

Estimation of ATE in Causal Survival: Comparison, Applications and Practical Recommendations

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Causal Survival analysis: example of questions

Survival analysis



Causal inference

⇒ **Effect of a policy/intervention/treatment A on an time to event outcome T**



What is the impact of an oncology medicine on long term mortality ?



What is the impact of a medicine all along the time (it can be beneficial in the short term but harmful in the long term) ?



Treatment : A

Treatment effect



Time to event : T

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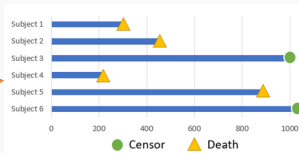


Treatment : A

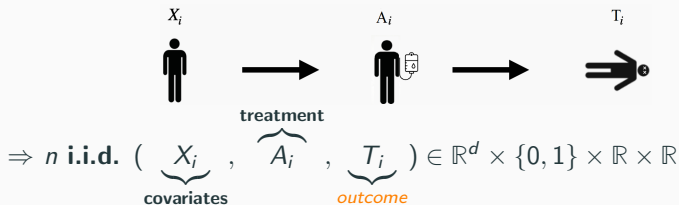
Treatment effect



Time to event : T



Potential outcomes



Let's say that in our example $X_1 = \text{sex}$ and $X_2 = \text{age}$.

Covariates		Treatment	Censoring	Status	Outcomes		
X_1	X_2	A	C	Δ	T(0)	T(1)	\tilde{T}
1	24	1	?	1	?	200	200
2	52	0	?	1	100	?	100
1	33	1	200	0	?	?	200

In grey, the observed data : $(X_i, A_i, \Delta_i, \tilde{T}_i)$ with $\tilde{T}_i = \min(T_i, C_i)$

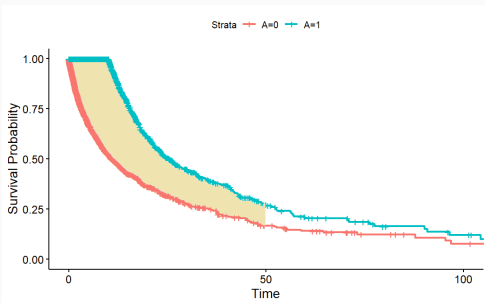
$\Rightarrow T$ is not directly observed

Causal effect in survival analysis

Difference in RMST : Average treatment effect in survival analysis

$$\begin{aligned}\hat{\theta}_{RMST}(\tau) &= E[\min(T(1), \tau) - \min(T(0), \tau)] \\ &= \int_0^{\tau} (\hat{S}_1(t) - \hat{S}_0(t)) dt\end{aligned}$$

RMST can be defined as a measure of average survival from time 0 to time τ a **fixed time horizon**



$\hat{\theta}_{RMST}(\tau = 50) = 10$ means that on average the treatment increases the survival time by 10 days at 50 days.

Figure 1: Plot of stratified kaplan meier survival function and the representation of $\theta_{RMST}(\tau = 50)$ (in yellow)

Identifiability assumptions

$$\text{S.T.U.V.A. } T = AT(1) + (1 - A)T(0)$$

RCT & Independent censoring

- **Random treatment assignment**
 $A \perp\!\!\!\perp (T(0), T(1), C, X)$
- **Independent censoring**
 $C \perp\!\!\!\perp T(0), T(1), X, A$

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 $A \perp\!\!\!\perp (T(0), T(1), C, X)$
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 $C \perp\!\!\!\perp T(0), T(1) | X, A$
- **Positivity for censoring**
 $0 < P(C > t \mid X = x, A = a) < 1$

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Obs & Independent censoring

- **Unconfoundedness** $A \perp\!\!\!\perp (T(0), T(1)) | X$
- **Positivity for treatment**
 $1 > P(A = a | X = x) > 0$
- **Independent censoring**
 $C \perp\!\!\!\perp T(0), T(1), X, A$

RCT & Dependent censoring

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Obs & Independent censoring

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- **Positivity for treatment**
 $1 > P(A = a | X = x) > 0$
- **Independent censoring**
 $C \perp\!\!\!\perp T(0), T(1), X, A$

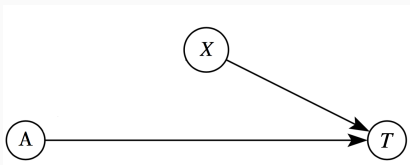
RCT & Dependent censoring

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 $A \perp\!\!\!\perp (T(0), T(1), C, X)$
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RCT & Independent censoring



Non-adjusted Kaplan-Meier estimator [Kaplan and Meier 1958]

