

# picoCountdowner

倒數計時器

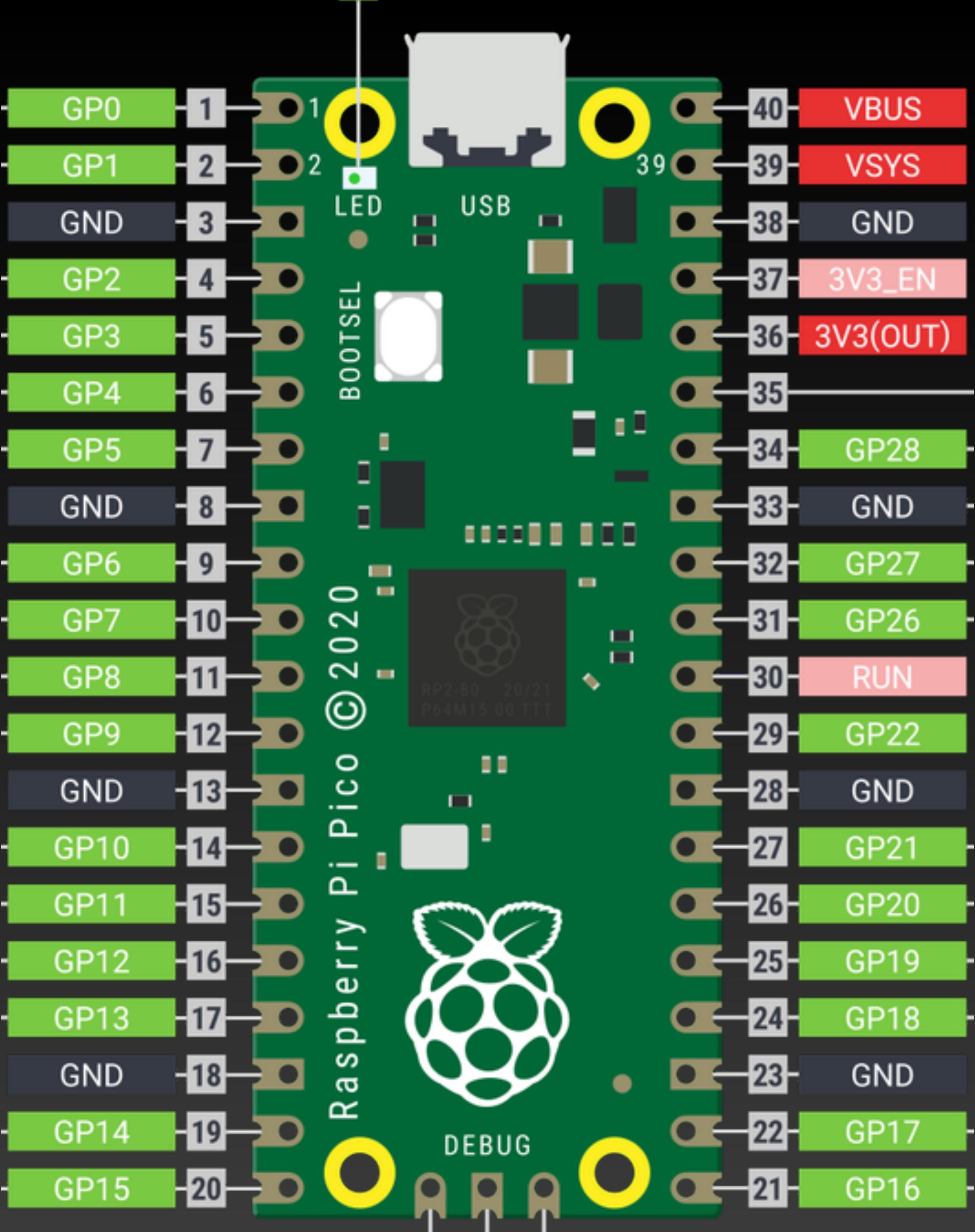
王棋俊  
chyijiunn



# What we use

## Material

- Raspberry pico
- Thonny
- Sg90 motor
- Buzz
- LED



# PythonLearningMap

**LED**

for  
while

**Buzz**

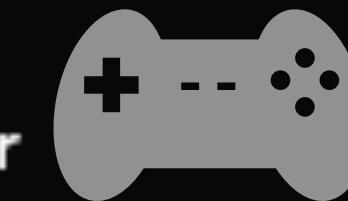
tone , Hz  
picoPinano

**button**

if  
ttraffic light

**ssd1306**

function  
module  
picoRetroGamer



16 bit

thread

picoPercussion

picoCountdowner



**servoMotor**



picoWatch

picoDrone



**gyro**

# Kickstarter project example

TempoFlow LightClock Pomodoro

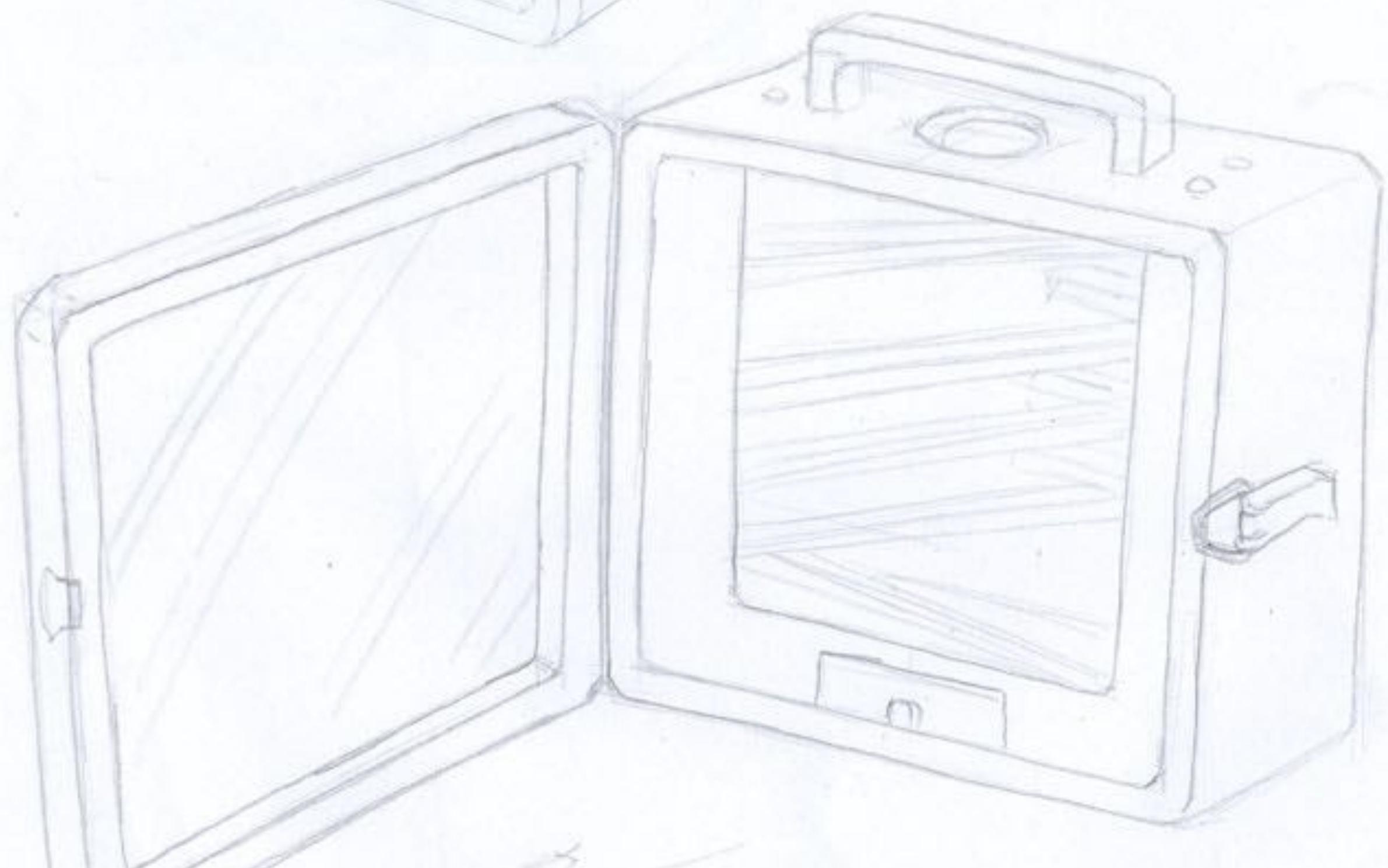
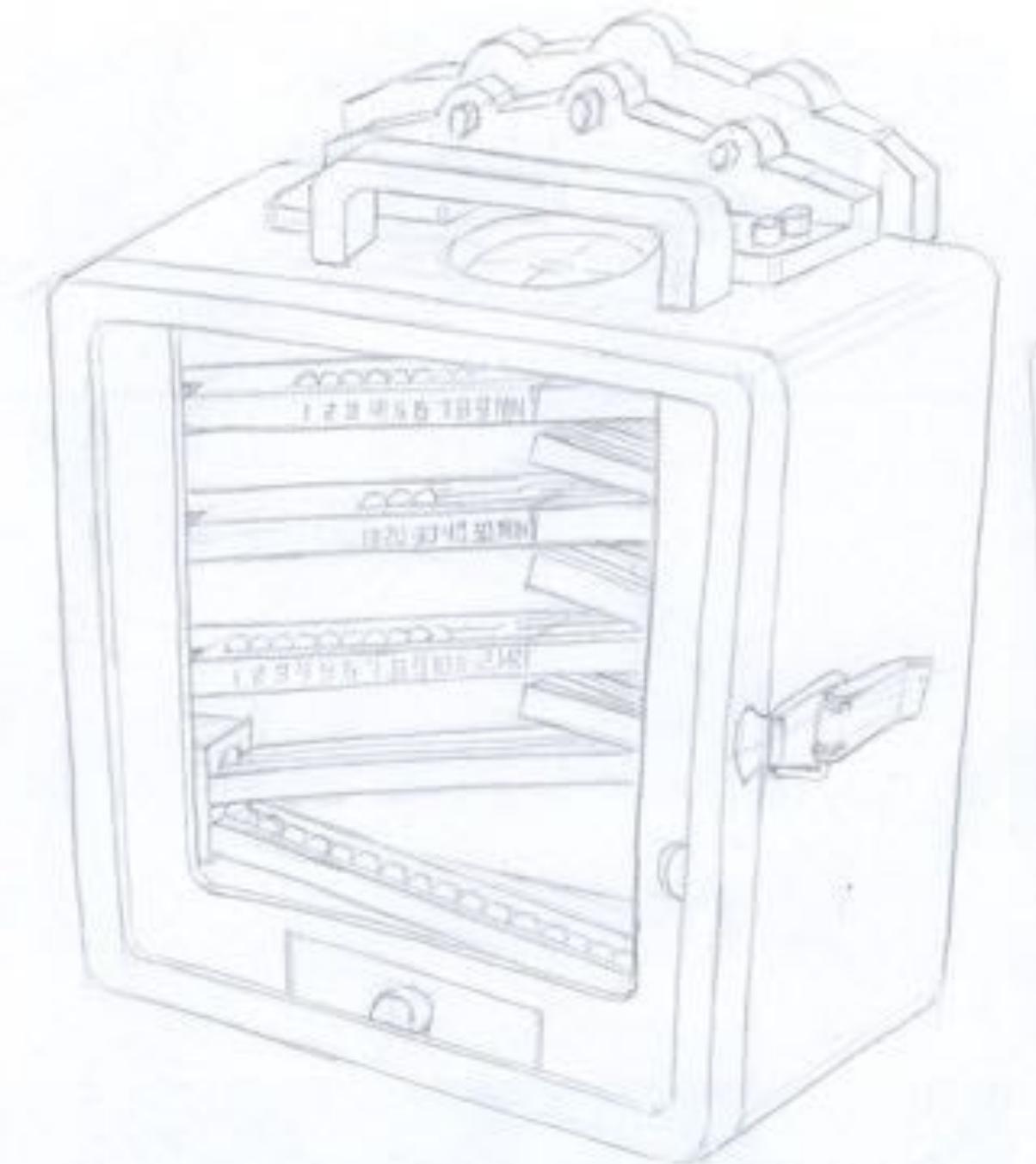
# Specs



