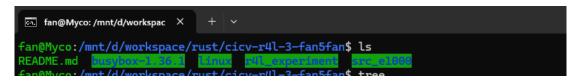
第三期训练营第二阶段 rust for linux 作业

一、环境配置

1、下载作业源码

git clone https://github.com/cicvedu/cicv-r4l-3-fan5fan.git

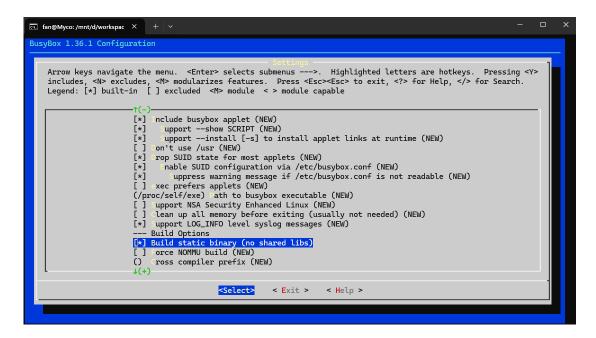


- 2、编译 BusyBox
 - 2.1 cd cicv-r4l-3-fan5fan/busybox-1.36.1/

```
fan@Myco:/mnt/d/workspace/rust/cicv-r4l-3-fan5fan$ cd busybox-1.36.1/fan@Myco:/mnt/d/workspace/rust/cicv-r4l-3-fan5fan/busybox-1.36.1$
```

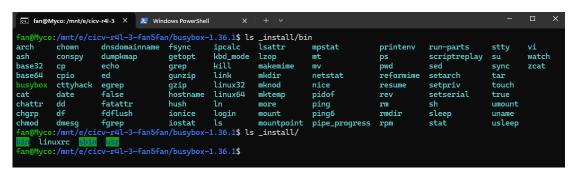
2.2 make menuconfig

2.3、启动静态链接



2.4、编译、安装

make install -j\$(nproc)



3、安装 Qemu

sudo apt install qemu-system-x86

```
fan@Myco:/mnt/d/workspace X + v

fan@Myco:/mnt/d/workspace/rust/cicv-r4l-3-fan5fan/linux$ qemu-system-x86_64 --version

QEMU emulator version 6.2.0 (Debian 1:6.2+dfsg-2ubuntu6.17)

Copyright (c) 2003-2021 Fabrice Bellard and the QEMU Project developers

fan@Myco:/mnt/d/workspace/rust/cicv-r4l-3-fan5fan/linux$
```

4、安装 rust

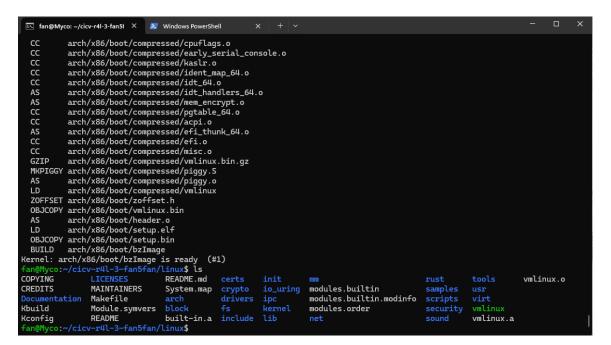
```
curl --proto '=https' --tlsv1.2 -sSf https://sh.rustup.rs | sh
```

5、配置 linux 文件夹

fan@Myco:/mnt/d/workspace/rust/cicv-r4l-3-fan5fan/linux\$ make LLVM=1 rustavailable
Rust is available!

