Data Mining and Machine Learning Bioinspired computational methods Biological data mining

Data Prepocessing

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Chapter 3: Data Preprocessing

Data Preprocessing: An Overview



- Data Quality
- Major Tasks in Data Preprocessing
- Data Cleaning
- Data Integration
- Data Reduction
- Data Transformation and Data Discretization
- Summary

Data Quality: Why Preprocess the Data?

- Measures for data quality: A multidimensional view
 - Accuracy: correct or wrong, accurate or not
 - Completeness: not recorded, unavailable, ...
 - Consistency: some modified but some not, dangling, ...
 - Timeliness: timely update?
 - Believability: how trustable the data are correct?
 - Interpretability: how easily the data can be understood?

Data cleaning

 Fill in missing values, smooth noisy data, identify or remove outliers, and resolve inconsistencies

Data integration

- Integration of multiple databases, data cubes, or files
- Problems
 - for instance, the attribute for customer identification could be identified as cust_id in one data base and customer_id in another;
 - the same name could be registered as Bill in one database and William in another.
- At the end of data integration, a new data cleaning pre-process can be needed for removing redundancies.

Data reduction

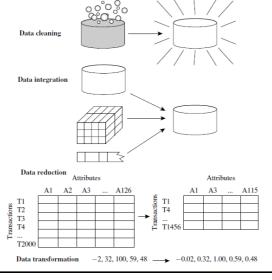
- Is there any way to reduce the size of data set without jeopardizing the data mining results?
- Dimensionality reduction: data encoding schemes are applied to obtain a compressed representation of the original data
 - Compression techniques
 - Attribute subset selection
 - Attribute construction
- Numerosity reduction: smaller representations using parametric models (regression models) or nonparametric models (cluster, sampling, ecc.)

Data transformation and data discretization

- Normalization
- Concept hierarchy generation

Data transformation and data discretization

- Normalization: scaled to a smaller range such as [0.0, 1.0]
 - Let us consider age and annual salary: in the computation of the distance the distance measurements taken on annual salary will outweigh distance measurements taken on age.
- Concept hierarchy generation
 - Raw values are replaced by higher-level concepts (youth, adult or senior)
 - Data mining at different levels of abstraction



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Data Cleaning

- Data in the Real World is Dirty: Lots of potentially incorrect data,
 e.g., instrument faulty, human or computer error, transmission error
 - incomplete: lacking attribute values, lacking certain attributes of interest, or containing only aggregate data
 - e.g., *Occupation*=" " (missing data)
 - noisy: containing noise, errors, or outliers
 - e.g., *Salary*="-10" (an error)
 - inconsistent: containing discrepancies in codes or names, e.g.,
 - Age="42", Birthday="03/07/2010"
 - Was rating "1, 2, 3", now rating "A, B, C"
 - discrepancy between duplicate records
 - <u>Intentional</u> (e.g., disguised missing data)
 - Jan. 1 as everyone's birthday?

Incomplete (Missing) Data

- Data is not always available
 - E.g., many tuples have no recorded value for several attributes, such as customer income in sales data
- Missing data may be due to
 - equipment malfunction
 - inconsistent with other recorded data and thus deleted
 - data not entered due to misunderstanding
 - certain data may not be considered important at the time of entry
 - not register history or changes of the data
- Missing data may need to be inferred

.0

How to Handle Missing Data?

- Ignore the tuple: usually done when class label is missing (when doing classification)—not effective when the % of missing values per attribute varies considerably
- Fill in the missing value manually: tedious + infeasible?
- Fill in it automatically with
 - a global constant: e.g., "unknown", a new class?!
 - the attribute mean
 - the attribute mean for all samples belonging to the same class: smarter
 - **the most probable value**: inference-based such as Bayesian formula or decision tree

Noisy Data

- Noise: random error or variance in a measured variable
- Incorrect attribute values may be due to
 - faulty data collection instruments
 - data entry problems
 - data transmission problems
 - technology limitation
 - inconsistency in naming convention
- Other data problems which require data cleaning
 - duplicate records
 - incomplete data
 - inconsistent data

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How to Handle Noisy Data?

- In many applications of ambient intelligence, the true signal amplitudes (y-axis values) change rather smoothly as a function of the x-axis values, whereas many kinds of noise are seen as rapid, random changes in amplitude from point to point within the signal.
- The noise can be reduced by a process called smoothing.
- Smoothing: the data points of a signal are modified so that individual points that are higher than the immediately adjacent points (presumably because of noise) are reduced, and points that are lower than the adjacent points are increased.
- This naturally leads to a smoother signal.

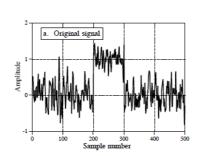
Rectangular or unweighted sliding-average smooth

- The simplest smoothing algorithm
- It simply replaces each point in the signal with the average of m adjacent points, where m is a positive integer called the smooth width. For example, for a 3point smooth (m = 3):

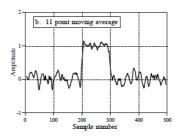
$$S_{j} = \frac{Y_{j-1} + Y_{j} + Y_{j+1}}{3}$$

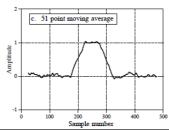
for j = 2 to n-1, where S_j the j^{th} point in the smoothed signal, Y_j the j^{th} point in the original signal, and n is the total number of points in the signal.

Rectangular or unweighted sliding-average smooth



Filtered with 11 and 51 point moving average filters





Rectangular or unweighted sliding-average smooth

- If the underlying function is constant, or is changing linearly with time (increasing or decreasing), then no bias is introduced into the result.
- A bias is introduced, however, if the underlying function has a nonzero second derivative. At a local maximum, for example, moving window averaging always reduces the function value.

Triangular smooth

 Implements a weighted smoothing function. For example, for a 5-point smooth (m = 5):

$$S_{j} = \frac{Y_{j-2} + 2Y_{j-1} + 3Y_{j} + 2Y_{j+1} + Y_{j+2}}{q}$$

for j=3 to n-2. This smooth is more effective at reducing high-frequency noise in the signal than the simpler rectangular smooth.

- The 5-point triangular smooth above is equivalent to two passes of a 3-point rectangular smooth
- The width of the smooth m is an odd integer and the smooth coefficients are symmetrically balanced around the central point, which is important point because it preserves the xaxis position of peaks and other features in the signal.

The Savitzky-Golay Smoothing Filters

 In general, the simplest type of digital filter (the nonrecursive or finite impulse response filter) replaces each data value Y_j by a linear combination S_i of itself and some number of nearby neighbors

$$S_j = \sum_{n=-n_L}^{n_R} c_n Y_{j+n}$$

where n_L is the number of points used "to the left" of a data point i, i.e., earlier than it, while n_R is the number used to the right, i.e., later.

The Savitzky-Golay Smoothing Filters

In the unweighted sliding-average smooth

$$c_n = \frac{1}{(n_L + n_R + 1)}$$

where n_L is the number of points used "to the left" of a data point i, i.e., earlier than it, while n_R is the number used to the right, i.e., later.

The Savitzky-Golay Smoothing Filters

- The idea of Savitzky-Golay filtering is to find filter coefficients c_n that preserve higher moments. Equivalently, the idea is to approximate the underlying function within the moving window not by a constant (whose estimate is the average), but by a polynomial of higher order, typically quadratic or quartic.
- For each point Y_i, we least-squares fit a polynomial to all n_L +n_R + 1 points in the moving window, and then set S_i to be the value of that polynomial at position i.

The Savitzky-Golay Smoothing Filters

- All these least-squares fits would be laborious if done as described.
- Luckily, since the process of least-squares fitting involves only a linear matrix inversion, the coefficients of a fitted polynomial are themselves linear in the values of the data.
- Thus, we can do all the fitting in advance, for fictitious data consisting of all zeros except for a single 1, and then do the fits on the real data just by taking linear combinations.

