

## Homework #6

### 6.1 Bayesian Universe

- (1) Because  $(\omega, \theta)$  is fixed,  $P(Z|(\omega, \theta)) = P(Z)$ . Derive as follows:

$$P(Z) = P(\{(x_n, y_n)\}_{n=1}^N) = \prod_{n=1}^N P(x_n)P(y_n|x_n) = \prod_{n=1}^N (P(x_n)P(y_n|\rho_n)) \quad (5.1.1)$$

By the procedure (c), substitute those parameters in equation (5.1.1),

$$P(x)P(y|\rho) = P(x) \left( \frac{1}{\sqrt{2\pi}} \exp(-(y - \rho)^2) \right) \quad (5.1.2)$$

Combine (5.1.1) and (5.1.2) we get the likelihood  $P(Z|(\omega, \theta))$

$$\prod_{n=1}^N P(x_n)P(y_n|\rho_n) = \prod_{n=1}^N \left( P(x_n) \left( \frac{1}{\sqrt{2\pi}} \exp(-(y_n - \rho_n)^2) \right) \right) \quad (5.1.3)$$

We look at the maximum likelihood function. Therefore, our goal function should satisfy

$$\arg \max_{(\omega, \theta)} \ln \prod_{n=1}^N \left( \frac{1}{\sqrt{2\pi}} \exp(-(y_n - \rho_n)^2) \right)$$

Because those parameter do not correlated to  $\omega, \theta$  can view as constant, the formula equal to

$$\arg \max_{(\omega, \theta)} \sum_{n=1}^N (-(y_n - \rho_n)^2) = \arg \min_{(\omega, \theta)} \sum_{n=1}^N (y_n - \rho_n)^2$$

That is same as *linear regression* that we did on Problem 2.3-(1).

- (2) By the Bayesian theorem, we can derive the posteriori as follow:

$$P((\omega, \theta)|Z) = \frac{P(Z|(\omega, \theta))P(\omega, \theta)}{P(Z)}$$

Where, the likelihood here derive as 5.1(1), that is

$$P(Z|(\omega, \theta)) = \prod_{n=1}^N \left( P(x_n) \left( \frac{1}{\sqrt{2\pi}} \exp(-(y_n - \rho_n)^2) \right) \right)$$

Therefore, posterior is

$$P((\omega, \theta)|Z) = \frac{\prod_{n=1}^N \left( P(x_n) \left( \frac{1}{\sqrt{2\pi}} \exp(-(y_n - \rho_n)^2) \right) \right) \frac{1}{(\sqrt{2\pi})^{d+1} \sigma^{d+1}} \exp\left(-\left(\frac{\|\omega\|^2 + \theta^2}{2\sigma^2}\right)\right)}{Q}$$

To maximum it, our goal function should satisfy

$$\arg \max_{(\omega, \theta)} \ln \prod_{n=1}^N \left( P(x_n) \left( \frac{1}{\sqrt{2\pi}} \exp(-(y_n - \rho_n)^2) \right) \right) \exp \left( - \left( \frac{\|\omega\|^2 + \theta^2}{2\sigma^2} \right) \right)$$

That is equal to

$$\arg \max_{(\omega, \theta)} \frac{1}{2} \left( \sum_{n=1}^N -(y_n - \rho_n)^2 - \frac{\|\omega\|^2 + \theta^2}{2\sigma^2} \right)$$

Consider the negation, rewrite the goal function as

$$\arg \min_{(\omega, \theta)} \frac{\frac{1}{2\sigma^2} \|\omega\|^2}{2} + \frac{\frac{1}{2\sigma^2} \theta^2}{2} + \frac{1}{2} \sum_{n=1}^N (y_n - \rho_n)^2$$

It is same as the *regularized linear regression*, and the relation between  $\lambda, \sigma$  is

$$\lambda = \frac{1}{2\sigma^2}$$

(3) We derive the likelihood as follow:

$$\begin{aligned} P(Z|\omega, \theta) &= P(\{(x_n, y_n)\}_{n=1}^N | \omega_n, \theta_n) \\ &= \prod_{n=1}^N P(x_n | \omega_n, \theta_n) P(y_n | x_n, \omega_n, \theta_n) \\ &= \prod_{n=1}^N P(x_n) P(y_n | \rho_n) \end{aligned}$$

The Objective function  $\max P(Z|\omega, \theta)$  should satisfy the equation

$$\begin{aligned} \arg \max_{\omega, \theta} \ln \prod_{n=1}^N P(x_n) P(y_n | \rho_n) &= \arg \max_{\omega, \theta} \ln \prod_{n=1}^N P(y_n | \rho_n) \\ &= \arg \max_{\omega, \theta} \ln \prod_{n=1}^N \frac{1}{1 + \exp(-y_n \rho_n)} \\ &= \arg \max_{\omega, \theta} \sum_{n=1}^N -(1 - y_n \rho_n) \\ &= \arg \min_{\omega, \theta} \sum_{n=1}^N (1 - y_n \rho_n) \end{aligned}$$

The *Logistic Regression* is equivalently gives the maximum likelihood estimated of  $(\omega, \theta)$ .