二、作业一编译 Linux 内核

```
fan@Myco: /mnt/d/workspac × + v
   onfig - Linux/x86 6.1.0-rcl Kernel Configuration
      Arrow keys navigate the menu. <Enter> selects submenus ---> (or empty submenus ----). Highlighted letters are hotkeys. Pressing <Y> includes, <N> excludes, <M> modularizes features. Press <Esc><Esc> to exit, <?> for Help, </> for Search. Legend: [*] built-in [] excluded <M> module <> module capable
                                    ()
                                             Initramfs source file(s)
                                    [*]
[*]
                                             Support initial ramdisk/ramfs compressed using gzip Support initial ramdisk/ramfs compressed using bzip2
                                             Support initial ramdisk/ramfs compressed using LZMA
                                             Support initial ramdisk/ramfs compressed using XZ
                                            Support initial ramdisk/ramfs compressed using LZO
Support initial ramdisk/ramfs compressed using LZ4
Support initial ramdisk/ramfs compressed using ZSTD
                                    [*] Support initial ra
                                    [*] Preserve cpio archive mtimes in initramfs
Compiler optimization level (Optimize for performance (-02)) --->
                                         Configure standard kernel features (expert users)
                                    [ ] Embedded system
Kernel Performance Events And Counters --->
                                    [*] Profiling support
                                   [*] Rust support
                                               <Select>
                                                                 < Exit >
                                                                                   < Help >
                                                                                                    < Save >
                                                                                                                          < Load >
```



注:用 WSL 编译内核时,不能将文件放在 Windows 的文件系统内,必须放在 WSL 里面,不然会编译不过

三、作业二对 Linux 内核进行一些配置

- 1、操作步骤
 - 1.0、进入源码文件夹 cd cicv-r4l-3-fan5fan/src_e1000
 - 1.1, make

1.2、执行./build image.sh

```
[ 2.203201] printk: console [netcon0] enabled
[ 2.203201] printk: console [netcon0] enabled
[ 2.203851] netconsole: network logging started
[ 2.260824] tsc: Refined TSC clocksource calibration: 2112.005 MHz
[ 2.260284] clocksource: tsc: mask: 0xfffffffffffffff max_cycles: 0xle717dlec85, max_idle_ns: 440795234704 ns
[ 2.263177] clocksource: Switched to clocksource tsc
[ 2.778727] input: ImEXPS/C Generic Explorer Mouse as /devices/platform/i8042/seriol/input/input3
[ 2.778030] el000: eth0 NIC Link is Up 1000 Mbps Full Duplex, Flow Control: RX
[ 2.795727] input: ImEXPS/C Generic Explorer Mouse as /devices/platform/i8042/seriol/input/input3
[ 2.778030] el000: eth0 NIC Link is Up 1000 Mbps Full Duplex, Flow Control: RX
[ 2.795927] device=eth0, hwaddr=52:54:00:12:34:56, ipaddr=10.0.2.15, mask=255.255.255.255.0, gw=10.0.2.1
[ 2.799387] host=10.0.2.15, domain=_none)
[ 2.809728] cfg80211: Loading compiled-in X.509 certificates for regulatory database
[ 2.809728] cfg80211: Loading compiled-in X.509 certificates for regulatory database
[ 2.809328] cfg80211: Loading compiled-in X.509 certificates for regulatory database
[ 2.809328] loading regulatory.0: Direct firmware load for regulatory.db failed with error -2
[ 2.809568] platform regulatory.0: Direct firmware load for regulatory.db failed with error -2
[ 2.809568] platform regulatory.0: Direct firmware load for regulatory.db failed with error -2
[ 2.809568] platform regulatory.0: Direct firmware load for regulatory.db failed with error -2
[ 2.809568] Preeing unused kernel image (text/rodata gap) memory: 2021K
[ 2.95508] Write protecting the kernel read-only data: 24576k
[ 2.959012] Freeing unused kernel image (text/rodata gap) memory: 2021K
[ 3.131633] x86/mm: Checked W+X mappings: passed, no W+X pages found.
[ 3.131633] x86/mm: Checked W+X mappings: passed, no W+X pages found.
[ 3.13199] Run sbin/init as init process
[ 3.195189] mount (71) used greatest stack depth: 13060 bytes left
[ 3.349714] mdev (73) used greatest stack depth: 13060 bytes left
```

