

Intermediate OpenCL Programming

Pangfeng Liu
National Taiwan University

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Buffer

There are three exclusive types of buffers.

CL_MEM_USE_HOST_PTR

CL_MEM_ALLOC_HOST_PTR

CL_MEM_COPY_HOST_PTR

CL_MEM_USE_HOST_PTR

- OpenCL uses the host memory as the buffer so the `host_ptr` must not be `NULL`.
- If the device is GPU then the access is slow because the buffer is in the host (CPU).

CL_MEM_ALLOC_HOST_PTR

- OpenCL will allocate a buffer in the device and the device will use it directly.
- This memory is accessible from the host by `clEnqueueWriteBuffer` and `clEnqueueReadBuffer`.
- Since the device will allocate the buffer we cannot provide a non-NULL `host_ptr`.
- The access is fast because the buffer is in the device

CL_MEM_COPY_HOST_PTR

- OpenCL will copy the contents of the host buffer to a buffer on the device
- The device will use the device buffer.
- The access is fast because the buffer is in the device (GPU/CPU).

Comparison

buffer type	host_ptr	device will use	speed from GPU
USE	<code>!= NULL</code>	the host buffer directly	slow
ALLOC	<code>== NULL</code>	the device buffer	fast
COPY	<code>!= NULL</code>	the device buffer copied from the host buffer	fast

Discussion

- Which of the allocation mode provides the slowest memory access from a device GPU?

Need not to Retrieve

- We would like to implement the vector addition program without getting the results back from the device.
- The idea is that we copy the vector A and B into device with `CL_MEM_COPY_HOST_PTR` buffer, and put the results in a `CL_MEM_USE_HOST_PTR` buffer.
- When the computation is over then we can get the results in the host buffer directly.

Example 1: (vectorAdd-nofetchC.c)

```
71 cl_mem bufferA =
72     clCreateBuffer(context,
73         CL_MEM_READ_ONLY | CL_MEM_COPY_HOST_PTR,
74         N * sizeof(cl_uint), A, &status);
75 assert(status == CL_SUCCESS);
76 cl_mem bufferB =
77     clCreateBuffer(context,
78         CL_MEM_READ_ONLY | CL_MEM_COPY_HOST_PTR,
79         N * sizeof(cl_uint), B, &status);
80 assert(status == CL_SUCCESS);
81 cl_mem bufferC =
82     clCreateBuffer(context,
83         CL_MEM_WRITE_ONLY | CL_MEM_USE_HOST_PTR,
84         N * sizeof(cl_uint), C, &status);
85 assert(status == CL_SUCCESS);
86 printf("Build buffers completes\n");
```

Execution

- After creating buffers, setting the parameter order, and set up the dimension of NDRange, we run the kernel by placing it into the command queue

clFinish

Example 2: (vectorAdd-nofetchC.c)

```
99  size_t globalThreads[] = {(size_t)N};
100 size_t localThreads[] = {1};
101 status =
102     clEnqueueNDRangeKernel(commandQueue, kernel, 1, NULL,
103                             globalThreads, localThreads,
104                             0, NULL, NULL);
105 assert(status == CL_SUCCESS);
106 printf("Kernel execution completes.\n");
```

Demonstration

- Run the `vector-nofetchC-cl` program.

Discussion

- Does it produce the correct answer?

Non-blocking

- The previous program does not produce the correct answer because the function call `clEnqueueNDRangeKernel` is *non-blocking*, which means it will not wait for the completion of the kernel.
- Since we check the contents of C before the kernel finishes, the answer is incorrect.
- We need to wait for the commands in the command queue to finish.

Prototype 3: clFinish.h

```
1 cl_int clFinish(cl_command_queue command_queue);
```

Parameters

`command_queue` Wait for the commands in this command queue to finish.

clFinish

Example 4: (vectorAdd-nofetchC-finish.c)

```
99  size_t globalThreads[] = {(size_t)N};  
100 size_t localThreads[] = {1};  
101 status =  
102     clEnqueueNDRangeKernel(commandQueue, kernel, 1, NULL,  
103                             globalThreads, localThreads,  
104                             0, NULL, NULL);  
105 assert(status == CL_SUCCESS);  
106 printf("Kernel execution completes.\n");  
107 /* getcvector */  
108 clFinish(commandQueue);
```

Demonstration

- Run the `vector-nofetchC-finish-cl` program.