**Steven LAM**

<https://www.tempo-flow.com/>





# Rewards

72 Hour Special

**\$159**

~~\$299~~  
47%  
Off



5 Day Special

**\$169**

~~\$299~~  
43%  
Off

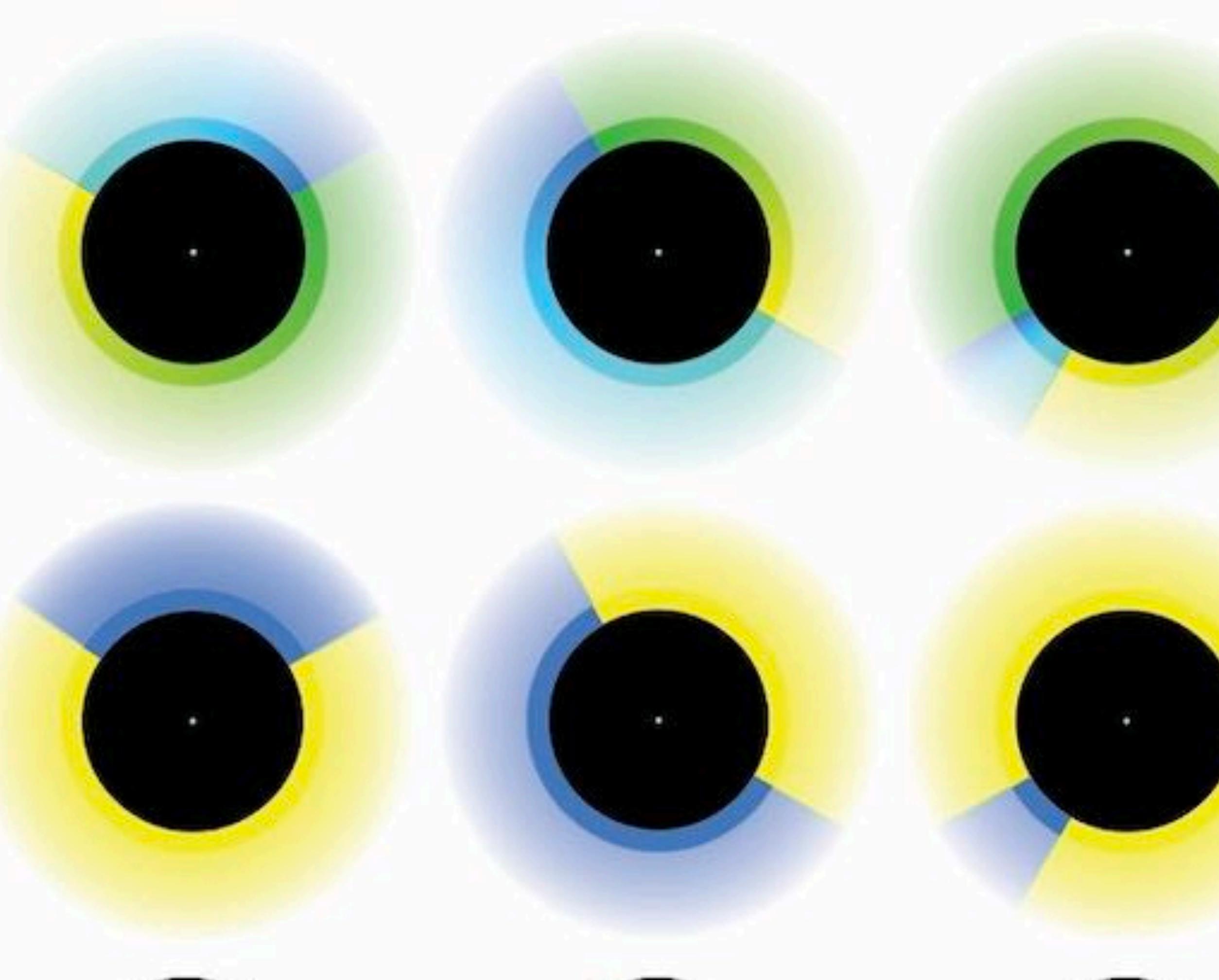


Super Early Bird

**\$179**

~~\$299~~  
40%  
Off

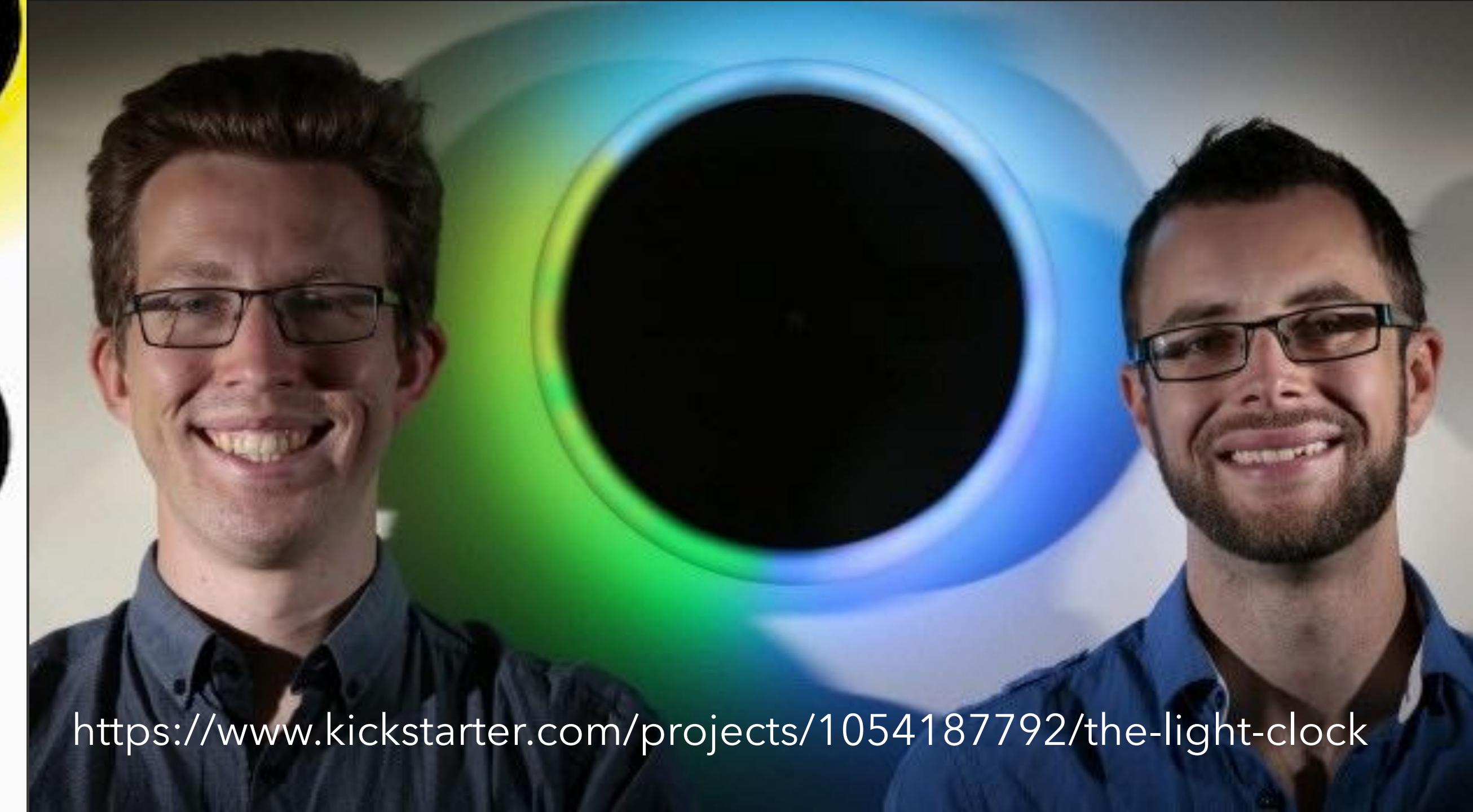




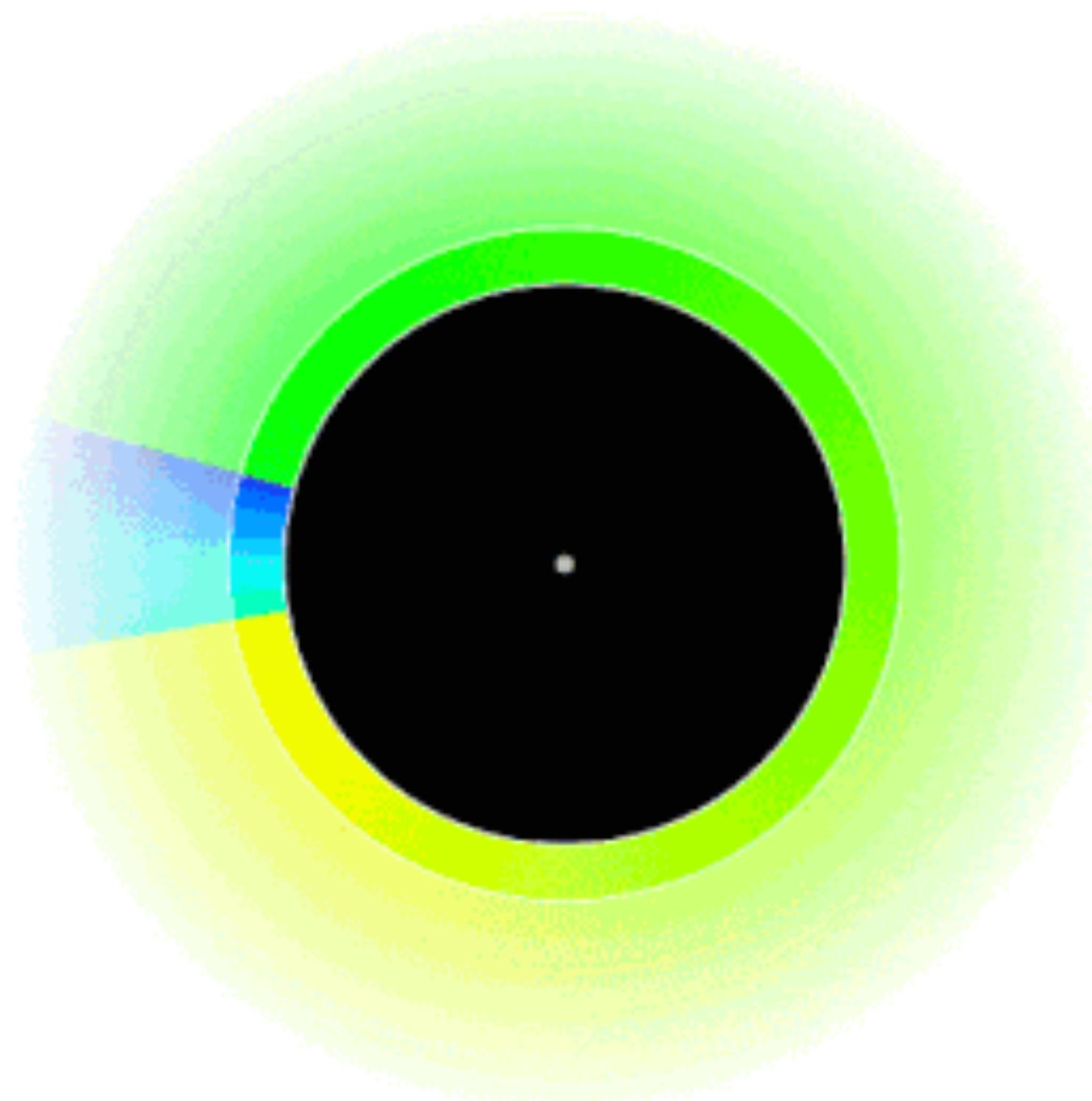
10:10

4:55

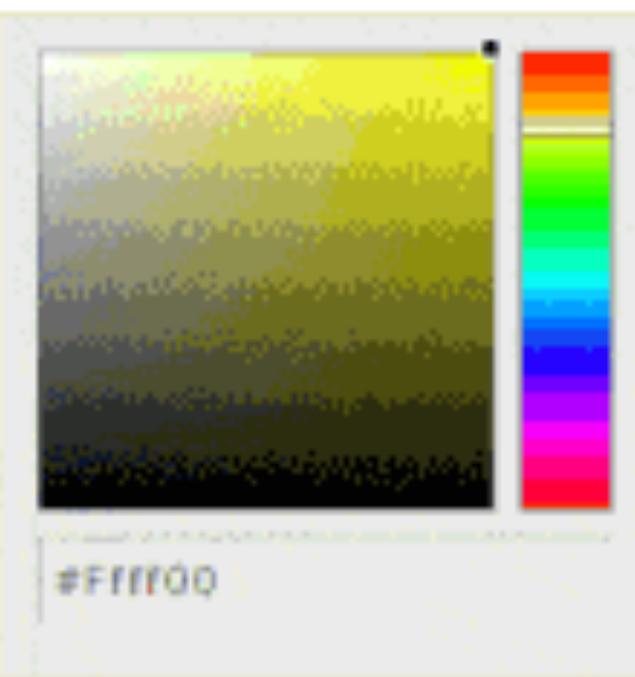
7:40



<https://www.kickstarter.com/projects/1054187792/the-light-clock>



Hour Colour

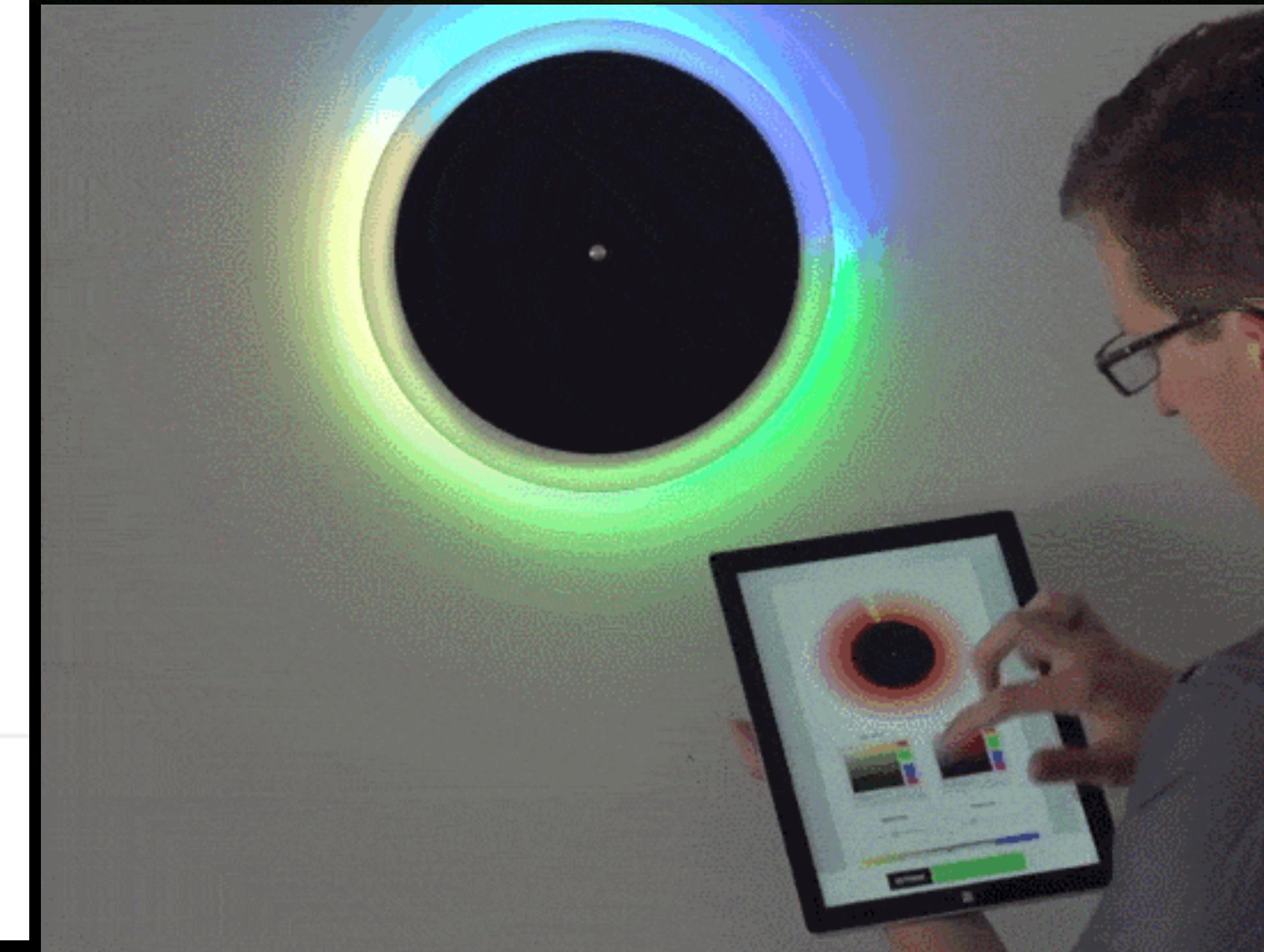
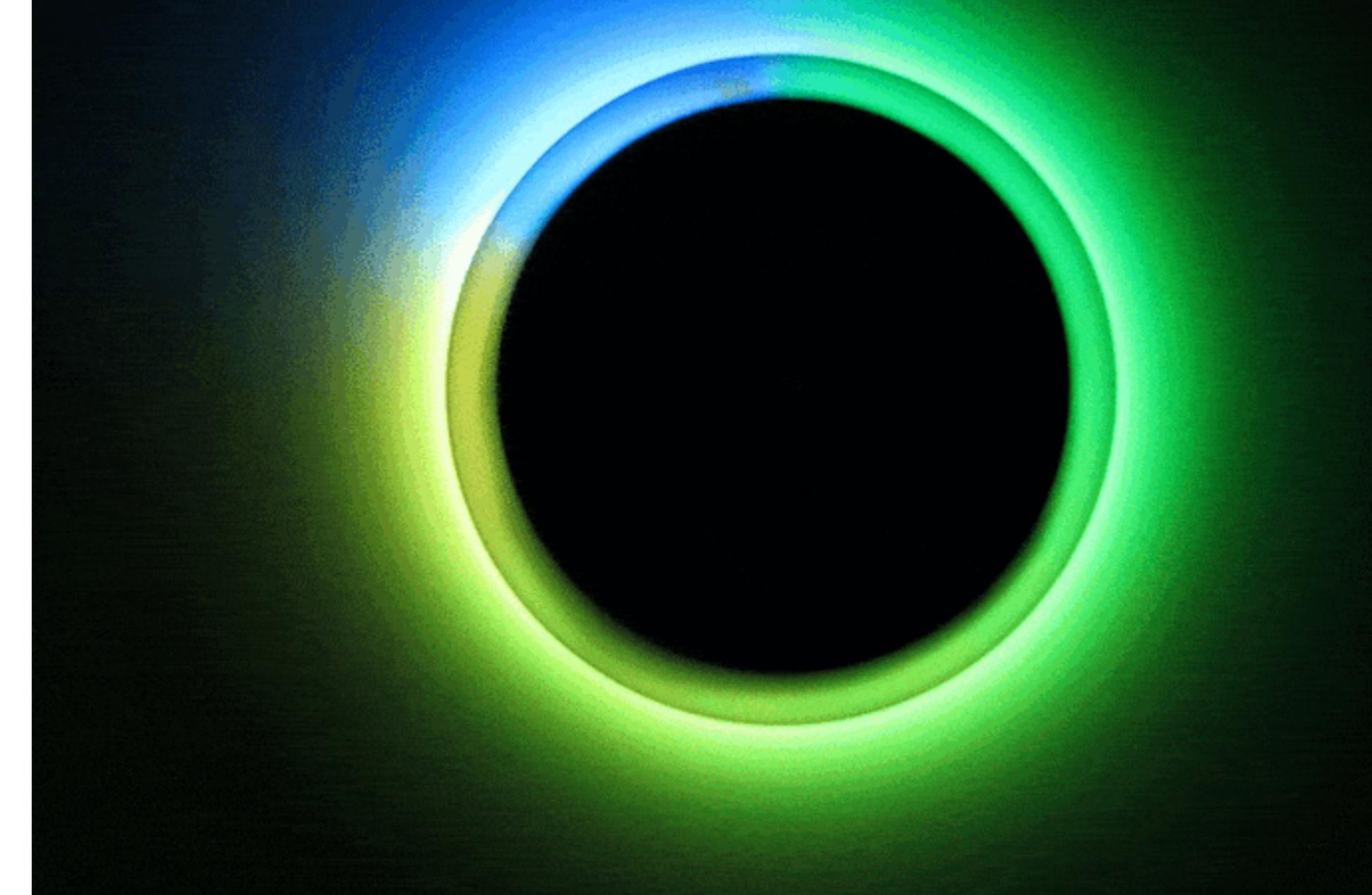