1.3、执行 ifconfig

1.4、执行 ping

1.5、安装 r4l e1000 demo.ko

```
| S | fan@Myco:-/cicv-r4l-3-fanSl X | Windows PowerShell | X | + V | - | X |

- # ls
bin linuxrc root usr
dev proc sbin
etc r4l_e1000_demo.ko sys

- # ismod r4l_e1000_demo.ko | 1 |

[ 369.831811] r4l_e1000_demo: loading out-of-tree module taints kernel.

[ 369.840387] r4l_e1000_demo: Rust for linux e1000 driver demo (init)

[ 369.842967] insmod (87) used greatest stack depth: 13336 bytes left

- # |
```

1.6、退出 Qemu

1.7、进入 linux 文件夹,重新 make LLVM=1 menuconfig,重新编译 linux 内核

```
config = Linux/x86 6.1.0-rcl Kernel Configuration
> Device Drivers > Network device support > Ethernet driver support

Arrow keys navigate the menu. <fnter> selects submenus ---> (or empty submenus ----). Highlighted letters are hotkeys. Pressing 
Arrow keys navigate the menu. <fnter> selects submenus ---> (or empty submenus ----). Highlighted letters are hotkeys. Pressing 
Arrow keys navigate the menu. <fnter> selects submenus ----> (or empty submenus ----). Highlighted letters are hotkeys. Pressing 
Arrow keys navigate the menu. <fnter> consider of the pression of the pressi
```

1.8、重新进入 Qemu, 并执行 ifconfig

1.9、安装 r4l e1000 demo.ko

```
# ls
bin linuxrc root usr
dev proc sbin
r4l_e1000_demo.ko sys

* # insmod r4l_e1000_demo.ko sys

* # insmod r4l_e1000_demo.ko sys

* # insmod r4l_e1000_demo. Rust for linux e1000 driver demo (init)

[ 79.518111] r4l_e1000_demo: Rust for linux e1000 driver demo (probe): None

[ 79.714171] ACPI: \SB_.LNKC: Enabled at IRQ II

[ 79.738197] r4l_e1000_demo: Rust for linux e1000 driver demo (net device get_stats64)

[ 79.742730] insmod (85) used greatest stack depth: 11192 bytes left

* # ifconfig

130.168963] r4l_e1000_demo: Rust for linux e1000 driver demo (net device get_stats64)

* # |
```

1.10、设置

ip link set eth0 up

```
# ip link set eth0 up

[ 234.092130] rul_e1000_demo: Rust for linux e1000 driver demo (net device open)

[ 234.096133] rul_e1000_demo: Rust for linux e1000 driver demo (net device get_stats64)

[ 234.096303] rul_e1000_demo: Rust for linux e1000 driver demo (net device get_stats64)

[ 234.096806] rul_e1000_demo: Rust for linux e1000 driver demo (net device get_stats64)

[ 234.114033] rul_e1000_demo: Rust for linux e1000 driver demo (net device get_stats64)

[ 234.114033] rul_e1000_demo: Rust for linux e1000 driver demo (net device start_xmit) tdt=0, tdh=0, rdt=7, rdh=0

[ 234.115791] rul_e1000_demo: Rust for linux e1000 driver demo (napi poll)

[ 234.11616] rul_e1000_demo: Rust for linux e1000 driver demo (napi poll)

[ 234.697017] rul_e1000_demo: Rust for linux e1000 driver demo (napi poll)

[ 234.697018] rul_e1000_demo: Rust for linux e1000 driver demo (napi poll)

[ 234.697017] rul_e1000_demo: Rust for linux e1000 driver demo (napi poll)

[ 234.887046] rul_e1000_demo: Rust for linux e1000 driver demo (napi poll)

[ 234.887046] rul_e1000_demo: Rust for linux e1000 driver demo (napi poll)

[ 234.887046] rul_e1000_demo: Rust for linux e1000 driver demo (napi poll)

[ 234.887046] rul_e1000_demo: Rust for linux e1000 driver demo (napi poll)

[ 234.887046] rul_e1000_demo: Rust for linux e1000 driver demo (napi poll)

[ 235.719924] rul_e1000_demo: Rust for linux e1000 driver demo (napi poll)

[ 235.721978] rul_e1000_demo: Rust for linux e1000 driver demo (napi poll)

[ 235.721978] rul_e1000_demo: Rust for linux e1000 driver demo (napi poll)

[ 235.722919] rul_e1000_demo: Rust for linux e1000 driver demo (napi poll)

[ 235.723501] rul_e1000_demo: Rust for linux e1000 driver demo (napi poll)

[ 235.723501] rul_e1000_demo: Rust for linux e1000 driver demo (napi poll)

[ 235.723930] rul_e1000_demo: Rust for linux e1000 driver demo (napi poll)

[ 235.72313] rul_e1000_demo: Rust for linux e1000 driver demo (napi poll)

[ 236.231693] rul_e1000_demo: Rust for linux e1000 driver demo (napi poll)

[ 236.231693] rul_e1000_demo
```

