To obtain full credit, you must **show all work** and carefully **justify all assertions**.

The use of notes, books and a calculator is **not** permitted.

## NAME:

(1) Consider the matrix

(a) (5 pts.) Find a basis of the Kernel of A.

$$. \times_{1} = 1, \times_{3} = 0, \times_{5} = 0 : \times_{1} = 0, \times_{2} = 0, \times_{3} = 1, \times_{5} = 0 : \times_{1} = 0, \times_{2} = 0, \times_{3} = 0, \times_{5} = 1 : \times_{1} = 0, \times_{2} = 0, \times_{3} = 0, \times_{5} = 1 : \times_{1} = 0, \times_{2} = 0, \times_{3} = 0, \times_{5} = 1 : \times_{1} = 0, \times_{2} = 0, \times_{3} = 0, \times_{5} = 1 : \times_{1} = 0, \times_{2} = 0, \times_{3} = 0, \times_{5} = 1 : \times_{1} = 0, \times_{2} = 0, \times_{3} = 0, \times_{3} = 0, \times_{5} = 1 : \times_{1} = 0, \times_{1} = 0, \times_{2} = 0, \times_{3} = 0, \times_{3} = 0, \times_{3} = 0, \times_{5} = 1 : \times_{1} = 0, \times_{1}$$

(b) (5 pts.) Find a basis of the Image of A.

(2) (10 pts.) Determine whether the following vectors form a basis of  $\mathbb{R}^4$ 

$$\frac{v_{1}}{1} = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} \qquad \frac{v_{2}}{2} = \begin{pmatrix} 1 \\ -1 \\ 1 \\ -1 \end{pmatrix} \qquad \frac{v_{3}}{2} = \begin{pmatrix} 1 \\ 2 \\ 4 \\ 8 \end{pmatrix} \qquad \frac{v_{4}}{2} = \begin{pmatrix} 1 \\ -2 \\ 1 \\ -8 \end{pmatrix}$$

$$A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ -1 & 2 & -2 \\ 1 & 1 & 4 & 1 \\ 1 & -1 & 8 & -8 \end{bmatrix} \qquad \text{check if in vertible} :$$

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$$A = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ 0 & -2 & 1 & -3 \\ 0 & 0 & 3 & 0 \\ 0 & -2 & 7 & -9 \end{bmatrix} - II \qquad \text{check if in vertible} \qquad 3$$

$$A = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ 0 & -2 & 1 & -3 \\ 0 & 0 & 3 & 0 \\ 0 & -2 & 7 & -9 \end{bmatrix} - II \qquad \text{check if in vertible} \qquad 3$$

$$A = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ 0 & -2 & 1 & -3 \\ 0 & 0 & 3 & 0 \\ 0 & -2 & 1 & -3 \\ 0 & 0 & 3 & 0 \\ 0 & -6 & 1 & 0 \\ 0 & 0 & -6 & 1 \end{bmatrix} \qquad \text{triangular with nonzero}$$

$$A = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ 0 & -2 & 1 & -3 \\ 0 & 0 & 3 & 0 \\ 0 & -6 & 1 & 0 \\ 0 & 0 & -6 & 1 \\ 0 & 0 & 0 & -6 & 1 \\ 0 & 0 & 0 & -6 & 1 \\ 0 & 0 & 0 & -6 & 1 \\ 0 & 0 & 0 & -6 & 1 \\ 0 & 0 & 0 & -6 & 1 \\ 0 & 0 & 0 & -6 & 1 \\ 0 & 0 & 0 & -6 & 1 \\ 0 & 0 & 0 & -6 & 1 \\ 0 & 0 & 0 & -6 & 1 \\ 0 & 0 & 0 & -6 & 1 \\ 0 & 0 & 0 & -6 & 1 \\ 0 & 0 & 0 & -6 & 1 \\ 0 & 0 & 0 & -6 & 1 \\ 0 & 0 & 0 & -6 & 1 \\ 0 & 0 & 0 & 0 & -6 \\ 0 & 0 & 0 & -6 & 1 \\ 0 & 0 & 0 & 0 & -6 \\ 0 & 0 & 0 &$$

(3) (10 pts.) Find the orthogonal projection of  $9\underline{e}_1$  onto the subspace W of  $\mathbb{R}^4$  spanned by the vectors

by the vectors
$$\underline{v}_1 = \begin{pmatrix} 2 \\ 2 \\ 1 \\ 0 \end{pmatrix} \quad \text{and} \quad \underline{v}_2 = \begin{pmatrix} -2 \\ 2 \\ 0 \\ 1 \end{pmatrix}$$

$$\underline{V}, \circ \underline{V}_2 = -\underline{V} + \underline{V} + \underline{O} + \underline{O} = \underline{O} \quad \Rightarrow \quad \text{orthogonal}.$$

$$\|\underline{V}_1\| = \sqrt{\underline{V} + \underline{V} + \underline{V}} - \underline{3} = \|\underline{V}_2\| \quad \Rightarrow \quad \underline{U}_1 = \frac{1}{3} \underline{V}, \quad \text{and} \quad \underline{U}_2 = \frac{1}{3} \underline{V}_2 \quad \text{orthonormal}.$$

$$= 6 \cdot \frac{1}{3} \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} - 6 \cdot \frac{1}{3} \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 8 \\ 0 \\ 2 \\ -2 \end{bmatrix}$$