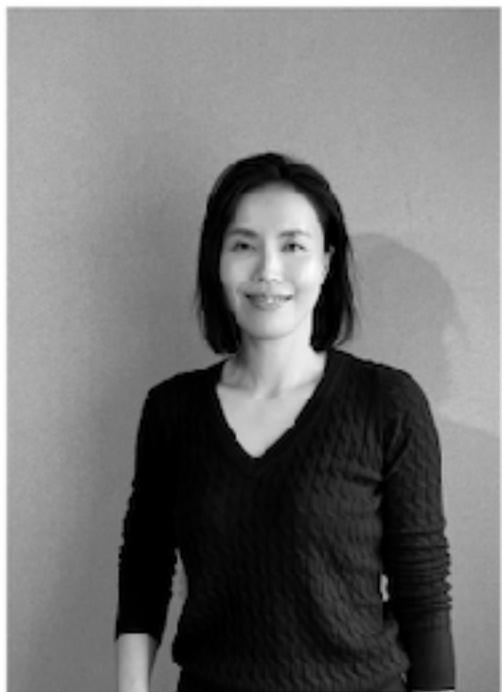
Minute Colour



SETTINGS

UPDATE THE LIGHT CLOCK





Founder / PM  
**Rachel**



Business Developer  
**Shaun**



Product Manager  
**Doo**



Hardware Engineer  
**Steve**



UI/UX Designer  
**Mari**



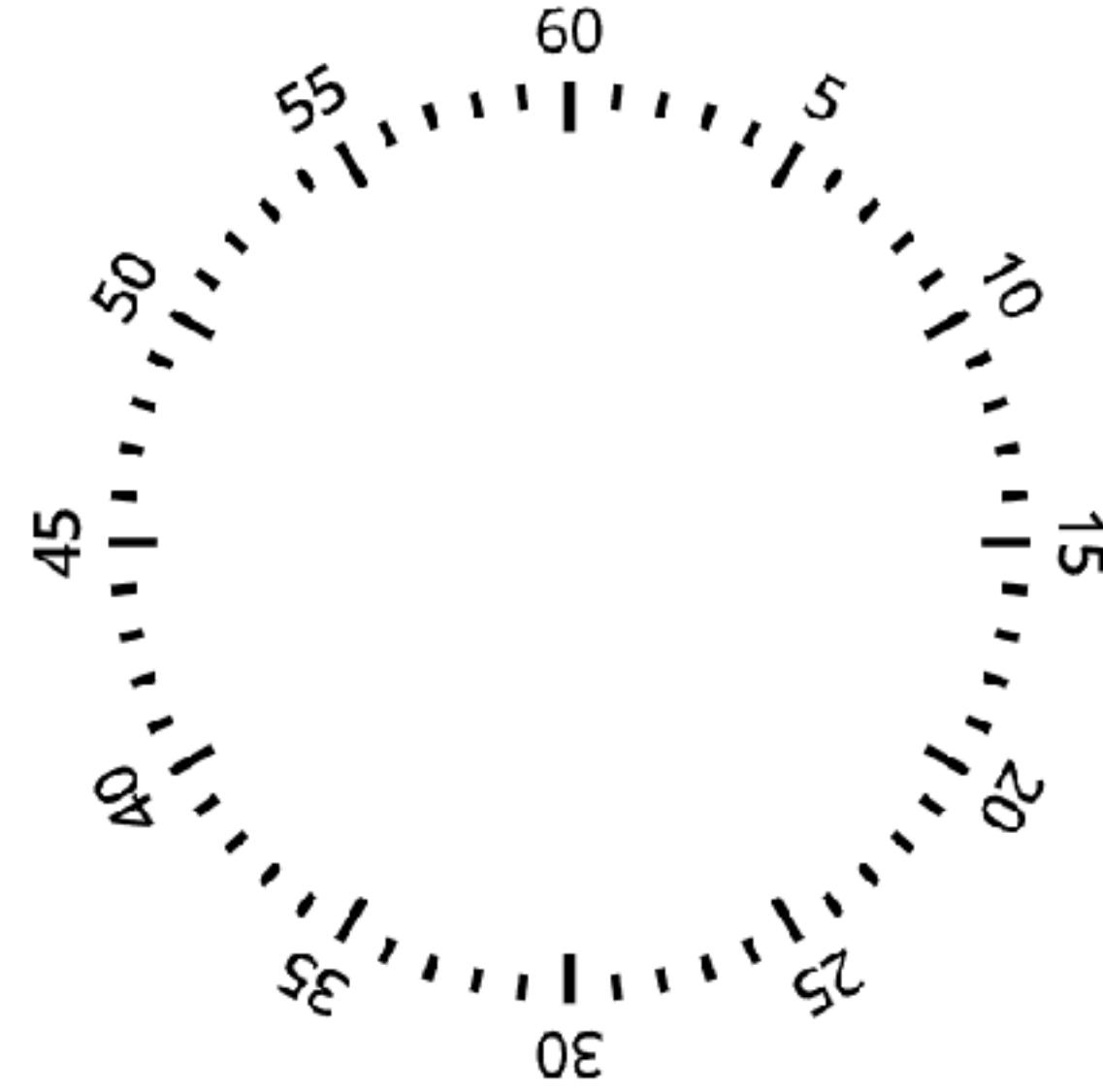
Software Engineer  
**SY Yun**



Marketer  
**Lennie**



Manufacturing QC  
**Zinna**



Focus time

Break time

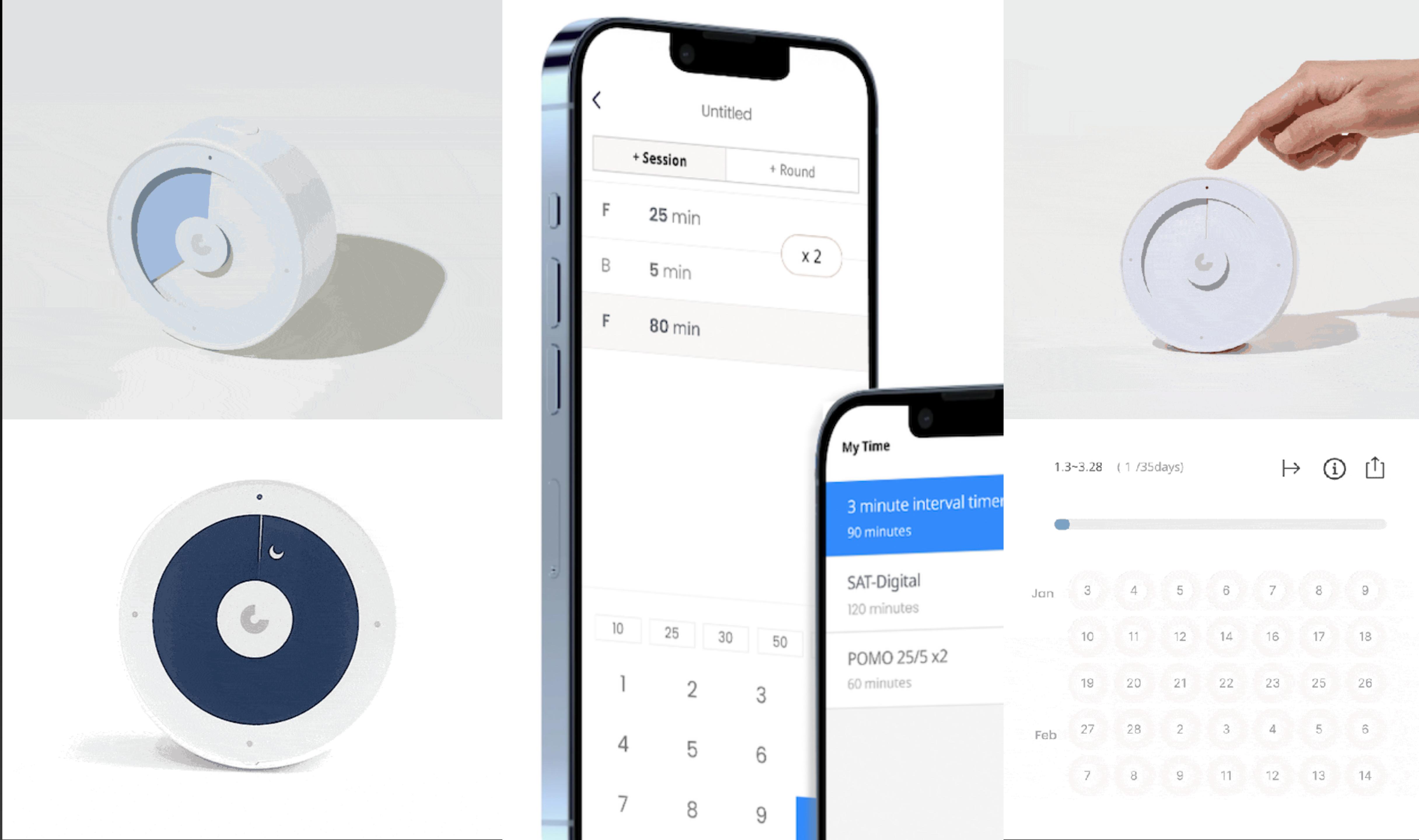
timer 4



minee 3



<https://www.kickstarter.com/projects/minee/minee-habit-tracking-pomodoro-timer-kit-for-your-goal>