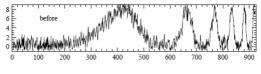
The Savitzky-Golay Smoothing Filters

Some example

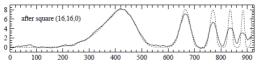
| M | n_L | n_R | Sample Savitzky-Golay Coefficients | | | | | | | | | | |
|---|-------|-------|------------------------------------|--------|--------|--------|-------|-------|-------|--------|--------|--------|--------|
| 2 | 2 | 2 | | | | -0.086 | 0.343 | 0.486 | 0.343 | -0.086 | | | |
| 2 | 3 | 1 | | | -0.143 | 0.171 | 0.343 | 0.371 | 0.257 | | | | |
| 2 | 4 | 0 | | 0.086 | -0.143 | -0.086 | 0.257 | 0.886 | | | | | |
| 2 | 5 | 5 | -0.084 | 0.021 | 0.103 | 0.161 | 0.196 | 0.207 | 0.196 | 0.161 | 0.103 | 0.021 | -0.084 |
| 4 | 4 | 4 | | 0.035 | -0.128 | 0.070 | 0.315 | 0.417 | 0.315 | 0.070 | -0.128 | 0.035 | |
| 4 | 5 | 5 | 0.042 | -0.105 | -0.023 | 0.140 | 0.280 | 0.333 | 0.280 | 0.140 | -0.023 | -0.105 | 0.042 |

The Savitzky-Golay Smoothing Filters

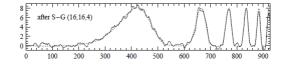
Some example



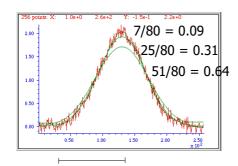
Sliding-average smooth with window of 33 points



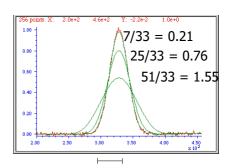
Savitzky-Golay of degree 4 with window of 33 points



- The larger the smooth width, the greater the noise reduction, but also the greater the possibility that the signal will be distorted by the smoothing operation.
- The optimum choice of smooth width depends upon the width and shape of the signal and the digitization interval.
- For peak-type signals, the critical factor is the smoothing ratio, the ratio between the smooth width and the number of points in the half-width of the peak. In general, increasing the smoothing ratio improves the signal-to-noise ratio but causes a reduction in amplitude and an increase in the bandwidth of the peak.



half-width of the peak 80 pts



half-width of the peak 33 pts

Optimization of smoothing

- If the objective of the measurement is to measure the true peak height and width, then smooth ratios below 0.2 should be used.
- If the objective of the measurement is to measure the peak position (x-axis value of the peak), much larger smoothing ratios can be employed if desired, because smoothing has no effect at all on the peak position (unless the increase in peak width is so much that it causes adjacent peaks to overlap).

When should you smooth a signal?

- for cosmetic reasons, to prepare a nicer-looking graphic of a signal for visual inspection or publication;
- 2. if the signal will be subsequently processed by an algorithm that would be adversely affected by the presence of too much high-frequency noise in the signal, for example if the location of maxima, minima, or inflection points in the signal is to be automatically determined by detecting zero-crossings in derivatives of the signal.

When should NOT you smooth a signal?

- 1. Prior to statistical procedures such as least-squares curve fitting, because:
 - (a) smoothing will not significantly improve the accuracy of parameter measurement by least-squares measurements between separate independent signal samples;
 - (b) all smoothing algorithms are at least slightly "lossy", entailing some change in signal shape and amplitude,
 - (c) it is harder to evaluate the fit by inspecting the residuals if the data are smoothed, because smoothed noise may be mistaken for an actual signal, and
 - (d) smoothing the signal will seriously **underestimate the parameters errors** predicted by propagation-of-error calculations and the bootstrap method.

How to Handle Noisy Data?

- Binning: smooth a sorted data value by consulting its neighborhood
 - first sort data and partition into (equal-frequency) bins
 - then one can smooth by bin means, smooth by bin median, smooth by bin boundaries, etc.

Sorted data for price (in dollars): 4, 8, 15, 21, 21, 24, 25, 28, 34

Partition into (equal-frequency) bins:

Bin 1: 4, 8, 15 Bin 2: 21, 21, 24 Bin 3: 25, 28, 34

Smoothing by bin means:

Bin 1: 9, 9, 9 Bin 2: 22, 22, 22 Bin 3: 29, 29, 29

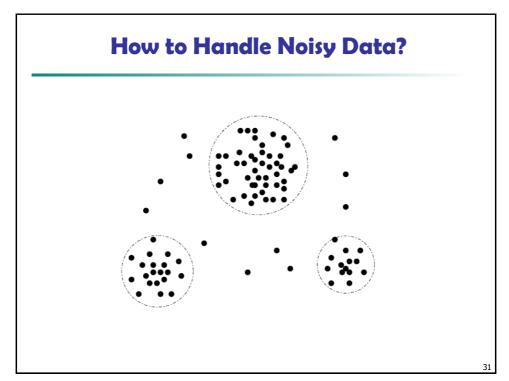
Smoothing by bin boundaries:

Bin 1: 4, 4, 15 Bin 2: 21, 21, 24 Bin 3: 25, 25, 34

How to Handle Noisy Data?

- Regression
 - smooth by fitting the data into regression functions
 - Linear regression (two attributes)
 - Multiple linear regression (multiple attributes)
- Clustering
 - detect and remove outliers
- Combined computer and human inspection
 - detect suspicious values and check by human (e.g., deal with possible outliers)

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Data Integration

Data integration:

- Combines data from multiple sources into a coherent store
- Schema integration: e.g., A.cust-id ≡ B.cust-#
 - Integrate metadata from different sources
- Entity identification problem:
 - Identify real world entities from multiple data sources, e.g., Bill
 Clinton = William Clinton
- Detecting and resolving data value conflicts
 - For the same real world entity, attribute values from different sources are different
 - Possible reasons: different representations, different scales, e.g., metric vs. British units

Handling Redundancy in Data Integration

- Redundant data occur often when integration of multiple databases
 - Object identification: The same attribute or object may have different names in different databases
 - Derivable data: One attribute may be a "derived" attribute in another table, e.g., annual revenue
- Redundant attributes may be able to be detected by correlation analysis and covariance analysis
- Careful integration of the data from multiple sources may help reduce/avoid redundancies and inconsistencies and improve mining speed and quality

Correlation Analysis (Nominal Data)

- X² (chi-square) test: The chi-square independence test is a procedure for testing if two categorical variables A and B are related in some population.
- Suppose:
 - $A = \{a_1, ..., a_c\}$
 - B= $\{b_1,...,b_r\}$
- The data tuples can be represented by a contingency table

| | b ₁ | b ₂ | b _r | |
|-----------------------|-----------------------|------------------|--------------------|------------------|
| a ₁ | O _{1,1} | 0 _{1,2} | O _{1,c} | O _{1,.} |
| a ₂ | 0 _{2,1} | 0 _{2,2} | O _{2,c} | O _{2,.} |
| | | | | |
| a _c | O _{r,1} | O _{r,2} | O _{r,c} | O _{r,.} |
| | 0.,1 | 0,,2 | O _{.,r} | Tot |

Correlation Analysis (Nominal Data)

X² (chi-square) test:

$$\chi^2 = \sum \frac{(Observed - Expected)^2}{Expected}$$

- The larger the X² value, the more likely the variables are related
- The cells that contribute the most to the X² value are those whose actual count is very different from the expected count

$$\chi^2 = \sum_{i=1}^c \sum_{i=1}^r \frac{(o_{ij} - e_{ij})^2}{e_{ij}} \qquad e_{ij} = \frac{count(A = a_i) \times count(B = b_j)}{n}$$

Chi-Square Calculation: An Example

| ding | | Play chess | Not play chess | Sum (row) |
|----------|--------------------------|------------|----------------|-----------|
| reading | Like science fiction | 250(90) | 200(360) | 450 |
| referred | Not like science fiction | 50(210) | 1000(840) | 1050 |
| refe | Sum(col.) | 300 | 1200 | 1500 |
| ο. | | | | |

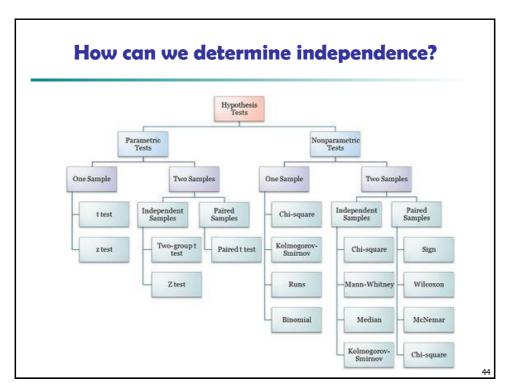
- X² (chi-square) calculation
 - numbers in parenthesis are expected counts calculated based on the data distribution in the two categories

$$e_{ij} = \frac{count(A = a_{i}) \times count(B = b_{j})}{N}$$

$$\chi^{2} = \frac{(250 - 90)^{2}}{90} + \frac{(50 - 210)^{2}}{210} + \frac{(200 - 360)^{2}}{360} + \frac{(1000 - 840)^{2}}{840} = 507.93$$

 It shows that like_science_fiction and play_chess are correlated in the group

- Parametric test: hypothesis test based on the assumption that observed data are distributed according to some distributions of wellknown form (normal, Bernoulli, and so on) up to some unknown parameter on which we want to make inference (say the mean, or the success probability)
- Nonparametric test: hypothesis test where it is not necessary (or not possible) to specify the parametric form of the distribution(s) of the underlying population(s).