Discussion

- Does it produce the correct answer?

NDRange

- We can set the dimension of NDRange in the `clEnqueueNDRangeKernel` call.
- In the previous example we set the dimension to one, now we want to set it to two.
- Now a work item in NDRange will have two indices for two dimensions.

Index

- We can call `get_global_id(i)` to know its index in the i -th dimension.
- The parameter `i` must be within the dimension of `NDRange`

Prototype 5: getGlobalId.h

```
1  size_t get_global_id(uint dimindx);
```

Parameters

`dimindx` The dimension in which we want to know the index.

Domain

- We will use an array to keep track of the global indices a kernel function can see from a work item.
- We declare this array as `int globalId[2][N][N]`, where N is 16.
- The first 2 is for two dimensions.

Kernel

Example 6: (get-global-id.cl)

```
1  #define N 16
2
3  __kernel void getGlobalId(__global int globalId[2][N][N])
4  {
5      int id0 = get_global_id(0);
6      int id1 = get_global_id(1);
7      globalId[0][id0][id1] = id0;
8      globalId[1][id0][id1] = id1;
9  }
```

Kernel

- We first call `get_global_id(0)` and `get_global_id(1)` to know the indices of this work item on the two dimensions, and put them into `id0` and `id1`.
- Then we place `id0` and `id1` into corresponding cells of `globalId`.

Discussion

- Google `__global` to and find out what it means.

Buffer

- In the main program we declare a host buffer `bufferGlobalId` to hold the global indices.
- This buffer will link to the `globalId[2][N][N]` parameter in the kernel function.

Buffers

Example 7: (get-global-id.c)

```
74 cl_mem bufferGlobalId =  
75     clCreateBuffer(context,  
76                     CL_MEM_WRITE_ONLY | CL_MEM_USE_HOST_PTR,  
77                     2 * N * N * sizeof(cl_uint), globalId, &status)  
78 assert(status == CL_SUCCESS);  
79 printf("Build buffers completes\n");  
80 /* setarg */  
81 status = clSetKernelArg(kernel, 0, sizeof(cl_mem),  
82                           (void*)&bufferGlobalId);  
83 assert(status == CL_SUCCESS);  
84 printf("Set kernel arguments completes\n");
```

Dimension

- Now we set the dimension of `NDRange` to 2, and set the size of each dimension to `N`, as in `globalDim`.
- Since `NDRange` has two dimensions, a work group will also have two dimension. For simplicity we set it to one by one, as in `localDim`.
- We place the kernel into the command queue, then call `clFinish` to wait for the completion.

Buffers

Example 8: (get-global-id.c)

```
86  size_t globalDim[] = {(size_t)N, (size_t)N};
87  size_t localDim[] = {1, 1};
88  status =
89      clEnqueueNDRangeKernel(commandQueue, kernel, 2, NULL,
90                             globalDim, localDim,
91                             0, NULL, NULL);
92  assert(status == CL_SUCCESS);
93  printf("Specify the shape of the domain completes.\n");
94  /* getresult */
95  clFinish(commandQueue);
96  printf("Kernel execution completes.\n");
97
98  printId("get_global_id(0)", globalId[0]);
99  printId("get_global_id(1)", globalId[1]);
```

printId

- We implement a `printId` function to print the contents in any array.
- The first parameter is a string for identification purpose, and the second parameter is the array of indices to print.

Buffers

Example 9: (get-global-id.c)

```
12 void printId(char *title, cl_uint id[N][N])
13 {
14     puts(title);
15     for (int i = 0; i < N; i++) {
16         for (int j = 0; j < N; j++)
17             printf("%2d ", id[i][j]);
18         printf("\n");
19     }
20 }
```

Demonstration

- Run the `get-global-id-cl` program.

Discussion

- Describe the printed indices.
- Will the output be affected if we set the work group size differently?