## 6.2 Power of Adaptive Boosting

- (1) In the first iteration we get

$$U^{(0)} = \sum_{n=1}^N \frac{1}{N} = \frac{1}{N} \sum_{n=1}^N 1 = 1$$

- (2) Proof by Induction:

- (a) Base: When  $t = 1$ , denote  $B_b = -y_n \alpha_b h_b(x_n)$ , by definition

$$U^{(1)} = U^{(2-1)} = \frac{1}{N} \sum_{n=1}^N 1 * \exp(B_1) = \frac{1}{N} \sum_{n=1}^N \exp\left(-y_n \sum_{\tau=1}^1 \alpha_{\tau} h_{\tau}(x_n)\right)$$

- (b) Inductive: Suppose that

$$U^{(k)} = \frac{1}{N} \sum_{n=1}^N \exp\left(-y_n \sum_{\tau=1}^k \alpha_{\tau} h_{\tau}(x_n)\right)$$

We have

$$\begin{aligned} U^{(k+1)} &= U^{(k+2-1)} = \frac{1}{N} \sum_{n=1}^N \exp\left(-y_n \sum_{\tau=1}^k \alpha_{\tau} h_{\tau}(x_n)\right) * \exp(B_{k+1}) \\ &= \frac{1}{N} \sum_{n=1}^N \exp\left(-y_n \sum_{\tau=1}^{k+1} \alpha_{\tau} h_{\tau}(x_n)\right) \end{aligned}$$

- (3) Express  $v(H) - U^{(T)} = s$ , denote that  $\sum_{\tau=1}^T \alpha_{\tau} h_{\tau}(x_n) = v$

$$s = \frac{1}{N} \sum_{n=1}^N I\left[y_n \neq \text{sign}\left(\sum_{\tau=1}^T \alpha_{\tau} h_{\tau}(x_n)\right)\right] - \frac{1}{N} \sum_{n=1}^N \exp\left(-y_n \sum_{\tau=1}^T \alpha_{\tau} h_{\tau}(x_n)\right)$$

The sign of $s$	$y_n \geq 0$	$y_n < 0$
The sign of $v \geq 0$	Zero - Nonzero	$1 - (\text{some value} \geq 1)$
The sign of $v < 0$	$1 - (\text{some value} \geq 1)$	Zero - Nonzero

In each cases we get the result that  $s \leq 0$ .

(4) Derive the step as follow:

$$\begin{aligned}
 U^{(t)} &= \sum_{n=1}^N u_n \exp(-\alpha_t y_n h_t(x_n)) \\
 &= \sum_{n+} u_n \exp(-\alpha_t) + \sum_{n-} u_n \exp(\alpha_t) \\
 &= \sum_{n+} u_n \sqrt{\frac{\epsilon_t}{1-\epsilon_t}} + \sum_{n-} u_n \sqrt{\frac{1-\epsilon_t}{\epsilon_t}} \\
 &= \sum_{n+} u_n \epsilon_t \sqrt{\frac{1}{\epsilon_t(1-\epsilon_t)}} + \sum_{n-} u_n (1-\epsilon_t) \sqrt{\frac{1}{\epsilon_t(1-\epsilon_t)}} \\
 &= \sqrt{\frac{1}{\epsilon_t(1-\epsilon_t)}} (\epsilon_t \sum_{n+} u_n + (1-\epsilon_t) \sum_{n-} u_n) \\
 &= \sqrt{\frac{1}{\epsilon_t(1-\epsilon_t)}} (\epsilon_t (1-\epsilon_t) U^{(t-1)} + (1-\epsilon_t) \epsilon_t U^{(t-1)}) \quad \text{By the definition of } \epsilon_t \\
 &= 2\sqrt{\epsilon_t(1-\epsilon_t)} U^{(t-1)}
 \end{aligned}$$