- Null Hypothesis (H₀): states that no association exists between the two cross-tabulated variables in the population and therefore the variables are statistically independent.
- Alternative Hypothesis (H₁): proposes that the two variables are related in the population.
- Be Careful: Correlation does not imply causality
 - # of hospitals and # of car-theft in a city are correlated
 - Both are causally linked to the third variable: population

- Degrees of Freedom: are the number of cells in the two-way table of the categorical variables that can vary, given the constraints of the row and column marginal totals. So each "observation" in this case is a frequency in a cell.
- The number of degrees of freedom *df* is equal to df= (r-1) (c-1), where r is the number of rows and c is the number of columns.

Examples:

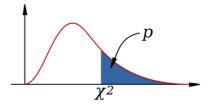
| | Categ | Total | |
|------------|-------|-------|----|
| Category B | ? | | 6 |
| Category | | | 15 |
| Total | 10 | 11 | 21 |

df=1

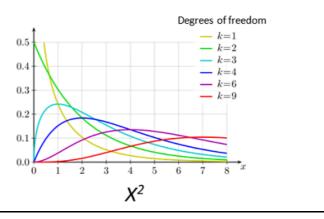
df=2

| | C | Total | | |
|------------|----|-------|---|----|
| Category B | ? | ? | | 15 |
| | | | | 15 |
| Total | 10 | 11 | 9 | 30 |

- The X² distribution is a type of probability distribution.
- Probability distributions provide the probability of every possible value that may occur.
- Distributions that are cumulative give the probability of a random variable being less than or equal to a particular value.
- To find the probability of a particular value, we find the area under the curve before the value. The area that's after the value is called the pvalue



- The X² distribution vary depending on the degrees of freedom and are asymmetric.
- The shape is always skewed right



How can we determine independence? Many statistical analyses involve using the p-value. However, calculating a portion of the area under the curve can be difficult. Alternatively Degrees of freedom 0.8 P-value - k=4 k=5When $X^2 = 5$ and K=4, 0.4 the p-value is app. 0.3 0.2 0.0 X2 = Pearson's cumulative test statistic 50

- It's often more efficient to use a X² table. In this table, each row represents a different degree of freedom along with several X² values.
 The corresponding p-values are listed at the top of each column
- The null hypothesis is rejected when the probability of a larger value of X^2 is lower than the significance level α .

Percentage Points of the Chi-Square Distribution

| Degrees of | | | | Probability | of a larger | value of x ² | | | |
|------------|-------|-------|-------|-------------|-------------|-------------------------|------|-------|-------|
| Freedom | 0.99 | 0.95 | 0.90 | 0.75 | 0.50 | 0.25 | 0.10 | 0.05 | 0.01 |
| 1 | 0.000 | 0.004 | 0.016 | 0.102 | 0.455 | 1.32 | 2.71 | 3.84 | 6.63 |
| 2 | 0.020 | 0.103 | 0.211 | 0.575 | 1.386 | 2.77 | 4.61 | 5.99 | 9.21 |
| 3 | 0.115 | 0.352 | 0.584 | 1.212 | 2.366 | 4.11 | 6.25 | 7.81 | 11.34 |
| 4 | 0.297 | 0.711 | 1.064 | 1.923 | 3.357 | 5.39 | 7.78 | 9.49 | 13.28 |
| 5 | 0.554 | 1.145 | 1.610 | 2.675 | 4.351 | 6.63 | 9.24 | 11.07 | 15.09 |

Chi-Square Calculation: Another Example

 A scientist wants to know if education level and marital status are related for all people in some country. He collects data on a simple random sample of n = 300 people

Marital Status by Education | n = 300

| | Middle school or lower | High school | Bachelor's | Master's | PhD or higher | Total |
|---------------|------------------------|-------------|------------|----------|---------------|-------|
| Never married | 18 | 36 | 21 | 9 | 6 | 90 |
| Married | 12 | 36 | 45 | 36 | 21 | 150 |
| Divorced | 6 | 9 | 9 | 3 | 3 | 30 |
| Widowed | 3 | 9 | 9 | 6 | 3 | 30 |
| Total | 39 | 90 | 84 | 54 | 33 | 300 |

Chi-Square Calculation: Another Example

Expected frequencies

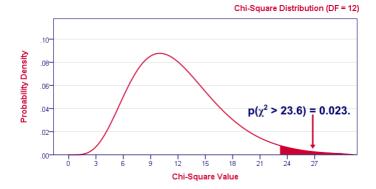
Expected Frequencies for Perfectly Independent Variables

| | Middle school or lower | High school | Bachelor's | Master's | PhD or higher | Total |
|---------------|------------------------|-------------|------------|----------|---------------|-------|
| Never married | 11.7 | 27.0 | 25.2 | 16.2 | 9.9 | 90.0 |
| Married | 19.5 | 45.0 | 42.0 | 27.0 | 16.5 | 150.0 |
| Divorced | 3.9 | 9.0 | 8.4 | 5.4 | 3.3 | 30.0 |
| Widowed | 3.9 | 9.0 | 8.4 | 5.4 | 3.3 | 30.0 |
| Total | 39.0 | 90.0 | 84.0 | 54.0 | 33.0 | 300.0 |

$$\chi^2 = rac{(18-11.7)^2}{11.7} + rac{(36-27)^2}{27} + \ldots + rac{(6-5.4)^2}{5.4} = 23.57$$

Chi-Square Calculation: Another Example

■ DF = 12



Conclusion: marital status and education are related in our population

Correlation Analysis (Numeric Data)

 Correlation coefficient (also called Pearson's product moment coefficient)

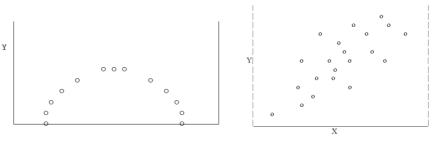
$$r_{A,B} = \frac{\sum_{i=1}^{n} (a_i - \bar{A})(b_i - \bar{B})}{n\sigma_A \sigma_B} = \frac{\sum_{i=1}^{n} (a_i b_i) - n\bar{A}\bar{B}}{n\sigma_A \sigma_B}$$

where n is the number of tuples, \bar{A} and \bar{B} are the respective means of A and B, σ_A and σ_B are the respective standard deviations of A and B, and $\Sigma(a_ib_i)$ is the sum of the AB cross-product.

- If $r_{A,B} > 0$, A and B are positively correlated (A's values increase as B's). The higher, the stronger correlation.
- $r_{A,B} = 0$: independent; $r_{AB} < 0$: negatively correlated

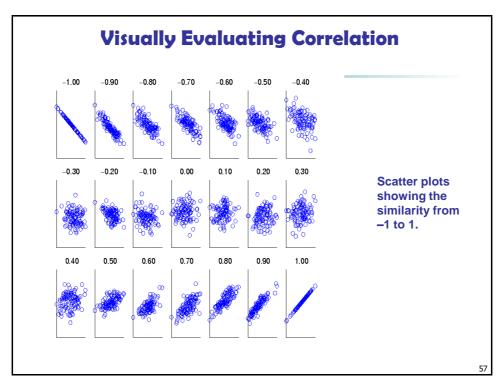
Correlation Analysis (Numeric Data)

 Be careful: The Pearson's product moment coefficient only detects linear relationships



Correlation 0

Correlation 0.8



Correlation (viewed as linear relationship)

- Correlation measures the linear relationship between objects
- To compute correlation, we standardize data objects, A and B, and then take their dot product

$$a'_{k} = (a_{k} - mean(A)) / std(A)$$

$$b'_k = (b_k - mean(B)) / std(B)$$

$$correlation(A, B) = A' \bullet B'$$

Covariance (Numeric Data)

Covariance is similar to correlation

$$Cov(A, B) = E((A - \bar{A})(B - \bar{B})) = \frac{\sum_{i=1}^{n} (a_i - \bar{A})(b_i - \bar{B})}{n}$$

Correlation coefficient:
$$r_{A,B} = \frac{Cov(A,B)}{\sigma_A \sigma_B}$$

where n is the number of tuples, \bar{A} and \bar{B} are the respective mean or **expected values** of A and B, σ_A and σ_B are the respective standard deviation of A and B.