NDRange

- Local index is the index within a work group.
- We can specify the size of each dimension for a work group in a `clEnqueueNDRangeKernel` call.
- In this example we will set the size of local dimension and observe the results.

Local Index

- We call `get_local_id(i)` to know its index in the i -th dimension.
- The parameter `i` must be within the dimension of `NDRange` because the local and the global index have the same number of dimensions.

Prototype 10: getLocalId.h

```
1 size_t get_local_id(uint dimindx);
```

Parameters

`dimindx` The dimension in which we want to know the index.

Domain

- We will use two arrays to keep track of global and local index a kernel function can see from a work item respectively.
- We declare two arrays as `int globalId[2][N][N]` and `int localId[2][N][N]`.

Kernel

Example 11: (get-global-local-id.cl)

```
1  #define N 16
2
3  __kernel void getGlobalId(__global int globalId[2][N][N],
4  __global int localId[2][N][N])
5  {
6      int id0 = get_global_id(0);
7      int id1 = get_global_id(1);
8      globalId[0][id0][id1] = get_global_id(0);
9      globalId[1][id0][id1] = get_global_id(1);
10     localId[0][id0][id1] = get_local_id(0);
11     localId[1][id0][id1] = get_local_id(1);
12 }
```

Kernel

- We first call `get_global_id(0)` and `get_global_id(1)` to know the indices of this work item in `NDRange`, and put them into `id0` and `id1`.
- Then we call `get_global_id` and `get_local_id` to get the indices.

Buffers

- In the main program we declare two host buffers `bufferGlobalId` and `bufferLocalId` to hold the global and local indices.
- This buffer will link to parameters `globalId[2][N][N]` and `localId[2][N][N]` in the kernel function.

Buffers

Example 12: (get-global-local-id.c)

```
75  cl_mem bufferGlobalId =
76      clCreateBuffer(context,
77                      CL_MEM_WRITE_ONLY | CL_MEM_USE_HOST_PTR,
78                      2 * N * N * sizeof(cl_uint), globalId, &status)
79  assert(status == CL_SUCCESS);
80  cl_mem bufferLocalId =
81      clCreateBuffer(context,
82                      CL_MEM_WRITE_ONLY | CL_MEM_USE_HOST_PTR,
83                      2 * N * N * sizeof(cl_uint), localId, &status);
84  assert(status == CL_SUCCESS);
85  printf("Build buffers completes\n");
86  /* setarg */
87  status = clSetKernelArg(kernel, 0, sizeof(cl_mem),
88                          (void*)&bufferGlobalId);
89  assert(status == CL_SUCCESS);
90  status = clSetKernelArg(kernel, 1, sizeof(cl_mem),
91                          (void*)&bufferLocalId);
92  assert(status == CL_SUCCESS);
93  printf("Set kernel arguments completes\n");
```

Dimension

- Now we set the dimension of `NDRange` to 2, and set the size of each dimension to `N`, as in `globalDim`.
- We set the size of dimension of a work group from the command line arguments, and place the sizes into `localDim`.
- We place the kernel into the command queue, then call `clFinish` to wait for the completion.

Buffers

Example 13: (get-global-local-id.c)

```
95  size_t globalDim[] = {(size_t)N, (size_t)N};
96  int groupRow = atoi(argv[2]);
97  int groupCol = atoi(argv[3]);
98  size_t localDim[] = {groupRow, groupCol};
99  status =
100      clEnqueueNDRangeKernel(commandQueue, kernel, 2, NULL,
101                              globalDim, localDim,
102                              0, NULL, NULL);
103  assert(status == CL_SUCCESS);
104  printf("Specify the shape of the domain completes.\n");
105  /* getresult */
106  clFinish(commandQueue);
107  printf("Kernel execution completes.\n");
108  /* pritnid */
109  printId("get_global_id(0)", globalId[0]);
110  printId("get_global_id(1)", globalId[1]);
111  printId("get_local_id(0)", localId[0]);
112  printId("get_local_id(1)", localId[1]);
```

Demonstration

- Run the `get-global-id-cl` program by setting the work group size to be 4 by 4.
- Run the `get-global-id-cl` program by setting the work group size to be 2 by 4.