(5) Consider the function  $E(x) = x(1-x) = -\left(x - \frac{1}{2}\right)^2 + \frac{1}{4}$ . In the region  $0 \leq \epsilon_t \leq \epsilon \leq \frac{1}{2}$ , we have

$$\sqrt{\epsilon_t(1-\epsilon_t)} \leq \sqrt{\epsilon(1-\epsilon)}$$

(6) Consider  $E(\epsilon) = \sqrt{\epsilon(1-\epsilon)} - \frac{1}{2} \exp\left(-2\left(\frac{1}{2} - \epsilon\right)^2\right)$ . In the case  $\epsilon = 1/2$ , we have  $E = 0$ , then we consider  $E'(\epsilon) = (1-2\epsilon) \left( \frac{1}{2} (\epsilon - \epsilon^2)^{-\frac{1}{2}} + \exp\left(\frac{1}{2} - 2\epsilon + 2\epsilon^2\right) \right) \leq 0$  in case  $\epsilon \leq \frac{1}{2}$ , thus,  $E(\epsilon) \leq 0$ .

(7) Use the equation above:

$$\begin{aligned}
 U^{(T)} &= \prod_{t=1}^T \sqrt{\epsilon_t(1-\epsilon_t)} \\
 &\leq \prod_{t=1}^T \sqrt{\epsilon(1-\epsilon)} \\
 &\leq \prod_{t=1}^T \frac{1}{2} \exp\left(-2\left(\frac{1}{2} - \epsilon\right)^2\right) \\
 &\leq \exp\left(-2T\left(\frac{1}{2} - \epsilon\right)^2\right)
 \end{aligned}$$

(8) Use the fact above,

$$v(H) \leq U^{(T)} \leq \exp\left(-2T\left(\frac{1}{2} - \epsilon\right)^2\right)$$

When  $T$  grow up,  $U^{(T)} \rightarrow 0$ . And we also know

$$v(H) \in \left\{\frac{n}{N}\right\}_{n=0}^N$$

Find a  $T$  such that

$$T = \frac{1}{2\left(\frac{1}{2} - \epsilon\right)^2} \log N + c = O(\log N)$$

Then we have

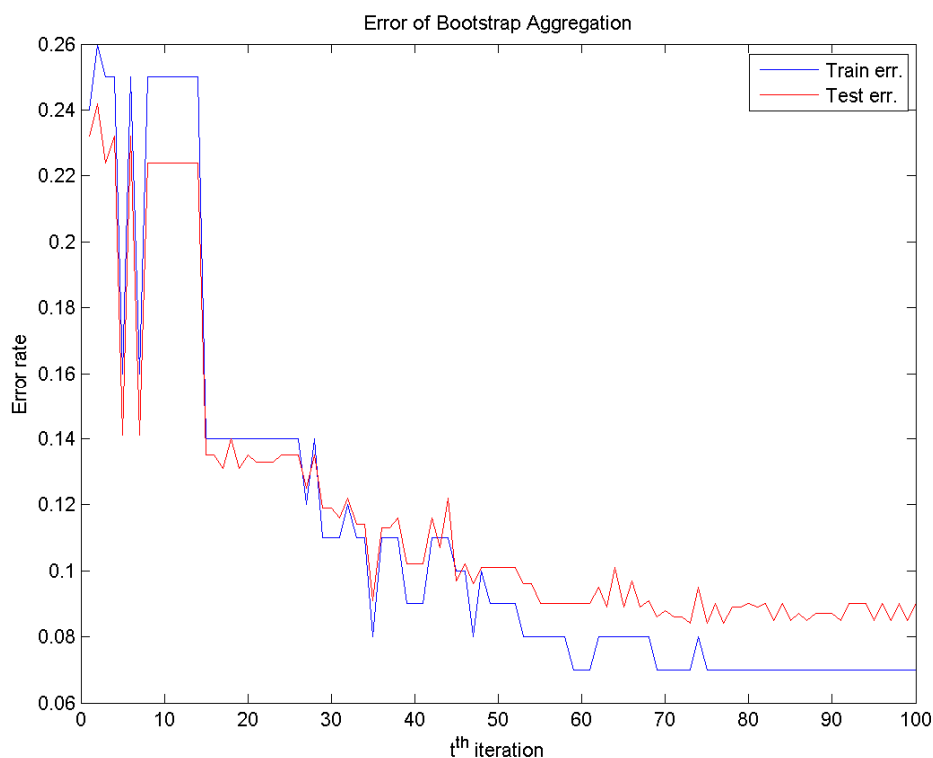
$$U^{(T)} < \frac{1}{N}$$

Therefore,

$$v(H) = 0$$

## 6.3 Experiments with Bootstrap Aggregation

- (1) The training error is 0.23, and the test error is 0.255. Our brief finding:
  - (a) The error always is a fixed value, unless we change  $\theta$ .
  - (b) One thing should be careful, the method that we find  $\theta$  should cover  $[-1, 1]$ , for a training data set range in  $[0, 1]$ .
- (2) The figure we found as follow:



Our brief finding:

- (a) Training error and testing error have strong correlated. Even a small pick on training error would reflect on testing error.
- (b) The performance seems better than expected.