ip addr add broadcast 10.0.2.255 dev eth0

ip addr add 10.0.2.15/255.255.255.0 dev eth0

ip route add default via 10.0.2.1



ping 10.0.2.2

2、问题

- 2.1、编译成内核模块,是在哪个文件中以哪条语句定义的? Kbuild 文件中的 obj-m := r4l_e1000_demo.o 这里定义的
- 2.2、该模块位于独立的文件夹内,却能编译成 Linux 内核模块,这叫做 out-of-tree module,请分析它是如何与内核代码产生联系的?

加载一个 out-of-tree 模块时,它通常有以下几种方式与内核代码发生关联:

- 1. 直接内核符号引用:模块可能会直接引用内核导出的符号,如函数和变量。
- 2. 内核服务:模块可能会使用内核提供的服务,如消息传递机制。
- 3. 设备文件节点:模块可能会创建设备文件节点,通过 /dev 目录与用户空间通信。
- 4. 模块参数:模块可以定义参数,在加载模块时传入这些参数。

四、作业三

1、在 samples/rust 里添加 rust helloworld.rs

2、修改 Kconfig

3、修改 Makefile

```
fan@Myco: ~/cicv-r4l-3-fan5l X 💹 fan@Myco: ~/cicv-r4l-3-fan5fa X
 fan@Myco:~/cicv-r4l-3-fan5fan/linux$ cat samples/rust/Makefile
# SPDX-License-Identifier: GPL-2.0
 obj-$(CONFIG_SAMPLE_RUST_MINIMAL)
 obj-$(CONFIG_SAMPLE_RUST_PRINT)
obj-$(CONFIG_SAMPLE_RUST_MODULE_PARAMETERS)
                                                                                                                    += rust_print.o
+= rust_module_parameters.o
obj-$(CONFIG_SAMPLE_RUST_MODULE_PARAMETER
obj-$(CONFIG_SAMPLE_RUST_SYNC)
obj-$(CONFIG_SAMPLE_RUST_SYNC)
obj-$(CONFIG_SAMPLE_RUST_CHRDEV)
obj-$(CONFIG_SAMPLE_RUST_MISCDEV)
obj-$(CONFIG_SAMPLE_RUST_SEMAPHORE)
obj-$(CONFIG_SAMPLE_RUST_SEMAPHORE_C)
obj-$(CONFIG_SAMPLE_RUST_RANDOM)
obj-$(CONFIG_SAMPLE_RUST_PLATFORM)
obj-$(CONFIG_SAMPLE_RUST_NETFILTER)
obj-$(CONFIG_SAMPLE_RUST_NETFILTER)
obj-$(CONFIG_SAMPLE_RUST_NETFILTER)
obj-$(CONFIG_SAMPLE_RUST_SELFFS)
obj-$(CONFIG_SAMPLE_RUST_SELFTSS)
                                                                                                                    += rust_sync.o
+= rust_chrdev.o
                                                                                                                    += rust_miscdev.o
+= rust_stack_probing.o
                                                                                                                    += rust_semaphore.o
+= rust_semaphore_c.o
                                                                                                                    += rust_random.o
                                                                                                                    += rust_platform.o
+= rust_netfilter.o
                                                                                                                    += rust_echo_server.o
+= rust_fs.o
+= rust_selftests.o
  obj-$(CONFIG_PRINT_HELLOWORLD)
                                                                                                                    += rust_helloworld.o
 subdir-$(CONFIG_SAMPLE_RUST_HOSTPROGS)
fan@Myco:~/cicv-r4l-3-fan5fan/linux$ |
                                                                                                                    += hostprogs
```