Discussion

- Describe the printed indices under different group sizes.

Matrix Multiplication

- We now use matrix multiplication as an example of using global index.
- We will multiply two N by N matrices using GPU.

Kernel

- The multiplication kernel has three parameters – A, B and C.
- We will multiply A with B, and place the results in C.
- We first get the row and column number of this work item, then perform an inner product.

Kernel

Example 14: (mul-kernel.cl)

```
1  #define N 1024
2
3  __kernel void mul(__global int matrixA[N][N],
4                    __global int matrixB[N][N],
5                    __global int matrixC[N][N])
6  {
7      int row = get_global_id(0);
8      int col = get_global_id(1);
9      int sum = 0;
10     for (int i = 0; i < N; i++)
11         sum += matrixA[row][i] * matrixB[i][col];
12     matrixC[row][col] = sum;
13 }
```

Matrices

- The main program first prepares host memory matrices A and B.

Buffers

Example 15: (matrixMul.c)

```
62  for (int i = 0; i < N; i++)  
63      for (int j = 0; j < N; j++) {  
64          A[i][j] = i + j;  
65          B[i][j] = i - j;  
66      }
```

Buffers

- The main program then creates OpenCL buffers for A, B and C.
- The contents of A and B will be copied into devices (`CL_MEM_COPY_HOST_PTR`), and the GPU will use host memory buffer directly (`CL_MEM_USE_HOST_PTR`).

Buffers

Example 16: (matrixMul.c)

```
68  cl_mem bufferA =
69      clCreateBuffer(context,
70                      CL_MEM_READ_ONLY | CL_MEM_COPY_HOST_PTR,
71                      N * N * sizeof(cl_uint), A, &status);
72  assert(status == CL_SUCCESS);
73  cl_mem bufferB =
74      clCreateBuffer(context,
75                      CL_MEM_READ_ONLY | CL_MEM_COPY_HOST_PTR,
76                      N * N * sizeof(cl_uint), B, &status);
77  assert(status == CL_SUCCESS);
78  cl_mem bufferC =
79      clCreateBuffer(context,
80                      CL_MEM_WRITE_ONLY | CL_MEM_USE_HOST_PTR,
81                      N * N * sizeof(cl_uint), C, &status);
82  assert(status == CL_SUCCESS);
83  printf("Build buffers completes\n");
```

Run Kernel

- We set the size of both dimensions to N , as in `globalDim`.
- We set the sizes of dimensions of a work group as 1 by 1 and place the sizes into `localDim`.
- We place the kernel into the command queue, then call `clFinish` to wait for the completion.

Buffers

Example 17: (matrixMul.c)

```
96  size_t globalThreads[] = {(size_t)N, (size_t)N};
97  size_t localThreads[] = {1, 1};
98  status =
99      clEnqueueNDRangeKernel(commandQueue, kernel, 2, NULL,
100                             globalThreads, localThreads,
101                             0, NULL, NULL);
102  assert(status == CL_SUCCESS);
103  printf("Specify the shape of the domain completes.\n");
104  /* getcvector */
105  clFinish(commandQueue);
106  printf("Kernel execution completes.\n");
```

Demonstration

- Run the `matrixMul-cl` program.

Discussion

- Did you notice the significant speed difference in the computation and verification parts?

Time Measurement

- We would like to measure the kernel execution time.
- The kernel is sent to a device through a *command queue*, so we need to enable the command queue for profiling.
- We associate an event with the end of a kernel execution, then wait for the event.
- We retrieve the timing information from the event.

Steps

- We set the property of the command queue to allow profiling.
- We then declare a variable of type `cl_event` for the event.
- We then supply the event as the last parameter when calling `clEnqueueNDRangeKernel`.
- We then wait for this event by calling a function `clWaitForEvents`.
- Finally we extract the timing information from the event by calling `clGetEventProfilingInfo`.

Command Queue

- The kernel is sent to a device through a *command queue*.
- If we want to time (profile) the kernel execution, we need to explicitly set the property of the command queue to `CL_PROFILING_COMMAND_QUEUED`.