It corresponds to a simple Kaplan meier estimator:

$$\hat{S}_{KM}(t | a) = \prod_{j=1, t_j \leq t} \left(1 - \frac{\sum_i I \left\{ \tilde{T}_i = t_j, \Delta_i = 1, A_i = a \right\}}{\sum_k I \left\{ \tilde{T}_k \geq t_j, A_i = a \right\}} \right)$$

$$\hat{\theta}_{RMST}(\tau) = \int_0^{\tau} \left(\hat{S}_1(t) - \hat{S}_0(t) \right) dt$$

RCT & Dependent censoring

Non-adjusted Kaplan-Meier is biased in this context:

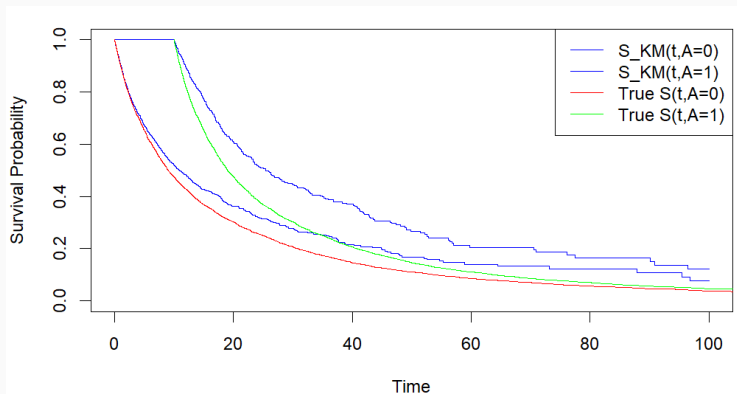


Figure 2: Plot of stratified kaplan meier survival function ($A=1$ and $A=0$) and the true survival function

⇒ The probability of survival is no longer consistent in using Non adjusted KM [Willems et al. 2018].

RCT & Dependent censoring

Notion of censoring unbiased transformation [Fan and Gijbels 1994]:

$$T^* = \Delta \phi_1(\mathbf{X}, A, \tilde{T}) + (1 - \Delta) \phi_2(\mathbf{X}, A, \tilde{T})$$

The basic requirement is that $E(T^*|X, A) = E(T \wedge \tau|X, A)$.

- **IPC transformation** [Koul, Susarla, and Ryzin 1981]

$$T^*(\tau) = \frac{\tilde{T} \wedge \tau * \Delta^\tau}{S_c(\tilde{T} \wedge \tau|X, A)}$$

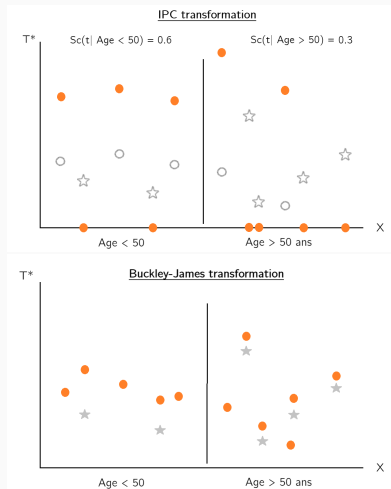
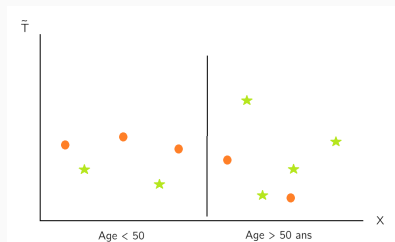
with $\hat{S}_c(t|X_i, A_i)$ is the probability of remain uncensored given the covariates and $\Delta^\tau = \mathbb{1}(\{\tilde{T} > \tau\}) + \mathbb{1}(\{\tilde{T} \leq \tau\}) \cdot \Delta$ is the censoring indicator of the restricted time (or restricted status).

- **Buckley-James transformation** [Buckley and James 1979]

$$T^*(\tau) = \Delta^\tau * (\tilde{T} \wedge \tau) + (1 - \Delta^\tau) * \mathbb{E}[T \wedge \tau|X, A, T \wedge \tau > \tilde{T} \wedge \tau]$$

RCT & Dependent censoring

Notion of censoring unbiased transformation [Fan and Gijbels 1994]:



RCT & Dependent censoring

IPCW adjusted Kaplan-Meier estimator [Robins and Finkelstein 2000]

$$\hat{S}_{IPCW}(t \mid A = a) = \prod_{j=1, t_j \leq t} \left(1 - \frac{\sum_i \hat{w}_i(t_j, X_i) \cdot I\{\tilde{T}_i = t_j, C_i \geq t_j, A_i = a\}}{\sum_k \hat{w}_k(t_j, X_k) \cdot I\{\tilde{T}_k \geq t_j, C_k \geq t_j, A_k = a\}} \right)$$

with $\hat{w}_i(t, X_i) = \frac{\Delta_i^\tau}{\hat{S}_c(t|X_i, A_i)}$: every uncensored observation is weighted by the inverse of the probability of remain uncensored given the covariates.