Covariance (Numeric Data)

- Positive covariance: If Cov_{A,B} > 0, then A and B both tend to be larger than their expected values.
- **Negative covariance**: If Cov_{A,B} < 0 then if A is larger than its expected value, B is likely to be smaller than its expected value.
- **Independence**: $Cov_{A,B} = 0$ but the converse is not true:
 - Some pairs of random variables may have a covariance of 0 but are not independent. Only under some additional assumptions (e.g., the data follow multivariate normal distributions) does a covariance of 0 imply independence



Co-Variance: An Example

$$Cov(A, B) = E((A - \bar{A})(B - \bar{B})) = \frac{\sum_{i=1}^{n} (a_i - \bar{A})(b_i - \bar{B})}{n}$$

It can be simplified in computation as

$$Cov(A, B) = E(A \cdot B) - \bar{A}\bar{B}$$

- Suppose two stocks A and B have the following values in one week:
 (2, 5), (3, 8), (5, 10), (4, 11), (6, 14).
- Question: If the stocks are affected by the same industry trends, will their prices rise or fall together?
 - E(A) = (2 + 3 + 5 + 4 + 6)/5 = 20/5 = 4
 - E(B) = (5 + 8 + 10 + 11 + 14) / 5 = 48 / 5 = 9.6
 - $Cov(A,B) = (2 \times 5 + 3 \times 8 + 5 \times 10 + 4 \times 11 + 6 \times 14)/5 4 \times 9.6 = 4$
- Thus, A and B rise together since Cov(A, B) > 0.

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Data Reduction Strategies

- Data reduction: Obtain a reduced representation of the data set that is much smaller in volume but yet produces the same (or almost the same) analytical results
- Why data reduction? A database/data warehouse may store terabytes of data. Complex data analysis may take a very long time to run on the complete data set.
- Data reduction strategies
 - Dimensionality reduction, e.g., remove unimportant attributes
 - Wavelet transforms
 - Principal Components Analysis (PCA)
 - Feature subset selection, feature creation
 - Numerosity reduction (some simply call it: Data Reduction)
 - Regression and Log-Linear Models
 - Histograms, clustering, sampling
 - Data cube aggregation
 - Data compression

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Data Reduction 1: Dimensionality Reduction

Curse of dimensionality

- When dimensionality increases, data becomes increasingly sparse
- Density and distance between points, which is critical to clustering, outlier analysis, becomes less meaningful
- The possible combinations of subspaces will grow exponentially

Dimensionality reduction

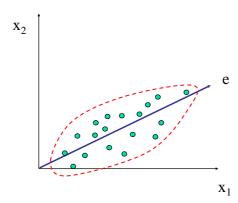
- Avoid the curse of dimensionality
- Help eliminate irrelevant features and reduce noise
- Reduce time and space required in data mining
- Allow easier visualization

Dimensionality reduction techniques

- Wavelet transforms
- Principal Component Analysis
- Supervised and nonlinear techniques (e.g., feature selection)

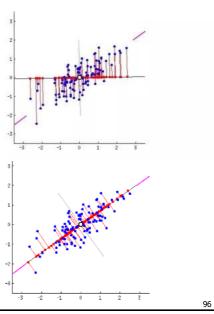
Principal Component Analysis (PCA)

- Find a projection that captures the largest amount of variation in data
- The original data are projected onto a much smaller space, resulting in dimensionality reduction. We find the eigenvectors of the covariance matrix, and these eigenvectors define the new space



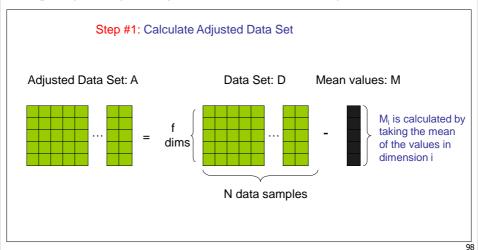
Principal Component Analysis (PCA)

- The projection error is less than in the original dataset
- Newly projected red points are more widely spread out than in the original dataset, i.e. more variance.



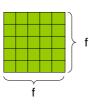
- Given N data vectors from f dimensions, find $k \le f$ orthogonal vectors (*principal components*) that can be best used to represent data
 - Normalize input data: Each attribute falls within the same range
 - Compute *k* orthonormal (unit) vectors, i.e., *principal components*
 - Each input data (vector) is a linear combination of the k principal component vectors
 - The principal components are sorted in order of decreasing "significance" or strength
 - Since the components are sorted, the size of the data can be reduced by eliminating the weak components, i.e., those with low variance (i.e., using the strongest principal components, it is possible to reconstruct a good approximation of the original data)
- Works for numeric data only

• Given N data vectors from f-dimensions, find $k \le f$ orthogonal vectors (*principal components*) that can be best used to represent data



Step #2: Calculate Co-variance matrix, C, from adjusted data set, A Remember: It is a measure of the extent to which corresponding elements from two sets of ordered data move in the same direction.

Co-variance Matrix: C



$$C_{ij} = cov(i,j)$$

COV(X, Y) = $\frac{\sum_{i=1}^{N} (X_i - \bar{X})(Y_i - \bar{Y})}{N - 1}$

Note: Since the means of the dimensions in the adjusted data set, A, are 0, the covariance matrix can simply be written as:

$$C = (A A^{T}) / (n-1)$$

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Example computation Covariance matrix

Suppose that you have a set of N=5 data items, representing 5 people, where each data item has a Height, test Score, and Age (therefore f = 3)

| | S1 | S2 | S3 | S4 | S5 | Mean |
|--------|-----|-----|-----------|-----------|-----|------|
| Height | 64 | 66 | 68 | 69 | 73 | 68 |
| Score | 580 | 570 | 590 | 660 | 600 | 600 |
| Age | 29 | 33 | 37 | 46 | 55 | 40 |

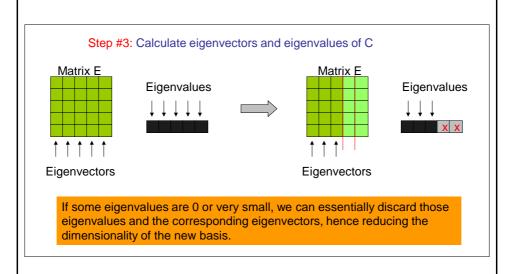
$$\begin{tabular}{ll} Var(Height) = [(64-68.0)^2 + (66-68.0)^2 + (68-68.0)^2 + (63-68.0)^2 + (73-68.0)^2] / (5-1) = (16.0 + 4.0 + 0.0 + 1.0 + 25.0) / 4 = 46.0 / 4 = 11.50. \\ \end{tabular}$$

Example computation Covariance matrix

Covar(Height-Score) = [(64-68.0)*(580-600.0) + (66-68.0)*(570-600.0) + (68-68.0)*(590-600.0) + (69-68.0)*(660-600.0) + (73-68.0)*(600-600.0)] / (5-1) = [80.0 + 60.0 + 0 + 60.0 + 0] / 4 = 200 / 4 = 50.0

| | Height | Score | Age |
|--------|--------|-------|-------|
| Height | 11.5 | 50 | 34.75 |
| Score | 50 | 1250 | 205 |
| Age | 34.75 | 205 | 110 |

.01



Step #4: Transforming data set to the new basis

$$F = E^{T}A$$

where:

- F is the transformed data set
- E^T is the transpose of the E matrix containing the eigenvectors
- A is the adjusted data set

Note that the dimensions of the new dataset, F, are less than the data set A

To recover A from F:

$$(E^{T})^{-1}F = (E^{T})^{-1}E^{T}A$$

 $(E^{T})^{T}F = A$
 $FF = A$

* E is orthogonal, therefore $E^{-1} = E^{T}$

Attribute Subset Selection

 Attribute subset selection: Another way to reduce dimensionality of data

Redundant attributes

- Duplicate much or all of the information contained in one or more other attributes
- E.g., purchase price of a product and the amount of sales tax paid

