

=

TRENDING → How Rotary Encoder Works and How To Use It with Arduino (http://howtomechatronics.co...



(https://www.youtube.com/user/DejanNedelkovski)

8+ (https://plus.google.com/+Howtomechatronics)

f (https://www.facebook.com/howtomechatronics/)

Follow me on: ()

Home (http://howtomechatronics.com) >

Tutorials (http://howtomechatronics.com/category/tutorials/) > Arduino

(http://howtomechatronics.com/category/tutorials/arduino/)

#### How To Build Custom Android App for your Arduino Project using MIT App Inventor

- 📤 Dejan Nedelkovski (http://howtomechatronics.com/author/howtom12\_wp/) 🧿 March 30, 2016
- □ Arduino (http://howtomechatronics.com/category/tutorials/arduino/)
- ∑ 18 (http://howtomechatronics.com/tutorials/arduino/how-to-build-custom-android-app-for-your-arduino-project-using-mit-app-inventor/#comments)

In this Arduino Tutorial we will learn how to build custom Android applications for controlling Arduino using the MIT App Inventor online application. You can watch the following video or read the written tutorial below.

How To Build Custom Android App for your Arduino Project using MIT App ...



#### **Overview**

For this tutorial we have two example. The first example is controlling a simple LED and the second one is controlling a Stepper Motor using the smartphone. In my <u>previous tutorial</u>

(http://howtomechatronics.com/tutorials/arduino/arduino-and-hc-05-bluetooth-module-tutorial/) we already learned how to make the Bluetooth communication between the Arduino Board and the Smartphone using the HC-05 Bluetooth (http://howtomechatronics.com/recommends/hc-05-bluetooth-module-bg/) module and explained the Arduino code needed for the first example.

#### **Arduino Code**

Here's a quick overview of that code. So, via the serial port we receive the incoming data from the smartphone and store it in the 'state' variable. If we receive the character '0' which is sent from the smartphone when the 'LED: OFF' button is pressed, we will turn the LED off and send back to the smartphone the String "LED: OFF". On the other hand, if we receive the character '1' we will turn the LED on and send back the String "LED: ON".

```
1.
        /* Arduino and HC-05 Bluetooth Module Tutorial
   2.
   3.
         * by Dejan Nedelkovski, www.HowToMechatronics.com
   4.
         */
   5.
   6.
        #define ledPin 7
   7.
        int state = 0;
   8.
   9.
        void setup() {
  10.
  11.
         pinMode(ledPin, OUTPUT);
  12.
         digitalWrite(ledPin, LOW);
         Serial.begin(38400); // Default communication rate of the Bluetooth module
  13.
  14.
  15.
        void loop() {
  16.
  17.
         if(Serial.available() > 0){ // Checks whether data is comming from the serial port
  18.
         state = Serial.read(); // Reads the data from the serial port
  19.
  20.
         if (state == '0') {
  21.
  22.
         digitalWrite(ledPin, LOW); // Turn LED OFF
         Serial.println("LED: OFF"); // Send back, to the phone, the String "LED: ON"
732.
         state = 0;
Shares
  25.
         else if (state == '1') {
  26.
```

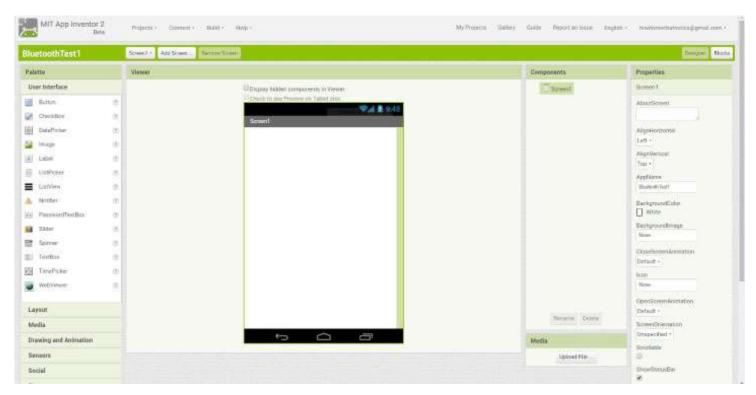
```
172/. digitalWrite(ledPin, HIGH);
18. Serial.println("LED: ON");;
19. state = 0;
107. 30. }
31. }
```

149

So now we need to build our custom Android application which will send those characters '0' and '1' when a Licular button is pressed, as well as, receive the incoming Strings from the Arduino.