$$\hat{\theta}_{RMST} = \int_0^\tau \hat{S}_{IPCW}(t, A = 1) - \hat{S}_{IPCW}(t, A = 0) dt$$

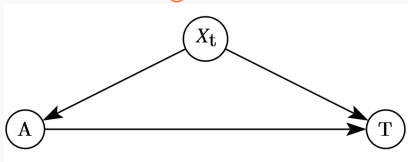
RCT & Dependent censoring

BJ based estimator

$$\hat{\theta}_{RMST} = \frac{1}{n_1} * \sum_{i=1}^{n_1} \left[\Delta_i^\tau * (\tilde{T}_i \wedge \tau) + (1 - \Delta_i^\tau) * \hat{Q}_S(C_i | X, A) \mid A = 1 \right] - \\ \frac{1}{n_0} * \sum_{j=1}^{n_0} \left[\Delta_j^\tau * (\tilde{T}_j \wedge \tau) + (1 - \Delta_j^\tau) * \hat{Q}_S(C_j | X, A) \mid A = 0 \right]$$

- n_1 corresponds to the number of observations in the treated group
- n_2 corresponds to the number of observations in the control group
- $\hat{Q}_S(\tilde{T} \wedge \tau \mid X, A) = \frac{1}{\hat{S}(\tilde{T} \wedge \tau \mid X, A)} \int_{\tilde{T} \wedge \tau}^{+\infty} \tilde{T} \wedge \tau. d\hat{F}(\tilde{T} \wedge \tau \mid X, A)$ the estimation function of the remaining survival function

Obs & Independent censoring



Risk of confounding bias

⇒ Need for balancing differences between the two groups.

IPTW adjusted Kaplan-Meier estimator [Xie and Liu 2005]

$$\hat{S}_{IPTW}(t \mid A = a) = \prod_{j=1, t_j \leq t} \left(1 - \frac{\sum_i \hat{w}_i(t_j, X_i) \cdot I\left\{\tilde{T}_i = t_j, C_i \geq t_j, A_i = a\right\}}{\sum_k \hat{w}_k(t_j, X_k) \cdot I\left\{\tilde{T}_k \geq t_j, C_k \geq t_j, A_k = a\right\}} \right)$$

$$\text{with } \hat{w}_i(t, X_i) = \frac{A_i}{\hat{e}(X_i)} + \frac{1-A_i}{1-\hat{e}(X_i)}$$

$$\hat{\theta}_{RMST} = \int_0^T \hat{S}_{IPTW}(t, A = 1) - \hat{S}_{IPTW}(t, A = 0) dt$$

Obs & Dependent censoring

Risk of **censoring bias** & **confounding bias**
⇒ Overcome by using **IPC transformation**
and **IPT weighting**

IPTW-IPCW adjusted Kaplan-Meier estimator

$$\hat{S}_{IPTW-IPCW}(t | A = a) = \prod_{j=1, t_j \leq t} \left(1 - \frac{\sum_i \hat{w}_i(t, X_i) * I\{T_i = t_j, C_i \geq t_j, A_i = a\}}{\sum_i \hat{w}_i(t, X_i) * I\{T_i \geq t_j, C_i \geq t_j, A_i = a\}} \right)$$

with $\hat{w}_i(t, X_i) = \frac{\Delta_i^\tau}{\hat{S}_C(\tilde{T} \wedge \tau | A_i, X_i)} * \left(\frac{A_i}{\hat{e}(X_i)} + \frac{1-A_i}{1-\hat{e}(X_i)} \right)$: every uncensored observation is weighted by the inverse of remain uncensored and by the inverse propensity score given the covariates.

$$\hat{\theta}_{RMST} = \int_0^\tau \hat{S}_{IPTW-IPCW}(t, A = 1) - \hat{S}_{IPTW-IPCW}(t, A = 0) dt$$

Obs & Dependent censoring

Risk of censoring bias & confounding bias
⇒ In using Buckley-James transformation
and IPT weighting

IPTW-BJ estimator

$$\hat{\theta}_{\text{IPTW-BJ}}(\tau) = \frac{1}{n} \sum_{i=1}^n \left(\Delta^{\tau} \tilde{T} \wedge \tau + (1 - \Delta^{\tau}) \hat{Q}_S(\tilde{T} \wedge \tau | X, A) \right) \left(\frac{A_i}{\hat{e}(X_i)} - \frac{1 - A_i}{1 - \hat{e}(X_i)} \right)$$