5, make LLVM=1 -j\$(nproc)

```
🔍 fan@Myco: ~/cicv-r4l-3-fan5fः 🗶 🗾 fan@Myco: ~/cicv-r4l-3-fan5l 🛛 🗡
        Myco:~/cicv-r4l-3-fan5fan/linux$ make LLVM=1 -j$(nproc)
NC include/config/auto.conf.cmd
SYNC include/confly/accord
DESCEND objtool
CALL scripts/checksyscalls.sh
AR samples/vfio-mdev/built-in.a
AR samples/rust/built-in.a
AR samples/built-in.a
AR built-in.a
 AR
AR
AR
AR
AR
LD
                        vmlinux.a
vmlinux.o
OBJCOPY modules.builtin.modinfo
GEN modules.builtin
GEN modules.builtin
MODPOST Module.symvers
UPD include/generated/utsversion.h
CC init/version-timestamp.o
LD .tmp_vmlinux.kallsyms1.syms
KSYMS .tmp_vmlinux.kallsyms1.S
AS .tmp_vmlinux.kallsyms1.S
AS
LD
                        .tmp_vmlinux.kallsyms1.s
.tmp_vmlinux.kallsyms2.syms
.tmp_vmlinux.kallsyms2.syms
.tmp_vmlinux.kallsyms2.s
.tmp_vmlinux.kallsyms2.s
 KSYMS
AS
LD
                        vmlinux
 NM System.map
SORTTAB vmlinux
CC arch/x86/boot/version.o
CC arch/x86/boot/compressed/../voffset.h

OBJCOPY arch/x86/boot/compressed/wmlinux.bin

RELOCS arch/x86/boot/compressed/wmlinux.relocs

CC arch/x86/boot/compressed/wmlinux.bin.gz

CC arch/x86/boot/compressed/misc.o

MKPIGGY arch/x86/boot/compressed/piggy.5
AS arch/x86/boot/compressed/piggy.o
LD arch/x86/boot/compressed/wnlinux
ZOFFSET arch/x86/boot/zoffset.h
OBJCOPY arch/x86/boot/ymlinux.bin
                       arch/x86/boot/header.o
arch/x86/boot/setup.elf
 OBJCOPY arch/x86/boot/setup.bin
```

6、复制 rust helloworld.ko 文件到 src e1000/rootfs/目录下

- 7、执行 build image.sh
- 8、执行 insmod 加载 rust helloworld.ko

Makefile 文件添加一行:

```
obj-$(CONFIG PRINT HELLOWORLD) += rust helloworld.o
```

Kconfig 文件添加:

```
config PRINT HELLOWORLD
```

tristate "Print Helloworld in Rust"

help

This option builds the Rust helloworld module sample.