#### MIT App Inventor

From the MIT App Inventor <u>website (http://appinventor.mit.edu/explore/)</u> we need to log in into the online building application by clicking the "Create apps!" button. In order to log in we need to have a Gmail account. Once we are logged in now we can create our first project. Here's how the design window looks and now we can start building our application.



But before do that, we can connect our smartphone to this project so that we can see how the app is taking shape directly on our smartphone in real time. In order to do that first we have to download the MIT AI2 Companion app from the Play Store and install it on our smartphone. Then from the Connect menu from the online editor we will select AI Companion and a barcode will appear which we just need to scan it or insert the code into the smartphone app and the connection between the online editor and the smartphone app will be established.



So now for example, if we insert a button in the screen of the online editor, the button will appear in real time on the smartphone as well. Similar to this, if you don't want to use your smartphone while building the app, you can install the Android Emulator on your computer and use in the same way. You can find more details how to set up the Emulator on their website.

#### **Building the App - Example 1**

Now we are ready to build the first example. We will start with the layout of the program. First we will add some HorizontalArrangements from the layout Palette and set their properties like the height, the width and the alignment to match our program desired look. Then from the UserInterface Palette we will add a ListPicker and attach an image to it. The ListPicker will be used for selecting the Bluetooth device to which our smartphone will connect.



(http://howtomechatronics.com/wp-content/uploads/2016/03/Building-the-Android-App-Example-01-.jpg?643d24)

Next we will add another HorizontalArrangements in which we will place a Label. This label will indicate whether the smartphone is connected or not to the Bluetooth module and that's why we will set the initial text of this label to "Not Connected". The next label will be used for displaying the status of the LED, whether is turned off or on. The initial state will be "LED: OFF". Next we will add the two buttons, 'Turn On' and 'Turn Off' for controlling the LED. At this point it is good to rename the components so that we can easier recognize and use them in the Blocks editor later. What's left now is to add the BluetoothClient which is a Non-visible component as well as a clock which will be used for the real time indication of the connection status.

#### **Blocks Editor**

Now in the Blocks editor we are ready to give life to our program. From the left side we got all the blocks and function related to the previously added components.

(http://howtomechatronics.com/wp-content/uploads/2016/03/123.jpg?643d24)

```
Built-in
     Control
                                    BluetoothList -
     Logic
                                  set BluetoothList . Elements to | BluetoothClient1 . AddressesAndNames .
     Math
     Text
                                    BluetoothList -
     Lists
                                                                                                                                    BluetoothClient1 - IsConnected -
                                           call BluetoothClient1 ... Connect
                                                                                                                                   set Connected . Text to Connected
     Colors
                                                                   address BluetoothList - Selection -
     Wariables
                                                                                                                                   set Connected Text to
                                        set BluetoothList . Elements to BluetoothClient1 . AddressesAndNames
     Procedures
                                                                                                                                          BluetoothClient1 - S IsConnected -
B Screen1
                                                                                                                                   set Connected . Text . to Not Connected
     HorizontalArrange
                                                                                                                                   set Connected . Text to
  ⊟ MorizontalArrange
                                    TurnOn_Button . Click
       BluetoothList
                                  call BluetoothClient1 .Send1ByteNumber
  ⊟ MorizontaiArrangen
                                                                  number (49)
       A Connected
                                   set (LED_Status . Text . to
                                                                  call BluetoothClient1 ReceiveText
     Horizontal Arrangement
                                                                                                     call BluetoothClient1 . BytesAvailableToRe
  ⊟ MorizontalArrangement
       A LED Status
                                    TurnOFF Button
  ☐ MorizontalArrangement *
                                   call BluetoothClient1 Send1ByteNumber
     Rename Delete
                                                                  number (48)
                                   set LED Status . Text . to
                                                                  call BluetoothClient1 .ReceiveText
Media
                                                                                    numberOfBytes | call | BluetoothClient1 | BytesAvailableToReceive
   button_connect.png
       Upload File ...
```

(http://howtomechatronics.com/wp-content/uploads/2016/03/Android-App-Blocks-Example-01.jpg?643d24)

We will start with the BluetoothList ListPicker. From there first we will add the 'BeforePicking' block and attach to it the 'set Bluetooth Elements' block. Then from the BluetoothClient blocks we will add the 'BluetoothClient AddressesAndNames' block. What this set of blocks will do is set a list of Bluetooth devices which are already paired with our phone so when we will click on the ListPicker "Connect Button" the list of all paired devices will show up.

```
when BluetoothList . BeforePicking

do set BluetoothList . Elements to BluetoothClient1 . AddressesAndNames .
```

Next we have to set what will happen after we will pick or select our particular Bluetooth module. From the BluetoothClient block we will add the 'call BluetoothClient .Connect address' block and add the block 'BluetoothList Selection' to it, which means that our phone will connect to the Bluetooth address that we have previously selected.