Obs & Dependent censoring

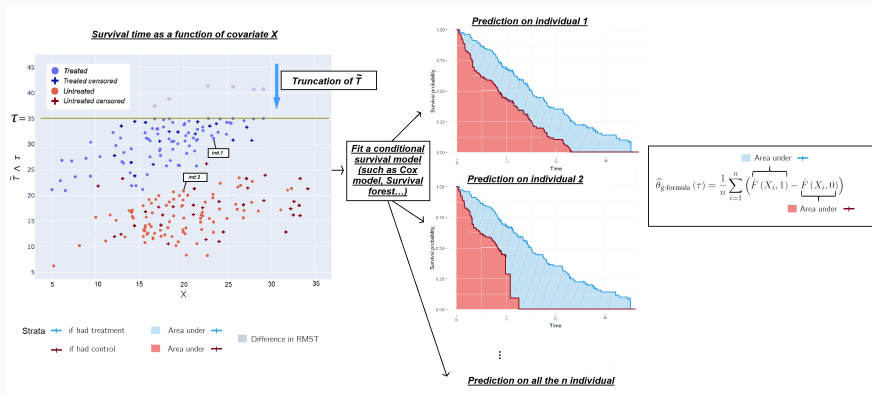
G-formula estimator

$$\hat{\theta}_{\text{g-formula}}(\tau) = \frac{1}{n} \sum_{i=1}^n \left(\hat{F}(X_i, 1) - \hat{F}(X_i, 0) \right)$$

with $\hat{F}(x, a) \triangleq \mathbb{E}[T \wedge \tau \mid X = x, A = a] = \int_0^{\tau} S(t \mid X = x, A = a)$ the integral of the conditional survival function truncated at τ .

- G-formula compute the θ_{RMST} for each individual based on its covariates \rightarrow can be estimated by Cox model, survival forest or parametric model (such as Weibull model, exponential model...).
- Then, it does the mean of the conditional θ_{RMST} on all individuals.

Obs & Dependent censoring



Two possibilities for estimating $\hat{S}(t|x, a)$:

- S-learner: **Fit one model** on all data with covariate adjustment on X and A.
- T-learner: **Fit two models** (stratified analysis) on data with A=1 and with A=0 and adjustment on X.

Obs & Dependent censoring

Augmented version of IPTW-IPCW [Ozenne et al. 2020],
a mix of :

- AIPTW (the equivalent of AIPW in causal inference)
- An other unbiased censoring transformation (AIPCW)

Obs & Dependent censoring

Augmented version of IPTW-IPCW [Ozenne et al. 2020]:

- **AIPTW** (Augmented Inverse Probability of Treatment Weighting [James M. Robins and Zhao 1994; James M. Robins and Zhao 1995; Chernozhukov et al. 2016]):

We consider **complete observation**, as the transformation will estimate it.

$$\begin{aligned}\theta_{AIPTW} &= \mathbb{E}[\mathbb{E}(T \wedge \tau | X, A = 1)] - \mathbb{E}[\mathbb{E}(T \wedge \tau | X, A = 0)] \\ &= \mathbb{E} \left[\frac{A \cdot T \wedge \tau}{\hat{e}(X)} + \hat{F}(X, A = 1) * \frac{\hat{e}(X) - A}{\hat{e}(X)} \right] - \\ &\quad \mathbb{E} \left[\frac{(1 - A) * T \wedge \tau}{1 - \hat{e}(X)} + \hat{F}(X, A = 0) * \frac{(1 - \hat{e}(X)) - A}{1 - \hat{e}(X)} \right]\end{aligned}$$

Obs & Dependent censoring

Augmented version of IPTW-IPCW [Ozenne et al. 2020]:

- **AIPCW** (Augmented Inverse Probability Censoring Weighting [Rubin and Laan 2007]):

$$T^*(O) = \frac{\tilde{T} \wedge \tau \Delta^\tau}{S_c(\tilde{T} \wedge \tau | X, A)} + \frac{Q_S(\tilde{T} \wedge \tau | X, A)(1 - \Delta^\tau)}{S_c(\tilde{T} \wedge \tau | X, A)} - \int_{-\infty}^{\tilde{T} \wedge \tau} \frac{Q_S(\tilde{T} \wedge \tau | X, A)}{S_c^2(\tilde{T} \wedge \tau | X, A)} d(1 - S_c(\tilde{T} \wedge \tau | X, A))$$

- The first term: IPC transformation
- The second term: BJ transformation
- The third one is an augmentation term