# 課程素材

GitHub: picoCountdowner

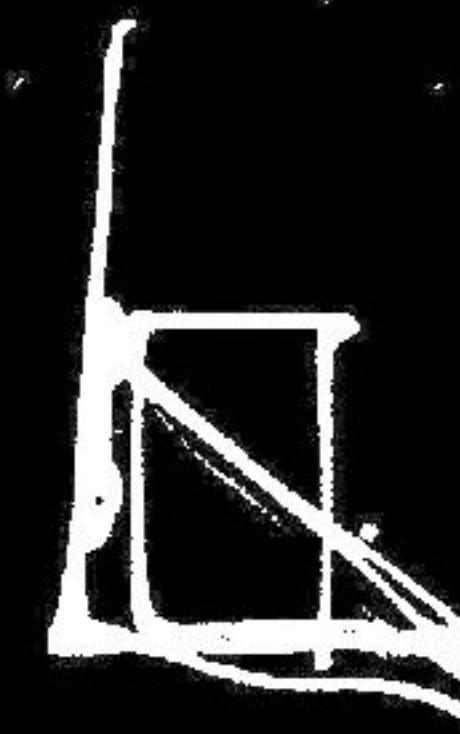
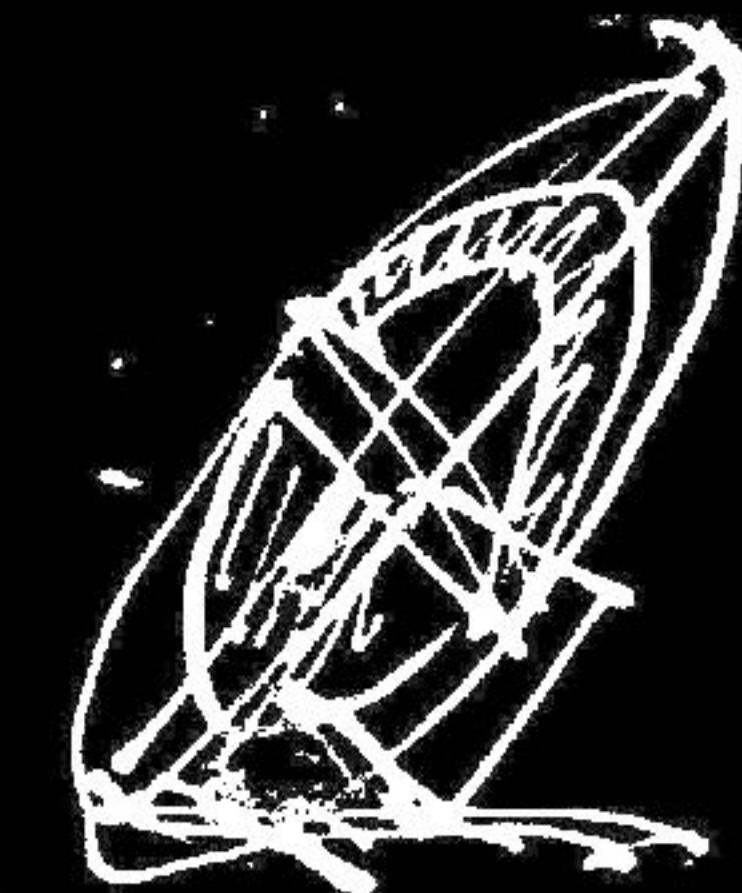
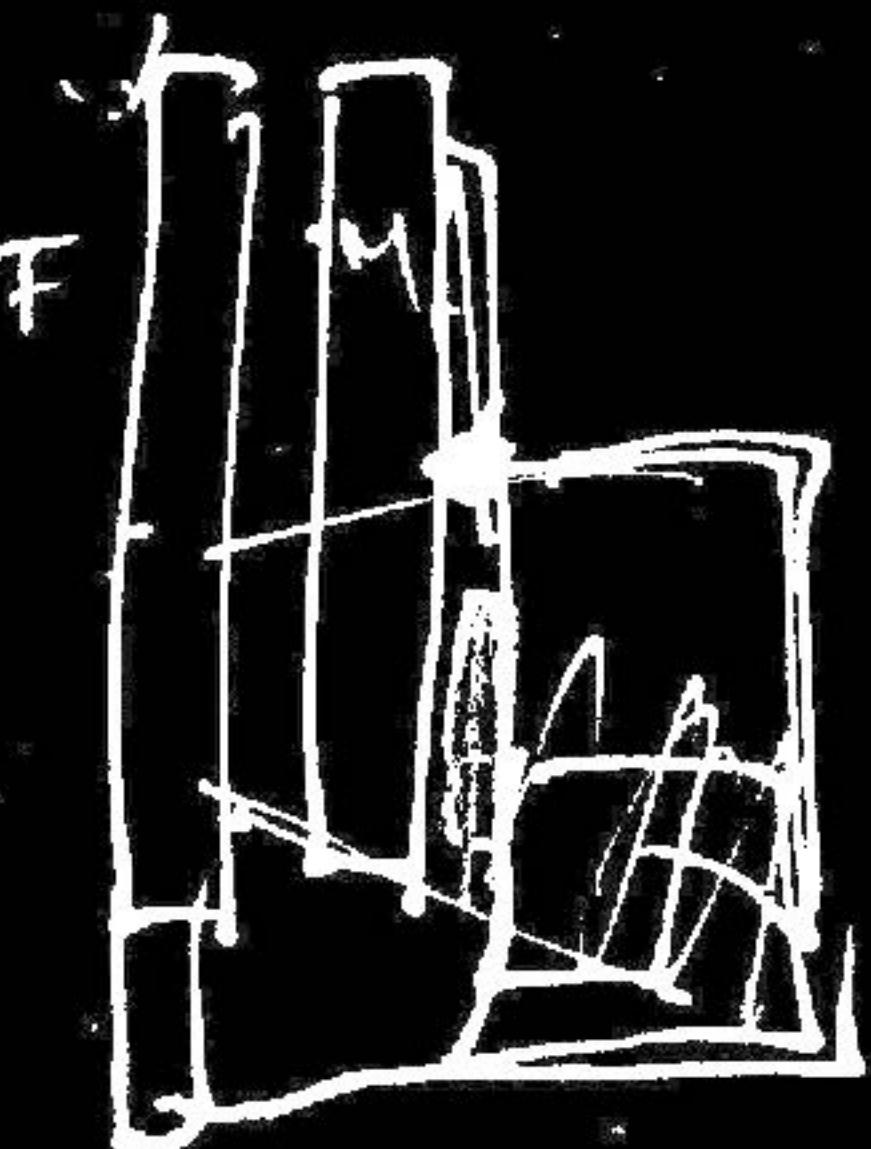
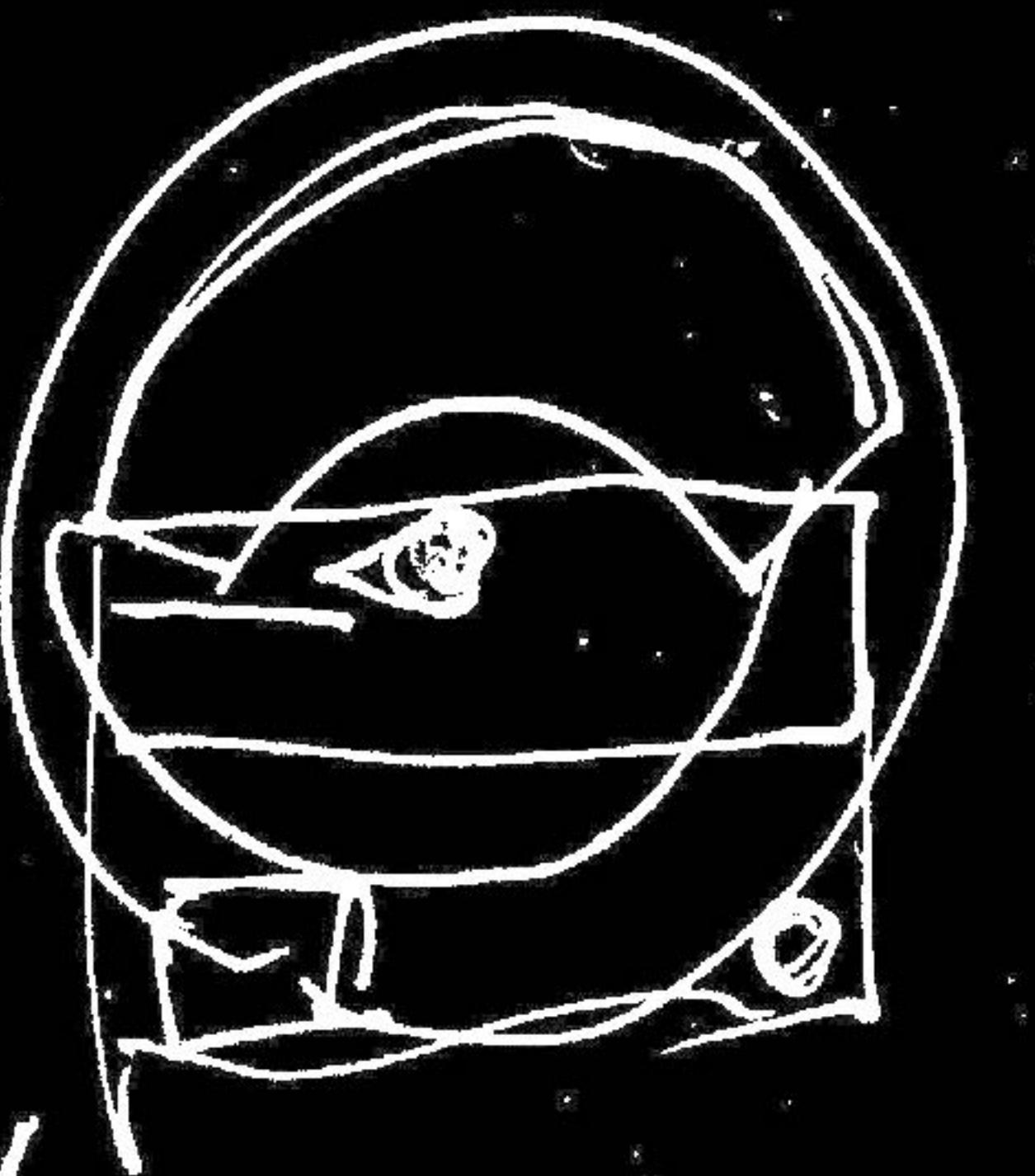
[github.com/chyijiunn/picoCountdowner](https://github.com/chyijiunn/picoCountdowner)



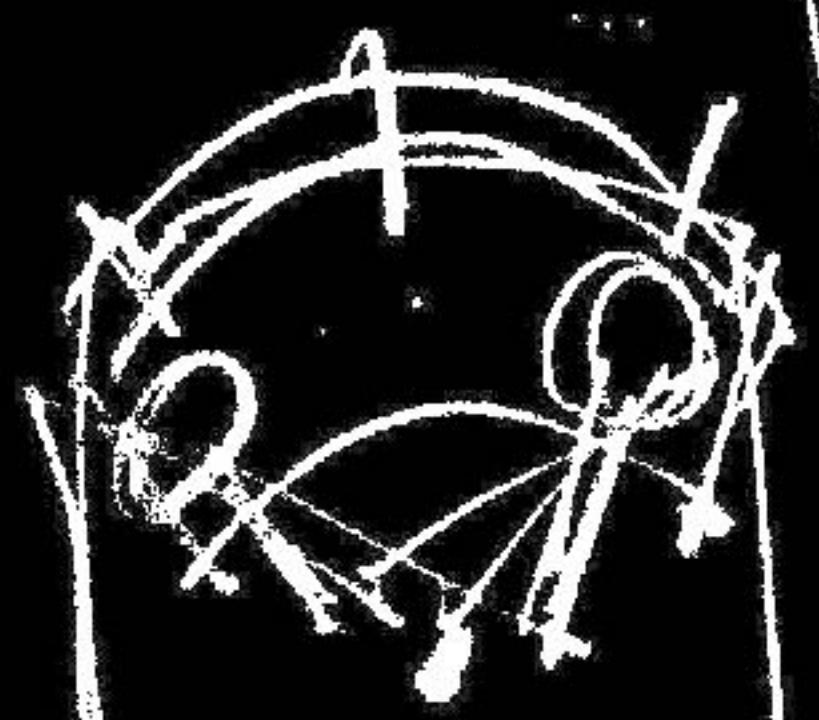
± 30°

15 min. to  
60°

# Start



if



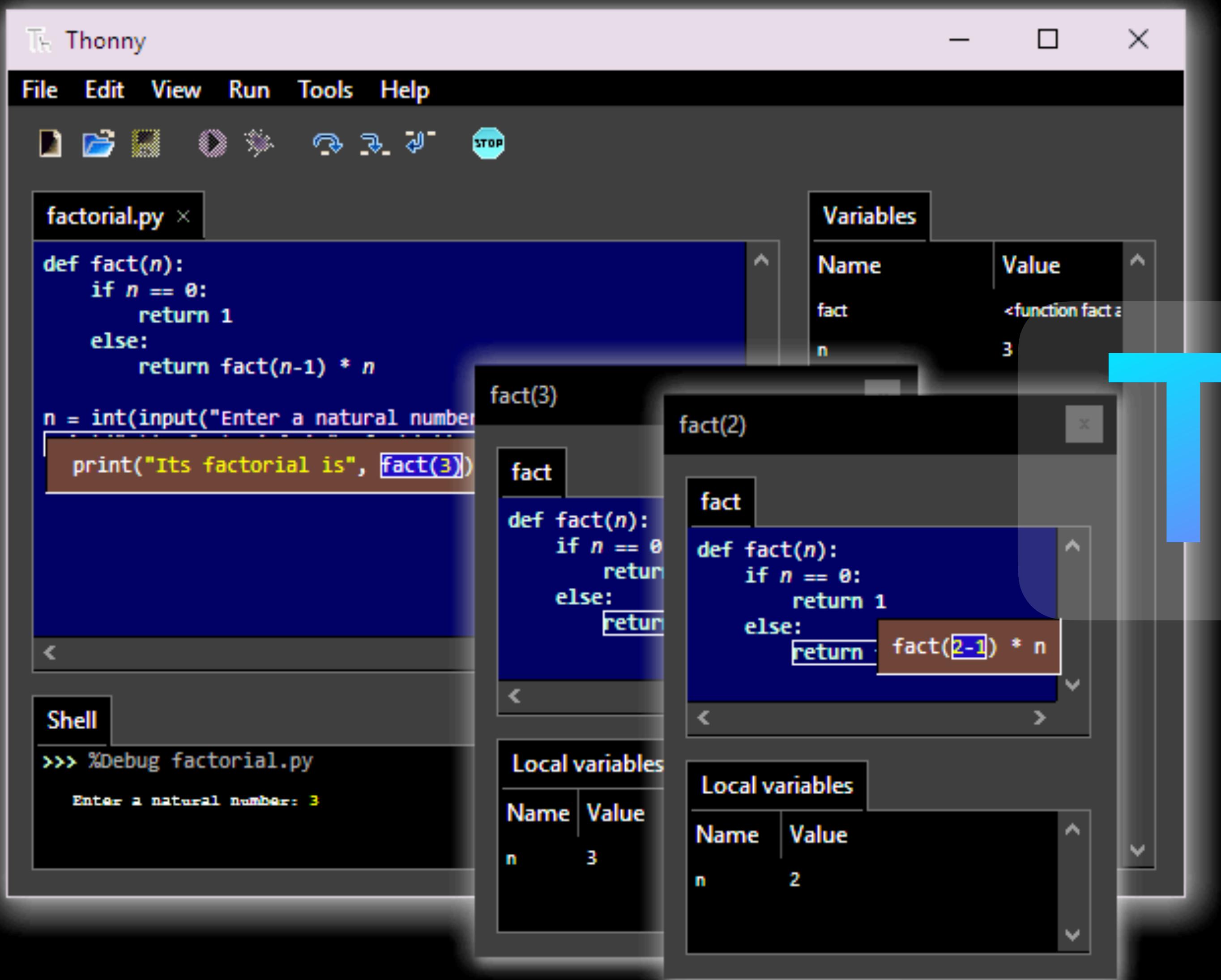
2.