Next from the Clock blocks we will add the ".Timer" block. Within this block we will make the real time indication whether the phone is connected or not to the Bluetooth module using the "set Text" block of the label named "Connected".

Next we need to give life to the two buttons. So when the "TurnOn\_Button" will be clicked we will use the Bluetooth client function "Send1ByteNumber" to send a number to the Arduino Bluetooth module. In our case that's the number 49 which corresponds to the character '1' according to the ASCII table and that will turn on the LED. Right after that we will use the "ReceiveText" BluetoothClient function to receive the incoming String which is send back from the Arduino to the phone. This String is set to the "LED\_Status" Label.

```
when TurnOn_Button v.Click

do call BluetoothClient1 v.Send1ByteNumber number (49)

set LED_Status v. Text v to (call BluetoothClient1 v.ReceiveText numberOfBytes (call BluetoothClient1 v.BytesAvailableToReceive do call BluetoothClient1 v.Send1ByteNumber number (48)

set LED_Status v. Text v to (call BluetoothClient1 v.ReceiveText numberOfBytes (call BluetoothClient1 v.BytesAvailableToReceive numberOfBytes (call BluetoothClient1 v.BytesAvailableToReceive)
```

The same procedure goes for the "TurnOff\_Button" where the sending number should be changed to 48 which corresponds to character '0'. What's left now is to download and install the program on our smartphone. We can do that from the "Build" menu by either saving it to our computer and then transfer to our phone or scan a QR code for online download of the program. Here's the demonstration of the example.

Here's a download file of the above MIT App Inventor project:



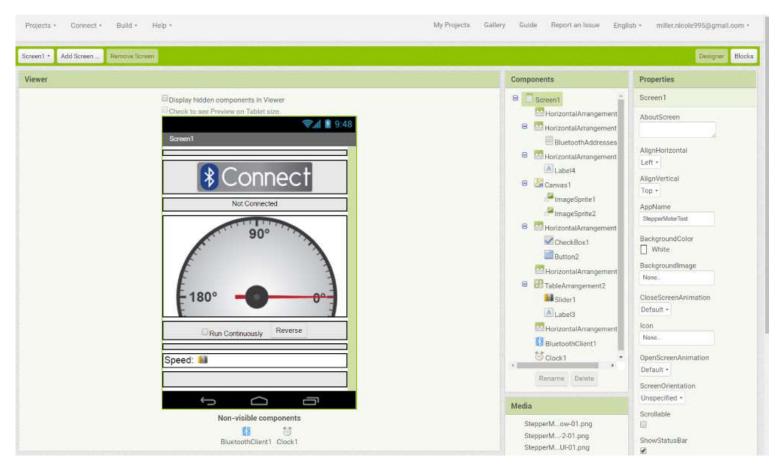
BluetoothTest.aia 5.16 KB Download

#### **Stepper Motor Control Example**

Now let's take a look at the second example, controlling a stepper motor. At the top of the screen we have the same components for the Bluetooth connection as the previous example. Next we have a Canvas component which is used for drawing and inserting images. I inserted two transparent images which I previously drew. The first one is an image of a gauge which will be fixed in place and the second one is an image of a pointer which will

mucrone is an image of a gauge which will be tixed in place and the second one is an image of a pointer which will

be rotating. Next we have a Check button for switching between Manual and Auto or continuously running mode and a button for changing the rotation direction. At the button we have a slider for changing the rotation speed of the stepper motor.



