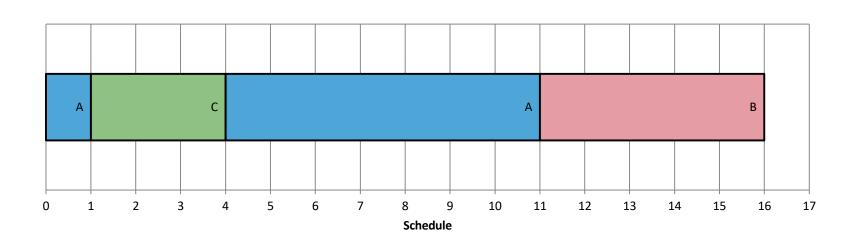
Time 1

1

B: **5** TUs

Time 1

5



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Priority Scheduling: Shortcomings

- Low priority process can starve:
 - High priority process keep hogging the CPU
 - Even worse in preemptive variant. Why?
- Possible solutions:
 - Decrease the priority of currently running process after every time quantum
 - Eventually dropped below the next highest priority
 - Give each process a minimum time quantum
 - Ensures that low-priority processes run for a while when they eventually get a chance
- Hard to guarantee/control the exact amount of CPU time given to a process using priority

Multi-Level Feedback Queue (MLFQ)

- Designed to solve one BIG + HARD issue:
 - How do we schedule without perfect knowledge?
 - Most algorithms require certain information (process behavior, running time, etc)

MLFQ is:

- Adaptive:
 - "Learn the process behavior automatically"
- Seeks to minimize both:
 - Response time for interactive and IO-bound processes
 - Turnaround time for CPU-bound processes

MLFQ: Rules

Basic rules:

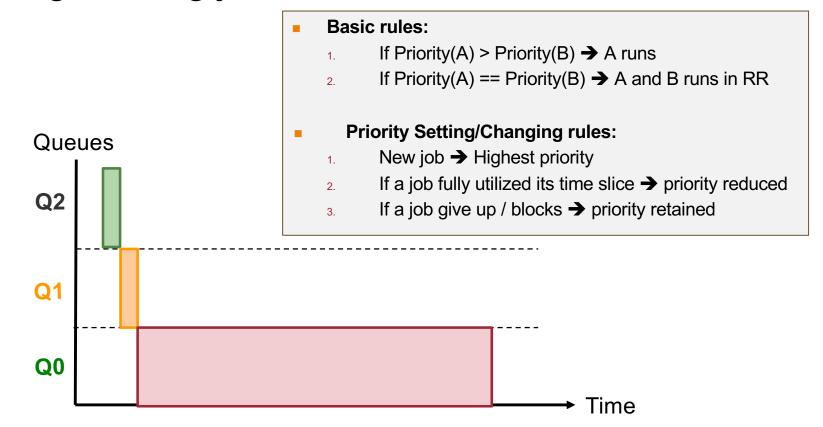
- 1. If $Priority(A) > Priority(B) \rightarrow A runs$
- If Priority(A) == Priority(B) \rightarrow A and B runs in RR

Priority Setting/Changing rules:

- New job → Highest priority
- If a job fully utilized its time slice → priority reduced
- If a job give up / blocks before it finishes the time slice → priority retained

MLFQ: Example 1

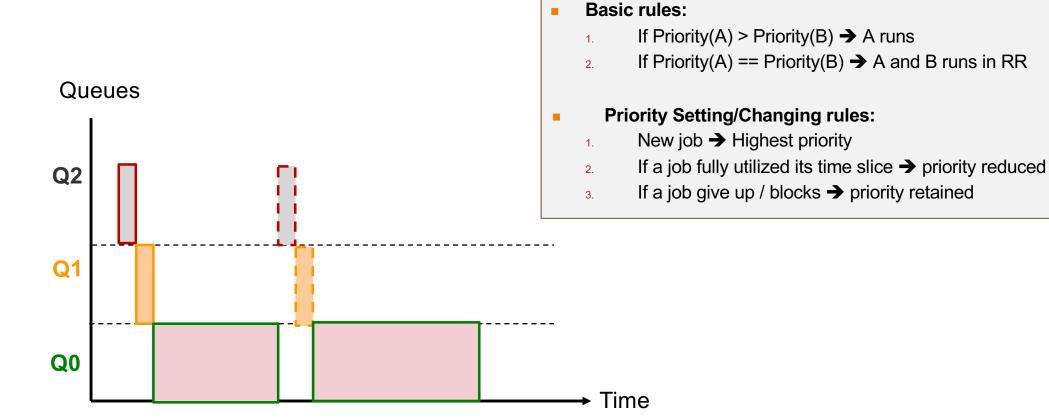
- 3 Queues: Q2 (highest priority), Q1, Q0
- A single long running job



MLFQ: Example 2

Example 1 + a short job in the middle

A short job appears sometime in the middle

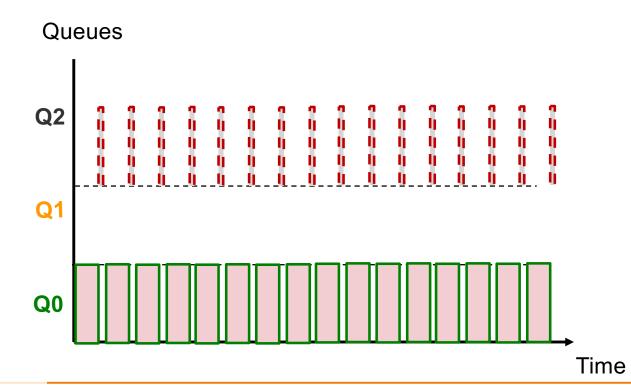


MLFQ: Example 3

Two jobs:

□ A = CPU bound (already in the system for quite some time)

B = I/O bound



MLFQ: Questions to ponder

- Can you think of a way to abuse the algorithm?
 - Equivalent question: MLFQ does not work well for what kind combination of jobs?

What are the ways to rectify the above?

Lottery Scheduling

General Idea:

- Scheduling is done in rounds. In every round:
 - Give out "lottery tickets" to processes for various system resources
 - E.g., CPU time, I/O device etc
 - When a scheduling decision is needed:
 - A lottery ticket is chosen randomly among eligible tickets
 - The winner is granted the resource
- In every round, a process holding X% of tickets
 - Can win X% of the lottery held
 - Use the resource X% of the time



Lottery Scheduling: Properties

Responsive:

- Every participating process gets to run in every round
- A newly created process can participate in the next lottery round
- Provides good level of control:
 - A process can be given Y lottery tickets
 - It can then distribute to its child process
 - An important process can be given more lottery tickets
 - Can control the proportion of usage
 - Each resource can have its own set of tickets
 - Different proportion of usage per resource per task
 - Simple implementation

Summary

- Scheduling in OS:
 - Basic definition
 - Factors that affect scheduling
 - Process, Environment
 - Criteria of good scheduling
- Scheduling Algorithms:
 - FCFS, SJF, SRT for Batch Processing System
 - RR, Priority, Multi-Level Queues and Lottery scheduling for Interactive System

References

- Modern Operating System (4th Edition)
 - Chapter 2.4
- Operating System Concepts (9th Edition)
 - Chapter 6
- Operating Systems: Three Easy Pieces
 - http://pages.cs.wisc.edu/~remzi/OSTEP
 - Chapters 7, 8, 9
 - Advanced (optional): chapter 10