(4) Consider the following vectors in  $\mathbb{R}^4$ :

$$\underline{v}_1 = \begin{pmatrix} 1 \\ 7 \\ 1 \\ 7 \end{pmatrix} \qquad \underline{v}_2 = \begin{pmatrix} 0 \\ 7 \\ 2 \\ 7 \end{pmatrix} \qquad \underline{v}_3 = \begin{pmatrix} 1 \\ 8 \\ 1 \\ 6 \end{pmatrix}$$

(a) (6 pts.) Perform the Gram-Schmidt process on  $\underline{v}_1, \underline{v}_2, \underline{v}_3$  to obtain orthonormal

vectors 
$$\underline{u}_{1}, \underline{u}_{2}, \underline{u}_{3}$$
.

$$\|\underline{y}_{1}\| = \sqrt{1 + 4q_{+} + 1 + 4q_{-}} = 10$$

$$y_{2}^{\perp} = \underline{y}_{2} - (\underline{y}_{2} \cdot \underline{y}_{1}) \underline{y}_{1} = \begin{bmatrix} 0 \\ 27 \\ 7 \end{bmatrix} - 10 \cdot \frac{1}{10} \begin{bmatrix} 1 \\ 7 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 7 \end{bmatrix}$$

$$|\underline{y}_{2}^{\perp}|_{1} = 12$$

$$|\underline{y}_{3}^{\perp}|_{1} = \overline{y}_{2} - (\underline{y}_{3} \cdot \underline{y}_{1}) \underline{y}_{1} - (\underline{y}_{3} \cdot \underline{y}_{2}) \underline{y}_{2} = \begin{bmatrix} 1 \\ 8 \\ 6 \end{bmatrix} - \begin{bmatrix} 1 \\ 7 \\ 7 \end{bmatrix} - \underline{0} = \begin{bmatrix} 0 \\ 1 \\ 0 \\ -1 \end{bmatrix}$$

$$|\underline{y}_{3}^{\perp}|_{1} = \overline{y}_{2}$$

$$|\underline{y}_{3}^{\perp}|_{1} = \overline{y}_{2}$$

$$|\underline{y}_{3}^{\perp}|_{1} = \overline{y}_{2}$$

(b) (4 pts.) Express your answer as the  $\mathbf{QR}$  factorisation of a matrix V (note: you are simply asked to give the matrix V and matrices Q, R such that V = QR.)

$$\begin{bmatrix} 1 & 0 & 1 \\ 7 & 7 & 8 \\ 1 & 2 & 1 \\ 7 & 7 & 6 \end{bmatrix} = V = QR = \begin{bmatrix} 1/10 & -1/12 & 0 \\ 7/10 & 0 & 1/12 \\ 1/10 & 1/12 & 0 \\ 7/10 & 0 & -1/12 \end{bmatrix} \begin{bmatrix} 10 & 10 & 10 \\ 0 & 72 & 0 \\ 0 & 0 & 72 \end{bmatrix}$$

(5) Let  $\phi, \theta$  be two fixed angles and consider the matrix

$$A = \begin{pmatrix} \sin \phi \cos \theta & \cos \phi \cos \theta & -\sin \theta \\ \sin \phi \sin \theta & \cos \phi \sin \theta & \cos \theta \\ \cos \phi & -\sin \phi & 0 \end{pmatrix}$$

(a) (5 pts.) Show that A is an orthogonal matrix.

(b) (5 pts.) Find the inverse  $A^{-1}$  of A.

$$A^{-1} = A^{T} = \begin{bmatrix} \sin \phi \cos \theta & \sin \phi \sin \theta & \cos \phi \\ \cos \phi \cos \theta & \cos \phi \sin \theta & -\sin \phi \\ -\sin \theta & \cos \theta & \cos \theta \end{bmatrix}$$

(checked in pt (a)!)

(6) Consider the system  $A\underline{x} = \underline{b}$  where

$$A = \begin{pmatrix} 1 & 1 \\ 1 & 0 \\ 0 & 1 \end{pmatrix} \quad \text{and} \quad \underline{b} = \begin{pmatrix} 3 \\ 3 \\ 3 \end{pmatrix}$$

(a) (7pts.) Find a least squares solution  $\underline{x}^*$  of  $A\underline{x} = \underline{b}$ .

$$X^* = (A^TA)^TA^Tb$$

$$ATb = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \frac{3}{3} \\ \frac{3}{3} \end{bmatrix} = \begin{bmatrix} 6 \\ 6 \end{bmatrix}$$

$$A^{T}A = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$
, 
$$(A^{T}A)^{-1} = \frac{1}{3} \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}$$

$$(A^TA)^{-1} = \frac{1}{3} \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}$$

$$\Rightarrow \quad \underline{X}^* = \frac{1}{3} \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 6 \\ 6 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \end{bmatrix}.$$

(b) (3 pts.) Is this solution unique? Justify your answer.