Obs & Dependent censoring

Augmented estimator: AIPTW-AIPCW

$$\hat{\theta}_{\text{AIPTW-AIPCW}} = \frac{1}{n} \sum_{i=1}^n \left(\frac{A_i}{\hat{e}(X_i)} - \frac{1 - A_i}{1 - \hat{e}(X_i)} \right) \hat{T}_{\text{DR}}^* + \hat{F}(X_i, A = 1) \left(1 - \frac{A_i}{\hat{e}(X_i)} \right) - \hat{F}(X_i, A = 0) \left(1 - \frac{1 - A_i}{1 - \hat{e}(X_i)} \right)$$

with $\hat{T}_{\text{DR}}^* = \frac{\tilde{T}_i \wedge \tau \cdot \Delta^\tau}{\hat{S}_C(\tilde{T}_i \wedge \tau | X_i)} + \frac{Q_S(\tilde{T}_i \wedge \tau | X, A) \cdot (1 - \Delta^\tau)}{\hat{S}_C(\tilde{T}_i \wedge \tau | X_i)} - \int_0^{\tilde{T}_i \wedge \tau} \frac{Q_S(c | X_i, A_i)}{\hat{S}_C^2(c | X_i, A_i)} d\hat{S}_C(c | X_i, A_i)$ and

$$Q_S(t | x, a) = \mathbb{E}[T \wedge \tau | X = x, A = a, T \wedge \tau > t]$$

⇒ 3 nuisance parameters to compute :

- Censoring model : $C \sim A + X$
- Propensity score model : $A \sim X$
- Conditional survival : $T \sim A + X$

Obs & Dependent censoring

Estimator	mis. outcome model	mis. censoring model	mis. treatment model	mis. outcome and censoring	mis. outcome and treatment	mis. censoring and treatment
Unadjusted KM						
IPCW-KM		☒				
BJ	☒					
IPTW-KM			☒			
IPTW-IPCW		☒	☒			
G-formula	☒					
IPTW-BJ	☒		☒			
AIPTW-AIPCW	✓	✓	✓	☒	☒	✓

Table 1: Consistency of estimator under model mis-specification. When all the nuisances models are mis-specified none of the estimators is consistent. ✓ indicates consistency of the estimator, ☒ indicates non consistency and empty box means there is no need to compute it.

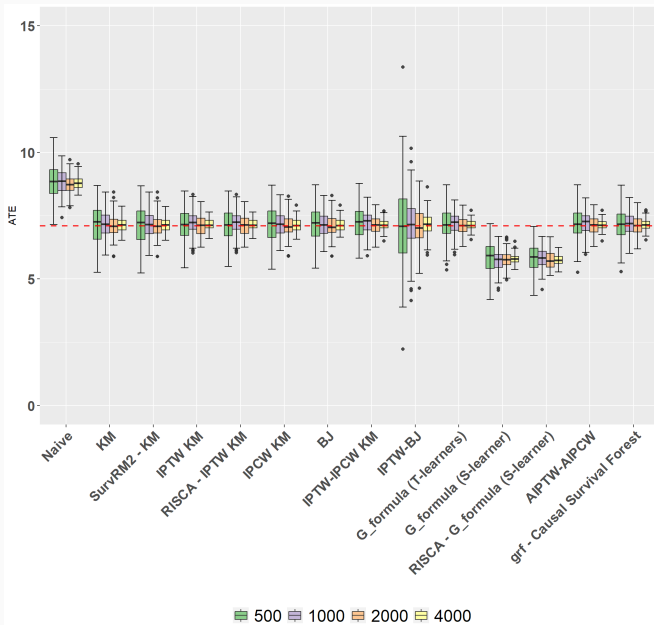
Simulations: Estimation of nuisance models

- 2 RCT (Ind. censoring & Dep. censoring), 2 Obs (Ind. censoring & Dep. censoring) in a context of **parametric simulation**.
- 1 Obs (Dep. censoring) in a context of **non-parametric simulation**.

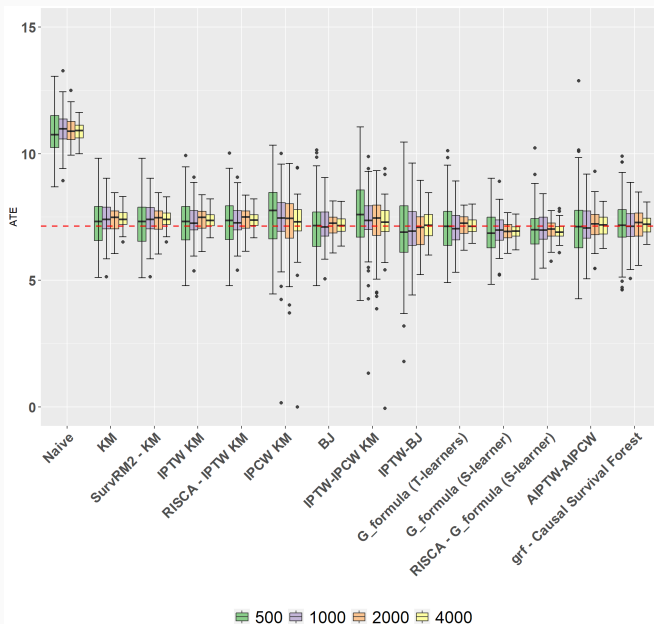
	Parametric simulation	Non-parametric simulation
Survival model	Cox model	Survival forest
Censoring model	Cox model	Survival forest
Propensity model	Logistic regression	Probability forest