Prototype 18: clCreateCommandQueue.h

```
1 cl_command_queue  
2 clCreateCommandQueue(cl_context context,  
3                       cl_device_id device,  
4                       cl_command_queue_properties  
5                       properties,  
6                       cl_int *errcode_ret);
```

Property

- We explicitly set the `CL_PROFILING_COMMAND_QUEUED` property of the command queue when we created it.

Example 19: (matrixMul-time.c)

```
36  cl_command_queue commandQueue =  
37      clCreateCommandQueue(context, GPU[0],  
38                          CL_QUEUE_PROFILING_ENABLE,  
39                          &status);  
40  assert(status == CL_SUCCESS);
```

Discussion

- Google to find out other properties that can be set for a command queue.

Kernel Execution

- After setting the command queue for profiling, we can start the kernel.
- We supply event as the last parameter while calling `clEnqueueNDRangeKernel`, so now we have associated the event with the kernel execution.

Prototype 20: clEnqueueNDRangeKernel.h

```
1  cl_int  
2  clEnqueueNDRangeKernel (cl_command_queue command_queue,  
3                          cl_kernel kernel,  
4                          cl_uint work_dim,  
5                          const size_t *global_work_offset,  
6                          const size_t *global_work_size,  
7                          const size_t *local_work_size,  
8                          cl_uint num_events_in_wait_list,  
9                          const cl_event *event_wait_list,  
10                         cl_event *event);
```

Example 21: (matrixMul-time.c)

```
98  size_t globalThreads[] = {(size_t)N, (size_t)N};
99  size_t localThreads[] = {1, 1};
100  cl_event event;
101  status =
102      clEnqueueNDRangeKernel(commandQueue, kernel, 2, NULL,
103                             globalThreads, localThreads,
104                             0, NULL, &event);
105  assert(status == CL_SUCCESS);
```

Wait for Event

- Now we have submitted the kernel to execution, we just wait for the event to happen.
- We call `clWaitForEvents` to wait for event(s).

clWaitForEvents

Prototype 22: clWaitForEvents.h

```
1 cl_int clWaitForEvents(cl_uint num_events,  
2                        const cl_event *event_list);
```

Parameters

`num_events` The number of events to wait for.

`event_list` The array of events to wait for.

Example 23: (matrixMul-time.c)

```
107     clWaitForEvents(1, &event);  
108     printf("Kernel execution completes.\n");
```

Discussion

- Trace the `matrixMul-time.c` to understand the flow so far.

Three Stages

A kernel execution will go through three stages.

- First the kernel joined the command queue for execution.
- When it is the turn of the kernel, it is submitted to the device for execution.
- When the kernel finished execution, it will trigger the event you associated with it.

Get Information

The event can provide the following four times.

- The time when the kernel joined the command queue.
- The time when the kernel was sent to the device for execution.
- The time when the kernel started execution.
- The time when the kernel finished execution.

Get Information

- We call `clGetEventProfilingInfo` to know the four times.
- The time-stamp is of type `cl_ulong`.

clGetEventProfilingInfo

Prototype 24: clGetEventProfilingInfo.h

```
1  cl_int  
2  clGetEventProfilingInfo(cl_event event,  
3                          cl_profiling_info param_name,  
4                          size_t param_value_size,  
5                          void *param_value,  
6                          size_t *param_value_size_ret);
```

Parameters

`event` The event that we want to query.

`param_name` The information to query.

`param_value_size` The length of buffer (`param_value`) to store the answer.

`param_value` The buffer to store the answer.

`param_value_size_ret` The actual length of the returned answer.

Four Time Points

- We put the four times in four variables – `timeEnterQueue`, `timeSubmit`, `timeStart`, and `timeEnd`.