#### (http://howtomechatronics.com/wp-content/uploads/2016/03/Android-App-Blocks-Example-02.jpg?643d24)

Here are the blocks and the Arduino code behind this example. So, in the Blocks editor again we have the same blocks for the Bluetooth connection as the previous example.

```
when BluetoothAddressesList BeforePicking
    set BluetoothAddressesList •
                                  Elements
                                               to I
                                                    BluetoothClient1 -
                                                                        AddressesAndNames -
when BluetoothAddressesList AfterPicking
               call BluetoothClient1 •
                                       Connect
do
     (O) II
                                       address |
                                                 BluetoothAddressesList -
                                                                           Selection -
               Label4 •
                           Text •
                                         Connected
                                       to
           set Label4
                          TextColor •
```

Now for rotating the pointer image we use the ImageSprite function ".PointInDirection" which rotates the image from 0° position to the X and Y coordinates where the Canvas has been touched. At the same time we set the rotated ImageSprite heading to the text label above. After that we call custom made procedure, or function which is actually a 10m seconds delay. Lastly we send the heading value as a Text to the Arduino using the "SendText"

Bluetooth function. This value will be accepted by the Arduino and it will rotate the stepper motor accordingly.

```
when Canvast Touched
    y touchedAnySprite
                                                                      initialize global delay to 0
   call [mageSprite2 - PointinDirection
                                                                      o to procedure
                                        get X
                                                                           set global delay to call (clock). SystemTime
                                         det (VIII)
                                                                           sat global delay . to |
                                                                                                 0
                                                                                                      gal global delay -
    set Label4 • Text • to round •
                                         ImageSprite2
                                                         Heading -
    call procedure ·
                                                                                                       SystemTime State
                                                                                                                           nati global delay
    call Bluetoothelienth SendText
                                     Label4 -
```

Next is the the CheckBox block. So if the CheckBox is checked we will send the text "Auto" to the Arduino which will activate stepper motor to rotate continuously. While we are in this mode if we press the "Reverse" button, we will send the text "Reverse" to the Arduino which will change the rotation direction of the motor. Also, while we are in this mode, we can change the speed of rotation. If we change the position of the slider, the current value of the slider position will be send to the Arduino which will change the rotation speed of the stepper. If we uncheck the CheckBox we will get back into the manual mode. Here's the demonstration of the example.

```
when Button2 Click
when CheckBox1 Changed
                                                                cal procedure -
           CheckBox1 -
                            Checked -
do
                                                                 cail BluetoothClient1 SendText
           call BluetoothClient1 . SendText
                                                                                                    Reverse
                                                                                            text
                                     text
                                             Auto
                                                           when Slider PositionChanged
              not CheckBox1
                                  Checked -
    6 II
                                                             thumbPosition
          call BluetoothClient1 - SendText
                                                                cal procedure -
                                             Manual
                                     text
                                                                call BluetoothClient1 . SendText
                                                                                                 get thumbPosition
                                                                                           text
```

Here's a download file of the above MIT App Inventor project, as well as the two images used in the project:



StepperMotorTest.aia 60.96 KB Download



Stepper Motor Gauge and Pointer Images 27.34 KB

Download

Here's the Arduino code of the second example:

```
9.
      const int dirPin = 6;
10.
      String state = "";
      int currentHeading=0;
11.
12.
      int currentAngle=0;
      int lastAngle=0;
13.
14.
      int angle=0;
15.
      int rotate=0;
16.
      int runContinuously=0;
      String mode = "Manual";
17.
18.
      boolean dirRotation = HIGH;
      int rotSpeed = 1500;
19.
20.
21.
      void setup() {
       // Sets the two pins as Outputs
22.
23.
        pinMode(stepPin,OUTPUT);
24.
        pinMode(dirPin,OUTPUT);
25.
        Serial.begin(38400); // Default communication rate of the Bluetooth module
26.
27.
      void loop() {
28.
        delayMicroseconds(1);
29.
        if(Serial.available() > 0){ // Checks whether data is comming from the serial port
          state = Serial.readString(); // Reads the data from the serial port
30.
31.
       // When Auto Button is pressed
32.
33.
       if (mode == "Auto") {
        if (state == "Reverse") {
34.
35.
          delay(10);
          if (dirRotation == HIGH) {
36.
            dirRotation = LOW;
37.
38.
          }
39.
          else {
40.
            dirRotation = HIGH;
41.
          digitalWrite(dirPin,dirRotation);
42.
          delay(10);
43.
          state = "";
44.
45.
        rotSpeed = state.toInt();
46.
        if (rotSpeed >= 300 && rotSpeed <= 3000) {</pre>
47.
48.
        digitalWrite(stepPin, HIGH);
49.
        delayMicroseconds (rotSpeed);
        digitalWrite(stepPin,LOW);
50.
        delayMicroseconds(rotSpeed);
51.
52.
        }
53.
        else {
        digitalWrite(stepPin,HIGH);
54.
55.
        delayMicroseconds (1500);
56.
        digitalWrite(stepPin,LOW);
        delayMicroseconds(1500);
57.
58.
        }
59.
60.
        if (state == "Manual") {
61.
          mode = state;
        }
62.
63.
       }
```

```
64.
        // When Program is in Manual mode
 65.
        else if (mode == "Manual") {
        currentHeading = state.toInt();
 66.
        //Serial.println(angle);
 67.
        //Serial.println(state);
 68.
        if (currentHeading < 0 ) {</pre>
69.
         currentHeading = 360+currentHeading;
70.
71.
        currentAngle = map(currentHeading,0,359,0,200);
72.
73.
        digitalWrite(dirPin, HIGH); // Enables the motor to move in a particular direction
         // Makes 200 pulses for making one full cycle rotation
74.
75.
         if (currentAngle != lastAngle) {
           if(currentAngle > lastAngle) {
76.
              rotate = currentAngle - lastAngle;
77.
             for(int x = 0; x < rotate; x++) {
78.
             digitalWrite(stepPin, HIGH);
79.
             delayMicroseconds (500);
80.
             digitalWrite(stepPin,LOW);
81.
82.
             delayMicroseconds (500);
83.
           }
84.
85.
           if(currentAngle < lastAngle) {</pre>
86.
             rotate = lastAngle - currentAngle;
87.
88.
             digitalWrite(dirPin,LOW); //Changes the rotations direction
             for (int x = 0; x < rotate; x++) {
89.
             digitalWrite(stepPin, HIGH);
90.
             delayMicroseconds (500);
91.
92.
             digitalWrite(stepPin,LOW);
             delayMicroseconds (500);
93.
94.
95.
96.
         lastAngle = currentAngle;
97.
         if (state == "Auto") {
98.
           mode = state;
99.
100.
101.
        }
102.
       }
```

We highly recommend **EasyEDA** for circuit design and **low cost PCB order**(https://easyeda.com/order)

Free Circuit Simulation Software - EasyEDA (https://easyeda.com/)

Powerful circuit design, mixed-mode circuit simulation and PCB design (https://easyeda.com/)

Android (http://howtomechatronics.com/tag/android/)

Arduino (http://howtomechatronics.com/tag/arduino/)

Bluetooth (http://howtomechatronics.com/tag/bluetooth/)

HC-05 Bluetooth (http://howtomechatronics.com/tag/hc-05-bluetooth/)

MIT App Inventor (http://howtomechatronics.com/tag/mit-app-inventor/)

Tutorial (http://howtomechatronics.com/tag/tutorial/)