Table 2: Model used for nuisance parameter estimation in the different simulation

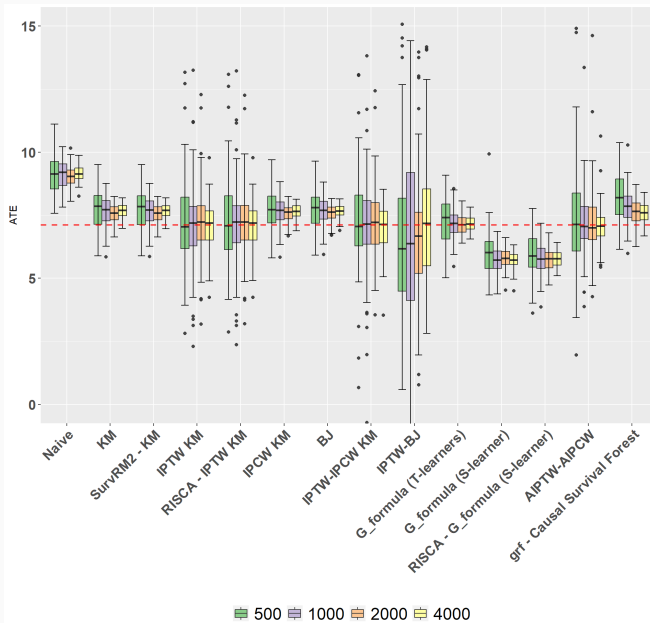
Parametric simulation: RCT & ind. censoring



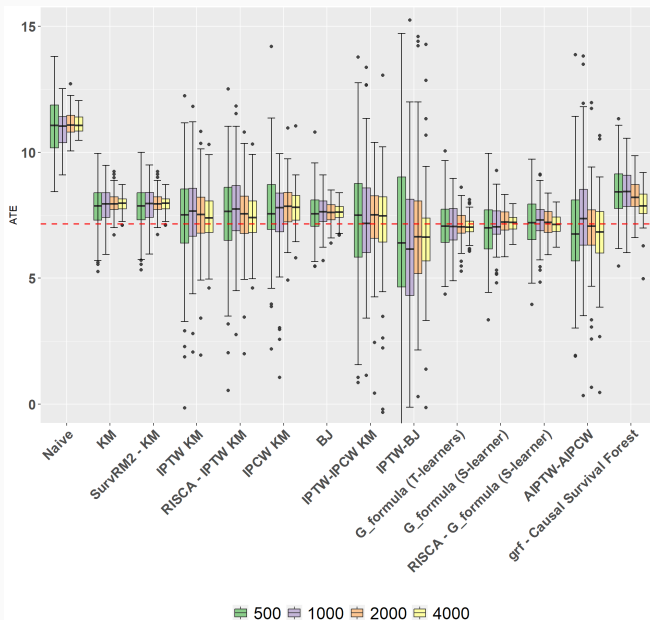
Parametric simulation: RCT & dep. cens



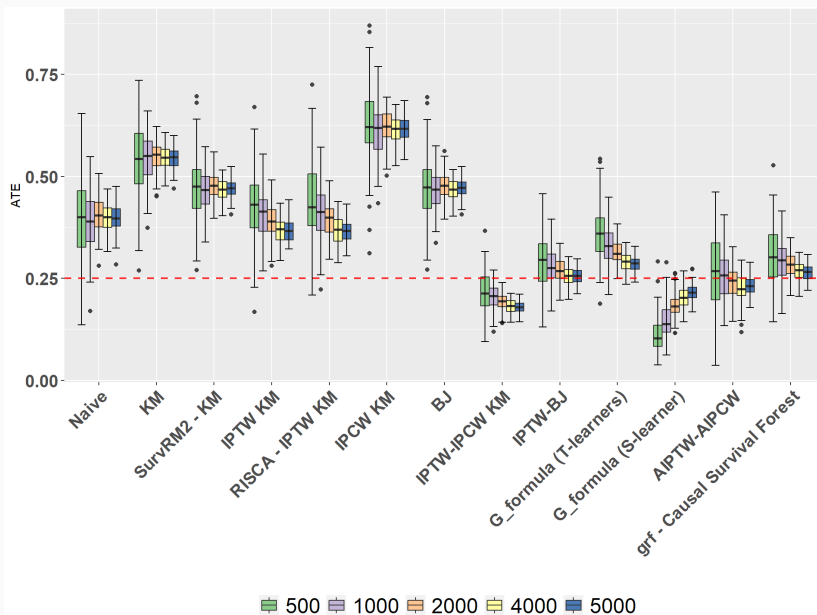
Parametric simulation: Obs & ind. censoring