Time Calculation

Example 25: (matrixMul-time.c)

```
110  cl_ulong timeEnterQueue, timeSubmit, timeStart, timeEnd;
111  status =
112      clGetEventProfilingInfo(event, CL_PROFILING_COMMAND_QUEUED,
113                              sizeof(cl_ulong), &timeEnterQueue, NULL);
114  assert(status == CL_SUCCESS);
115  status =
116      clGetEventProfilingInfo(event, CL_PROFILING_COMMAND_SUBMIT,
117                              sizeof(cl_ulong), &timeSubmit, NULL);
118  assert(status == CL_SUCCESS);
119  status =
120      clGetEventProfilingInfo(event, CL_PROFILING_COMMAND_START,
121                              sizeof(cl_ulong), &timeStart, NULL);
122  assert(status == CL_SUCCESS);
123  status =
124      clGetEventProfilingInfo(event, CL_PROFILING_COMMAND_END,
125                              sizeof(cl_ulong), &timeEnd, NULL);
126  assert(status == CL_SUCCESS);
```

Time Calculation

- We calculate the duration of each stage by the difference of the beginning and the ending time-stamps.
- The unit of time is nano (10^{-9}) second.

Example 26: (matrixMul-time.c)

```
128 printf("kernel queued time %f seconds\n",  
129        (timeSubmit - timeEnterQueue) / 1000000000.0);  
130 printf("kernel submission time %f seconds\n",  
131        (timeStart - timeSubmit) / 1000000000.0);  
132 printf("kernel execution time %f seconds\n",  
133        (timeEnd - timeStart) / 1000000000.0);
```

Demonstration

- Run the `matrixMul-time-cl` program.

Discussion

- Observe the times of the three stages.

Buffer Comparison

- Now we know how to measure kernel execution time, we can compare the effects of different communication buffers on the execution time.
- We will compare the executive time of using `CL_MEM_COPY_HOST_PTR` and `CL_MEM_USE_HOST_PTR` for creating A and B buffers.
- We will fix the allocation method of C to make a meaning comparison.

Difference

- The only difference between the following two programs is how they allocate A and B matrices.

Example 27: (matrixMul-time-copy.c)

```
70 cl_mem bufferA =
71     clCreateBuffer(context,
72                     CL_MEM_READ_ONLY | CL_MEM_COPY_HOST_PTR,
73                     N * N * sizeof(cl_uint), A, &status);
74 assert(status == CL_SUCCESS);
75 cl_mem bufferB =
76     clCreateBuffer(context,
77                     CL_MEM_READ_ONLY | CL_MEM_COPY_HOST_PTR,
78                     N * N * sizeof(cl_uint), B, &status);
79 assert(status == CL_SUCCESS);
80 cl_mem bufferC =
81     clCreateBuffer(context,
82                     CL_MEM_WRITE_ONLY | CL_MEM_USE_HOST_PTR,
83                     N * N * sizeof(cl_uint), C, &status);
84 assert(status == CL_SUCCESS);
85 printf("Build buffers completes\n");
```


Example 28: (matrixMul-time-use.c)

```
70  cl_mem bufferA =
71      clCreateBuffer(context,
72                      CL_MEM_READ_ONLY | CL_MEM_USE_HOST_PTR,
73                      N * N * sizeof(cl_uint), A, &status);
74  assert(status == CL_SUCCESS);
75  cl_mem bufferB =
76      clCreateBuffer(context,
77                      CL_MEM_READ_ONLY | CL_MEM_USE_HOST_PTR,
78                      N * N * sizeof(cl_uint), B, &status);
79  assert(status == CL_SUCCESS);
80  cl_mem bufferC =
81      clCreateBuffer(context,
82                      CL_MEM_WRITE_ONLY | CL_MEM_USE_HOST_PTR,
83                      N * N * sizeof(cl_uint), C, &status);
84  assert(status == CL_SUCCESS);
85  printf("Build buffers completes\n");
```

Demonstration

- Run the `matrixMul-time-copy-cl` and `matrixMul-time-use-cl` programs.

Discussion

- Compare the execution times of the two programs.
- What is the reason for this difference in kernel execution time?

Local Memory

- Local memory is shared by processing units in the same work group.
- Local memory is fast but small.
- We will use local memory to speed up matrix multiplication.

Idea

- Both matrices A and B are N by N .
- We will partition the matrices into Blk by Blk blocks, so each block has N/Blk rows and columns.
- For ease of notation we will use $Block(A, i, j)$ to denote the block in i -th row of blocks and j -th column of blocks in A .