# Thonny

Python IDE for beginners

 Download version [4.1.7](#) for  
Windows • Mac • Linux



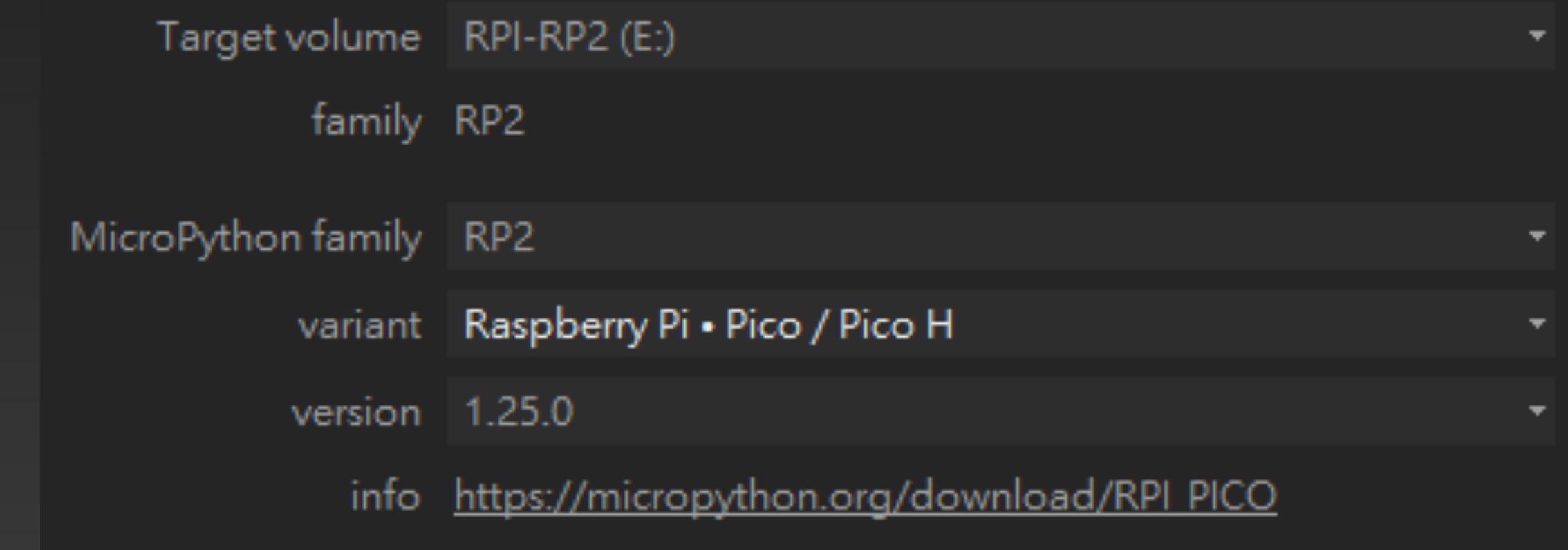
# Thonny

介面使用  
韌體操作  
寫三行

# 韌體

按住BOOT SEL - 插入USB - 讀取如隨身碟

- 推薦使用
- 下載韌體
- 拖拉韌體進入
- 隨身碟顯示退出
- 工具 - 選項 - 直譯器
- 選 PICO
- 安裝或更新MICROPYTHON



# 檢視 - 檔案

Raspberry Pi Pico

00.py  
01.py

MicroPython v1.25.0 on 2025-04-15; Raspberry Pi Pico with RP2040

Type "help()" for more information.

>>>

選 pico

本機  
/ Users / trunking / Documents /  
GitHub / picoCountdowner

▷ media  
  ↳ 00.py  
  ↳ 01\_led1.py  
  ↳ 02\_led0.py  
  ↳ 03\_ledBlink.py  
  ↳ 04\_ws2812.py  
  ↳ 05\_chasingStripe.py  
  ↳ 06\_breathStripe.py  
  ↳ 07\_buzzerScale.py  
  ↳ 08\_buzzerScaleFor.py  
  ↳ 09\_buzzerFre.py  
  ↳ 10\_beep.py  
  ↳ 11\_sg90.py  
  ↳ 12\_sg90While.py  
  ↳ 13\_sg90For.py  
  ↳ 14\_Timer.py  
  ↳ 15\_period.py  
  ↳ 16\_beepMotor.py  
  ↳ 17\_final\_LED.py  
  ↳ 18\_finalA.py  
  ↳ 19\_finalB.py  
  ↳ 20\_thread.py  
  ↳ main.py  
  ↳ README.md  
  ↳ signLCDMain.py

```
1 from machine import Pin, PWM
2 from utime import sleep
3 buzzer = PWM(Pin(14))
4 buzzer.freq(4000)
5
6 for j in range(4):
7     for i in range(4):
8         buzzer.duty_u16(1000)
9         sleep(0.15)
10        buzzer.duty_u16(0) #短暫的靜音
11        sleep(0.01)
12    sleep(0.8)
```

MicroPython (Raspberry Pi Pico) • Board in FS mode @ /dev/cu.usbmodem14601

# 右鍵 - 上傳

在 Thonny 中開啟

使用預設的外部程式開啟

設定 .py 檔...

顯示隱藏檔

上傳到 /

建立新檔...

新增目錄...

剪下

複製

貼上

移至垃圾桶

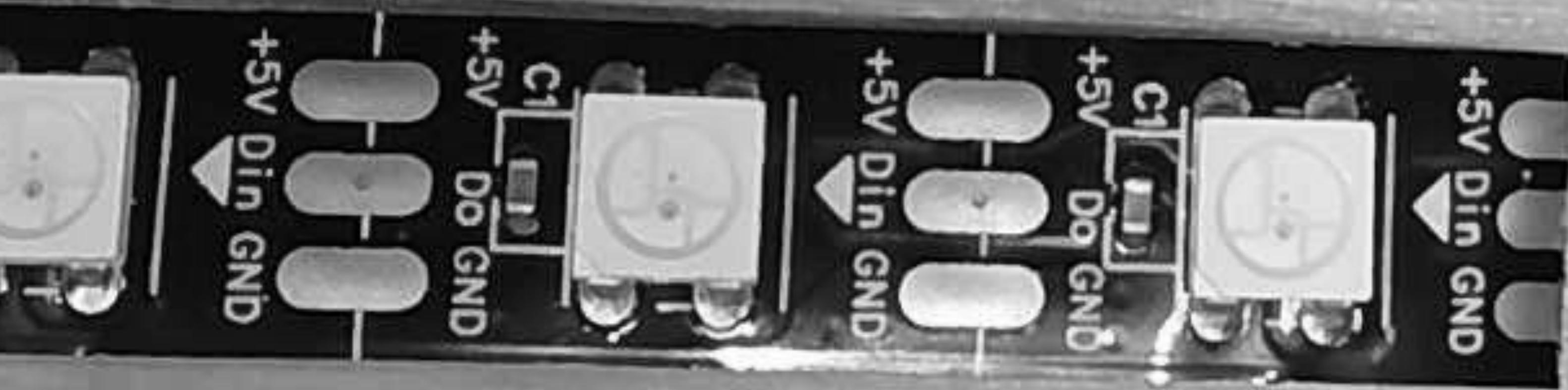
屬性

```
2 from utime import sleep
3 buzzer = PWM(Pin(14))
4 buzzer.freq(4000)
5
6 for j in range(4):
7     for i in range(4):
8         buzzer.duty_u16(1000)
9         sleep(0.15)
10        buzzer.duty_u16(0) #短暫的靜音
11        sleep(0.01)
12        sleep(0.8)
```

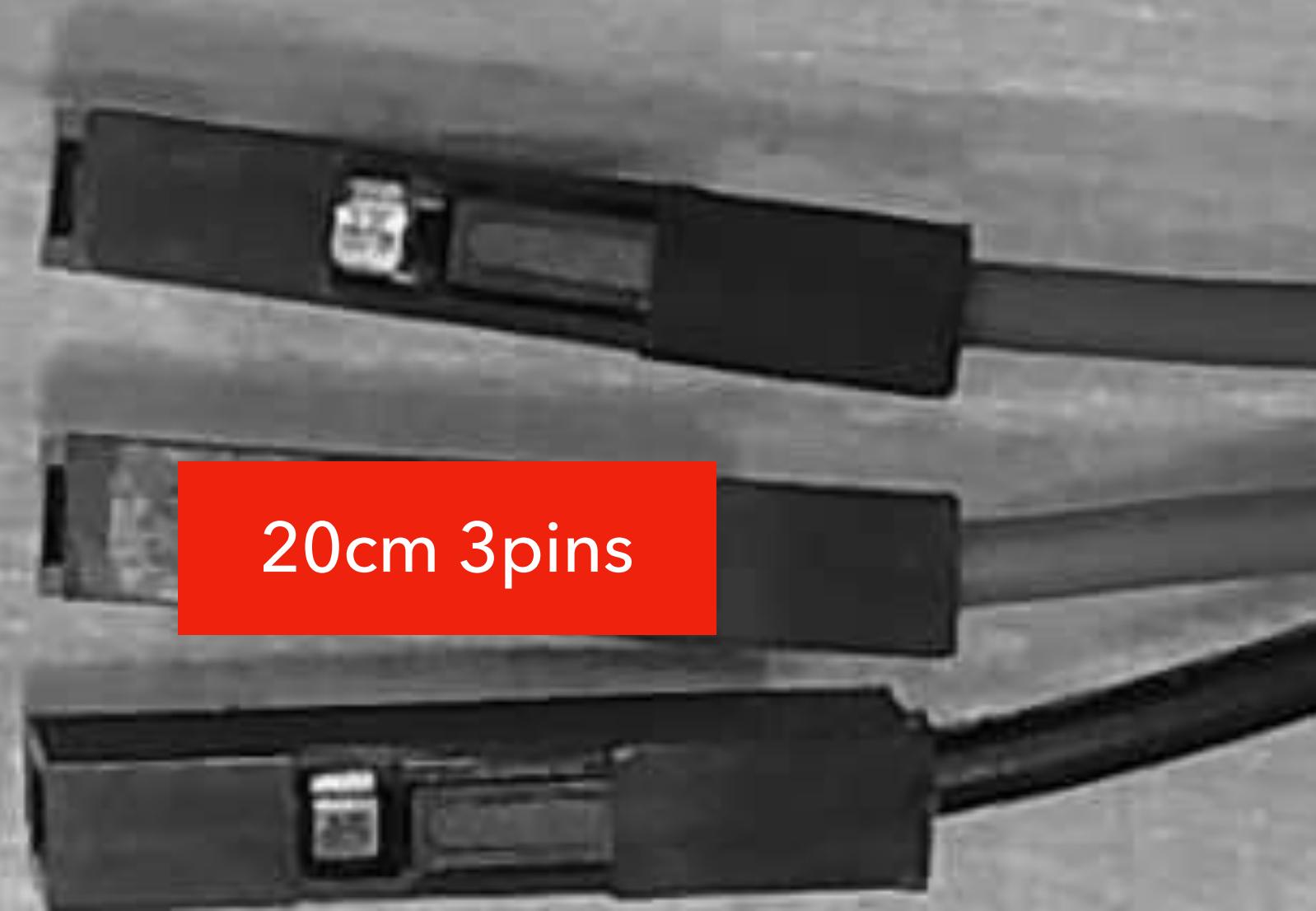
互動環境 ×

MicroPython v1.25.0 on 2025-04-15; Raspberry Pi Pico with RP2040  
Type "help()" for more information.

