

Modelling and Optimisation with Graphs

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Constraint Programming

- A declarative way of specifying (hard) problems.
- Variables, each with a domain of possible values.
 - Finite, usually integers or booleans.
 - Arrays and sets of integers also supported, either directly or indirectly.
 - Some solvers do floating point.
- Constraints.
 - No requirements of linearity, convexity, etc.
 - Rich global constraints, e.g. all different, regular, circuit.
- An objective.
 - Assign each variable a value from its domain, respecting all constraints.
 - Decide, enumerate, minimise a variable, or maximise a variable.
 - Can also produce Pareto fronts.

Solvers

- Dedicated constraint programming solvers:
 - Gecode, Minion, Choco, OR-Tools, ...
 - Combine inference and intelligent backtracking search.
- Specialised solvers for more restricted settings:
 - SAT (boolean variables and constraints).
 - MIP (integer and real variables, linear inequalities).
 - Lots more...
- Or local search, which loses any guarantees of completeness.

High Level Modelling with Essence and Conjure

<http://conjure.readthedocs.io/en/latest/>

- Developed at St Andrews and York.
- Supports rich and nested structural types, such as sets of functions from sets of sets to partitions of matrices.
- Extensive automated reformulation.
- Targets CP, MIP, SAT, local search solvers.

Magic Squares

CLASS. VII. MATHEMATICA HIEROGLYPH. 47 CAP.IV.

Sigillum Iouis.

Sed procedamus ad secundi quadrati Schematismum, sive *Sigillum Iouis*, quod ex quaternario in se ducto emergit, estque 16: cuius dispositio talis est, ut singuli numerorum ordines, normales sive perpendiculares, transuersi, diagonales sive diametrales, vti & quadratulorum medium circumstantium numeri simul iuncti, semper eundem numerum restituant, videlicet 34, summa vero omnium sit 136. *Sigillum* sequitur vna cum additione numerorum.

Sigillum Iouis.

4	14	15	1
9	7	6	12
5	11	10	8
16	2	3	13

Additio perpendiculare.

4	14	15	1
9	7	6	12
5	11	10	8
16	2	3	13

Transuersalis.

4	9	5	16
14	7	11	2
15	6	10	3
1	12	8	13

Diagonalis.

1	4
6	7
11	10
16	13

Page 47 of the second part of Vol. II of Athanasius Kircher's "Oedipus Aegyptiacus", published 1653. Scan by Feldkurat Katz. Public domain.

Magic Squares

```
given n : int(1..)
```

```
letting Index be domain int(1..n),  
    Value be domain int(1..n**2)
```

```
find square : matrix indexed by [Index,Index] of Value,  
    s : int(1..sum i : int(n**2+1-n..n**2) . i)
```

such that

```
allDiff(flatten(square)),  
forAll r : Index . (sum c : Index . square[r,c]) = s,  
forAll c : Index . (sum r : Index . square[r,c]) = s,  
(sum d : Index . square[d,d]) = s,  
(sum d : Index . square[d,n+1-d]) = s
```

Magic Squares

```
$ echo "letting n be 4" > magic.param
$ ./conjure solve magic.essence magic.param
$ tail magic-magic.solution
1 2 15 16
12 14 3 5
13 7 10 4
8 11 6 9
```

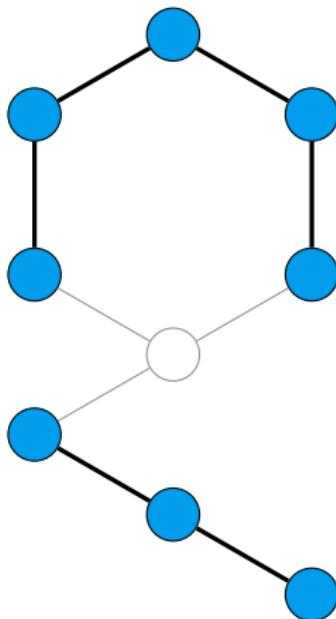
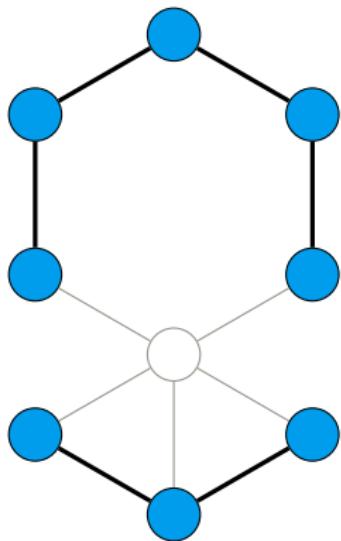
What About Graphs?