Parametric simulation: Obs & dep.censoring



Non parametric simulation: Obs & dep.censoring



Conclusions:

- RMST is one extension of causal inference in survival analysis.
- The choice of the time horizon τ impacts the assumption of censoring positivity.

PARAMETRIC SIMULATION

- Robust estimators such as AIPTW-AIPCW is outperformed by G-formula estimator.
- BUT G-formula is not robust to mis-specification.
- AND in parameteric setting, G-formula relies on Cox model (proportional hazard assumption).

NON PARAMETRIC SIMULATION

- IPTW-BJ, AIPTW-AIPCW and Causal Survival Forest outperform the other in non-parametric setting.
- BUT IPTW-BJ is not robust to mis-specification.
- AIPTW-AIPCW and Causal Survival Forest need more data due to their complexity.

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Appendix

Why $\theta_{RMST}(\tau) = E[\min(T(1), \tau) - \min(T(0), \tau)]$ and $\theta_{RMST}(\tau) = \int_0^\tau (S_1(t) - S_0(t)) dt$ are equal ?

$$E(T \wedge \tau) = E(\int_0^{T \wedge \tau} 1 dt) = E(\int_0^\tau I\{T > t\} dt) = \int_0^\tau E(I\{T > t\}) dt = \int_0^\tau S(t) dt$$

Non adjusted Kaplan meier

$$\theta_{RMST} = \mathbb{E}[T(1) \wedge \tau - T(0) \wedge \tau]$$

$$= \int_0^{\tau} \mathbb{E}[I\{T(1) > t\} - I\{T(0) > t\}]dt \quad (\text{By definition})$$

$$= \int_0^{\tau} \mathbb{E}[I\{T(1) > t\}] - \mathbb{E}[I\{T(0) > t\}]dt \quad (\text{By linearity})$$

$$= \int_0^{\tau} \mathbb{E}[I\{T(1) > t|A = 1\}] - \mathbb{E}[I\{T(0) > t|A = 0\}]dt \quad (\text{Random treatment assignment})$$

$$= \int_0^{\tau} \mathbb{E}[I\{T > t|A = 1\}] - \mathbb{E}[I\{T > t|A = 0\}]dt \quad (\text{By consistency})$$

$$= \int_0^{\tau} \mathbb{P}(T > t|A = 1) - \mathbb{P}(T > t|A = 0)dt$$

$$= \int_0^{\tau} S(t|A = 1) - S(t|A = 0)dt$$

$$\begin{aligned}
 \theta_{RMST} &= \mathbb{E}[T(1) \wedge \tau - T(0) \wedge \tau] \\
 &= \int_0^\tau \mathbb{E}[I\{T(1) > t\}] - \mathbb{E}[I\{T(0) > t\}] dt \\
 &= \int_0^\tau \mathbb{E}[\mathbb{E}[I\{T > t\} | A = 1, X]] - \mathbb{E}[\mathbb{E}[I\{T > t\} | A = 0, X]] \\
 &= \int_0^\tau \mathbb{E} \left[\frac{\mathbb{E}[I\{T > t | A = 1, X\}] * \mathbb{E}[I\{T \wedge \tau < C | A = 1, X\}]}{S_c(T(1) \wedge \tau | X, A = 1)} \right] - \\
 &\quad \mathbb{E} \left[\frac{\mathbb{E}[I\{T > t | A = 0, X\}] * \mathbb{E}[I\{T \wedge \tau < C | A = 0, X\}]}{S_c(T(0) \wedge \tau | X, A = 0)} \right] dt \\
 &= \int_0^\tau \mathbb{E} \left[\frac{\mathbb{E}[I\{T > t | A = 1, X\}] * I\{T \wedge \tau < C | A = 1, X\}}{S_c(T \wedge \tau | X, A = 1)} \right] - \\
 &\quad \mathbb{E} \left[\frac{\mathbb{E}[I\{T > t | A = 0, X\}] * I\{T \wedge \tau < C | A = 0, X\}}{S_c(T \wedge \tau | X, A = 0)} \right] dt \\
 &= \int_0^\tau \mathbb{E} \left[\frac{I\{T > t | A = 1\} * \Delta^\tau}{S_c(T \wedge \tau | X, A = 1)} \right] - \mathbb{E} \left[\frac{I\{T > t | A = 0\} * \Delta^\tau}{S_c(T \wedge \tau | X, A = 0)} \right] dt
 \end{aligned}$$