## (3) Pseudocode:

- 1  $D = \text{Sort data points increasingly}$  in time  $O(N \log N)$
- 2  $L^+ = [0, \text{Aggregating the positive value from left to right}]$  in time  $O(N)$
- 3  $R^- = [\text{Aggregating the negative value from right to left}, 0]$  in time  $O(N)$
- 4  $R^+ = [\text{Aggregating the positive value from right to left}, 0]$  in time  $O(N)$
- 5  $L^- = [0, \text{Aggregating the negative value from left to right}]$  in time  $O(N)$
- 6  $W^1 = \text{column weighted sum on } [L^+, R^-]$  in time  $O(N)$
- 7  $W^2 = \text{column weighted sum on } [R^+, L^-]$  in time  $O(N)$
- 8  $2\theta^1 = (A_1^1 + A_2^1) = \text{The argmin value column in } W^1$  in time  $O(N)$
- 9  $2\theta^2 = (A_1^2 + A_2^2) = \text{The argmin value column in } W^2$  in time  $O(N)$
- 10  $\theta = \min(\theta^1 + \theta^2)$  in time  $O(N)$

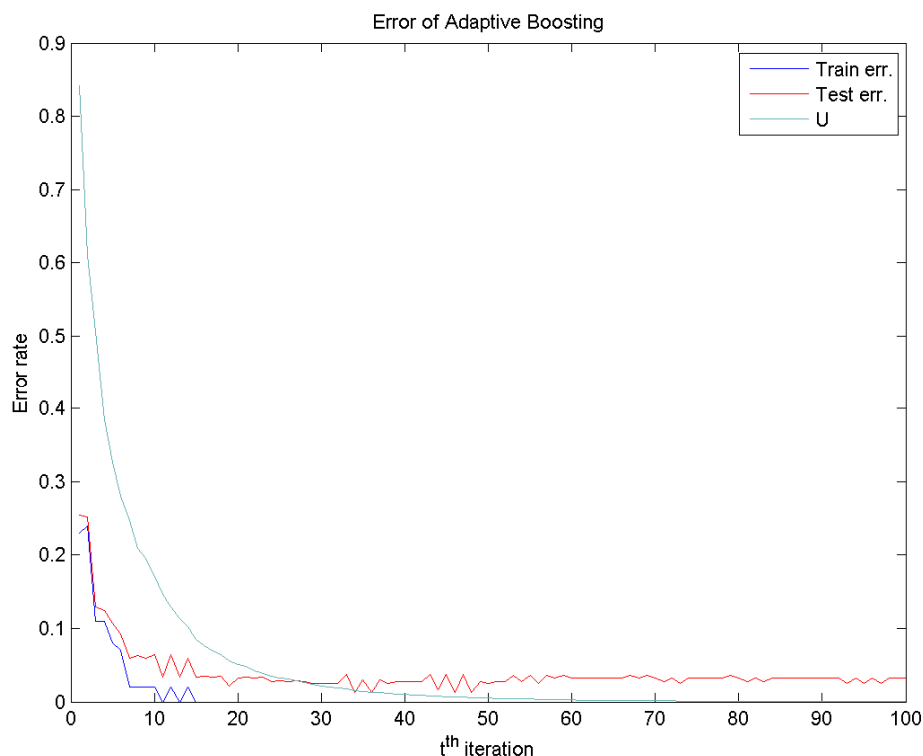
Our object function is

$$\arg \min_{h_{s,i,\theta}} \sum_{n=1}^N u_n I[y_n \neq h_{s,i,\theta}(x_n)]$$

Therefore, we use the pseudocode above and get minimum a good result in time  $O(N \log N)$ .

## 6.4 Experiments with Adaptive Boosting

(1) The figure show as follow:



Our brief finding:

- (a) Training error 'seems' always less than testing error, and it would converge to 0.
- (b) U 'seems' has an inverse proportion with  $t$ .

(2) Brief finding:

- (a) Adaptive Boosting algorithm (AdaBoost) has a better result than Bootstrap Aggregation algorithm (Bagging).
- (b) AdaBoost has a zero training error performance, but Bagging does not have that.
- (c) Both of algorithms start with a not bad error rate, Bagging would go up but AdaBoost won't.