- How are they represented? Adjacency lists? Adjacency matrix?
- Some of the graphs we'd like to deal with are quite big.
- Expressing certain constraints (e.g. connectivity) by hand is difficult and heavily representation-dependent.
- It's very easy to end up with an $O(|V|^3)$ or $O(|V|^4)$ in the encoding size...

Modelling and Optimisation with Graphs

- Three year project led by Glasgow, together with St Andrews and Edinburgh.
- Working:
 - High level modelling for graphs, in Essence.
 - Better dedicated graph solvers.
- Ongoing:
 - Better compilation and reformulation.
 - Hybrid solving strategies.

Graphs by Example: Maximum Common Subgraphs



Graphs by Example: Maximum Common Subgraphs

- Finding the difference between two graphs comes down to finding as large a graph as possible that they both have in common. This is known as the *maximum common induced subgraph problem*.
- This concept generalises to n graphs.
- Application in metabolomics: we're given approximate molecular weights for the constituents of some compound, and we want to identify what the molecules are from a database. Sets of molecules with high similarities are much more likely to occur than unrelated molecules.

Graphs by Example: Maximum Common Subgraphs

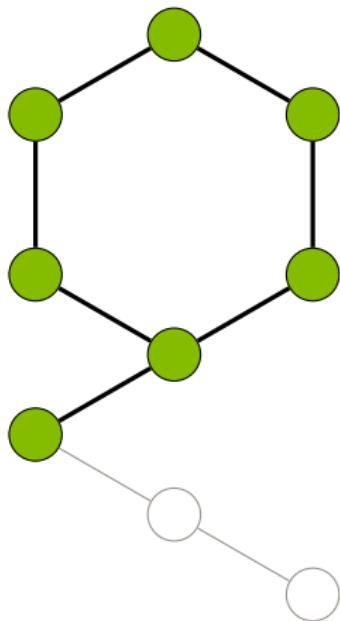
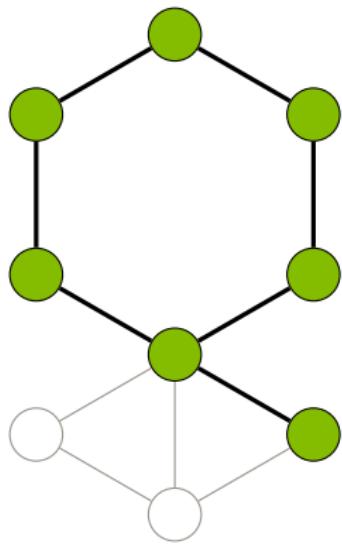
```
given n : int
given t : int
given G : matrix indexed by [int(1..t)] of
    graph of int(1..n)

find z : graph of int(1..n)
find F : matrix indexed by [int(1..t)] of
    function int(1..n) --> int(1..n)

such that forAll i : int(1..t) .
    subisomorphismInduced(z, G[i], F[i])

maximising |vertices(z)|
```

Graphs by Example: Maximum Common Subgraphs



Graphs by Example: Diseased Cows

- We have a graph of contacts (trade, or adjacent farms) between cattle in Scotland.
- If a disease outbreak occurs, we want to limit its spread.
- Can we vaccinate or screen on a small number of trade and contact routes?
- This comes down to deleting edges from a graph, to avoid having any large components.