注意燈條DIN方向



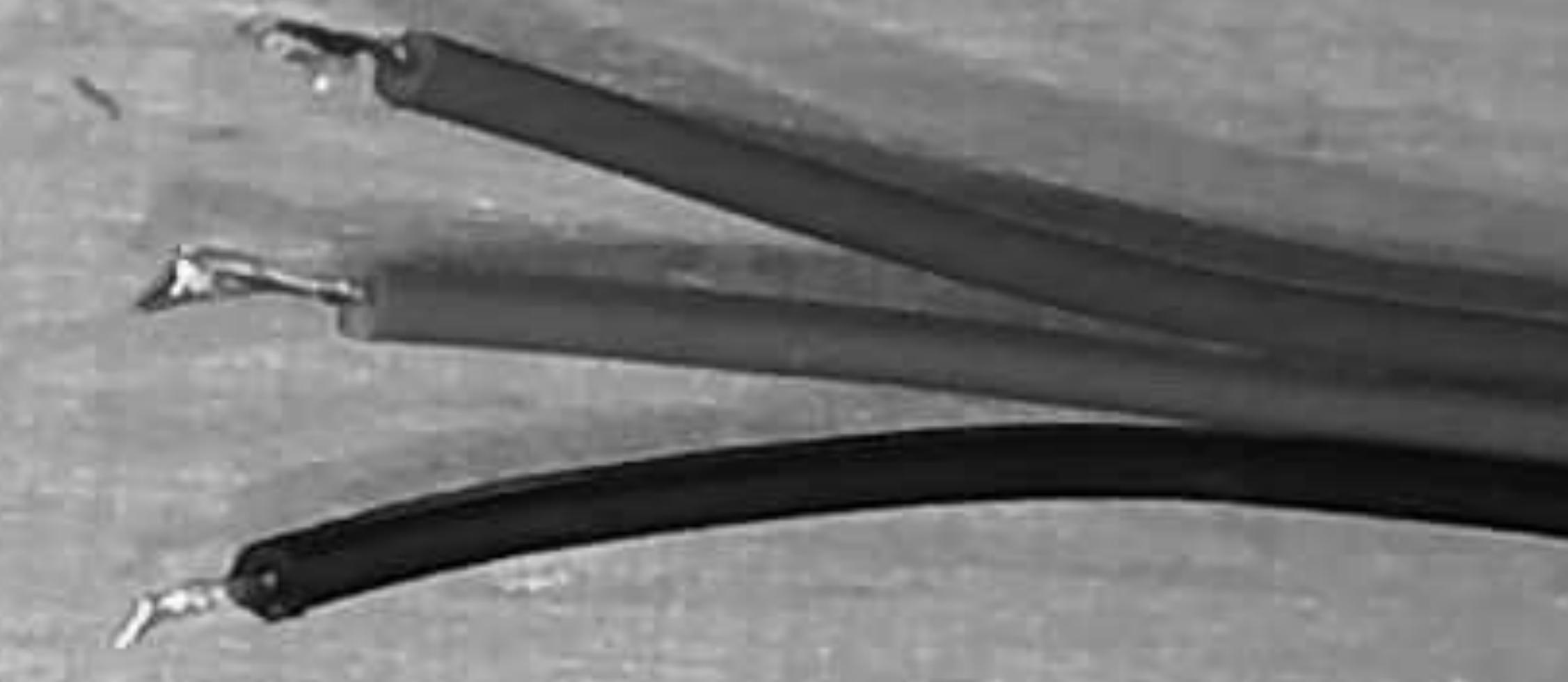
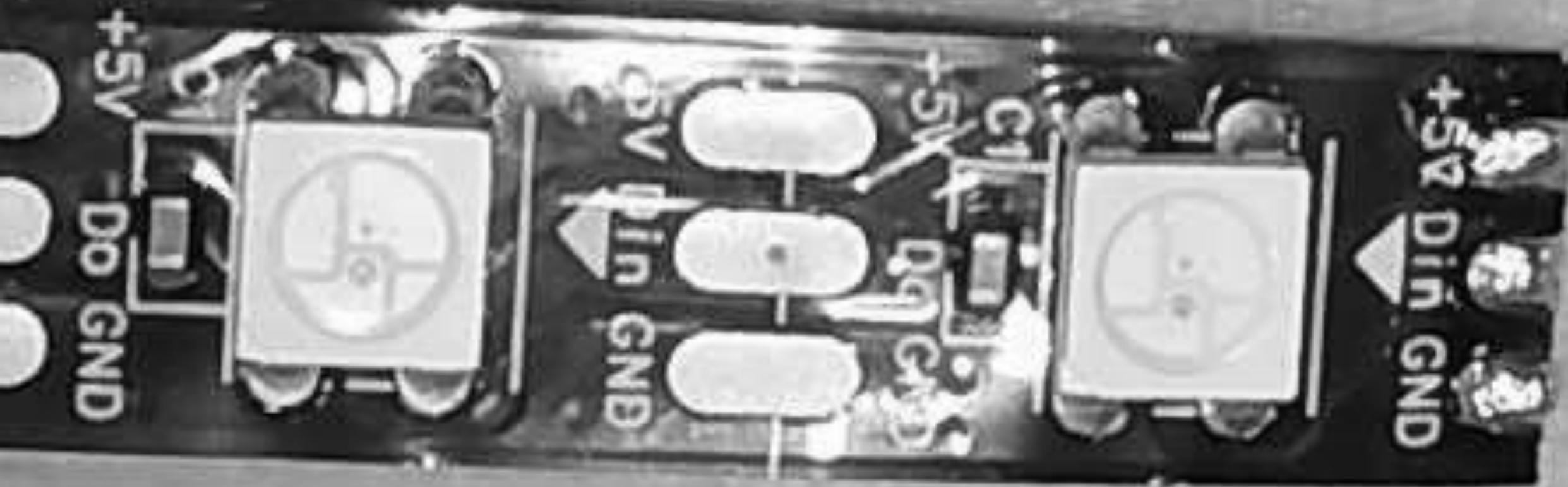
20cm 3pins