Irrelevant attributes

- Contain no information that is useful for the data mining task at hand
- E.g., students' ID is often irrelevant to the task of predicting students' GPA (Grade-Point Average)

Heuristic Search in Attribute Selection

- There are 2^d possible attribute combinations of d attributes
- Greedy approaches: make what looks to be the best choice at the time
- Typical heuristic attribute selection methods:
 - Best single attribute under the attribute independence assumption: choose by significance tests
 - Best step-wise feature selection:
 - The best single-attribute is picked first
 - Then next best attribute condition to the first, ...
 - Step-wise attribute elimination:
 - Repeatedly eliminate the worst attribute
 - Best combined attribute selection and elimination
 - Optimal branch and bound:
 - Use attribute elimination and backtracking

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Heuristic Search in Attribute Selection

| Forward selection | Backward elimination | Decision tree induction |
|---|---|---|
| Initial attribute set: {A ₁ , A ₂ , A ₃ , A ₄ , A ₅ , A ₆ } | Initial attribute set: {A ₁ , A ₂ , A ₃ , A ₄ , A ₅ , A ₆ } | Initial attribute set: {A ₁ , A ₂ , A ₃ , A ₄ , A ₅ , A ₆ } |
| Initial reduced set: $\{\}$ $\Rightarrow \{A_1\}$ $\Rightarrow \{A_1, A_4\}$ $\Rightarrow \text{Reduced attribute set:}$ $\{A_1, A_4, A_6\}$ | => {A ₁ , A ₃ , A ₄ , A ₅ , A ₆ } => {A ₁ , A ₄ , A ₅ , A ₆ } => Reduced attribute set: {A ₁ , A ₄ , A ₆ } | A_4 ? A_4 ? A_6 |

Example of Heuristic Approach

Example of heuristic approaches

- Pablo A. Estévez, Michel Tesmer, Claudio A. Perez, and Jacek M. Zurada, "Normalized Mutual Information Feature Selection", IEEE Transactions on neural networks, Vol. 20, N. 2, February 2009.
- Consider two discrete variables X and Y, with alphabets XX and YY, respectively. The mutual information (I) between X and Y with a joint probability mass function p(x,y) and marginal probabilities p(x) and p(y) is defined as follows:

$$I(X,Y) = \sum_{x \in XX} \sum_{y \in YY} p(x,y) \cdot \log \frac{p(x,y)}{p(x)p(y)}$$

 Alphabets XX and YY contain the possible values for X and Y, respectively.

Example of heuristic approach Digression: Information and Entropy

• Suppose we want to encode and transmit a long sequence of symbols from the set {a, c, e, g} drawn randomly according to the following probability distribution D:

| Symbol | а | С | е | g |
|-------------|-----|-----|-----|-----|
| Probability | 1/8 | 1/8 | 1/4 | 1/2 |

- Since there are 4 symbols, one possibility is to use 2 bits per symbol
- In fact, it's possible to use 1.75 bits per symbol, on average Can you see how?

Example of heuristic approach Digression: Information and Entropy

Here's one way:

| Symbol | Encoding |
|--------|----------|
| a | 000 |
| С | 001 |
| е | 01 |
| g | 1 |

- Average number of bits per symbol = $1/8 *3 + 1/8 *3 + 1/4 *2 + \frac{1}{2} *1 = 1.75$
- Information theory: Optimal length code assigns log₂ 1/p = log₂ p bits to a message having probability p

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Example of heuristic approach Digression: Information and Entropy

 Given a distribution D over a finite set, where <p₁, p₂, ..., p_n> are the corresponding probabilities, define the entropy of D by

$$H(D) = -\sum_{i} p_{i} \log_{2} p_{i}$$

For example, the entropy of the distribution we just examined, <1/8, 1/8, 1/4, 1/2, is 1.75 (bits)

Also called information

In general, entropy is higher the closer the distribution is to being uniform

MI has two main properties:

The capacity of measuring any kind of relationship between variables

Its invariance under space transformations (translations, rotations and any transformation that preserve the order of the original elements of the variables)

Feature selection based on MI:

Extremely sensitive to the estimation of the pdfs

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Problem statement

- Given an initial set F with n features, find subset $S \subset F$ with k features that maximizes the MI I(C;S) between the class variable C, and the subset of selected features S.
- Normalized MI between f_i and f_s

$$NI(f_{i}, f_{s}) = \frac{I(f_{i}; f_{s})}{\min\{H(f_{i}), H(f_{s})\}}$$

 The selection criterion used in NMIFS consists in selecting the feature that maximizes the measure G

$$G = I(C, f_i) - \frac{1}{S} \sum_{f_s \in S} NI(f_i; f_s)$$

$$G = I(C, f_i) - \frac{1}{S} \sum_{f_s \in S} NI(f_i; f_s)$$
 where
$$I(C, fi) = \sum_{c \in CC} \sum_{f_i \in FF} p(c, fi) \cdot \log \frac{p(c, fi)}{p(c)p(fi)}$$

Problem statem

The normalization compensates for the features that MI bias toward multivalued features, and C. and the subs restricts its values to the range [0,1]

Normalized MI between t_i and t_s

$$NI(f_i, f_s) = \frac{I(f_i; f_s)}{\min\{H(f_i), H(f_s)\}}$$

The selection criterion used in NMIFS consists in selecting the feature that maximizes the measure G

$$G = I(C, f_i) - \frac{1}{S} \sum_{f_i \in S} NI(f_i; f_s)$$

$$G = I(C, f_i) - \frac{1}{S} \sum_{f_s \in S} NI(f_i; f_s)$$
 where
$$I(C, fi) = \sum_{c \in CC} \sum_{f_i \in FF} p(c, fi) \cdot \log \frac{p(c, fi)}{p(c)p(fi)}$$

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Proble Given tha sul Norma

Adaptive redundancy penalization term, which corresponds to the average normalized MI between the candidate feature and the set of selected features.

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The selection criterion used in NMIFS consists in selecting the feature that maximizes the measure G_{ℓ}

that maximizes the measure
$$G$$

$$G = I(C,fi) - \frac{1}{|S|} \sum_{f_c \in S} NI(fi;fs)$$
 where $I(C,fi) = \sum_{c \in CC} \sum_{f_i \in FF} p(c,fi) \cdot \log \frac{p(c,fi)}{p(c)p(fi)}$

where
$$I(C, fi) = \sum_{c \in CC} \sum_{f_i \in FF} p(c, fi) \cdot \log \frac{p(c, fi)}{p(c)p(fi)}$$

The algorithm

- 1. *Initialization*: Set $F = \{f_i / i = 1,...,N\}$, initial set of N features, and $S = \{\emptyset\}$, empty set.
- 2. Calculate the MI with respect to the classes: calculate $I(f_i; C)$, for each $f_i \in F$.
- 3. Select the first feature: Find $\hat{f}_i = \max_{i=1,\dots,N} \{I(f_i;C)\}$. Set $F \leftarrow F \setminus \{\hat{f}_i\}$; set $S \leftarrow \{\hat{f}_i\}$
- *4. Greedy Selection*: Repeat until |S| = k.
 - a. Calculate the MI between features: Calculate $I(f_i; f_s)$ for all pairs $(f_i; f_s)$, with $f_i \in F$ and $f_s \in S$
 - b. Select next feature: Select feature $f_i \in F$ that maximizes G. Set $F \leftarrow F \setminus \{\widehat{f}_i\}$; set $S \leftarrow \{\widehat{f}_i\}$.
- 5. Output the set S containing the selected features.

Attribute Creation (Feature Generation)

- Create new attributes (features) that can capture the important information in a data set more effectively than the original ones
- Three general methodologies
 - Attribute extraction
 - Domain-specific
 - Mapping data to new space (see: data reduction)
 - E.g., Fourier transformation, wavelet transformation, manifold approaches (not covered)
 - Attribute construction
 - Combining features
 - Data discretization

Data Reduction 2: Numerosity Reduction

- Reduce data volume by choosing alternative, smaller forms of data representation
- Parametric methods (e.g., regression)
 - Assume the data fits some model, estimate model parameters, store only the parameters, and discard the data (except possible outliers)
 - Ex.: linear regression obtain value at a point in m-D space as the product on appropriate marginal subspaces
- Non-parametric methods
 - Do not assume models
 - Major families: histograms, clustering, sampling, ...