To compile this as a module, choose M here:

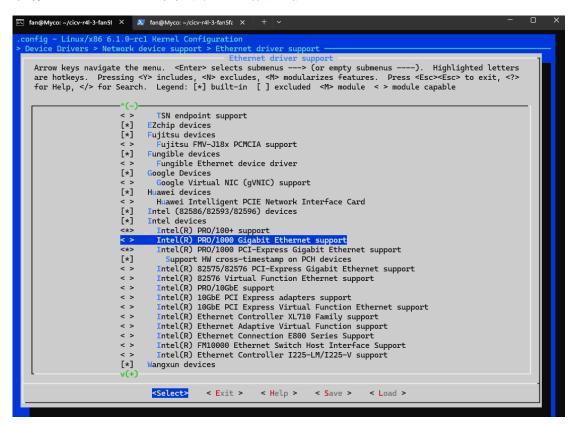
If unsure, say N.

```
五、作业四
     1、修改 r4l_e1000_demo.rs
           fn device_remove(&self) {
              pr_info!("Rust for linux e1000 driver demo (device_remove)\n");
              let netdev = self. netdev reg.dev get();
              netdev.netif carrier off();
              netdev.netif stop queue();
            }
         fn remove(dev: &mut pci::Device, data: &Self::Data) {
             pr info!("Rust for linux e1000 driver demo (remove)\n");
             let bars = dev.select bars((bindings::IORESOURCE MEM |
bindings::IORESOURCE IO) as u64);
             dev.release selected regions(bars);
             dev.disable_device();
             drop(data);
     2、修改 linux/rust/kernel/pci.rs, 并添加两个函数
        pub trait Driver {
             fn remove(dev: &mut Device, _data: &Self::Data);
        }
        impl Device {
             pub fn release selected regions(&mut self, bars: i32) {
```

```
unsafe { bindings::pci_release_selected_regions(self.ptr, bars) };
}

pub fn disable_device(&mut self) {
    unsafe { bindings::pci_disable_device(self.ptr) };
}
```

