Overview of the Brain for the robot

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1 Robot Brain

The robot brain is the main class managing all the components of the robot. The main cycle of the robot is inside this class.

2 Learning Algorithms

There is a general interface that is for every learning algorithm. It consists of

• next_evaluation()

2.1 RLPowerAlgorithm

The RLPowerAlgorithm is an implementation of the Learning Algorithm. It stands for $Reinfoced\ Learning\ Power\ Algorithm$.

Here is an example on how it works:

3 Controllers

This is interpreting the output of the learning algorithm and sending the signals to the servos.

4 Servos

This is taking the control input for the servo and sending it to the hardware.