Yes: Solution of  $A^TA \times = A^Tb$ .

Yes: Since  $\ker(A^TA) = \ker(A) = \{0\}$ System is consistent and has unique solution!

(7) Consider the matrix  $A = \begin{pmatrix} \cos k & 1 & -\sin k \\ 0 & 2 & 0 \\ \sin k & 0 & \cos k \end{pmatrix}$ .

(a) (5 pts.) Compute the determinant of A.

(b) (5 pts.) Determine the values of k for which A is invertible.

(8) (opts.) Compute the determinant

$$\begin{vmatrix} 0 & 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 0 & 2 \\ 0 & 4 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ \hline 5 & 0 & 0 & 0 & 0 \end{vmatrix} = +5 \begin{vmatrix} 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 2 \\ 0 & 0 & 1 & 0 \end{vmatrix} = +5.4. \begin{vmatrix} 3 & 0 & 0 \\ 0 & 0 & 2 \\ 0 & 1 & 0 \end{vmatrix} =$$

$$=5.4.3.\begin{vmatrix}02\\10\end{vmatrix}=5.4.3.(-2)=-120$$

(9) (10 pts.) Use row operations to compute the determinant

$$\begin{vmatrix}
1 & -1 & 2 & -2 \\
-1 & 2 & 1 & 6 \\
2 & 1 & 14 & 10 \\
-2 & 6 & 10 & 33 & +2I
\end{vmatrix}$$

$$\begin{vmatrix}
1 & -1 & 2 & -2 \\
0 & 1 & 3 & 4 \\
0 & 3 & 10 & 14 \\
0 & 4 & 14 & 29 & -4II
\end{vmatrix}$$

- (10) True or false? (No justification is required for your answers to the questions below. A correct answer is worth 1 point, no answer is worth 0 points, and an incorrect answer is worth -1 points).
  - (a) If  $\underline{v}_1, \ldots, \underline{v}_n$  and  $\underline{u}_1, \ldots, \underline{u}_m$  are two bases of  $\mathbb{R}^{10}$ , then n must be equal to m.

(b) If A is a  $5 \times 6$  matrix of rank 4, then dim Ker A is equal to 1.

Frank nullity thm.:
$$dim(\ker A) + dim(\operatorname{im} A) = G \rightarrow dim(\ker A) = 2$$

$$= \operatorname{rank}(A) = 4$$
image of a 3 × 4 matrix is a subspace of  $\mathbb{R}^4$ 

(c) The image of a  $3 \times 4$  matrix is a subspace of  $\mathbb{R}^4$ .

- (d) If  $\underline{v}_1, \ldots, \underline{v}_n$  span  $\mathbb{R}^4$ , then n must be equal to 4. n=4 only if they are linearly independent.
- (e) There exists a  $5 \times 4$  matrix whose image consists of all of  $\mathbb{R}^5$ .

  by rank nullity thm.

(f) If the vectors  $\underline{v}_1, \underline{v}_2, \underline{v}_3, \underline{v}_4$  are linearly independent in  $\mathbb{R}^n$ , then the vectors  $\underline{v}_1,\underline{v}_2,\underline{v}_3$  must be linearly independent.

T if 
$$C_1 \vee_1 + C_2 \vee_2 + C_3 \vee_3 = 0$$
, not all  $C_1 = 0$ , then  $c_1 \vee_1 + c_2 \vee_2 + c_3 \vee_3 + 0 \vee_4 = 0$ .

(g) If the vectors  $\underline{v}_1, \underline{v}_2, \underline{v}_3, \underline{v}_4$  span a subspace W of  $\mathbb{R}^n$ , then the vectors  $\underline{v}_1, \underline{v}_2, \underline{v}_3$ must be also span W.

(h) If a subspace W of  $\mathbb{R}^3$  contains the standard vectors  $\underline{e}_1,\underline{e}_2,\underline{e}_3$ , then W must be  $\mathbb{R}^3$ .

$$T$$
 dim  $W = rank((e_1, e_2, e_3)) = 3$ 

(i) If W is a subspace of  $\mathbb{R}^n$  of dimension m, then  $m \leq n$ .

(i) If the kernel of a matrix A consists of the zero vector only, then the columns of A must be linearly independent.

T

if 
$$A = [Y_1, ..., Y_n]$$
 and

 $C_1Y_1 + ... + C_nY_n = Q$ , then  $C = [C_n]$  is in

ker(A)

Since her  $A = \{Q\}$ , the columns

must be linearly independent.