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Parametric Data Reduction: Regression Models

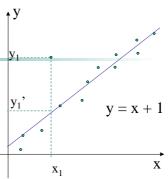
Linear regression

- Data modeled to fit a straight line
- Often uses the least-square method to fit the line

Multiple regression

 Allows a response variable Y to be modeled as a linear function of multidimensional feature vector

- Regression analysis: A collective name for techniques for the modeling and analysis of numerical data consisting of values of a dependent variable (also called response variable or measurement) and of one or more independent variables (aka. explanatory variables or predictors)
- The parameters are estimated so as to give a "best fit" of the data
- Most commonly the best fit is evaluated by using the *least squares method*, but other criteria have also been used



Used for prediction (including forecasting of time-series data), inference, hypothesis testing, and modeling of causal relationships

.20

- Linear regression: $y = w_1 x + w_0$
 - Two regression coefficients, w_1 and w_0 , specify the line and are to be estimated by using the data at hand
 - Using the least squares criterion to the known values of y_1 , y_2 , ..., x_1 , x_2 ,

Size of the dataset
$$w_{1} = \frac{\sum_{i=1}^{|D|} (x_{i} - \overline{x})(y_{i} - \overline{y})}{\sum_{i=1}^{|D|} (x_{i} - \overline{x})^{2}} \qquad w_{0} = \overline{y} - w_{1} \cdot \overline{y}$$

- <u>Linear regression</u>: Example
 - the x_i column shows scores on the aptitude test. Similarly, the y_i column shows statistics grades

| Student | xi | Уi | (x _i -x) | (y _i -y) |
|---------|-----|-----|---------------------|---------------------|
| 1 | 95 | 85 | 17 | 8 |
| 2 | 85 | 95 | 7 | 18 |
| 3 | 80 | 70 | 2 | -7 |
| 4 | 70 | 65 | -8 | -12 |
| 5 | 60 | 70 | -18 | -7 |
| Sum | 390 | 385 | | |
| Mean | 78 | 77 | | |

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- <u>Linear regression</u>: Example
 - Computation of the squares of the deviation scores

| Student | x _i | Уi | $(x_i-x)^2$ | (y _i -y) ² |
|---------|----------------|-----|-------------|----------------------------------|
| 1 | 95 | 85 | 289 | 64 |
| 2 | 85 | 95 | 49 | 324 |
| 3 | 80 | 70 | 4 | 49 |
| 4 | 70 | 65 | 64 | 144 |
| 5 | 60 | 70 | 324 | 49 |
| Sum | 390 | 385 | 730 | 630 |
| Mean | 78 | 77 | | |

- <u>Linear regression</u>: Example
 - Computation of the product of the deviation scores

| Student | Χį | Уi | (x _i -x)(y _i -y) |
|---------|-----|-----|--|
| 1 | 95 | 85 | 136 |
| 2 | 85 | 95 | 126 |
| 3 | 80 | 70 | -14 |
| 4 | 70 | 65 | 96 |
| 5 | 60 | 70 | 126 |
| Sum | 390 | 385 | 470 |
| Mean | 78 | 77 | |

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- <u>Linear regression</u>: Example
 - Computation of w_1 $w_1 = 470/730 = 0.644$
 - Computation of w_0 $w_0 = 77 - 0.644 \cdot 78 = 26.768$
 - Linear regression equation

$$y = 0.644x + 26.768$$

- Multiple linear regression: $y = w_0 + w_1 x_1 + w_2 x_2$
 - Many nonlinear functions can be transformed into the above

$$\mathbf{W} = \left(\mathbf{X}^T \mathbf{X}\right)^{-1} \mathbf{X}^T \mathbf{Y}$$

.26

Non-linear Regression Analysis

- Polynomial regression: $y = w_0 + w_1 x + w_2 x^2 + w_3 x^3$
 - To convert this equation to linear form, we apply the following transformation
 - X₁=X
 - $x_2 = x^2$
 - $x_3 = x^3$

Thus, the equation becomes

$$y = w_0 + w_1 x_1 + w_2 x_2 + w_3 x_3$$

which can be solved by using the methods for multiple regression analysis.

Histogram Analysis

- Divide data into buckets and store average (sum) for each bucket
- Partitioning rules:
 - Equal-width: equal bucket range
 - Equal-frequency (or equal-depth)

Histograms. The following data are a list of *AllElectronics* prices for commonly sold items (rounded to the nearest dollar). The numbers have been sorted: 1, 1, 5, 5, 5, 5, 8, 8, 10, 10, 10, 10, 12, 14, 14, 14, 15, 15, 15, 15, 15, 15, 18, 18, 18, 18, 18, 18, 18, 20, 20, 20, 20, 20, 20, 21, 21, 21, 21, 25, 25, 25, 25, 25, 28, 28, 30, 30, 30.

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Histogram Analysis

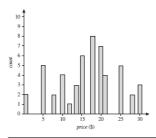


Figure 3.7 A histogram for *price* using singleton buckets—each bucket represents one price-value/ frequency pair.

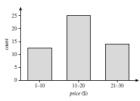


Figure 3.8 An equal-width histogram for price, where values are aggregated so that each bucket has a uniform width of \$10.

Clustering

- Partition data set into clusters based on similarity, and store cluster representation (e.g., centroid and diameter) only
- Can be very effective if data is clustered but not if data is "smeared"
- Can have hierarchical clustering and be stored in multidimensional index tree structures
- There are many choices of clustering definitions and clustering algorithms
- Cluster analysis will be studied in depth in the following

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Sampling

- Sampling: obtaining a small sample s to represent the whole data set N
- Allow a mining algorithm to run in complexity that is potentially sub-linear to the size of the data
- **Key principle**: Choose a representative subset of the data
 - Simple random sampling may have very poor performance in the presence of skew
 - Develop adaptive sampling methods, e.g., stratified sampling
- Note: Sampling may not reduce database I/Os (page at a time)

Types of Sampling

Simple random sampling

There is an equal probability of selecting any particular item

Sampling without replacement

 Once an object is selected, it is removed from the population

Sampling with replacement

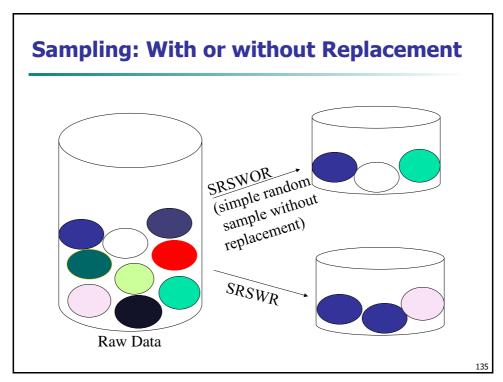
A selected object is not removed from the population

Stratified sampling:

- Partition the data set, and draw samples from each partition (proportionally, i.e., approximately the same percentage of the data)
- Used in conjunction with skewed data (also the smaller group of items will be sure to be represented)

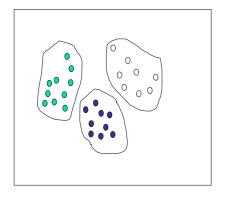
Types of Sampling

- Sampling with and without replacement. What is the difference
 - When we sample with replacement, the two sample values are independent.
 - what we get on the first one doesn't affect what we get on the second.
 - The covariance between the two is zero.
 - In sampling without replacement, the two sample values aren't independent.
 - what we got on for the first one affects what we can get for the second one.
 - The covariance between the two is population with variance σ^2 $\frac{-\sigma^2}{N-1}$ from a

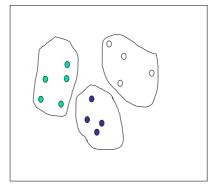


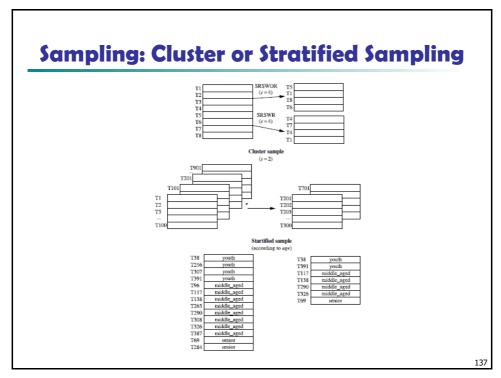
Sampling: Cluster or Stratified Sampling