剪掉杜邦頭



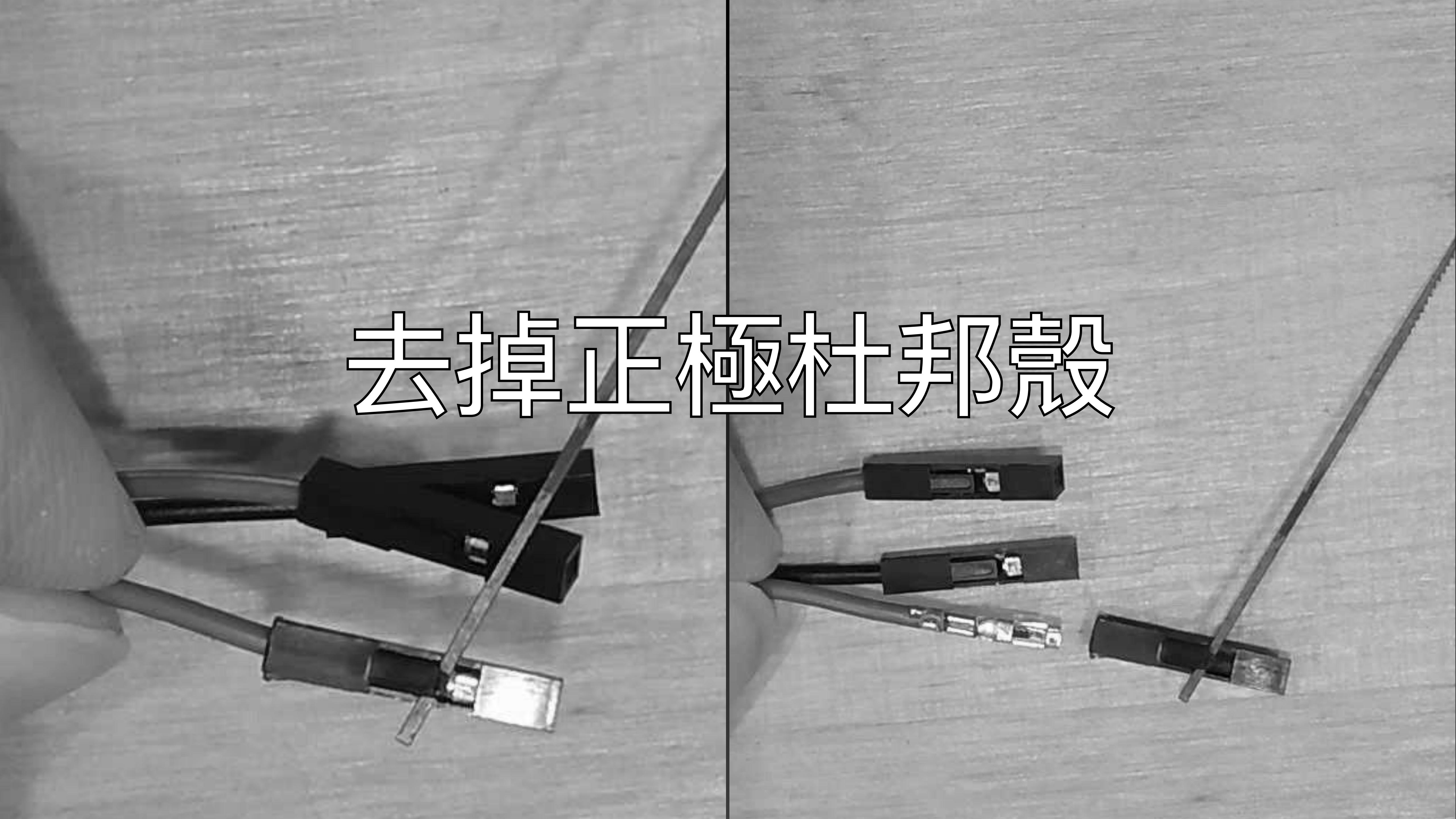
接錫再齊刺齊早助火上



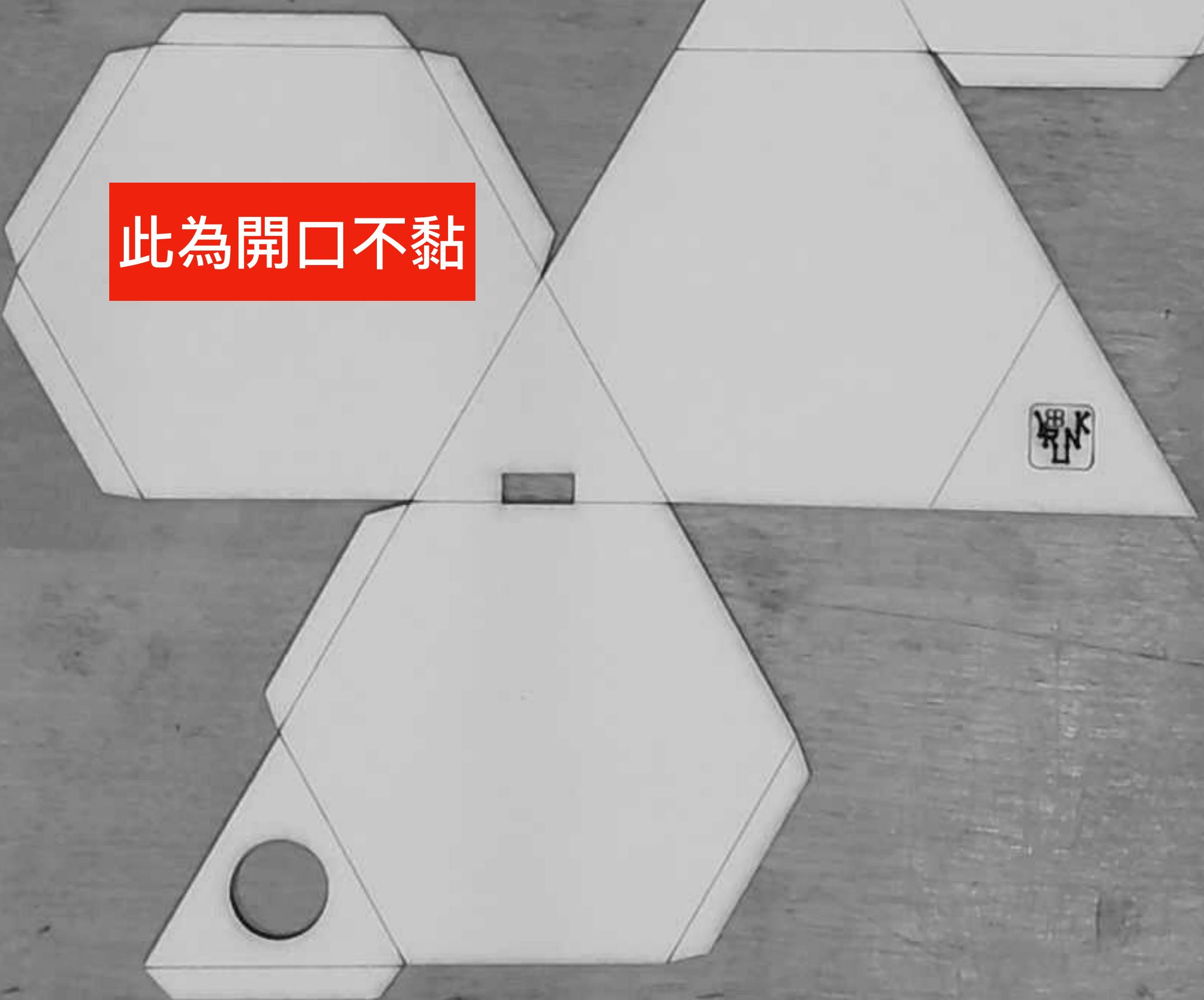
接錫再剪齊早助火上



去掉正極杜邦殼



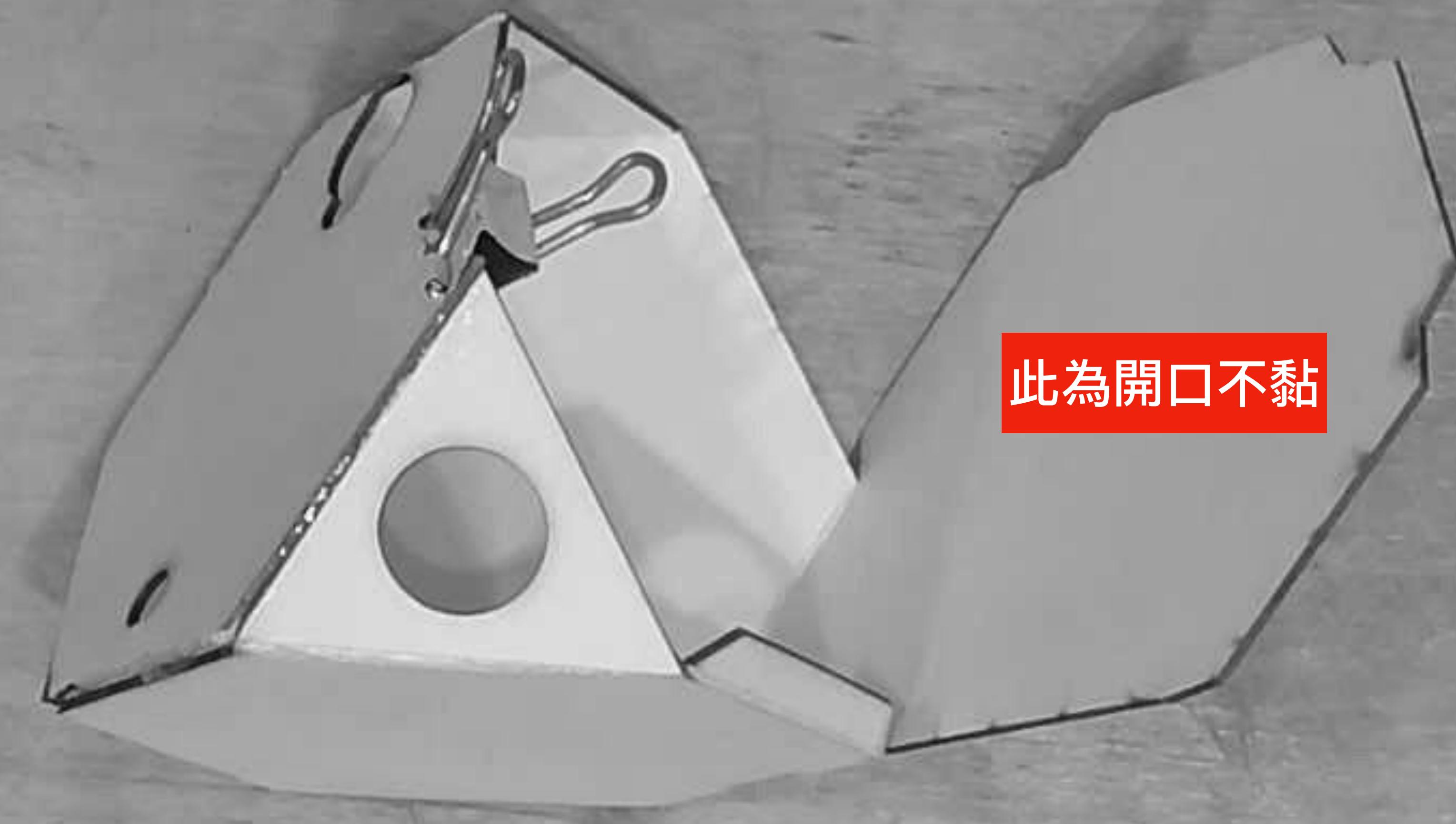
# 有記號為外側





折線都朝外  
為山折線

# 長尾夾輔助固定



此為開口不黏



# 剪掉sg90側翅

並去掉信號線杜邦殼

開口盒舌

置入sg90





圓紙片貼合

對齊小圓孔

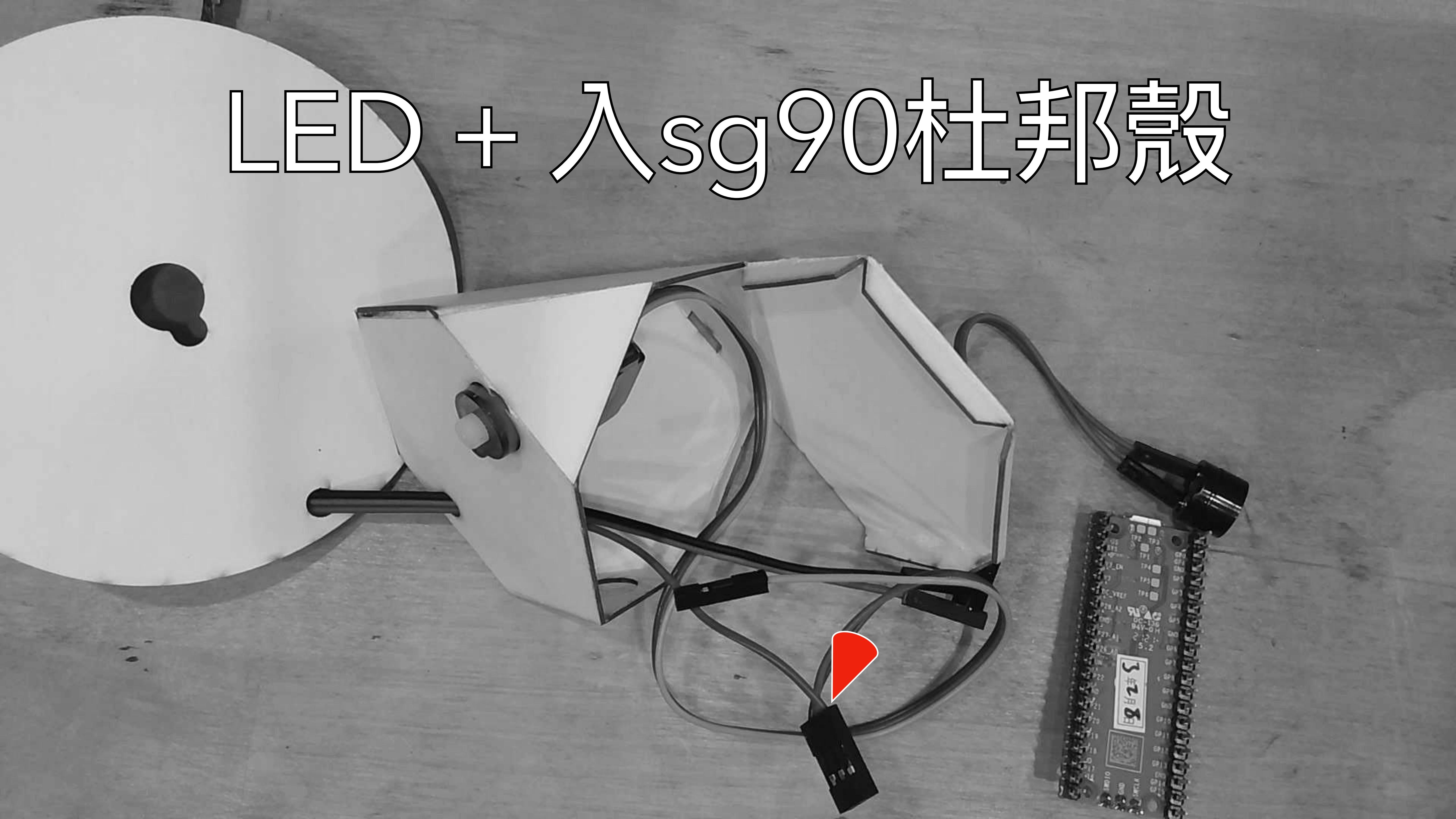


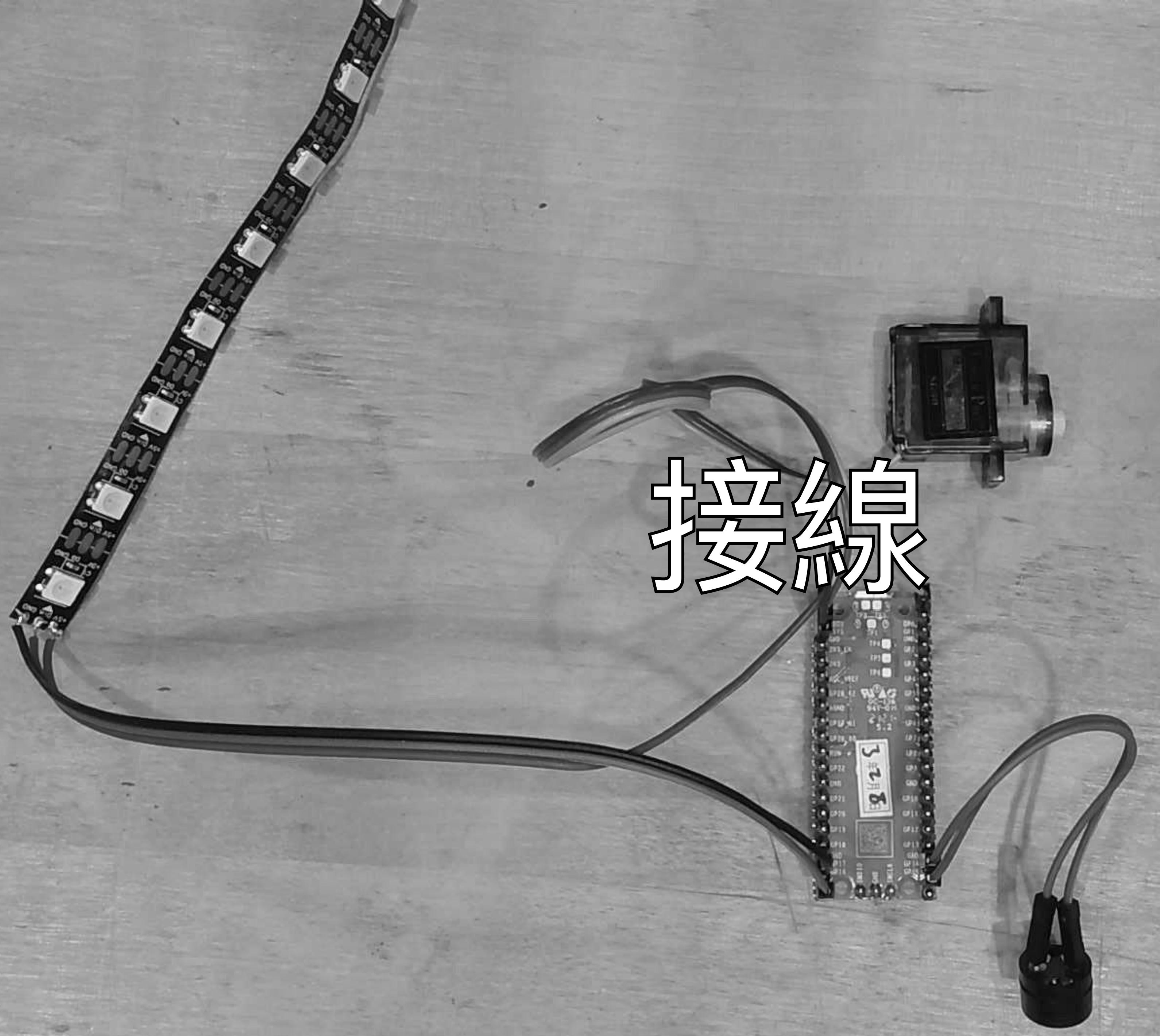
小圓孔に穿過LED線

LED + 入sg90杜邦殼

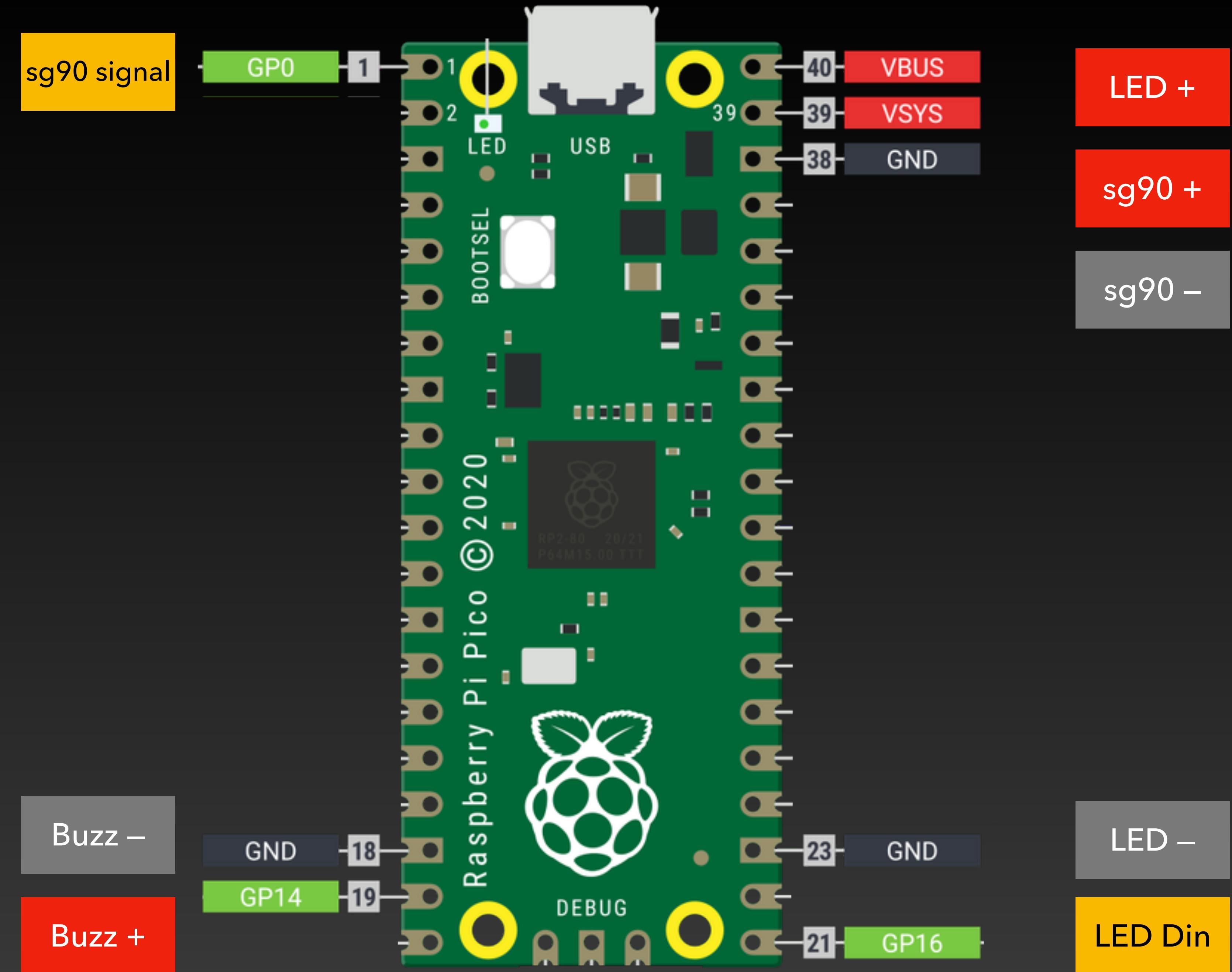


LED + 入sg90杜邦殼





接線



LED +

sg90 +

sg90 -

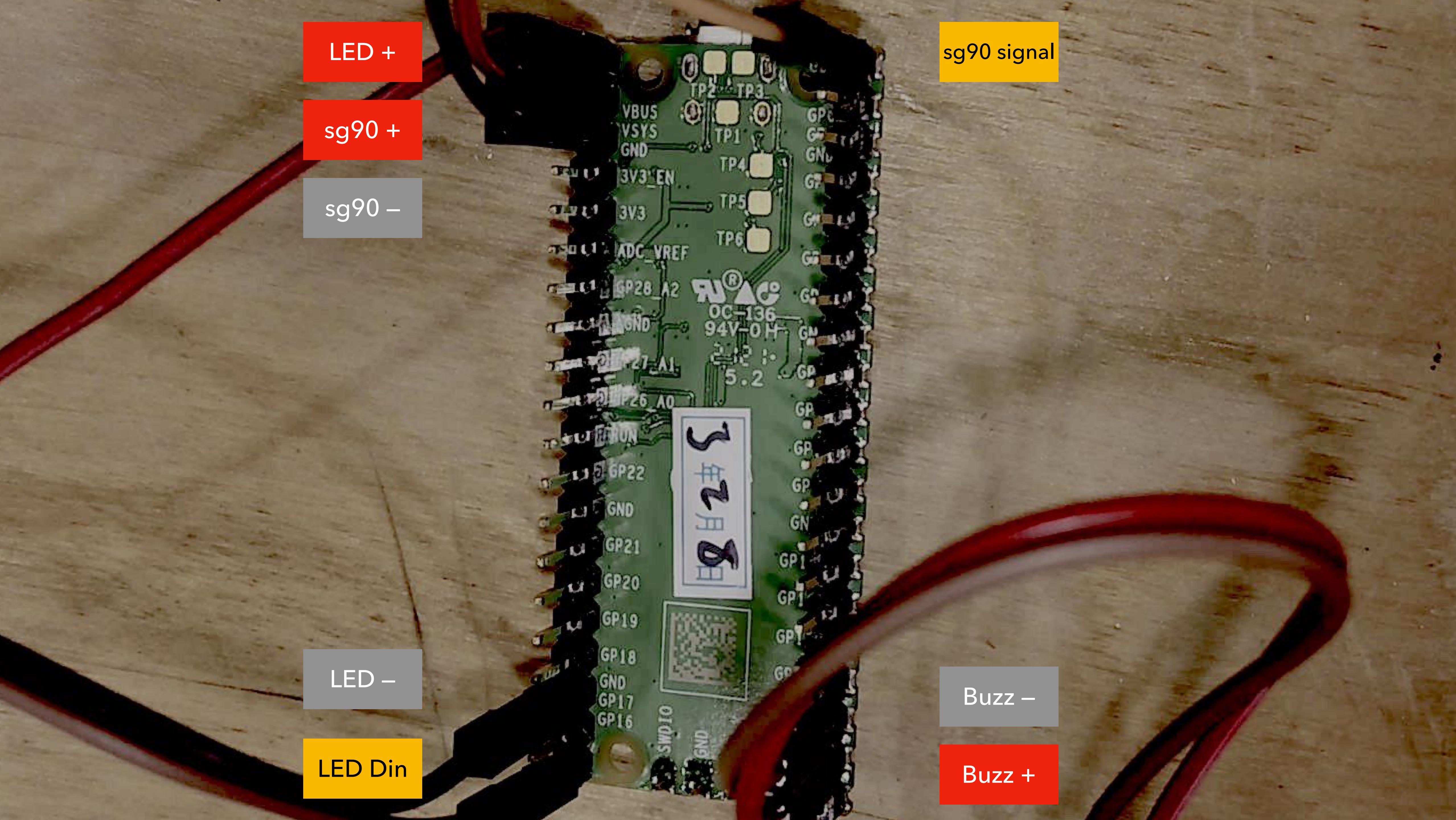
LED -

LED Din

sg90 signal

Buzz -

Buzz +



# LED +

# sg90 +

sg90 -

**LED -**

# LED Din

# sg90 signal

Buzz —

# Buzz +

整線

USB孔朝後下

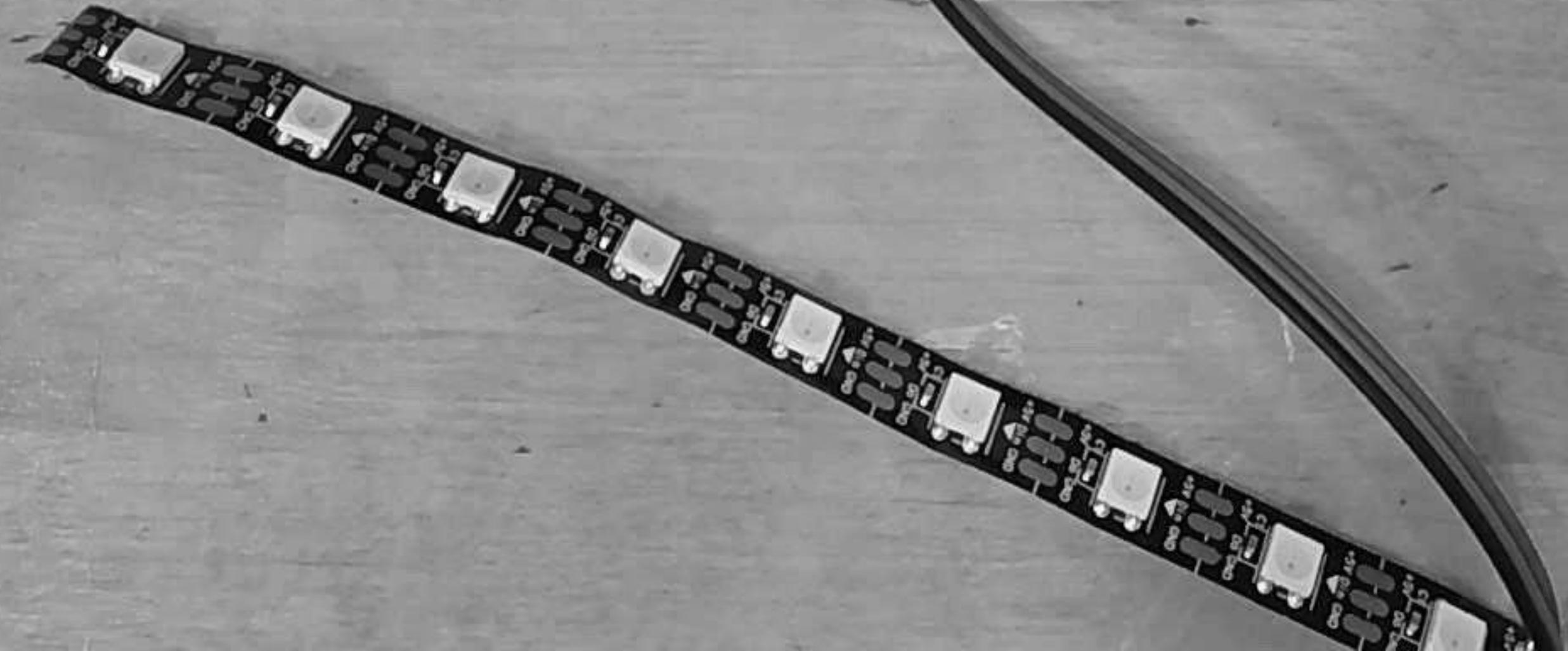


Buzz 入門

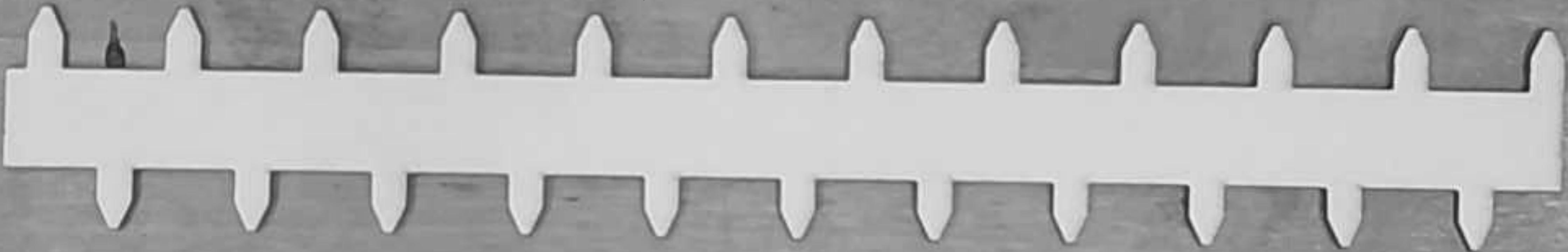