$$\theta = \mathbb{E}[T(1) \wedge \tau - T(0) \wedge \tau]$$

$$= \int_0^{\tau} \mathbb{E}[I\{T(1) > t\}] - \mathbb{E}[I\{T(0) > t\}] dt$$

(By linearity)

$$= \int_0^{\tau} \mathbb{E}[\mathbb{E}[I\{T(1) > t\} | X]] - \mathbb{E}[\mathbb{E}[I\{T(0) > t\} | X]]$$

(Law of total probability and Consistency)

$$= \int_0^{\tau} \mathbb{E} \left[\frac{\mathbb{E}[I\{T(1) > t | X\}] * \mathbb{E}[A | X]}{e(X)} \right] - \mathbb{E} \left[\frac{\mathbb{E}[I\{T(0) > t | X\}] * \mathbb{E}[1 - A | X]}{1 - e(X)} \right] dt$$

(In color, the terms are equal)

$$= \int_0^{\tau} \mathbb{E} \left[\frac{\mathbb{E}[I\{T(1) > t\} * A | X]}{e(X)} \right] - \mathbb{E} \left[\frac{\mathbb{E}[I\{T(0) > t\} * (1 - A) | X]}{1 - e(X)} \right] dt$$

(By unconfoundedness)

$$= \int_0^{\tau} \frac{\mathbb{E}[I\{T(1) > t\} * A]}{e(X)} - \frac{\mathbb{E}[I\{T(0) > t\} * (1 - A)]}{1 - e(X)} dt$$

(Law of total probability)

$$= \int_0^{\tau} \frac{\mathbb{E}[I\{T(1) > t | A = 1\} * A]}{e(X)} - \frac{\mathbb{E}[I\{T(0) > t | A = 0\} * (1 - A)]}{1 - e(X)} dt$$

$$= \int_0^{\tau} \frac{\mathbb{E}[I\{T > t | A = 1\} * A]}{e(X)} - \frac{\mathbb{E}[I\{T > t | A = 0\} * (1 - A)]}{1 - e(X)} dt$$

(By consistency)

$$= \int_0^{\tau} p(T \geq t | A = 1) * \left(\frac{A}{e(X)} \right) - p(T \geq t | A = 0) * \left(\frac{1 - A}{1 - e(X)} \right) dt$$

RCTs simulations

For the simulation, 2000 samples $(X_i, A_i, C, T_i(0), T_i(1))$ are generated in the following way:

- $X \sim \mathcal{N}(\mu = [1, 1, -1, 1]^\top, \Sigma = I_4)$
- $e(X) = 0.5$ (constant) for the propensity score (A)
- $\lambda(0)(X) = 0.01 \cdot \exp\{0.5X_1 + 0.5X_2 - 0.5X_3 + 0.5X_4\}$ hazard for the event time $T(0)$
- The hazard for the censoring time C :
 - Scenario 1: $\lambda_c = 0.03$.
 - Scenario 2:
 $\lambda_c(X) = 0.03 \cdot \exp\{0.7X_1 + 0.3X_2 - 0.25X_3 - 0.1X_4 - 0.2A\}$.
- $T(1) = T(0) + 10$
- the event time is $T = AT(1) + (1 - A)T(0)$
- The observed time is $\tilde{T} = \min(T, C)$
- The status is $\Delta = 1(T \leq C)$

Obs simulations

For the simulation, 2000 samples $(X_i, A_i, C, T_i(0), T_i(1))$ are generated in the following way:

- $X \sim \mathcal{N}(\mu = [1, 1, -1, 1]^\top, \Sigma = I_4)$
- $\text{logit}\{e(X)\} = -1X_1 - 1X_2 + 2.5X_3 - 1X_4$ for the propensity score (A)
- $\lambda(0)(X) = 0.01 \cdot \exp\{0.5X_1 + 0.5X_2 - 0.5X_3 + 0.5X_4\}$ hazard for the event time $T(0)$
- The hazard for the censoring time C :
 - Scenario 1: $\lambda_c = 0.09$.
 - Scenario 2: $\lambda_c(X) = 0.03 \cdot \exp\{0.7X_1 + 0.3X_2 - 0.25X_3 - 0.1X_4\}$.
- $T(1) = T(0) + 10$
- the event time is $T = AT(1) + (1 - A)T(0)$
- The observed time is $\tilde{T} = \min(T, C)$
- The status is $\Delta = 1(T \leq C)$