3、取消选中内置 e1000 网卡驱动, 重新编译内核



- 4、运行 src e1000/build image.sh
- 5、进入 qemu, 并测试网络

6、加载 r4l e1000 demo.ko

7、添加网络设置

8、卸载 r4l e1000 demo.ko, 重新加载 r4l e1000 demo.ko

```
### Twmmod rwll_e1000_demo.ko

| 122.66046771_rwll_e1000_demo.ko
| 122.66046771_rwll_e1000_demo: Rust for linux e1000 driver demo (remove)
| 122.6046771_rwll_e1000_demo: Rust for linux e1000 driver demo (remove)
| 122.8578741_rwll_e1000_demo: Rust for linux e1000 driver demo (device_remove)
| 122.8578741_rwll_e1000_demo: Rust for linux e1000 driver demo (net device get_stats64)
| 122.6604676_rwll_e1000_demo: Rust for linux e1000 driver demo (net device get_stats64)
| 122.6604676_rwll_e1000_demo: Rust for linux e1000 driver demo (net device get_stats64)
| 122.660476_rwll_e1000_demo. Rust for linux e1000 driver demo (net device get_stats64)
| 184.661430_rwll_e1000_demo: Rust for linux e1000 driver demo (net device get_stats64)
| 184.66236_rwll_e1000_demo: Rust for linux e1000 driver demo (net device get_stats64)
| 184.66236_rwll_e1000_demo: Rust for linux e1000 driver demo (net device get_stats64)
| 198.553170_rwll_e1000_demo: Rust for linux e1000 driver demo (net device get_stats64)
| 198.553170_rwll_e1000_demo: Rust for linux e1000 driver demo (net device get_stats64)
| 198.553170_rwll_e1000_demo: Rust for linux e1000 driver demo (net device get_stats64)
| 198.570111_rwll_e1000_demo: Rust for linux e1000 driver demo (net device get_stats64)
| 198.570111_rwll_e1000_demo: Rust for linux e1000 driver demo (net device stat_xmit) tdt=0, tdh=0, rdt=7, rdh=0
| 198.570111_rwll_e1000_demo: Rust for linux e1000 driver demo (net device stat_xmit) tdt=1, tdh=1, rdt=7, rdh=0
| 199.180835_rwll_e1000_demo: Rust for linux e1000 driver demo (net device stat_xmit) tdt=1, tdh=1, rdt=7, rdh=0
| 199.180835_rwll_e1000_demo: Rust for linux e1000 driver demo (net device stat_xmit) tdt=2, tdh=2, rdt=7, rdh=0
| 199.180935_rwll_e1000_demo: Rust for linux e1000 driver demo (net device stat_xmit) tdt=2, tdh=2, rdt=7, rdh=0
| 199.180935_rwll_e1000_demo: Rust for linux e1000 driver demo (net device stat_xmit) tdt=3, tdh=3, rdt=7, rdh=0
| 199.180935_rwll_e1000_demo: Rust for linux e1000 driver demo (net device stat_xmit) tdt=3, tdh=3, rdt=7,
```

```
## ping 10.0.2.2

PING 10.0.2.2 (10.0.2.2): 56 data bytes

[ 249.112578] rHl_e1000_deno: Rust for linux e1000 driver demo (net device start_xmit) tdt=1, tdh=1, rdt=7, rdh=0

[ 249.112578] rHl_e1000_deno: Rust for linux e1000 driver demo (handle_irq)

[ 249.115576] rHl_e1000_deno: Rust for linux e1000 driver demo (napi poll)

[ 249.115576] rHl_e1000_deno: Rust for linux e1000 driver demo (napi poll)

[ 249.115576] rHl_e1000_deno: Rust for linux e1000 driver demo (napi poll)

[ 249.120837] rHl_e1000_deno: Rust for linux e1000 driver demo (napi poll)

[ 249.12031] rHl_e1000_deno: Rust for linux e1000 driver demo (napi poll)

[ 249.12272] rHl_e1000_deno: Rust for linux e1000 driver demo (napi poll)

64 bytes from 10.0.2.2: seq=0 ttl=255 time=20.233 ms

[ 250.123650] rHl_e1000_deno: Rust for linux e1000 driver demo (napi poll)

64 bytes from 10.0.2.2: seq=0 ttl=255 time=20.233 ms

[ 250.123290] rHl_e1000_deno: Rust for linux e1000 driver demo (napi poll)

65 bytes from 10.0.2.2: seq=0 ttl=255 time=5.556 ms

[ 251.133500] rHl_e1000_deno: Rust for linux e1000 driver demo (napi poll)

64 bytes from 10.0.2.2: seq=1 ttl=255 time=5.556 ms

[ 251.135500] rHl_e1000_deno: Rust for linux e1000 driver demo (napi poll)

65 bytes from 10.0.2.2: seq=1 ttl=255 time=5.556 ms

[ 251.137990] rHl_e1000_deno: Rust for linux e1000 driver demo (napi poll)

66 bytes from 10.0.2.2: seq=2 ttl=255 time=4.652 ms

[ 251.137990] rHl_e1000_deno: Rust for linux e1000 driver demo (napi poll)

67 bytes from 10.0.2.2: seq=2 ttl=255 time=4.652 ms

[ 252.14350] rHl_e1000_deno: Rust for linux e1000 driver demo (napi poll)

68 bytes from 10.0.2.2: seq=3 ttl=255 time=4.652 ms

[ 252.14350] rHl_e1000_deno: Rust for linux e1000 driver demo (napi poll)

69 bytes from 10.0.2.2: seq=3 ttl=255 time=4.652 ms

[ 252.14350] rHl_e1000_deno: Rust for linux e1000 driver demo (napi poll)

69 bytes from 10.0.2.2: seq=3 ttl=255 time=4.650 ms

[ 252.14350] rHl_e1000_deno: Rust for linux e1000 driver demo (napi poll)
```