USB孔對齊



準備固定燈條



齒條朝向向折彎



折繪

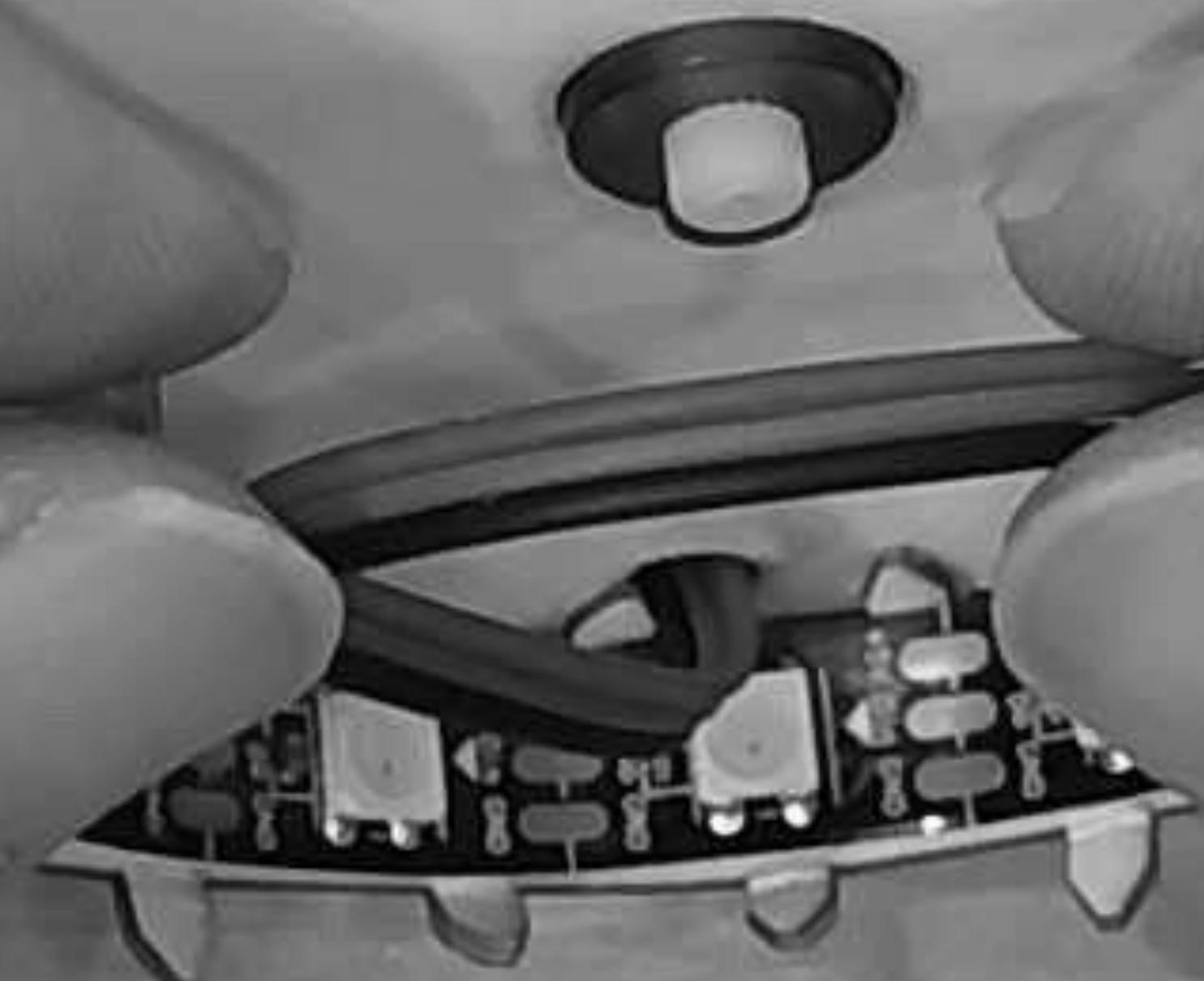




點膠貼合

置中對齊下緣

燈條置中貼齊齒條



燈條置中貼齊齒條



整線



絕緣膠帶



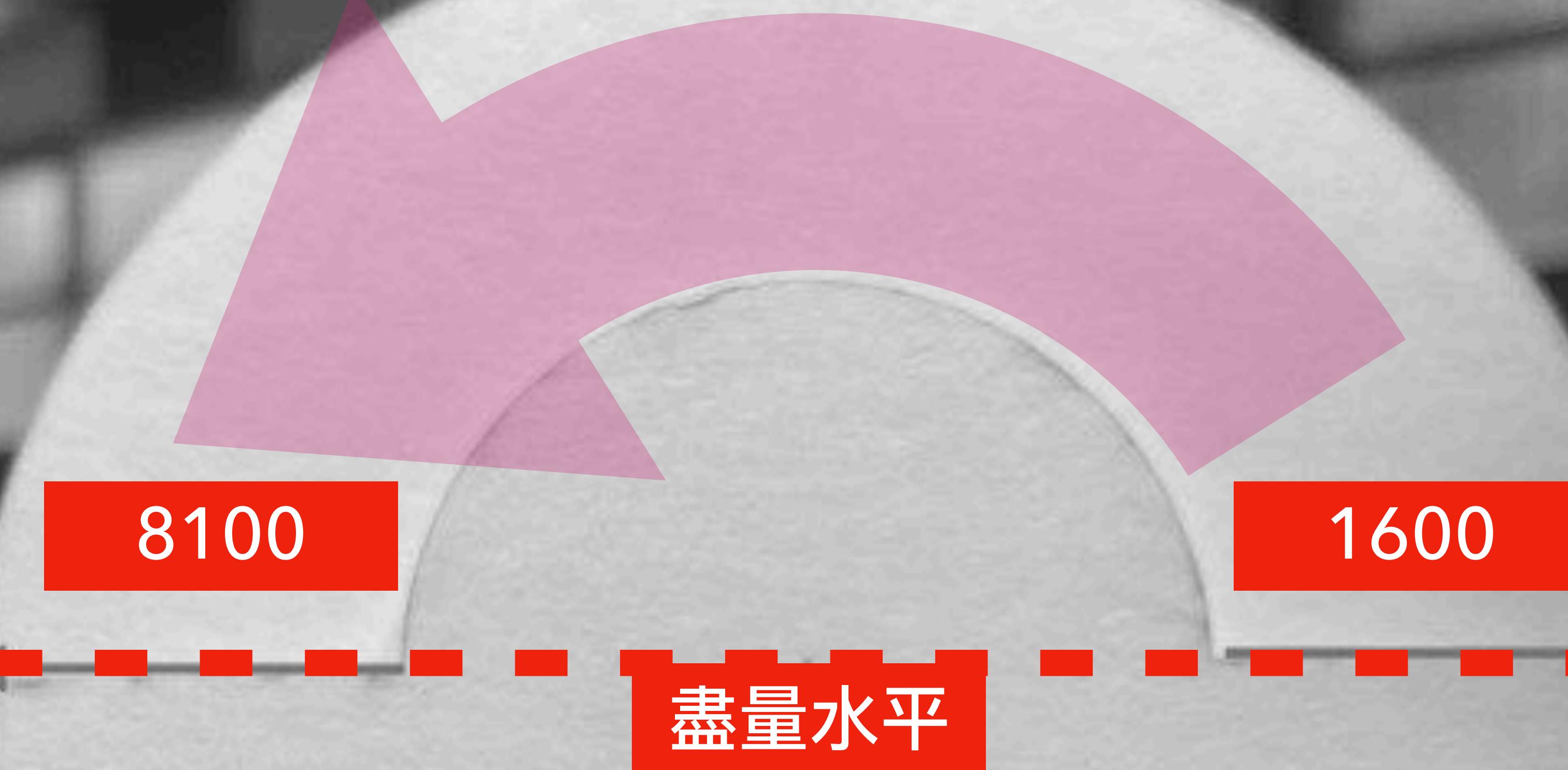
sg90配件水平貼於中央



黑點置中定位



輕輕扣上



# 調整馬達數值

確認角度後用力扣上



貼上護蓋  
完成



▷ media  
  00.py  
  01\_led1.py  
  02\_led0.py  
  03\_ledBlink.py  
  04\_ws2812.py  
  05\_chasingStripe.py  
  06\_breathStripe.py  
  07\_buzzerScale.py  
  08\_buzzerScaleFor.py  
  09\_buzzerFre.py  
  10\_beep.py  
  11\_sg90.py  
  12\_sg90While.py  
  13\_sg90End.py  
  14\_micropython-p

# 另存新檔

Raspberry Pi Pico

00.py  
01.p

# RASPBERRY PI PICO

存檔位置？

本機

Raspberry Pi Pico

互動環境 ×

MicroPython v1.25.0 on 2025-04-15; Raspberry Pi Pico with RP2040  
Type "help()" for more information.

另存 main.py

通電即執行