#### **SHARE ON:**

Share 298

ike {298

**931** 149

Tweet

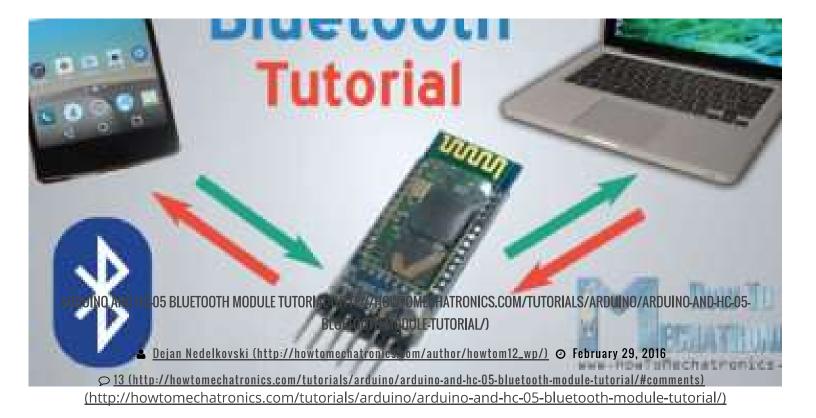
Stur

#### **RELATED POSTS**

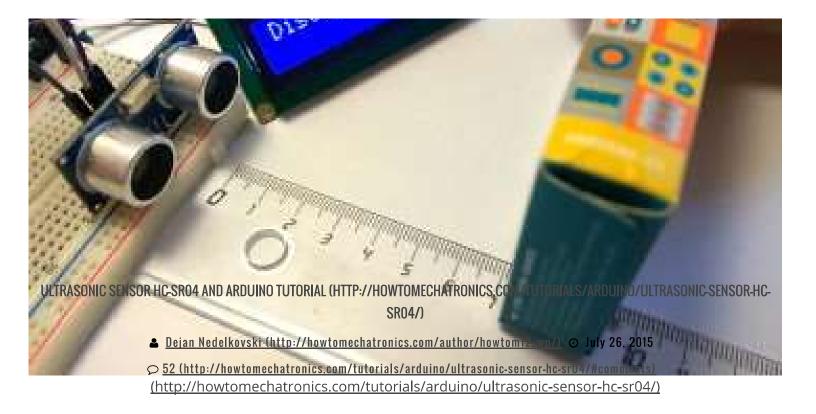


(http://howtomechatronics.com/tutorials/arduino/how-to-control-stepper-motor-with-a4988-driver-and-arduino/)





The state of the s







(http://howtomechatronics.com/tutorials/arduino/control-high-voltage-devices-arduino-relay-tutorial/)

#### 18 RESPONSES

# Joabe Alexandre

April 7, 2016 (http://howtomechatronics.com/tutorials/arduino/how-to-build-custom-android-app-for-your-arduino-project-using-mit-app-inventor/#comment-776)

Hello, very good your video classes. I was trying to make a mixture of those programs that you did. I would like to make a radar as you used in the processor or something like that, with app inventor, it is possible? I did not find any information on how to do this in Al2. It would be necessary another application to create the radar? Which application?

The Al2 would get the values starting from arduino , reading data ( angle and distance) would be sent via Bluetooth .

It is possible to do it? I do not have much knowledge on AI2, but I can learn more.

Thank you!

REPLY

April 7, 2016 (http://howtomechatronics.com/tutorials/arduino/how-to-build-custom-android-app-for-your-arduino-project-using-mit-app-inventor/#comment-777)

Hi there and thanks! Well I think it's possible to be done but of course it would require quit a work. You should first see and learn the Al2 capabilities and maybe it can be done.

REPLY

#### Gabriel

April 7, 2016 (http://howtomechatronics.com/tutorials/arduino/how-to-build-custom-android-app-for-your-arduino-project-using-mit-app-inventor/#comment-780)

hello, thank you is really good! how can I create an app and a sketch but using the Ethernet Shield? could you help me? I would like to create an application for Android and manage Arduino pin remotely. Thanks so much!

**REPLY** 

# Dejan Nedelkovski (http://howtomechatronics.com)

April 8, 2016 (http://howtomechatronics.com/tutorials/arduino/how-to-build-custom-android-app-for-your-arduino-project-using-mit-app-inventor/#comment-783)

Hi there and thank. Sorry but currently I don't have any tutorial for Ethernet Shield.

REPLY

#### subutay

April 14, 2016 (http://howtomechatronics.com/tutorials/arduino/how-to-build-custom-android-app-for-your-arduino-project-using-mit-app-inventor/#comment-805) hello there.

great tutorial. using app inventor 2, i did the same app but there is problem. after i run the app on my phone in the beginning it displays not connected message but after that it displays a number (-65536). so i dont know whether the device is connected or not?

REPLY

# <u>Dejan Nedelkovski (http://howtomechatronics.com)</u>

April 14, 2016 (http://howtomechatronics.com/tutorials/arduino/how-to-build-custom-android-app-for-your-arduino-project-using-mit-app-inventor/#comment-808)

Hi there and thanks. Well download my app and thy with it. Do you get the same error again?

REPLY

#### **Aasif Shah**

April 15, 2016 (http://howtomechatronics.com/tutorials/arduino/how-to-build-custom-android-app-for-your-arduino-project-using-mit-app-inventor/#comment-810)

Hello. Thanks for this awesome tutorial. I need to do something similar in my project. I want to display the signal (as a graph) on the app. The signal being fed to Arduino analog input. Is there any way to do it? I am not so good at programming, so appinventor seemed easy way to make an app.

Thanks!

REPLY

# Dejan Nedelkovski (http://howtomechatronics.com)

April 18, 2016 (http://howtomechatronics.com/tutorials/arduino/how-to-build-custom-android-app-for-your-arduino-project-using-mit-app-inventor/#comment-829)

Hi here and thanks. Well it could be possible but you will have to experiment about that as I haven't tried it.