Work Group

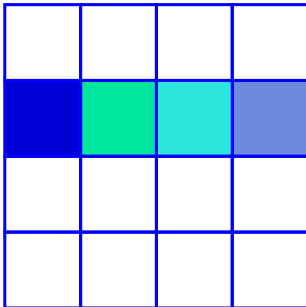
- Each work group will compute a block in C .
- Each thread will compute an element of C .

Divide and Conquer

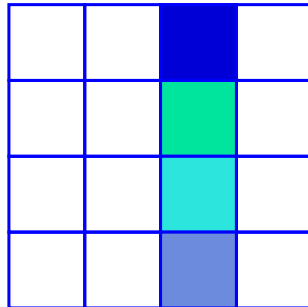
- Now consider the work group that is responsible for computing the $Block(C, i, j)$.
- This work group will first multiply $Block(A, i, 1)$ by $Block(B, 1, j)$.
- This work group will then multiply $Block(A, i, 2)$ by $Block(B, 2, j)$.
- ...
- This work group will then multiply $Block(A, i, N)$ by $Block(B, N, j)$.
- Then $Block(C, i, j)$ is the sum of all these products.

Divide and Conquer

A



B



Discussion

- Make sure that you understand this algorithm.

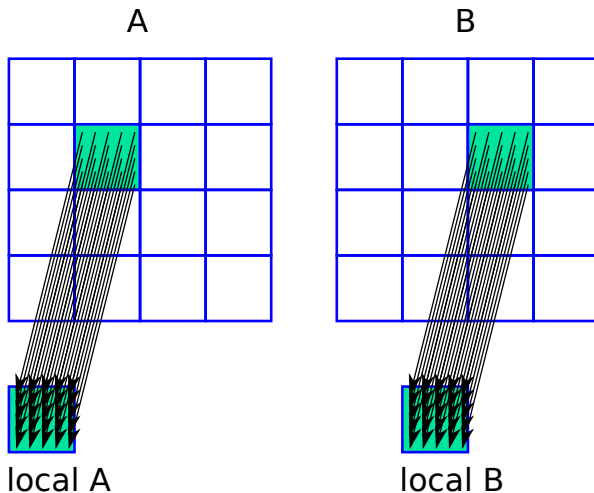
Fast multiplication

- If we know how to do matrix multiplication on two blocks, we know how to solve the whole problem.
- The problem is that if we do this on global memory, it will be slow.
- The idea is to bring $Block(A, i, 1)$ and $Block(B, 1, j)$ into local memory, then we can multiply them fast.
- How??

Memory Movement

- There are $(N/Blk)^2$ elements in $Block(A, i, 1)$.
- There are $(N/Blk)^2$ threads in this work group.
- We make each thread to move an element from both $Block(A, i, 1)$ $Block(B, 1, j)$ into local memory, then from both $Block(A, i, 2)$ and $Block(B, 2, j)$, and so on.
- After each movement each thread computes an element in $Block(C, i, j)$ using the data in local memory.

Move to Local Memory



Profitable

- Why is this profitable?
- Each thread only moves two data.
- Each thread will do a vector inner product on two vector of length (N/Blk) .
- That is, every data moved into local memory is shared by (N/Blk) other threads.

Discussion

- Make sure that you understand this profitable theory.

Steps

Now from a thread, or a kernel point of view, it will go through the following steps.

- Get the global and local indices of this work item.
- Go through Blk iterations, where each of these iterations multiplies two blocks.
 - Move a data from A in global memory into local memory.
 - Move a data from B in global memory into local memory.
 - After both steps are done compute the inner product and add it to a variable `sum`
- Put `sum` into the corresponding C element.

Constants

- Since the kernel function file cannot include other source files, we can only define these constants here. A more consistent method should be used in the future.
- We define a symbol `BSIDE` for the size of a side of the a block.

Example 29: (mul-local-kernel.cl)

```
2 #define N 1024
3 #define Blk 64
4 #define BSIDE (N / Blk)
```

Interface

- We use global memory as the interface between the kernel and the host, and the interface is the same as before.
- We declare two local matrices in local memory, using the `__local` keyword.