六、作业五

1, make LLVM=1 menuconfig

```
fan@Myco: ~/cicv-r4l-3-fan5l X 🗾 fan@Myco: ~/cicv-r4l-3-fan5fa X
          Linux/x86 6.1.0-rcl Kernel Configuratio
   Arrow keys navigate the menu. <Enter> selects submenus ---
are hotkeys. Pressing <>> includes <
                                                                                -> (or empty submenus ----). Highlighted letters
   are hotkeys. Pressing <Y> includes, <N> excludes, <M> modularizes features. Press <Esc><Esc> to exit, <?> for Help, </> for Search. Legend: [*] built-in [ ] excluded <M> module <> module capable
                            --- Rust samples
<M> Print Helloworld in Rust
                                    Minimal
                                    Printing macros
                                   Module parameters
                                    Synchronisation primitives
Character device
                                   Miscellaneous device
                                   Stack probing
                                   Semaphore
                                   Semaphore (in C, for comparison)
                                 Platform device driver
                                   File system
                                   Network filter module
                                   Echo server module
                           c> Echo Server ...
[] Host programs
c> Self tests
                                     <Select>
                                                 < Exit >
                                                                   < Help > < Save >
                                                                                                   < Load >
```

2、重新编译内核

3、执行操作

```
[ 1.845854] PM: Magic number: 0:719:210
[ 1.858515] printk: console [netcon0] enabled
[ 1.858515] printk: console [netcon0] enabled
[ 1.858515] nrintk: console [netcon0] enabled
[ 1.8587017] ata2: found unknown device (class 0)
[ 1.997017] ata2: found unknown device (class 0)
[ 1.997023] ata2.0: ATAPI: QPUN UDP-ROM, 2.5+ max UDMA/100
[ 1.917625] scsi 1:0:0:0: CD-ROM QPUN QPUN UDP-ROM 2.5+ PQ: 0 ANSI: 5
[ 1.958908] art 1:0:0:0: Exrol scsi 3-mmc drive: uK/xx cd/rw xa/form2 tray
[ 1.958908] art 1:0:0:0: Exrol scsi 3-mmc drive: uK/xx cd/rw xa/form2 tray
[ 1.958908] art 1:0:0:0: Attached scsi generic sg0 type 5
[ 2.93880] input: INEXPS/2 Generic Explorer Mouse as /devices/platform/i80412/seriol/input/input3
[ 2.448908] tsc: Refined TSC clocksource calibration: 2111.976 HMz
[ 2.445085] clocksource: striched to clocksource tsc
[ 2.445085] clocksource: Striched to clocksource tsc
[ 144,672807] cfg80211: Loadding compiled-in X.509 certificates for regulatory database
[ 144,78103] efg80211: Loadding compiled-in X.509 certificates for regulatory database
[ 144,78303] efg80211: Loadd X.509 cert 'sforshee: 08b28ddfdfVaef9cea7'
[ 144,78309] platform regulatory.0 Direct firmware load for regulatory.0b failed with error -2
[ 144,78109] platform regulatory.0 Direct firmware load for regulatory.0b failed with error -2
[ 144,78109] flatform regulatory.0 Direct firmware load for regulatory.0 Brailed With error -2
[ 144,78109] flatform regulatory.0 Direct firmware load for regulatory.0 Brailed With error -2
[ 144,78109] flatform regulatory.0 Direct firmware load for regulatory.0 Brailed With error -2
[ 144,78109] flatform regulatory.0 Brailed With error -2
[ 145,0007] flatform regulatory.0 Braile
```

4、作业 5 中的字符设备/dev/cicv 是怎么创建的?它的设备号是多少?它是如何与我们写的字符设备驱动关联上的?

echo "mknod /dev/cicv c 248 0" >> etc/init.d/rcS

- 1、由系统启动时 init.d/reS 文件的 mknod 指令创建
- 2、它的记设备号是248,次设备号是0
- 3、kernel::file::Operations trait 是一个函数指针的集合. 这些操作大部分负责实现系统调用, 在驱动注册时, 实现了这个 trait 的结构与驱动关联.

let mut chrdev_reg = chrdev::Registration::new_pinned(name, 0, module)?;
chrdev_reg.as_mut().register::<RustFile>()?;

RustFile 这个结构实现了 kernel::file::Operations。