REPLY

#### Rishi

May 23, 2016 (http://howtomechatronics.com/tutorials/arduino/how-to-build-custom-android-app-for-your-arduino-project-using-mit-app-inventor/#comment-946)

If I use a different version of the HC-05 Bluetooth module, will this still work or do I have to use the exact bluetooth module used in this tutorial?

REPLY

# Dejan Nedelkovski (http://howtomechatronics.com)

May 24, 2016 (http://howtomechatronics.com/tutorials/arduino/how-to-build-custom-android-app-for-your-arduino-project-using-mit-app-inventor/#comment-949)

If it's different version it might require some modification in the Arduino code.

REPLY

# TUSAR RANJAN PRADHAN

May 26, 2016 (http://howtomechatronics.com/tutorials/arduino/how-to-build-custom-android-app-for-your-arduino-project-using-mit-app-inventor/#comment-970)

Hello Sir, this project is really good. I install .apk file from this website for led toturial .It open and connect with my bluetooth. when I Turn On led my led is not blinking .and mobile going hang. I also repet this process in my other android device ..there also connection between mobile and bluetooth is success .but led is not blink (mobile work properly)......Please help me to solve this problame.....

REPLY

# Dejan Nedelkovski (http://howtomechatronics.com)

May 27, 2016 (http://howtomechatronics.com/tutorials/arduino/how-to-build-custom-android-app-for-your-arduino-project-using-mit-app-inventor/#comment-975)

Did you upload the same arduino code and connected everything on the same pins as described?

**REPLY** 

May 27, 2016 (http://howtomechatronics.com/tutorials/arduino/how-to-build-custom-android-app-for-your-arduino-project-using-mit-app-inventor/#comment-978)

yes sir i upload same arduino code, &, connected everything on the sae pin

#### subhasis

May 27, 2016 (http://howtomechatronics.com/tutorials/arduino/how-to-build-custom-android-app-for-your-arduino-project-using-mit-app-inventor/#comment-979)

Hello sir, can you provide a tutorial -to create a softwear in visual studio that connect & control ardunio and display senser data like temp,humidity,servo motor speed,led on off......

REPLY

# Dejan Nedelkovski (http://howtomechatronics.com)

May 28, 2016 (http://howtomechatronics.com/tutorials/arduino/how-to-build-custom-android-app-for-your-arduino-project-using-mit-app-inventor/#comment-982)

Sorry but I don't have such a tutorial at this time and I also don't have it on my tutorials to do list for this year.

REPLY

#### swati sharma

July 17, 2016 (http://howtomechatronics.com/tutorials/arduino/how-to-build-custom-android-app-for-your-arduino-project-using-mit-app-inventor/#comment-1066)

hello sir its a great project and i am going to do it for my college project...... but i want to have a video on how to connect the arduino with blutooth and stepper motor in this project...... if you can upload a video on how to connect the hardware it would be great..... thank you!

REPLY

#### swati sharma

July 25, 2016 (http://howtomechatronics.com/tutorials/arduino/how-to-build-custom-android-app-for-your-arduino-project-using-mit-app-inventor/#comment-1095)

can we use arduino uno for the same project?

**REPLY** 

#### Bakke Medina

July 25, 2016 (http://howtomechatronics.com/tutorials/arduino/how-to-build-custom-android-app-for-your-arduino-project-using-mit-app-inventor/#comment-1100)

Hello, I have a problem in compare data

receives from arduino to the cellphone but when I need to compare the data had problems. Example Arduino send: "a", Android recive and compare: "a"="1" I have no response in the label

REPLY

# LEAVE A REPLY

Your email address will not be published.

Comment

e*	Email*	
site		
site		

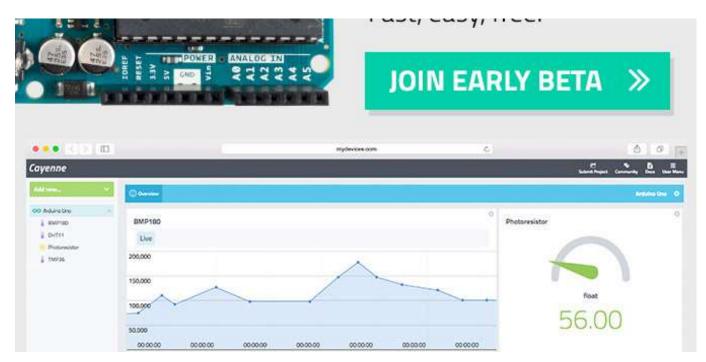
# ARDUINO ARDUINO ARDUINO

**SUBMIT** 

# Beta Test **Cayenne** with Arduino

Test our drag-and-drop project builder.

