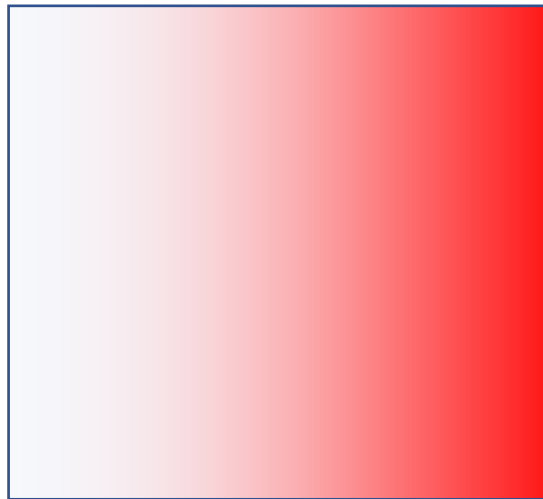




Tesi di Dottorato/Ph.D. Thesis

**Video-Conditioned Multi-Task Imitation
Learning for Robotic Systems: Enhancing
Robustness Through Object Centric Reasoning**
Francesco Rosa



Supervisor: **Prof. Mario Vento**

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