Graphs by Example: Diseased Cows

```
given n : int
given k : int
given g : graph of int(1..n)

find deletions : set of (int(1..n), int(1..n))
find h       : graph of int(1..n)

such that h subgraph g
such that edges(h) = edges(g) - deletions
such that all[ |cc| < k | cc <- connectedComponents(h) ]

minimising |deletions|
```

Graphs by Example: Kidney Exchange

- If two people both need kidney transplants, and have willing but incompatible donors, then they can exchange donors.
- Also, we can do this with cycles of three people.
- Also, we might have altruistic donors.
- Potential exchanges show up as 2-cycles, 3-cycles, etc in a graph.
- Given a set of pattern graphs, try to cover as much of the exchange graph as possible, not using any vertex more than once.

Graphs by Example: Kidney Exchange

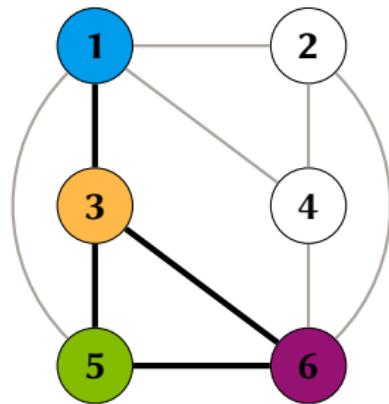
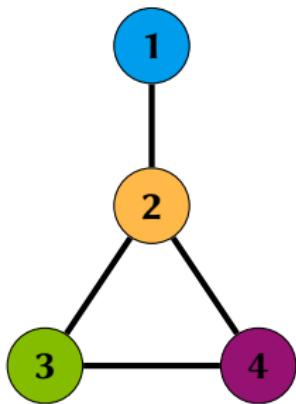
```
given np          : int
given max_pat_sz : int
given patterns   : matrix indexed by [int(1..np)] of
                    graph of int(1..max_pat_sz)
given benefit    : matrix indexed by [int(1..np)] of int
given tgt_sz     : int
given target     : graph of int(1..tgt_sz)
find map         : set of (int(1..np), function
                    int(1..max_pat_sz) --> int(1..tgt_sz))
such that forAll (i, f) in map .
    subisomorphism(patterns[i], target, f)
such that forAll {(i1,f1), (i2,f2)} subsetEq map .
    range(f1) intersect range(f2) = {}
maximising sum([benefit[i] | (i, f) <- map])
```

Unfortunately...

- Often orders of magnitude slower than dedicated solvers.
- Can only handle small graphs.

The Glasgow Subgraph Solver

<https://github.com/ciaranm/glasgow-subgraph-solver>



The Glasgow Subgraph Solver

<https://github.com/ciaranm/glasgow-subgraph-solver>

- The bestest subgraph isomorphism solver in the whole wide world.
- Support for non-induced subgraph isomorphism, induced subgraph isomorphism, graph homomorphisms, locally injective graph homomorphisms, clique.
- A bit like a constraint programming solver, but with specialised algorithms, data structures, and search strategies.

Unfortunately...

- It only supports subgraph finding, and basic labelling on vertices and edges.
- I *really* don't want to have to start implementing dozens of new constraints for it.
- Although it's theoretically possible to reduce non-subgraph constraints to clique, the encoding is huge and loses lots of helpful information.
 - (Exceptions apply, and this *can* be a really good idea occasionally.)
- For graph generation problems, we probably want to use another different solver.

Why Not Both?

- We could use a graph solver for graphy things, and a constraint programming solver for rich constraints.
- This can go in at least two ways:
 - Let a graph solver use a constraint programming solver to check a few side constraints. Useful for “find me a subgraph isomorphism that uses no more than three red vertices and at least two blue vertices”.
 - Use graph solvers to (dynamically?) generate parts of a constraint or MIP model. This is the state of the art for kidney exchange.
- The high level modelling suite of tools should take care of all of this for us.

The Easy Part

- The subgraph solver can output partial or full candidate assignments, or reduced domains.
- The constraint solver can treat these as additional constraints to a model.
 - Output one of “yes”, or “no because ...”.
 - Better: have an option for an “I can’t easily tell, but I do know that ...” mode.
 - Fortunately, this is minimal effort in most constraint solvers.
- Three line shell script to glue the two together.

The Hard Part

- Which bits go where?

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