Fast easy free



(http://www.cayenne-mydevices.com/arduino-beta-signup/?

utm source=howtomechatronics&utm medium=banner ad&utm campaign=howtomechatronics ArduinoBeta)

#### **LATEST**



#### **FOLLOW ME!**

(https://www.fartebso.o/parcong.chatebsc.com

A . P ....

# **Get Email Updates!**

Signup now and receive an email once I publish new content.

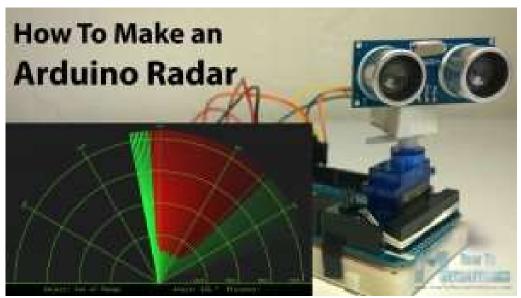
Enter Your Name

Enter Your Email Address

Sign Up

I will never give away, trade or sell your email address. You can unsubscribe at any time.

#### **POPULAR**



Arduino Radar Project (http://howtomechatronics.com/projects/ radar-project/)

▲ <u>Dejan Nedelkovski</u> (http://howtomechatronics.com/autho

② July 28, 2015

(http://howtomechatronics.com/proje radar-project/#comments)

(http://howtomechatronics.com/projects/arduino-radar-project/)

Ultrasonic Sensor HC-SRO4 and Arduino Tutorial (http://howtomechatronics.com/tutorials/arduino/ultrasonic-sensor-hc-srO4/)

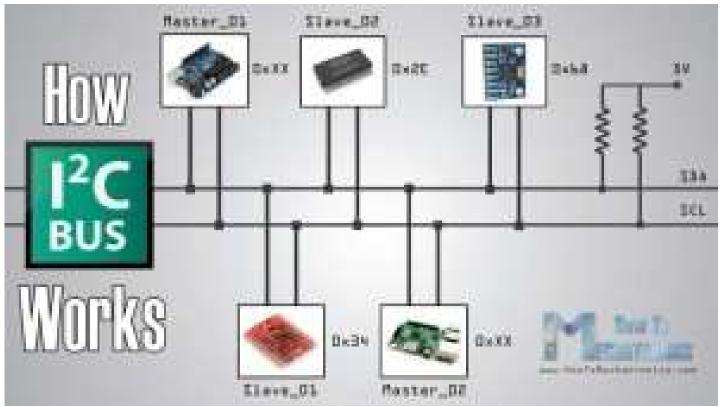
▲ Dejan Nedelkovski (http://howtomechatronics.com/author/howtom12\_wp/) ② July 26, 2015

© 52 (http://howtomechatronics.com/tutorials/arduino/ultrasonic-sensor-hc-sr04/#comments)





(http://howtomechatronics.com/tutorials/arduino/ultrasonic-sensor-hc-sr04/)



(http://howtomechatronics.com/tutorials/arduino/how-i2c-communication-works-and-how-to-use-it-with-arduino/)



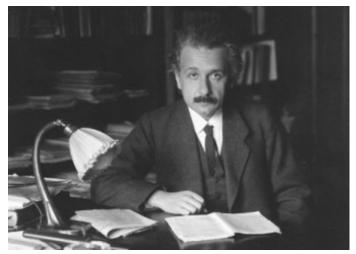


HowToMechatronics is an education website in the area of Mechanical, Electrical and Computer Engineering. Tutorials, Tips, Tricks, How It Works, Projects, Examples, Source Codes, Download files and much more can be found here.

#### FOLLOW HOWTOMECHATRONICS ON SOCIAL MEDIA

(https://www.fantepbso.6/policong/thatgales/ar/oward/halforountiods)ecb.ant/anexyDejanNedelkovsk

# DAILY INSPIRATION



(http://www.inspireartachienecom/inspirational/quotes/30-brilliant-quotes-from-albert-einstein-that-will-blowvBlown/ဂုဏ်/ Mind

Copyright © 2016 HowToMechatronics.com. All rights reserved. Terms and Conditions (http://howtomechatronics.com/disclaimer/)