Example 30: (mul-local-kernel.cl)

```
6  __kernel void mul(__global int A[N][N],
7                      __global int B[N][N],
8                      __global int C[N][N])
9  {
10     int globalRow = get_global_id(0);
11     int globalCol = get_global_id(1);
12     int localRow = get_local_id(0);
13     int localCol = get_local_id(1);
14
15     __local int ALocal[BSIDE][BSIDE];
16     __local int BLocal[BSIDE][BSIDE];
```

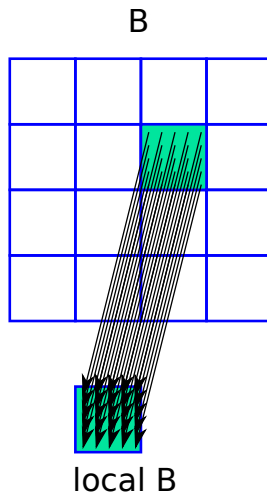
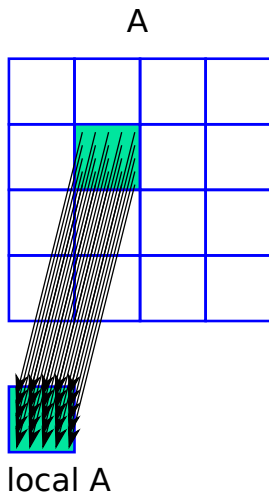
Data Movement

- Each thread (kernel function) moves one data into local A and B .
- However, we need to make sure that when we start the inner product, *all* the data are there.
- Remember a thread only moves two data, other data are moved by other threads – we do not know if they have finished or not.
- We need to synchronize with all other threads in the work group.

Example 31: (mul-local-kernel.cl)

```
18  int sum = 0;
19  for (int block = 0; block < Blk; block++) {
20      ALocal[localRow][localCol] =
21          A[globalRow][block * BSIDE + localCol];
22      BLocal[localRow][localCol] =
23          B[block * BSIDE + localRow][globalCol];
24      barrier(CLK_LOCAL_MEM_FENCE);
```

Move to Local Memory



Discussion

- Do we need to synchronize with thread in other work groups?
- Convince yourself that the index calculation is correct.

Synchronization

- We use barrier to synchronize threads.
- All threads in the same group will synchronize.

barrier

Prototype 32: barrier.h

```
1 void barrier(cl_mem_fence_flags flags);
```

Parameters

flags The memory level this synchronization guarantees.

CLK_LOCAL_MEM_FENCE Guarantees that all local memory operations will finish.

CLK_GLOBAL_MEM_FENCE Guarantees that all global memory operations will finish.

Example 33: (mul-local-kernel.cl)

```
18  int sum = 0;
19  for (int block = 0; block < Blk; block++) {
20      ALocal[localRow][localCol] =
21          A[globalRow][block * BSIDE + localCol];
22      BLocal[localRow][localCol] =
23          B[block * BSIDE + localRow][globalCol];
24      barrier(CLK_LOCAL_MEM_FENCE);
25      /* inner */
26      for (int k = 0; k < BSIDE; k++)
27          sum += ALocal[localRow][k] * BLocal[k][localCol];
28      barrier(CLK_LOCAL_MEM_FENCE);
29  }
30  C[globalRow][globalCol] = sum;
31 }
```

C

- The answer in `C` is accumulated throughout the iterations in variable `sum`.
- We place another barrier after the inner product.
- We only update local memory so we use `CLK_LOCAL_MEM_FENCE`.

C

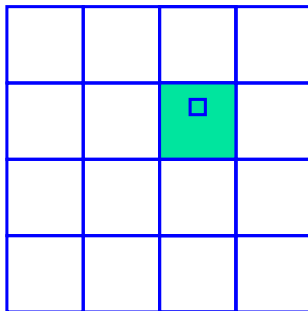


local A



local B

C



Demonstration

- Run the `matrixMul-time-copy-local-cl` program.

Discussion

- Do we need both synchronizations?
- Observe the timing.