Raw Data



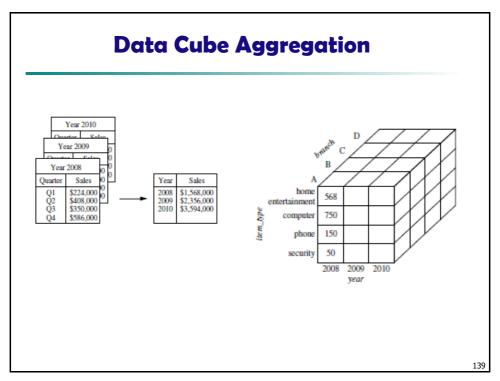
Cluster/Stratified Sample





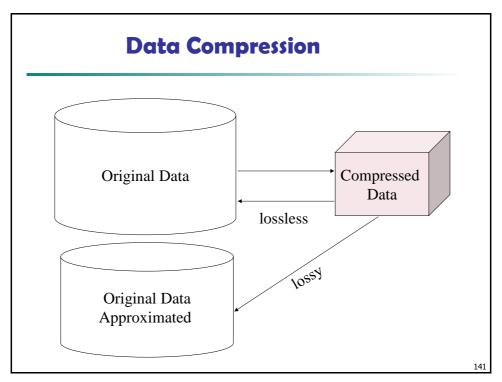
Data Cube Aggregation

- The lowest level of a data cube (base cuboid)
 - The aggregated data for an individual entity of interest
 - E.g., a customer in a phone calling data warehouse
- Multiple levels of aggregation in data cubes
 - Further reduce the size of data to deal with
- Reference appropriate levels
 - Use the smallest representation which is enough to solve the task
- Queries regarding aggregated information should be answered using data cube, when possible



Data Reduction 3: Data Compression

- String compression
 - There are extensive theories and well-tuned algorithms
 - Typically lossless, but only limited manipulation is possible without expansion
- Audio/video compression
 - Typically lossy compression, with progressive refinement
 - Sometimes small fragments of signal can be reconstructed without reconstructing the whole
- Time sequence is not audio
 - Typically short and vary slowly with time
- Dimensionality and numerosity reduction may also be considered as forms of data compression



Chapter 3: Data Preprocessing

- Data Preprocessing: An Overview
 - Data Quality
 - Major Tasks in Data Preprocessing
- **Data Cleaning**
- Data Integration
- Data Reduction
- Data Transformation and Data Discretization



Summary

Data Transformation

- A function that maps the entire set of values of a given attribute to a new set of replacement values such that each old value can be identified with one of the new values
- Methods
 - Smoothing: Remove noise from data
 - Attribute/feature construction
 - New attributes constructed from the given ones
 - Aggregation: Summarization, data cube construction
 - Normalization: Scaled to fall within a smaller, specified range
 - min-max normalization
 - z-score normalization
 - normalization by decimal scaling
 - Discretization: Concept hierarchy climbing

Normalization

Min-max normalization: to [new_min_A, new_max_A]

$$v' = \frac{v - min_A}{max_A - min_A} (new _max_A - new _min_A) + new _min_A$$

- Ex. Let income range \$12,000 to \$98,000 normalized to [0.0, 1.0]. Then \$73,600 is mapped to $\frac{73,600-12,000}{98,000-12,000}(1.0-0)+0=0.716$
- Z-score normalization (μ: mean, σ: standard deviation):

$$v' = \frac{v - \mu_A}{\sigma_A}$$

• Ex. Let $\mu = 54,000$, $\sigma = 16,000$. Then $\frac{73,600-54,000}{16,000} = 1.225$

Normalization

Normalization by decimal scaling

$$v' = \frac{v}{10^{j}}$$
 where j is the smallest integer such that Max(|v'|) < 1

Suppose that the recorded values of A range from -986 to 917. The maximum absolute value of A is 986. To normalize by decimal scaling, we therefore divide each value by 1000 (i.e., j = 3) so that -986 normalizes to -0.986 and 917 normalizes to 0.917.

Discretization

- Three types of attributes
 - Nominal—values from an unordered set, e.g., color, profession
 - Ordinal—values from an ordered set, e.g., military or academic rank
 - Numeric—real numbers, e.g., integer or real numbers
- Discretization: Divide the range of a continuous attribute into intervals
 - Interval labels can then be used to replace actual data values
 - Reduce data size by discretization
 - Supervised (uses information on the class) vs. unsupervised
 - Split (top-down) vs. merge (bottom-up)
 - Discretization can be performed recursively on an attribute
 - Prepare for further analysis, e.g., classification

Data Discretization Methods

- Typical methods: All the methods can be applied recursively
 - Binning
 - Top-down split, unsupervised
 - Histogram analysis
 - Top-down split, unsupervised
 - Clustering analysis (unsupervised, top-down split or bottom-up merge)
 - Decision-tree analysis (supervised, top-down split)
 - Correlation (e.g., χ^2) analysis (supervised, bottom-up merge)

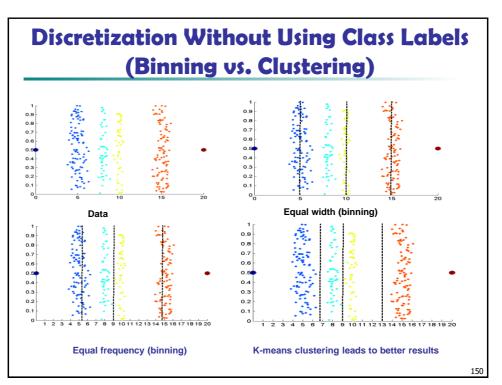
Simple Discretization: Binning

- Equal-width (distance) partitioning
 - Divides the range into N intervals of equal size: uniform grid
 - if A and B are the lowest and highest values of the attribute, the width of intervals will be: W = (B-A)/N.
 - The most straightforward, but outliers may dominate presentation
 - Skewed data is not handled well.
- Equal-depth (frequency) partitioning
 - Divides the range into N intervals, each containing approximately same number of samples
 - Good data scaling

Binning Methods

- Sorted data for price (in dollars): 4, 8, 9, 15, 21, 21, 24, 25, 26, 28, 29, 34
- * Partition into equal-frequency (equi-depth) bins:
 - Bin 1: 4, 8, 9, 15
 - Bin 2: 21, 21, 24, 25
 - Bin 3: 26, 28, 29, 34
- * Smoothing by **bin means**:
 - Bin 1: 9, 9, 9, 9
 - Bin 2: 23, 23, 23, 23
 - Bin 3: 29, 29, 29, 29
- * Smoothing by **bin boundaries**:
 - Bin 1: 4, 4, 4, 15
 - Bin 2: 21, 21, 25, 25
 - Bin 3: 26, 26, 26, 34

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Discretization by Classification & Correlation Analysis

- Classification (e.g., decision tree analysis)
 - Supervised: Given class labels, e.g., cancerous vs. benign
 - Using entropy to determine split point (discretization point)
 - Top-down, recursive split
 - Details to be covered in the following
- Correlation analysis (e.g., Chi-merge: χ²-based discretization)
 - Supervised: use class information
 - Bottom-up merge: find the best neighboring intervals (those having similar distributions of classes, i.e., low χ^2 values) to merge
 - Merge performed recursively, until a predefined stopping condition

ChiMerge Discretization

| | | i |
|--------|----|---|
| Sample | F | K |
| 1 | 1 | 1 |
| 2 | 3 | 2 |
| 3 | 7 | 1 |
| 4 | 8 | 1 |
| 5 | 9 | 1 |
| 6 | 11 | 2 |
| 7 | 23 | 2 |
| 8 | 37 | 1 |
| 9 | 39 | 2 |
| 10 | 45 | 1 |
| 11 | 46 | 1 |
| 12 | 59 | 1 |

- Statistical approach to Data Discretization
- Applies the Chi Square method to determine the probability of similarity of data between two intervals.
 - F -> feature
 - K -> class

ChiMerge Discretization

| Sample | F | K | Intervals |
|--------|----|---|-----------|
| 1 | 1 | 1 | {0,2} |
| 2 | 3 | 2 | {2,5} |
| 3 | 7 | 1 | {5,7.5} |
| 4 | 8 | 1 | {7.5,8.5} |
| 5 | 9 | 1 | {8.5,10} |
| 6 | 11 | 2 | {10,17} |
| 7 | 23 | 2 | {17,30} |
| 8 | 37 | 1 | {30,38} |
| 9 | 39 | 2 | {38,42} |
| 10 | 45 | 1 | {42,45.5} |
| 11 | 46 | 1 | {45.5,52} |
| 12 | 59 | 1 | {52,60} |

- Sort and order the attributes that you want to group (in this example attribute F).
- Start with having every unique value in the attribute be in its own interval.
- Independence: change in the values of the feature, same label for the class

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ChiMerge Discretization

| Sample | F | K |
|--------|----|---|
| 1 | 1 | 1 |
| 2 | 3 | 2 |
| 3 | 7 | 1 |
| 4 | 8 | 1 |
| 5 | 9 | 1 |
| 6 | 11 | 2 |
| 7 | 23 | 2 |
| 8 | 37 | 1 |
| 9 | 39 | 2 |
| 10 | 45 | 1 |
| 11 | 46 | 1 |
| 12 | 59 | 1 |

 Begin calculating the Chi Square test on every interval

| Sample | K=1 | K=2 | |
|--------|-----|-----|---|
| 2 | 0 | 1 | 1 |
| 3 | 1 | 0 | 1 |
| total | 1 | 1 | 2 |

| Sample | K=1 | K=2 | |
|--------|-----|-----|---|
| 3 | 1 | 0 | 1 |
| 4 | 1 | 0 | 1 |
| total | 2 | 0 | 2 |

ChiMerge Discretization

| Sample | K=1 | K=2 | |
|--------|-----|-----|---|
| 2 | 0 | 1 | 1 |
| 3 | 1 | 0 | 1 |
| total | 1 | 1 | 2 |

$$\mathbf{E_{11}} = (1/2)*1 = .5$$

$$\mathbf{E_{12}} = (1/2)*1 = .5$$

$$\mathbf{E_{21}} = (1/2)*1 = .5$$

$$\mathbf{E_{22}} = (1/2)*1 = .5$$

$$X^2 = (0-.5)^2/.5 + (0-.5)^2/.5 + (0-.5)^2/.5 + (0-.5)^2/.5 = 2$$

| Sample | K=1 | K=2 | |
|--------|-----|-----|---|
| 3 | 1 | 0 | 1 |
| 4 | 1 | 0 | 1 |
| total | 2 | 0 | 2 |

$$\mathbf{E_{11}} = (1/2)*2 = 1$$

$$\mathbf{E_{12}} = (0/2)*2 = 0$$

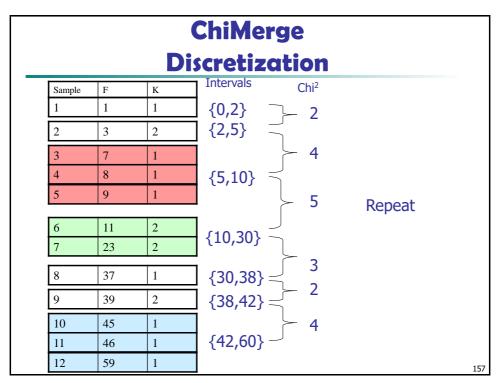
$$\mathbf{E_{21}} = (1/2)*2 = 1$$

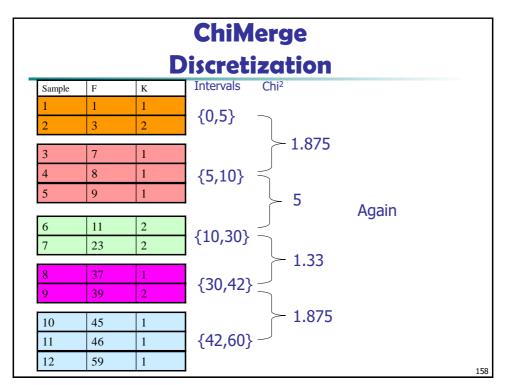
$$\mathbf{E_{22}} = (0/2)*2 = 0$$

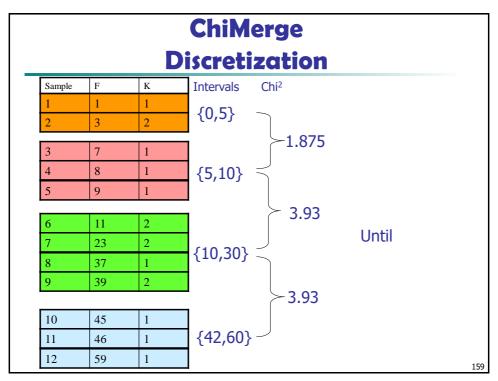
$$\mathbf{X}^2 = (1-1)^2/1 + (0-0)^2/0 + (1-1)^2/1 + (0-0)^2/0 = \mathbf{0}$$

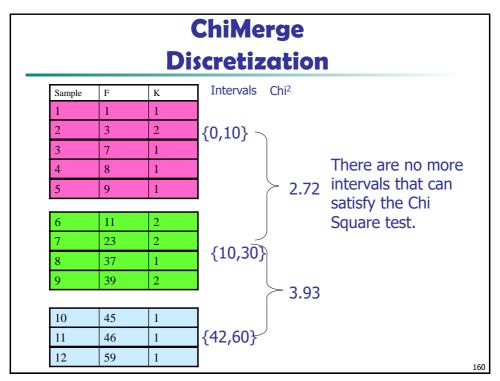
Threshold .1 with df=1 from Chi square distribution chart merge if $\mathbf{X}^2 < 2.7024$

| | ChiMerge | | | |
|----------|------------|---|--|--|
| | | | Discretization | |
| Sample 1 | F 1 | 1 | Intervals Chi ² {0,2} 2 | |
| 2 | 3 | 2 | {2,5} Calculate all | |
| 3 | 7 | 1 | Square value | |
| 5 | 9 | 1 | {7.5,8.5} 0 for all intervals {8.5,10} | |
| 6 | 11 | 2 | {10.17} Merge the intervals with | |
| 7 | 23 | 2 | 17,30} = 0 the smallest Chi values | |
| 8 | 37 | 1 | [30,38] = 2 | |
| 9 | 39 45 | 1 |] {38,42} = | |
| 11 | 46 | 1 | [45.5,52] 0 0 | |
| 12 | 59 | 1 | [{52,60} | |









Concept Hierarchy Generation

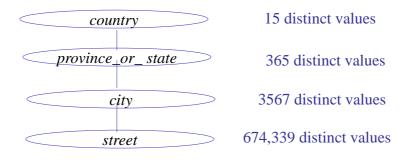
- Concept hierarchy organizes concepts (i.e., attribute values)
 hierarchically and is usually associated with each dimension in a data warehouse
- Concept hierarchies facilitate <u>drilling and rolling</u> in data warehouses to view data in multiple granularity
- Concept hierarchy formation: Recursively reduce the data by collecting and replacing low level concepts (such as numeric values for age) by higher level concepts (such as youth, adult, or senior)
- Concept hierarchies can be explicitly specified by domain experts and/or data warehouse designers
- Concept hierarchy can be automatically formed for both numeric and nominal data. For numeric data, use discretization methods shown.

Concept Hierarchy Generation for Nominal Data

- Specification of a partial/total ordering of attributes explicitly at the schema level by users or experts
 - street < city < state < country</p>
- Specification of a hierarchy for a set of values by explicit data grouping
 - {Urbana, Champaign, Chicago} < Illinois
- Specification of only a partial set of attributes
 - E.g., only street < city, not others
- Automatic generation of hierarchies (or attribute levels) by the analysis of the number of distinct values
 - E.g., for a set of attributes: { street, city, state, country}

Automatic Concept Hierarchy Generation

- Some hierarchies can be automatically generated based on the analysis of the number of distinct values per attribute in the data set
 - The attribute with the most distinct values is placed at the lowest level of the hierarchy
 - Exceptions, e.g., weekday, month, quarter, year



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Chapter 3: Data Preprocessing

- Data Preprocessing: An Overview
 - Data Quality
 - Major Tasks in Data Preprocessing
- Data Cleaning
- Data Integration
- Data Reduction
- Data Transformation and Data Discretization
- Summary



Summary

- Data quality: accuracy, completeness, consistency, timeliness, believability, interpretability
- Data cleaning: e.g. missing/noisy values, outliers
- Data integration from multiple sources:
 - Entity identification problem
 - Remove redundancies
 - Detect inconsistencies
- Data reduction
 - Dimensionality reduction
 - Numerosity reduction
 - Data compression
- Data transformation and data discretization
 - Normalization
 - Concept hierarchy generation

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